

Fast Algorithms for Particle-Based Simulations

Stan Moore

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1444 Interview Candidate

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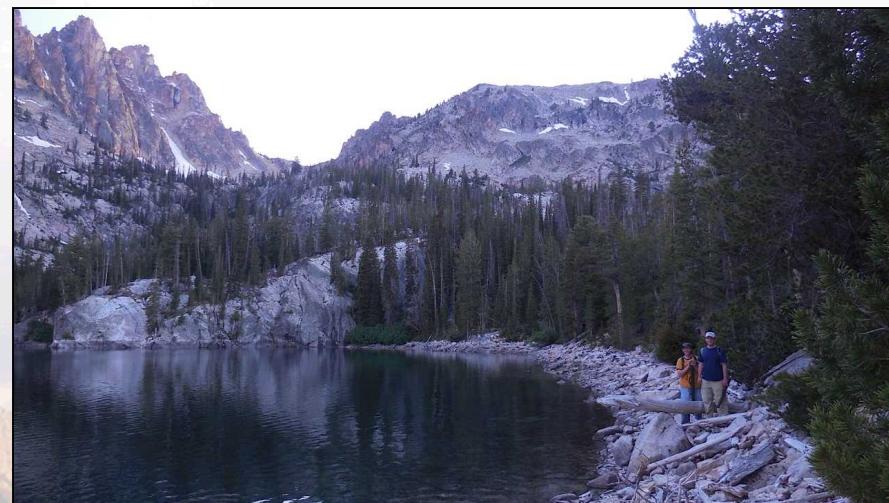


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A little about me ...

- Grew up on a farm in Filer, Idaho
- Love outdoor activities (backpacking, hiking, fly fishing, etc.)
- BS Chemical Engineering, Brigham Young University, 2008
- PhD Chemical Engineering, Brigham Young University, 2012
- Dissertation topic: Developing a new method to predict chemical potential using molecular simulations



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Sandia Projects

- Been at Sandia since August, 2012

Projects:

- **LAMMPS (molecular dynamics) code development:** Added and improved long-range electrostatic methods
- **Modeling of a dipolar fluid in an external electric field** (uses LAMMPS)
- **Advanced force field development (SNAP)** (uses LAMMPS, working to develop a quantum accurate SiO₂ force field)
- **Aleph (PIC-DSMC) code development:** Added an automatic mesh coarsening method for particle interactions (based on oct-tree algorithm)
- **Modeling of triggered vacuum gap switches**

Thanks to Paul Crozier for being a great mentor during my time at Sandia



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Importance of Algorithms

- Computing resources limited
- Gains in processor speed not as dramatic as before
- Increasing number of processors increases power consumption
- Better algorithms can save time and money
- Example: Fast Fourier transform (FFT) vs traditional discrete Fourier transform



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Introduction

- Hybrid particle-in-cell (PIC) and direct simulation Monte Carlo (DSMC) methods are frequently used to simulate low density interacting plasmas
- A single mesh is often used for both PIC and DSMC calculations
- The mesh size for PIC is often limited by the Debye length
- The collision cell size for DSMC is limited by the mean free path (can be much larger than the Debye length)
- Too few computational particles per DSMC collision cell can lead to errors
- Therefore, the optimal PIC mesh may be suboptimal for calculating DSMC collisions



Parts of this work were done in collaboration with Paul Crozier, Chris Moore, and Matt Bettencourt



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Overview of New Patching Method

- Use a fine mesh for PIC (unstructured)
- Use a rectangular grid to conglomerate many PIC elements into a single DSMC collision cell
- Size DSMC collision cells based on mean free path, λ_{mfp}
- Use oct-tree algorithm to adjust the size of DSMC collision cells on the fly

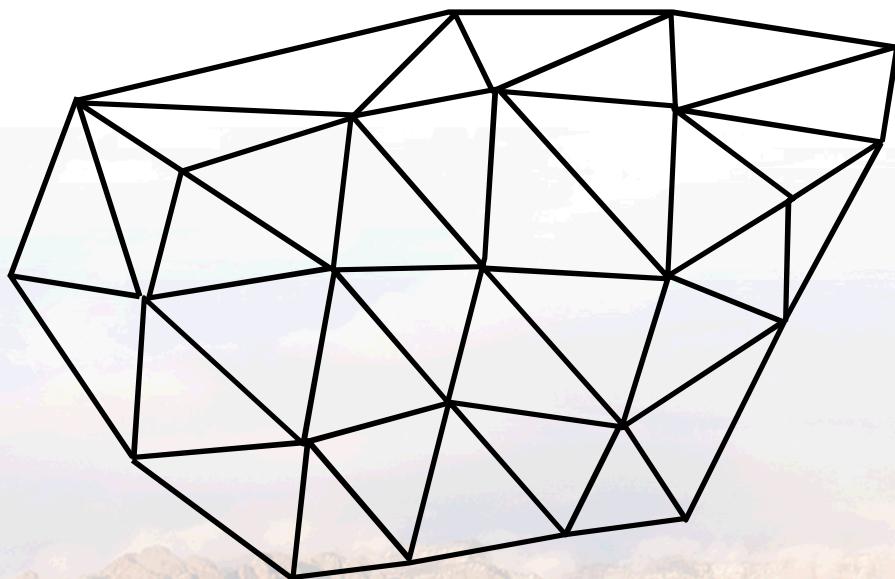


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Patch Method

- Original (unstructured) PIC mesh

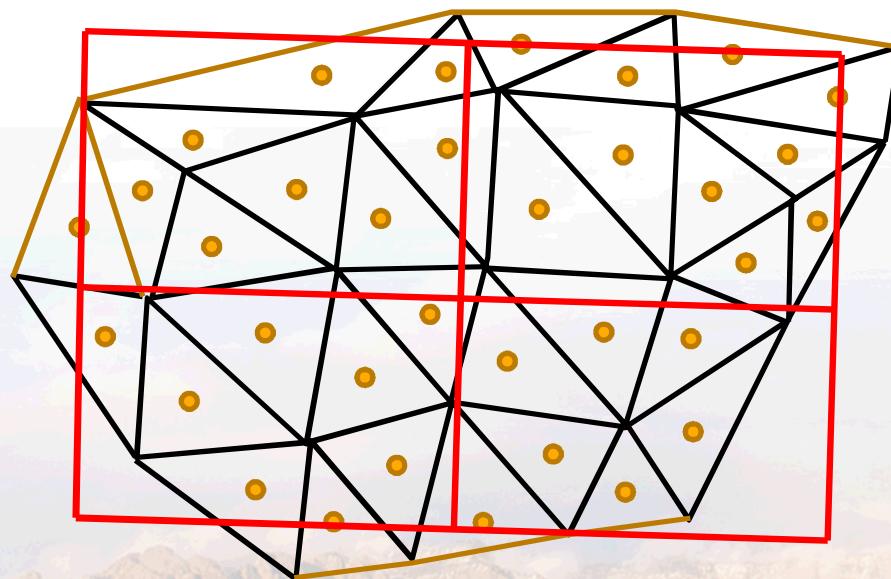


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Patch Method

- Apply rectilinear grid based on element centroid

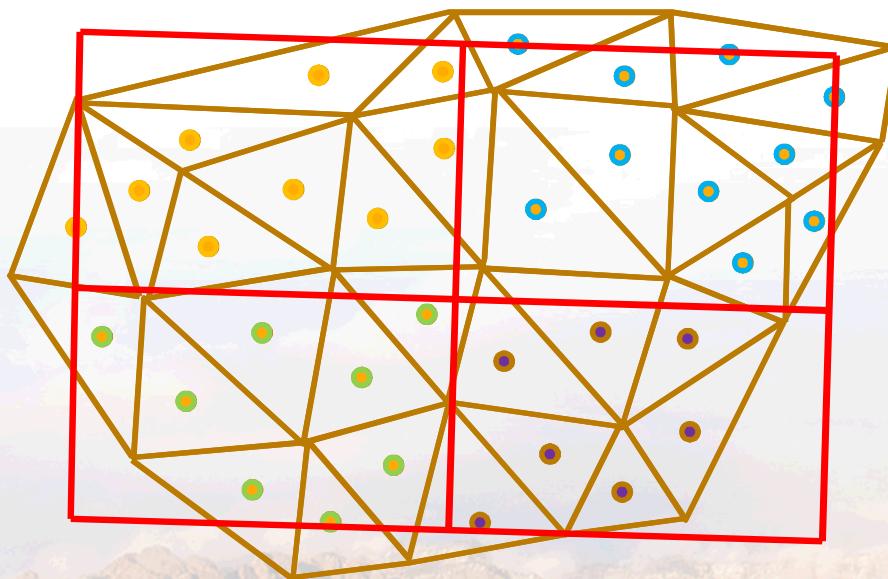


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Patch Method

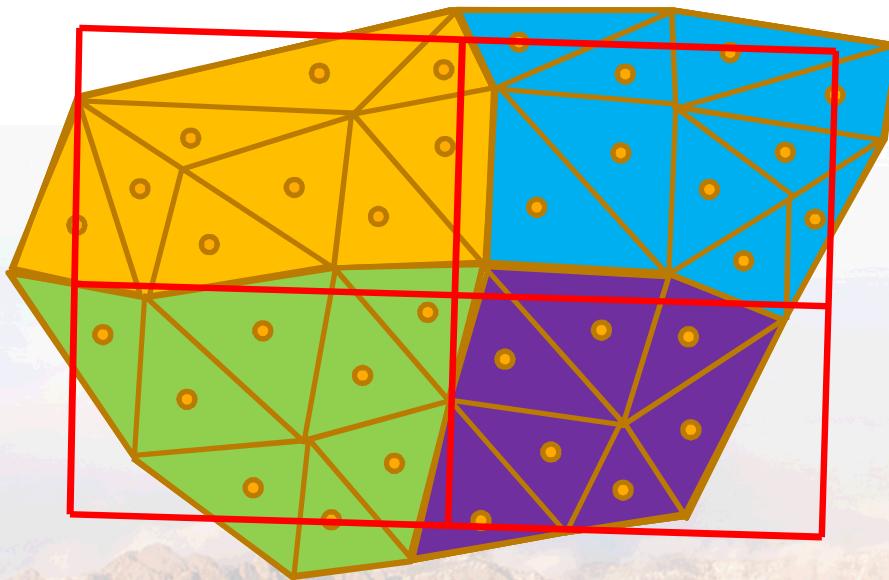
- Assign elements to patches (based on element centroid)



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Patch Method

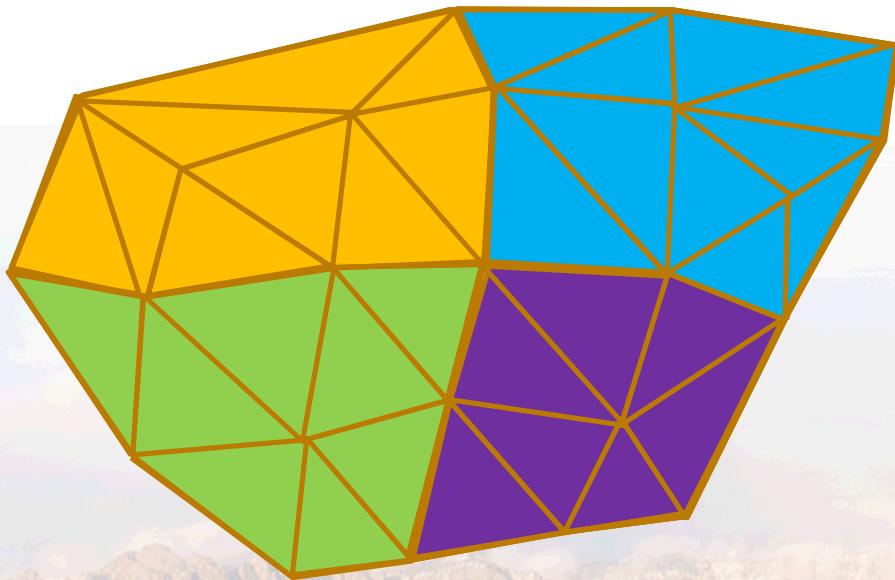


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Patch Method

- Patched mesh
- Use patches to compute DSMC collisions

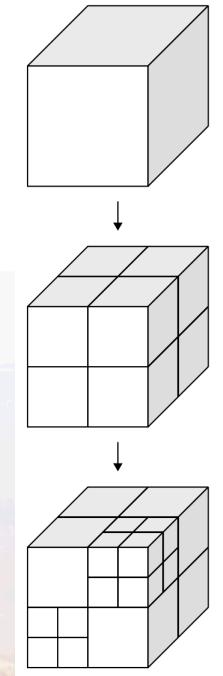
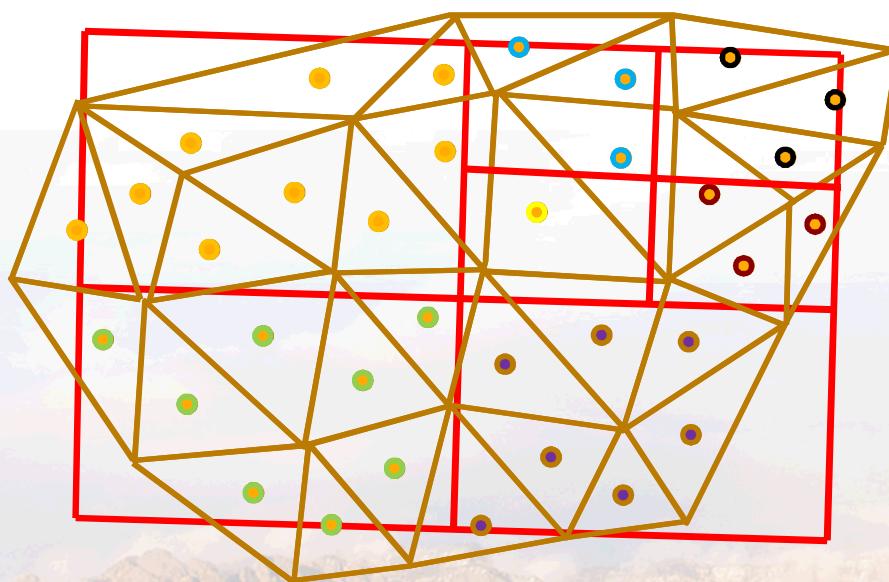


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Oct-tree Refinement

- Use oct-tree algorithm to refine mesh based on mean free path

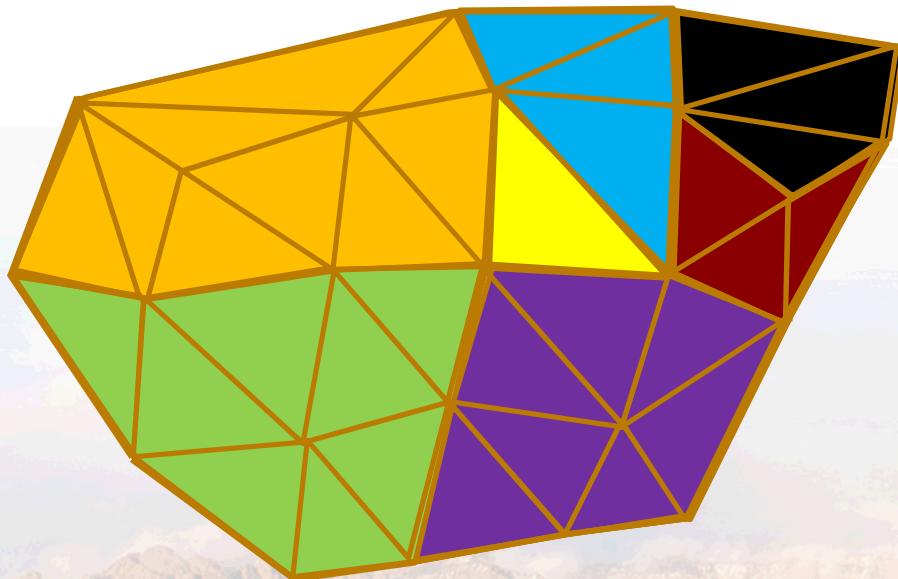


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Oct-tree Refinement

- Refined mesh



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Temporal Averaging

- Calculate λ_{mfp} for each element as:

$$\lambda_{\text{mfp}} = \frac{v}{Z} n$$

v = velocity
 Z = interaction frequency
 n = number of particles

- With a high computational particle weighting, temporal smoothing is needed. Can use either:

$$\langle \lambda_{\text{mfp}} \rangle = \left\langle \frac{v}{Z} n \right\rangle \quad \quad \quad \langle \lambda_{\text{mfp}} \rangle = \frac{\langle v \rangle}{\langle Z \rangle} \langle n \rangle$$

- Sometimes can get zero interactions in a timestep. With the first option, this leads to division by zero
- Found that the second option works much better



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Automatic Sizing of Patches

Patch size is dynamically adjusted based on the local mean free path λ_{mfp} :

1. **Compute λ_{mfp} for each interaction on an elemental basis (using all species)**
2. **For each interaction, average λ_{mfp} over elements in the oct-tree cell**
3. **Take the minimum of all the average λ_{mfp} and divide by 2, use this to size patches using the oct-tree algorithm**



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HI Test Problem

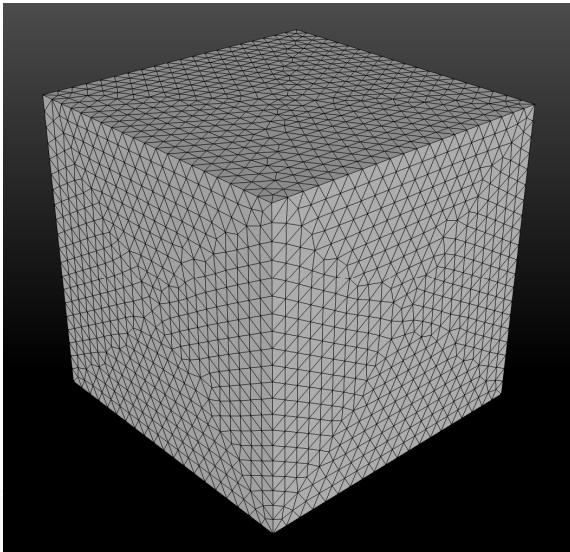
- Hydrogen iodide (HI) molecules interacting with elastic collisions
- Use variable hard sphere (VHS) interaction cross section
- $T = 594.6 \text{ K}$, $n = 10^{20} \text{ m}^{-3}$
- 3D cubic system, $L = 5 \text{ cm}$
- Analytic $\lambda_{\text{mfp}} = 3.67 \text{ cm}$
- $0.5 * \lambda_{\text{mfp}} \Rightarrow \text{minimum of 27 patches, but oct-tree on cube uses powers of 8} \Rightarrow 64 \text{ patches}$



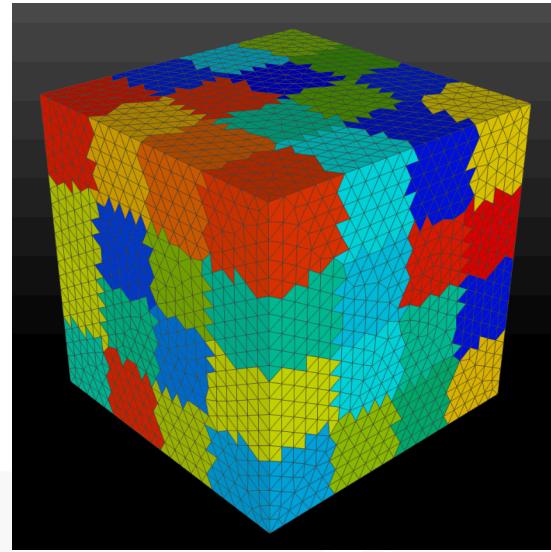
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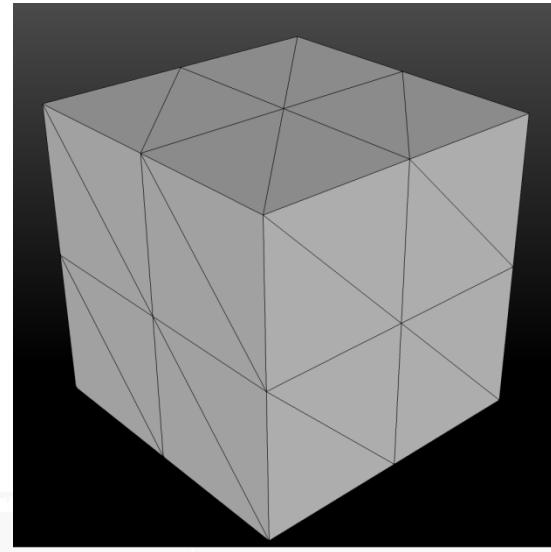
3 Meshes



fine mesh
56,557 elements
1,696,710 particles



patched mesh
64 patches
1,920 particles



coarse mesh
96 elements
2,880 particles

- **Adjust particle weighting → approximately 30 particles per element or patch**



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Accuracy Comparison

Ran each simulation for 3 hours ($\Delta t = 10^{-5}$ s) on one processor, repeated 6 times with a different random number seed

Average Collision Frequency:

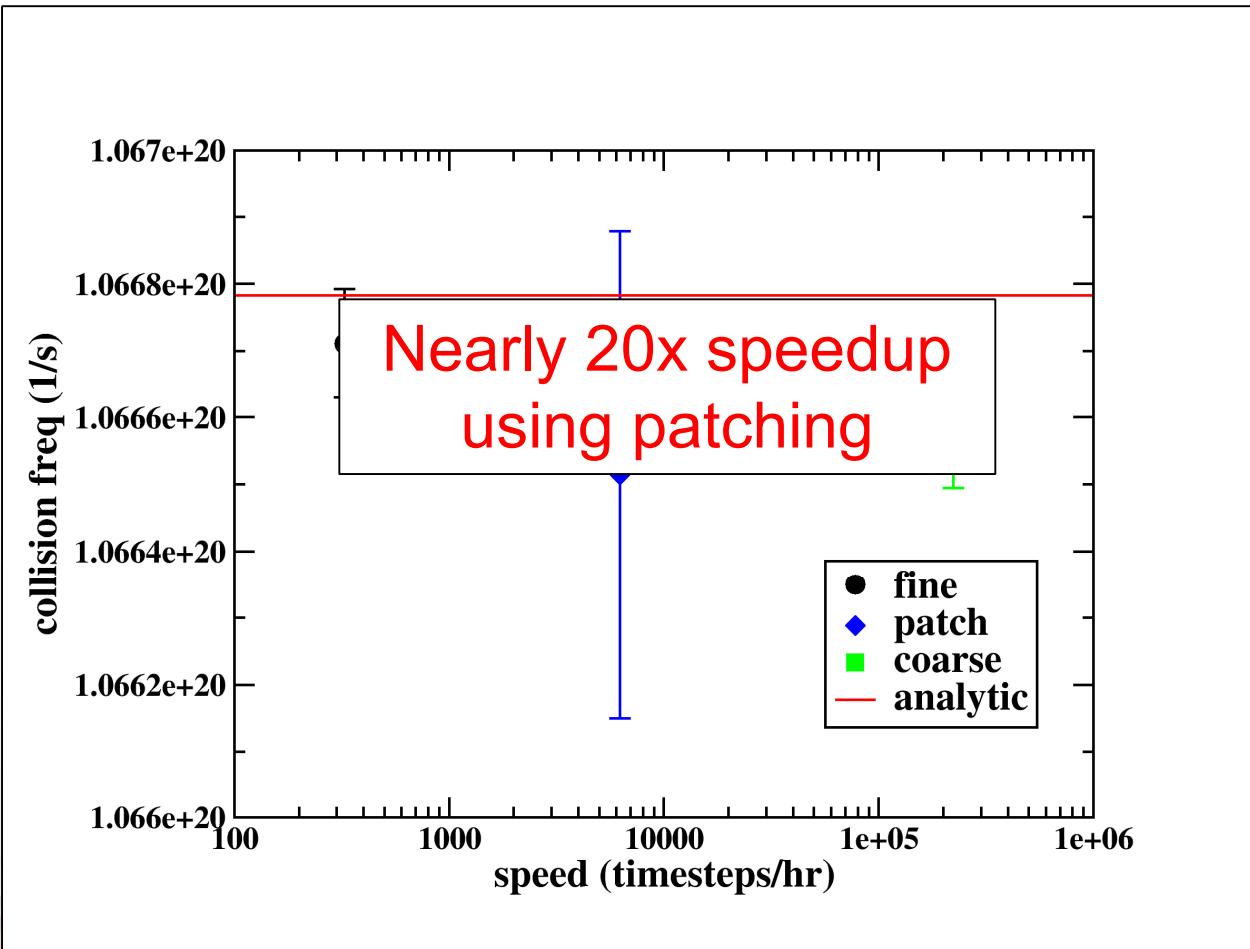
- $f_{\text{analytic}} = 1.0667 \cdot 10^{20} \text{ s}^{-1}$
- $f_{\text{fine}} = 1.0668 \cdot 10^{20} \text{ s}^{-1} \rightarrow 0.007\% \text{ relative error}$
- $f_{\text{patch}} = 1.0665 \cdot 10^{20} \text{ s}^{-1} \rightarrow 0.025\% \text{ relative error}$
- $f_{\text{coarse}} = 1.0666 \cdot 10^{20} \text{ s}^{-1} \rightarrow 0.021\% \text{ relative error}$



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Results for the HI Test Problem

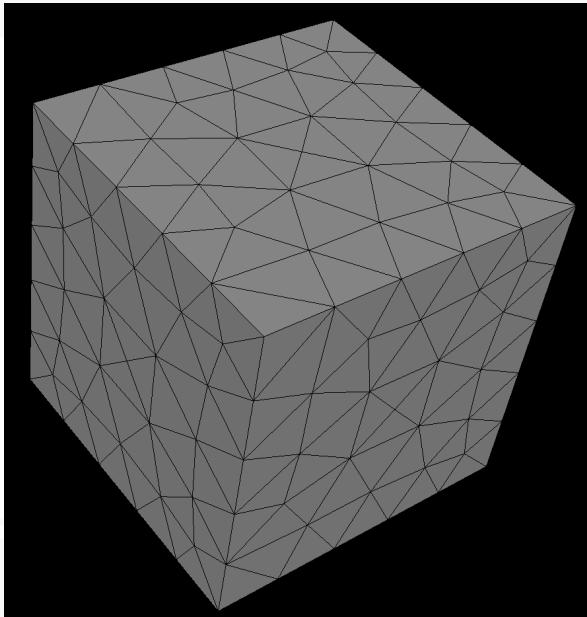
- Error bars represent 95% confidence intervals



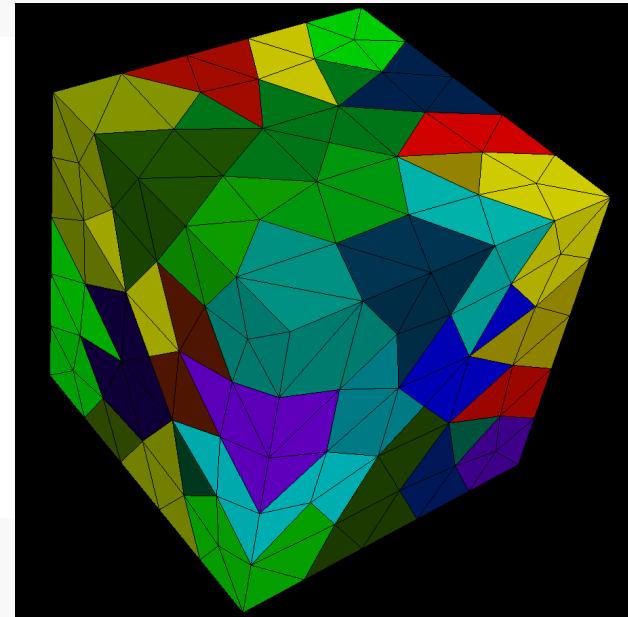
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Another 2 Meshes



fine mesh
1,184 elements
1,223 particles



patched mesh
64 patches
1,223 particles

- Same HI test problem (ran for 2000 timesteps)
- Patched mesh runs nearly **4x** faster (with virtually the same accuracy)
- Global average (0D problem) may hide errors



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1D Inelastic Collision Problem



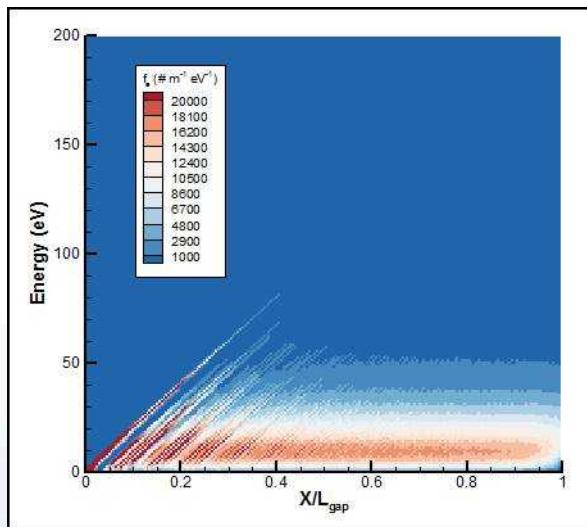
- Electrons gain energy due to the field
- Electrons lose energy due to inelastic collisions with N_2 particles (fixed in space)
- Vary N_2 particle weight so that there are approximately:
 1. 10 computational particles per cell
 2. 0.1 computational particles per cell
- About 10 λ_{mfp} across the gap



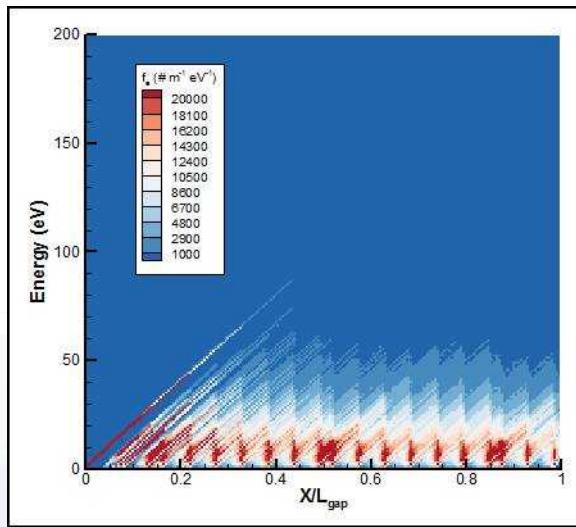
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Electron Energy Distribution Function (EEDF)

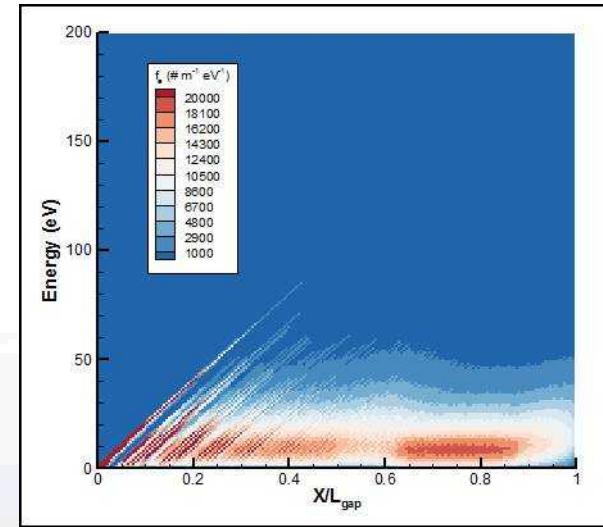
10 N₂ particles per cell



0.1 N₂ particles per cell



0.1 N₂ particles per cell with patching



- Using patching gives a more realistic EEDF (crucial for simulating accurate breakdown voltages)
- Patching allows one to use fewer N₂ particles

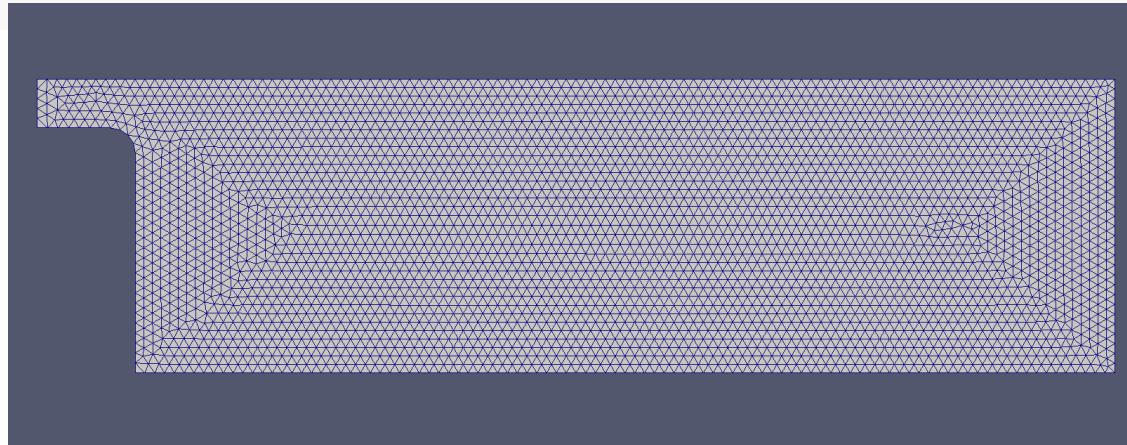


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2D Vacuum Gap Breakdown

Anode
350 V



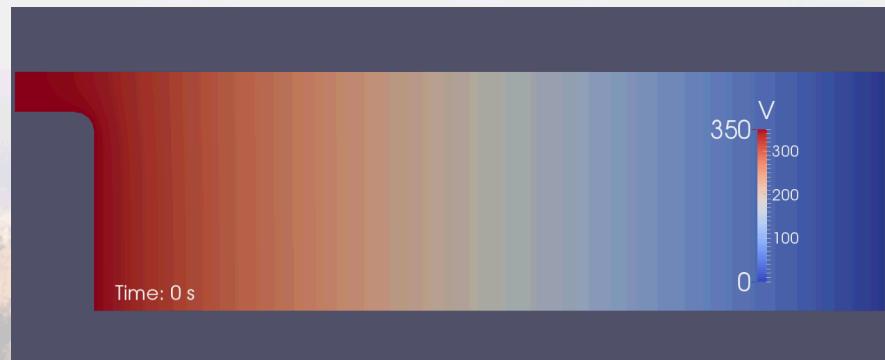
Cathode
0 V

- Air injected at high velocity and high temperature from the anode
- Low density electrons injected from the cathode
- Air ionizes and eventually will form plasma and break the gap



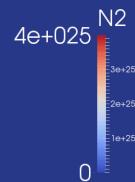
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Species Densities (m^{-3})



Dynamic Sizing of DSMC Collision Cells

Time: 0 s



Time: 0 s

Time: 0 s

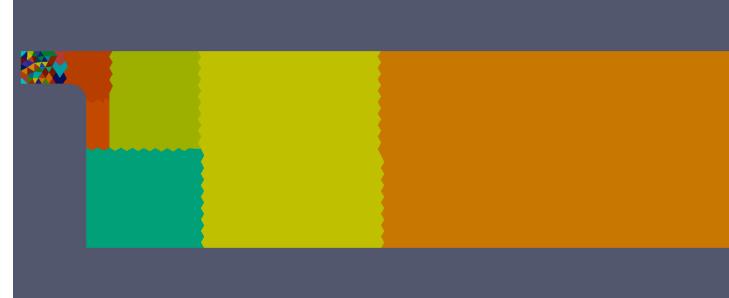


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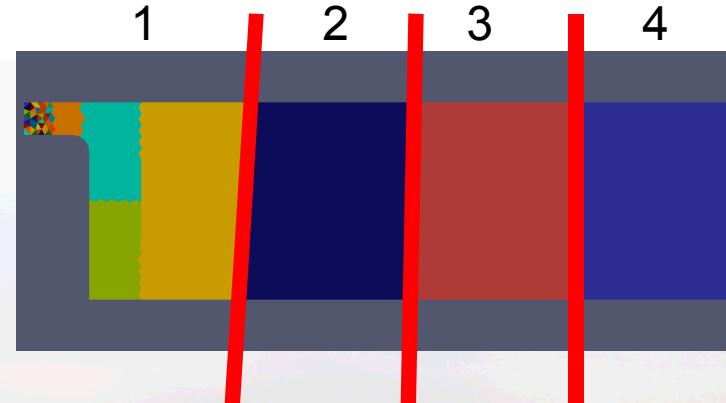
Parallelization

- Currently each processor uses an independent oct-tree (simple):

1 processor:



4 processors:



- Issue: can lead to narrow/small cells (can happen with 1 proc too)
- In the future, could use a more robust method like inter-processor communication with ghosting, load balancing, etc.



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Conclusions

- Developed a new method (patching) to enhance hybrid PIC-DSMC simulations
- Using fewer particles with patching gives similar accuracy and uncertainty as using a fine mesh with many particles
- Allows one to dramatically speed up the simulation if the PIC mesh is too small for DSMC collisions
- Allows one to dynamically adjust the size of DSMC collision cells on the fly (based on mean free path)



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Sandia Projects

- Been at Sandia since August, 2012

Projects:

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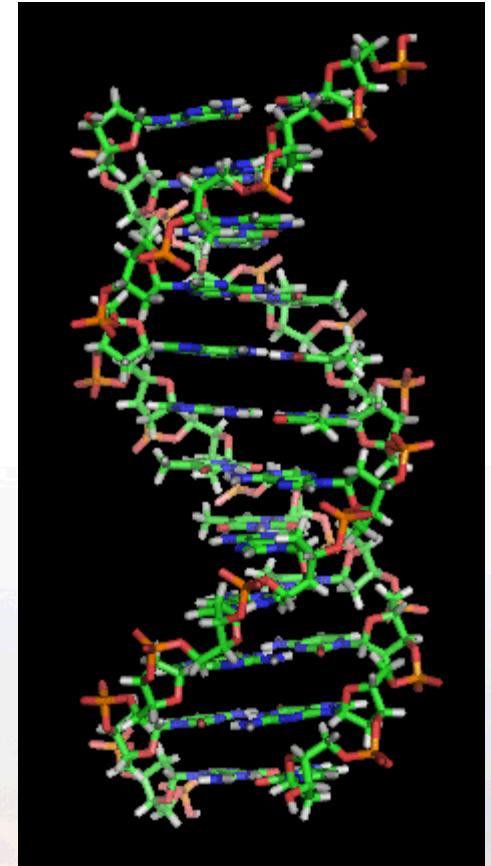
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Why do we care about LRE?

LRE = long-range electrostatics

- Electrostatics are extremely important in many atom-level (and coarser) models.
- Long-range part usually cannot be neglected in molecular simulations (simple cutoff can lead to artifacts).
- Large fraction of compute cycles are used in LRE calculations.
- LRE calculations represent a scaling bottleneck in many MD calculations.



Parts of the LAMMPS long-range electrostatic work were done in collaboration with Paul Crozier, Steve Plimpton, and Stephen Bond

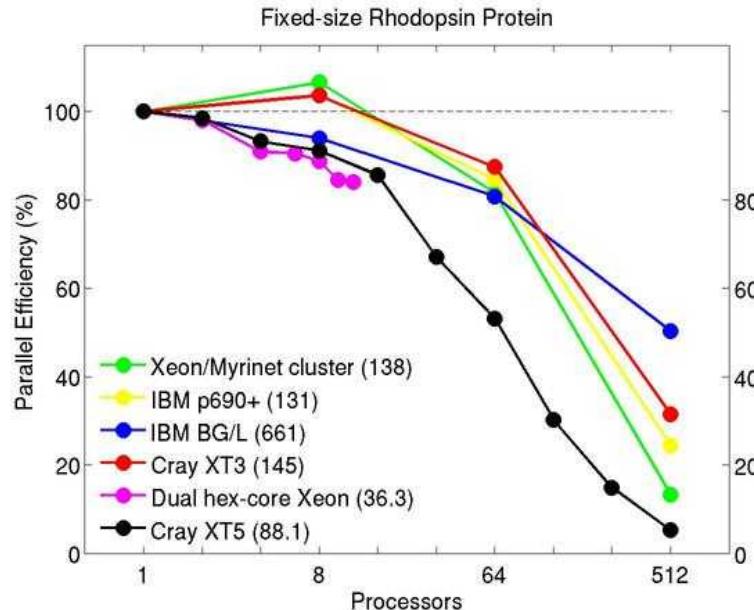


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The motivation: FFTs don't scale very well

(and HPC core counts are growing quickly)

- LAMMPS originally had two methods for computing long-range electrostatics: Ewald and particle-particle/particle-mesh (PPPM)
- Ewald summation is fastest for small systems (or very high accuracy), but expensive for large systems
- PPPM relies on FFTs, which don't scale well on many processors:



<http://lammps.sandia.gov/bench/rhodo.fixed.jpg>



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Multilevel-summation method (MSM) background

- Multi-grid method (but not iterative); split potential and approximate the slowly varying part on a hierarchy of grids
- No FFTs are required, so the communication cost of MSM is expected to scale better than PPPM on large core counts
- PPPM scales with number of atoms as $O(N \log N)$ while MSM scales as $O(N)$
- MSM may be faster for large problems running on large core counts

D. J. Hardy, Ph.D. thesis, University of Illinois at Urbana-Champaign (2006).

D. J. Hardy, J. E. Stone, and K. Schulten, Parallel Comput. **35**, 164 (2009).



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MSM Algorithm pieces

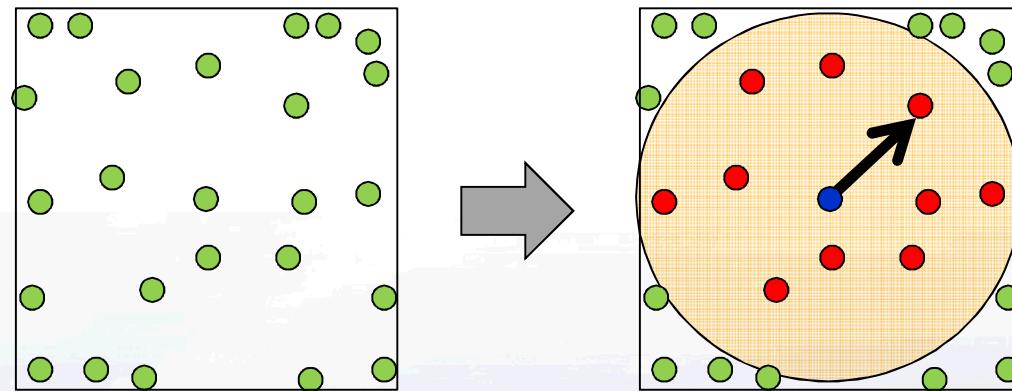
1. Short-range part
2. Anterpolation
3. Direct sum
4. Restriction
5. Prolongation
6. Interpolation



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Algorithm pieces

1. Short-range part
2. Anterpolation
3. Direct sum
4. Restriction
5. Prolongation
6. Interpolation



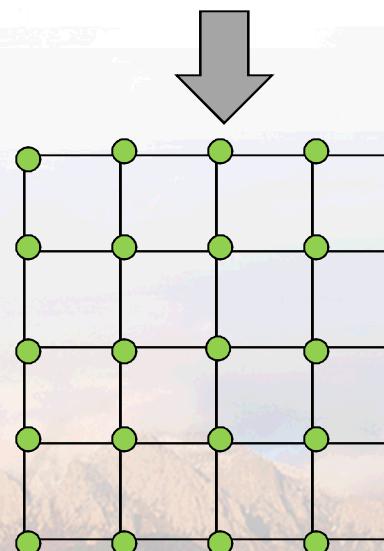
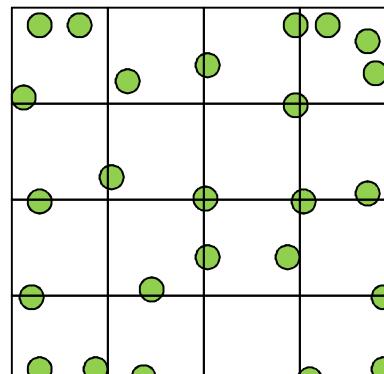
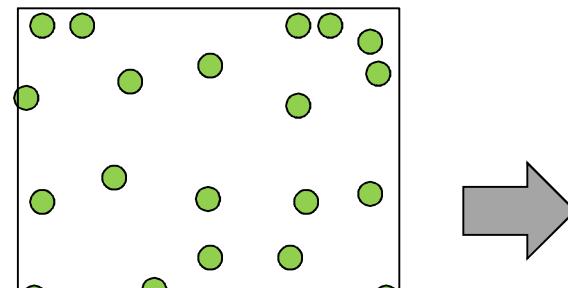
Particles interact within a spherical cutoff to get short-range forces, energy, and pressure



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Algorithm pieces

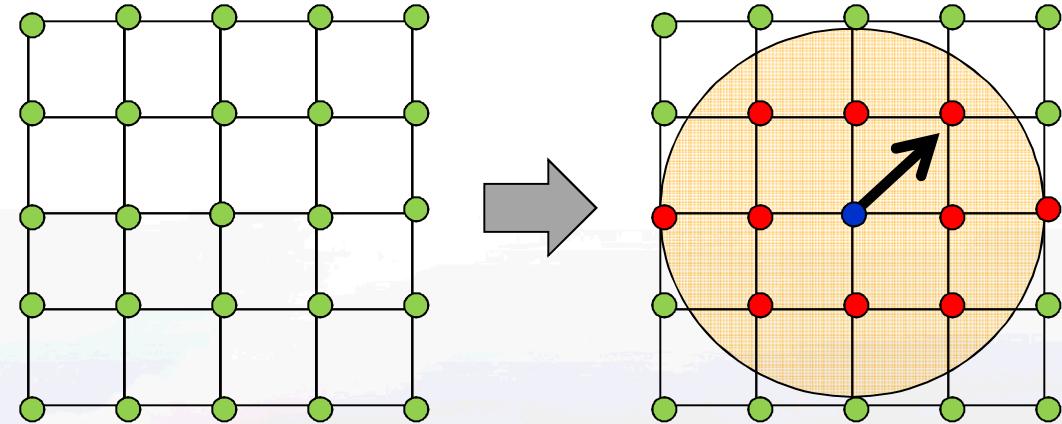
1. Short-range part
2. **Interpolation**
3. Direct sum
4. Restriction
5. Prolongation
6. Interpolation



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Algorithm pieces

1. Short-range part
2. Interpolation
3. **Direct sum**
4. Restriction
5. Prolongation
6. Interpolation



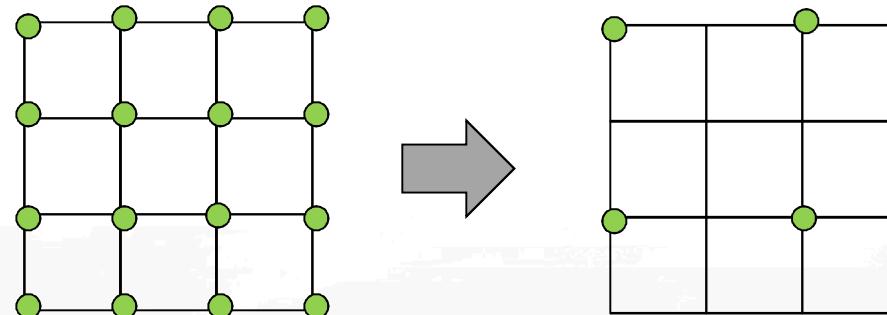
Mesh points interact within a spherical cutoff to get long-range electric field, energy, and pressure



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Algorithm pieces

1. Short-range part
2. Anterpolation
3. Direct sum
4. **Restriction**
5. Prolongation
6. Interpolation



Interpolate charge from finer mesh to coarser mesh

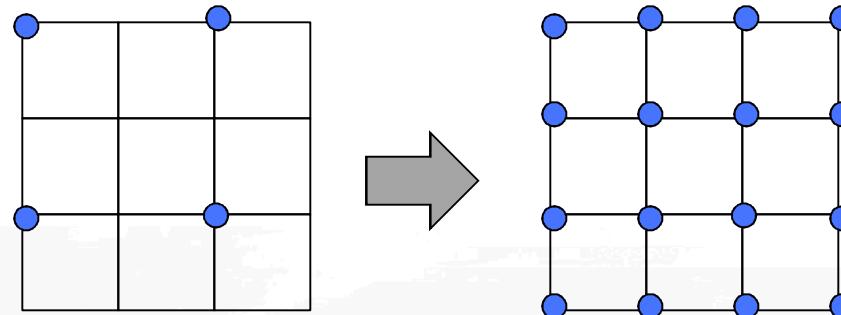
Repeat steps 3 and 4 until finished on coarsest mesh



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Algorithm pieces

1. Short-range part
2. Anterpolation
3. Direct sum
4. Restriction
5. **Prolongation**
6. Interpolation



Interpolate electric field from coarser mesh to finer mesh

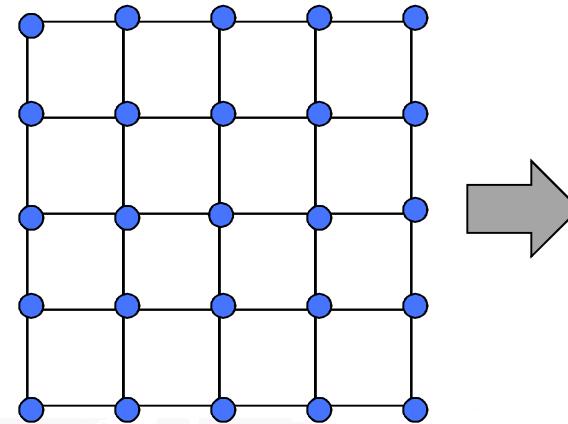
Repeat step 5 until the finest mesh is reached



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Algorithm pieces

1. Short-range part
2. Interpolation
3. Direct sum
4. Restriction
5. Prolongation
6. **Interpolation**



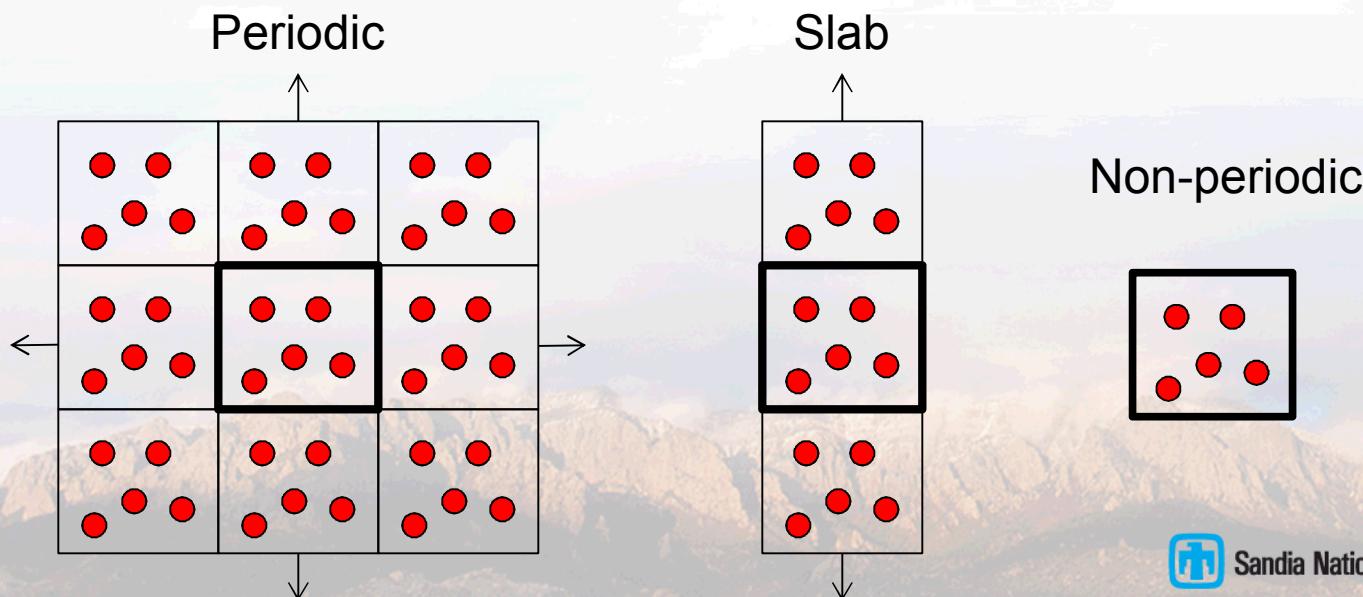
Compute force from electric field on finest mesh and back-interpolate force from mesh to atoms



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Non-Periodic BCs

- MSM works for both periodic and non-periodic boundary conditions
- Ewald and PPPM only work for periodic or slab (periodic in x and y and non-periodic in z) boundary conditions

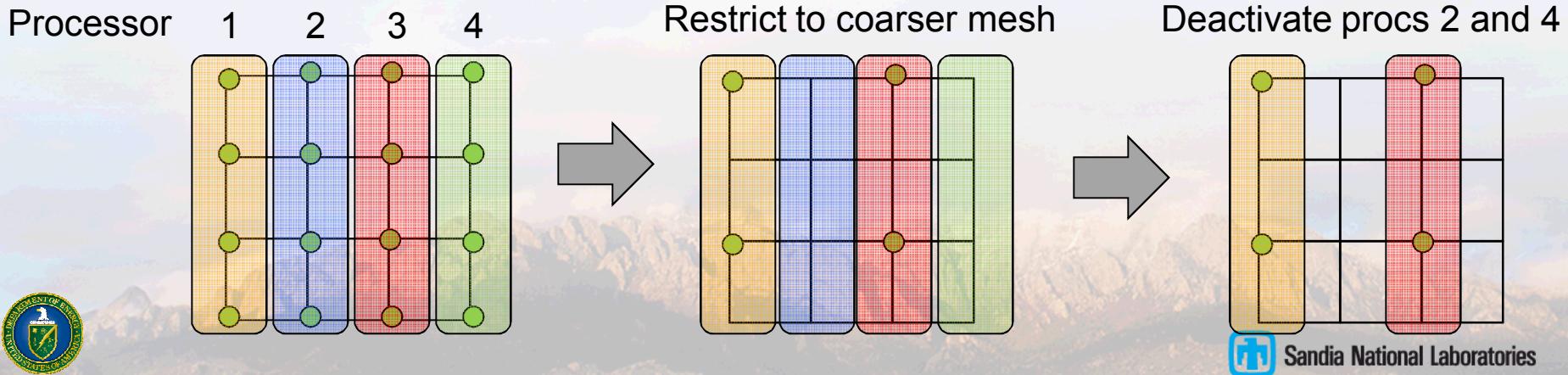


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Parallelization Strategy

- **Challenge: lots of work on finest grid, very little work on coarsest grid**
- **Use same domain-decomposition layout on all levels (simple)**
- **Inactive processors don't participate in MPI communication routines**
- **Use neighbor point-to-point communication for fine grids**
- **Use MPI AllReduce for coarse grids**





Enhancements to MSM

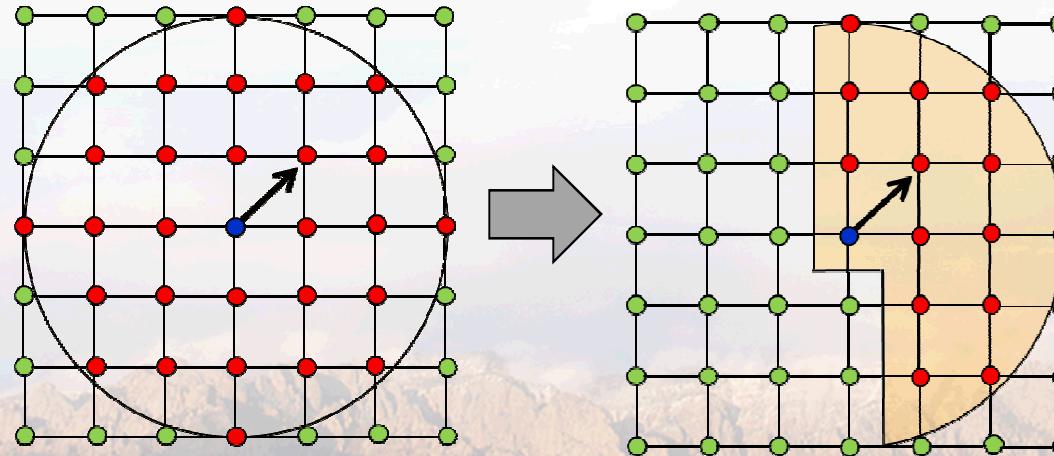
- Error estimator (important for comparing to other methods like PPPM)
- Pressure calculation
- Added heuristic to estimate optimal parameters, including automatic adjustment of Coulombic cutoff (based on work by Hardy)
- Per-atom energy/virial
- Fast scalar pressure
- OMP threaded version of MSM (Axel Kohlmeyer)



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Improving Single-Core Performance

- Use hemisphere (instead of full sphere) for direct sum interactions to avoid double computations
- Using a hemisphere can also (sometimes) reduce the amount of communication needed
- Added various other code optimizations
- Compared to Hardy's NAMD-lite code, LAMMPS MSM was 60% faster for periodic and 25% faster for non-periodic (1 processor, two point-charges in a box, order 4)



[David J. Hardy, *NAMD-Lite*, <http://www.ks.uiuc.edu/Development/MDTools/namdlite/>,
University of Illinois at Urbana-Champaign, 2007.]



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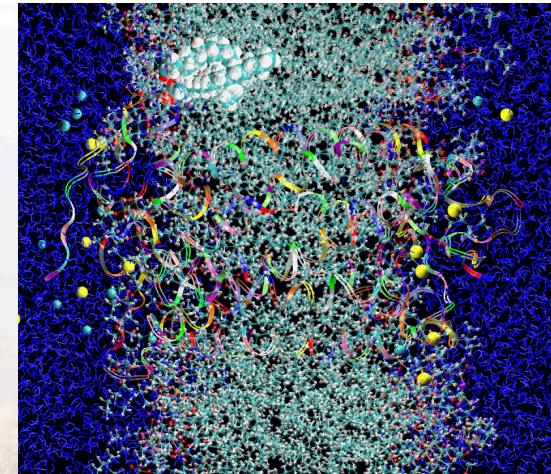
Fast (Scalar) Pressure Calculation

- Calculation of the 6-component pressure tensor is expensive with MSM (increases cost by ~2x)
- Often only scalar pressure [i.e. $1/3*(P_{xx} + P_{yy} + P_{zz})$] is needed
- For Coulombic systems, can use a virial “trick” to relate energy to scalar pressure (much cheaper)
- For SPC/E system, reduces overall cost by 20% (short-range part has some overhead)
- Can use scalar pressure to run isotropic barostat



LRE speed and scalability tests

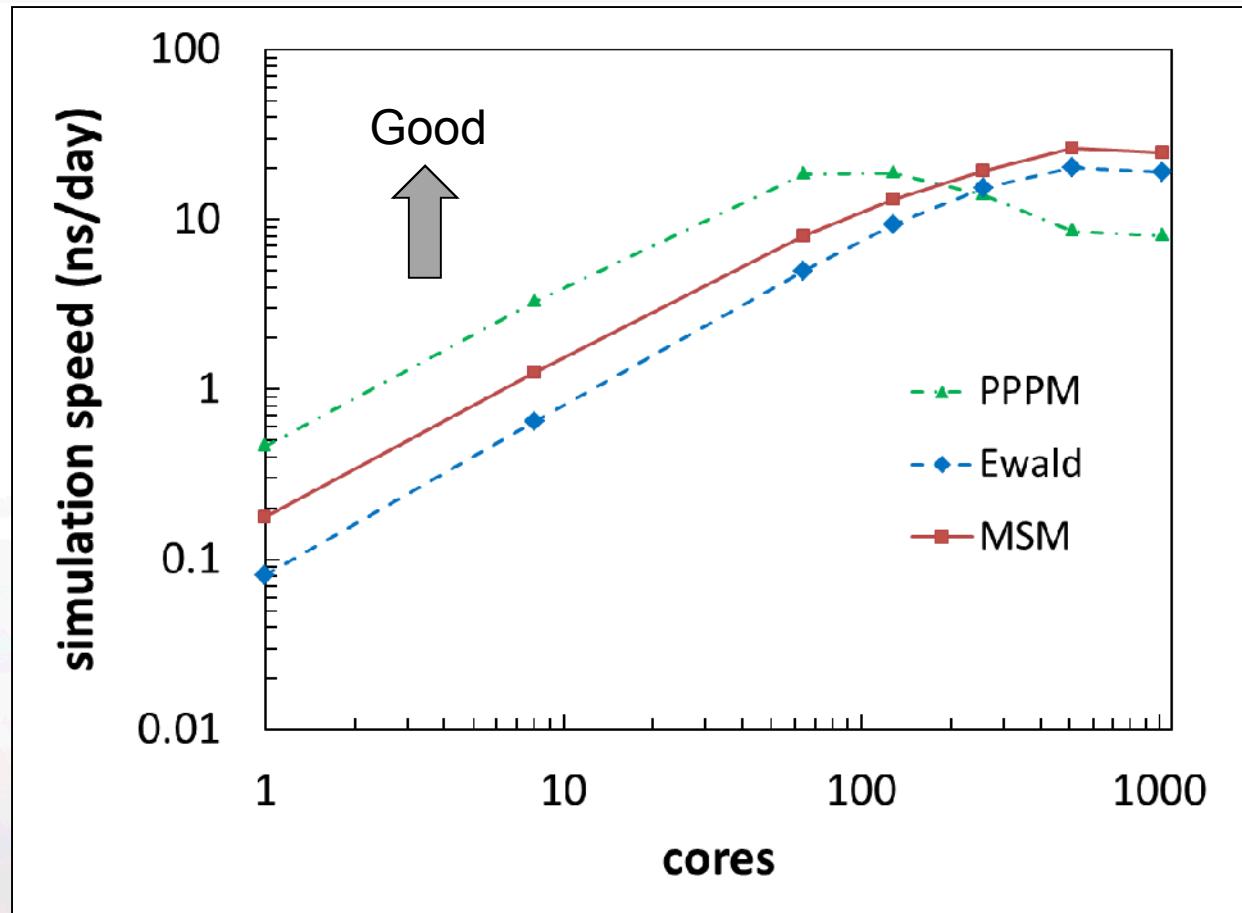
<u>Chama</u>	<u>Redsky</u>	<u>Rhodopsin benchmark</u>
• Sandy-Bridge (2.6 GHz)	• Nehalem (2.93 GHz)	• NVT dynamics
• 2012	• 2009	• 1e-4 relative accuracy
• 16 cores/node	• 8 cores/node	• 32k atoms, replicable
• 1,232 nodes	• 2,816 nodes	• 2 fs timestep size
• 19,712 cores	• 22,528 cores	
• Infiniband 4X QDR, Fat Tree, Qlogic	• Infiniband 4X QDR, 3D Torus, Mellanox	



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Redsky, 32k atoms, 10^{-4} accuracy

- PPPM is fastest at low core count
- MSM is fastest at high core count
- MSM scales better than PPPM since it doesn't rely on FFTs
- Maxes out at 26 ns/day



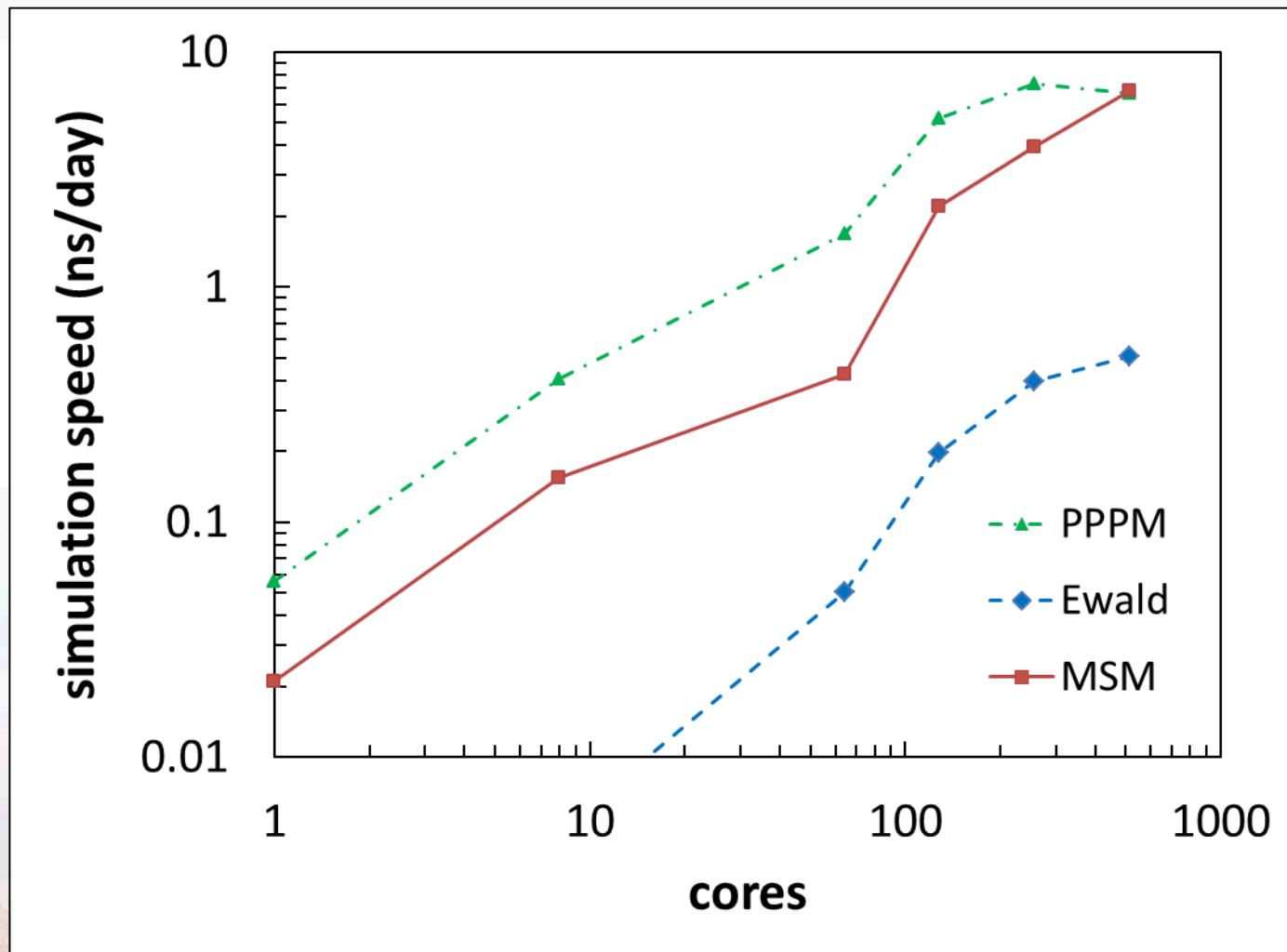
10 Angstrom cutoff, default parameters, MSM order 10



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Redsky, 256k atoms, 10^{-4} accuracy

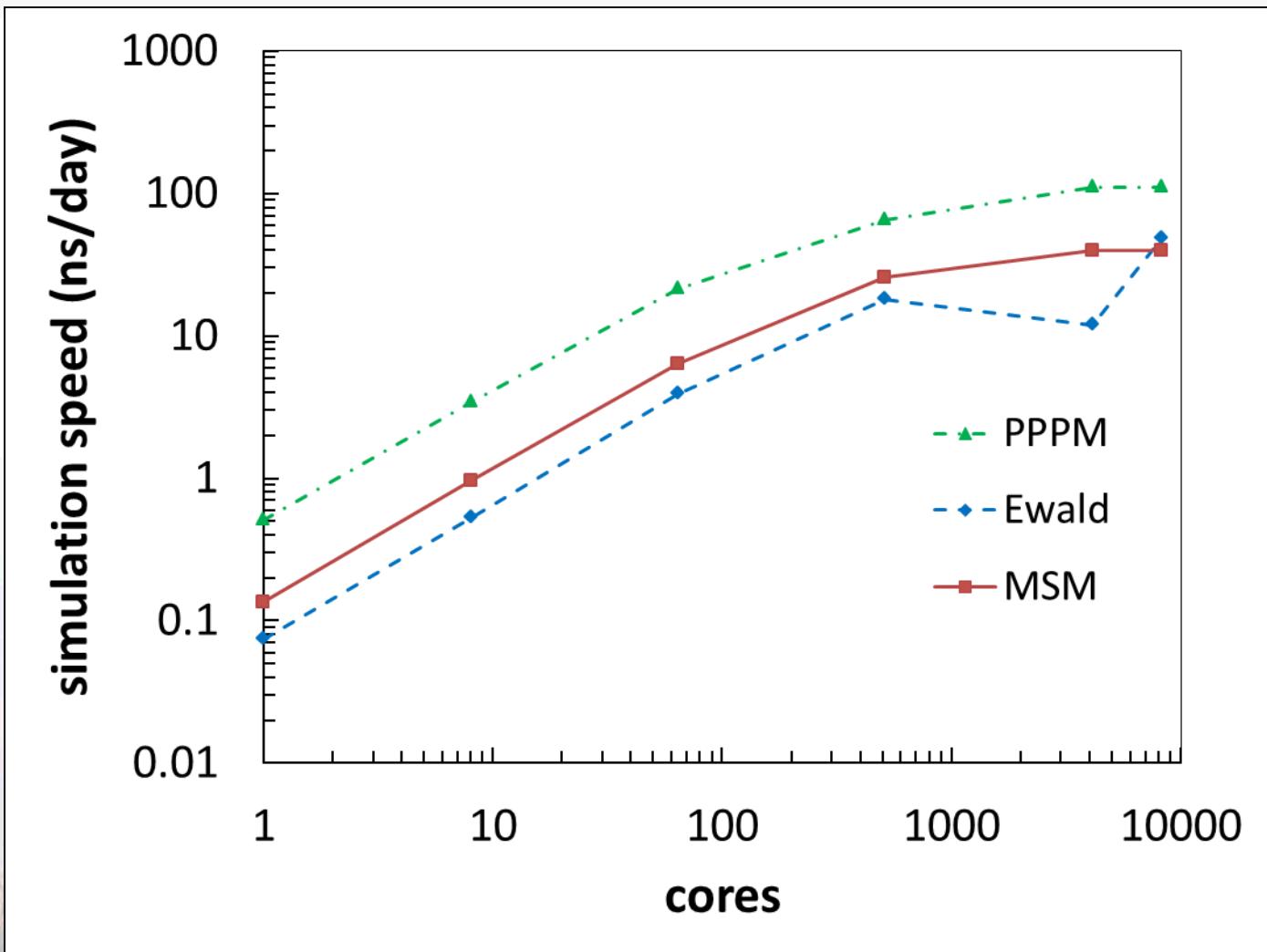
- 8x as many atoms as before
- Ewald chokes
- PPPM FFT bottleneck pushed out to larger core count
- Scaling: MSM $O(N)$, PPPM $O(N \log(N))$, Ewald $O(N^{1.5})$



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Chama, 32k atoms, 10^{-4} accuracy

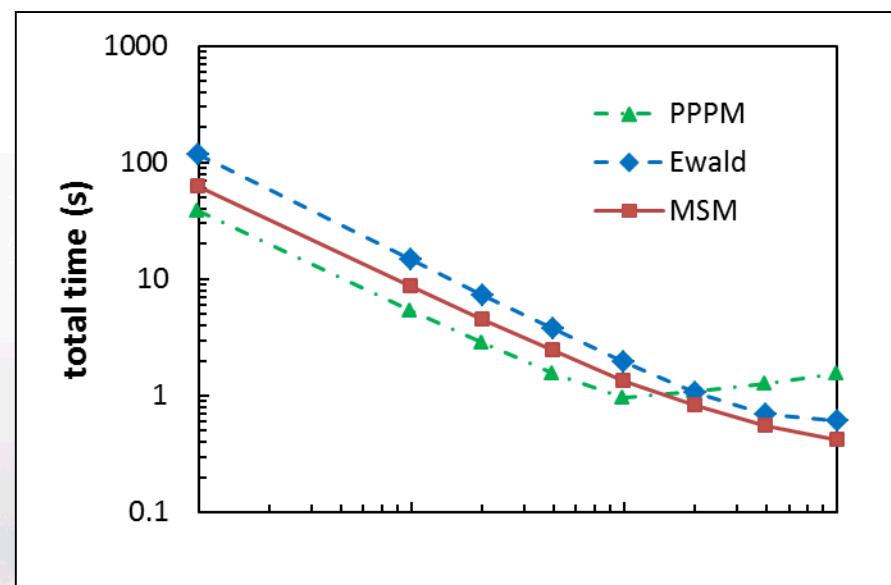
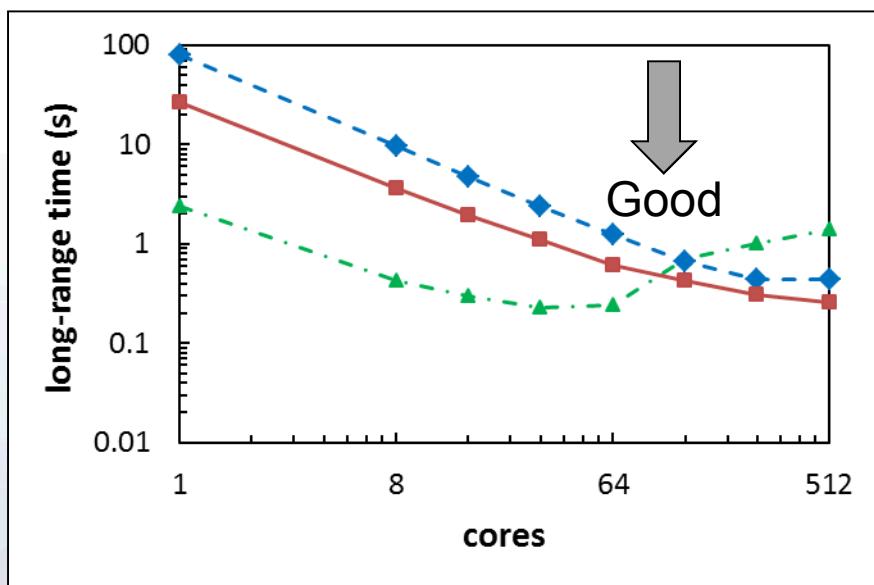
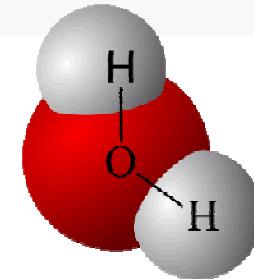
- Chama gives better overall performance
- PPPM wins, but we can't expect more scaling
- Maxes at 110 ns/day



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SPC/E Water Benchmark

- 36,000 atoms (strong scaling on Redsky)
- NVT, pressure computed every 50 timesteps
- 1e-3 accuracy

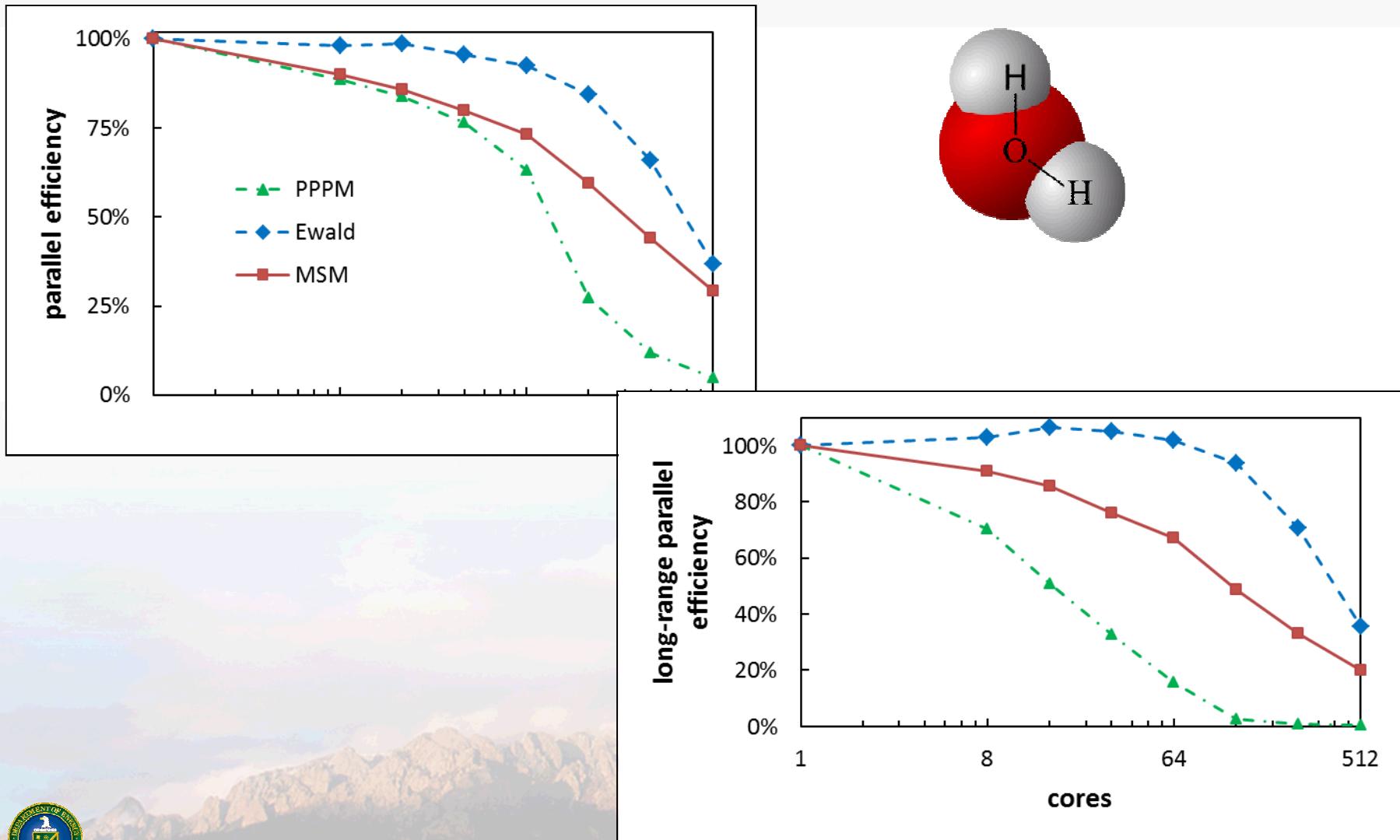


10 Angstrom cutoff, default parameters, MSM order 8



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SPC/E Water Benchmark



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Other Enhancements to LRE in LAMMPS

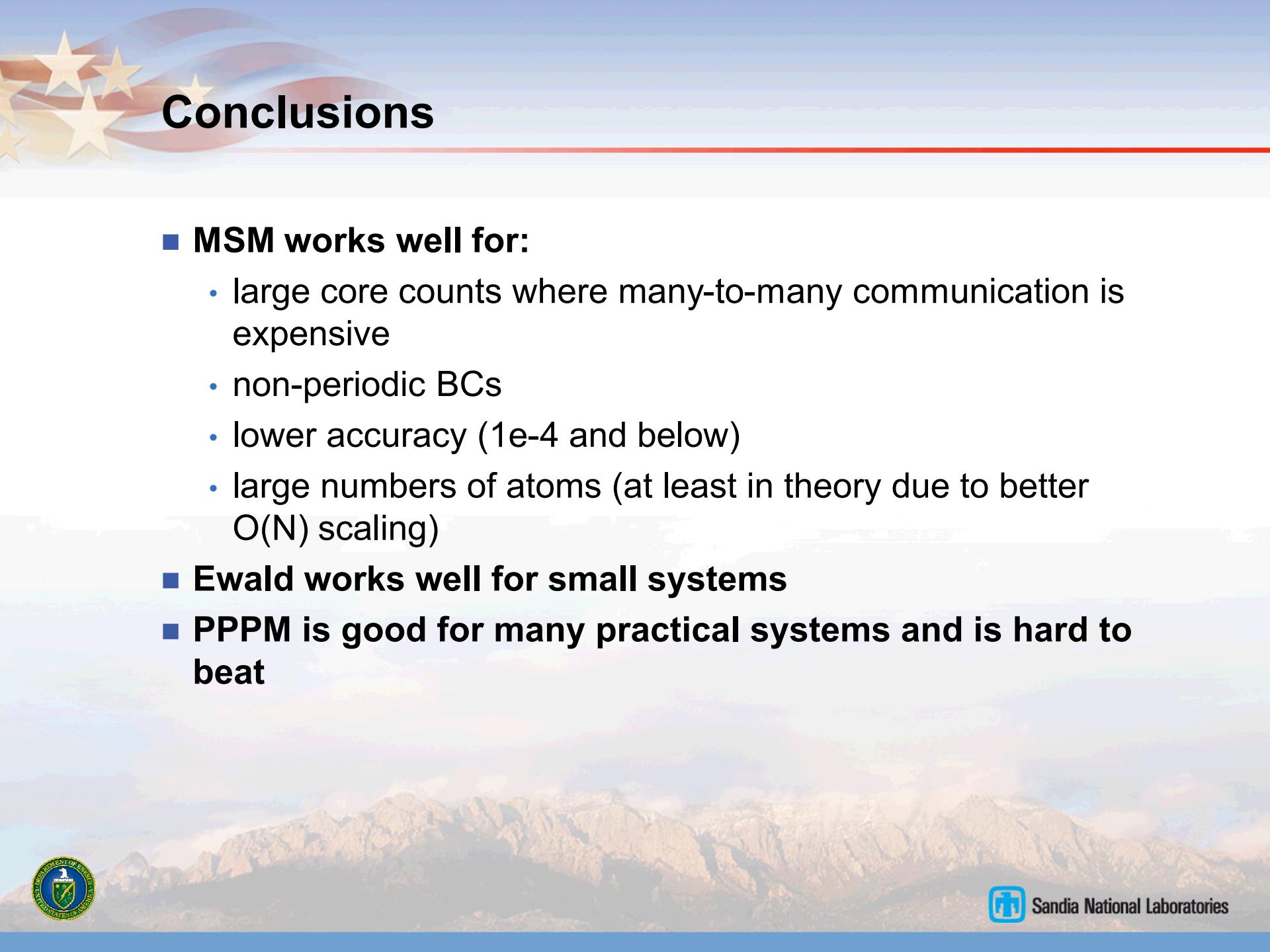
- Per-atom energy/virial for kspace
- Compute group/group for PPPM and Ewald
- Triclinic for kspace
- Ewald/disp for point-dipoles
- Staggered PPPM (up to 4x faster for high accuracy)

Good for PPPM on large core counts:

- Fix verlet/split
- 2 FFT PPPM



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Conclusions

- **MSM works well for:**
 - large core counts where many-to-many communication is expensive
 - non-periodic BCs
 - lower accuracy (1e-4 and below)
 - large numbers of atoms (at least in theory due to better $O(N)$ scaling)
- **Ewald works well for small systems**
- **PPPM is good for many practical systems and is hard to beat**



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Thank You

Questions or Comments?



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