

# Intrepid Functionality for Parvis

Kara Peterson <sup>1</sup>

Pavel Bochev<sup>1</sup>

Denis Ridzal<sup>2</sup>

<sup>1</sup>Numerical Analysis & Applications

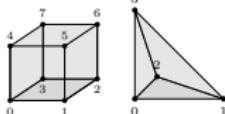
<sup>2</sup>Optimization & Uncertainty Quantification  
Sandia National Labs

Parvis Meeting  
April 11, 2011

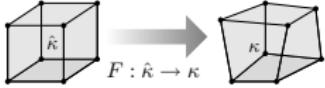
# Intrepid Functionality

## Cell Geometry

- Topology from Shards (line, tri, quad, hex, hex, tet, wedge)



- Maps to and from reference cells



- Jacobians ( $DF, J = \det(DF)$ )
- Surface normals, line tangents, cell areas
- Tests for point inclusion

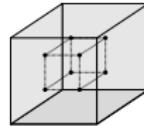
## Discrete Spaces and Operators

- Nodal, edge, and face basis functions ( $\phi_i$ )
- Discrete differential operators ( $\nabla \phi_i, \nabla \times \phi_i, \nabla \cdot \phi_i, D^k \phi_i$ )

$$f^h(x) = \sum_{i=1}^N f_i \phi_i(x)$$

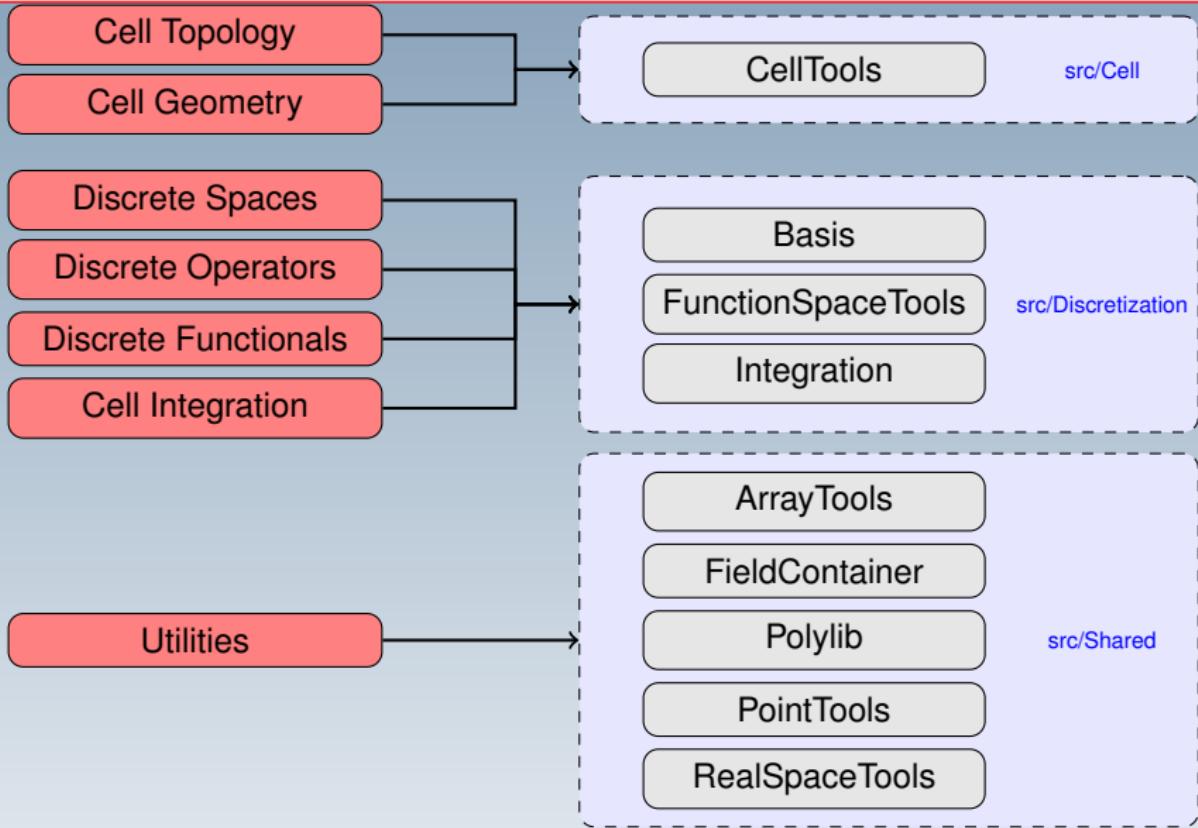
## Integration

- Cubature points ( $x_p$ ) and weights ( $w_p$ )





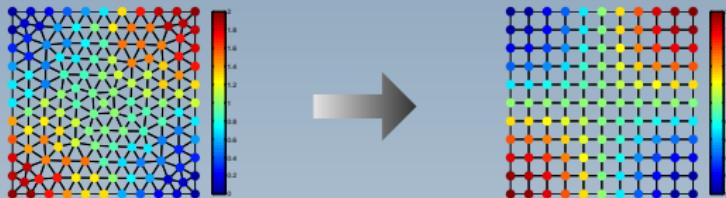
# Mapping Functionality to Software





# Example: linint2

**linint2**: Interpolate from one grid to another grid using bilinear interpolation



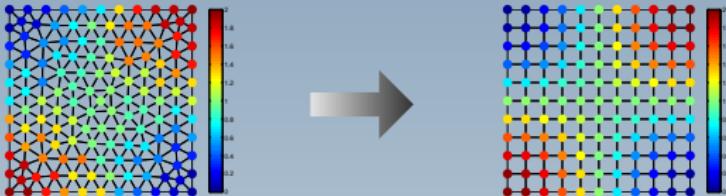
$$f(\mathbf{x}) = 1 + \sin(\pi x) \sin(\pi y)$$

- Read mesh with MOAB and store connectivity
- Define cell topology
- Locate quadrilateral grid nodes ( $\mathbf{x}_p$ ) on triangle mesh
- For each point in triangle grid cell
  - Evaluate basis at point in reference cell,  $\hat{\phi}_i(\hat{\mathbf{x}}_p)$
  - Transform basis values to physical space,  $\hat{\phi}_i \rightarrow \phi_i$
  - Evaluate function at point in physical space  $f^h(\mathbf{x}_p) = \sum_{i=1}^N f_i \phi_i(\mathbf{x}_p)$



# Example: linint2

**linint2**: Interpolate from one grid to another grid using bilinear interpolation



```
// Get cell topology for base triangle
ShardsCellTopology cellType(shards::getCellTopologyData<shards::Triangle<3> >() );

// Loop over elements in triangle grid
for (moab::Range::iterator it = elems.begin(); it != elems.end(); ++it) {

    // Loop over nodes in quadrilateral grid
    for (int ipt=0; ipt<numNodesQuad; ++ipt) {

        // Coordinates of point in physical space
        FieldContainer<double> physPoints(1, spaceDim);
        physPoints(0,0)= quadPoints(ipt, 0);
        physPoints(0,1)= quadPoints(ipt, 1);

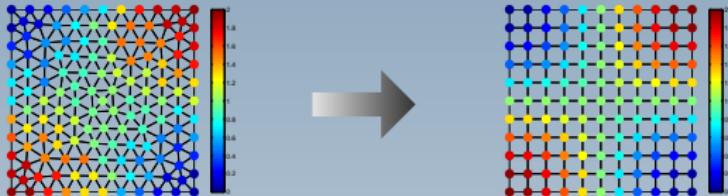
        // Define point in reference cell where basis is evaluated
        FieldContainer<double> refPoints (1, spaceDim);
        IntrepidCTools::mapToReferenceFrame(refPoints, physPoints, cellWorkset,
                                             cellType, 0);

        // check whether point is in cell
        double points[2] = {physPoints(0,0), physPoints(0,1)};
        int inCell = IntrepidCTools::checkPointInclusion(points, spaceDim, cellType);
    }
}
```



# Example: linint2

**linint2**: Interpolate from one grid to another grid using bilinear interpolation

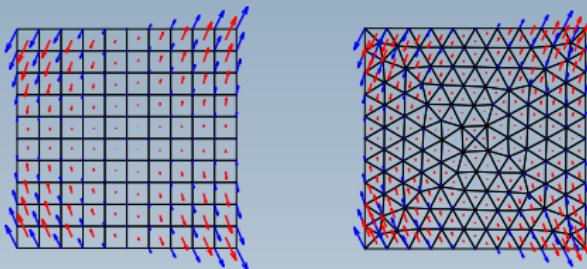


```
if (inCell > 0) {  
    // Define basis  
    Intrepid::Basis_HGRAD_TRI_C1_FEM<double, FieldContainer<double> > interpBasis;  
    int numFields = interpBasis.getCardinality();  
    FieldContainer<double> refBasisValues(numFields, 1);  
  
    // Evaluate basis values at points in reference space  
    interpBasis.getValues(refBasisValues, refPoints, OPERATOR_VALUE);  
  
    // Containers for basis values transformed to physical space  
    FieldContainer<double> physBasisValues (1, numFields, 1);  
  
    // Containers for interpolated values of f  
    FieldContainer<double> fNodeQuad (1, 1);  
  
    // Transform basis values to physical frame:  
    IntrepidFSTools::HGRADtransformVALUEx<double>(physBasisValues,refBasisValues);  
  
    // Evaluate function at a point:  $\sum f_i(x_p) \phi_i(x_p)$   
    IntrepidFSTools::evaluate<double>(fNodeQuad, fNodeTri, physBasisValues);  
  
    // Put quad cell values into global array  
    fNodeQ[0][ipt] = fNodeQuad(0,0);  
}  
// if point in cell
```



# Example: Vector Interpolation

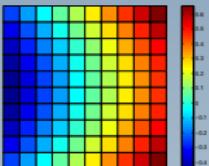
Interpolate vector from node to cell centers,  $\mathbf{v}(\mathbf{x}) = [xy^2, xy]$



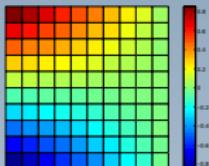
- Read mesh with MOAB and store connectivity
- Define cell topology
- Define interpolation points on reference cell ( $\hat{\mathbf{x}}_p$ )
- Evaluate basis at points in reference cell,  $\hat{\phi}_i(\hat{\mathbf{x}}_p)$
- Transform basis to physical space,  $\hat{\phi}_i \rightarrow \phi_i$
- Evaluate function at points in physical space  $\mathbf{v}^h(\mathbf{x}_p) = \sum_{i=1}^N \mathbf{v}_i \phi_i(\mathbf{x}_p)$

# Example: Derivatives of a Field

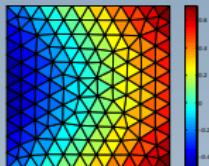
Calculate divergence and vorticity from nodal vector field at cell centers



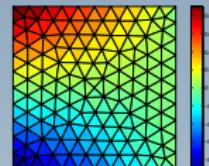
divergence



vorticity



divergence

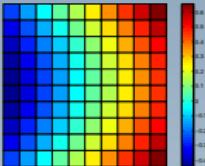


vorticity

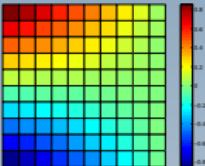
- Read mesh with MOAB and store connectivity
- Define cell topology
- Define interpolation points on reference cell ( $\hat{\mathbf{x}}_p$ )
- Evaluate gradient of basis at points in reference cell,  $\nabla \hat{\phi}_i(\hat{\mathbf{x}}_p)$
- Calculate cell Jacobian,  $DF$
- Transform gradient of basis to physical space,  $\nabla \phi_i = (DF)^{-T} \nabla \hat{\phi}_i$
- Evaluate gradient of vector components at points  
 $\mathbf{v} = (u, v) \quad \nabla u^h(\mathbf{x}_p) = \sum_{i=1}^N u_i \nabla \phi_i(\mathbf{x}_p)$
- Calculate divergence and vorticity from components  
 $\text{div} = \partial u^h / \partial x + \partial v^h / \partial y \quad \text{vort} = \partial v^h / \partial x - \partial u^h / \partial y$

# Example: Derivatives of a Field

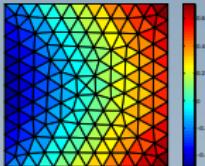
Calculate divergence and vorticity from nodal vector field at cell centers



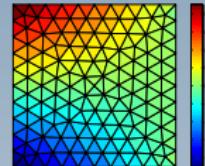
divergence



vorticity



divergence



vorticity

```
// Calculate Jacobian
Intrepid::CellTools::setJacobian(worksetJacobian, evalPoints, cellWorkset, cellType);
Intrepid::CellTools::setJacobianInv(worksetJacobInv, worksetJacobian );

// Evaluate basis values at evaluation points
Intrepid::Basis_HGRAD_QUAD_C1_FEM<double, FieldContainer<double> > interpBasis;
int numFields = interpBasis.getCardinality();
interpBasis.getValues(basisGrads, evalPoints, OPERATOR_GRAD);

// Transform basis gradients to physical frame
Intrepid::FunctionSpaceTools::HGRADtransformGRAD<double>(worksetBasisGrads,
                                                               worksetJacobInv,
                                                               basisGrads);

// Evaluate gradients at a point: \sum v_i(x_p) grad \phi_i(x_p)
Intrepid::FunctionSpaceTools::evaluate<double>(worksetCell_du, worksetvCoef_x, worksetBasisGrads)
Intrepid::FunctionSpaceTools::evaluate<double>(worksetCell_dv, worksetvCoef_y, worksetBasisGrads)

// Calculate divergence and vorticity and store in global array
for(int cell = worksetBegin; cell < worksetEnd; cell++){
    // Compute cell ordinal relative to the current workset
    int cellOrdinal = cell - worksetBegin;

    divCell[0][cell] = worksetCell_du(cellOrdinal,0,0) + worksetCell_dv(cellOrdinal,0,1);
    vortCell[0][cell] = worksetCell_dv(cellOrdinal,0,0) - worksetCell_du(cellOrdinal,0,1);

    } // *** workset cell loop **
```



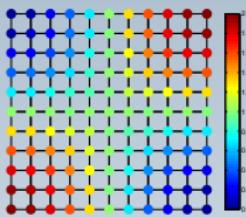
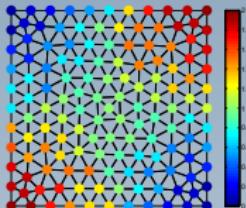
# Summary and Future Plans

- Current Capabilities

- Interpolation from grid to points
- Function approximations with node, edge, or face basis functions
- Differential operators
- Integration over cells

- Future Plans

- Interpolation from points to grid
- Additional cell topologies (eg. polygons)



For more information see:

<http://trilinos.sandia.gov/packages/intrepid>