

Wave Energy Converters: Designing and Modeling a Successful Device

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Sandia National Laboratories.

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UNM Mechanical Engineering Seminar

Sandia Water Power Overview

Technology Assessment: Reference Model Project

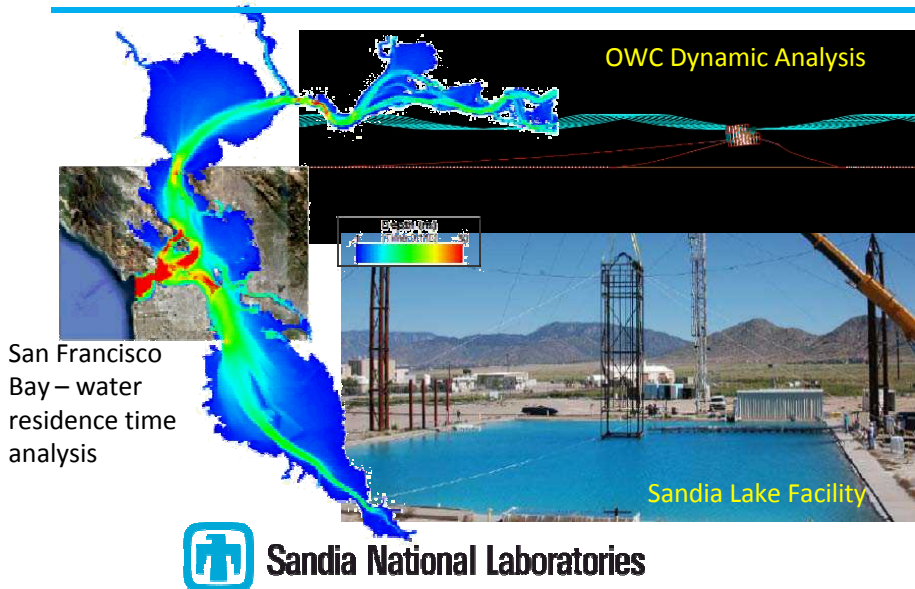
- Goal: obtain baseline Cost Of Energy (COE) estimates for a variety of Marine Hydro-Kinetic (MHK) devices.

Technology Development: Modeling Tools & Advanced Materials

- Modeling Tools: predict power performance of MHK devices
- Advanced Materials: evaluate new corrosion resistant and antifouling material coatings

Market Acceleration: Environmental Impact

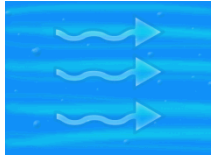
- SNL-EFDC: MHK –capable environmental circulation and array performance code
- SNL-SWAN: tool to evaluate environmental effects of WEC arrays



Unique Capabilities

- SEAWOLF laboratory/field oscillatory-flow sediment transport testing
- Sandia Lake Facility – potential for large scale wave testing
- Ability to leverage defense spending on fundamental sciences: controls, hydrodynamics, aerodynamics, experimentation, etc.

Marine Hydrokinetic (MHK) Devices



ORPC TidGen



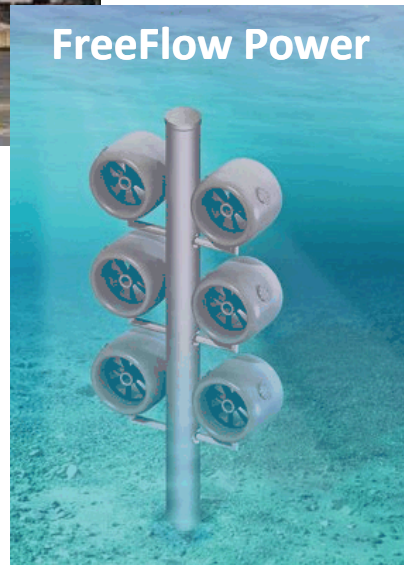
OPT Power Buoy



CPT SeaRay



Verdant



FreeFlow Power



Ocean Energy BBDB



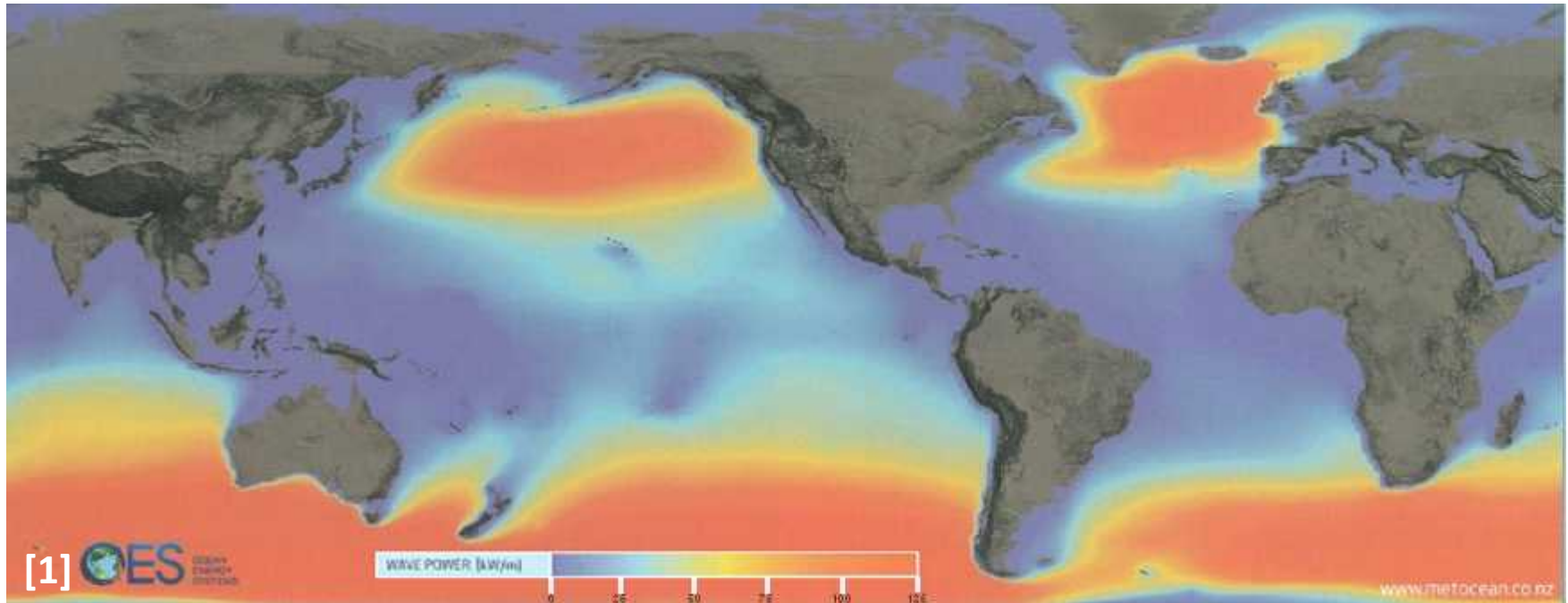
Resolute Marine Energy



Pelamis



Ocean Wave Resource



Globally ^[2]

- **3.4 TW (29,400 TWh/yr)**

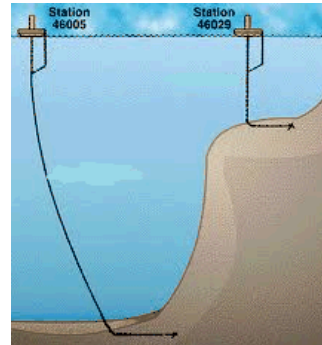
United States ^[3]

- **300GW (2,640 TWh/yr)**
 - West Coast (WA, OR, CA): 67 GW (590 TWh/yr)
 - Hawaii: 15 GW (130 TWh/yr)
 - East Coast (NC thru ME): 23 GW (200 TWh/yr)
 - Alaska (Pacific Ocean): 155 GW (1,360 TWh/yr).

WEC Types [4]

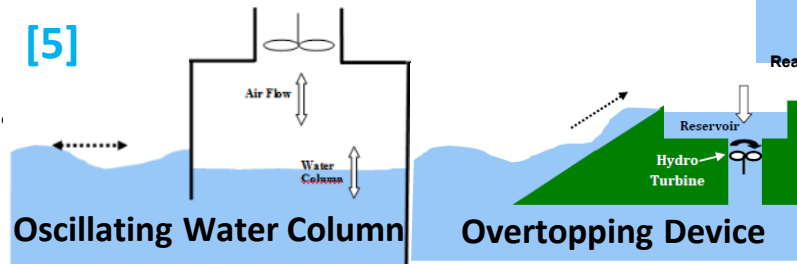
Water Depth

- Shore-Mounted.
- Near-Shore.
- Offshore.



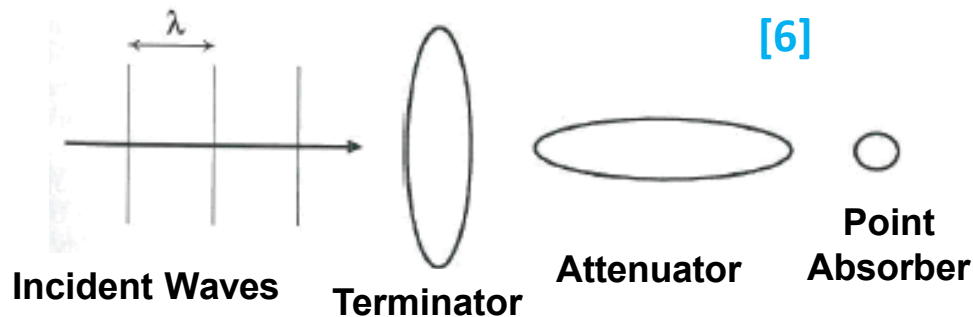
Conversion mechanism

- Oscillating Water Column (OWC)
- Overtopping Device (OTD)
- Wave Activated Body (WAB)

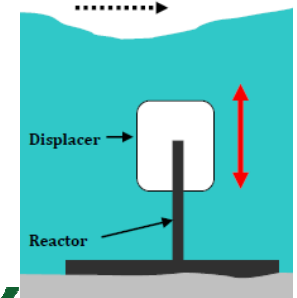
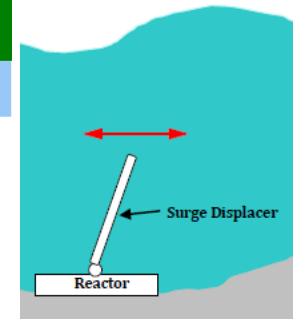
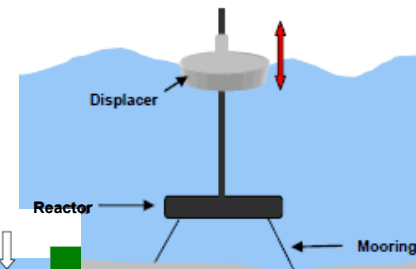
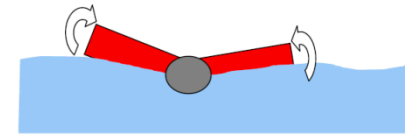


Directional dependence

- Point Absorber
- Terminator
- Attenuator



Wave Activated Bodies



WEC Classification

Placement in the water column

- Surface expression or submerged

Buoyancy

- Neutrally buoyant or \pm buoyancy

Mooring & Anchoring Type

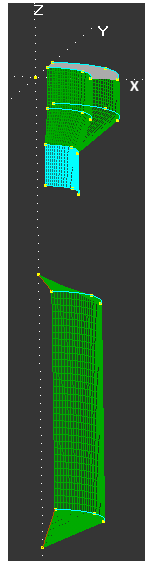
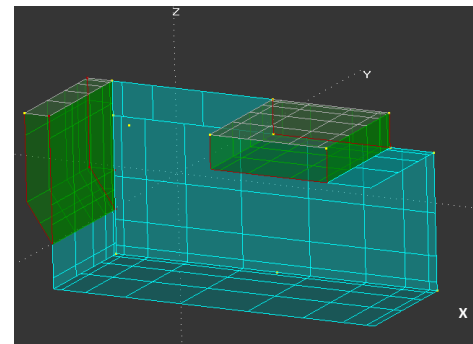
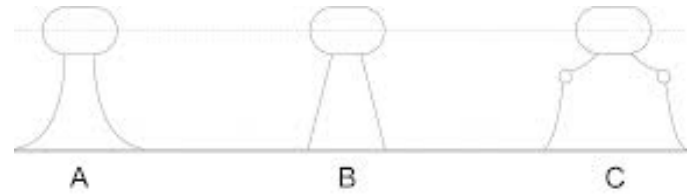
- Number of legs, slack or taut, presence of subsurface floats, anchor type, watch circle radius

Symmetry

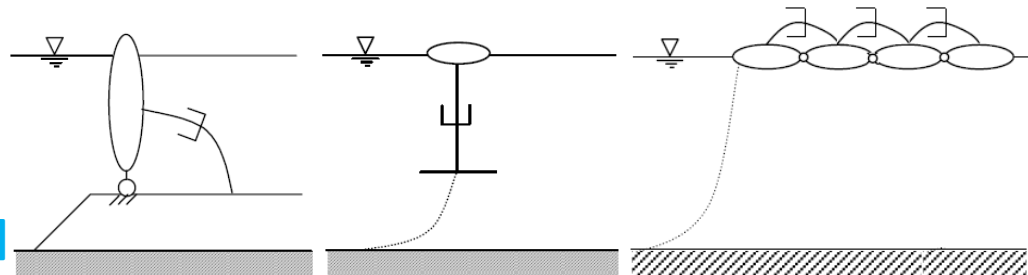
- Identifies directional dependence & manufacturing constraints

Number of bodies

- Identifies complexity and indicates: PTO reference and deployment depth range



[4]



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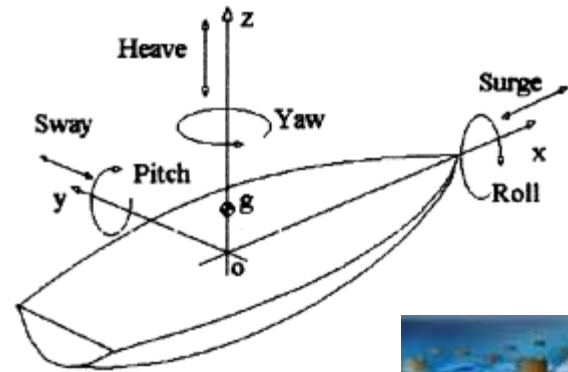


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WEC Classification

Primary oscillation directions

- Identifies primary excitation mode and indicates maximum theoretical energy capture (along with directional dependence)

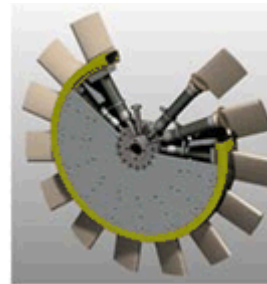


Drivetrain Type

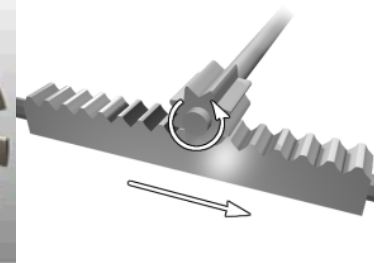
- Component of power conversion that converts motions of WEC into mechanical power.

Drivetrain reference

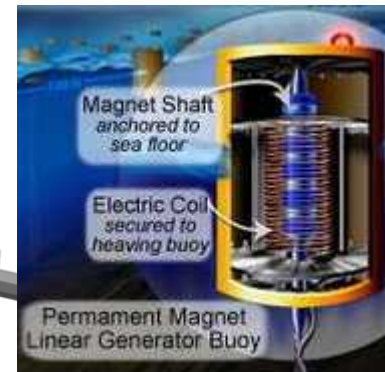
- Identifies reference through which power conversion happens and indicates deployment depth range



Air Turbine



Mechanical:
rack & pinion



Linear Generator
(drivetrain & generator)

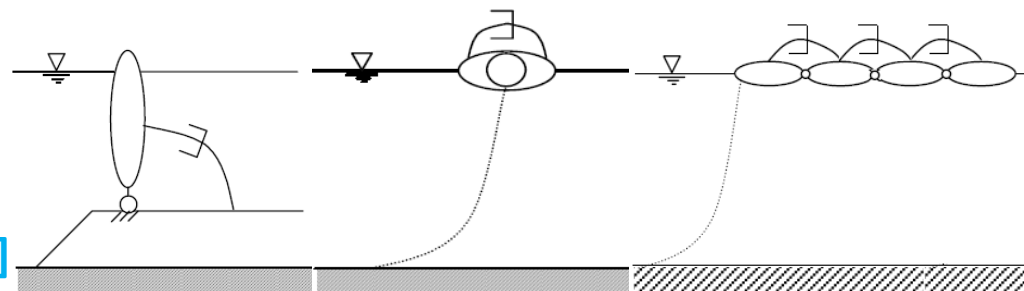
Oscillation constraint

- Identifies maximum extension of the drivetrain components if present

Survival strategy

- Identifies how the device will survive large waves that could potentially damage the drivetrain

[4]



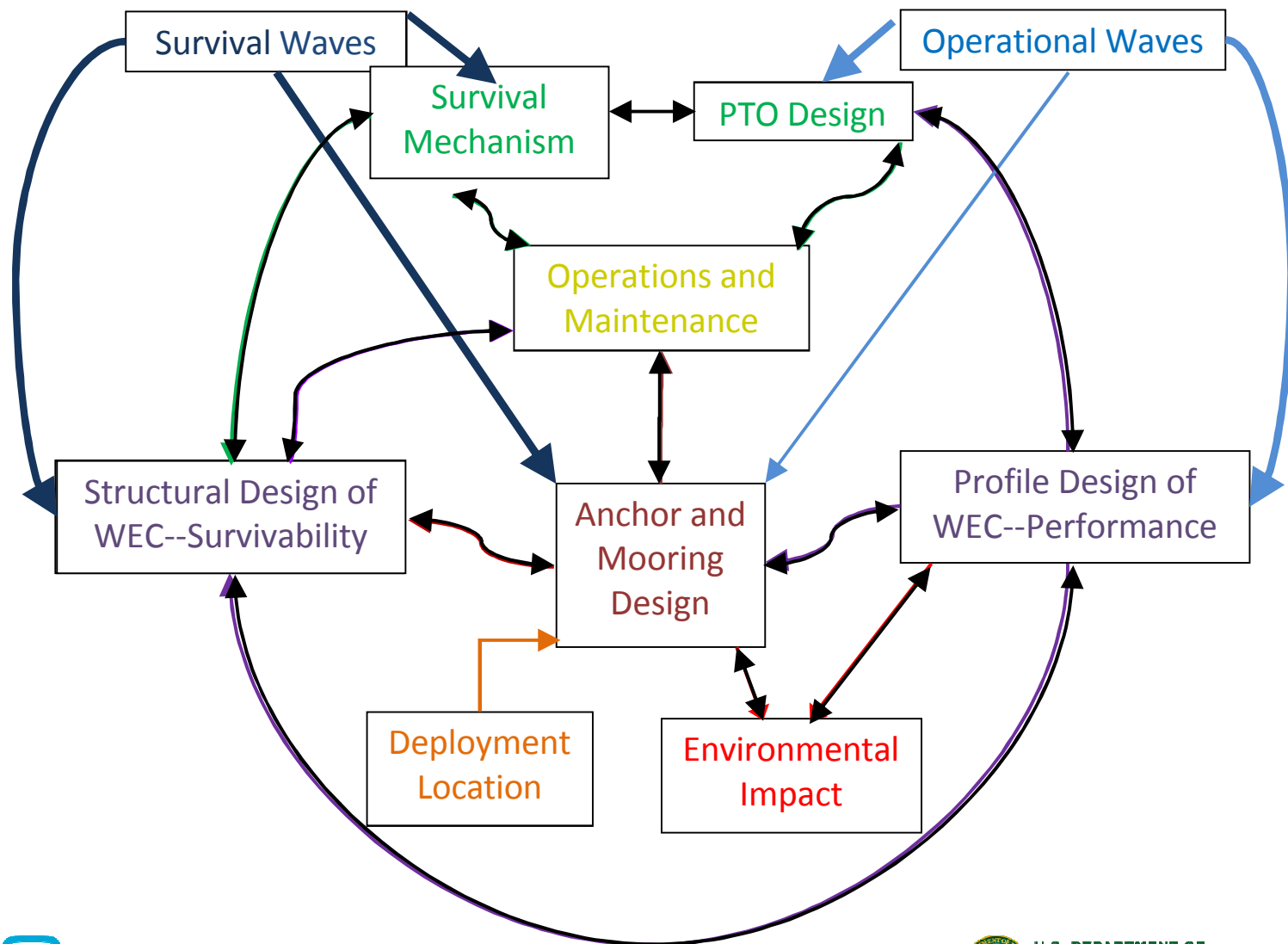
Ground

Self – inertia

Self – reacting
bodies



WEC Design

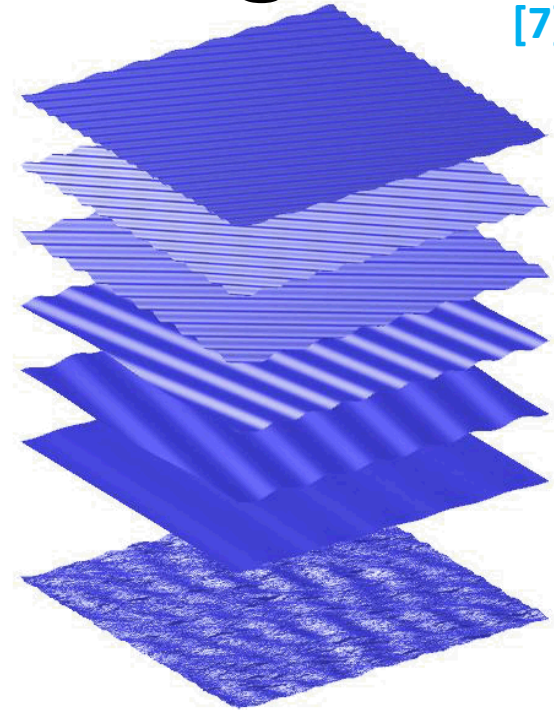


Wave Climate Modeling

[7]

Modeling Ocean Waves

- **Superposition of harmonic waves**
 - Distinct frequencies, amplitudes, and incident directions.
- **Wave Spectra**
 - Represent distribution of energy content as a function of frequency and direction.
 - Use standard distributions to describe waves in different parts of the world.



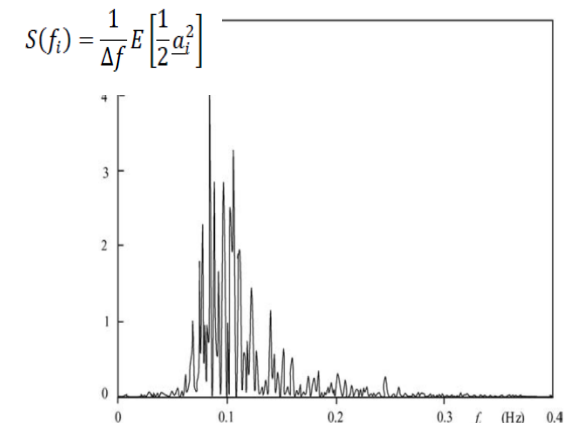
Linear Wave Theory Assumptions

- **Velocity potential formulation**
 - Small amplitude motion, incompressible, inviscid & irrotational flow
- **Satisfies the Laplace Equation**

$$\nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} = 0$$

- Meets bottom boundary condition (no flow),
 - dynamic free surface boundary condition (no pressure discontinuity at surface), and
 - kinematic free surface boundary condition (no velocity discontinuity at surface)
- **Dispersion relation**
 - Establishes relationship between wave period and wave length

$$\eta(x, y, t) = \sum_i a_i \cos(k_i(x \cos \theta_i + y \sin \theta_i) - 2\pi f_i t + \phi_i)$$



[illegible]

Wave Structure Interaction

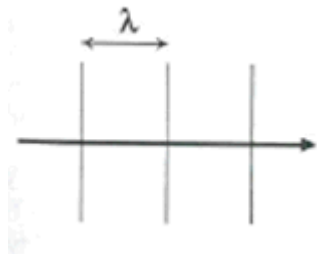
Hydrodynamic Forces

Potential Flow

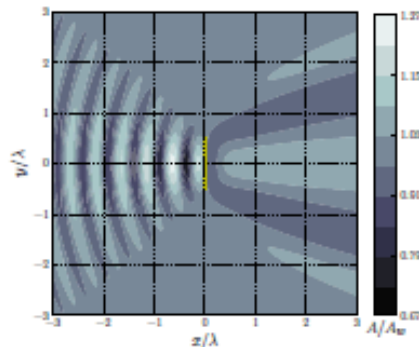
• Frequency Domain Response

- Superposition of incident, diffracted, and radiated potentials : $\hat{\phi} = \hat{\phi}_o + \hat{\phi}_d + \hat{\phi}_r$
- Based on linear wave theory assumptions.

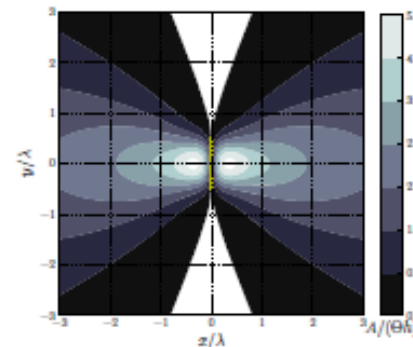
Incident Linear Theory Wave



Diffracted Wave



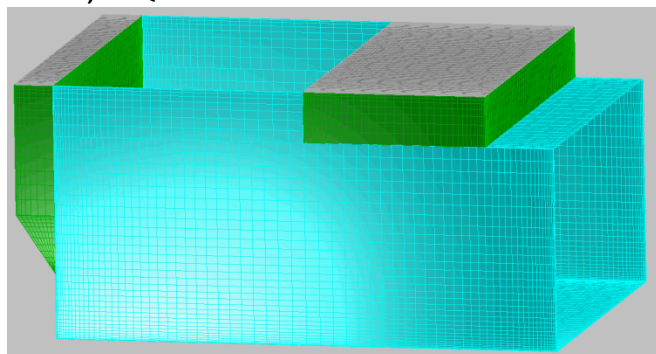
Radiated Wave



[8]

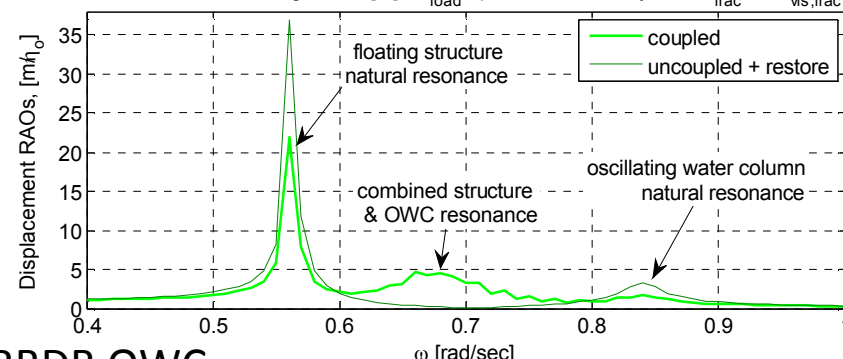
• Commercial programs apply potential flow theory using Boundary Element Method (BEM) to obtain the response of a structure to incoming waves

- WAMIT, AQWA.



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Heave RAOs. Air Chamber Height of 20[m]. R_{load} optimization = Body+Air. $G_{frac}=0$, $B_{vis,frac}=0$.



RM6: BBDB OWC



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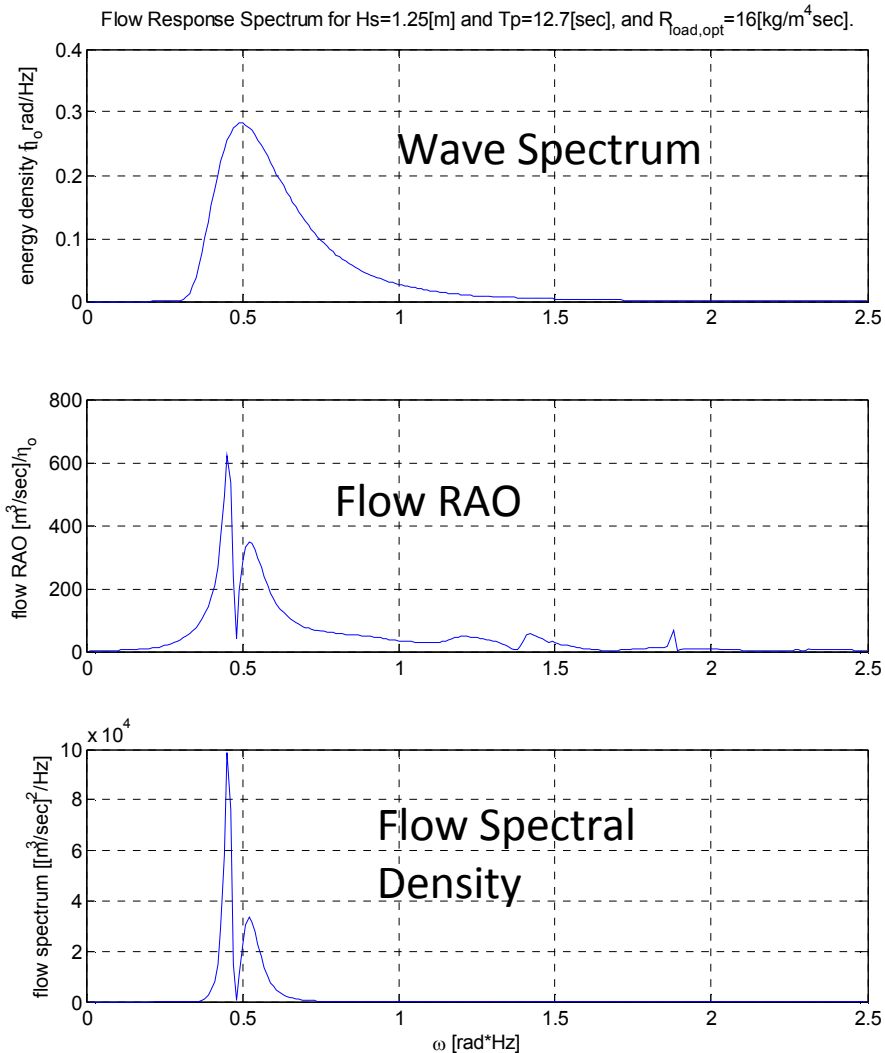
Performance Modeling

Frequency Domain

Equations of motion for a device are derived from governing equation:

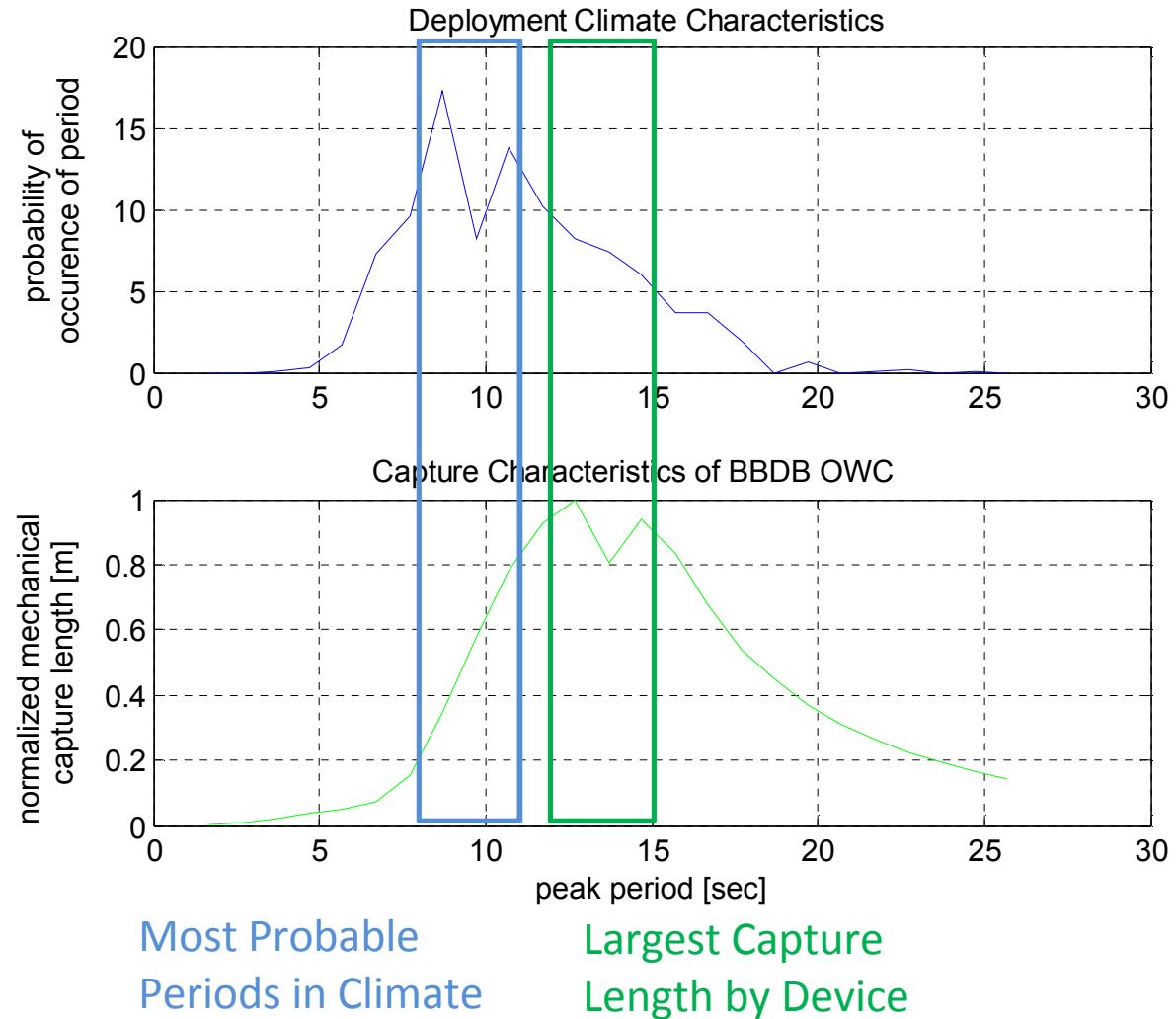
$$F_{total} = F_{hydrodynamic} + F_{hydrostatic} + F_{ViscousDamping} + F_{mooring} + F_{Control}$$

- $F_{hydrodynamic}$ & $F_{hydrostatic}$ are found from a potential flow solver, like WAMIT
- $F_{ViscousDamping}$ found with aid of CFD, experiment, or targeted RAO response at resonance
- $F_{Mooring}$ are found through evaluation of design in OrcaFlex for operational conditions.
- $F_{Control}$, the optimal “slow tuning” parameters are found for each sea state
 - The control parameters are independent of the PTO type at this stage.



Performance Model Outcome

- The average power for each sea state is found through
$$\langle P \rangle = R_{control} \int_0^{\infty} |u|^2 S(\omega) d\omega$$
- Evaluating a design can be aided by comparing the deployment characteristics to the device capture characteristics.
- Goal is to match the device design to the deployment location.



Anchor and Mooring Modeling

Mooring Design Driven by Survival Waves

- Potential Flow is NOT a valid method to predict dynamics
- Morison Eq. is a valid approach to predict dynamics

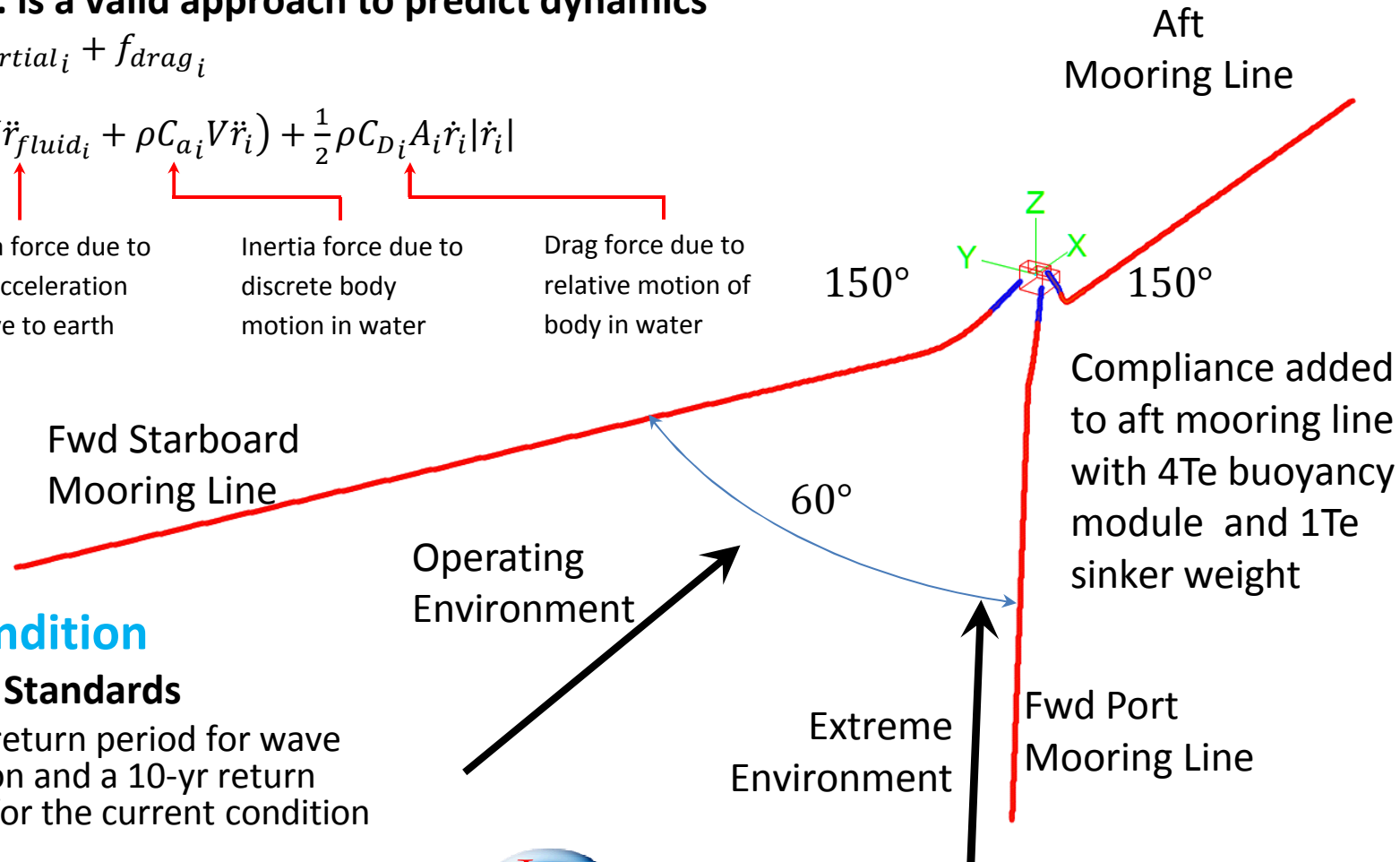
$$f_i = f_{inertial_i} + f_{drag_i}$$

$$= (\rho V \ddot{r}_{fluid_i} + \rho C_{a_i} V \ddot{r}_i) + \frac{1}{2} \rho C_{D_i} A_i \dot{r}_i |\dot{r}_i|$$

Inertia force due to
fluid acceleration
relative to earth

Inertia force due to
discrete body
motion in water

Drag force due to
relative motion of
body in water



Survival Condition

- Apply DNV Standards
 - 100-yr return period for wave condition and a 10-yr return period for the current condition



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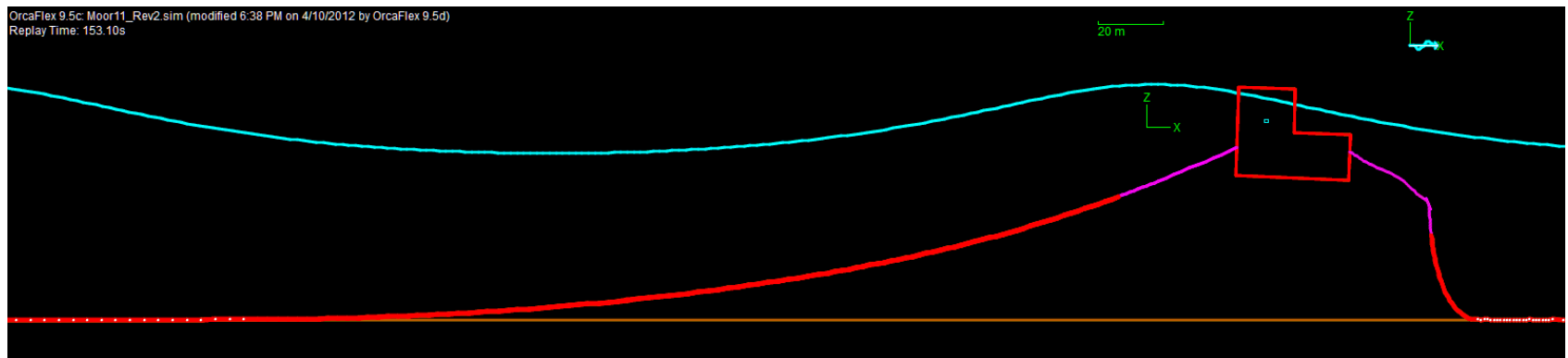
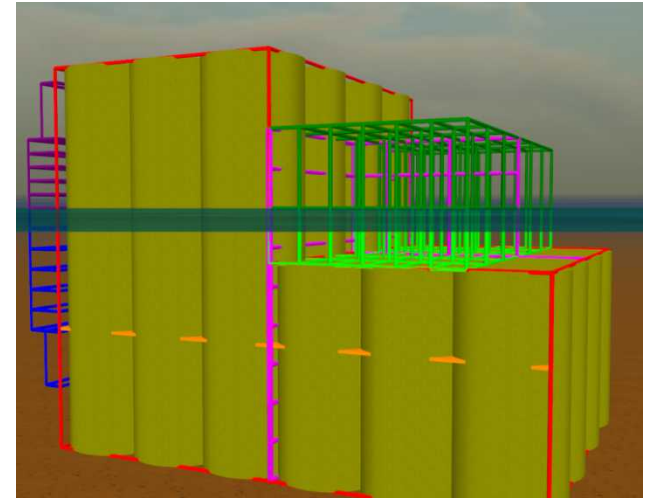
Anchor and Mooring Modeling

OrcaFlex

- **3D time domain solution of equations of motion for bodies subjected to hydrodynamic loads**
 - Hydrodynamic loads calculated using extended formulation of Morison's equation.

Discretization Methodology

- **Model rigid structure as an array of 6-DOF discrete bodies to capture**
 - Buoyancy distribution
 - Hydrodynamic characteristics that account for inertial and viscous effects
- **Rotational response controlled by distribution and density of discrete bodies.**

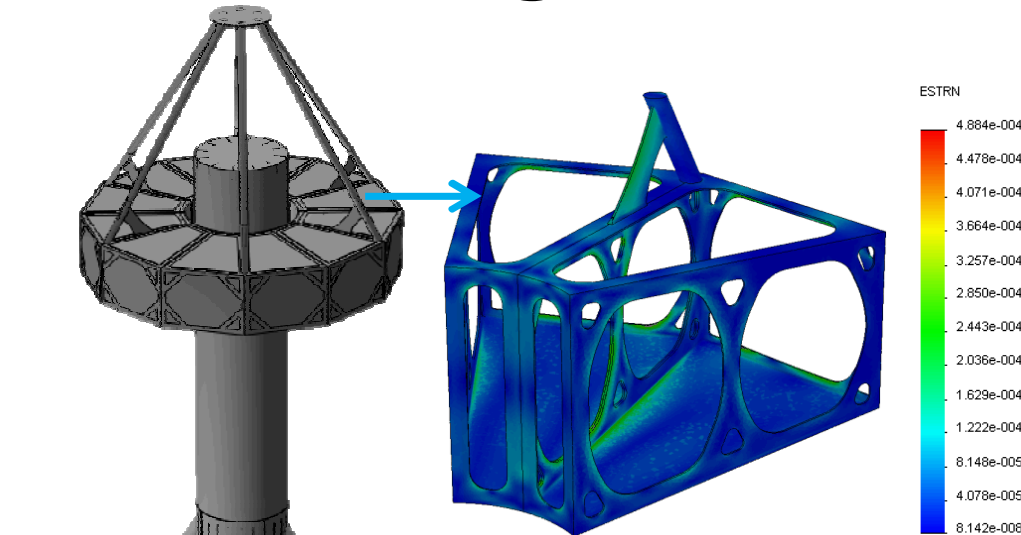


[9]

Structural Modeling

Initial Design

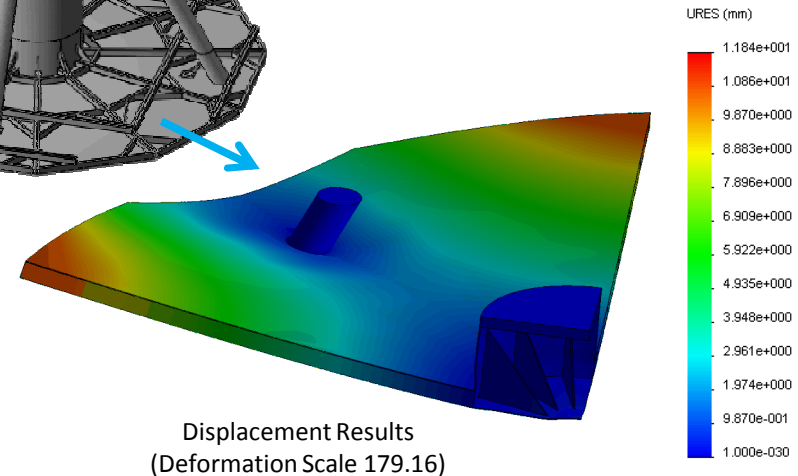
- **Use Standards to estimate structural requirements**
 - Survival conditions drive structural design
 - Use conservative estimates of load to generate baseline design
- **Determine Basic Properties**
 - Center of Gravity & Center of Buoyancy
 - Moments of Inertia
 - Required Ballast
 - Expected natural resonances
- **Select Baseline Materials**
 - A36 steel is often used in marine environments



Strain Results (98% Accurate)

Structural Integrity

- **Refine Design**
 - Add appropriate supports while minimizing required material
 - Obtain higher accuracy loading estimates from wave-structure modeling tools
- **Finite Element Analysis (FEA)**
 - Ensure design meets required Factors of Safety (FOS) for provided loads
- **Consider manufacturing constraints**
 - Designs requiring metal cutting and welding not only offer points of failure but also increase expense



Displacement Results
(Deformation Scale 179.16)

Power Conversion Chain Modeling

Designing PTO, must balance:

Large variability's:

- Across the entire deployment climate.
- Within a particular sea state—average vs. peak values.

Single vs. Multiple Drivetrains

- Added redundancy can increase WEC availability but may adversely effect cost or efficiencies

Drivetrain & Generator sizes

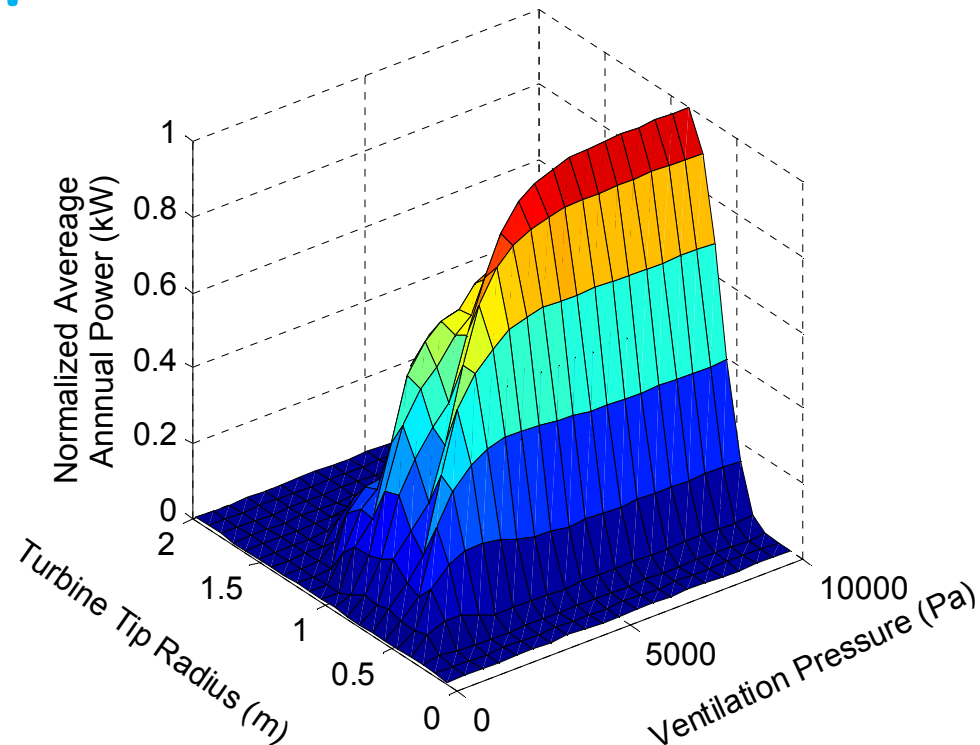
- Must be optimized for the climate variability

Power Conversion Efficiency

Power Conversion serviceability and reliability

- The drivetrain, generator, and other subcomponents are the most likely to fail: need to really consider O&M for this subsystem

Normalized Average Annual Power



ARL in collaboration with SNL has been developing an optimization code to optimize average annual electrical power for various Well's Turbines for RM6 (BBDB OWC)

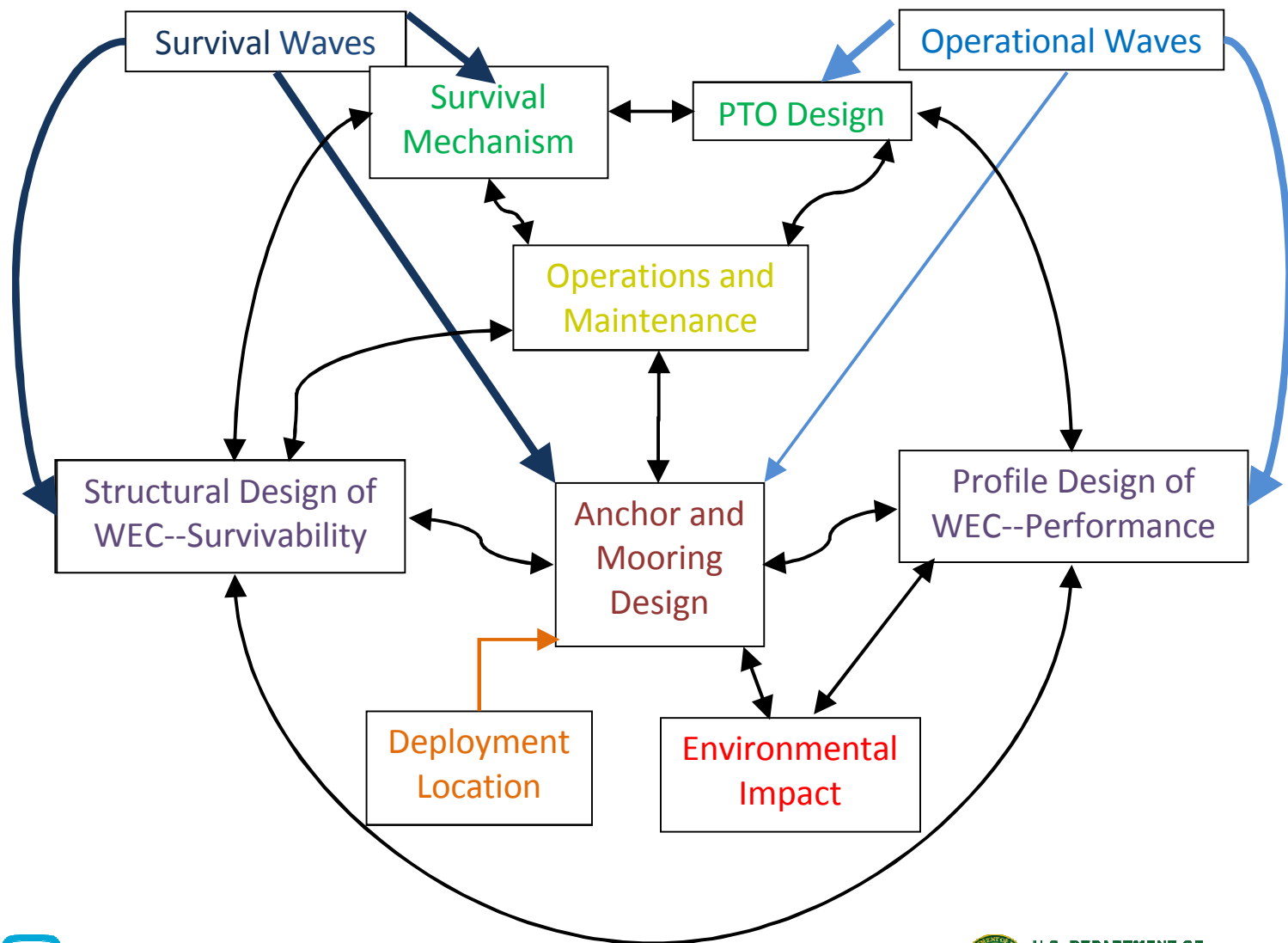


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WEC Design



SAMPLEING OF SNL'S WORK IN WATER POWER

Reference Model

Summary

- Multi-Lab collaborative effort to obtain **baseline** performance and Cost Of Energy (**COE**) estimates for a variety of Marine Hydro-Kinetic (MHK) devices.
- Method to achieve cost of energy estimates is to develop **public domain designs** incorporating the following:
 - Power performance models
 - Structural models
 - Anchor and mooring design
 - Economic Model
 - PTO Design
 - O&M / Installation
 - Permitting & Environment
- Designs are intended to be conservative, robust, and **experimentally verified**.

SNL Developed Tools

- Performance Models**—WEC: developed 3-dimen model capable of handling 7DOF in Matlab, FEC: developed CACTUS
- Survival Model**—developed methodology to utilize a Morison's Eq. approach to model extreme conditions
- Structural Sizing Tool**—developed tool that determines weight, ballast, COG & COB locations, and natural frequencies
- PTO Sizing Tool**—developed Turbine sizing tool

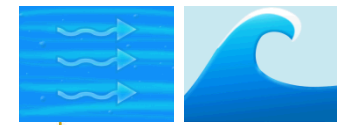
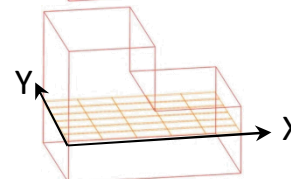
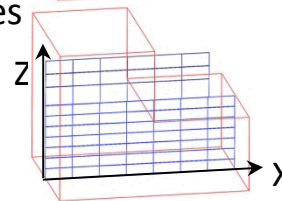
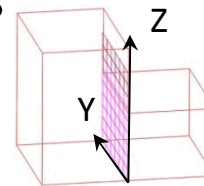
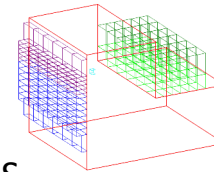
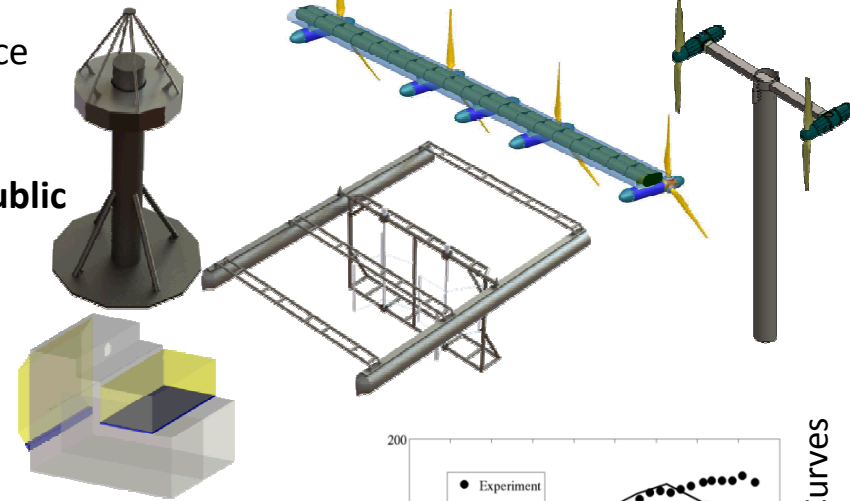
SNL Utilized Tools

- Hydrodynamics**—WAMIT / AQWA / Fluent
- Mooring**—OrcaFlex / AQWA Moor
- Structural Integrity**—ANSYS / SolidWorks

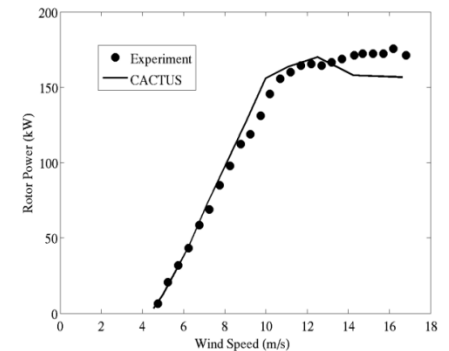
- Partners:** PNNL, ARL, NREL, ORNL



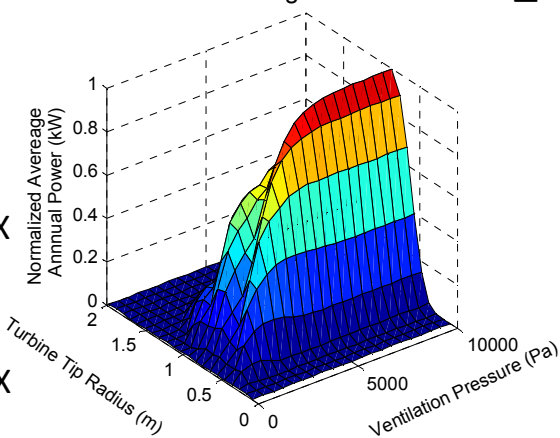
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PI: Neary



Normalized Average Annual Power



SNL-SWAN: WEC Array Performance and Optimization



PI: Ruehl

Summary/Impact

- SNL is developing a new modeling tool, **SNL-SWAN**, by modifying the SWAN source code to include a **WEC Module** that accounts for **wave height- and frequency-dependent** energy extraction of WECs

Tools

- SWAN – Simulating WAVes Nearshore is an **open source** third-generation wave model developed at Delft University of Technology that solves the **spectral wave action balance equation**.

Accomplishments

- FY12: SWAN **Sensitivity analysis** in the **OSU Tsunami Basin** model domain, modeled the **CPT experiments** (see figures)

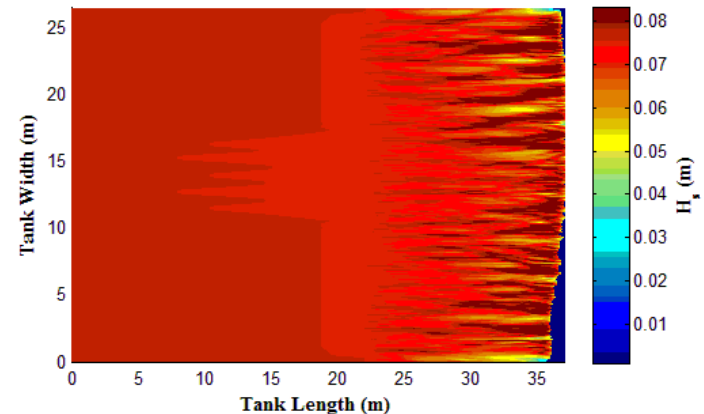
Partners:

- Coast and Harbor Engineering (C&H), Columbia Power Technologies (CPT), Oregon State University (OSU), Sea Engineering Inc. (SEI)

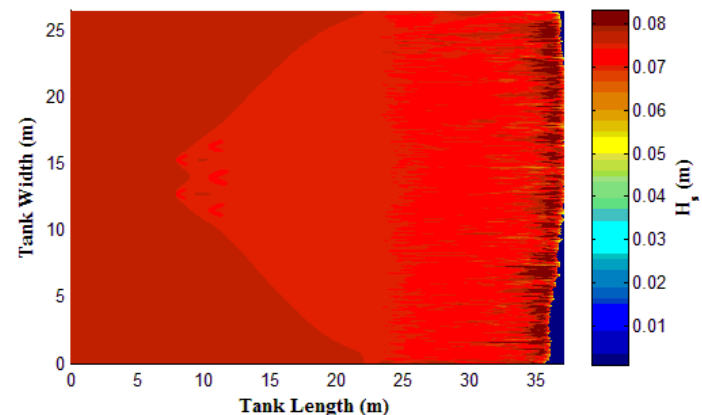


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SWAN Tsunami Basin Model for 5 WEC Array



$H_s = 0.0758$ [m], $T_p = 1.82$ [s], Unidirectional Waves,
Obstacle Transmission = 0 (aka 100% Absorption)

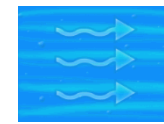


$H_s = 0.0758$ [m], $T_p = 1.82$ [s],
Directionally Spread Waves (DSR=4),
Obstacle Transmission = 0 (aka 100% Absorption)



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SNL-EFDC: FEC Array Performance and Optimization



PI: Roberts

Summary/LCOE Impact

- Refine and apply **SNL-EFDC**: a tool for **balancing** MHK-turbine energy harvest **efficiency and environmental effects**.
- **Maximize power** and **minimize** potentially harmful **environmental effects**
- Accurately modeling MHK-turbines addresses **performance and environmental concerns** about large-scale development.

Accomplishments

- Modified EFDC source code to include **CEC module** that treats CECs as momentum sink and source/dissipation of TKE.
- SNL-EFDC validation with flume data
- SNL-EFDC application – Mississippi River, LA
 - Investigated **performance, flood hazard, and sedimentation** concerns for 12, 132, 534 CEC arrays (FFP)

Tools

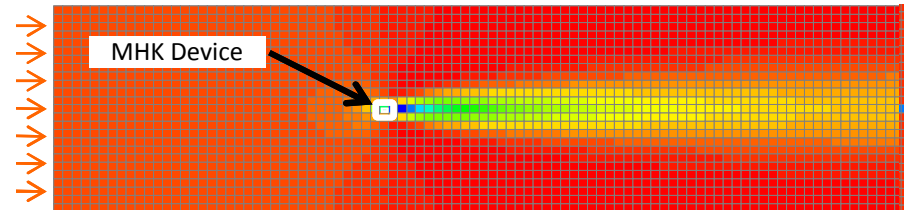
- EFDC – Environmental Fluid Dynamics Code (RANS)
- Originally Developed by the EPA for Clean Water Act
- **SNL-EFDC** – adds **MHK-turbine module** and advanced **sediment transport routines**.

Partners:

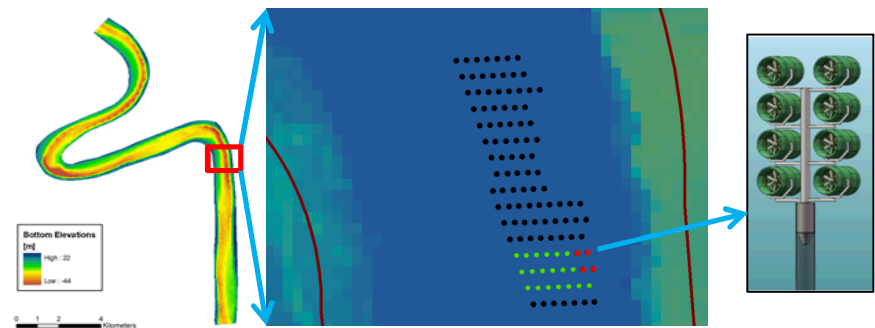
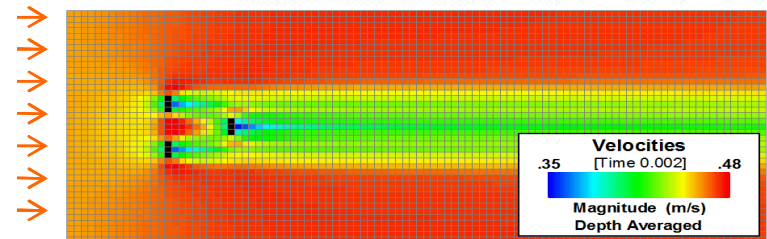
- Ocean Renewable Power Company (ORPC)
- Argonne National Lab (ANL)
- University of Maine (UM)
- Sea Engineering Inc. (SEI)



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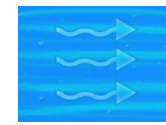
Treats MHK-turbine device as a momentum sink and source of turbulent kinetic energy and its dissipation rate



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Blade Strike Analysis

(Collaboration with PNNL)



PI: Jepsen

Summary/LCOE Impact

- **Regulatory Driver:** Little is known about blade strike on marine mammals.
- **Simulate strike events** to characterize potential **impact to marine mammals**.
 - Consider multiple turbine designs and mammal types.

Background

- SNL defines **turbine properties & simulates strike** to determine dynamic impact.
 - Use 3 impact velocities within turbine operating conditions for deformation trends.
- PNNL defines **mammal properties** and **tissue response** based on simulated deformation.

Tools

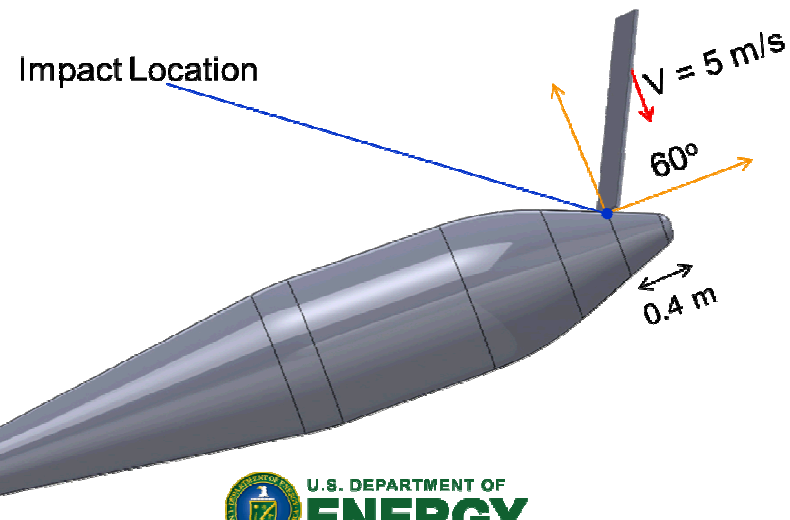
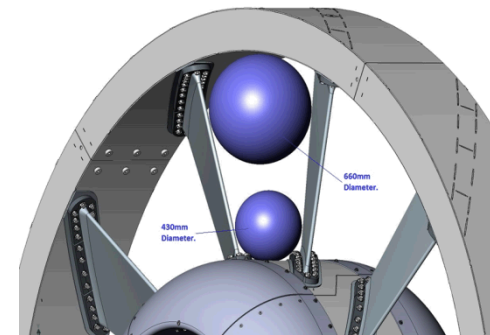
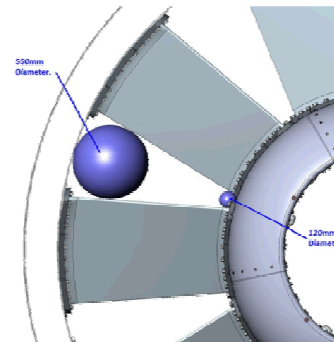
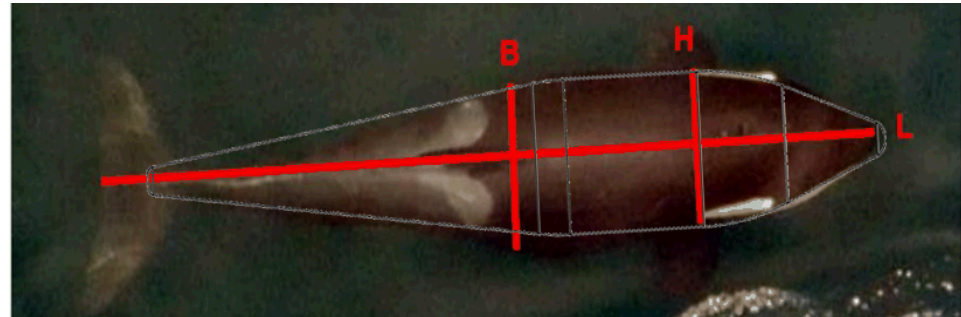
- **PRESTO- SNL weapons code** for L/E analysis of high solid deformation events.
- **RM designs and performance models**

Partners

- Pacific Northwest National Lab

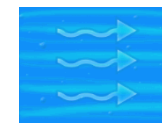


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CACTUS: Code for Axial and Cross-flow Turbine Simulation



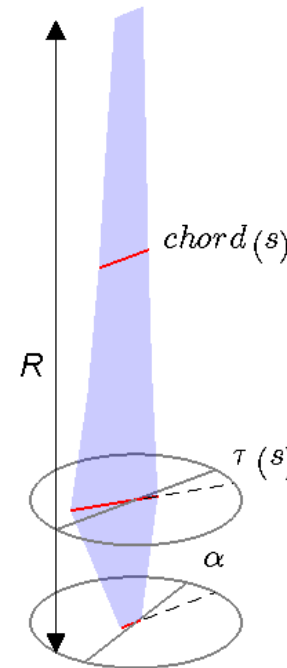
PI: Barone

• LCOE Impact

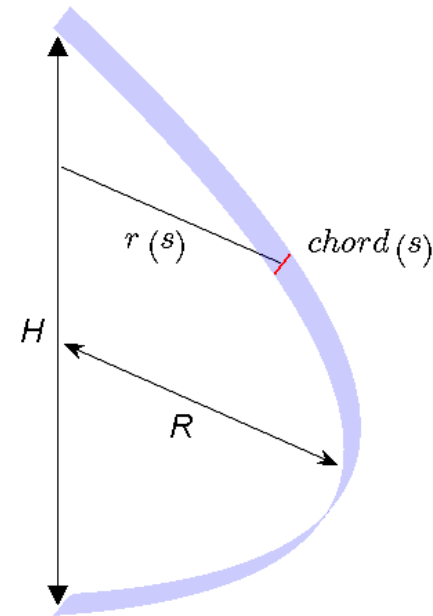
- Open-Source, publicly available, Validated, & Rapid run-times: Coded in Fortran95, compiled in Linux, Windows, & OSX
- **Performance:** power predictions for generalized rotor geometry
- **Structural:** unsteady hydrodynamic load estimates for generalized rotor geometry
- Solves for wake profile without the need for high-fidelity CFD

• Tool Capabilities

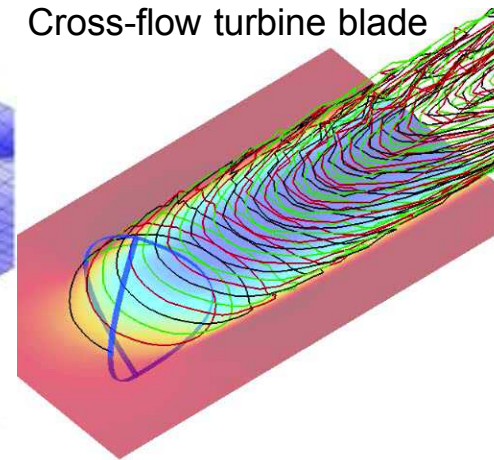
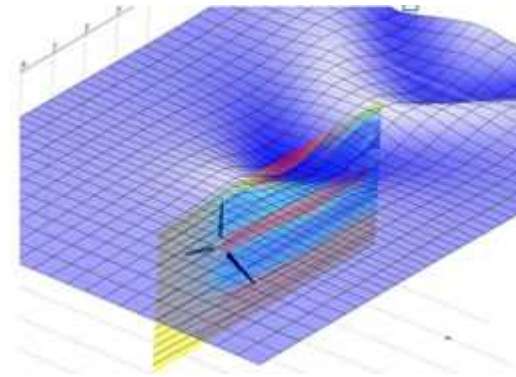
- Generalized Axial and Cross-Flow Turbine designs, including struts and joints
- Time Domain Simulation
- Blades represented as lifting lines with forces determined from input foil data
- Rotor wake represented with vortex elements
- Drag from support struts can be included
- Free surface effects included
- Dynamic Stall model included



Axial turbine blade



Cross-flow turbine blade



Code Development: Matt, Erick Johnson, & Jon Murray

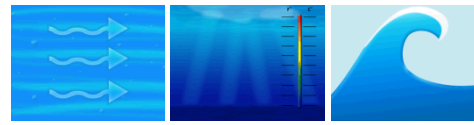


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Materials & Coatings



PI: Hernandez-Sanchez

Summary

- Novel Coating Synthesis
- Biofouling Testing
- Corrosion and Reliability Testing
- Composite Fabrication and Performance Testing
- Material Environmental Impact

LCOE Impact

- **Development Cycle, Performance, Reliability, Survivability, O&M:** impacted by materials & coatings selected for component/structure
- **Industrial Assessment:** impact of material choices to be analyzed and integrated into program
- **Repository of Expertise:** ability to direct industry to proven technologies

Accomplishments

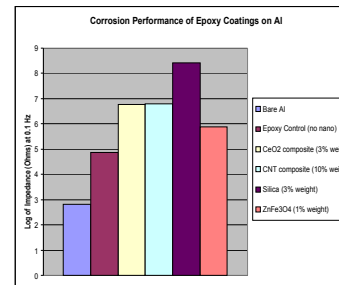
- Novel antifouling & anticorrosion coatings with significant performance
- Significant Industry Involvement
- Testing salt water effects on composites
- Ocean correlated laboratory testing
- ONRL: No acute Toxicity on Zwitterionic coating

- **Partners:** BYU, MSU, NDSU, ORNL

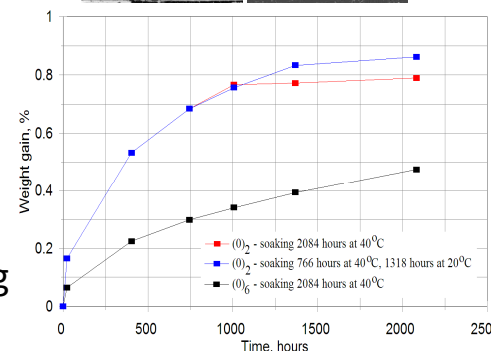
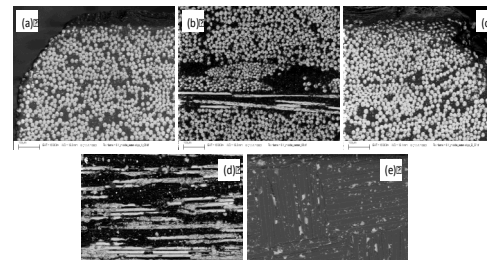


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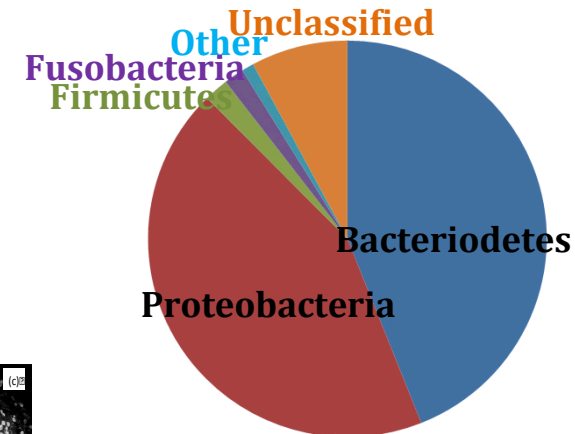
Corrosion Studies



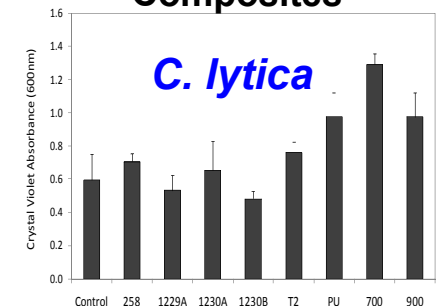
Salt Water Effects on Composites



Biofilm Characterization on Verdant Power Systems Deployed in East River



Biofilm Testing of Owens-Corning Composites



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Sediment Transport, Scour, and Foundation Impact Analysis

PI: Roberts

Summary/LCOE Impact

- Develop **public domain methods/tools** for assessing wind farm and ecosystem risk from **ocean forces & sediment mobilization**
- **Reduce Siting Risk** and Uncertainty
- **Reduce time and costs associated with permitting**

Focus Areas/Background

- Pre- and post-installation analysis of sediment mobility and effect of underwater structures
- Fine-scale scour analysis
- SEAWOLF – sediment testing for model calibration and validation

Tools

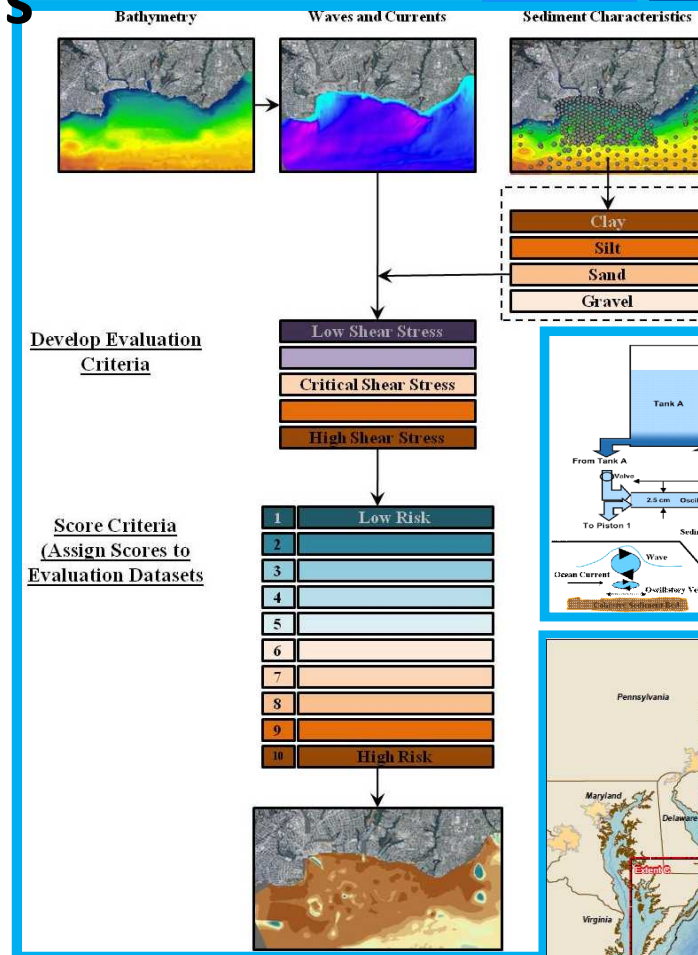
- SNL-EFDC (unique code for macro-scale studies)
- Fluent (commercial code)
- SEAWOLF mobile erosion test facility

Accomplishments

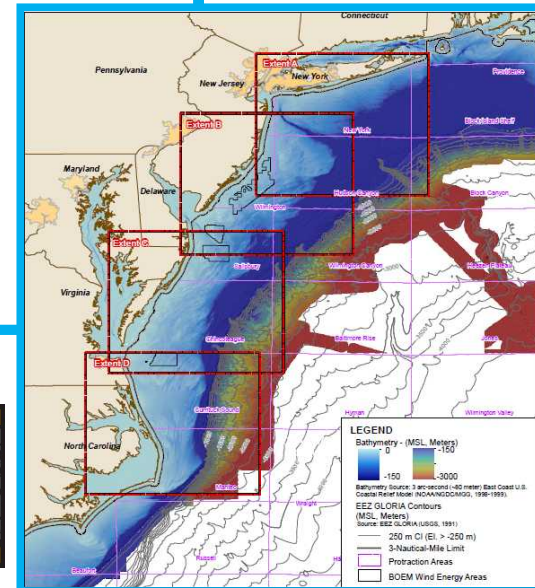
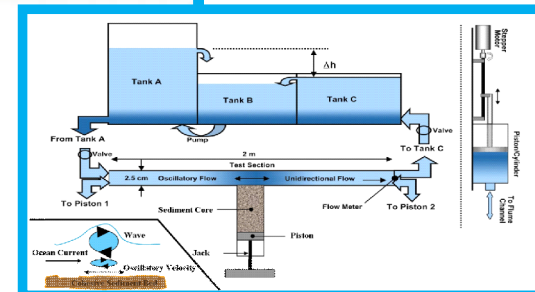
- Draft Sediment Stability Guidance Document
- Beta version of sediment stability mapping tool

Partners:

- **Technical:** Fugro and Sea Engineering
- **Advisory:** MMI, Alpine, Fisherman's, Global Marine, Mott MacDonald, Prysmian



SEAWOLF Flume



Large Offshore Rotor Development

PI: Griffith

• Summary/LCOE Impact

- Advanced large blade design studies aimed to **reduce technology risk**; enable cost-effective large rotors
- **Public domain blade project**

• Objectives/Focus Areas

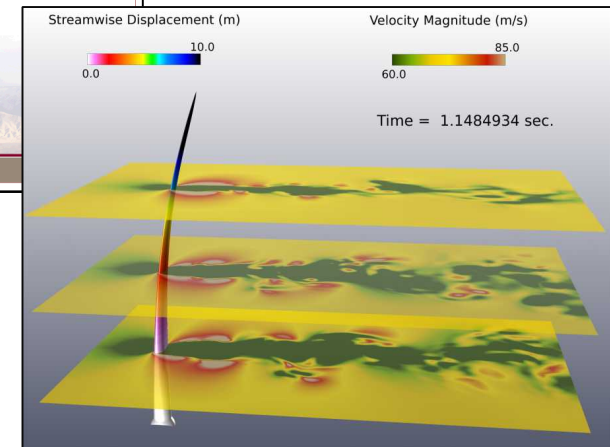
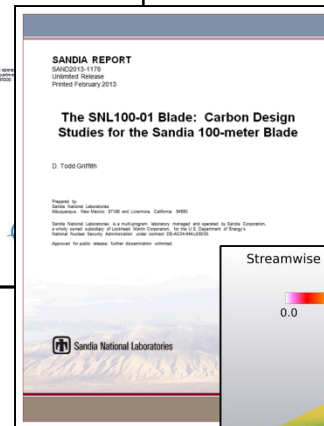
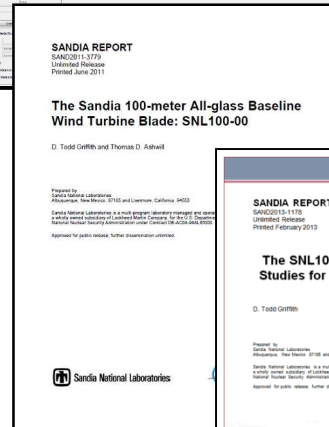
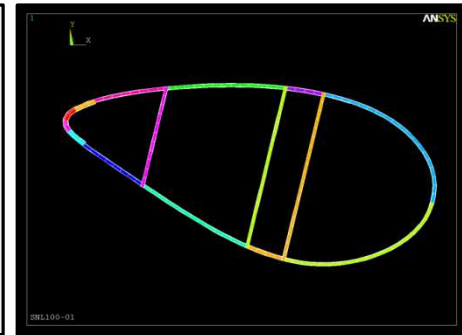
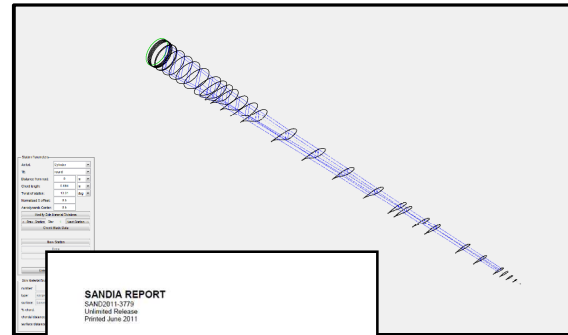
- Identify trends and challenges
- **Detailed 100-meter reference designs**
- **Targeted follow-on studies: advanced concepts, materials, flutter, manufacturing cost trends, thick airfoils, CFD**

• Products

- Design reports
- 100-m blade and 13.2 MW turbine reference models
- <http://largeoffshorerotor.sandia.gov>

• Partners:

- **None funded, 40+ users, ECN, Altair, Bristol, Stuttgart**



Innovative Offshore Vertical-Axis Wind Turbine Rotors (FOA)

PI: Paquette & Griffith

• Summary/LCOE Impact

- This project focuses on the development of a deepwater, offshore VAWT design to explore possible LCOE benefits
- This includes optimization of the rotor in response to higher balance of station and O&M costs associated with the offshore environment
- Goal is to achieve a *transformative* LCOE reduction for deepwater offshore wind

• Background/Current Focus

- Historical VAWT Expertise (1970s to 1990s)
- Current focus on VAWT Aero-Hydro-Elastic Design Code development and Preliminary Design Studies

• Tools

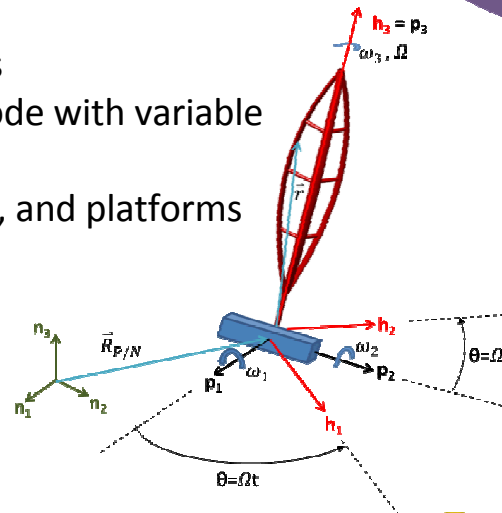
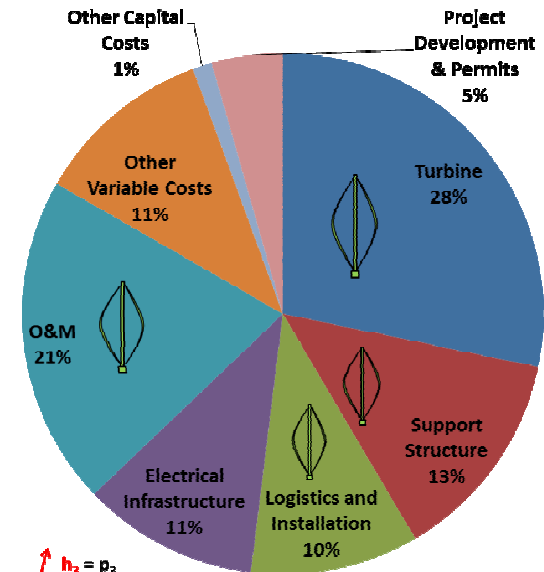
- Legacy Codes and Experimental Measurements
- New VAWT-specific aero-hydro-servo-elastic code with variable fidelity
- VAWT-specific airfoils, manufacturing methods, and platforms

• Partners:



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Offshore System Cost with Potential VAWT Impacts



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Vincent Neary: Technology Development Lead
Jesse Roberts: Market Acceleration Lead

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References

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In general all non-referenced pictures not produced by personal or collaborative work were goggled and can be easily found.

Thank you.

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Sandia National Laboratories.

March 29th, 2013.

UNM Mechanical Engineering Seminar



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