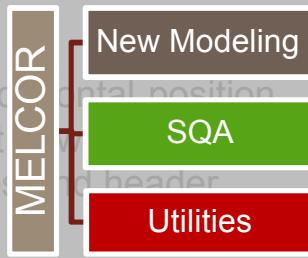
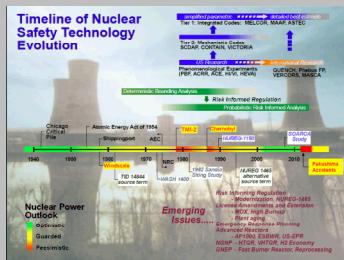


Exceptional service in the national interest

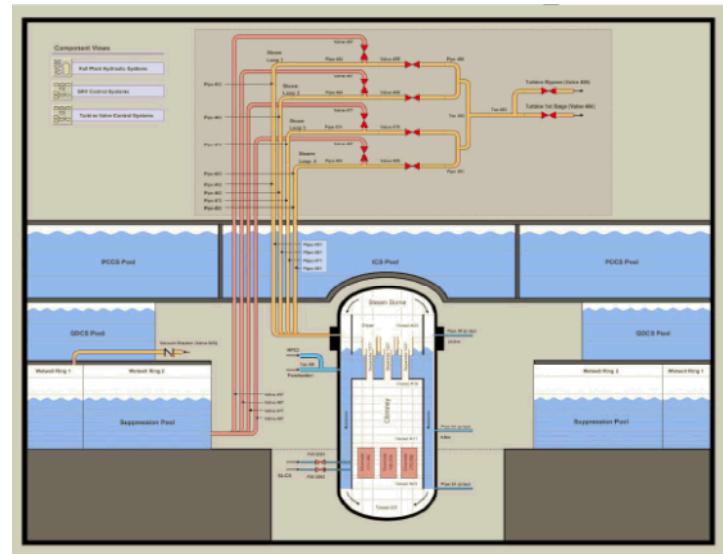
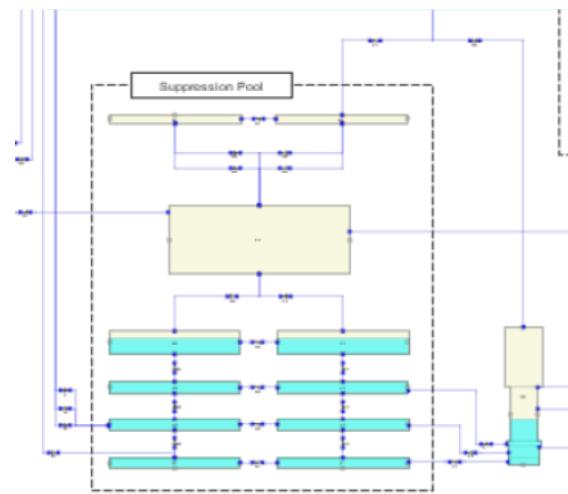


MELCOR Overview

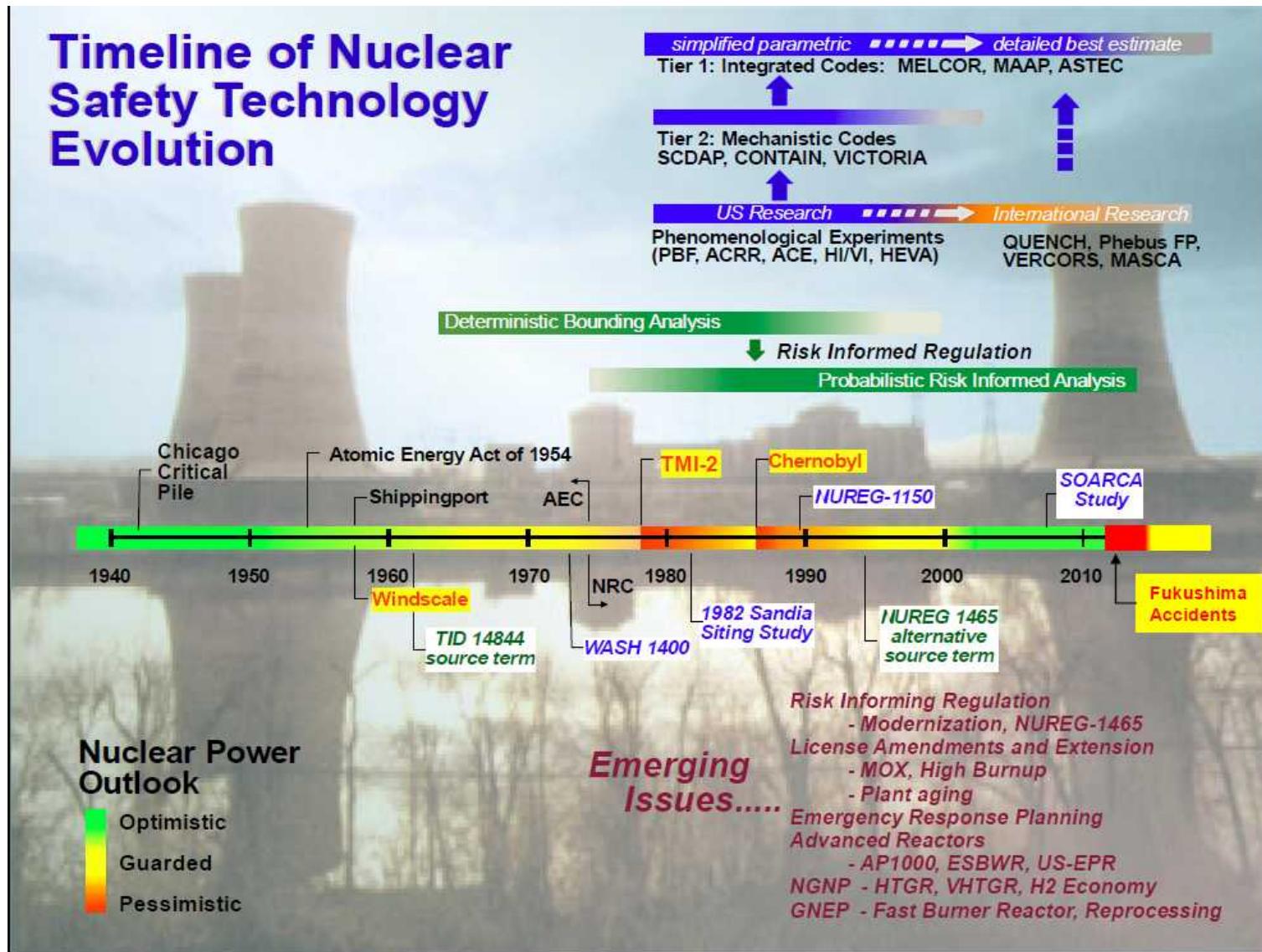
Workshop on Operational Experience and Advances in MELCOR Modeling
Shenzhen, China, November 19-23, 2012
Presented by Larry Humphries (llhumpf@sandia.gov)

What is the MELCOR Code

- NRC sponsored simulation code for analysis of accidents in nuclear power plants
 - Also applied to containment DBA simulation
 - PWR, BWR, HTGR, PWR-SFP, BWR-SFP
- Fully Integrated, engineering-level code
 - Thermal-hydraulic response in the reactor coolant system, reactor cavity, containment, and confinement buildings;
 - Core heat-up, degradation, and relocation;
 - Core-concrete attack;
 - Hydrogen production, transport, and combustion;
 - Fission product release and transport behavior
- Desk-top application
 - Windows/Linux versions
 - Relatively fast-running
 - One or two days common
 - One or two weeks possible
 - Project to improve code performance
 - SNAP for post-processing, visualization, and GUI



Timeline of Nuclear Safety Technology Evolution

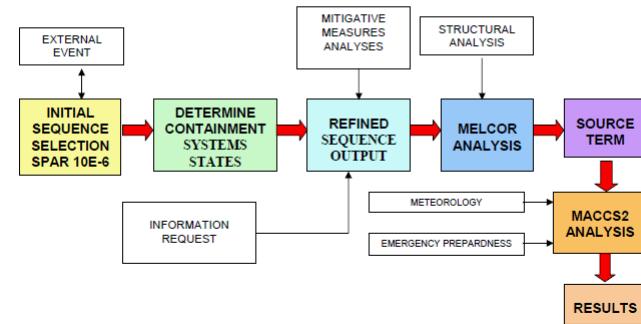


MELCOR Applications

- Forensic analysis of accidents
 - Fukushima, TMI
- State-of-the-art Reactor Consequence Analysis- SOARCA
- License Amendments
- Risk informed regulation
- Design Certification
- Preliminary Analysis of new designs
- Support of International Regulatory Bodies
- Non-reactor applications
 - Leak Path Factor Analysis
 - DOE Safety Software “Toolbox” code

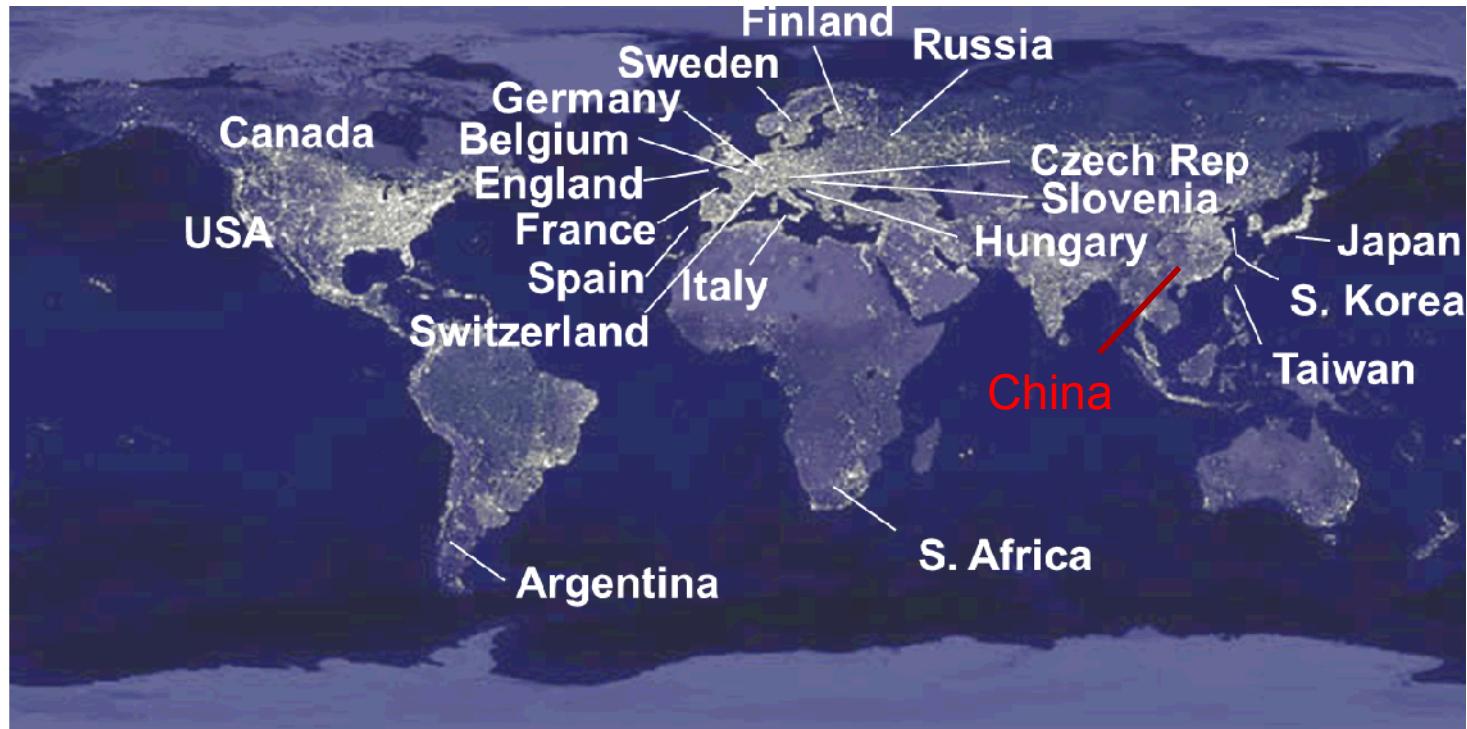


SOARCA PROCESS



MELCOR Users Worldwide

- Argentina
- Belgium
- Bulgaria
- Canada
- China**
- Czech Republic
- Finland
- France
- Germany
- India
- Italy
- Japan
- Mexico
- Netherlands
- Poland
- Russia
- S.Korea
- Slovak Republic
- South Africa
- Spain
- Sweden
- Switzerland
- Turkey
- UAE
- UK
- USA



MELCOR User Workshops and Meetings

- MELCOR Workshop
 - September 12-15, 2011
 - More than 70 participants
 - Use of SNAP
 - September 10, 2012
 - More than 90 registered
- MELCOR Code Assessment Program (MCAP)
 - September 22-23, 2011
 - September 13-14, 2012
- European MELCOR User Group (EMUG)
 - ENEA: April 11-12, 2011
 - GRS : April 16-17, 2012



MELCOR Documentation



NUREG/CR-6119, Vol. 1, Rev 3179
SAND2011-xxxx

MELCOR Computer Code Manuals

Vol. 1: Primer and Users' Guide Version 2.1 September 2011

Manuscript Completed: September 2011
Date Published:

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Sandia National Laboratories
Albuquerque, NM 87185-0739

Prepared for
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Office of Nuclear Regulatory Research
U.S. Nuclear Regulatory Commission
Washington, DC 20585-0001
NRC Job Code Y6802



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SAND2011-xxxx

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NRC Job Code Y6802



NUREG/CR-6119, Vol. 3, Rev. 0
SAND2001-0929P

MELCOR Computer Code Manuals

Vol. 3: Demonstration Problems Version 1.8.5 May 2001

Revised October 2000
Printed May 2001

Prepared by
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NRC Job Code W6203



Volume I: User Guide

Volume II: Reference Manual

Volume III: Assessments

Phenomena Modeled by MELCOR



- Goal of modeling “all” relevant phenomena is quite ambitious
- Main phenomena modeled include
 - Two-phase hydrodynamics, from RCS (Reactor Coolant System) to environment
 - Heat conduction in solid structures
 - Reactor core heatup and degradation
 - Ex-vessel behavior of core debris
 - Fission product release and transport
 - Aerosol and vapor physics
- Others will be mentioned in presentation
- There is no detailed neutronics model
 - Fission power history can be user-specified
 - Point kinetics model available

MELCOR Modeling Approach

- Modeling is as mechanistic as possible, consistent with a reasonable run time
 - “Reasonable” is up to the user, depends on level of detail
 - Original thought was “a few hours”
 - Some applications now run many days
- Some parametric models, where appropriate
- Uses general, flexible models
 - Relatively easy to model novel designs
 - Puts greater burden on analyst to develop input deck
- Allows sensitivity analyses
 - Many parameters accessible to user from input
 - Properties of materials, coefficients in correlations, numerical controls and tolerances, etc.

MELCOR Packages

- Major pieces of MELCOR called “Packages”
 - Each handles a set of closely-related modeling functions
 - Do *not* correspond to ancestral codes
- Three general types of packages in MELCOR
 - Basic physical phenomena
 - Hydrodynamics, heat and mass transfer to structures, gas combustion, aerosol and vapor physics, etc.
 - Reactor-specific phenomena
 - Core degradation, ex-vessel phenomena, sprays and other ESFs (Engineered Safety Features)
 - Support data and functions for general use
 - Thermodynamic equations of state, other material properties, decay heat generation data
 - Data-handling utilities, equation solvers

MELCOR Code Structure

- Code structure reflects basic phenomena more than reactor design
 - Same general control-volume/flow-path hydrodynamics used in reactor cooling system and containment
 - There is NO single package that deals with the vessel and all its contents or with a steam generator
- Time advancement for each package is largely independent
 - Reduces need for simultaneous solutions of many equations
 - Solution strategy for each can be appropriately chosen
 - Possible through carefully designed package interfaces
 - Restricted information exchange between packages
 - Use of partially-implicit “predictor/corrector-like” methods to deal with stiffness of equations

MELCOR Top-Level Control (1)

- Executive level coordinates other modules
 - Manages input, output, time step definition, etc.
 - Each package has its own i/o routines, called in turn
 - Time step chosen subject to various constraints
 - Executive input defines maximum and minimum timesteps
 - Any package can request a limit on timestep for next advancement
 - Executive considers all requests and reconciles with bounds
 - » Calculation will be terminated if no acceptable timestep
 - Controls time advancement of each package's data, in turn
 - Package coupling numerically explicit
 - Each package uses start-of-step data from other packages (with a very few exceptions, where end-of-step data are used)
 - Pass changes (e.g. heat and mass transfers) to other packages
 - Order of advancement chosen to facilitate this

MELCOR Top-Level Control (2)

- Executive deals with advancement problems
 - Any package can force a “fallback”
 - Problems in advancement of package itself
 - Convergence problem or other failure of solution algorithm
 - Change in properties too large (excessive rate of change)
 - Problems with end-of-step data from *another* package
 - Change too large (e.g. advection far overshoots ignition limit for combustion)
 - Requests repeat of advancement attempt with a reduced timestep
 - Executive provides graceful termination with final text edit and restart dump if advancement fails
 - Timestep less than minimum
 - Error in any package where reduced step wouldn't help
 - “Logic Error”, meaning occurrence of a situation that the code developer considered impossible

More about MELCOR Packages

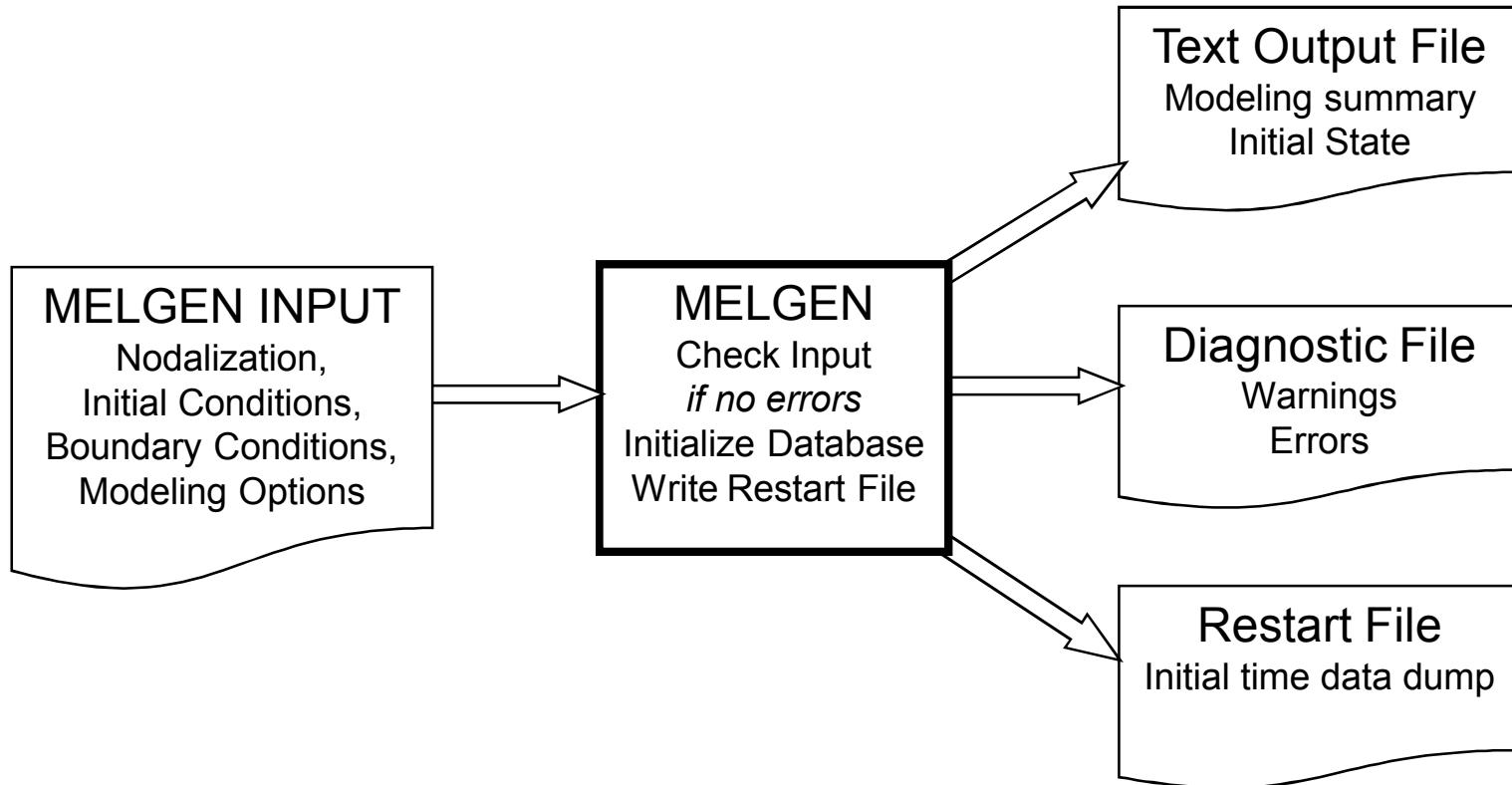
- Packages conventionally referred to by 2- or 3-letter names, mnemonic of functions, e.g.
 - Used extensively in input record identifiers
 - CVH (Control Volume Hydrodynamics) and FL (FLow path) treat the control volume and flow path portions of the hydrodynamic modeling
 - HS (Heat Structures) treats conduction in, heat and mass transfer to/from structures such as walls, floors, pipes
 - COR (CORe) treats reactor core response and degradation phenomena
 - MP (Material Properties) provides various properties
 - TF (Tabular Function) is a general table utility
- In general, no duplication of function
 - No in-line materials properties; (should) use MP package
 - All input data tables (should be) processed and stored by TF package

MELGEN and MELCOR

- “MELCOR” is actually two executables that perform different parts of the simulation
- MELGEN is run first
 - Its basic task is to set up the desired calculation
 - Problem definition, initial and boundary conditions
 - Has no time-advancement capability
- MELCOR is run next
 - Its basic task is to advance the simulation in time
 - Reads complete problem description from a file
 - Has limited ability to modify that description before starting the time advancement
- Two codes share many subroutines
 - I/O, properties, etc.

- MELGEN execution
 - Basic task is to set up the desired calculation
 - Input focuses on problem definition
 - Reads description of system to be simulated as provided through user input, including:
 - Nodalization to be used
 - Initial and boundary conditions
 - Modeling options
 - Checks input for completeness and consistency
 - Issues diagnostic warnings and/or error messages when appropriate
 - If (and *only* if) input contains no errors
 - Initializes all time-dependent data
 - Writes full text edit with model and state description
 - Writes restart file dump with complete database

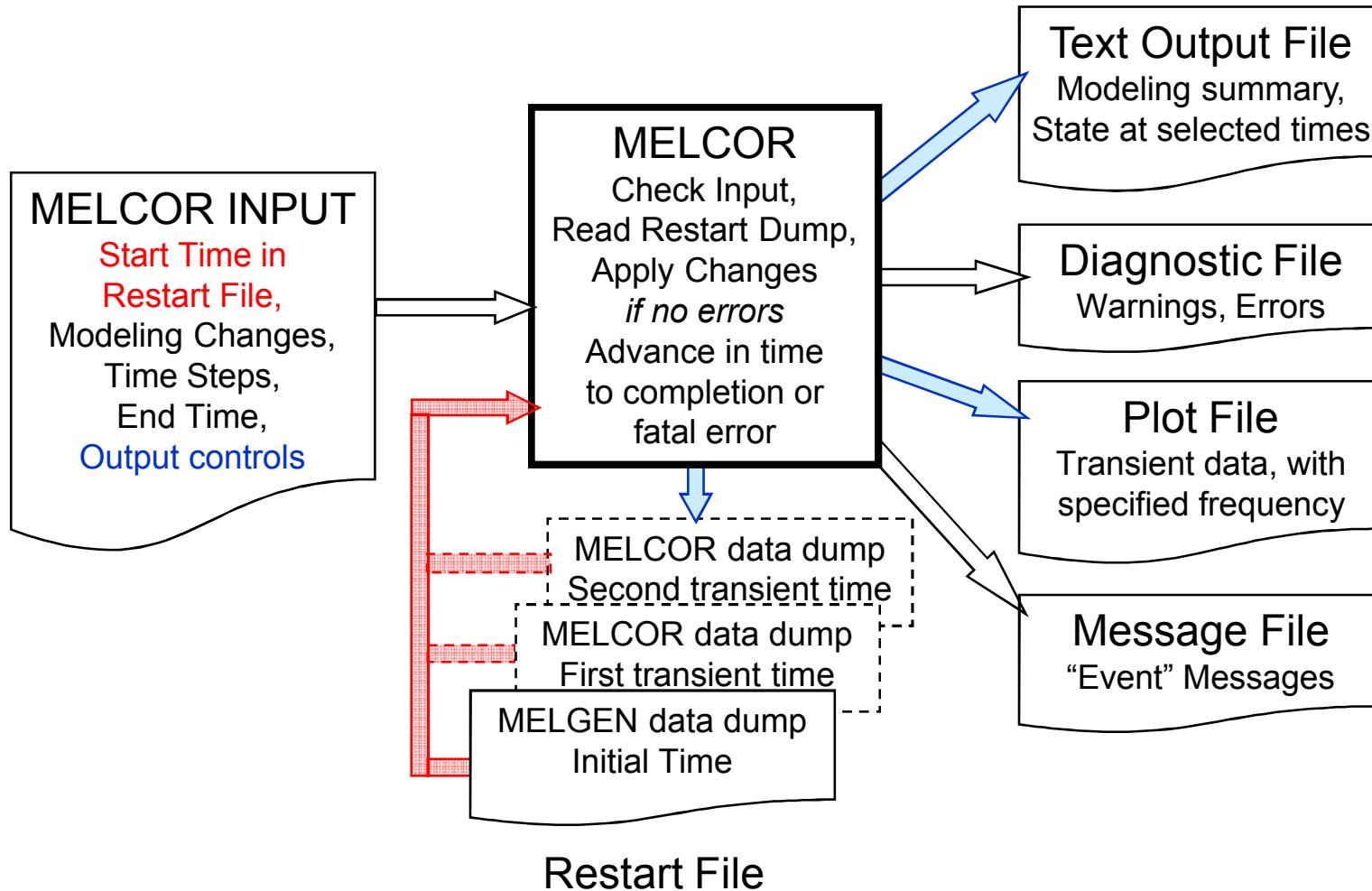
MELGEN Files and Information Flow



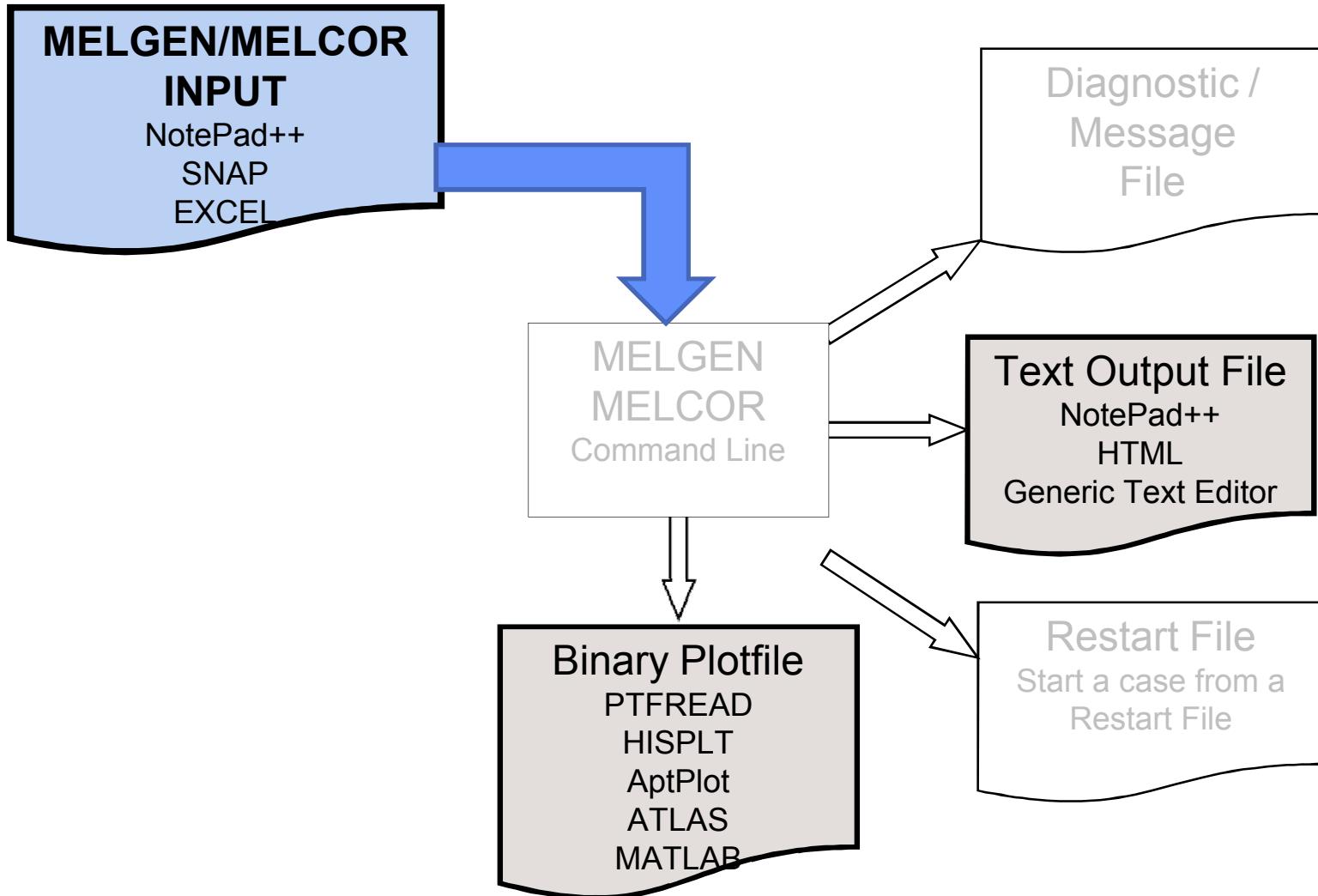
MELCOR

- MELCOR execution
 - Basic task is to advance simulation in time
 - Always run in “restart” mode
 - Reads time-independent and initial time-dependent data from a restart file “dump”
 - First restart written by MELGEN
 - Successive restart dumps from previous MELCOR run
 - Advances time-dependent data through time
 - Input focuses on control of advancement
 - Start time, end time, time steps, output frequency
 - Limited capability to modify problem description
 - Useful for sensitivity studies, treatment of branches in event trees
 - Recently added ‘Smart’ restart capability for modifying control functions
 - Writes text edits, restart, and plot files as requested
 - Any point in the restart file can be used as the initial state for a subsequent MELCOR execution

MELCOR Files and Information Flow

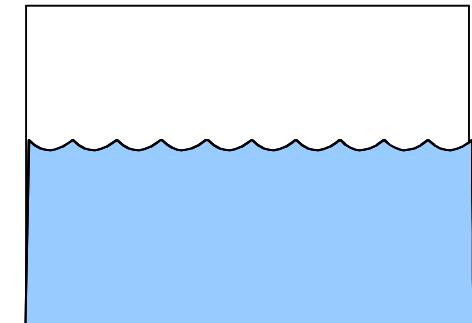


MELCOR I/O Tools

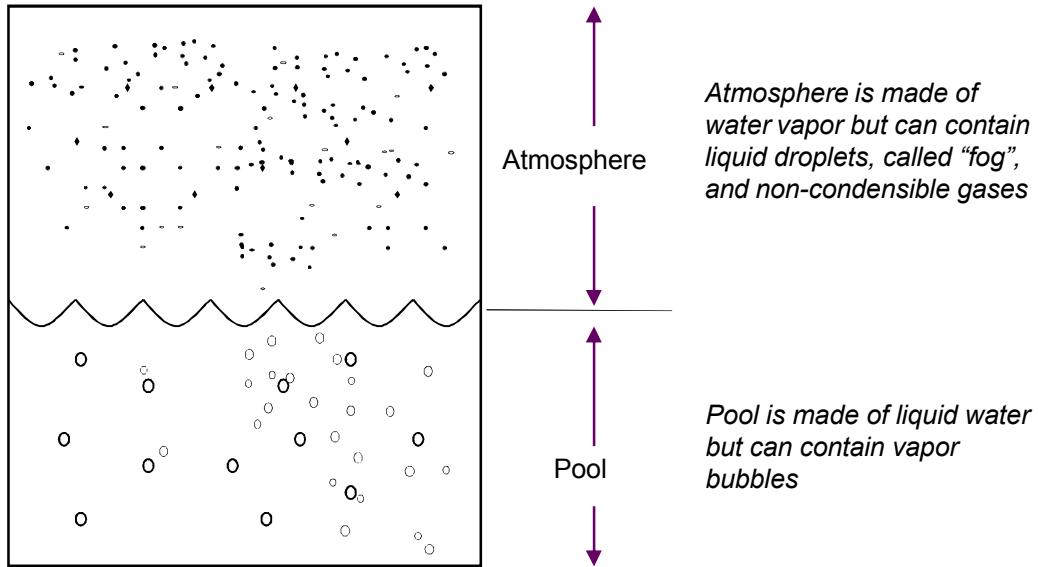


Control Volume Hydrodynamics (CVH) Package

- Definition of control volume
 - A region of space that contains hydrodynamic materials
 - User defines geometry from volume-altitude tables (no pre-defined shapes)
 - Thermodynamic states
 - Pressure and temperature
 - Equilibrium, non-equilibrium
 - Multi-Materials
 - Water, steam,
 - 14 noncondensable gases in atmosphere (H_2 , N_2 , O_2 , etc.)
 - Sources and Sinks
 - Mass and Energy
- Interfaces to almost everything else in MELCOR
 - Provides boundary conditions to other packages
 - “Sees” most other packages only as sources and sinks of mass, energy, and volume available to fluids
 - Zircaloy oxidation in core is a sink of H_2O with source of H_2 and/or sink of O_2
 - Movement of core debris changes volume available to fluids in CVH
 - Changes in core geometry can change flow resistance
 - Not default, requires optional user input to relate nodalizations



CVH Package (2)

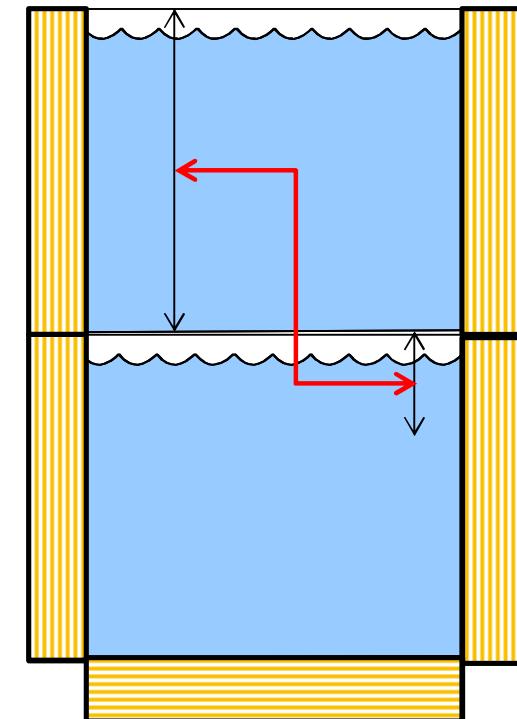


Pool and atmosphere are coupled. They exchange mass and energy due to condensation or evaporation

- CV contents partitioned into two fields:
 - Fields are called “pool” and “atmosphere”
 - Each is in complete internal thermodynamic equilibrium. Equal pressures, $P_{\text{pool}}=P_{\text{atm}}$

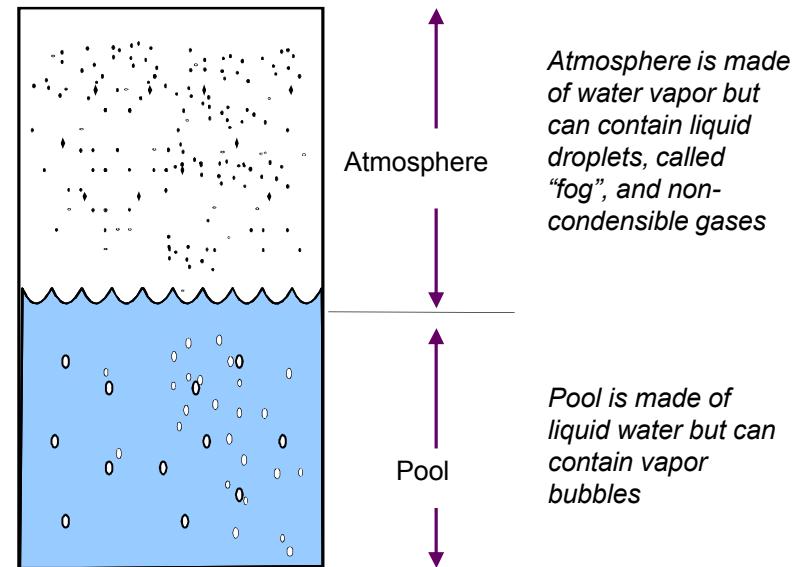
Flow Path (FL) Package

- All flow of hydro materials is through flow paths
- Each flow path connects two control volumes
 - One volume is referred to as the 'from' volume and the other as the 'to' volume thus defining positive flow
 - User specifies junction elevations and opening heights
- No volume, mass, or energy is associated with a flow path itself
- Each flow path is characterized by a nominal area and length.
 - The area may be modified by controlling the open fraction (e.g., to model valves)
- Wall Friction & Form Losses



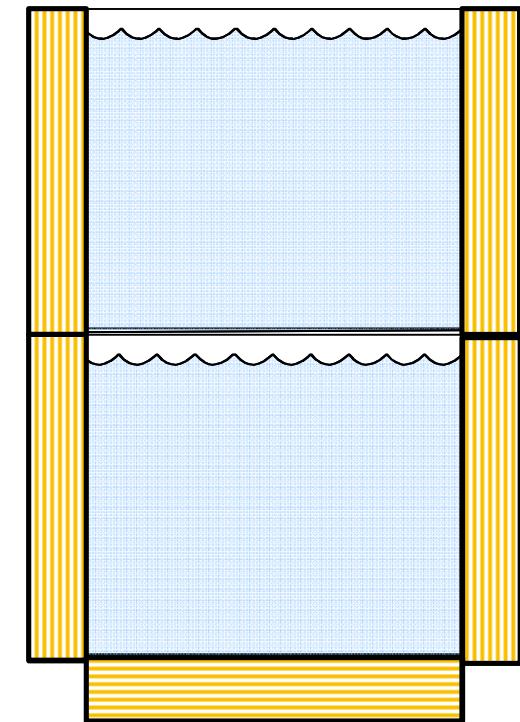
CVH/FL Package (2)

- Formulation of Equations
 - Four-field formulation
 - Continuous liquid (pool)
 - Continuous vapor (atmosphere)
 - Dispersed liquid (fog)
 - Dispersed vapor (bubbles)
 - Homogeneous equilibrium model (HEM) reduces 12 equations (mass, momentum & energy) to 6
 - Pool: Continuous liquid & dispersed vapor in equilibrium
 - Total Mass, total energy, same velocity
 - Atm: Continuous vapor & dispersed liquid in equilibrium
 - Total mass, total energy, same velocity
- Implicit Continuous-fluid Eulerian (ICE)
 - Substitute mass equation into momentum equation
 - Solve a matrix for velocity
 - Back solve for density
 - Pressure from linearized EOS
 - Iterate to get pressure correct



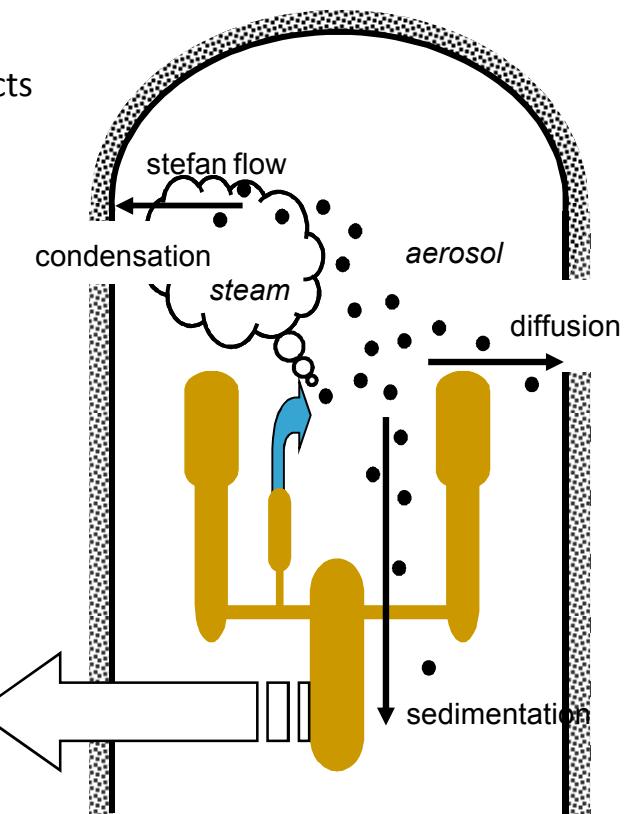
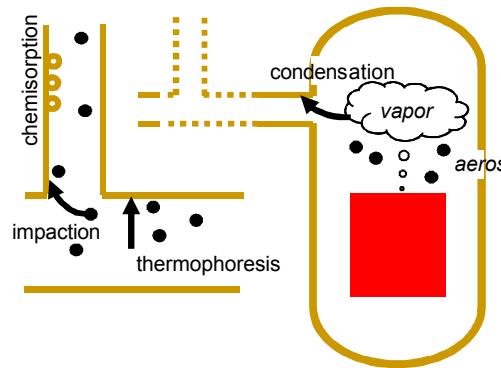
Heat Structure (HS) Package

- MELCOR heat structures used to model thermal response of solid objects
 - Used for everything except parts of core
- Limited ability to decompose or melt
 - Degassing of hot concrete, with gases to CVH
 - Melting of ice condensers, with water to CVH
 - Melting of core shroud, with debris to COR package
- One-Dimensional Conduction
 - Rectangular, cylindrical, spherical
- Surface boundary conditions
 - Interfaces with CVH
 - Condensation, evaporation
 - Radiation (to gases or other HS surfaces)
 - Adiabatic, specified temperature, specified heat flux
- Film Drainage models



RadioNuclide (RN) Package

- What is RN Package
 - Originally intended to treat behavior (release, transport, interactions) of RadioNuclides
 - Radionuclides are a source of decay heat
 - Important coupling to fuel, fluids, or HS surfaces
- Basic assumptions
 - RN materials are “traces”, hosted by other materials or objects
 - Fuel and/or debris
 - Hydrodynamic materials (pool and atmosphere)
 - Surfaces of heat structures
 - Mass, volume, heat capacity, are negligible
 - Temperature, when needed, taken as that of host
 - Radionuclides grouped into classes
 - Too many RNs to track individually
 - Grouped by similar characteristics (physical and chemical)



Ex-Vessel Debris Phenomena (1)

- If reactor vessel fails, debris can be ejected
 - Ends up on floor
 - Can interact with gases and/or water pools on the way
- CAV (CAVity) Package models behavior of “core on the floor”
 - Essentially CORCON Mod 3
 - Concrete ablation
 - Release of interstitial and hydrated water
 - Decomposition of hydroxides and carbonates
 - Addition of oxides to debris
 - Oxidation of metal in debris by released H_2O and CO_2
 - Mass sources, heat transfer to CVH fluids
 - Heat transfer from debris surface
 - Reduced gases, primarily H_2 and CO

Ex-Vessel Debris Phenomena (2)

- FDI (Fuel Dispersion Interactions) Package models interactions between vessel and floor
 - Use is optional, depends on user input
 - Low pressure melt ejection (LPME) option
 - Debris falls under gravity
 - Break up of debris in water pool
 - Heat transfer to water pool in CVH
 - High pressure melt ejection (HPME) option
 - More violent expulsion of debris
 - Heat transfer to CVH fluids
 - Oxidation of debris
 - Deposition of some debris on structure surfaces

Support Packages

- Equations of State, EOS Package
 - Implements a mixed-material equation of state for hydrodynamic materials (water and gases)
 - Water properties from H2O package
 - Keenan & Keyes formulation
 - Augmented by JANAF data (T>1589)
 - NonCondensible Gas properties from NCG Package
 - H2O and NCG properties are also available separately
- Materials Properties, MP Package
 - Provides thermal EOS for non-hydrodynamic materials
 - Provides thermophysical properties for all materials
 - Thermal conductivity, viscosity, diffusivity, etc
 - Mixture rules used where appropriate
- Decay Heat, DCH Package
 - Can provide whole-core decay heat and/or distribution of that heat among fission products (discuss later)

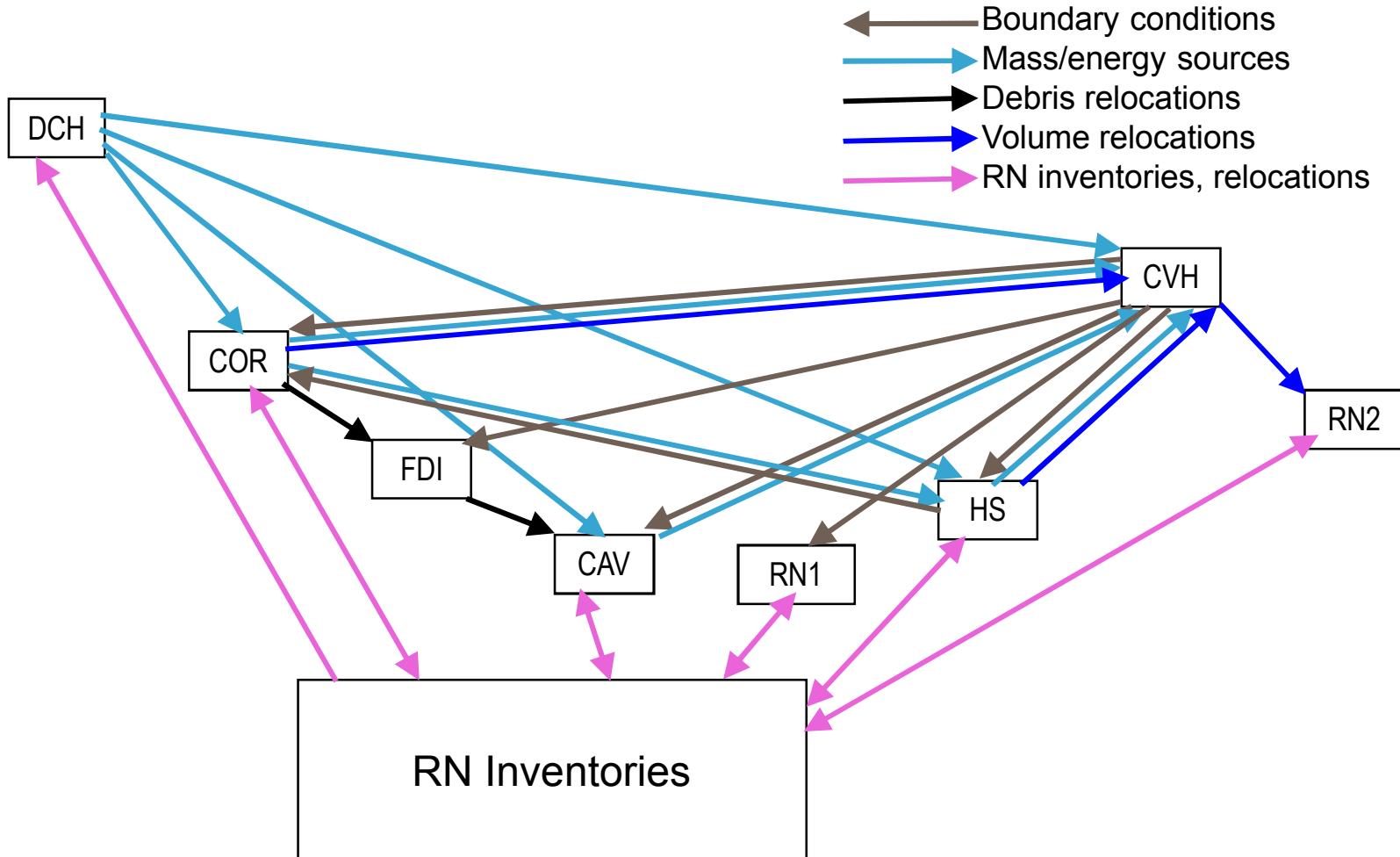
Phenomena Closely Tied to Hydro (1)

- BUR handles combustion (BURn) of H₂, CO
 - Permitted in any volume
 - Deflagration only (no detonations)
 - Includes modeling of igniters
- Various containment models, some grouped as ESFs (Engineered Safety Features)
 - SPR models containment SPRays
 - PAR models Passive Autocatalytic Recombiners
 - FCL models Fan CooLers
 - CND models an Isolation CoNDenser System (ICS) and/or Passive Containment Cooling System (PCCS)

Order of Advancement

- Advance packages that evaluate sources or relocations before those that use them
 - DCH: First to update time-dependent decay heat data
 - COR: Before CVH and HS that will receive heat/mass
 - SPR: Before CVH that will receive heat/mass
 - BUR: Before CVH that will receive mass changes
 - FDI: After COR to receive debris, before CAV and CVH
 - CAV: After COR and FDI to receive debris, before CVH
 - ESF: Before CVH
 - RN1: After COR and CAV to receive releases
 - HS: After COR to receive sources, before CVH
 - CVH: After COR, CAV, and HS to receive sources
 - RN2: After CVH to use fluid relocations

Information Communicated Between MELCOR Packages



Control Functions (CF) Package

- Control Functions, CF Package
 - Heart of MELCOR power and flexibility
 - Comes close to letting user write code as part of input
- Allows user input to define functions of MELCOR-calculated time-dependent variables
 - Values can be REAL or LOGICAL, are part of time-dependent database with all other time-dependent data
 - Calculated from definition using *current* conditions
 - Relatively easy, *very* flexible way to model complex systems
 - Older versions used own “language”, difficult to read
 - MELCOR 2.X adds ability to write function as a FORMULA, that looks much like fortran
 - Many (not all) variables are available as arguments

Control Function Use

- Can be used to generate custom output
 - Values can be printed, plotted
 - Change in value of logical can produce event message
- Function values can be used in calculations
 - Input to many packages allows reference to the value of a control function rather than a fixed constant
 - Sources, sinks, other boundary conditions
 - Allow dependence on current state
 - » Drain liquid currently present in volume with correct enthalpy
 - Valves, pipe failures, containment failures
 - Complex control logic
 - Larson-Miller cumulative damage strain model
 - Can provide simple modeling of systems (injection, cooling, etc.) when no internal model provided
 - Define mass/energy sources and sinks with appropriate logic
 - PAR could have been done entirely with CFs

MELCOR Code Development History



- MELCOR 1.8.2 (1993)
 - One of the earliest versions for widespread release.
 - Version not recommended for use
- MELCOR 1.8.3 (1994)
 - BH Package
 - CORCON-MOD3
 - Version not recommended for use
- MELCOR 1.8.4 (1997)
 - Retention of molten metals behind oxide shells
 - Vessel creep rupture model
 - Flow blockage model
 - Radiant heat transfer between HSs
 - Hygroscopic aerosols, chemisorption on surfaces,
 - SPARC 90
- MELCOR 1.8.5 (2000)
 - CF arguments could be added to plotfile
 - Consistency checks on COR/CVH volumes
 - Iterative flow solver added
 - Diffusion flame model
 - SS & NS components added for structural modeling
 - Upward & downward convective & radiative heat transfer from plates
 - Particulate debris in bypass introduced
 - Improvements to candling, debris slumping, and conductive, radiative, and candling heat transfer
 - PAR model was added
 - Csl added as a default class
 - Improvements to hygroscopic model
 - Iodine pool modeling
 - Carbon steel was added to MP package

MELCOR Code Development History



- MELCOR 1.8.6 (2005)
 - An option was added to generate input for the MACCS consequences model.
 - Input was added to simplify conformance with the latest best practices (now defaults in 2.x)
 - New control functions (LM-CREEP & PIP-STR) for modeling pipe rupture
 - Modeling of the lower plenum was revised to account for curvature of the lower head
 - Formation and convection of stratified molten pools
 - Core periphery model for PWRs to model core baffle/formers and the bypass region
 - Reflood quench model
 - Oxidation of B4C poison
 - Release of AgInCd control poison
 - Column support structures was added
 - Interacting materials added to allow modifying enthalpy tables
 - Spent Fuel Pool modeling
 - Flashing model
 - Modified CORSOR Booth release model added
 - Jet impaction model
 - Hydrogen chemistry models
- MELCOR 2.x (Beta release in 2006)
 - Code internal structure greatly modified
 - Dynamic memory allocation
 - New input format
 - Formula type control functions
 - New HTGR modeling (PBR, PMR)
 - Counter-current flow model
 - Point kinetics model
 - Smart restart
 - Simplified accumulator model
 - Ability to track radionuclide activities
 - Turbulent deposition model & bend impaction
 - Control function for deposition mass for each deposition mechanism.
 - MELCOR/SNAP interaction in real-time
 - Full report to user of sensitivity values
 - Cell-based porosity
 - Spent fuel pool models
 - Intermediate heat exchanger /machinery models
 - Hydrogen chemistry models

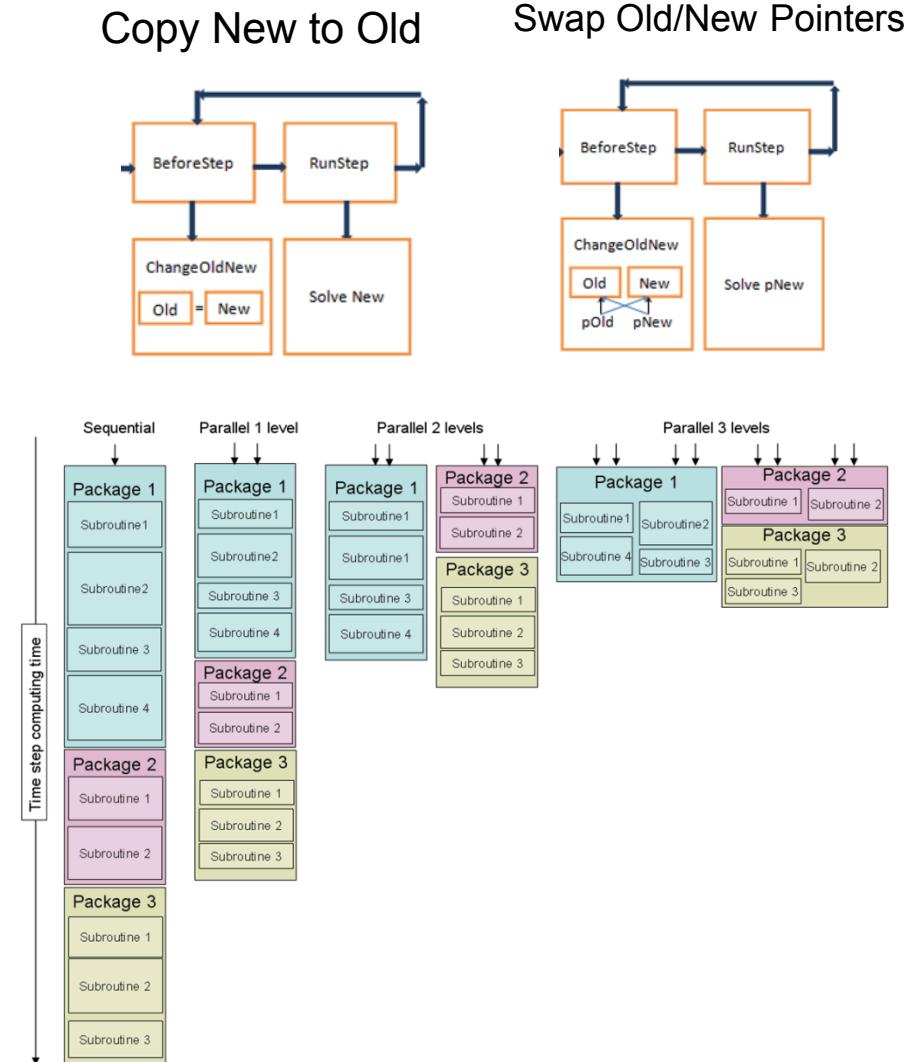
Upcoming/Ongoing Code Development



- Code Assessment and Publication of Volume III report
- CORQUENCH modeling to be added to CAV package
- CONTAIN modeling capabilities to be added to MELCOR
 - Modifications for correlations for CONTAIN/MELCOR parity
- Liquid metal reactors
 - Sodium properties to be added to MELCOR
 - Substitute working fluid
 - Other CONTAIN/LMR modeling to be added for modeling sodium fires

MELCOR Code Performance

- Ongoing work performed at Russian Academy of Science
- MELCOR code performance improvement strategies
 - Variables swapping
 - Numerical Solvers
 - Time step optimization
 - Parallelization
 - Package by package parallelization
 - MELCOR CVH/FL package parallelization results
 - RN1 and RN2 packages parallelization results
 - Further MELCOR code parallelization strategies



Discussion on MELCOR Overview

