

Grid-bridging Inverter Application at St. Mary's/Mountain Village Microgrid Systems

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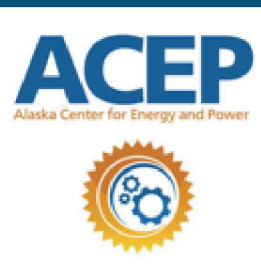
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Alaska Village Electric Cooperative (AVEC)

- Provides electricity to members in 58 communities
 - >40% of Alaska village population
 - Village sizes from ~100 to ~1,000 customers (100 kW to 3 MW)
- None connected to a transmission grid
 - Power generated locally utilizing diesel electric generators
 - Wind (11) and solar power in a subset of communities
- Interested in replicating successful approaches microgrid systems
 - Reducing fuel consumption while increasing resiliency



Alaska Center for Energy and Power (Univ. of Alaska-Fairbanks)

- Power Systems Integration Lab
- On the same scale as a village power system
 - Emulates isolated hybrid-diesel grid at up to 500 kW
 - 480 VAC three-phase, up to 600A
 - Wind, diesel, and grid-forming emulators
 - Fault/contingency scenarios



St. Mary's and Mountain Village, AK



St. Mary's, AK. Pop. 550
Peak load: 600 kW (winter)
Min load: 150 kW



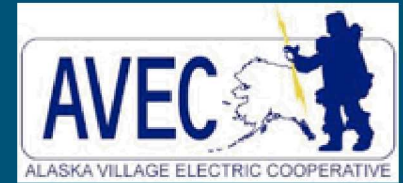
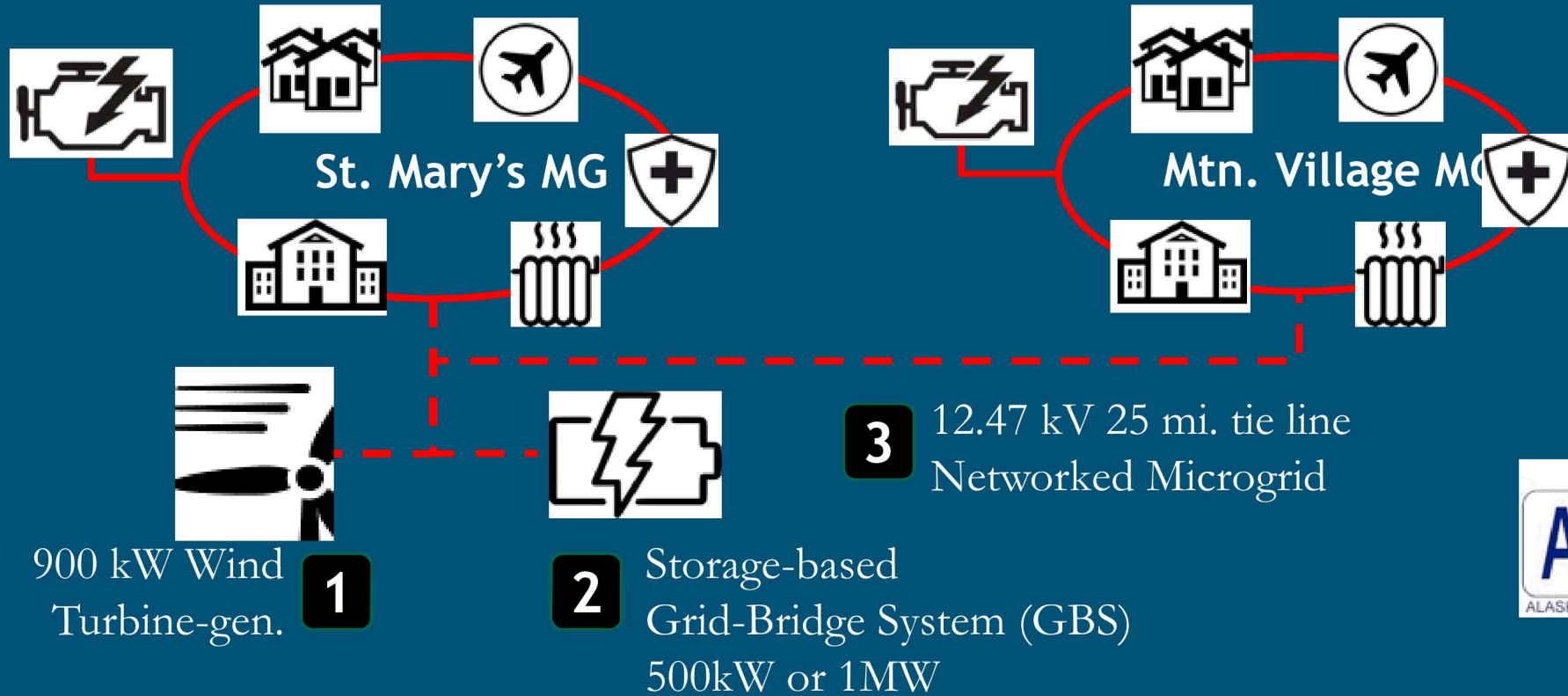
Mountain Village, AK. Pop. 820
Peak load: 500 kW (winter)
Min load: 150 kW



Energy Resilience Challenge:

- Both villages are rural microgrids supplied by diesel gensets
- Diesel fuel shipped up Yukon River, impassable August-April
- Life threatening issues if diesel runs out during winter
 - Necessity for high reliability, low maintenance components
- High energy cost, >25% of average household income

St. Mary's and Mountain Village, AK



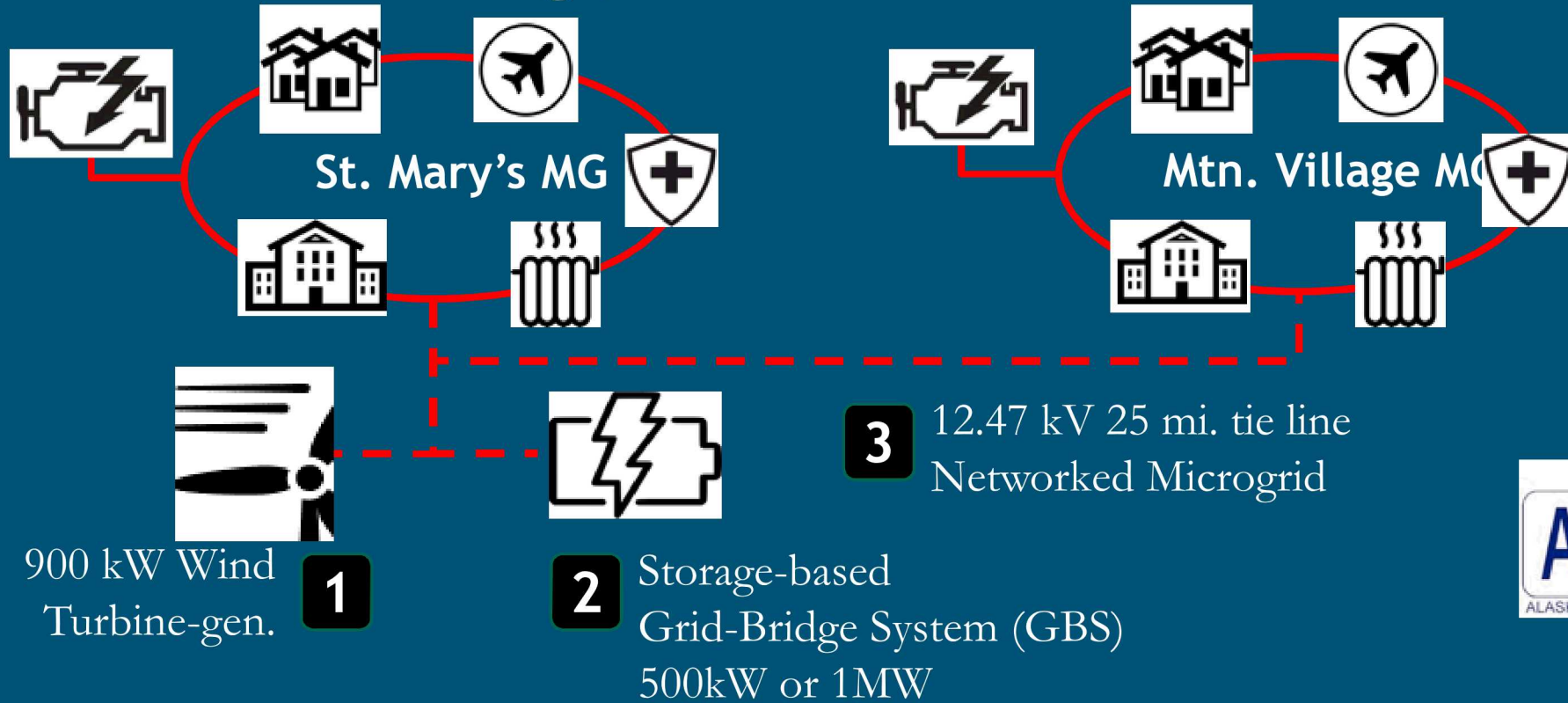
- Currently three diesel gensets (499 kW to 908 kW)
- Three-stage plan to lower costs and increase reliability and resilience
 1. Wind turbine-generator to reduce fuel use (DOE/IA)
 - EWT 900 kW Type IV pitch-controlled wind turbine generator
 2. Storage-based grid bridge system (GBS) for spinning reserve (DOE/OE + DOD/ONR)
 3. Network St. Mary's MG with Mountain Village MG via 12.47 kV tie-line

Currently Operational

Procurement Underway, est. Sept 2019

Currently Commissioning

St. Mary's and Mountain Village, AK

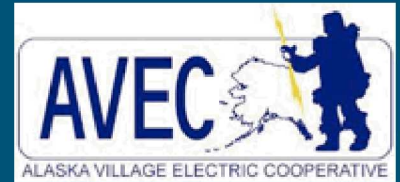
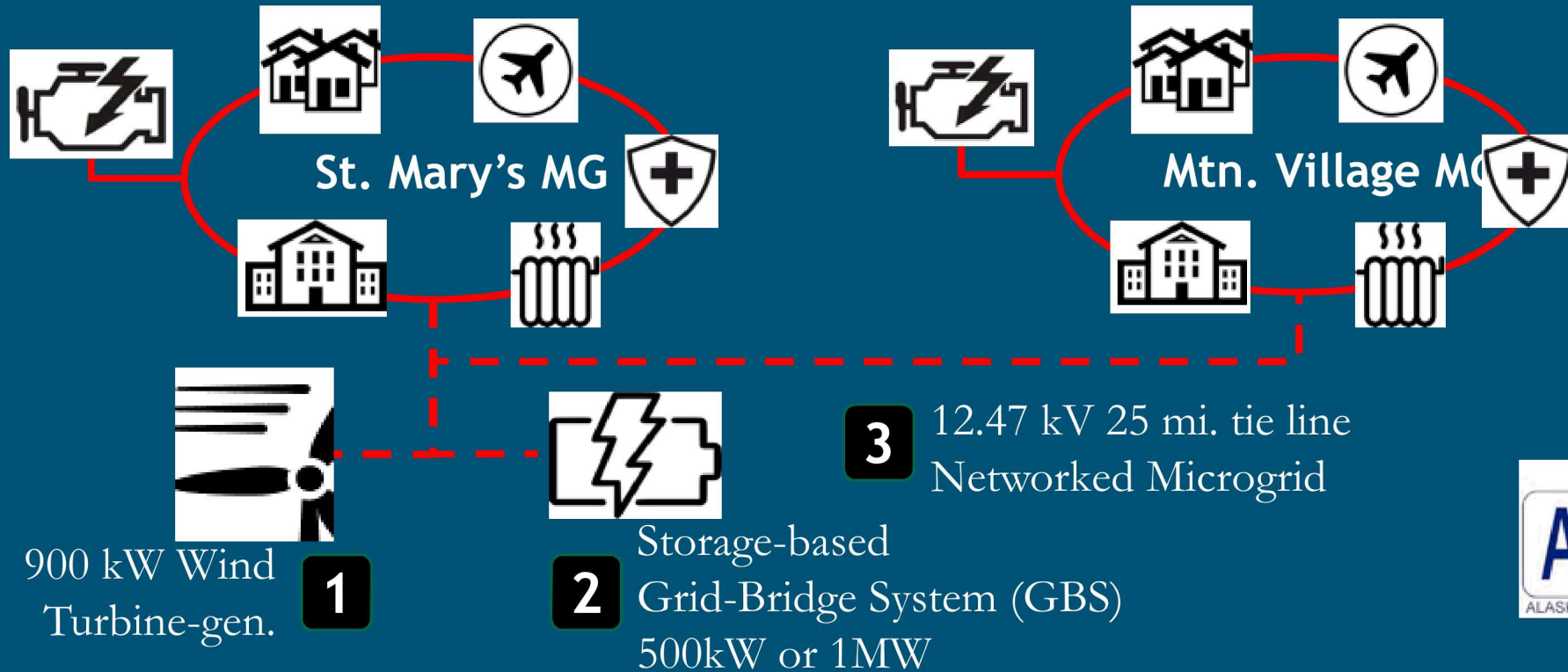


Grid Bridge System (GBS)

- For high stochastic distributed generation
 - potential loss of power quality due to constant shifting between generation sources
 - less efficient to provide operational (spinning) reserves from diesel generators
- In previous work, ACEP showed
 - significant operational cost savings from shifting spinning reserves to 'synthetic' reserves
 - Grid forming inverter backed by high power, low energy capacity storage system

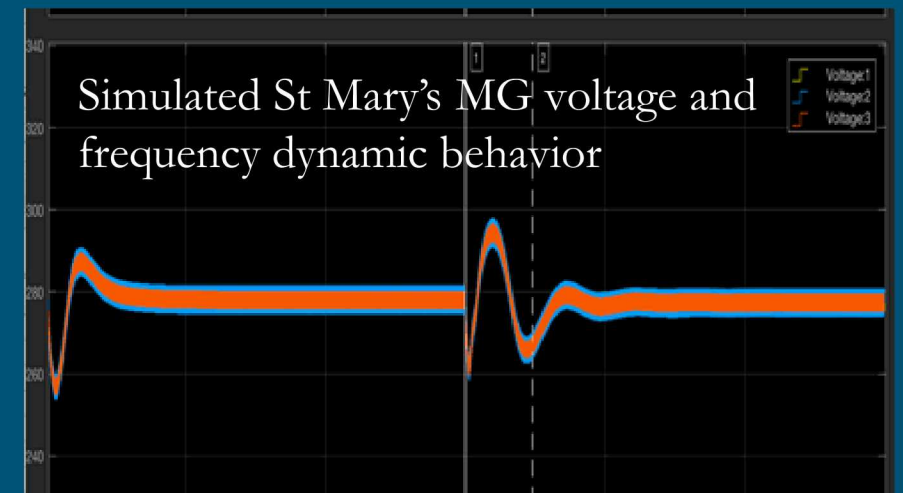
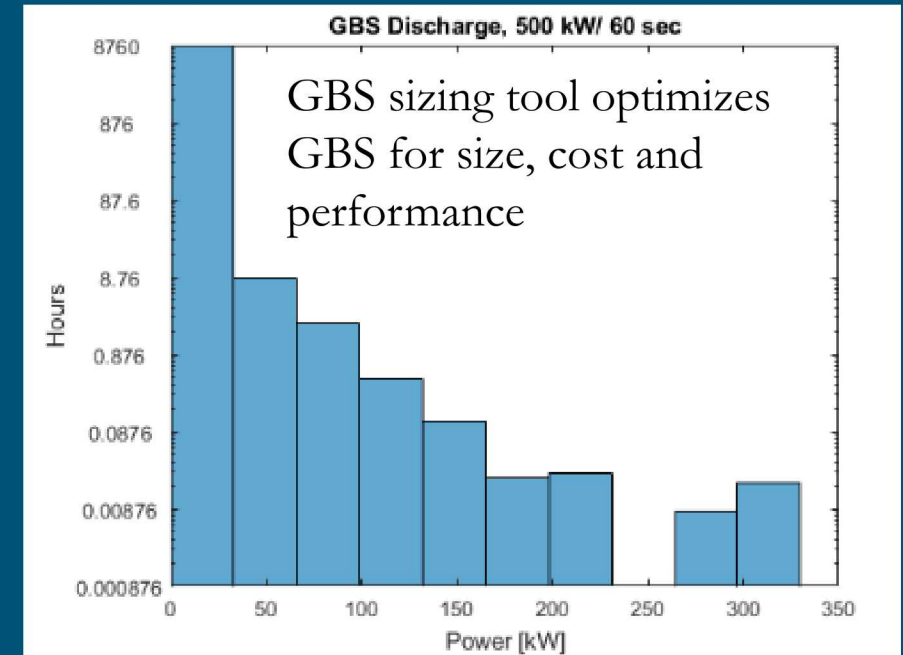
St. Mary's and Mountain Village, AK

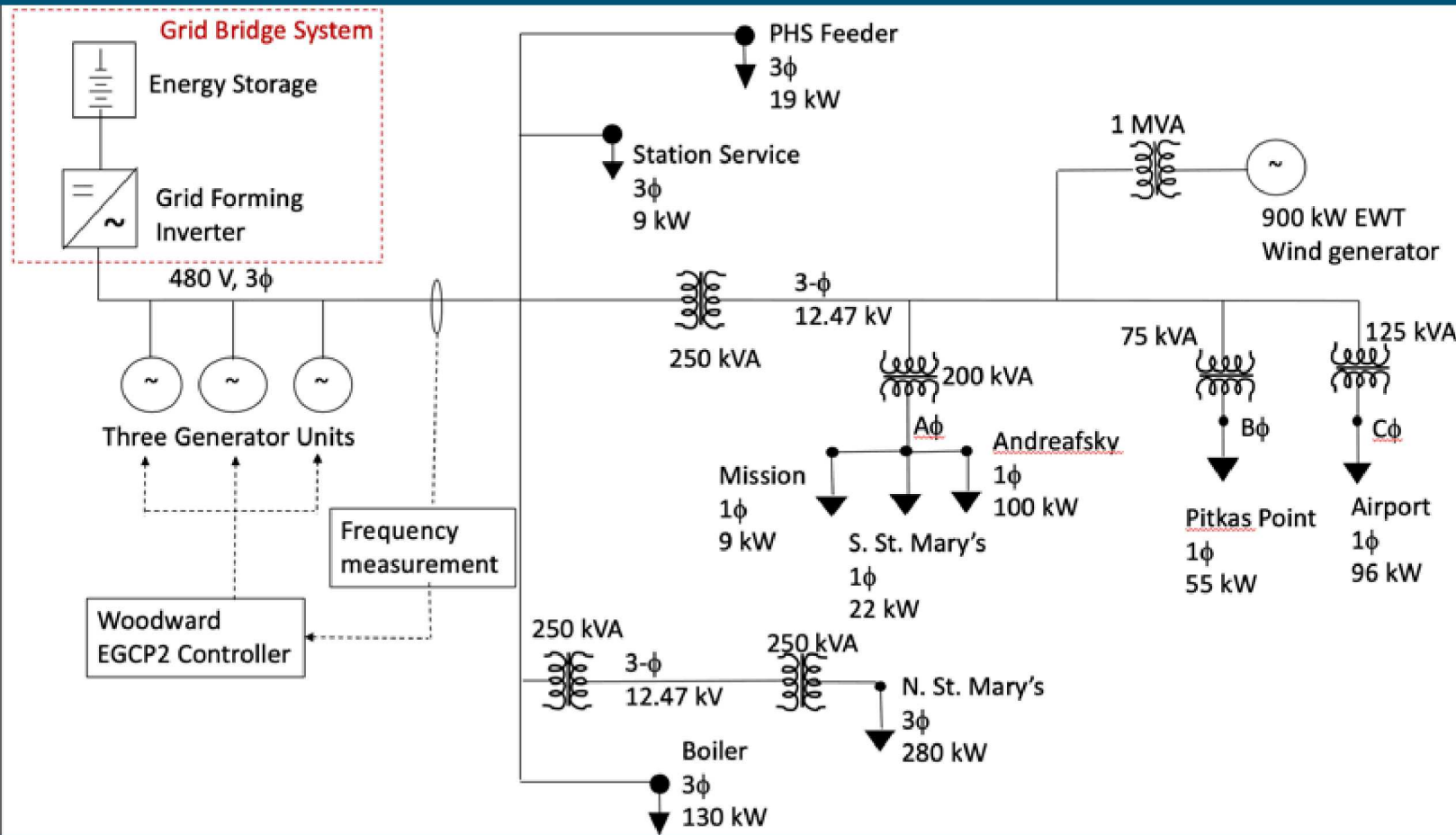
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- Primary use as spinning reserve and associated step-load capabilities
 - Fast frequency and voltage support whenever active (~200kW, 3 seconds, ~100,000 cycles/year)
 - Inherently stiff (low impedance) voltage source that will provide good transient support during events
 - Adjustable droop response for both frequency and voltage deviations
- Eventual goal to run in diesels-off mode
- Desire to replicate successful approach across other their hybrid-diesel microgrid systems
 - Applicable for any similarly sized microgrid faced with increasing penetration of renewables

- Sandia National Labs Alaska, Village Electric Coop (AVEC), and Alaska Center for Energy and Power (ACEP), partnering to study and demonstrate advanced renewable-based microgrids
- Planned outcomes:
 1. Validated open-source models for RE-based networked MG, including grid-forming inverters
 2. Demonstration of replicable and sustainable energy resilience solution for AK & beyond
 - 6 potential AK locations identified
 3. Identification of technology, standards and workforce gaps relevant to the deployment of islanded and grid-connected networked microgrids
 4. Open-source GBS optimal sizing tool for microgrid implementation





- Developed full Matlab Simulink model for the St. Mary's microgrid
 - includes developed models for diesel
 - wind turbine
 - Grid Bridge System
- System size based on average winter high consumption, provided by AVEC
- System has voltage imbalance of $\sim 5\%$
- Implemented on Real Time simulator (Opal RT)
 - Allows for Hardware-in-loop testing

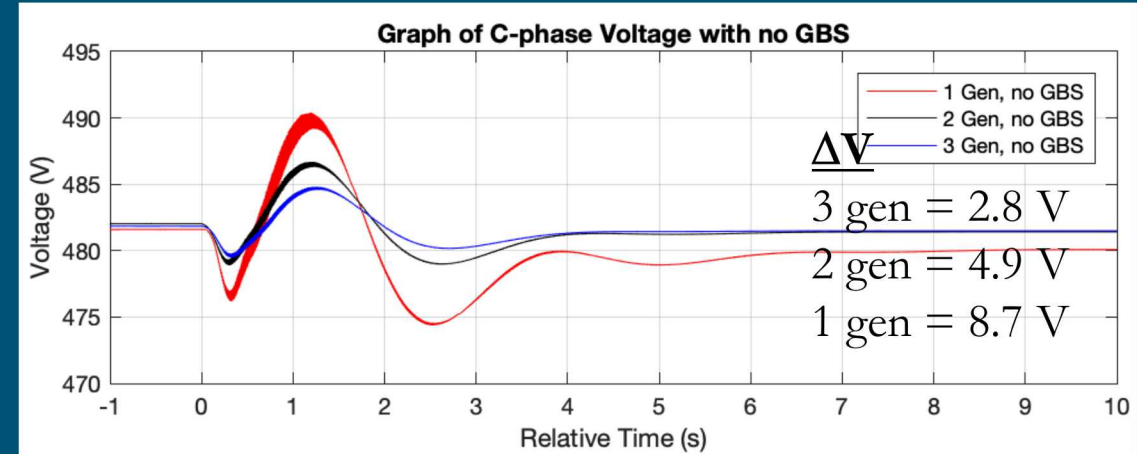
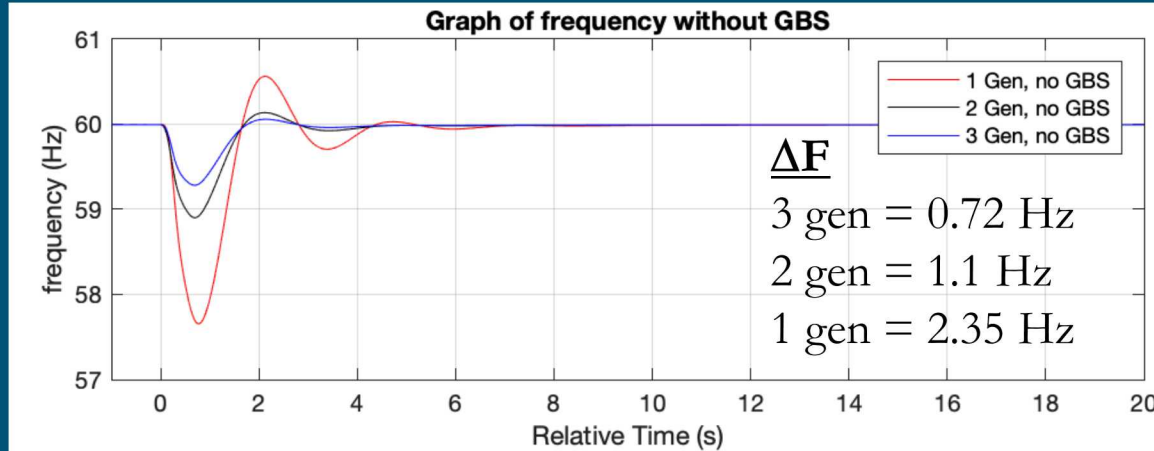
GFM can be used to provide spinning reserve

Evaluated GBS ability to provide spinning reserve for loss-of-wind scenario

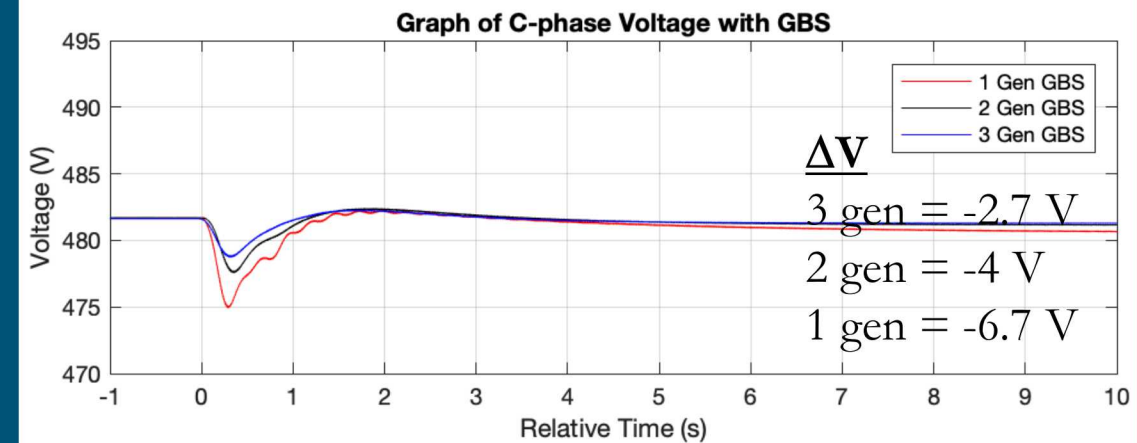
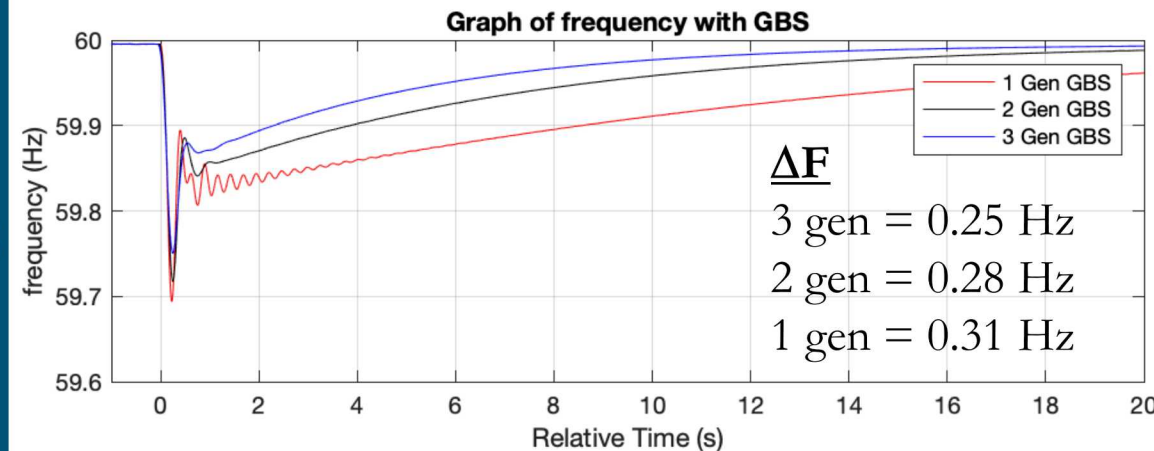
Frequency

Voltage

No GBS



With GBS



Contingency event:
Wind penetration 85% \rightarrow 15% in 2s

GFM can be used to provide spinning reserve

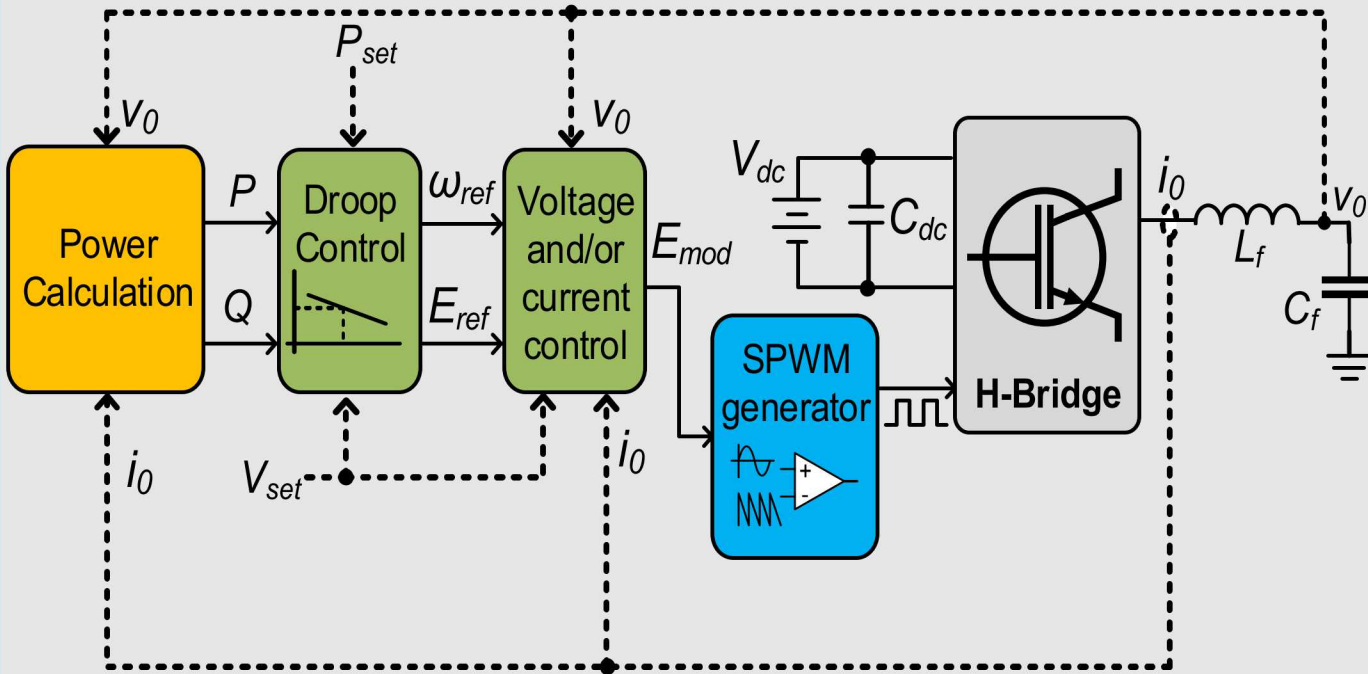
Evaluating different control schemes and differences in providing spinning reserve



AVEC

ACEP

Center for Energy and Power



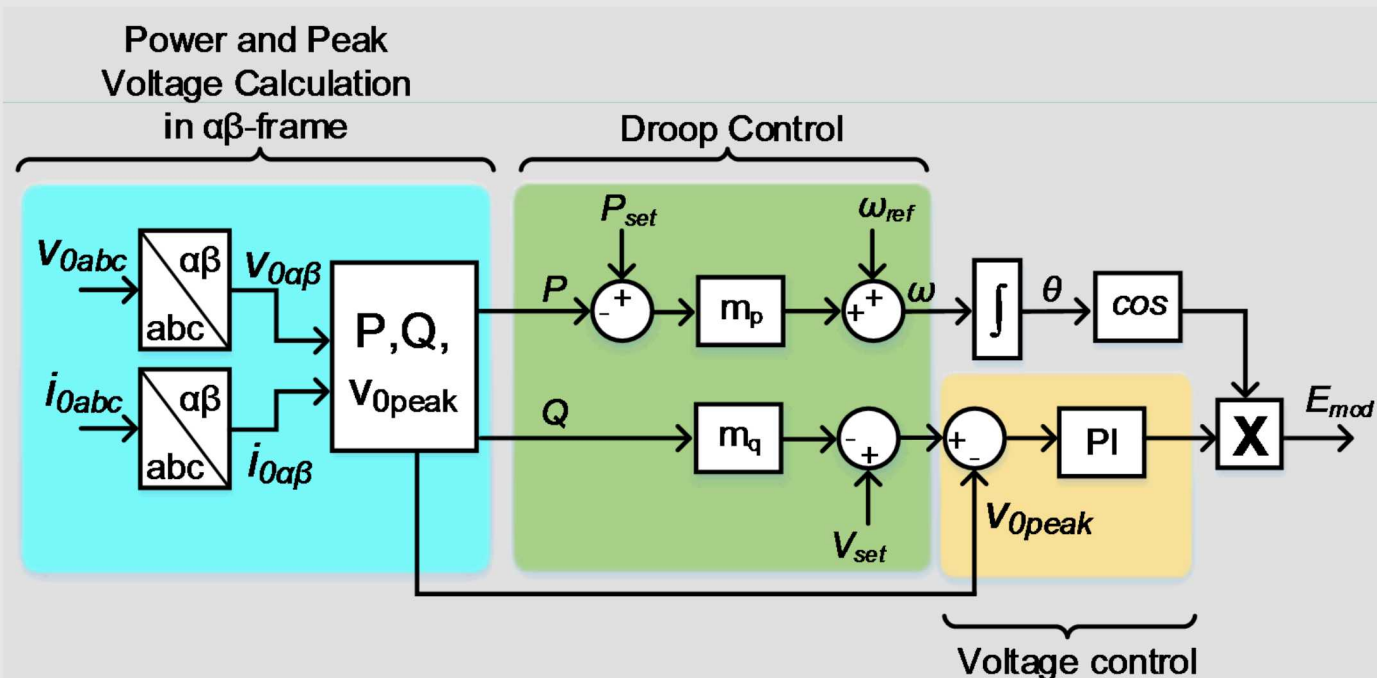
- Both share the same generic control scheme
- After the power calculation block, notice that droop control is a fundamental part of the control scheme

➤ Need some more info about “generic” GFM

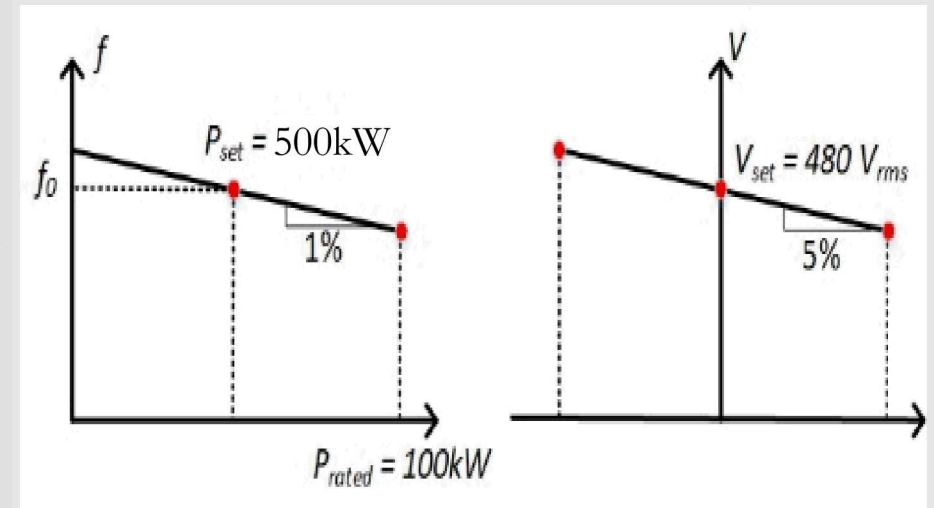
Open-source models for RE-based networked MG

GBS model based on CERTS control

- Consortium for Electric Reliability Technology Solutions (CERTS) formed in 1999
- Droop control (freq. and voltage) to allow flexible hybrid microgrids (Plug-and-play)
 - No single component (e.g. master controller) required for operation of the microgrid
- Output variables i_o and v_o are mapped into the $\alpha\beta$ -frame
- PI controller is used to regulate the voltage reference provided by the voltage droop stage



S_{base}	500 kVA	KP_{vol}	6.1
V_{base}	480 Vrms	KI_{vol}	0.001
m_p	0.01	L_f	0.8 mH
m_q	0.05	C_f	1500 μ F
C_{dc}	10000 μ F	V_{dc}	900 V

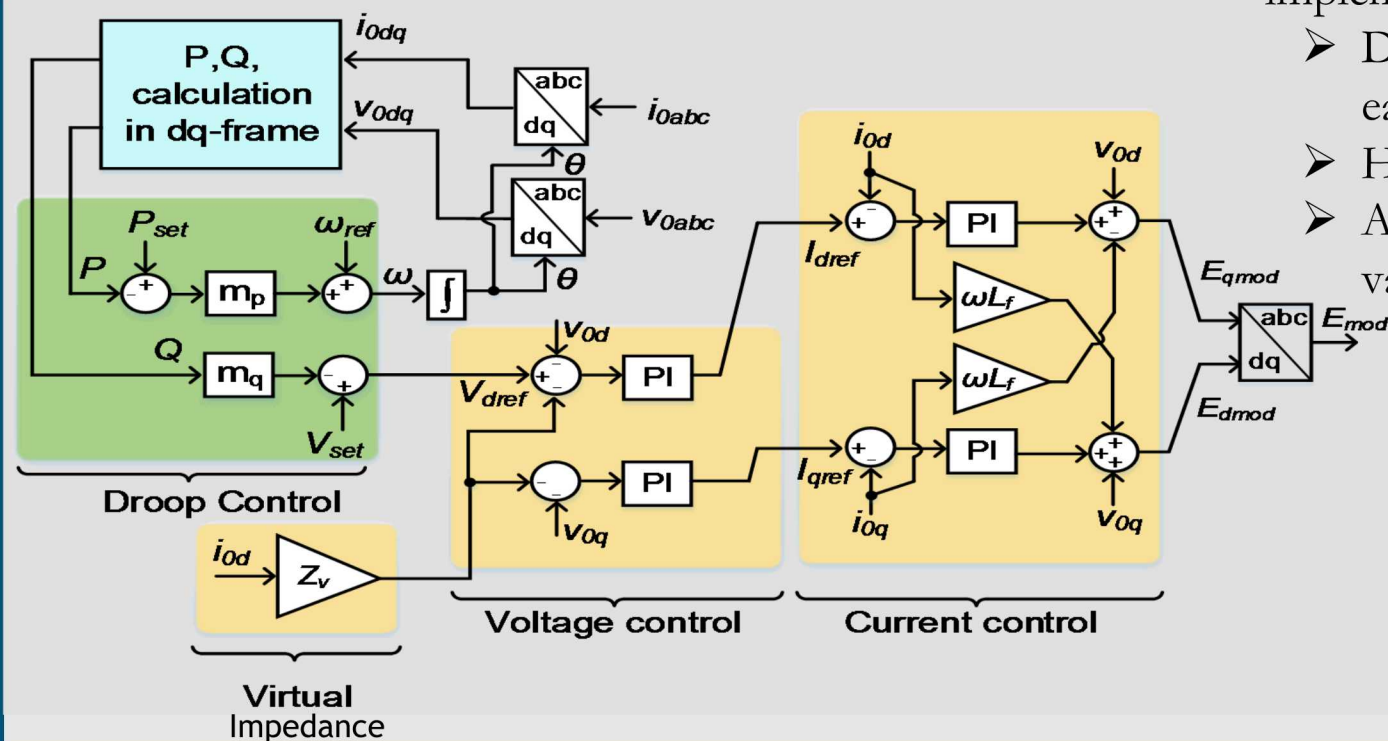


Open-source models for RE-based networked MG

GBS model based on DQ control with virtual impedance

- Same generic control scheme as CERTS, but different voltage regulation scheme
 - Frequency-droop scheme dictates the frequency according to load demand
 - dq -frame transformation
 - used to calculate the real and reactive power in real time
 - q -component reference (V_{qref}) is normally set to zero (lack of negative sequence)

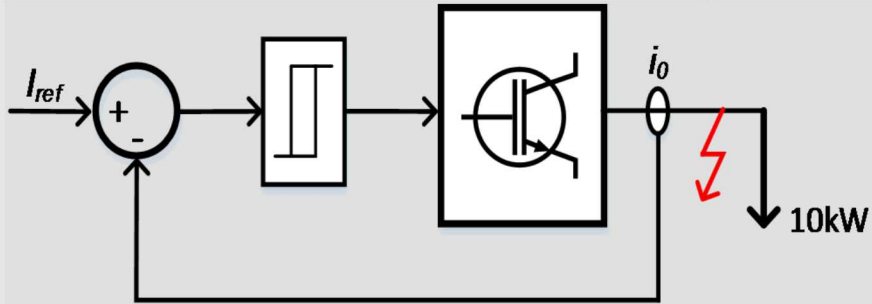
- Compensation of the cross-coupling ωL_f terms must be implemented
 - Decouple the dynamics of each current control loop from each other
 - Highly dependent on system impedance \rightarrow stability issues
 - Addition of virtual impedance (Z_v) stabilizes model for variety of system impedances



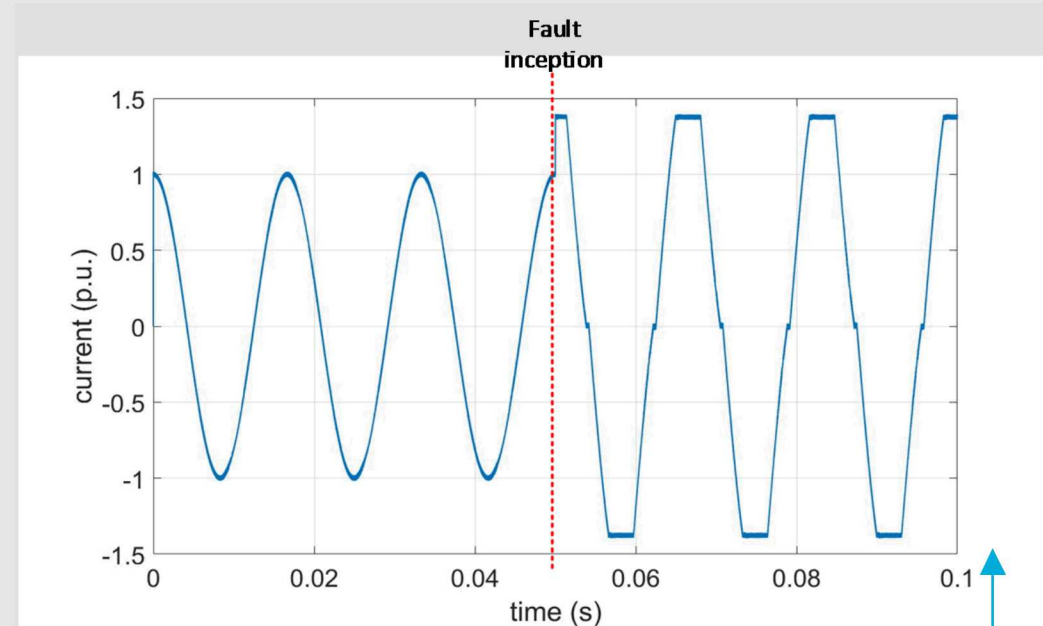
S_{base}	500 kVA	KP_{vol}	1.0
V_{base}	480 Vrms	KI_{vol}	10.0
m_p	0.01	L_f	3.0 mH
m_q	0.05	C_f	100 μ F
C_{dc}	10000 μ F	V_{dc}	900 V
KP_{curr}	5.663	KI_{curr}	1700

Open-source models for RE-based networked MG

GBS model based on Hysteresis control

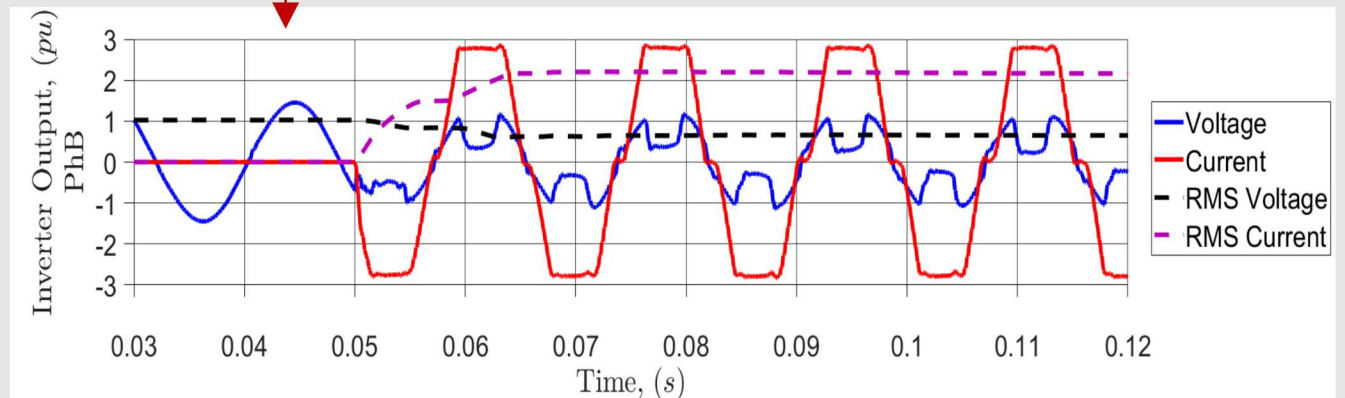


- Control switching scheme based on hysteresis
 - facilitates the four-quadrant operation of the inverter as an AC current source into a grid regulated for voltage and frequency
 - hysteresis comparison implemented by using output current of the inverter
- Validated against real GFM
 - fault applied at the terminals of the inverter supplying rated power (10 kW) at a time of 0.05 s
- Fault behavior shows a good qualitative match to the experimental fault behavior
 - inverter current saturates in a near square wave behavior
 - characteristic shoulder at a current of 0 p.u
- Further work is ongoing to implement full closed loop control

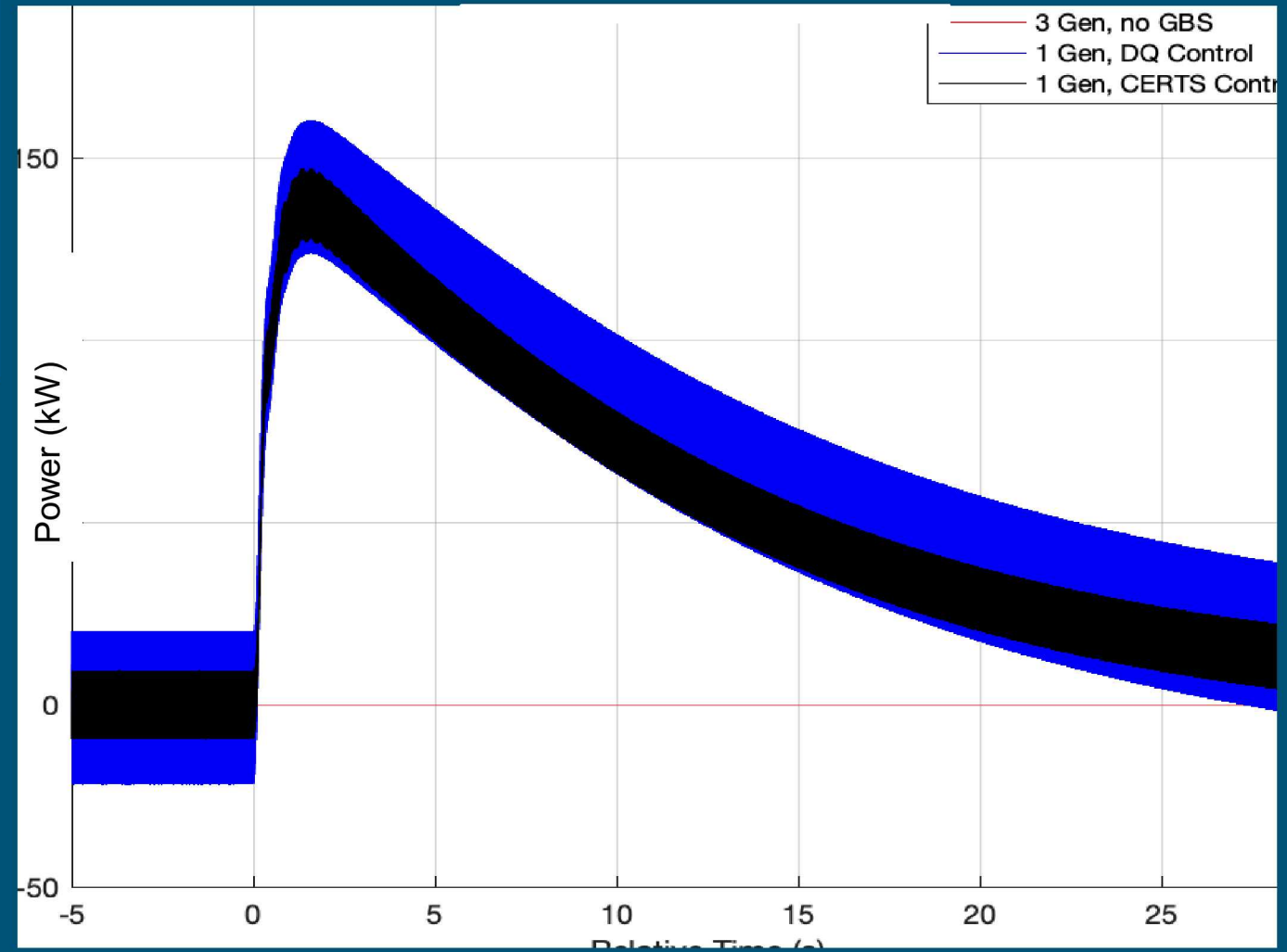


Experimental

Simulated

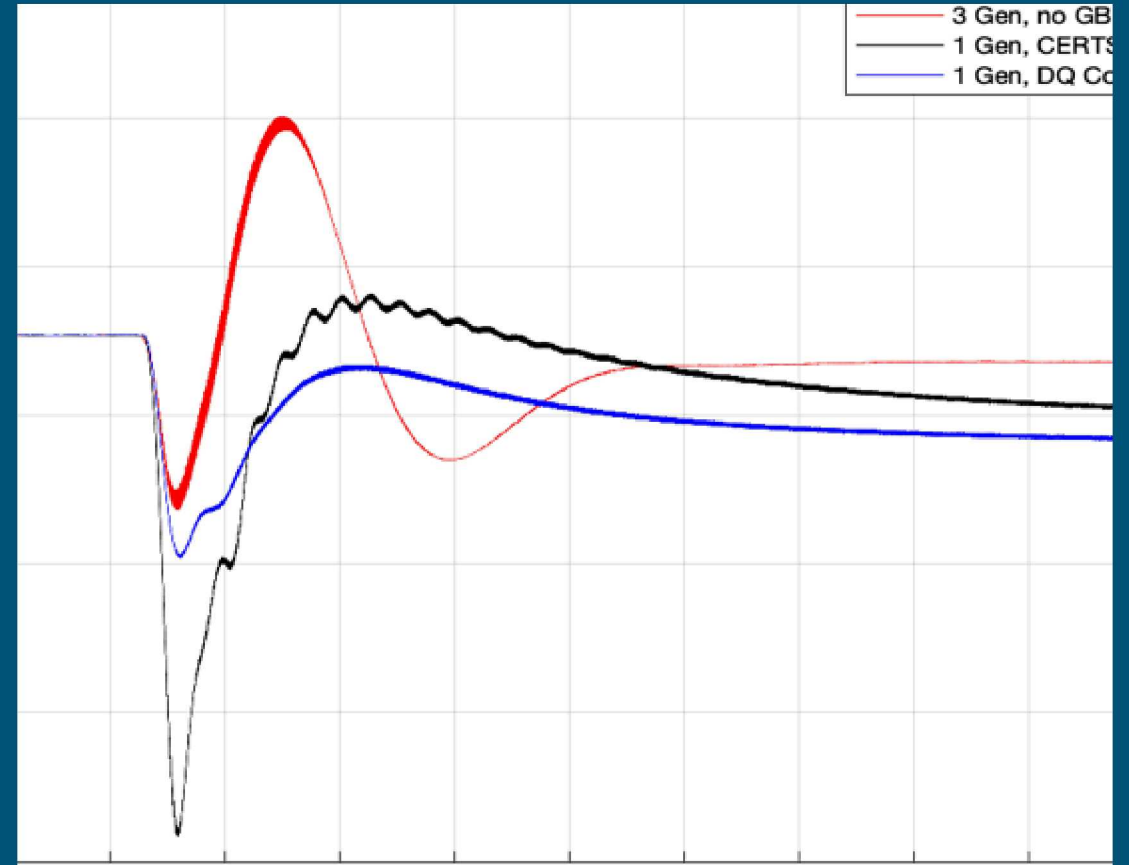
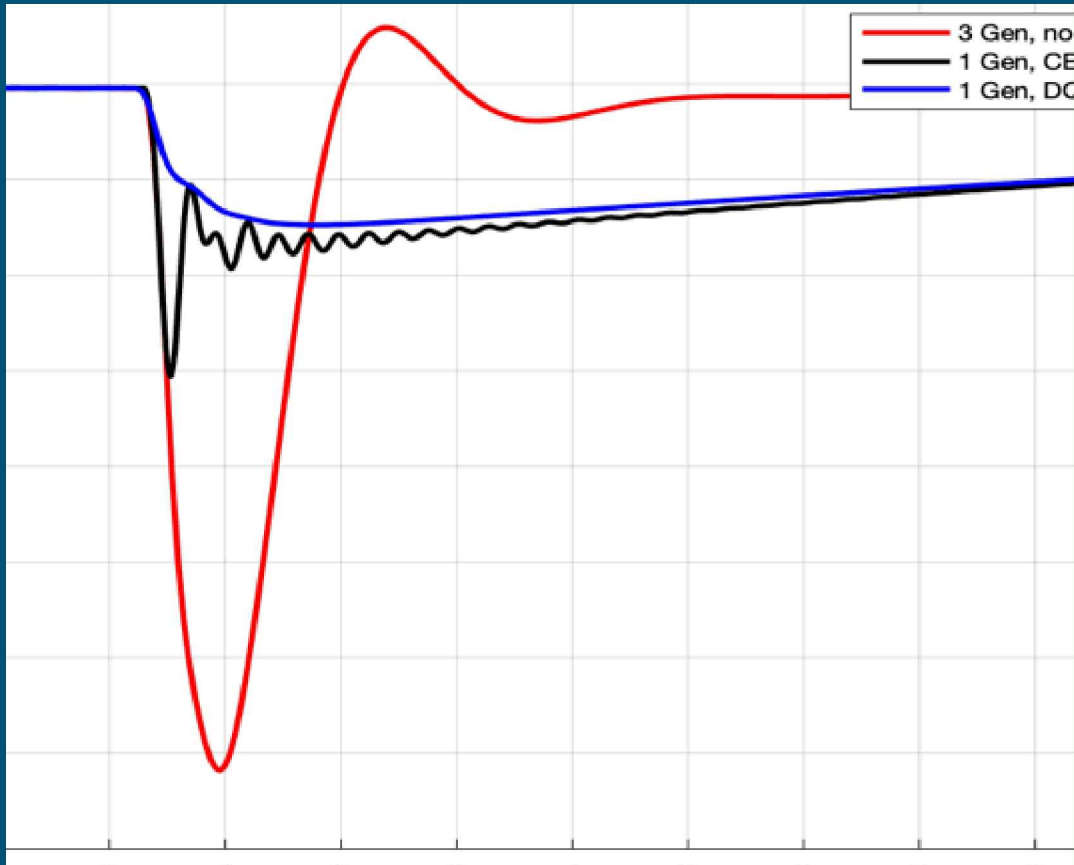


- Both DQ and CERTS droop control can provide spinning reserve
 - Have not compared Hysteresis control yet
- Respond to frequency injection within ~ 1 s
 - Tail off gradually to 30s
 - Allows time for generation to spin-up



Open-source models for RE-based networked MG

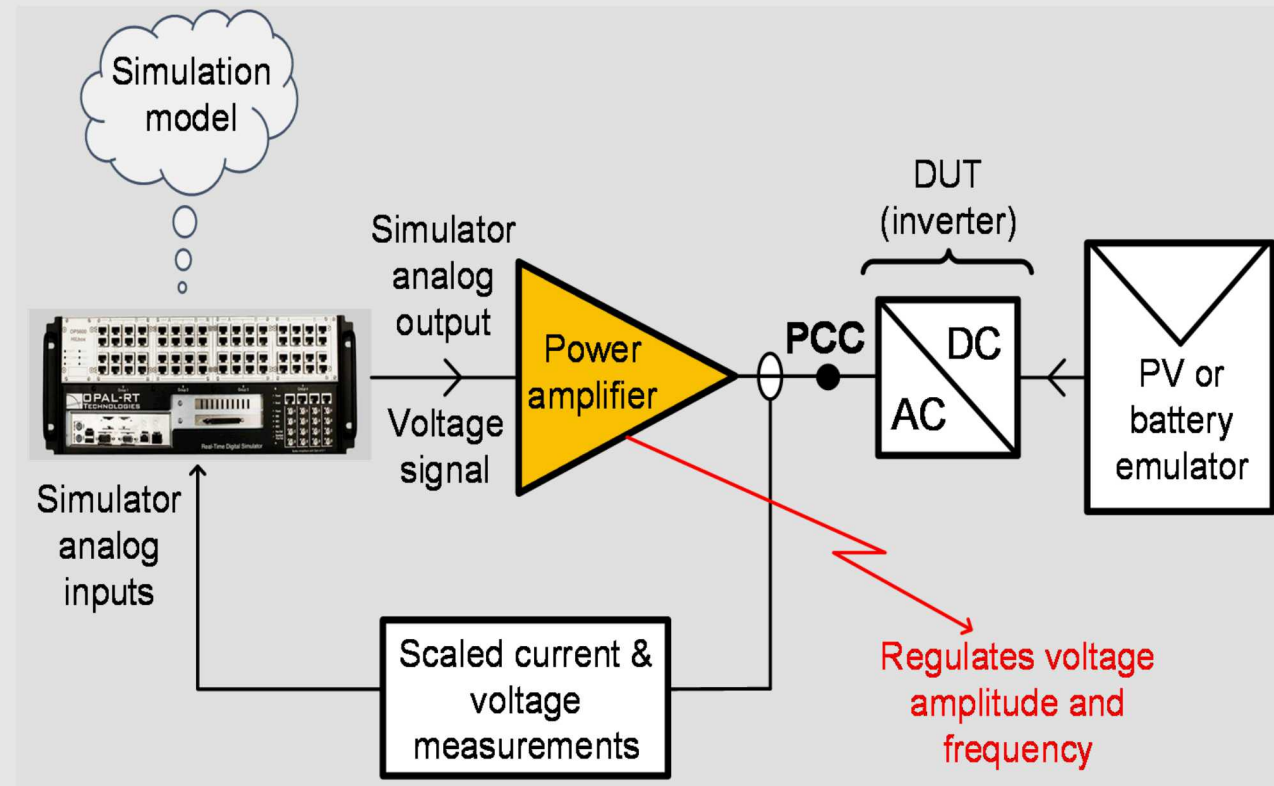
- GFM results in better frequency and voltage response than splitting spinning reserve among 3 generators
- DQ control demonstrates better response to voltage and frequency
 - Smooth frequency nadir and response
 - Faster voltage arresting
 - CERTS control suffers from some oscillatory behavior



Power Hardware in Loop Validation of GFM for spinning Reserve

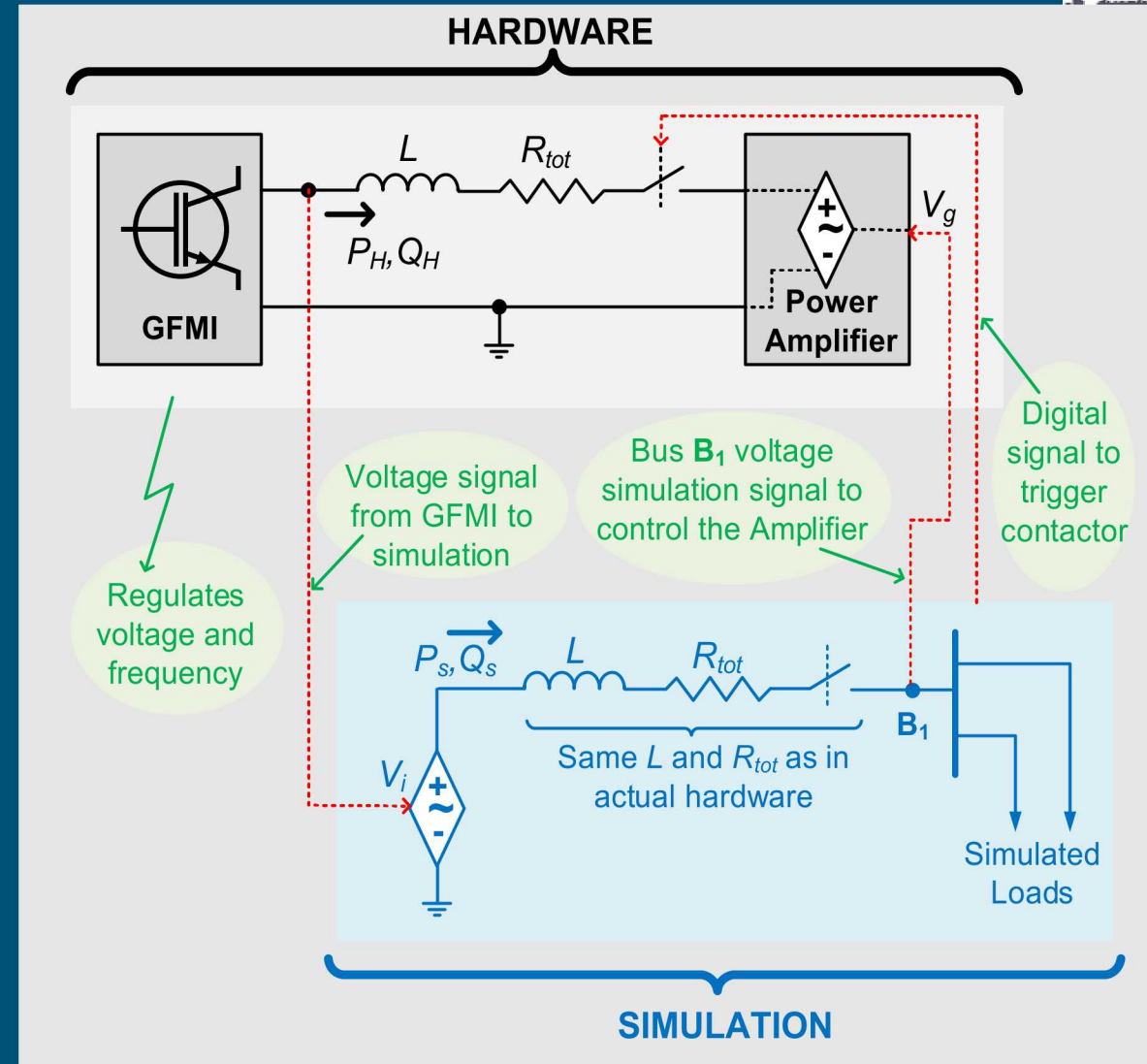
- Next step is to move from pure simulation to evaluating commercial hardware
- Utilizing Power Hardware-in-Loop (PHIL) setup to characterize real devices in St. Mary's environment

- PHIL simulation setups for traditional Grid Following Inverters (GFLIs) are well documented
- However, the interfacing of GFMs into closed-loop PHIL simulation setups is lightly documented
 - If DUT is a GFM, then direct connection with power amplifier can lead to instability → catastrophic damage
 - Both devices inherently try to regulate the voltage and frequency at their own settings
 - Lack of angle synchronization between the two devices
- We are developing method to interface GFM with simulation in PHIL

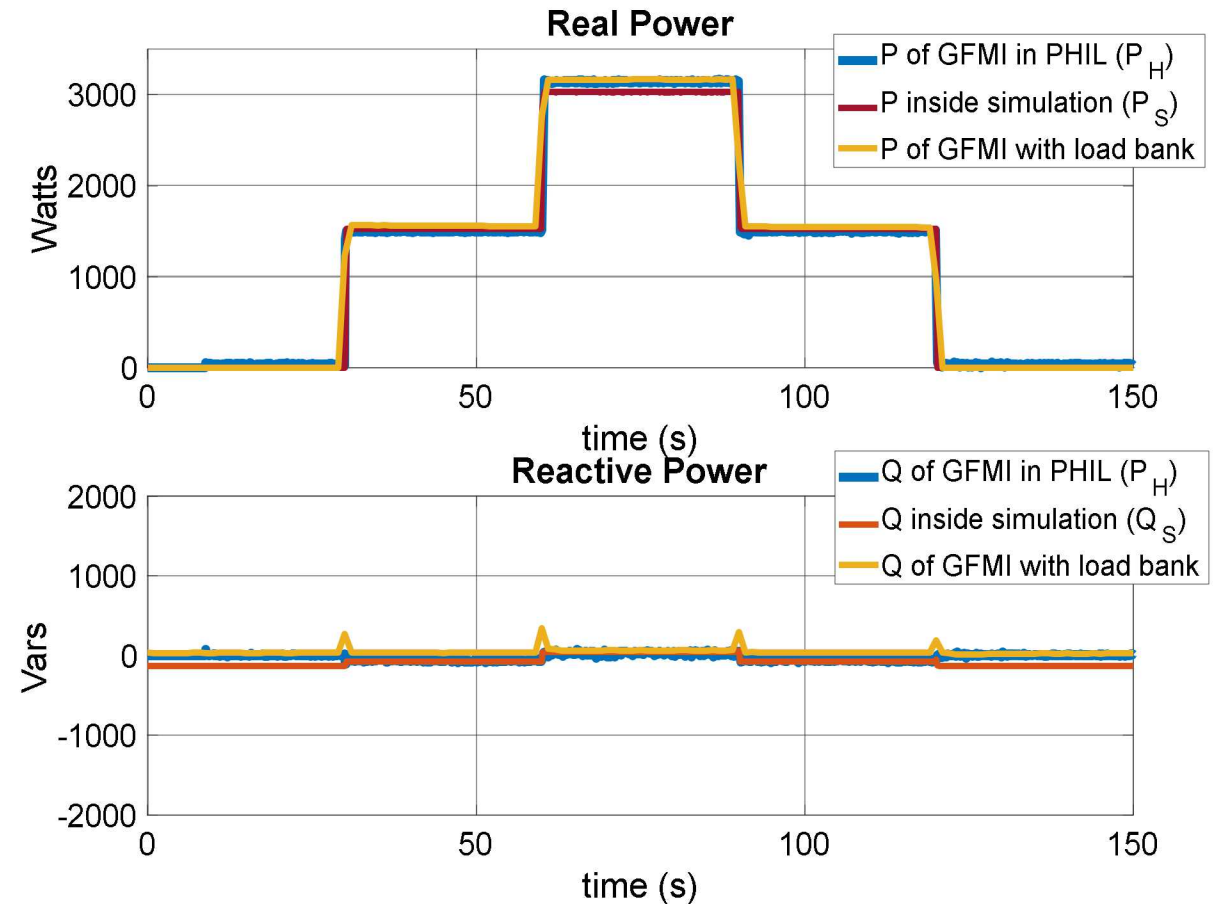
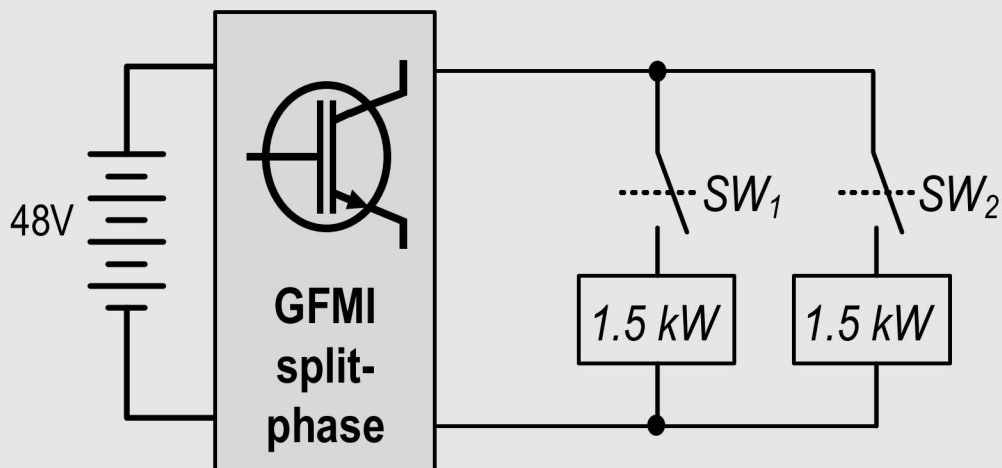


➤ Proposed method:

- Inductor placed between GFM and power amplifier
 - Avoids instability issues previously mentioned
- Contactor controls interconnection devices and
 - triggered by a digital signal from real time simulator.
- In simulation voltage measured at GFM replicated in controlled voltage source V_i
- Inductor and total resistance of hardware replicated inside the simulation
- Power amplifier emulates voltage at bus B1



- To verify accuracy of method compared GFM with a staircase load pattern
 - Compare simulation only, PHIL, and hardware only
- Good agreement between all three methods
 - Agreement between methods of $\leq 5\%$
 - PHIL method fully stable under abrupt load change



Power Hardware in Loop Validation of GFM for spinning Reserve

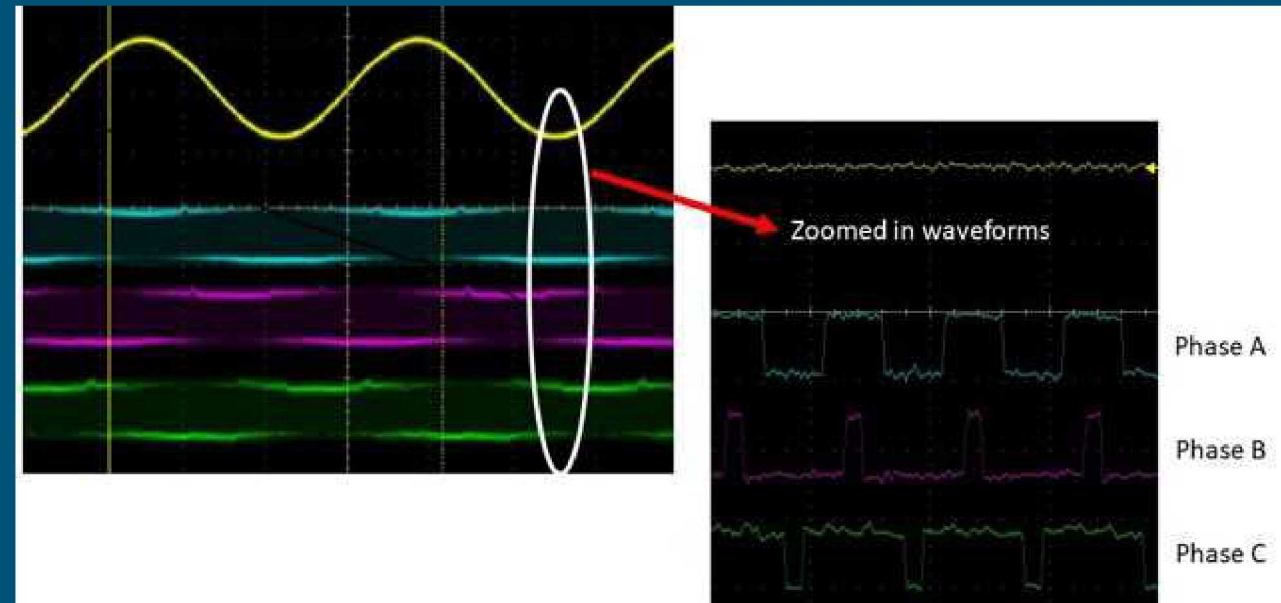
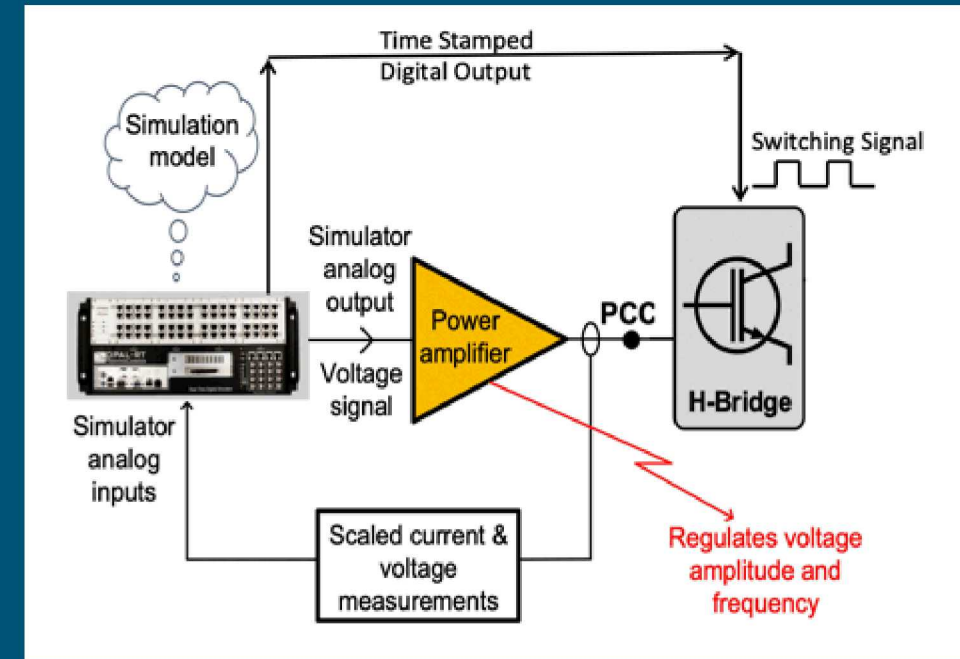


AVEC
Advanced Voltage Electronics Consortium

ACEP
Advanced Control for Energy and Power

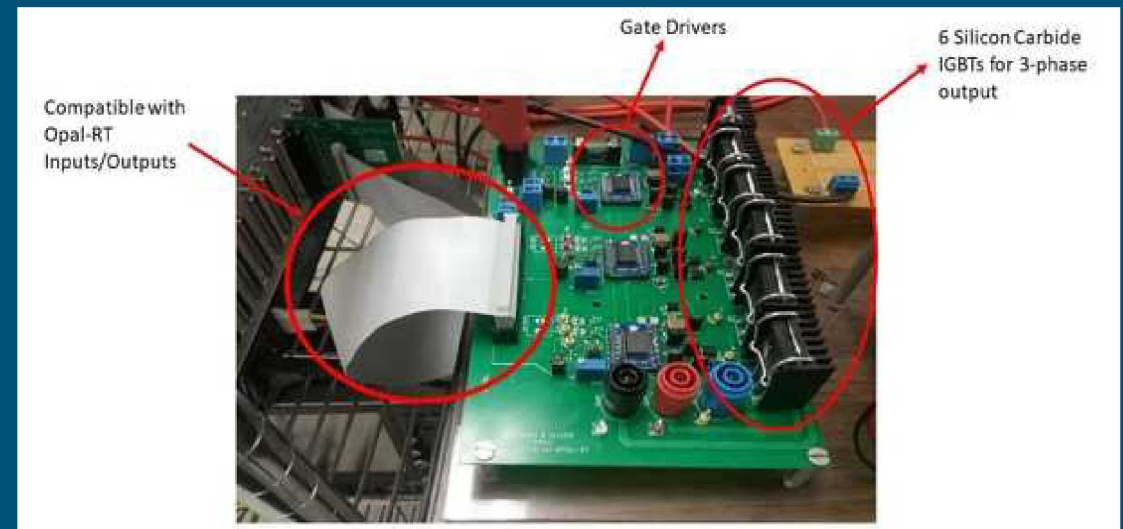
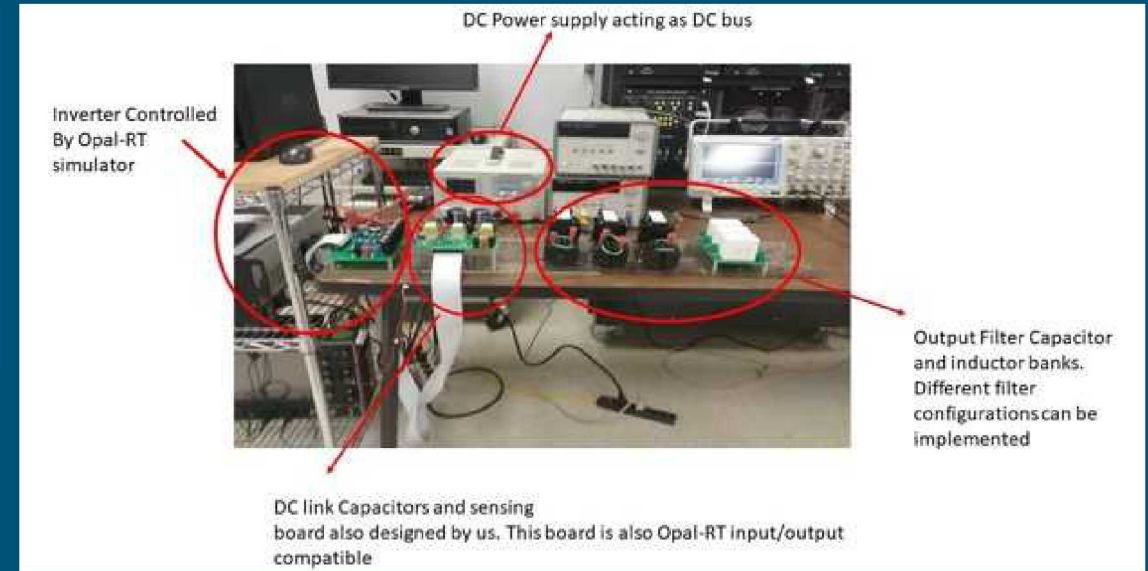
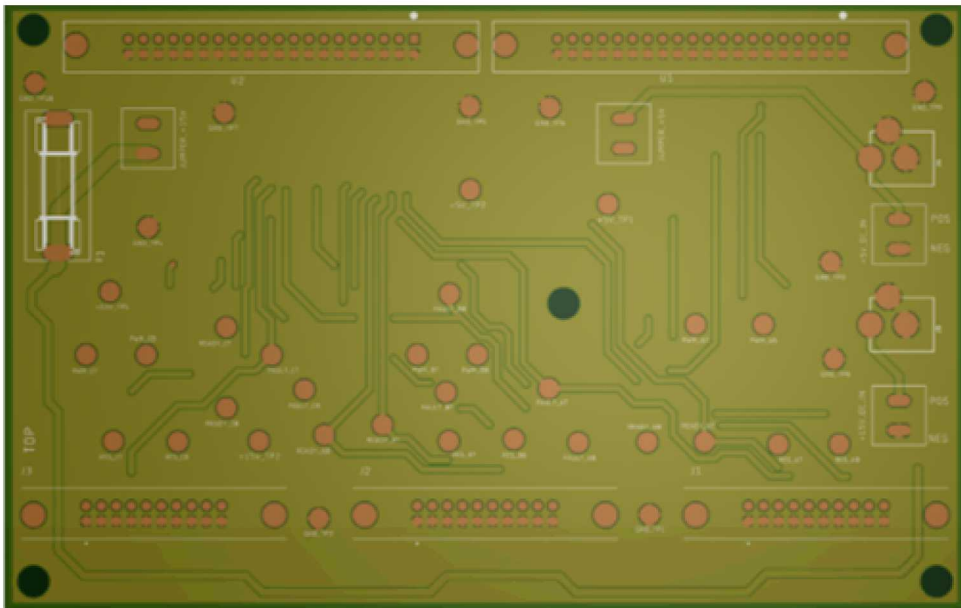
UT Austin
University of Texas at Austin

- PHIL evaluation of commercial hardware is valuable, but does not allow us to compare control schemes
- Need hardware testbed for GFM that has complete flexibility for changing/adapting control schemes
 - Not just parameters in a particular mode
 - But comparing different control modes with similar hardware
- Utilizing Opal RT system to supply gate drive signals to hardware
 - Time Stamped Digital Outputs allow for $\sim 300\text{kHz}$ switching within $40\text{ }\mu\text{s}$ timestep



Power Hardware in Loop Validation of GFM for spinning Reserve

- Initial prototype replicates work of collaborator, NMSU
- Current work focuses on design 7 kW (10 A)
 - Working on sizing of components and developing heatsink capabilities
 - Layout of PCB boards for higher power version



- Finish PHIL implementation of 3 ϕ GFM and evaluate commercial devices to contingencies in St. Mary's
- Complete flexible testbed construction to test PHIL of different control schemes
- Assist AVEC with procurement of GBS system for St Mary's
 - Target installation Sept 2020
- Work with ACEP to evaluate real system behavior before final installation at St. Mary's
 - Laboratory Acceptance Testing
 - Final validated model for St. Mary's with real GBS system