



Advanced WEC Dynamics and Controls

2.1.2.701

Marine and Hydrokinetics Program

Oct. 9, 2019

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Sandia National Labs

Project Overview



Project Summary

- Wide body of research has shown massive potential for control to improve WEC performance (more power, reduced loads, & fundamentally transform the WEC design problem)
- Project focus is realizing those benefits for WEC developers by creating a tractable engineering workflow

Project Objective & Impact

The goal of this project has been to deliver actionable methods for WEC developers to apply in order to improve the performance of their devices via control. This goal has been achieved and extended upon as our research has led us to better understand the need to incorporate the knowledge available from WEC control design into the large WEC design process.

Project Information

Project Principal Investigator(s)

Ryan Coe & Giorgio Bacelli
Sandia National Labs

WPTO Lead

Bill McShane

Project Partners/Subs

US Navy
Michigan Tech.
Oregon State University

Project Duration

- Oct. 2016
- Sept. 2019

Marine and Hydrokinetics (MHK) Program Strategic Approaches

Data Sharing and Analysis

Foundational
and
Crosscutting
R&D

Technology-
Specific
Design and
Validation

Reducing
Barriers to
Testing

Foundational and Crosscutting R&D

- Drive innovation in components, controls, manufacturing, materials and systems with early-stage R&D specific to MHK applications
- Develop, improve, and validate numerical and experimental tools and methodologies needed to improve understanding of important fluid-structure interactions
- Improve MHK resource assessments and characterizations needed to optimize devices and arrays, and understand extreme conditions
- Collaboratively develop and apply quantitative metrics to identify and advance technologies with high ultimate techno-economic potential for their market applications

- Sandia leverages expertise from aerospace, defense, and robotics control to deliver methodologies for WEC device and control design capable of delivering dramatic improvements in performance and economic viability.
- To deliver a robust framework for WEC device and control testing and design, Sandia has developed and validated numerous methodologies and experimental techniques. The methods provide WEC developers with a tractable path for WEC and control design. Experimental methods have increased the effectiveness of wave tank testing, enabling WEC developers to accomplish more in less tank time.

Technology-Specific Design and Validation

- Validate performance and reliability of systems by conducting in-water tests of industry-designed prototypes at multiple relevant scales
- Improve methods for safe and cost efficient installation, grid integration, operations, monitoring, maintenance, and decommissioning of MHK technologies
- Support the development and adoption of international standards for device performance and insurance certification
- Evaluate current and potential future needs for MHK-specific IO&M infrastructure (vessels, port facilities, etc.) and possible approaches to bridge gaps

- Sandia's Advanced WEC Dynamics and Controls project has produced the most popular dataset on MHK-DR.
- Sandia's improved testing methods are being used heavily for the update of IEC Technical Specification 62600-103 (*"Best practices and recommended procedures for the testing of pre-prototype scale devices"*).

Project Budget



FY17	FY18	FY19 (Q1 & Q2 Only)	Total Project Budget (FY17 - FY19 Q1 & Q2)	
Costed	Costed	Costed	Total Costed	Total Authorized
\$1,381K	\$1,132K	\$470K	\$2,983K	\$3,528K

- *Leverage synergies/funding from*
 - *MARINET2*
 - *Sandia internal funding (SWEPT Lab)*

Management and Technical Approach



- Problem: Clear potential for improvements based on WEC control since 1970s, but limited real-world benefits



- Goal: Holistic approach to realize these gains and provide a basis for co-design

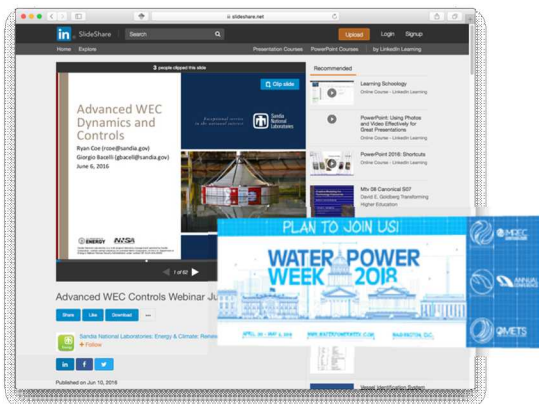


- Strategy: Leverage methods and tools proven successful in other applications to provide a tractable work flow for WEC control design

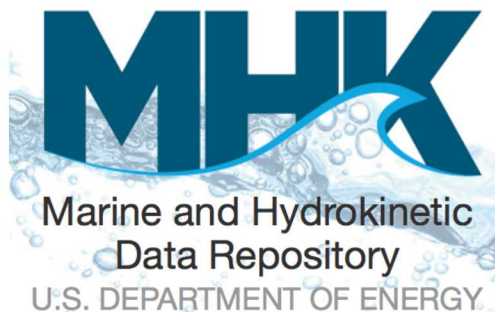


End-User Engagement and Dissemination Strategy

Annual workshop
& 4 webinars



Most popular public
dataset on MHK-DR



Broad ranging research
collaborations



4 patent applications
(2 granted)



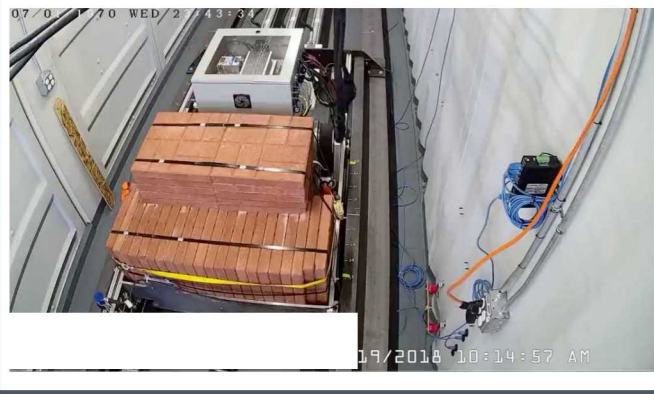
Private developer collaborations



40+ project publications

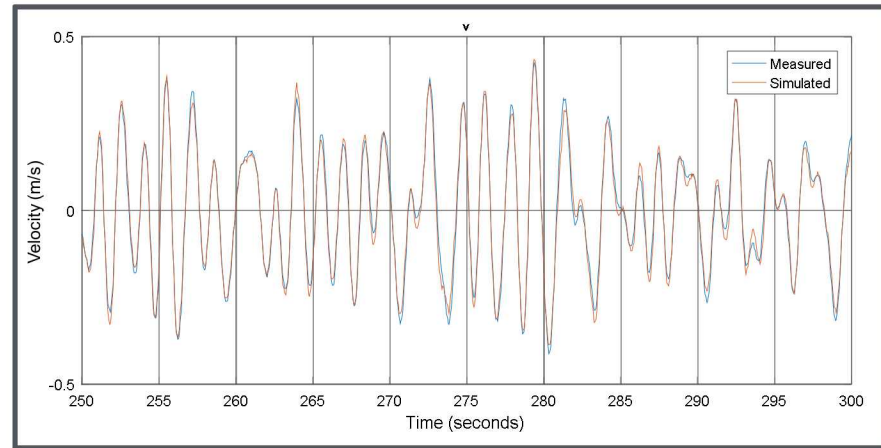


Technical Accomplishments

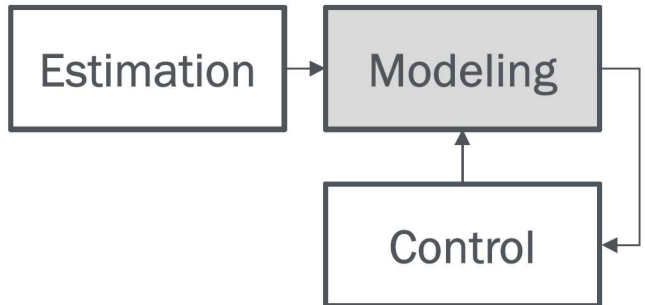
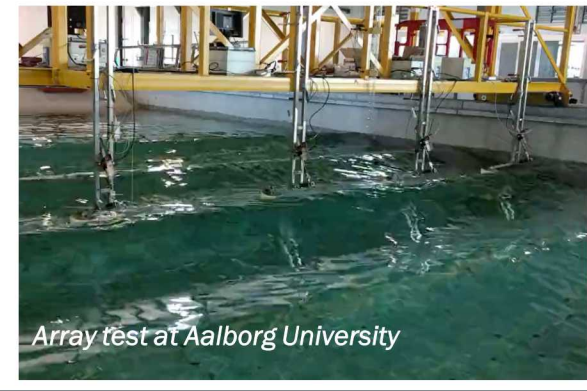
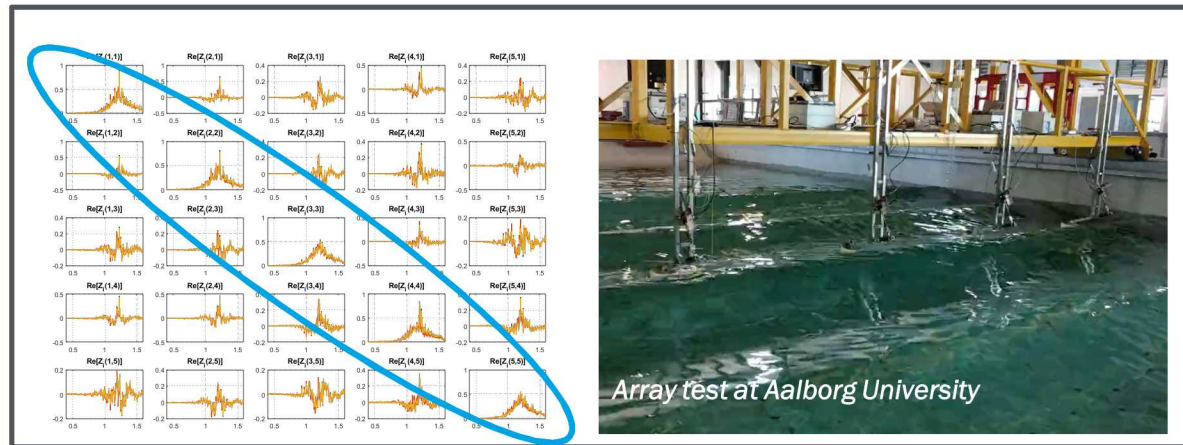


Testing practices deliver better results in less time

Models better than 90% accurate

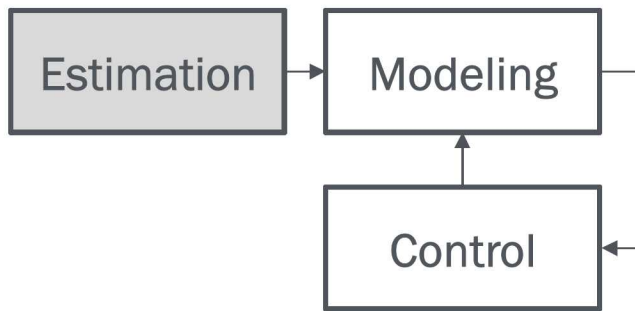
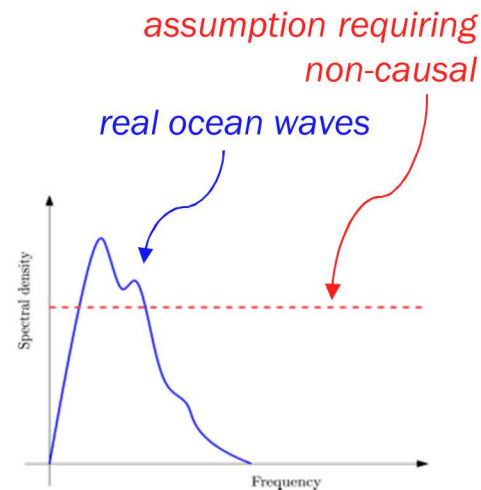
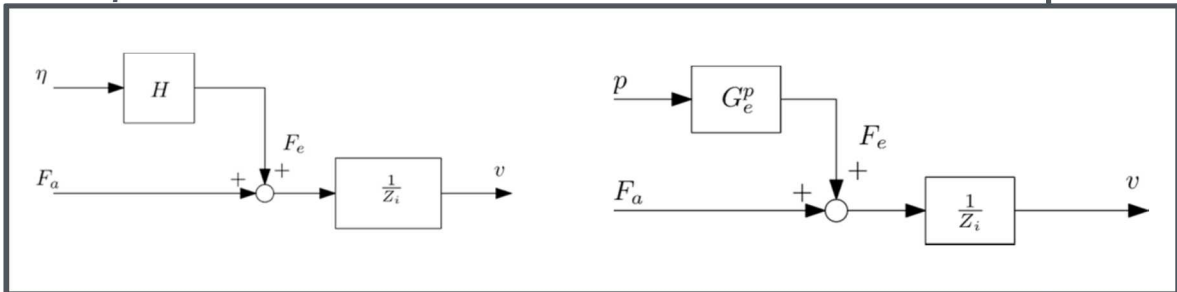


Works just as well on multi-device & multi-DOF systems

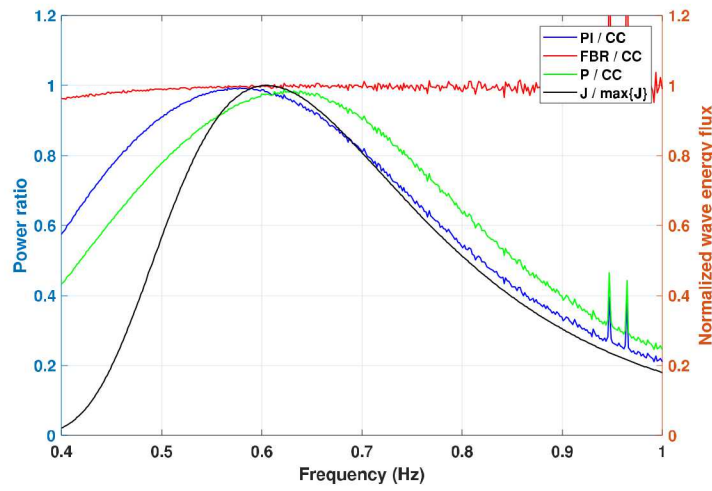


Technical Accomplishments (Cont.)

Use pressure to estimate excitation force



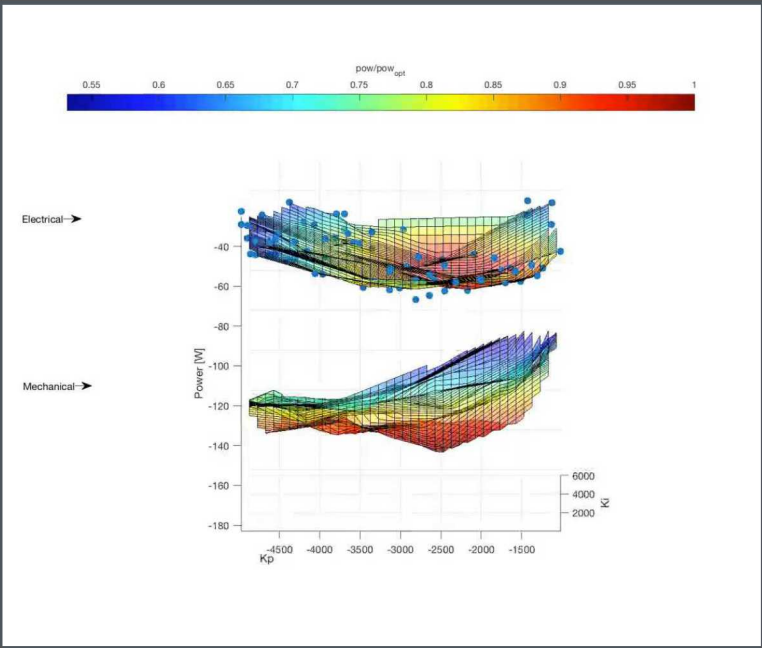
Engineering approach shows that in real waves, need for prediction greatly reduced



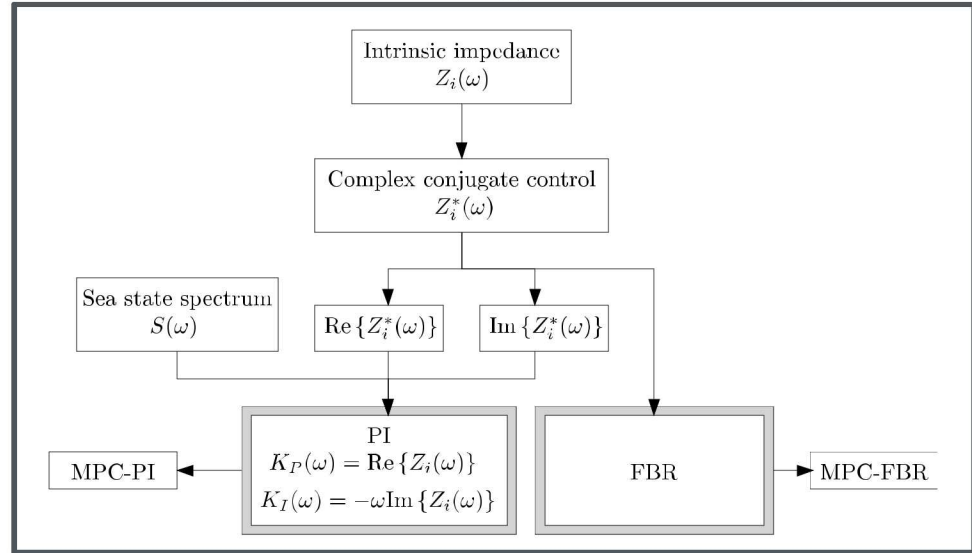
Technical Accomplishments (Cont.)



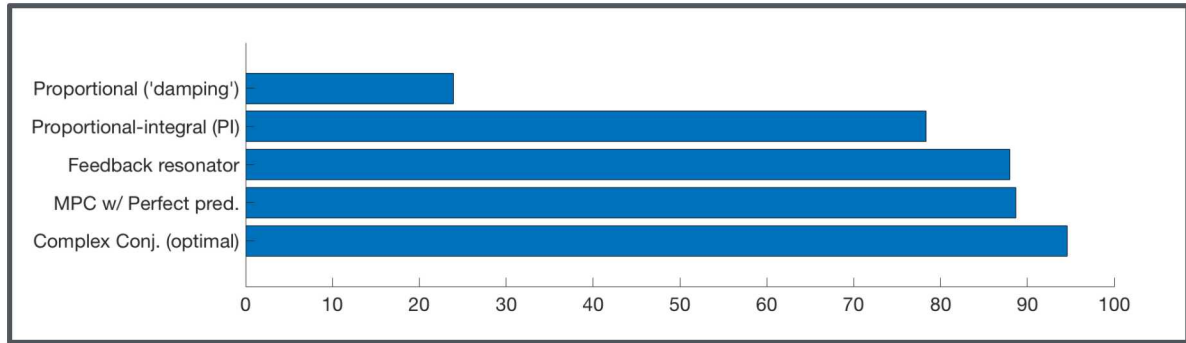
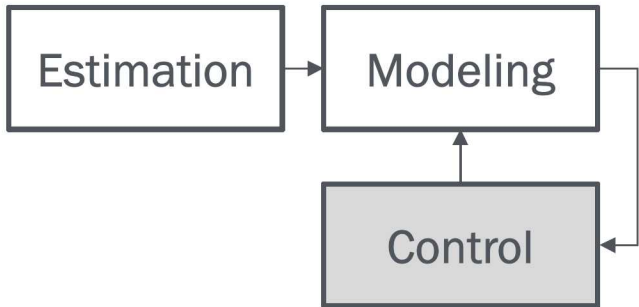
Control design focused on LCOE



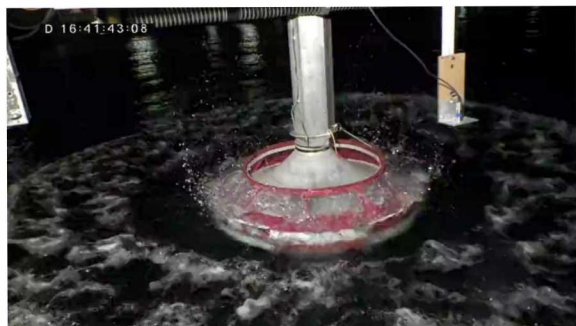
Feedback approach based on impedance matching, provides insight for co-design



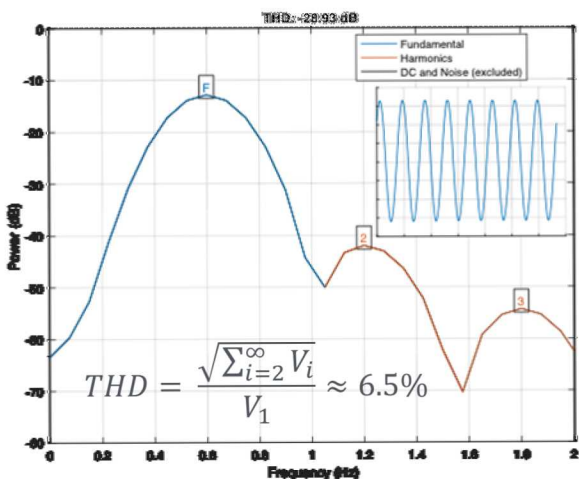
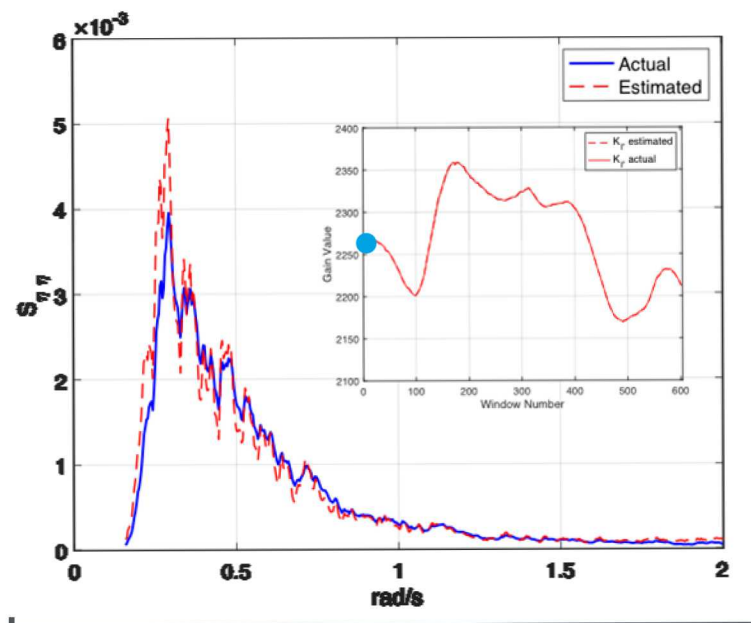
Nearly optimal performance without prediction



Progress Since Project Summary Submittal



Self-tuning controller for changing weather



Are these methods really device-agnostic?

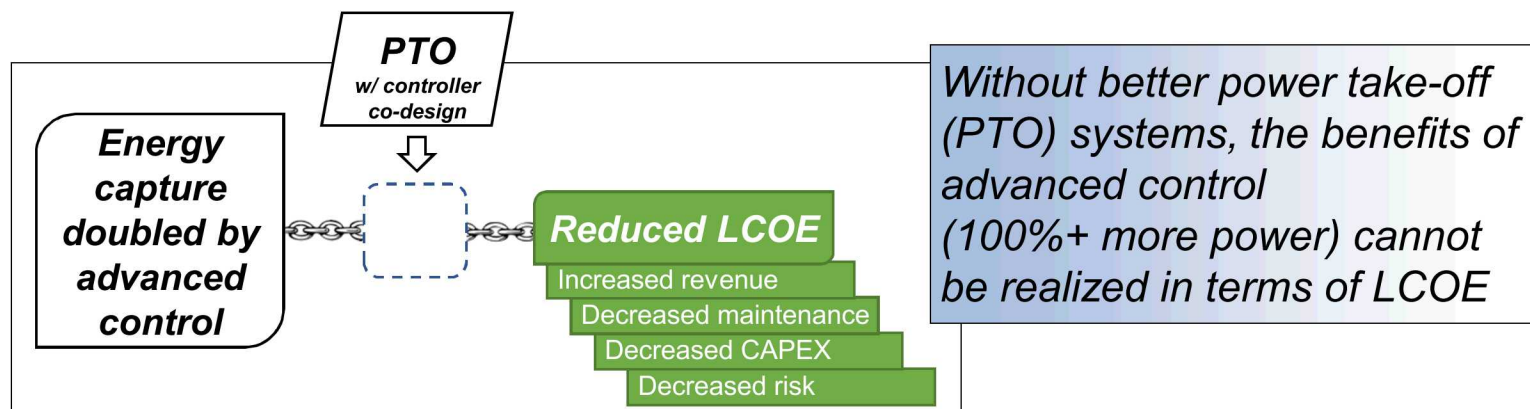
Just how nonlinear are WEC hydrodynamics?



Tank test: Dec. 2-20

Future Work

- **Problem:** WEC PTO design is *linchpin* enabling efficiency gains and load reduction from advanced controls to be realized in terms of LCOE (*absorbed* power -> *generated* power)
- **Goal:** Develop method for *co-design* of WEC PTO and control systems utilizing predictionless control to deliver 100% power increase in full-scale WEC



“Predictionless” WEC control

PTO

Hydrodynamics

Control

Mooring

Sandia’s “predictionless” WEC control *enables synchronous co-design*