

# Introduction to the Basics of Uncertainty Quantification



PRESENTED BY

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## 1. Motivating Uncertainty Quantification

- “All Models are Wrong”
- UQ in the Real World: Dorian
- Predictive Science and UQ

## 2. Fundamentals of Probability

- Frequentist vs Bayesian
- Probability Space and Random Variables

## 3. Coin Toss Experiment

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- George Box

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- McCullagh and Nedler (1989)

“... it does not seem helpful just to say that all models are wrong. The very word model implies simplification and idealization. The idea that complex physical, biological or sociological systems can be exactly described by a few formulae is patently absurd.”

- Cox (1995)

“A model is a simplification or approximation of reality and hence will not reflect all of reality.”

- Burnham and Anderson (2002)

“In general, when building statistical models, we must not forget that the aim is to understand something about the real world. Or predict, choose an action, make a decision, summarize evidence, and so on, but always about the real world, not an abstract mathematical world: our models are not the reality”

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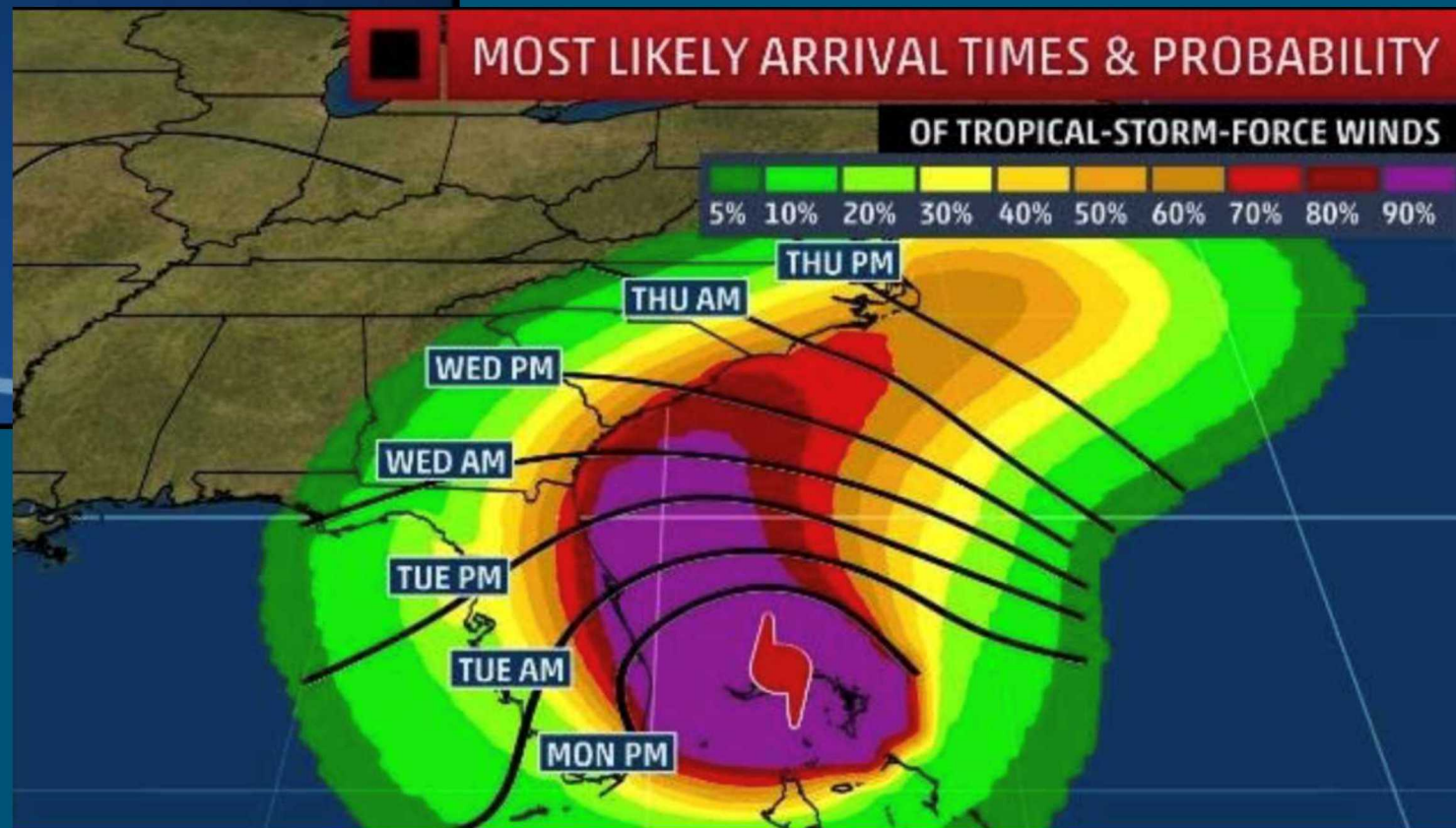
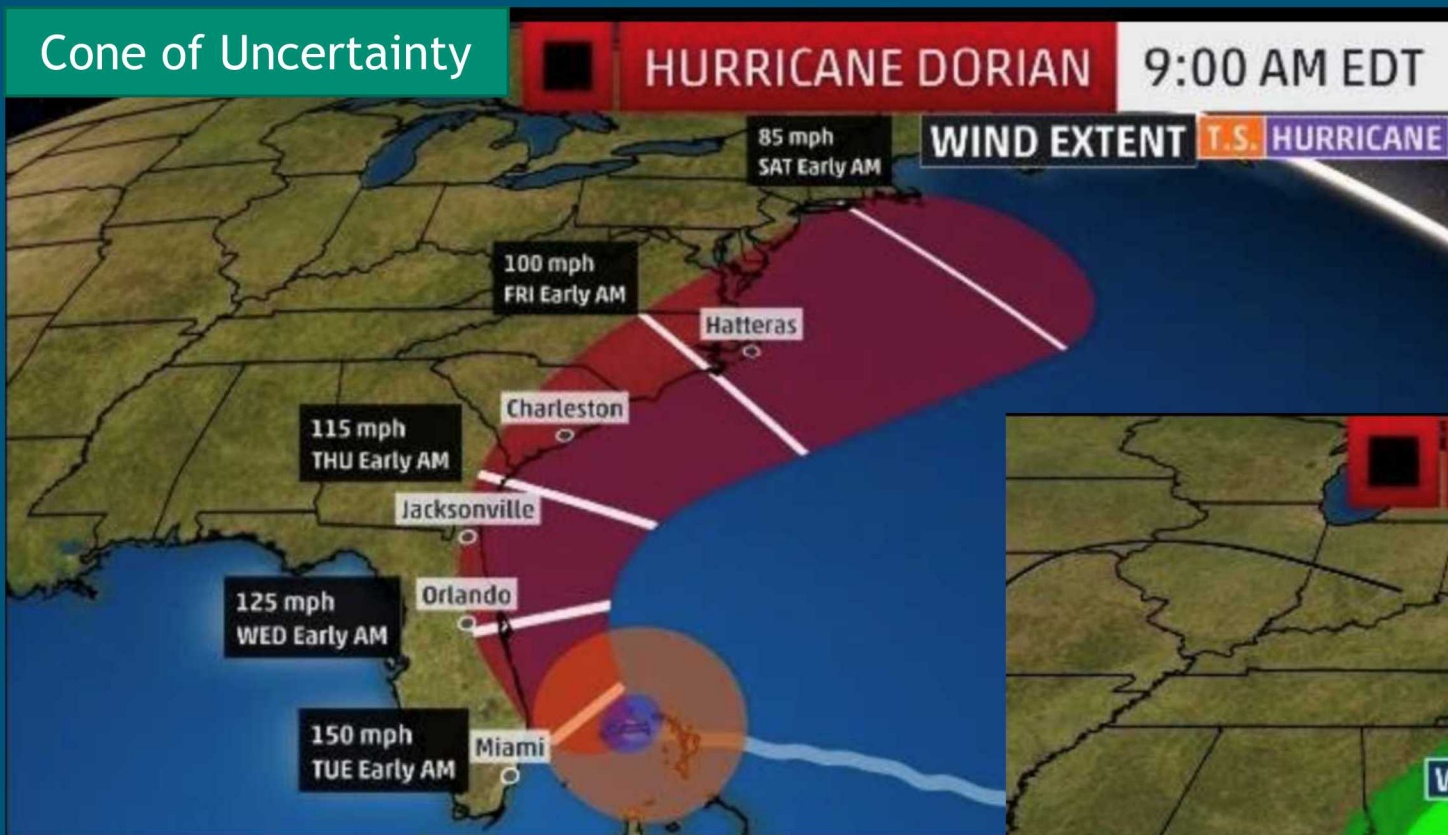
Why do we even bother then?



# Dorian: Hurricane Trajectory Projections

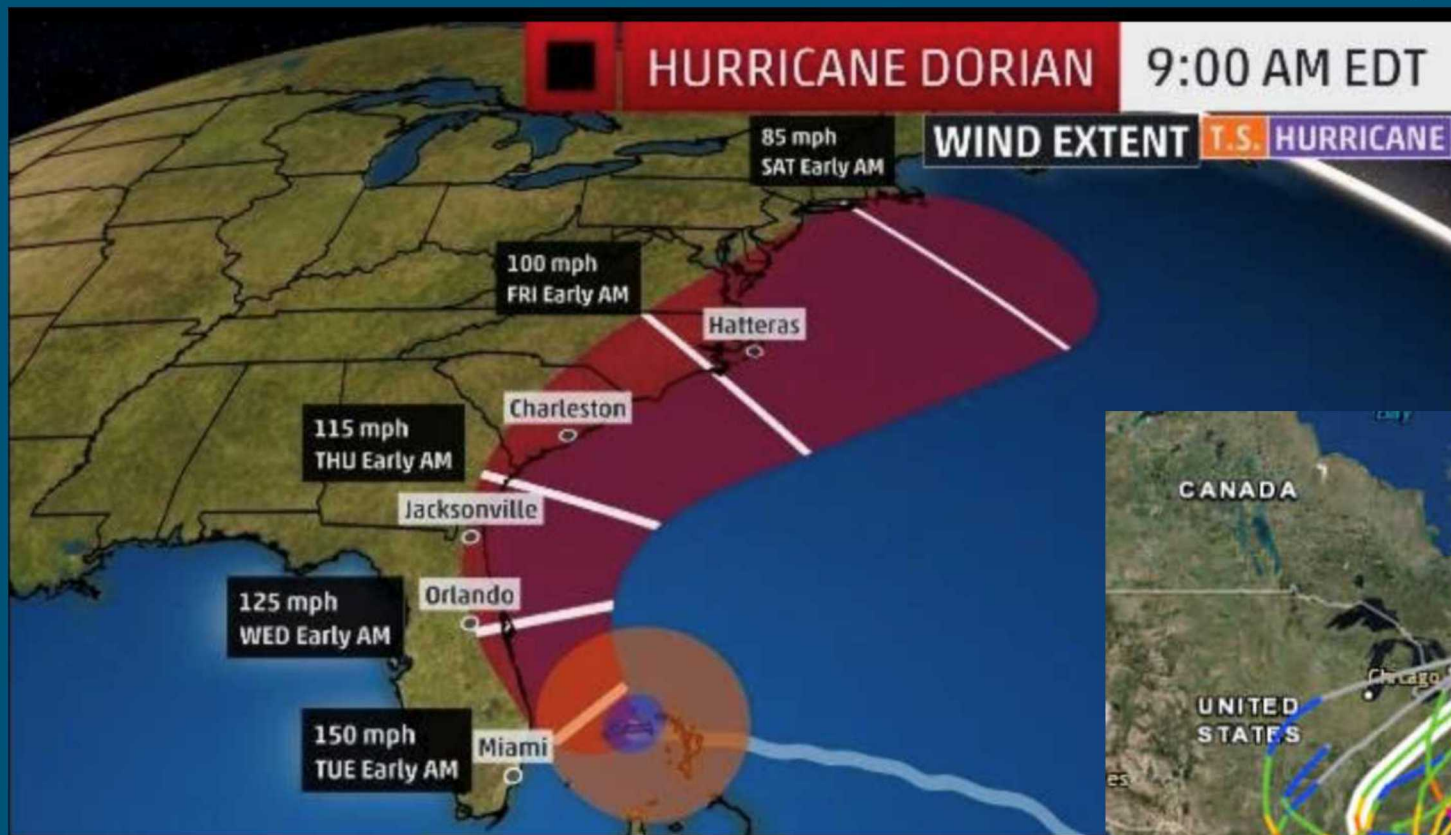
as of 9:00AM EDT on Monday 09/02/2019

## Cone of Uncertainty





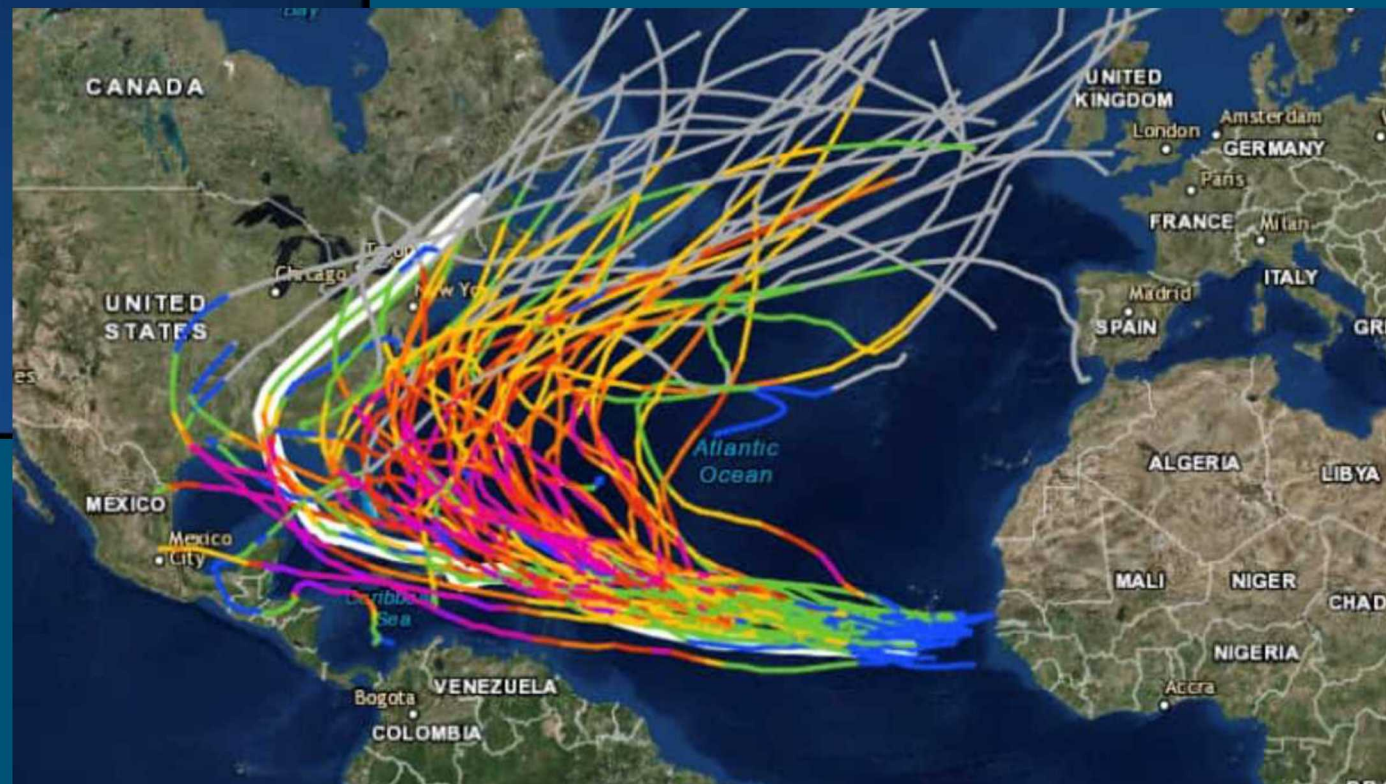
## 7 How do the weather forecasters make these projections?



\* <https://www.weather.com/amp/storms/hurricane/news/2019-09-02-hurricane-dorian-labor-day-bahamas-florida-georgia-carolinas.html>

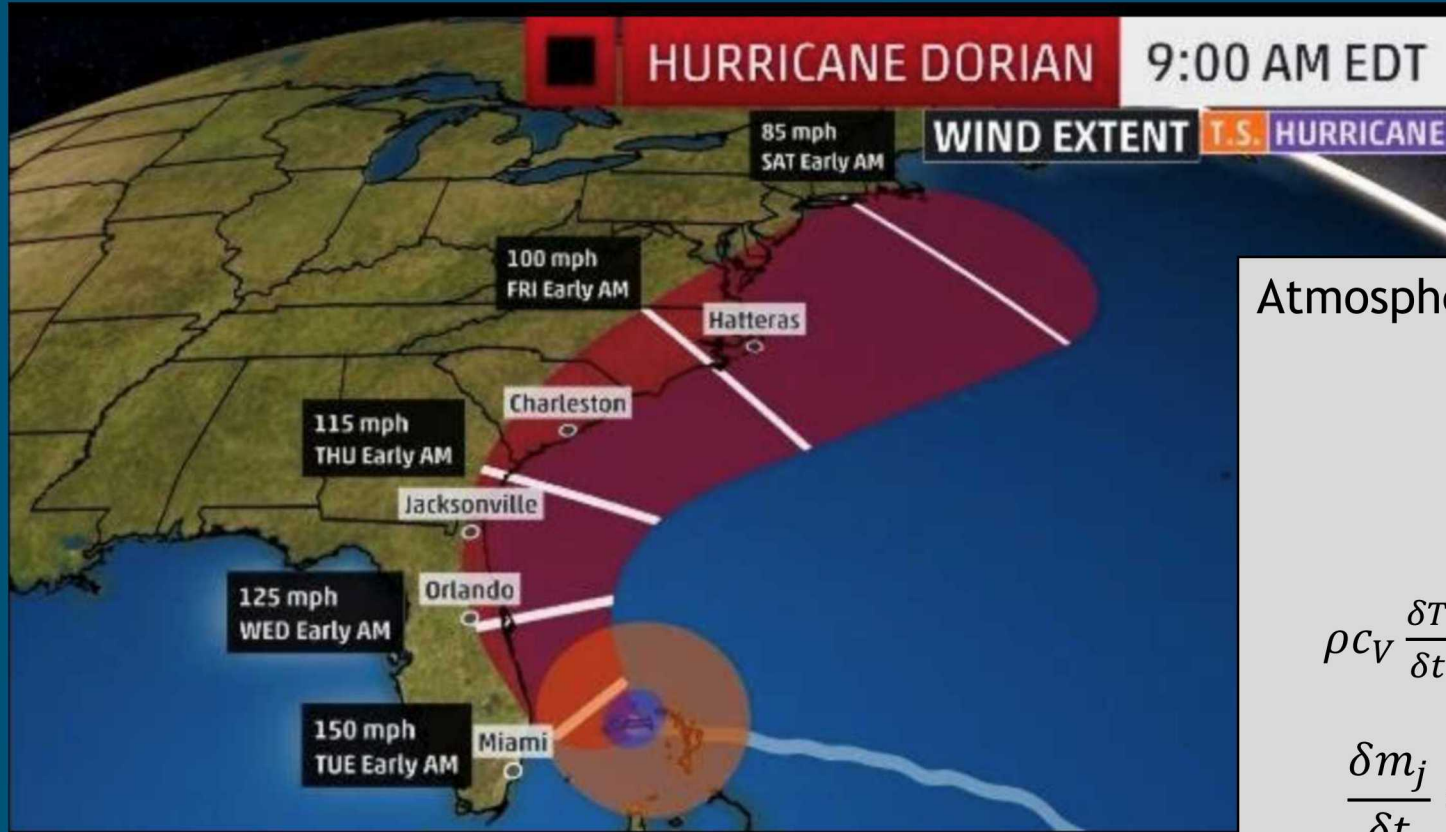
## Historical Data

\* <https://oceanservice.noaa.gov/news/historical-hurricanes/>



>150 years of category 4 and 5 hurricane tracking data





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## Mathematical Models

Atmospheric Physics Equations:

$$\frac{\delta \rho}{\delta t} + \nabla \cdot (\rho v) = 0,$$

$$\frac{\delta v}{\delta t} = -v \cdot \nabla v - \frac{1}{\rho} \nabla \rho - g \hat{k} - 2\Omega \times v,$$

$$\rho c_v \frac{\delta T}{\delta t} + \rho \nabla \cdot v = -\nabla \cdot F + \nabla \cdot (k \nabla T) + \rho \dot{q}(T, p, \rho),$$

$$p = \rho R T,$$

$$\frac{\delta m_j}{\delta t} = -v \cdot \nabla m_j + S_{m_j}(T, m_j, \chi_j, \rho), \quad j = 1, 2, 3,$$

$$\frac{\delta \chi_j}{\delta t} = -v \cdot \nabla \chi_j + S_{\chi_j}(T, \chi_j, \rho), \quad j = 1, \dots, J$$

Where  $\rho, v, T, p, k$ , and  $c_v$  respectively denote the density, velocity, temperature, pressure, thermal conductivity, and specific heat of air

\* Smith, *Uncertainty Quantification: Theory, Implementation, and Applications*, SIAM, 2014. page: 2



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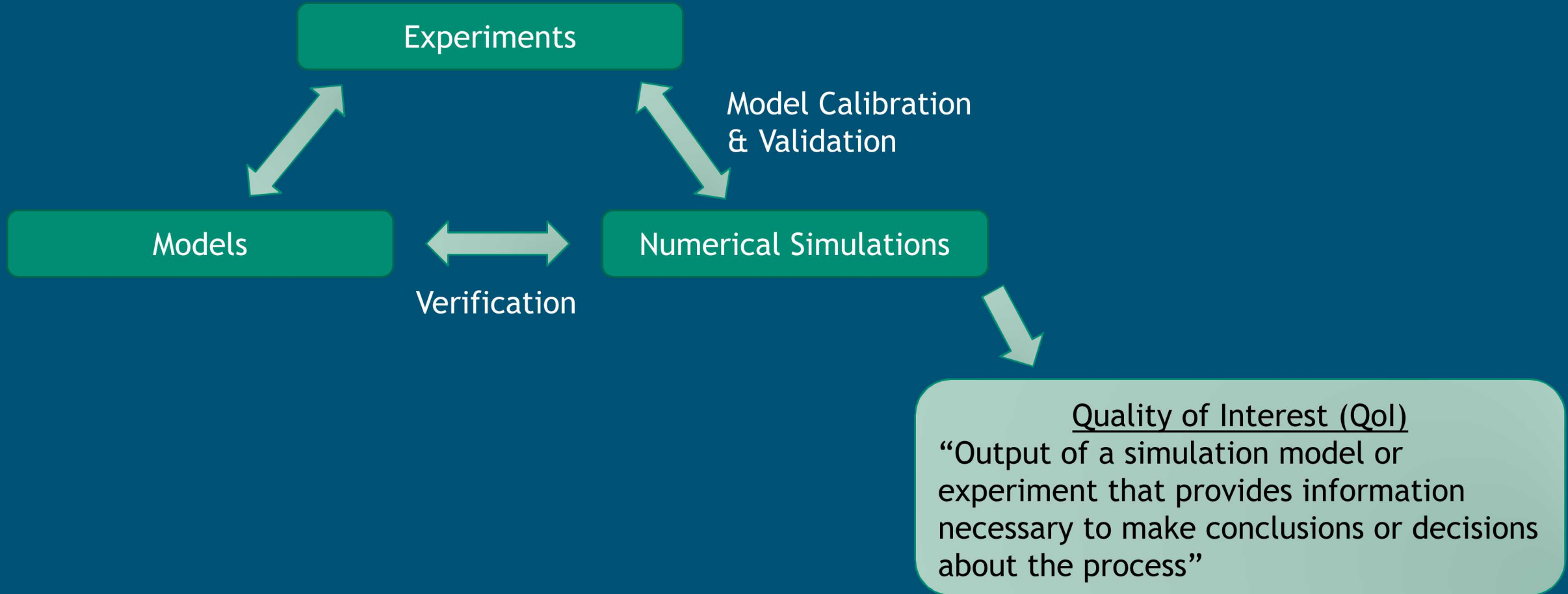
**Validation:** “describes the process of determining the accuracy with which mathematical models quantify the physical process of interest”[1]

**Verification:** “refers to the process of quantifying the accuracy of simulation codes used to implement mathematical models” [1]



# Predictive Science

The following introduction to Uncertainty Quantification (UQ) is a summary of what is provided by Dr. Ralph Smith in his 2014 SIAM publication, *Uncertainty Quantification: Theory, Implementation, and Applications*. [1]



# What is Uncertainty Quantification?

“Uncertainty quantification is both a new field and one that is as old as the disciplines of probability and statistics.”

-Smith (2014)

**Uncertainty Quantification:** “[in the context of predictive science] uncertainty quantification is the science identifying, quantifying, and reducing uncertainties associated with models, numerical algorithms, experiments, and predicted outcomes or quantities of interest.”

## Multi-disciplinary Field:

- Probability
- Statistics
- Analysis
- Numerical Analysis

## Areas of Research Interest:

- Parameter Selection
- Surrogate Model Construction
- Local & Global Sensitivity Analysis
- Quantification of Model Discrepancies



## Experimental Uncertainties and Limitations

- Limited or incomplete data
- Limited accuracy or resolution of sensors

Experiments

Model Calibration  
& Validation

Models

Numerical Simulations

Verification

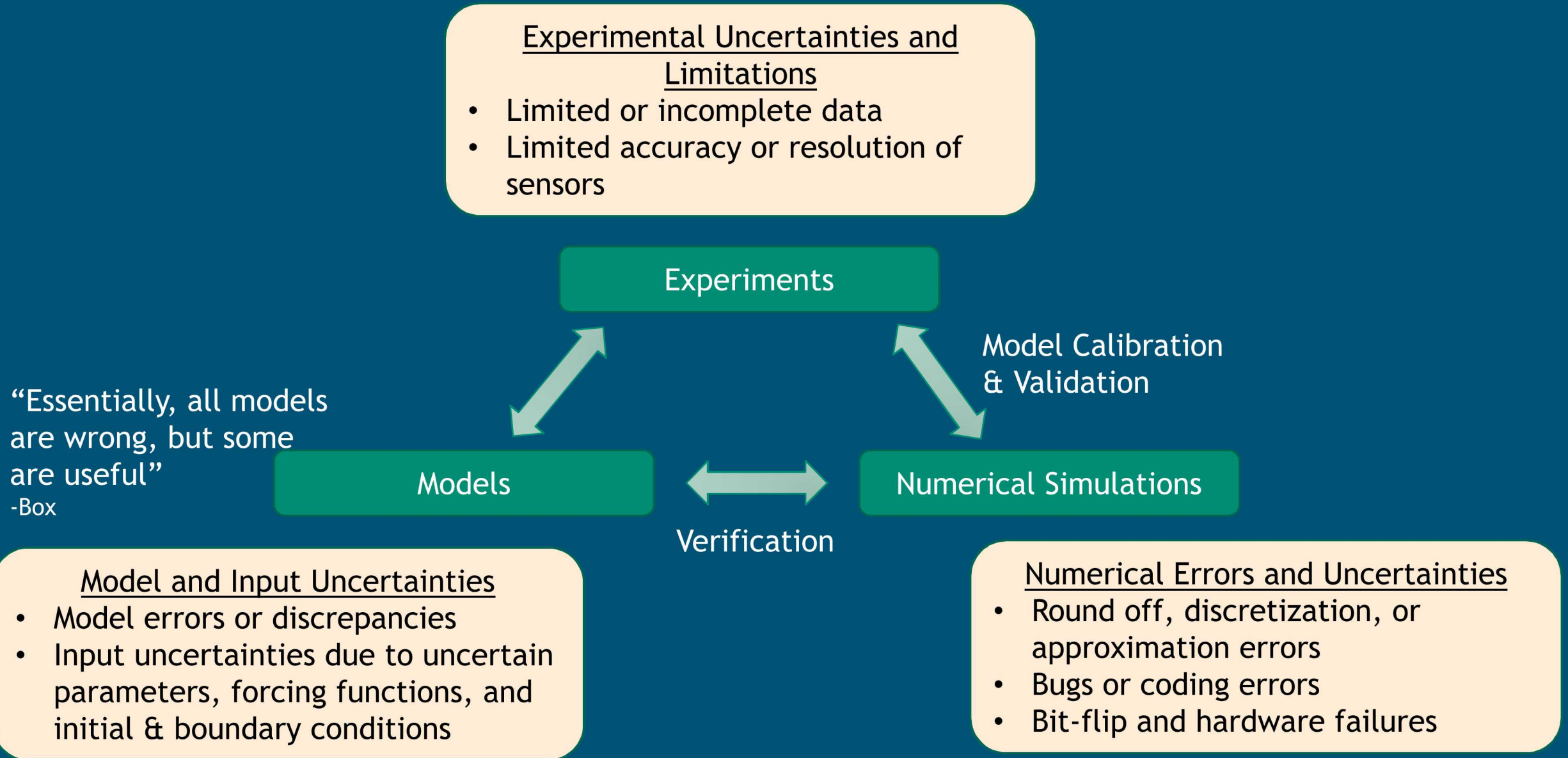
## Model and Input Uncertainties

- Model errors or discrepancies
- Input uncertainties due to uncertain parameters, forcing functions, and initial & boundary conditions

## Numerical Errors and Uncertainties

- Round off, discretization, or approximation errors
- Bugs or coding errors
- Bit-flip and hardware failures

# Uncertainty in Predictive Science





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-Gunzburger

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## **Aleatoric (Statistical, Stochastic, or Irreducible Uncertainty):**

“Uncertainty inherent to a problem or experiment that in principle cannot be reduced by additional physical or experimental knowledge.”

## **Epistemic (Systemic Uncertainty):**

“Uncertainty due to simplifying model assumptions, missing physics, or basic lack on knowledge.”



“Consider parameters and measurement errors to be random variables whose statistical properties or distributions we wish to infer using measured data”

Frequentist:

“Probabilities are defined as the frequency with which an event occurs if the experiment is repeated a large number of times”

Bayesian:

“treats probabilities as a distribution of subjective values, rather than a single frequency, that are constructed or updated as data is observed”

# Probability Space and Univariate Random Variable

**Probability Space:** A probability space  $(\Omega, \mathcal{F}, P)$  is comprised of three components:

- $\Omega$ : sample space is the set of all possible outcomes from an experiment
- $\mathcal{F}$ :  $\sigma$ - field of subsets of  $\Omega$  that contains all events of interest
- $P: \mathcal{F} \rightarrow [0,1]$ : probability or measure that satisfies the postulates
  - i.  $P(\emptyset) = 0$
  - ii.  $P(\Omega) = 1$
  - iii. If  $A_i \in \mathcal{F}$  and  $A_i \cap A_j = \emptyset$ , then
$$P(\cup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} P(A_i)$$

**Random Variable:** a univariate random variable is a function  $X: \Omega \rightarrow \mathbb{R}$  with the property that

$\{\omega \in \Omega \mid X(\omega) \leq x\} \in \mathcal{F}$  for each  $x \in \mathbb{R}$ ; i.e. it is measurable

**Realization:** the value

$$x = X(\omega)$$

of a random variable  $X$  for an event  $\omega \in \Omega$  is termed a realization of  $X$ .

## Some Properties of a Univariate Random Variable

Cumulative Distribution Function (cdf):

$$\begin{aligned} F_X: \mathbb{R} &\rightarrow [0,1] \\ F_X(x) &= P\{\omega \in \Omega \mid X(\omega) \leq x\} \\ F_X(x) &= P\{X \leq x\} \end{aligned}$$

Probability Density Function (pdf):

For a continuous random variable  $X$  the cdf can be expressed as,

$$F_X(x) = \int_{-\infty}^x f_X(s) ds, \quad x \in \mathbb{R}$$

where the derivative  $f_X = \frac{dF_X}{dx}$  is the pdf.

Probability Mass Function (pmf):

The pmf of a discrete random variable  $X$  is given by  $f_X(x) = P(X = x)$



$$\mathbb{E}(X^n) = \int_{\mathbb{R}} x^n f_X(x) dx$$

Mean (Expected Value): Density central location

$$\mu = \int x f_x(x) dx$$

Variance: Density's variability or width

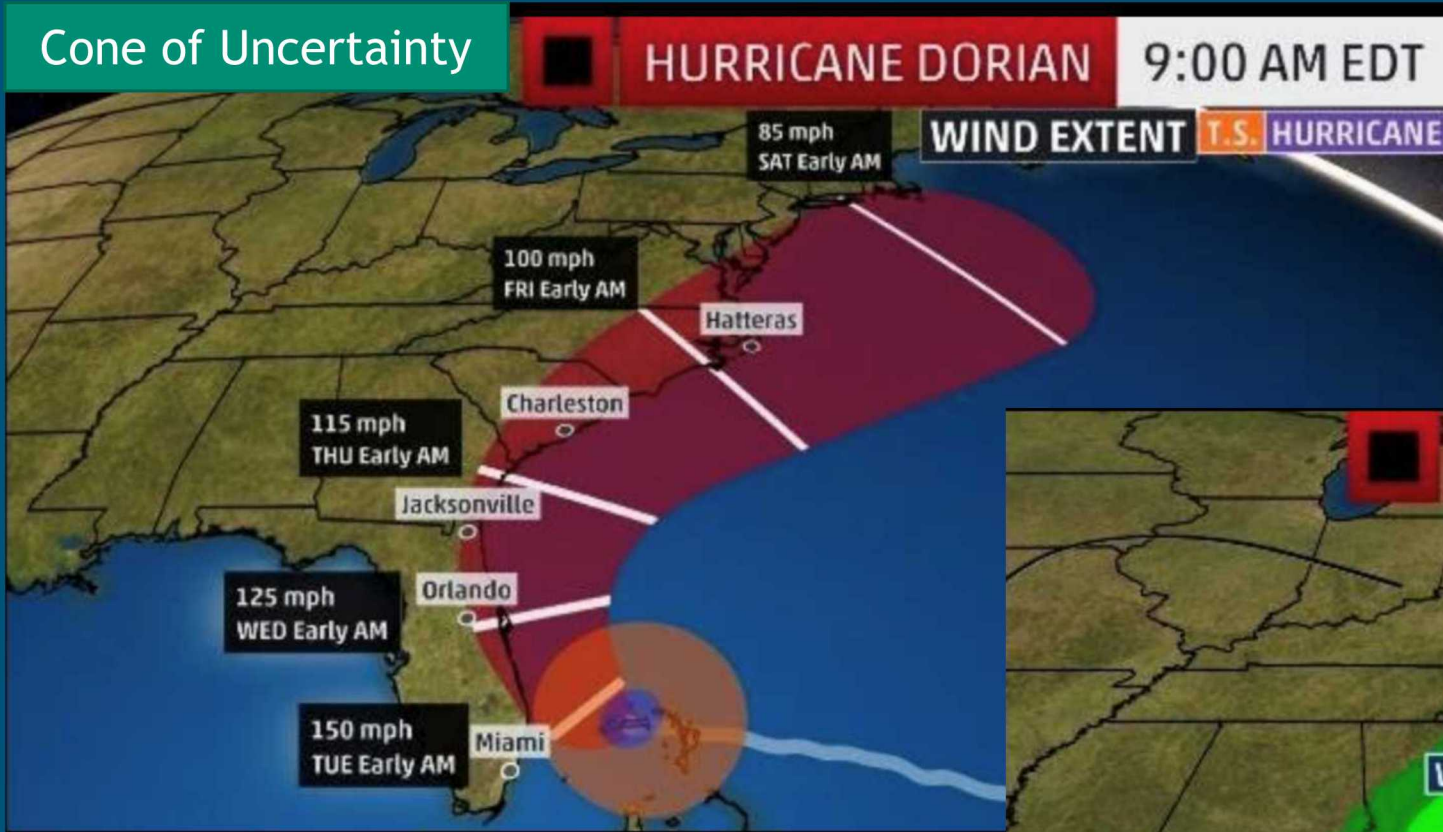
$$\sigma^2 = \int (x - \mu)^2 f_x(x) dx$$

Skewness: Density's symmetry about  $\mu$

Kurtosis: Magnitude of tail contributions

# Why is the cone of uncertainty "tighter" than the probability distribution?

## Cone of Uncertainty



# Coin Toss Experiment