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Tethered Multi-Rotor System Development: Technology Overview & Status

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Funding agency/POC:
End user POC:

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Project Summary



Project began in April 2018

Objective: Develop, test, and deliver a Tethered Multi-Rotor System to supply command & control, power, and data feeds to a hexacopter UAS for use as an aerial platform for communications, intelligence collection, and CUAS purposes.

Accomplishments

Complete

- Demonstrated prototype system, flights to 300+ ft under software control, power and comm over tether

In process

- Integration of remaining payloads
- Engineering fix for two issues (required for functionality)
 - Thermal management in UAS body
 - Tether fatigue/early life failure
- Further design upgrades desired, TBD based on funding

Deliverables and/or Milestones

Milestone	Original	Actual (Planned)
Project kick-off upon receipt of funding	4/2018	4/2018
Preliminary Design Review	8/2018	10/2018
Critical Design Review	12/2018	1/2019
Initial Prototype complete	2/2019	5/2019
Prototype demonstration at SNL	4/2019	7/2019
Final delivery	5/2019	12/2019

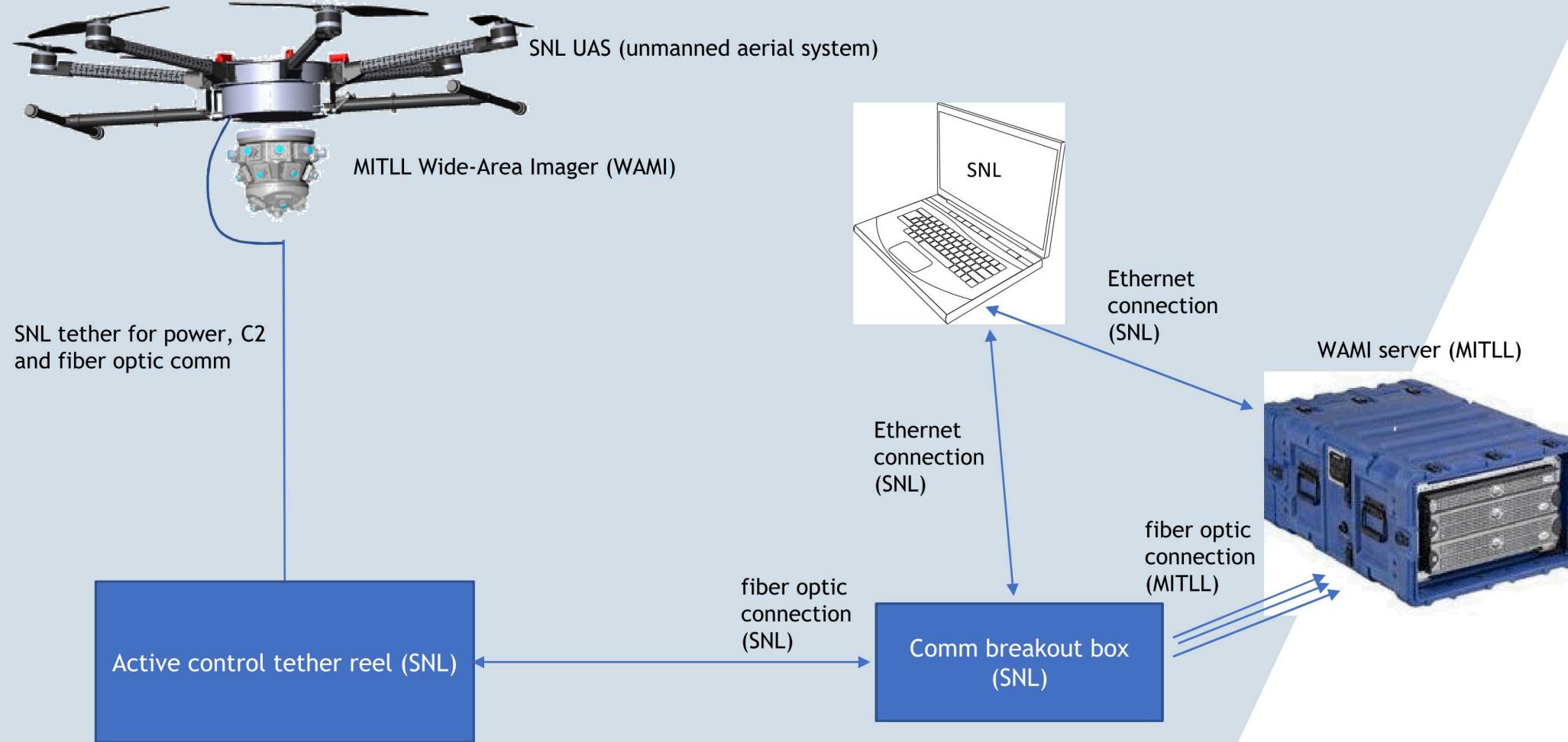
Top Risks & Issues

- Inability to build off previous TMRS system significantly increased development cost & schedule
 - Original proposal plan included using a previously developed reel system and control software; however they did not support current requirements



Current system shown with simulated payload

HIGH LEVEL SYSTEM OVERVIEW

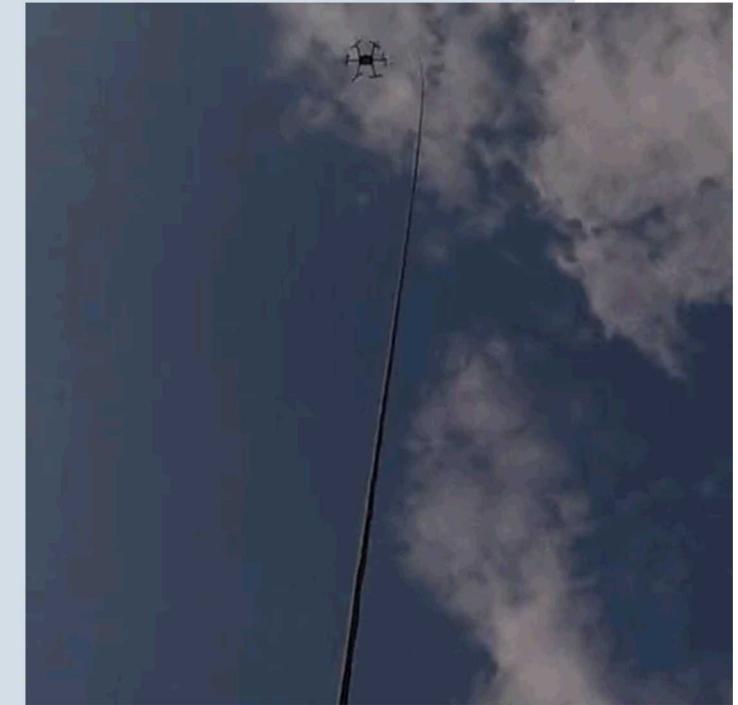


SYSTEM DEMONSTRATION - 07/23/2019



System Launch

View from Onboard GoPro at 300' AGL



Reel Mounted GoPro: 100'
AGL, ~10 mph cross-wind