



# Utilizing Hopkinson Bar for High-G, High-Frequency Mechanical Shock Tests

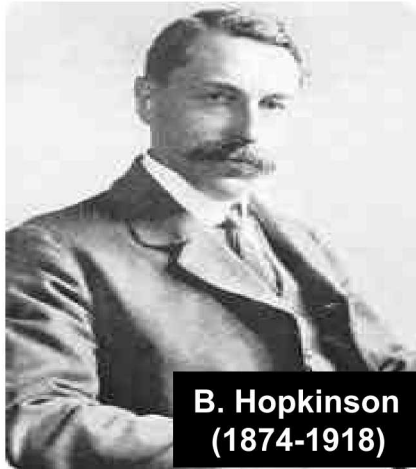
Bo Song, Brett Sanborn

*Sandia National Laboratories*



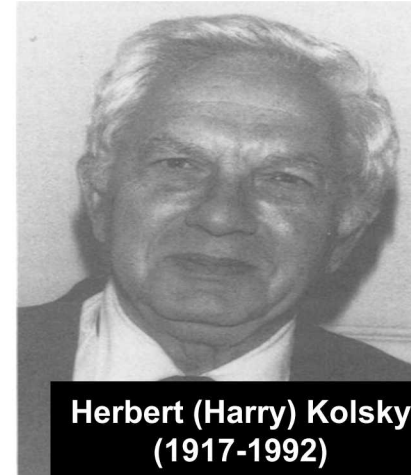
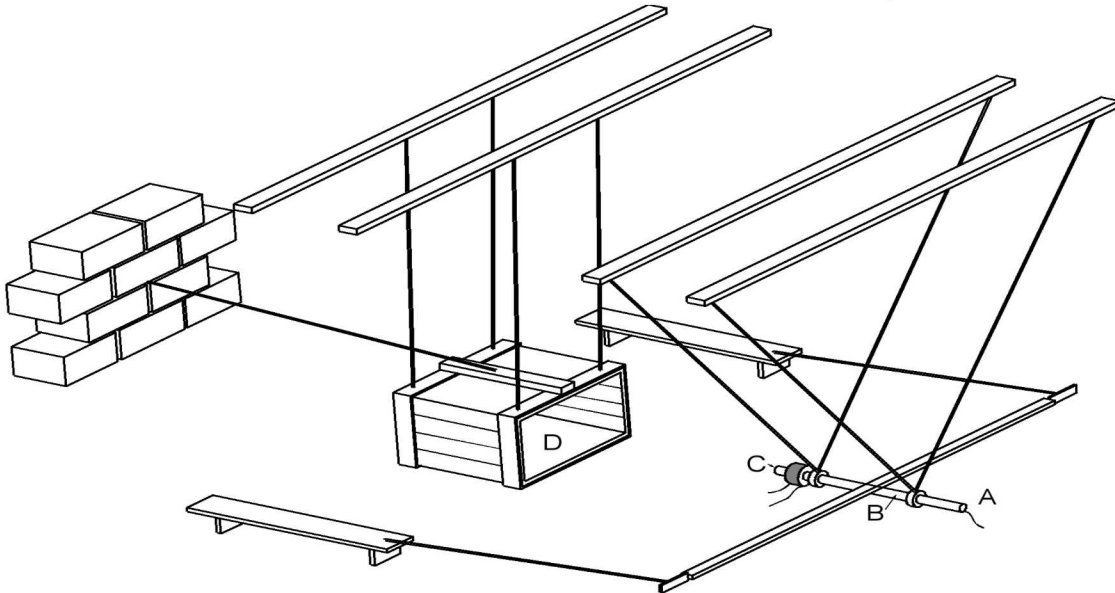
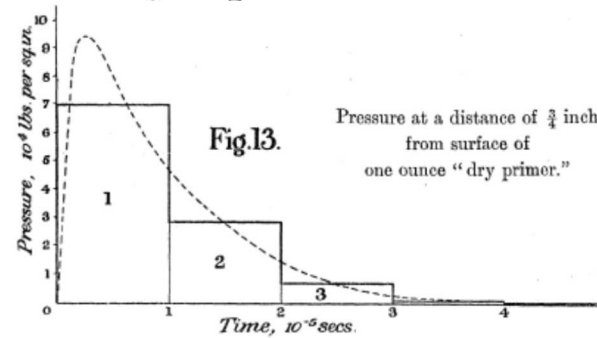
Sandia National Laboratories is a multimission laboratory managed and operated by National Technology & Engineering Solutions of Sandia, LLC, a wholly owned subsidiary of Honeywell International Inc., for the U.S. Department of Energy's National Nuclear Security Administration under contract DE-NA0003525.

## 2 | Hopkinson (Hoppy) Bar/Kolsky Bar



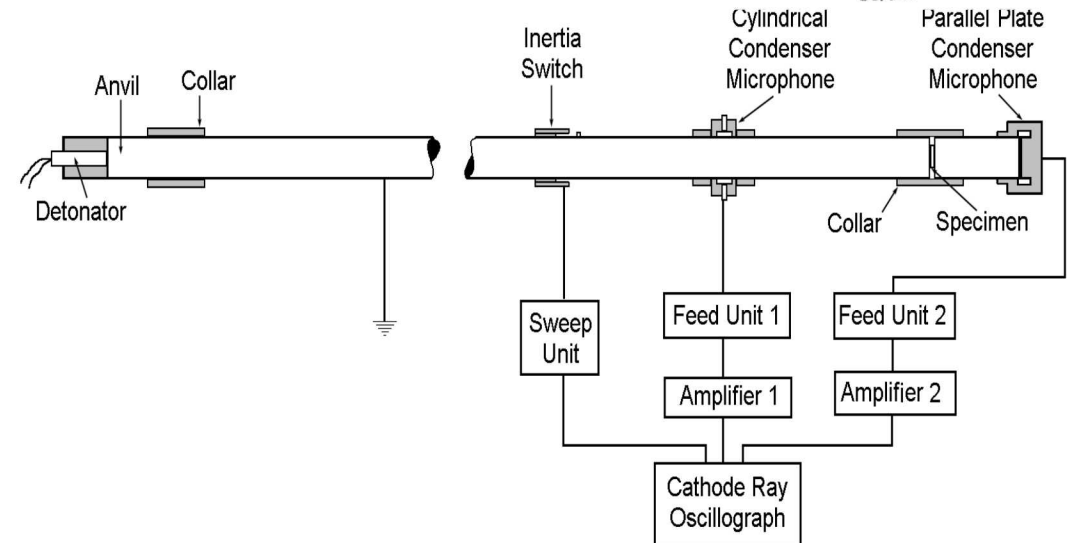
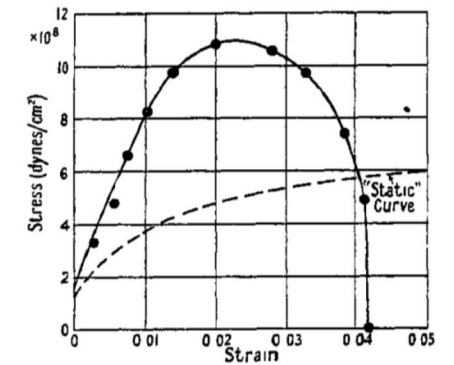
### Hopkinson Bar (1914)

*To measure pressure profile generated by explosives*



### Kolsky Bar (1949)

*To measure dynamic stress-strain curves of materials*



### 3 Hopkinson (Hoppy) Bar/Kolsky Bar/Split Hopkinson Bar

Hopkinson Bar

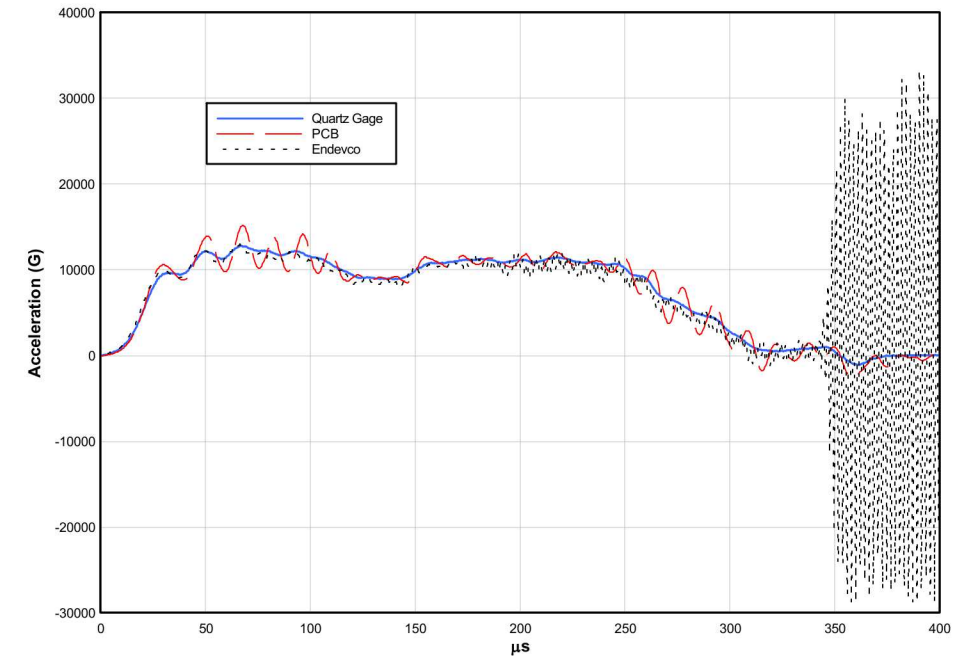
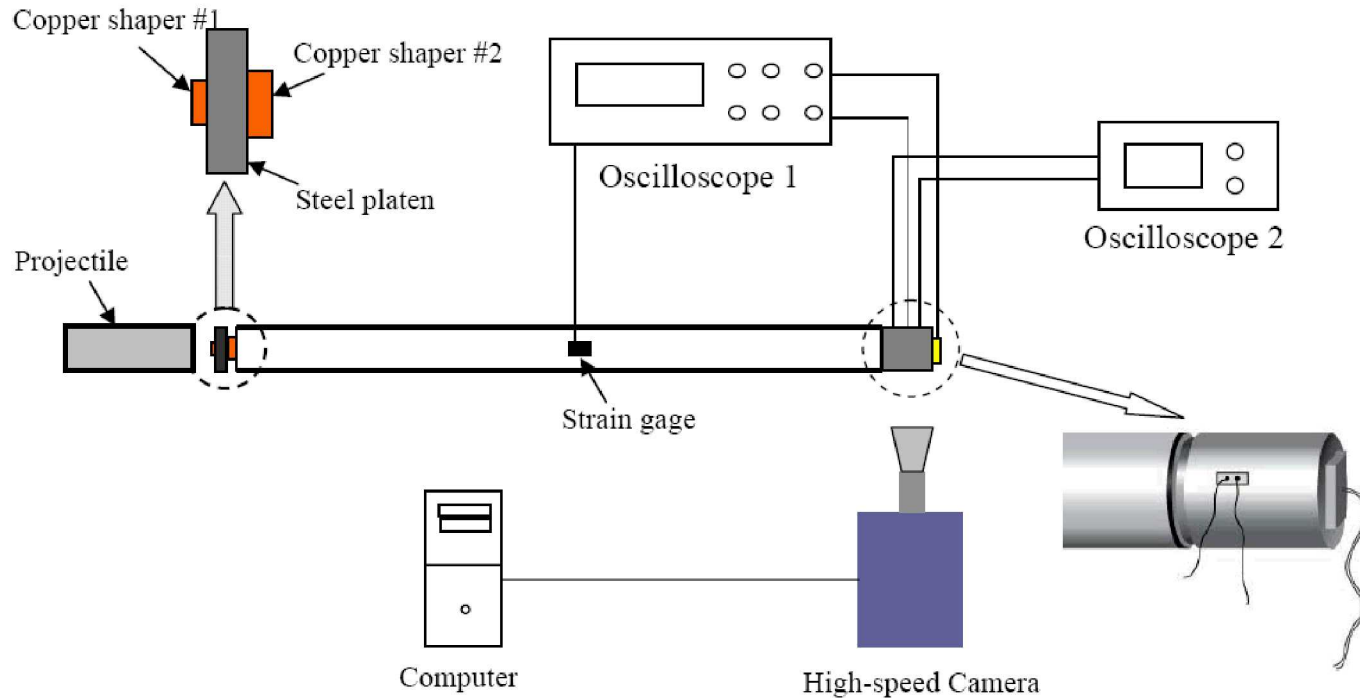


Kolsky Bar



Split Hopkinson Bar

## **Hopkinson Bar (Actuator)** – *with auxiliary sensors (accelerometers) if needed*



## 4 Hopkinson (Hoppy) Bar/Kolsky Bar/Split Hopkinson Bar

Hopkinson Bar

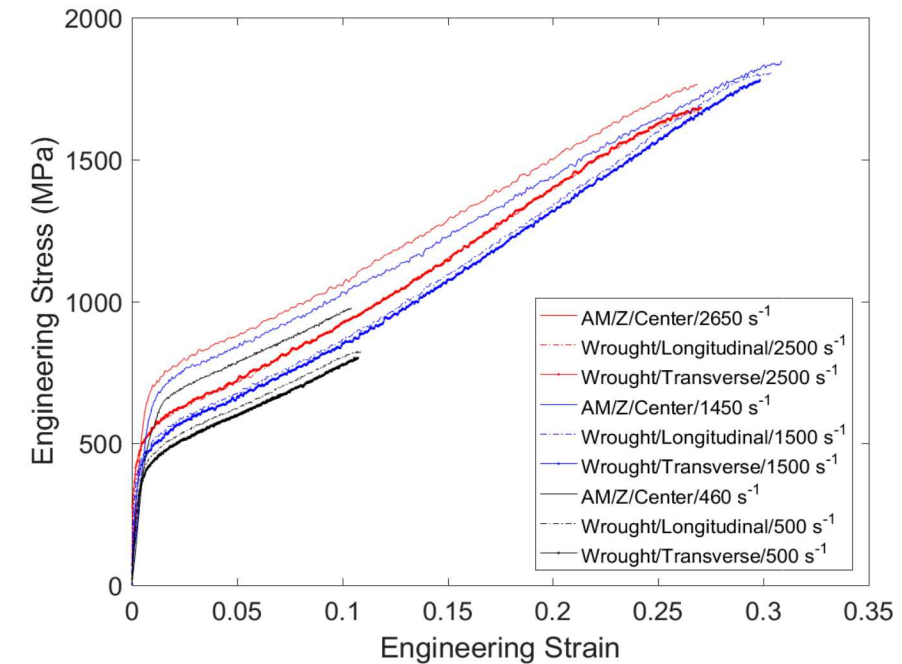
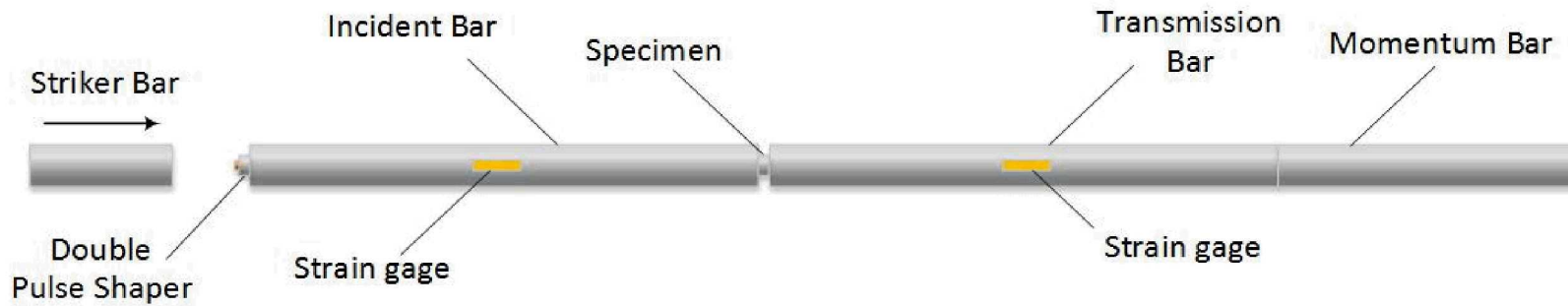


Kolsky Bar



Split Hopkinson Bar

### *Kolsky Bar/Split Hopkinson Bar (Actuator & Sensor)*



*Currently, Kolsky bar/split Hopkinson bar is more commonly used than Hopkinson bar.*

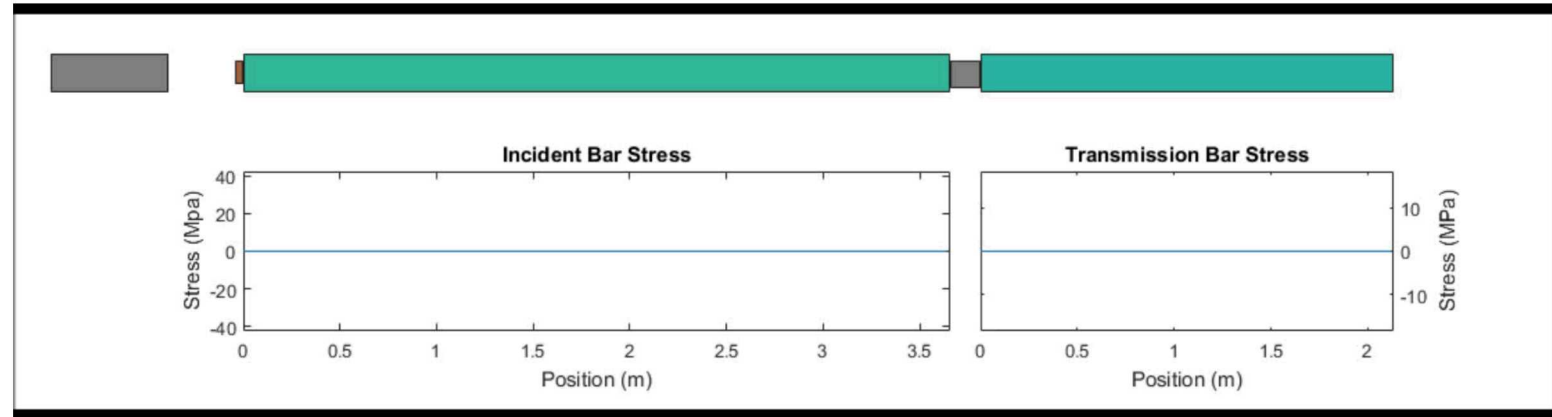
***Similar setup but different languages*****Split Hopkinson Bar/Kolsky Bar**

- Stress/Force
- Strain/Displacement
- Strain rate/Velocity
- Stress-strain (or Force-displacement) curve

**Hopkinson Bar**

- Acceleration
- Duration
- Frequency
- Shock response spectrum (SRS)

# *One-dimensional Elastic Stress Wave Propagation*



## Mass Conservation

$$V_1 = C_0(\varepsilon_i - \varepsilon_r)$$

$$V_2 = C_0\varepsilon_t$$

$$\dot{\varepsilon} = \frac{V_1 - V_2}{l_s} = \frac{C_0}{l_s}(\varepsilon_i - \varepsilon_r - \varepsilon_t)$$

$$\varepsilon = \int_0^t \dot{\varepsilon}(\tau) d\tau$$

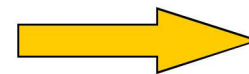
## Momentum Conservation

$$F_1 = E_0 A_0(\varepsilon_i + \varepsilon_r)$$

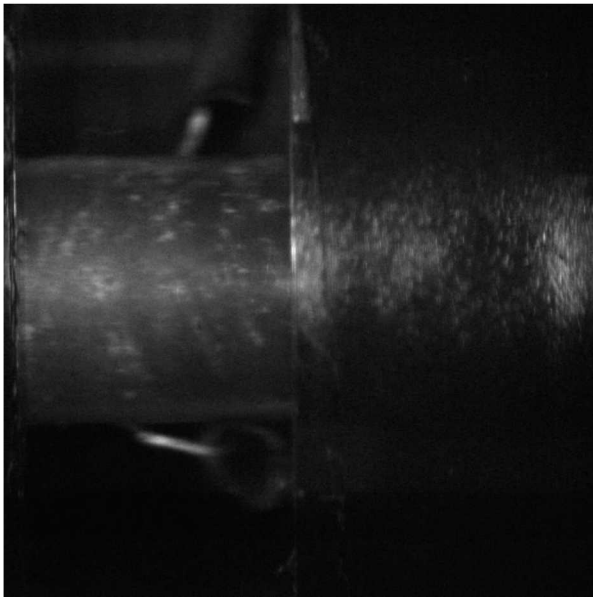
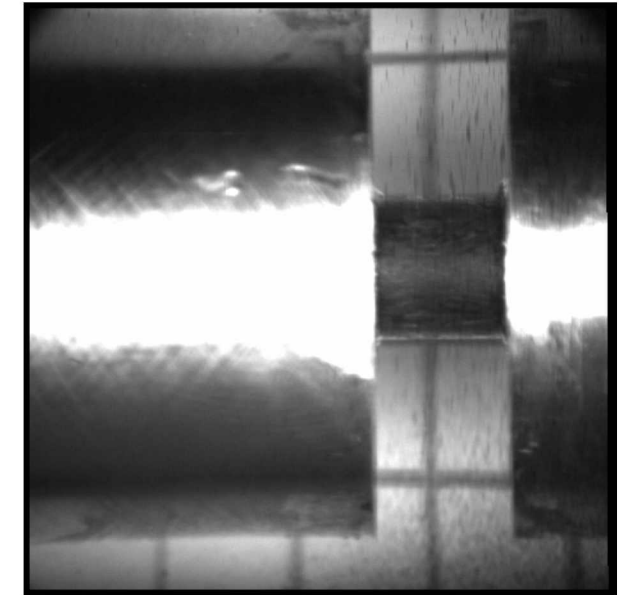
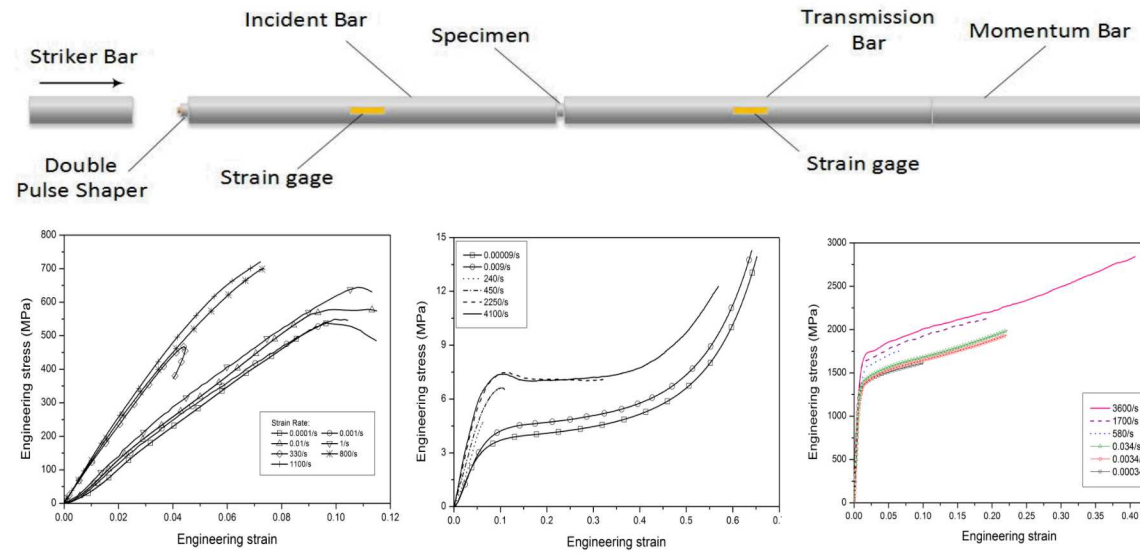
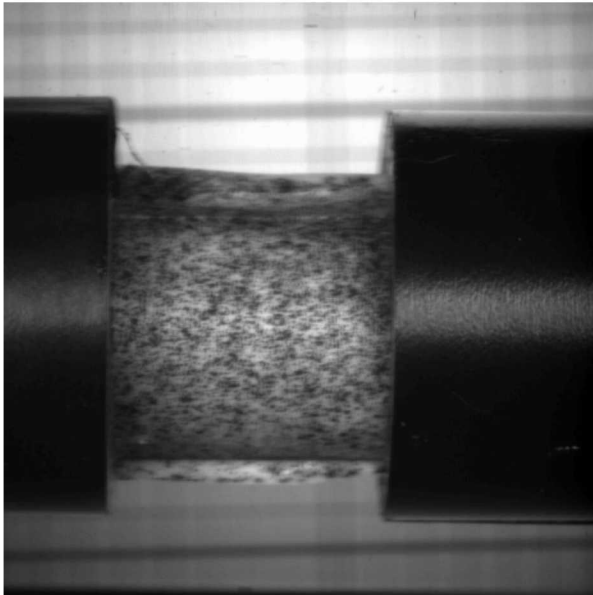
$$F_2 = E_0 A_0 \varepsilon_t$$

$$\sigma = \frac{F_1 + F_2}{2A_s} = \frac{E_0 A_0}{2A_s}(\varepsilon_i + \varepsilon_r + \varepsilon_t)$$

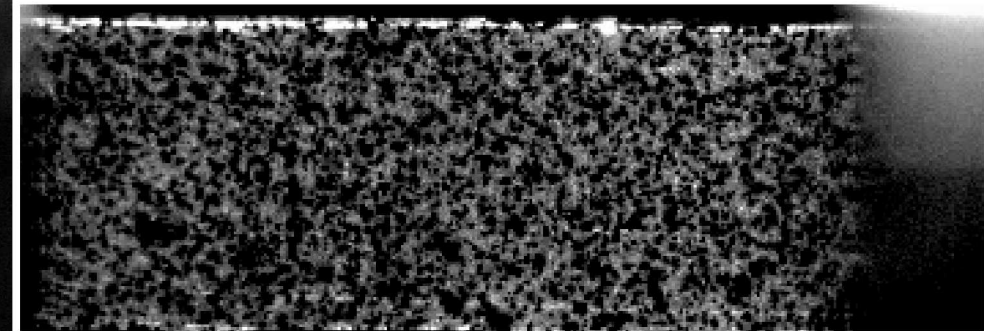
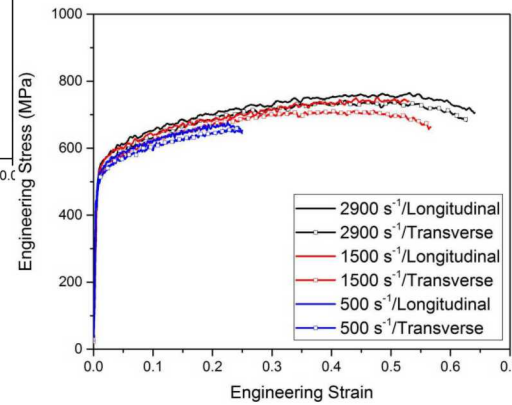
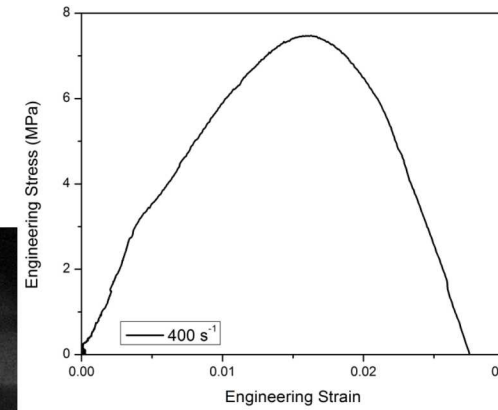
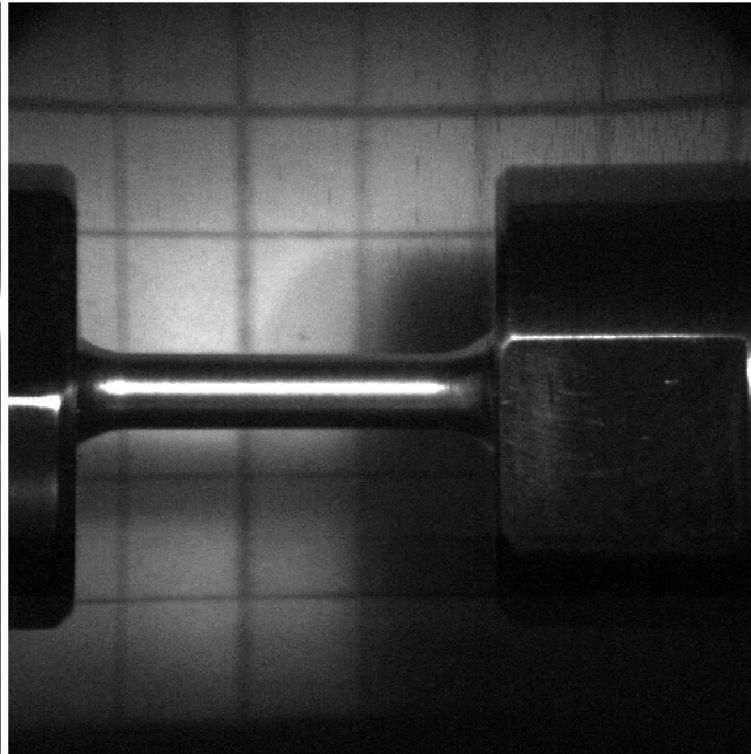
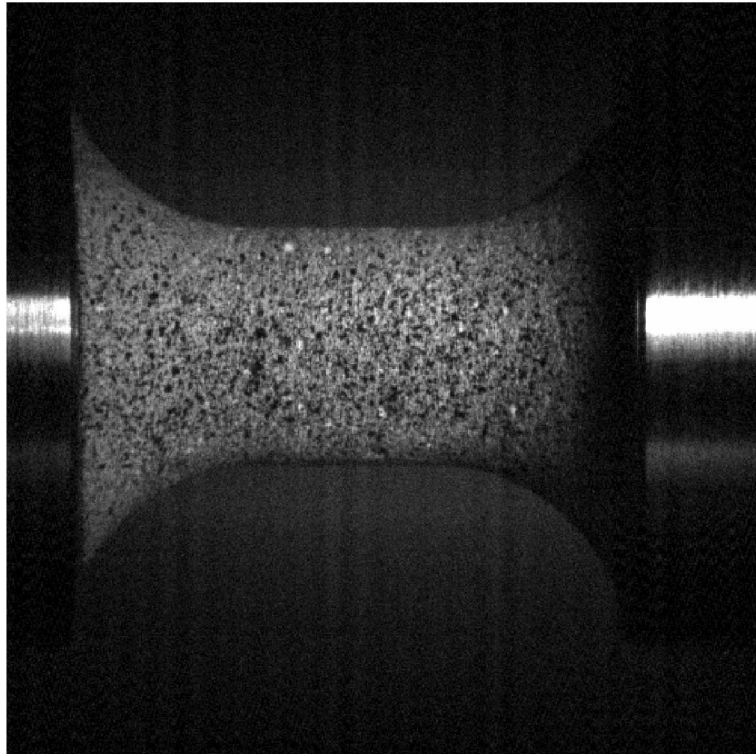
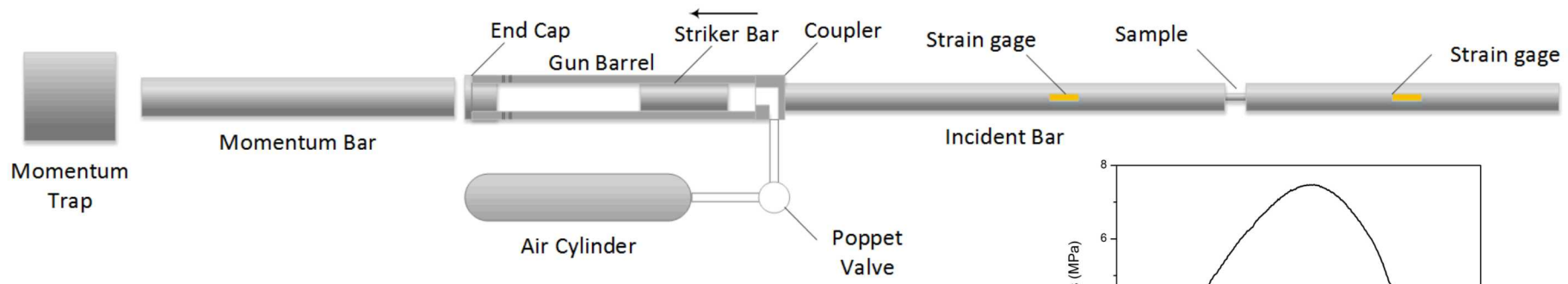
$$\sigma \sim \varepsilon$$



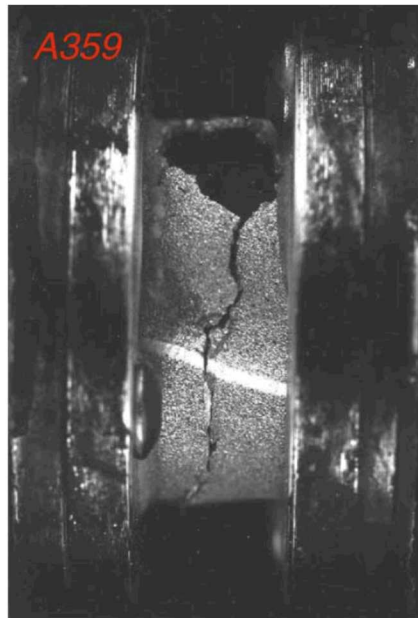
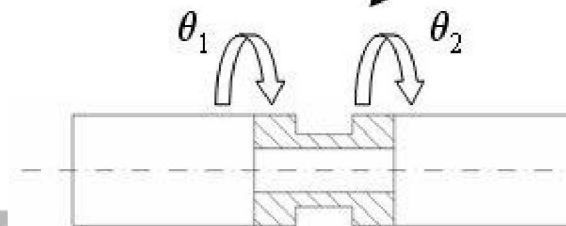
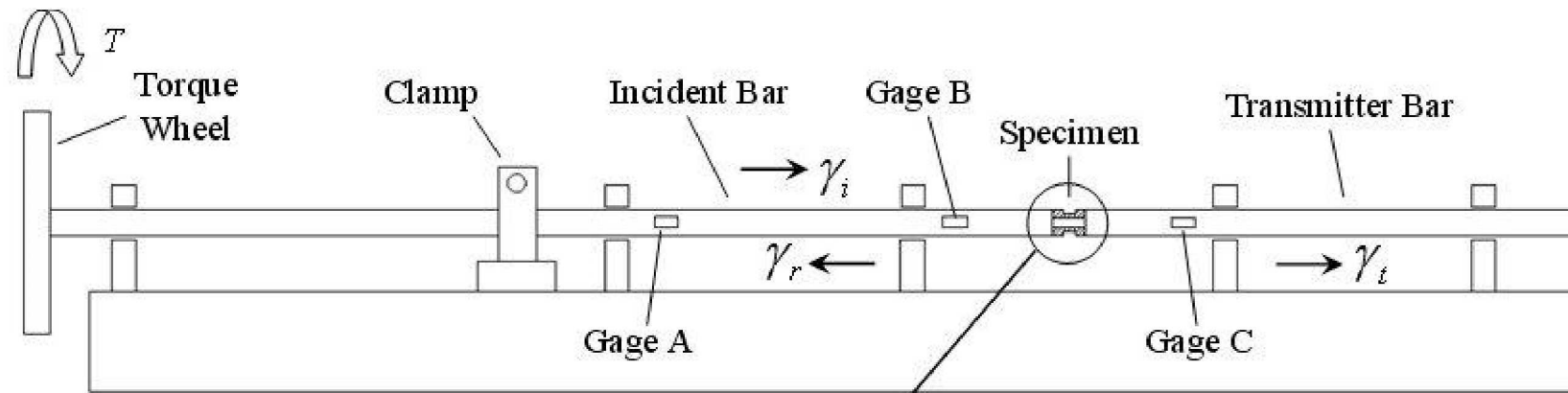
# Split Hopkinson (Kolsky) Bar for Compression



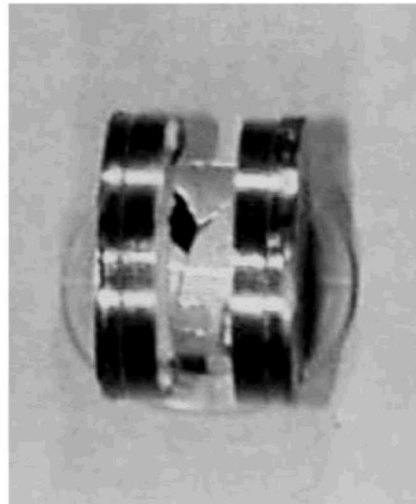
# Split Hopkinson (Kolsky) Bar for Tension



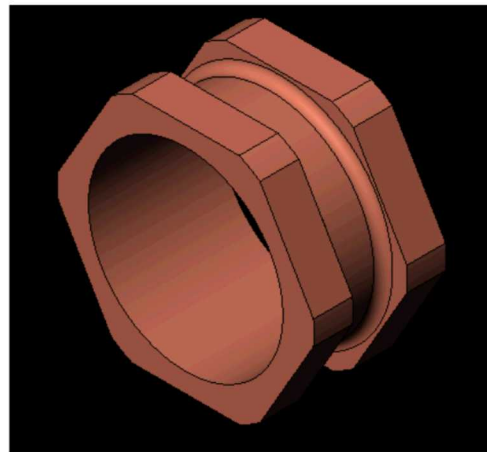
## 9 Split Hopkinson (Kolsky) Bar for Torsion



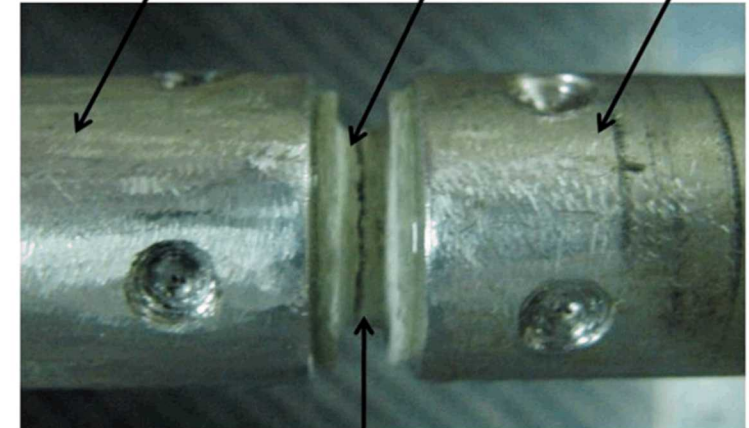
(a) Matrix Specimen



(b) Composite Specimen

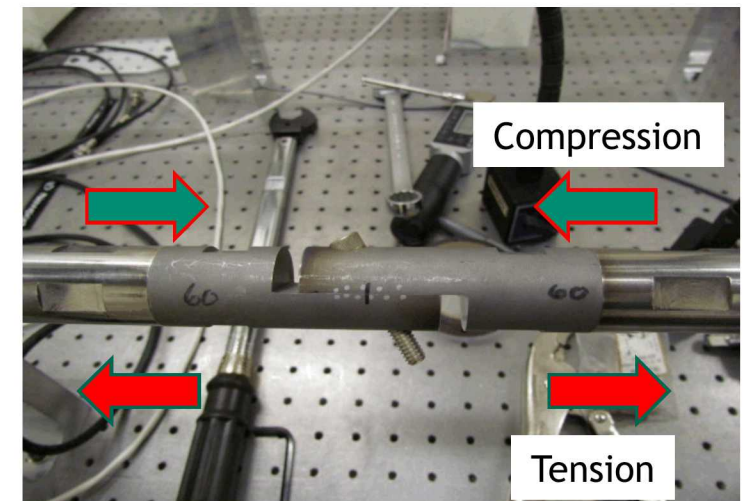
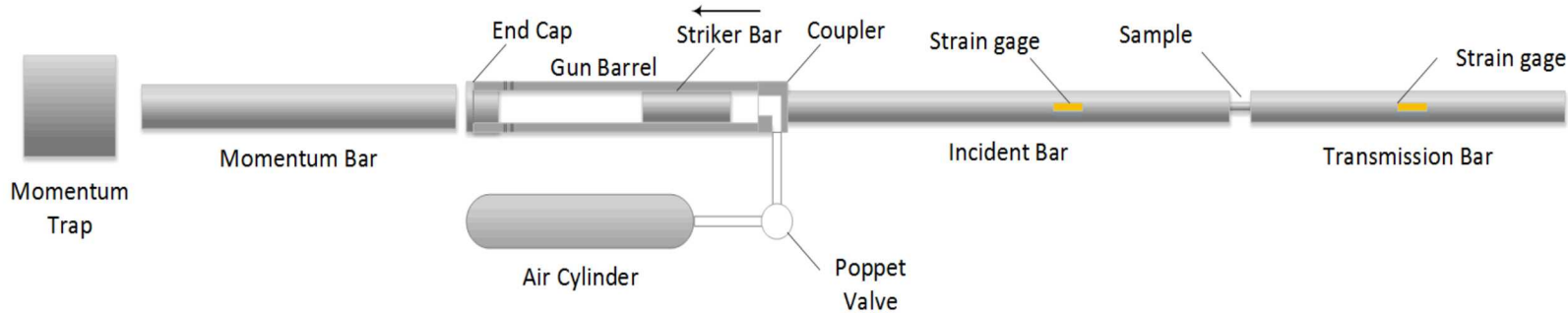
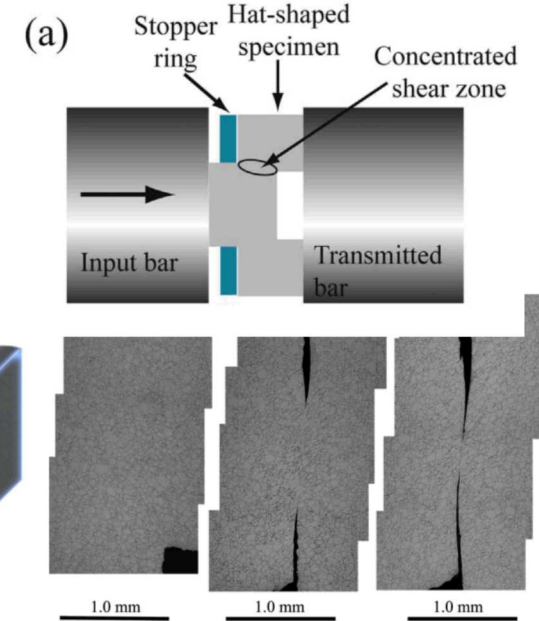
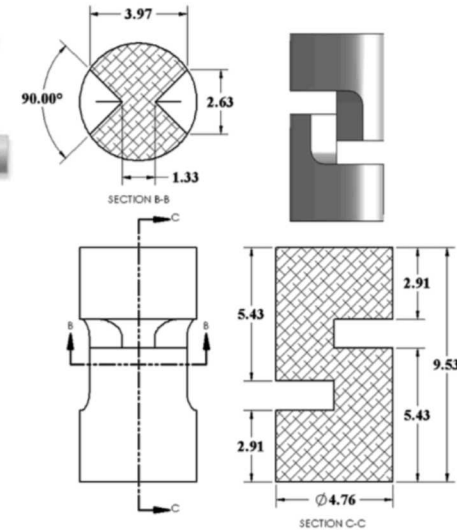
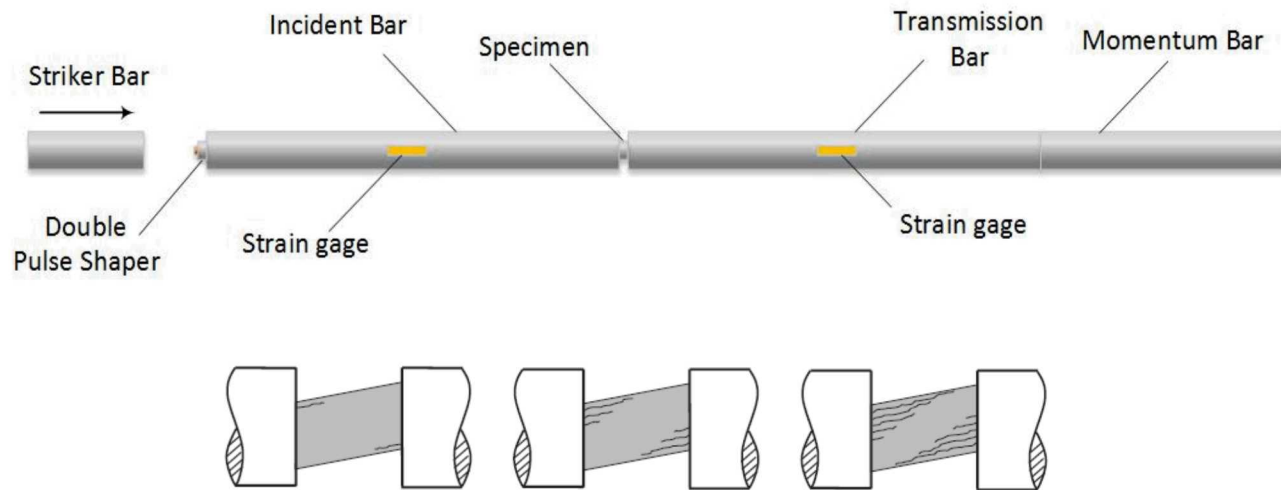


(b) Transmitter bar Failed specimen Incident bar

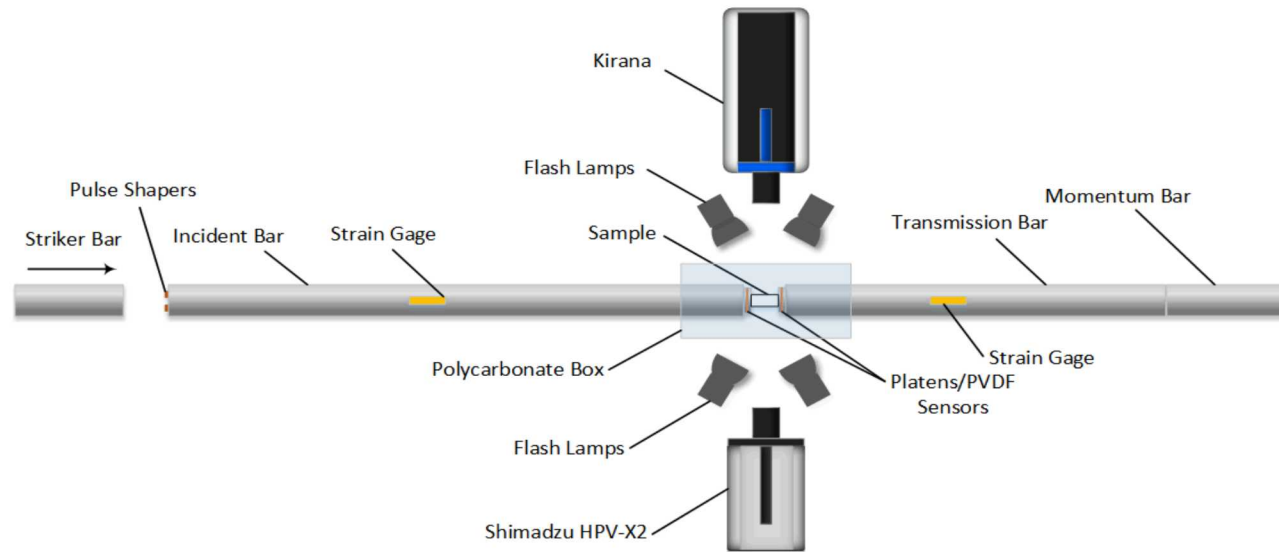


Fracture plane

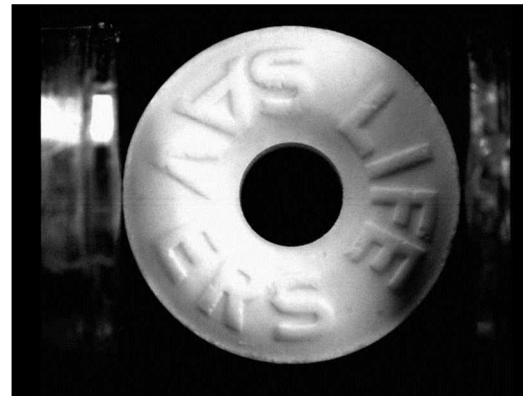
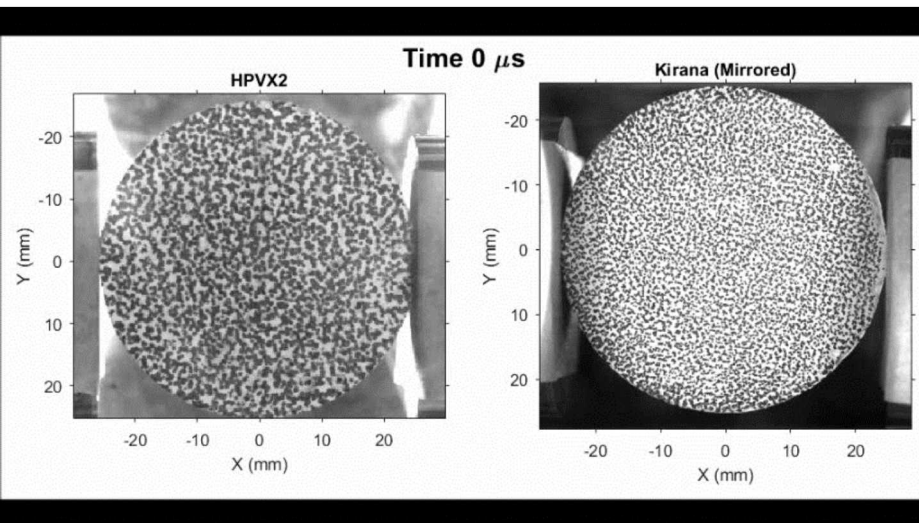
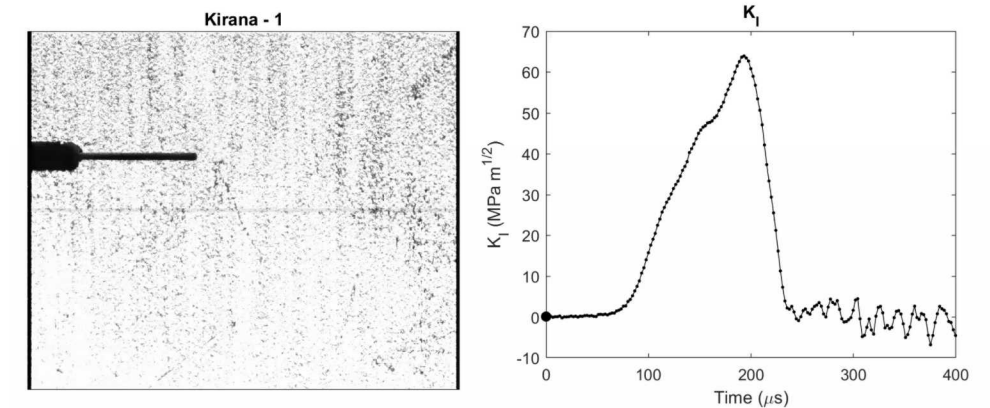
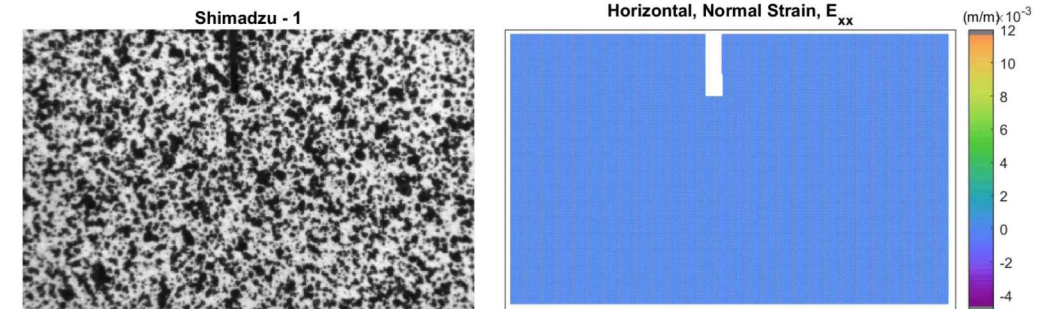
# Split Hopkinson (Kolsky) Bar for Dynamic Shear, Compression/Shear, Tension/Shear



# Split Hopkinson (Kolsky) Bar for Dynamic Fracture



Sample01

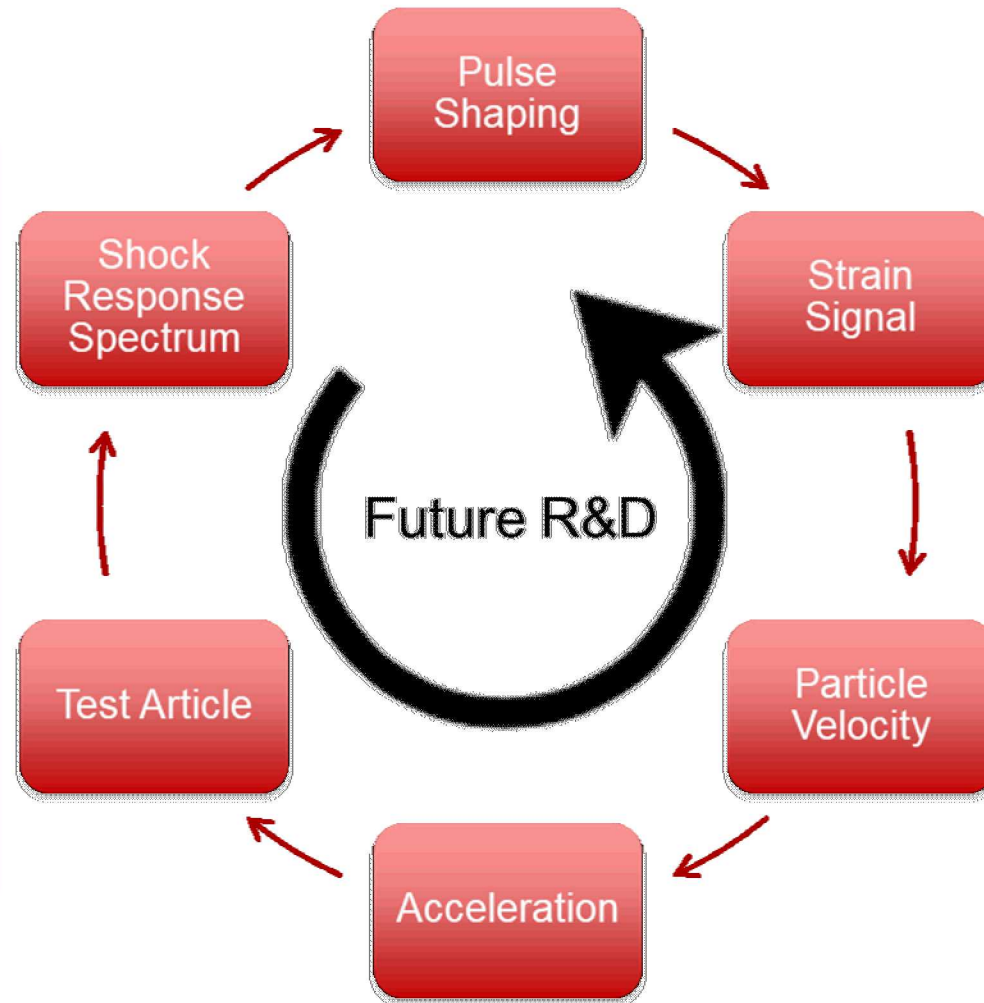


## General Principles

- *Send a high-acceleration, high-frequency shock wave to excite test articles*
- *Test the components in terms of survivability, functionality, etc.*

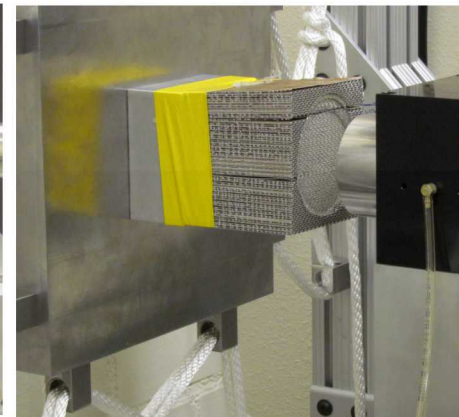
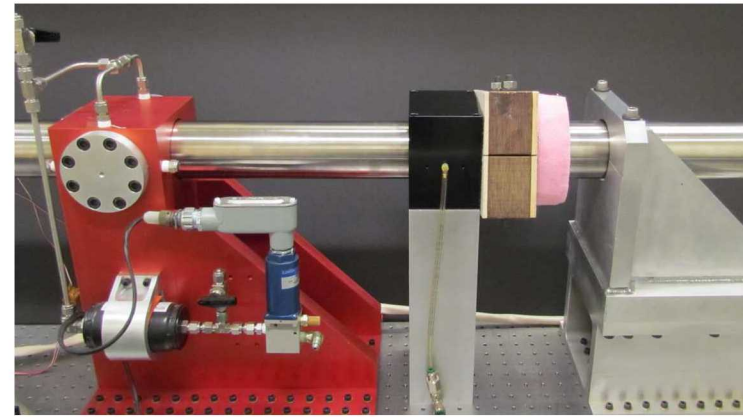
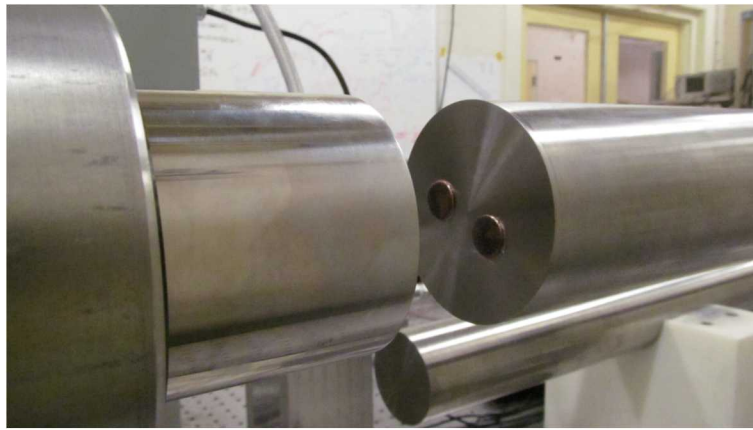
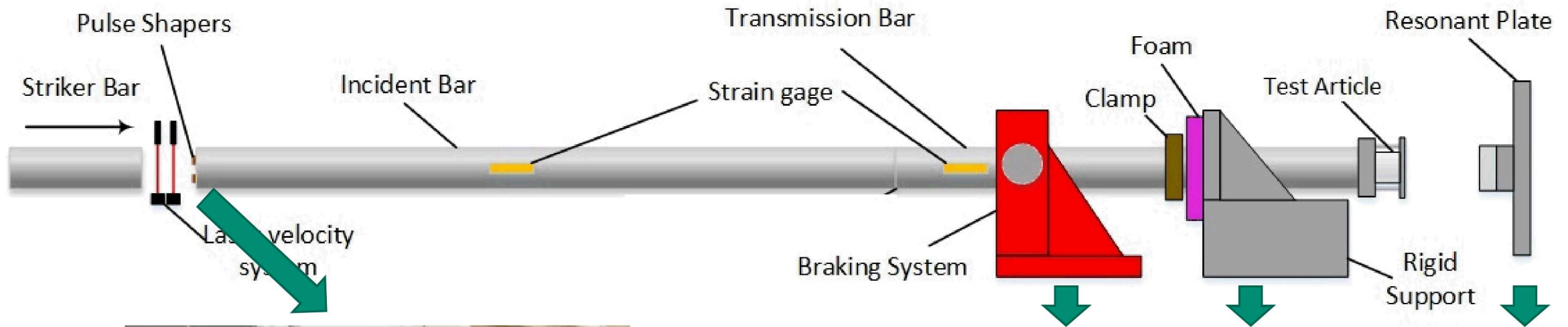
### Keys:

- Acceleration (g-level)
- Duration
- Frequency
- Shock response spectrum (SRS)

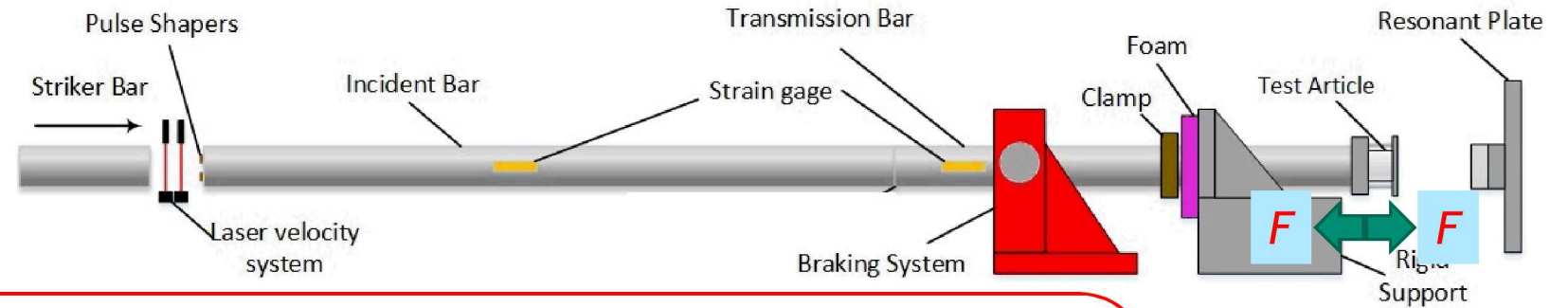


## General Configuration

- *Pulse shaping for desired pulses (g-level, frequency, duration, etc)*
- *Bar stop mechanism (braking system, clamp, etc)*
  - *Not to smash/crush the test article*



## Design Considerations



### • *Bar Material*

- Higher yield strength

- ✓ Higher load capacity
- ✓ Higher g-level
- ✓ Larger mass

- Higher elastic wave speed

- ✓ Shorter rise time
- ✓ Higher frequency

### • *Bar Diameter*

- Larger cross-sectional area

Trade Off



- ✓ Larger size test article
- ✓ High load capacity
- ✓ Higher g-level
- ✓ Larger mass

- Longer rise time

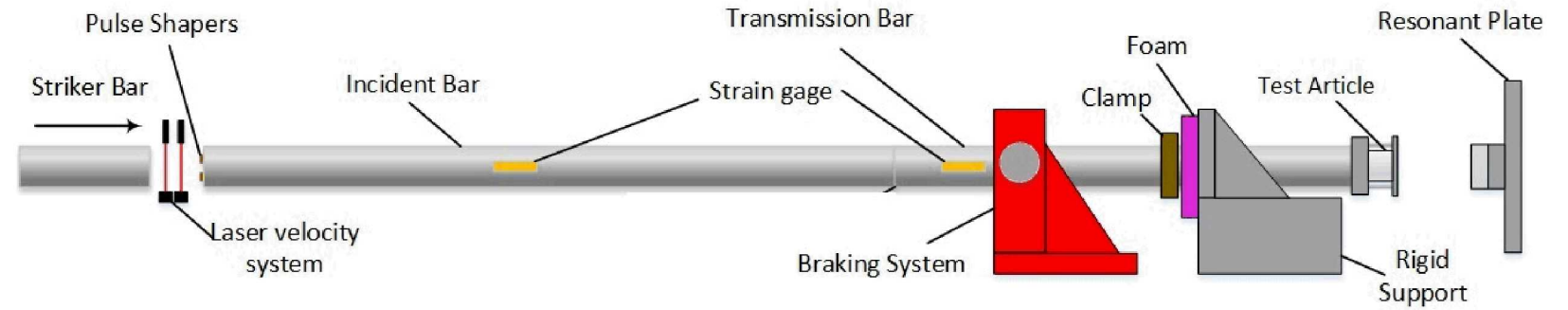
- ✓ Lower frequency

$$F = m \cdot a$$

$m \uparrow \updownarrow a \uparrow$

$$F = \sigma \cdot A \uparrow$$

## Design Considerations



- *Bar Length*

➤ Recommendation: at least 2 times of striker length for not messing up strain gage signal

➤ “Natural frequency” due to wave propagation back and forth in the bar

$$f = \frac{C_0}{2L}$$

For a 12'-long bar,

$$f \sim 700\text{Hz}$$

*For general mechanical shock tests, a large-diameter, relatively long Hopkinson bar made of a high-strength alloy is preferred.*

## 3"-Hopkinson Bar at Sandia National Laboratories

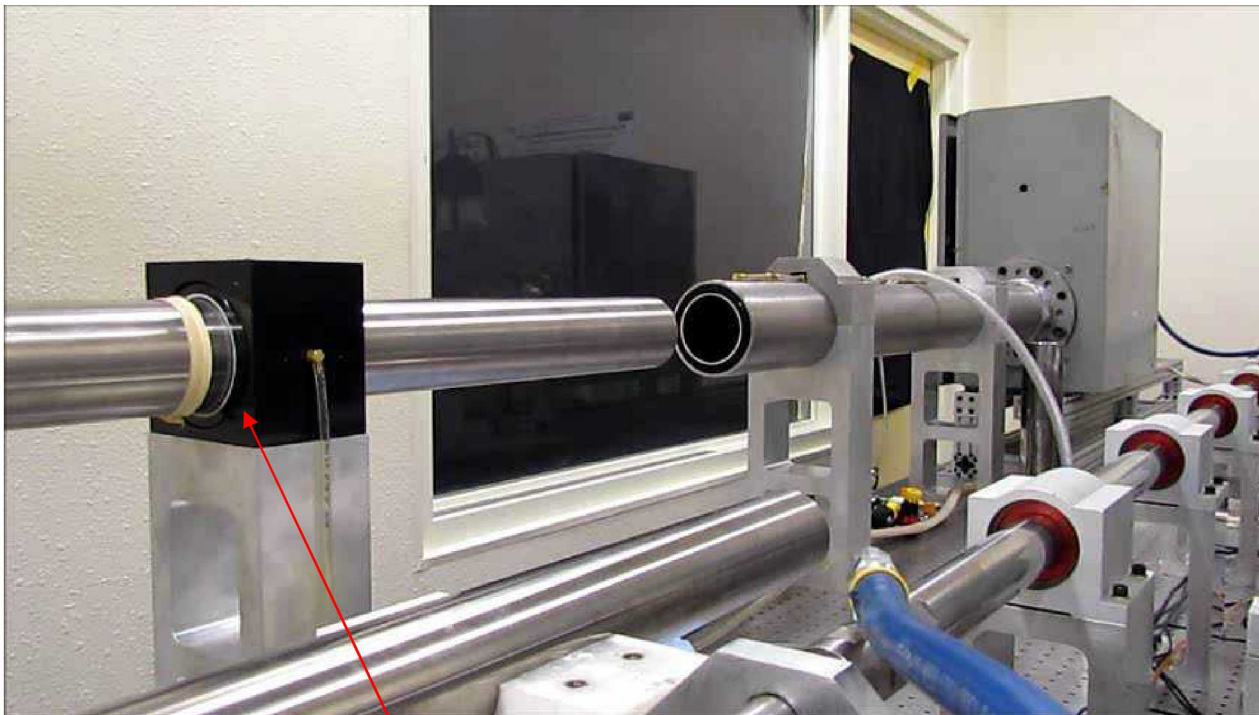
**Diameter: 3"**

**Length: 12' with additional 7' and 5' bars**

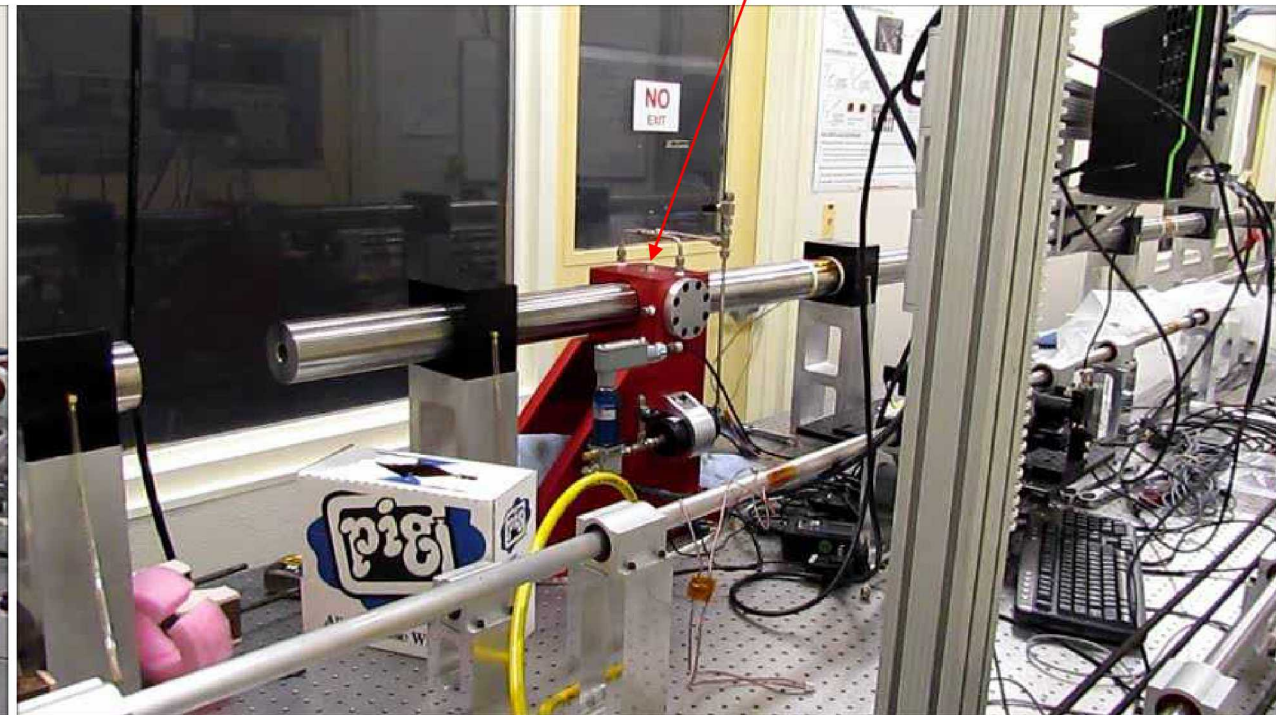
**Material: C300 maraging steel**

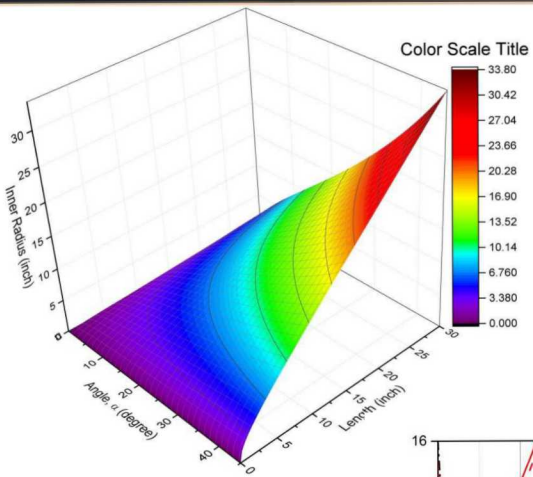
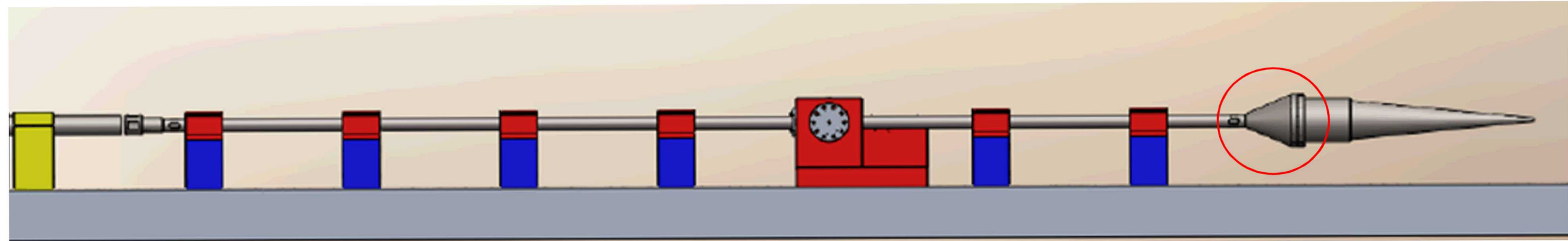
**Operation pressure: 60 psi**

Computer-Controlled  
Braking System

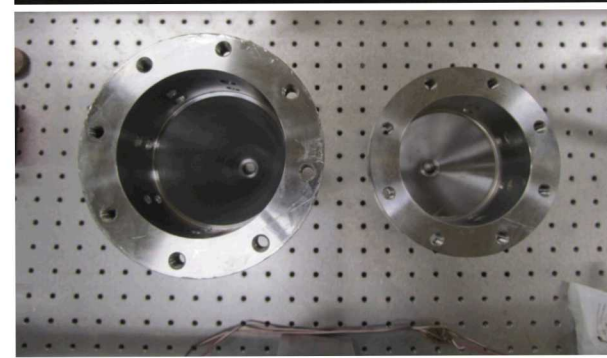
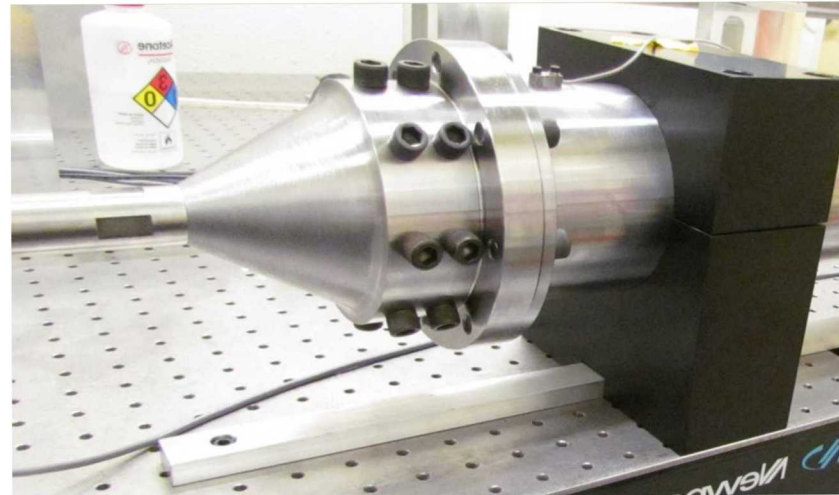
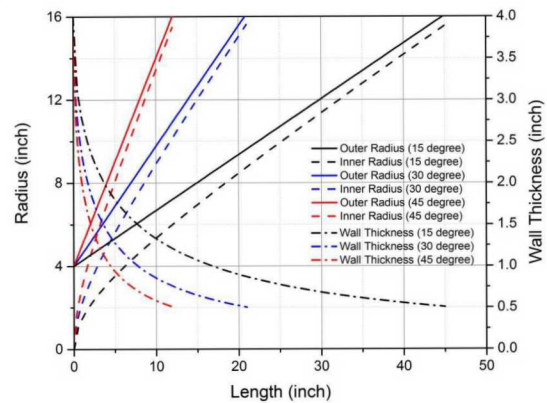


Air Bushing

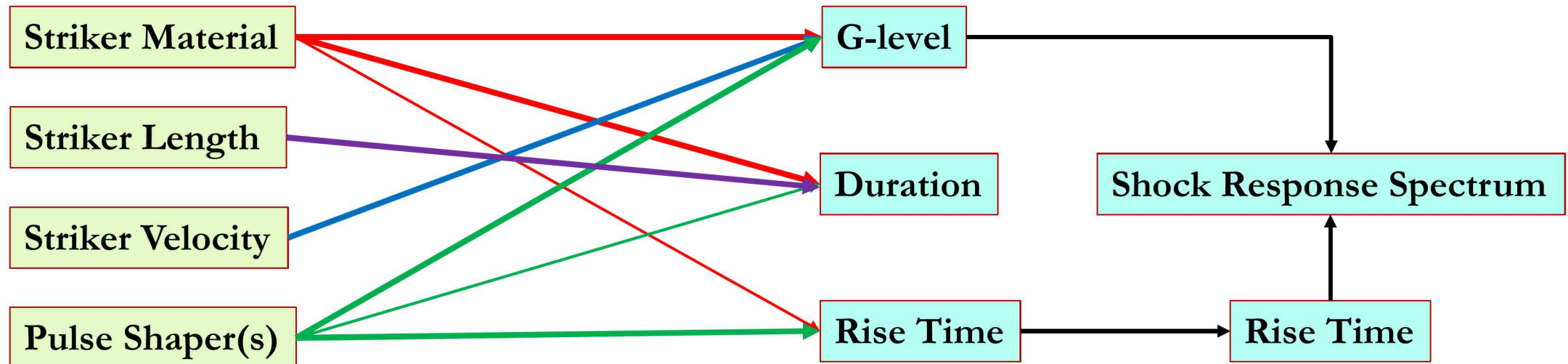
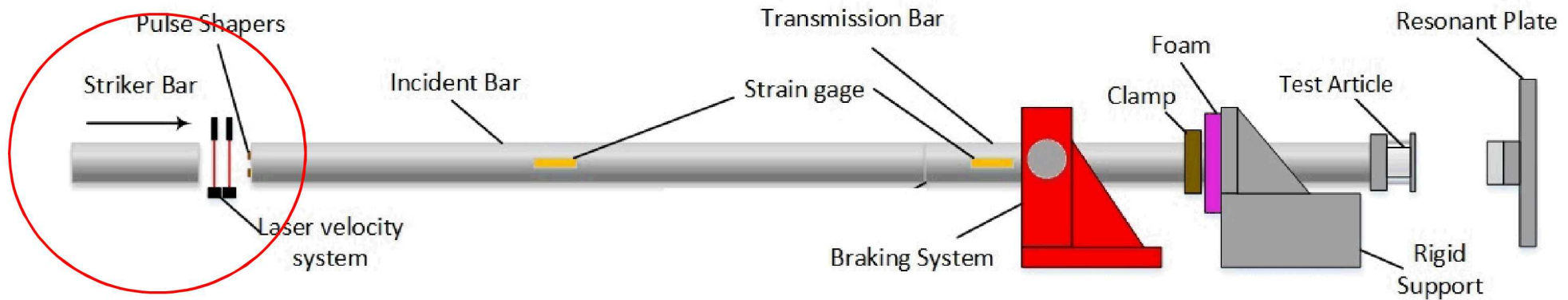


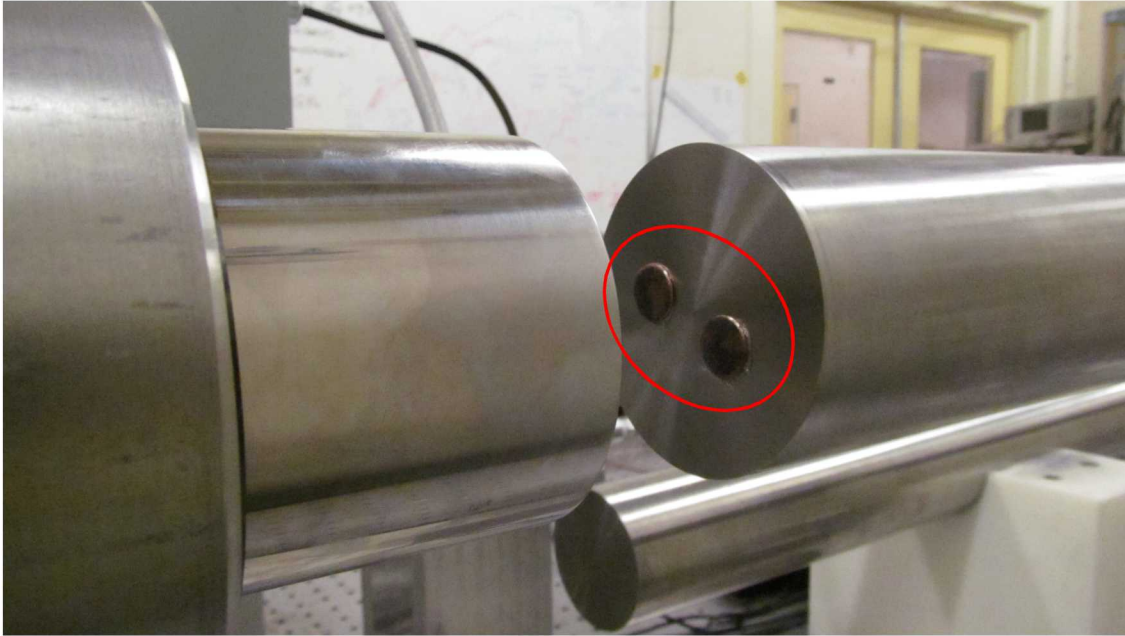


## Mechanical Impedance Matched Adapting Cone



## Test Design (Which Controls What?)

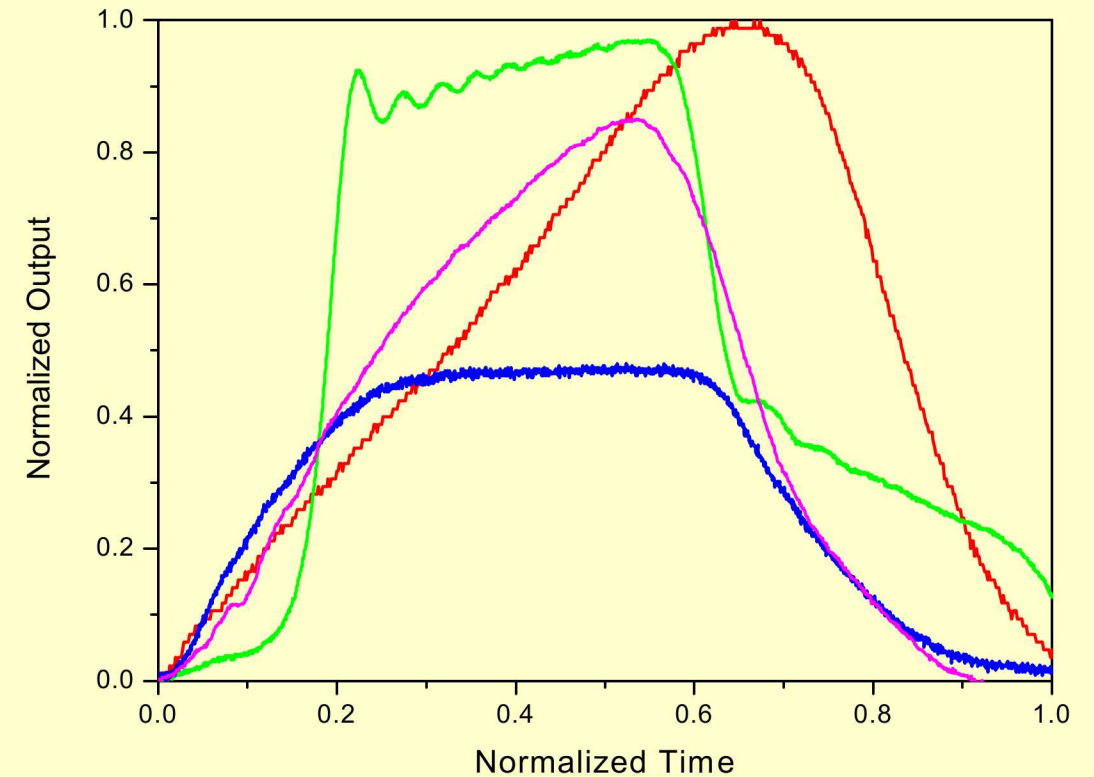




### Pulse Shaper(s)

- Material
- Diameter
- Thickness

*Pulse shaping design also depends on impact velocity and duration.*



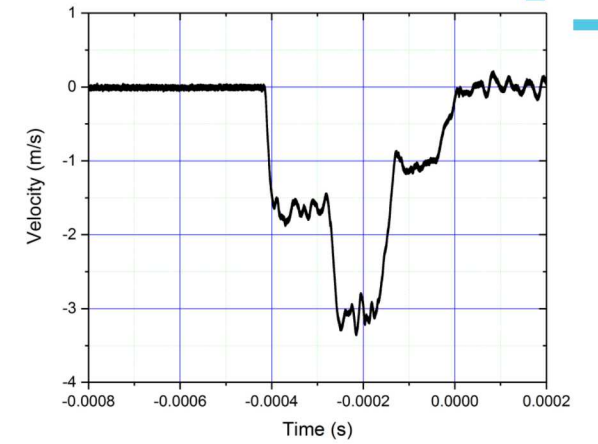
# Special Pulse Shaping Design Examples

*By changing striker material*

steel

Aluminum

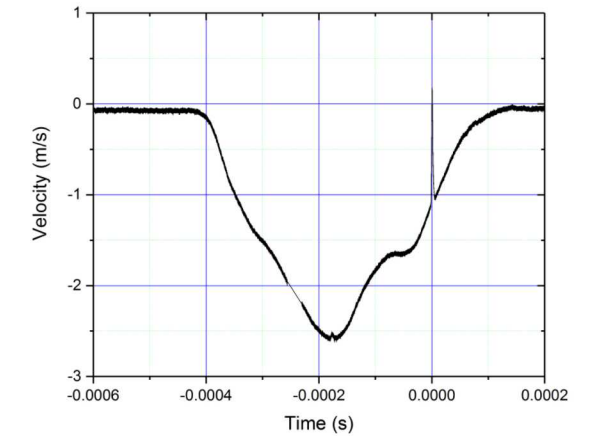
steel



steel

Aluminum

steel

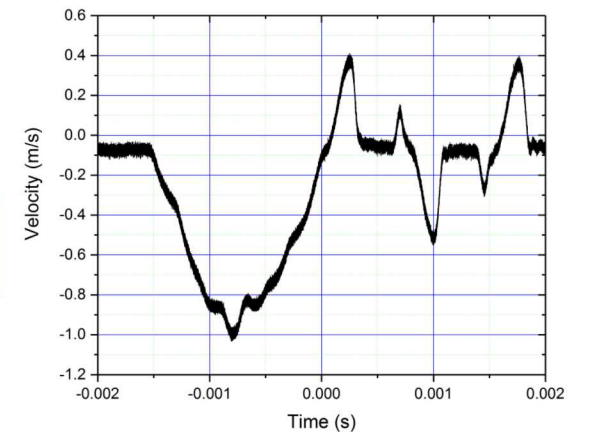


steel

Aluminum

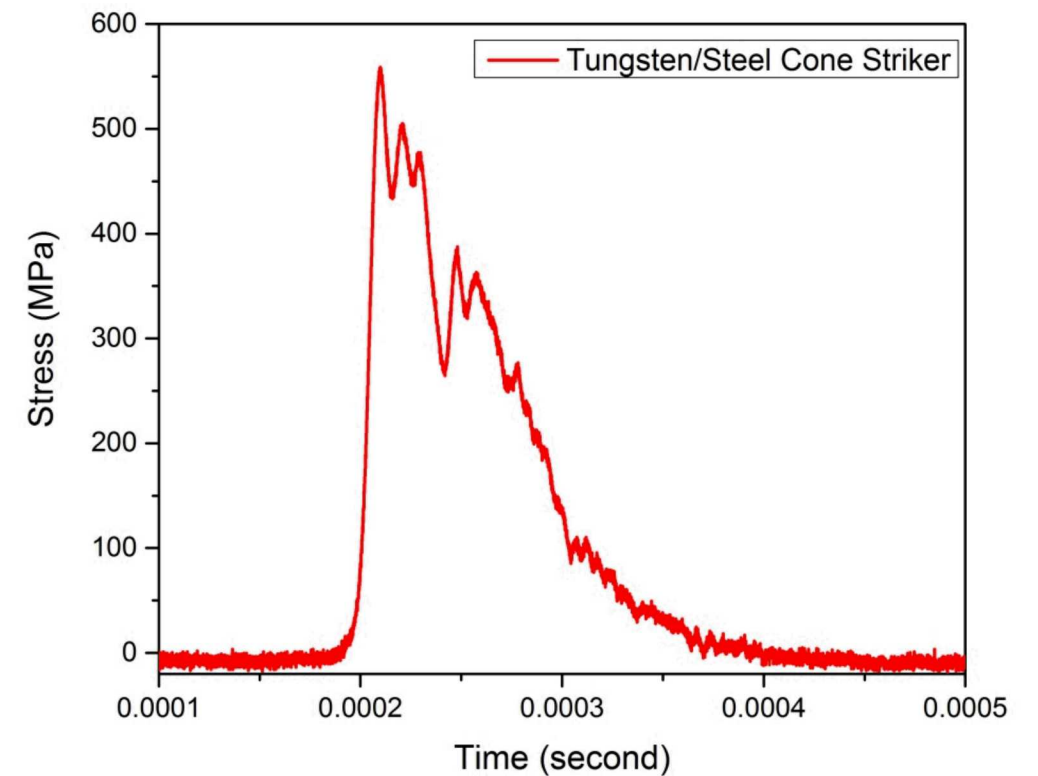
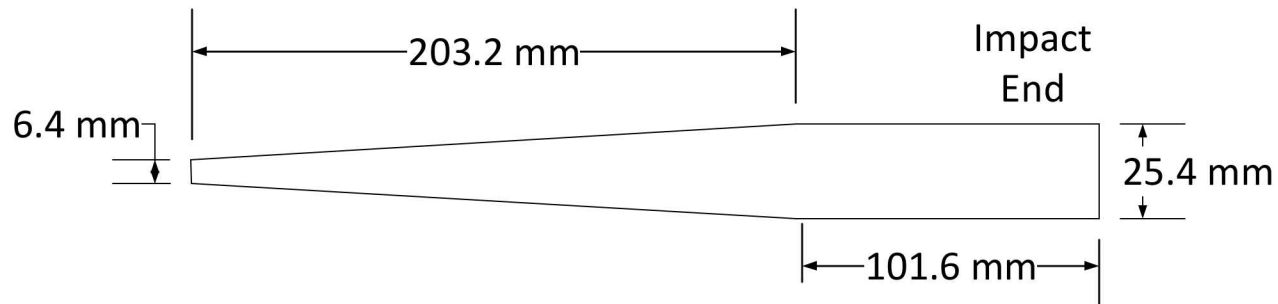
delrin

steel



## Special Pulse Shaping Design

*By changing striker shape (and material)*



### Striker impact velocity

$$V < \frac{2 \cdot \sigma_y}{\rho_0 \cdot C_0} = \frac{2 \cdot \sigma_y}{\sqrt{\rho_0 \cdot E_0}} \quad \text{(striker is made of the same material as the bar and had the same diameter)}$$

For maraging C300 steel,

$$\sigma_y = 300 \text{ ksi} \approx 2.1 \text{ GPa}$$

$$\rho_0 = 8000 \text{ kg/m}^3$$

$$E_0 = 189.6 \text{ GPa}$$



$$V < 107.8 \text{ m/s}$$

### Rise Time for Velocity

$$\Delta t \square \frac{2.5 \cdot D_{bar}}{C_0} = \frac{2.5 \cdot D_{bar}}{\sqrt{E_0 / \rho_0}}$$

For 1"-diameter maraging C300 steel bar,

$$D_{bar} = 1" = 25.4 \text{ mm}$$

$$\rho_0 = 8000 \text{ kg/m}^3$$

$$E_0 = 189.6 \text{ GPa}$$



$$\Delta t \square 13 \mu\text{s}$$

**Acceleration**

$$a = \frac{V}{\Delta t}$$

For 1"-diameter maraging C300 steel bar,

$$V < 107.8 m/s$$

$$\Delta t \leq 13 \mu s$$



$$a < 8,300,000 m/s^2 = 846,000 g$$

A more conservative estimate:  $a < 400,000 g$

**Frequency for Velocity**

$$f_V = \frac{1}{\Delta t}$$

For 1"-diameter maraging C300 steel bar,

$$f_V < 65 kHz$$

**Frequency for Acceleration**

$$F[a(t)] = F\left[\frac{dV(t)}{dt}\right] = i\omega \cdot V(\omega)$$

*The frequency would be much higher for accelerations.*

# Hopkinson Bar Limitations for Mechanical Shock Tests

## Duration of Loading

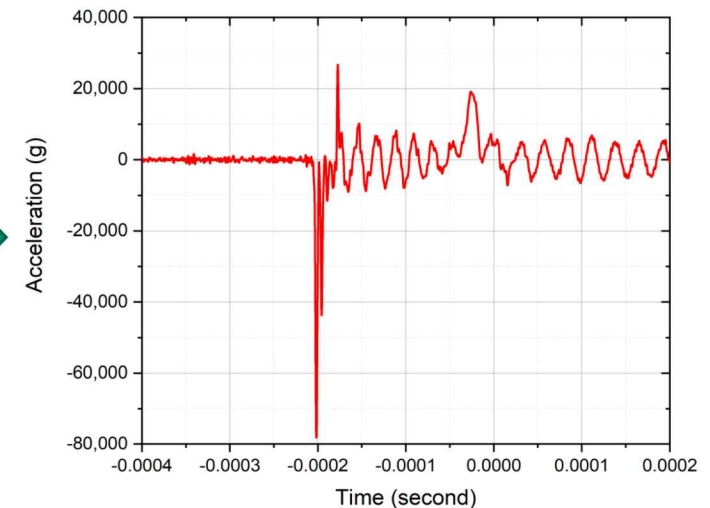
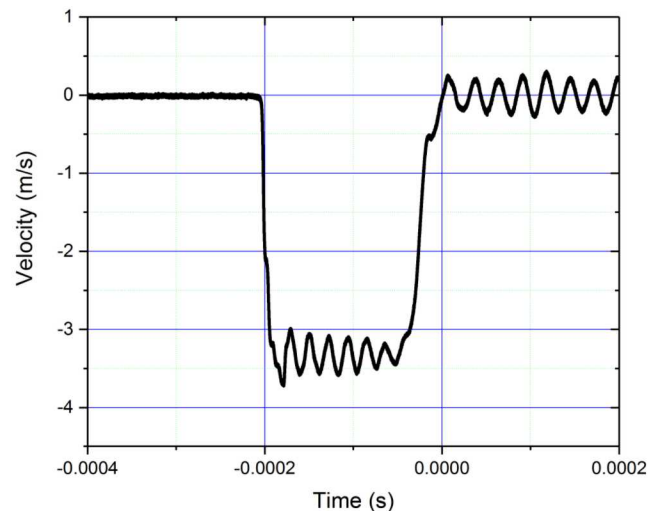
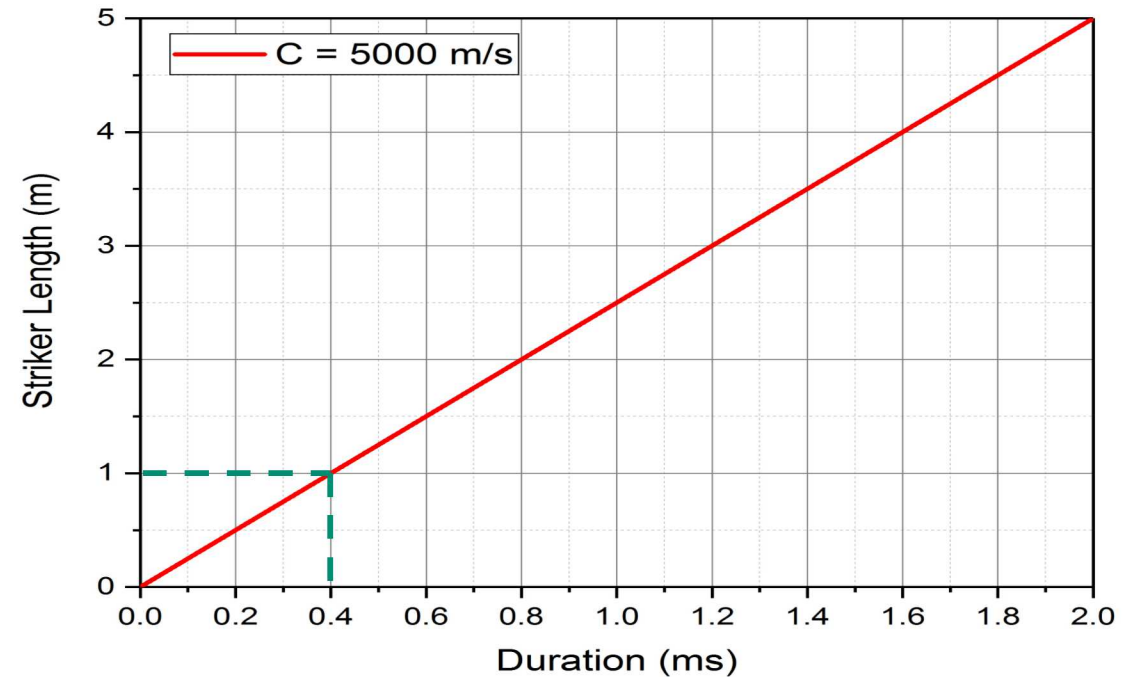
$$T = \frac{2 \cdot L_s}{C_0} = \frac{2 \cdot L_s}{\sqrt{E_0 / \rho_0}}$$

For 1-m-long maraging C300 striker,

$$T \approx 0.4 \text{ ms}$$

*This duration is for velocity pulse.  
For acceleration, the duration will  
be much shorter.*

*For a certain striker, pulse shaper(s)  
may further extend the duration of  
loading.*



# Hopkinson Bar Limitations for Mechanical Shock Tests

## Acceleration

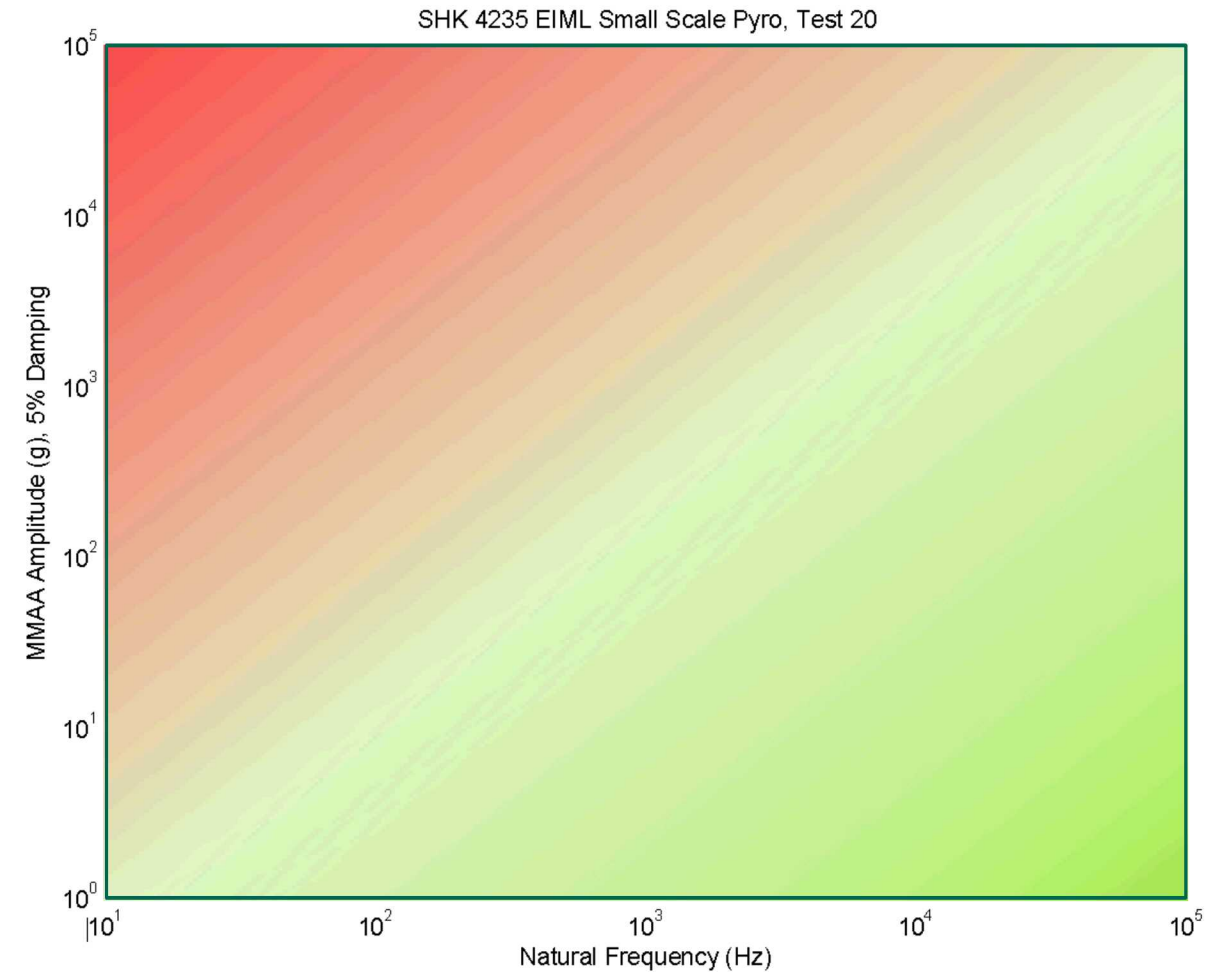
$$a \leq 400,000g$$

## Frequency

$$f \leq 100,000Hz$$

## Duration of Loading

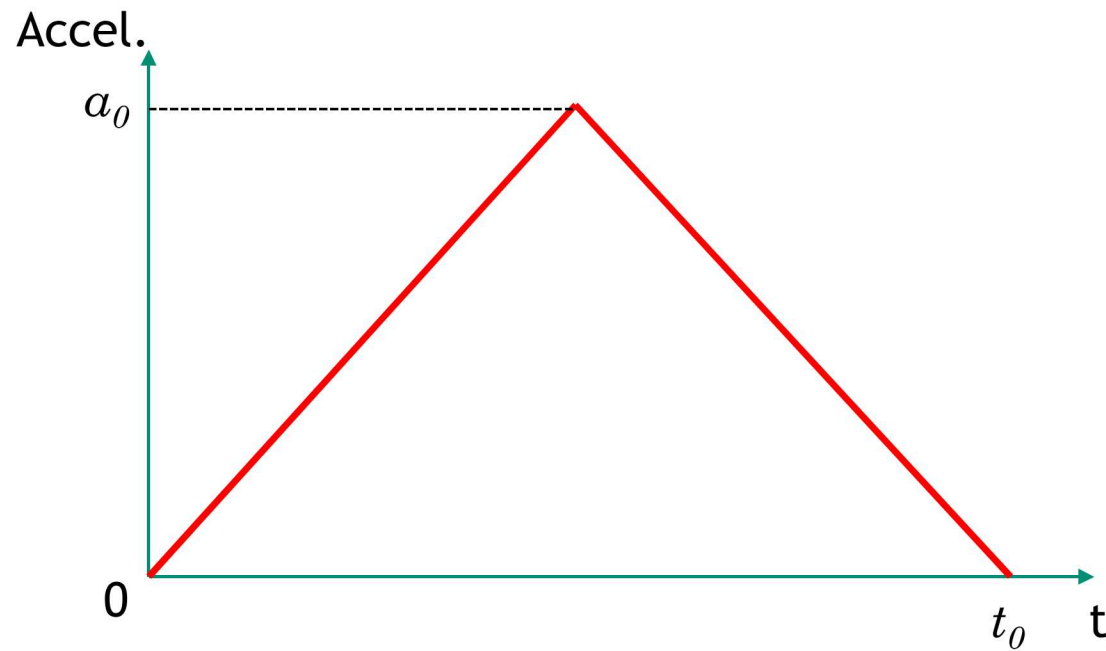
$$T \sim 0.4ms$$



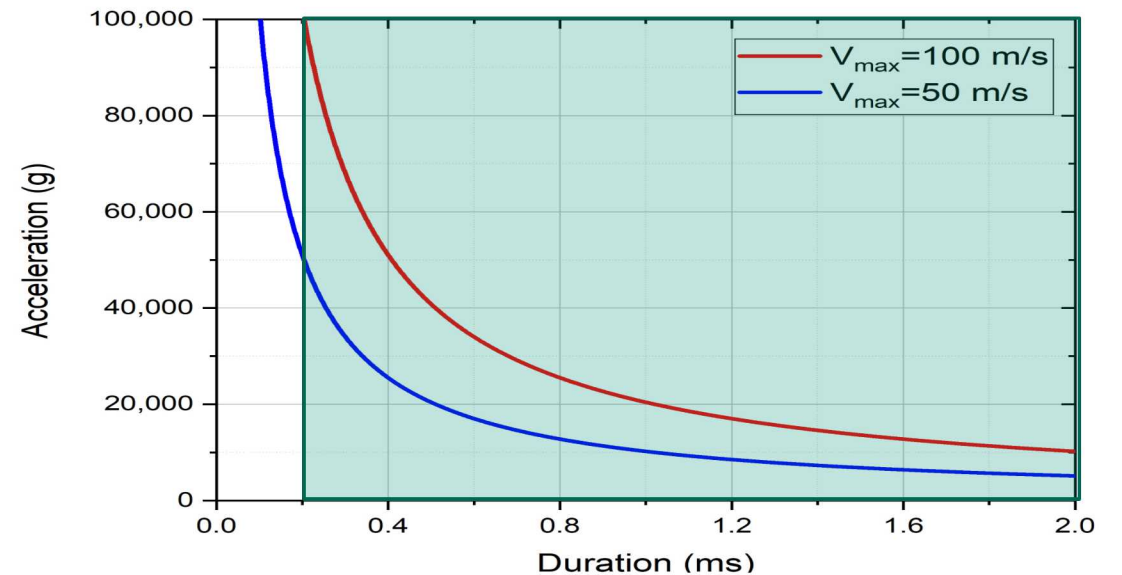
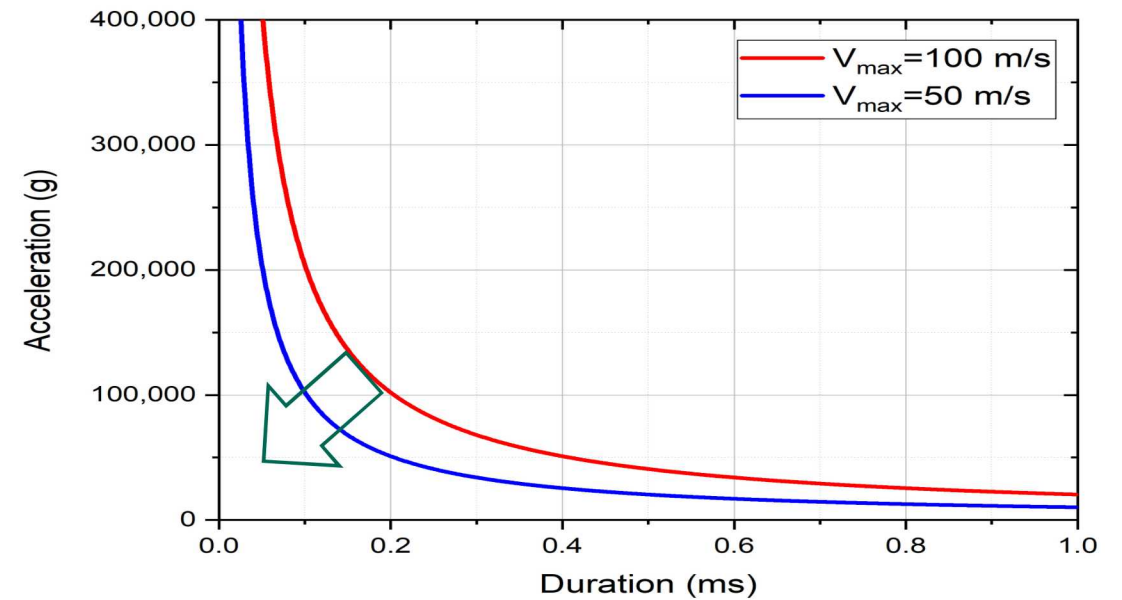
*Can we do all of them simultaneously in a single test?*

# A Very Tricky Problem

*For a triangular mechanical shock pulse with a peak of  $a_0$  and a loading duration of  $t_0$ .*



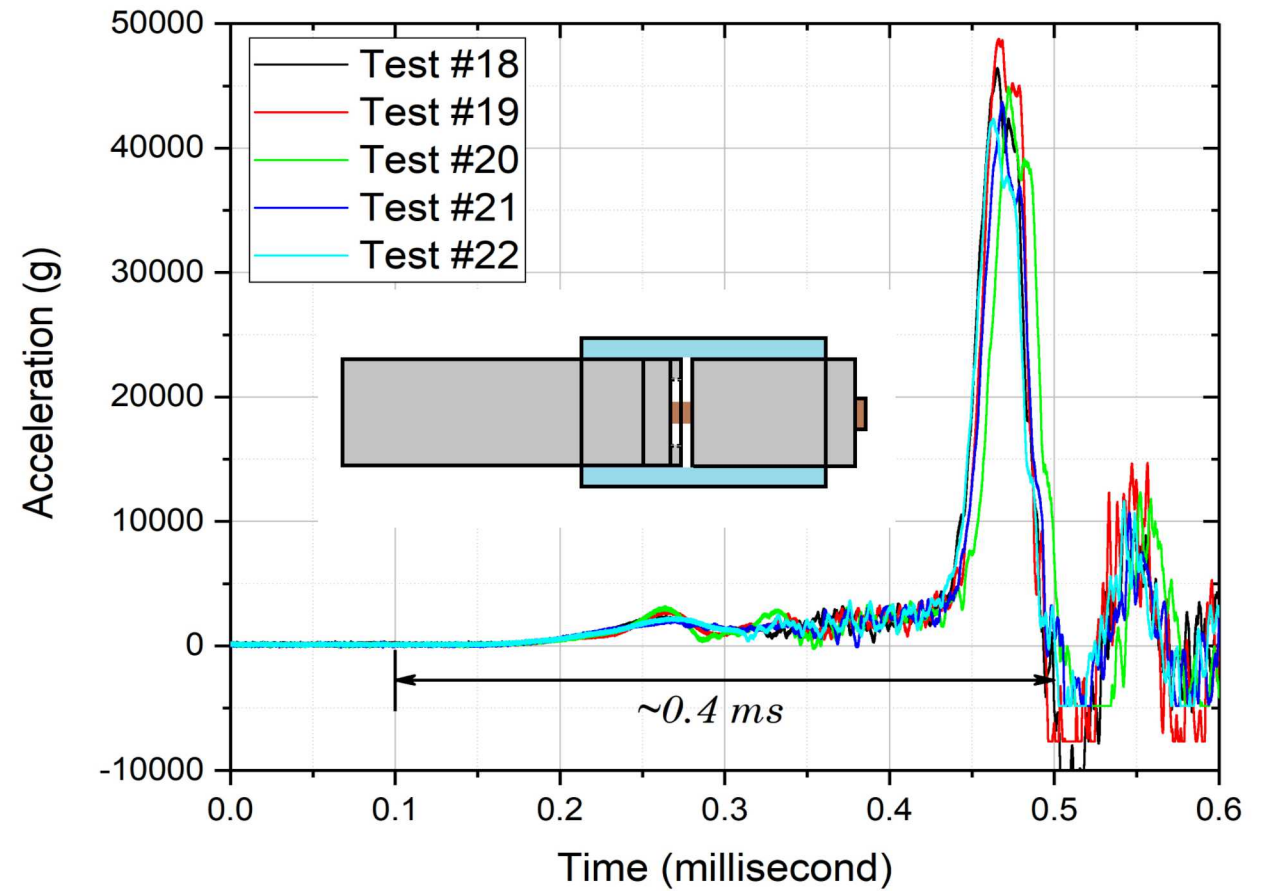
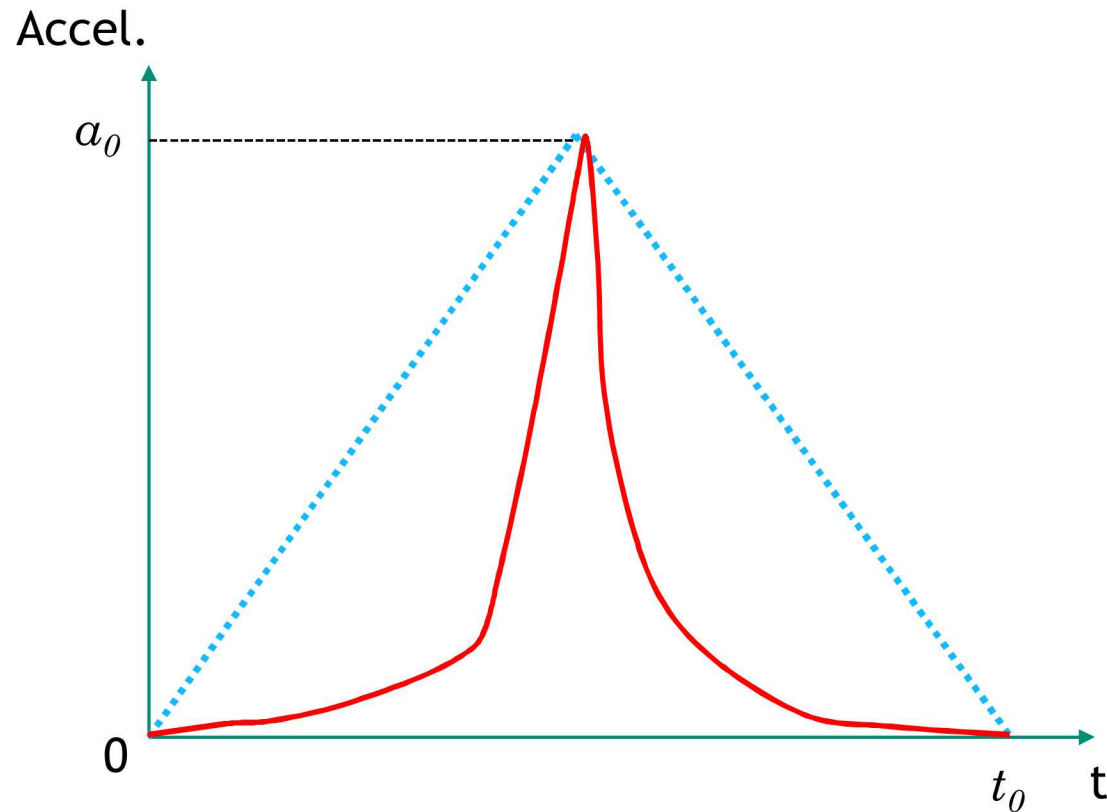
$$V = \int_0^{t_0} a(t) dt = \frac{1}{2} a_0 t_0 < V_{\max}$$





## Near-term Solution

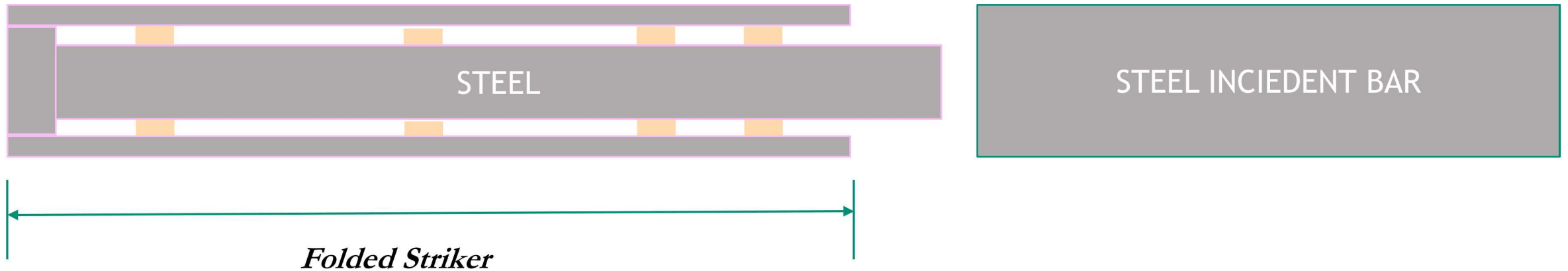
$$V = \int_0^{t_0} a(t) dt = \frac{1}{2} a_0 t_0 < V_{\max}$$



Very unique pulse shaping design



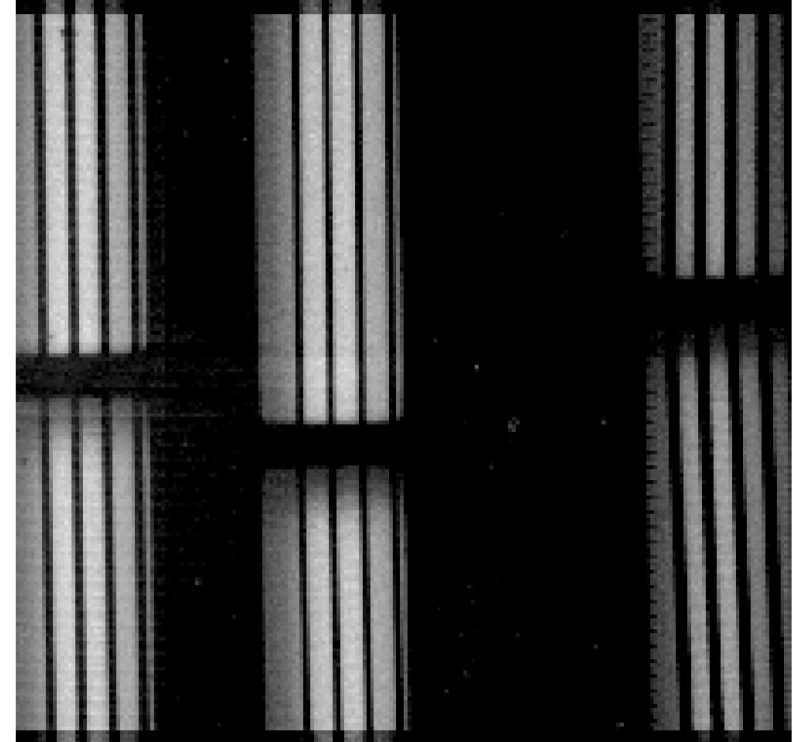
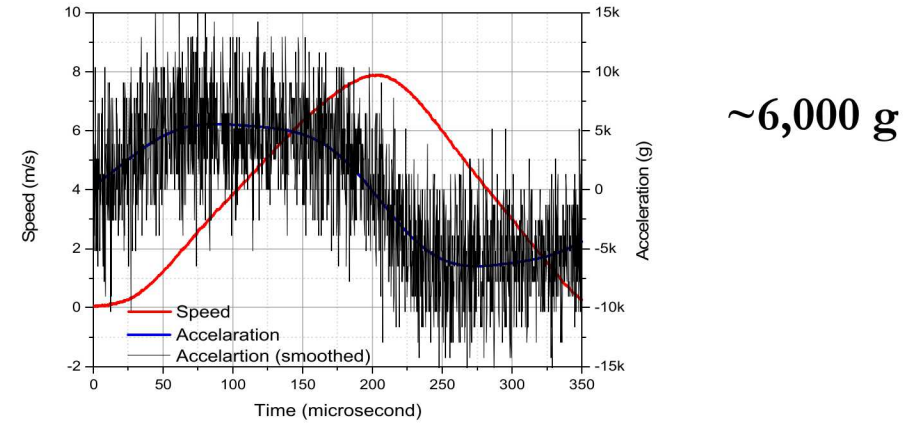
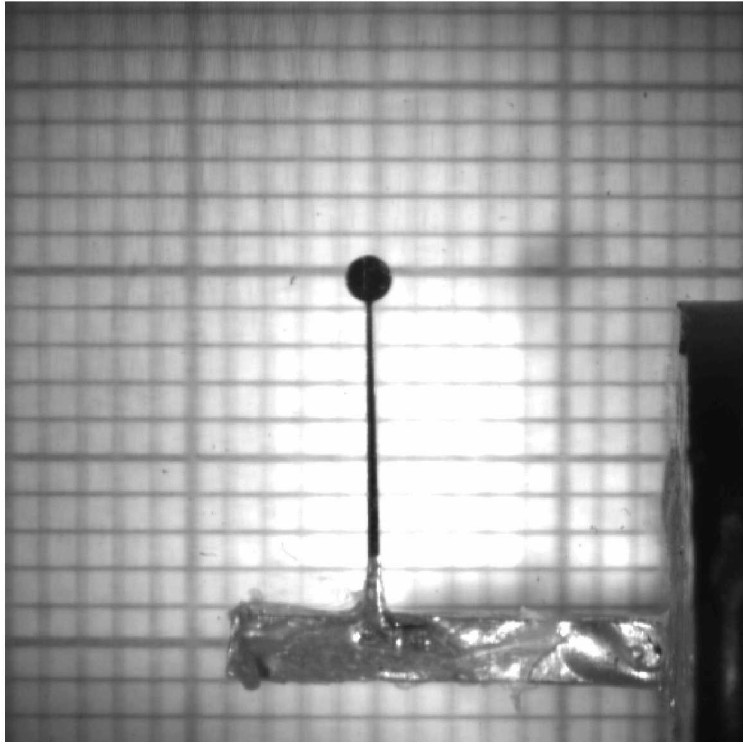
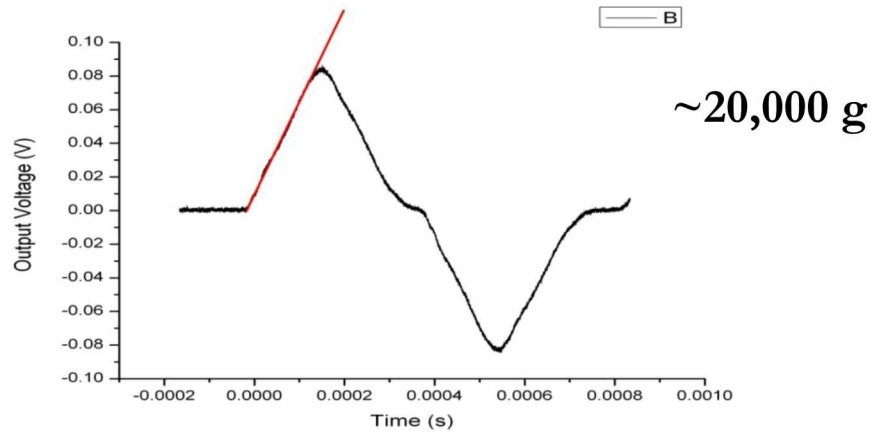
## Near-term Solution



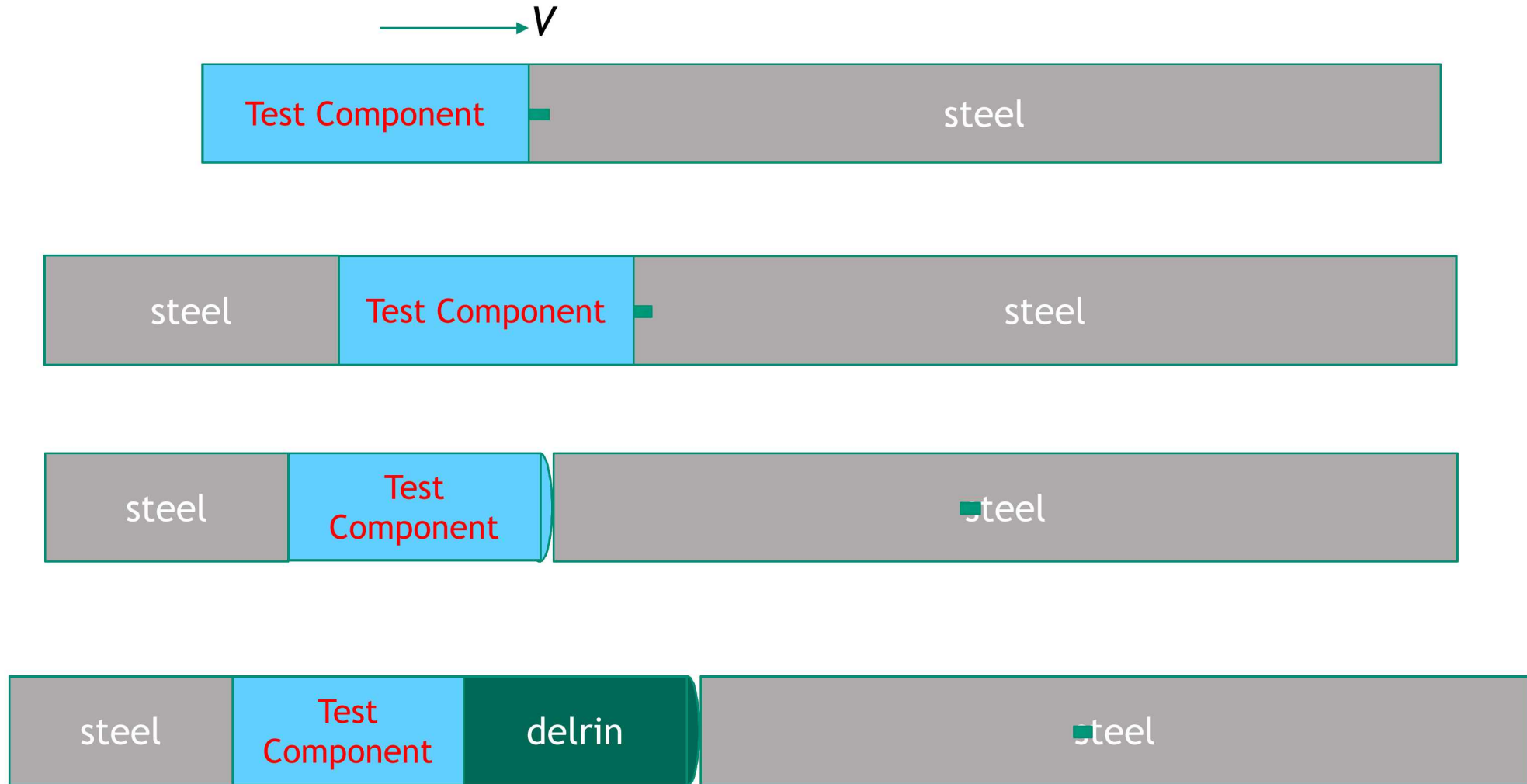
## Long-term Solution

**A large-diameter, long gas gun/Hopkinson bar system.**

# Examples – High-G Shock Tests of Microelectronic Devices with a Hopkinson Bar



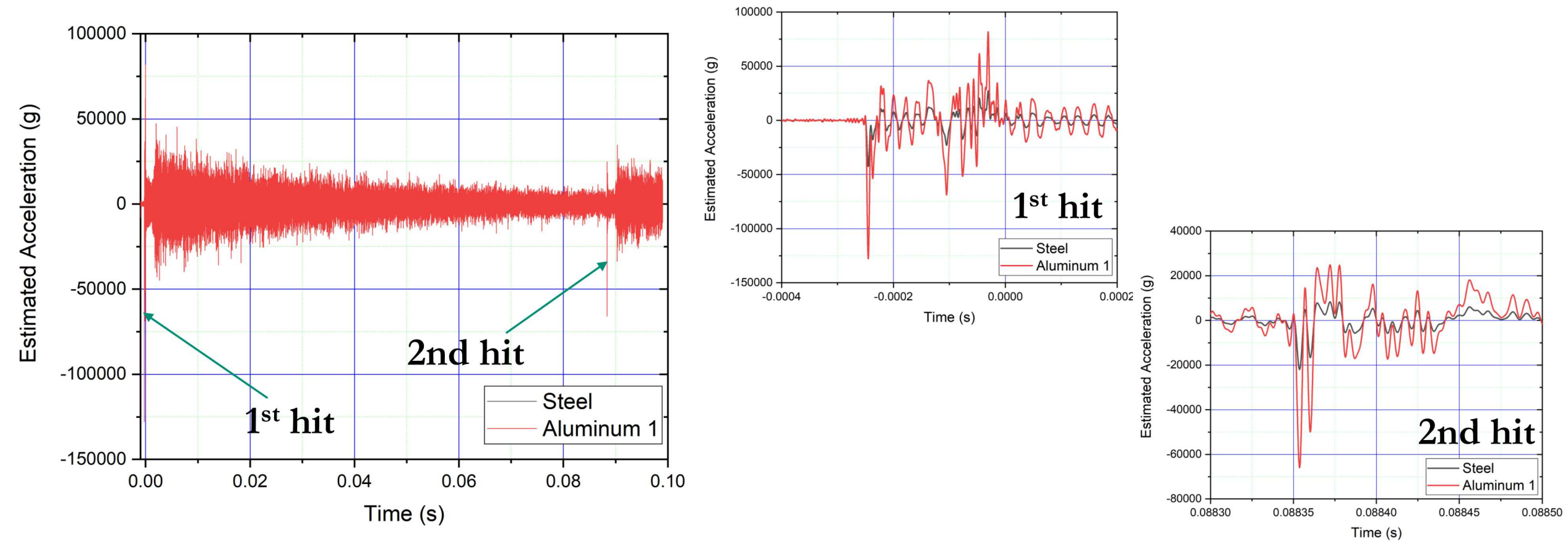
## Other Options - Reverse Impact



# Multiple Hits



The impedance of the test component is lower than that of the pressure bar.



- Hopkinson bar is demonstrated to be an effective and efficient tool for high-g, high-frequency mechanical shock tests
  - *Duration is the most challenge*
- Experimental design for high-g, high-frequency mechanical shock tests with Hopkinson bars is case by case, depending on the test unit and requirements
  - *Pulse shaping is the most challenge*
- Hopkinson bar can be extended for more specific tests
  - *Reverse impact*
  - *Multiple hits*
  - *Environmental temperatures*

**Bo Song**

(505) 844-4285

bsong@sandia.gov

**Brett Sanborn**

(505) 845-1087

bsanbor@sandia.gov

