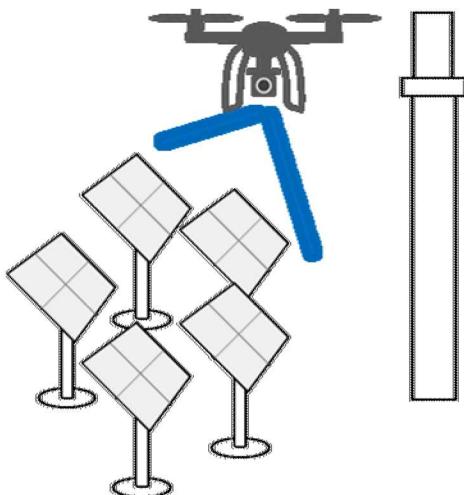


SETO CSP Program Summit 2019



Development of a UAS-Driven Universal Field Assessment, Correction, Enhancement Tool Adopting Non-Intrusive Optics

CPS # 34249, 34242

Partners: CU-Boulder, Tietronix, SolarReserve
March 19, 2019

PI: Julius Yellowhair, Sandia National Laboratories

Outline

- Introduction
- Purpose
- Technology Overview
- Optical Methods
 - Near-Field Target Imaging
 - Far-Field Target Image
- Conclusion

Introduction

- The project aims to develop a first-of-a-kind airborne, non-intrusive optical characterization tool for heliostat fields
 - Develop data collection and analysis methods to assess optical performance of heliostat collector fields: slope error, canting error, tracking error
 - Develop capability for airborne assessments using an unmanned aerial system (UAS)
 - Demonstrate at NSTTF and then at a commercial field
 - Advance the concept from TRL3 to TRL6



Purpose

- No tool currently exists that will assess multiple optical errors in a heliostat field efficiently and accurately
- Benefits:
 - Assess heliostat field for optical errors, identify low performing heliostats, and make corrections to those heliostats
 - Frequent monitoring of the heliostat field
 - Quickly identify issues
 - Quantify temporal effects on optical performance
 - Ensure high performance from the heliostat field
 - Consistently achieve needed high temperatures for Gen3 power towers
 - Reduce O&M costs
 - Efficiently and accurately assessing the heliostat field using UAS technology

Technology Overview

Develop flight paths for UAS

- Apply constraints to optimize flight paths



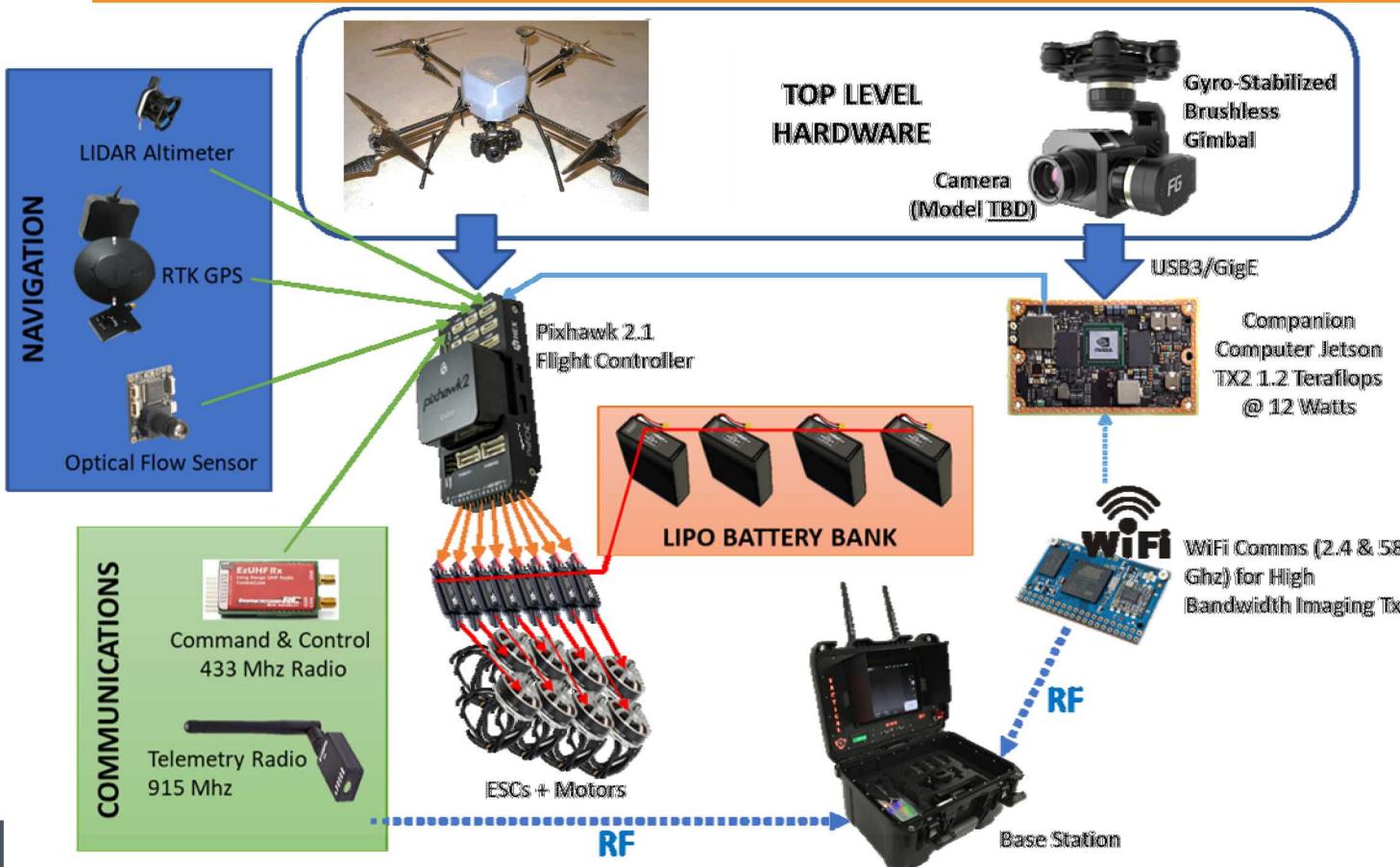
Assess field for optical errors using far-field targets

- Slope error
- Tracking error
- Canting error

Correct canting using near-field target imaging

- Use live video with theoretical target mapping as overlay to provide feedback
 - Stretch Goal – autonomously ID specific correction plan in real-time

UAS Imaging Platform



Criteria

- Positional accuracy
- Stability
- Flight time
- Payload

UAS

- Flybycopters (frame, motors, ESC, props, RTK GPS)

Camera

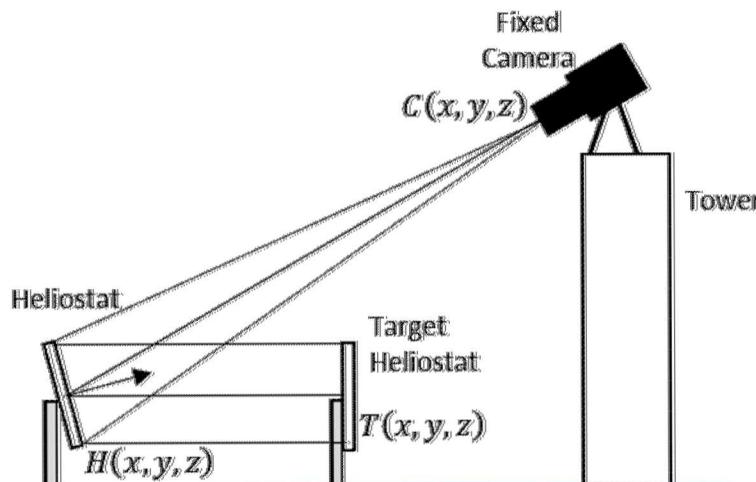
- 10-12 Mpix

Outline

- Introduction
- Purpose
- Technology Overview
- Optical Methods
 - Near-Field Target Imaging
 - Far-Field Target Image
- Conclusion

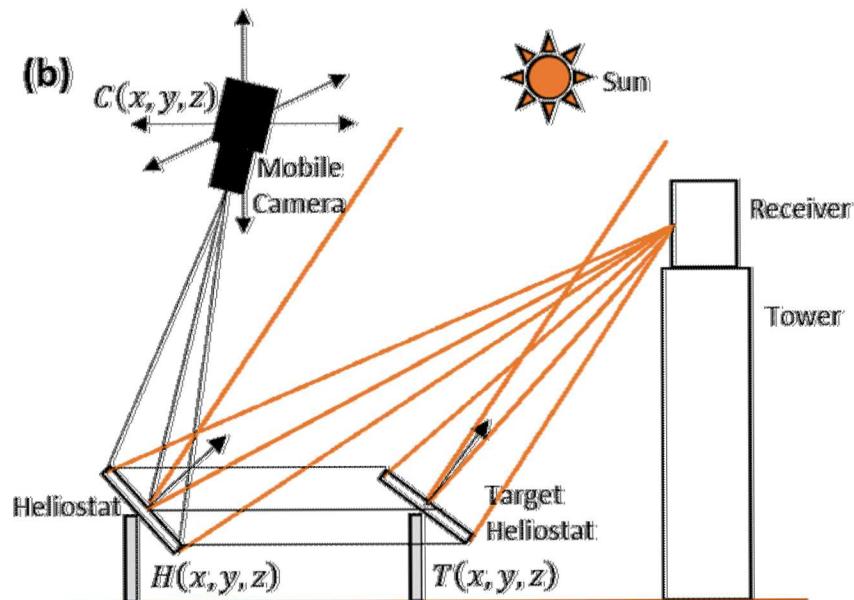
Near-Field Target Imaging (HFACET → UFACET)

(a)



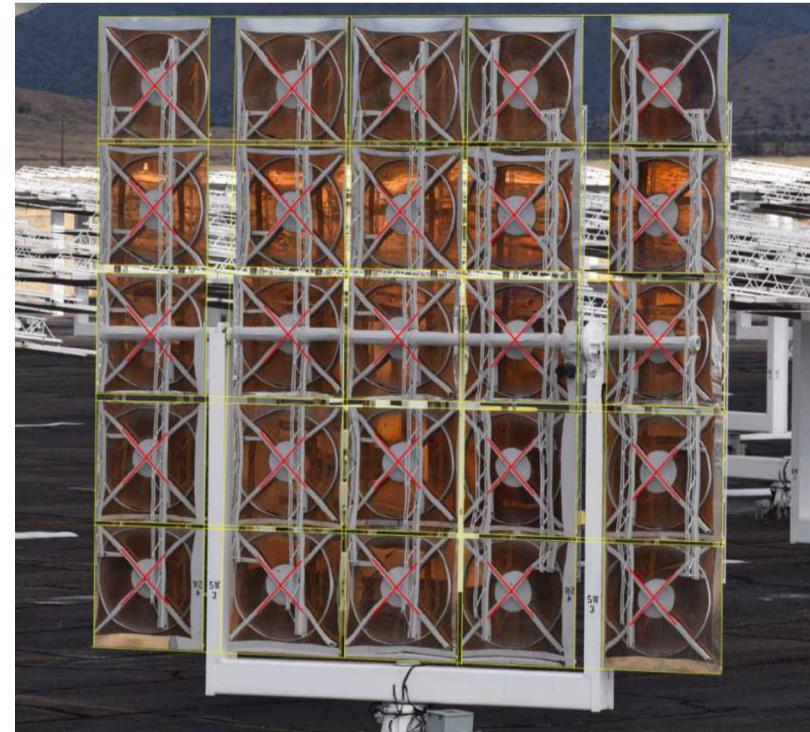
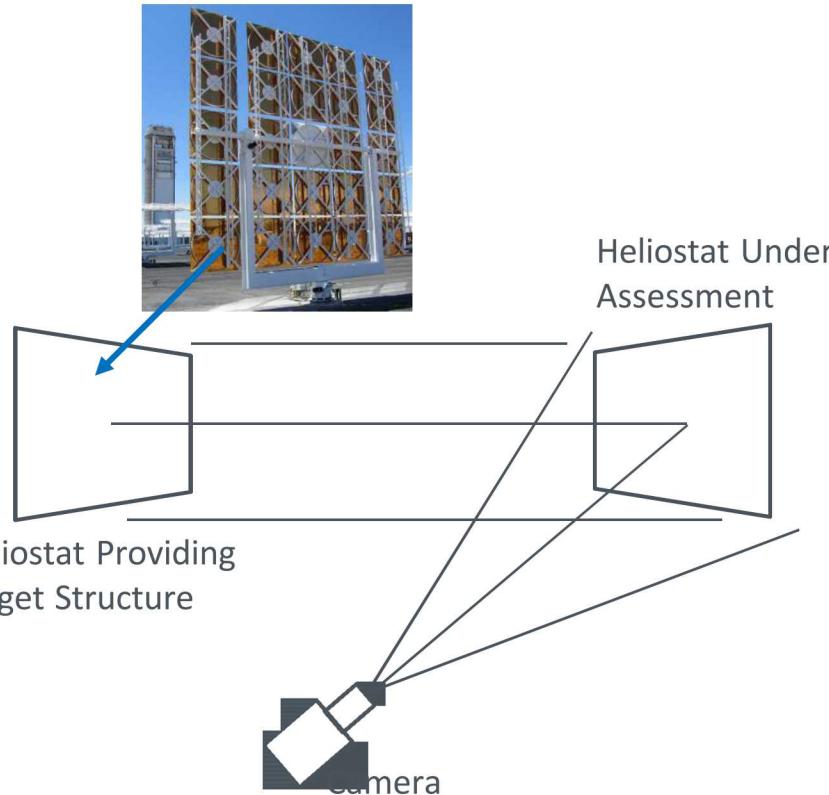
Camera on Fixed Platform – Heliostats Off-Line

(b)



Camera on Mobile Platform – Heliostats In-Situ

UFACET Analysis



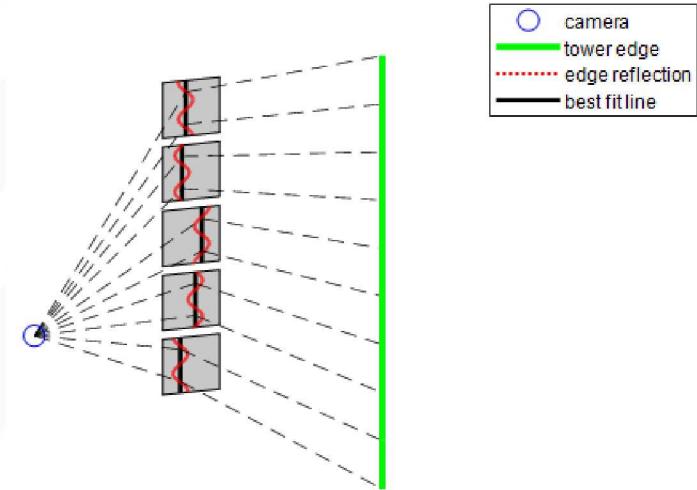
Non-Intrusive Optics Approach (1/2)

- Develop a flexible and non-intrusive optical (NIO) characterization methodology and tool to efficiently survey a utility-scale field without interrupting plant operation



Non-Intrusive Optics Approach (2/2)

- Given a series of images of a heliostat, compare the reflected tower edge in each facet with that of a reference facet with known canting
- Distortions and misalignments of the reflected edge can be measured to calculate optical errors



Conclusions

- Sandia and NREL are developing a UAS-based imaging system to assess heliostats for optical errors using far-field targets
 - Slope errors
 - Tracking errors
 - Canting errors
- Correct canting errors using near-field target imaging for feedback

Questions

Thank you!

Contacts:

Julius Yellowhair, Sandia, jeyello@sandia.gov

Guangdong Zhu, NREL, Guangdong.zhu@nrel.gov

Dan Small, Sandia, desmall@sandia.gov