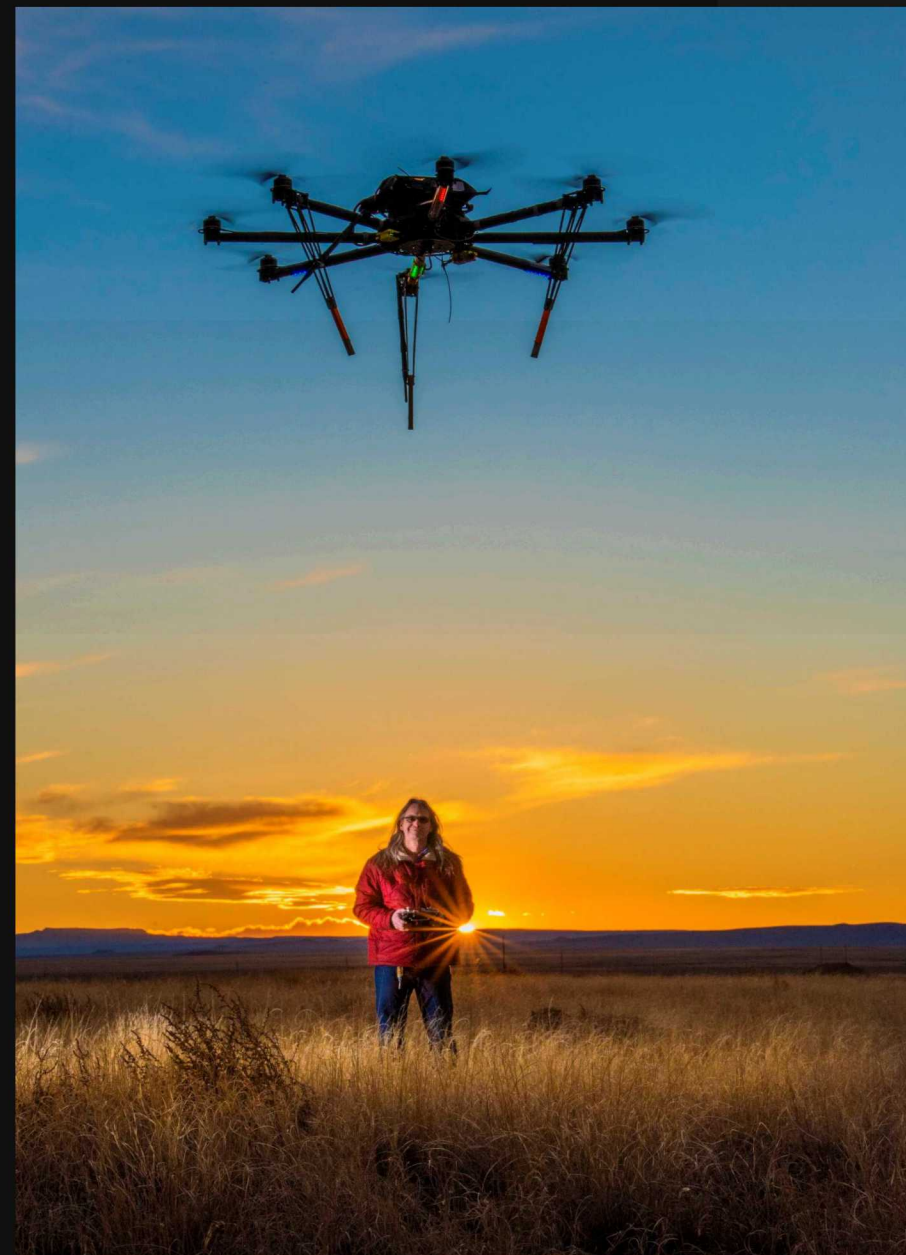


Introduction

Commercial CUAS solutions are agreeable due to their development level and availability. However, few systems possess a reliable method of UAS assessment. The challenges in imaging these small targets are many, which has resulted in a move away from them. However, this phenomenology can still be useful by combining the spatial and temporal information using frequencies. Valuable frequency content of an image can be obtained by monitoring the changing values of a pixel over time and the frequency content extracted and filtered. This approach allows us to view these small targets when we classically could not.

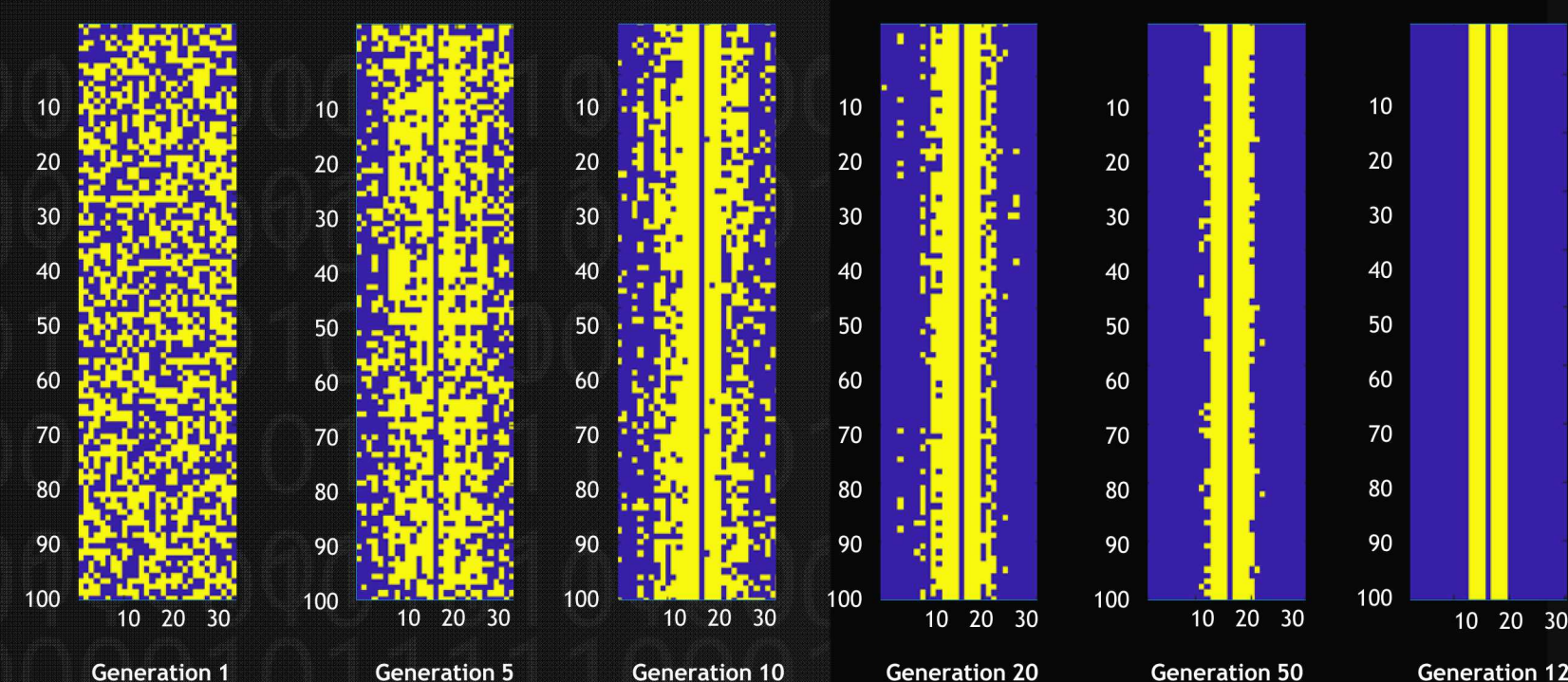


TFA Coefficient Optimization

SYNTHETIC DATA GENERATION OUTPUT SHOWS THE OUTPUT OF SYNTHETICALLY GENERATED DATA.



$$\varphi = 1 - C = 1 - \left(\frac{I_{max} - I_{min}}{I_{max} + I_{min}} \right)$$

This figure shows the progression for a binary genetic algorithm optimization with 100 individuals and 30 filter coefficients. Low to mid spatial frequencies provide the most information for TFA.



TFA Signal Optimization

TFA VS. STANDARD BACKGROUND IMAGE SUBTRACTION AND TFA BACKGROUND SUBTRACTION FOR FLAGS IN 15MPH WINDS

TFA Base Background Noise Norm = 2.484142	TFA Background Subtraction Background Noise Norm = 1.125943
	

A background TFA frame is slightly different than a standard background frame. A standard background frame contains constant items in the image, the background scene. However, a TFA background image shows the consistent background is already removed. By subtracting a TFA background from the scene, the waving flags caused by the wind can be nearly removed. While TFA limits this noise inherently, the TFA background subtraction reduces the noise.

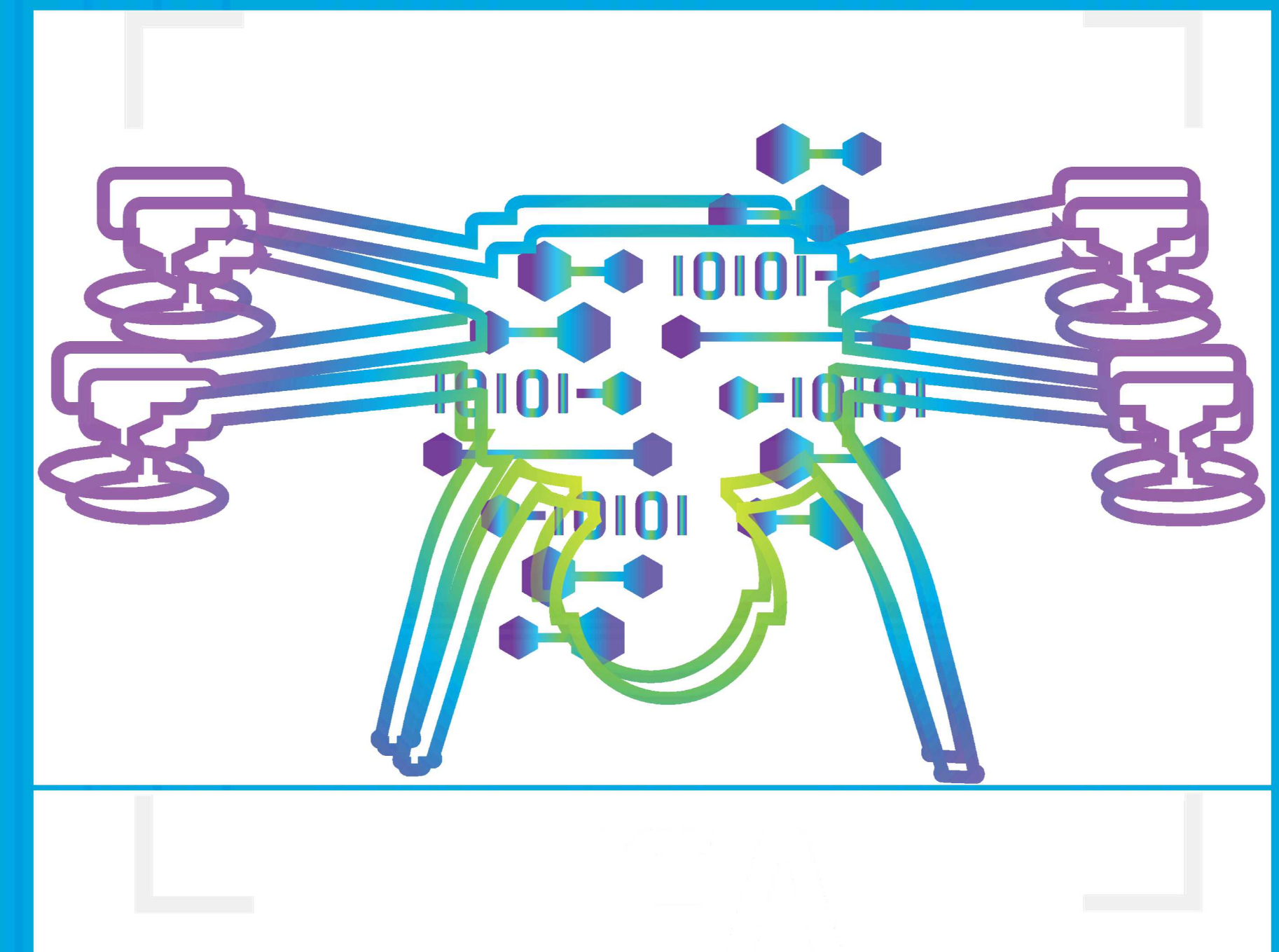
Machine Learning in the TFA Domain

c) Improved TFA

Previously, TFA machine learning consisted of a convolutional neural network (CNN) classifying an image to determine if an UAS was present. This had negative results when multiple targets were in the scene with this iteration, the team decided to pursue object detection using a regional CNN (R-CNN) due to its ability to draw boxes around the object of interest located within the image. With the large amount of data, computational time needed to train an R-CNN from scratch, an existing network was utilized which was then transfer learned to the domain. The network that was carried out goes by the name You Only Look Once (YOLO) due to the way it predicts the bounding boxes and probabilities.

Results

TFA is designed to monitor subtle changes in the positions of pixels in video-data and distinguish these frequencies from the frequencies of other biological entities. This advanced detection capability allows operators to clearly identify small targets in cluttered environments.



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