

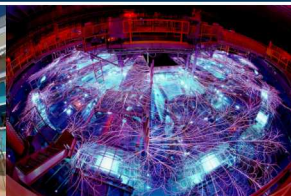
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SAND2019-12934C



Bulk-Interface-Flux-Recovery (Bulk-IFR) Method for Coupling the Atmosphere-Ocean Interface

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10/22/19



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- Does solving the monolithic problem give improvements over explicit treatment of a Robin condition?
 - Well informed coupling scheme: Utilize Schur Complement of monolithic problem to produce boundary conditions. Similar to variational flux recovery
- 1 Define interface-flux variable λ with its own DOF space (could be either model's or a 3rd set). No remapping necessary!
 - 2 At each time step, isolate interface DOF's using Schur complement
 - 3 Isolate and solve for λ with second Schur complement
 - 4 Back substitute λ into interface systems to find fluxes on the interface for each model (exact with respect to the data at the last time step).
 - 5 Fluxes act as boundary conditions for interior evolution
 - 6 Repeat

Atmosphere–Ocean Coupling

- Abstract formulation of coupled model (Lemarié, et al. 2015)
- Γ is Atmosphere–Ocean interface
- Linear operator $\mathcal{L}$, flux function $\mathcal{F}$, BC operator $\mathcal{B}$, flux coupling $\mathbf{F}_{ao}$

$$\frac{dU_a}{dt} + \mathcal{L}_a \mathcal{F}_a(U_a) = f_a \quad \text{in } \Omega_a \times [0, T]$$

$$\mathcal{B}_a U_a = b_a \quad \text{on } \partial\Omega_a \setminus \Gamma \times [0, T]$$

$$\mathcal{F}_a(U_a) = \alpha(U_a - U_o) \quad \text{on } \Gamma \times [0, T]$$

$$\frac{dU_o}{dt} + \mathcal{L}_o \mathcal{F}_o(U_o) = f_o \quad \text{in } \Omega_o \times [0, T]$$

$$\mathcal{B}_o U_o = b_o \quad \text{on } \partial\Omega_o \setminus \Gamma \times [0, T]$$

$$\mathcal{F}_o(U_o) = \alpha(U_o - U_a) \quad \text{on } \Gamma \times [0, T]$$

- Bulk condition on interface with constant α

$$\mathcal{F}_a(U_a) = \mathcal{F}_o(U_o) = \alpha(U_a - U_o) \leftrightarrow k_a \nabla U_a \cdot \mathbf{n} = -k_o \nabla U_o \cdot \mathbf{n} = \alpha(U_a - U_o)$$

- More Generally: Strategy for $\alpha(x, t)$ clear, $\alpha(U_a, U_o)$ not clear.

Weak Formulation

- Assume Dirichlet boundary conditions are satisfied on $\partial\Omega_a \setminus \Gamma$ and $\partial\Omega_o \setminus \Gamma$ (i.e non Γ boundaries)
- Introduce boundary flux variable $\lambda = \mathcal{F}_a(U_a) = \mathcal{F}_o(U_o) = \alpha(U_a - U_o)$
- Test functions $\psi_a \in V_a$, $\psi_o \in V_o$, $\mu \in V_\Gamma$,

$$\begin{aligned} \left(\psi_a, \frac{dU_a}{dt} \right)_{\Omega_a} + (\psi_a, \mathcal{L}_a \mathcal{F}_a(U_a))_{\Omega_a} &= (\psi_a, f_a)_{\Omega_a} && \text{in } \Omega_a \times [0, T] \\ \left(\psi_o, \frac{dU_o}{dt} \right)_{\Omega_o} + (\psi_o, \mathcal{L}_o \mathcal{F}_o(U_o))_{\Omega_o} &= (\psi_o, f_o)_{\Omega_o} && \text{in } \Omega_o \times [0, T] \\ (\mu, \alpha(U_a - U_o) - \lambda)_\Gamma &= 0 && \text{on } \Gamma \times [0, T] \end{aligned}$$

- Integration-by-parts

$$\begin{aligned} \left(\psi_a, \frac{dU_a}{dt} \right)_{\Omega_a} - (\widetilde{\mathcal{L}}_a \psi_a, \widetilde{\mathcal{F}}_a(U_a))_{\Omega_a} + (\psi_a, \lambda)_\Gamma &= (\psi_a, f_a)_{\Omega_a} && \text{in } \Omega_a \times [0, T] \\ \left(\psi_o, \frac{dU_o}{dt} \right)_{\Omega_o} - (\widetilde{\mathcal{L}}_o \psi_o, \widetilde{\mathcal{F}}_o(U_o))_{\Omega_o} - (\psi_o, \lambda)_\Gamma &= (\psi_o, f_o)_{\Omega_o} && \text{in } \Omega_o \times [0, T] \\ (\mu, \alpha(U_a - U_o) - \lambda)_\Gamma &= 0 && \text{on } \Gamma \times [0, T] \end{aligned}$$

- Expand U_a , U_o , and λ with trial functions

$$\mathbf{M}_a \frac{d\mathbf{U}_a}{dt} - \mathbf{K}_a \mathbf{U}_a + \mathbf{G}_a^\top \lambda = \mathbf{f}_a$$

$$\mathbf{M}_o \frac{d\mathbf{U}_o}{dt} - \mathbf{K}_o \mathbf{U}_o - \mathbf{G}_o^\top \lambda = \mathbf{f}_o$$

$$\alpha \mathbf{G}_a \mathbf{U}_a - \alpha \mathbf{G}_o \mathbf{U}_o - \tilde{\mathbf{M}} \lambda = 0$$

- Explicit-Explicit time-stepping

$$\mathbf{M}_a \mathbf{U}_a^n + \Delta t \mathbf{G}_a^\top \lambda = \mathbf{g}_a(\mathbf{U}_a^{n-1})$$

$$\mathbf{M}_o \mathbf{U}_o^n - \Delta t \mathbf{G}_o^\top \lambda = \mathbf{g}_o(\mathbf{U}_o^{n-1})$$

$$\alpha \mathbf{G}_a \mathbf{U}_a^n - \alpha \mathbf{G}_o \mathbf{U}_o^n - \tilde{\mathbf{M}} \lambda = 0$$

$$\begin{pmatrix} \mathbf{M}_a & 0 & \Delta t \mathbf{G}_a^\top \\ 0 & \mathbf{M}_o & \Delta t \mathbf{G}_o^\top \\ \alpha \mathbf{G}_a & \alpha \mathbf{G}_o & \tilde{\mathbf{M}} \end{pmatrix} \begin{pmatrix} \mathbf{U}_a^n \\ \mathbf{U}_o^n \\ \lambda \end{pmatrix} = \begin{pmatrix} \mathbf{g}_a^{n-1} \\ \mathbf{g}_o^{n-1} \\ 0 \end{pmatrix}$$

- RHS is

$$\mathbf{g}_i^{n-1} = \Delta t \mathbf{f}_i + \Delta t \mathbf{K}_i \mathbf{U}_i^{n-1} + \mathbf{M} \mathbf{U}_i^{n-1} \quad i = a, o$$

Interface Problem: Explicit-Explicit Coupling

- Separate DOFs on interior and interface

$$\begin{pmatrix} \mathbf{M}_{a,\Gamma} & 0 & \Delta t \mathbf{G}_a^T & \mathbf{M}_{a,\Gamma\Omega} & 0 \\ 0 & \mathbf{M}_{o,\Gamma} & -\Delta t \mathbf{G}_o^T & 0 & \mathbf{M}_{o,\Gamma\Omega} \\ \alpha \mathbf{G}_a & -\alpha \mathbf{G}_o & \tilde{\mathbf{M}}_\Gamma & 0 & 0 \\ \mathbf{M}_{a,\Omega\Gamma} & 0 & 0 & \mathbf{M}_{a,\Omega} & 0 \\ 0 & \mathbf{M}_{o,\Omega\Gamma} & 0 & 0 & \mathbf{M}_{o,\Omega} \end{pmatrix} \begin{pmatrix} \mathbf{U}_{a,\Gamma}^n \\ \mathbf{U}_{o,\Gamma}^n \\ \lambda \\ \mathbf{U}_{a,\Omega}^n \\ \mathbf{U}_{o,\Omega}^n \end{pmatrix} = \begin{pmatrix} \mathbf{g}_{a,\Gamma}^{n-1} \\ \mathbf{g}_{o,\Gamma}^{n-1} \\ 0 \\ \mathbf{g}_{a,\Omega}^{n-1} \\ \mathbf{g}_{o,\Omega}^{n-1} \end{pmatrix}$$

- Interface System

$$\begin{pmatrix} \mathbf{A}_{a,\Gamma} & 0 & \Delta t \mathbf{G}_a^T \\ 0 & \mathbf{A}_{o,\Gamma} & -\Delta t \mathbf{G}_o^T \\ \alpha \mathbf{G}_a & -\alpha \mathbf{G}_o & \tilde{\mathbf{M}}_\Gamma \end{pmatrix} \begin{pmatrix} \mathbf{U}_{a,\Gamma}^n \\ \mathbf{U}_{o,\Gamma}^n \\ \lambda \end{pmatrix} = \begin{pmatrix} \hat{\mathbf{g}}_{a,\Gamma}^{n-1} \\ \hat{\mathbf{g}}_{o,\Gamma}^{n-1} \\ 0 \end{pmatrix}$$

$$\mathbf{A}_{i,\Gamma} = \mathbf{M}_{i,\Gamma} - \mathbf{M}_{i,\Gamma\Omega} \mathbf{M}_{i,\Omega}^{-1} \mathbf{M}_{i,\Omega\Gamma} \quad \hat{\mathbf{g}}_{i,\Gamma}^{n-1} = \mathbf{g}_{i,\Gamma}^{n-1} - \mathbf{M}_{i,\Gamma\Omega} \mathbf{M}_{i,\Omega}^{-1} \mathbf{g}_{i,\Omega}^{n-1} \quad i = a, o$$

- Schur Complement: solve for interface flux

$$\lambda = \mathbf{S}^{-1} \left(\alpha \Delta t \mathbf{G}_a^T \mathbf{A}_{a,\Gamma}^{-1} \mathbf{g}_{a,\Gamma}^{n-1} - \alpha \Delta t \mathbf{G}_o^T \mathbf{A}_{o,\Gamma}^{-1} \mathbf{g}_{o,\Gamma}^{n-1} \right)$$

$$\mathbf{S} = \left(\alpha \Delta t \mathbf{G}_a^T \mathbf{A}_{a,\Gamma}^{-1} \mathbf{G}_a + \alpha \Delta t \mathbf{G}_o^T \mathbf{A}_{o,\Gamma}^{-1} \mathbf{G}_o - \tilde{\mathbf{M}}_\Gamma \right)$$

Explicit-Implicit Coupling

- Explicit-Implicit time-stepping

$$\begin{aligned} \mathbf{M}_a \mathbf{U}_a^n + \Delta t \mathbf{G}_a^\top \lambda &= \mathbf{g}_a(\mathbf{U}_a^{n-1}) \\ \mathbf{M}_o \mathbf{U}_o^n - \Delta t \mathbf{K}_o \mathbf{U}_o^n - \Delta t \mathbf{G}_o^\top \lambda &= \widetilde{\mathbf{g}}_o(\mathbf{U}_o^{n-1}) \\ \alpha \mathbf{G}_a \mathbf{U}_a^n - \alpha \mathbf{G}_o \mathbf{U}_o^n - \widetilde{\mathbf{M}} \lambda &= 0 \end{aligned} \quad \begin{pmatrix} \mathbf{M}_a & 0 & \Delta t \mathbf{G}_a^\top \\ 0 & \mathbf{W}_o & \Delta t \mathbf{G}_o^\top \\ \alpha \mathbf{G}_a & \alpha \mathbf{G}_o & \widetilde{\mathbf{M}} \end{pmatrix} \begin{pmatrix} \mathbf{U}_a^n \\ \mathbf{U}_o^n \\ \lambda \end{pmatrix} = \begin{pmatrix} \mathbf{g}_a^{n-1} \\ \widetilde{\mathbf{g}}_o^{n-1} \\ 0 \end{pmatrix}$$

- RHS is

$$\widetilde{\mathbf{g}}(\mathbf{U}^{n-1}) = \Delta t \mathbf{f} + \mathbf{M} \mathbf{U}^{n-1}, \quad \mathbf{W}_o = \mathbf{M}_o - \Delta t \mathbf{K}_o$$

- Separate DOFs $\rightarrow$ Schur Complement $\rightarrow$ Interface System

$$\begin{pmatrix} \mathbf{A}_{a,\Gamma} & 0 & \Delta t \mathbf{G}_a^\top \\ 0 & \widetilde{\mathbf{A}}_{o,\Gamma} & -\Delta t \mathbf{G}_o^\top \\ \alpha \mathbf{G}_a & -\alpha \mathbf{G}_o & \widetilde{\mathbf{M}}_\Gamma \end{pmatrix} \begin{pmatrix} \mathbf{U}_a^{n-1}|_\Gamma \\ \mathbf{U}_o^{n-1}|_\Gamma \\ \lambda \end{pmatrix} = \begin{pmatrix} \widehat{\mathbf{g}}_{a,\Gamma}^{n-1} \\ \widehat{\mathbf{g}}_{o,\Gamma}^{n-1} \\ 0 \end{pmatrix}$$

$$\mathbf{A}_{a,\Gamma} = \mathbf{M}_{a,\Gamma} - \mathbf{M}_{a,\Gamma\Omega} \mathbf{M}_{a,\Omega}^{-1} \mathbf{M}_{a,\Omega\Gamma}, \quad \widetilde{\mathbf{A}}_{o,\Gamma} = \mathbf{W}_{o,\Gamma} - \mathbf{W}_{o,\Gamma\Omega} \mathbf{W}_{o,\Omega}^{-1} \mathbf{W}_{o,\Omega\Gamma}$$

$$\widehat{\mathbf{g}}_{a,\Gamma}^{n-1} = \mathbf{g}_{a,\Gamma}^{n-1} - \mathbf{M}_{a,\Gamma\Omega} \mathbf{M}_{a,\Omega}^{-1} \mathbf{g}_{a,\Omega}^{n-1}$$

$$\widehat{\mathbf{g}}_{o,\Gamma}^{n-1} = \widetilde{\mathbf{g}}_{o,\Gamma}^{n-1} - \mathbf{W}_{o,\Gamma\Omega} \mathbf{W}_{o,\Omega}^{-1} \widetilde{\mathbf{g}}_{o,\Omega}^{n-1}$$

- Advection in x direction, diffusion in y direction

- Denote a by 1 and o by 2

$$\frac{\partial \varphi_i}{\partial t} - \frac{\partial}{\partial y} k_i \frac{\partial \varphi_i}{\partial y} + u_i \frac{\partial \varphi_i}{\partial x} = f_i \quad \text{in } \Omega_i \times [0, T] \quad i = 1, 2$$

- Initial condition

$$\varphi_i(x, y, 0) = \varphi_{i,0}(x, y) \quad \text{in } \Omega_i \quad i = 1, 2$$

- Non-interface boundary conditions

$$\varphi_i = g_i \quad \text{on } \partial\Omega_i \quad i = 1, 2.$$

- Bulk condition

$$k_1 \frac{\partial \varphi_1}{\partial y} = k_2 \frac{\partial \varphi_2}{\partial y} = \alpha(\varphi_1 - \varphi_2) \quad \text{on } \Gamma.$$

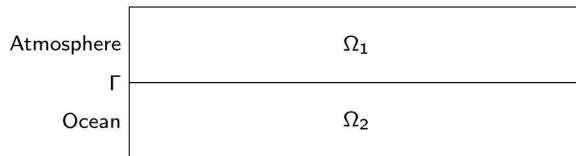


Figure: Atmosphere-Ocean domain with interface Γ .

- Domain size $(x, y) \in [0, x_{\max}] \times [-y_{\max}, y_{\max}]$, with $x_{\max} = 10$ km and $y_{\max} = 500$ m. Γ is line $y(x) = 0$.
- Method of manufactured solutions to give realistic test case
- Explicit – Explicit coupling

- Manufactured solution: Oscillation about some reference temperature

$$\varphi_1 = -\frac{A}{2N\pi k_1} \cos(N\pi(x - ut))(y-a)^2 + T$$

$$\varphi_2 = \frac{B}{N\pi k_2} \cos(N\pi(x - ut))(y + y_{\max}) + T,$$

- Forcing: $f_1 = \frac{A}{N\pi} \cos(N\pi(x - u_1 t))$
and $f_2 = 0$

- Bulk conditions on $y(x) = 0$ demands

$$\frac{aA}{N\pi} = \frac{B}{N\pi} = \alpha \left(-a^2 \frac{A}{2N\pi k_1} - \frac{B}{N\pi k_2} b \right).$$

- Implies that

$$aA = B, \quad \alpha = -\frac{Aa}{\left(\frac{a^2 A}{2k_1} + \frac{B}{k_2} b\right)}$$

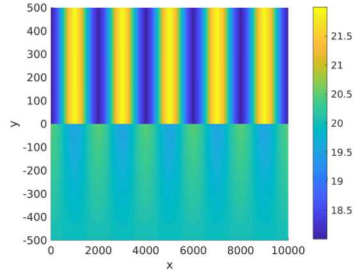
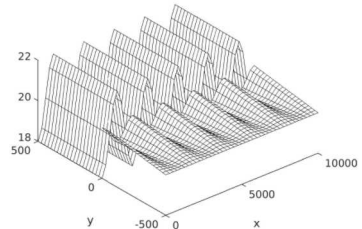


Figure: Initial Condition

- Maximum amplitude around T must be bounded.

$$\max |\varphi_2 - T| = \left(\frac{By_{\max}}{N\pi k_2} \right) = M_2 \Leftrightarrow B = \frac{M_2 N \pi k_2}{y_{\max}}$$

$$\max |\varphi_1 - T| = \frac{Aa^2}{2N\pi k_1} = M_1 \Leftrightarrow a = \frac{2M_1 N \pi k_1}{B}$$

Parameter	Value
T	293.15 K = 20 °C
N	$\frac{1}{1000}$
u	2 m s ⁻¹
M_1	2.0 °C
M_2	0.5 °C

Table: Model parameters for the simplified atmosphere-ocean test case

- k_1 and k_2 have yet to be specified.

- Time Horizon: 2 minutes, time step: 0.05 sec, SUPG stabilization, consistent mass matrices, linear Lagrange elements, forward Euler.
- Advection Dominated: $k_1 = 2 \times 10^{-3}$ and $k_1 = 1 \times 10^{-5}$

h_x	h_y	Rel. $\ err\ _{L_2}$	Rel. $ err _{H_1}$
333	33.3	1.661e-01	4.101e-01
166	16.6	3.670e-02	2.019e-01
83.3	8.33	8.349e-03	1.011e-01
Rate	-	2.136	0.997

- Medium Diffusion: $k_1 = 2$ and $k_1 = 1 \times 10^{-1}$

h_x	h_y	Rel. $\ err\ _{L_2}$	Rel. $ err _{H_1}$
333	33.3	1.627e-01	3.937e-01
166	16.6	3.581e-02	2.005e-01
83.3	8.33	8.152e-03	1.011e-01
Rate	-	2.135	0.987

- Large Diffusion: $k_1 = 200$ and $k_2 = 1$

h_x	h_y	Rel. $\ err\ _{L_2}$	Rel. $ err _{H_1}$
333	33.3	1.441e-01	3.876e-01
166	16.6	3.240e-02	2.003e-01
83.3	8.33	7.740e-03	1.011e-01
Rate	-	2.065	0.986

- Convergence rates are reasonable

- Ocean grid is approximately 1.5 times finer
- Advection Dominated: $k_1 = 2 \times 10^{-3}$ and $k_1 = 1 \times 10^{-5}$
- Atmosphere is mortar side

$h_{1,x}$	$h_{1,y}$	$h_{2,x}$	$h_{2,y}$	Rel. $\ err\ _{L_2}$	Rel. $\ err\ _{H_1}$
333	33.3	222	22.2	7.169e-02	2.737e-01
166	16.6	111	11.1	1.611e-02	1.365e-01
83.3	8.33	55.5	5.55	3.676e-03	6.837e-02
Rate	—	—	—	2.131	0.997

- Similar errors when ocean is mortar side

- Direct Method: Let $\lambda = \alpha(\varphi_1^{n-1} - \varphi_2^{n-1})$
- Large Diffusion: $k_1 = 200$ and $k_2 = 1$
- Time Horizon: 1 hour, Time-step: 0.05

Method	$h_{1,x}$	$h_{1,y}$	Rel. $\ err\ _{L_2}$	Rel. $ err _{H_1}$
Direct	166	16.6	1.673e-02	8.192e-02
IFR	166	16.6	1.525e-02	7.962e-02

- Interface flux can be implicit solved for any combination of explicit or implicit time integration. Heterogeneous time-integration
- Rigorous stability analysis required
- Extend to Primitive equations and FD-FV models.
- Extend to IMEX methods, multi-rate methods, and exploit horizontally-explicit vertically-implicit type methods.
- Heterogeneous Asynchronous Time Integration methods (HATI)
- Typically, one must compromise between conservation or unconditional stability
- We want Conservative Heterogeneous Asynchronous Time Integration that is Unconditionally Stable

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