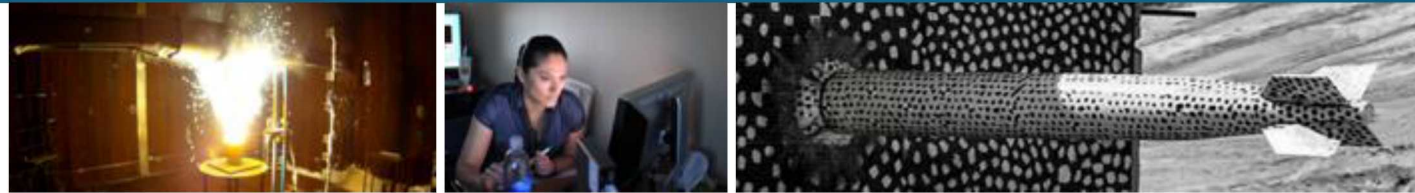




Sandia
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SAND2019-12762C

Uncertainty Quantification in Cyber Emulation



PRESENTED BY

Laura Swiler

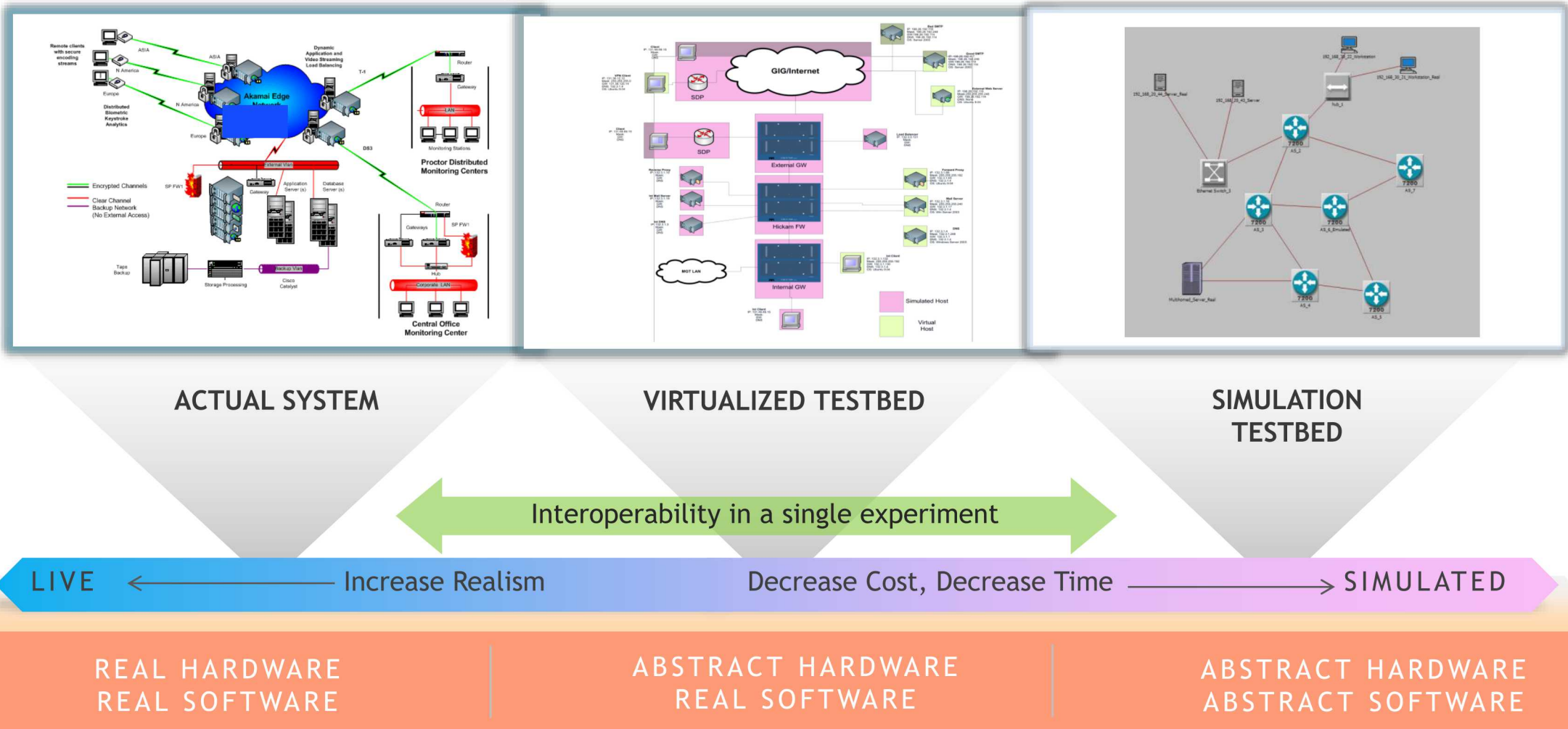
Gianluca Geraci, Bert Debusschere, Jonathan Crussell

INFORMS Annual Meeting, Oct. 22, 2019



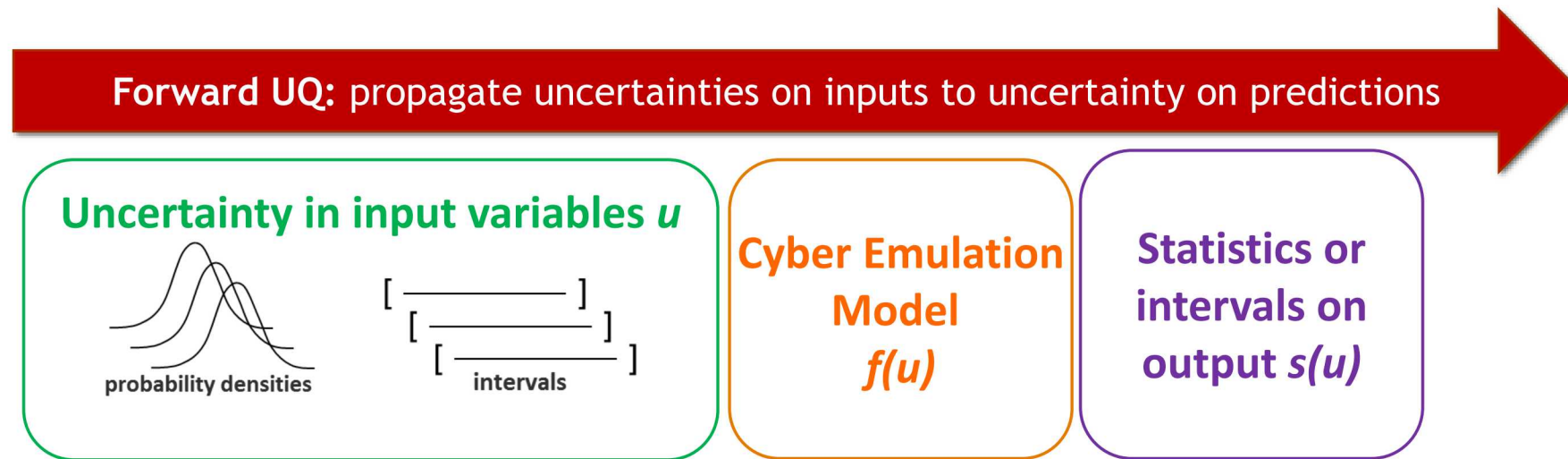
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2 ■ Emulation + Analytics = Emulytics



SECURE is integrating the mathematics of uncertainty quantification with emulytics to improve cyber experimentation.

- **Uncertainty Quantification (UQ)** is the process of characterizing all uncertainties that could affect the results of the cyber experimental runs.
- Once the uncertainties are identified and characterized as “input uncertainties”, they are propagated (e.g. mapped) through the experiment to obtain uncertainties on the results (“output uncertainties”).



4 What is Experimental Design?

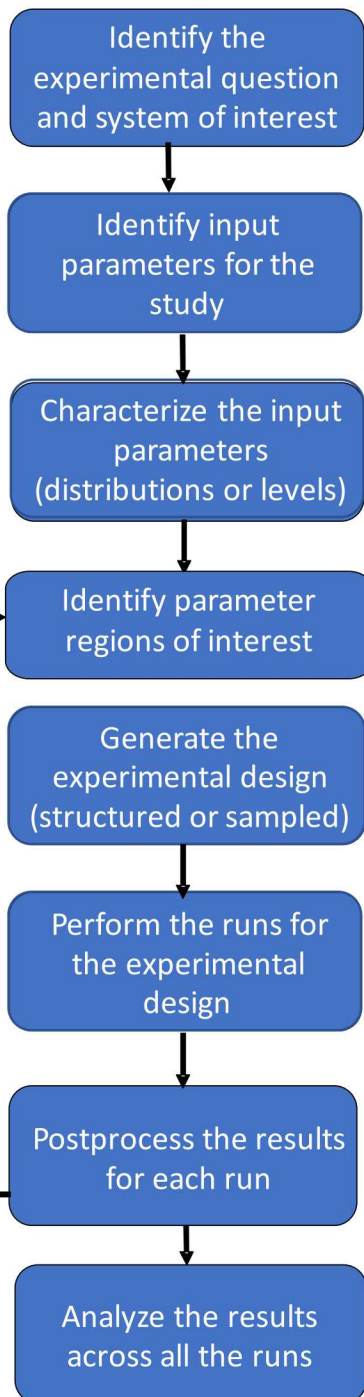


- **Experiment design** involves the **selection of a set of experimental parameter settings** at which one will run the cyber experimental model (e.g. various choices of number of cores per machine, protocols and environment settings, packet size of traffic, bandwidth of links, etc.)
- The goal of experimental design is to generate an “ensemble” of runs, where each run itself may involve replicate runs or not.
- Experiments are often tailored to address a specific question, such as: does the packet size matter when looking at packet response time on a network with sufficient bandwidth?
- There are a variety of design criteria.
 - Some experiments are space-filling (Monte-Carlo sampling and variations)
 - Some designs optimize some property of the run matrix, X .
 - A D-optimal design minimizes the determinant of the information matrix $[X^T X]^{-1}$ which results in maximizing the information content of the parameter values. A G-optimal design minimizes the maximum variance of the predicted values from a regression fit built on the dataset X .

There is significant overlap between UQ and experimental design. Both involve exploring the parameter space. UQ is more focused on distributional mapping.

- Think about the advantages of a structured vs. random sample design
- Think about the question you want to address
- Computational cost is a big factor

Additional
designs
needed?



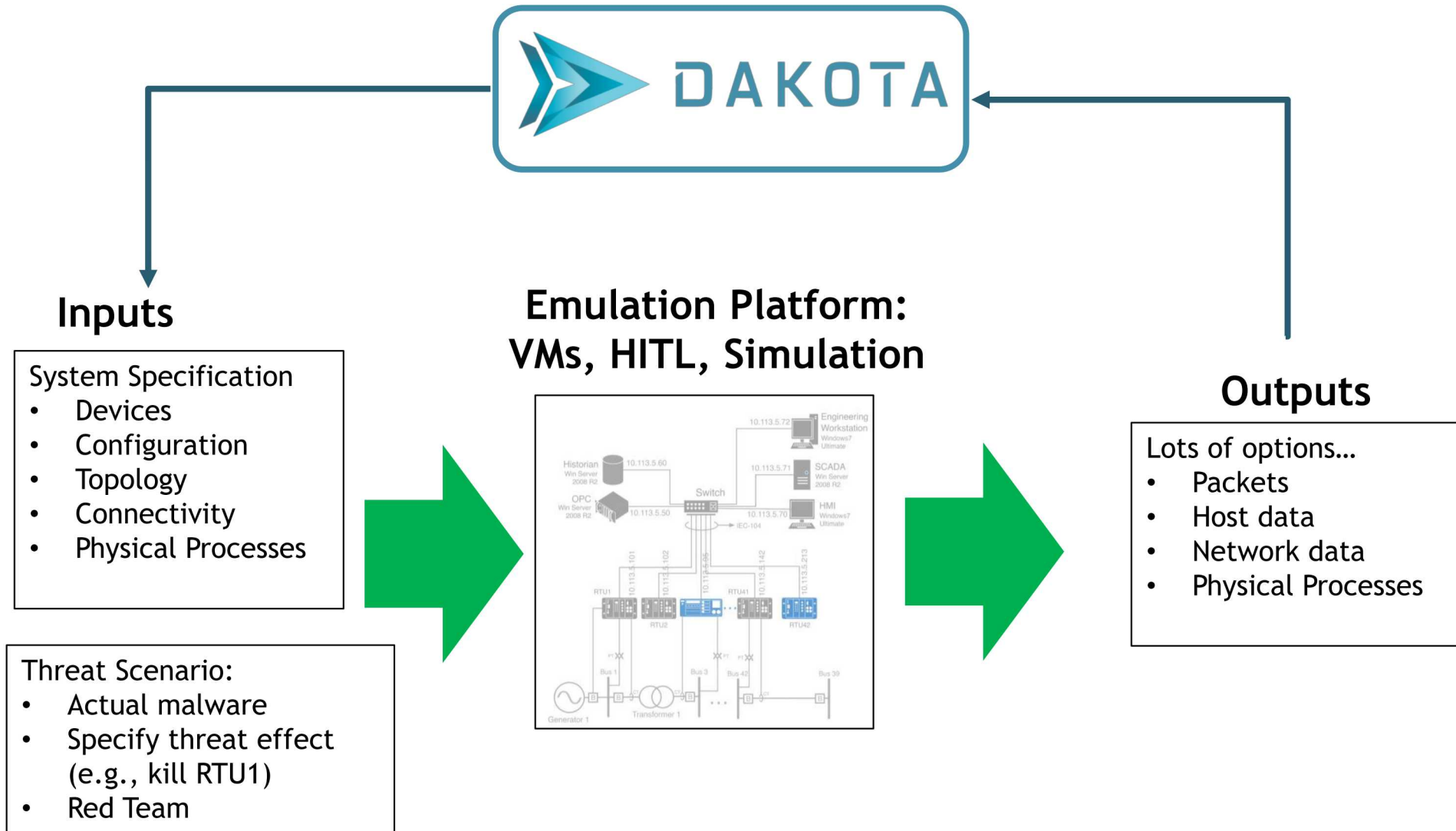
- **Sensitivity analysis (SA)** is the process of identifying the most significant factors or variables affecting the uncertainty of the cyber model predictions
- Over the past few decades, the computational simulation community has developed a strong emphasis on **Verification and Validation** activities to build credibility in scientific computing. A study by the National Research Council at the National Academies issued a report outlining the mathematical and statistical foundations of V&V and UQ as primary activities supporting the reliability of computational models [1]. We take as definitions those outlined in [2]:
 - *Verification* is the process of assessing software correctness and numerical accuracy of the solution to a given mathematical model.
 - *Validation* is the process of assessing the physical accuracy of a mathematical model based on comparisons between computational results and experimental data.

1. National Research Council. Assessing the Reliability of Complex Models: Mathematical and Statistical Foundations of Verification, Validation, and Uncertainty Quantification. Washington, DC: The National Academies Press, 2012. <https://doi.org/10.17226/13395>.
2. Oberkampf, W.L. and C.J. Roy. Verification and Validation in Scientific Computing. Cambridge University Press, 2010.

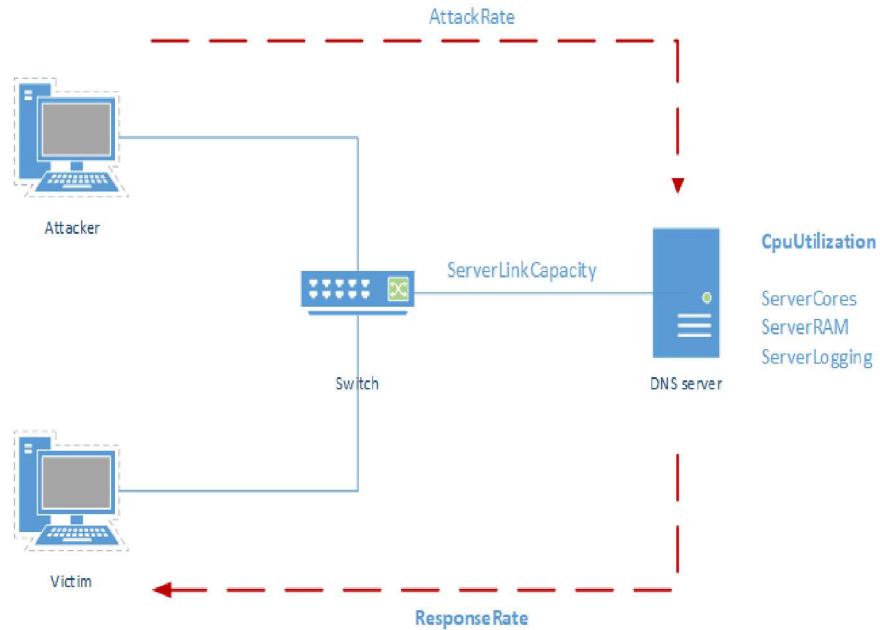


- **Factorial design:** A factorial design is an experimental design that samples the full combination of all parameters.
 - Thus, if there were 3 parameters and each had 5 allowable values or levels, a full factorial design would involve $5 \times 5 \times 5 = 125$ runs.
 - A fractional factorial design only involves a subset of the full factorial.
 - A full factorial design is an orthogonal array and can be used for main effects analysis
- **Replicates.** A replicate refers to running the same set of experimental settings multiple times to see how the response varies with-in that setting. A replicate can also be called an iterate.

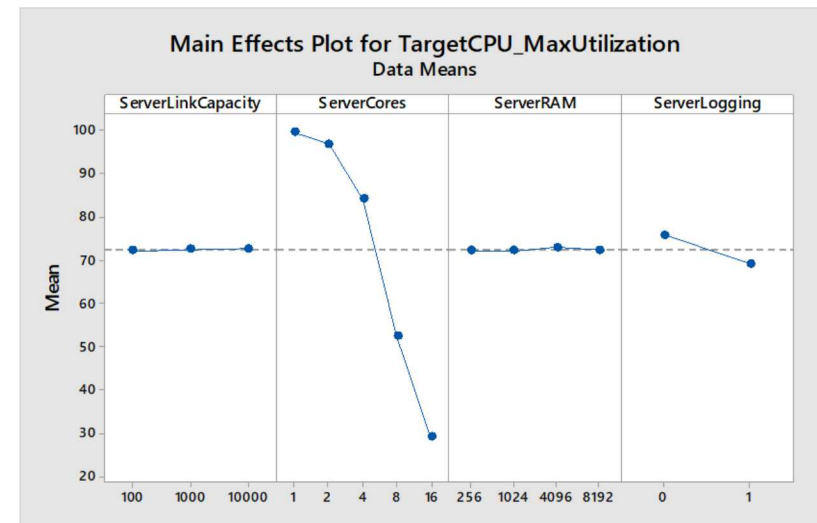
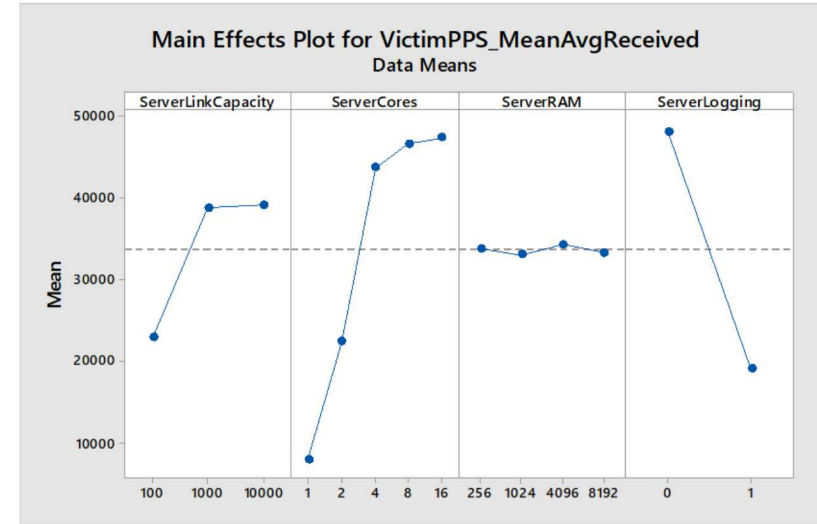
Dakota: Toolkit of Sensitivity analysis, UQ, and experimental design methods to drive external codes



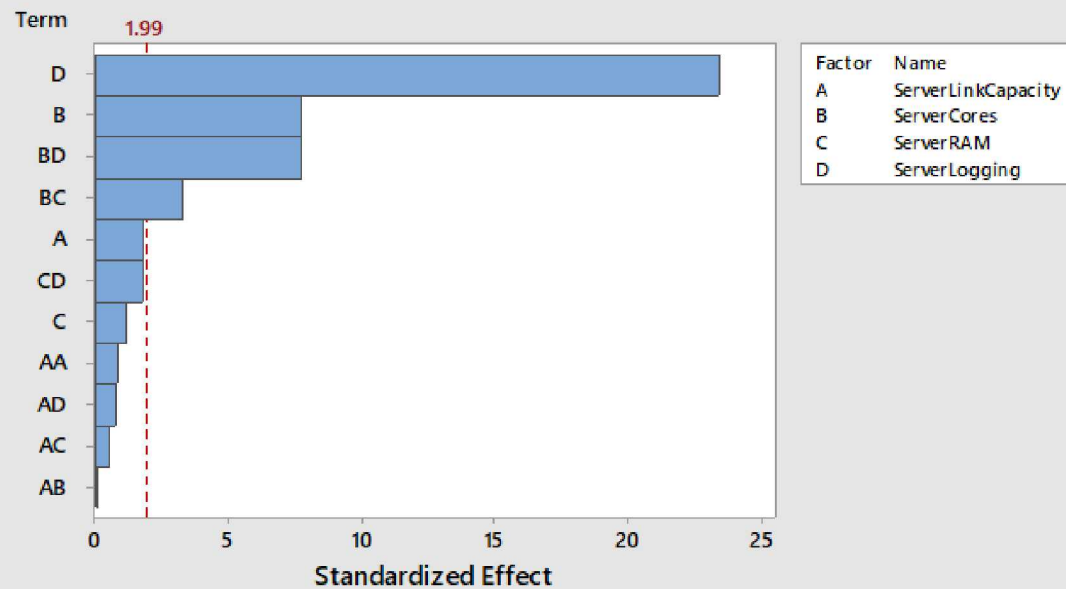
Example: Denial of Service Amplification Attack with Full Factorial Parameter Study



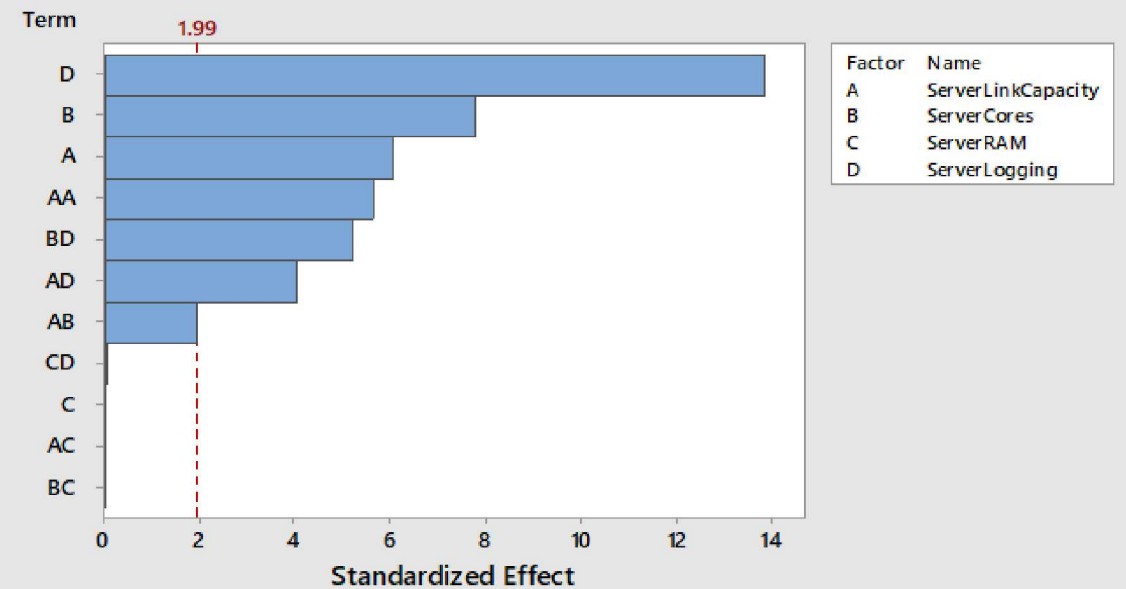
Input parameter	Levels
ServerLinkCapacity	100, 1000, 10000 Mbps
ServerCores	1,2,4,8,16
ServerRAM	256, 1024, 4096, 8192 MB
ServerLogging	True, False



Pareto Chart of the Standardized Effects
(response is TargetCPU_MaxUtilization, $\alpha = 0.05$)



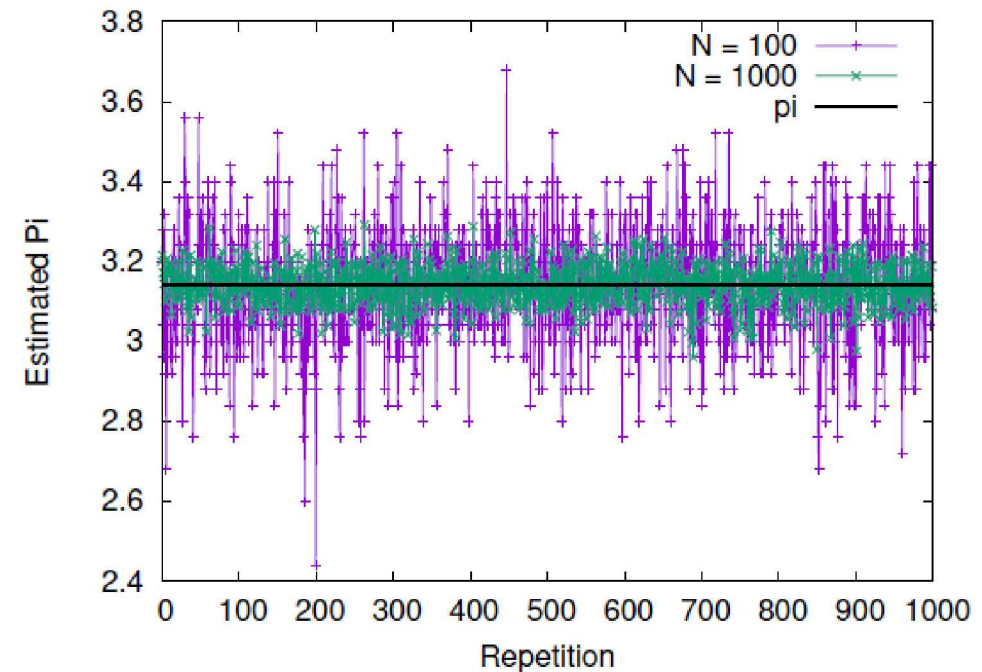
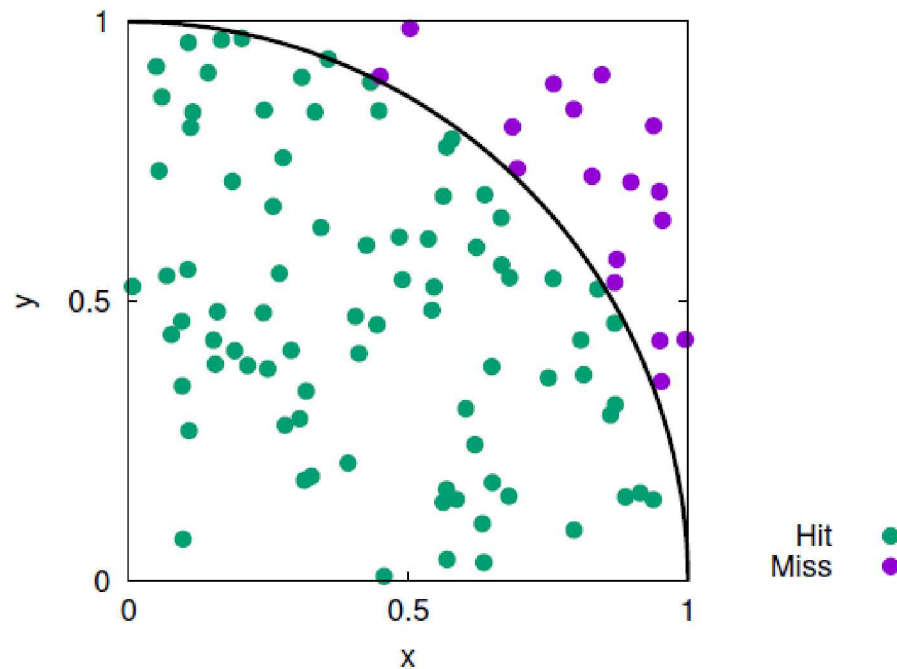
Pareto Chart of the Standardized Effects
(response is VictimPPS_MeanAvgReceived, $\alpha = 0.05$)



- Emulations may be difficult and time-consuming to set up. For every sample, a number of virtual machines has to be instantiated, initialized, and start communicating with each other.
- Running emulations may also be expensive. If one is emulating a large cyber network with hundreds or thousands of nodes, this will require significant time.
- The UQ community has recently been investigating “multi-fidelity” methods, where many runs (1000s) of a low-fidelity are performed to augment a relatively few (tens) of runs of a high fidelity model.
- In the context of cyber modeling, a network simulator or discrete event model might be the low-fidelity model and the emulation the high fidelity one.
- We are currently investigating the feasibility of multifidelity methods for cyber models.

Sampling: Most common method to perform uncertainty analysis. Can handle nonlinearities, discontinuities, etc. but has a slow convergence rate.

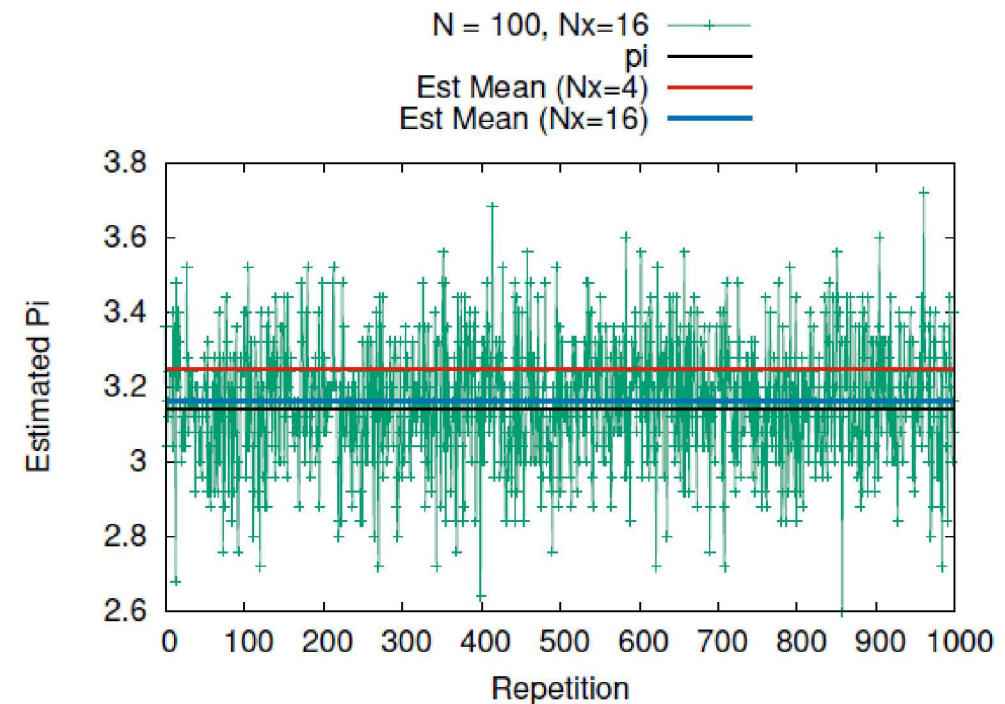
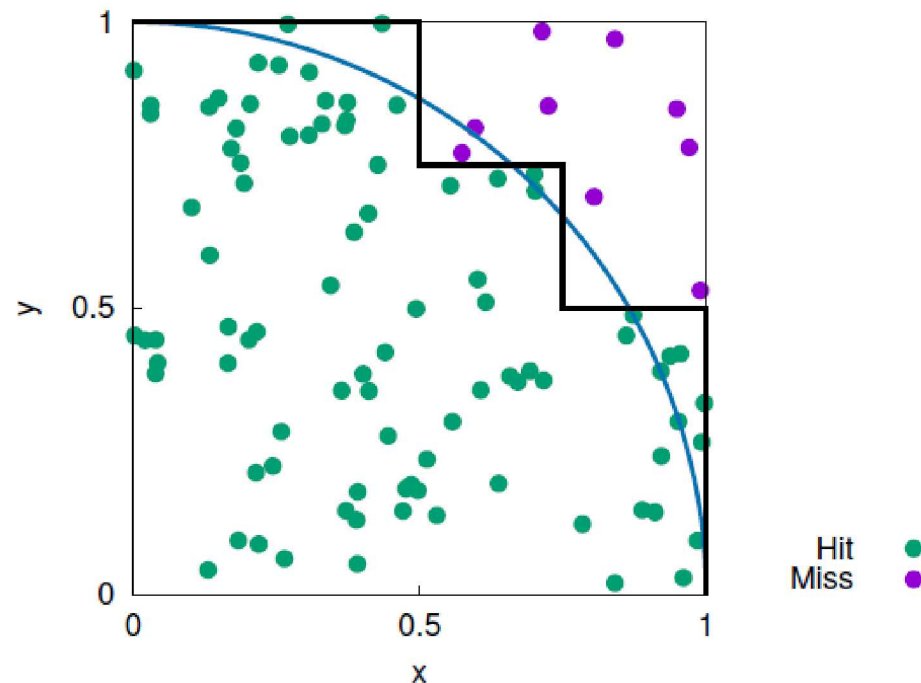
Let's use MC to compute the value $\pi = \frac{\# \text{Hit}}{N}$



Whenever a numerical problems **cannot be resolved with infinite accuracy** (discretization error), the MC estimator for a specific **M**th level

$$\hat{Q}_{\mathbf{M},N}^{MC} \stackrel{\text{def}}{=} \frac{1}{N} \sum_{i=1}^N Q_{\mathbf{M}}^{(i)}$$

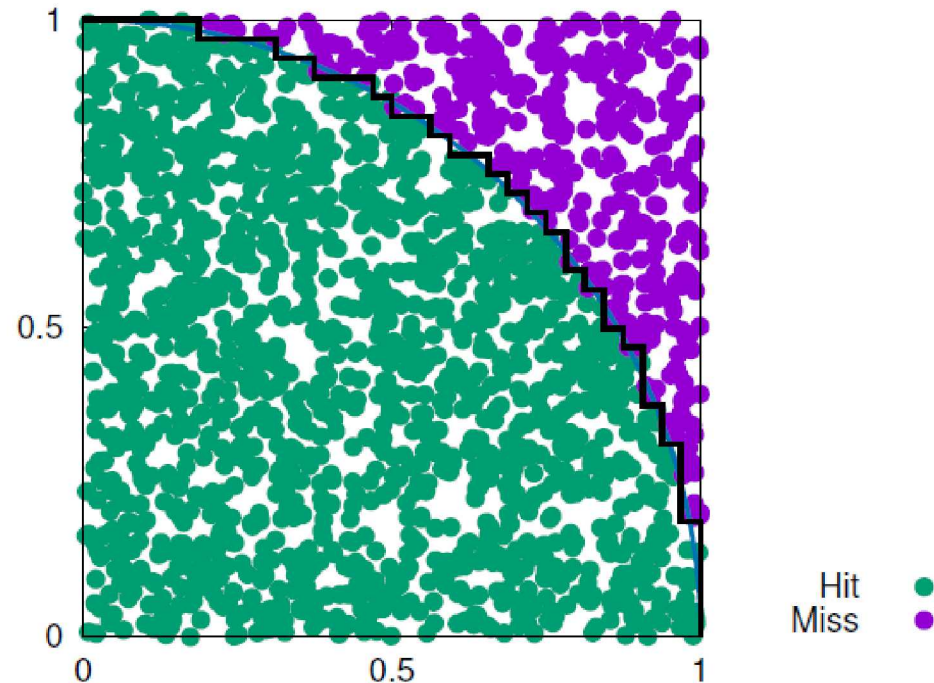
Let's use MC to compute the value $\pi = \frac{\text{\#Hit}}{N}$



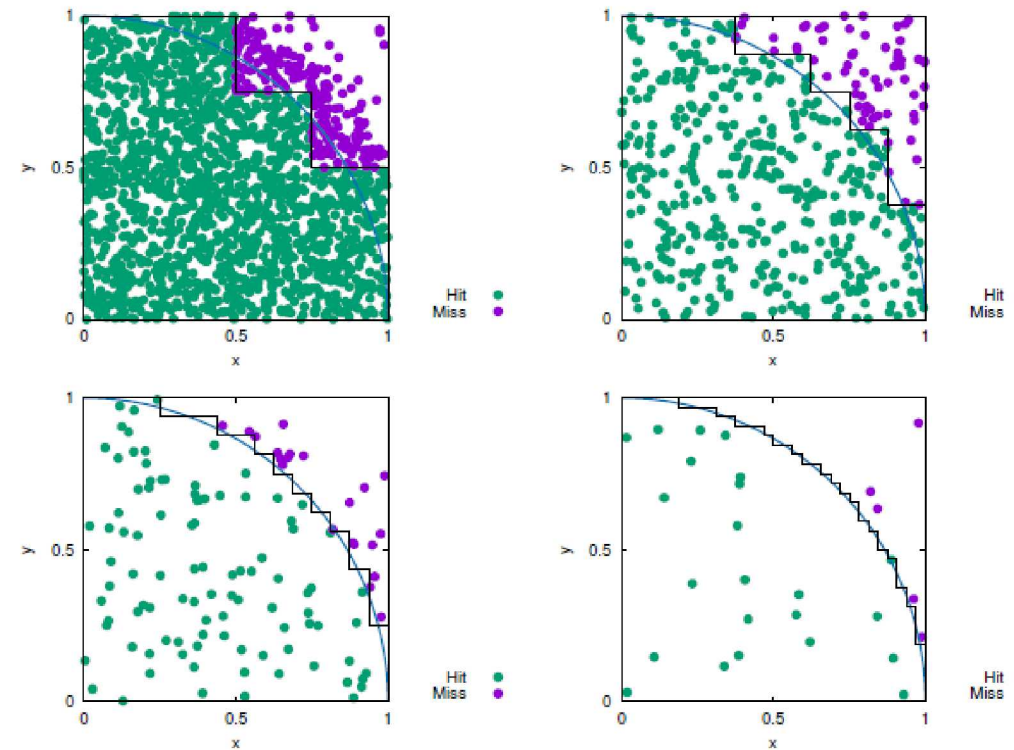
Pivotal idea:

- ▶ **High-fidelity** models are **costly**, but **accurate**
 - ▶ **low-bias** estimates
- ▶ Simplified (**low-fidelity**) models are **inaccurate** but **cheap**
 - ▶ **low-variance** estimates

Single Fidelity



Multi Fidelity



Two sources of error in the **Mean Square Error**:

$$\mathbb{E} \left[(\hat{Q}_{M,N}^{MC} - \mathbb{E}[Q])^2 \right] = \text{Var}(\hat{Q}_{M,N}^{MC}) + (\mathbb{E}[Q_M - Q])^2$$

- **Sampling error**: replacing the expected value by a (finite) sample average, *i.e.*

$$\text{Var}(\hat{Q}_{M,N}^{MC}) = \frac{\text{Var}(Q)}{N}$$

- **Model fidelity (e.g. discretization)**: finite accuracy

Accurate estimation \Rightarrow **Large number** of samples evaluated for the **high fidelity** model

$$\mathbb{E}[Q_M] - \hat{Q}_{M,N}^{MC} \sim \sqrt{\frac{\text{Var}(Q_M)}{N}} \mathcal{N}(0, 1)$$

In our network application we operate under the assumptions that

- The emulytics is the highest **unbiased** fidelity model, *i.e.* $(\mathbb{E}[Q_M - Q])^2 = 0$
- Our goal is to solely **reduce the variance** of the estimator by introducing low-fidelity evaluations

Let's consider M **low-fidelity models with known mean**. The Optimal Control Variate (OCV) is generated by adding M unbiased terms to the MC estimator

$$\hat{Q}^{\text{CV}} = \hat{Q} + \sum_{i=1}^M \alpha_i (\hat{Q}_i - \mu_i)$$

- ▶ \hat{Q}_i MC estimator for the i th low-fidelity model
- ▶ μ_i known expected value for the i th low-fidelity model
- ▶ $\underline{\alpha} = [\alpha_1, \dots, \alpha_M]^T$ set of weights (to be determined)

Let's define

- ▶ The covariance matrix among all the low-fidelity models: $\mathbf{C} \in \mathbb{R}^{M \times M}$
- ▶ The vector of covariances between the high-fidelity Q and each low-fidelity Q_i : $\mathbf{c} \in \mathbb{R}^M$
- ▶ $\bar{\mathbf{c}} = \mathbf{c} / \text{Var}(Q) = [\rho_1 \text{Var}(Q_1), \dots, \rho_M \text{Var}(Q_M)]^T$, where ρ_i is the correlation coefficient (Q, Q_i)

The optimal weights are obtained as $\underline{\alpha}^* = -\mathbf{C}^{-1}\mathbf{c}$ and the variance of the OCV estimator

$$\begin{aligned} \text{Var}(\hat{Q}^{\text{CV}}) &= \text{Var}(\hat{Q}) (1 - \bar{\mathbf{c}}^T \mathbf{C}^{-1} \bar{\mathbf{c}}) \\ &= \text{Var}(\hat{Q}) (1 - R_{\text{OCV}}^2), \quad 0 \leq R_{\text{OCV}}^2 \leq 1. \end{aligned}$$

➡ For a single low-fidelity model: $R_{\text{OCV}-1}^2 = \rho_1^2$

Network Configuration

- ▶ 1 client - 1 server (possible to extend to multiple clients)
- ▶ 100 Requests

Uncertain Parameters

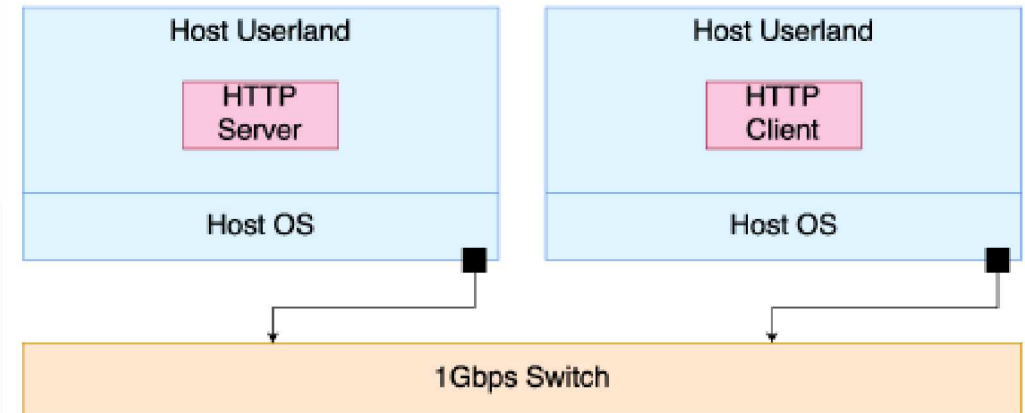
- ▶ $\text{DataRate} \sim \mathcal{U}(5, 500) \text{Mbps}$
- ▶ $\text{ResponseSize} \sim \ln \mathcal{U}(500, 16 \times 10^6) B$

Fidelity definition

- ▶ minimega – HF: 100 Requests (average over 10 repetitions)
- ▶ ns3 – LF: 10 Requests (Delay 50ms)
- ▶ ns3 – LF*: 1 Requests (Delay 5ms)

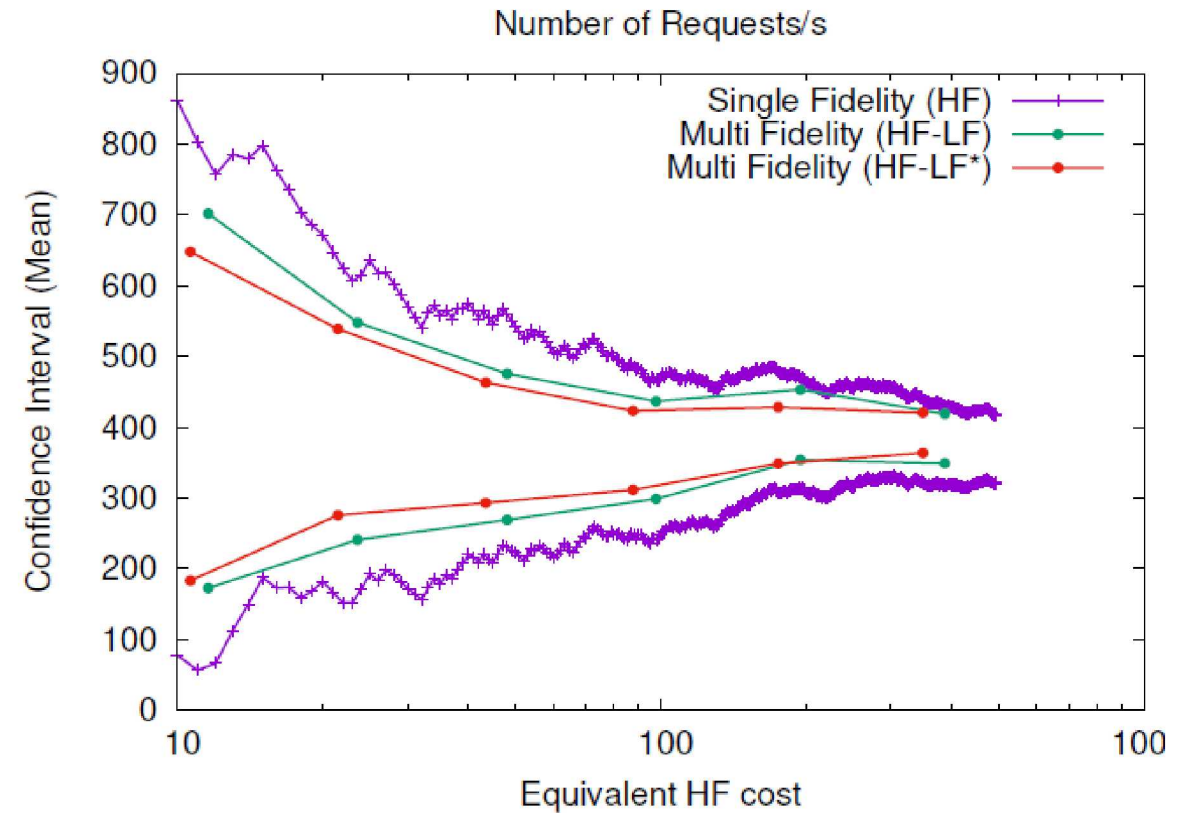
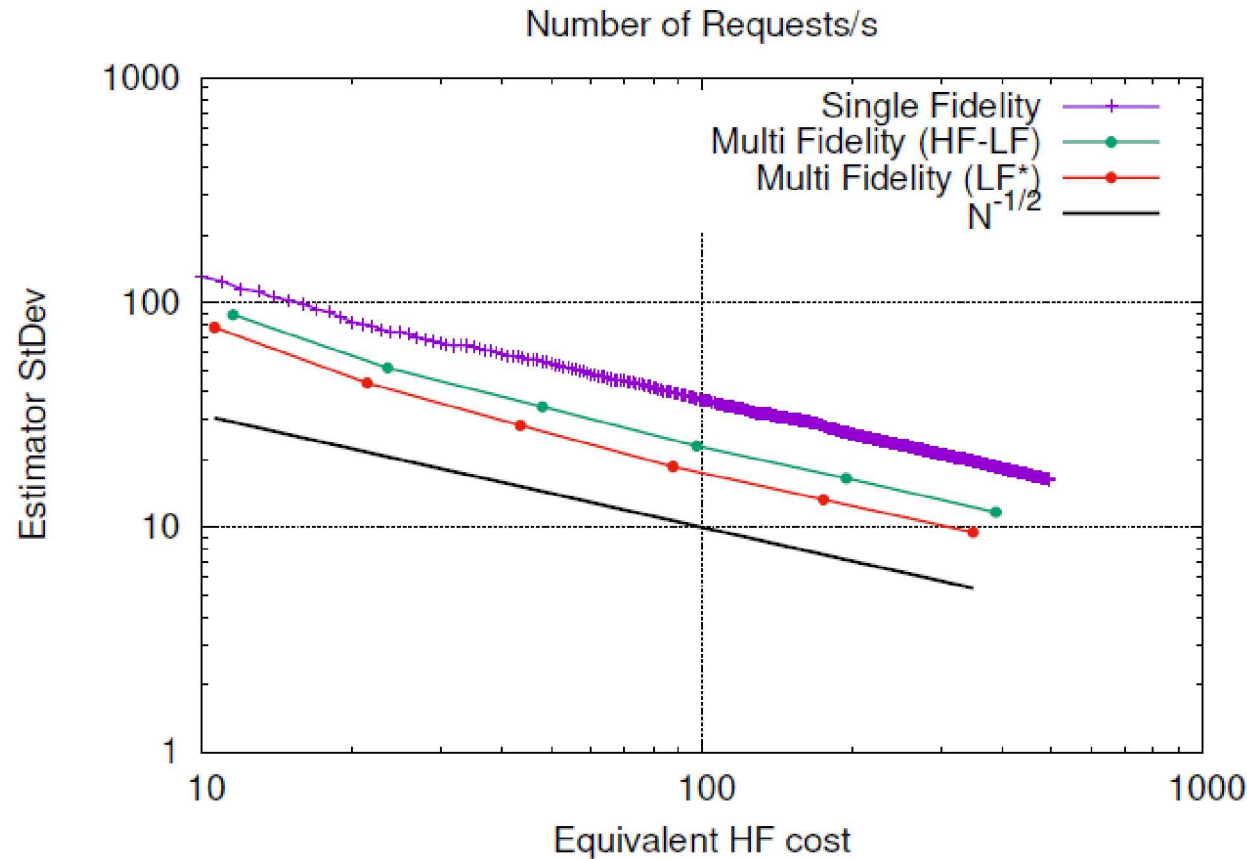
Correlation between models

	HF	LF	LF*
HF	1	0.86	0.90
LF	0.86	1	0.99
LF*	0.90	0.99	1



Relative cost between models

Model	Cost
HF	1
LF	0.016
LF*	0.002



Graphs show 4-fold reduction in variance when estimating the *mean number of http requests completed per second* for the same computational budget

- Computational workflows around Emulytics models are starting to be developed similar to what the computational simulation community has done.
- Uncertainty quantification and experimental design are important components in understanding the sensitivities of a model and identifying the range and distribution of model output.
- There are several issues performing UQ for emulations, including replicability and large variation in performance across runs; difficulty of setting up multiple emulations concurrently; and large, discrete parameter spaces.
- The use of new approaches to UQ such as multifidelity methods is interesting and worthy of further investigation.