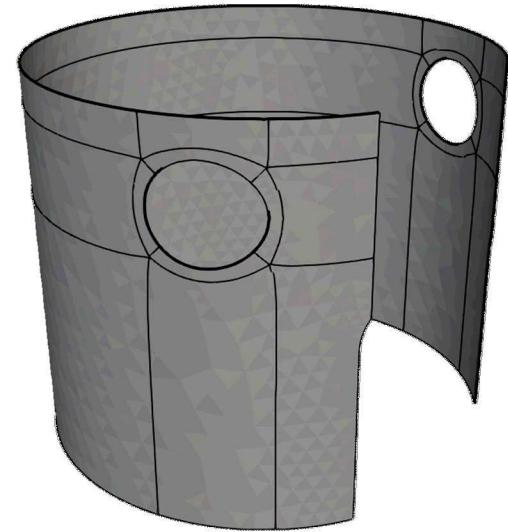


# THROUGH ROBUST REFINEMENT OF CROSS SEPARATRIX LINES



erotel

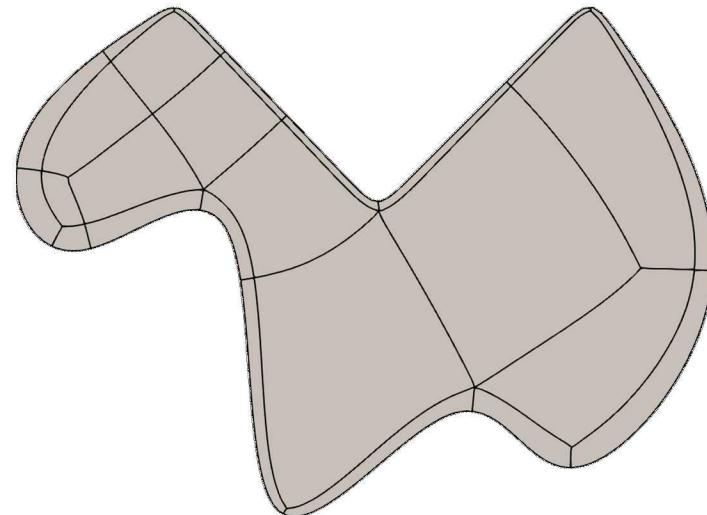
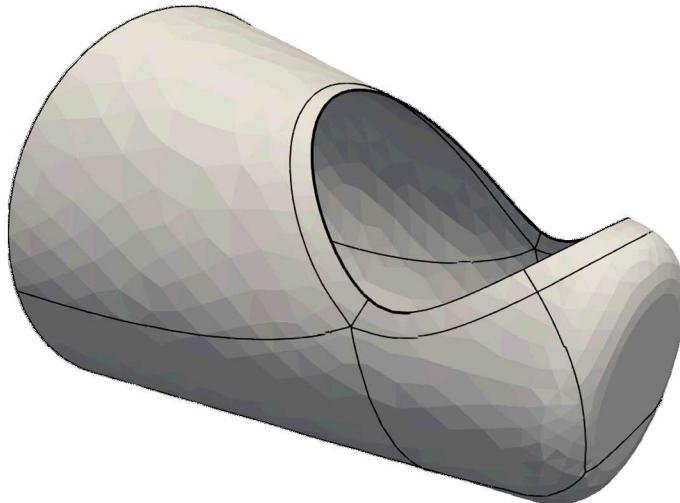
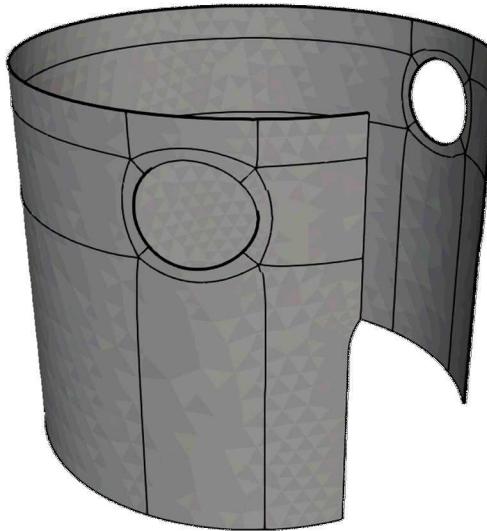
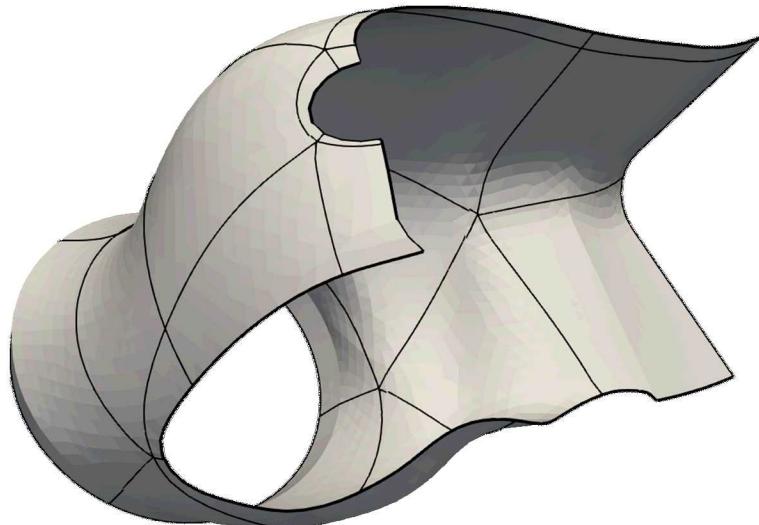
October 16<sup>th</sup> 2019

28<sup>th</sup> International Meshing Roundtable



Sandia National Laboratories is a multi-mission laboratory managed and operated by National Technology & Engineering Solutions of Sandia, LLC., a wholly owned subsidiary of Honeywell International, Inc., for the U.S. Department of Energy's National Nuclear Security Administration under contract DE-NA0003525.

# Goal: Coarse boundary aligned quad partitions



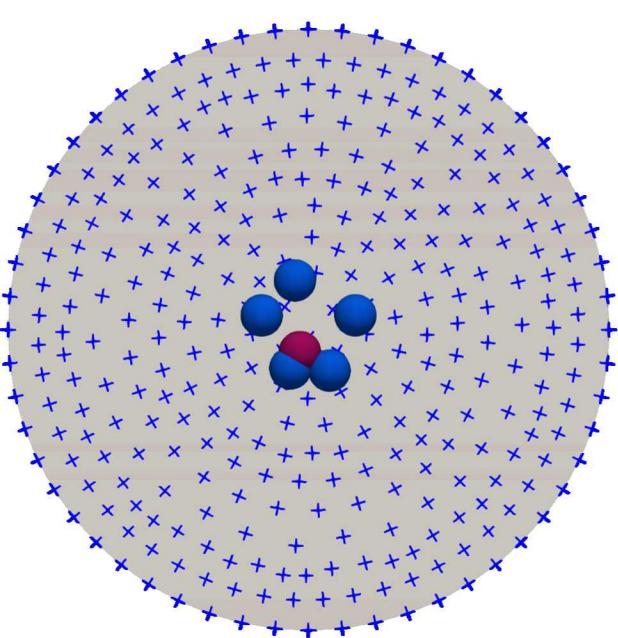
# Contributions:

1. Extend MBO method for cross field design to curved surfaces
2. Prove that near singularities, streamlines of a cross field are hyperbolic under a conformal map.
3. Partition simplification algorithm to generate coarse quad layouts

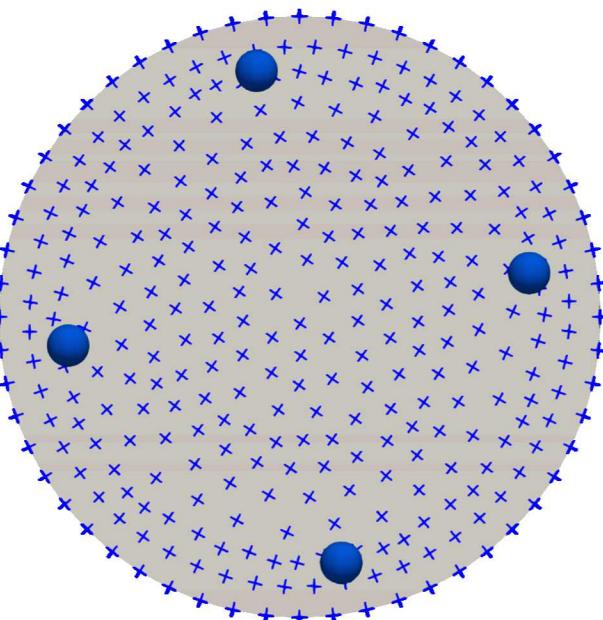
# **Merriman-Bence-Osher (MBO) Method for Cross Field Design**

# Why MBO?

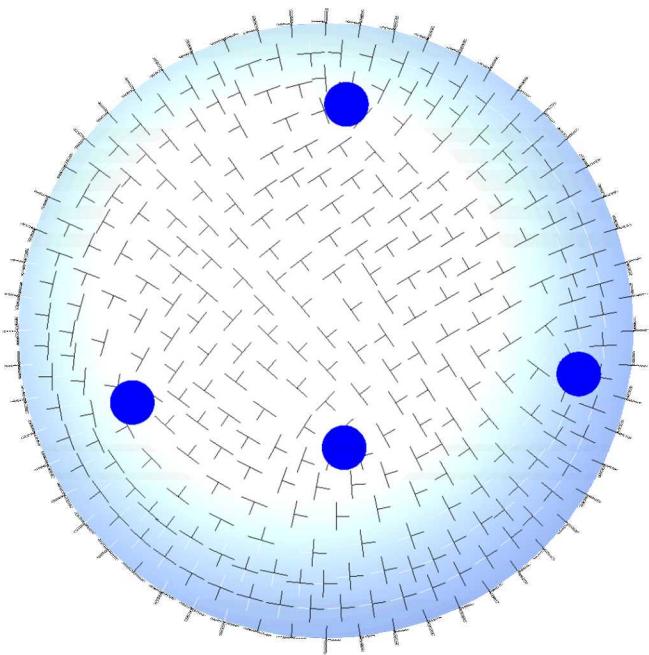
- Easy to implement
- Fast
- Good singularity placement



Knoppel et al. 2013



MBO

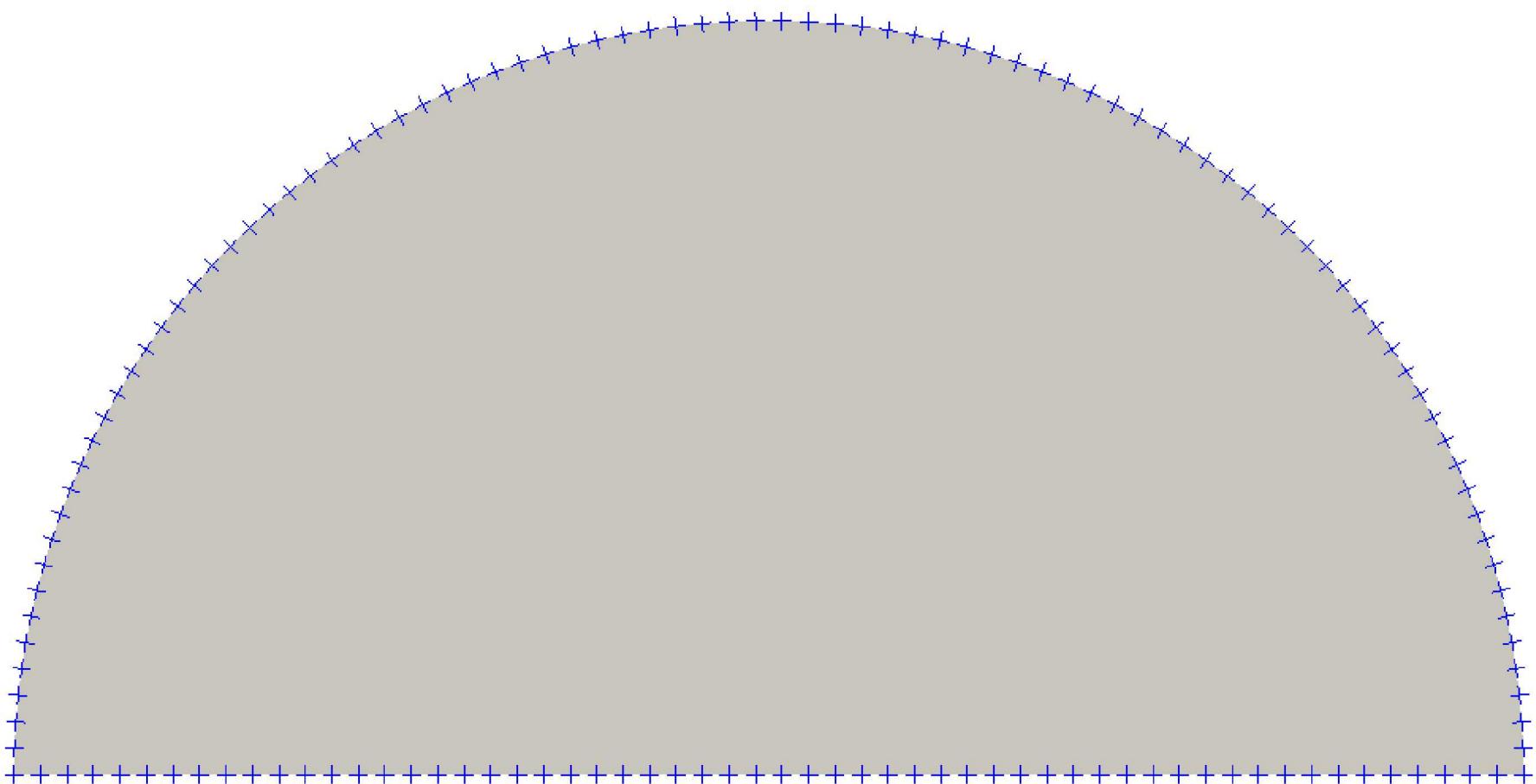


Jakob et al. 2014

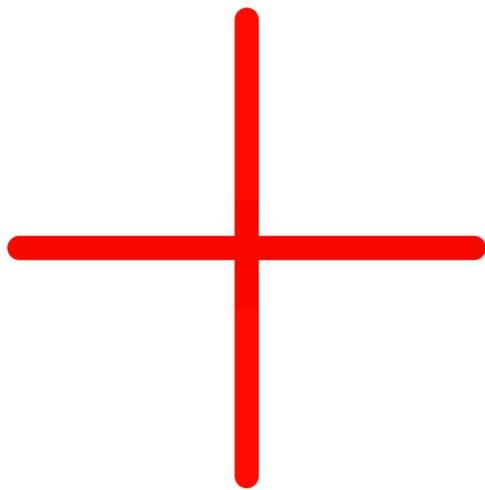
# MBO Method for Cross Fields



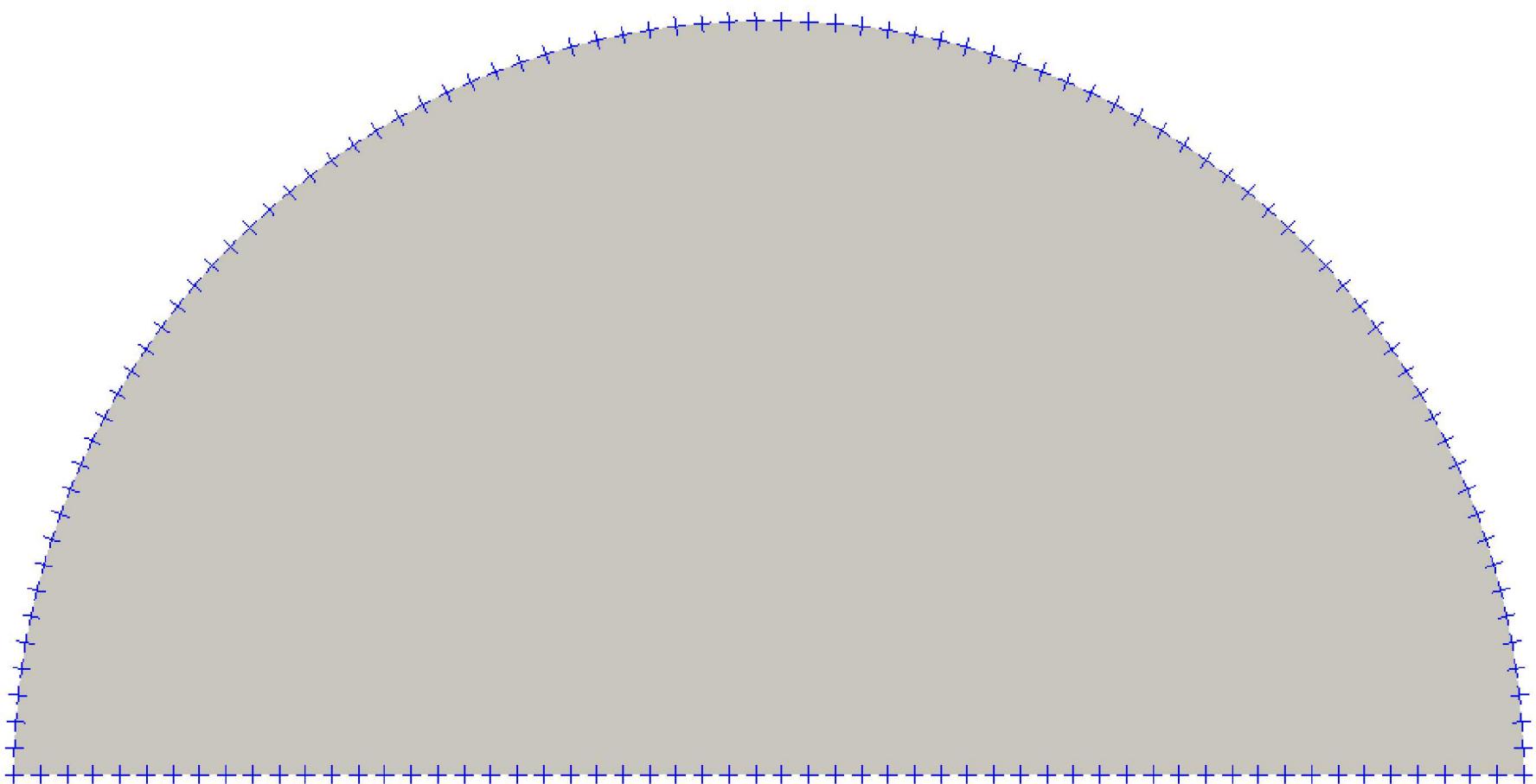
# MBO Method for Cross Fields



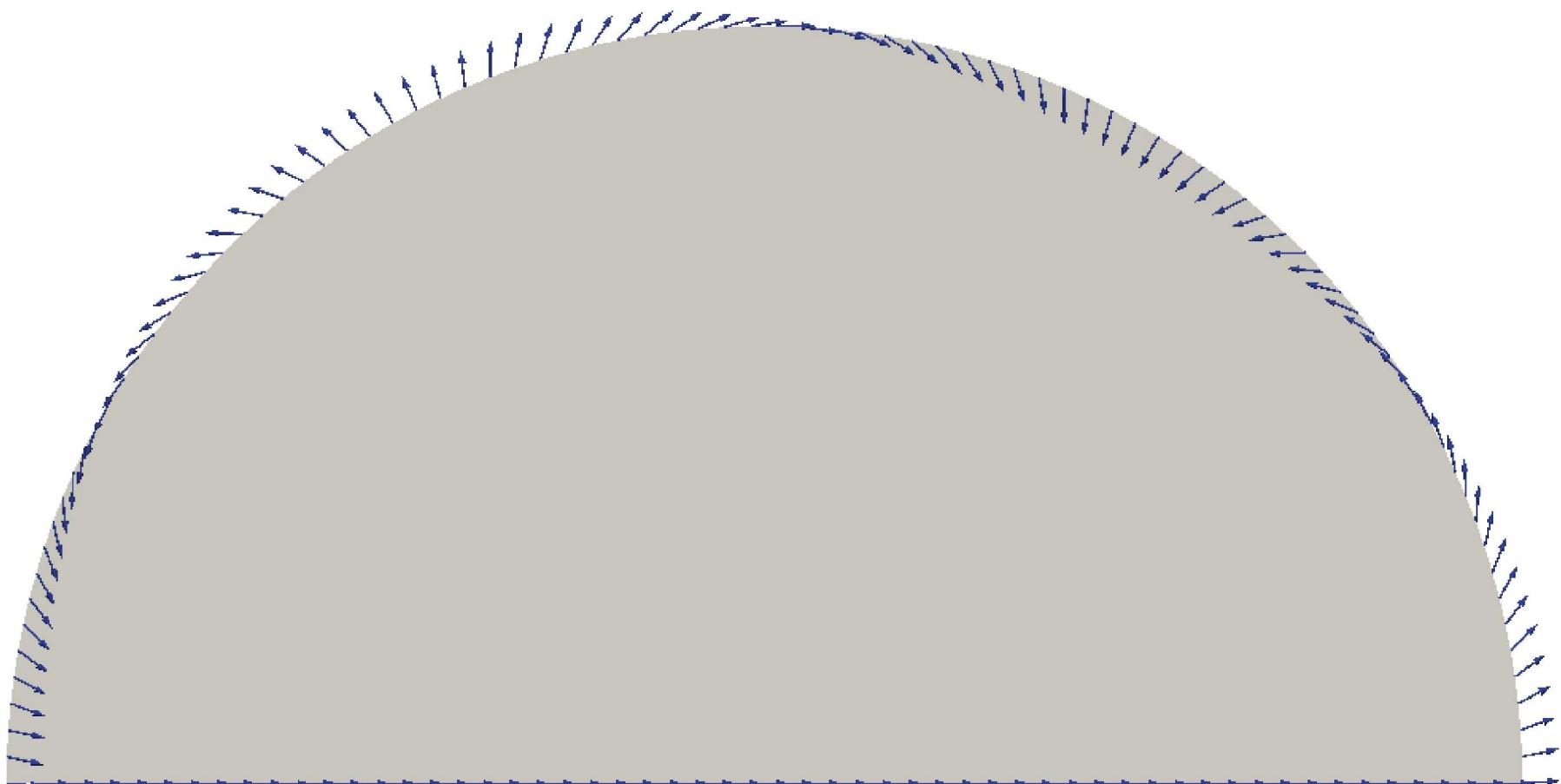
# The Representation Map



# MBO Method for Cross Fields



# MBO Method for Cross Fields



# MBO Method for Cross Fields

$$\min_{u \in H_g^1(D, \mathbb{C})} E(u)$$

$$E(u) = \frac{1}{2} \int_D |\nabla u|^2 dA$$

$$u(x) = g(x) \quad \forall x \in \partial D$$

$$|u(x)| = 1 \quad \text{a.e. } x \in D$$

# MBO Method for Cross Fields

Ginzburg-Landau Relaxation:

$$E_\epsilon(u) = \frac{1}{2} \int_G |\nabla u|^2 + \frac{1}{4\epsilon^2} \int_G (|u|^2 - 1)^2$$

Iterative method to minimize cross field energy:

1. Until time  $\tau$  solve

$$u_t(t, x) = \Delta u(t, x) \quad x \in M$$

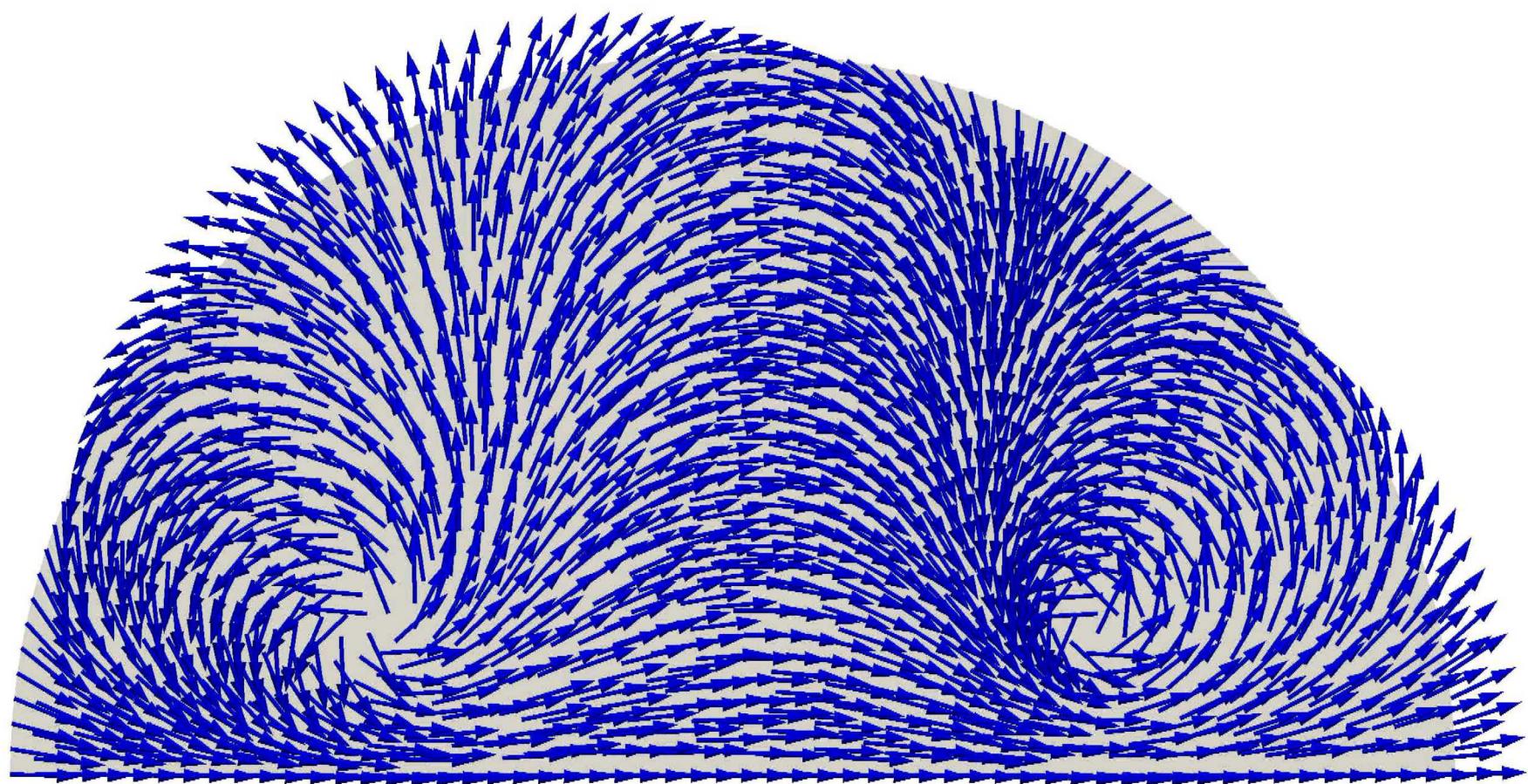
$$u(t, x) = g(x) \quad x \in \partial M$$

$$u(0, x) = u_0(x) \quad x \in M$$

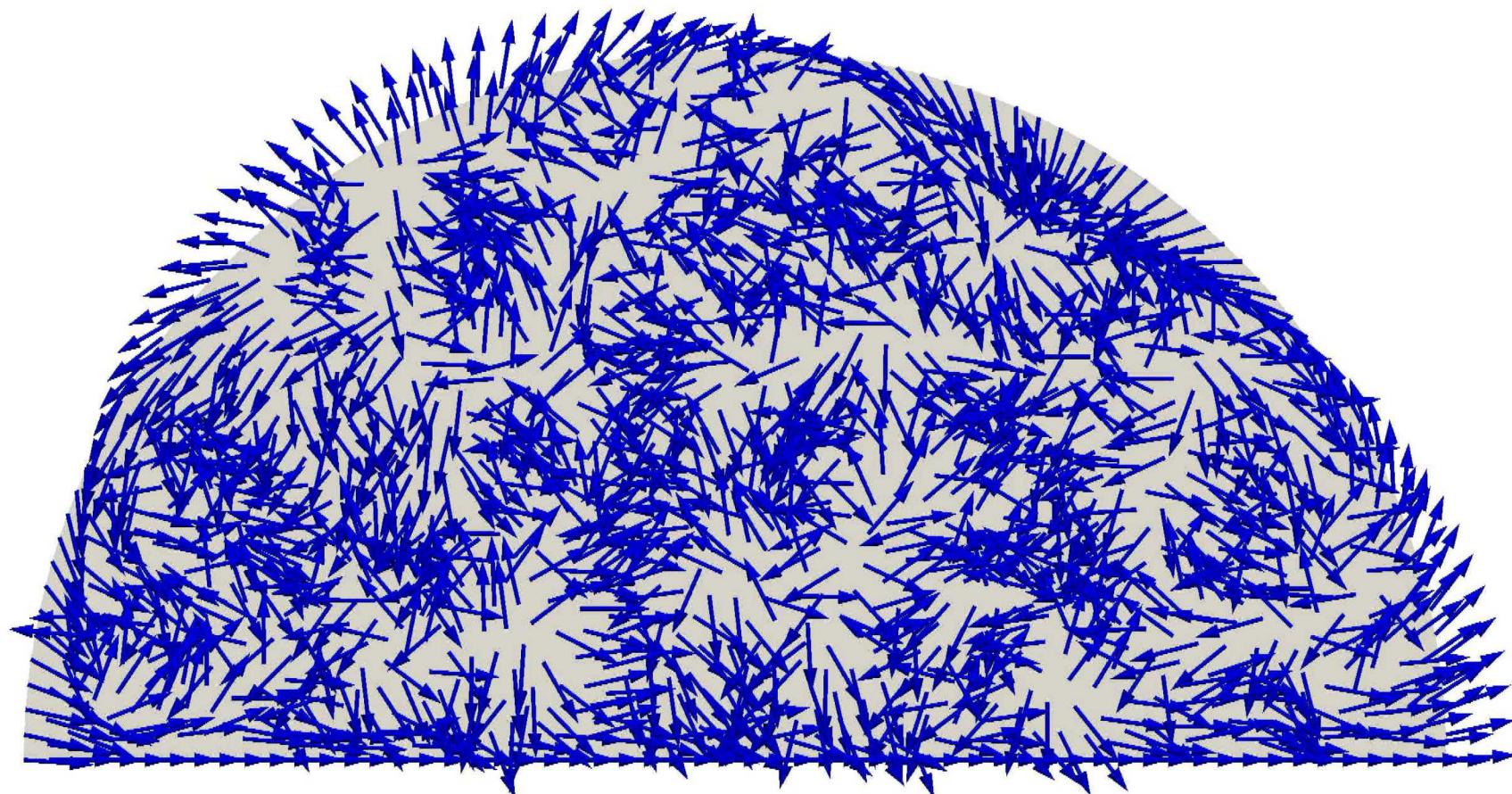
2. Renormalize

$$u(\tau, x) = \frac{u(\tau, x)}{\|u(\tau, x)\|}$$

# MBO Method



# MBO Method



# MBO on Surfaces

1. Until time  $\tau$  solve

$$u_t(t, x) = \underbrace{\Delta u(t, x)}_{?} \quad x \in M$$

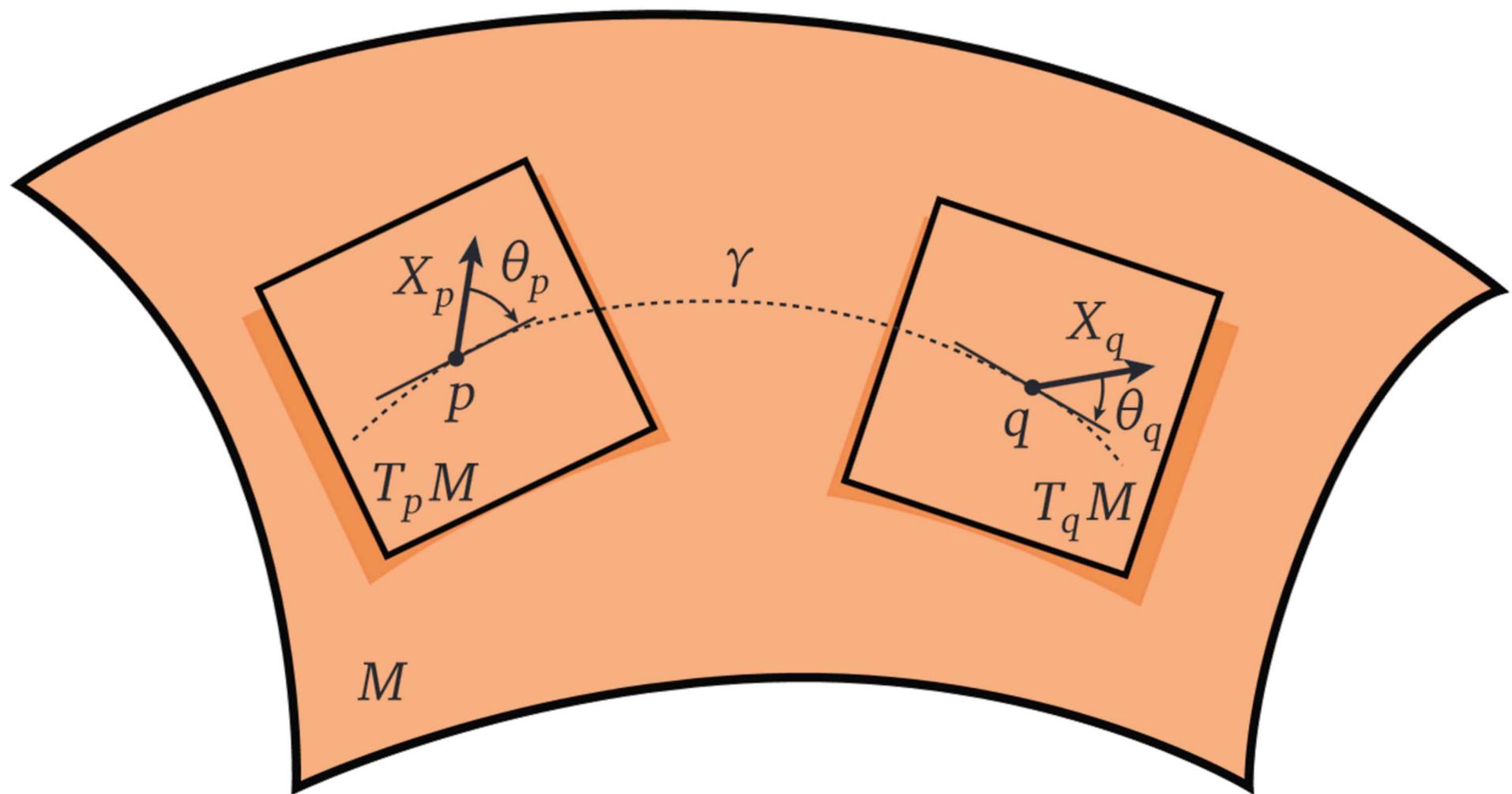
$$u(t, x) = g(x) \quad x \in \partial M$$

$$u(0, x) = u_0(x) \quad x \in M$$

2. Renormalize

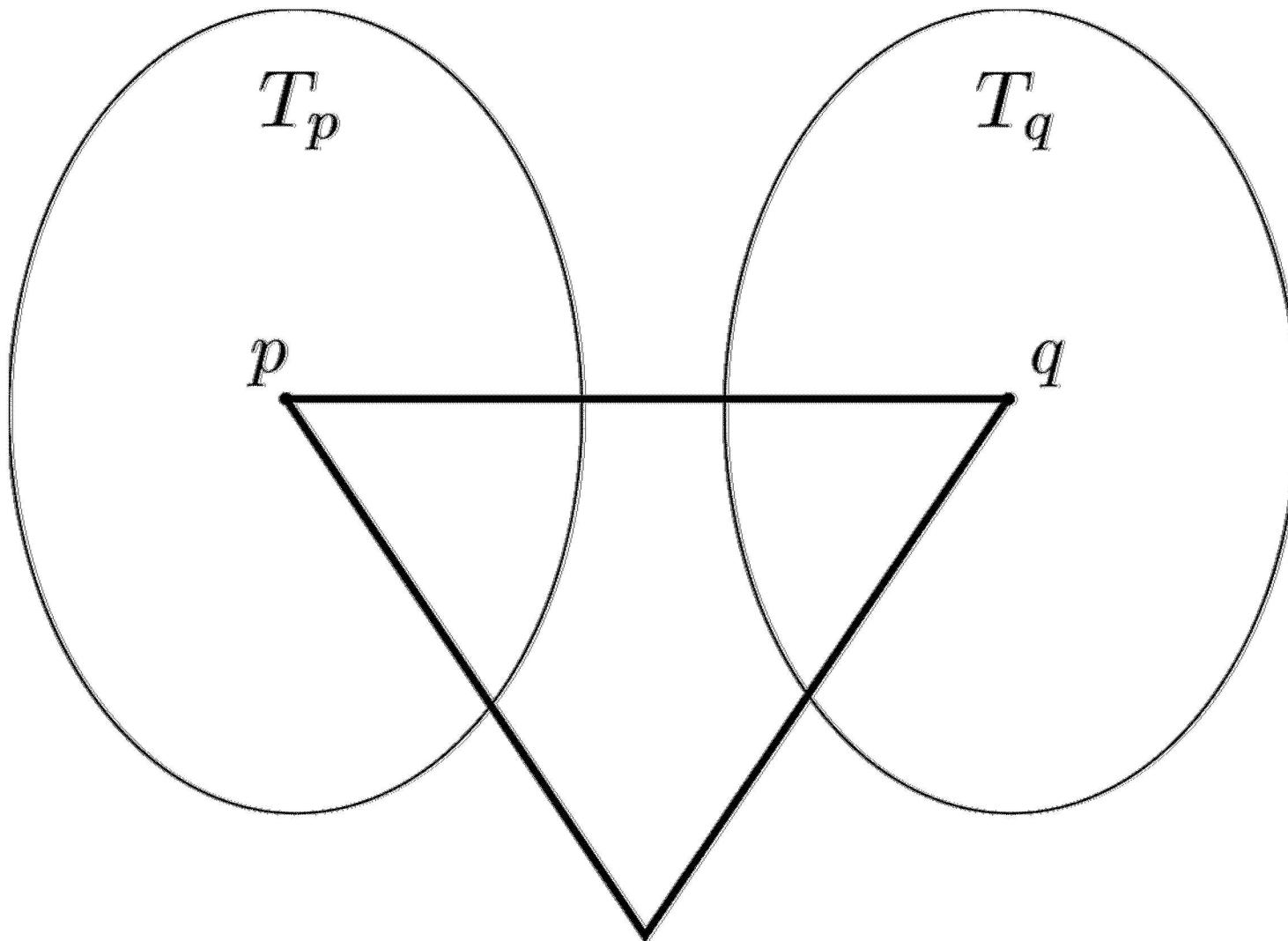
$$u(\tau, x) = \frac{u(\tau, x)}{\|u(\tau, x)\|}$$

# Levi-Civita Connection

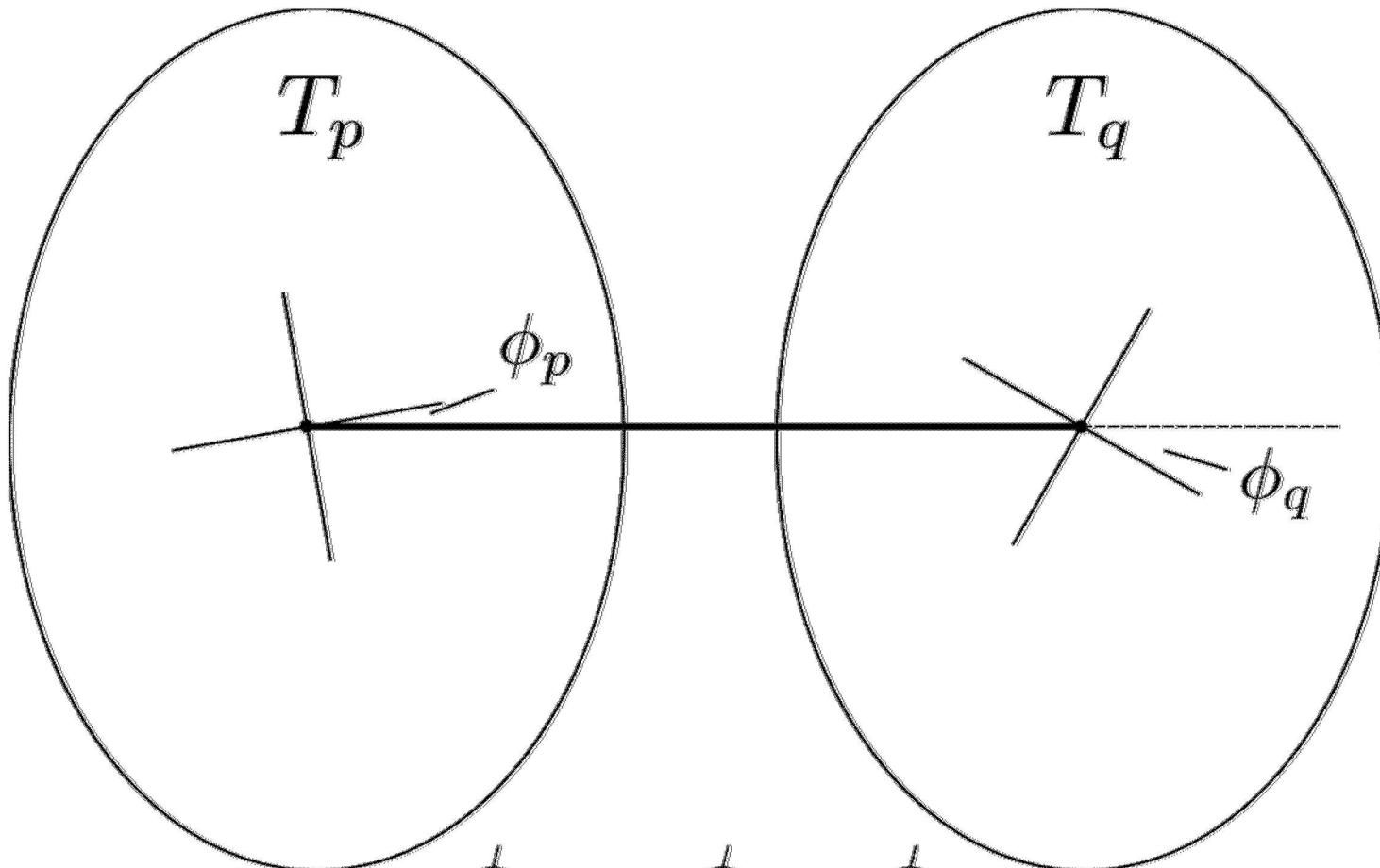


Knoppel et al. 2013

# Cross Field Design on Surfaces



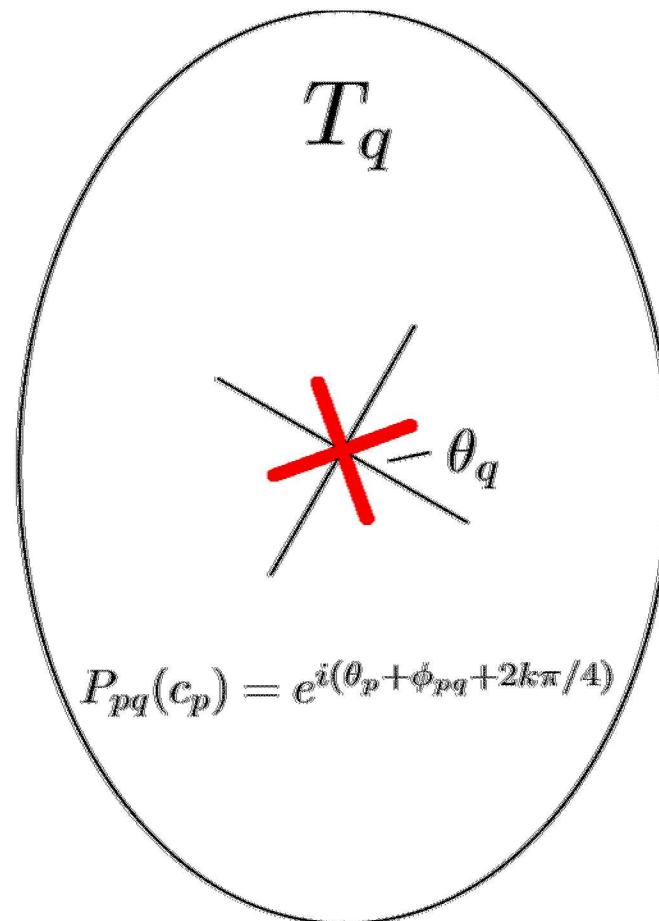
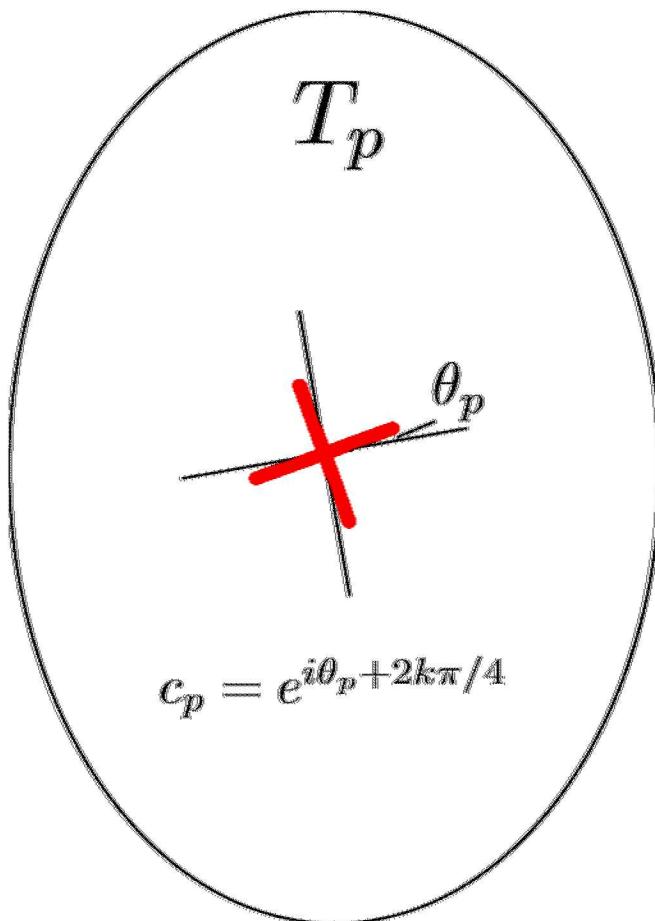
# Cross Field Design on Surfaces



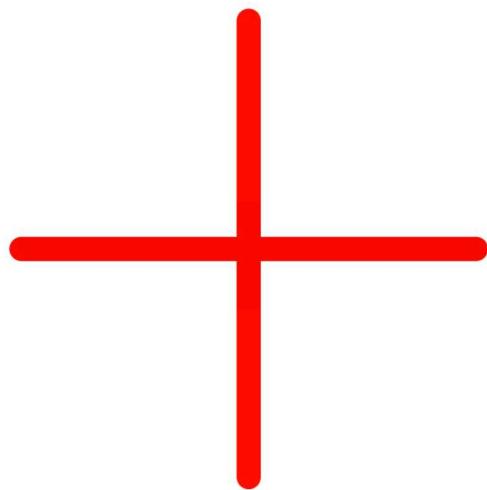
$$\phi_{pq} = \phi_p - \phi_q$$

$$P_{pq}(v) = e^{i\phi_{pq}}v$$

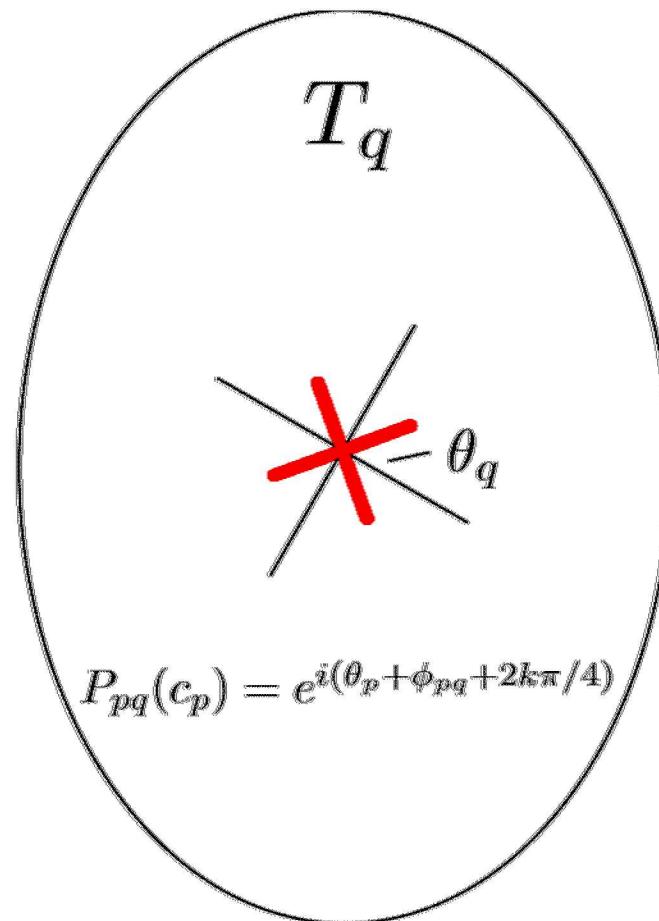
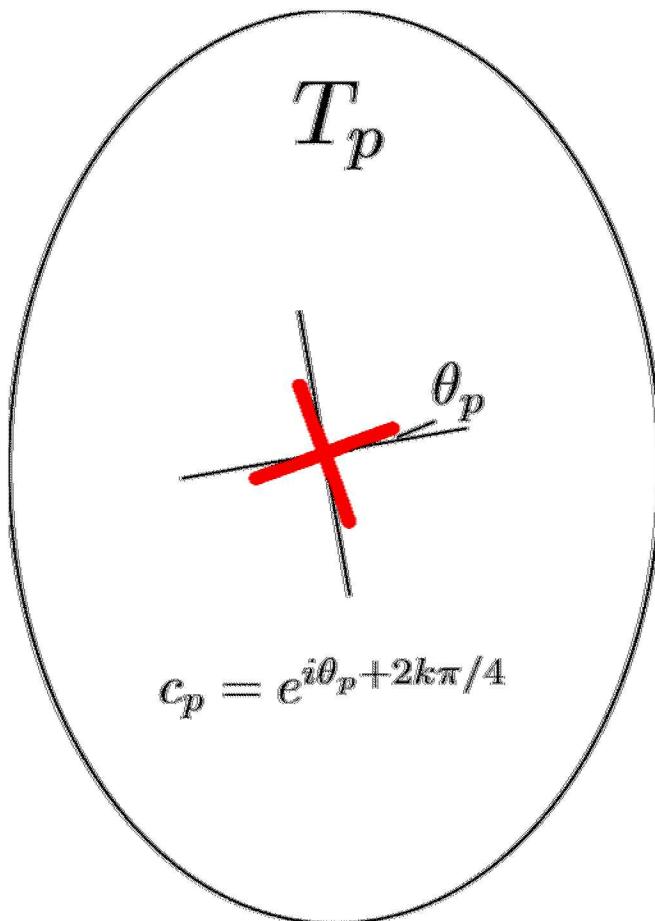
# Cross Field Design on Surfaces



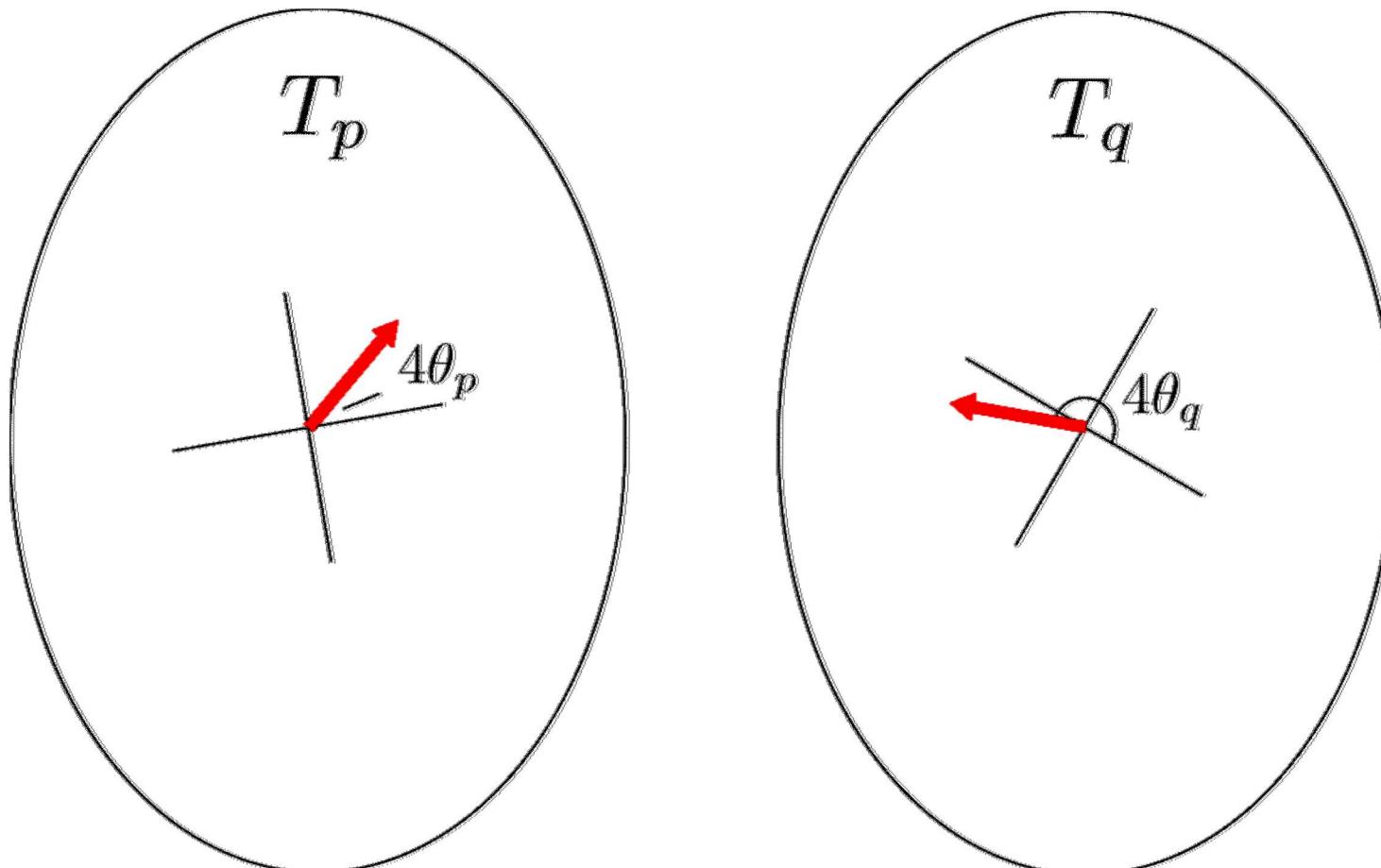
# The Representation Map



# Cross Field Design on Surfaces



# Cross Field Design on Surfaces



$$\begin{aligned} Q_{pq}(e^{4i\theta_p}) &= e^{4i(\theta_p + \phi_{pq})} \\ \implies Q_{pq}(v) &= e^{4i\phi_{pq}} v \end{aligned}$$

# Discrete Laplacian for Representation Vectors

$$v \in T_q$$

$$u \in T_p$$

$$|v - Q_{pq}u|^2$$

# Discrete Laplacian for Representation Vectors

$$v \in T_q$$

$$u \in T_p$$

$$|v - Q_{pq}u|^2$$

$$\Delta_Q(\vec{u})|_i = \frac{1}{|\mathcal{N}(n_i)|} \sum_{n_j \in \mathcal{N}(n_i)} (u_j - Q_{ij}(u_i))$$

# Discrete MBO on Surfaces

---

**Algorithm 2** A diffusion generated method for designing smooth cross fields

---

Let  $u^0$  be the solution to  $Au = b$ .

Fix  $\tau$ ,  $\delta$ , and set  $k = 0$ .

**while**  $\|u^k - u^{k-1}\| > \delta$ , **do**

Solve the discrete diffusion equation,

$$(I - \tau A)u^{k+1} = u^k + \tau b \quad (6)$$

**for**  $j \in [0, n]$  **do**

Set  $u_j^{k+1} = \frac{u_j^{k+1}}{|u_j^{k+1}|}$

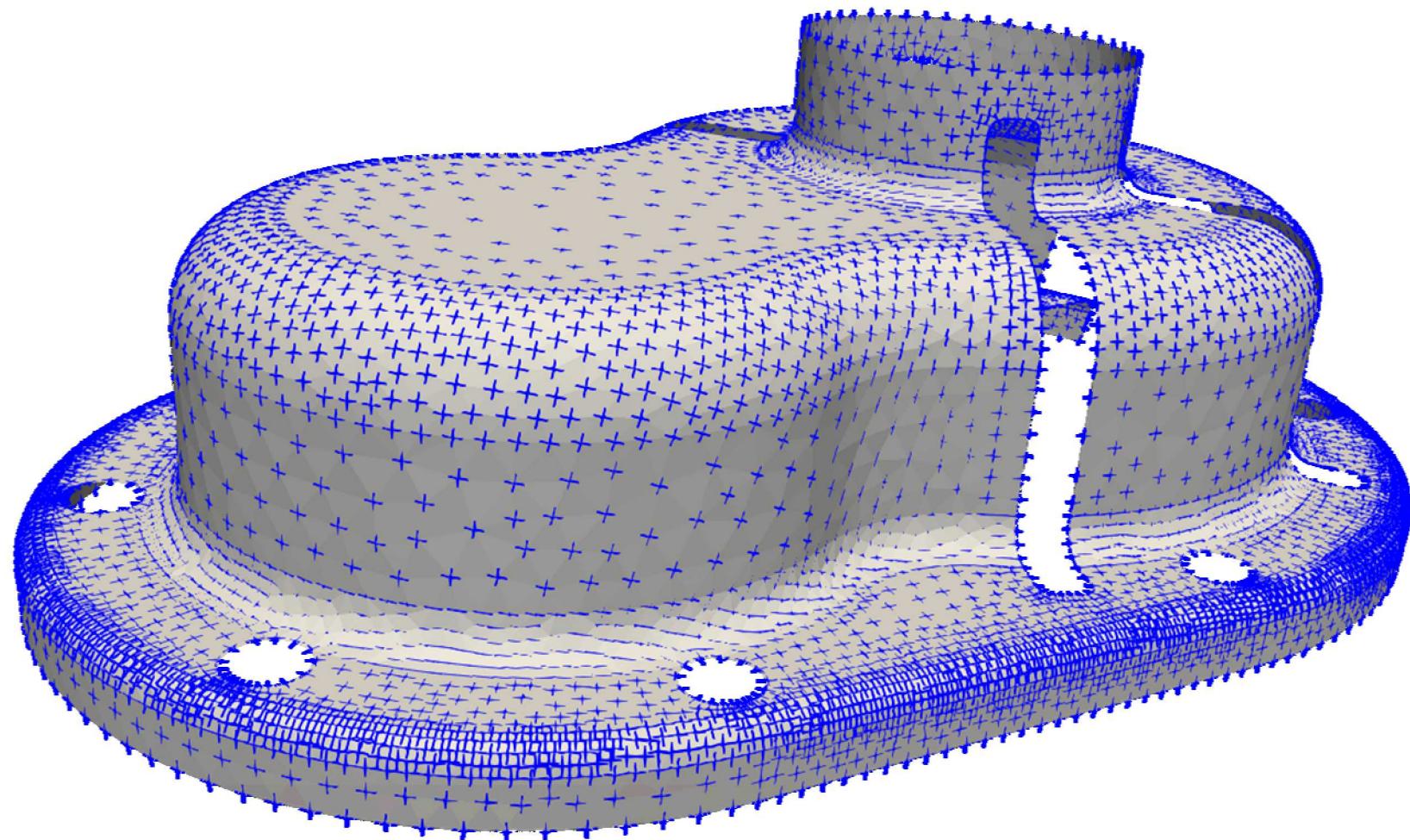
**end for**

$k++$

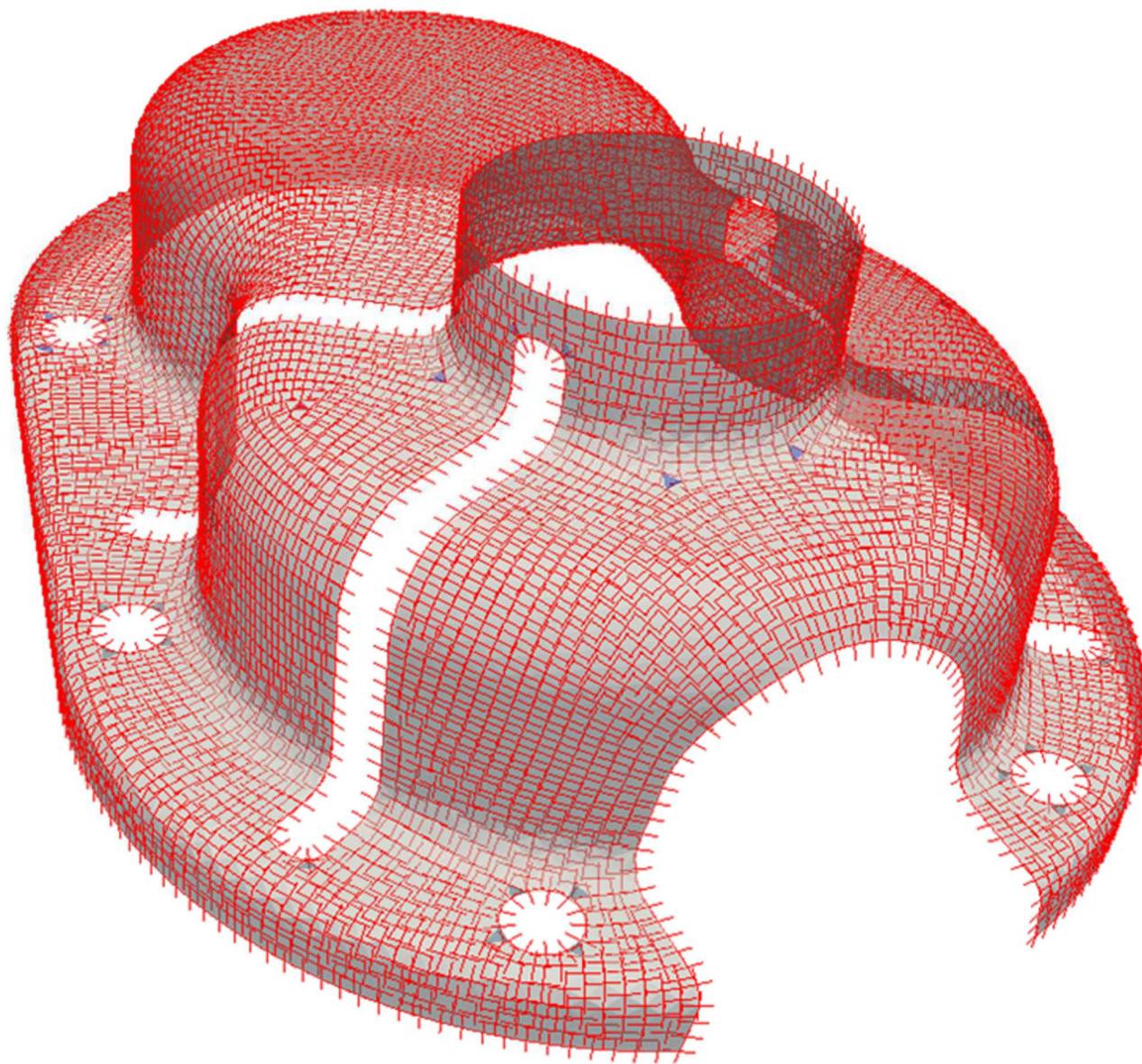
**end while**

---

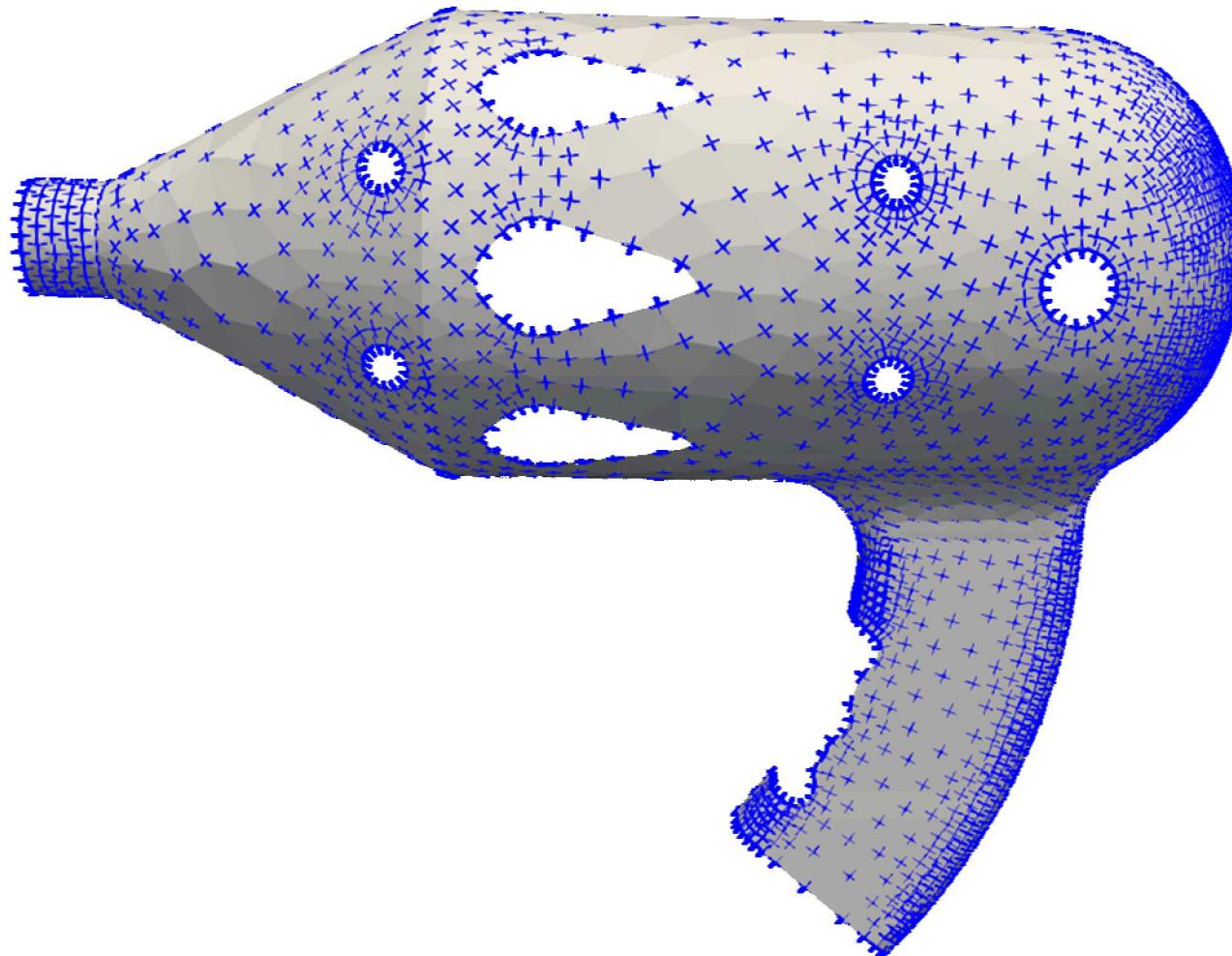
# Cross Fields on Surfaces



# Curved Surfaces

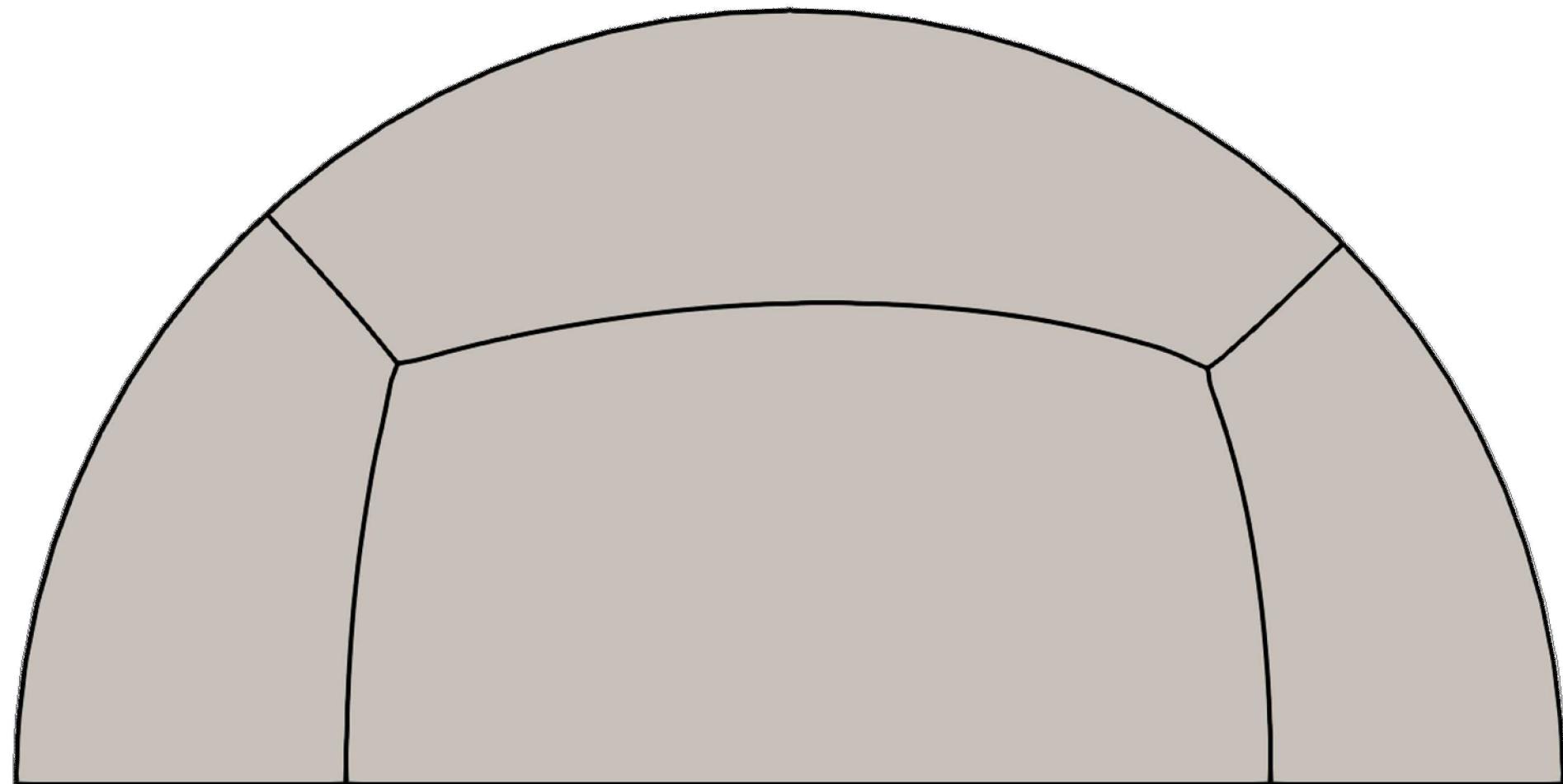


# Cross Fields on Surfaces

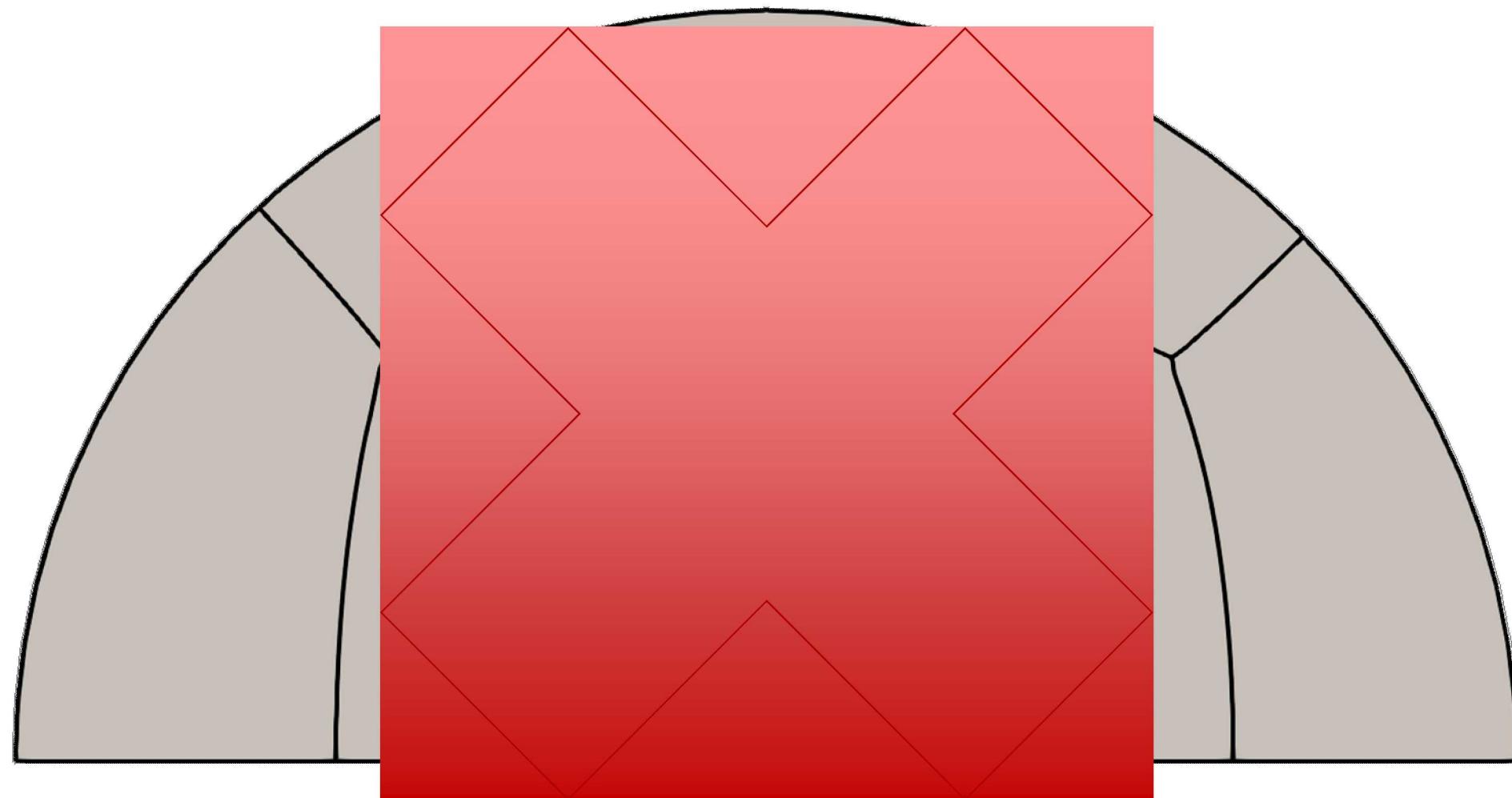


# Partition Simplification

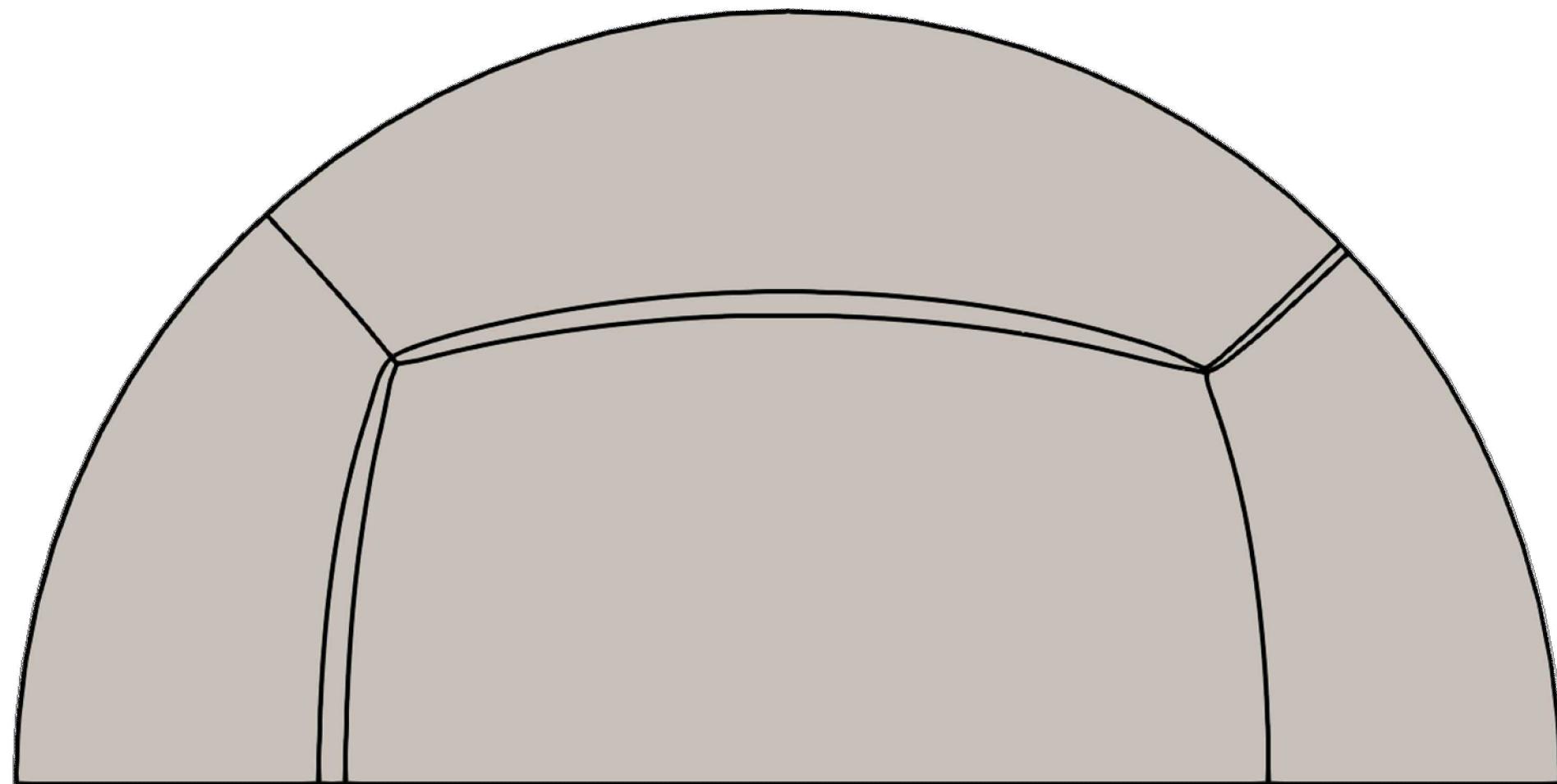
# Naive Partition



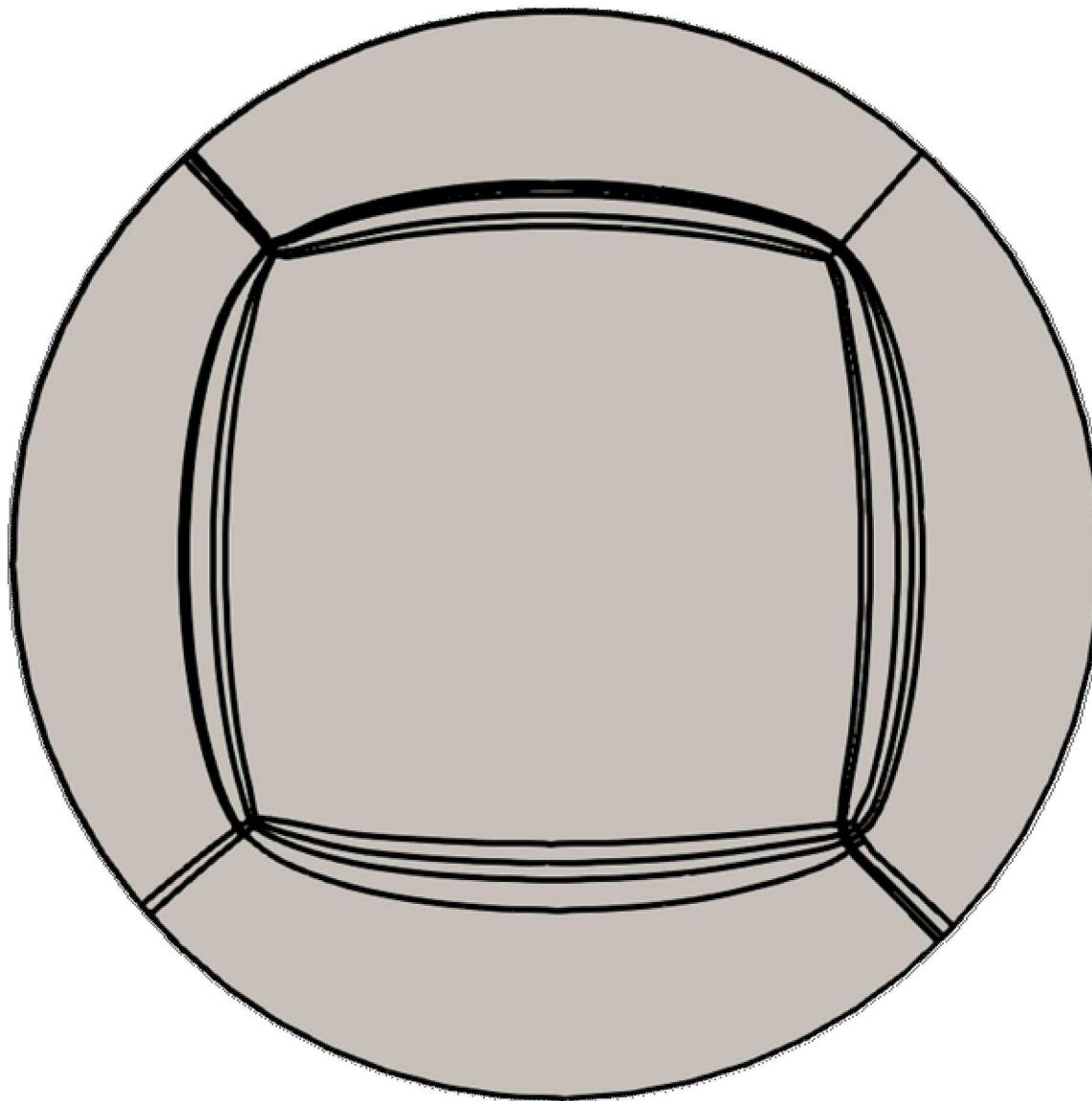
# Naive Partition



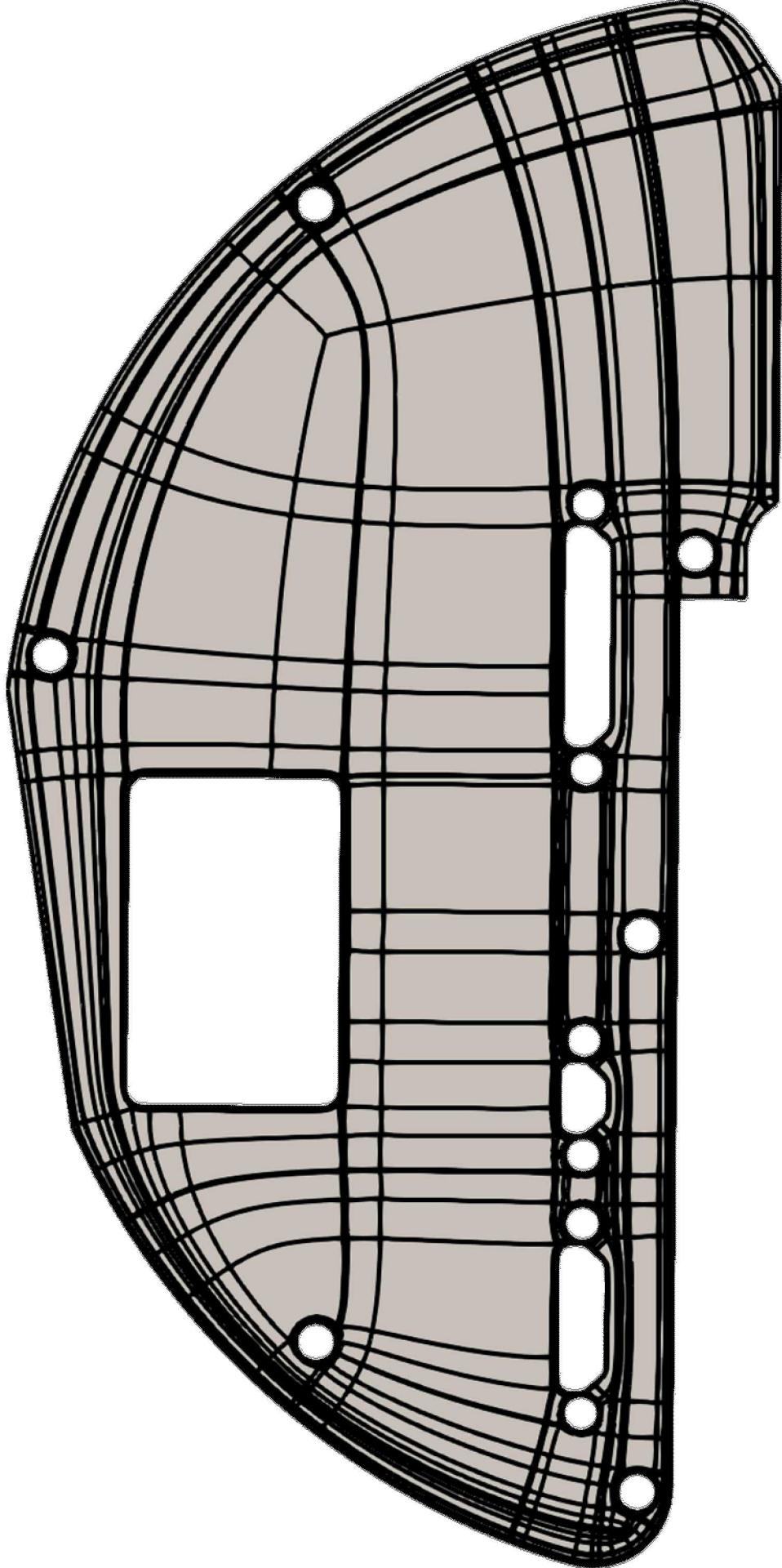
# Naive Partition



# Limit Cycles Are Common



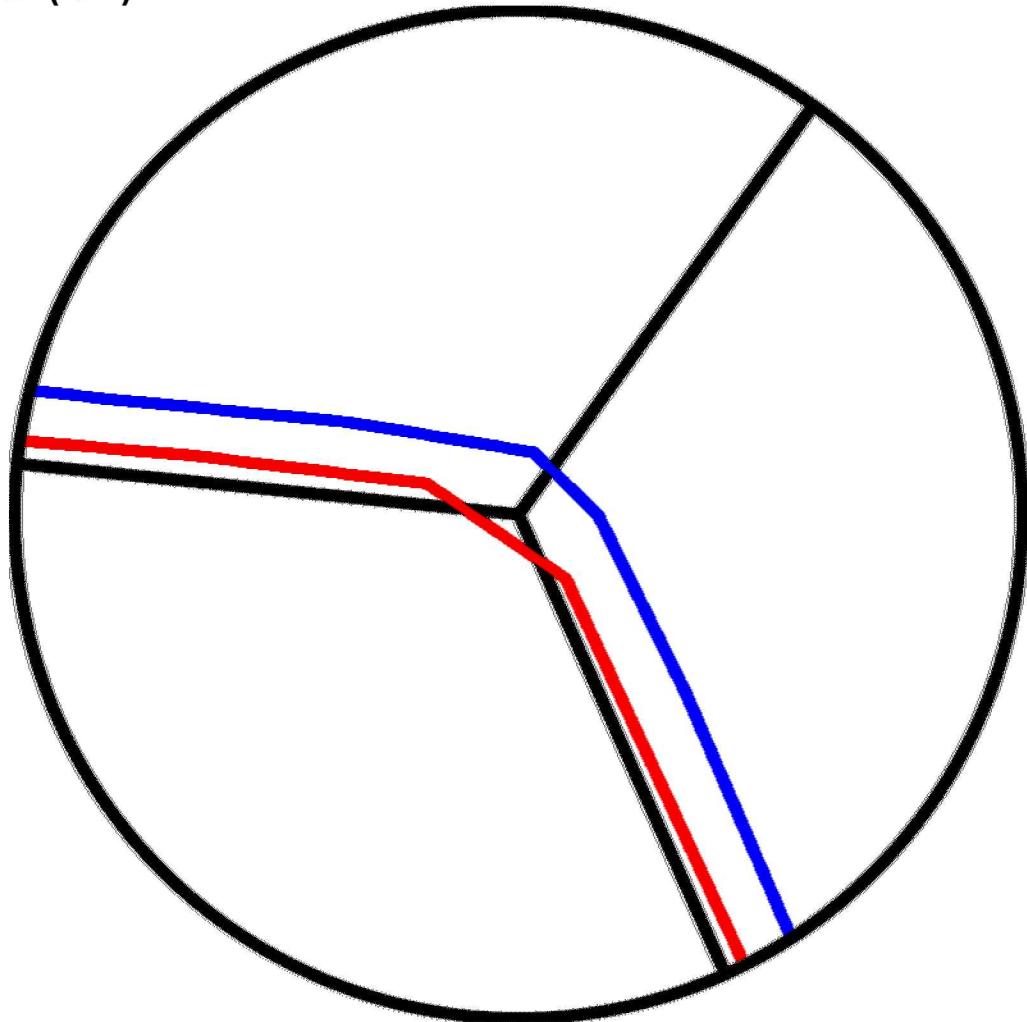
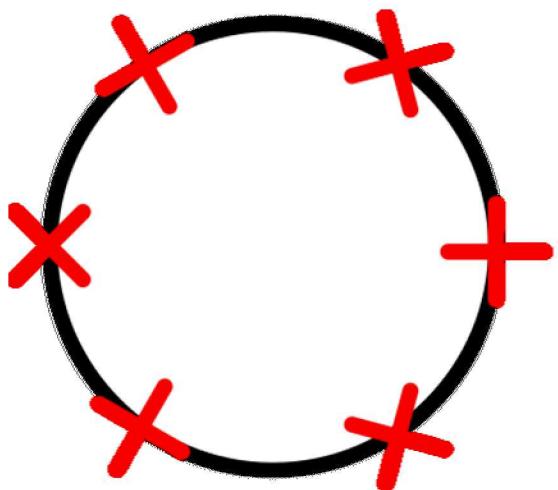
# Partition Gets Ugly Quickly



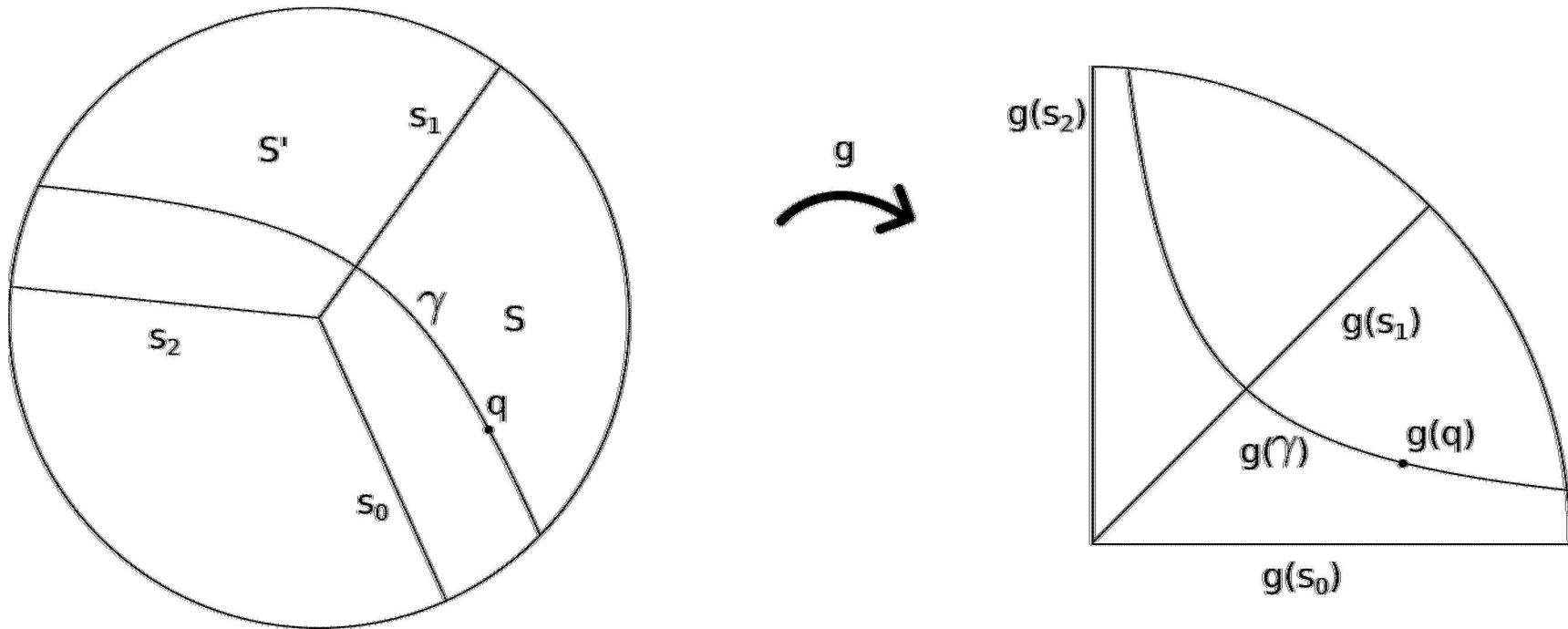
# Hyperbolic Trajectory of Streamlines

# Streamlines Near Singularities

$$f(z) = e^{i(\frac{d\theta}{4} + \frac{2k\pi}{4})} + o(r)$$

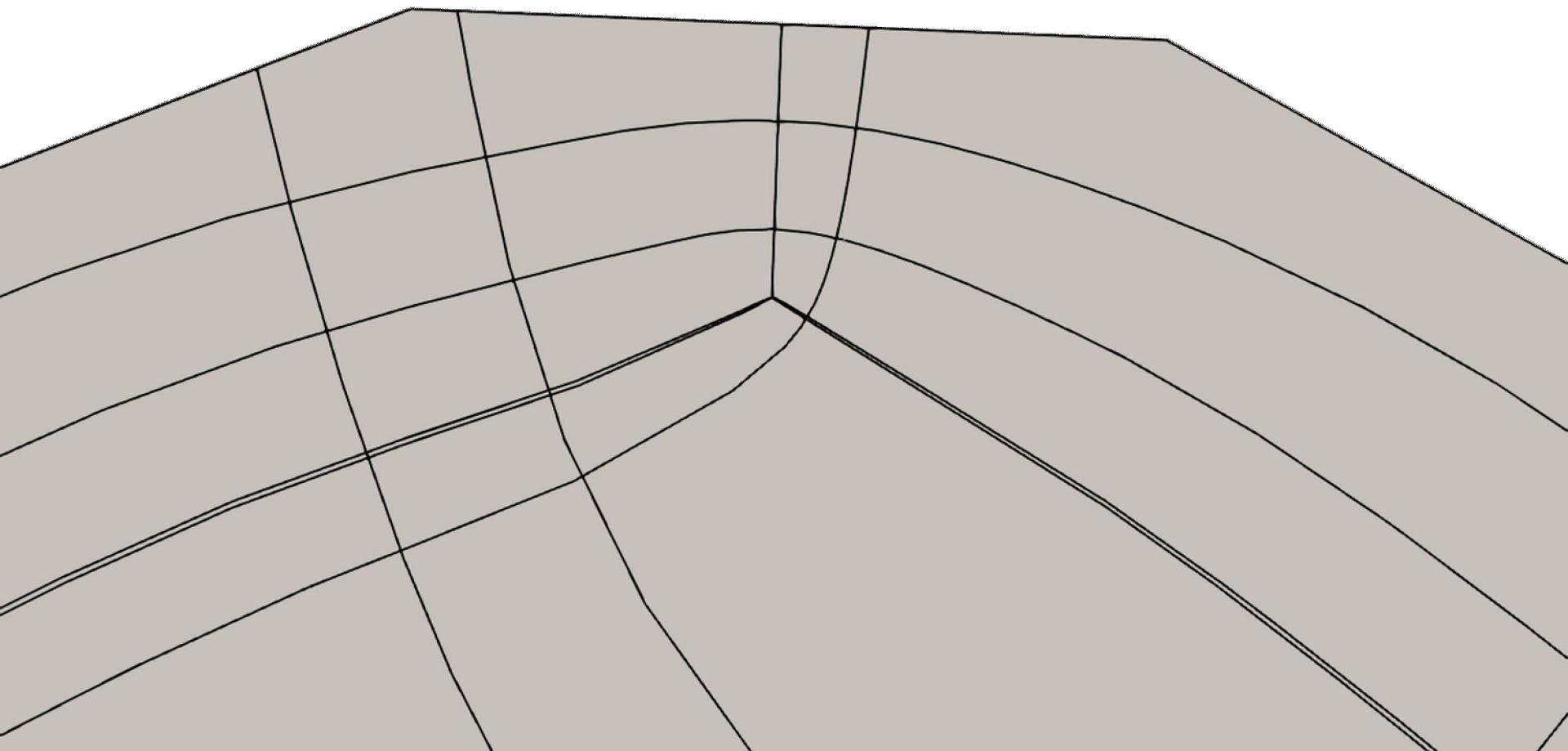


# Streamlines Near Singularities



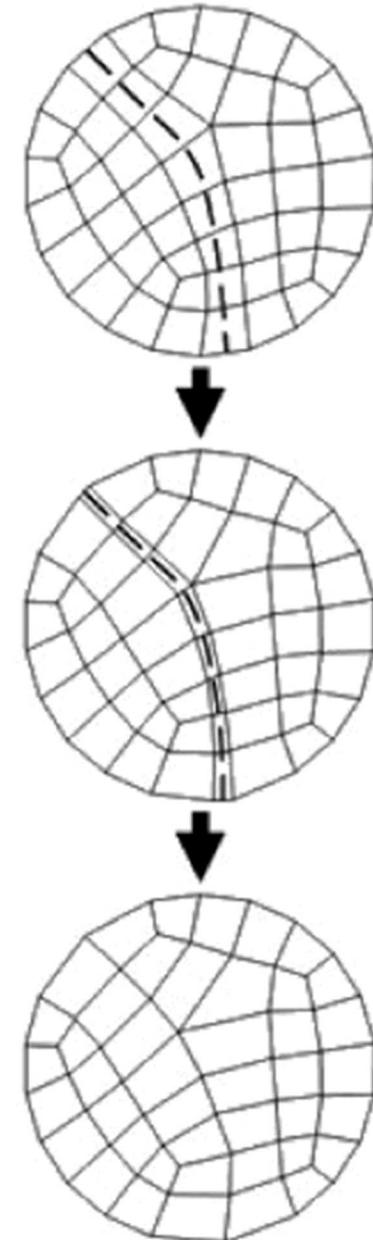
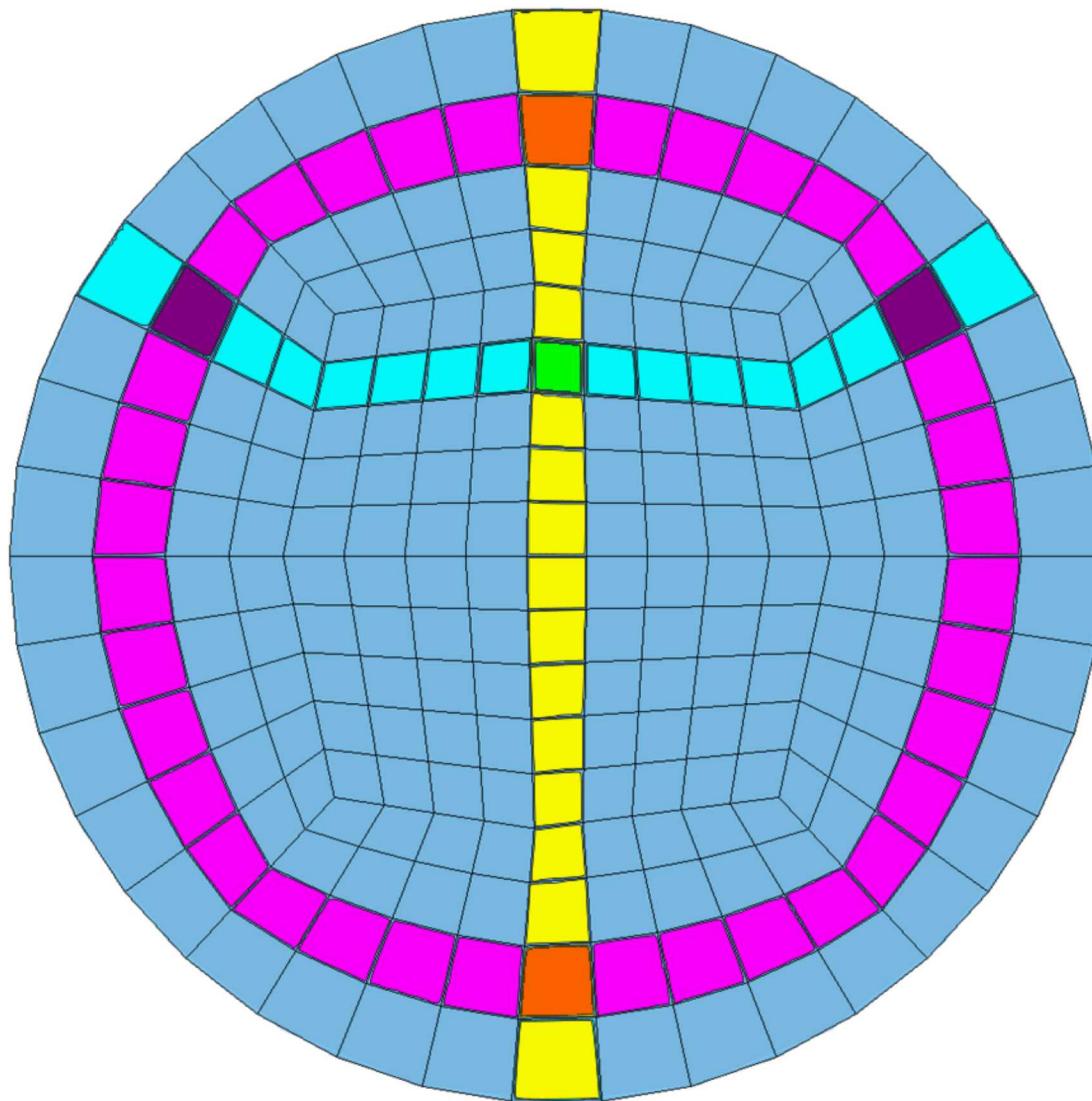
$$g(z) = z^{(4-d)/8}$$

# Streamlines Near Singularities

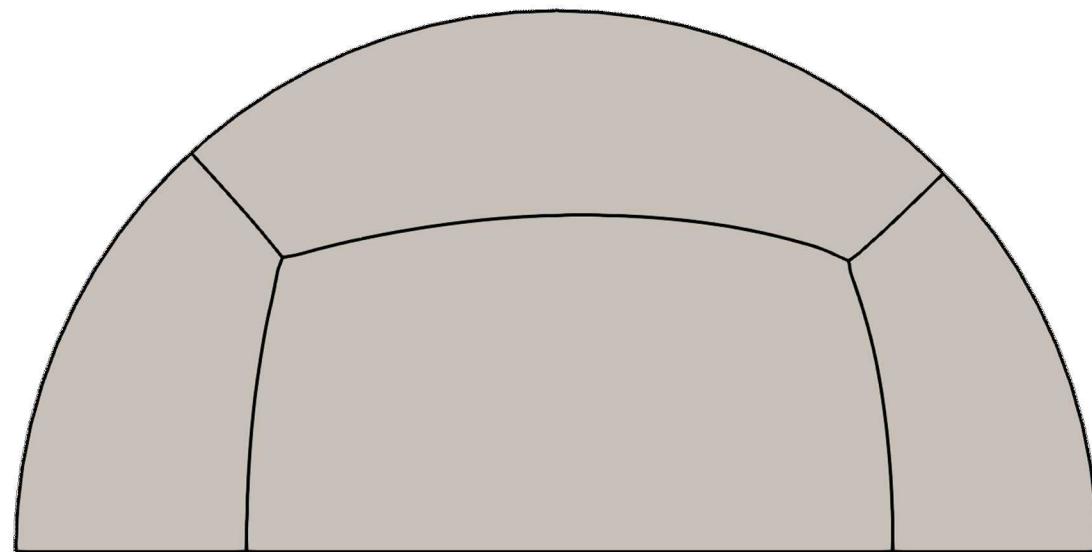
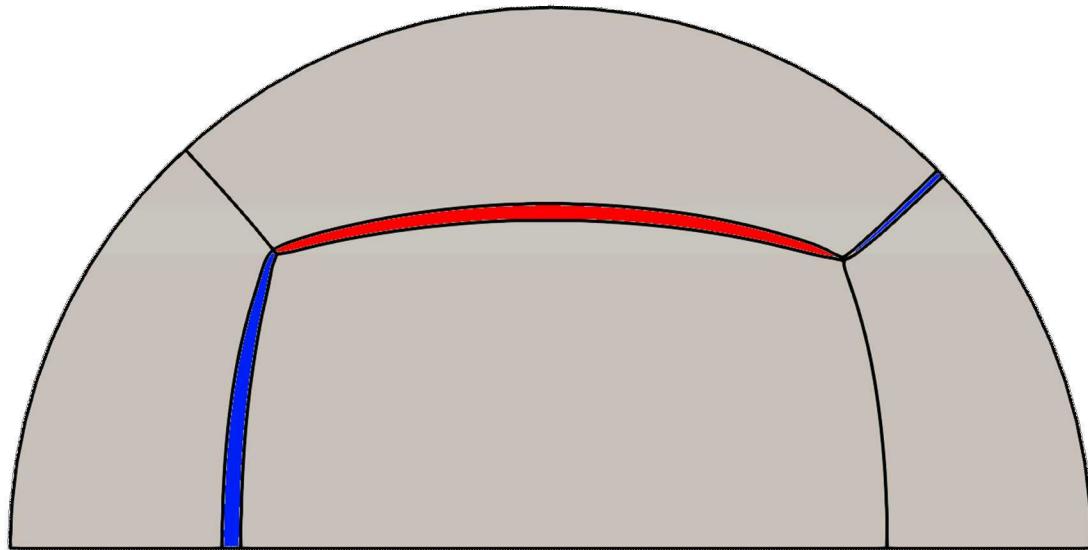


# Partition Simplification

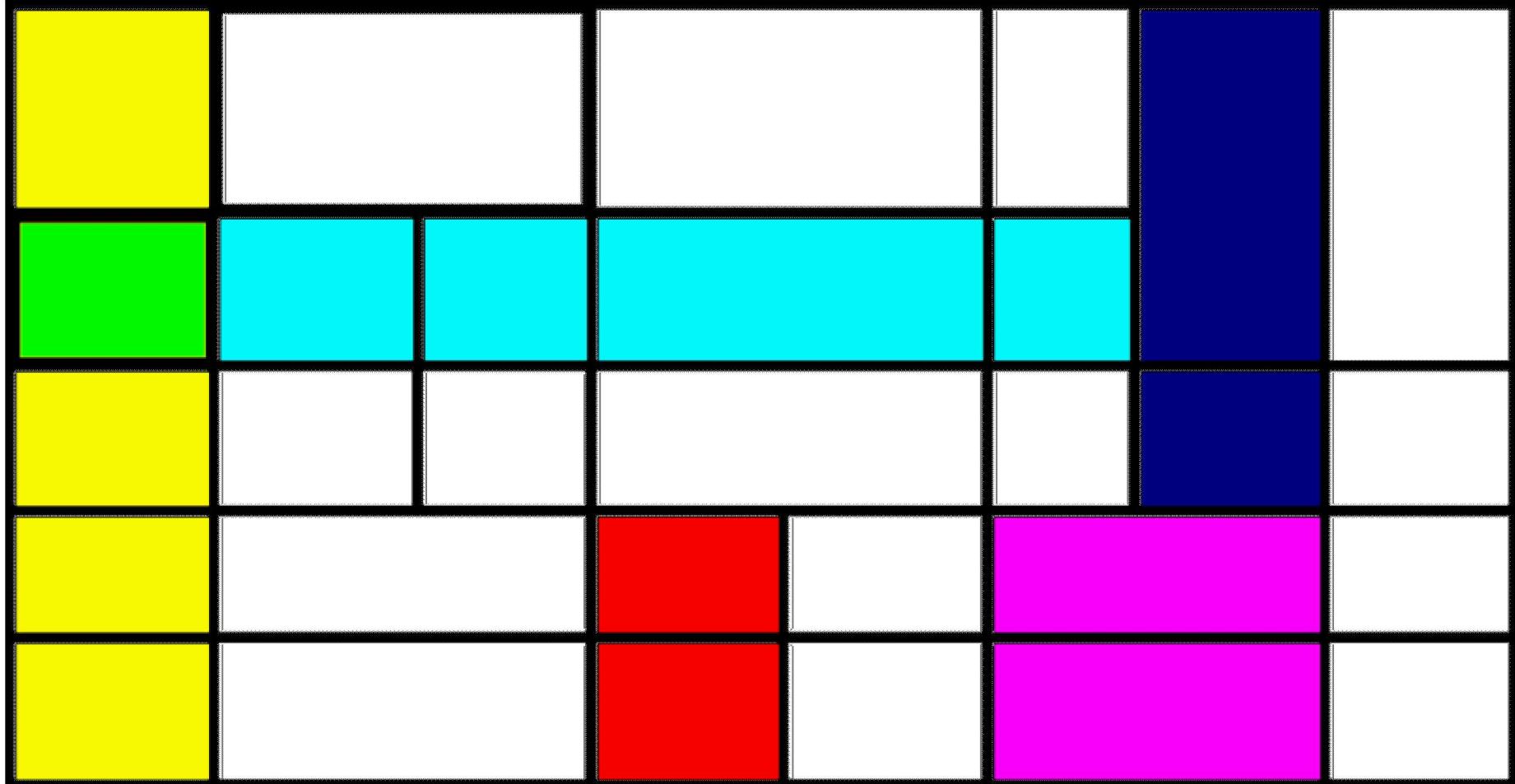
# Chord Collapse



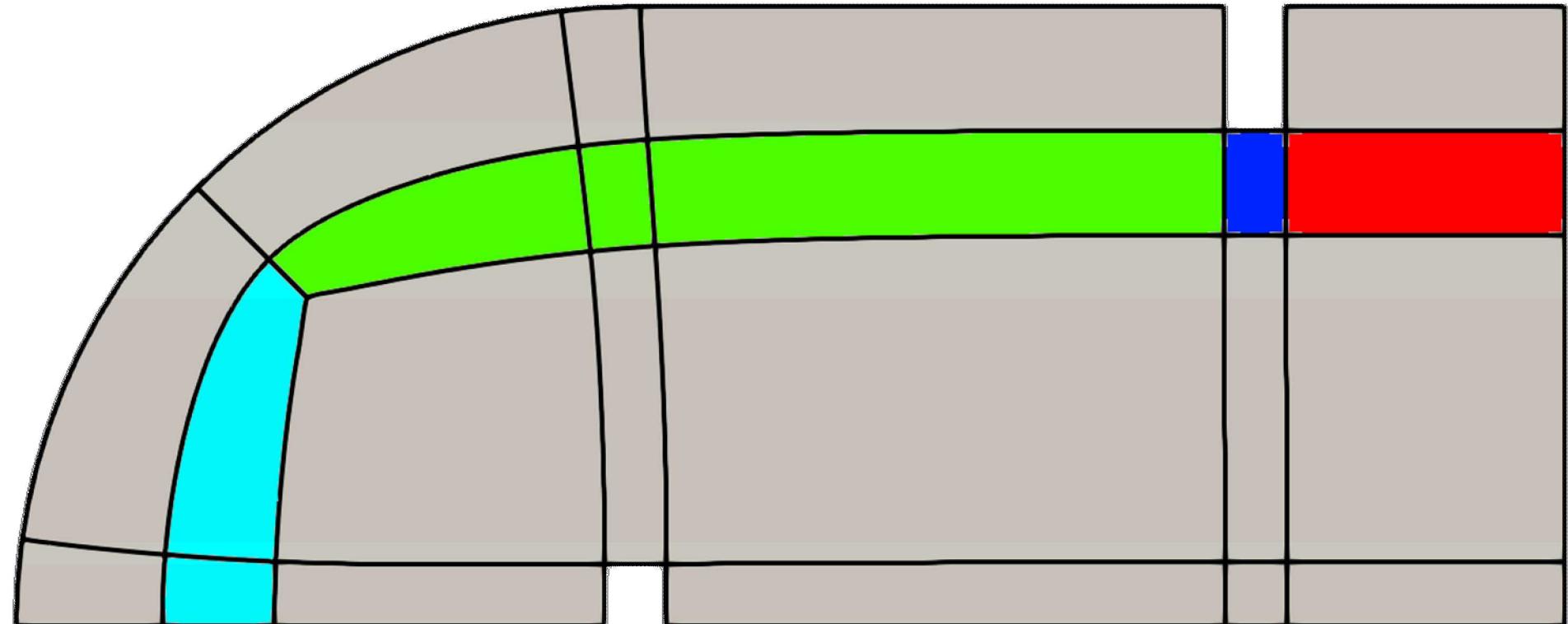
# Chord Collapse



# Chords of a T-layout

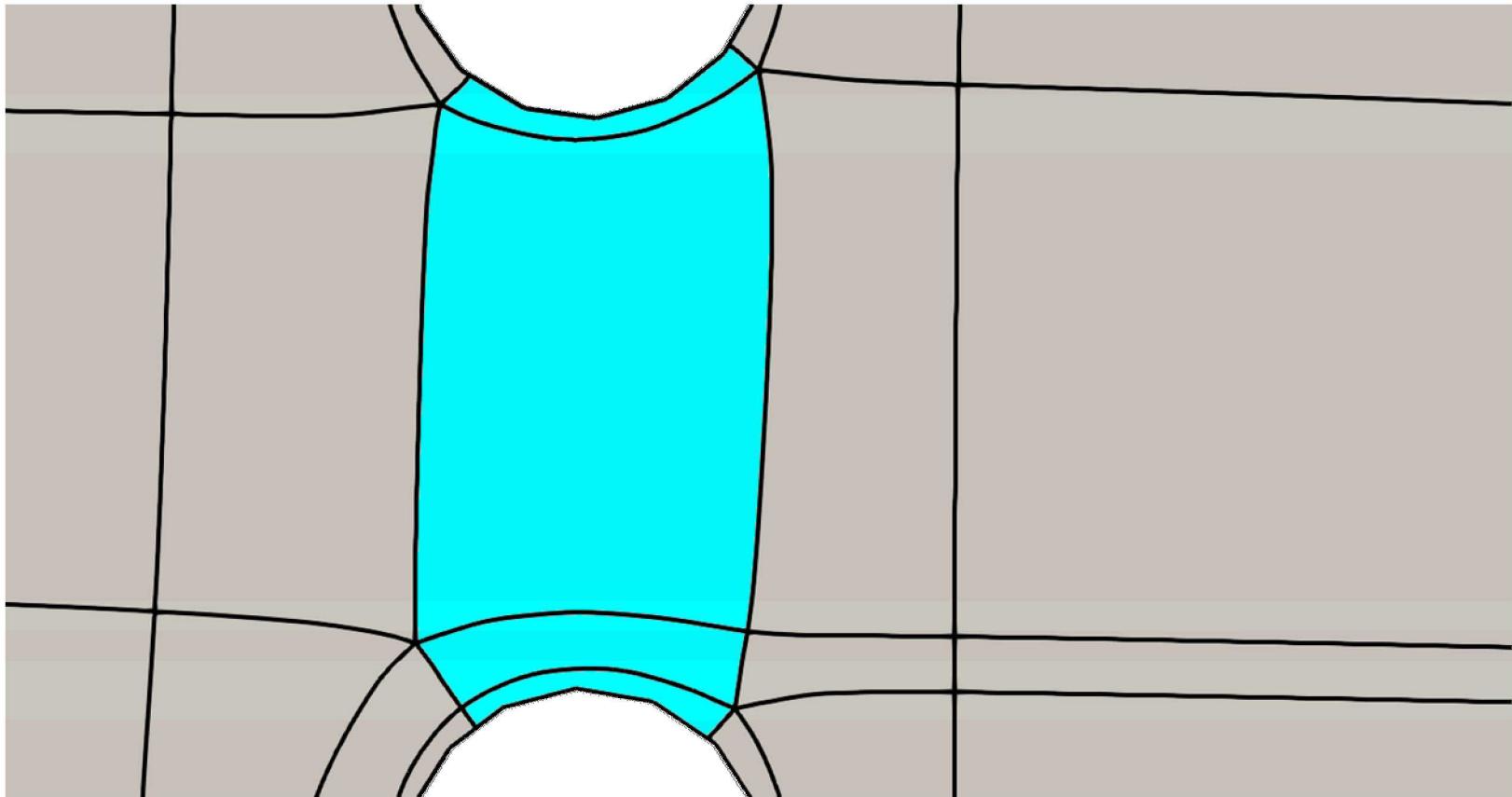


# Patches of a Chord



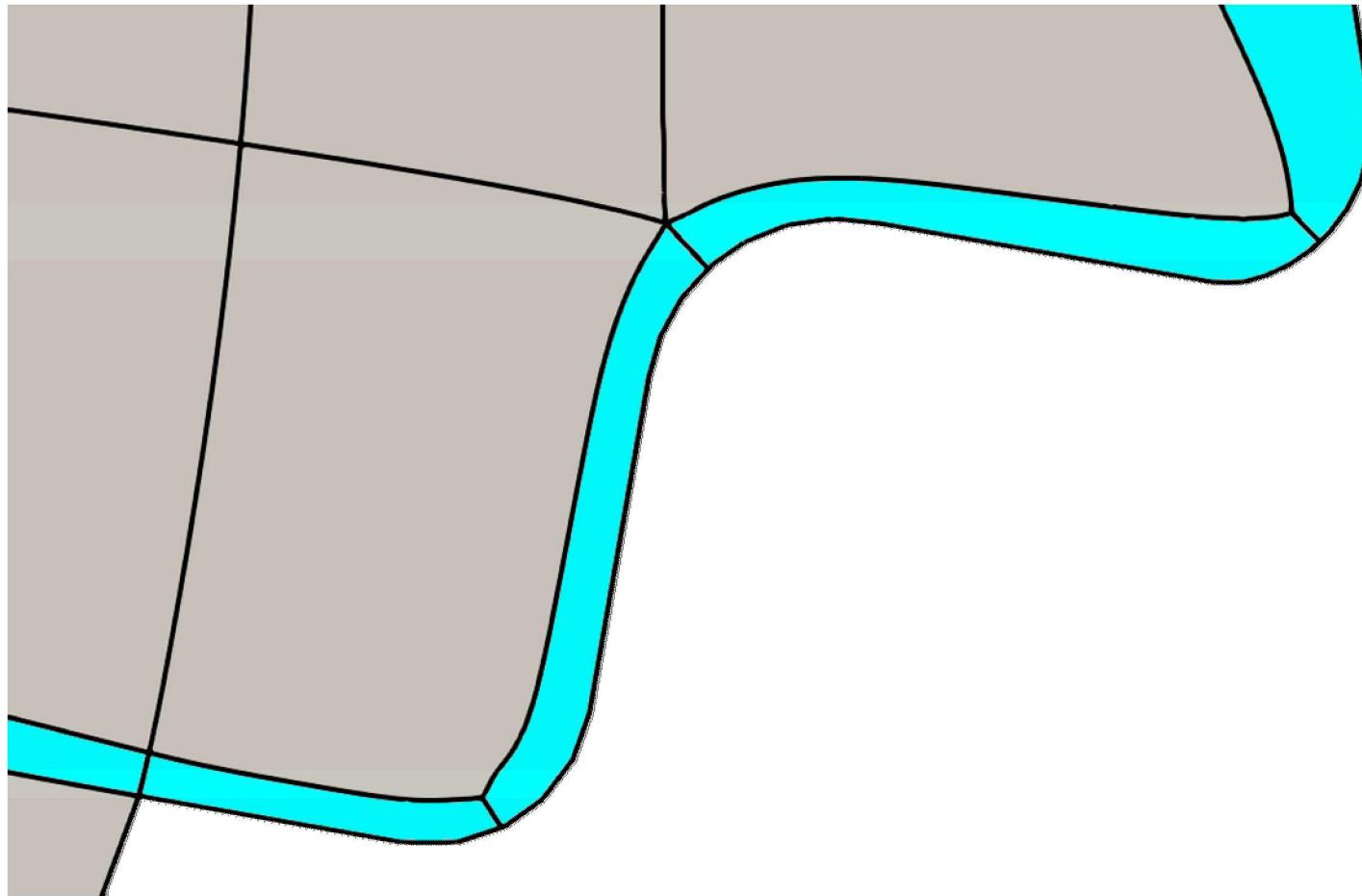
# Collapsible Chords

1. No singularities are connected across any transverse rung of the patch.



# Collapsible Chords

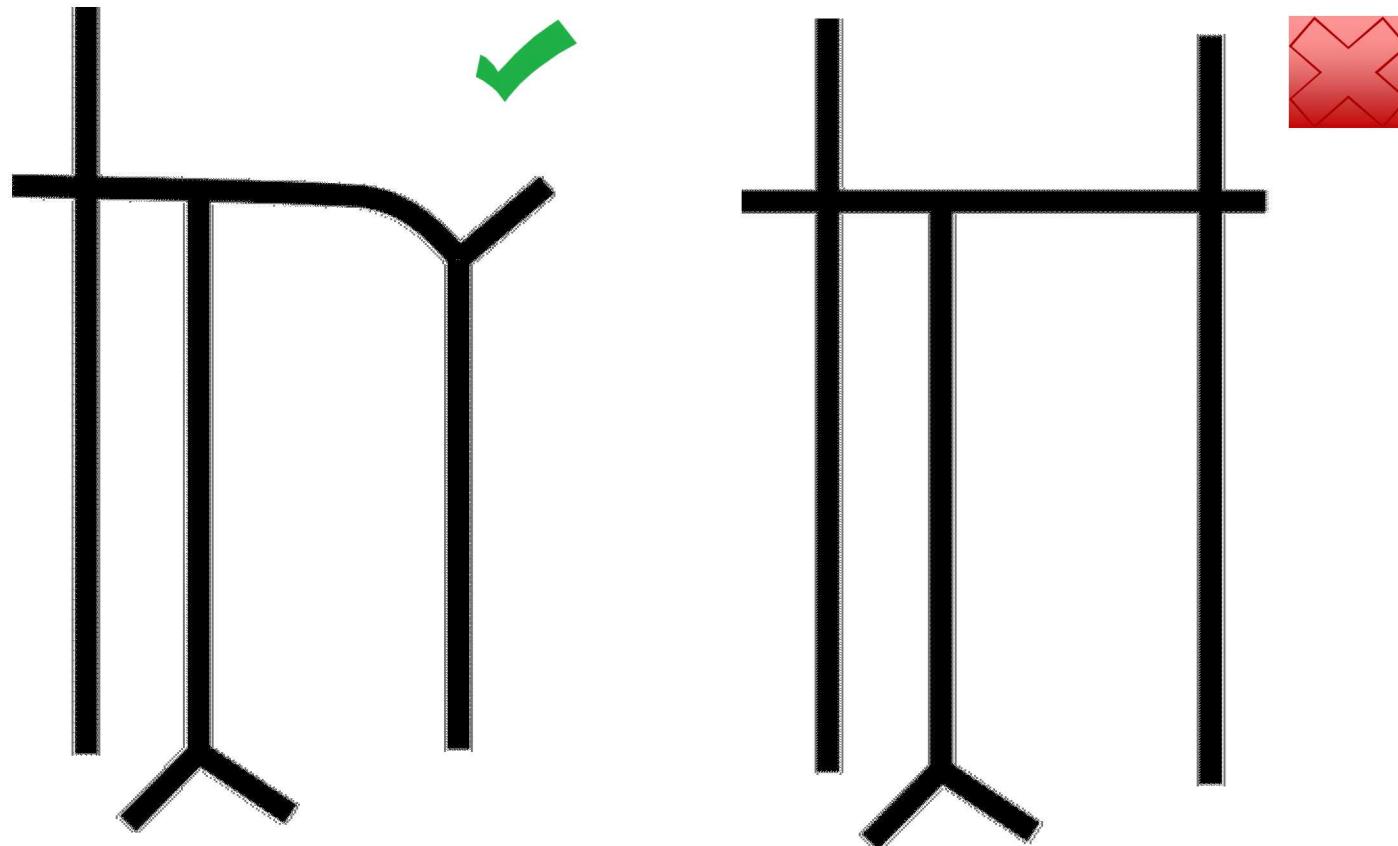
2. No singularity is connected to a boundary across any transverse rung of the patch.



# Collapsible Chords

3. If the patch starts or ends at a T-junction:

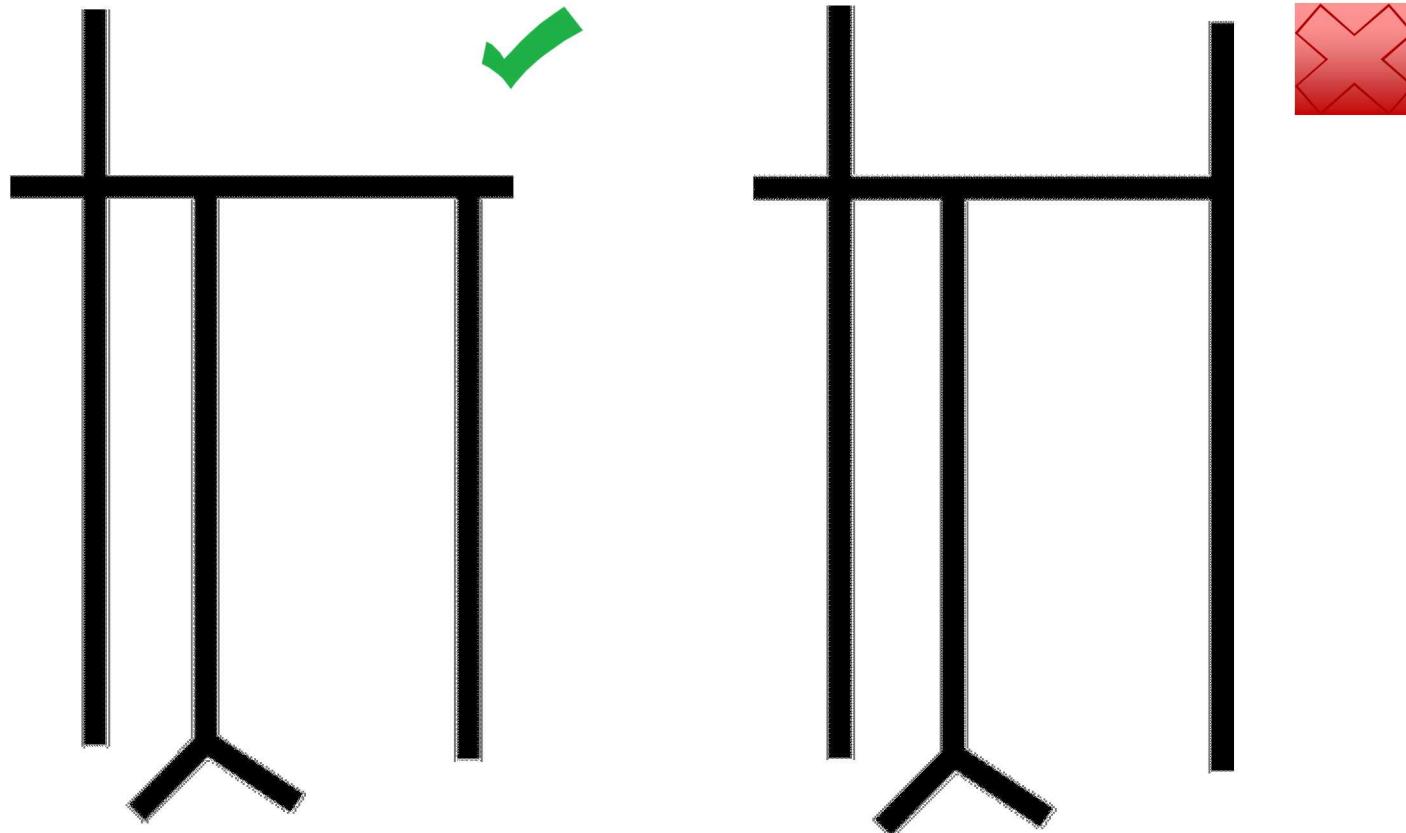
(a) The node opposite the T-junction on the same transverse rung is a singularity.



# Collapsible Chords

### 3. If the patch starts or ends at a T-junction:

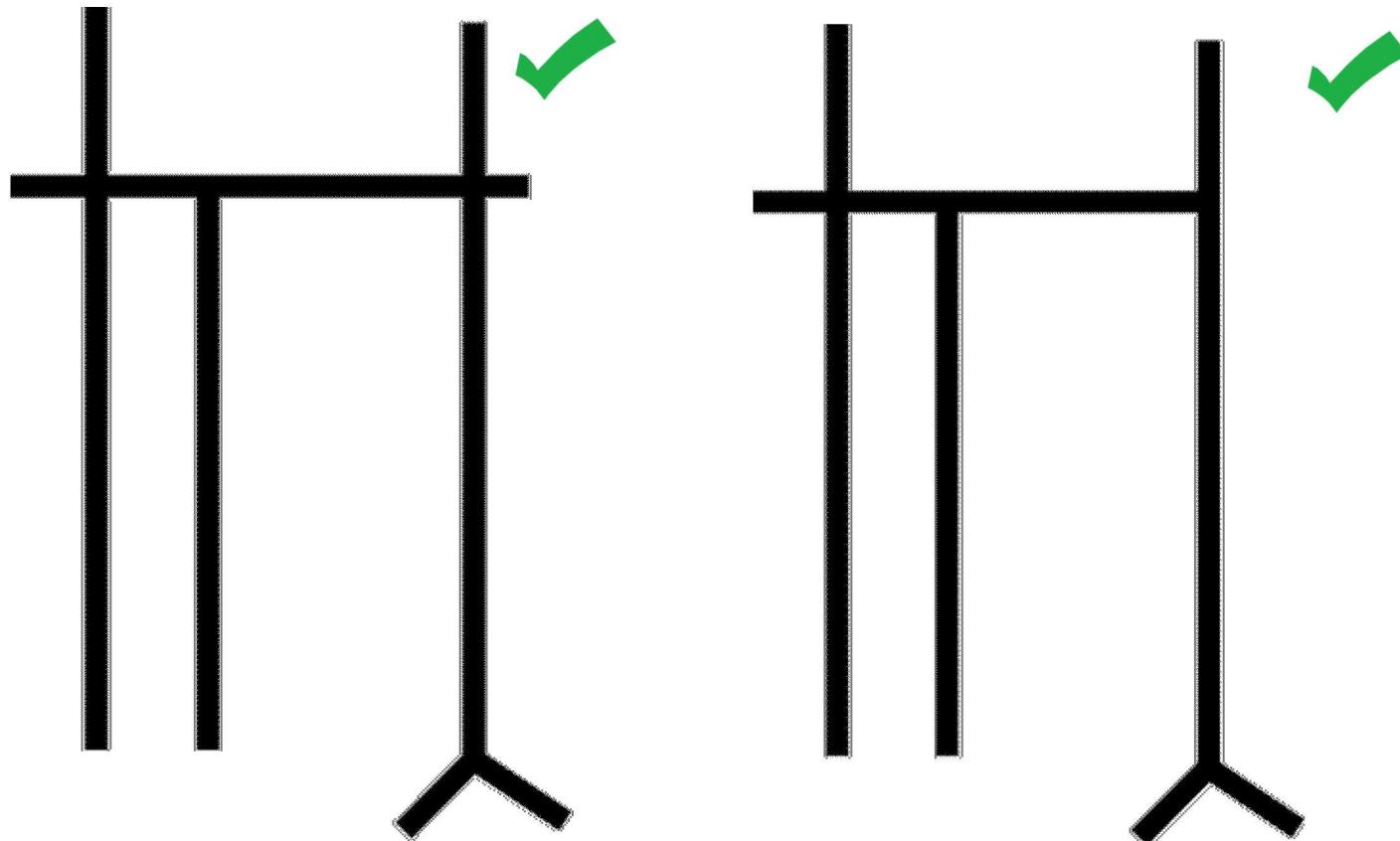
(b) The node opposite the T-junction on the same transverse rung is another T-junction with the same orientation.



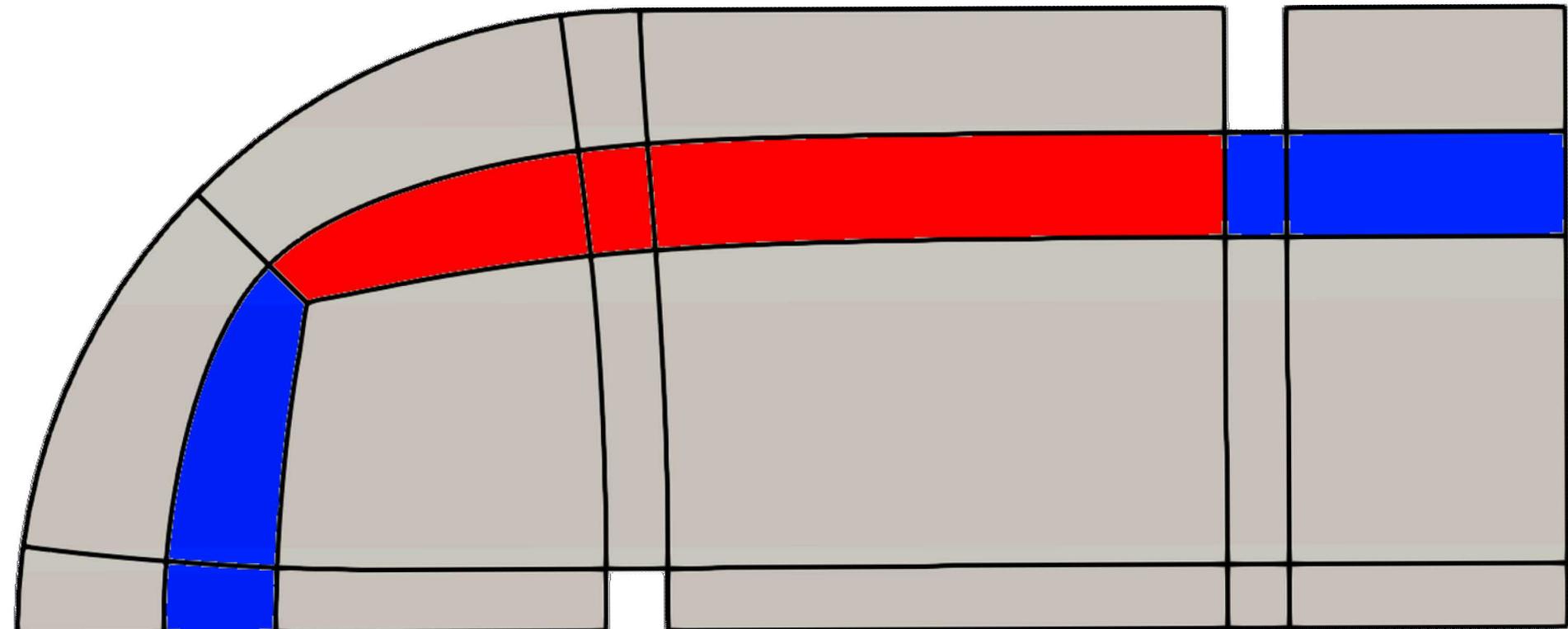
# Collapsible Chords

3. If the patch starts or ends at a T-junction:

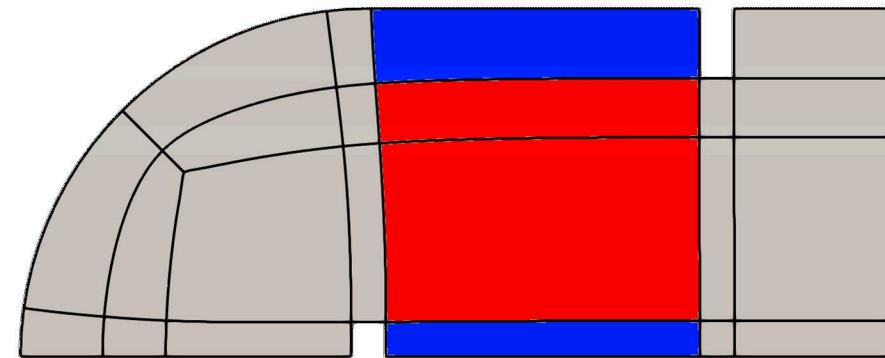
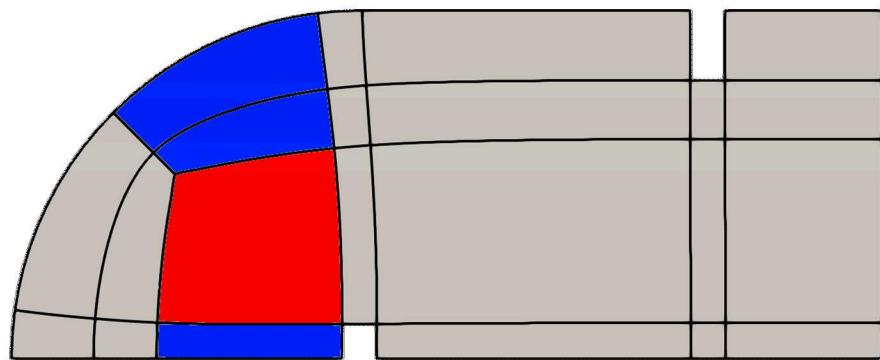
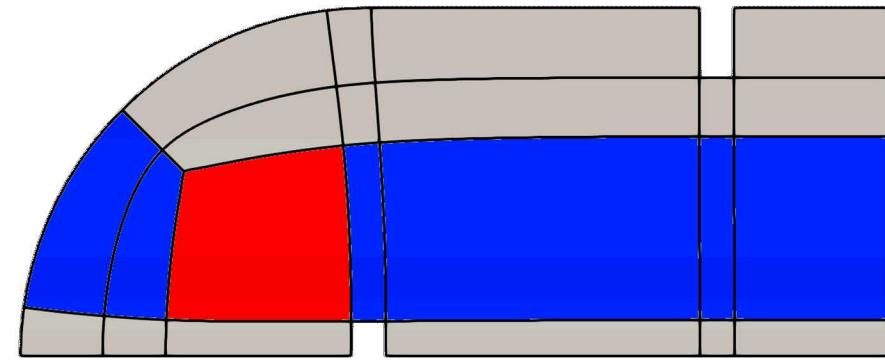
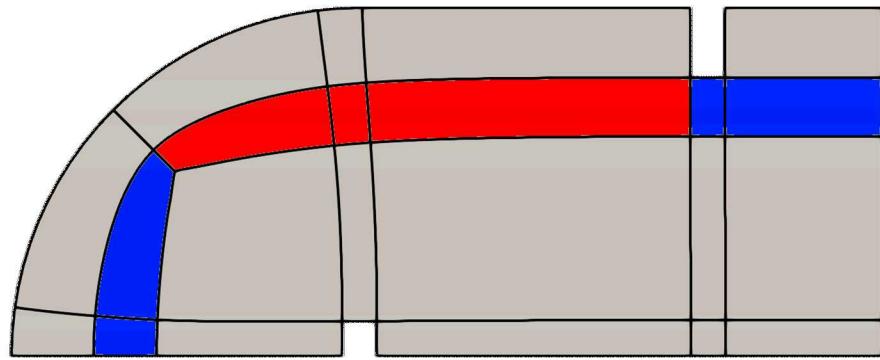
(c) The node on the opposite corner of the patch from the T-junction is a singularity.



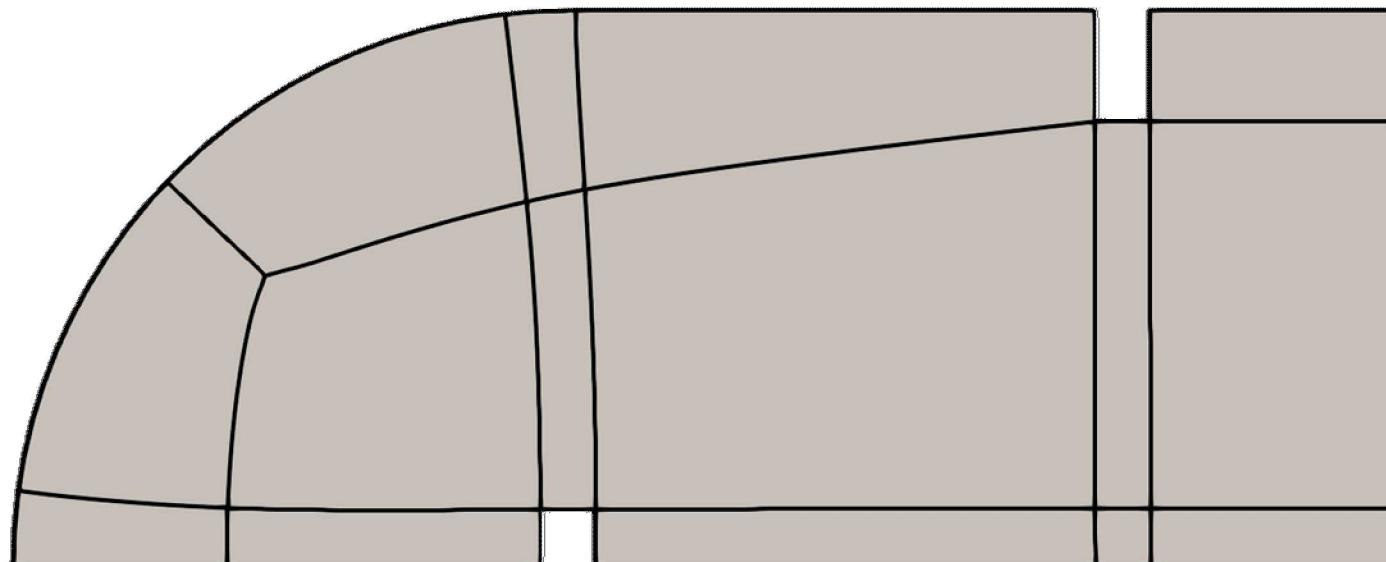
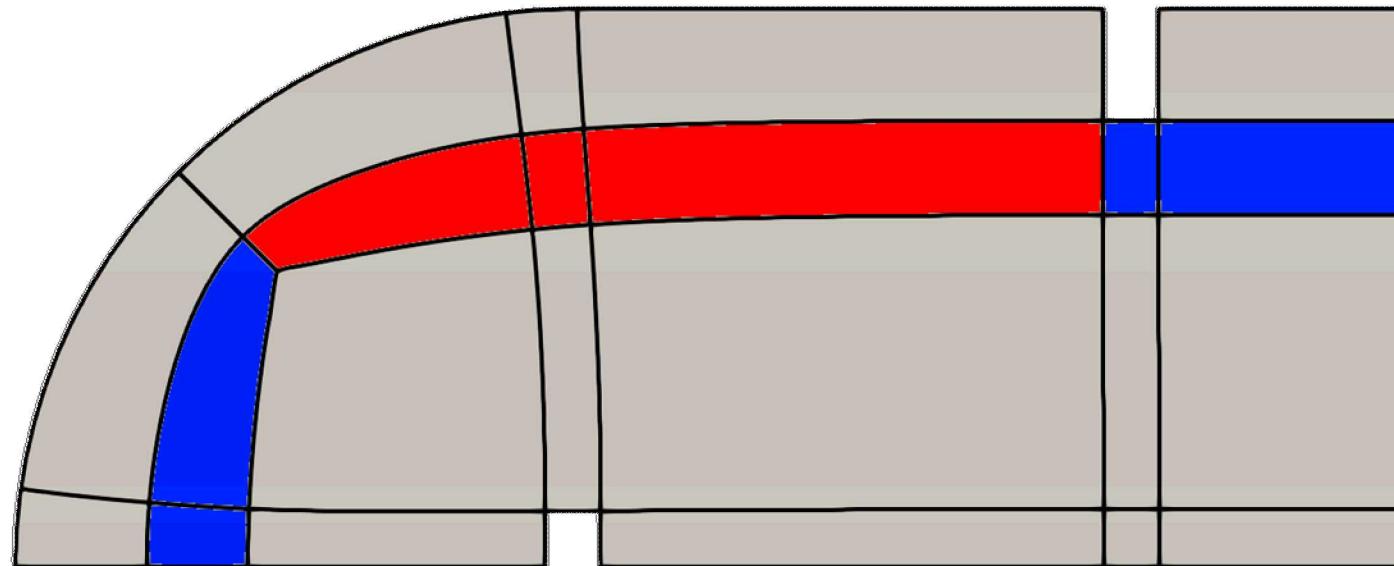
# Zip and Non-Zip Patches



# Collapsible Chords



# Collapse Operation



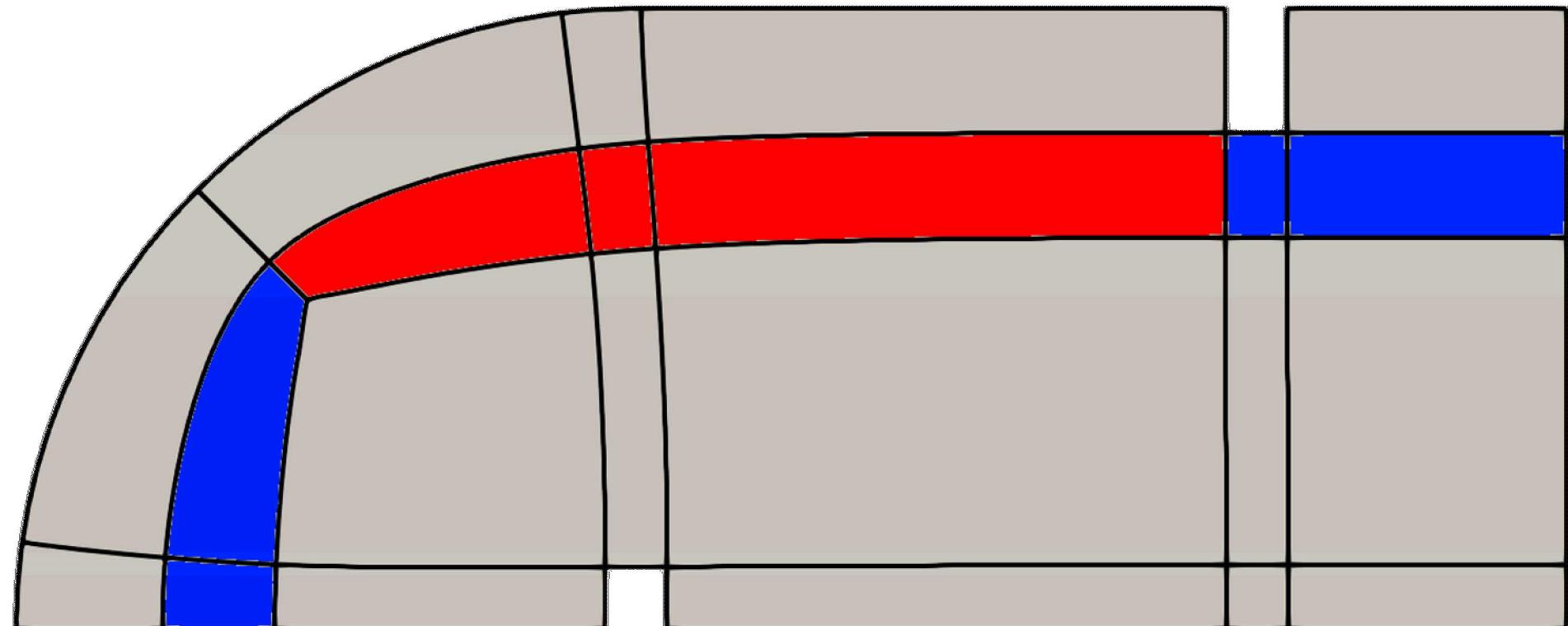
# Condition for Collapse

Collapse if:  $E > 0$

$$E = \min_{p \in C} E_p$$

$$E_{zip} = \frac{\pi}{8} - \tan^{-1} \frac{w}{l}$$

$$E_{nozip} = 1$$



# Collapse Algorithm

---

## Algorithm 3 Partition Simplification

---

Let  $\Gamma$  be the set of collapsible chords of the partition

**while**  $|\Gamma| > 0$  **do**

**if** No chords meet the conditions for collapse **then**

**Stop.**

**else**

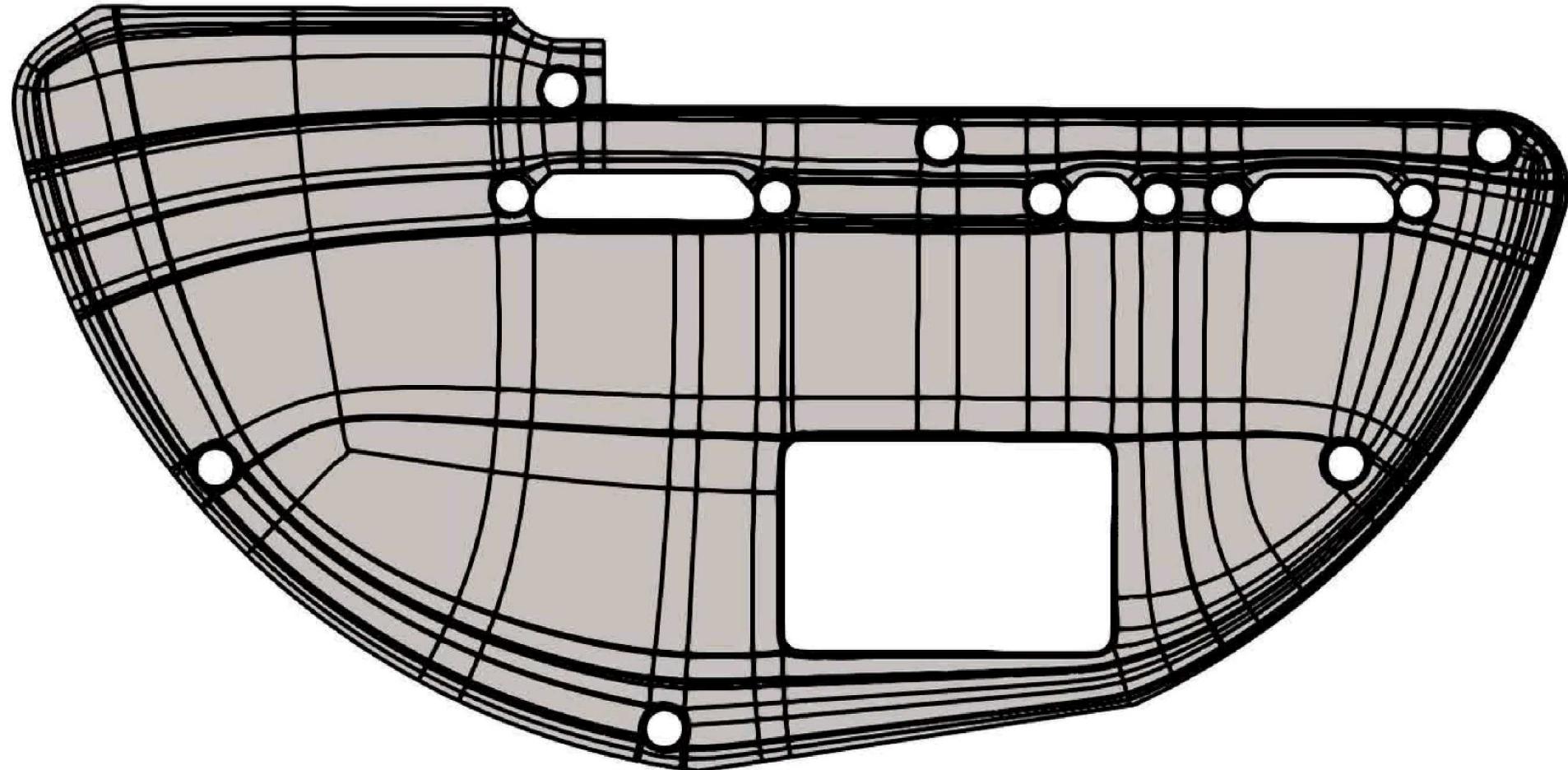
        Collapse the chord with the smallest minimum width

        Determine new set of collapsible chords  $\Gamma$

**end if**

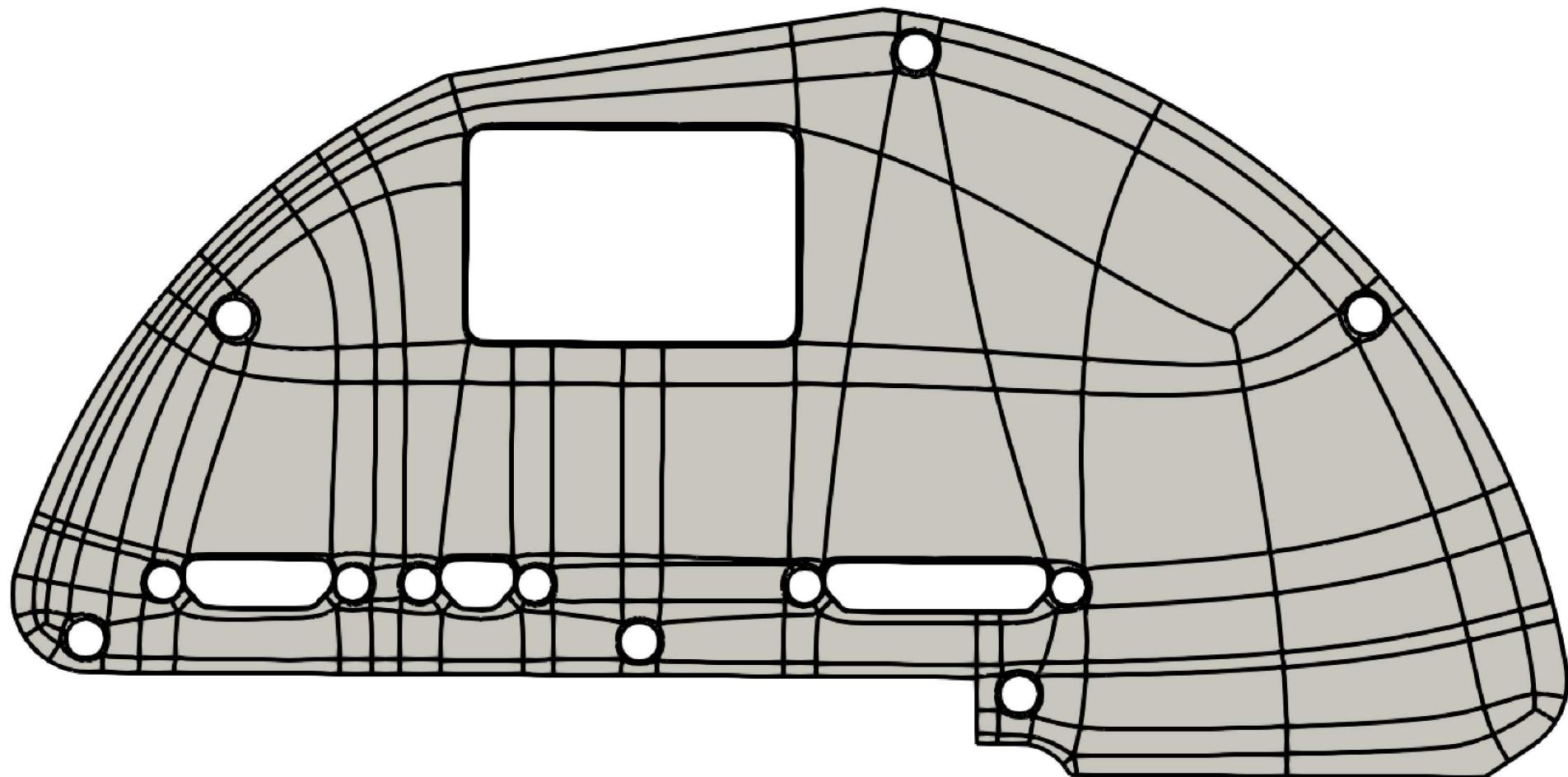
**end while**

---

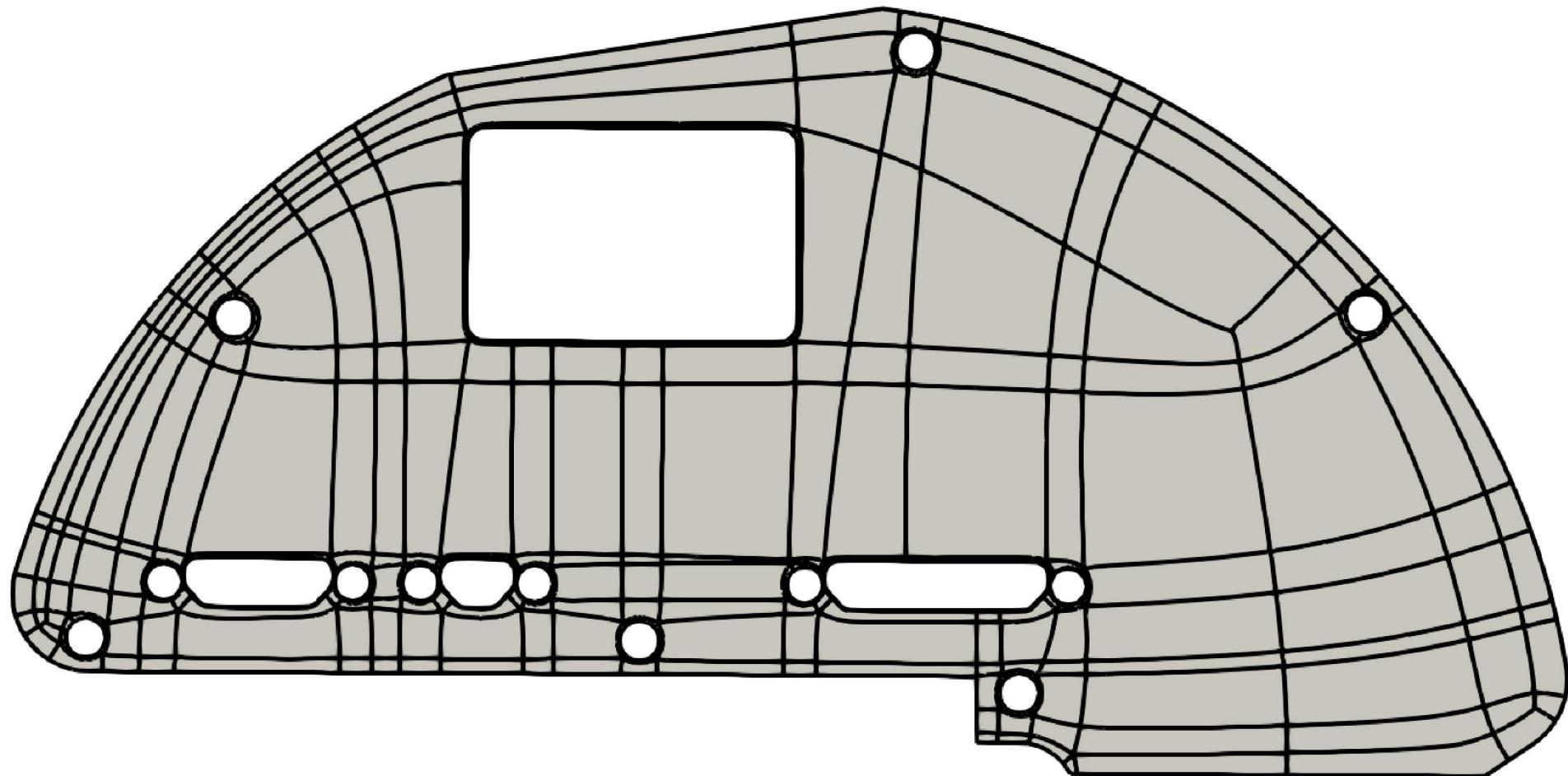


Collapse Algorithm

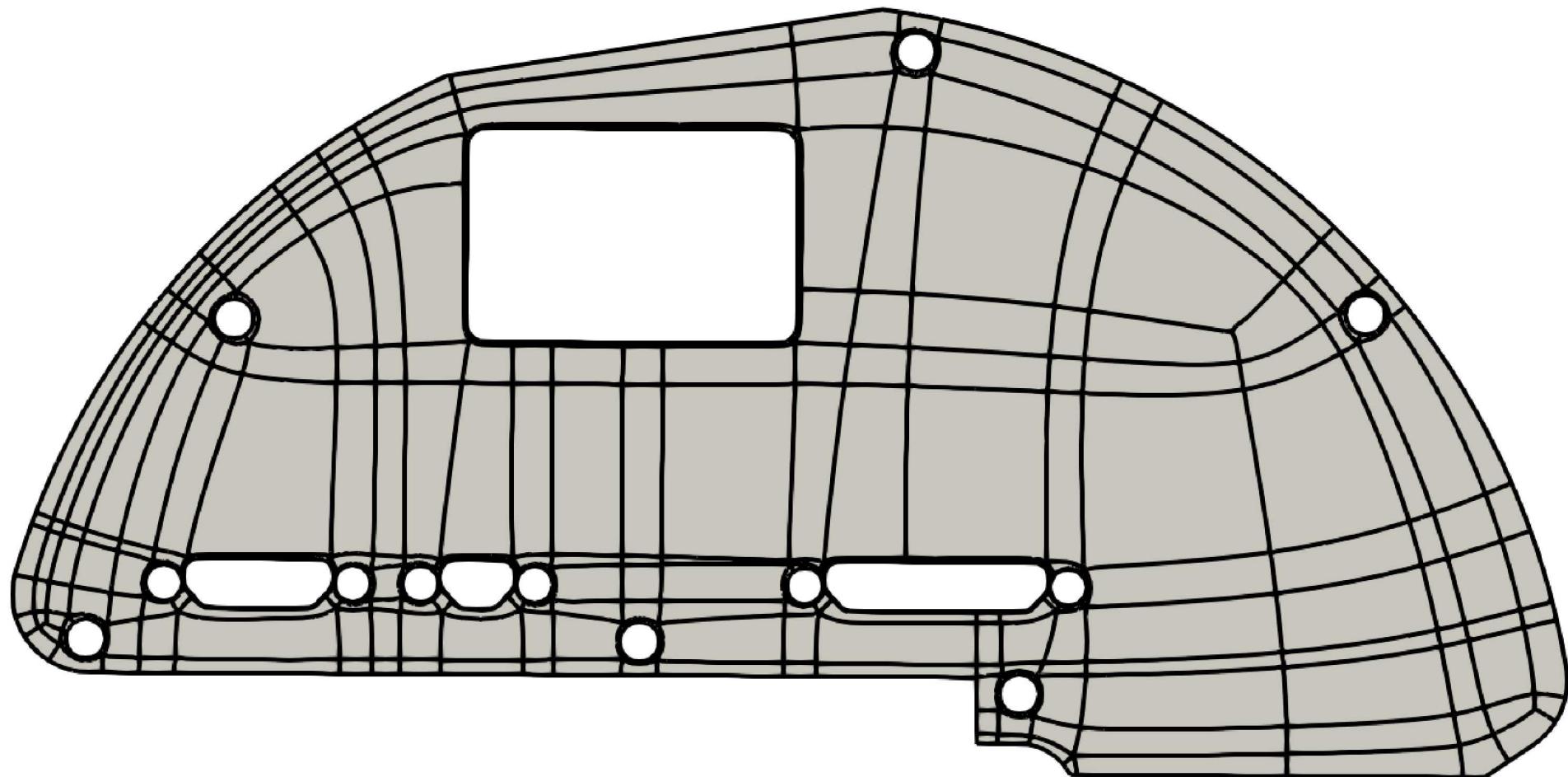
# Collapse Algorithm



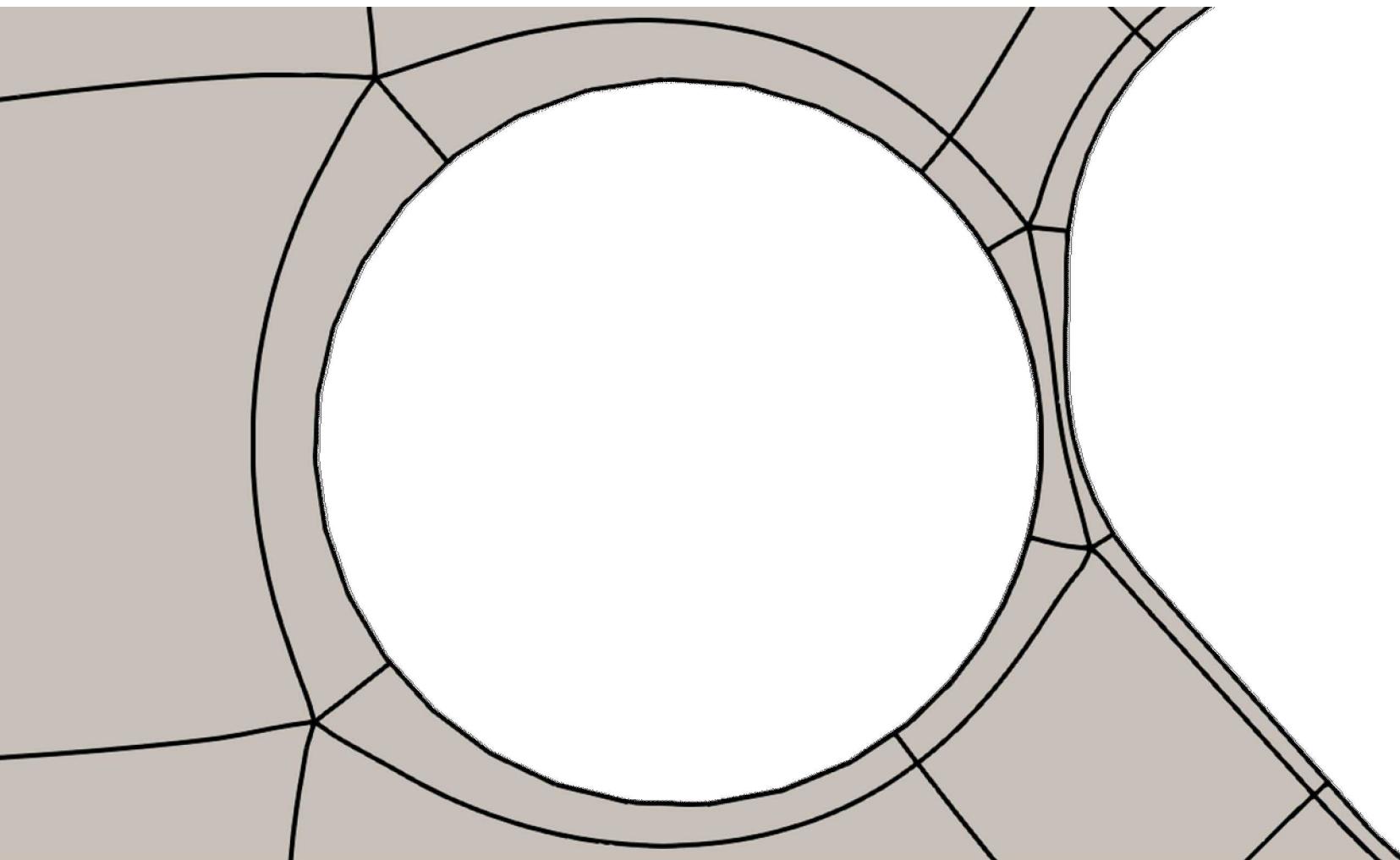
# Collapse Algorithm



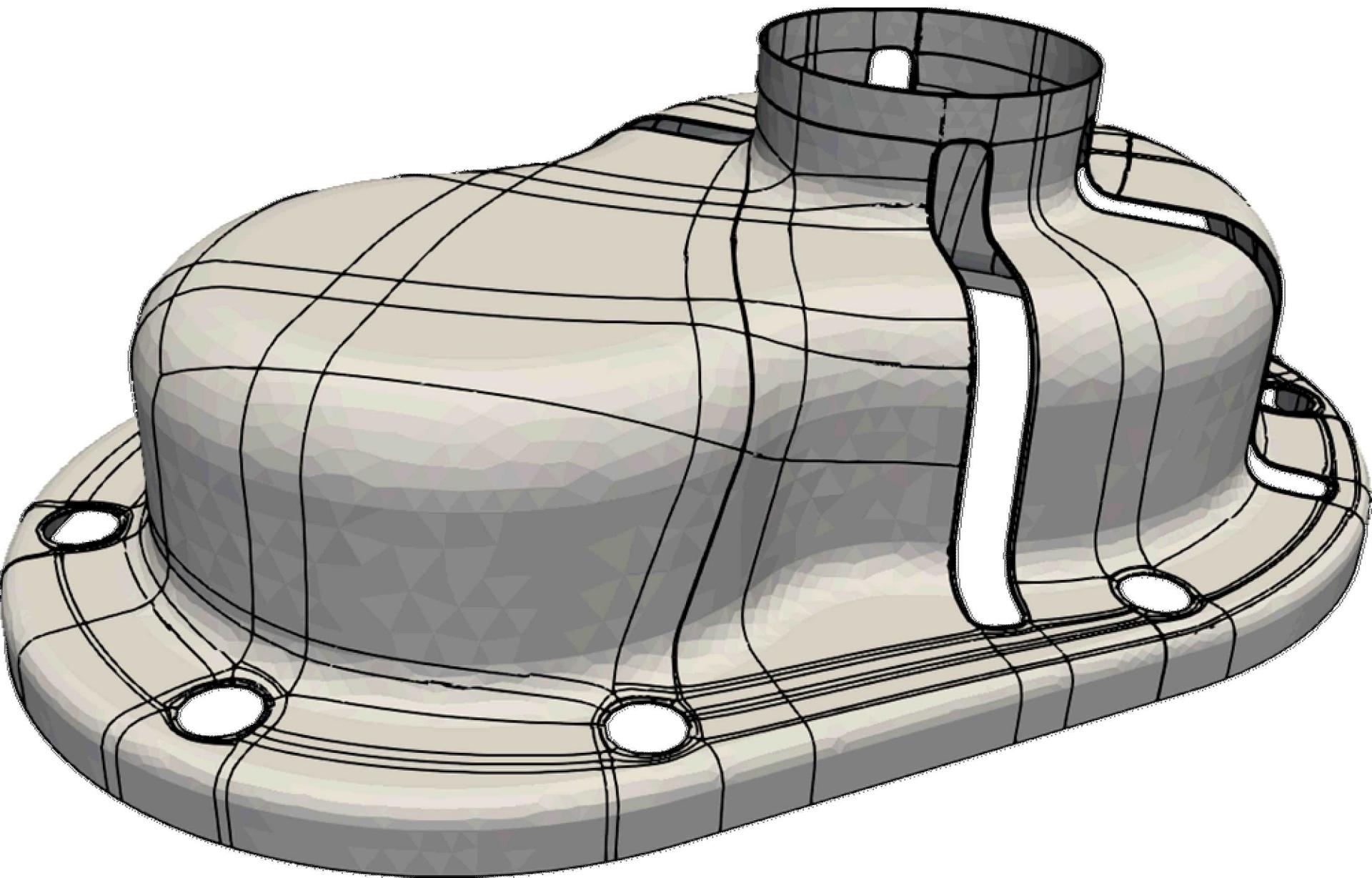
# Collapse Algorithm



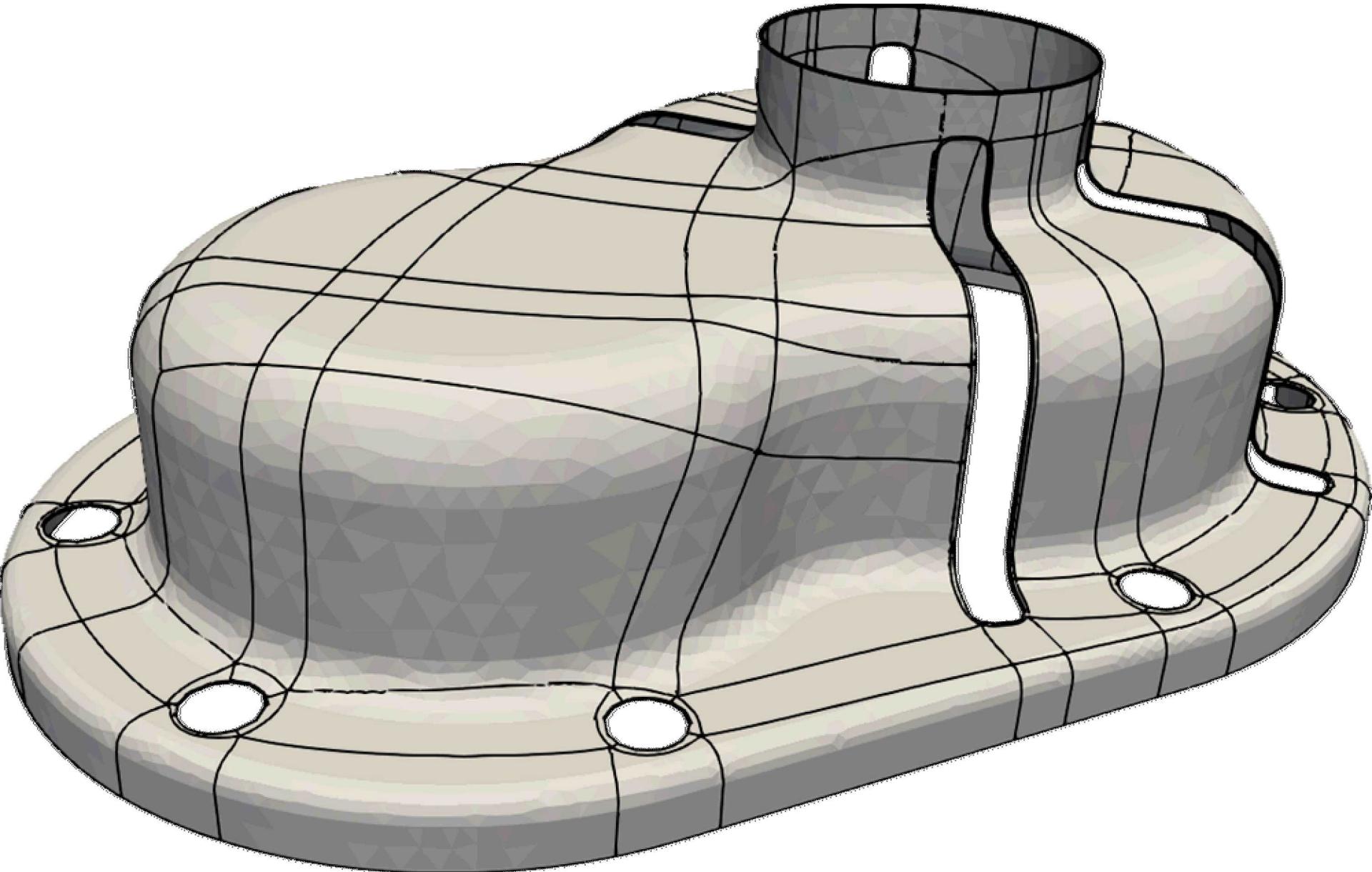
# Collapse Algorithm



# Partition Simplification on Surfaces



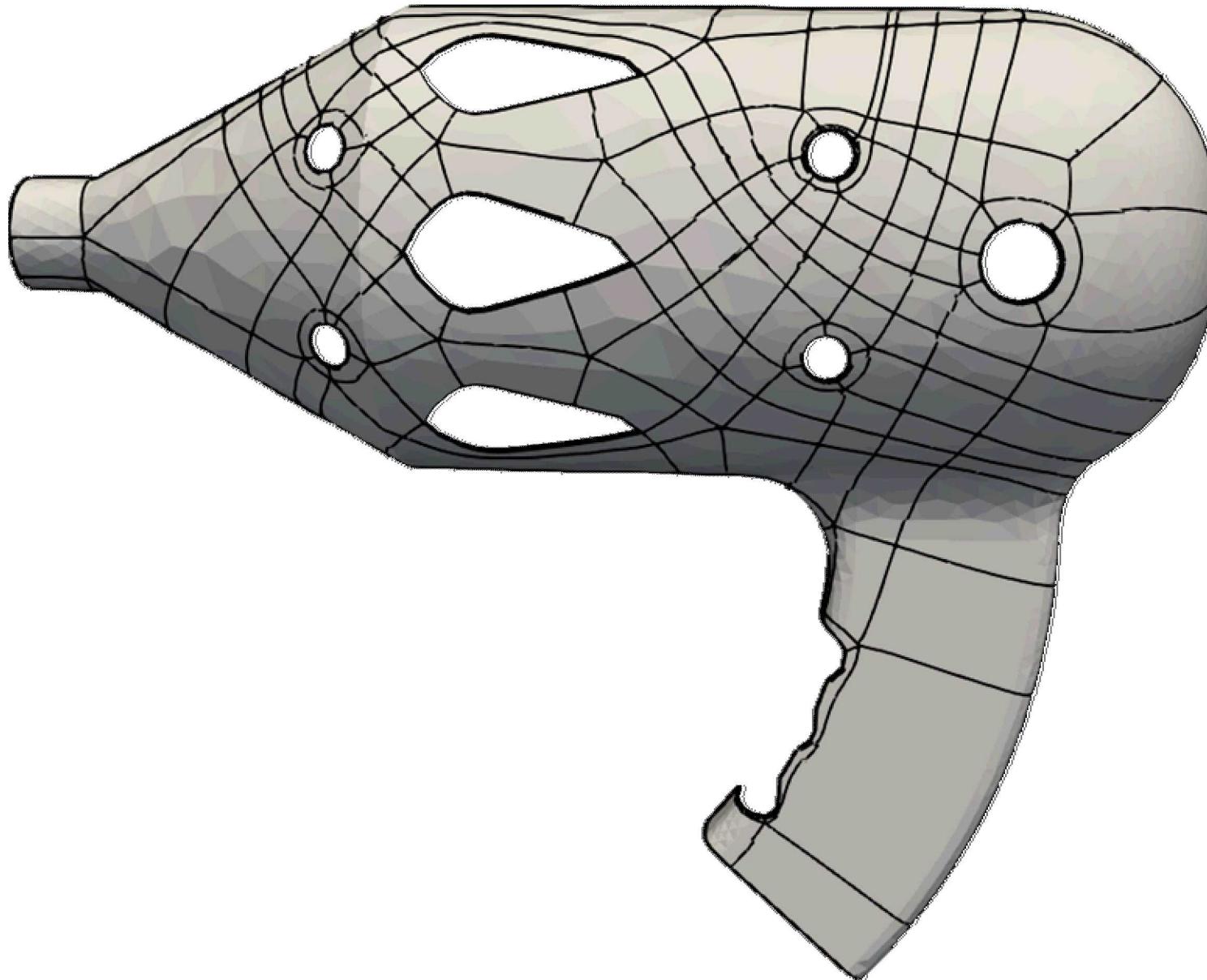
# Partition Simplification on Surfaces



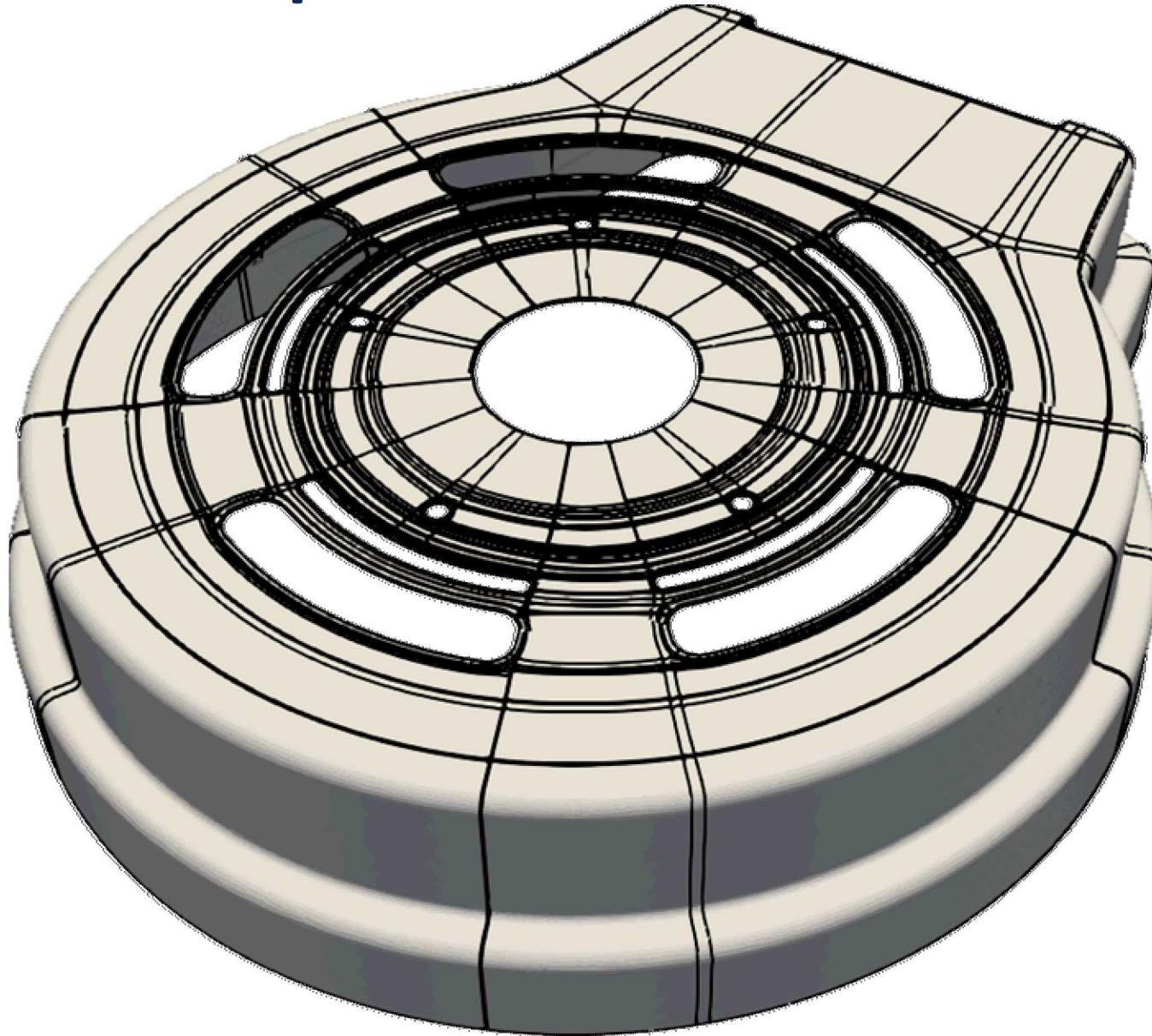
# Partition Simplification on Surfaces



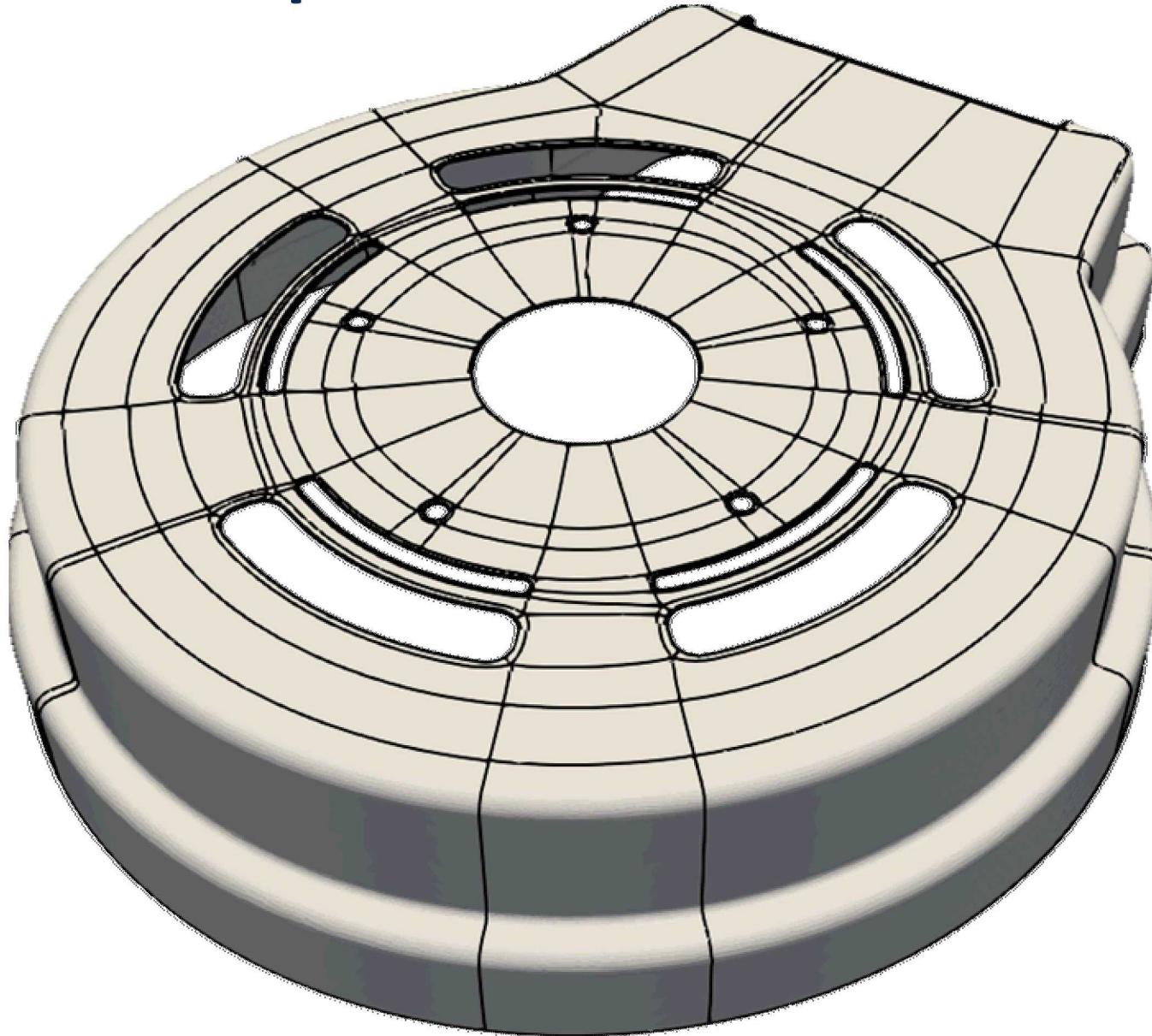
# Partition Simplification on Surfaces



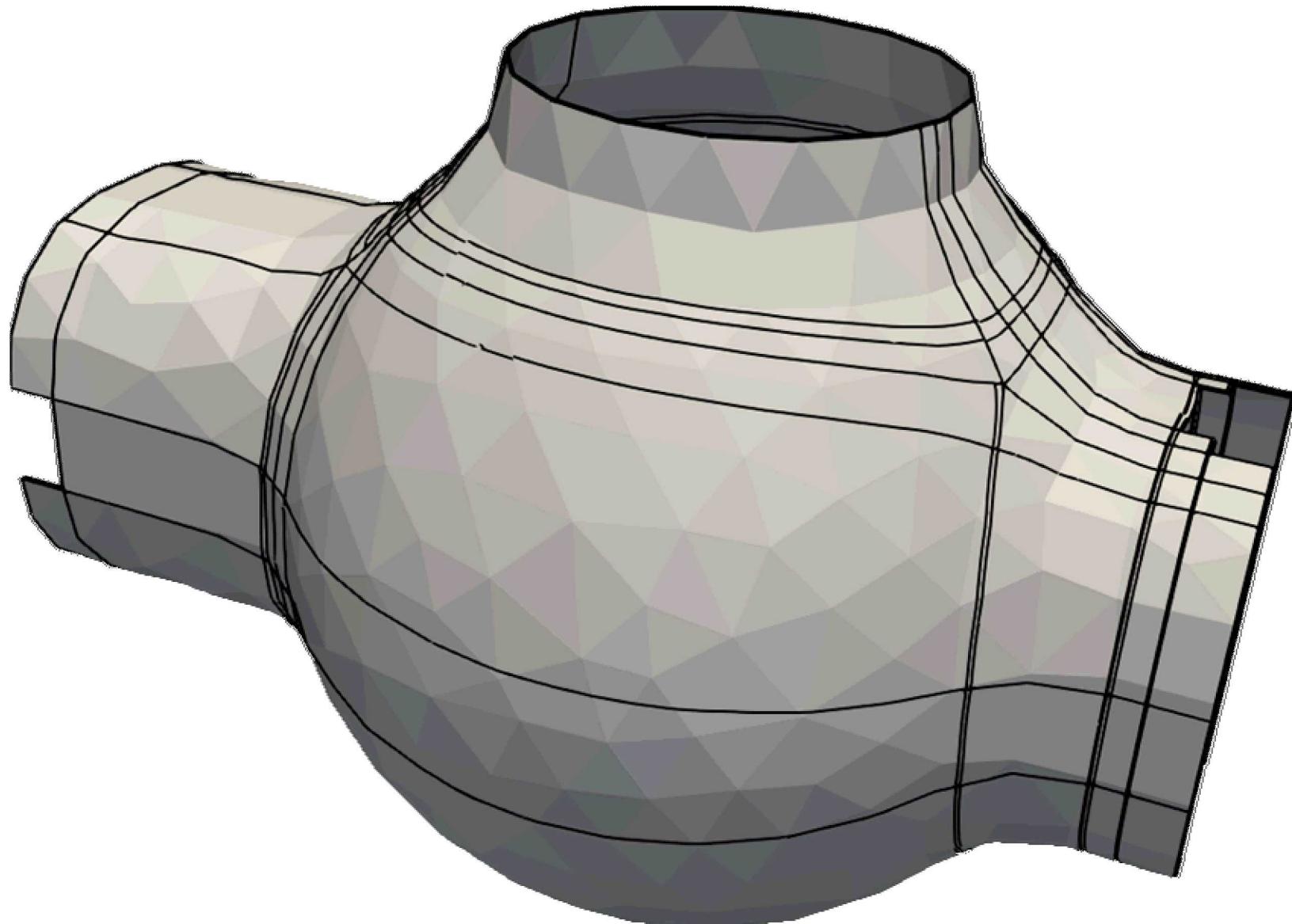
# Partition Simplification on Surfaces



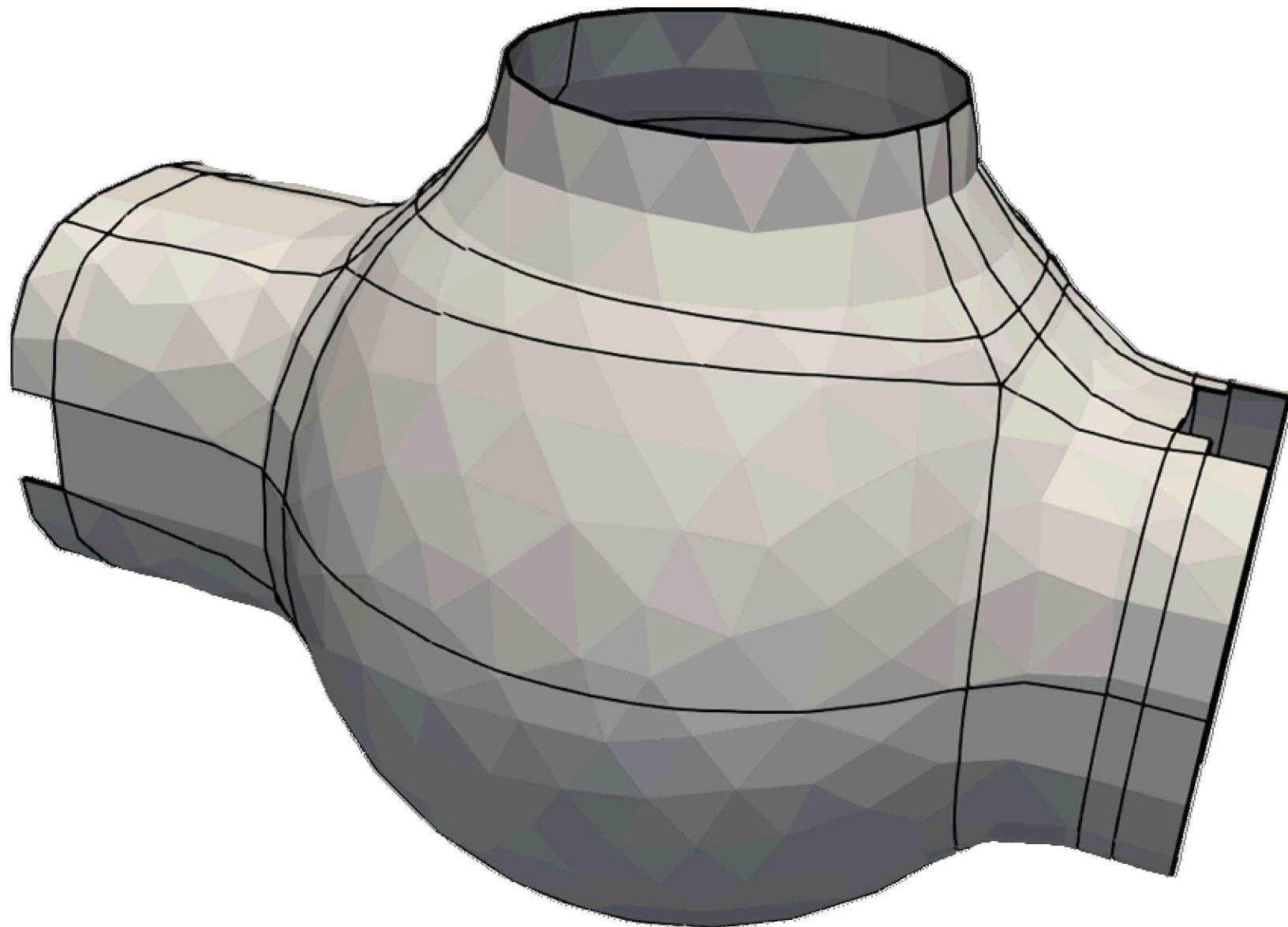
# Partition Simplification on Surfaces



# Partition Simplification on Surfaces



# Partition Simplification on Surfaces

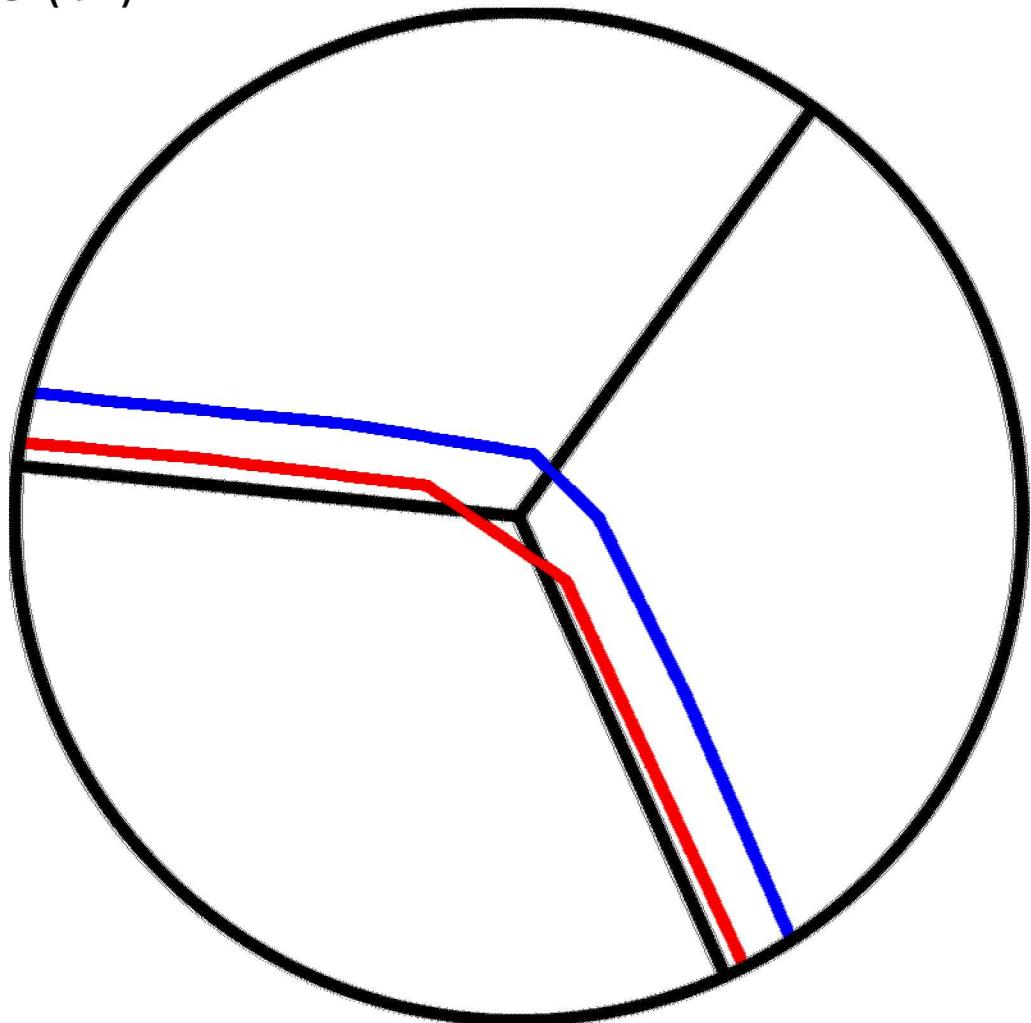
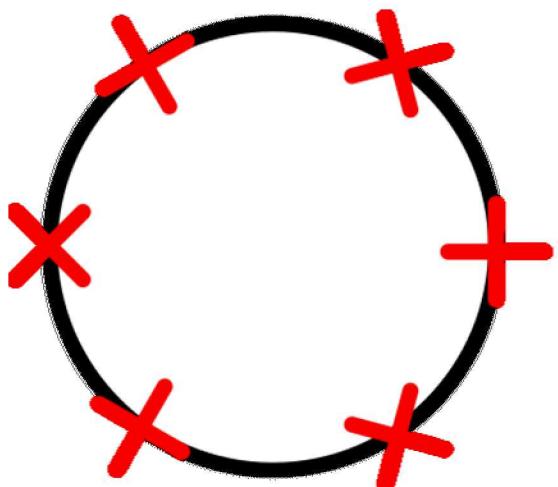


# Extra Slides

# Hyperbolic Trajectory of Streamlines

# Streamlines Near Singularities

$$f(z) = e^{i(\frac{d\theta}{4} + \frac{2k\pi}{4})} + o(r)$$



# Streamlines Near Singularities

$$f(z) = e^{i(\frac{d\theta}{4} + \frac{2k\pi}{4})} + o(r)$$

# Streamlines Near Singularities

$$f(z) = e^{i(\frac{d\theta}{4} + \frac{2k\pi}{4})} + \cancel{o(r)}$$

# Streamlines Near Singularities

$$f(z) = e^{i(\frac{d\theta}{4} + \frac{2k\pi}{4})} + \cancel{o(r)}$$

Streamlines are given by  $z' = f(z)$

# Streamlines Near Singularities

$$f(z) = e^{i(\frac{d\theta}{4} + \frac{2k\pi}{4})} + o(\cancel{r})$$

Streamlines are given by  $z' = f(z)$

WLOG let  $k = 0$ , we are looking for the set

$$C = \{z(t) \in B(a, r_0) \mid t \in (t_a, t_b)\}$$

# Streamlines Near Singularities

Proposition:

$$C = \{(x + iy)^{-(4-d)/8} \mid xy = A, x \in I_x\}$$

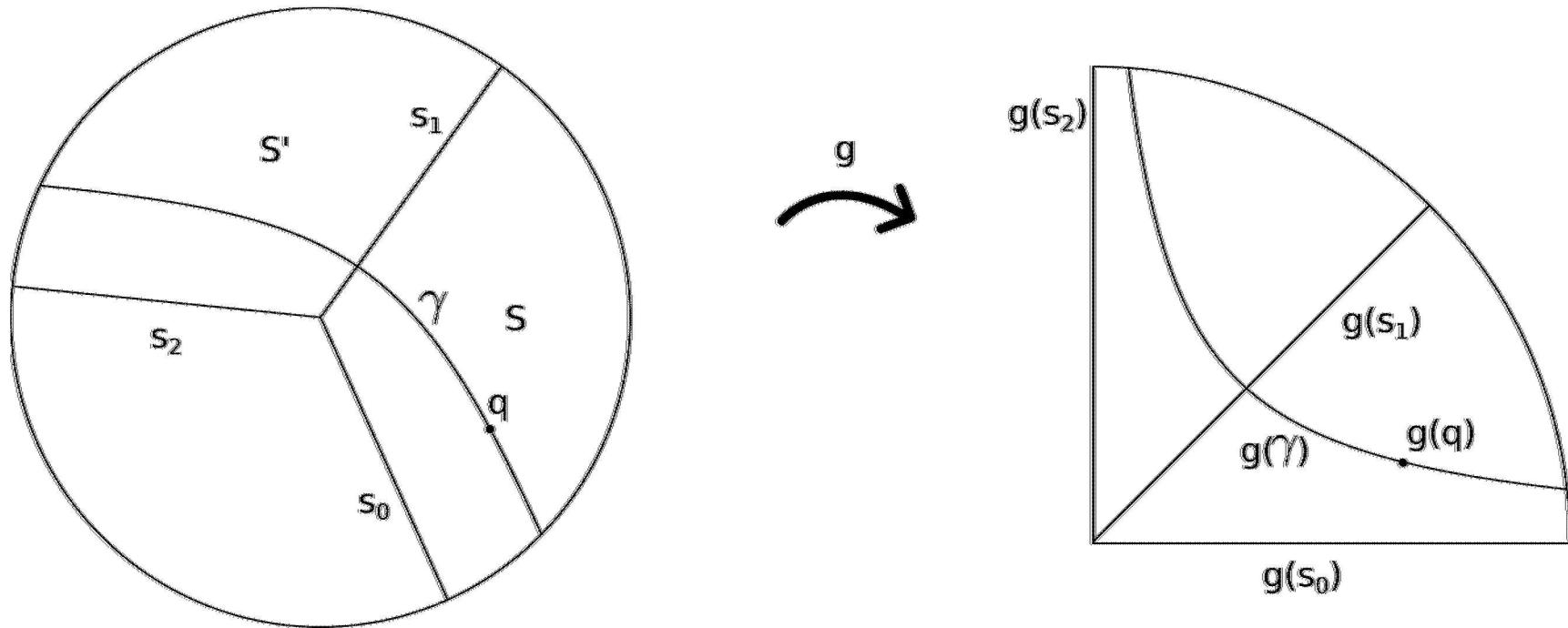
For some constant  $A$  on some interval  $I_x$

Proof:

Consider

$$g(z) = z^{(4-d)/8}$$

# Streamlines Near Singularities



$$g(z) = z^{(4-d)/8}$$

# Streamlines Near Singularities

$$w(t) = g(z(t))$$

# Streamlines Near Singularities

$$w(t) = g(z(t))$$

$$w'(t) = g'(z(t))z'(t)$$

# Streamlines Near Singularities

$$w(t) = g(z(t))$$

$$w'(t) = g'(z(t))z'(t)$$

$$g'(z) \neq 0 \text{ in } D$$

$$\arg w'(t) = \arg (g'(z(t))z'(t))$$

# Streamlines Near Singularities

$$w(t) = g(z(t))$$

$$w'(t) = g'(z(t))z'(t)$$

$$g'(z) \neq 0 \text{ in } D$$

$$\begin{aligned}\arg w'(t) &= \arg (g'(z(t))z'(t)) \\ &= \arg g'(z(t)) + \arg z'(t)\end{aligned}$$

# Streamlines Near Singularities

$$w(t) = g(z(t))$$

$$w'(t) = g'(z(t))z'(t)$$

$$g'(z) \neq 0 \text{ in } D$$

$$\begin{aligned}\arg w'(t) &= \arg (g'(z(t))z'(t)) \\ &= \arg g'(z(t)) + \arg z'(t) \\ &= \left( \frac{4-d}{8} - 1 \right) \theta + \arg(z'(t))\end{aligned}$$

# Streamlines Near Singularities

$$\arg w'(t) = \left( \frac{4-d}{8} - 1 \right) \theta + \arg(z'(t))$$

# Streamlines Near Singularities

$$\begin{aligned}\arg w'(t) &= \left( \frac{4-d}{8} - 1 \right) \theta + \arg(z'(t)) \\ &= \frac{d\theta}{4} + \left( \frac{4-d}{8} - 1 \right) \theta\end{aligned}$$

# Streamlines Near Singularities

$$\begin{aligned}\arg w'(t) &= \left( \frac{4-d}{8} - 1 \right) \theta + \arg(z'(t)) \\ &= \frac{d\theta}{4} + \left( \frac{4-d}{8} - 1 \right) \theta \\ &= -\frac{(4-d)\theta}{8}\end{aligned}$$

# Streamlines Near Singularities

$$\begin{aligned}\arg w'(t) &= \left( \frac{4-d}{8} - 1 \right) \theta + \arg(z'(t)) \\ &= \frac{d\theta}{4} + \left( \frac{4-d}{8} - 1 \right) \theta \\ &= -\frac{(4-d)\theta}{8} \\ &= -\varphi\end{aligned}$$

# Streamlines Near Singularities

$$\implies w'(t) = \alpha(t)e^{-i\varphi}$$

# Streamlines Near Singularities

$$\implies w'(t) = \alpha(t)e^{-i\varphi}$$

$$w(t) = x(t) + iy(t)$$

$$x'(t) = \alpha(t) \cos(\varphi)$$

$$y'(t) = -\alpha(t) \sin(\varphi)$$

# Streamlines Near Singularities

$$\implies w'(t) = \alpha(t)e^{-i\varphi}$$

$$w(t) = x(t) + iy(t)$$

$$x'(t) = \alpha(t) \cos(\varphi)$$

$$y'(t) = -\alpha(t) \sin(\varphi)$$

$$\frac{dy}{dx} = -\tan(\varphi) = -\frac{y}{x} \implies y = \frac{A}{x}$$

# Streamlines Near Singularities

$$\implies w'(t) = \alpha(t)e^{-i\varphi}$$

$$w(t) = x(t) + iy(t)$$

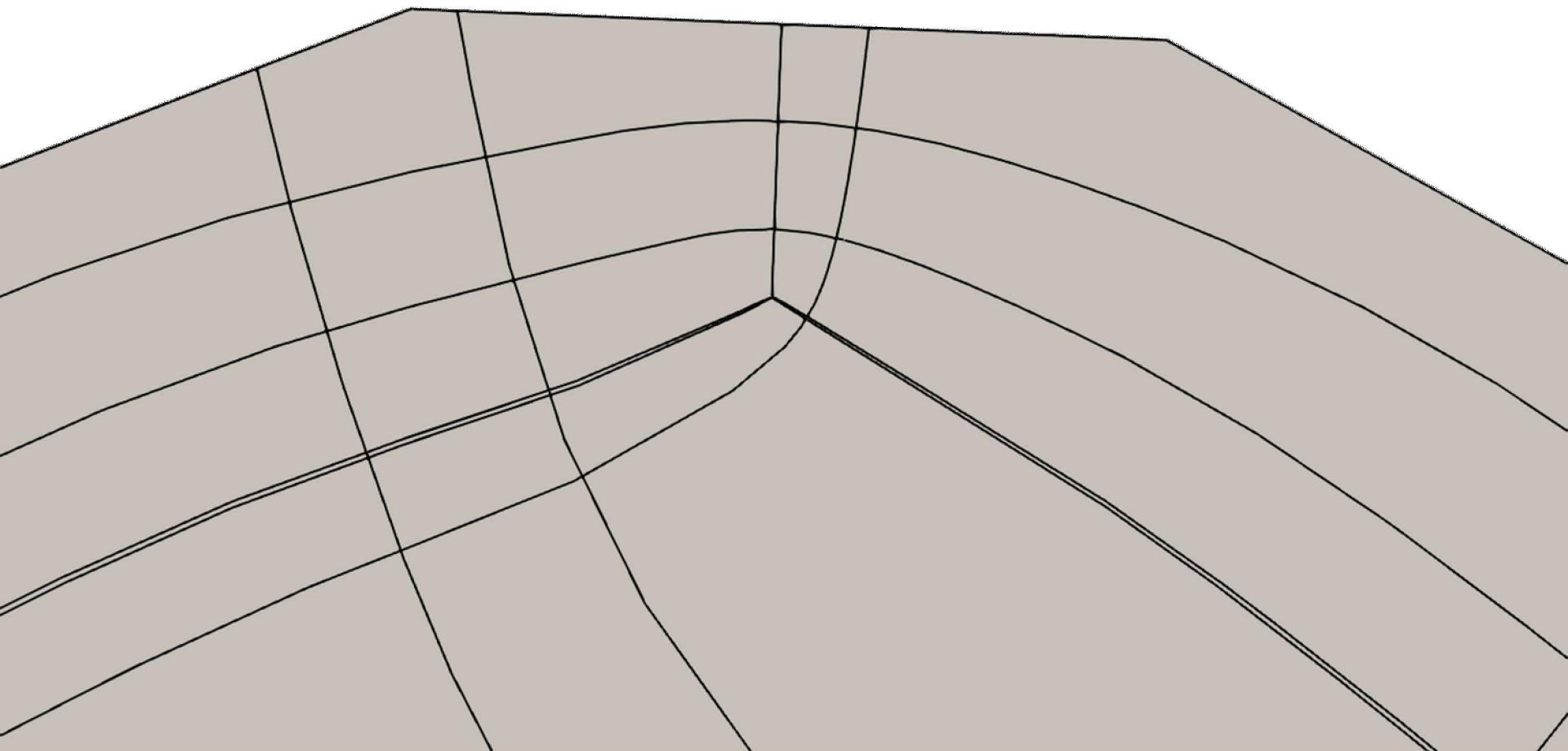
$$x'(t) = \alpha(t) \cos(\varphi)$$

$$y'(t) = -\alpha(t) \sin(\varphi)$$

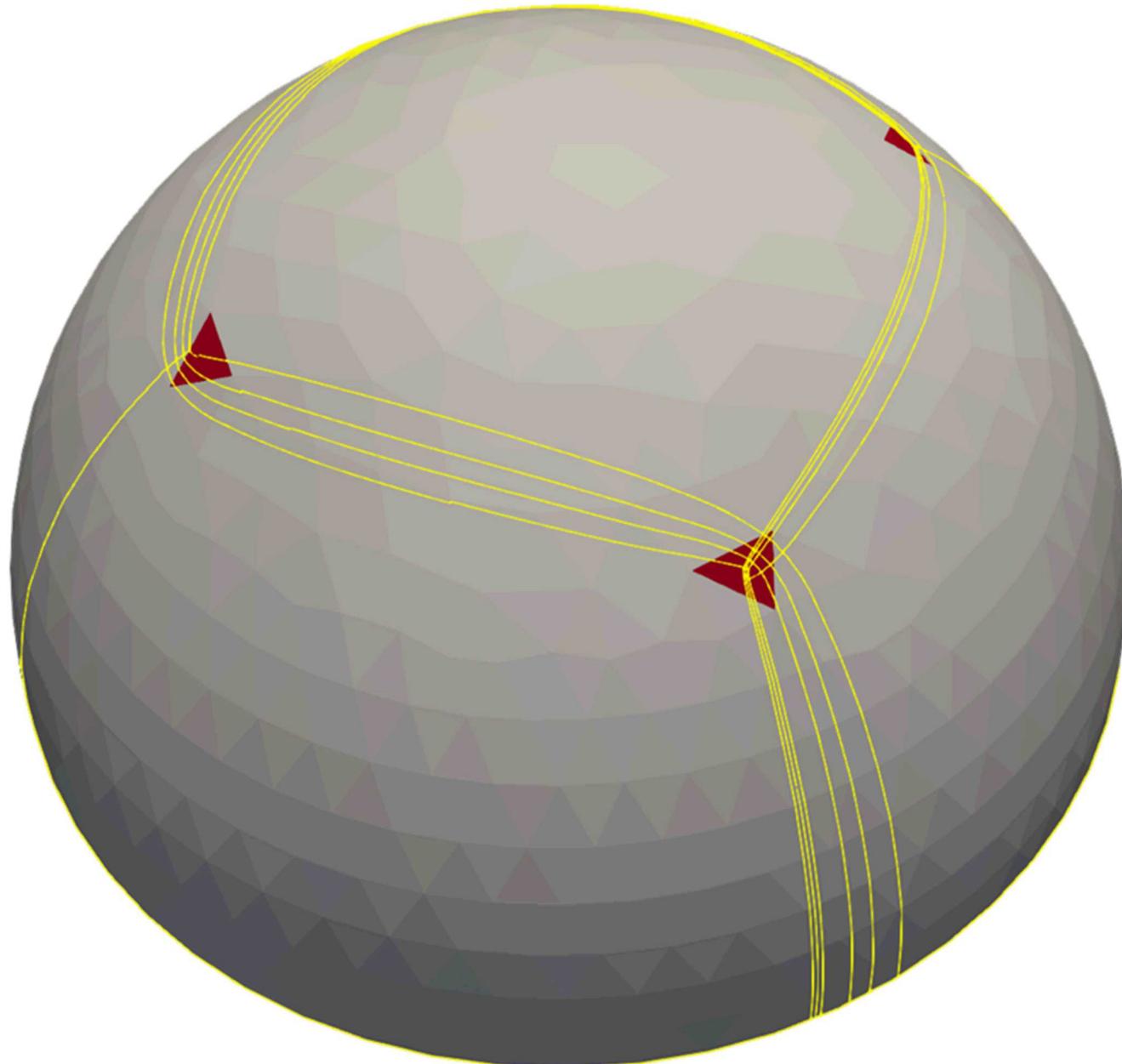
$$\frac{dy}{dx} = -\tan(\varphi) = -\frac{y}{x} \implies y = \frac{A}{x}$$

$$C = \{(x + iy)^{-(4-d)/8} \mid xy = A, x \in I_x\}$$

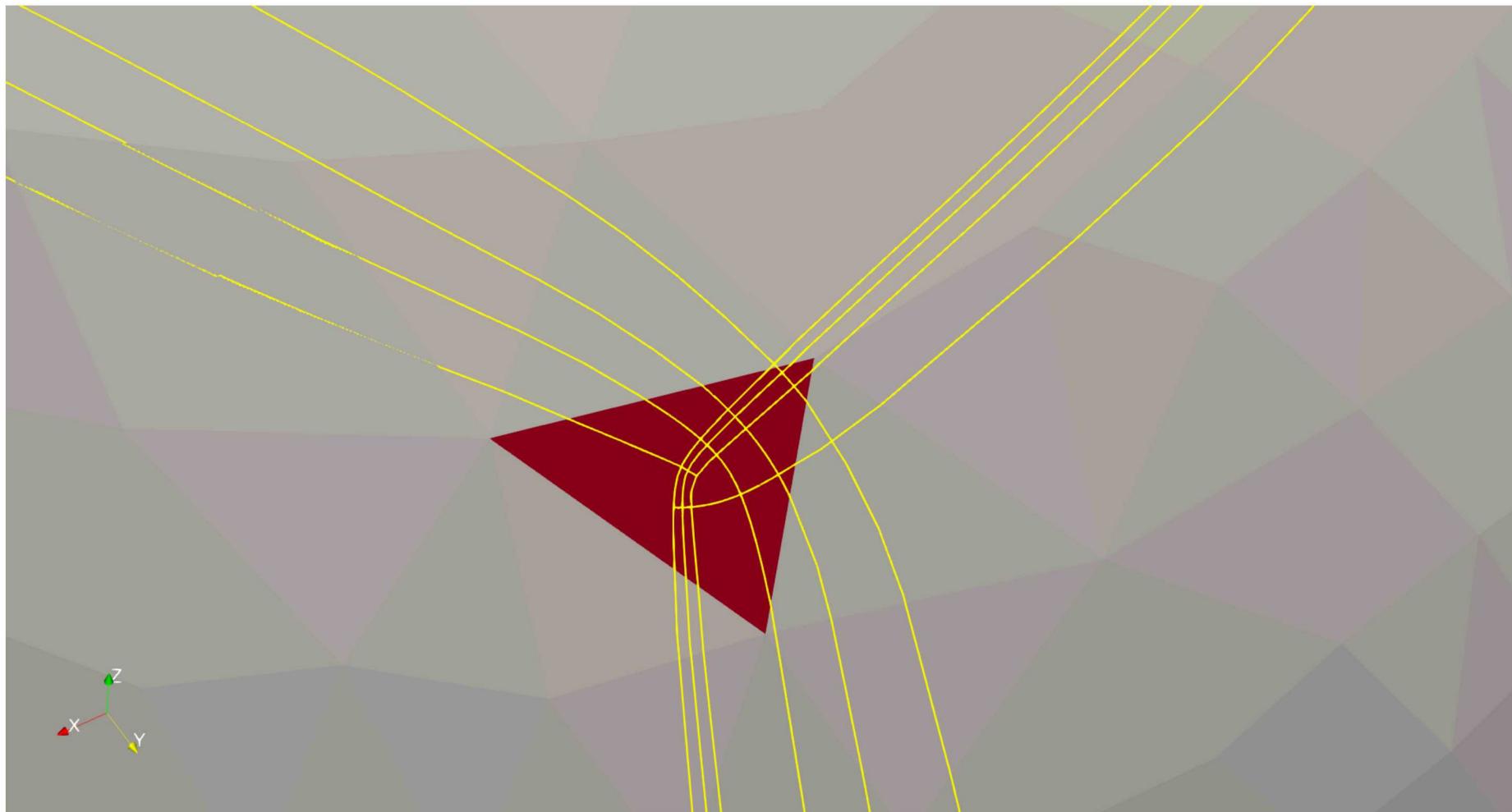
# Streamlines Near Singularities



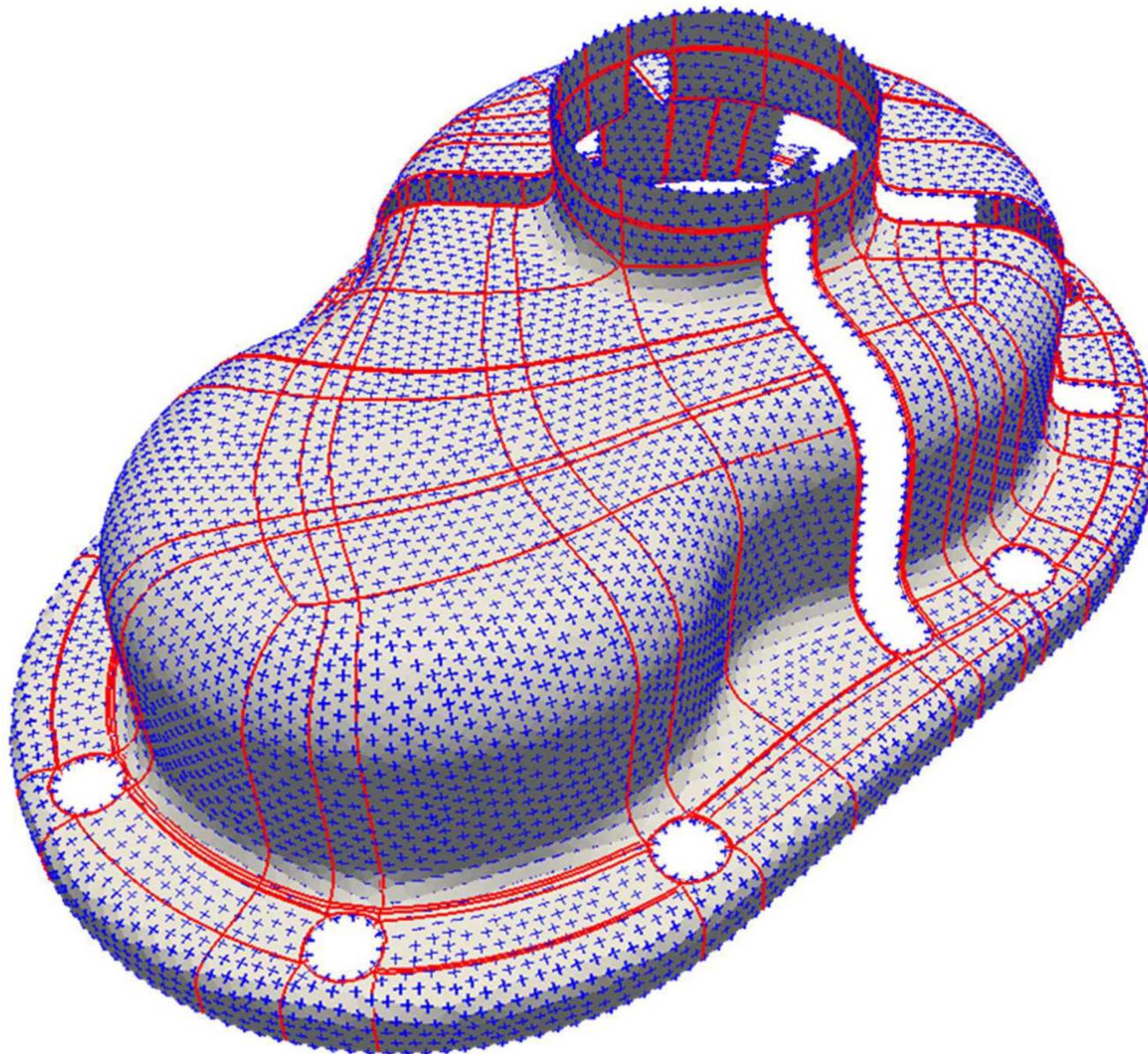
# Streamline Tracing



# Streamline Tracing



# Streamline Tracing



# Connection to Ginzburg- Landau Theory

# Ginzburg-Landau Functional

Original problem:

$$\min_{u \in H_g^1(D, \mathbb{C})} E(u)$$

$$E(u) = \frac{1}{2} \int_D |\nabla u|^2 dA$$

$$u(x) = g(x) \quad \forall x \in \partial D$$

$$|u(x)| = 1 \quad \text{a.e. } x \in D$$

Relaxed problem:

$$\min_{u \in H_g^1(D, \mathbb{C})} E_\epsilon(u)$$

$$E_\epsilon(u) = \frac{1}{2} \int_G |\nabla u|^2 + \frac{1}{4\epsilon^2} \int_G (|u|^2 - 1)^2$$

# Results of Ginzburg-Landau Theory (Bethuel et al.) and Applications to Cross Fields

# Well Defined Limit of Relaxed Problem

**Theorem 2.2.2** (Bethuel et al. [4]). *Let  $d = \deg(g, \partial D)$ . Given a sequence  $\varepsilon_n \rightarrow 0$  there exists a subsequence  $\varepsilon_{n_i}$  and exactly  $d$  points  $a_1, a_2, \dots, a_d$  in  $D \subset \mathbb{C}$  and a smooth harmonic map  $u_*: D \setminus \{a_1, \dots, a_d\} \rightarrow \mathbb{T}$  with  $u_* = g$  on  $\partial D$  such that*

$$u_{\varepsilon_{n_i}} \rightarrow u_* \text{ in } C_{loc}^k(D \setminus \bigcup_i (a_i)) \quad \forall k \text{ and in } C^{1,\alpha}(\bar{D} \setminus \bigcup_i (a_i)) \quad \forall \alpha < 1$$

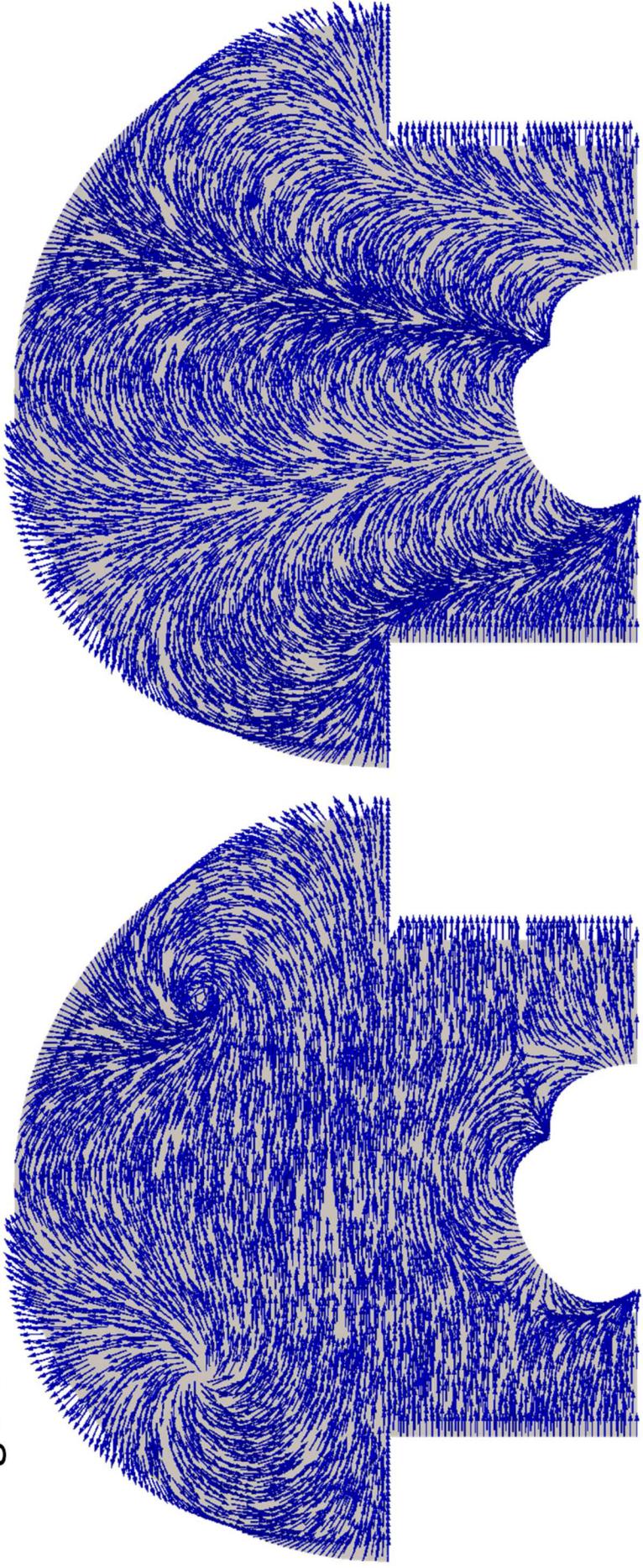
*In addition, if  $d \neq 0$  each singularity of  $u_*$  has index  $\text{sgn}(d)$  and, more precisely, there are complex constants  $(\alpha_i)$  with  $|\alpha_i| = 1$  such that*

$$\left| u_*(z) - \alpha_i \frac{z - a_i}{|z - a_i|} \right| \leq C|z - a_i|^2 \text{ as } z \rightarrow a_i, \quad \forall i$$

This gives us a generalized sense in which to understand the energy minimization problem

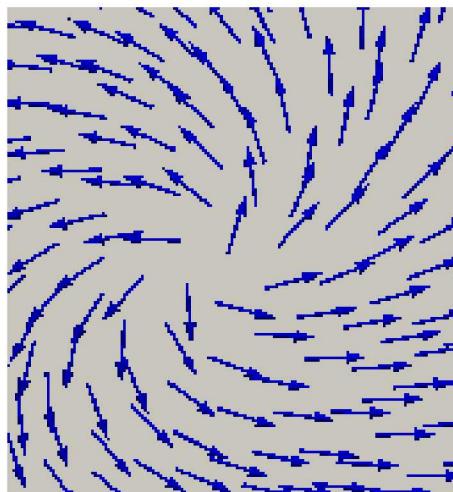
# Canonical Harmonic Map

- Harmonic vector field defined everywhere except a finite number of points
- All vectors are unit vectors
- Unique for a given boundary condition and configuration of singularities



# Asymptotic Estimate

$$\left| u_0(z) - \alpha_j \frac{(z - a_j)^{d_j}}{|z - a_j|^{d_j}} \right| \leq C|z - a_j| \quad \text{as } z \rightarrow a_j$$

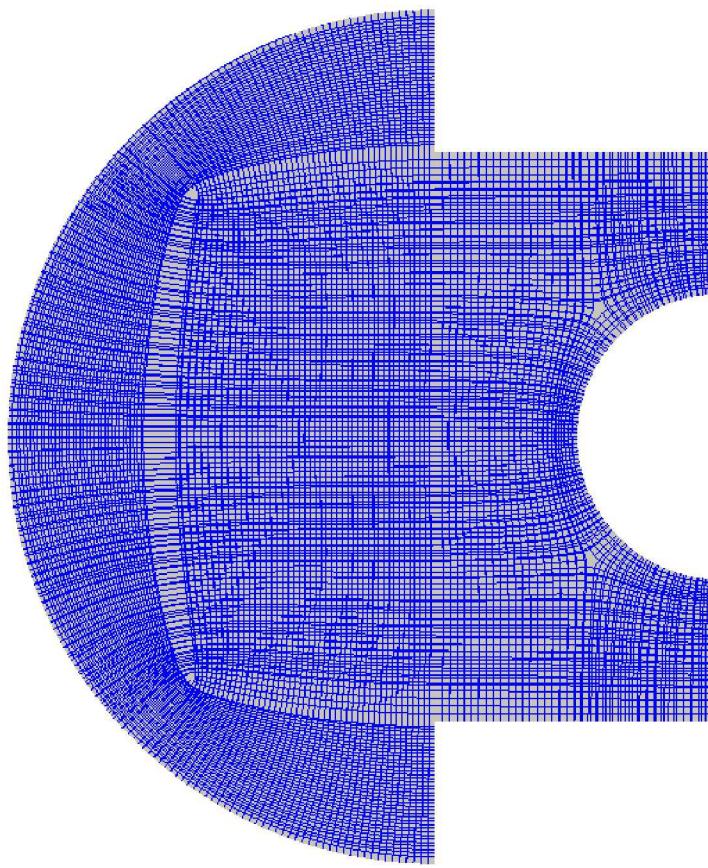
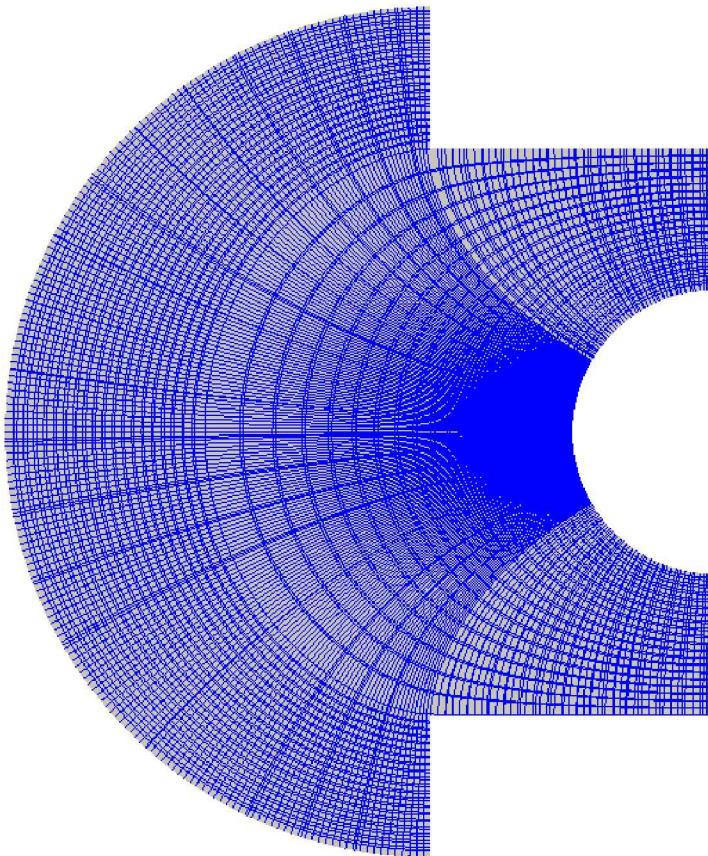


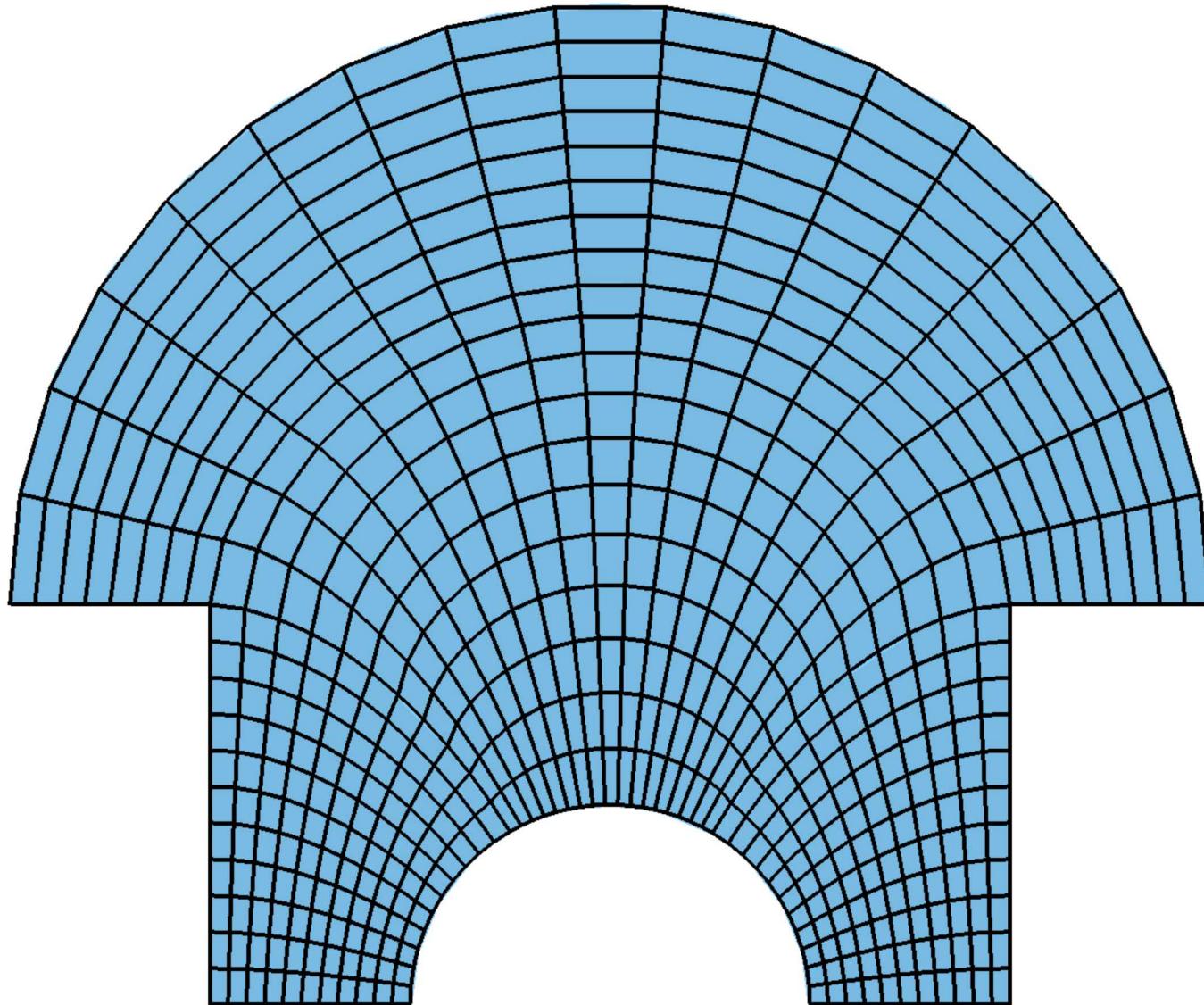
# Energy Argument for Local Minimizers

For a local minimizer of the Ginzburg-Landau energy, the singularities are:

- Isolated
- Simple
- Occur on the interior of the domain

# Implication for Cross Fields: Strange Minimizer

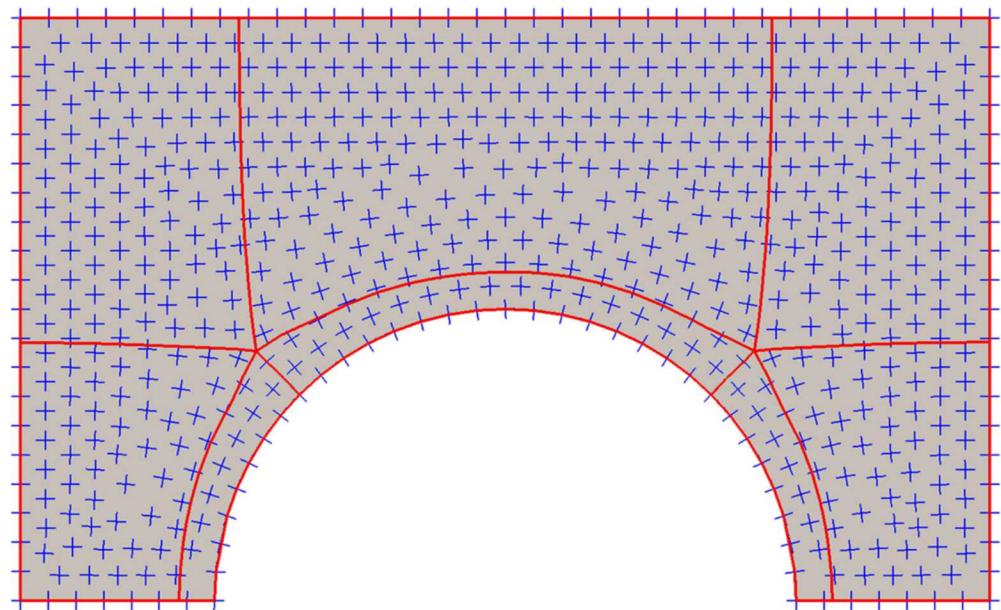
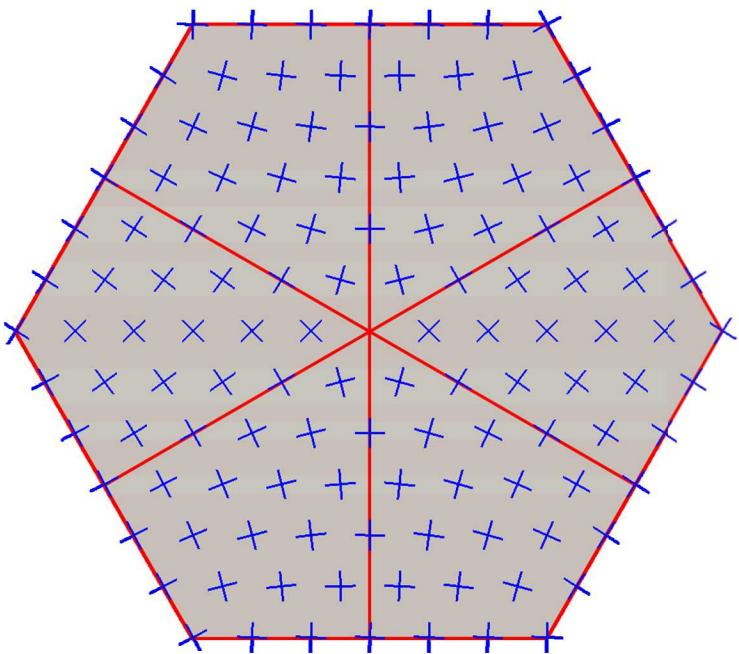




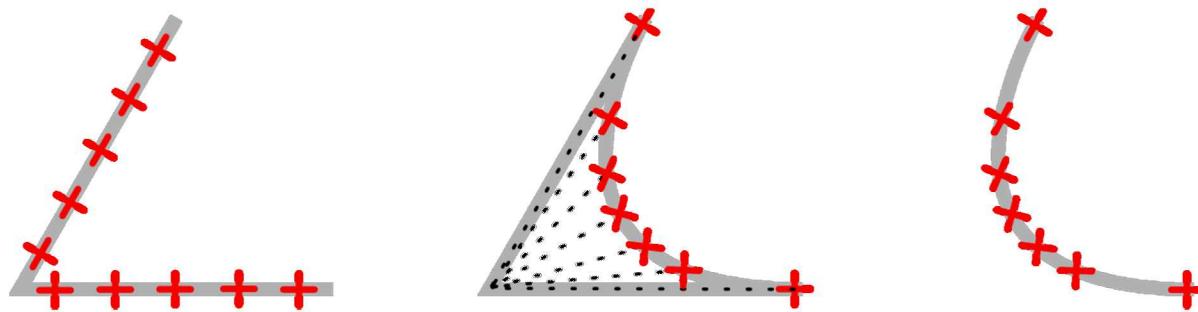
# Streamlines and Asymptotic Behavior of Cross Fields Near Singularities

# Separatrices

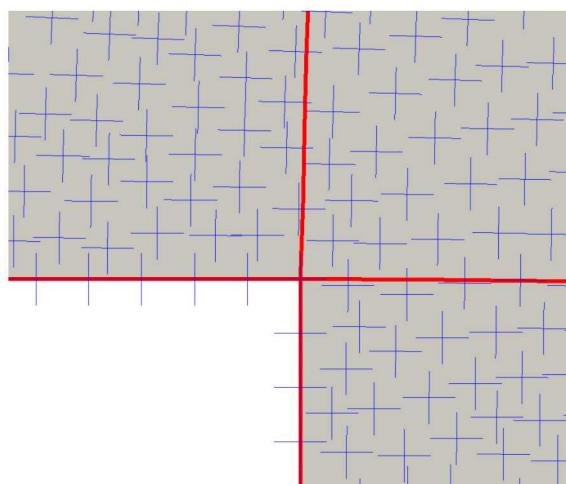
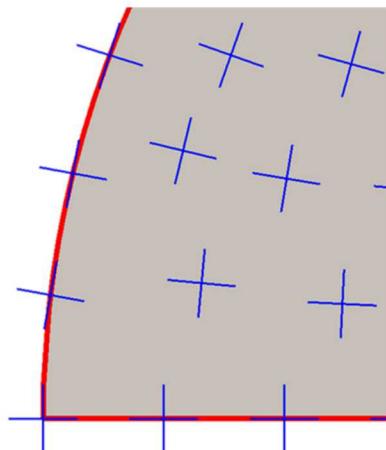
LEMMA 5.1. *Let  $f$  be a boundary-aligned canonical harmonic cross field on  $D$ . Let  $a$  be an interior singularity of  $f$  of index  $d/4$  with  $d < 4$ . There are exactly  $4 - d$  separatrices meeting at  $a$ . These separatrices partition a neighborhood of  $a$  into  $4 - d$  even-angled sectors.*



# Boundary Singularities

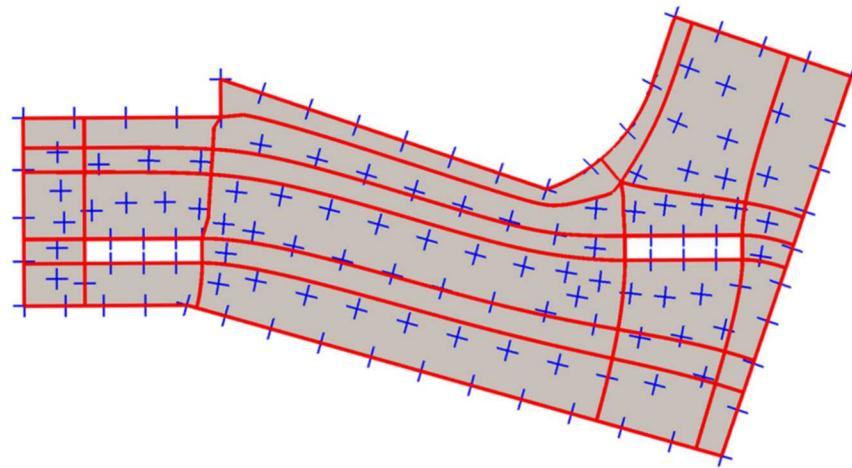
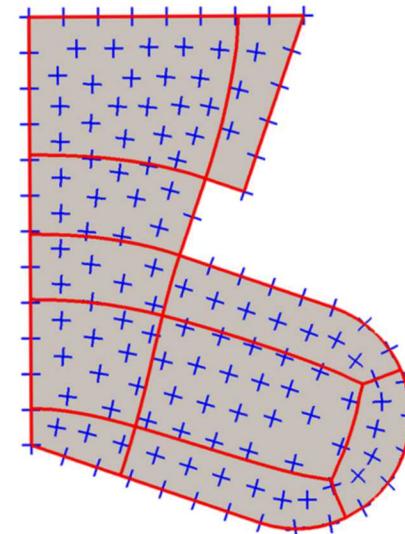
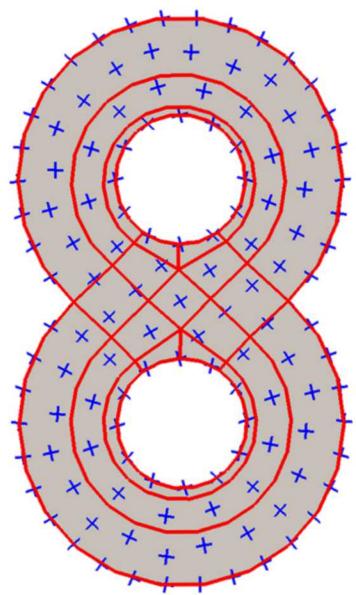
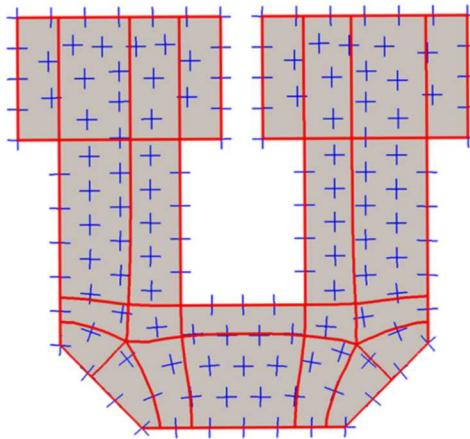


LEMMA 5.4. Let  $c$  be a boundary singularity of  $f$  of index  $d/4$  with  $d < 2$ . There are exactly  $3 - d$  separatrices meeting at  $c$  (including the boundaries themselves). These separatrices partition a neighborhood of  $c$  into  $2 - d$  even-angled sectors.

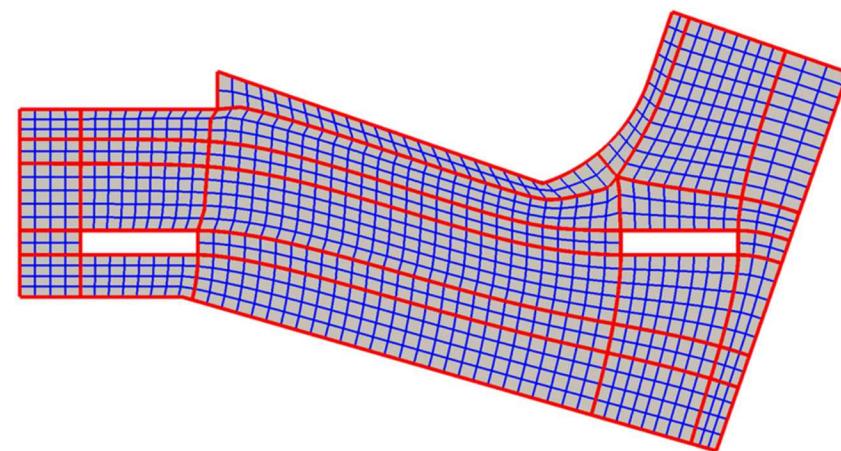
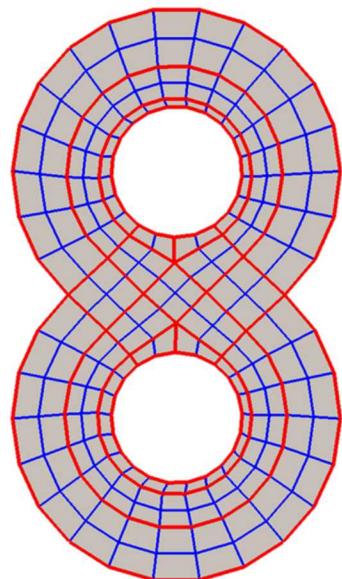
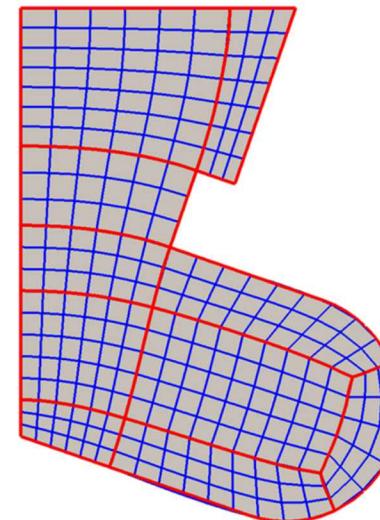
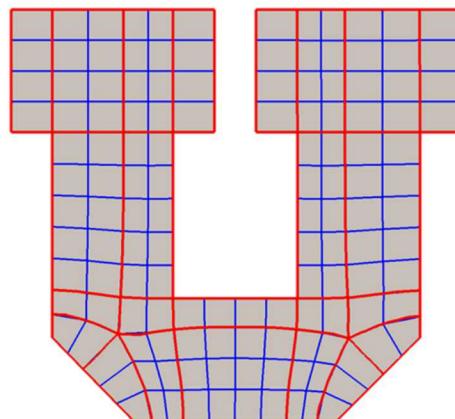


# Partitioning Theorem

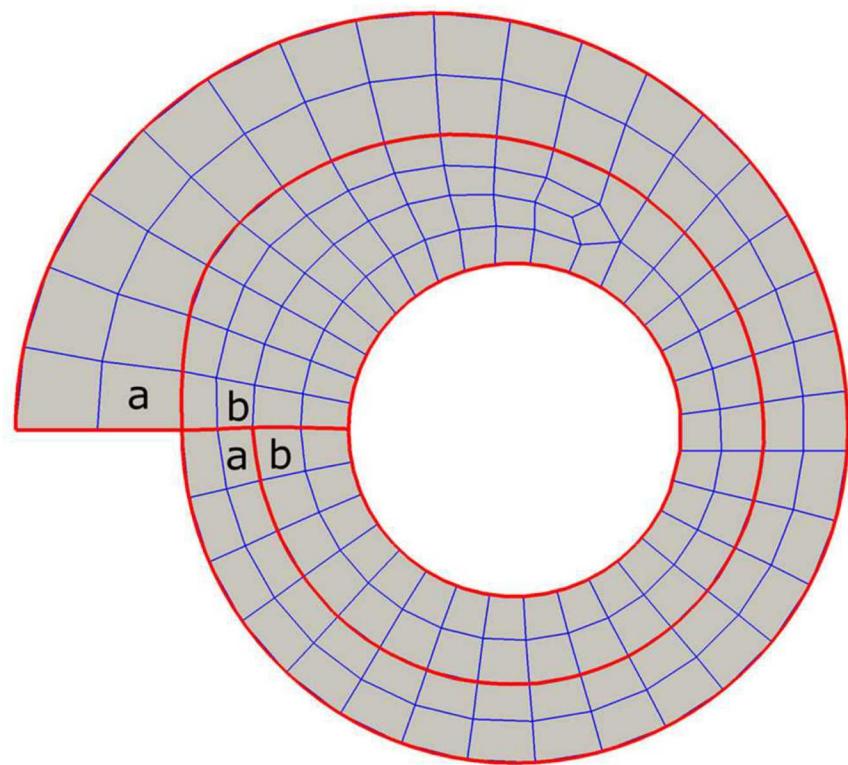
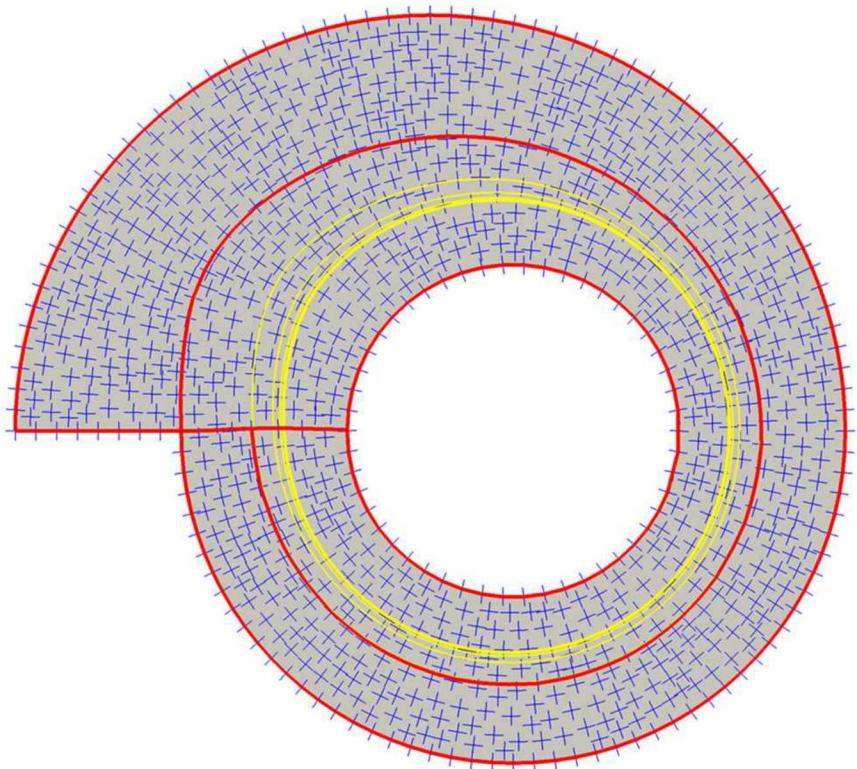
# Partition into four-sided regions



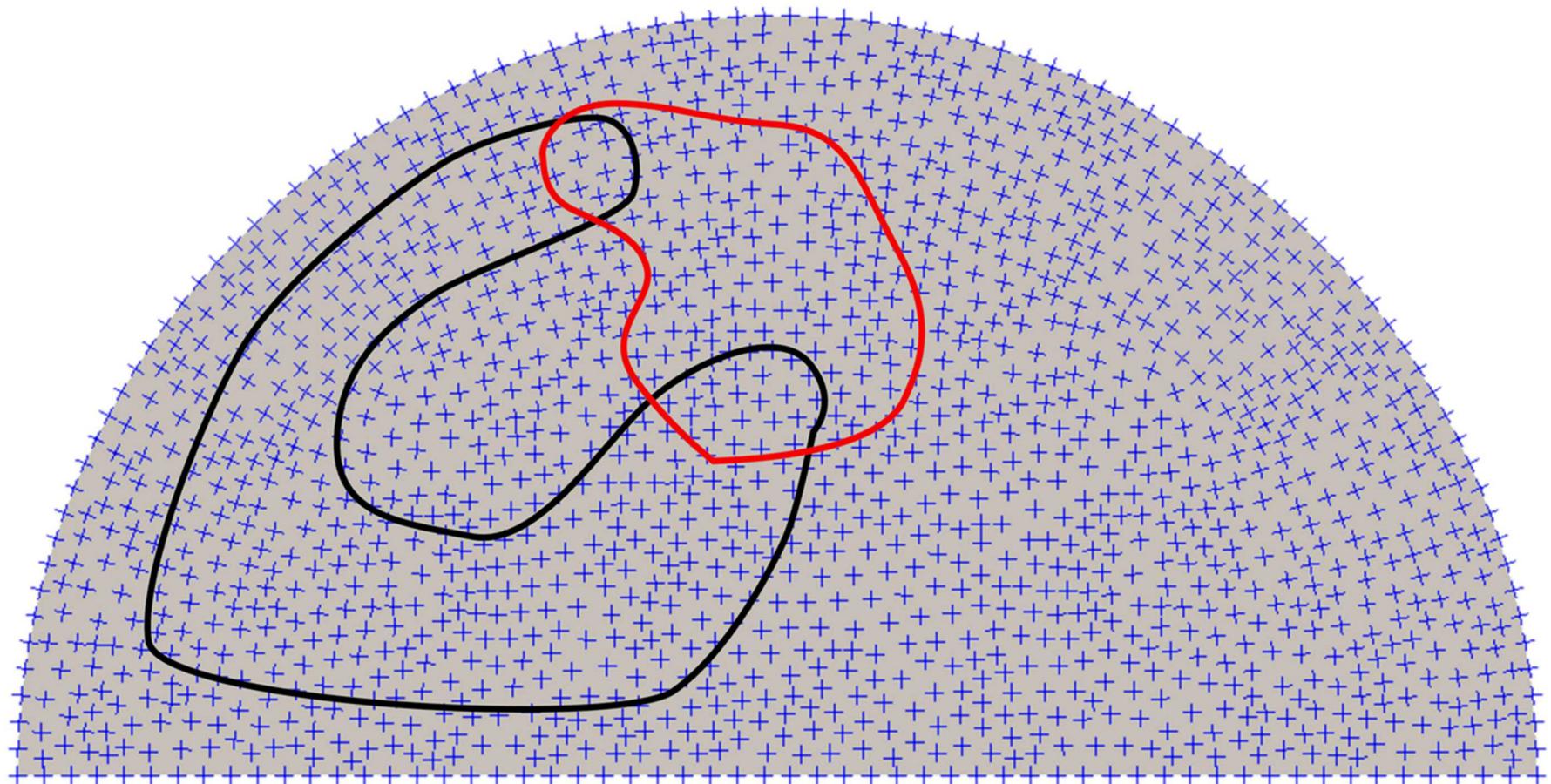
# Meshing



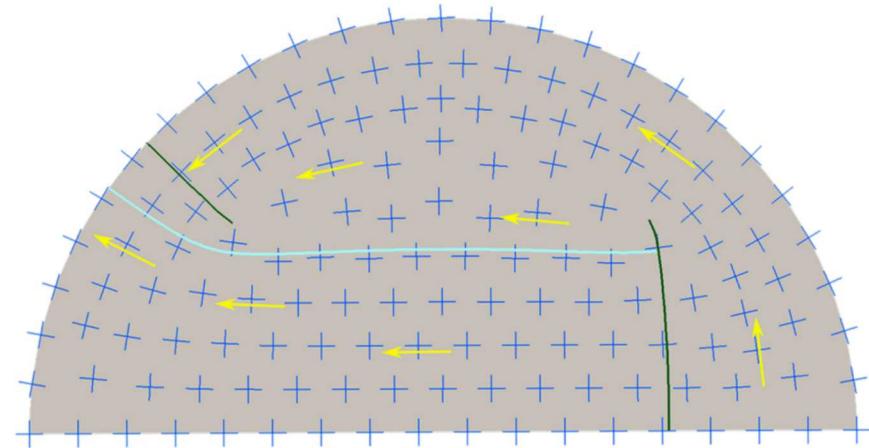
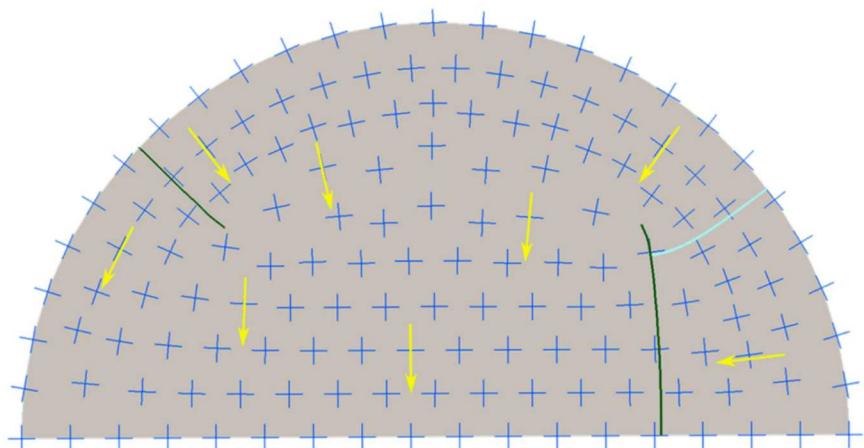
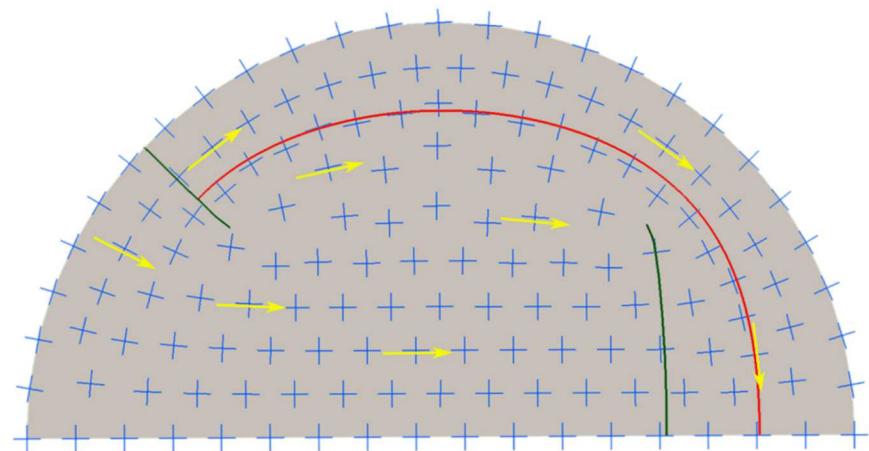
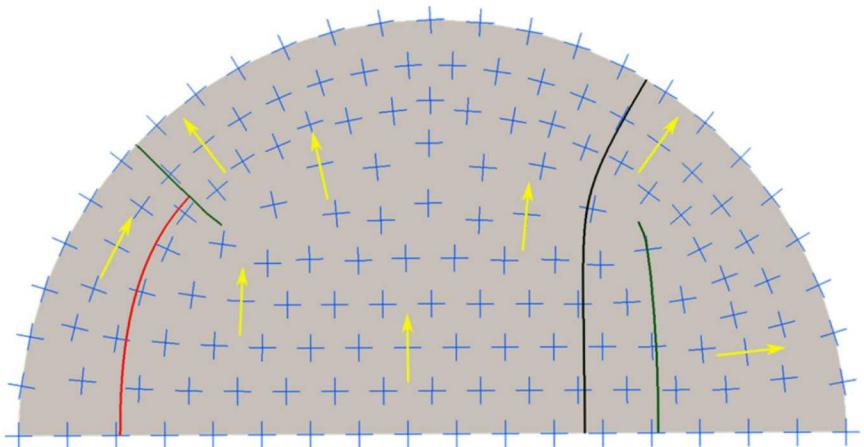
# Limit Cycles



# Cross Fields can be Decomposed Locally into 4 Orthogonal Vector Fields



# Riemann Surface and Streamlines



# Proof

LEMMA 5.1. *Let  $f$  be a boundary-aligned canonical harmonic cross field on  $D$ . Let  $a$  be an interior singularity of  $f$  of index  $d/4$  with  $d < 4$ . There are exactly  $4 - d$  separatrices meeting at  $a$ . These separatrices partition a neighborhood of  $a$  into  $4 - d$  even-angled sectors.*

$$(4) \quad \left| u_0(z) - \alpha_j \frac{(z - a_j)^{d_j}}{|z - a_j|^{d_j}} \right| \leq C|z - a_j| \quad \text{as } z \rightarrow a_j$$

*Proof.* Let  $u_0$  be the representation vector field for  $f$ . Write  $z = a + re^{i\theta}$ . The estimate (4) gives

$$(8) \quad u_0(z) = \alpha e^{id\theta} + o(r) \quad \text{for } \theta \in [0, 2\pi).$$

Writing  $\alpha = e^{i\theta_0/N}$ , the  $N$ th-roots of the  $u_0(z)$  are then given by  $e^{i(\frac{d\theta+\theta_0}{N} + \frac{2\pi k}{N})}$  for  $k \in \mathbb{Z}$ .

We seek directions where the vector originating at  $a$  and pointing towards  $z$  is parallel to a vector originating at the origin and pointing towards any of the  $N$ th-roots. Thus we want to solve the equation

$$(9) \quad e^{i\theta} = e^{i(\frac{d\theta+\theta_0}{N} + \frac{2\pi k}{N})} \quad \Rightarrow \quad \theta = 2\pi k/(N - d) + \theta_0/(N - d)$$

# Algorithm

---

**Algorithm 1** Partitioning  $D$  into a quad layout with T-junctions.

---

**Input:** A domain  $D$  satisfying [Assumption 3.1](#), and a boundary-aligned canonical harmonic cross field  $f$  with singularities of index  $\leq 1/4$ .

**Output:** A set  $\mathcal{B}$  containing limit cycles and separatrices that define a quad layout with T junctions.

Let  $\mathcal{S}$  be the set of separatrices that do not converge to a limit cycle. Let  $\mathcal{P}$  be the set of separatrices that do. Let  $\mathcal{L}$  be the set of limit cycles.

Initialize the set  $\mathcal{B} = \mathcal{S}$ .

**for**  $l \in \mathcal{L}$  **do**

**if** no element of  $\mathcal{B}$  intersects  $l$  **then**

        (i) Add  $l$  to  $\mathcal{B}$ .

        (ii) By [Corollary 5.8](#), there is an element of  $\mathcal{P}$  that intersects  $l$ . Let  $\rho'$  be the portion of that separatrix beginning at the singularity and ending in a T-junction with  $l$ .

        (iii) Add  $\rho'$  to  $\mathcal{B}$ .

        (iv) remove  $\rho$  from  $\mathcal{P}$ .

**end if**

**end for**

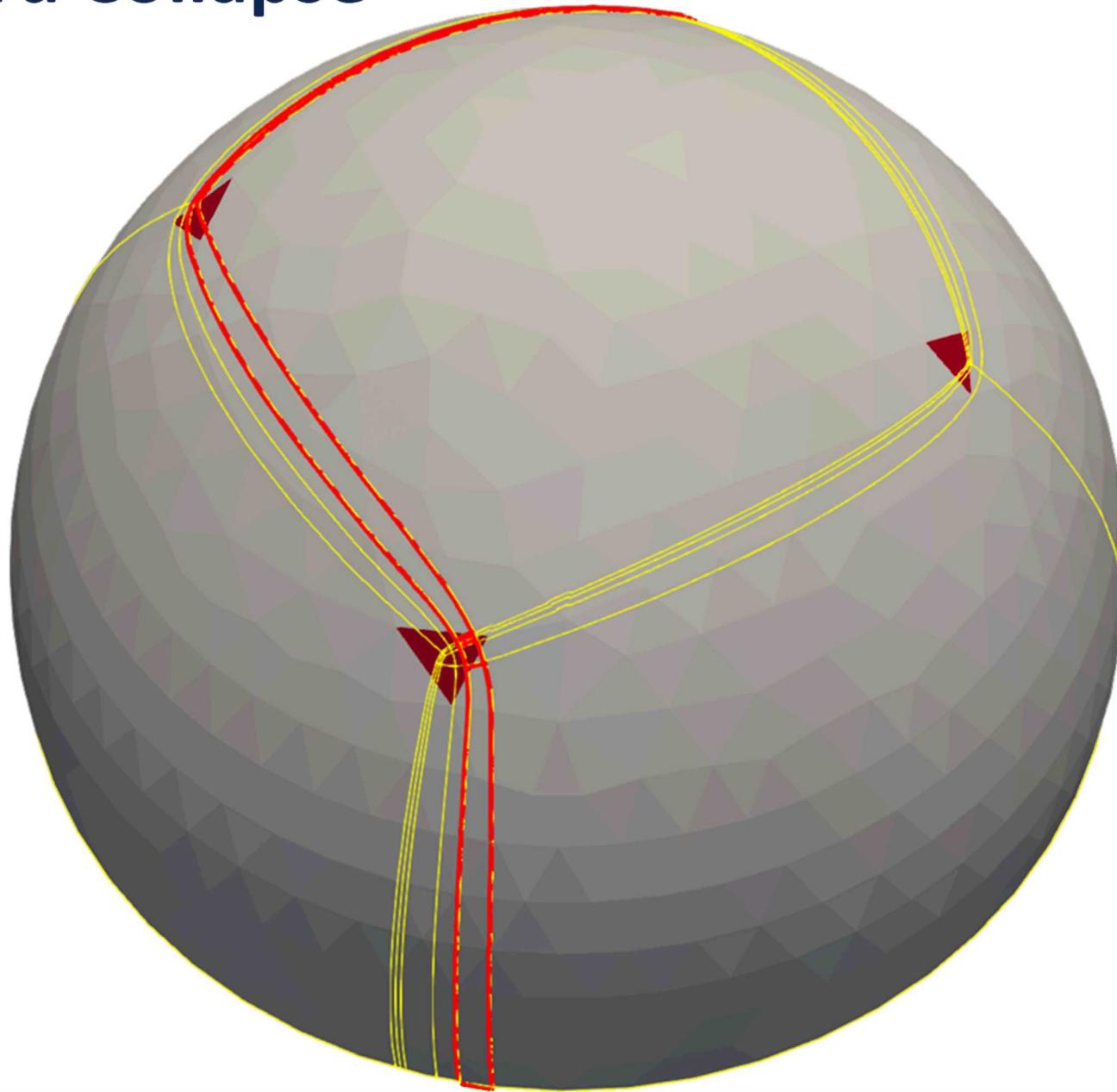
**for**  $\rho \in \mathcal{P}$  **do**

    Let  $\rho'$  be the curve segment of  $\rho$  beginning at the singularity and continuing until it intersects an element of  $\mathcal{B}$ . Add  $\rho'$  to  $\mathcal{B}$ .

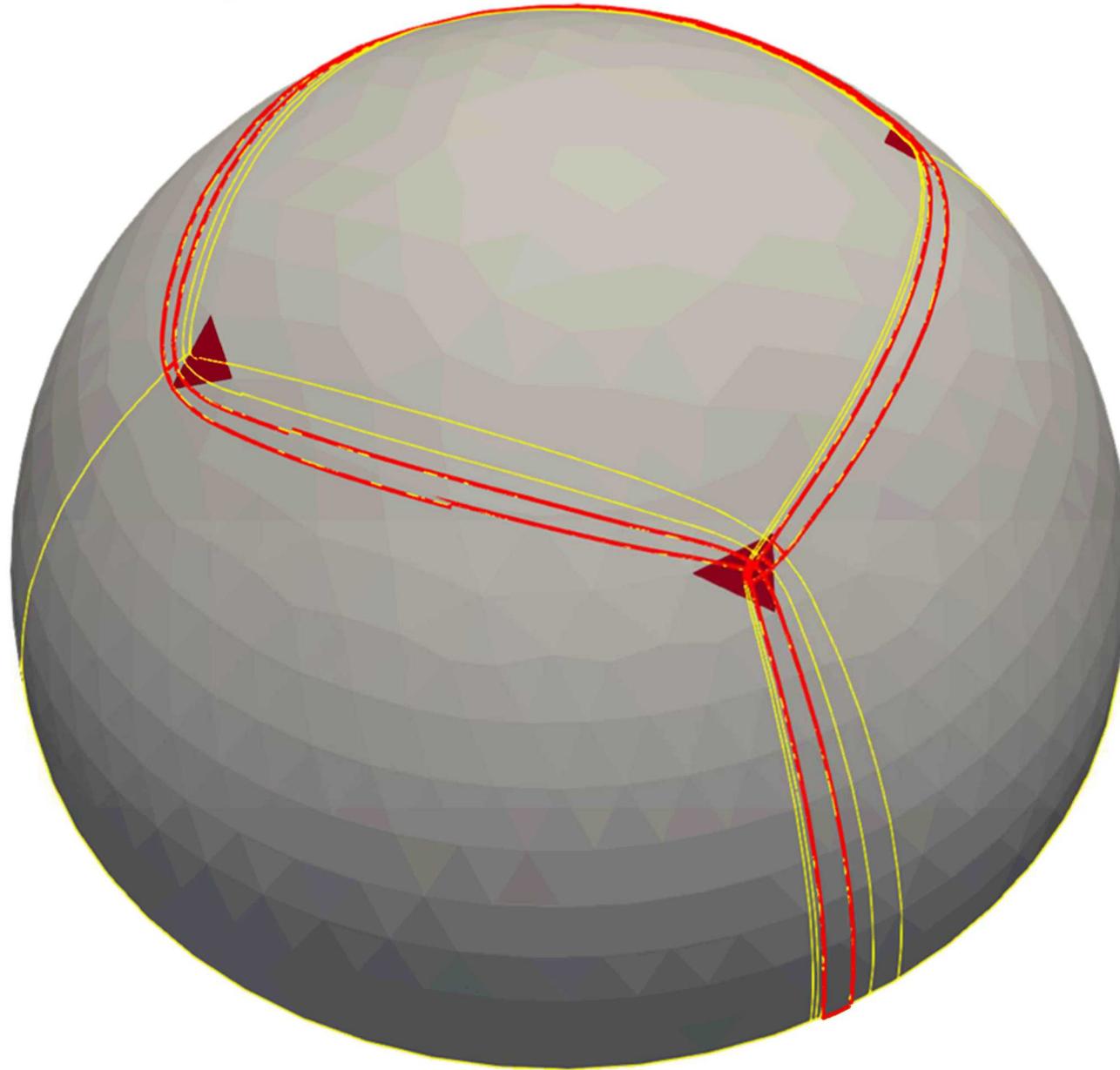
**end for**

---

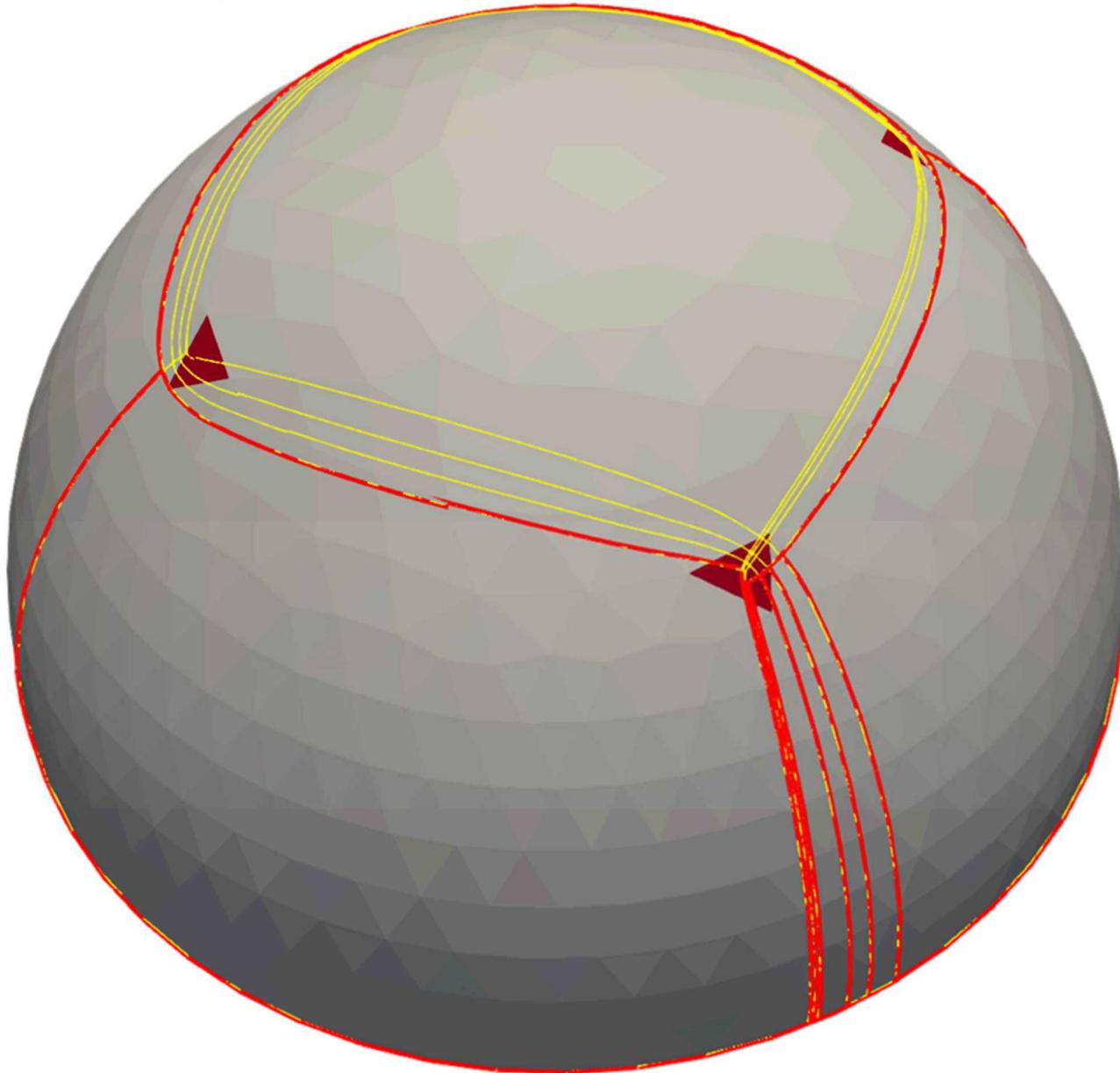
# Chord Collapse



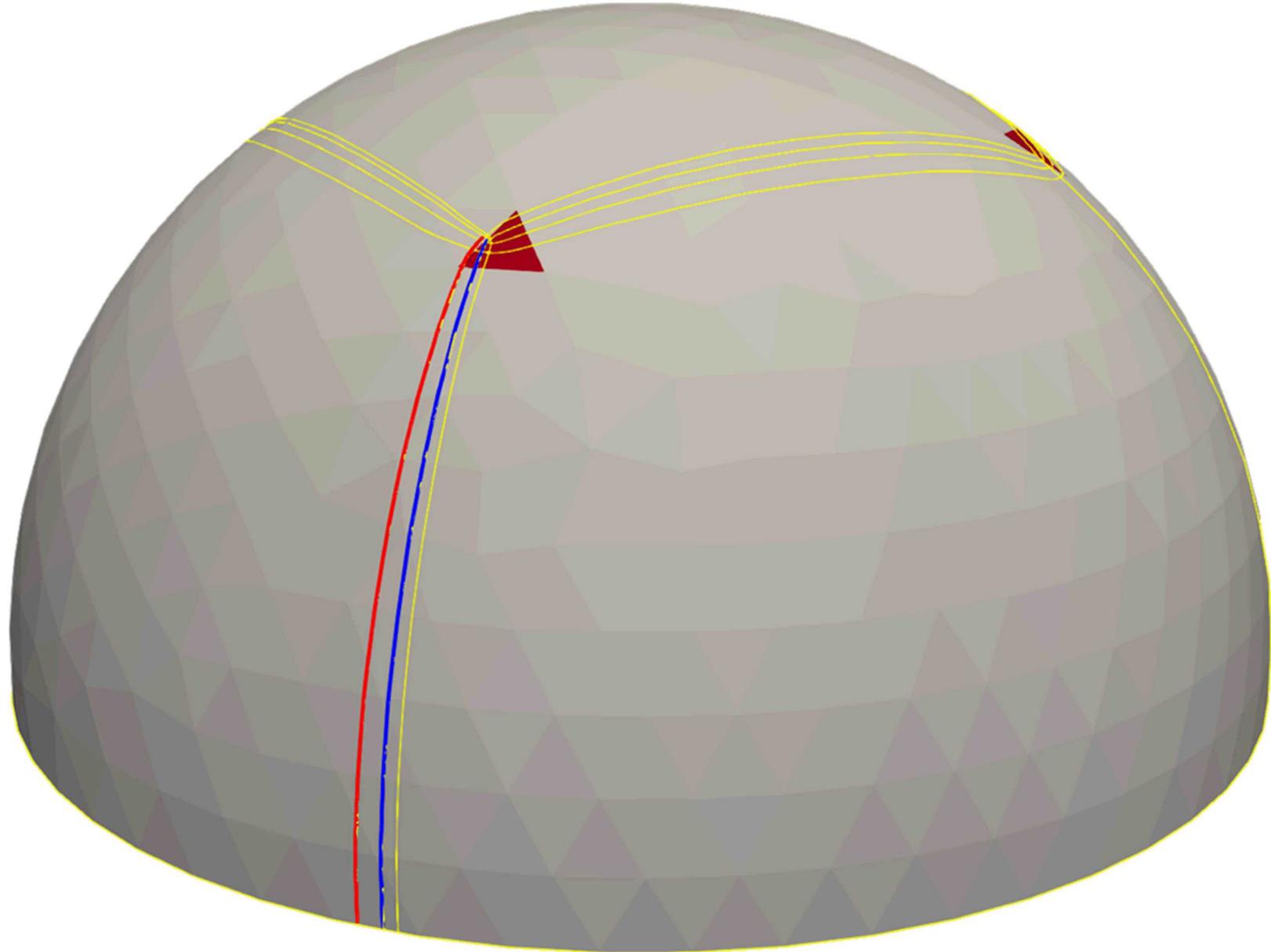
# Chord Collapse



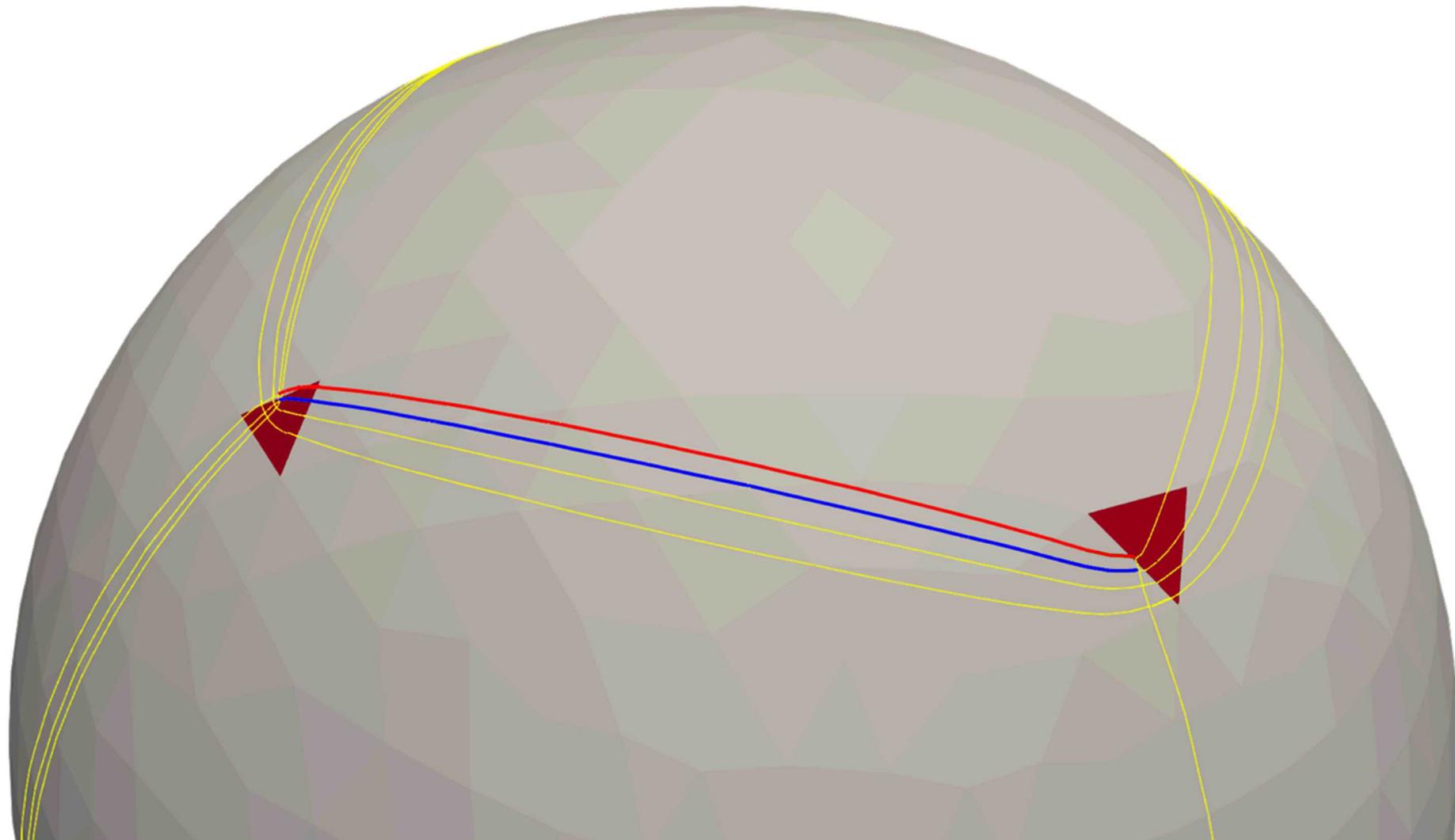
# Chord Collapse



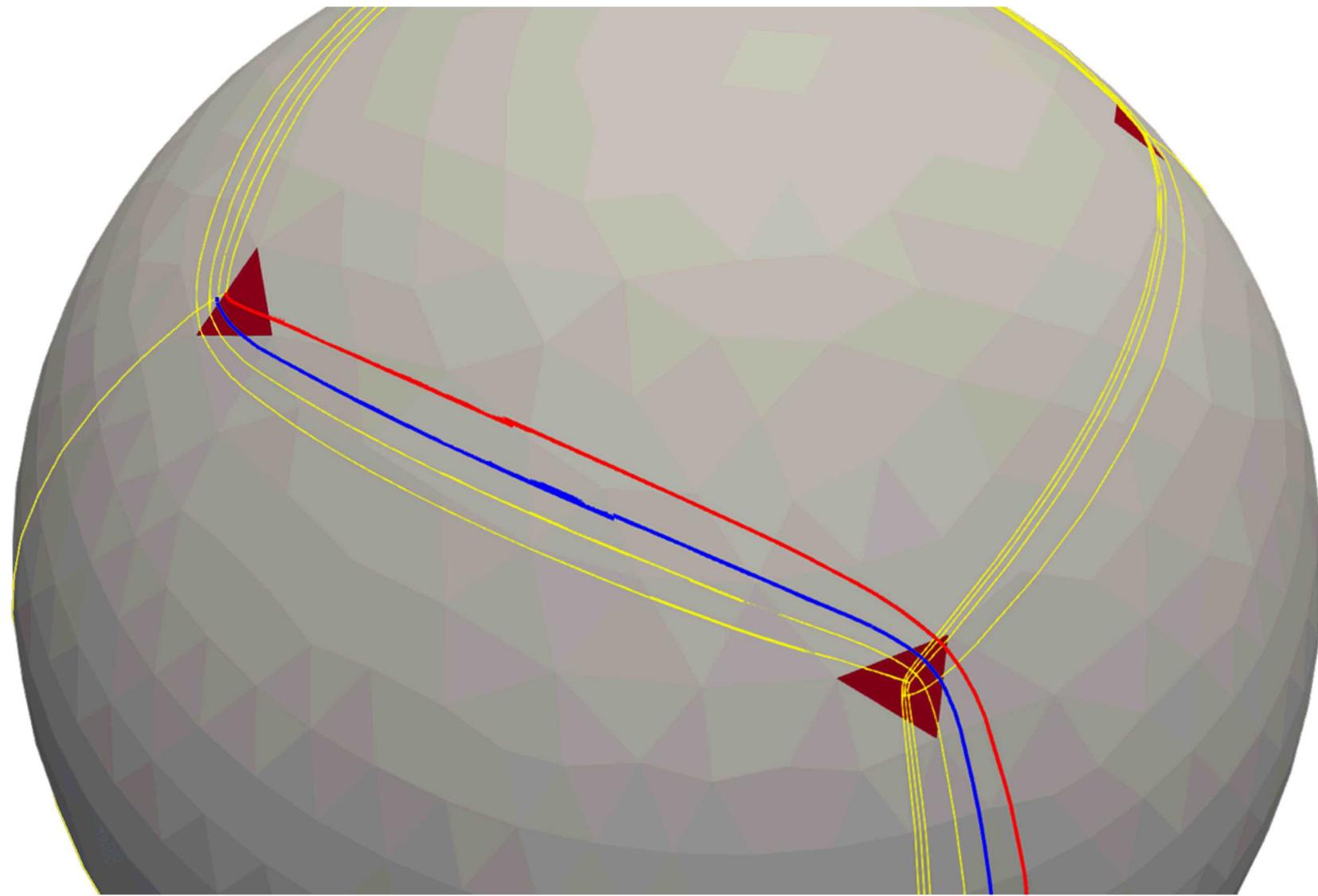
# Chord Collapse



# Chord Collapse



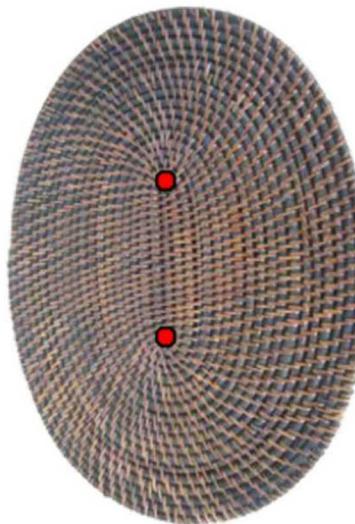
# Chord Collapse



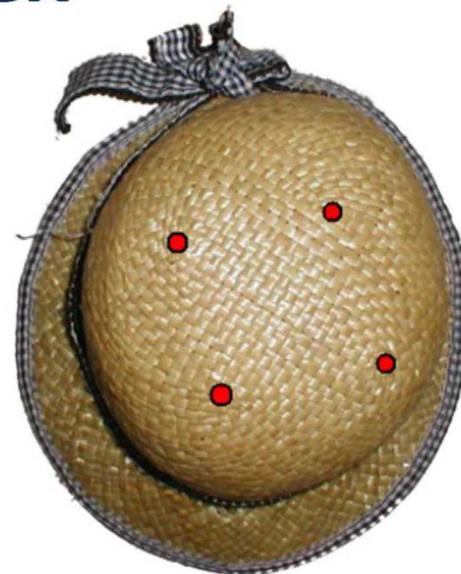
# Singularities of Fractional Index



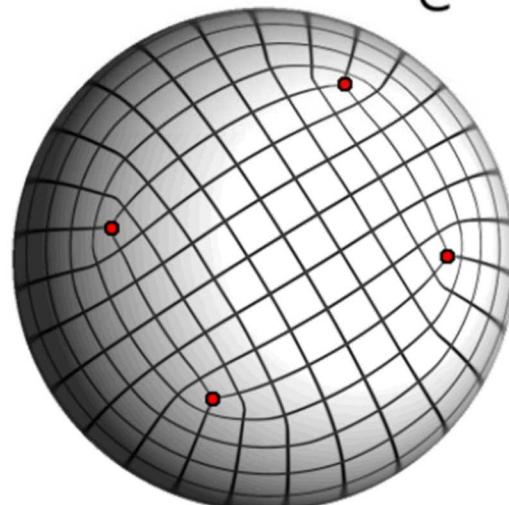
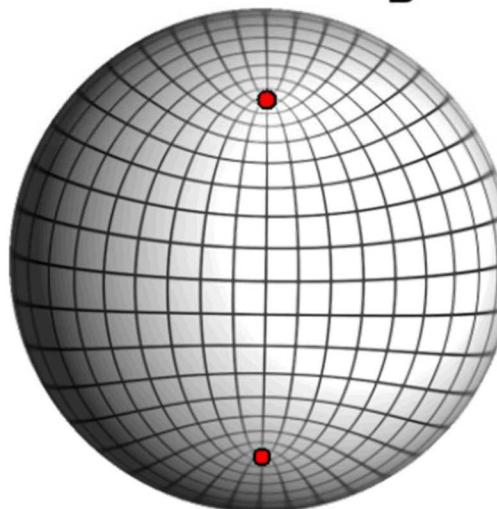
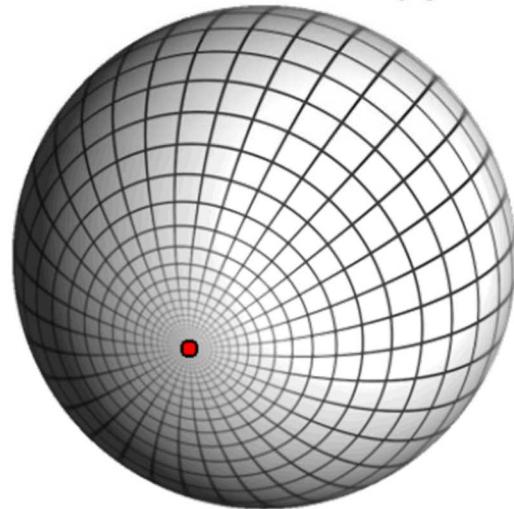
A



B

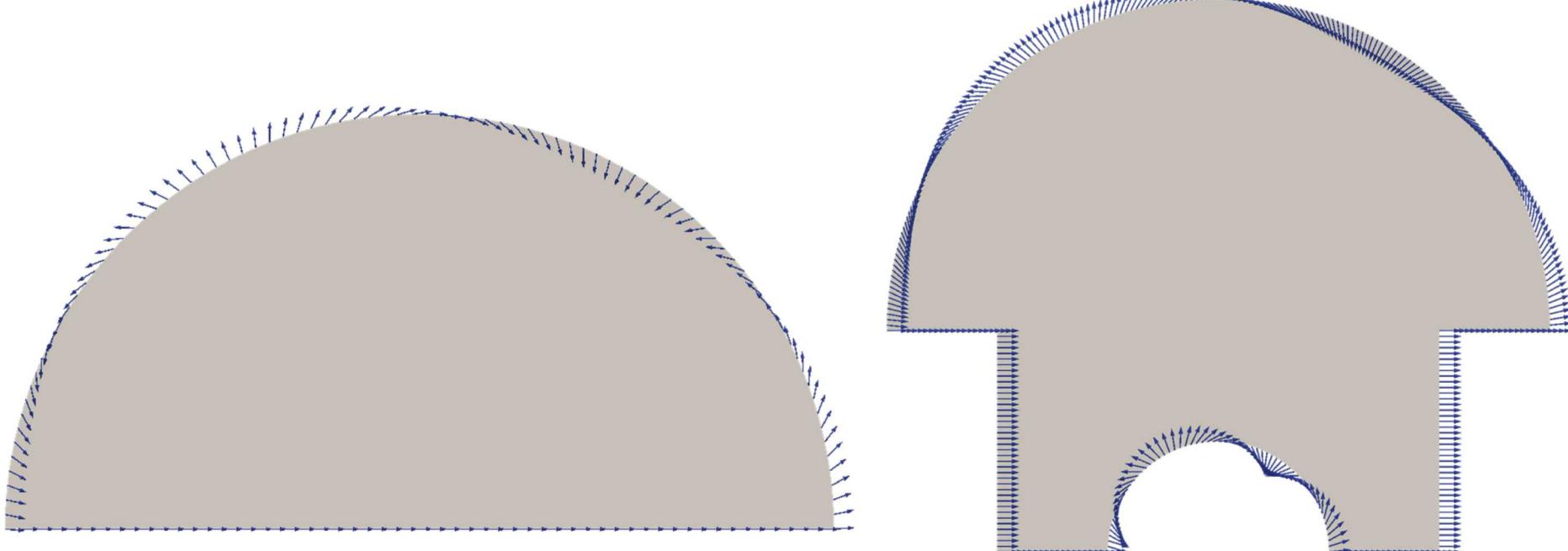


C



# Brouwer Degree

- Let  $g(x)$  be the boundary condition on the domain  $G$ .
- Let  $d = \deg(g, \partial G)$  be the Brouwer degree.



$d = 2$

$d = 0$

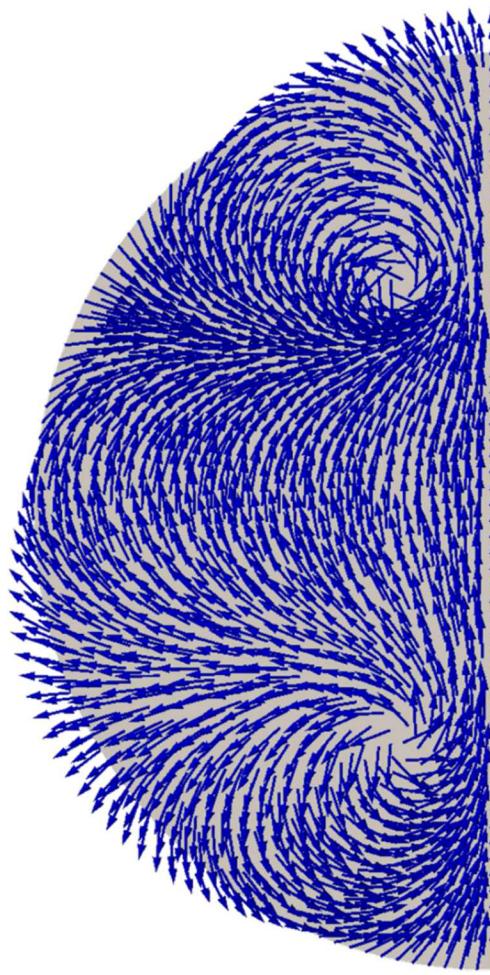
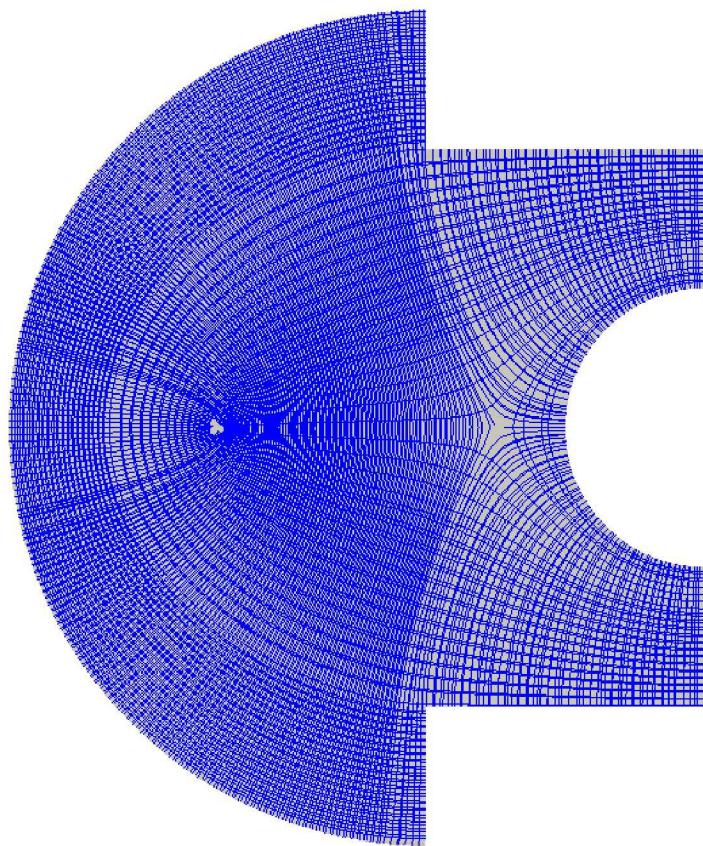
# Explicit Formula to Design Field with Fixed Singularities

$$e^{i\varphi_0(z)} = g(z) \frac{|z - b_1|^{\alpha_1}}{(z - b_1)^{\alpha_1}} \frac{|z - b_2|^{\alpha_2}}{(z - b_2)^{\alpha_2}} \cdots \frac{|z - b_n|^{\alpha_n}}{(z - b_n)^{\alpha_n}}$$

$$\begin{cases} \Delta\varphi = 0 \text{ in } D \\ \varphi = \varphi_0 \text{ on } \partial D \end{cases}$$

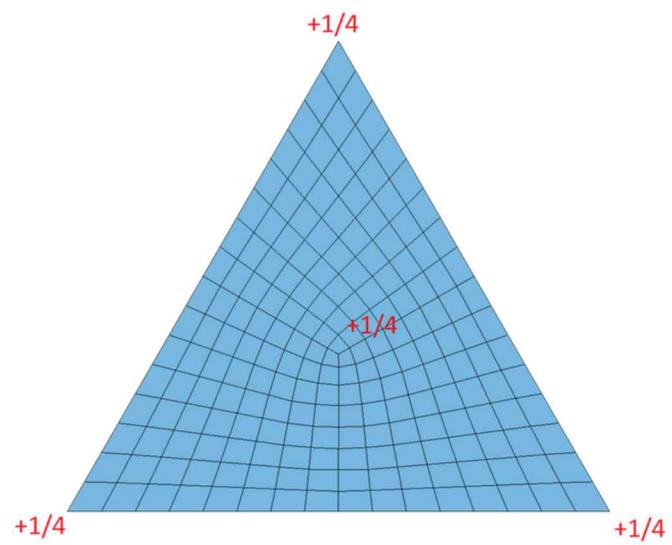
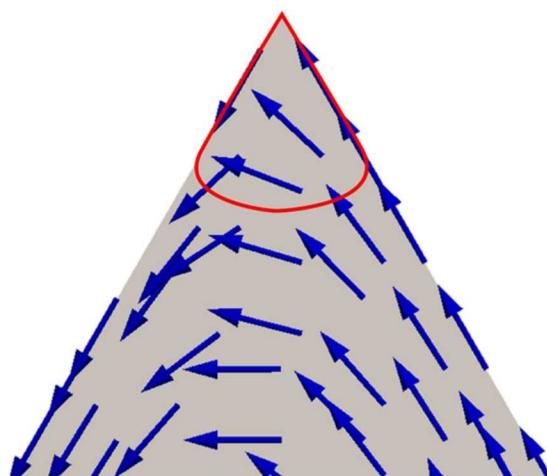
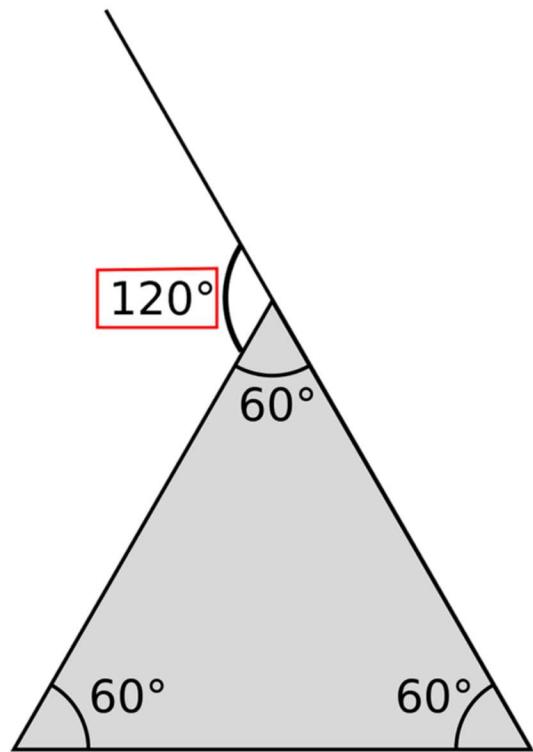
$$u_0 = e^{i\varphi(z)} \frac{(z - b_1)^{\alpha_1}}{|z - b_1|^{\alpha_1}} \frac{(z - b_2)^{\alpha_2}}{|z - b_2|^{\alpha_2}} \cdots \frac{(z - b_n)}{|z - b_n|^{\alpha_n}}$$

# Application: New Cross Field Design Method

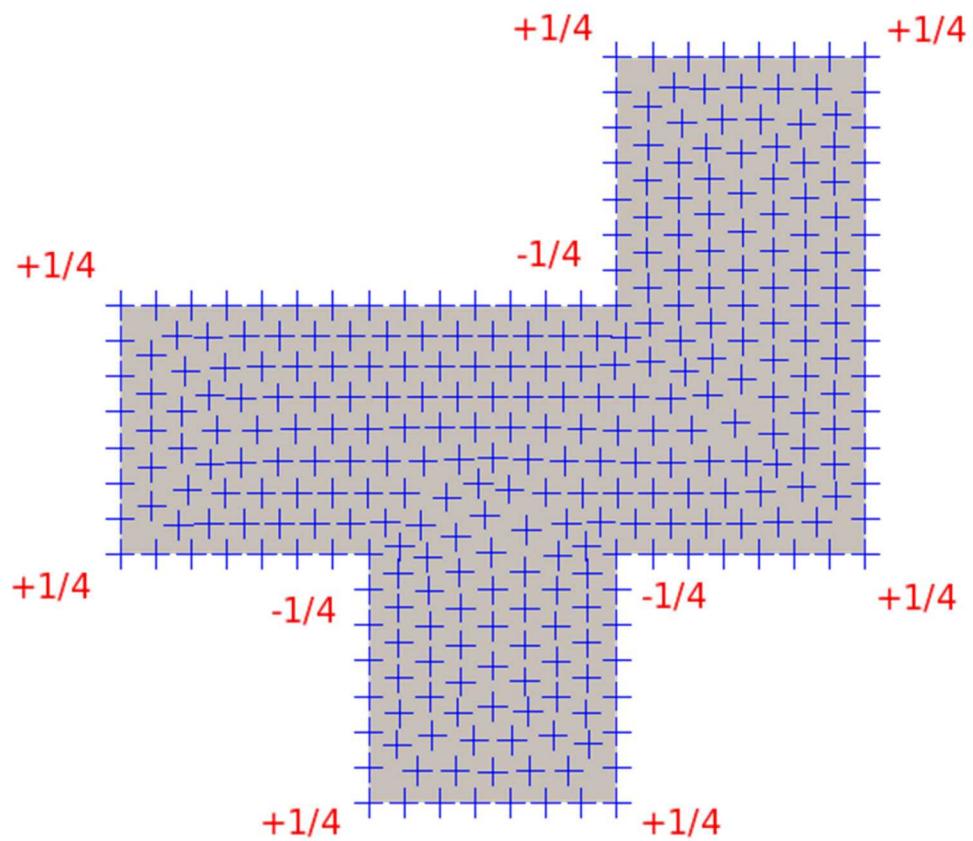
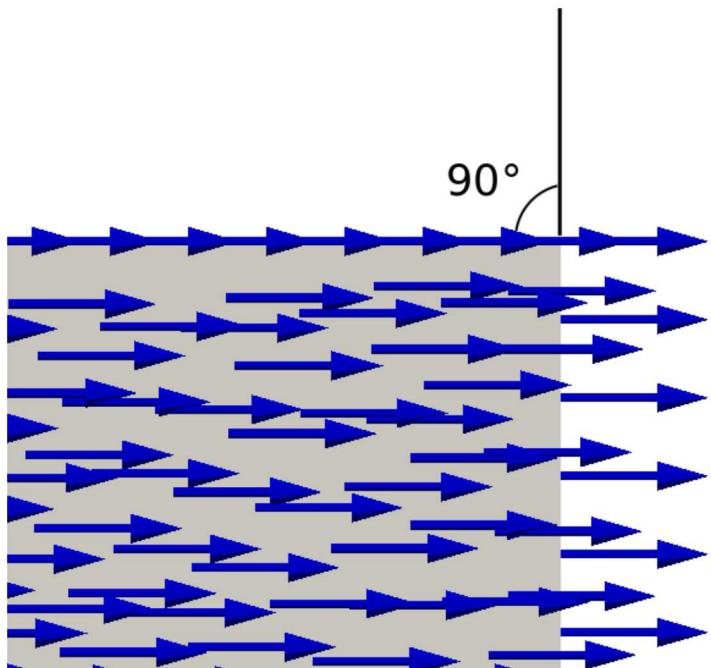


# Boundary Singularities

$$\lim_{s \downarrow 0} \frac{\operatorname{dev}(c_i) - \frac{1}{4}[\arg R(f(\gamma(s))) - \arg R(f(\gamma(1-s)))]}{2\pi}$$



# Boundary Singularities



# Singularity Indices

