



Energy Storage Models for Risk-Averse Optimization

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Self-guided-summary

Main idea

Models

This proposed BESS controller performs better and/or is more robust to fluctuating capacity than the state-of-the-art controllers.

Abstract—When batteries supply behind-the-meter services such as arbitrage or peak load management, an optimal controller can be designed to minimize the total electric bill. The limitations of the batteries, such as on voltage or state-of-charge, are represented in the model used to forecast the system's state dynamics. Control model inaccuracy can lead to an optimistic shortfall, where the achievable schedule will be costlier than the schedule derived using the model. To improve control performance and avoid optimistic shortfall, we develop a novel methodology for high performance, risk-averse battery energy storage controller design. Our method is based on two contributions. First, the application of a more accurate, but non-convex, battery system model is enabled by calculating upper and lower bounds on the globally optimal control solution. Second, the battery model is then modified to consistently underestimate capacity by a statistically selected margin, thereby hedging its control decisions against normal variations in battery system performance. The proposed model predictive controller, developed using this methodology, performs better and is more robust than the state-of-the-art approach, achieving lower bills for energy customers and being less susceptible to popular statement.

Popular Statement
Consider a hypothetical commercial electrical customer billed for power under both time-of-use (TOU) and a \$50/kW demand charge. Electric Bill without

$f_{\text{bill}} = \Delta t \mathbf{c}^T \mathbf{1} + \max(\mathbf{l}) d$

Electric Bill with

$f_{\text{bill}} = \Delta t \mathbf{c}^T (\mathbf{1} + \mathbf{p}) + \max(\mathbf{l} + \mathbf{p}) d$

where \mathbf{p} is the battery system power that element wise subtracts from \mathbf{l} when the battery system is discharging. The problem is thus formulated: design a control algorithm to optimally calculate a vector of battery system power that minimize f_{bill} a customer's bill without exceeding the battery's limits

Methods

We compare three controller models: the state-of-the-art energy reservoir model (ERM), a more accurate charge reservoir model (CRM), and a modified risk-averse CRM. To perform a **pseudo-empirical analysis** of the optimal schedules calculated from each model we simulate how the battery system would respond to each control signal using an extended CRM that incorporates additional constraints and parameters to improve its accuracy. The simulation model uses slightly different functions and parameters, enabling an analysis of the effects of model and parameter uncertainty on controller performance.

Simulation Results

The results of all three models, with open-loop and closed-loop implementation, are compared using a simulation model with either mean capacity, or extreme capacity. Total bill reduction is used to measure performance and optimistic short-fall is used to measure robustness.

TABLE VI
SUMMARY OF RESULTS FROM SIMULATED CONTROL SCENARIOS

Controller Scenario	Sim-Model*	Total Bill	% Savings	Optimistic Short-fall**
Baseline	—	\$310.88	—	—
ERM OL Cal	—	\$274.91	11.6%	—
ERM OL Ach	mean	\$273.93	11.9%	-\$0.98
ERM CL Ach	mean	\$273.56	12.0%	-\$1.35
ERM CL Ach	extreme	\$273.69	12.0%	-\$1.22
—upper bound	—	\$272.72✓	—	—
CRM OL Cal	—	\$269.55	13.3%	—
—lower bound	—	\$228.89✓	—	—
CRM OL Ach	mean	\$274.98	11.5%	\$5.43
CRM CL Ach	mean	\$269.55	13.3%	\$0.00
CRM CL Ach	extreme	\$292.53	5.9%	\$22.98
—upper bound	—	\$274.21✓	—	—
RA CRM OL Cal	—	\$271.22	12.8%	—
—lower bound	—	\$235.35✓	—	—
RA CRM OL Ach	mean	\$271.17	12.8%	-\$0.05
RA CRM CL Ach	mean	\$271.08	12.8%	-\$0.14
RA CRM CL Ach	extreme	\$271.21	12.8%	-\$0.01

✓denotes that the solution to the non-convex problem satisfies the bound
* The extended CRM is used to simulate the BESS being controlled. It's parameters are selected to represent average behavior "mean", or "extreme case" lower than normal available energy as described in Section VI
** Optimistic Shortfall compares the bill achieved by applying control action to the simulated BESS to the open-loop calculated bill from each controller
Cal - calculated, Ach - achieved, OL - open-loop, CL - closed-loop, RA - risk-averse

Conclusions

- In this paper we develop and demonstrate an advanced methodology for designing BESS controllers under ToU price arbitrage and peak demand charge management applications.
- The proposed CRM based model predictive controller outperforms the ERM, but is sensitive to BESS capacity.
- The risk-averse CRM still outperforms the ERM, but is more robust to variations in BESS performance
- This methodology for can be applied wherever the risk profile of a scheduled service is asymmetric.
- Incremental improvements in controller performance can reduce the cost of deploying storage to

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Energy Reservoir Model

$$\text{(ERM)} \min_{\mathbf{x}_e \in \mathbb{R}^{n+3}} \Delta t \mathbf{c}^T (\mathbf{1} + \mathbf{p}^+ + \mathbf{p}^-) + \tau d + \Pi_1 \|\mathbf{p}^+ + \mathbf{p}^-\|_2^2 \quad (3a)$$

$$\text{subject to: } Q_{\text{cap}} \mathbf{D} \mathbf{s} = \eta_e \mathbf{p}^+ + \mathbf{p}^- \quad (3b)$$

$$\mathbf{s}[1] = \mathbf{s}_0 \quad (3c)$$

$$\mathbf{s}[1] = \mathbf{s}[n] \quad (3d)$$

$$[\mathbf{0}] \leq \mathbf{p}^+ \leq p_{\text{max}}[\mathbf{1}] \quad (3e)$$

$$p_{\text{min}}[\mathbf{1}] \leq \mathbf{p}^- \leq [\mathbf{0}] \quad (3f)$$

$$s_{\text{min}}[\mathbf{1}] \leq \mathbf{s} \leq s_{\text{max}}[\mathbf{1}] \quad (3g)$$

$$\mathbf{1} + \mathbf{p}^+ + \mathbf{p}^- \leq \tau[\mathbf{1}] \quad (3g)$$

where $\mathbf{x}_e = \{\mathbf{p}^+, \mathbf{p}^-, \mathbf{s}, \tau\} \in \mathbb{R}^{3n+2}$, $\mathbf{p}^+ \in \mathbb{R}_+^n$ is the ac electrical power provided to charge battery system, $\mathbf{p}^- \in \mathbb{R}_-^n$ is the ac electrical power discharged from the battery system, $\mathbf{s} \in \mathbb{R}^{n+1}$ is the battery SoC, $\tau \in \mathbb{R}$ is the peak demand power and the differential matrix \mathbf{D} is shown in (4).

$$\mathbf{D} = \frac{1}{\Delta t} \begin{bmatrix} -1 & 1 & 0 & \cdot & \cdot & 0 \\ 0 & -1 & 1 & 0 & \cdot & \cdot \\ & & \cdot & \cdot & \cdot & \cdot \\ 0 & & & \cdot & \cdot & 1 \end{bmatrix}_{n \times (n+1)} \quad (4)$$

Charge Reservoir Model

$$\text{(CRM)} \min_{\mathbf{x}_e \in \mathbb{R}^{n+3}} \Delta t \mathbf{c}^T (\mathbf{1} + \mathbf{p}) + \tau d + \Pi_1 \|\mathbf{p}\|_2^2 + \Pi_2 \|\mathbf{v}_s\|_1 \quad (5a)$$

$$\text{subject to: } \phi_0 \mathbf{p}^2 + \phi_1 \mathbf{p} + \phi_2 \geq \mathbf{p}_{\text{dc}} \quad (5b)$$

$$\mathbf{p}_{\text{dc}} = (\mathbf{i}_{\text{bat}}^+ + \mathbf{i}_{\text{bat}}^-) \mathbf{v}_{\text{bat}} \quad (5c)$$

$$\mathbf{v}_{\text{bat}} = \mathbf{v}_{\text{oc}}[1:n] + R_0(\mathbf{i}_{\text{bat}}^+ + \mathbf{i}_{\text{bat}}^-) + \mathbf{v}_s \quad (5d)$$

$$\mathbf{v}_{\text{oc}} = \alpha \mathbf{s}^3 + \beta \mathbf{s}^2 + \gamma \mathbf{s} + \delta \quad (5e)$$

$$C_{\text{cap}} \mathbf{D} \mathbf{s} = \eta_e \mathbf{i}_{\text{bat}}^+ + \mathbf{i}_{\text{bat}}^- \quad (5f)$$

$$\mathbf{s}_1 = \mathbf{s}_0 \quad (5g)$$

$$\mathbf{s}_1 = \mathbf{s}_{n+1} \quad (5h)$$

$$p_{\text{min}}[\mathbf{1}] \leq \mathbf{p} \leq p_{\text{max}}[\mathbf{1}] \quad (5i)$$

$$s_{\text{min}}[\mathbf{1}] \leq \mathbf{s} \leq s_{\text{max}}[\mathbf{1}] \quad (5j)$$

$$v_{\text{min}}[\mathbf{1}] \leq \mathbf{v}_{\text{bat}} \leq v_{\text{max}}[\mathbf{1}] \quad (5k)$$

$$[\mathbf{0}] \leq \mathbf{i}_{\text{bat}}^+ \leq i_{\text{max}}[\mathbf{1}] \quad (5l)$$

$$i_{\text{min}}[\mathbf{1}] \leq \mathbf{i}_{\text{bat}}^- \leq [\mathbf{0}] \quad (5m)$$

$$\mathbf{1} + \mathbf{p} \leq \tau[\mathbf{1}] \quad (5n)$$

where $\mathbf{x}_e = \{\mathbf{p}, \mathbf{p}_{\text{dc}}, \mathbf{i}_{\text{bat}}^+, \mathbf{i}_{\text{bat}}^-, \mathbf{v}_{\text{bat}}, \mathbf{v}_s, \mathbf{v}_{\text{oc}}, \mathbf{s}, \tau\} \in \mathbb{R}^{8n+3}$, $\mathbf{p}_{\text{dc}} \in \mathbb{R}^n$ is the dc electrical power provided to battery, $\mathbf{v}_{\text{bat}} \in \mathbb{R}^n$ is the battery terminal voltage, $\mathbf{v}_s \in \mathbb{R}_+^n$ is the slack voltage used in calculation of an upper bound, $\mathbf{v}_{\text{oc}} \in \mathbb{R}^{n+1}$ is the battery open-circuit voltage, and $\tau \in \mathbb{R}$ is the peak power demand.

Risk-Averse Capacity (value at

$$\tilde{C}_{\text{cap}} = \min\{C_{\text{cap}} \in \mathbb{R} \mid \mathbb{P}(\tilde{C}_{\text{cap}} \leq C_{\text{cap}}) \geq 0.13\% \} \quad (9)$$

where $\tilde{C}_{\text{cap}} \sim \mathcal{N}(\mu = 0, \sigma = 2.6\text{Ah})$ is the random component of the battery's capacity, assumed to be a zero-mean, normal distribution.

$$\tilde{C}_{\text{cap}} = \min\{C_{\text{cap}} \in \mathbb{R} \mid \mathbb{P}(\tilde{C}_{\text{cap}} \leq C_{\text{cap}}) \geq 0.13\% \} \quad (10)$$

Bounding the Global Minimum

The CRM is a non-convex, non-pseudoconvex problem, hence we cannot guarantee that a gradient based solver will find the globally optimal solution. An upper bound to a minimization problem can be found by restricting the feasible set (adding additional constraints) while a lower bound can be calculated by expanding the feasible set (relaxing or removing constraints).

Lower Bound (convex relaxation)

$$\min_{\mathbf{x}_e \in \mathbb{R}^{8n+3}} \Delta t \mathbf{c}^T (\mathbf{1} + \mathbf{p}) + \tau d + \Pi_1 \|\mathbf{p}\|_2^2 + \Pi_2 \|\mathbf{v}_s\|_1 \quad (11)$$

$$\mathbf{p}_{\text{dc}}^+ \in \mathbb{R}_+^n, \quad \mathbf{p}_{\text{dc}}^- \in \mathbb{R}_-^n$$

$$\text{subject to: } \text{ (5d) and (5f) through (5n) unchanged}$$

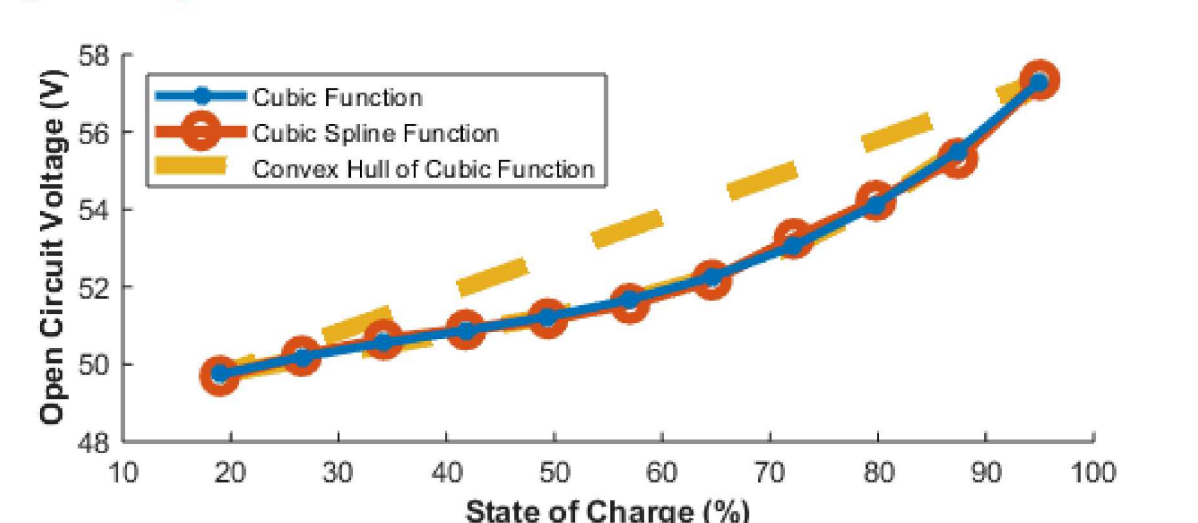
$$\text{relaxing (5b)} \quad \phi_0 \mathbf{p}^2 + \phi_1 \mathbf{p} + \phi_2 \geq \mathbf{p}_{\text{dc}}^+ + \mathbf{p}_{\text{dc}}^- \quad (7a)$$

$$\text{relaxing (5c)} \quad \mathbf{A}_1[\mathbf{i}_{\text{bat}}^+, \mathbf{v}_{\text{bat}}, \mathbf{p}_{\text{dc}}^+]^T \leq \mathbf{b}_1[\mathbf{1}]_{1 \times n} \quad (7b)$$

$$\mathbf{A}_2[\mathbf{i}_{\text{bat}}^-, \mathbf{v}_{\text{bat}}, \mathbf{p}_{\text{dc}}^-]^T \leq \mathbf{b}_2[\mathbf{1}]_{1 \times n} \quad (7c)$$

$$\text{relaxing (5e)} \quad \mathbf{A}_3[\mathbf{s}, \mathbf{v}_{\text{oc}}]^T \leq \mathbf{b}_3[\mathbf{1}]_{1 \times n} \quad (7d)$$

where \mathbf{p}_{dc}^+ and \mathbf{p}_{dc}^- are the charge and discharge dc powers respectively.



Upper Bound (convex restriction/approximation)

$$\min_{\mathbf{x}_e \in \mathbb{R}^{8n+3}} \Delta t \mathbf{c}^T (\mathbf{1} + \mathbf{p}) + \tau d + \Pi_1 \|\mathbf{p}\|_2^2 + \Pi_2 \|\mathbf{v}_s\|_1 \quad (12)$$

$$\mathbf{v}_{1-5} \in \mathbb{R}_+^{n+1}, \quad \mathbf{s}_{1-5} \in \mathbb{R}_+^{n+1}, \quad \mathbf{w}_{1-5} \in \{0, 1\}^{n+1}$$

$$\text{subject to: } \text{ (5b) and (5f) through (5n) unchanged}$$

$$\text{restricting (5c)} \quad \mathbf{p}_{\text{dc}} = (\mathbf{i}_{\text{bat}}^+ + \mathbf{i}_{\text{bat}}^-) \mathbf{v}_{\text{ocmin}} \quad (8a)$$

$$\text{restricting (5d)} \quad \mathbf{v}_{\text{ocmin}}[\mathbf{1}] = \mathbf{v}_{\text{oc}}[1:n] + R_0(\mathbf{i}_{\text{bat}}^+ + \mathbf{i}_{\text{bat}}^-) + \mathbf{v}_s \quad (8b)$$

$$\text{approx. (5e)} \quad \mathbf{v}_{\text{oc}} = \mathbf{v}_{\text{ocmin}}[\mathbf{1}] + \nu_1 + \nu_2 + \nu_3 + \nu_4 + \nu_5 \quad (8c)$$

$$\mathbf{s} = s_{\text{min}}[\mathbf{1}] + \mathbf{s}_1 + \mathbf{s}_2 + \mathbf{s}_3 + \mathbf{s}_4 + \mathbf{s}_5 \quad (8d)$$

$$[\nu_1, \nu_2, \nu_3, \nu_4, \nu_5]^T = \mathbf{A}_4[\mathbf{s}_1, \mathbf{s}_2, \mathbf{s}_3, \mathbf{s}_4, \mathbf{s}_5]^T \quad (8e)$$

$$s_{\text{seg}} \mathbf{w}_1 \leq \mathbf{s}_1 \leq s_{\text{seg}} \quad (8f)$$

$$s_{\text{seg}} \mathbf{w}_2 \leq \mathbf{s}_2 \leq s_{\text{seg}} \mathbf{w}_1 \quad (8g)$$

$$s_{\text{seg}} \mathbf{w}_3 \leq \mathbf{s}_3 \leq s_{\text{seg}} \mathbf{w}_2 \quad (8h)$$

$$s_{\text{seg}} \mathbf{w}_4 \leq \mathbf{s}_4 \leq s_{\text{seg}} \mathbf{w}_3 \quad (8i)$$

$$0 \leq \mathbf{s}_5 \leq s_{\text{seg}} \mathbf{w}_4 \quad (8j)$$