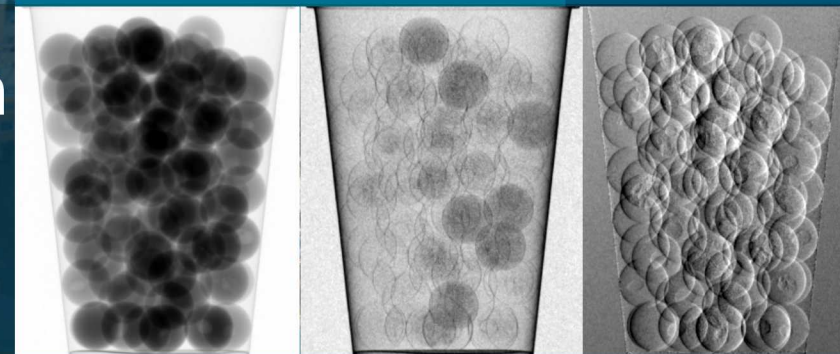
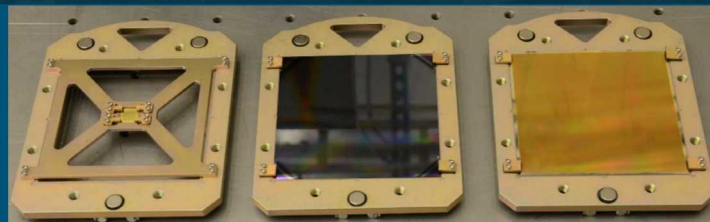
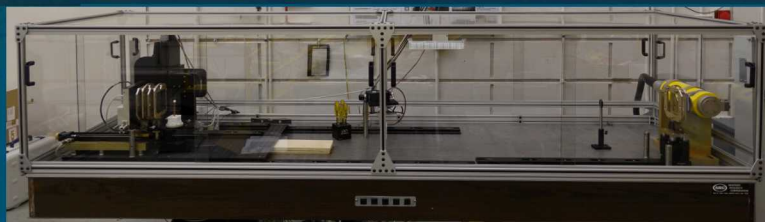


# Influence of Data Acquisition Algorithms on X-Ray Phase Contrast Imaging Computed Tomography



PRESENTED BY

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QNDE 2019

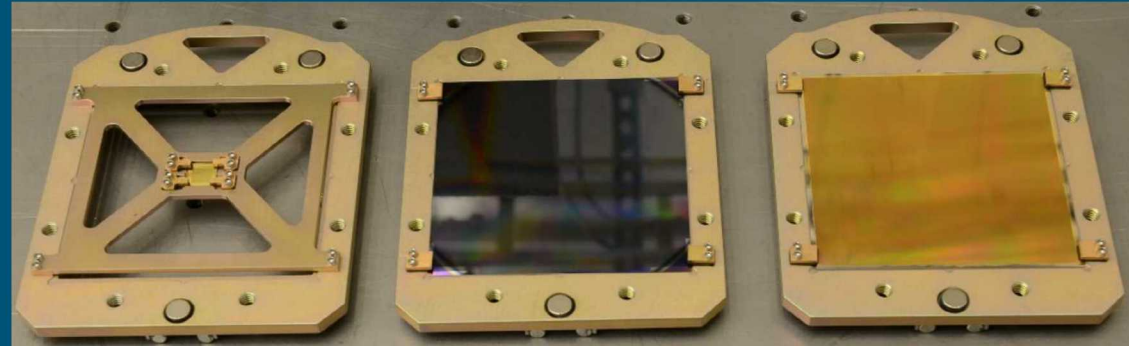
2019-07-16



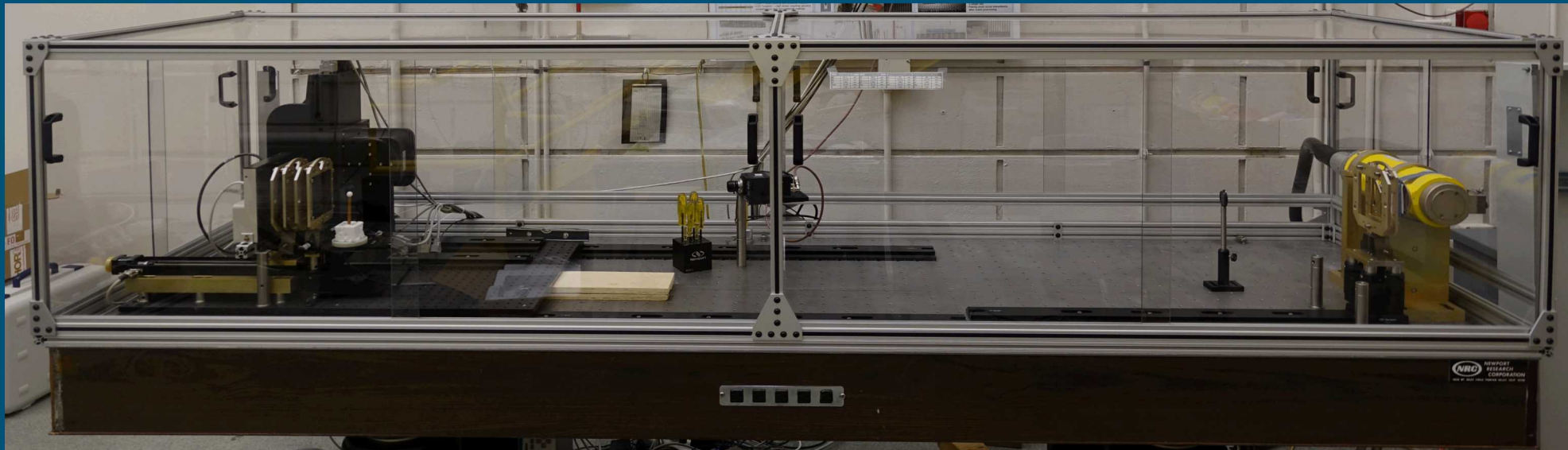
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SAND NO.

- X-ray Phase Contrast Imaging
- Acquisition Algorithms
- Data Comparison
- Conclusions



SNL large-area Talbot-Lau interferometer gratings



SNL Talbot-Lau XPCI System





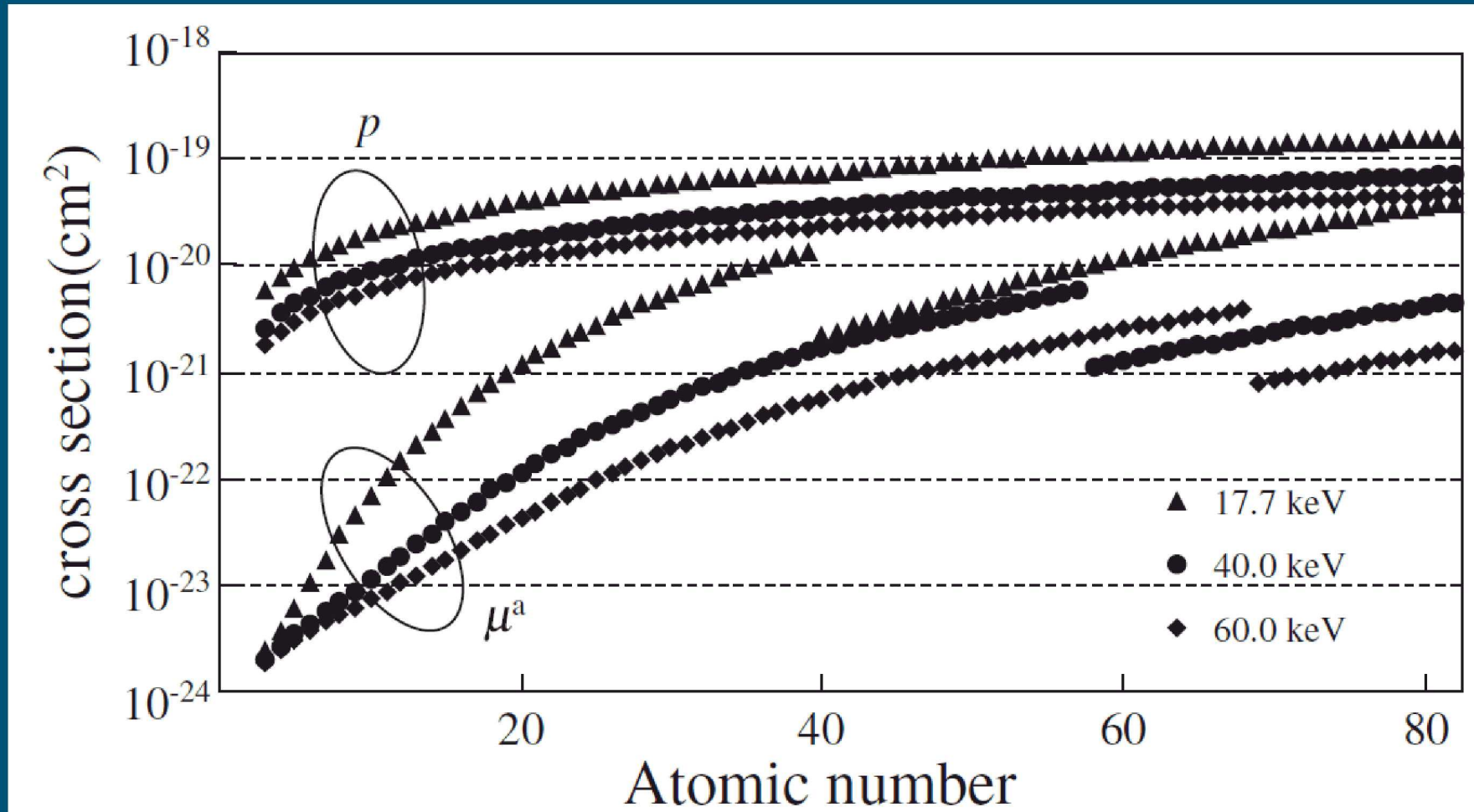
# X-Ray Phase Contrast Imaging

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A brief introduction

# XPCI succeeds where traditional radiography fails

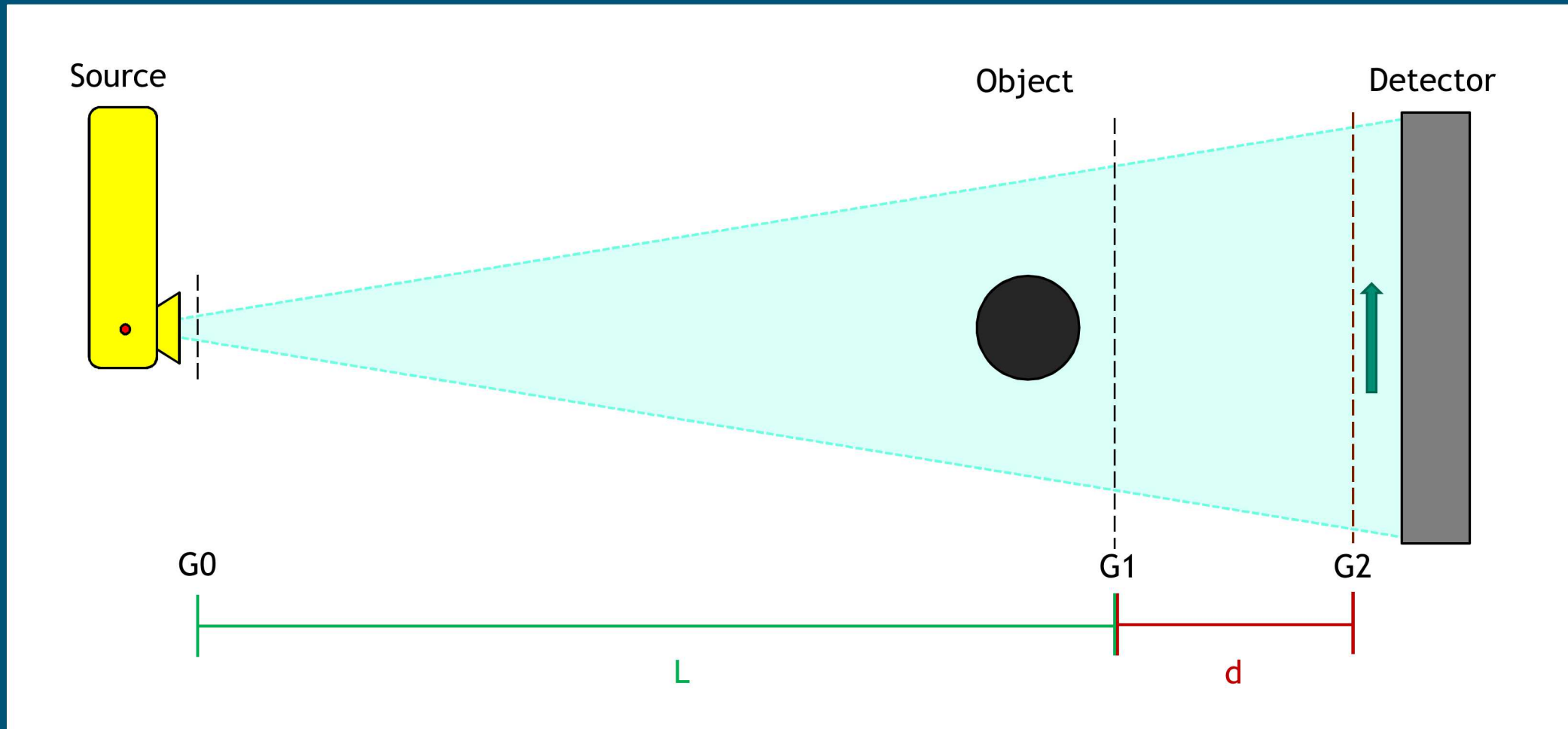
Traditional radiography yields low-contrast images for low-Z components



Momose, Atsushi. "Recent Advances in X-ray Phase Imaging." *Japanese Journal of Applied Physics* 44.9A (2005): 6355-367.

# Our apparatus implements a Talbot-Lau Interferometer

Grating interferometer enables phase imaging using laboratory X-ray sources

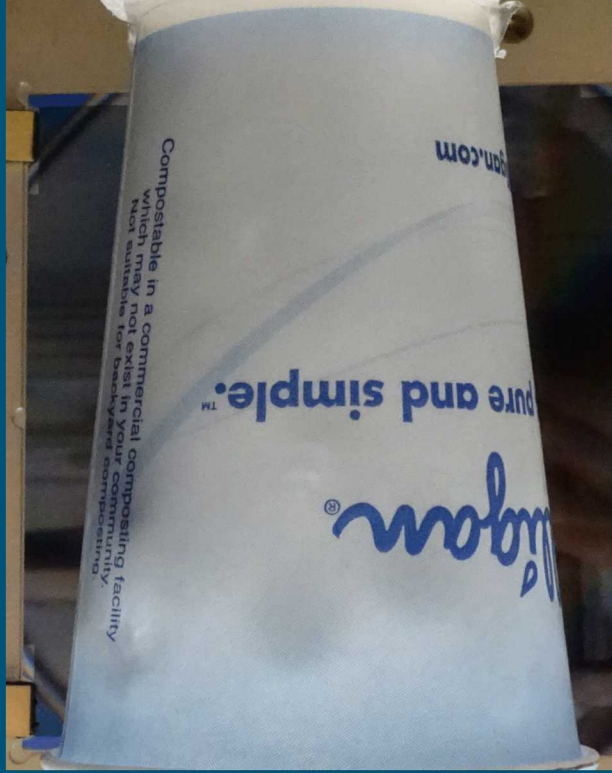




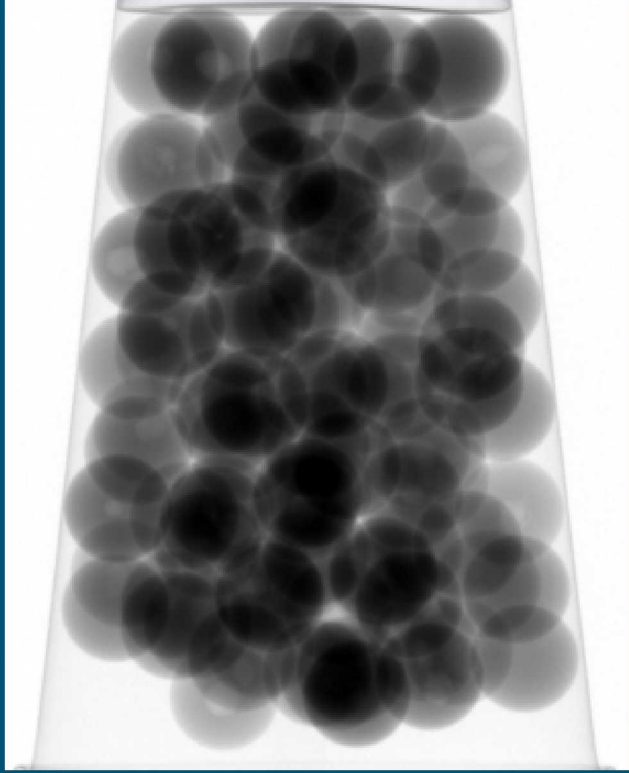
# XPCI yields Trimodal Image Data

Single image set reconstructed into three distinct image products

Photograph



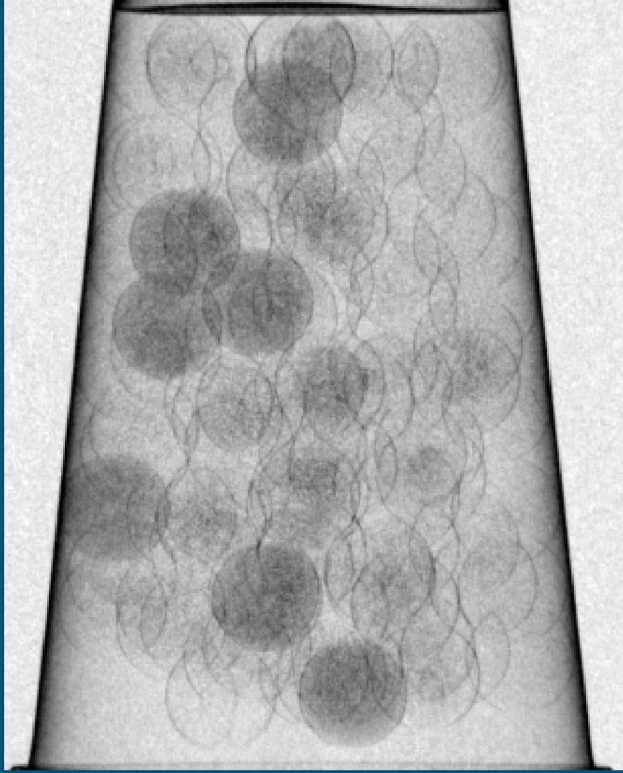
Tau



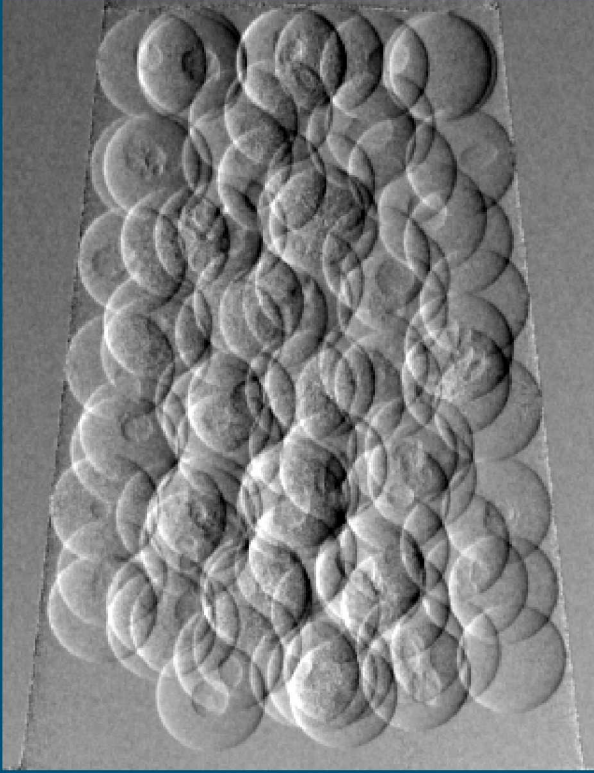
Absorption  
Projection 0

Small-Angle Scatter  
Projection 0

Dark Field

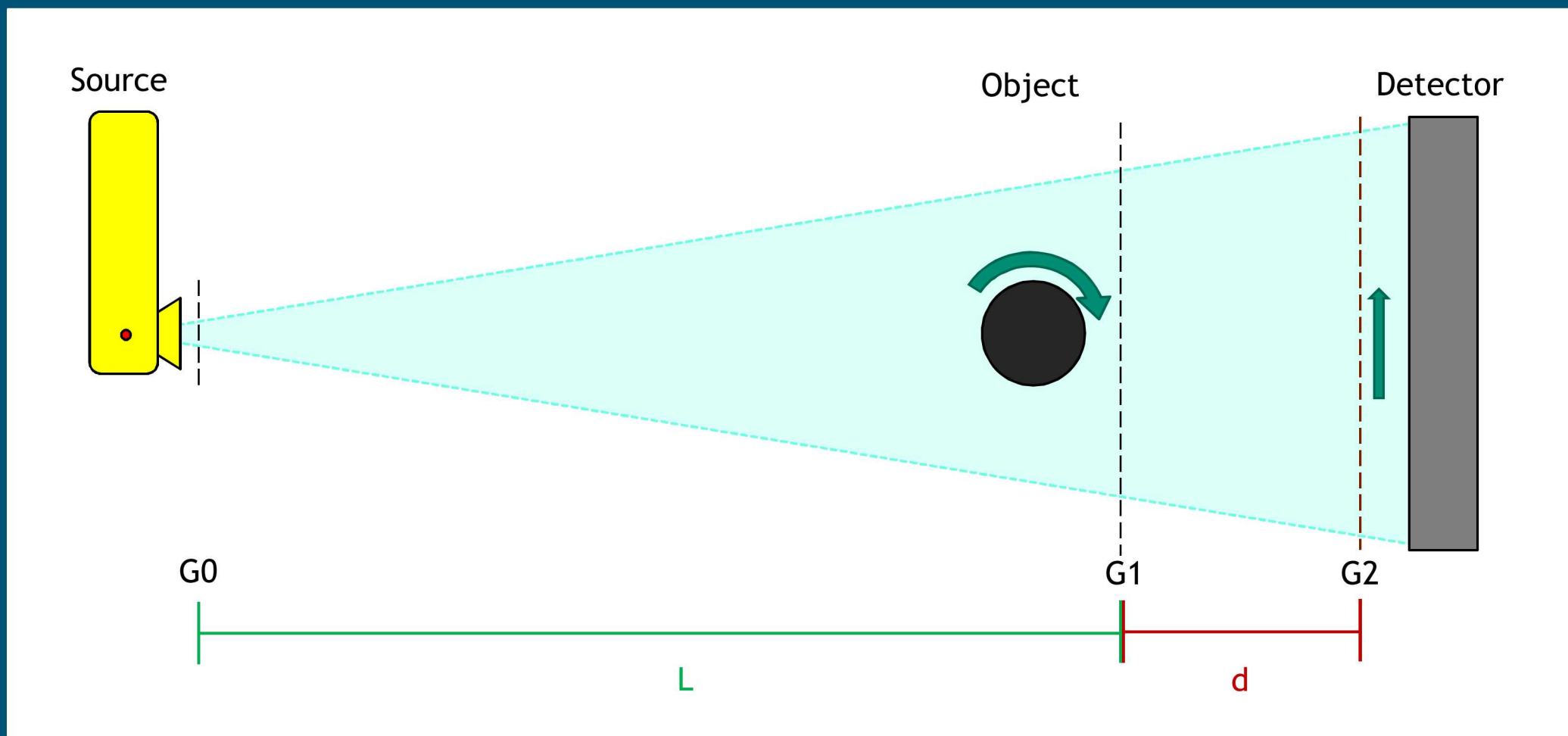


Differential Phase  
Refraction  
Projection 0



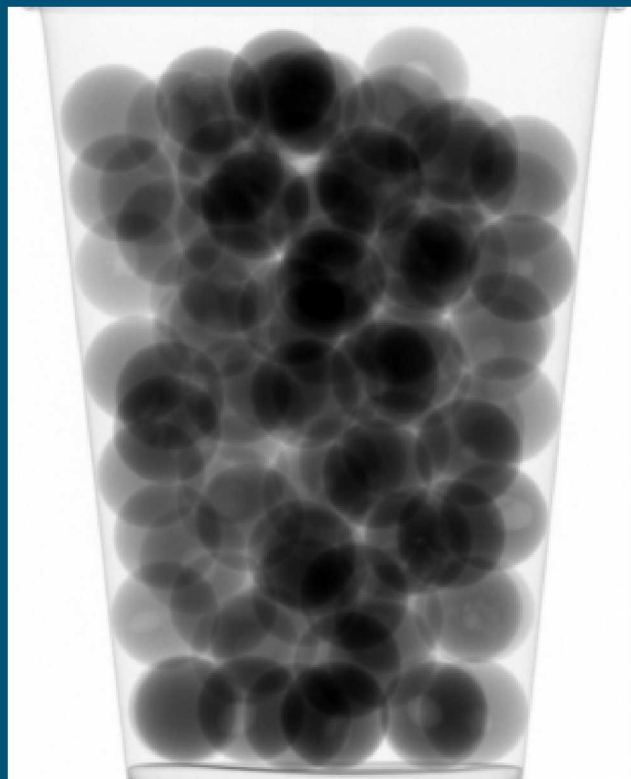
# Acquire volumetric data using Computed Tomography

Capture data for volumetric reconstruction by rotating object

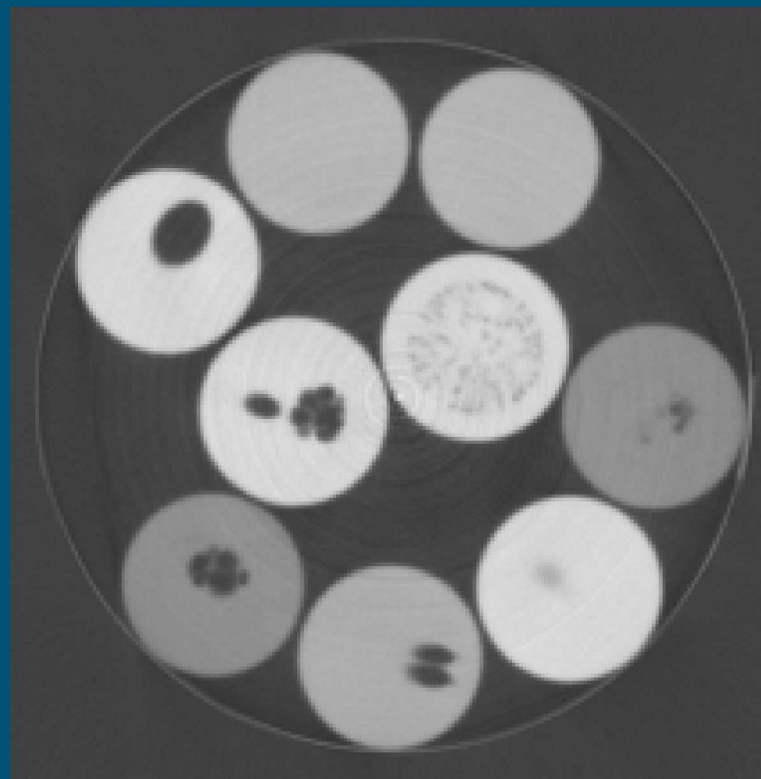


# CT Reconstruction reveals object internal structure

Set of projections reconstructed to set of slices within object volume



Tau  
Absorption  
Projection 0



Tau  
Absorption  
Slice 26





# Acquisition Algorithms

---

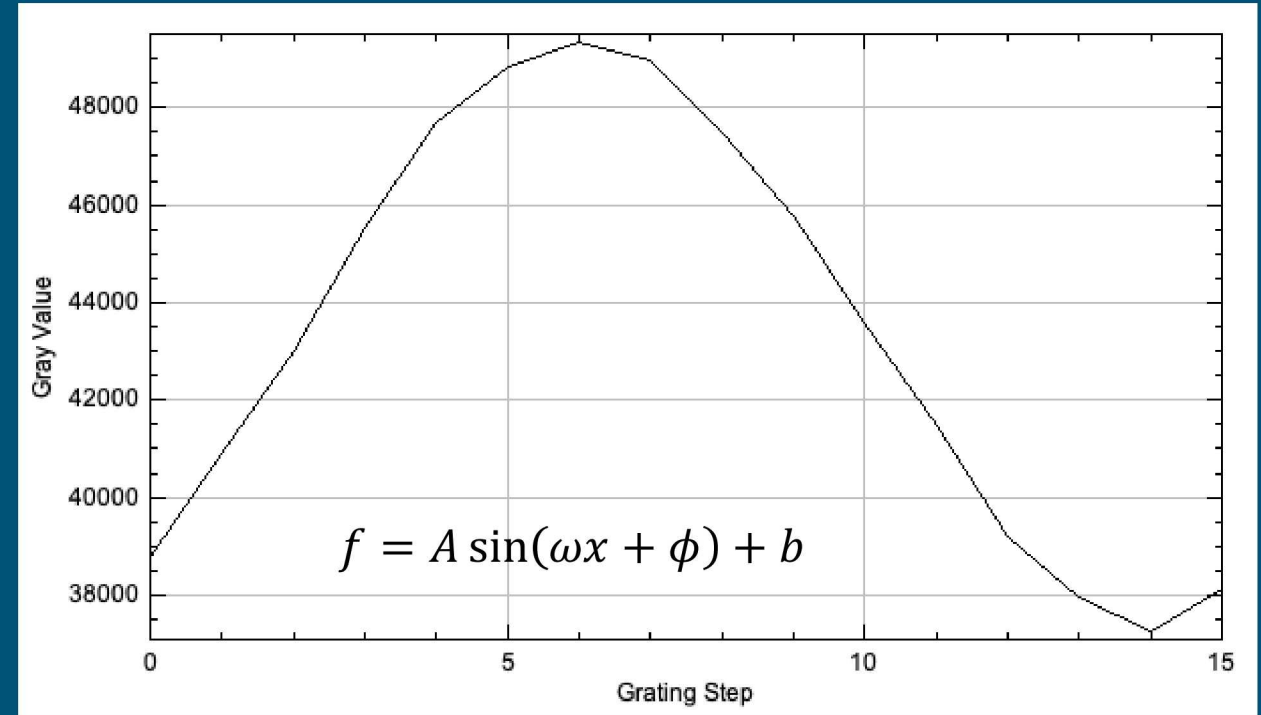
Different methods to acquire XPCI CT data

# XPCI CT Data requires analyzer grating translation

G2 grating translation causes translation of interferometer fringes



Raw reference image set (cropped)



Value of pixel (158, 236)

Tau

$$\tau = \frac{b_S}{b_R}$$

Dark Field

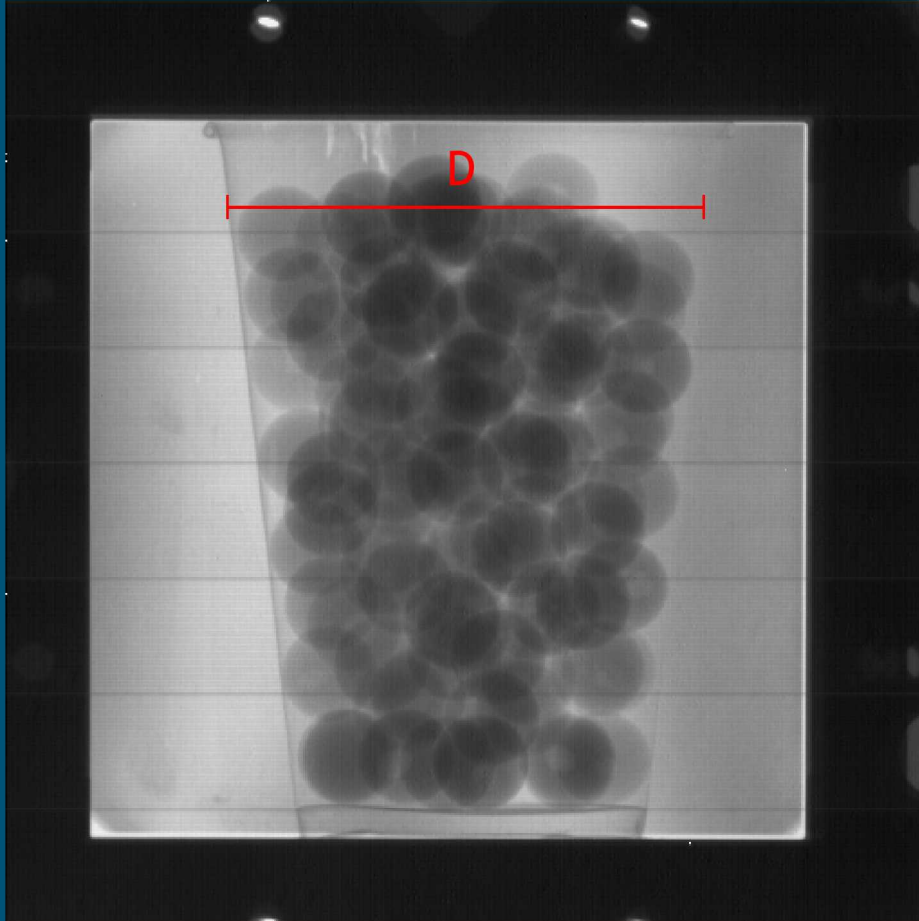
$$DF = \frac{A_S}{A_R} \times \frac{b_R}{b_S}$$

Differential Phase

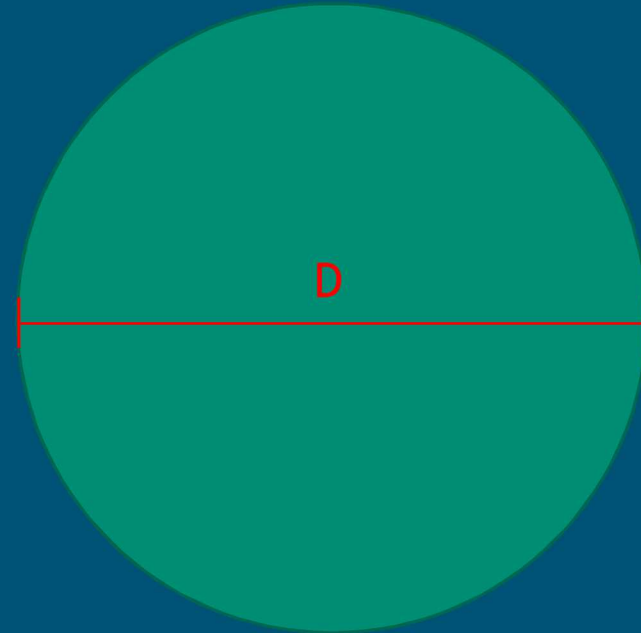
$$dP = \phi_S - \phi_R$$

# XPCI CT Data requires object rotation

Number of angular projections dictated by Shannon-Nyquist Theorem



Raw sample image



$$P \geq D * \frac{\pi}{2}$$



# Step First Algorithm

Outer loop = Rotating

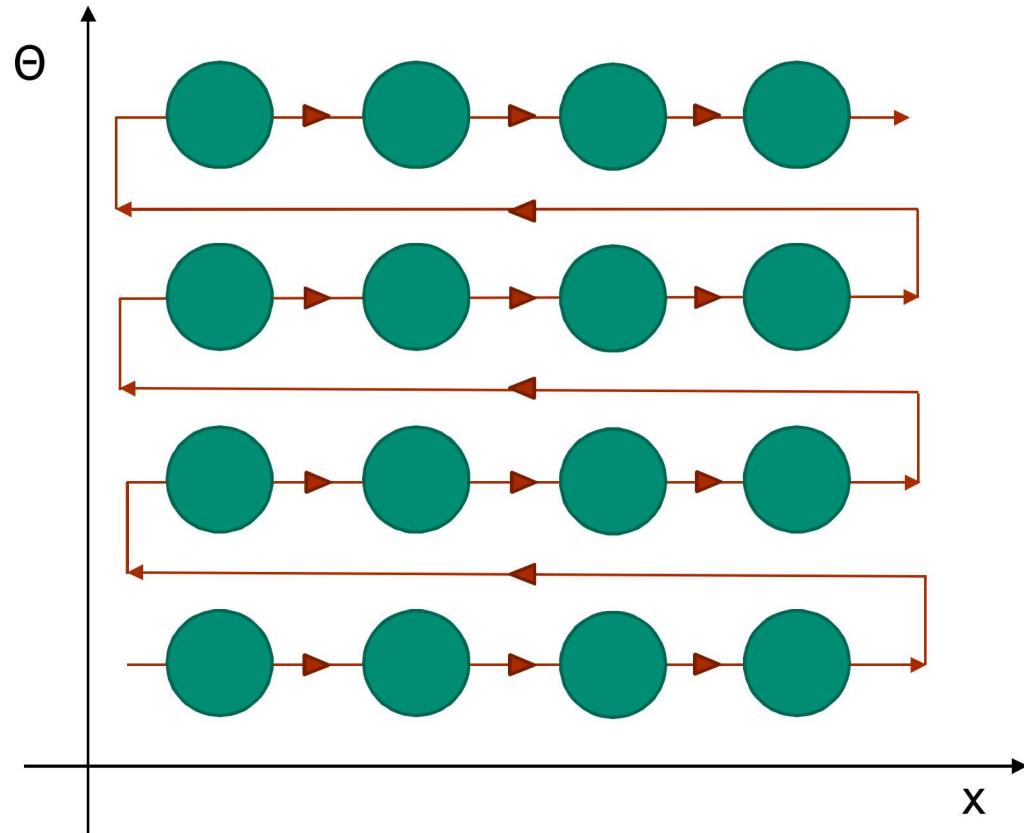
Inner loop = Phase stepping

Let  $\Theta$  = rotational angle,  $x$  = G2 grating position

```

for  $i := 0$  to  $CT\text{-}projections$  do
   $\theta = \theta_0 + \Delta\theta * i$ 
  for  $j := 0$  to  $G2\text{-}positions$  do
     $x = x_0 + \Delta x * j$ 
  end
end
end
  
```

PhaseCT1 Motion Parameter Space



# Rotate First Algorithm

Outer loop = Phase stepping

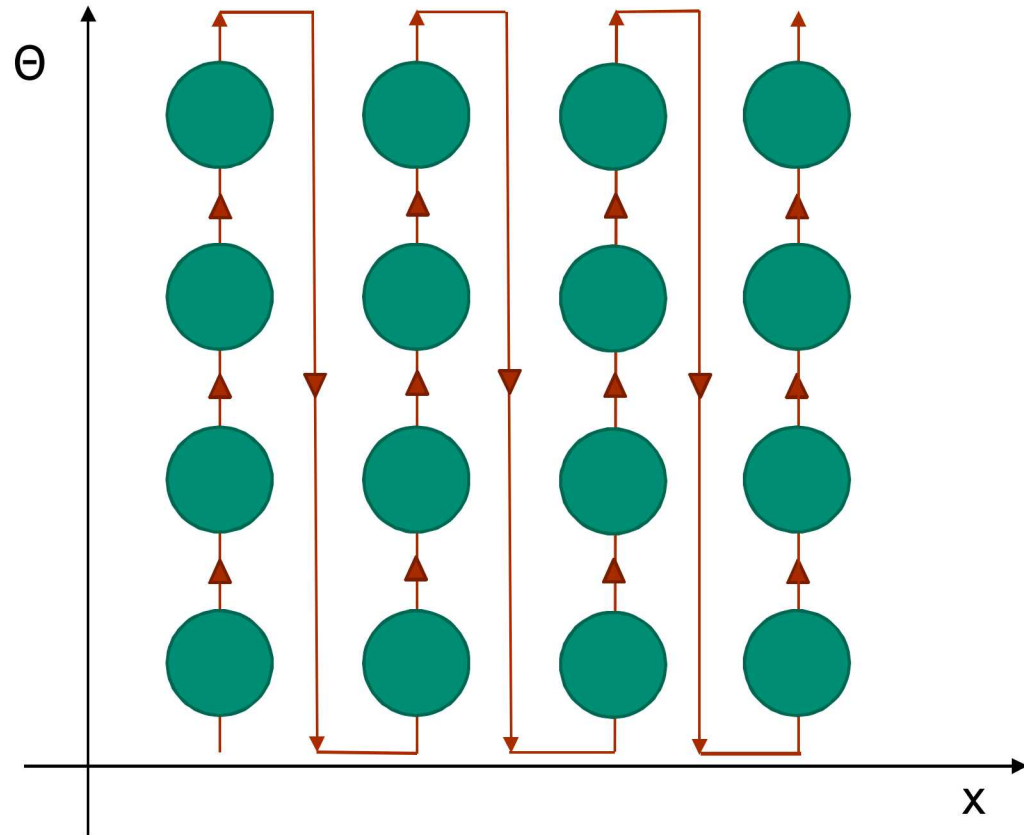
Inner loop = Rotating

Let  $\Theta$  = rotational angle,  $x$  = G2 grating position

```

for  $i := 0$  to  $G2\text{-positions}$  do
   $x = x_0 + \Delta x * i$ 
  for  $j := 0$  to  $CT\text{-projections}$  do
     $\theta = \theta_0 + \Delta\theta * j$ 
  end
end
end
  
```

PhaseCT2 Motion Parameter Space





# Data and Results

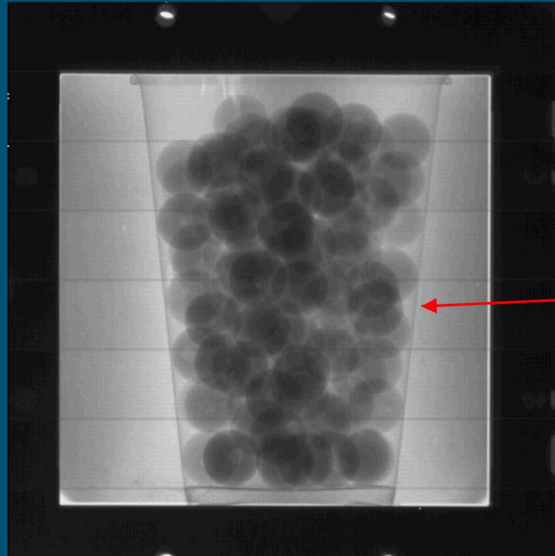
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Comparing images acquired with the different algorithms



# Fringe Motion Degradation apparent in Rotate First data

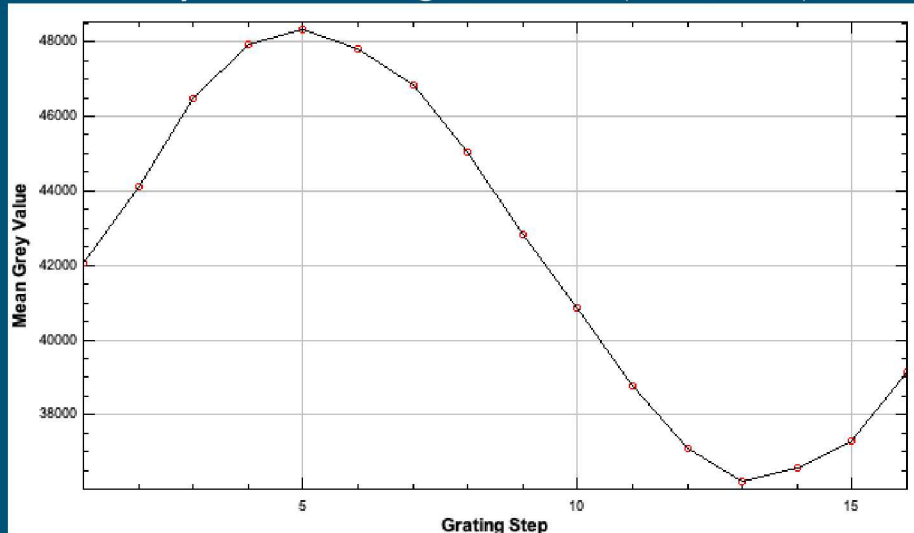
Superior fringe profile captured by Step First



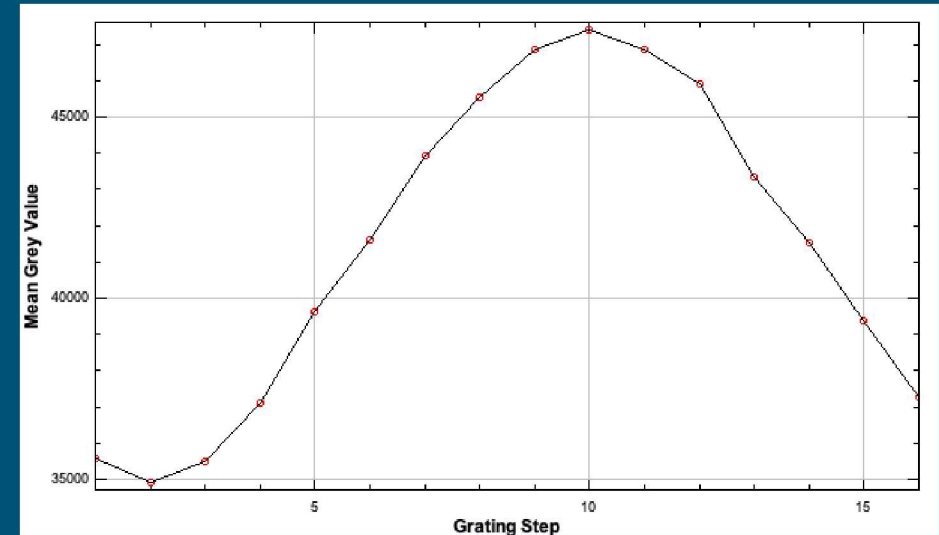
(280,130)

Raw sample image

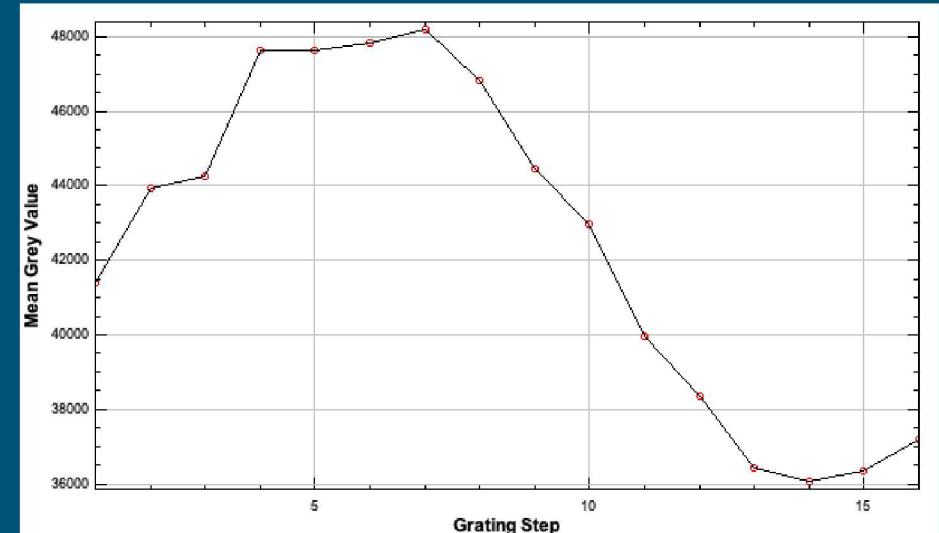
Step First Fringe, Pixel (280,130)



Reference Fringe, Pixel (280,130)



Rotate First Fringe, Pixel (280,130)

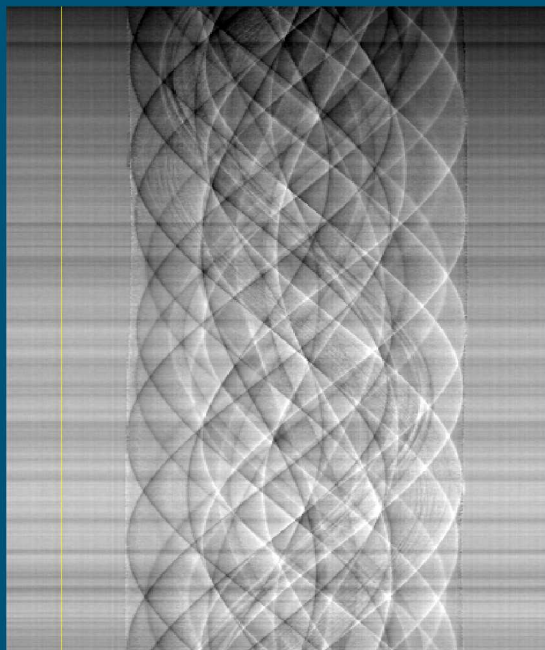


# Sinogram Intensity Variation appears in Step First Data

Smoother dP sinogram 'intensity' profile captured by Rotate First

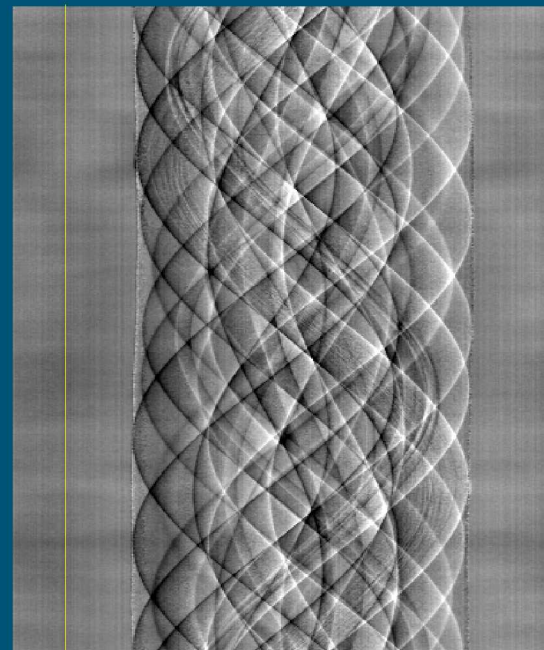
Step First  
Differential Phase

Slice 185



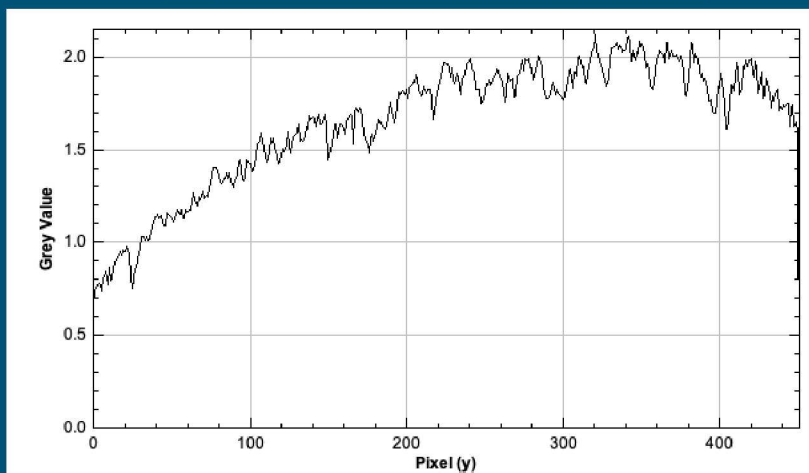
Rotate First  
Differential Phase

Slice 185



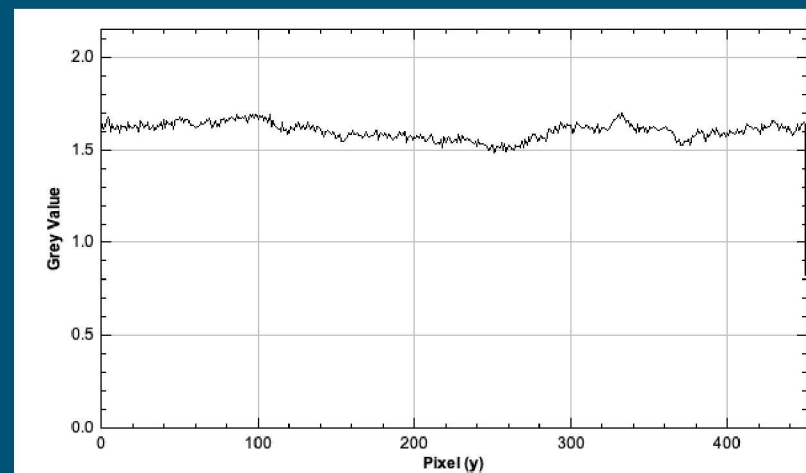
Step First  
Differential Phase

Slice 185  
Column X=50



Rotate First  
Differential Phase

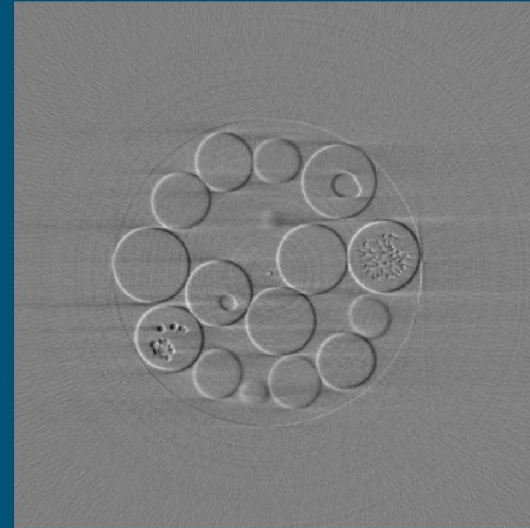
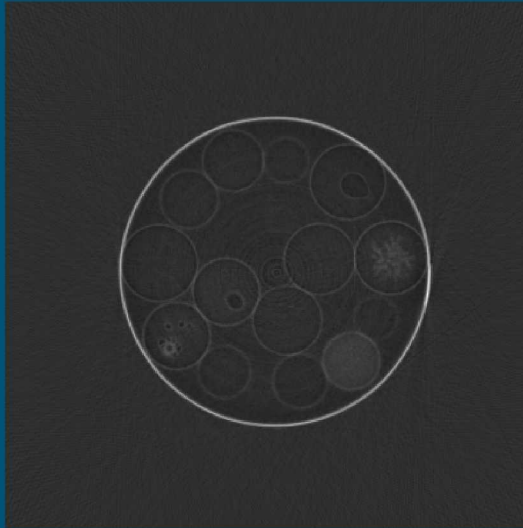
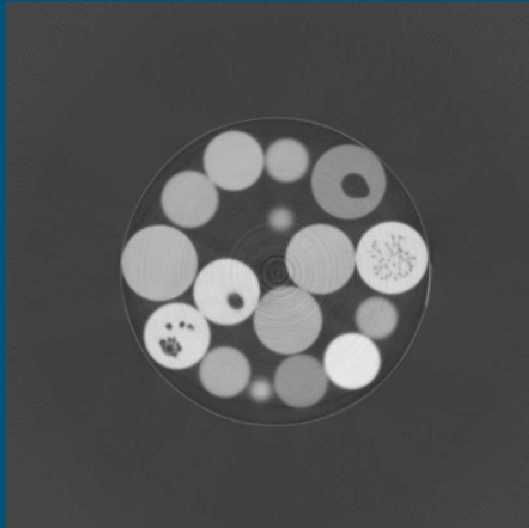
Slice 185  
Column X=50



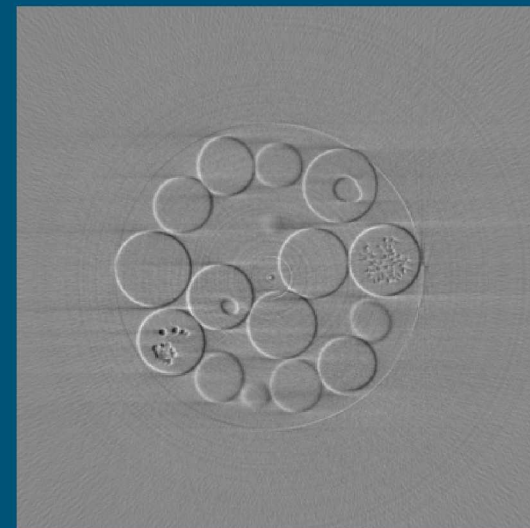
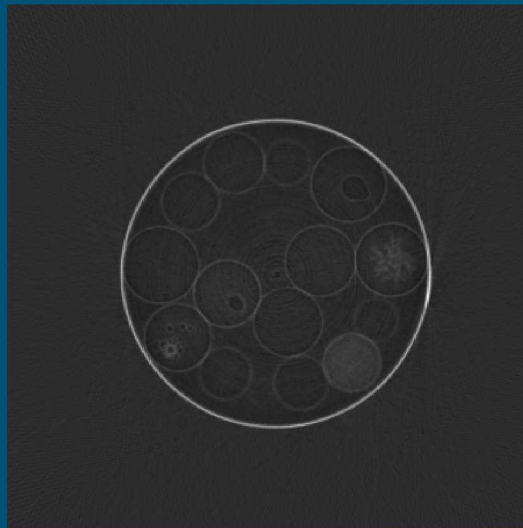
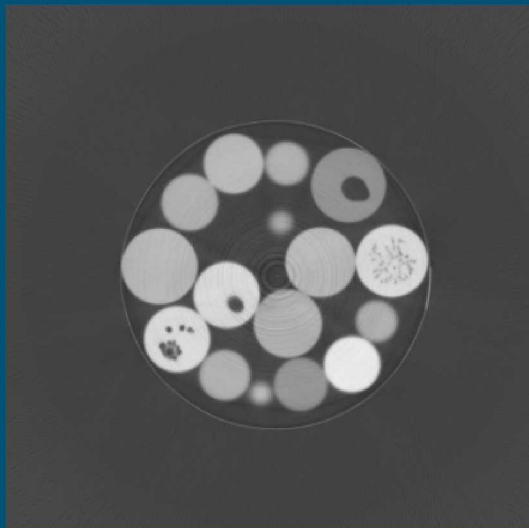
# CT Reconstructions yield similar results

Resulting CT reconstructions appear similar to the eye

Step First



Rotate First



Tau

Dark Field

Differential Phase

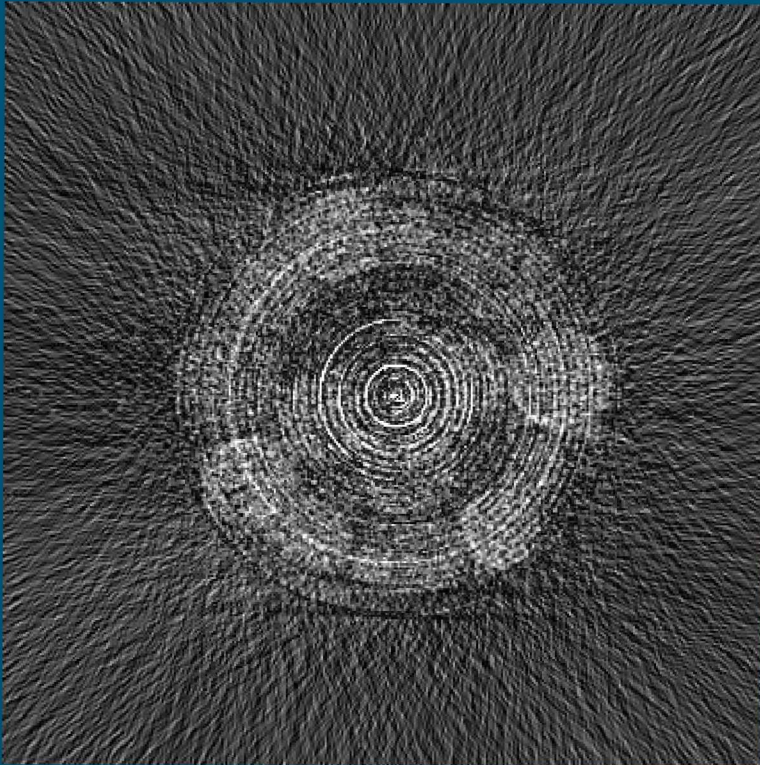
Slice 103



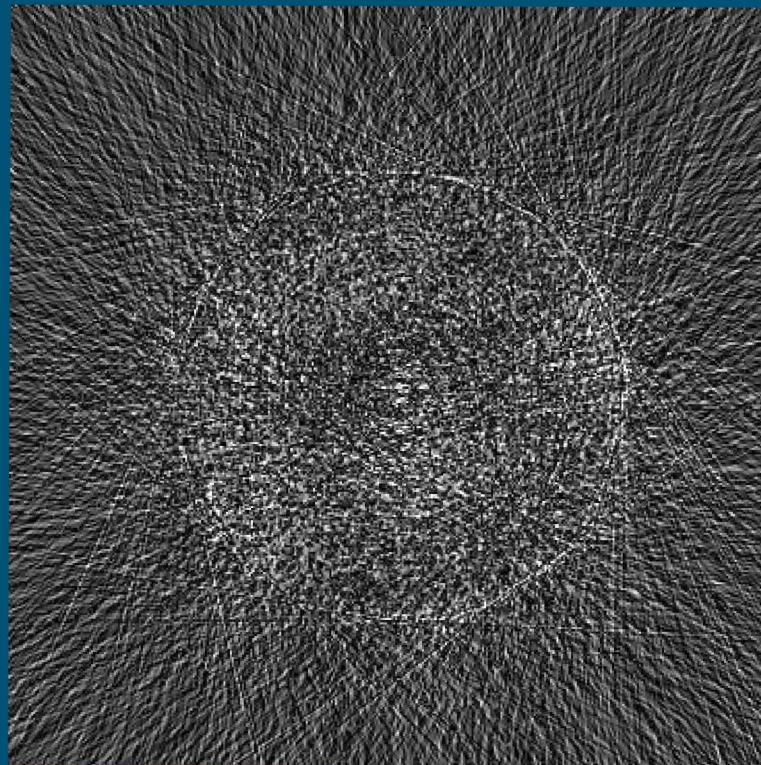
# CT Reconstructions do have numerical differences

Computed subtraction between slices reveals minute but distinct differences

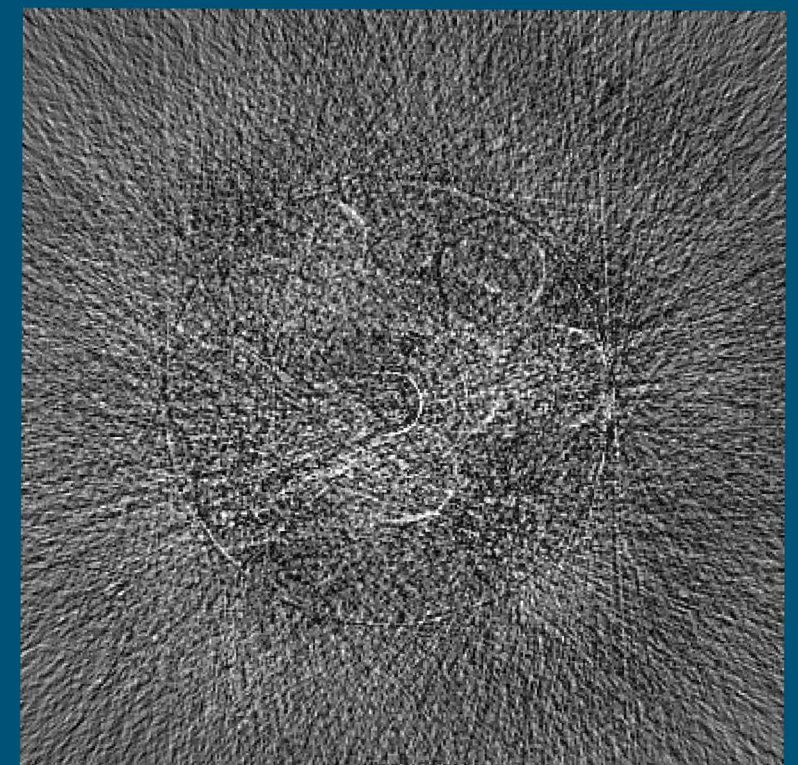
Result of (Step First data) - (Rotate First data)



Tau



Dark Field



Differential Phase

Slice 103





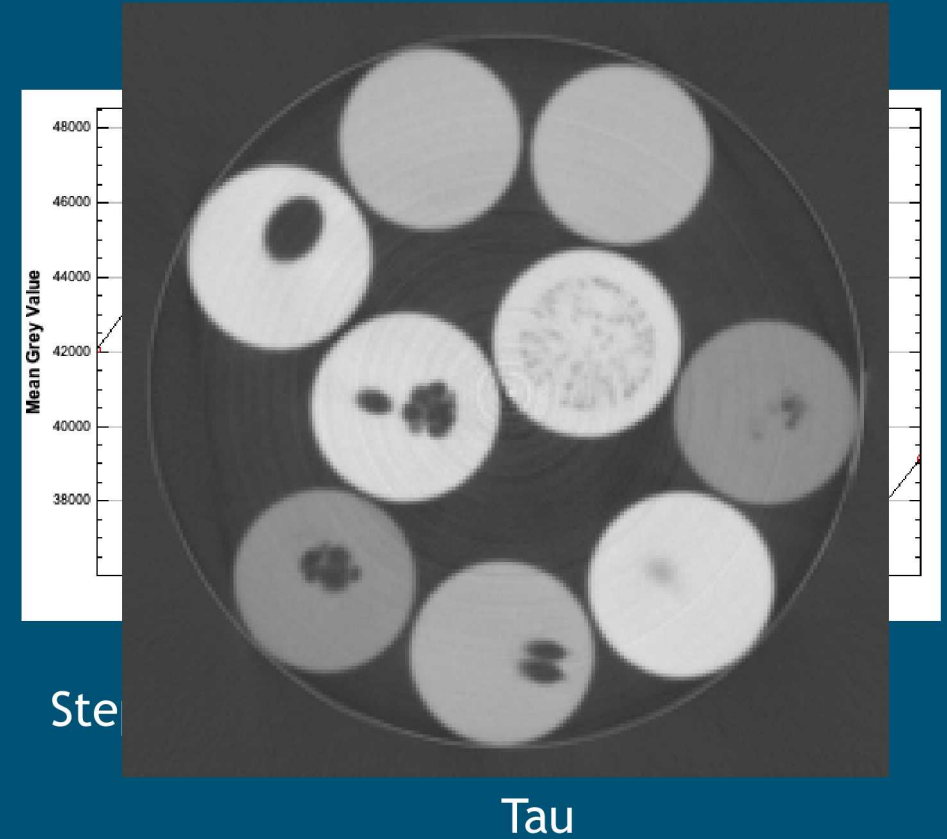
# Conclusions

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Choosing an algorithm

# Conclusions

- Use PhaseCT1 as primary acquisition algorithm
  - Superior fringe profile yields more accurate XPCI reconstruction
  - Intensity variations easily normalized for CT reconstruction
  - In case of failure, yields partial dataset that can be reconstructed
- Con: ineligible for continuous scan (slower)
- Hypothesis: system error largely due to thermal drift





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Thanks to Ryan Goodner, Kyle R. Thompson, and Amber L. Dagele and the rest of the SNL XPCI Encapsulants/Rapid3D teams.

This paper describes objective technical results and analysis. Any subjective views or opinions that might be expressed in the paper do not necessarily represent the views of the U.S. Department of Energy or the United States Government.

This work was supported by the Laboratory Directed Research and Development program at Sandia National Laboratories.

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