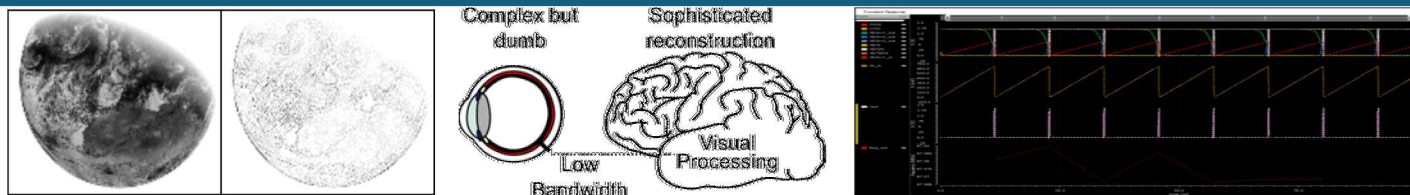


SPARR: the Spiking/Processing Array for Remote Sensing



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PRESENTED BY

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Patent pending



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SPARR's Foundational Research Goals

Increase the number of pixels possible in focal plane arrays to:

- Improve spatial resolution
- Improve signal-to-background ratio

Increase array sample rate

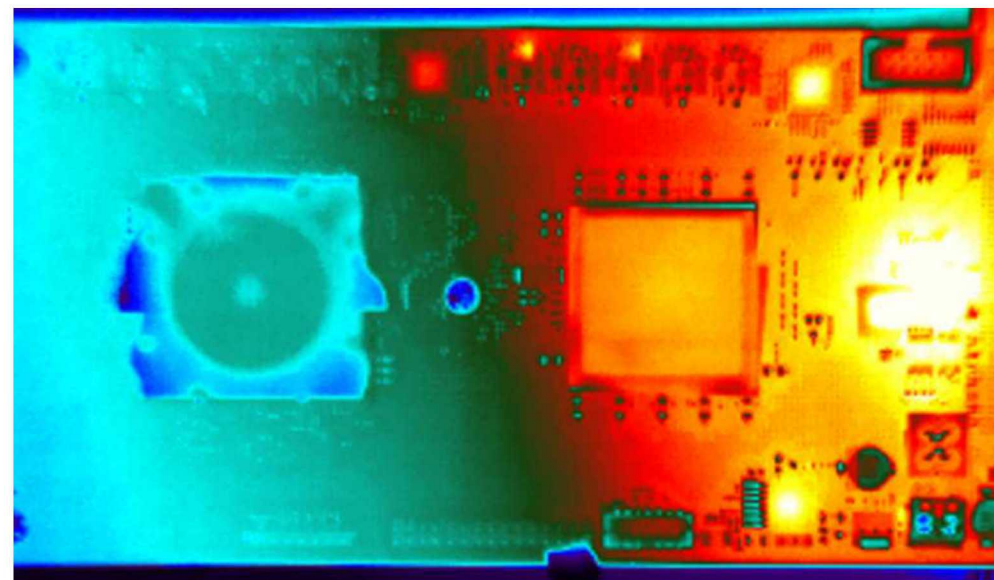
- Reduce latency in optical control systems for robotics and autonomy
- Improve transient signal onset-time accuracy
- Improve time-resolution of fast-changing signals

In contrast to available focal-plane systems

- High speed systems use burst memory, not persistent observation
- Demand and dissipate large amounts of power
- Poorly adapted to the spiking neural processing platforms in development

Spiking neuromorphic processing needs alternate data sources to realize its potential

SPARR adopts neural concepts to address the sensing for space computing

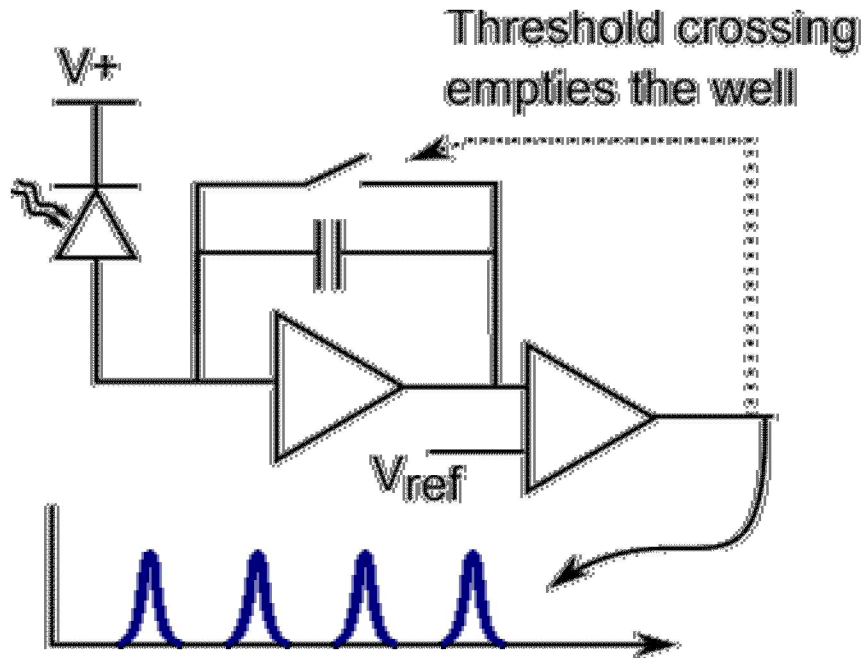


Thermal image of IBM's TrueNorth (left/cool) with support electronics, esp. FPGA (right/hot) [Jackson]

Spiking Processing begins at the Phototransducer

SPARR is a focal plane array built from pixels

Each pixel is a spike generator

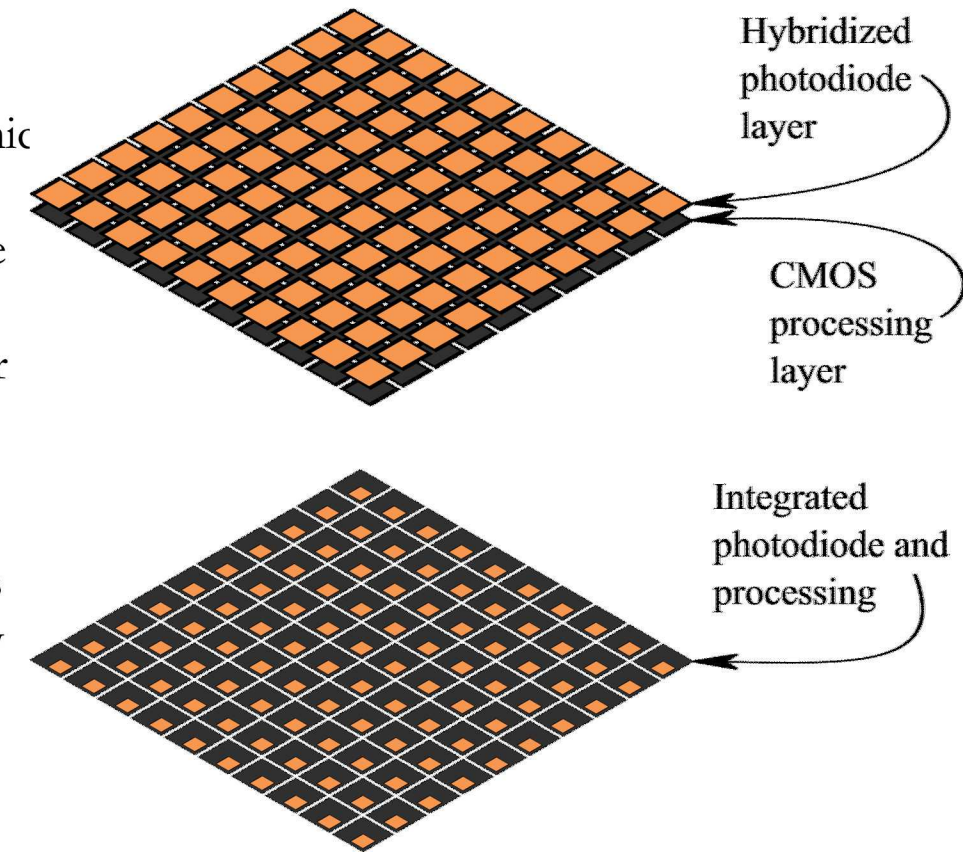


The Integrate-and-Fire pixel may be thought of as a converter of optical power to spike rate

Hybridization using semiconductor layers may enable non-CMOS photonic such as

- Single Photo Avalanche Diode (SPAD)
- InGaAs or HgCdTe for infrared sensitivity

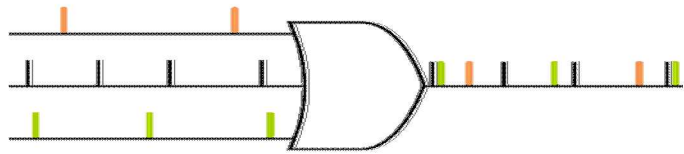
Monolithic CMOS enables simplified fabrication. May use microlens array to increase effective photodetector fill factor



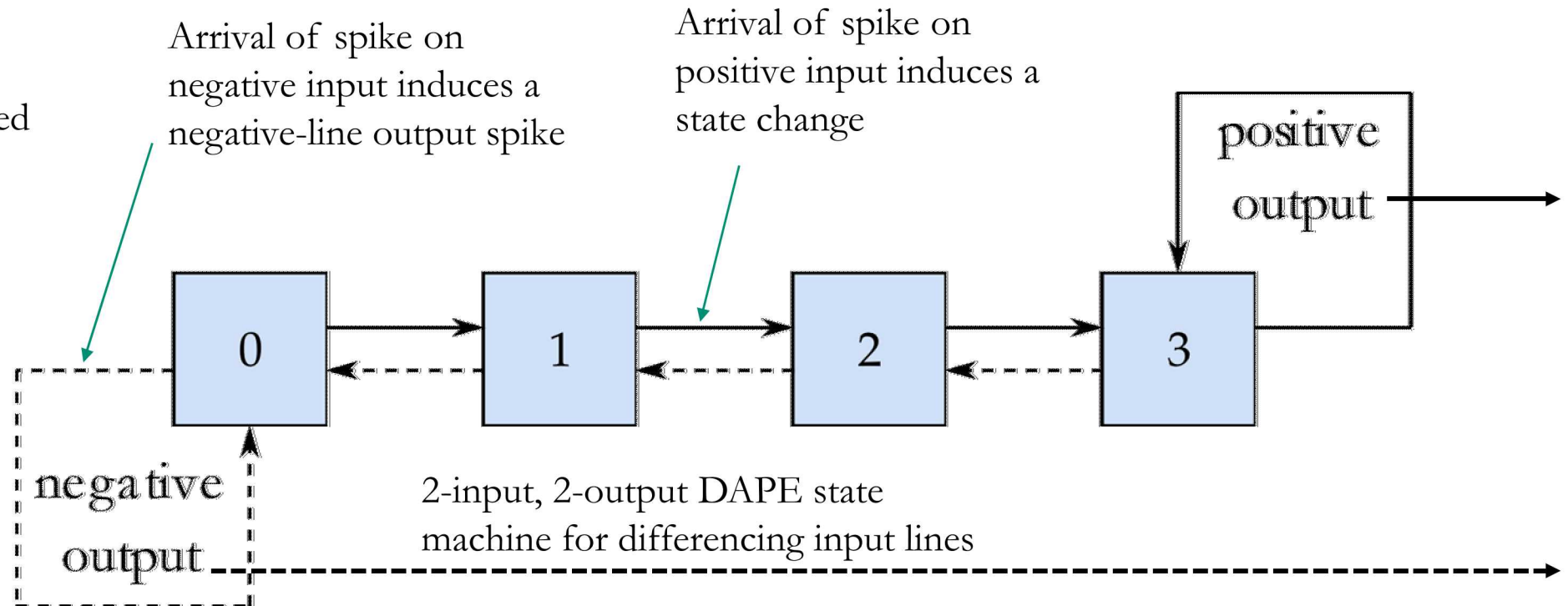
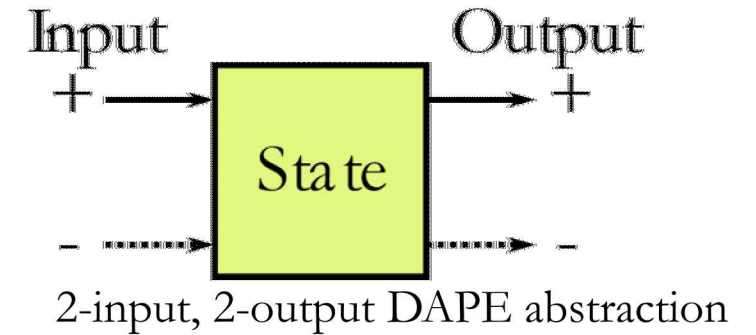
Self-clocking Digital Asynchronous Processing Element (DAPE)

Self-clocking; incoming spikes induce a clock function

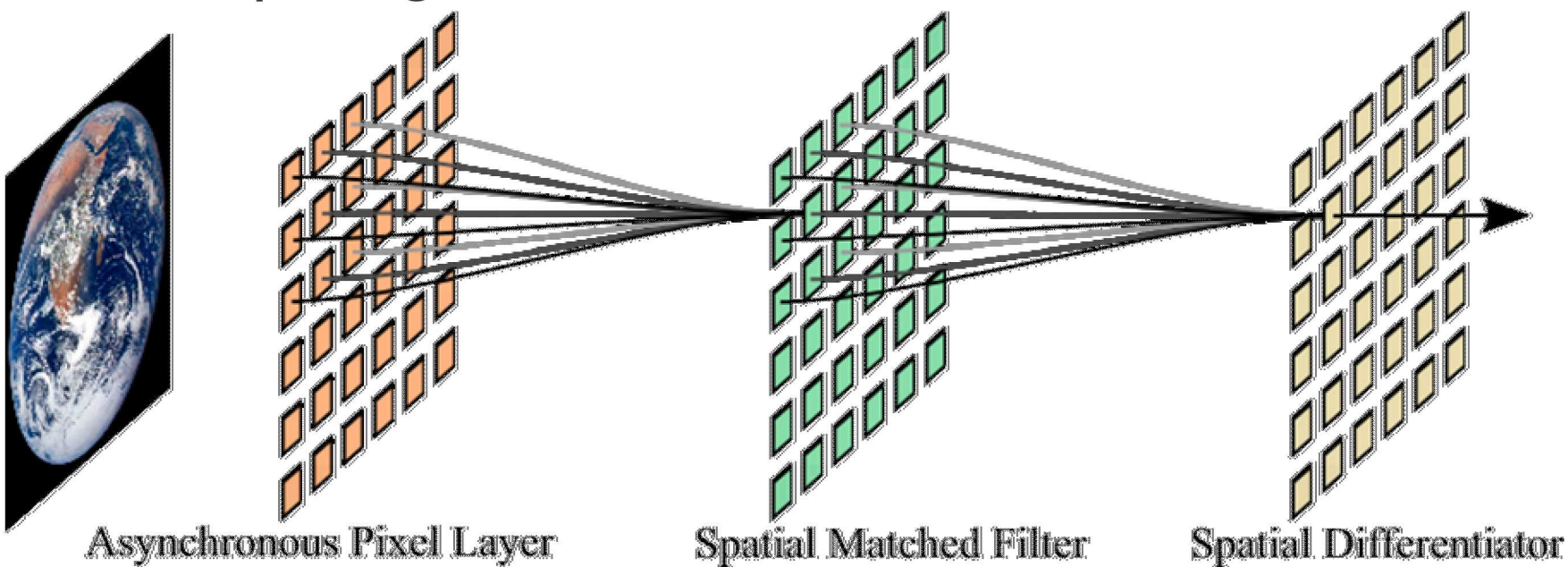
Spikes *are* the data; incoming and outgoing spikes transfer information



Multiple source spike streams can be provided to one DAPE input

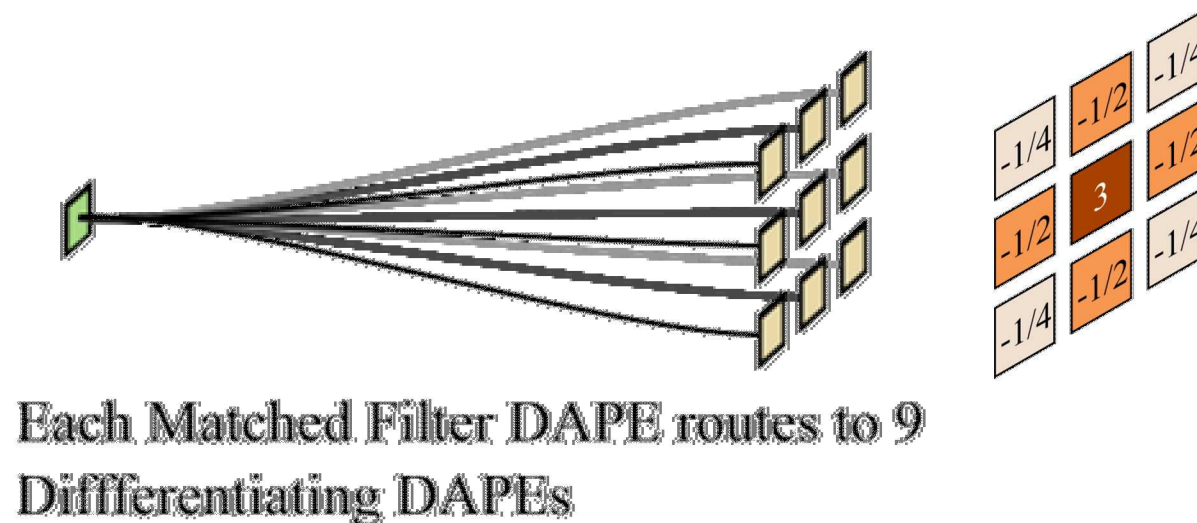
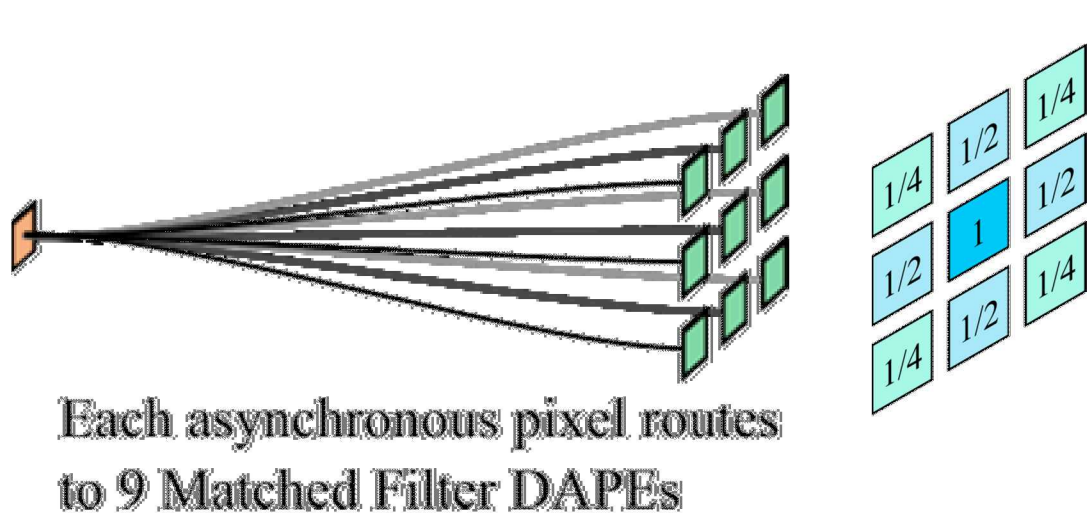


One Topology of DAPES Performs Distributed in-FPA Computing



This Spatial Matched-filter cascades into a spatial contrast filter to enhance point-like luminous objects

Many other signal processing chains are possible.



Human Visual Data Rate Estimate

Channel Capacity

- Human optic nerve contains 0.7 to 1.7 million nerve fibers [Kolb] (10⁶ fibers)
- Peak spike rates may be 100 Hz [Berry] but are typically less than 15 Hz [Perge] (15 spike/s)
- Timing uncertainty is about 1 ms [Berry] (10 bit/spike)

$$10^6 \text{ [fibers]} \cdot 15 \left[\frac{\text{spike}}{\text{s}} \right] \cdot 10 \left[\frac{\text{bit}}{\text{spike}} \right] = 1.5 \times 10^8 \left[\frac{\text{bit}}{\text{s}} \right]$$

Sensor Capacity

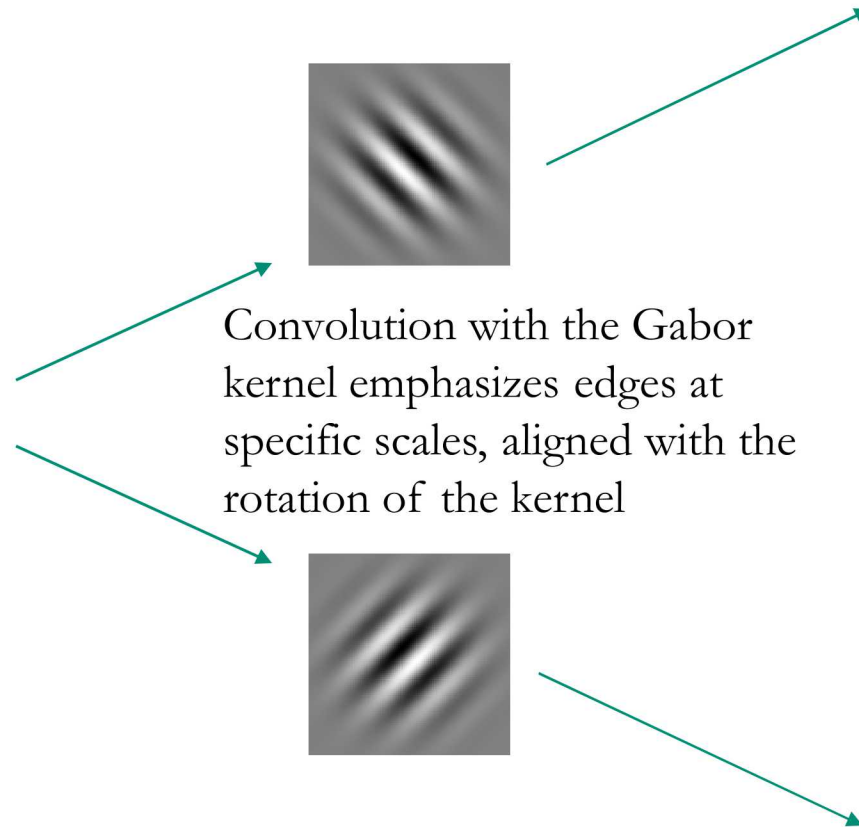
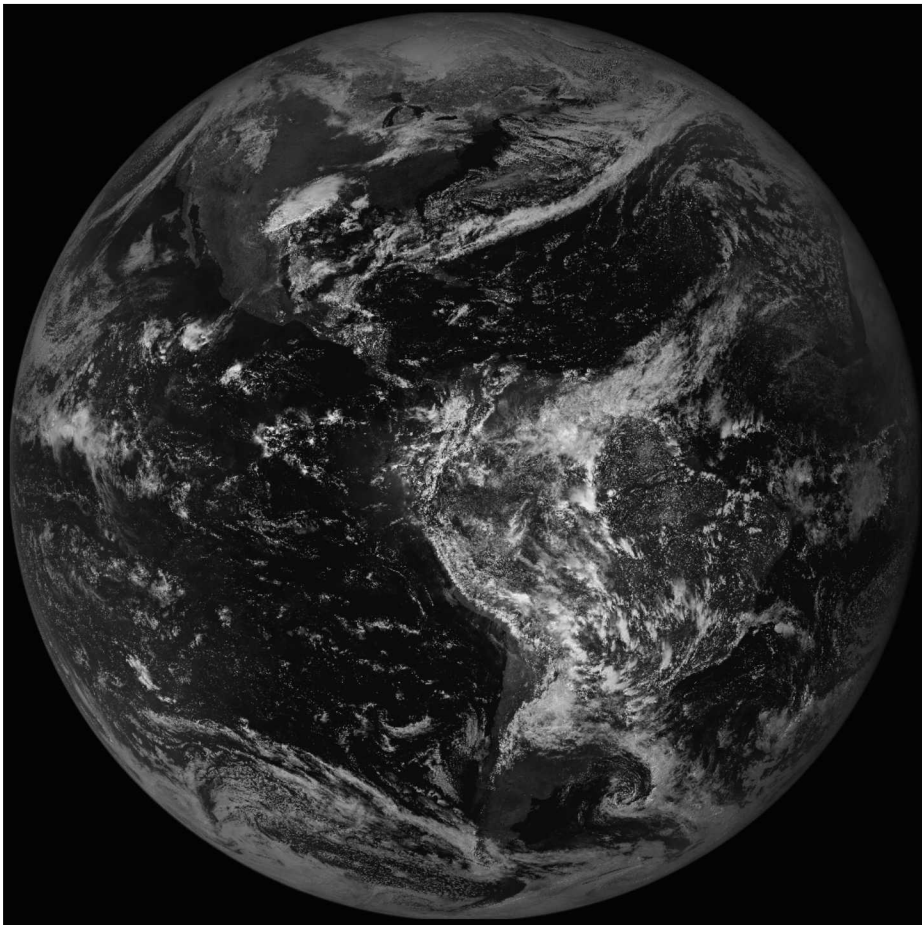
- There are 6.4 million cones in the retina [Kolb]
- Approximately 100 ms integration time [Berry]
- Assume time precision also implies 10 bit/spike at transducer

$$6.4 \times 10^6 \text{ [cones]} \cdot 10 \left[\frac{\text{bit}}{\text{spike}} \right] \cdot \frac{1}{10^{-1}} \left[\frac{1}{\text{s}} \right] = 6.4 \times 10^8 \left[\frac{\text{bit}}{\text{s}} \right]$$

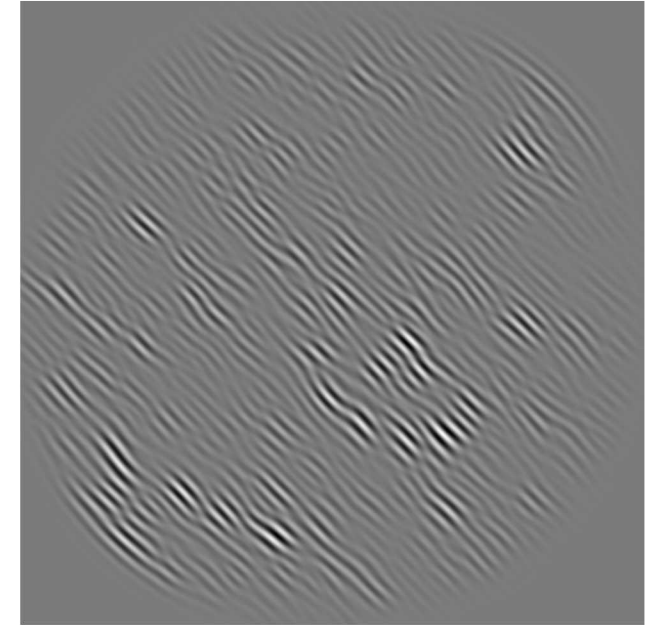
Implies a Compression Ratio about 4:1

Gabor Transform as Biologically-Inspired Sensor Compression

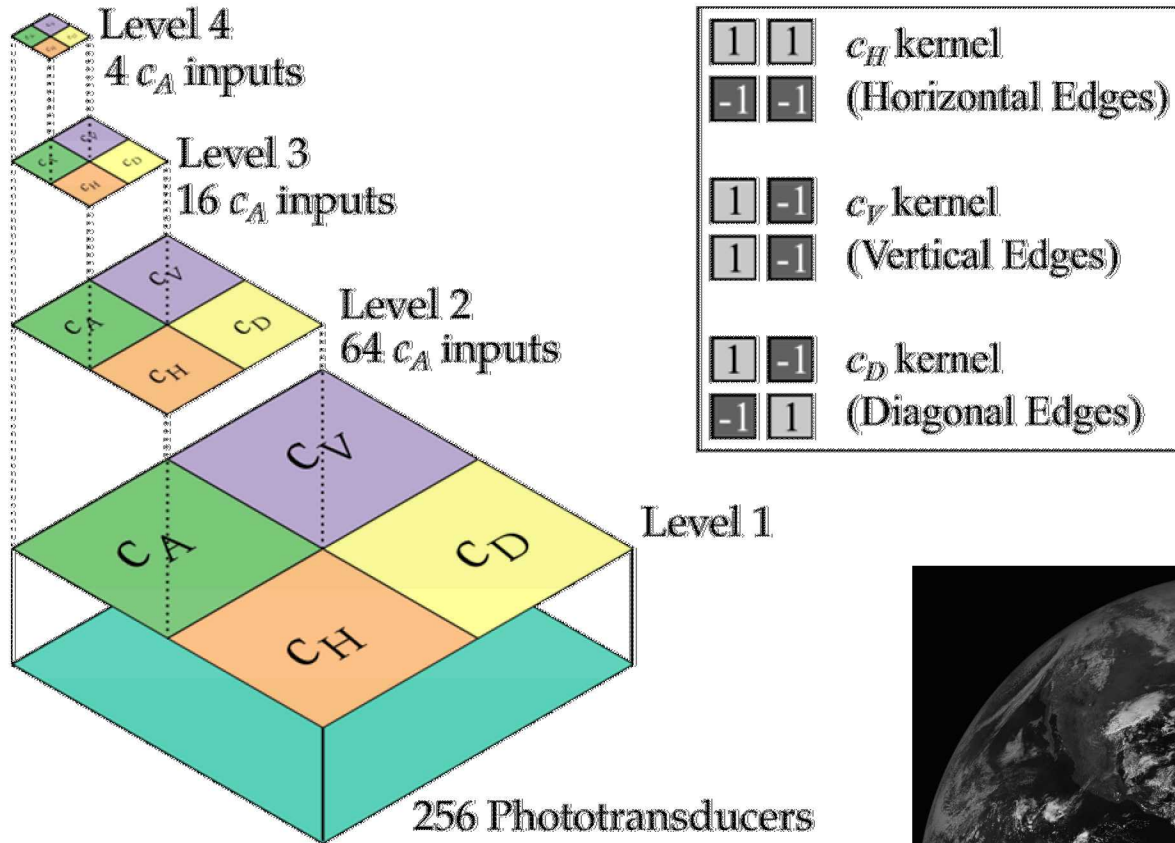
- Gabor transform appears biologically similar to cortical response [Marčelja]
- It identifies edges in multiple orientations
- It operates across a wide range of scales
- In wavelet form can execute compression to 20:1 [Daugman]



Gabor transform is not digital friendly

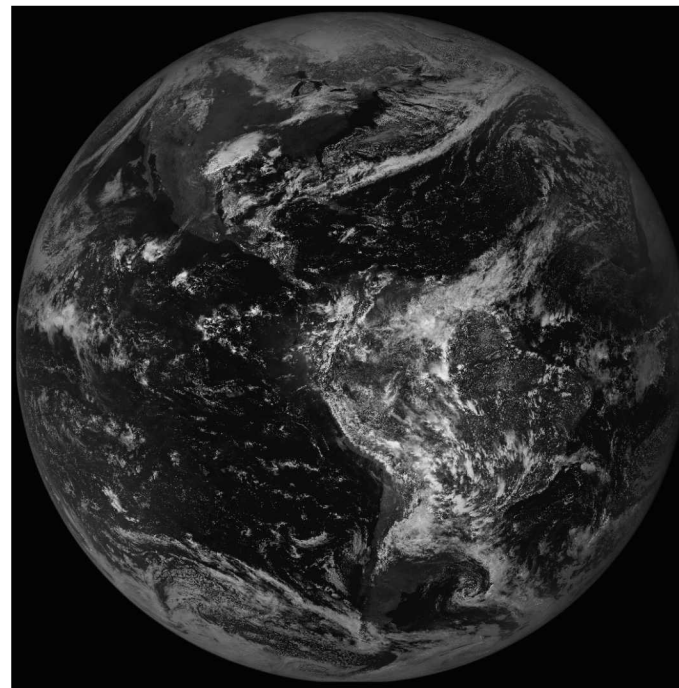


Haar Spatial Wavelet Transform

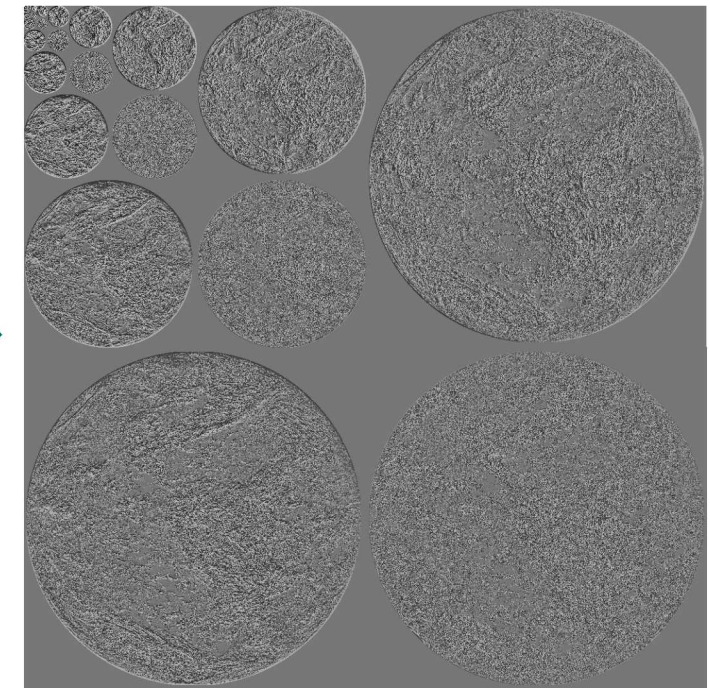


Haar wavelet transform *is* digitally friendly
Similar Properties to Gabor

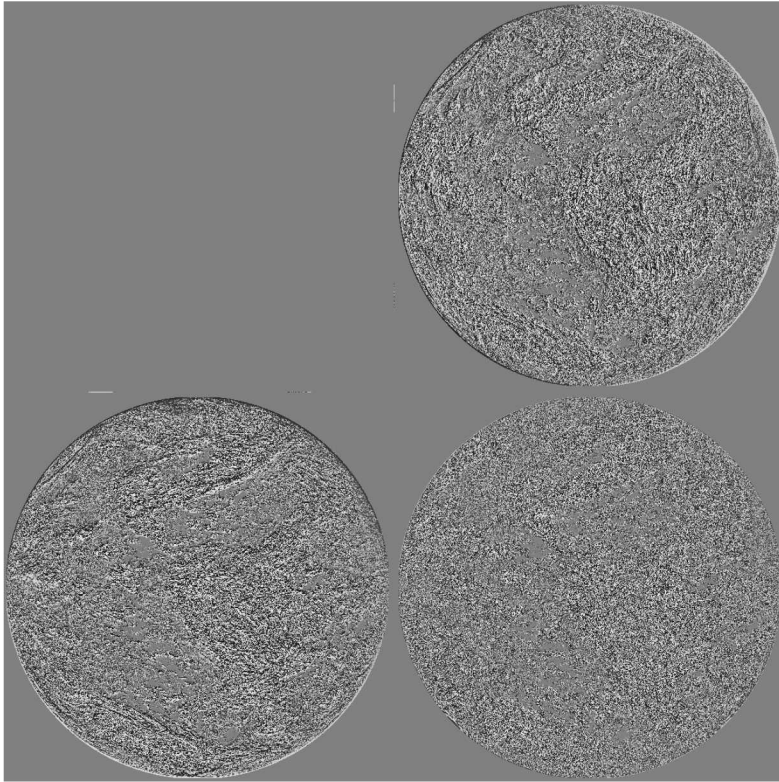
- Responds to edges in different orientation
- Represents multiple scales
- Capable of performing compression



arcsinh of Haar transform



Haar Transform can Whiten Spatial Spectrum



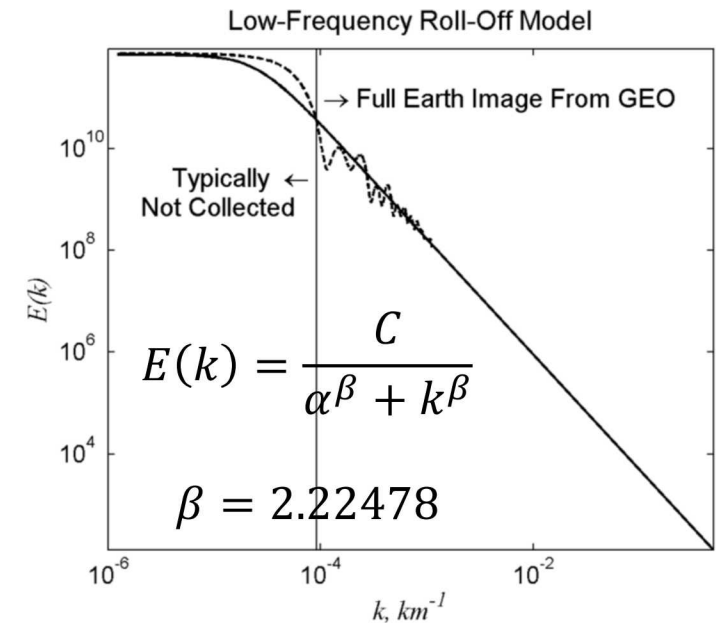
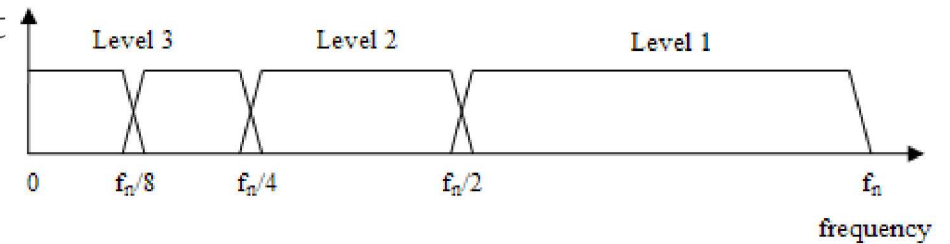
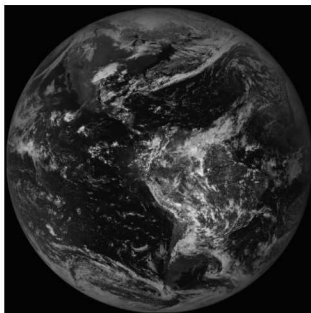
Level 1 (arcsinh above) of the decomposition contains 6% of the energy of the total signal in $3/4$ of the decomposition.

The vast majority of the signal energy is at large scales (low spatial frequencies)

Applying a deterministic weight (spike decimation) at each level of transform to whiten the transformed signal

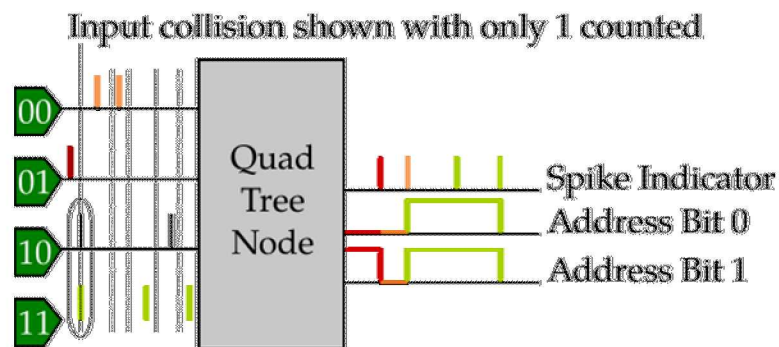
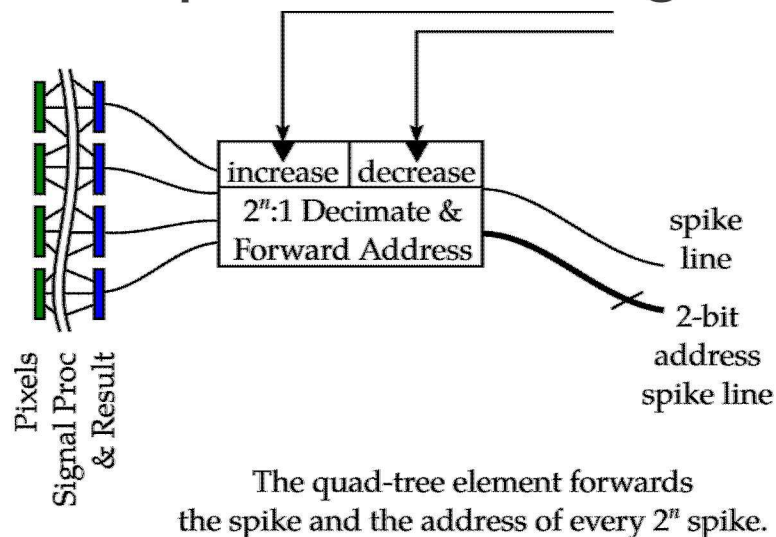
This performs significant compression to the scene

Many natural scenes have similar spatial spectra, so the deterministic weight is broadly applicable

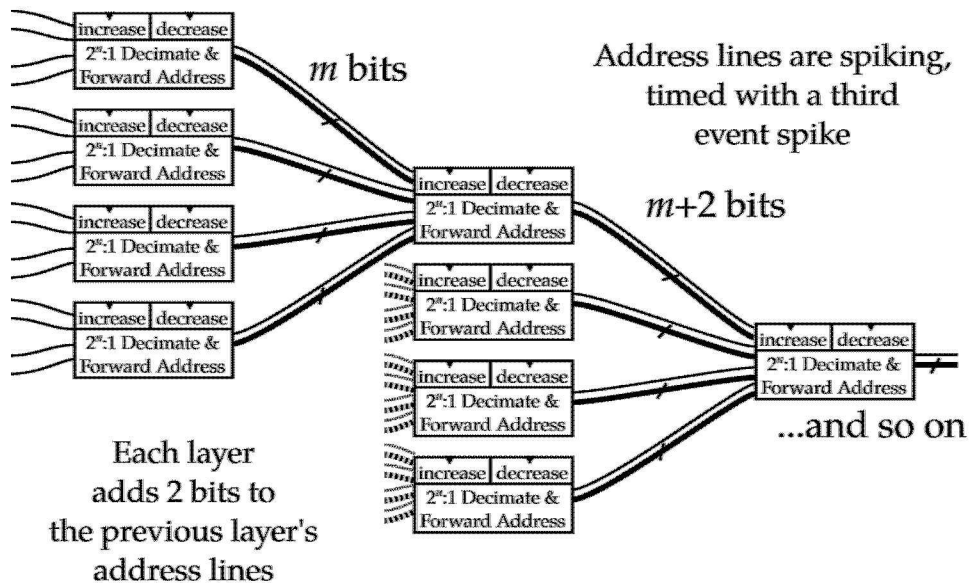
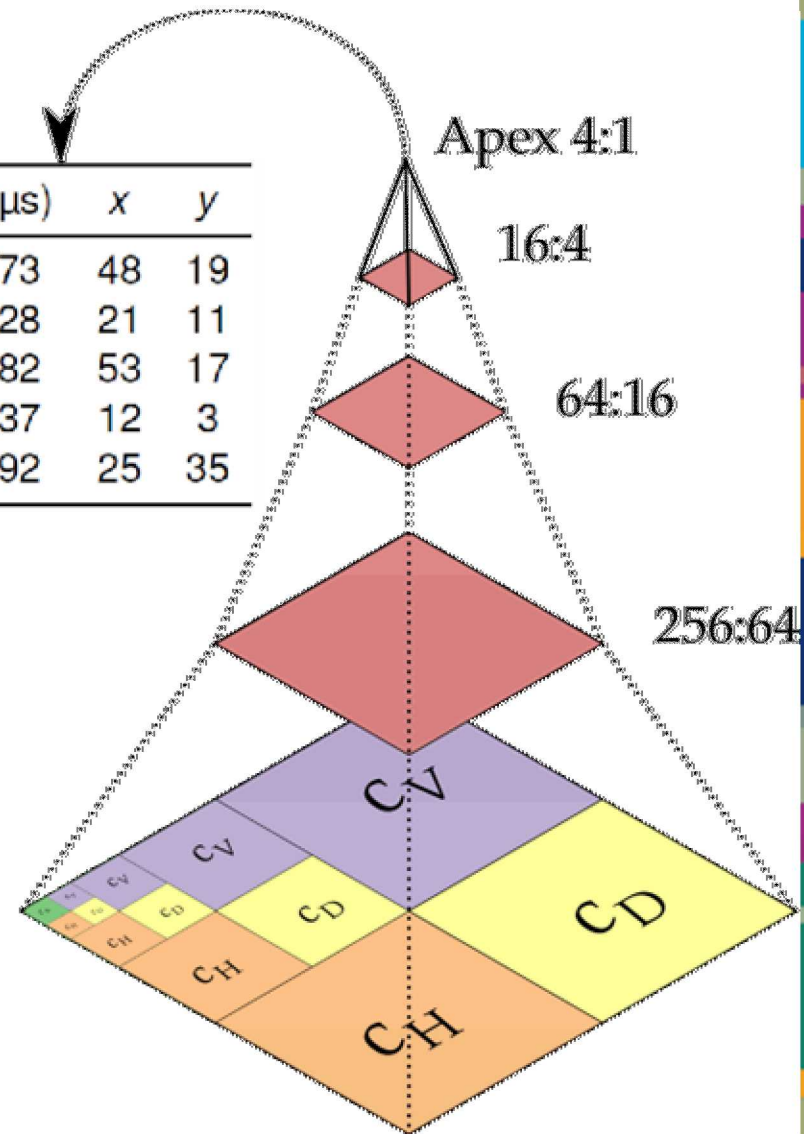


Natural scenes tend to have spatial power spectral density like $k^{-\beta}$

Spike Processing Continues Into Quad-Tree Readout



Time (μ s)	x	y
1.10773	48	19
1.32928	21	11
1.55082	53	17
1.77237	12	3
1.99392	25	35

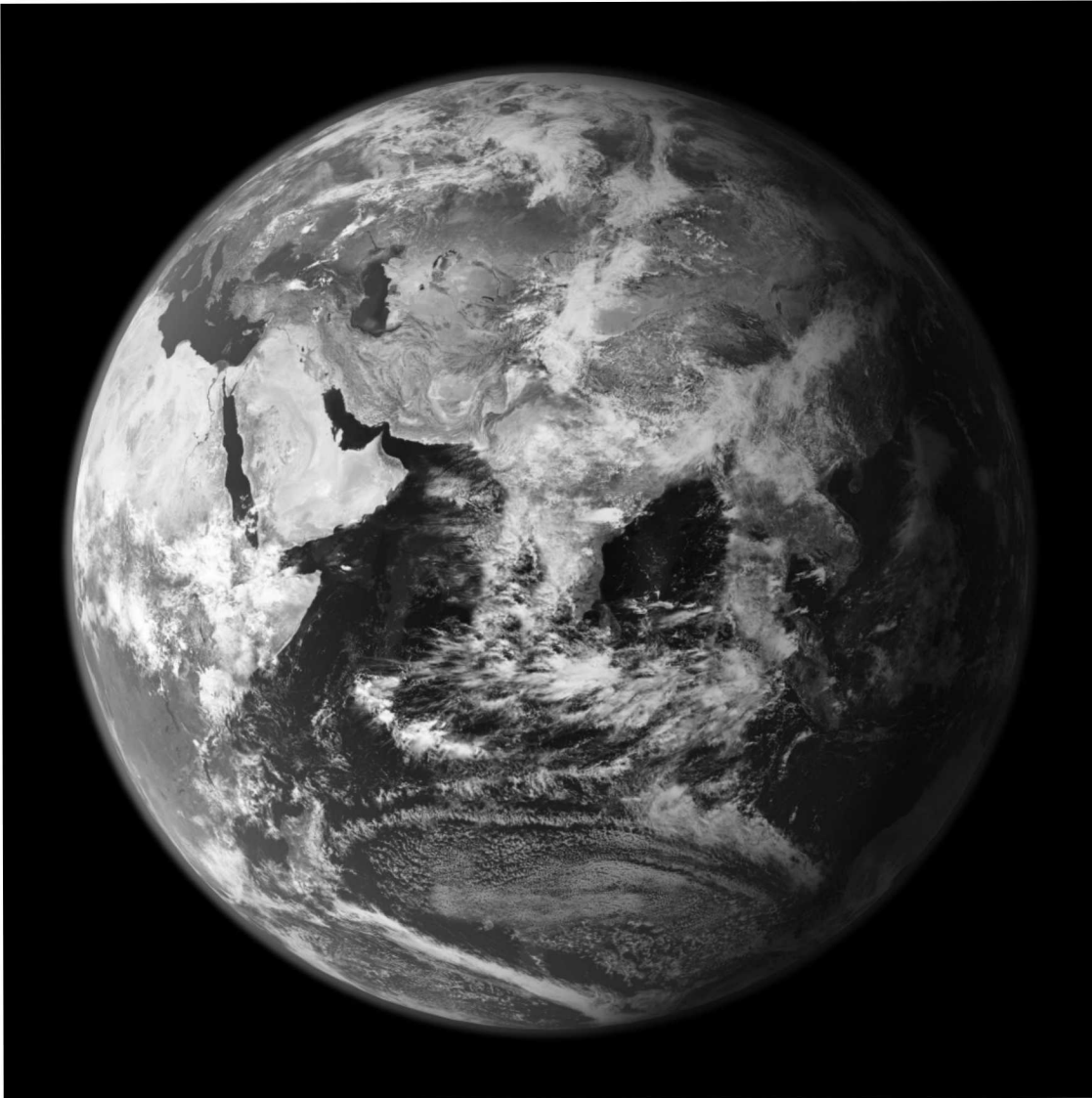


Haar spatial whitener allows scene compression with little information loss

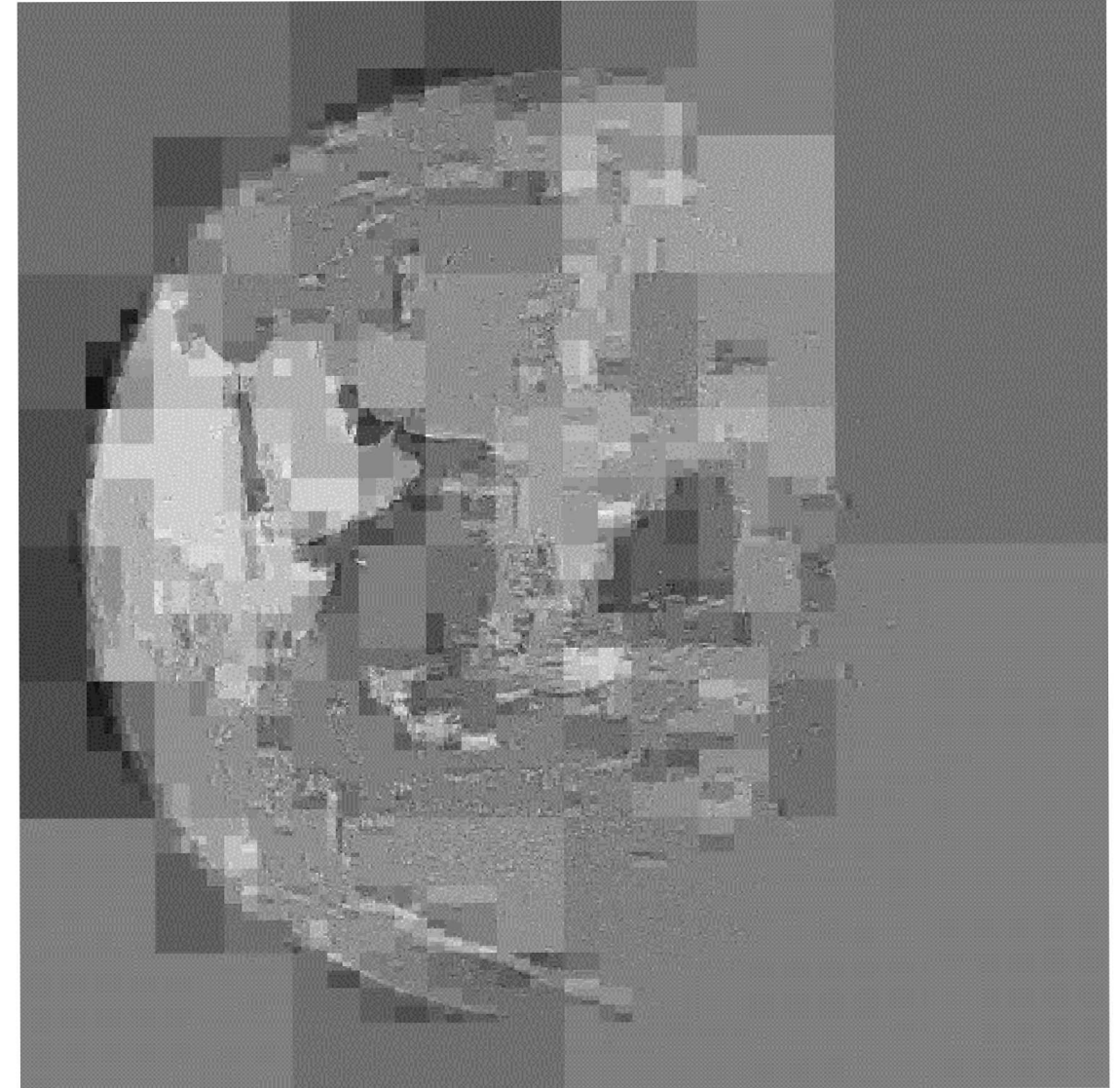
The quad tree provides the sequence of spikes to off-FPA processing

Example: Imaging with Whitening at High “Frame” Rates

1024×1024 pixel array, each frame 250 μ s, total interval 10 ms



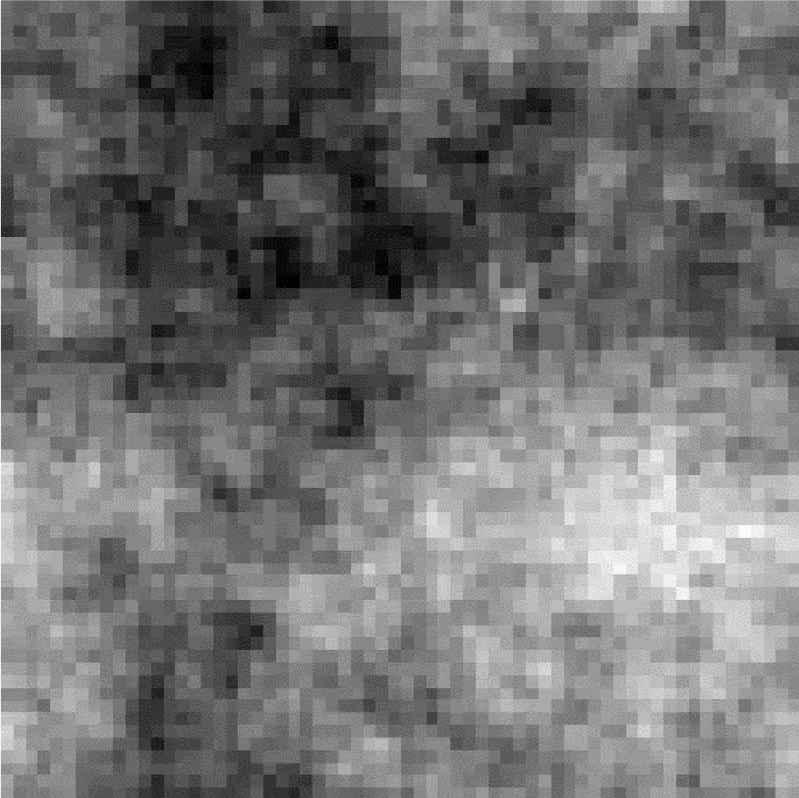
Original Image



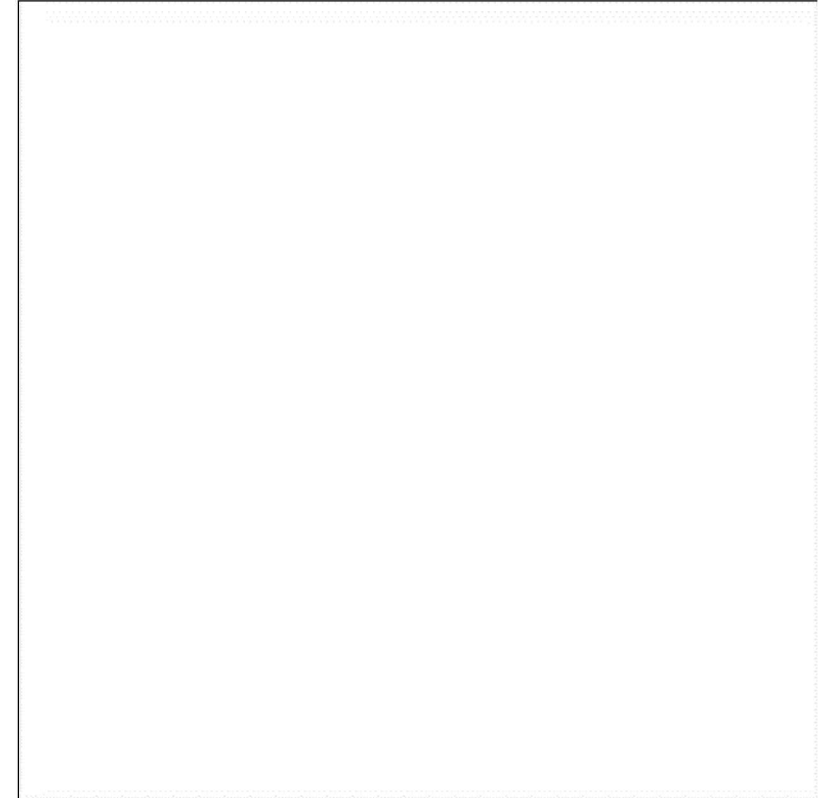
Time-Evolving Reconstruction from Quad-Tree Readout

Spike Trains from Haar + Quad-Tree may be Reconstructed to get Time-Varying Signals

Reconstructed Scene with Fluctuating Source



Reconstructed Time Series of Event Pixel



500 frame/sec reconstruction

2.7 dB SNR

Example: Spike Processing for Tracked Satellite

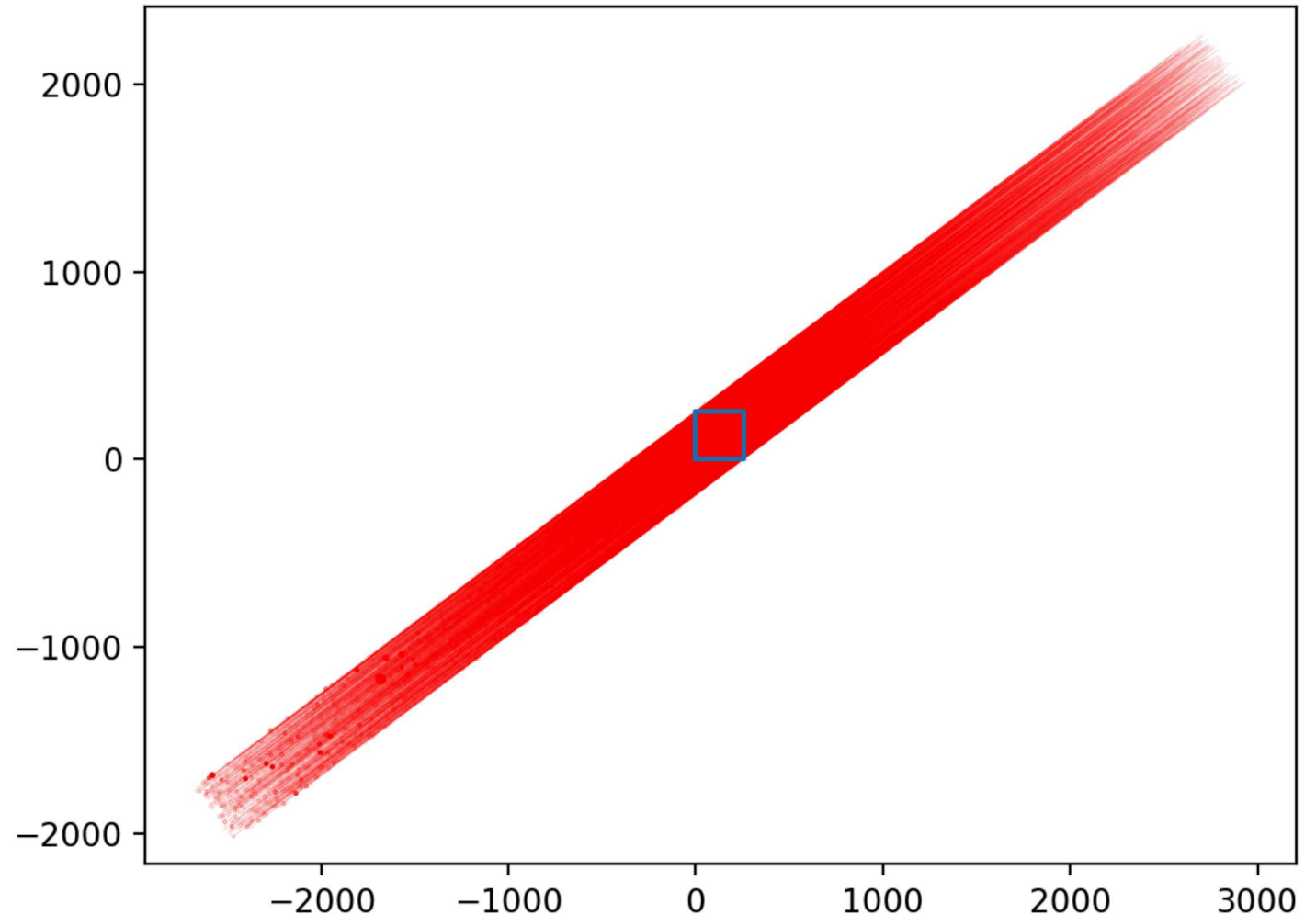
Dark background, with only random dark current noise

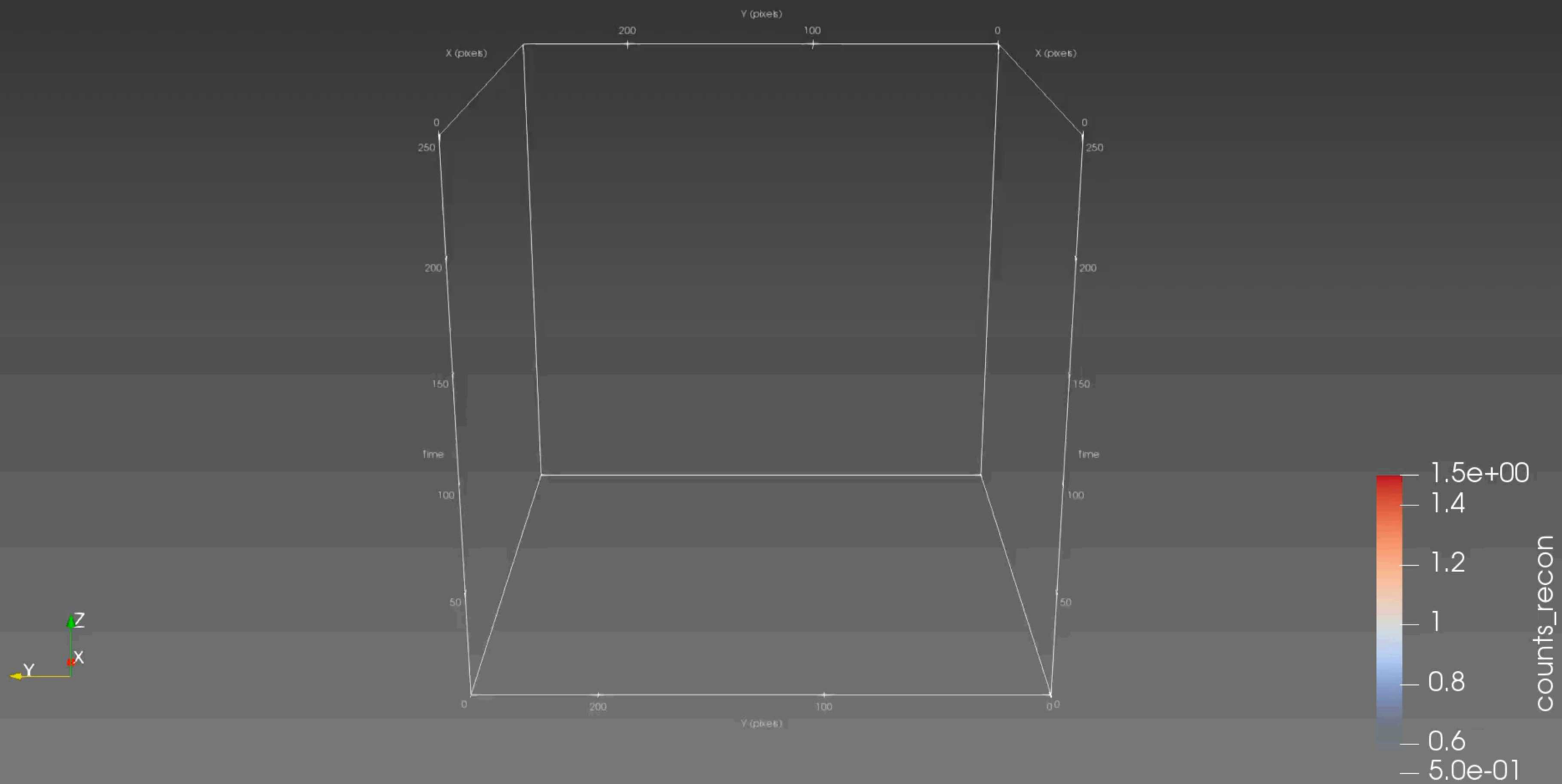
A single luminous object is tracked in the center of the focal plane

Stars (truth data) “streak” across the background

FPA performs Haar transform and quad-tree readout. Spikes for each Haar coefficient are counted during an interval.

The accumulator is inverse-transformed, thresholded, and plotted





SPARR offers an alternative data source to support neuromorphic processing, especially spiking architectures

- Bio-inspired retina-like signal processing in the focal plane performs initial data compression
- Time encoding with sub-nanosecond precision provides a natural connection to time encoding (spiking) processing

Couple with neuromorphic processing

- Object recognition: spatial transform and whitening may provide an effective feature space for multi-scale processing, perhaps with spiking realizations of capsule networks or reservoir computing [Elsner]
- Optical temporal pattern extraction and recognition
- Object tracking: extension of object recognition to tracking via recurrent networks with memory ([Milan] non-spiking)
- Spatial situational awareness: passive (non-radar) with neural optical flow processing (e.g., [Apitzsch] non-spiking)

SPARR fits into the gap created by the creation of new neuromorphic computing platforms

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