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CODE-VERIFICATION TECHNIQUES FOR HYPERSONIC REACTING FLOWS IN THERMOCHEMICAL NONEQUILIBRIUM

Brian A. Freno
Brian Carnes
V. Gregory Weirs
Sandia National Laboratories

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Outline

- Introduction
- Governing Equations
- Verification Techniques for Spatial Accuracy
- Spatial-Discretization Verification Results
- Verification Techniques for Thermochemical Source Term
- Thermochemical-Source-Term Verification Results
- Summary

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- Introduction
 - Hypersonic Flow
 - Sandia Parallel Aerodynamics and Reentry Code (SPARC)
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Hypersonic Flow

Hypersonic flows and underlying aerothermochemical phenomena

- Important in design & analysis of vehicles exiting/reentering atmosphere
- High flow velocities and stagnation enthalpies
 - Induce chemical reactions
 - Excite thermal energy modes
- Aerodynamic and thermochemical models require full coupling

Sandia Parallel Aerodynamics and Reentry Code (SPARC)

Sandia Parallel Aerodynamics and Reentry Code (SPARC)

- Under development at Sandia National Laboratories
- Compressible computational fluids dynamics code
- Models transonic and hypersonic reacting turbulent flows
- Solves transient heat equation and equations associated with decomposing and non-decomposing ablators
- One- and two-way couplings between fluid-dynamics and ablation solvers

Verification and Validation

Credibility of computational physics codes requires verification and validation

- **Validation** assesses how well models represent physical phenomena
 - Computational results are compared with experimental results
 - Assess suitability of models, model error, and bounds of validity
- **Verification** assesses accuracy of numerical solutions against expectations
 - *Solution verification* estimates numerical error for particular solution
 - *Code verification* verifies correctness of numerical-method implementation

Code Verification

Code verification is focus of this work

- Governing equations are numerically discretized
 - Discretization error is introduced in solution
- Seek to verify discretization error decreases with refinement of discretization
 - Should decrease at an expected rate
- Use manufactured and exact solutions to compute error

Code Verification

Code verification demonstrated in many computational physics disciplines

- Fluid dynamics
- Solid mechanics
- Heat transfer
- Multiphase flows
- Electrodynamics
- Electromagnetism
- Fluid–structure interaction
- Radiation hydrodynamics

Code-verification techniques for hypersonic flows have been presented

- Single-species perfect gas
- Multi-species gas in thermal equilibrium

We present code-verification techniques for hypersonic reacting flows in thermochemical **nonequilibrium** and demonstrate effectiveness

- Spatial discretization
- Thermochemical source term

Outline

- Introduction
- Governing Equations
 - Conserved Quantities
 - Vibrational Energy
 - Translational–Vibrational Energy Exchange
 - Chemical Kinetics
 - Scope of Code Verification
- Verification Techniques for Spatial Accuracy
- Spatial-Discretization Verification Results
- Verification Techniques for Thermochemical Source Term
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Governing Equations: n_s Species in Vibrational Nonequilibrium

Conservation of mass, momentum, and energy:

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_c(\mathbf{U}) = -\nabla \cdot \mathbf{F}_p(\mathbf{U}) + \nabla \cdot \mathbf{F}_d(\mathbf{U}) + \mathbf{S}(\mathbf{U}),$$

where

$$\mathbf{U} = \begin{Bmatrix} \rho \\ \rho \mathbf{v} \\ \rho E \\ \rho e_v \end{Bmatrix}, \quad \mathbf{F}_c(\mathbf{U}) = \begin{Bmatrix} \rho \mathbf{v}^T \\ \rho \mathbf{v} \mathbf{v}^T \\ \rho E \mathbf{v}^T \\ \rho e_v \mathbf{v}^T \end{Bmatrix}, \quad \mathbf{F}_p(\mathbf{U}) = \begin{Bmatrix} \mathbf{0} \\ p \mathbf{I} \\ p \mathbf{v}^T \\ \mathbf{0} \end{Bmatrix}, \quad \mathbf{F}_d(\mathbf{U}) = \begin{Bmatrix} -\mathbf{J} \\ \boldsymbol{\tau} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_v - \mathbf{J}^T \mathbf{h})^T \\ (-\mathbf{q}_v - \mathbf{J}^T \mathbf{e}_v)^T \end{Bmatrix},$$

$$\mathbf{S}(\mathbf{U}) = \begin{Bmatrix} \dot{\mathbf{w}} \\ \mathbf{0} \\ 0 \\ Q_{t-v} + \mathbf{e}_v^T \dot{\mathbf{w}} \end{Bmatrix}, \quad \begin{aligned} \rho &= \{\rho_1, \dots, \rho_{n_s}\}^T, & \dot{\mathbf{w}} &= \{\dot{w}_1, \dots, \dot{w}_{n_s}\}^T : \text{mass production rates per volume,} \\ \rho &= \sum_{s=1}^{n_s} \rho_s, & e_v &= \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} e_{v_s} : \text{mixture vibrational energy per mass,} \\ p &= \sum_{s=1}^{n_s} \frac{\rho_s}{M_s} \bar{R} T, & \mathbf{e}_v &= \{e_{v_1}, \dots, e_{v_{n_s}}\}^T : \text{vibrational energies per mass,} \\ & & Q_{t-v} &: \text{translational-vibrational energy exchange,} \end{aligned}$$

$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} (c_{v_s} T + e_{v_s} + h_s^o)$$

Governing Equations: n_s Species in Vibrational Nonequilibrium

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Multiple species

$$\mathbf{S}(\mathbf{U}) = \begin{Bmatrix} \dot{\mathbf{w}} \\ 0 \\ 0 \\ Q_{t-v} + \mathbf{e}_v^T \dot{\mathbf{w}} \end{Bmatrix}, \quad \begin{aligned} \boldsymbol{\rho} &= \{\rho_1, \dots, \rho_{n_s}\}^T, & \dot{\mathbf{w}} &= \{\dot{w}_1, \dots, \dot{w}_{n_s}\}^T: \text{mass production rates per volume,} \\ \rho &= \sum_{s=1}^{n_s} \rho_s, & e_v &= \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} e_{v_s}: \text{mixture vibrational energy per mass,} \\ p &= \sum_{s=1}^{n_s} \frac{\rho_s}{M_s} \bar{R} T, & \mathbf{e}_v &= \{e_{v_1}, \dots, e_{v_{n_s}}\}^T: \text{vibrational energies per mass,} \\ & & Q_{t-v} &: \text{translational-vibrational energy exchange,} \end{aligned}$$

$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} (c_{v_s} T + e_{v_s}^a)$$

Governing Equations: n_s Species in Vibrational Nonequilibrium

Conservation of mass, momentum, and energy:

Local time derivative

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_c(\mathbf{U}) = -\nabla \cdot \mathbf{F}_p(\mathbf{U}) + \nabla \cdot \mathbf{F}_d(\mathbf{U}) + \mathbf{S}(\mathbf{U}),$$

where

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$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} (c_{v_s} T + e_{v_s} + h_s^o)$$

Governing Equations: n_s Species in Vibrational Nonequilibrium

Conservation of mass, momentum, and energy:

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_c(\mathbf{U}) = -\nabla \cdot \mathbf{F}_p(\mathbf{U}) + \nabla \cdot \mathbf{F}_d(\mathbf{U}) + \mathbf{S}(\mathbf{U}),$$

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$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} (c_{v_s} T + e_{v_s} + h_s^0)$$

Governing Equations: n_s Species in Vibrational Nonequilibrium

Conservation of mass, momentum, and energy:

Pressure flux gradient

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_c(\mathbf{U}) = -\nabla \cdot \mathbf{F}_p(\mathbf{U}) + \nabla \cdot \mathbf{F}_d(\mathbf{U}) + \mathbf{S}(\mathbf{U}),$$

where

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$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} (c_{v_s} T + e_{v_s} + h_s^0)$$

Governing Equations: n_s Species in Vibrational Nonequilibrium

Conservation of mass, momentum, and energy:

Diffusive flux gradient

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_c(\mathbf{U}) = -\nabla \cdot \mathbf{F}_p(\mathbf{U}) + \nabla \cdot \mathbf{F}_d(\mathbf{U}) + \mathbf{S}(\mathbf{U}),$$

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$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} (c_{v_s} T + e_{v_s} + h_s^o)$$

Governing Equations: n_s Species in Vibrational Nonequilibrium

Conservation of mass, momentum, and energy:

Thermochemical source term

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_c(\mathbf{U}) = -\nabla \cdot \mathbf{F}_p(\mathbf{U}) + \nabla \cdot \mathbf{F}_d(\mathbf{U}) + \mathbf{S}(\mathbf{U}),$$

where

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Vibrational Energy

Mixture vibrational energy per mass:

$$e_v = \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} e_{v_s},$$

where

$$e_{v_s} = \begin{cases} \sum_{m=1}^{n_{v_s}} e_{v_s,m}(T_v) & \text{for molecules,} \\ 0 & \text{for atoms,} \end{cases}$$

and

$$e_{v_s,m}(T') = \frac{\bar{R}}{M_s} \frac{\theta_{v_s,m}}{\exp(\theta_{v_s,m}/T') - 1}$$

n_{v_s} : number of vibrational modes of species s ($n_{v_s} = 0$ for atoms)

$\theta_{v_s,m}$: characteristic vibrational temperature of mode m of species s

Translational–Vibrational Energy Exchange

Landau–Teller model:

$$Q_{t-v} = \sum_{s=1}^{n_s} \rho_s \sum_{m=1}^{n_{v_s}} \frac{e_{v_s,m}(T) - e_{v_s,m}(T_v)}{\langle \tau_{s,m} \rangle}$$

Translational–vibrational energy relaxation time for mode m of species s :

$$\langle \tau_{s,m} \rangle = \left(\sum_{s'=1}^{n_s} \frac{y_{s'}}{\tau_{s,m,s'}} \right)^{-1} + \left[\left(N_A \sum_{s'=1}^{n_s} \frac{\rho_{s'}}{M_{s'}} \right) \sigma_{v_s} \sqrt{\frac{8 \bar{R} T}{\pi M_s}} \right]^{-1},$$

where

$$y_s = \frac{\rho_s/M_s}{\sum_{s'=1}^{n_s} \rho_{s'}/M_{s'}}, \quad \tau_{s,m,s'} = \frac{\exp [a_{s,m,s'} (T^{-1/3} - b_{s,m,s'}) - 18.42]}{p'}, \quad \sigma_{v_s} = \sigma'_{v_s} \left(\frac{50,000 \text{ K}}{T} \right)^2$$

p' : pressure in atmospheres.

$a_{s,m,s'}$ and $b_{s,m,s'}$: vibrational constants for mode m of species s with colliding species s'

N_A : Avogadro constant

σ_{v_s} : collision-limiting vibrational cross section

σ'_{v_s} : collision-limiting vibrational cross section at 50,000 K.

Chemical Kinetics

Mass production rate per volume for species s : $\dot{w}_s = M_s \sum_{r=1}^{n_r} (\beta_{s,r} - \alpha_{s,r}) (R_{f_r} - R_{b_r})$

Forward and backward reaction rates for reaction r :

$$R_{f_r} = \gamma k_{f_r} \prod_{s=1}^{n_s} \left(\frac{1}{\gamma} \frac{\rho_s}{M_s} \right)^{\alpha_{s,r}} \quad \text{and} \quad R_{b_r} = \gamma k_{b_r} \prod_{s=1}^{n_s} \left(\frac{1}{\gamma} \frac{\rho_s}{M_s} \right)^{\beta_{s,r}}$$

Forward and backward reaction rate coefficients:

$$k_{f_r}(T_c) = C_{f_r} T_c^{\eta_r} \exp(-\theta_r/T_c) \quad \text{and} \quad k_{b_r}(T) = \frac{k_{f_r}(T)}{K_{e_r}(T)}$$

Equilibrium constant for reaction r :

$$K_{e_r}(T) = \exp \left[A_{1_r} \left(\frac{T}{10000} \right) + A_{2_r} + A_{3_r} \ln \left(\frac{10000}{T} \right) + A_{4_r} \frac{10000}{T} + A_{5_r} \left(\frac{10000}{T} \right)^2 \right]$$

$\alpha_{s,r}$ and $\beta_{s,r}$: stoichiometric coefficients for species s in reaction r

γ : unit conversion factor

C_{f_r} , η_r , A_{i_r} : empirical parameters

θ_r : activation energy of reaction r , divided by Boltzmann constant

T_c : rate-controlling temperature ($T_c = \sqrt{TT_v}$ for dissociation, $T_c = T$ for exchange)

Scope of Code Verification

Conservation of mass, momentum, and energy:

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$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} (c_{v_s} T + e_{v_s} + h_s^o)$$

Scope of Code Verification

Conservation of mass, momentum, and energy:

Non-diffusive flux gradients

Thermochemical source term

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_c(\mathbf{U}) = -\nabla \cdot \mathbf{F}_p(\mathbf{U}) + \nabla \cdot \mathbf{F}_d(\mathbf{U}) + \mathbf{S}(\mathbf{U}),$$

where

$$\mathbf{U} = \begin{Bmatrix} \rho \\ \rho \mathbf{v} \\ \rho E \\ \rho e_v \end{Bmatrix}, \quad \mathbf{F}_c(\mathbf{U}) = \begin{Bmatrix} \rho \mathbf{v}^T \\ \rho \mathbf{v} \mathbf{v}^T \\ \rho E \mathbf{v}^T \\ \rho e_v \mathbf{v}^T \end{Bmatrix}, \quad \mathbf{F}_p(\mathbf{U}) = \begin{Bmatrix} 0 \\ p \mathbf{I} \\ p \mathbf{v}^T \\ 0 \end{Bmatrix}, \quad \mathbf{F}_d(\mathbf{U}) = \begin{Bmatrix} -\mathbf{J} \\ \boldsymbol{\tau} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_v - \mathbf{J}^T \mathbf{h})^T \\ (-\mathbf{q}_v - \mathbf{J}^T \mathbf{e}_v)^T \end{Bmatrix},$$

$$\mathbf{S}(\mathbf{U}) = \begin{Bmatrix} \dot{\mathbf{w}} \\ 0 \\ 0 \\ Q_{t-v} + \mathbf{e}_v^T \dot{\mathbf{w}} \end{Bmatrix}, \quad \begin{aligned} \rho &= \{\rho_1, \dots, \rho_{n_s}\}^T, & \dot{\mathbf{w}} &= \{\dot{w}_1, \dots, \dot{w}_{n_s}\}^T: \text{mass production rates per volume,} \\ \rho &= \sum_{s=1}^{n_s} \rho_s, & e_v &= \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} e_{v_s}: \text{mixture vibrational energy per mass,} \\ p &= \sum_{s=1}^{n_s} \frac{\rho_s}{M_s} \bar{R} T, & \mathbf{e}_v &= \{e_{v_1}, \dots, e_{v_{n_s}}\}^T: \text{vibrational energies per mass,} \\ & & Q_{t-v} &: \text{translational-vibrational energy exchange,} \end{aligned}$$

$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} (c_{v_s} T + e_{v_s} + h_s^o)$$

Scope of Code Verification

Conservation of mass, momentum, and energy:

Non-diffusive flux gradients

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_c(\mathbf{U}) = -\nabla \cdot \mathbf{F}_p(\mathbf{U}) + \nabla \cdot \mathbf{F}_d(\mathbf{U}) + \mathbf{S}(\mathbf{U}),$$

where

Spatial discretization

$$\mathbf{U} = \begin{Bmatrix} \rho \\ \rho \mathbf{v} \\ \rho E \\ \rho e_v \end{Bmatrix}, \quad \mathbf{F}_c(\mathbf{U}) = \begin{Bmatrix} \rho \mathbf{v}^T \\ \rho \mathbf{v} \mathbf{v}^T \\ \rho E \mathbf{v}^T \\ \rho e_v \mathbf{v}^T \end{Bmatrix}, \quad \mathbf{F}_p(\mathbf{U}) = \begin{Bmatrix} \mathbf{0} \\ p \mathbf{I} \\ p \mathbf{v}^T \\ \mathbf{0} \end{Bmatrix}, \quad \mathbf{F}_d(\mathbf{U}) = \begin{Bmatrix} -\mathbf{J} \\ \boldsymbol{\tau} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_v - \mathbf{J}^T \mathbf{h})^T \\ (-\mathbf{q}_v - \mathbf{J}^T \mathbf{e}_v)^T \end{Bmatrix},$$

$$\mathbf{S}(\mathbf{U}) = \begin{Bmatrix} \dot{\mathbf{w}} \\ \mathbf{0} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_v^T \dot{\mathbf{w}} \end{Bmatrix}, \quad \begin{aligned} \rho &= \{\rho_1, \dots, \rho_{n_s}\}^T, & \dot{\mathbf{w}} &= \{\dot{w}_1, \dots, \dot{w}_{n_s}\}^T: \text{mass production rates per volume,} \\ \rho &= \sum_{s=1}^{n_s} \rho_s, & e_v &= \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} e_{v_s}: \text{mixture vibrational energy per mass,} \\ p &= \sum_{s=1}^{n_s} \frac{\rho_s}{M_s} \bar{R} T, & \mathbf{e}_v &= \{e_{v_1}, \dots, e_{v_{n_s}}\}^T: \text{vibrational energies per mass,} \\ & & Q_{t-v} &: \text{translational-vibrational energy exchange,} \end{aligned}$$

$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} (c_{v_s} T + e_{v_s} + h_s^o)$$

Scope of Code Verification

Conservation of mass, momentum, and energy:

Thermochemical source term

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_c(\mathbf{U}) = -\nabla \cdot \mathbf{F}_p(\mathbf{U}) + \nabla \cdot \mathbf{F}_d(\mathbf{U}) + \mathbf{S}(\mathbf{U}),$$

where

Implementation

$$\mathbf{U} = \begin{Bmatrix} \rho \\ \rho \mathbf{v} \\ \rho E \\ \rho e_v \end{Bmatrix}, \quad \mathbf{F}_c(\mathbf{U}) = \begin{Bmatrix} \rho \mathbf{v}^T \\ \rho \mathbf{v} \mathbf{v}^T \\ \rho E \mathbf{v}^T \\ \rho e_v \mathbf{v}^T \end{Bmatrix}, \quad \mathbf{F}_p(\mathbf{U}) = \begin{Bmatrix} 0 \\ p \mathbf{I} \\ p \mathbf{v}^T \\ 0 \end{Bmatrix}, \quad \mathbf{F}_d(\mathbf{U}) = \begin{Bmatrix} -\mathbf{J} \\ \boldsymbol{\tau} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_v - \mathbf{J}^T \mathbf{h})^T \\ (-\mathbf{q}_v - \mathbf{J}^T \mathbf{e}_v)^T \end{Bmatrix},$$

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$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} (c_{v_s} T + e_{v_s} + h_s^o)$$

Outline

- Introduction
- Governing Equations
- Verification Techniques for Spatial Accuracy
 - Spatial Accuracy
 - Solutions
 - Error Norms
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Spatial Accuracy (Steady State)

Governing equations

$$\mathbf{r}(\mathbf{U}; \boldsymbol{\mu}) = \mathbf{0}$$

Discretized equations

$$\tilde{\mathbf{r}}(\tilde{\mathbf{U}}; \boldsymbol{\mu}) = \mathbf{0}$$

For \tilde{p}^{th} -order-accurate discretization, error is

$$\mathbf{e}(\mathbf{x}) = \tilde{\mathbf{U}}(\mathbf{x}) - \mathbf{U}(\mathbf{x}) = \mathbf{C}(\mathbf{x})h^{\tilde{p}(\mathbf{x})} + \mathcal{O}(h^{\tilde{p}(\mathbf{x})+1})$$

h : relative characterization of cell sizes

- Between meshes, with respect to one dimension
- Individual cell sizes may be non-uniform functions of h
- Sufficiently fine meshes \rightarrow asymptotic region ($h^{\tilde{p}(\mathbf{x})+1} \ll h^{\tilde{p}(\mathbf{x})}$)

$$\mathbf{e}(\mathbf{x}) \approx \mathbf{C}(\mathbf{x})h^{\tilde{p}(\mathbf{x})}$$

$\mathbf{C}(\mathbf{x})$: function of derivative(s) of the state vector \mathbf{U} at \mathbf{x}

- Approximately constant between meshes in asymptotic region

Order of Accuracy

Observed accuracy $\tilde{p}(\mathbf{x})$ computed using 2 meshes:

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Finer mesh (h/q)

(q -times as fine in each dimension)

$$e_2(\mathbf{x}) = C(\mathbf{x})(h/q)^{\tilde{p}(\mathbf{x})}$$

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$\tilde{p}(\mathbf{x})$ is computed by

$$\tilde{p}(\mathbf{x}) = \frac{\log |e_1(\mathbf{x})/e_2(\mathbf{x})|}{\log q} = \log_q |e_1(\mathbf{x})/e_2(\mathbf{x})|$$

Solutions

Need solution to compute error

Solutions

Exact Solutions

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- Do not satisfy original equations: $\mathbf{r}(\mathbf{U}_{\text{MS}}; \mu) \neq \mathbf{0}$

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 - Maximum error
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- Without discontinuities, both norms should yield same p

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1D Supersonic Flow using a Manufactured Solution

- One-dimensional domain: $x \in [0, 1]$ m
- Boundary conditions:
 - Supersonic inflow ($x = 0$ m)
 - Supersonic outflow ($x = 1$ m)
- 5 uniform meshes: 50, 100, 200, 400, 800 elements
- Solution consists of small, smooth perturbations to uniform flow:

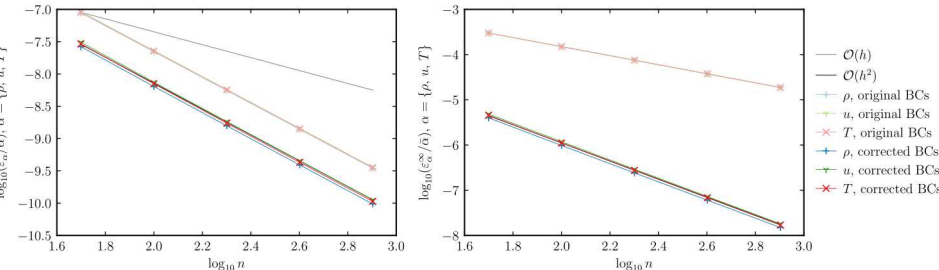
$$\rho(x) = \bar{\rho} [1 - \epsilon \sin(\pi x)],$$

$$u(x) = \bar{u} [1 - \epsilon \sin(\pi x)],$$

$$T(x) = \bar{T} [1 + \epsilon \sin(\pi x)],$$

$$\bar{\rho} = 1 \text{ kg/m}^3, \bar{T} = 300 \text{ K}, \bar{M} = 2.5, \epsilon = 0.05$$

1D Supersonic Flow using a Manufactured Solution



Mesh	First-order accurate			Second-order accurate		
	Original boundary conditions			Corrected boundary conditions		
	ρ	u	T	ρ	u	T
1-2	1.0008	1.0008	1.0008	2.0313	2.0362	2.0351
2-3	1.0002	1.0002	1.0002	2.0157	2.0184	2.0178
3-4	1.0001	1.0001	1.0000	2.0079	2.0093	2.0090
4-5	1.0000	1.0000	1.0000	2.0040	2.0047	2.0045

Observed accuracy p using L^∞ -norms of the error

2D Supersonic Flow using a Manufactured Solution

- Two-dimensional domain: $(x, y) \in [0, 1] \text{ m} \times [0, 1] \text{ m}$
- Boundary conditions:
 - Supersonic inflow ($x = 0 \text{ m}$)
 - Supersonic outflow ($x = 1 \text{ m}$)
 - Slip wall (tangent flow) ($y = 0 \text{ m}$ & $y = 1 \text{ m}$)
- 5 nonuniform meshes: $25 \times 25 \rightarrow 400 \times 400$
- Solution consists of small, smooth perturbations to uniform flow:

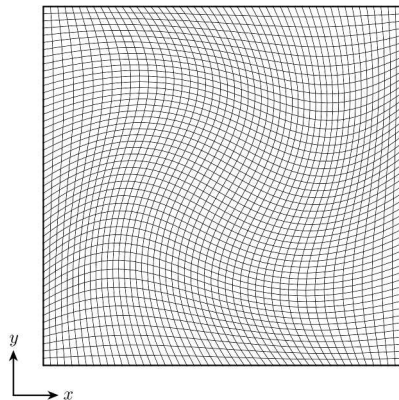
$$\rho(x, y) = \bar{\rho} \left[1 - \epsilon \sin\left(\frac{5}{4}\pi x\right) \left(\sin(\pi y) + \cos(\pi y) \right) \right],$$

$$u(x, y) = \bar{u} \left[1 + \epsilon \sin\left(\frac{1}{4}\pi x\right) \left(\sin(\pi y) + \cos(\pi y) \right) \right],$$

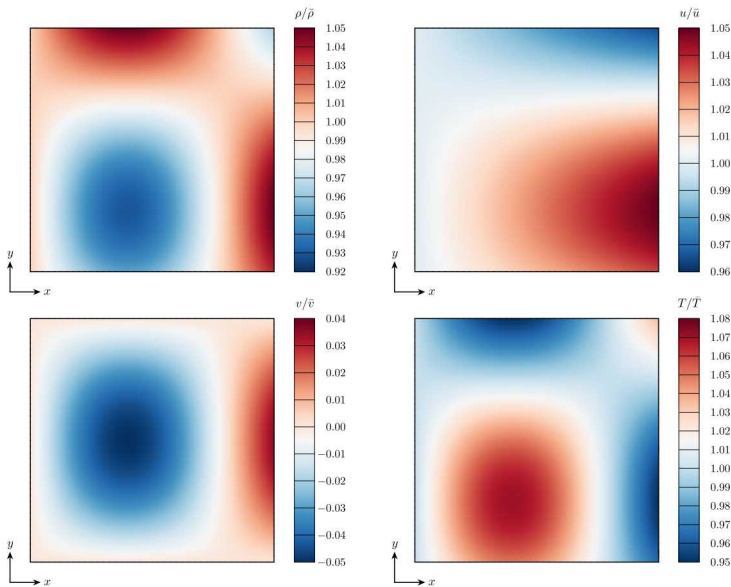
$$v(x, y) = \bar{v} \left[-\epsilon \sin\left(\frac{5}{4}\pi x\right) \left(\sin(\pi y) - \cos(\pi y) \right) \right],$$

$$T(x, y) = \bar{T} \left[1 + \epsilon \sin\left(\frac{5}{4}\pi x\right) \left(\sin(\pi y) + \cos(\pi y) \right) \right],$$

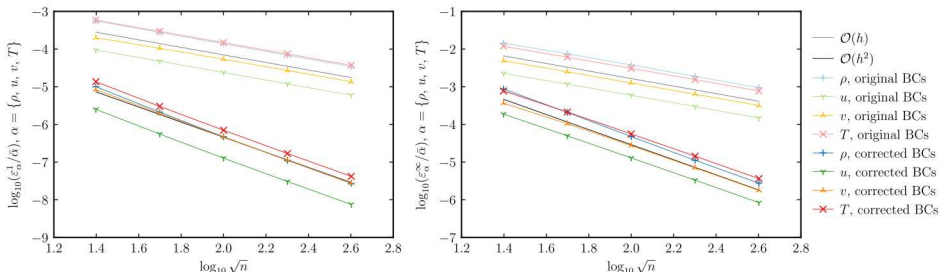
$$\bar{\rho} = 1 \text{ kg/m}^3, \bar{T} = 300 \text{ K}, \bar{M} = 2.5, \epsilon = 0.05$$



2D Supersonic Flow using a Manufactured Solution



2D Supersonic Flow using a Manufactured Solution



Mesh	First-order accurate				Second-order accurate			
	Original boundary conditions				Corrected boundary conditions			
	ρ	u	v	T	ρ	u	v	T
1-2	0.9420	0.9409	0.9721	0.9628	2.0623	1.9188	1.8174	1.8598
2-3	0.9850	0.9902	0.9910	0.9874	2.1304	1.9450	1.9221	1.9280
3-4	0.9960	1.0002	0.9924	0.9952	2.0902	1.9603	1.9671	1.9586
4-5	0.9989	1.0009	0.9959	0.9984	2.0128	1.9823	1.9860	1.9809

Observed accuracy p using L^∞ -norms of the error

2D Supersonic Flow using an Exact Solution

- Two-dimensional domain: $(r, \theta) \in [1, 1.384] \times [0, 90]^\circ$
- Boundary conditions:
 - Supersonic inflow ($\theta = 90^\circ$)
 - Supersonic outflow ($\theta = 0^\circ$)
 - Slip wall (tangent flow) ($r = 1$ & $r = 1.384$)
- 6 meshes: $32 \times 8 \rightarrow 1024 \times 256$
- Solution is steady isentropic vortex:

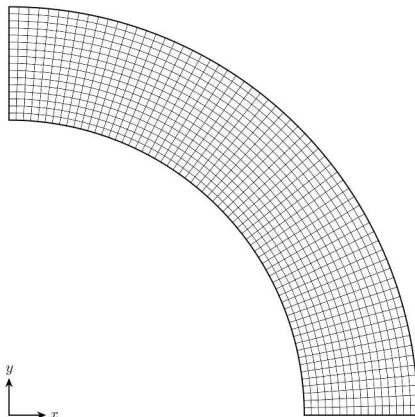
$$\rho(r) = \rho_i \left[1 + \frac{\gamma-1}{2} M_i^2 \left(1 - \left(\frac{r_i}{r} \right)^2 \right) \right]^{\frac{1}{\gamma-1}},$$

$$u_r(r) = 0,$$

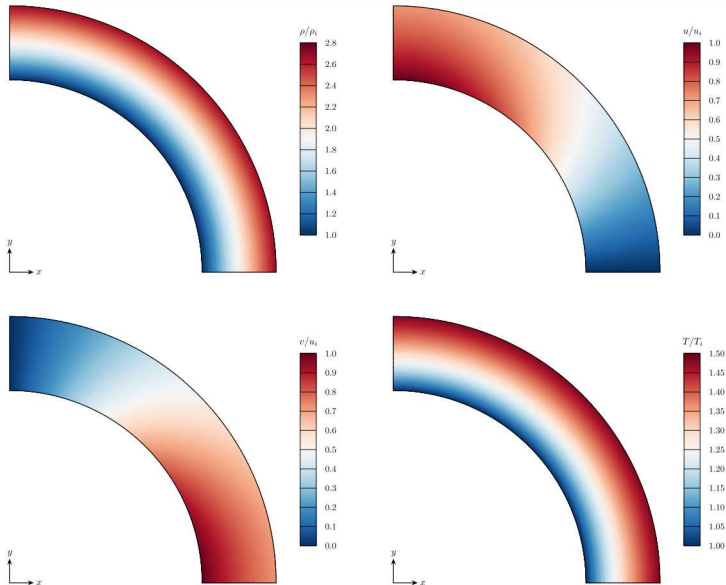
$$u_\theta(r) = -a_i M_i \frac{r_i}{r},$$

$$T(r) = T_i \left[1 + \frac{\gamma-1}{2} M_i^2 \left(1 - \left(\frac{r_i}{r} \right)^2 \right) \right],$$

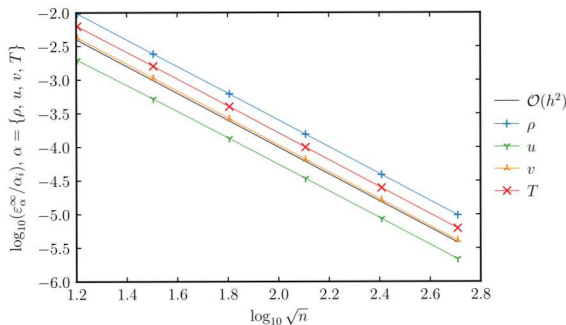
$$\rho_i = 1, a_i = 1, M_i = 2.25, T_i = 1/(\gamma R)$$



2D Supersonic Flow using an Exact Solution



2D Supersonic Flow using an Exact Solution



Mesh	ρ	u	v	T
1-2	1.9896	1.9119	1.9943	1.9699
2-3	1.9735	1.9589	2.0070	1.9979
3-4	1.9954	1.9760	2.0099	2.0076
4-5	1.9972	1.9879	2.0054	2.0044
5-6	1.9986	1.9940	2.0029	2.0025

Observed accuracy p using L^{∞} -norms of the error

3D Supersonic Flow using a Manufactured Solution

- Three-dimensional domain: $(x, y, z) \in [0, 1] \text{ m} \times [0, 1] \text{ m} \times [0, 1] \text{ m}$
- Boundary conditions:
 - Supersonic inflow ($x = 0 \text{ m}$)
 - Supersonic outflow ($x = 1 \text{ m}$)
 - Slip wall (tangent flow) ($y = 0 \text{ m}, y = 1 \text{ m}, z = 0 \text{ m}, z = 1 \text{ m}$)
- 5 nonuniform meshes: $25 \times 25 \times 25 \rightarrow 400 \times 400 \times 400$
- Solution consists of small, smooth perturbations to uniform flow:

$$\rho(x, y, z) = \bar{\rho} \left[1 - \epsilon \sin\left(\frac{5}{4}\pi x\right) (\sin(\pi y) + \cos(\pi y)) (\sin(\pi z) + \cos(\pi z)) \right],$$

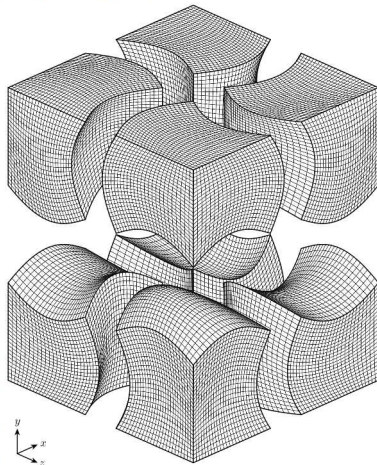
$$u(x, y, z) = \bar{u} \left[1 + \epsilon \sin\left(\frac{1}{4}\pi x\right) (\sin(\pi y) + \cos(\pi y)) (\sin(\pi z) + \cos(\pi z)) \right],$$

$$v(x, y, z) = \bar{v} \left[-\epsilon \sin\left(\frac{5}{4}\pi x\right) (\sin(\pi y)) (\sin(\pi z) + \cos(\pi z)) \right],$$

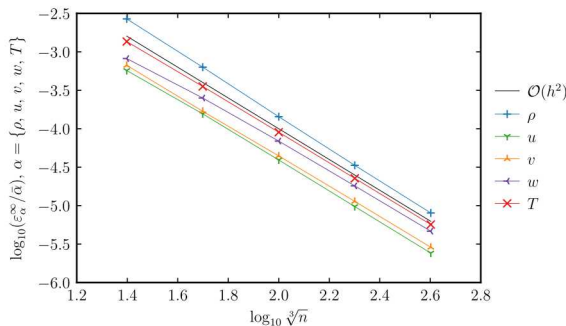
$$w(x, y, z) = \bar{w} \left[-\epsilon \sin\left(\frac{5}{4}\pi x\right) (\sin(\pi y) + \cos(\pi y)) (\sin(\pi z)) \right],$$

$$T(x, y, z) = \bar{T} \left[1 + \epsilon \sin\left(\frac{5}{4}\pi x\right) (\sin(\pi y) + \cos(\pi y)) (\sin(\pi z) + \cos(\pi z)) \right],$$

$$\bar{\rho} = 1 \text{ kg/m}^3, \bar{T} = 300 \text{ K}, \bar{M} = 2.5, \epsilon = 0.05$$



3D Supersonic Flow using a Manufactured Solution



Mesh	ρ	u	v	w	T
1-2	2.0849	1.8731	1.9841	1.7039	1.9404
2-3	2.1406	1.9923	1.9295	1.8621	1.9774
3-4	2.0990	2.0115	1.9623	1.9349	1.9922
4-5	2.0585	2.0100	1.9820	1.9571	1.9964

Observed accuracy p using L^{∞} -norms of the error

Five-Species Air Model

5 species: N₂, O₂, NO, N, and O

17 reactions:

r	Reaction		Type of Reaction
1–5	$\text{N}_2 + \mathcal{M} \rightleftharpoons \text{N} + \text{N} + \mathcal{M},$	$\mathcal{M} = \{\text{N}_2, \text{O}_2, \text{NO}, \text{N}, \text{O}\}$	Dissociation
6–10	$\text{O}_2 + \mathcal{M} \rightleftharpoons \text{O} + \text{O} + \mathcal{M},$	$\mathcal{M} = \{\text{N}_2, \text{O}_2, \text{NO}, \text{N}, \text{O}\}$	Dissociation
11–15	$\text{NO} + \mathcal{M} \rightleftharpoons \text{N} + \text{O} + \mathcal{M},$	$\mathcal{M} = \{\text{N}_2, \text{O}_2, \text{NO}, \text{N}, \text{O}\}$	Dissociation
16	$\text{N}_2 + \text{O} \rightleftharpoons \text{N} + \text{NO}$		Exchange
17	$\text{NO} + \text{O} \rightleftharpoons \text{N} + \text{O}_2$		Exchange

Five-Species Inviscid Flow in Chemical Nonequilibrium

- Two-dimensional domain: $(x, y) \in [0, 1] \text{ m} \times [0, 1] \text{ m}$
- Same boundary conditions
- 7 nonuniform meshes: $25 \times 25 \rightarrow 1600 \times 1600$
- Solution consists of small, smooth perturbations to uniform flow

$$\rho_{\text{N}_2}(x, y) = \bar{\rho}_{\text{N}_2} \left[1 - \epsilon \sin\left(\frac{5}{4}\pi x\right) \left(\sin(\pi y) + \cos(\pi y) \right) \right],$$

$$\rho_{\text{O}_2}(x, y) = \bar{\rho}_{\text{O}_2} \left[1 + \epsilon \sin\left(\frac{3}{4}\pi x\right) \left(\sin(\pi y) + \cos(\pi y) \right) \right],$$

$$\rho_{\text{NO}}(x, y) = \bar{\rho}_{\text{NO}} \left[1 + \epsilon \sin(\pi x) \left(\sin(\pi y) \right) \right],$$

$$\rho_{\text{N}}(x, y) = \bar{\rho}_{\text{N}} \left[1 + \epsilon \sin(\pi x) \left(\cos\left(\frac{1}{4}\pi y\right) \right) \right],$$

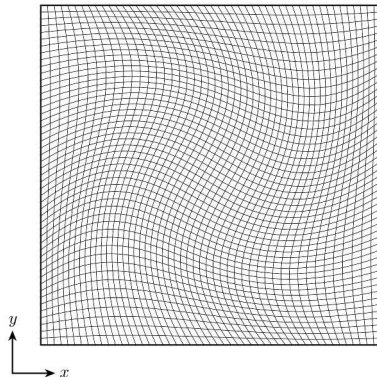
$$\rho_{\text{O}}(x, y) = \bar{\rho}_{\text{O}} \left[1 + \epsilon \sin(\pi x) \left(\sin(\pi y) + \cos\left(\frac{1}{4}\pi y\right) \right) \right],$$

$$u(x, y) = \bar{u} \left[1 + \epsilon \sin\left(\frac{1}{4}\pi x\right) \left(\sin(\pi y) + \cos(\pi y) \right) \right],$$

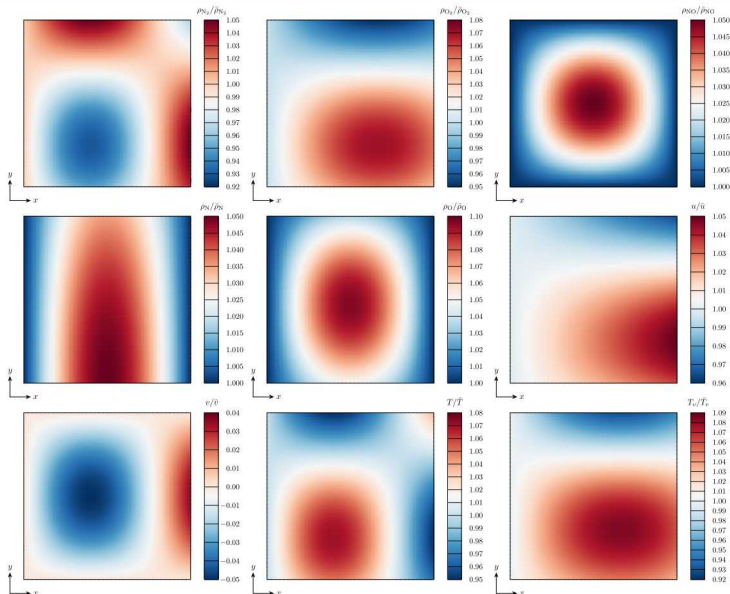
$$v(x, y) = \bar{v} \left[-\epsilon \sin\left(\frac{5}{4}\pi x\right) \left(\sin(\pi y) \right) \right],$$

$$T(x, y) = \bar{T} \left[1 + \epsilon \sin\left(\frac{5}{4}\pi x\right) \left(\sin(\pi y) + \cos(\pi y) \right) \right],$$

$$T_v(x, y) = \bar{T}_v \left[1 + \epsilon \sin\left(\frac{3}{4}\pi x\right) \left(\sin\left(\frac{5}{4}\pi y\right) + \cos\left(\frac{3}{4}\pi y\right) \right) \right]$$

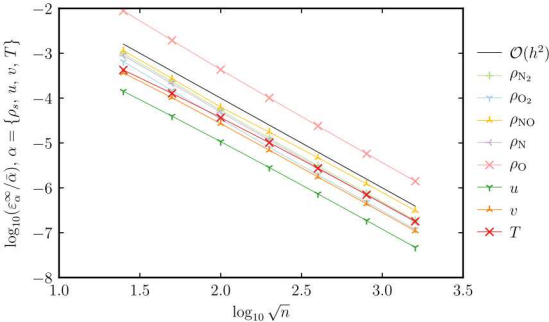


Five-Species Inviscid Flow in Chemical Nonequilibrium



2D Supersonic Flow in Thermal Equilibrium using a Manufactured Solution

Variable	Value	Units
$\bar{\rho}_{\text{N}_2}$	0.77	kg/m ³
$\bar{\rho}_{\text{O}_2}$	0.20	kg/m ³
$\bar{\rho}_{\text{NO}}$	0.01	kg/m ³
$\bar{\rho}_{\text{N}}$	0.01	kg/m ³
$\bar{\rho}_{\text{O}}$	0.01	kg/m ³
\bar{T}	3500	K
\bar{M}	2.5	
ϵ	0.05	

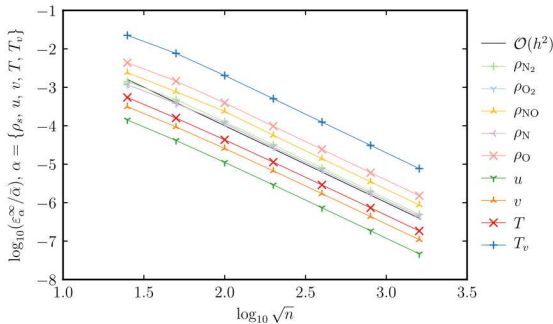


Mesh	ρ_{N_2}	ρ_{O_2}	ρ_{NO}	ρ_{N}	ρ_{O}	u	v	T
1-2	2.0608	2.1382	2.0698	2.0644	2.1885	1.8425	1.8289	1.7351
2-3	2.1161	2.1219	2.1127	2.1072	2.1697	1.8875	1.9220	1.7923
3-4	2.0798	2.0813	1.8555	2.0754	2.0971	1.9200	1.9686	1.8525
4-5	2.0456	2.0458	1.8917	2.0428	2.0806	1.9522	1.9871	1.9079
5-6	2.0243	2.0243	1.9427	2.0228	2.0529	1.9735	1.9939	1.9485
6-7	2.0125	2.0125	1.9790	2.0118	2.0318	1.9865	1.9969	1.9737

2D MMS, $n_s = 5$, $T_v = T$, $\dot{\mathbf{w}} \neq \mathbf{0}$: Observed accuracy p using L^∞ -norms of the error

2D Hypersonic Flow in Thermal Nonequilibrium using a Manufactured Solution

Variable	Value	Units
$\bar{\rho}_{\text{N}_2}$	0.0077	kg/m ³
$\bar{\rho}_{\text{O}_2}$	0.0020	kg/m ³
$\bar{\rho}_{\text{NO}}$	0.0001	kg/m ³
$\bar{\rho}_{\text{N}}$	0.0001	kg/m ³
$\bar{\rho}_{\text{O}}$	0.0001	kg/m ³
\bar{T}	5000	K
\bar{T}_v	1000	K
\bar{M}	8	
ϵ	0.05	



Mesh	ρ_{N_2}	ρ_{O_2}	ρ_{NO}	ρ_{N}	ρ_{O}	u	v	T	T_v
1-2	1.5659	1.6370	1.6555	1.6046	1.5869	1.7742	1.7337	1.7814	1.5545
2-3	1.9067	1.6944	1.6986	1.7598	1.8819	1.8916	1.8701	1.8768	1.9150
3-4	1.9868	2.0475	2.0698	2.0477	2.0110	1.9488	1.9357	1.9349	2.0082
4-5	2.0074	1.9941	2.0138	1.9936	2.0089	1.9752	1.9684	1.9672	2.0168
5-6	2.0062	1.9939	2.0004	1.9935	2.0061	1.9879	1.9843	1.9836	2.0111
6-7	2.0037	1.9965	1.9994	1.9962	1.9955	1.9940	1.9922	1.9918	2.0063

2D MMS, $n_s = 5$, $T_v \neq T$, $\dot{\mathbf{w}} \neq \mathbf{0}$: Observed accuracy p using L^∞ -norms of the error

Outline

- Introduction
- Governing Equations
- Verification Techniques for Spatial Accuracy
- Spatial-Discretization Verification Results
- Verification Techniques for Thermochemical Source Term
 - Techniques
 - Distinctive Features
- Thermochemical-Source-Term Verification Results
- Summary

Verification Techniques for Thermochemical Source Term

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 - For many values of $\{\boldsymbol{\rho}, T, T_v\}$
 - Compare with independently developed code
- For each query, compute symmetric relative difference

$$\delta_\beta = 2 \left| \frac{\beta_{\text{SPARC}} - \beta'}{\beta_{\text{SPARC}} + \beta'} \right|$$

$$\beta = \{Q_{t-v}, e_{v_{\text{N}_2}}, e_{v_{\text{O}_2}}, e_{v_{\text{NO}}}, \dot{w}_{\text{N}_2}, \dot{w}_{\text{O}_2}, \dot{w}_{\text{NO}}, \dot{w}_{\text{N}}, \dot{w}_{\text{O}}\}$$

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Outline

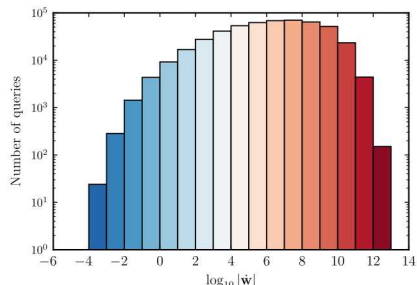
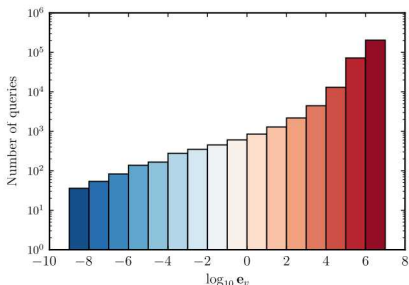
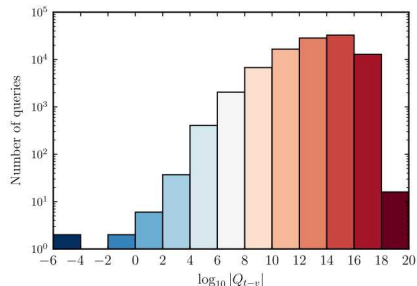
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Samples of $Q_{t-v}(\rho, T, T_v)$, $e_v(\rho, T, T_v)$, and $\dot{w}(\rho, T, T_v)$

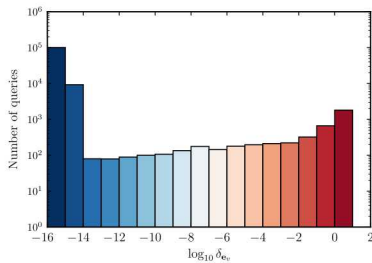
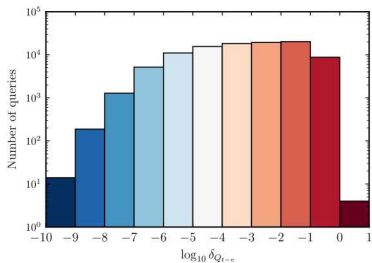
Variable	Minimum	Maximum	Units	Spacing
ρ_{N_2}	10^{-6}	10^1	kg/m ³	Logarithmic
ρ_{O_2}	10^{-6}	10^1	kg/m ³	Logarithmic
ρ_{NO}	10^{-6}	10^1	kg/m ³	Logarithmic
ρ_N	10^{-6}	10^1	kg/m ³	Logarithmic
ρ_O	10^{-6}	10^1	kg/m ³	Logarithmic
T	100	15,000	K	Linear
T_v	100	15,000	K	Linear

Ranges and spacings for 100,000

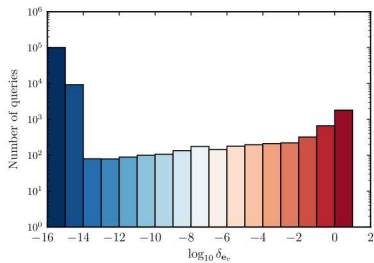
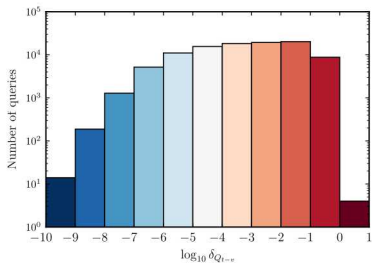
Latin hypercube samples of ρ , T , and T_v



Original Nonzero Relative Differences in Q_{t-v} and e_v

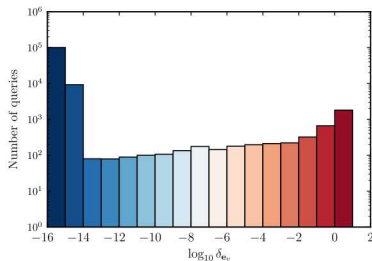
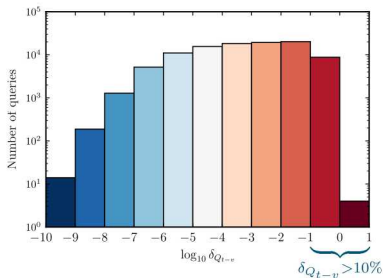


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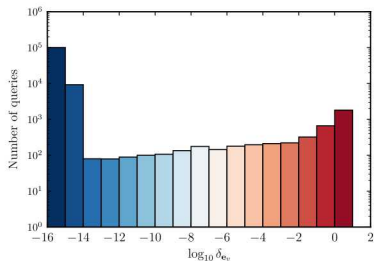
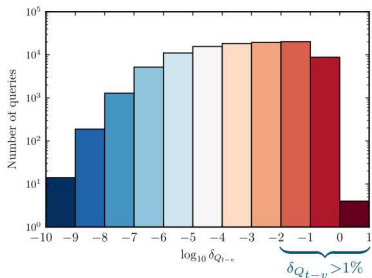
- Relative differences are **not** near machine precision

Original Nonzero Relative Differences in Q_{t-v} and e_v



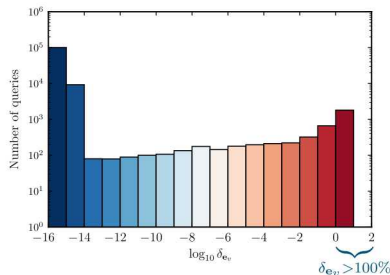
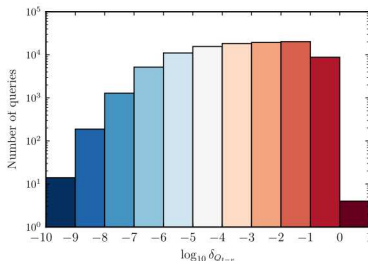
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- $\delta_{Q_{t-v}} > 10\%$ in 8.8% of simulations

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- $\delta_{Q_{t-v}} > 1\%$ in 29% of simulations

Original Nonzero Relative Differences in Q_{t-v} and e_v



- Relative differences are **not** near machine precision
- $\delta_{Q_{t-v}} > 10\%$ in 8.8% of simulations
- $\delta_{Q_{t-v}} > 1\%$ in 29% of simulations
- $\delta_{e_v} > 100\%$ for some simulations

Causes of Large Relative Differences in Q_{t-v} and e_v

Two causes:

Causes of Large Relative Differences in Q_{t-v} and e_v

Two causes:

- **Incorrect lookup table values** for vibrational constants
 - For N_2 and O_2 when the colliding species is NO
 - Introduced error in Q_{t-v} for all simulations
 - For high-enthalpy (20 MJ/kg), hypersonic, laminar double-cone flow, 1.4% change in pressure and 2.7% change in heat flux

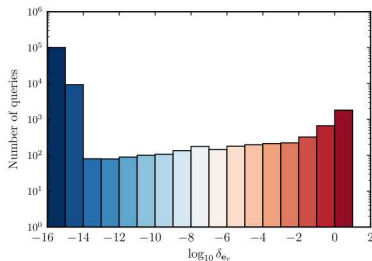
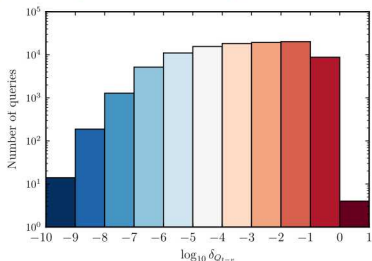
Causes of Large Relative Differences in Q_{t-v} and \mathbf{e}_v

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- **Loose convergence criteria** for computing T_v from ρe_v
 - Unsuitable for low values of T_v
 - Introduced errors in Q_{t-v} and \mathbf{e}_v for a few simulations
 - For converged, steady problem, original criteria are acceptable

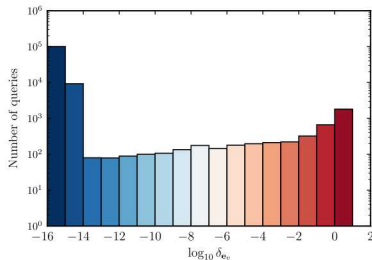
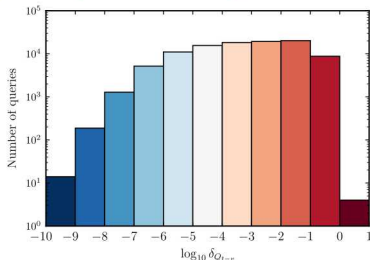
Corrected Nonzero Relative Differences in Q_{t-v} and e_v

Original lookup table and convergence criteria

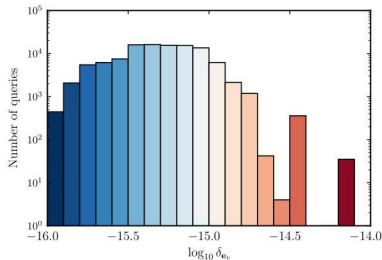
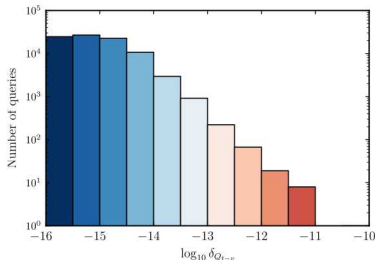


Corrected Nonzero Relative Differences in Q_{t-v} and e_v

Original lookup table and convergence criteria

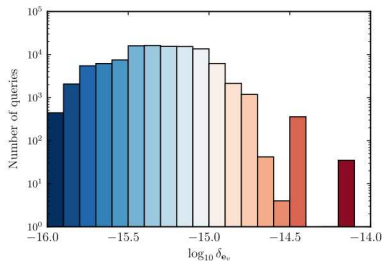
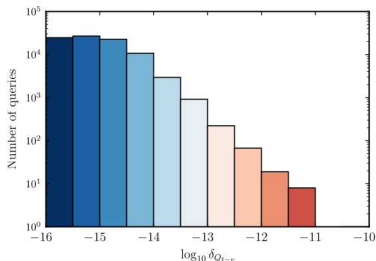


Corrected lookup table and tighter convergence criteria



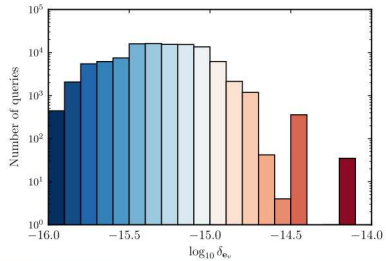
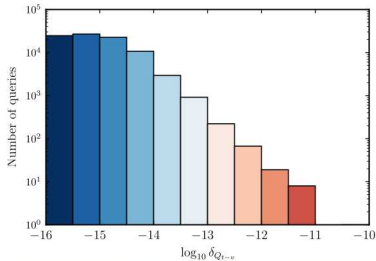
Corrected Nonzero Relative Differences in Q_{t-v} and e_v

- Relative differences are consistent with our expectations



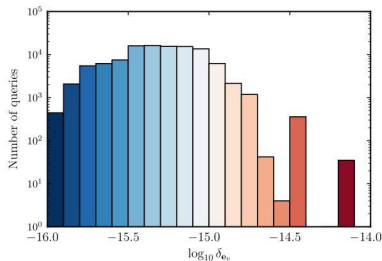
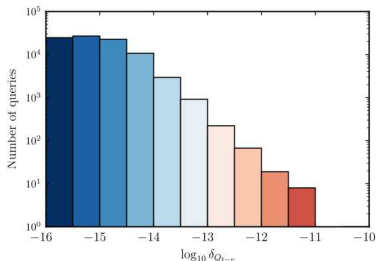
Corrected Nonzero Relative Differences in Q_{t-v} and e_v

- Relative differences are consistent with our expectations
- $\delta_{Q_{t-v}} < 10^{-10}$ and $\delta_{e_v} < 10^{-14}$ in all simulations



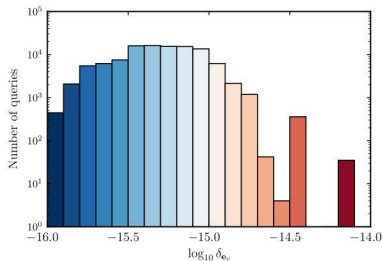
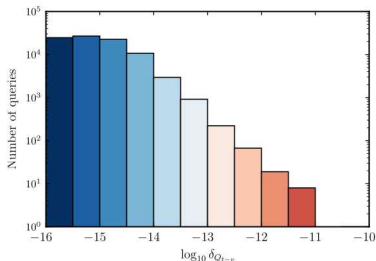
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- $\delta_{Q_{t-v}} < 10^{-10}$ and $\delta_{e_v} < 10^{-14}$ in all simulations
- $\delta_{Q_{t-v}} > 10^{-12}$ in 28/100,000 simulations



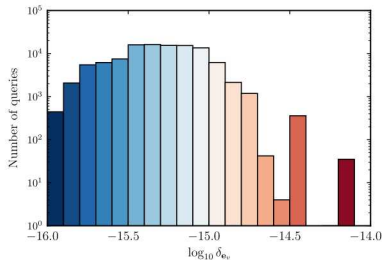
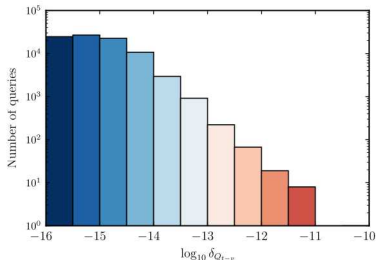
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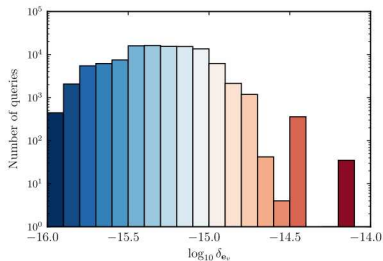
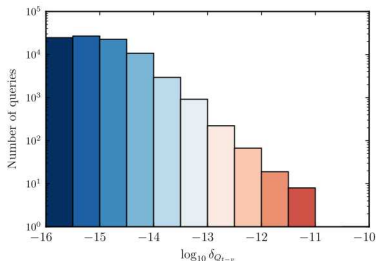
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 - In numerator of $\frac{e_{v,s,m}(T) - e_{v,s,m}(T_v)}{\langle \tau_{s,m} \rangle}$, $e_{v,s,m}(T)$ and $e_{v,s,m}(T_v)$ share many leading digits

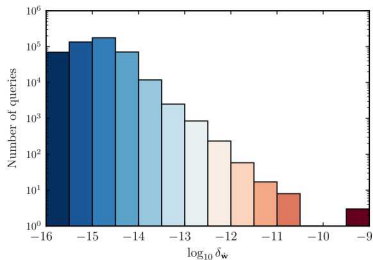


Corrected Nonzero Relative Differences in Q_{t-v} and e_v

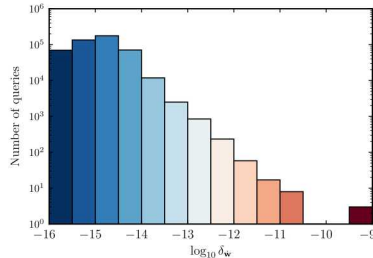
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 - Precision lost when computing difference



Nonzero Relative Differences in $\dot{\mathbf{w}}$

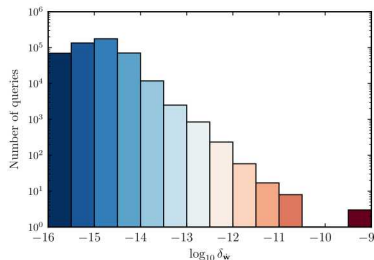


Nonzero Relative Differences in $\dot{\mathbf{w}}$



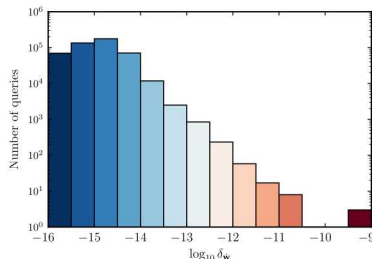
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Nonzero Relative Differences in \dot{w}



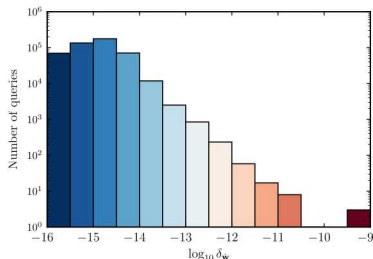
- Relative differences are consistent with our expectations
- $\dot{w} < 10^{-9}$ in all simulations

Nonzero Relative Differences in $\dot{\mathbf{w}}$



- Relative differences are consistent with our expectations
- $\dot{\mathbf{w}} < 10^{-9}$ in all simulations
- $\dot{\mathbf{w}} > 10^{-12}$ for 87/500,000 computed values (5 species, 100,000 simulations)

Nonzero Relative Differences in $\dot{\mathbf{w}}$



- Relative differences are consistent with our expectations
- $\dot{\mathbf{w}} < 10^{-9}$ in all simulations
- $\dot{\mathbf{w}} > 10^{-12}$ for 87/500,000 computed values (5 species, 100,000 simulations)
 - Due to precision loss that can occur from subtraction in

$$\dot{w}_s = M_s \sum_{r=1}^{n_r} (\beta_{s,r} - \alpha_{s,r}) (R_{f_r} - R_{b_r})$$

Outline

- Introduction
- Governing Equations
- Verification Techniques for Spatial Accuracy
- Spatial-Discretization Verification Results
- Verification Techniques for Thermochemical Source Term
- Thermochemical-Source-Term Verification Results
- Summary
 - Code-Verification Techniques

Code-Verification Techniques

- Manufactured and exact solutions
 - Effective approaches for verifying spatial accuracy – detected multiple issues
 - Rigorous norms improve effectiveness – L^∞ -norm of error more useful
 - Insufficient for algebraic source terms – both evaluations the same
- Thermochemical-source-term approach
 - Effective approach for verifying implementation – detected multiple issues

Questions?

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