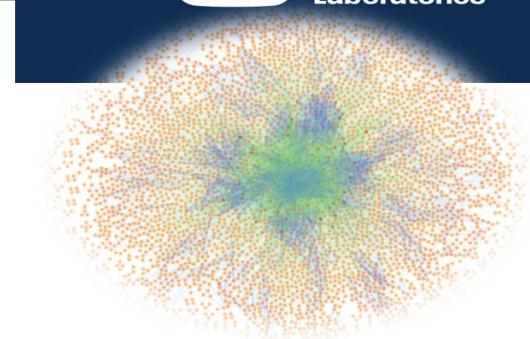


Exceptional service in the national interest



Higher Order Moment Tensors for Combustion Analysis: GPU Acceleration

Hemanth Kolla, Jed Duersch, Aditya Konduri and Jackie Chen
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Numerical Combustion, May 06th-08th, 2019, Aachen

Acknowledgments

- US-DOE, Office of Science, Exascale Computing Project (ECP).
- US-DOE, ASCR funded project *“In-situ Machine Learning for Exascale”*.
- Warren Davis, Tim Shead, Prashant Rai, Philip Kegelmeyer, Tammy Kolda, Julia Ling.
- Oakridge Leadership Computing Facility (OLCF).

Problem context

- Combustion simulation data are multi-scale, multi-variate.
- Tensors are a very powerful abstraction; Tensor decomposition offer a rich set of analyses.
- Higher order tensors are usually large and expensive to compute/store.
- Tensor algebra can (often is) posed as “multi-linear algebra”.
- GPU acceleration, leveraging well-established linear algebra kernels, can provide great speedups.

Outline

- Tensor-based analysis.
- Algorithm outline.
- Computational Challenge.
- GPU acceleration.

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- Tensor-based analysis: anomalous event detection.
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Hypothesis and proposed solution

- Information of anomalous events present in higher order statistical moments, e.g. kurtosis.
- For multi-variate non-Gaussian fields, joint moments (co-kurtosis) need to be analysed.
- Identify **principal vectors of kurtosis** (analogous to PCs in PCA) in the variable (a.k.a feature) space.
- *Anomalies manifest as principal kurtosis vectors (PKVs) that are “distinct”.*

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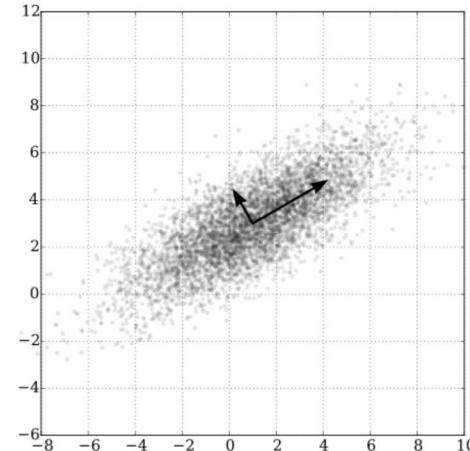
Principal Component Analysis (PCA) Revisit

- Eigen-decomposition of co-variance matrix.

- $$C = Q \Lambda Q^T$$

Covariance matrix

$$= \begin{matrix} \lambda_1 & q_1 \\ q_1 & \end{matrix} + \begin{matrix} \lambda_2 & q_2 \\ q_2 & \end{matrix} + \dots$$



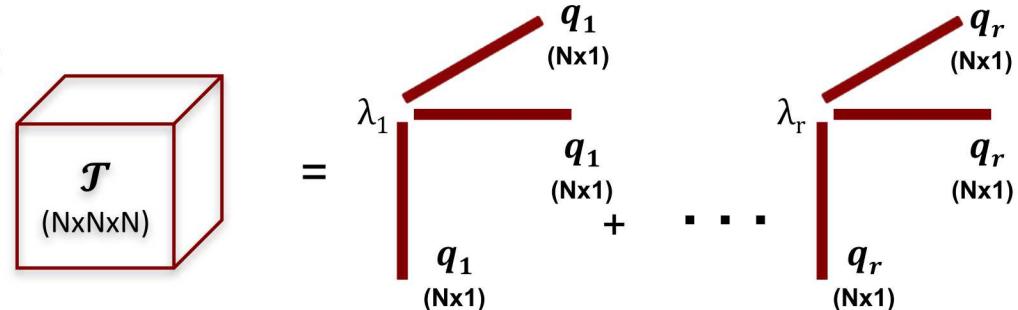
<https://commons.wikimedia.org/w/index.php?curid=46871195>

- Principal Components represent directions of variance in the data.
- By analogy, *we seek vectors that represent the higher moments*:
 - extend concept of PCA to higher joint moment (co-kurtosis) tensors.
 - becomes a *symmetric tensor decomposition problem*.

Symmetric Tensor Decomposition: Choices

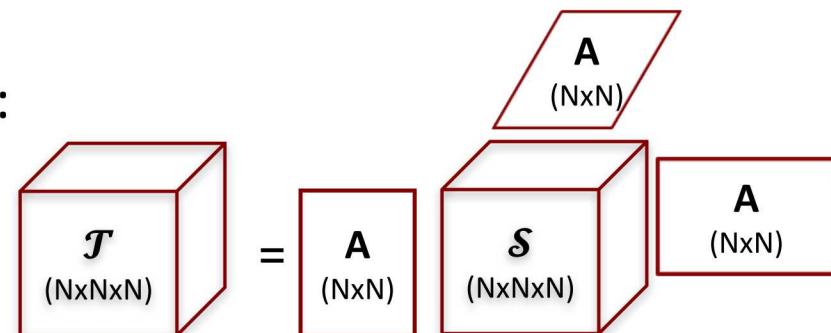
- Canonical Polyadic (CP) decomp:

- Sum of outer products of vectors.
- What rank, r (Comon *et al.* 2008)?
- Not orthogonal in general.



- Higher Order SVD (HOSVD, Lathauwer *et al.* 2000):

- Symmetric tensor is a special case
- Factor matrices (\mathbf{A}) are orthogonal.



- Tensor Eigenpairs (Lim 2005, Qi 2005, Kolda & Mayo 2011) :

- $\mathcal{T}\mathbf{x}^{m-1} = \lambda\mathbf{x}$

Outline

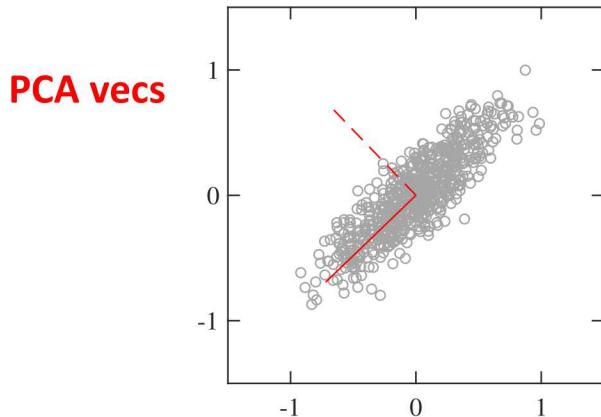
- Tensor-based analysis.
- Algorithm outline: Extract, Compare PKVs.
- Computational Challenge.
- GPU acceleration.

Simple Moment-Tensor Decomposition

- Motivated by connections to Independent Component Analysis (ICA).
- Operate on fourth cumulant tensor (Lathauwer & Moore 2001, Comon & Jutten 2010, Anandkumar *et al.* 2014)
 - $\mathcal{M}_4 := \mathbb{E}[x \otimes x \otimes x \otimes x] - \mathbb{E}[x_{i1}x_{i2}] \mathbb{E}[x_{i3}x_{i4}] - \mathbb{E}[x_{i1}x_{i3}] \mathbb{E}[x_{i2}x_{i4}] - \mathbb{E}[x_{i1}x_{i4}] \mathbb{E}[x_{i2}x_{i3}]$
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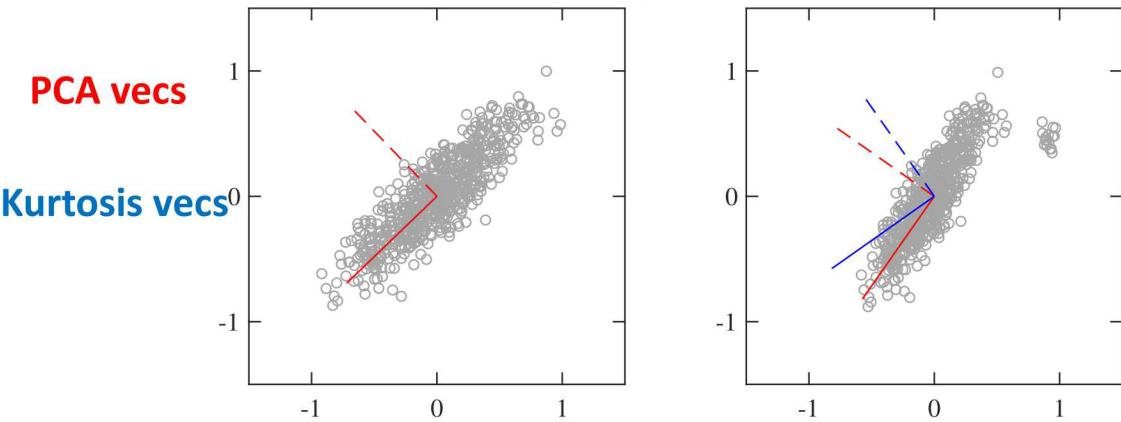
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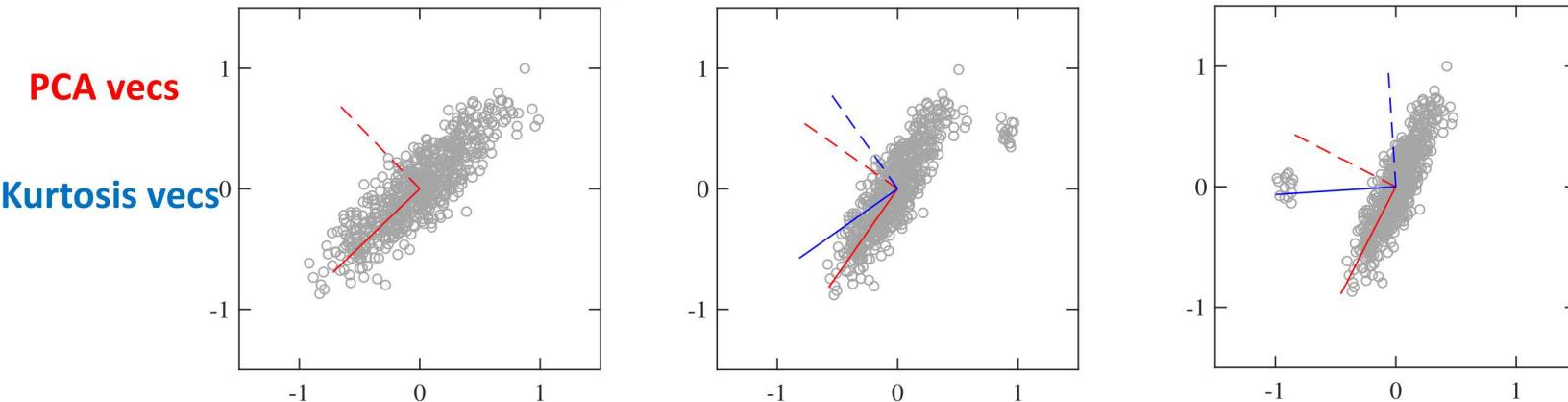
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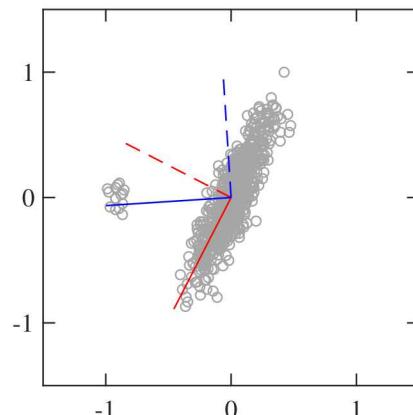
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Putting It Together: HCCI Data Set

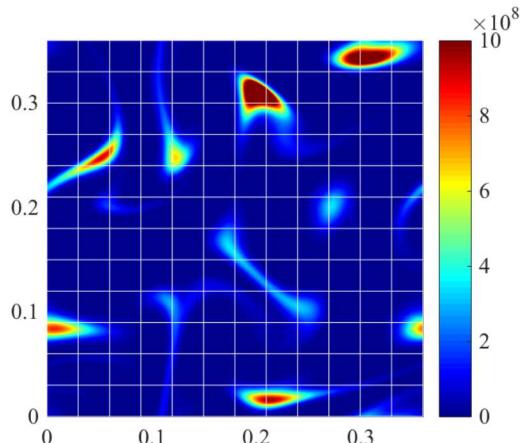
- Extract Principal Kurtosis Vectors (PKVs) on each MPI rank.
- Transform PKVs to a “moment (kurtosis) metric per feature (variable)”.
 - Moment metrics quantify contribution of a feature to overall kurtosis.
 - Normalized (between 0-1), and also sum to 1 (like a discrete distribution).
- Compare moment metrics across MPI ranks (**Hellinger distance**).



feature X has a higher metric (close to 1) than feature Y (close to 0).

Putting It Together: HCCI Data Set

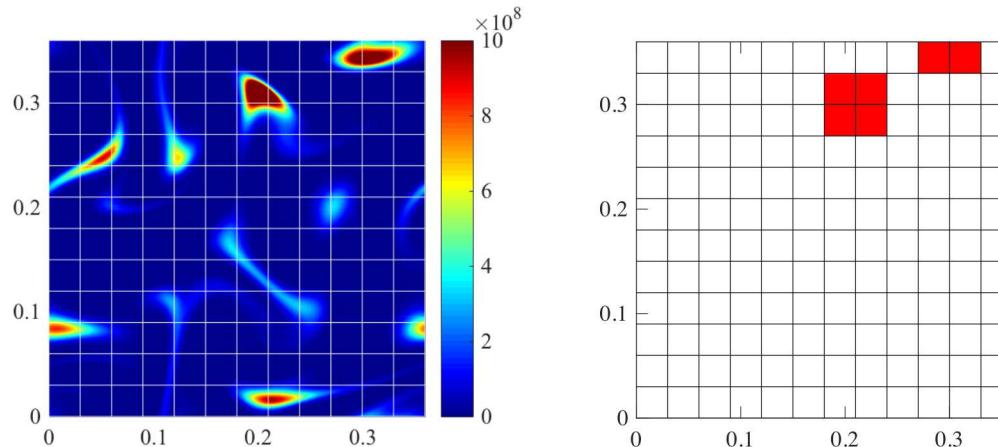
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K. Aditya, H. Kolla, W. P. Kegelmeyer, T. M. Shead, J. Ling, Warren L Davis IV, 2019,
[“Anomaly detection in scientific data using joint statistical moments”](#), *Journal of Computational Physics*, vol. 387, pp:522.

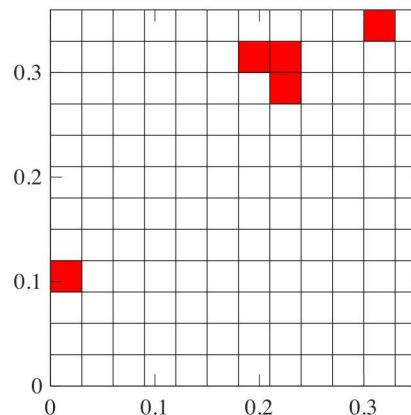
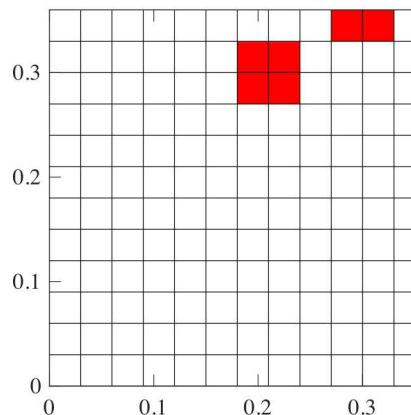
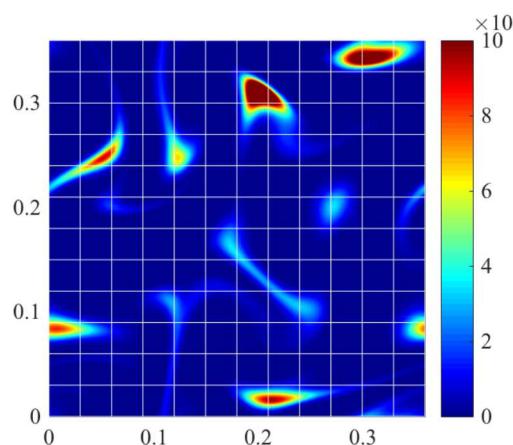
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Outline

- Tensor-based analysis.
- Algorithm outline.
- Computational Challenge: Moment Tensors are expensive.
- GPU acceleration.

Computational Considerations

- Revisiting the fourth moment (cumulant) tensor:
 - $\mathcal{M}_4 := \mathbb{E}[x \otimes x \otimes x \otimes x] - \mathbb{E}[x_{i1}x_{i2}] \mathbb{E}[x_{i3}x_{i4}] - \mathbb{E}[x_{i1}x_{i3}] \mathbb{E}[x_{i2}x_{i4}] - \mathbb{E}[x_{i1}x_{i4}] \mathbb{E}[x_{i2}x_{i3}]$
- Co-kurtosis tensor is large ($\mathcal{O}(\text{nvars}^4)$).
- Very expensive to compute.

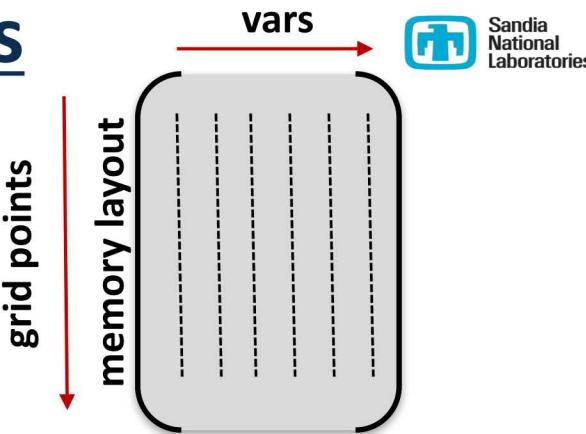
```

do L = 1, nvars
  do K = 1, nvars
    do J = 1, nvars
      do I = 1, nvars
        do N = 1, nx*ny*nz
          .....
        enddo
      enddo
    enddo
  enddo
enddo

```

Solution: Refactored Lin-Alg Kernels

Typical layout of data matrix, X (ngrid x nvars)



- Key insight: \mathcal{M}_4 can be expressed as sequence of operations on X^T
 - $\mathcal{S} = X^T \odot X^T$; \odot - Khatri-Rao product
 - $\text{mat}(\mathcal{M}_4) = \mathcal{S} \mathcal{S}^T$; matrix-matrix multiplication
- Any moment tensor can be expressed as such sequence; in the limit covariance $\mathcal{C} = X^T X$
- This refactoring saves both memory and compute.

Khatri-Rao product

- Preliminary: Kronecker product $\mathbf{A} \otimes \mathbf{B}$

$$\mathbf{A} := \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix}; \quad \mathbf{A} \otimes \mathbf{B} := \begin{bmatrix} a_{11}\mathbf{B} & \cdots & a_{1n}\mathbf{B} \\ \vdots & \ddots & \vdots \\ a_{m1}\mathbf{B} & \cdots & a_{mn}\mathbf{B} \end{bmatrix}$$

- Khatri-Rao product = column-wise Kronecker product

$$\mathbf{A} := \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix}; \quad \mathbf{B} := [b_1 \dots b_n]; \quad \mathbf{A} \odot \mathbf{B} := \begin{bmatrix} a_{11}b_1 & \cdots & a_{1n}b_n \\ \vdots & \ddots & \vdots \\ a_{m1}b_1 & \cdots & a_{mn}b_n \end{bmatrix}$$

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- Computational Challenge.
- GPU acceleration: Handwritten + cuBLAS kernel

GPU-fication of Key Lin-Alg Kernels

- $\mathcal{S} = \mathbf{X}^T \odot \mathbf{X}^T$; Khatri-Rao product hand-optimised:

- Coarse-grain parallelism.

- Thread parallelism + memory coalescence.

$$\mathbf{A} \odot \mathbf{B} := \begin{bmatrix} a_{11}b_1 & \cdots & a_{1n}b_n \\ \vdots & \ddots & \vdots \\ a_{m1}b_1 & \cdots & a_{mn}b_n \end{bmatrix}$$

GPU-fication of Key Lin-Alg Kernels

- $\mathcal{S} = X^T \odot X^T$; Khatri-Rao product hand-optimised:

- Coarse-grain parallelism: 2D Thread Block grid
- Thread parallelism + memory coalescence.

$$A \odot B := \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{p1} & a_{p2} & \dots & a_{pn} \end{bmatrix} \odot \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ b_{21} & b_{22} & \dots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{p1} & b_{p2} & \dots & b_{pn} \end{bmatrix}$$

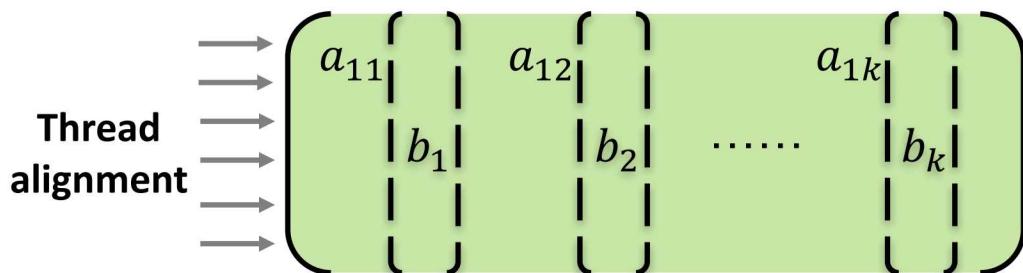
$$= \begin{bmatrix} TB(1,1) & TB(1,2) & \dots & TB(1,n) \\ TB(2,1) & TB(2,2) & \dots & TB(2,n) \\ \vdots & \vdots & \ddots & \vdots \\ TB(p,1) & TB(p,2) & \dots & TB(p,n) \end{bmatrix}$$

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- Threads operate on contiguous rows
- Reads (b_i) are contiguous vectors.
- Writes are also contiguous row elems.
- Threads in a block operate one column at a time.

- $\text{mat}(\mathcal{M}_4) = \mathcal{S} \mathcal{S}^T$; `cublasDgemm`.

GPU-Speedup

- Tests for the 2D-HCCI data set:
 - 56 x 56 grid points per block (MPI rank), 28 species.
 - Comparisons of refactored + GPU-fied kernel vs naïve Fortran.
 - Time includes the cost of a one-time data transpose, and host-GPU copies.
- Runs on Rhea @OLCF:
 - Intel® Xeon® E5-2695 (14 cores) + K80 GPUs.
 - cuda/10.0.130.
- CPU version (naïve Fortran), 9.5s; GPU version, 0.3s, **30x speedup.**

Summary

- For anomaly detection in scientific data, statistical models based on higher moments may be promising.
- Use of “principal vectors of Kurtosis” as indicators of anomalous events.
- Metrics quantify change in the principal kurtosis vectors and identify anomalous subdomains.
- Construction of PKVs as a symmetric tensor decomposition problem.
- Refactored linear algebra kernels for tensor formation ported effectively to GPUs, with ~30x speedups.

Extra Slides

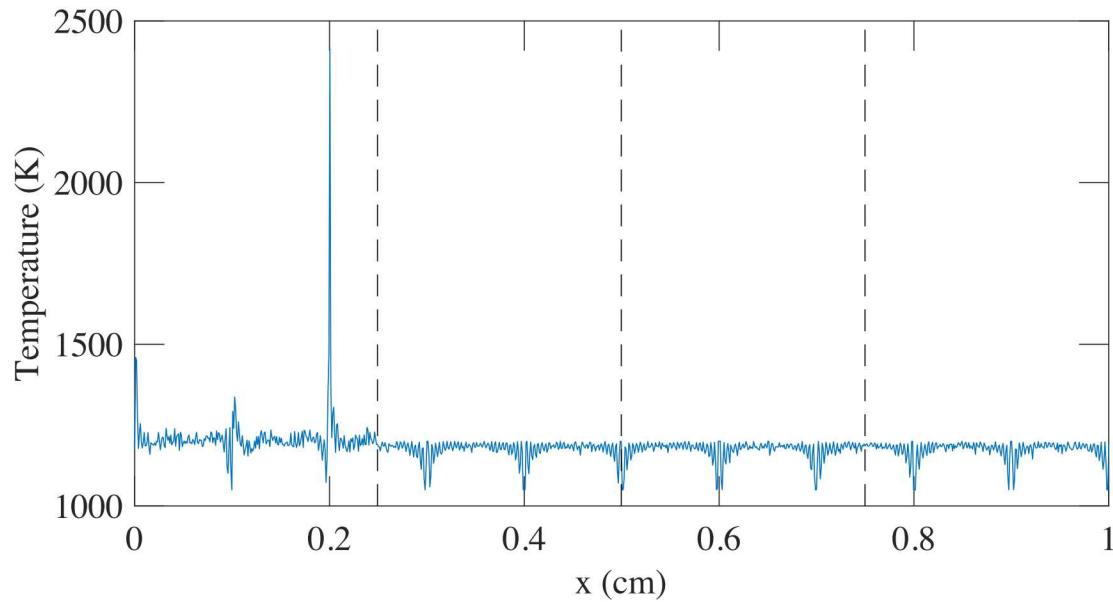
- Identifies non-Gaussian independent random variables that are linearly mixed:
 - $\mathbf{x} := \mathbf{As} + \mathbf{n}$. (x-observed vector; \mathbf{s} -independent sources, \mathbf{n} -Gaussian i.i.d noise)

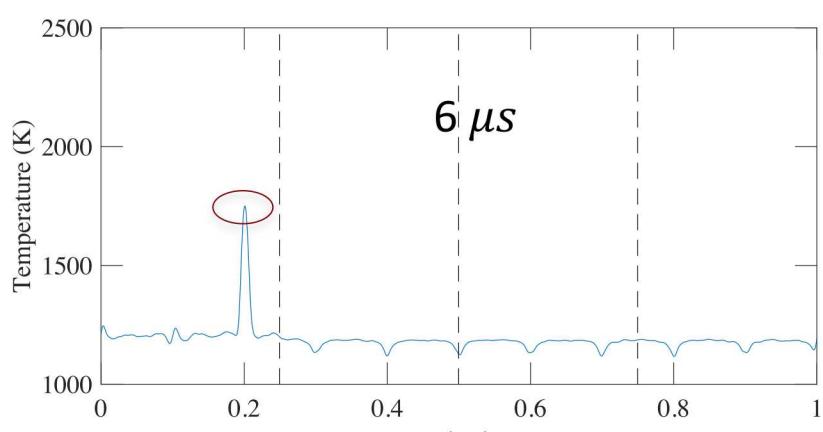
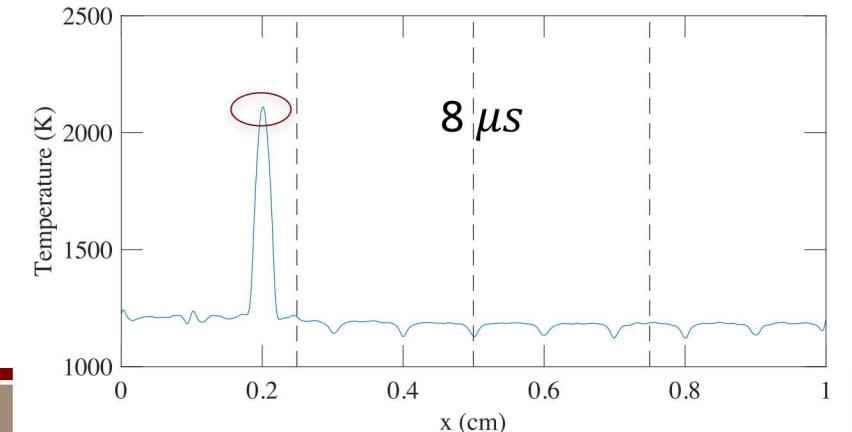
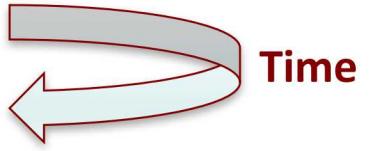
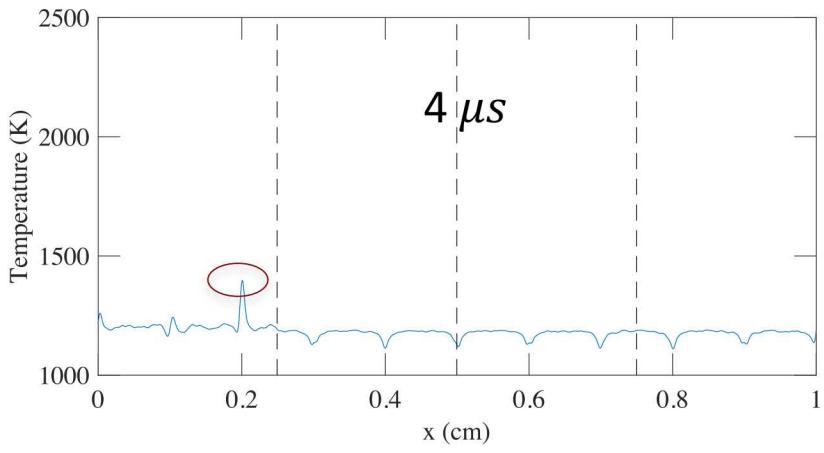
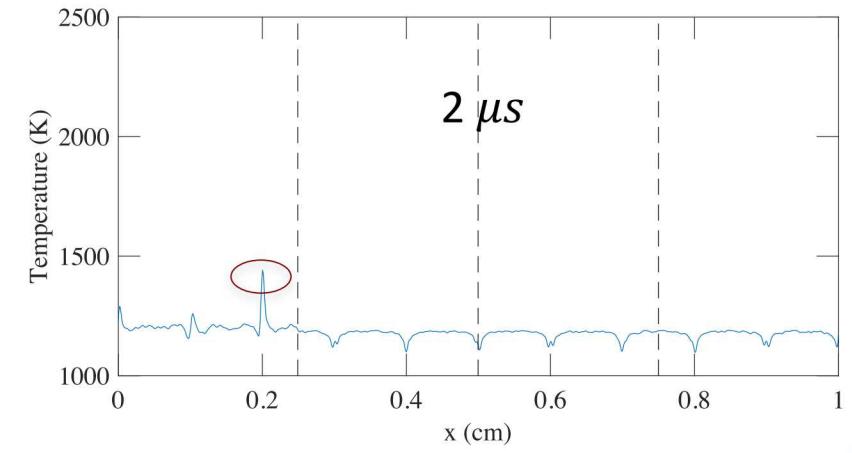
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Independent Component Analysis (ICA)

- Identifies non-Gaussian independent random variables that are linearly mixed:
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 - Caveats: repeated or close eigenvalues.

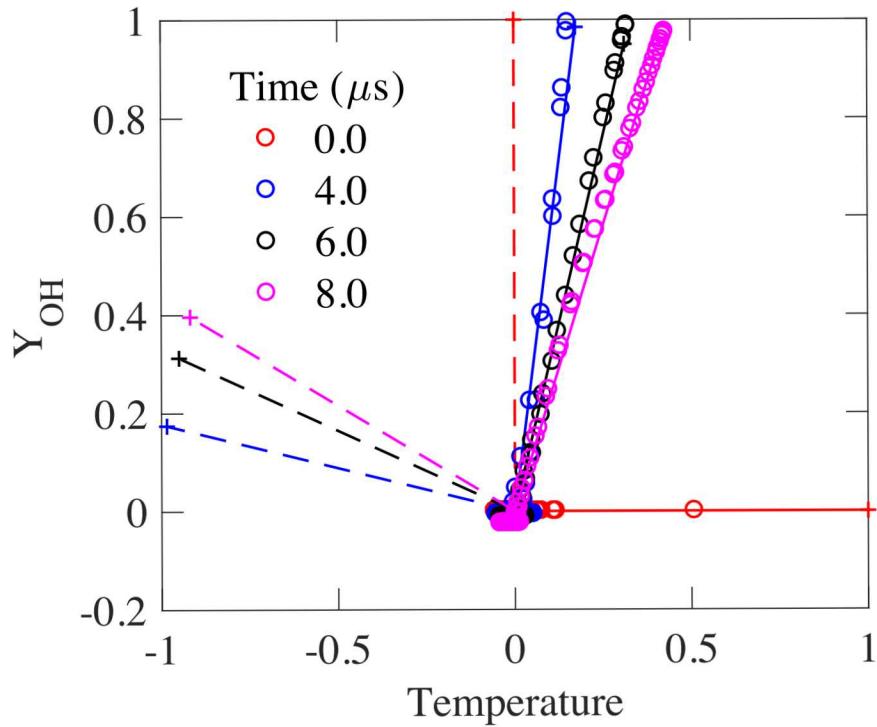
Simple 1D configuration with initial temperature inhomogeneity.



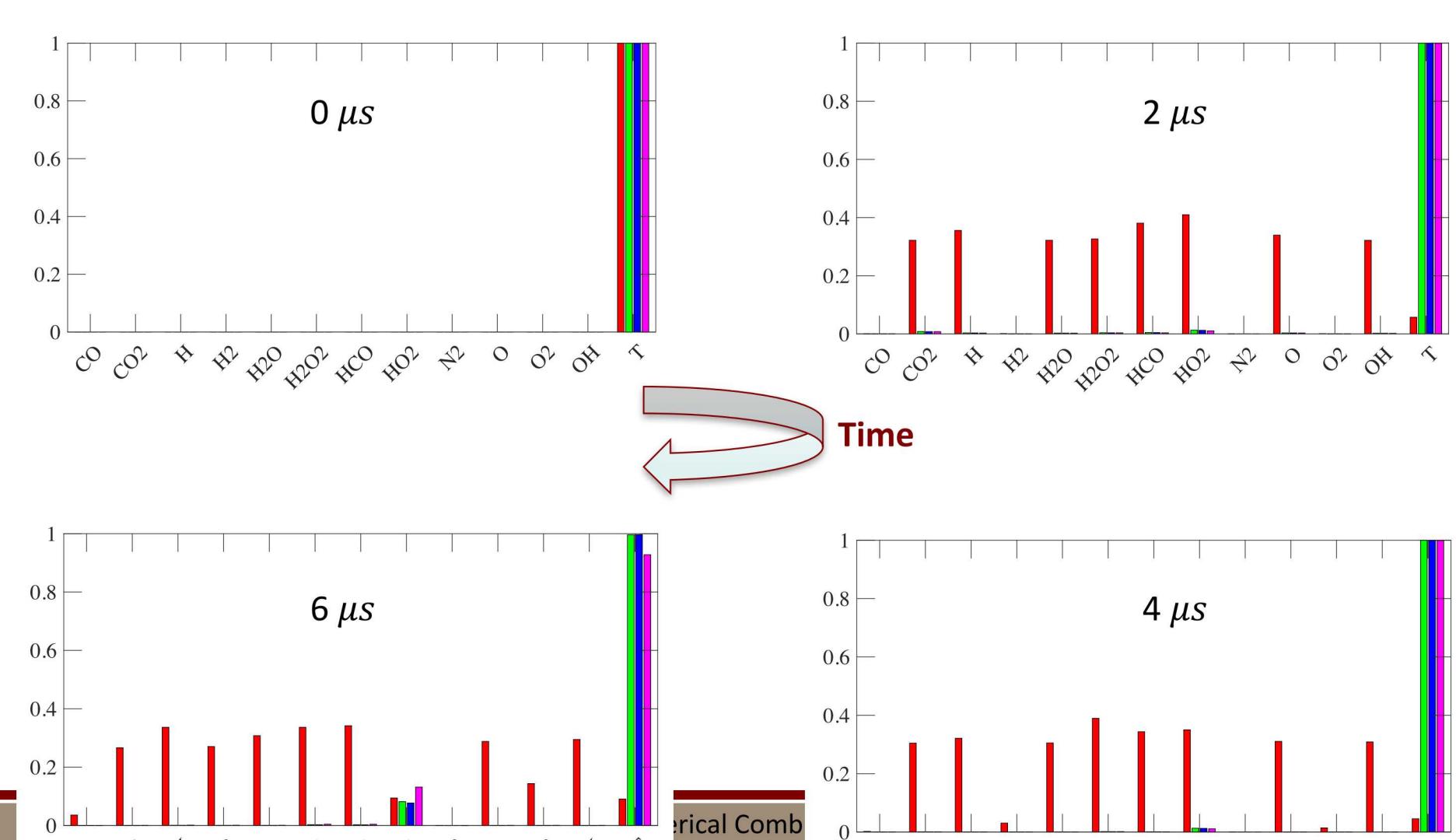


Numerical Combustion

Evolution of Kurtosis vectors.



$$\text{Feature Anomaly Metric (FAM}_i\text{)} = \frac{\sum_i \lambda_i (\vec{e}_i \cdot \vec{v}_i)}{\sum_i \lambda_i}$$



Defined per processor, aggregated over
all features

$$M1_{p_j} = \sqrt{\frac{1}{n_v} \sum_{i=1}^{n_v} \frac{[\text{FIM}_{i,p_j}(t) - \overline{\text{FIM}_i(t)}]^2}{\overline{\text{FIM}_i(t)}^2}}$$

