

# Robust Arrival Time Uncertainty Estimation Using Gaussian Blurring



*PRESENTED BY*

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# Our Problem and Motivation

Analysts have to make decisions on waveforms very quickly

- They have hundreds of signals to go through in a given day
- More data is coming in than is being completed

We want to give more information to the analyst to help the decision making process of when an onset detection occurs

# Our Approach

## Given

- We have a window of a waveform  
We know a signal arrives at some point in this window

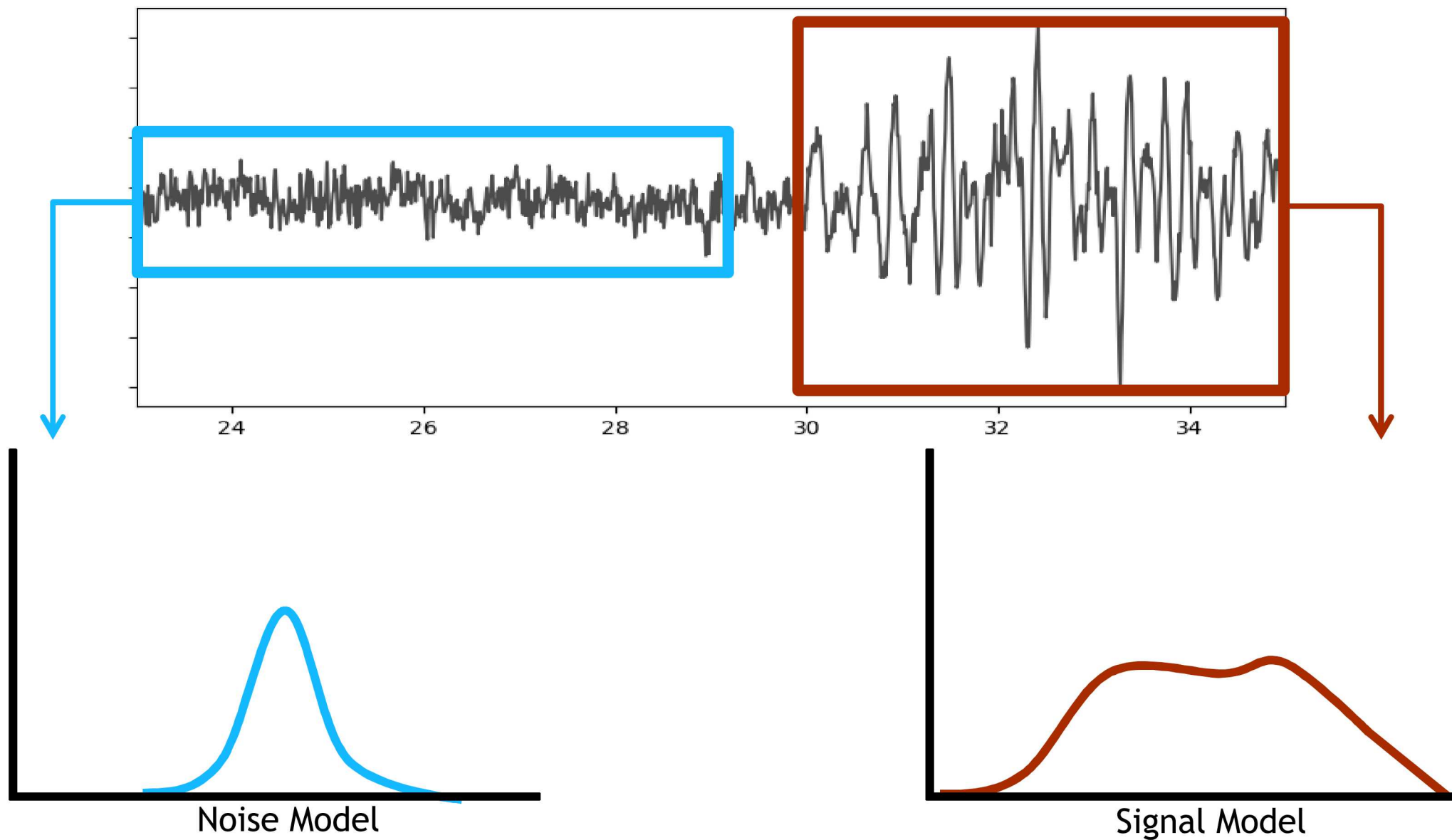
## Output

- A distribution over time of the probability that an onset time occurs

## What we do

- Calculate a model for the Noise and Signal
- Generate noise
- Create Bootstrap samples by adding noise to the signal
- Pick the onset time for each Bootstrap Sample
- Aggregate the Bootstrap picks into a distribution over time of where the True Onset time occurs

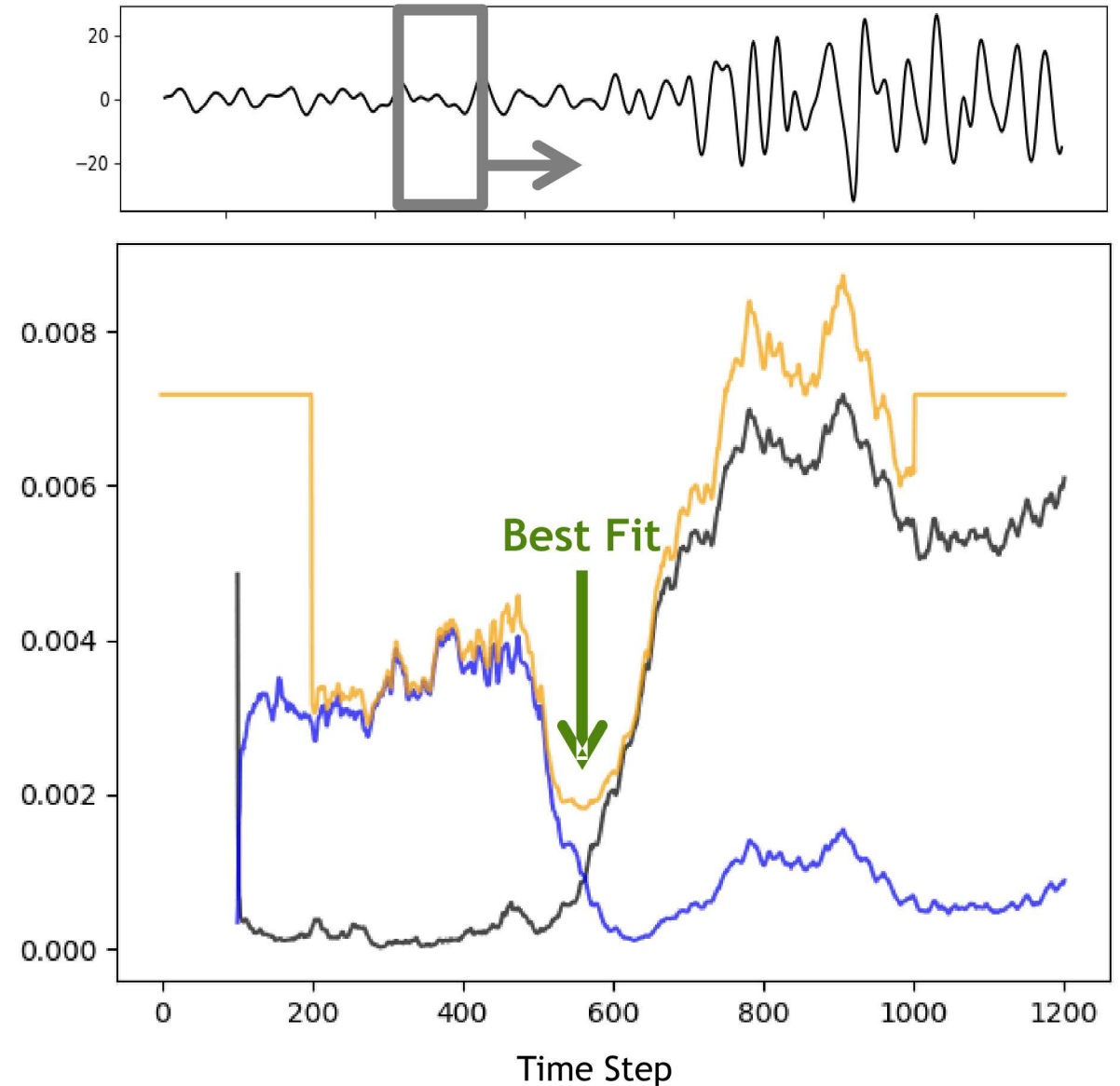
# Creating our Noise and Signal Models



## Finding the Onset

We calculate the fitting metrics of our Noise and Signal models across the entire search space

- **BLACK** line is the fitting of the Noise model
- **BLUE** line is the fitting of the Signal model
- **YELLOW** line is the combination of both the noise and signal fitting scores
- The lowest value is the best fit point, shown in **GREEN**



# Generating Bootstrap Samples

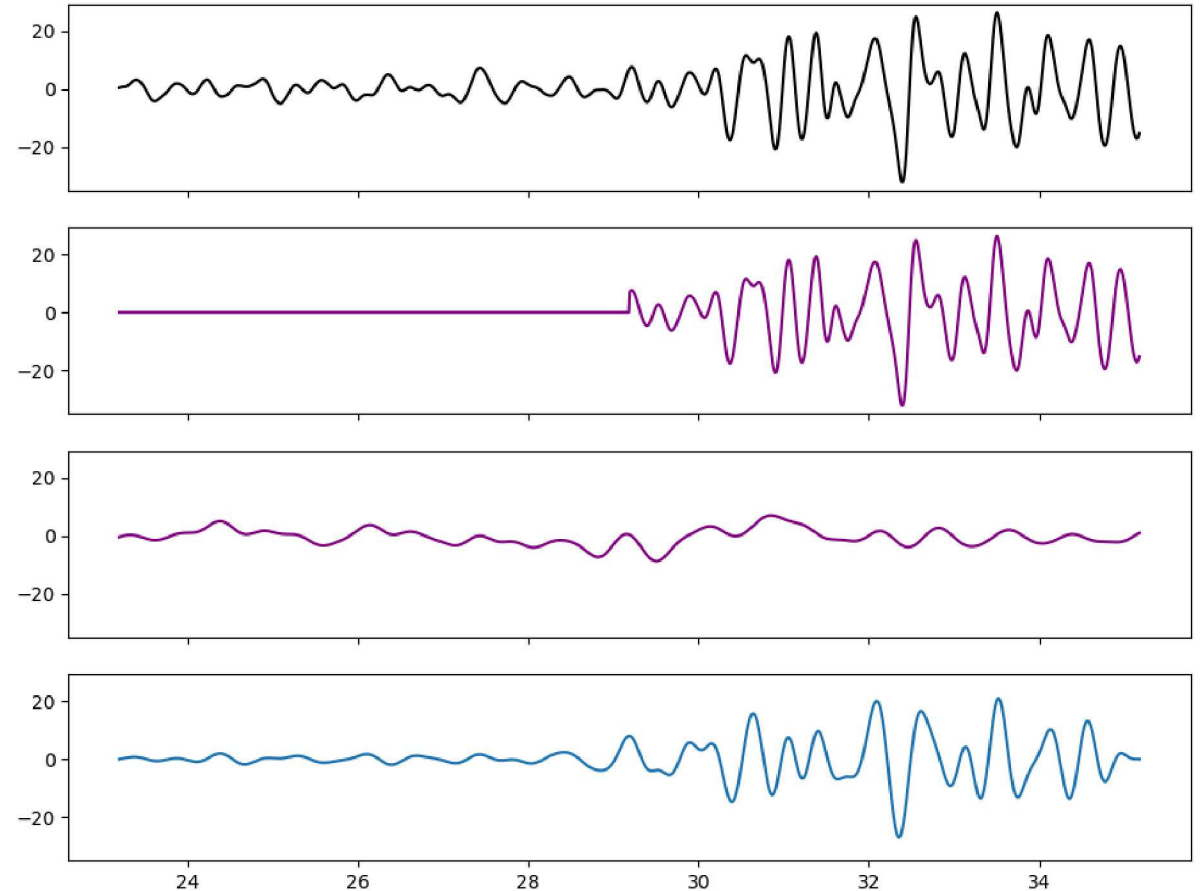
Row 1: the **BLACK** line is the original filtered waveform

Row 2: the **PURPLE** line is the signal from the original waveform

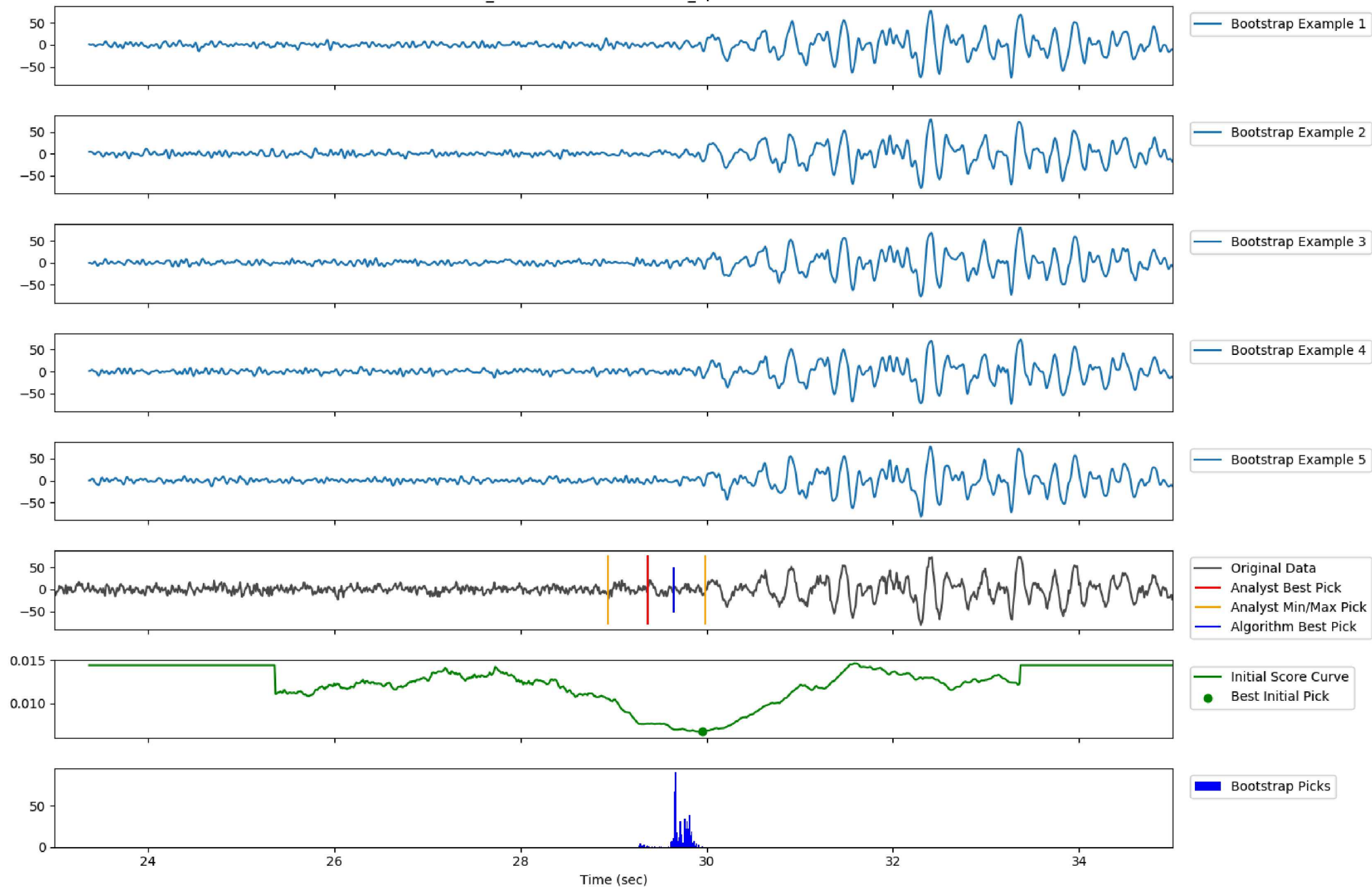
Row 3: the **PURPLE** line is the generated noise

Row 4: the **BLUE** line is the new bootstrap sample

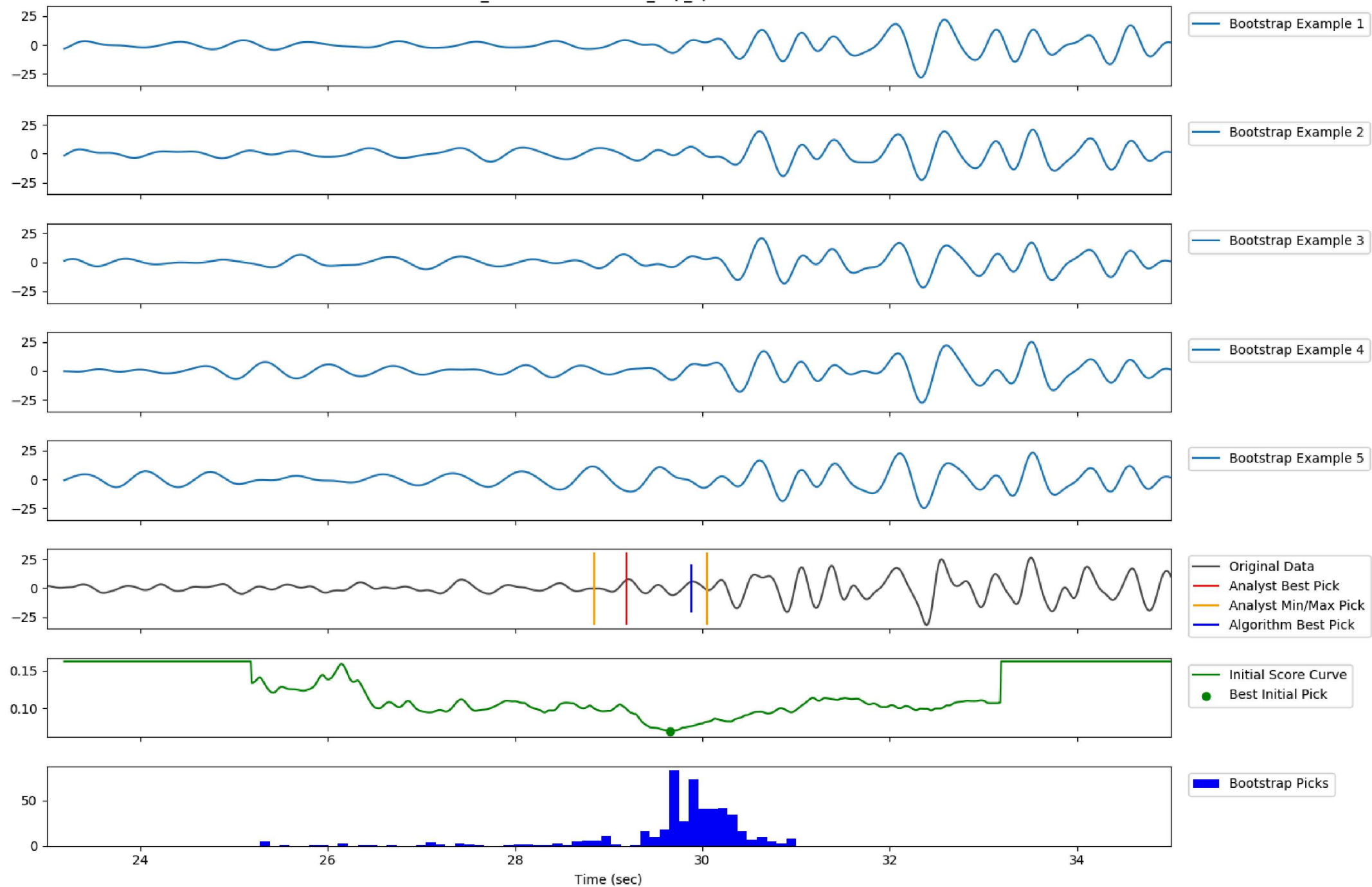
- The summation of Rows 2 and 3







CHS\_CirclevilleMain.sac.1\_3bp\_1pass.sac





Improve our noise generation method

- Currently only taking amplitude into account
- We want to incorporate frequency

Add more features to our Noise and Signal models

- We want to track the changes in frequency as well as the amplitude changes

Remove the assumption that an onset time occurs in our search window

- We currently know that a signal arrives somewhere in our search window
- This allows us to assume the left side of the window is mostly noise and the right side is mostly signal