

Toward a Multi-Agent System Architecture for Insight & Cybersecurity in Cyber-Physical Systems



PRESENTED BY

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Background

Benefits vs State-of-the-Art

Opportunities

Multi-Agent Systems

Building a MAS

Conclusions



Operational Technology (OT) networks existed before the dawn of the internet

- Security by isolation

Convergence of OT and IT networks...

- ICS, IIoT, IoT
- Impending threat/execution of cyber attack
 - MITM/signal emulation
 - Sensor influence/hijack
 - Malware/ransomware
 - D/DoS
 - Device destruction



Methods to secure cannot be reasonably implemented due to:

- legacy equipment
- vendor complicity
- cost (resource, monetarily)

New approaches are needed to address past tech, current tech, and still be flexible to accommodate and grow with future tech.

Ref cloud/IT network-security based on agents

- Multi-Agent Systems (MAS)

Current approaches;

- username/passwords
- embedded certificates
- block-chain

Oft rely on greenfield, proprietary, retrofitting

Disproportionate cost vs. device resources/usage

MAS to provide:

- intelligent, uninfluenced visibility
- extensibility (to other networks)
- interfaces to support additional responses/defenses



Ubiquity/proliferation of OT-networks

- Address legacy, inject to new technology
 - Augment legacy with “on-the-wire” devices
 - SDN, containers, virtualization for new deployments
- Cross-pollination of IT/cloud and OT
 - Industrial {Internet | IoT}
 - Io{T | V}
 - Smart{homes | grids}

Coming soon: Software-defined OT

- Cyber to the fog and endpoint
- Intelligent Edge (IT-compatible)



Multi-Agent System (MAS)

- agent (Latin, agree, “to do”): operate autonomously, perceive their environment, persist over a time period, adapt to change, create or pursue goal(s).
- Akin to an organization
 - Departments/operations to support org goals
 - Independent/interfaces/information exchange
- Reactive: react to commands/environments
- Proactive: actively achieve goals thru interaction
- Social: communicate with other (agents)



Multi-Agent System (MAS)

- Sensors: perceive their environment
- Actuators: act upon the environment
- Percepts: perceptual inputs
 - Percept sequence: history of all the agent has perceived
- AI → ability to act autonomously
 - Bridge the gap between sensing and actuating
- Agent view: Micro-perspective
- MAS view: Macro-perspective



Multi-Agent System (MAS)

- Coordination (cooperation): needed to ensure community MAS work together cohesively; coordination due to:
 - agent goals may conflict internally/externally
 - agent goals may be interdependent
 - agents may have different knowledges/capabilities
 - agents goals may be accomplished faster (work together)
- Coordination Approaches:
 - Organizational structuring
 - Contracting
 - Multiagent planning
 - Negotiation



IT/Cloud operating in untrusted network-space, leveraging agents.

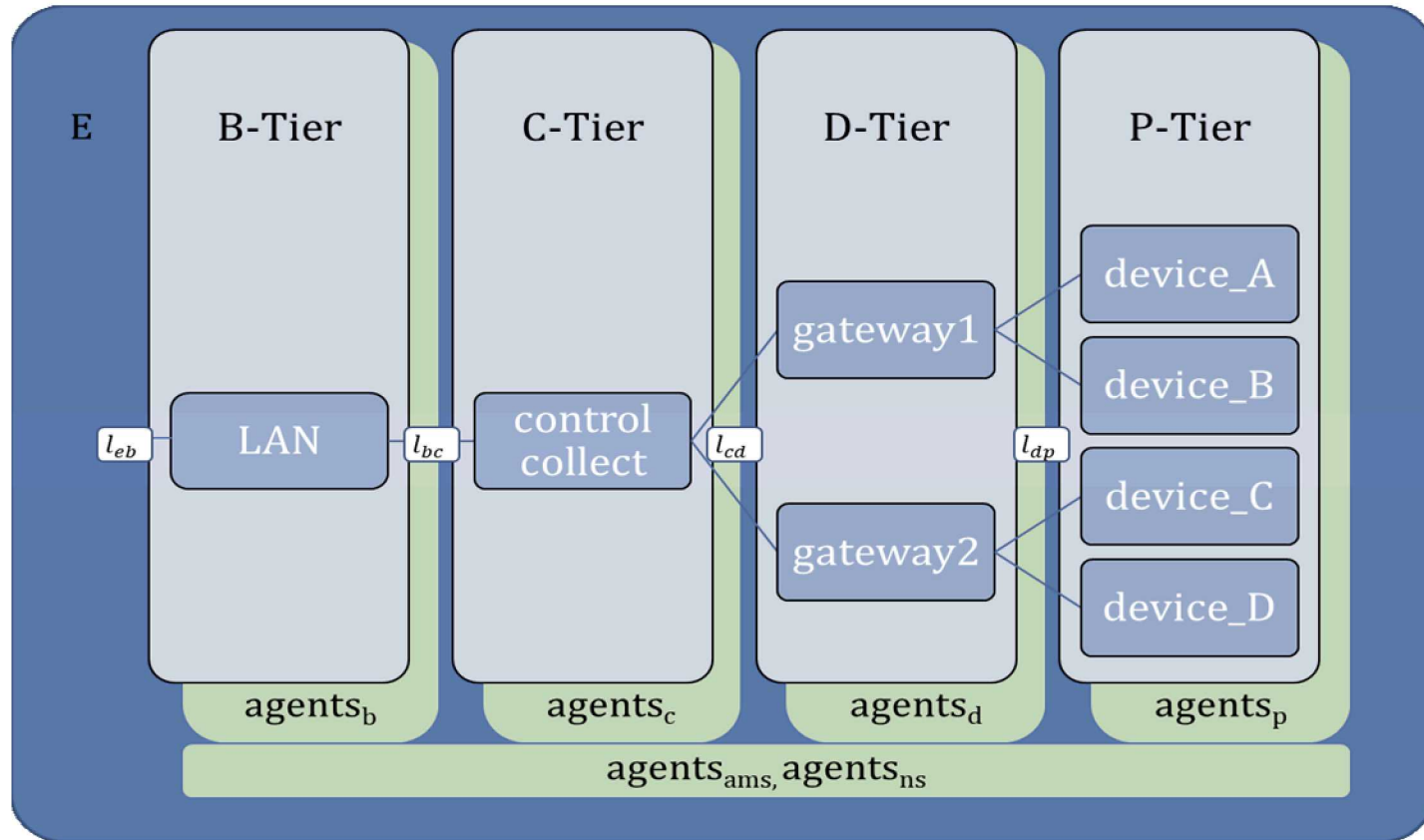
Autonomous Agents (AA)

- SW or broadcast-medium based, proving:
 - Passive listening/active probing (where applicable)
 - Data/metadata collection
 - Behavioral analysis and majority voting schemes
 - AA self-policing
 - Active defense techniques
 - Security policy enforcement



General Categorization for Network Architectures (OT and IT)

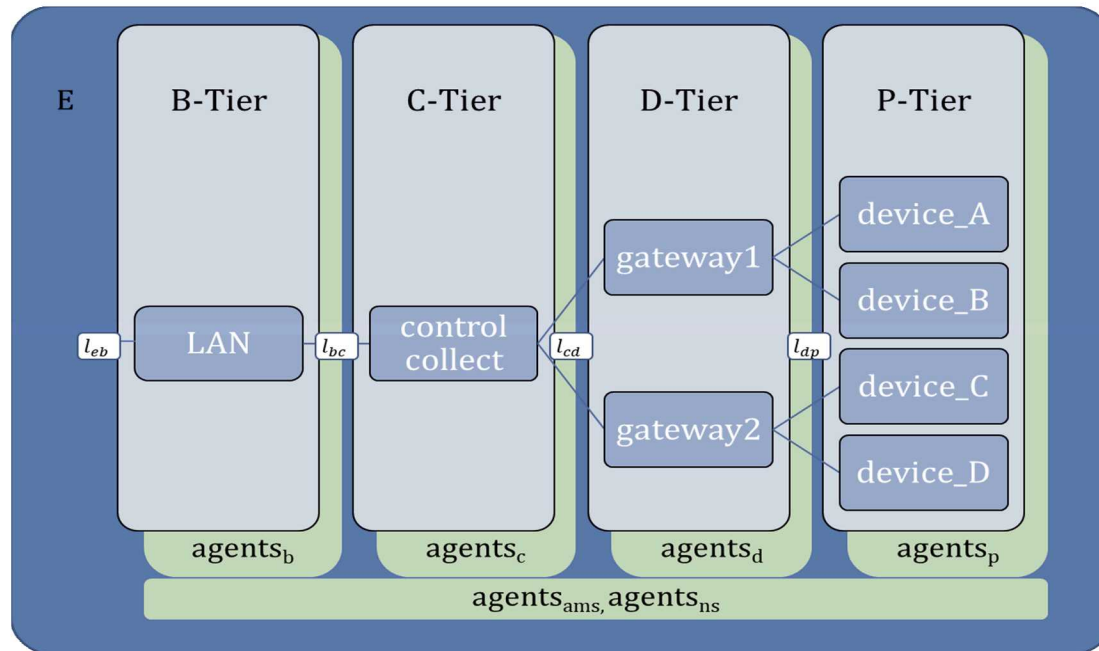
Network Model	B-Tier	C-Tier	D-Tier	P-Tier
ICS	Business, Logistics (Level 4)	Control software, HMI, Operations (Level 2/3)	Remote devices, collection (Level 1/2)	Physical domain, devices (Level 0/1)
IoT	Business, User Access (Actions)	Storage, Processing, Reporting, Cloud (Insights)	Gateways, Hub	Things, sensors
IIoT	Business Integration	Information, operations, applications	Control	Proximity and physical systems
Enterprise/Cloud	Data center, edge, cloud	Core routing, boundary	Concentrator, distribution	Access, mobile, endpoints



$$S_n = \langle E|B|C|D|P \rangle$$

$$L = \langle l_{eb}|l_{bc}|l_{cd}|l_{dp} \rangle$$

$$S_a = \langle a_{\{b,c,d,p\}}|ns_j|ams_k \rangle$$



$$a_i = \langle \kappa | \sigma | \alpha | \rho | \gamma | kb \rangle$$

$\kappa = \text{developer or AMS knowledge}$

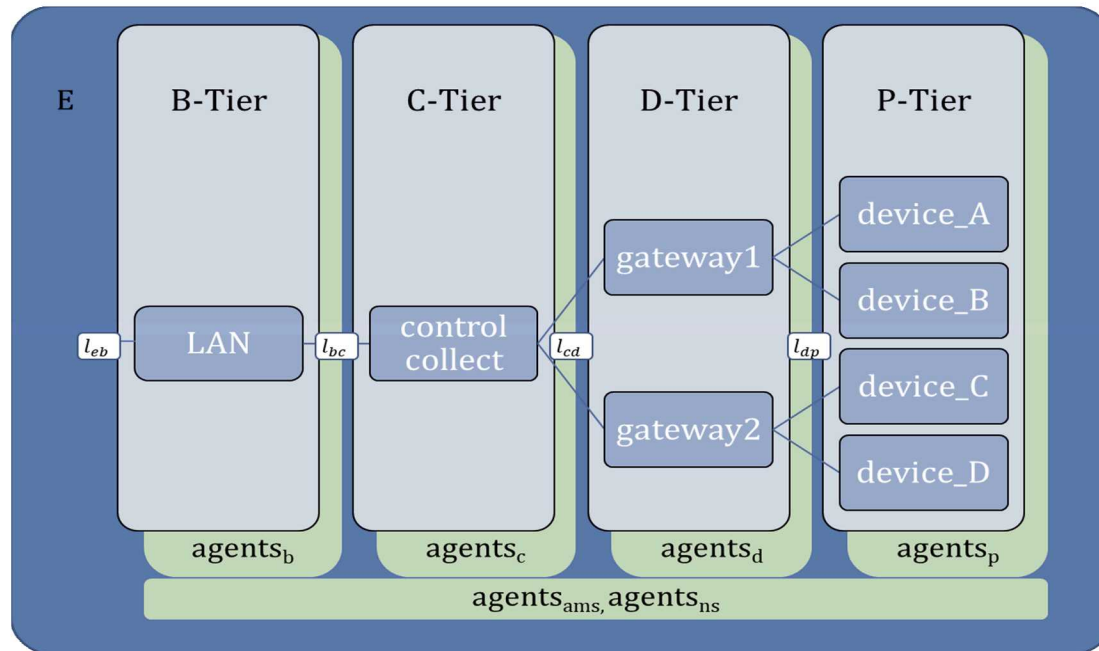
$\sigma = \text{sensors}$

$\alpha = \text{actuators}$

$\rho = \text{percept}$

$\gamma = \text{goals}$

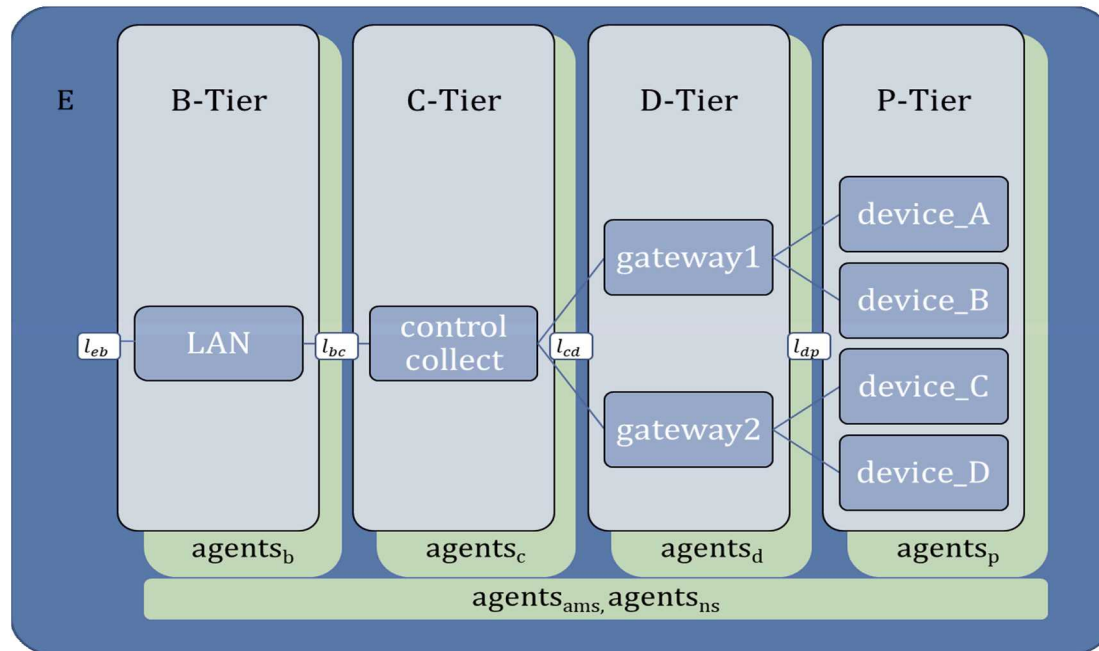
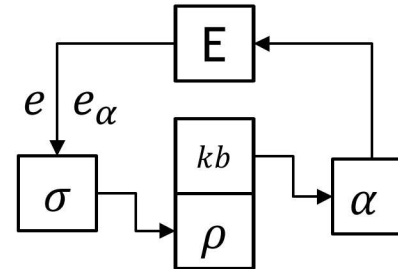
$kb = \text{knowledge base}$



$kb = \text{knowledge base}$

$$kb = \bigcup_i^n \rho_i \cup \sigma_\alpha \cup \kappa$$

$e = \text{event or observation}$



Security in OT is both an old and new paradigm; technology to do so must be flexible to address legacy systems and still grow with new tech and defense mechanism.

We introduced using a Multi-agent System for OT security, further research delve further into coordination and specification of agents.

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