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Approximating Two-Stage Chance-Constrained Programs with Classical Probability Bounds

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Chance Constraint Setting

Consider a linear Joint Chance Constraint:

$$P(x_t \leq y_t^\omega + w_t^\omega, \forall t \in T) \geq 1 - \varepsilon$$

Background:

- Two-stage stochastic program with recourse
- Possibly integer restrictions
- i.i.d. samples of uncertainty w_t^ω
- First stage decision, x_t , second-stage decision, y_t^ω

Challenges

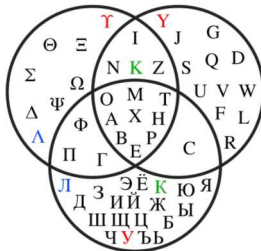
- CC models are computationally intractable
- A known NP-hard problem
- Existing algorithms not scalable to practical sized problems
- Feasible region is non-convex

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Approximations with classical probability bounds

Satisfying a JCC is an intersection of events. Failing a JCC is a union of events.



We can rewrite the JCC as follows:

$$\mathbb{P}\left(\bigcup_{t \in T} F_t\right) \leq \varepsilon.$$

where F_t denotes the set of scenarios that we “fail”; i.e.,
 $F_t = \{\omega : x_t > y_t^\omega + w_t^\omega\}..$

Approximations with Classical Probability Bounds

$$\mathbb{P}\left(\bigcup_{t \in T} F_t\right) \leq \varepsilon.$$

Consider an optimization model with a JCC with a maximization objective.

- Lower Bound (LB): Approximate the LHS using a quantity **larger** than $\mathbb{P}(\bigcup_{t \in T} F_t)$. Feasible region is **restricted**.
- Upper Bound (UB): Approximate the LHS using a quantity **smaller** than $\mathbb{P}(\bigcup_{t \in T} F_t)$. Feasible region is **enlarged**.

Approximations with Classical Probability Bounds

$$\mathbb{P}(\bigcup_{t \in T} F_t) = S_1 - S_2 + \cdots (-1)^{|T|-1} S_T$$

where, $S_k = \mathbb{P}(\sum_{1 \leq i_1 < \cdots < i_k \leq |T|} F_{i_1} \cap \cdots \cap F_{i_k})$.

Bonferroni bounds:

$$\mathbb{P}(\bigcup_{t \in T} F_t) \leq S_1 \leftarrow \text{LB} \quad (1a)$$

$$\mathbb{P}(\bigcup_{t \in T} F_t) \geq S_1 - S_2 \leftarrow \text{UB}. \quad (1b)$$

Approximations with Classical Probability Bounds

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Tighter bounds from Sathe et al. [1980]:

$$\mathbb{P}(\bigcup_{t \in T} F_t) \leq S_1 - \frac{2}{T} S_2 \leftarrow \text{LB} \quad (2a)$$

$$\mathbb{P}(\bigcup_{t \in T} F_t) \geq \frac{S_1 + 2S_2}{T^2} \leftarrow \text{UB}. \quad (2b)$$

Approximations with Classical Probability Bounds

$$\mathbb{P}(\bigcup_{t \in T} F_t) = S_1 - S_2 + \cdots (-1)^{|T|-1} S_T$$

where, $S_k = \mathbb{P}(\sum_{1 \leq i_1 < \cdots < i_k \leq |T|} F_{i_1} \cap \cdots \cap F_{i_k})$.

And more from Dawson and Sankoff [1967]:

$$\mathbb{P}(\bigcup_{t \in T} F_t) \geq \frac{S_1^2}{S_1 + 2S_2} \leftarrow \text{UB} \quad (3a)$$

can be linearized for $JCC \leq \varepsilon$:

$$2\varepsilon S_2 \geq \alpha_n S_1 + \beta_n, n = 0, 1, \dots, |N| - 1, \leftarrow \text{UB} \quad (3b)$$

Optimizing over JCCs

$u_t^\omega = 1$: failure at t in scenario ω

$v_{tt'}^\omega = 1$: failure at t and t' in scenario ω

$$x_t - y_t^\omega - w_t^\omega \leq M_t^\omega u_t^\omega, \forall t \in T, \omega \in \Omega$$

$$\text{McCormick envelope} \begin{cases} v_{t,t'}^\omega \leq u_t^\omega, (t, t') \in T, t < t', \omega \in \Omega \\ v_{t,t'}^\omega \leq u_{t'}^\omega, \forall (t, t') \in T, t < t', \omega \in \Omega \\ v_{t,t'}^\omega \geq u_t^\omega + u_{t'}^\omega - 1, \forall (t, t') \in T, t < t', \omega \in \Omega \end{cases}$$

$$u_t^\omega = \{0, 1\}, \forall t \in T, v_{t,t'}^\omega = \{0, 1\}, \forall (t, t') \in T, \omega \in \Omega$$

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A case study

$$\max_{x,y} \quad \sum_{t \in T} (R_t x_t - \mathbb{E}[B_t y_t^\omega]) \quad (4a)$$

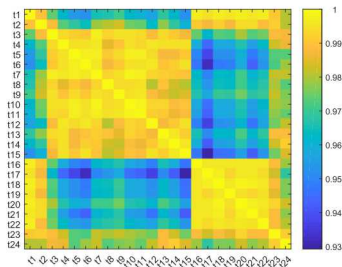
$$\text{s.t.} \quad \mathbb{P}(y_t^\omega + w_t^\omega \geq x_t, \forall t \in T) \geq 1 - \varepsilon \quad (4b)$$

$$0 \leq y_t^\omega \leq \Delta, \forall t \in T, \omega \in \Omega \quad (4c)$$

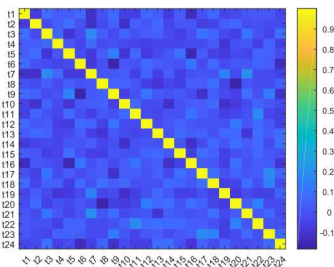
$$x_t \geq 0, \forall t \in T. \quad (4d)$$

Computational results

We compare two sampling procedures: (a) ARMA(2,2) process, and (b) normal random variables. Both samples have the same hourly means and variances.



(a)



(b)

Figure: Correlation structure of w_t

Computational results: ARMA (large correlation)

ε	Bounding constraint	Optimal objective value			Time (seconds)	Gap from optimal
		Lower bound	Upper bound	MIP gap		
0.01	(1a)	8,351.3	8,351.3	0%	2	3.3%
	(1b)	21,282.8	21,282.8	0%	12	59.4%
	(2a)	8,351.3	8,365.8	0.1%	2100	3.3%
	(2b)	8,339.6	10,682.1	21.9%	2100	19.2%
	(3a)	8,339.7	8,726.7	4.5%	2100	1.1%
	(3b)	8,688.9	8,702.1	0.2%	2100	0.8%
0.03	(1a)	8,374.6	8,374.6	0%	2	8.5%
	(1b)	22,353.2	22,353.2	0%	14	59.0%
	(2a)	8,339.6	8,755.4	4.7%	2100	8.9%
	(2b)	8,339.6	13,321.2	37.4%	2100	31.3%
	(3a)	9,137.3	9,311.4	1.9%	2100	1.7 %
	(3b)	9,074.4	9,252.2	1.9%	2100	1.1%

Table: Tightest lower and upper bounds for $\varepsilon = 0.01$ are 8,351.3 and 8,702.1; true optimal value is 8,634.1

Tightest lower and upper bounds for $\varepsilon = 0.03$ are 8,374.6 and 9,252.2; true optimal value is 9,154.9

Computational results: Gaussian (weak correlation)

ε	Bounding constraint	Optimal objective value			Time (seconds)	Gap from optimal
		Lower bound	Upper bound	MIP gap		
0.01	(1a)	9,100.8	9,100.8	0%	1	2.7%
	(1b)	21,606.6	21,606.6	0%	18	56.7%
	(2a)	9,102.08	9,113.3	0.1%	2100	2.7%
	(2b)	9092.3	11,365.5	20%	2100	17.7%
	(3a)	9,434.3	9,486.3	0.5%	2100	1.4%
	(3b)	9,421.5	9,452.3	0.3%	2100	1.1%
0.03	(1a)	9,124.3	9,124.3	0%	2	7.7%
	(1b)	22,762.1	22,762.1	0%	21	56.6%
	(2a)	9,124.8	9,198.4	0.8%	2100	7.7%
	(2b)	9,092.3	13,907.6	34.9%	2100	28.9%
	(3a)	9,092.3	10,062.6	9.6%	2100	1.8%
	(3b)	9,092.3	10,004.8	9.1%	2100	1.2%

Table: Tightest lower and upper bounds for $\varepsilon = 0.01$ are 9,100.8 and 9,449.9; true optimal value is 9,353.2

Tightest lower and upper bounds for $\varepsilon = 0.03$ are 9,124.3 and 10,004.8; true optimal value is 9,884.0

Computational results

- Bonferroni lower bound and Dawson & Sankoff upper bound consistently perform better than others
- Weaker correlation in uncertainty leads to easier-to-solve models
- MIQCP formulation of Dawson & Sankoff bound is challenging

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Possible reasons for long computation time of naive solve

- No extended variable formulation above
- Big M
- Less reliable regime, more combinations to choose from

Computational results: ARMA (large correlation) with 500 scenarios

ε	Bounding constraint	Optimal objective value			Time (seconds)	Gap from optimal
		Lower bound	Upper bound	MIP gap		
0.01	(1a)	8,453.4	8,453.4	0%	1	2.9%
	(1b)	21,582.9	21,582.9	0%	129	59.7%
	(2a)	8,701.0	8,701.0	0%	1717	0%
	(2b)	10,462.7	11,318.4	7.5%	2100	23.1%
	(3a)	8,348.9	40,116.9	79.2%	2100	78.3%
	(3b)	8,348.9	8,772.9	4.8%	2100	0.8%
0.03	(1a)	8,542.5	8,542.5	0%	3	7.3%
	(1b)	22,570.6	22,570.6	0%	175	59.2%
	(2a)	8,348.9	9,396.1	11.1%	2100	9.4%
	(2b)	8,348.9	15,127.8	44.8%	2100	39.1%
	(3a)	8,348.9	41,151.4	79.8%	2100	77.6 %
	(3b)	8,348.9	9,352.9	10.7%	2100	1.5%

Table: Tightest lower and upper bounds for $\varepsilon = 0.01$ are 8,701.0 and 8,772.9; true optimal value is 8,701.0

Tightest lower and upper bounds for $\varepsilon = 0.03$ are 8,542.5 and 9,352.9; true optimal value is 9,211.3

Computational results: Gaussian (weak correlation) with 500 scenarios

ε	Bounding constraint	Optimal objective value			Time (seconds)	Gap from optimal
		Lower bound	Upper bound	MIP gap		
0.01	(1a)	9,005.1	9,005.1	0%	1	3.7%
	(1b)	21,503.7	21,503.7	0%	75	56.5%
	(2a)	8866.9	8,889.3	1.3%	2100	5.1%
	(2b)	8,866.9	11,071.9	19.9%	2100	15.6%
	(3a)	8,866.9	40,126.1	77.9%	2100	76.7%
	(3b)	9,343.6	9,390.3	0.5%	2100	0.5%
0.03	(1a)	9,148.2	9,148.2	0%	3	7.4%
	(1b)	22,565.4	22,565.4	0%	46	56.2%
	(2a)	8,866.9	9,315.3	4.8%	2100	10.2%
	(2b)	8,866.9	13,711.9	35.3%	2100	27.9%
	(3a)	8,866.9	41,187.8	78.5%	2100	76.0 %
	(3b)	8,866.9	9,990.9	11.2%	2100	1.2%

Table: Tightest lower and upper bounds for $\varepsilon = 0.01$ are 9,005.1 and 9,390.3; true optimal value is 9,346.4

Tightest lower and upper bounds for $\varepsilon = 0.03$ are 9,148.2 and 9,990.9; true optimal value is 9,874.1

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