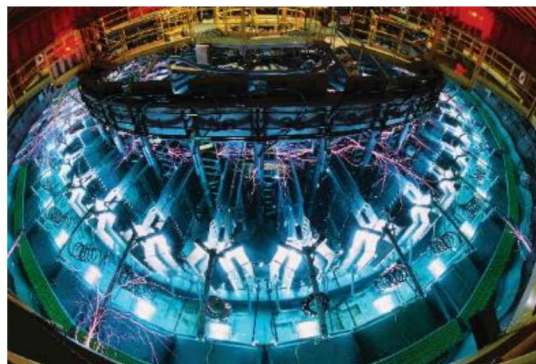
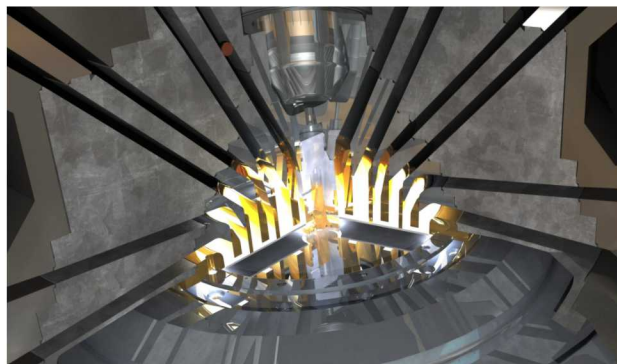


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Estimates of Saturn Radiation Output Scaling versus Machine Design Parameters

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What I will talk about

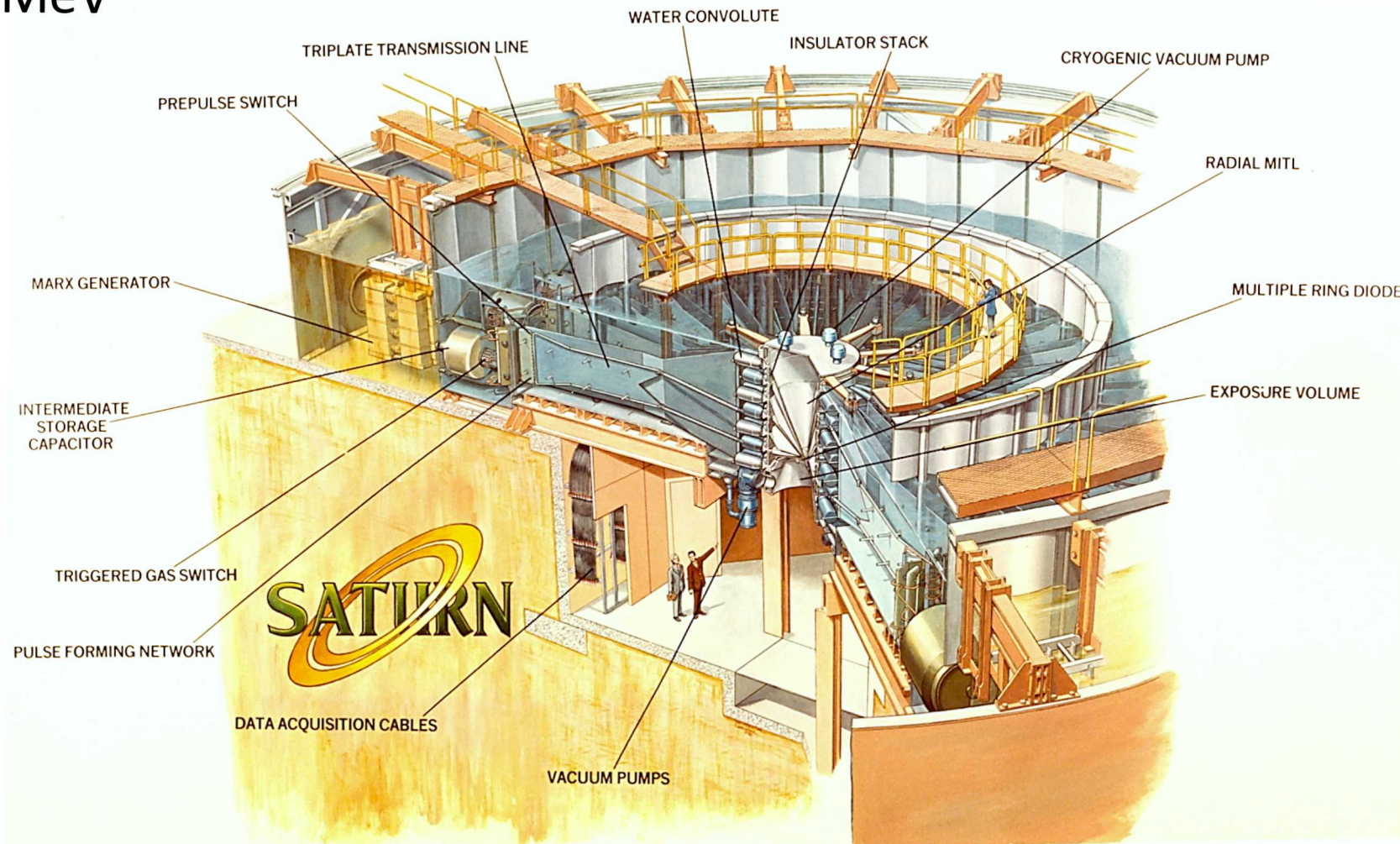
- Quick review of what Saturn is and what are its capabilities
- What we are planning to do with the machine
- Some estimates on how radiation output can scale with various design parameters

The Saturn Accelerator

- Saturn is a short-pulse (~ 40 ns FWHM) x-ray generator capable of delivering up to 10 MA into a bremsstrahlung diode to yield up to 5×10^{12} rad/s (Si) per shot at an energy of 1 to 2 MeV.
- It was built in the 1980's as a rebuild of the PBFA I accelerator
- Has been a reliable scientific tool since its first shot in 1987 as a driver for both radiation sources and z-pinch plasmas

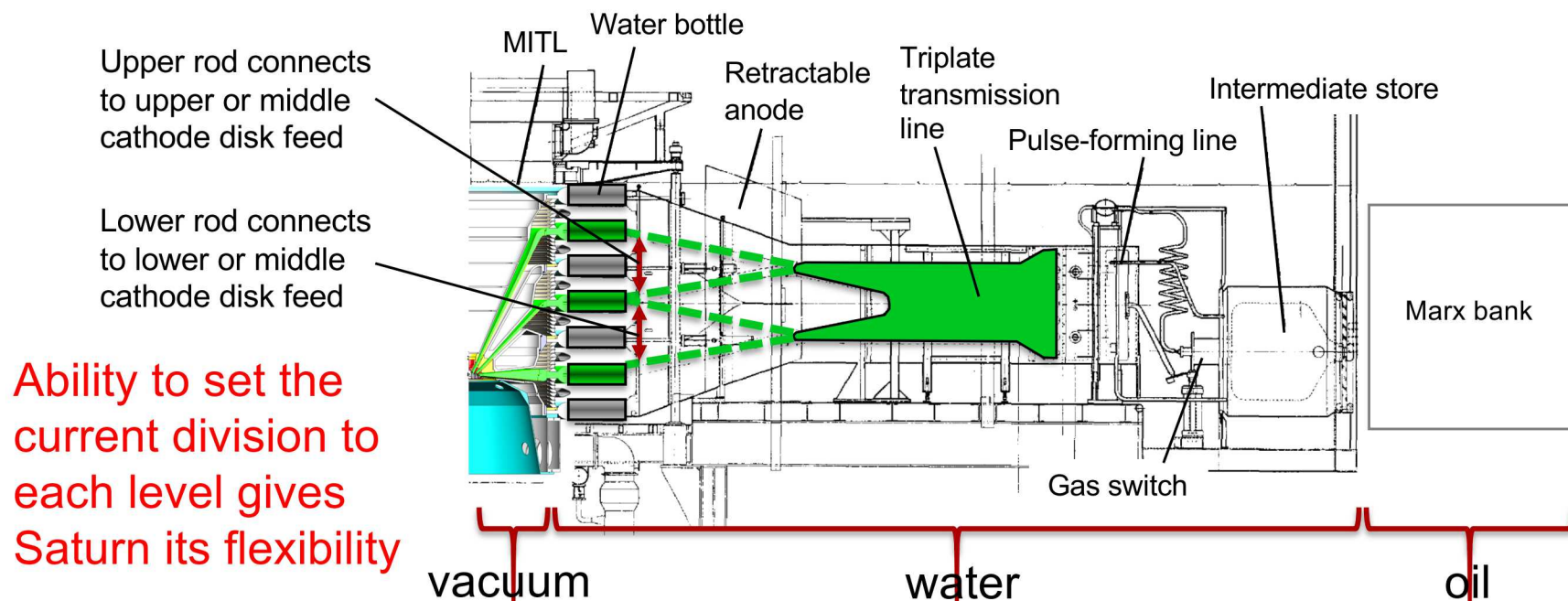
Saturn has thirty-six Marx banks and water PFLs that drive 3 “independent” Bremsstrahlung radiation loads

Nominally 10 MA, 1.6 MV, 40 ns power pulse, 5×10^{12} rad/s (Si) at 1 MeV

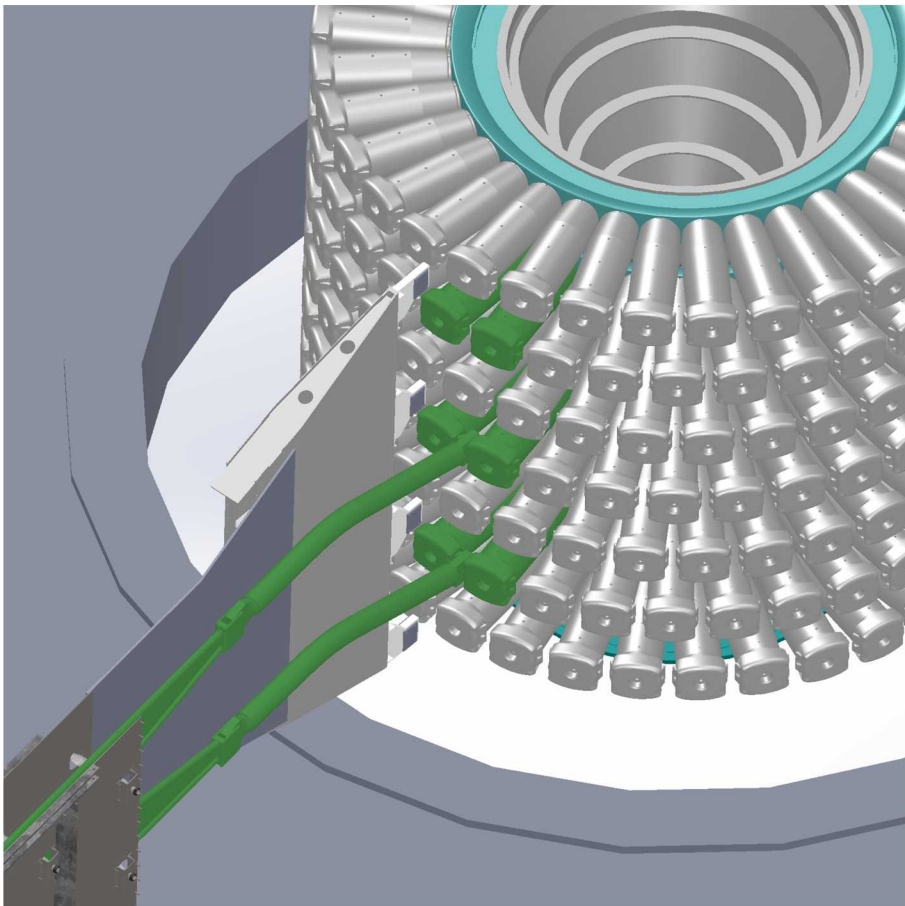


Saturn pulsed power

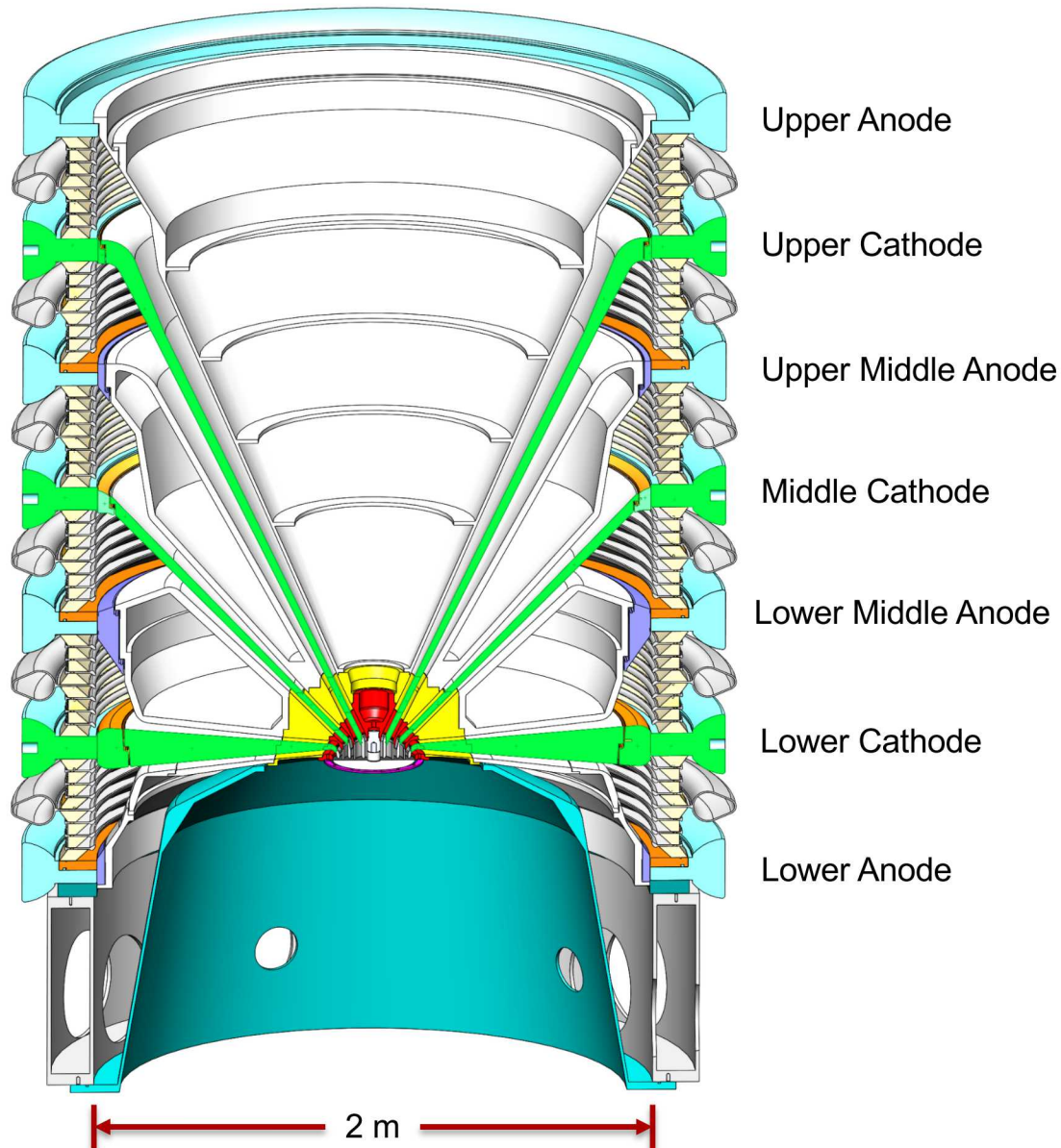
- Each one of 36 vertical triplate lines
 - 50 kJ forward-going energy
 - ~2 MV at beginning of TL
 - 40 ns FWHM power pulse
 - Nominally 2Ω
 - Anode is grounded, cathode is pulsed negative
- Water convolute connects lines to vacuum stack
 - Each line is connected to two 8Ω rods
 - Each rod connects to $\frac{1}{2} \Omega$ radial cathode disk feed in water
 - Up to 36 rods (half machine) can be connected to each level



Rods connect the water transmission lines to the bottles at the stack



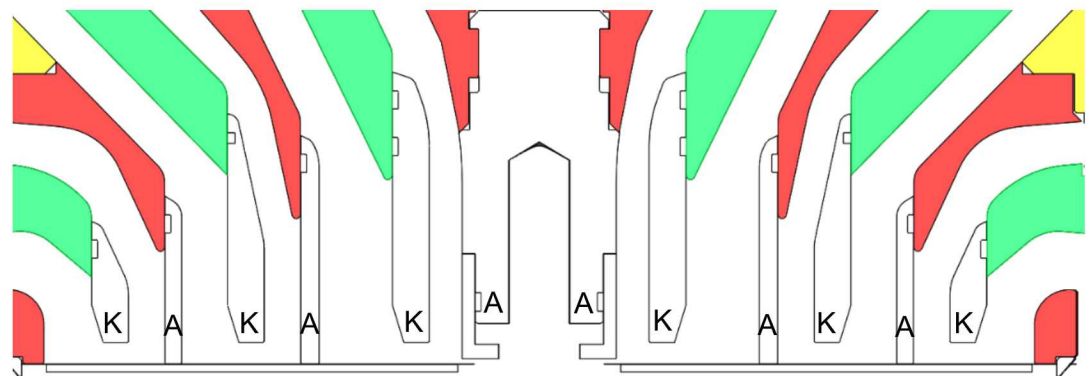
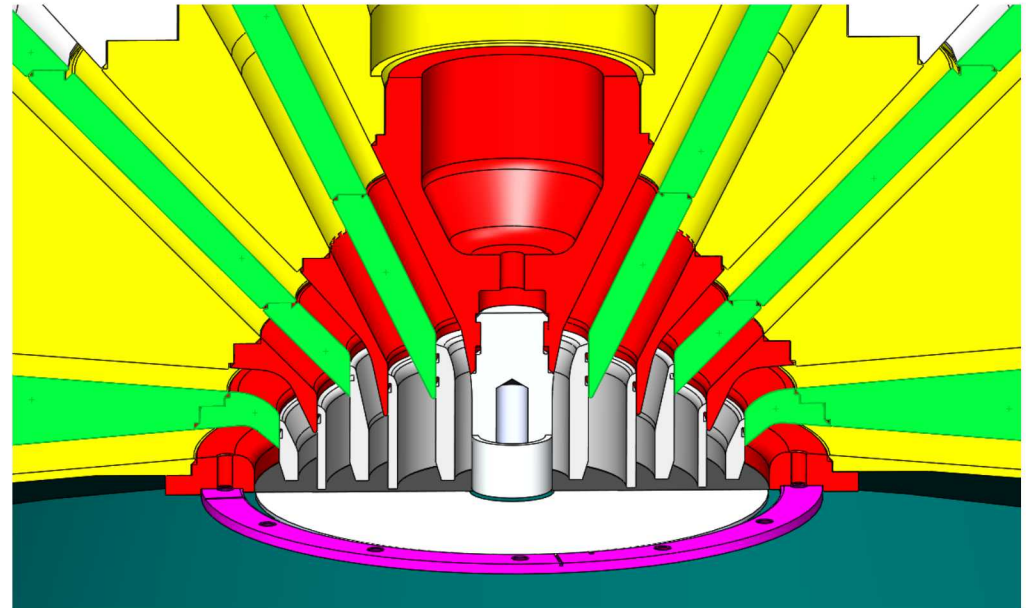
Vacuum Stack, MITLs, and Load Region



- 3 nested conical triaxial lines
- Bottom 2 lines are $2\ \Omega$ driven by 36 rods
- Middle two lines are $3\ \Omega$ driven by 24 rods
- Top two lines are $6\ \Omega$ driven by 12 rods
- Each conical electrode is made in three sections
- Replacing relatively small hardware close to the axis allows a variety of loads to be fielded
- The upper and lower anodes are not vacuum barriers. The vacuum barrier is separate

Standard diode on Saturn – three nested annular diodes for low inductance

- Three nested annular triaxial diodes
- Ratio of radii 3:2:1
- Equal widths so ratio of areas 3:2:1
- Impedances balanced so have equal current density on each annular cathode
- At the diode, get 10 MA, 1.6 MV (power weighted mean voltage), 20 ns radiation pulse
- This has been the workhorse



Aluminum tip hardware shown in white replaced after each shot

We need to rebuild/upgrade Saturn

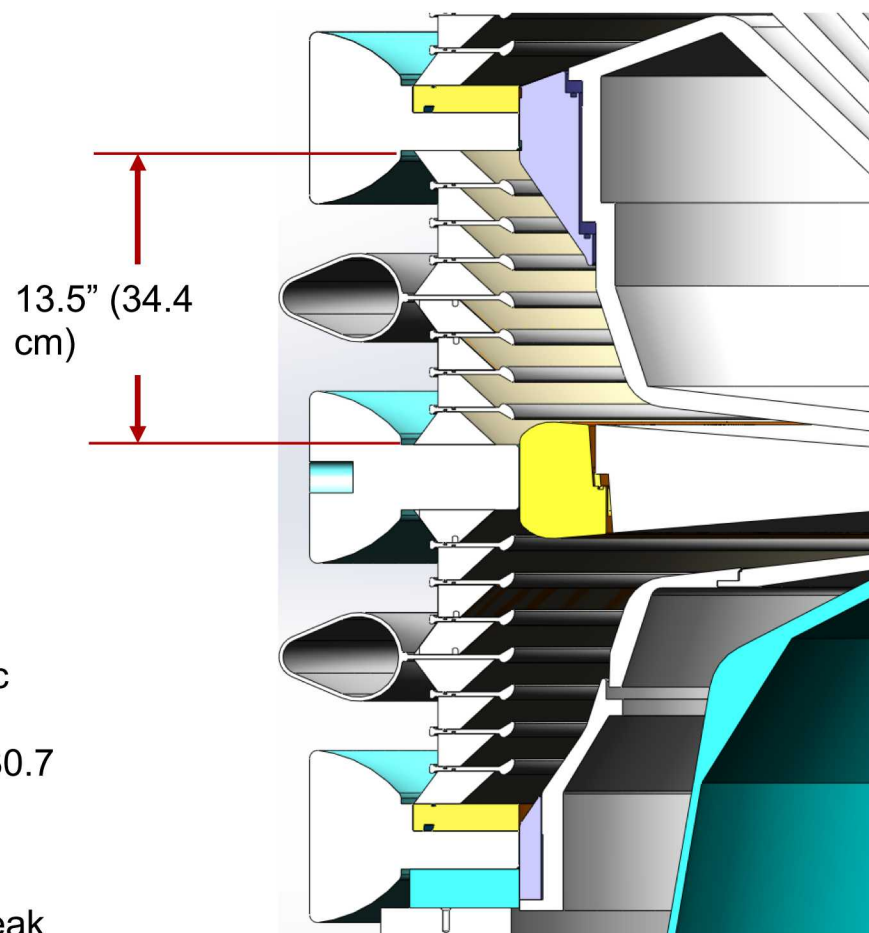
Over-riding requirement is to maintain existing capability

- The machine is 30 years old. Components are wearing out. We need to rebuild and replace many.
- We need to increase reproducibility and reliability
- Better/more diagnostics at stack and in vacuum
- We need to improve data collection and handling
 - Improved timing, delays
 - Cable compensation for fast signals
- Is feasible we want to double radiation output at the same or lower endpoint energy (1 MV)

Components that need attention:

- Rimfire gas switch (in oil or water?)
- Trigger for the rimfire gas switch
 - Upgrade existing electrical trigger
 - Or, implement laser triggering
- Water/Vacuum insulator stack
 - Too conservative, too much inductance
 - Mechanical wear and tolerance
- Connections to the vacuum lines (water bottles)
- Intermediate store water capacitor
- Mechanical alignment of water switches
- Water line impedance
- Lower impedance diode

A & B Stack Dimensions



Total height – 7 x grading ring height = plastic height

$$34.4 \text{ cm} - 7 \times 0.526 \text{ cm} = 30.7 \text{ cm (12")}$$

For a peak voltage of 2.0 MV, the average peak field is

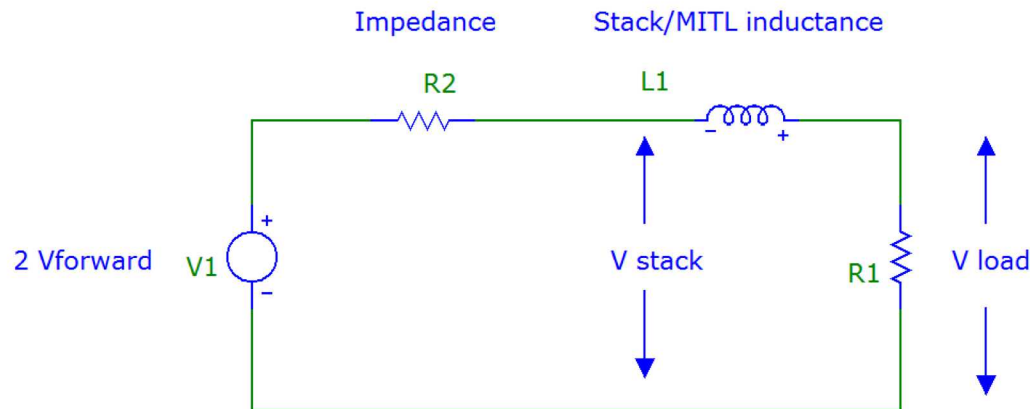
$$2000 \text{ kV} / 30.7 \text{ cm} = 65 \text{ kV/cm}$$

Potential upgrade options

- Same water-line architecture
 - Minor changes, refurbish existing components
 - Design changes to better access unused Marx bank energy
- Fast Marx design that could eliminate need for gas switch
- Magnetic switching to replace water switching
- Others?

Much can be learned from simple scaling calculations using a sine-squared drive pulse

- Represent the machine as an LRC circuit with a resistive load
 - Inductance primarily the stack and MITLs
 - Consider the load as a fixed small resistance (0.1 Ohm)
- Estimate radiation scaling as current x diode voltage^{2.7}
- Look at effects of voltage, current, inductance



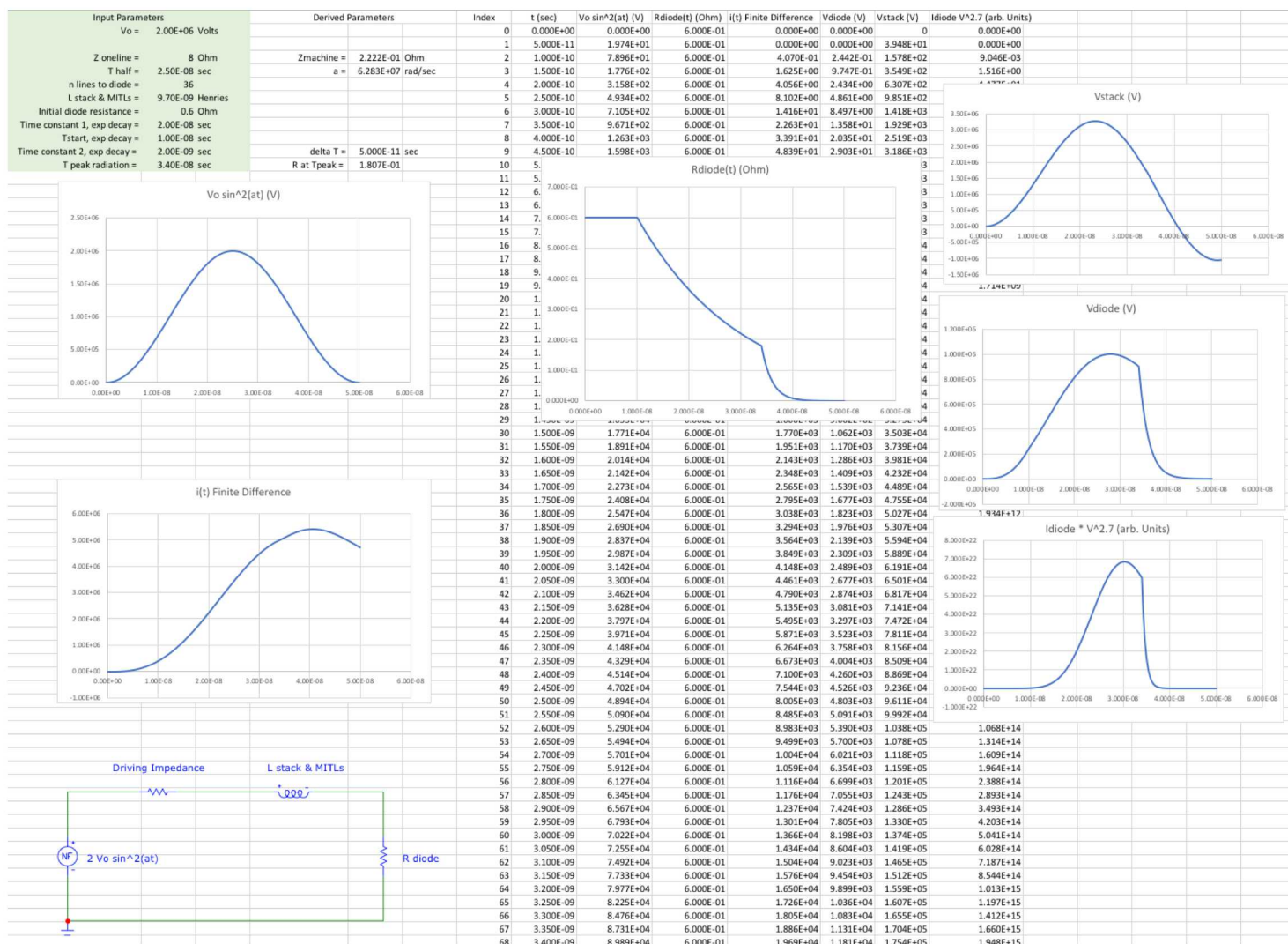
2.0 MV sine-squared drive, FWHM 25 ns

A & B MITLS only

36 8-Ohm rods

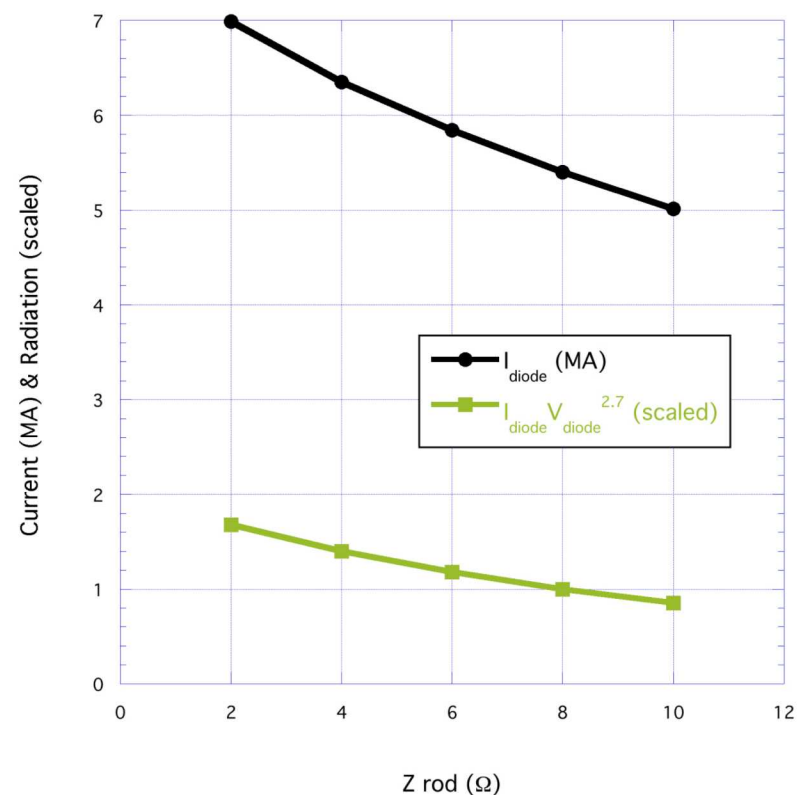
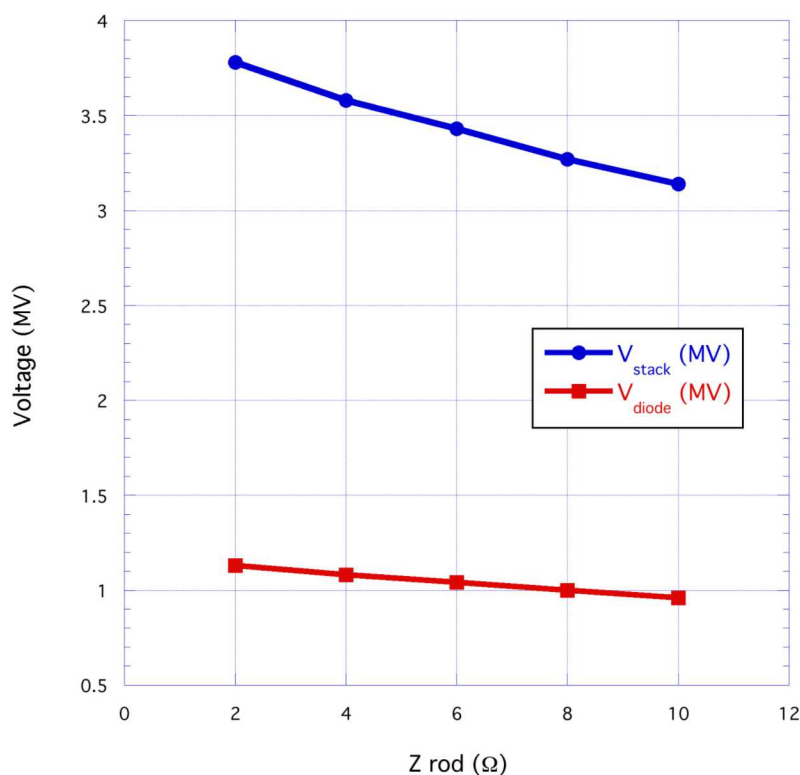
Double-exponential diode resistance

Current solved with a 50 ps timestep



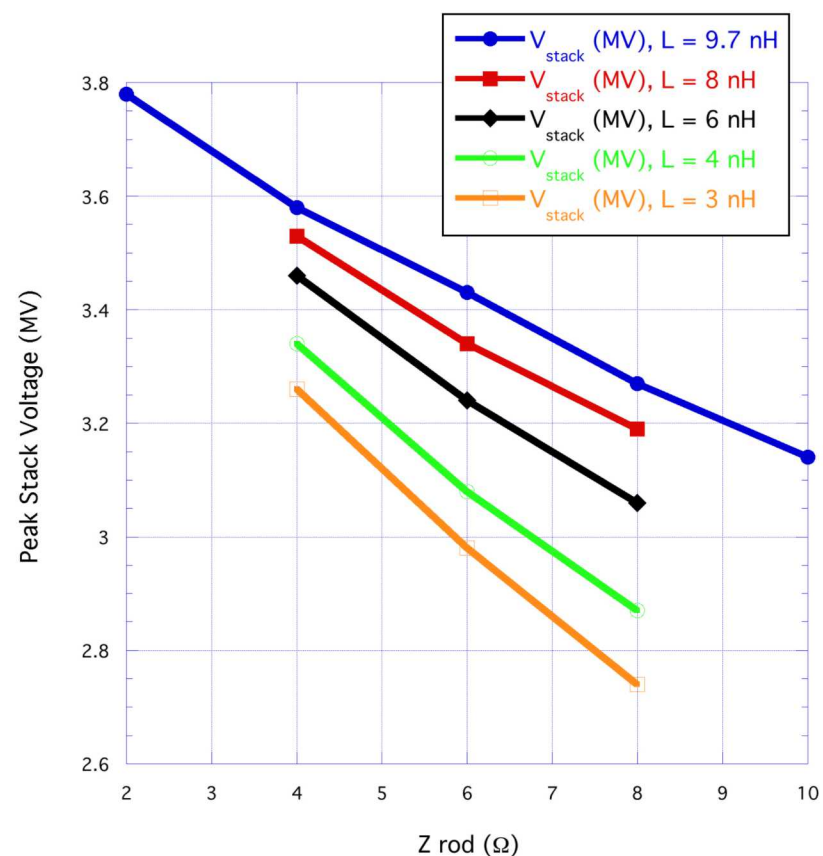
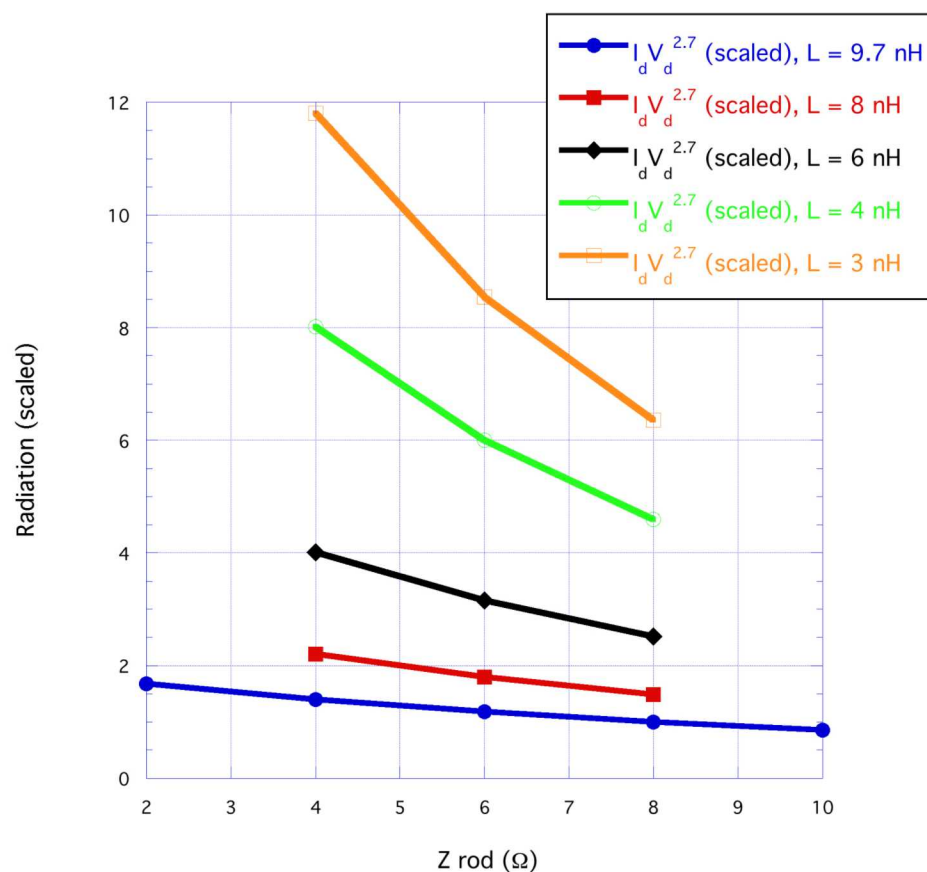
Scaling of the existing configuration with rod impedance

Peak voltage, current, and radiation vs. Z_{rod}

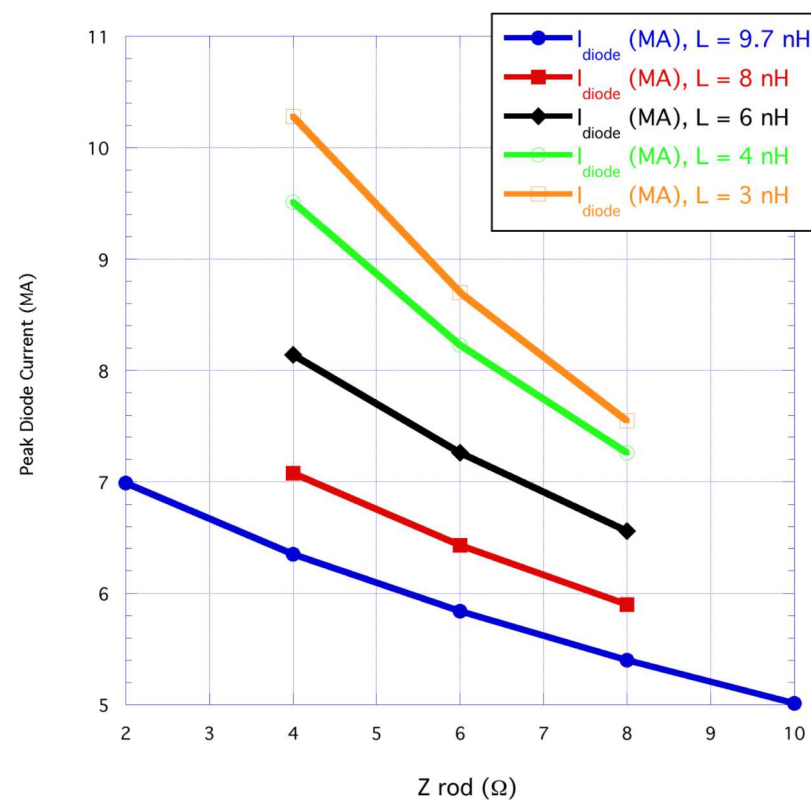
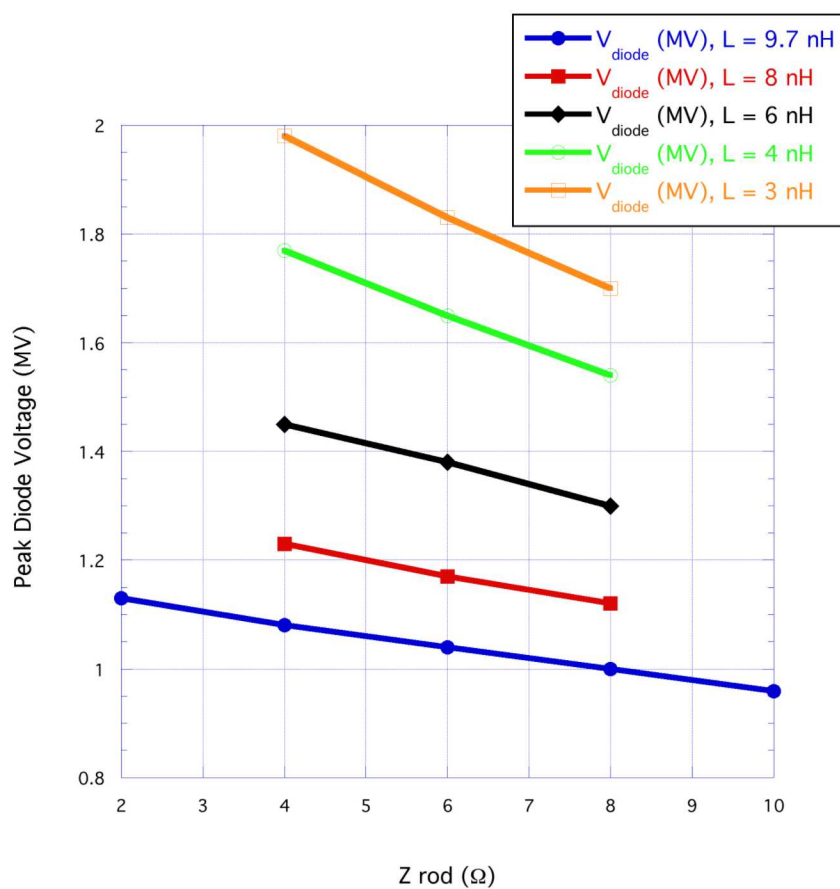


Radiation yield scaled to configuration with 8 Ohm rods with 9.7 nH A&B Stack & MITL inductance

Radiation & Stack Voltage vs L and Z



Diode Voltage & Current vs. L and Z



Observations from the scaling study

- Stack voltage relatively insensitive to L and Z , but
 - Decreases with decreasing L
 - Increases with decreasing Z
 - Linear with V_o
- Current very sensitive to L and Z
- Rad output proportional to current to the 3.7 power
since diode voltage = $I R_{\text{diode}}$

Conclusions

- We are still in the position of deciding how much to change for the rebuild of Saturn.
- Redesign and rebuild of the gas switches already started, but major design changes of other components yet to be decided.
- Options are available for both increasing reliability as well as performance.
- Most likely approach will be to rebuild Saturn using the existing water-line architecture with improvements to some components and functions, and seeking to use more energy from the Marx bank.