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Many-to-One Sweeper Redesign

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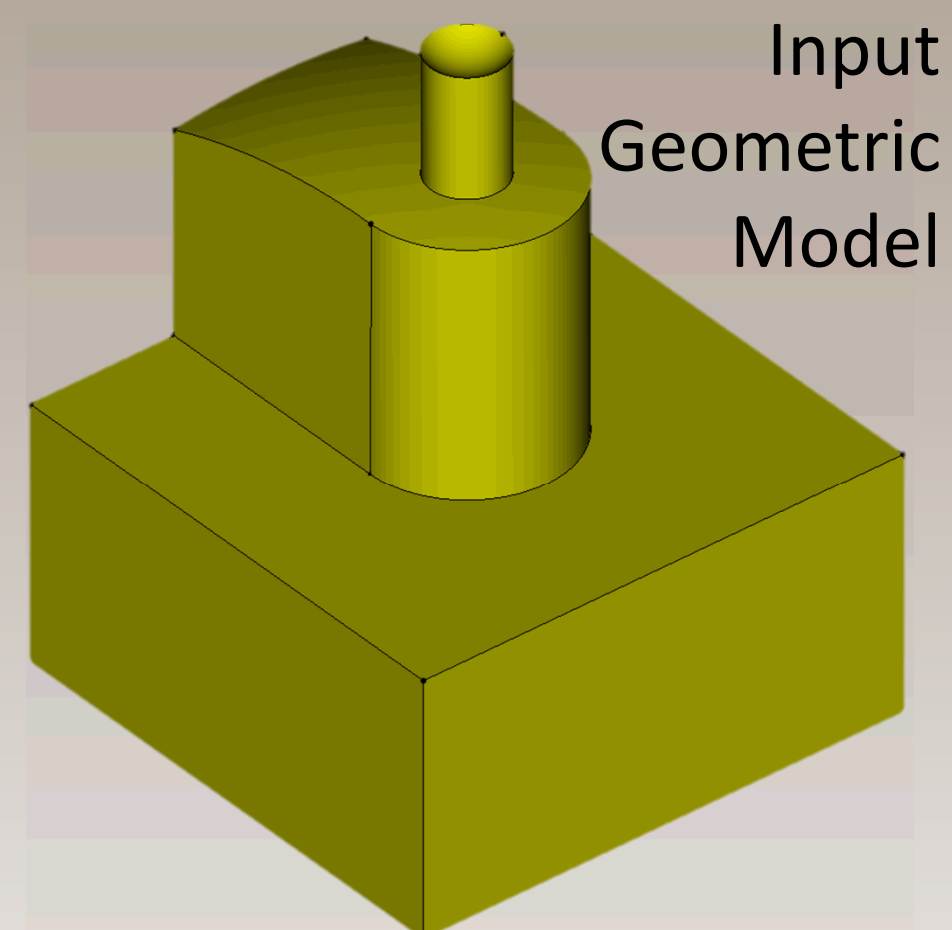
Sandia
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Problem Statement

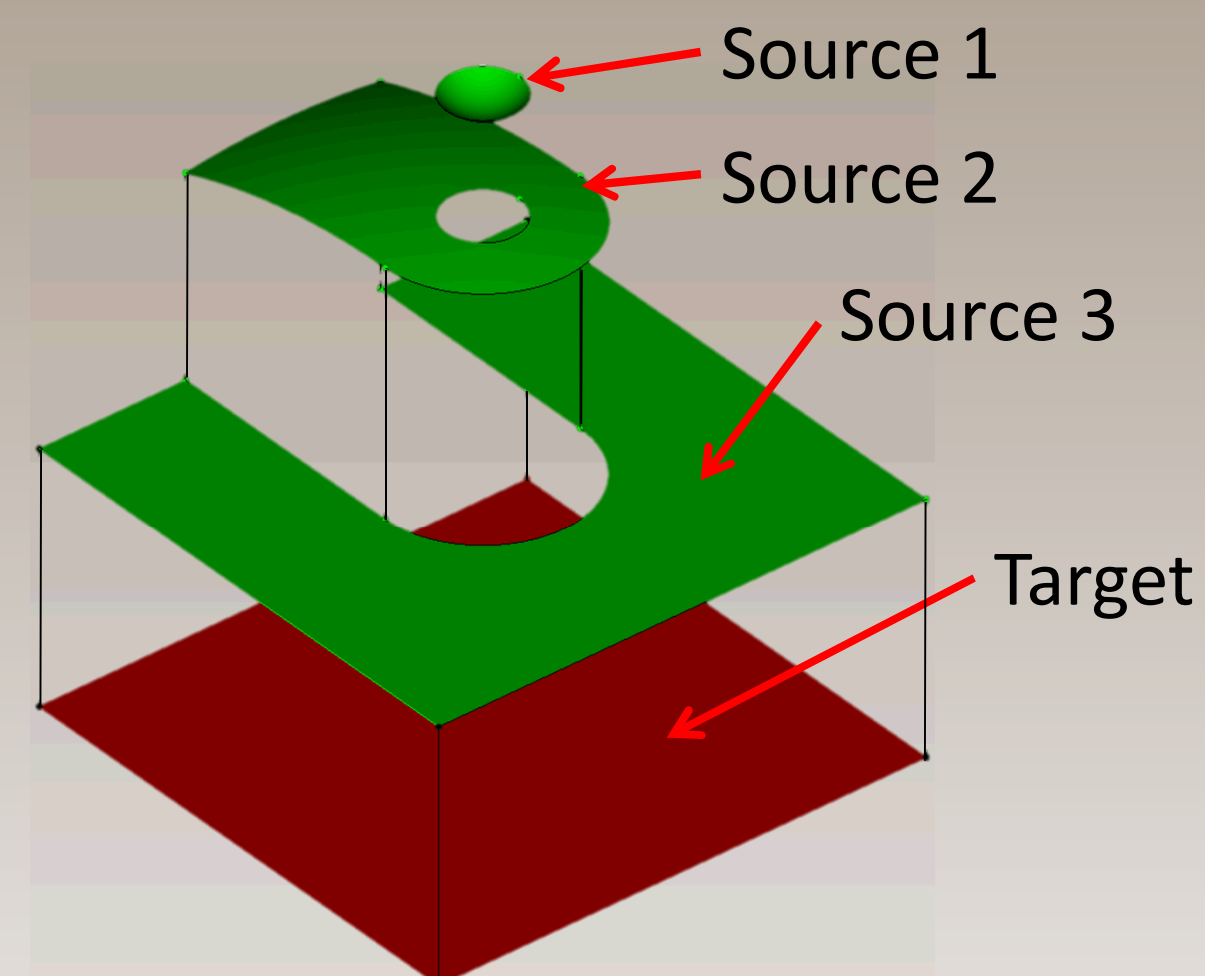
The many-to-one hex sweeper was rewritten for Cubit 15.0 to improve performance and element quality.

Sweeper Input

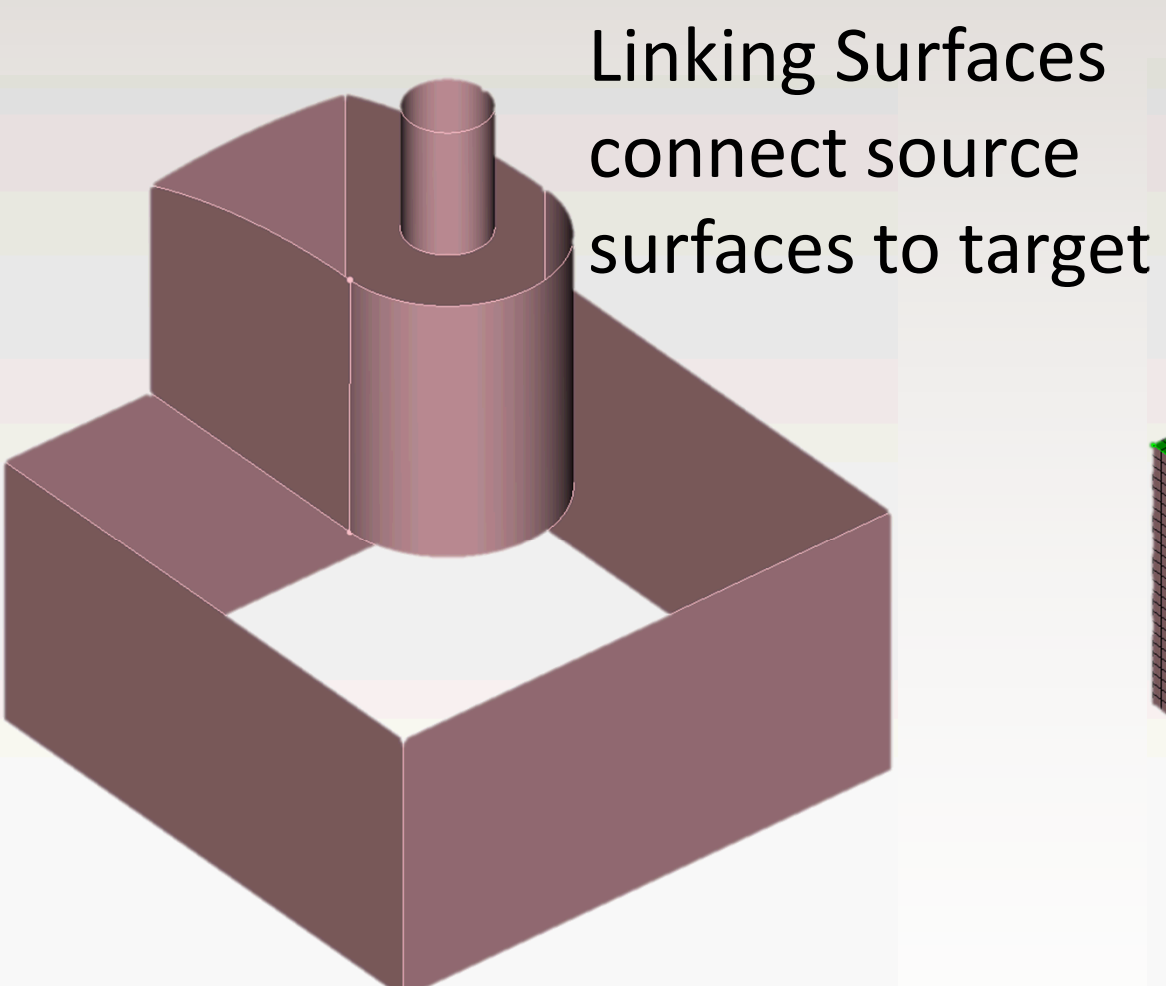
1. Any number of pre-meshed source surfaces
2. Linking surfaces pre-mesh with mapped or sub-mapped meshes
3. An unmeshed target surface



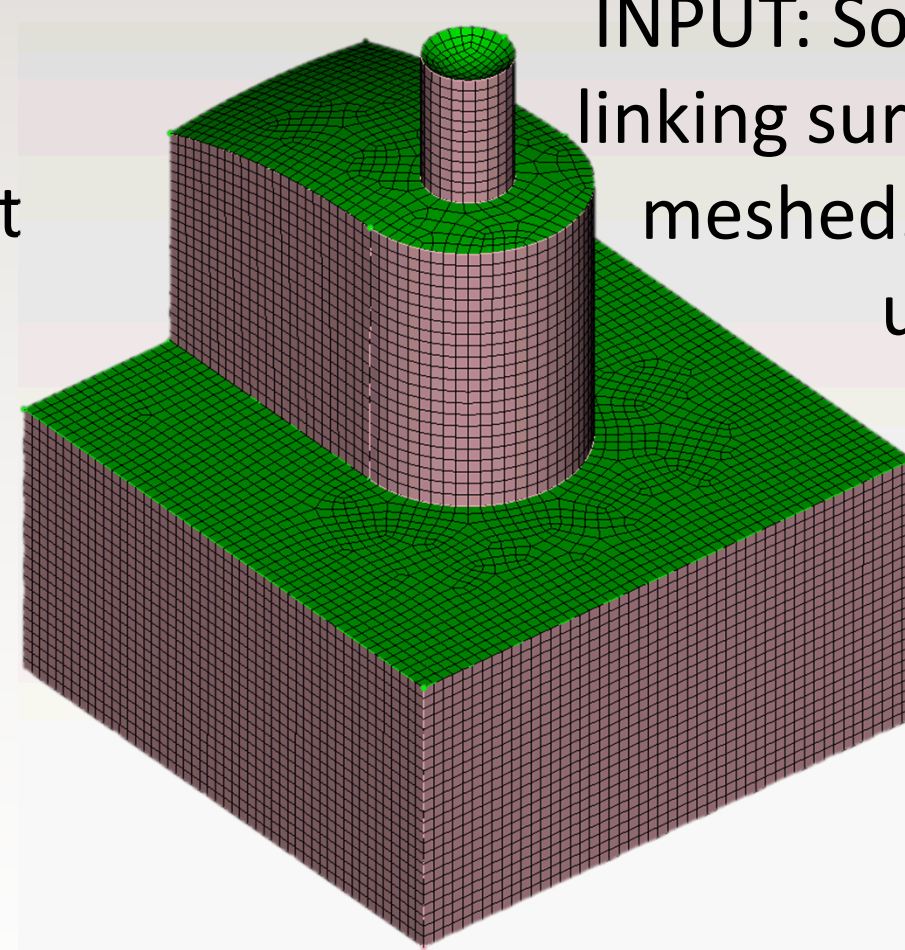
Input
Geometric
Model



INPUT: Sources and
linking surfaces pre-
meshed. Target is
unmeshed



Linking Surfaces
connect source
surfaces to target

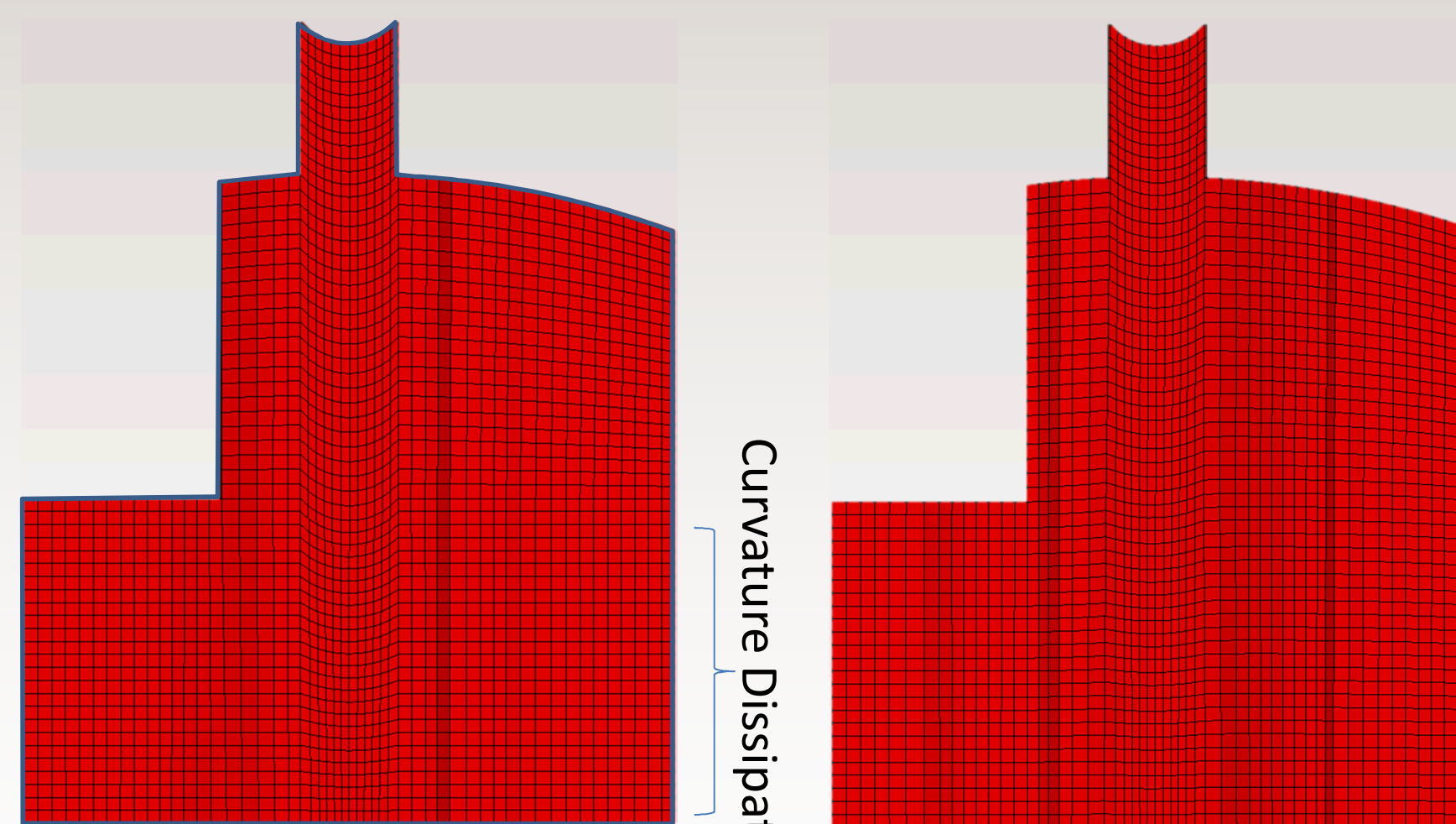
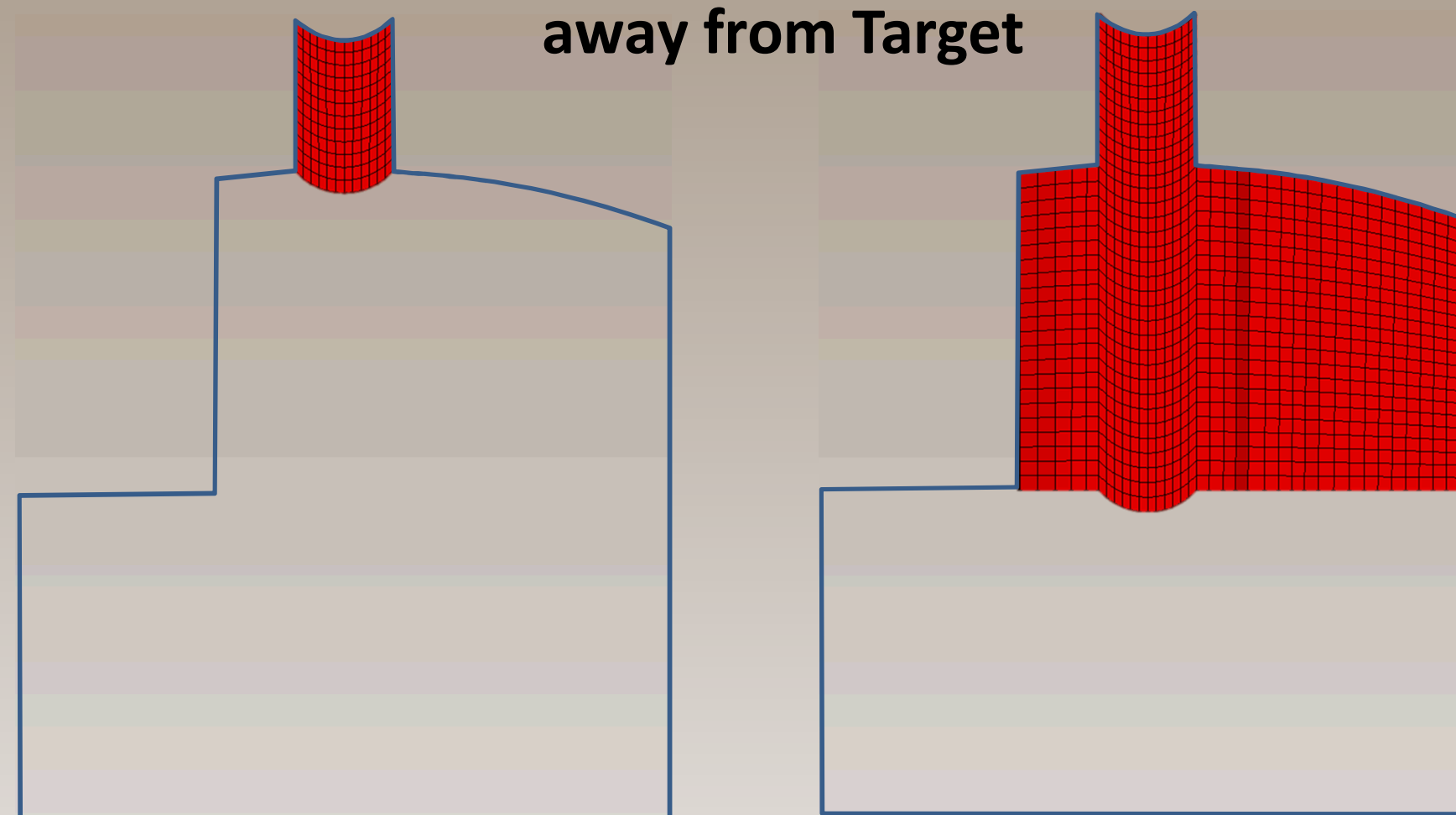


Motivation:

The old sweeper often resulted in poor quality on models with non-planar sources & targets, and was too slow. The old sweeper starts from Source 1 and sweeps to Source 2, and so forth progressing towards the target. However, there is no connection to the target surface yet, so source/target curvature cannot be dissipated. Source/target curvature is only averaged between last source and target, requiring post-processing to redundantly reposition all the nodes in the sweep.

Interpolation of layers was also based on layer index, rather than length along the sweep. Target surface smoothing was also enhanced.

Old Algorithm Sweep from source furthest to closest away from Target



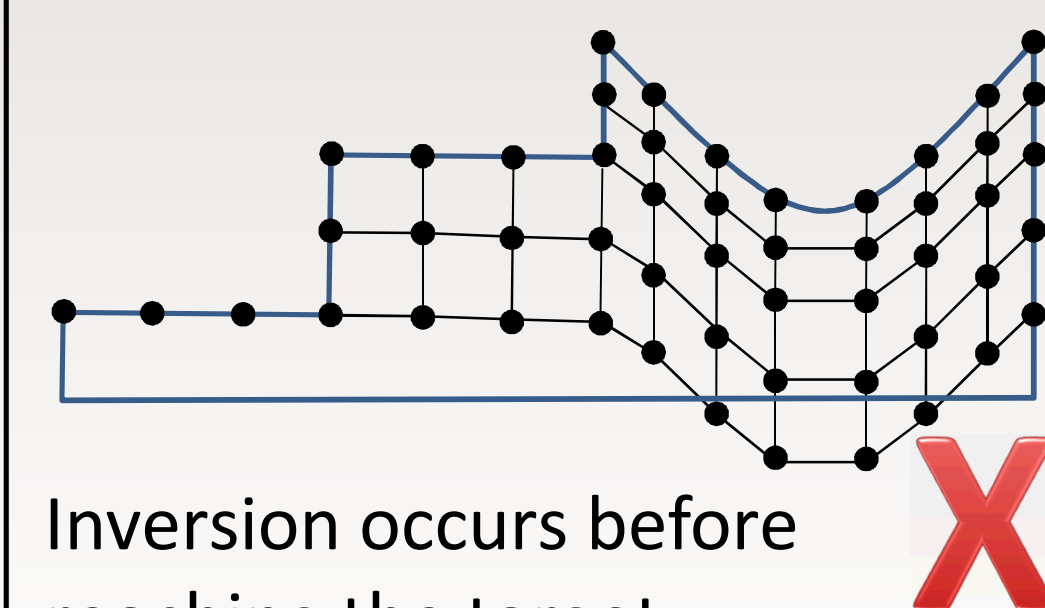
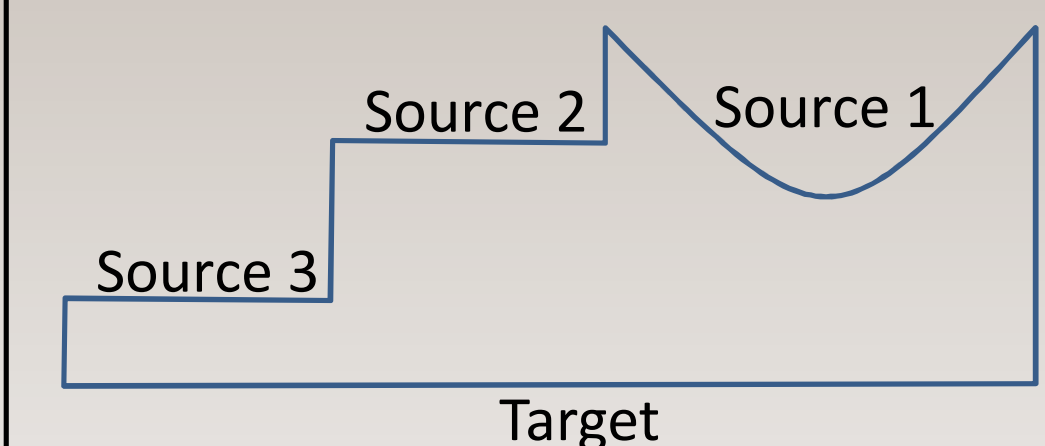
Old Algorithm

New Algorithm

Curvature Dissipation

Curvature Dissipation

Curvature Dissipation becomes a problem with thin models.

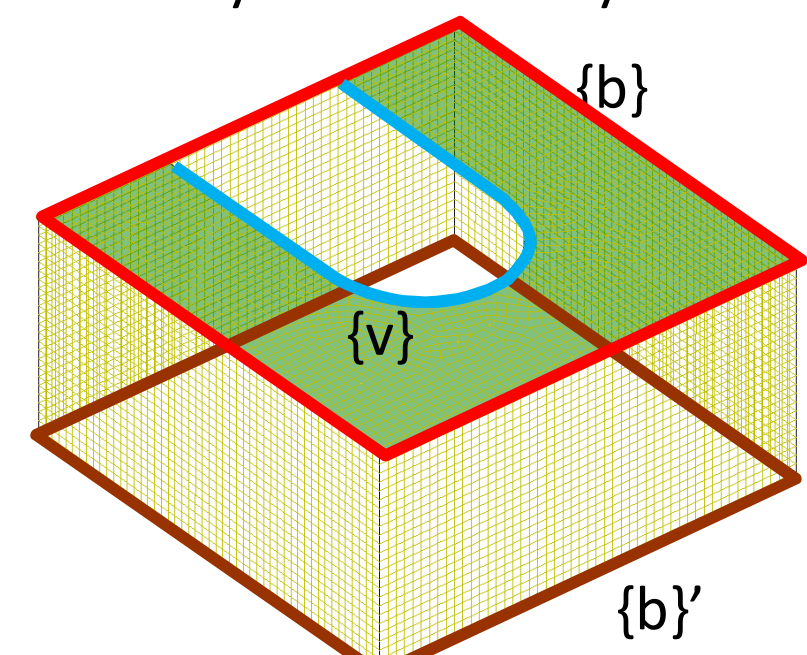


Inversion occurs before reaching the target.

New Algorithm:

The new sweeper goes backwards, starting with the source that is *closest* to the target.

Step 1: Choose Source surface CLOSEST to target. Project any of its boundary which is not yet on the target



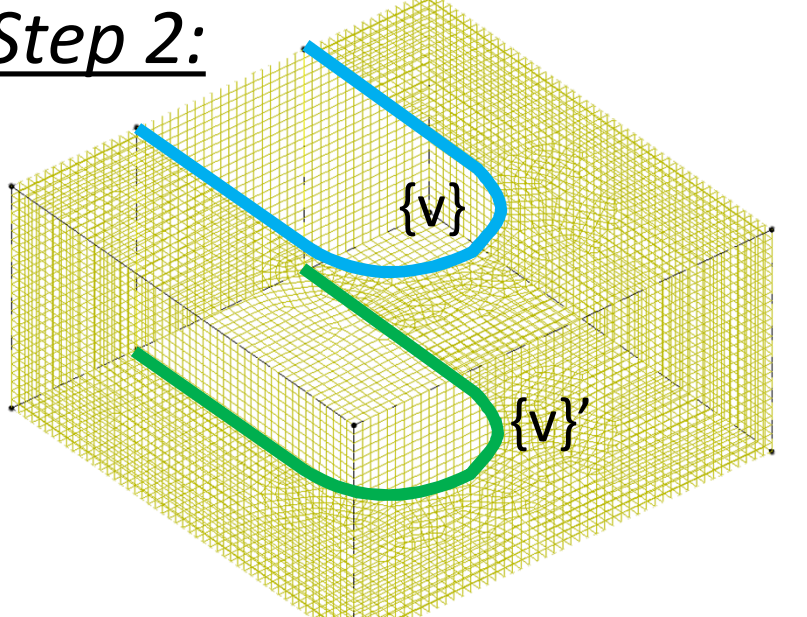
$\text{red line} = \{b\}$ Part of Source boundary that IS present on Target - KNOWN

$\text{brown line} = \{b'\}$ Part of Target that corresponds to $\{b\}$ - KNOWN

$\text{blue line} = \{v\}$ Part of Source boundary that IS NOT present on Target - KNOWN

Compute transformation matrix M between $\{b\}$ and $\{b'\}$. $\{b\} * M = \{b'\}$

Step 2:

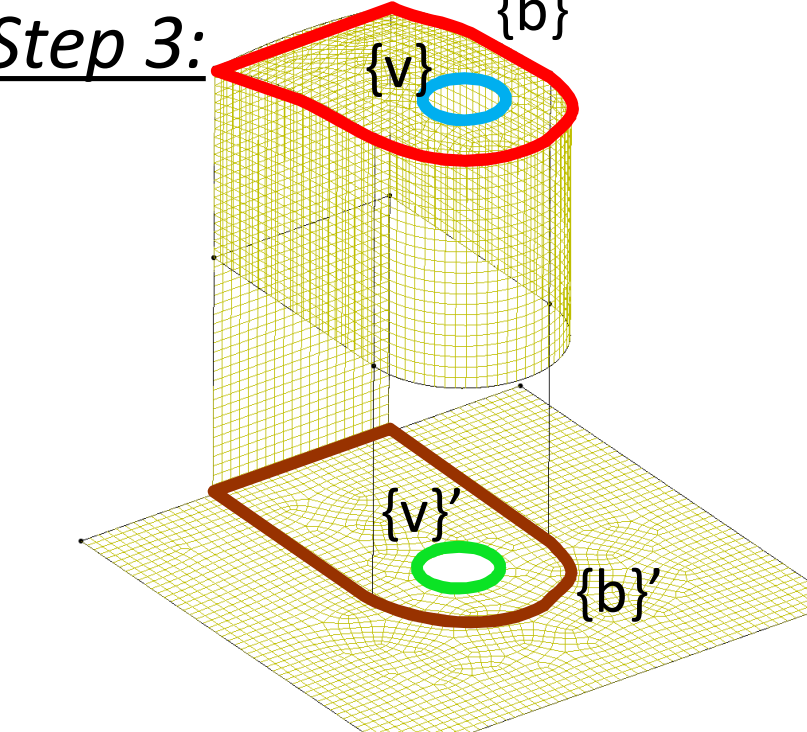


Transform $\{v\}$ using M to get $\{v'\}$.

$\{v\} * M = \{v'\}$

Project source mesh onto target. Target is now partially meshed.

Step 3:



Repeat for source *next* closest to target. Known: $\{b\}, \{b'\}, \{v\}$ Unknown: $\{v'\}$

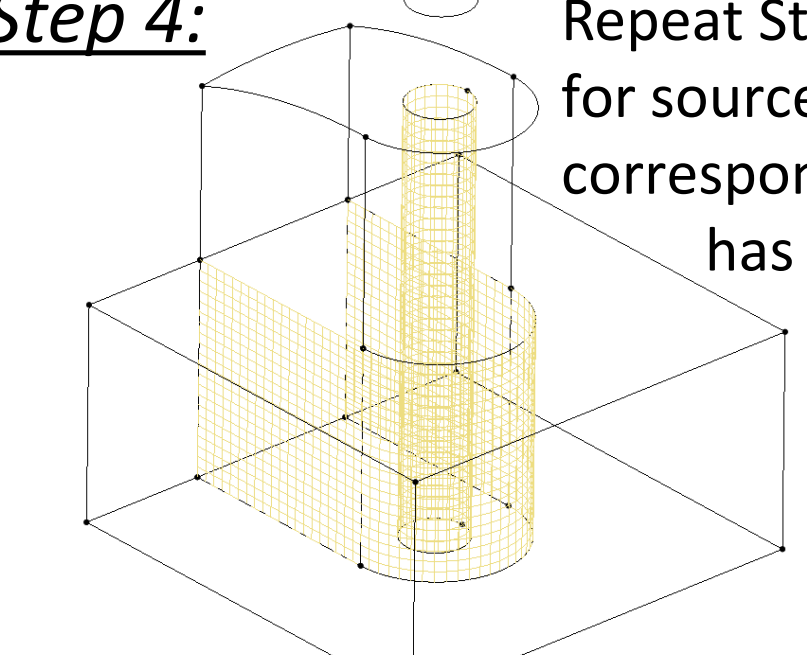
Solve for M : $\{b\} * M = \{b'\}$

Solve for $\{v'\}$: $\{v\} * M = \{v'\}$

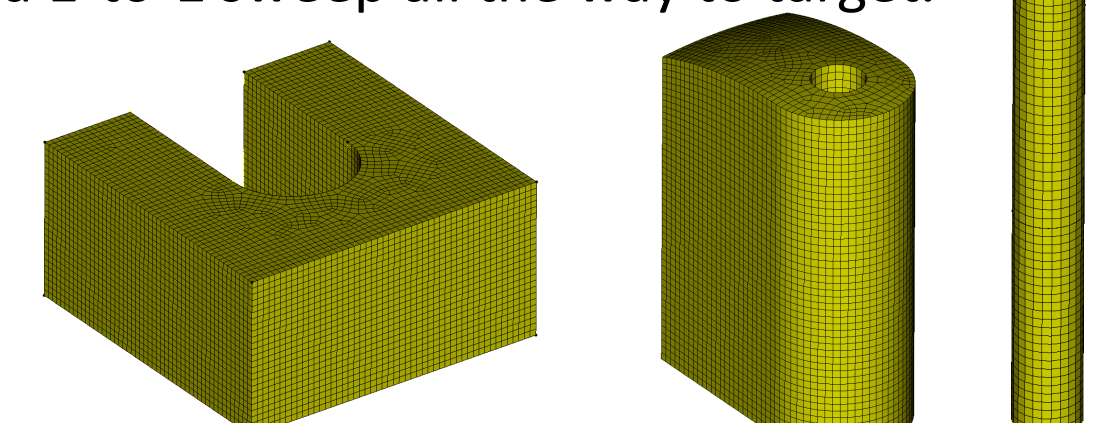
Project interior nodes & quads on this layer to target.

Repeat until all sources projected to target. Smooth target mesh if desired.

Step 4:



Repeat Steps 1-3 but project to intermediate layers for source boundaries. Every source node has a corresponding target node. Every source now has a 1-to-1 sweep all the way to target.



Improved Interpolation

Known: $P_S, P_T, \{b\}_S, \{b\}_T, \{b\}_L$

Unknown: P_L

Solve for M_S : $\{b\}_S * M_S = \{b\}_L$

Solve for M_T : $\{b\}_T * M_T = \{b\}_L$

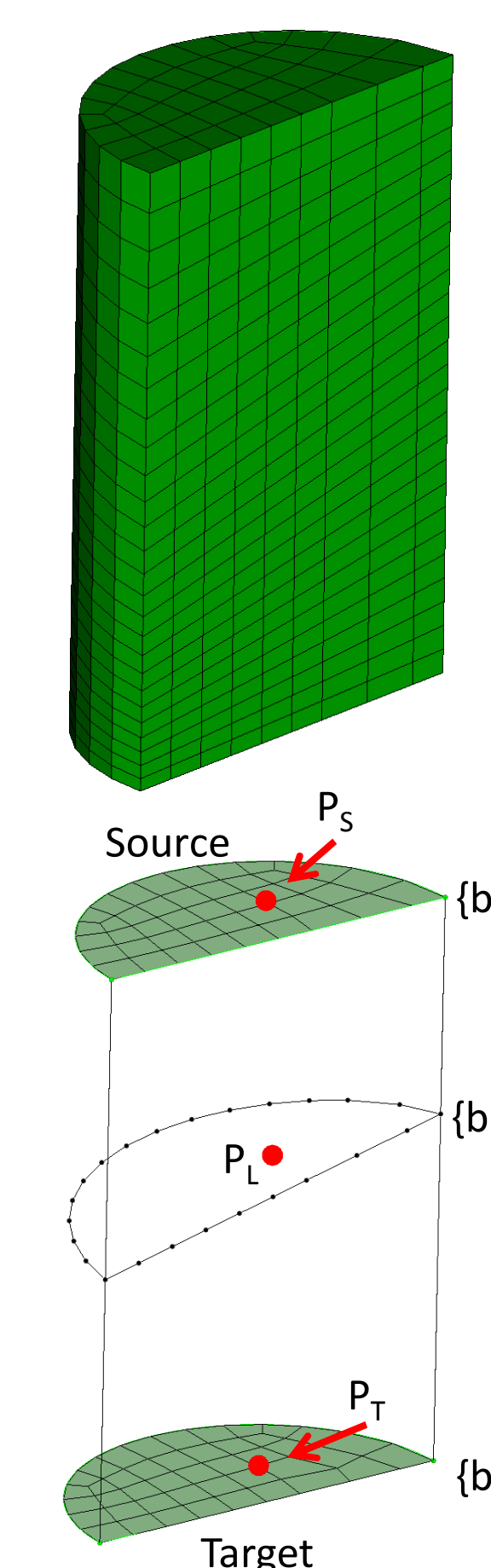
Solve for SP_L : $P_S * M_S = SP_L$

Solve for TP_L : $P_T * M_T = TP_L$

$P_L = w_S * SP_L + w_T * TP_L$

How to find w_S and w_T ?

We parameterize each 'rib' along sweep path, each node on a rib gets a t value, which is ratio along sweep path. We then do inverse distance squared weighted interpolation of t values to compute w_S and w_T .



New Target Smoothing Options

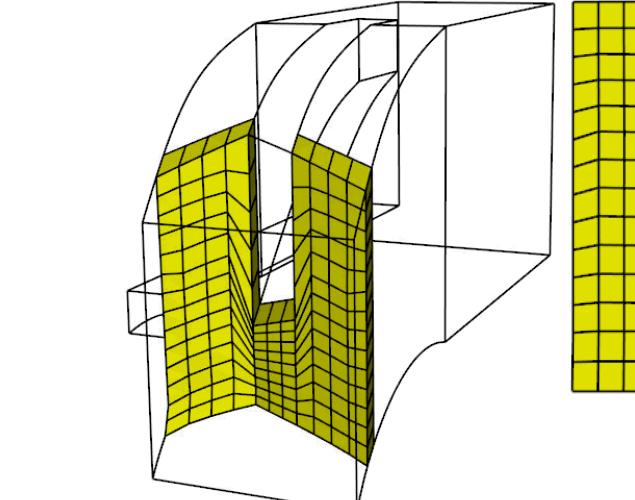
Option 1: Smooth all Nodes on target surface

Option 2: Fix nodes that are "imprints" from nodes on source curves

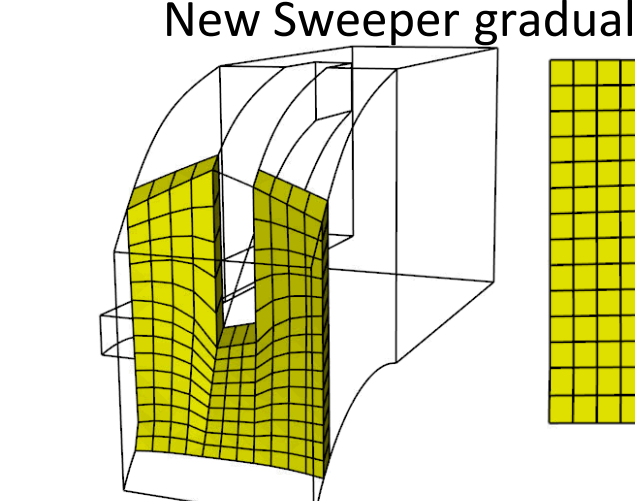
Option 3: Only smooth nodes which are within N elements of a target surface quad that has a scaled Jacobian less than user controlled tolerance.

Example #1

Old Sweeper has skew near side walls



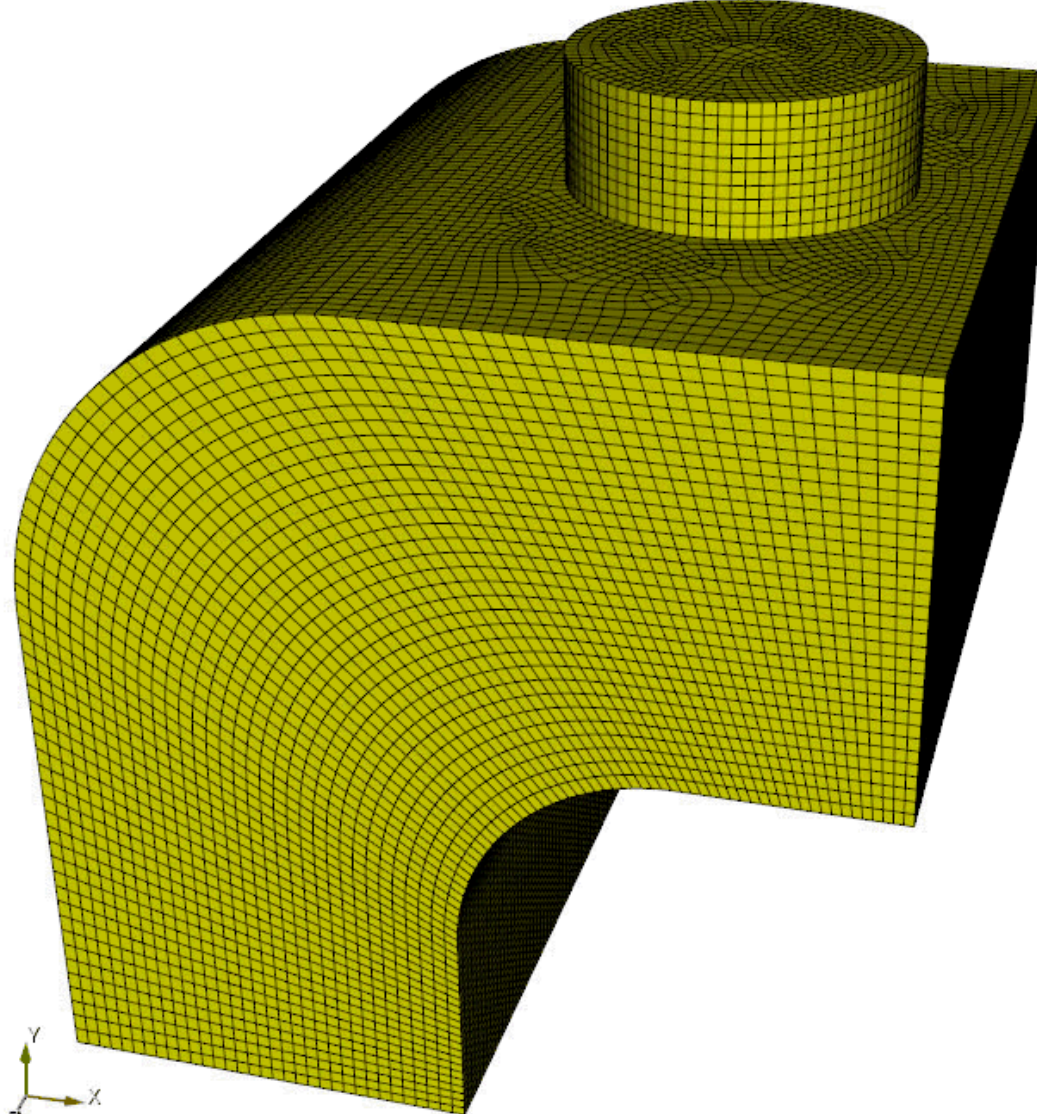
New Sweeper gradually tapers to side walls



Current Sweeper
TIME: 0.16 sec
Max Scaled J: 1.000
Ave Scaled J: 0.8982
Min Scaled J: 0.1135

New Sweeper
TIME: 0.08 sec
Max Scaled J: 1.000
Ave Scaled J: 0.9033
Min Scaled J: 0.2349

Example #2

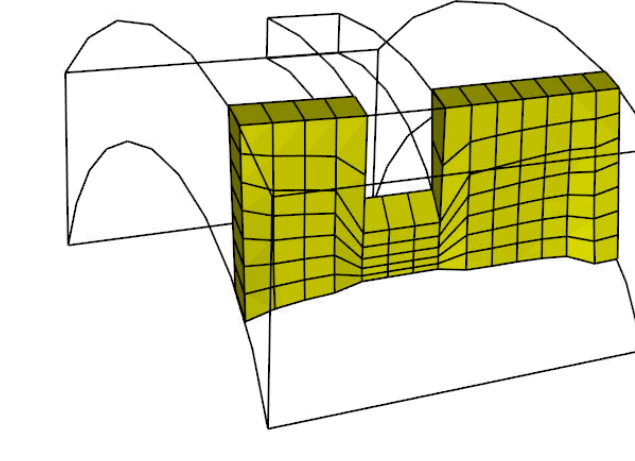


Current Sweeper
TIME: 26.74 sec
Max Scaled J: 1.0
Ave Scaled J: 0.9361
Min Scaled J: 0.4279

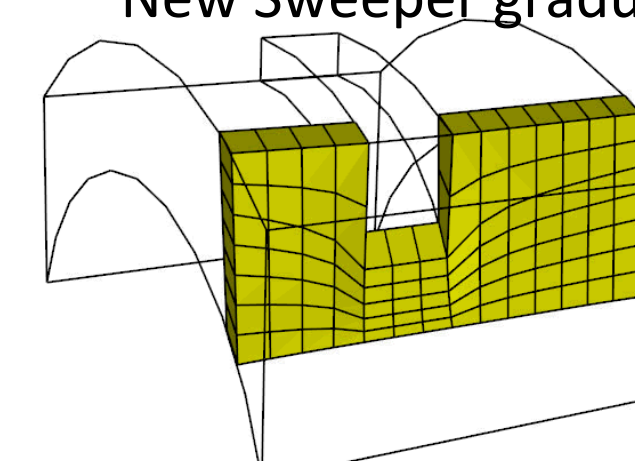
New Sweeper
TIME: 1.92 sec
Max Scaled J: 1.0
Ave Scaled J: 0.9380
Min Scaled J: 0.4228

Example #3

Old Sweeper has skew near side walls



New Sweeper gradually tapers to side walls



Current Sweeper
TIME: 0.08 sec
Max Scaled J: 0.9990
Ave Scaled J: 0.8061
Min Scaled J: 0.2758

New Sweeper
TIME: 0.11 sec
Max Scaled J: 0.9993
Ave Scaled J: 0.7901
Min Scaled J: 0.2563