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Optimal Bayesian Design of Borehole Locations for Inferring Past Ice Sheet Surface Temperatures

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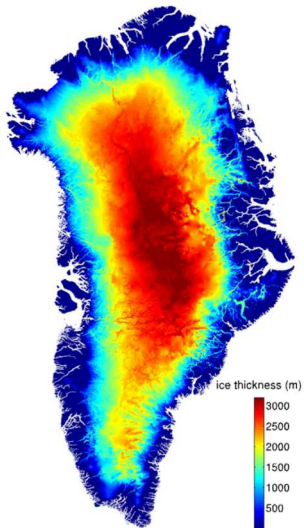
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Motivation



Source: (left) National Snow & Ice Data Center, (middle) earth-chronicles.com, (right) Andrew D. Davis

Motivation

Ice sheets **impact future global mean sea level**

- Greenland: ≈ 6 meters

Antarctica: ≈ 60 meters



Source: National Geographic

Model calibration from field observations

Generally, we need to...

- develop and improve physics-based models
- calibrate models with observation data
- predict with quantified uncertainty

Past surface temperature:

- An indication of past climate and geological events
- Inferred from borehole data
- Drill, insert, equilibrate, measure

⇒ Overall process 2-4 years!

Some measurements are more useful than others

Borehole data acquisition is:

- time-consuming
- expensive
- dangerous



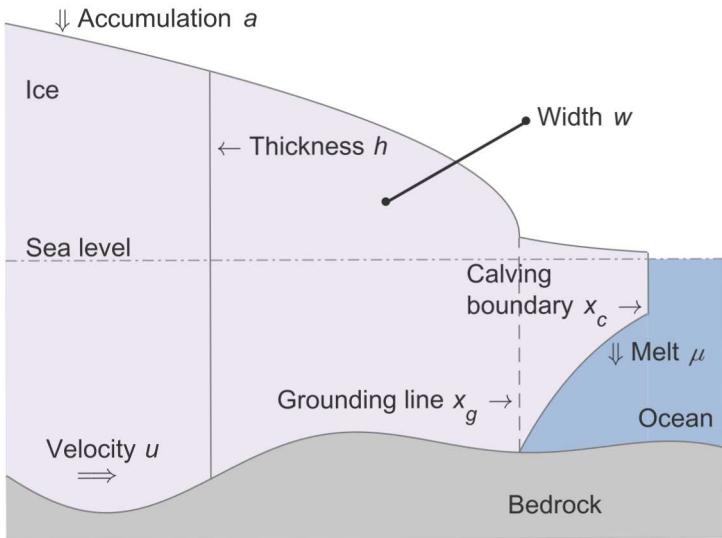
Goal of **Optimal Experimental Design**:

Select borehole locations that maximize the value of data for inferring past surface temperature

Outline

- 1 Physical model
- 2 Optimal Bayesian Experimental Design
- 3 Results

Anatomy of an ice stream



Three-part physical model

Three-part flowline model:

- ① Compute grounded thickness $h(x, t)$ and velocity $\mathbf{u}(x, t)$ from stress and mass balance equations [Dupont 05, Hindmarsh 12, Jamieson 12, Pegler 13, Pegler 16]
- ② Select a calving law and solve for the terminus $x_c(t)$ [Nick 10, Schoof 17]
- ③ Describe temperature $T(x, z, t)$ using advection-diffusion
 - Dirichlet boundary condition at the surface (assumed constant in x)

$$\dot{T} + \kappa \nabla^2 T + \mathbf{u} \cdot \nabla T = 0$$

$$T(x, h(x, t), t) = T_s(t; \theta)$$

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Forward problem: $\theta \rightarrow T(x, z, t)$

Inverse problem: noisy $T(\xi, :, t_f) \rightarrow \theta$

Optimal experimental design: best location ξ^* for noisy $T(\xi^*, :, t_f) \rightarrow \theta$

Parameterization of the surface temperature

Surface temperature field. . .

- assumed independent of x but changes with t
- modeled using a **Gaussian process** [Rasmussen 06]

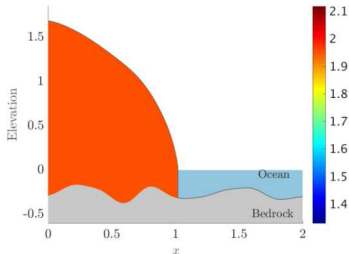
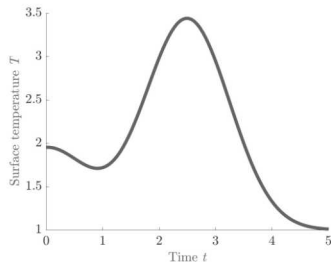
$$T_s(t; \theta) \approx \sum_{k=1}^{k_t} \sqrt{\theta_k} q_k(t) \zeta_k$$

with kernel $K(t, t') = \exp\left(-\frac{\|t - t'\|_2^2}{2\ell^2}\right)$

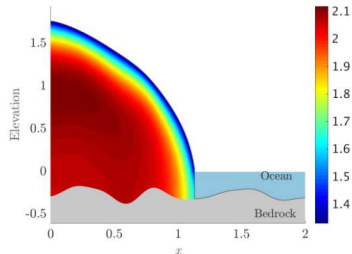
- k_t : number of terms after truncation (~ 10 in our study)
- K : covariance kernel (square-exponential; hyperparams fixed for now)
- θ_k : k^{th} eigenvalue of K
- $q_k(t)$: k^{th} eigenfunction of K
- ζ_k : $\overset{\text{iid}}{\sim} \mathcal{N}(0, 1)$

Sample modeling results

Surface temperature:



Initial condition (steady state)



Observable snapshot

Outline

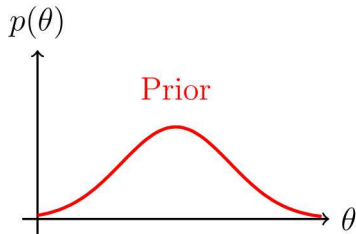
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Bayesian inference

Characterize uncertainty using **Bayes' Theorem**:

$$\overbrace{p(\theta)}^{\text{prior}}$$

θ — parameters δ — noisy data

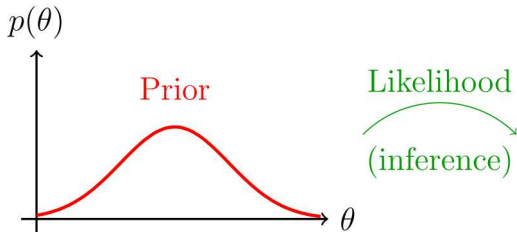


Bayesian inference

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$$\underbrace{p(\delta|\theta)}_{\text{likelihood}} \underbrace{p(\theta)}_{\text{prior}}$$

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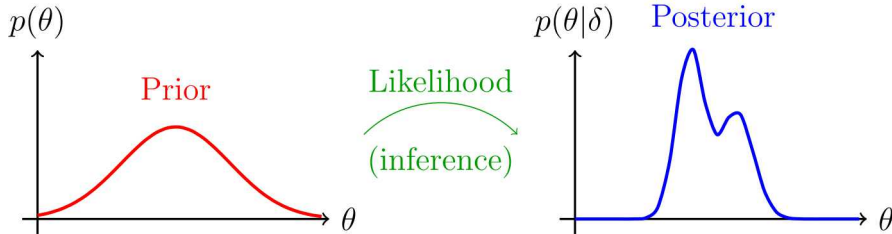


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$$\underbrace{p(\theta|\delta)}_{\text{posterior}} = \frac{\underbrace{p(\delta|\theta)}_{\text{likelihood}} \underbrace{p(\theta)}_{\text{prior}}}{\underbrace{p(\delta)}_{\text{evidence}}}$$

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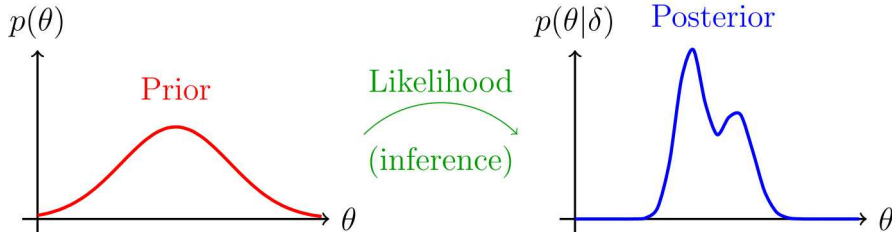


Bayesian inference

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$$\underbrace{p(\theta|\delta, \xi)}_{\text{posterior}} = \frac{\underbrace{p(\delta|\theta, \xi)}_{\text{likelihood}} \underbrace{p(\theta|\xi)}_{\text{prior}}}{\underbrace{p(\delta|\xi)}_{\text{evidence}}}$$

θ — parameters δ — noisy data ξ — design (experimental conditions)



Expected information gain

Expected **Kullback-Leibler (KL)** divergence between posterior and prior
 (\iff **mutual information** between data and parameters) [Lindley 56]

$$\begin{aligned}
 U(\xi) &= \mathbb{E}_{\delta|\xi} [D_{\text{KL}}(p(\theta|\delta, \xi) || p(\theta|\xi))] \\
 &= \int_{\delta} \left[\int_{\theta} \ln \left[\frac{p(\theta|\delta, \xi)}{p(\theta)} \right] p(\theta|\delta, \xi) d\theta \right] p(\delta|\xi) d\delta \\
 &\approx \frac{1}{N} \sum_{i=1}^N \left\{ \ln [p(\delta^{(i)}|\theta^{(i)}, \xi)] - \ln [p(\delta^{(i)}|\xi)] \right\}
 \end{aligned}$$

$$p(\delta^{(i)}|\xi) \approx \frac{1}{M} \sum_{j=1}^M p(\delta^{(i)}|\theta^{(i,j)}, \xi) \quad (\text{nested Monte Carlo!}) \quad [\text{Ryan 03}]$$

U — expected utility

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Find optimal design: $\xi^* = \underset{\xi}{\operatorname{argmax}} U(\xi)$

Computationally prohibitive: $N = M = 10^3$ requires 10^6 forward evaluations

Another perspective on the expected utility

$$\begin{aligned}
 U(\xi) &= \int_{\theta} \underbrace{\int_{\delta} \{ \ln [p(\delta|\theta, \xi)] - \ln [p(\delta|\xi)] \} p(\delta|\theta, \xi) d\delta}_{f(\xi, \theta)} p(\theta) d\theta \\
 &\approx \frac{1}{N_1} \sum_{i_1=1}^{N_1} \underbrace{\frac{1}{N_2} \sum_{i_2=1}^{N_2} \{ \ln [p(\delta^{(i_2)}|\theta^{(i_1)}, \xi)] - \ln [p(\delta^{(i_2)}|\xi)] \}}_{\hat{f}(\xi, \theta)}
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with $\theta^{(i_1)} \sim p(\cdot)$, $\delta^{(i_2)} \sim p(\cdot|\theta, \xi)$ and an importance sampling estimate

$$p(\delta^{(i_2)}|\xi) \approx \sum_{j=1}^M p(\delta^{(i_2)}|\theta^{(i_2, j)}, \xi) w^j \quad \text{with} \quad \theta^{(j)} \sim q(\cdot)$$

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- Triple-nested, but no new cost in integration
- Avoids surrogates that involve data δ (high-dimensional)
- Inner loops produce **noisy estimates** $\hat{f}(\theta, \xi) \approx f(\theta, \xi)$

Adaptive surrogate for Bayesian evidence

Given noisy estimates $\{\hat{f}_i(\theta_i, \xi_i)\}_{i=1}^S$ with known variance, we compute a **local polynomial surrogate** using regression

$$\eta(\theta, \xi) = \operatorname{argmin}_{m \in \mathcal{P}} \sum_{i=1}^S \left(m(\theta_i, \xi_i) - \hat{f}_i(\theta_i, \xi_i) \right)^2 \mathcal{K}(\theta_i, \xi_i; \theta, \xi)$$

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The error bound can be shown to be

$$\|\eta(\theta, \xi) - f(\theta, \xi)\| \leq C_S \Delta^{p+1}$$

Replacing f with η introduces a bias of $C_S \Delta^{p+1}$; choose S such that

$$\begin{aligned} [\text{Monte Carlo variance}] &\sim [\text{Surrogate bias}]^2 \\ C_{MC} N^{-1} &\sim C_S^2 \Delta^{2(p+1)} \end{aligned}$$

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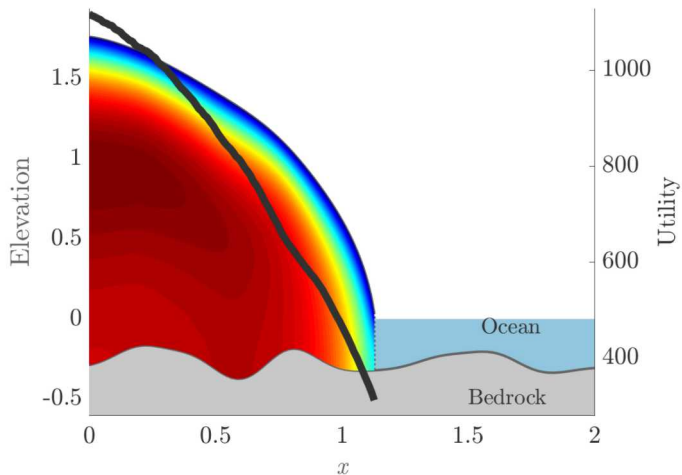
- Regression averages noise from \hat{f} so we can choose smaller N_2, M
- Choosing $S \approx 50, N_2 = M = 10$ requires $SN_2M \approx 5000 \ll 10^6$ model evaluations

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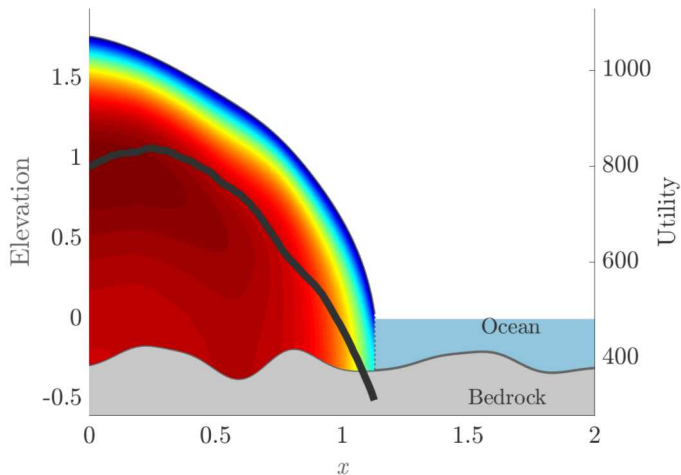
Expected information gain

$$U(\xi) = \mathbb{E}_{\delta|\xi} [D_{\text{KL}}(p(\theta|\delta, \xi) || p(\theta|\xi))]$$



Expected information gain with inland hiking penalty

$$U(\xi) = \mathbb{E}_{\delta|\xi} [D_{\text{KL}}(p(\theta|\delta, \xi) || p(\theta|\xi))] - 250(x_g - \xi)^2$$



Summary

Conclusions:

- Formulated borehole selection problem in a Bayesian setting and using optimal experimental design
- Constructed surrogate on information gain to significantly reduce computational costs from nested Monte Carlo
- Adapted surrogate based on bias-variance tradeoff
- Designed locations to maximize expected information gain on past surface temperature

Summary

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Future work:

- Incorporate more complex physical model: geothermal heating, frictional heating, internal source/sinks
- Include more sophisticated cost/constraints within a 2D spatial setting
- Design multiple locations on single expedition

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- Massachusetts Institute of Technology
- U.S. Department of Energy
- National Science Foundation

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