

Nuclear Science and Security Consortium

Fall Workshop and Advisory Board Meeting 2018

Warhead Verification Using Time-Encoded Imaging

October 1, 2018

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UC-Berkeley
Sandia National Lab

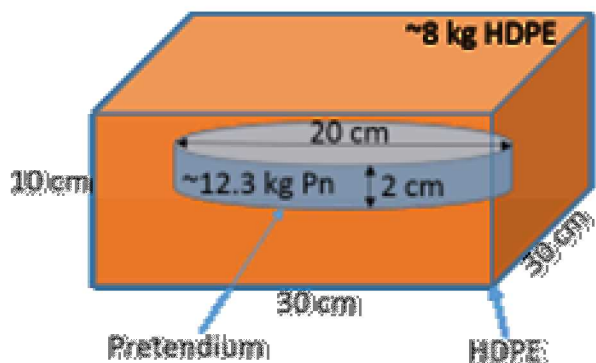


October 1-2, 2018

- **Motivation**
 - Authentication question
- **Time Encoded Imaging**
- **CONFIDANTE**
 - Concept
 - Prototype
 - Multiplicity

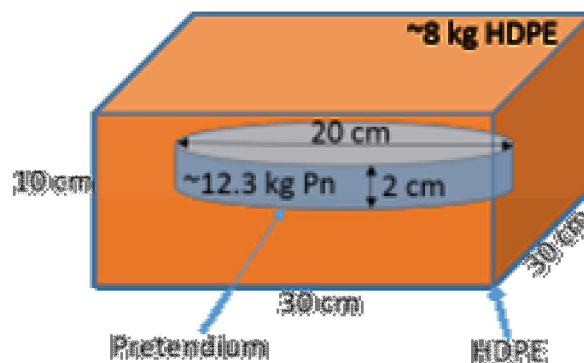
Authentication - the process by which a monitoring party gains confidence that reported characteristics of an entity reflect the true state of that entity

Certification – the process by which a host party gains confidence that sensitive information regarding an entity or facility remains secure.



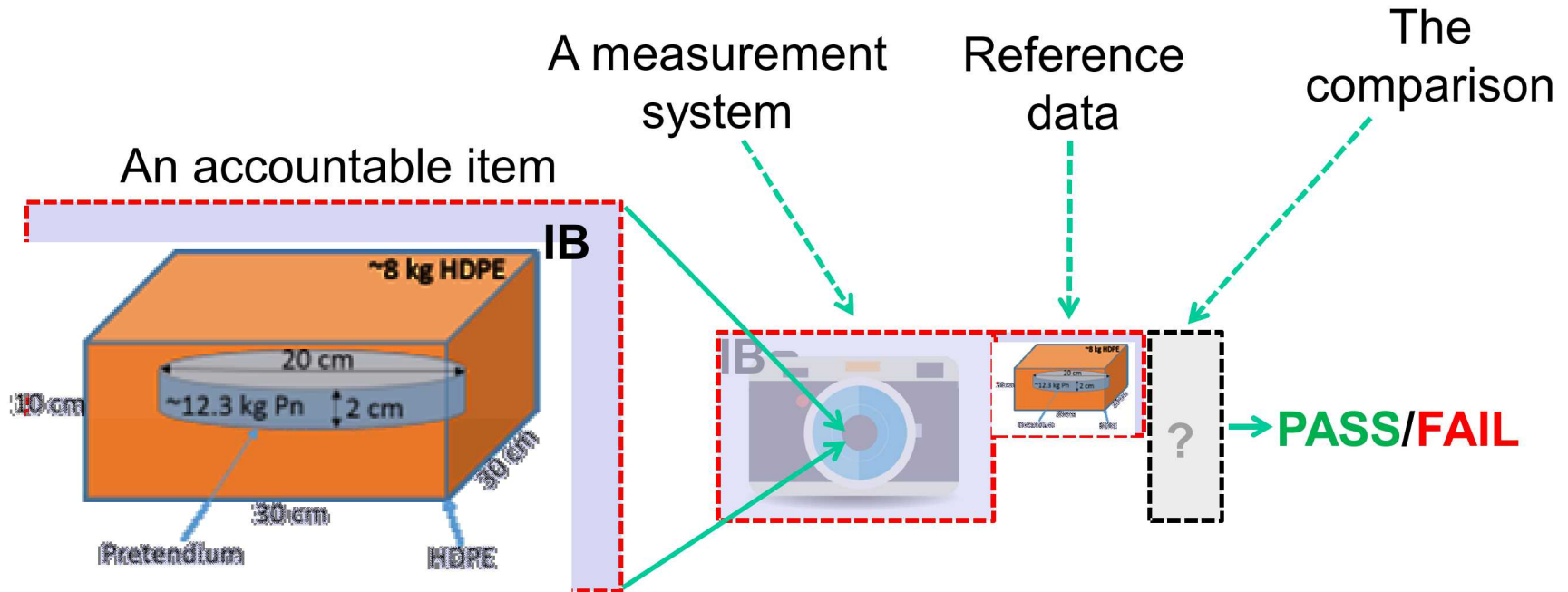
**Object T = valid type
1 TAI**

= (?)



Object X = ?

Generic confirmation by comparison to a reference

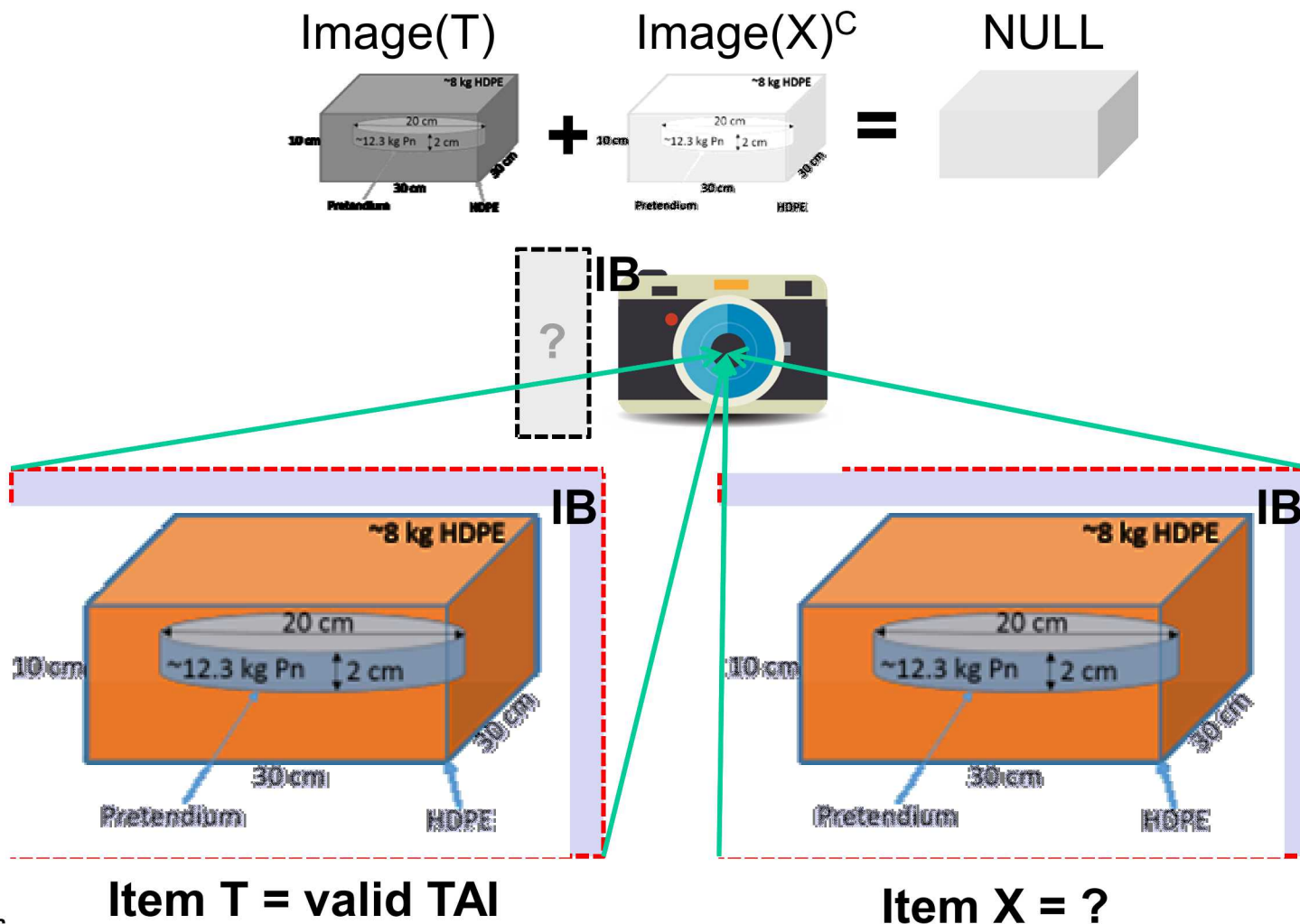


Can we decrease the amount of information behind a barrier while still maintaining confidence?

Can we get rid of a barrier all together?

Proposal – complementary comparison

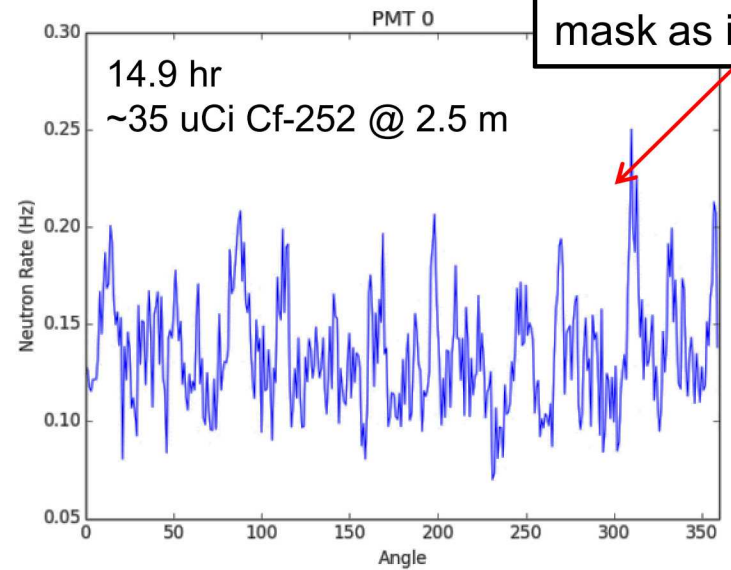
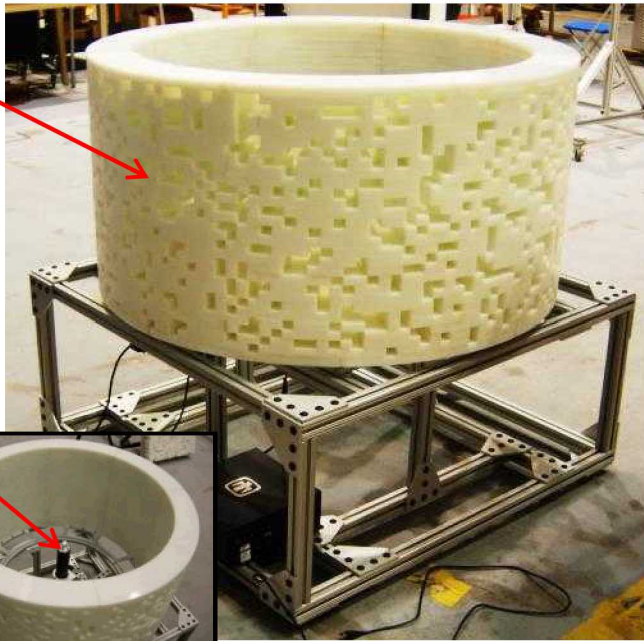
- What we need is to turn one image into its complement *at all times*.



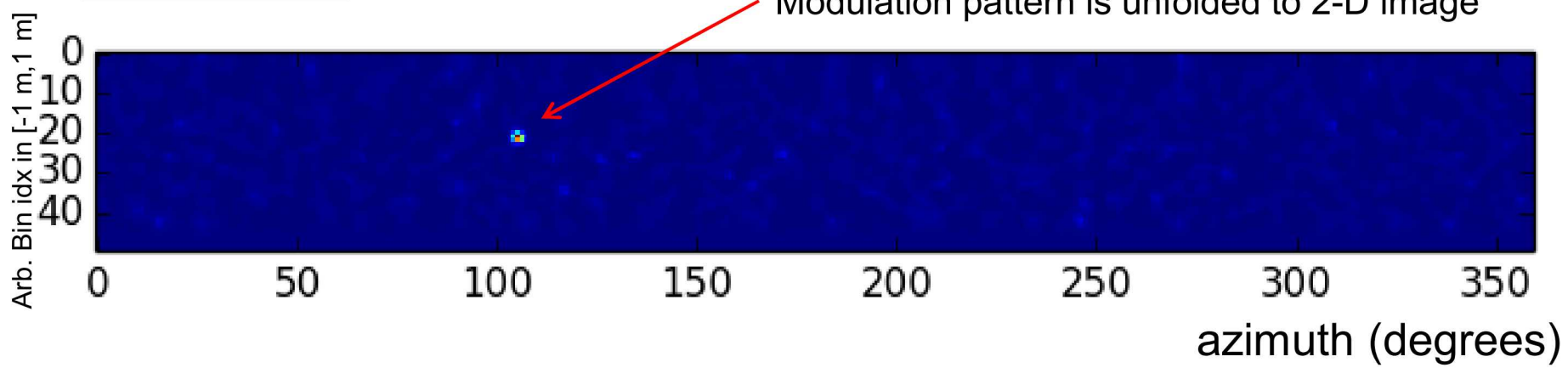
2D Time-Encoded Imaging (TEI)

2-d
coded
mask

Single
1"D x 1"
LS pixel

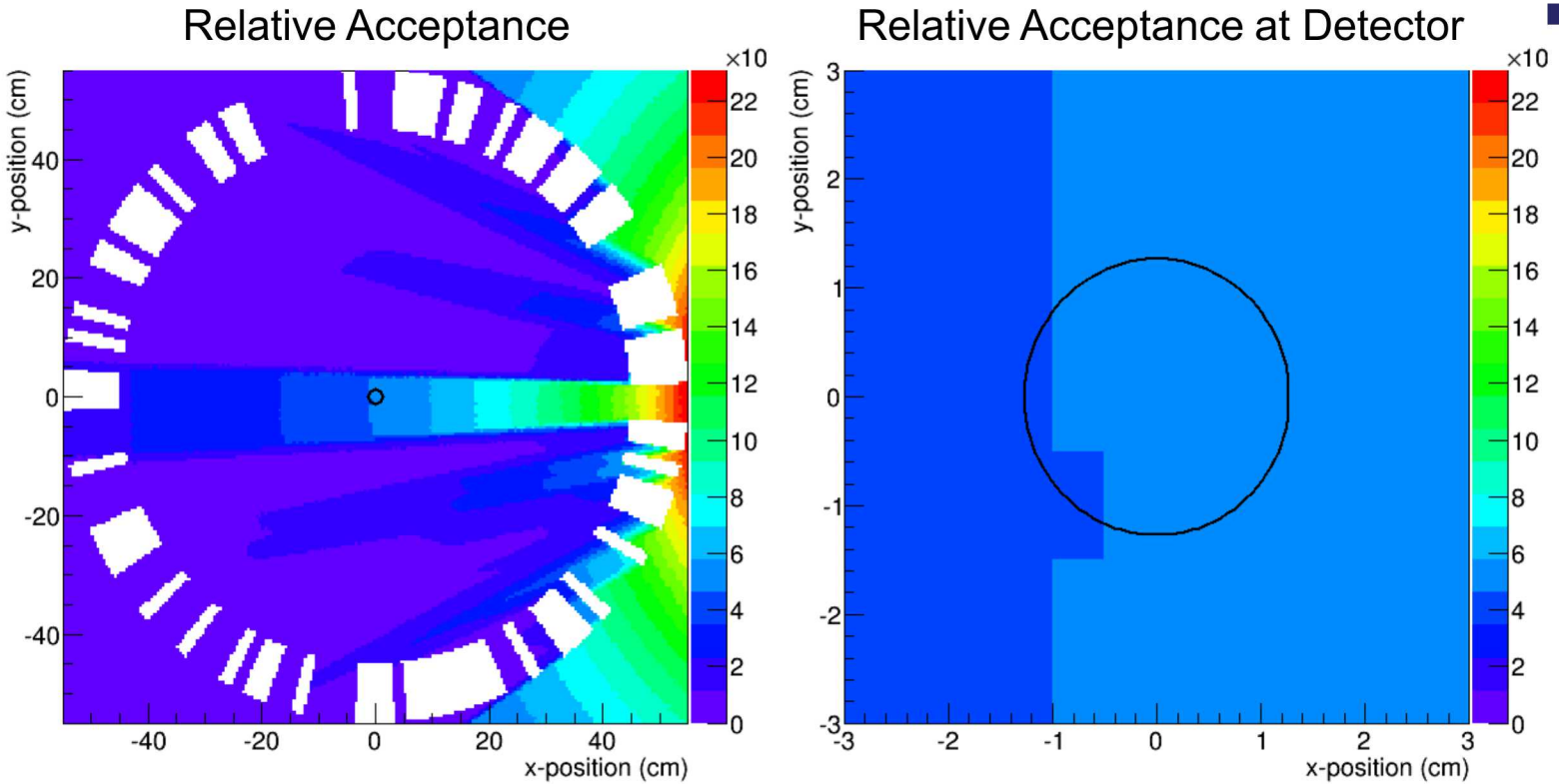


Single pixel rate is modulated by the mask as it rotates.



Modulation pattern is unfolded to 2-D image

Time Encoded Imaging

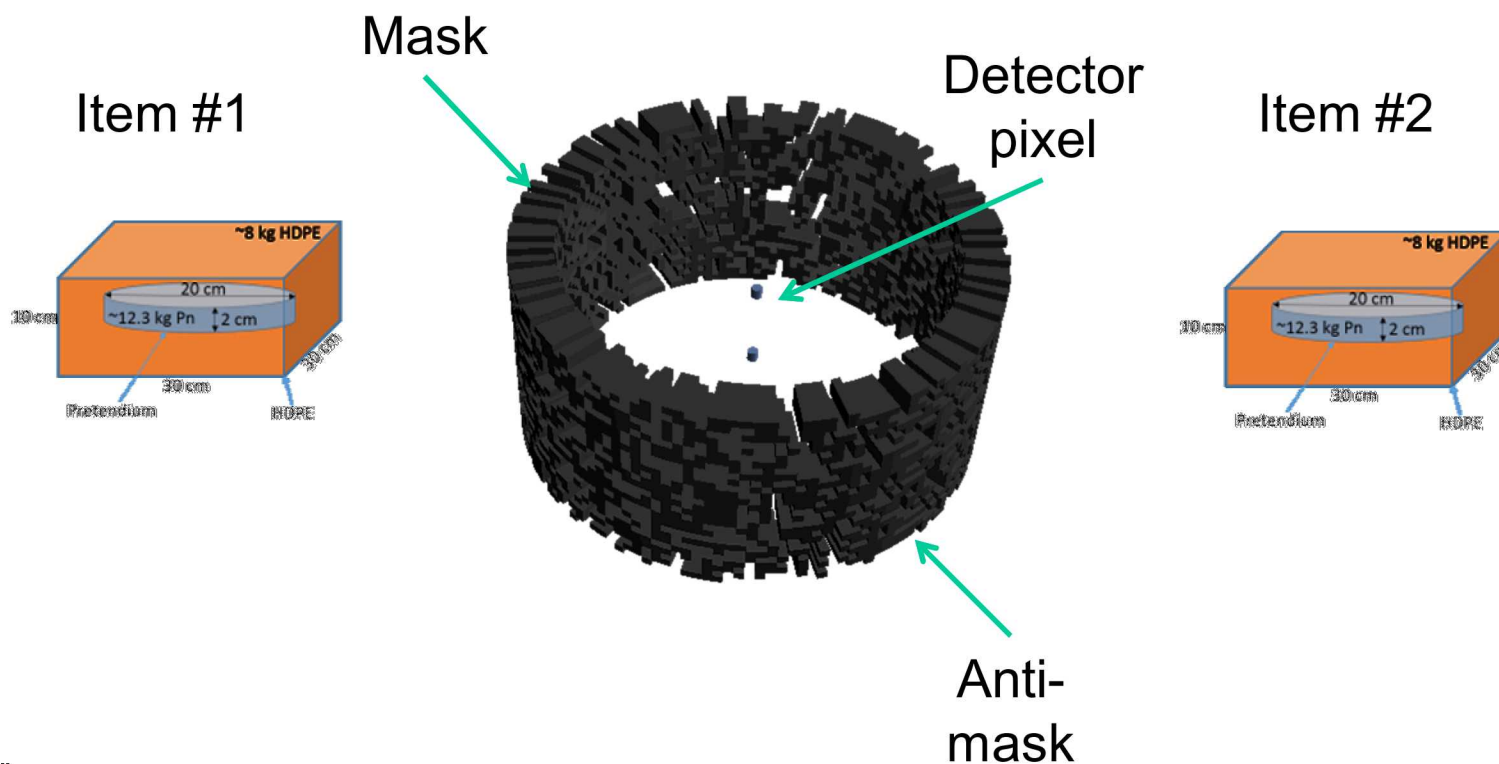


Sum of Acceptance in Detector

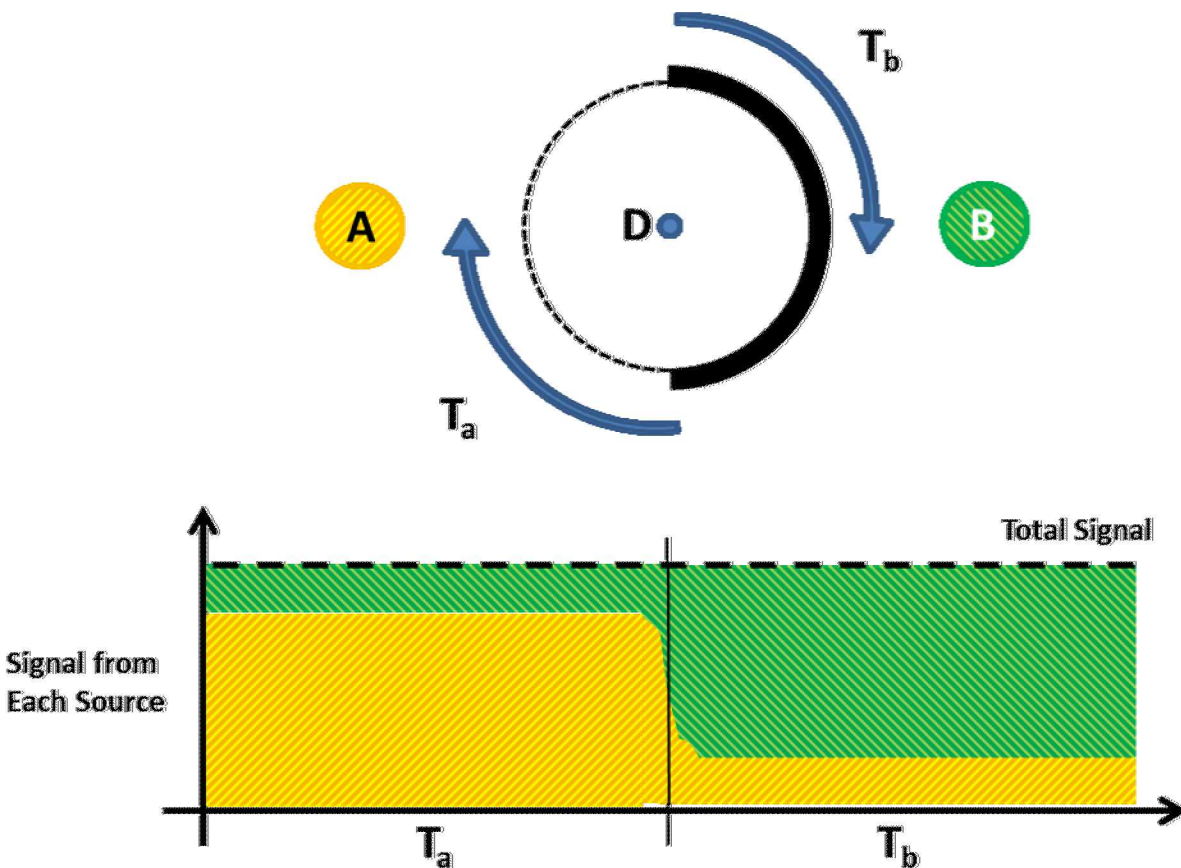


Solution: 2D-TEI mask/anti-mask

If the mask is designed such that one side is the anti-mask of the other, then **Item #2 projects the anti-image of Item #1 at all times if and only if they are identical!**

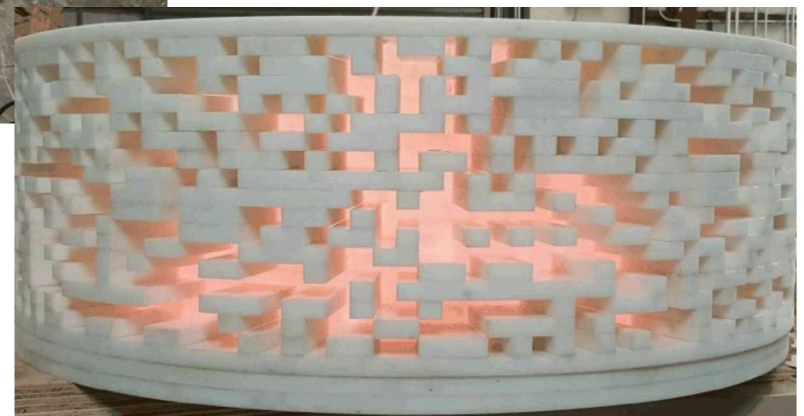


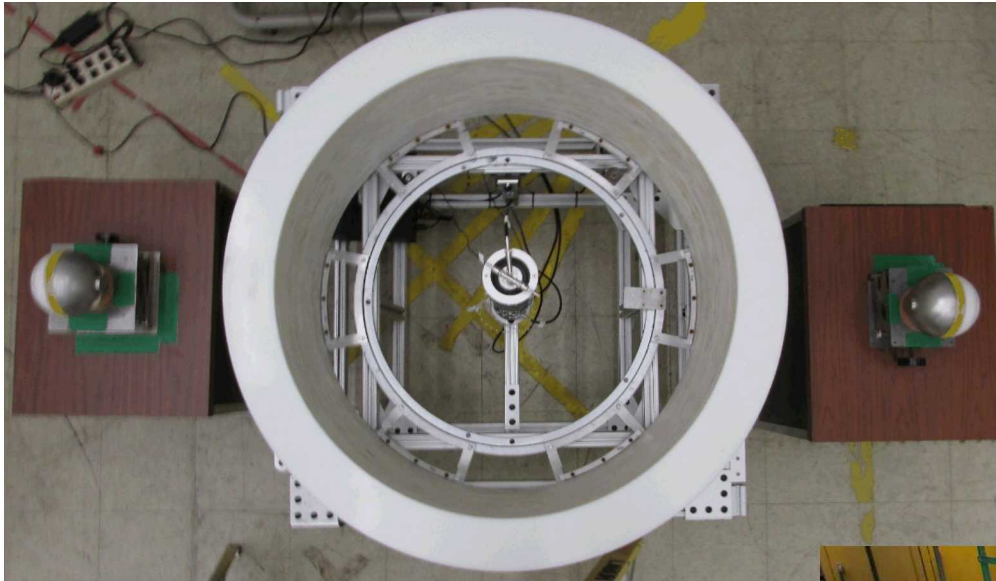
A very simple example



- The simplest possible mask with this property: half mask, half aperture.
- The fraction of total count rate coming from A and B is unknown at any given angle.
- In this example, the location (and shape) of the boundary between regions is not revealed.

CONFIDANTE



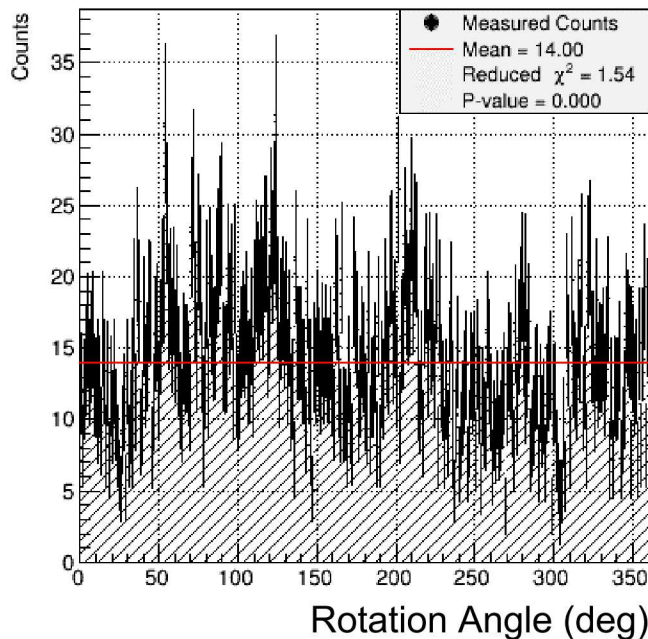


- One hemisphere was placed on either side of CONFIDANTE (180 deg. apart).
- ~68 hours of data was taken.

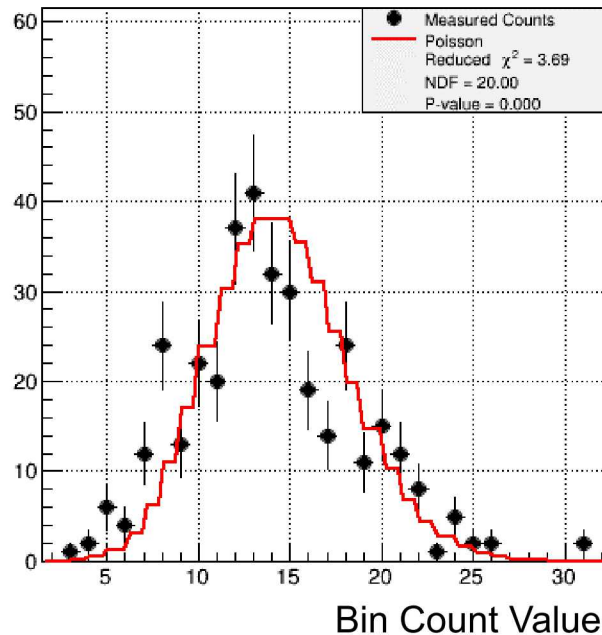


One PuO₂ sphere – 25 hours

Detector Counts (det 0)

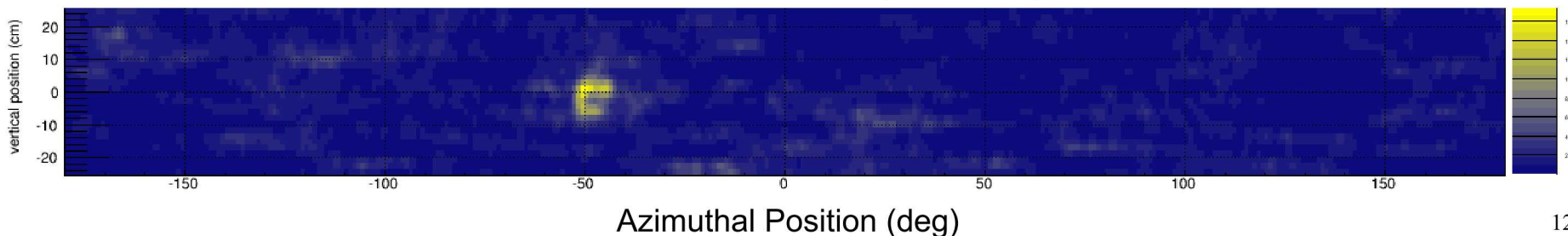


Counts per Angle Distribution (det 0)



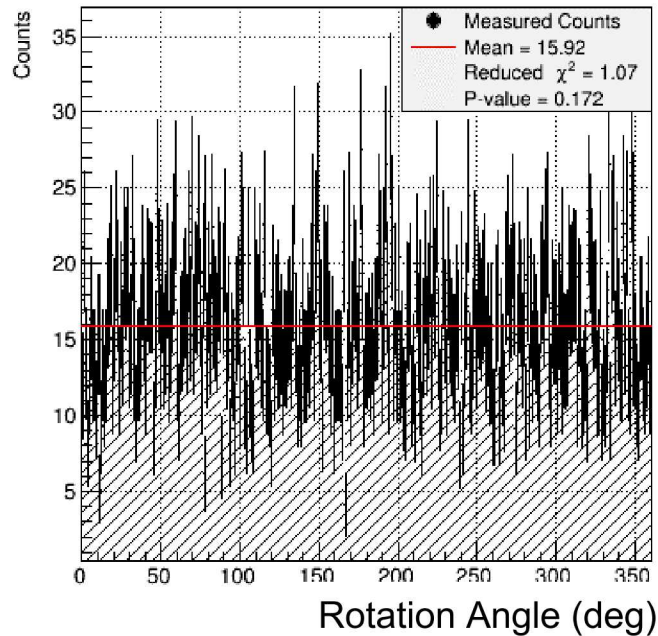
- 2 hours was sufficient for χ^2 convergence.
- Can reject the null-hypothesis (constant rate) with $p\text{-value} < 0.05$

MLEM Reconstruction (25 hours)

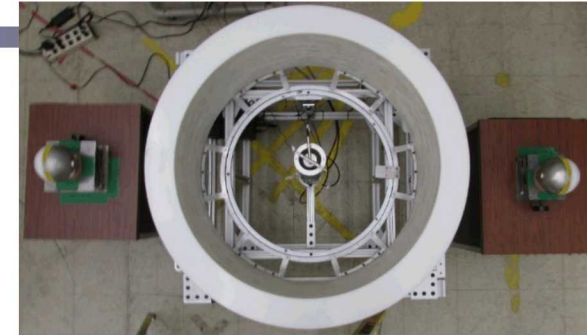
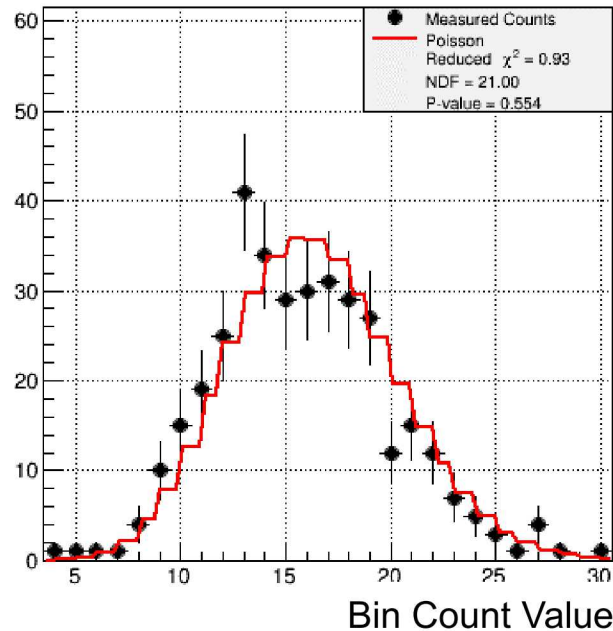


Two aligned PuO_2 hemispheres (positive)

Detector Counts (det 0)

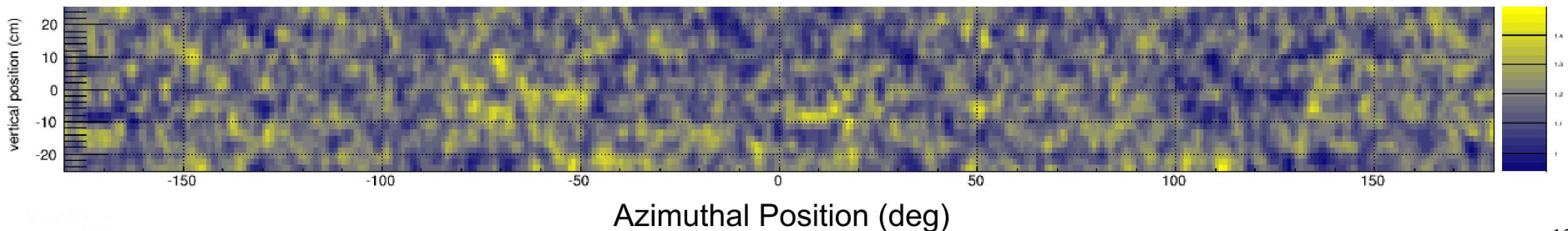


Counts per Angle Distribution (det 0)



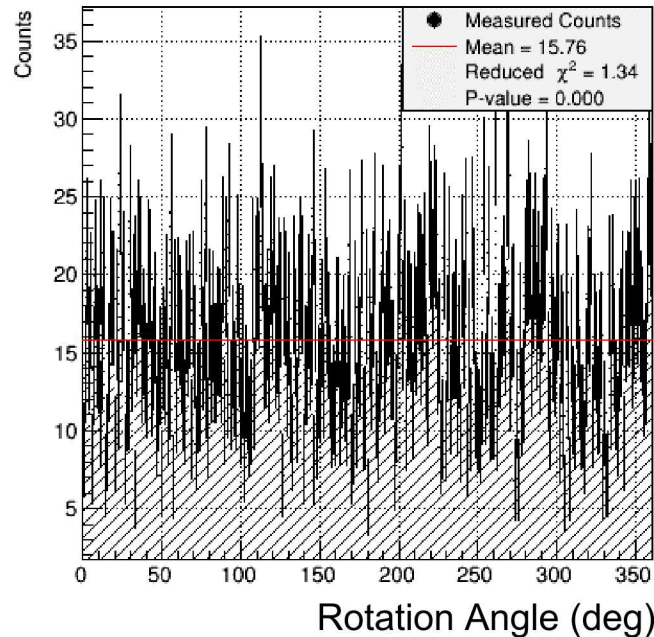
- 25 hours was sufficient for χ^2 convergence.
- We **cannot** reject the null-hypothesis (constant rate) with p-value = ~ 0.5

MLEM Reconstruction (25 hours)

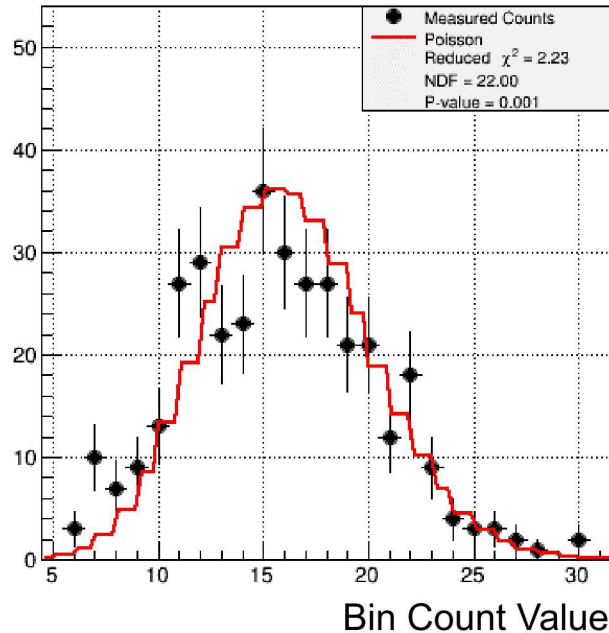


Two misaligned PuO_2 hemispheres (negative)

Detector Counts (det 0)

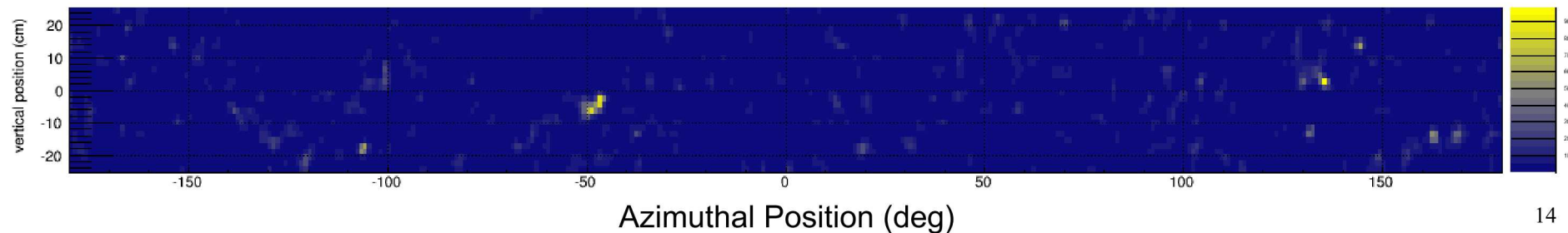


Counts per Angle Distribution (det 0)



- One hemi was rotated by 90° .
- 15 hours was sufficient for χ^2 convergence.
- We reject the null-hypothesis (constant rate) with $p\text{-value} < 0.05$

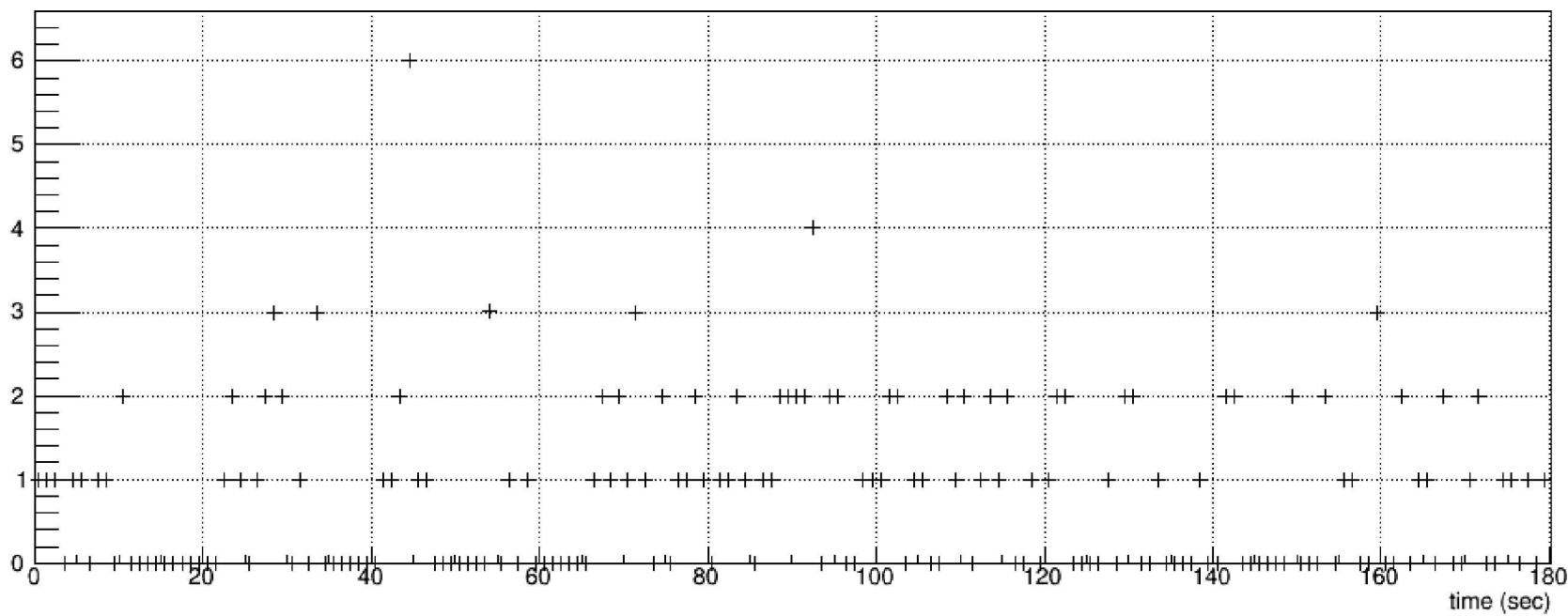
MLEM Reconstruction (48 hours)



Multiplicity

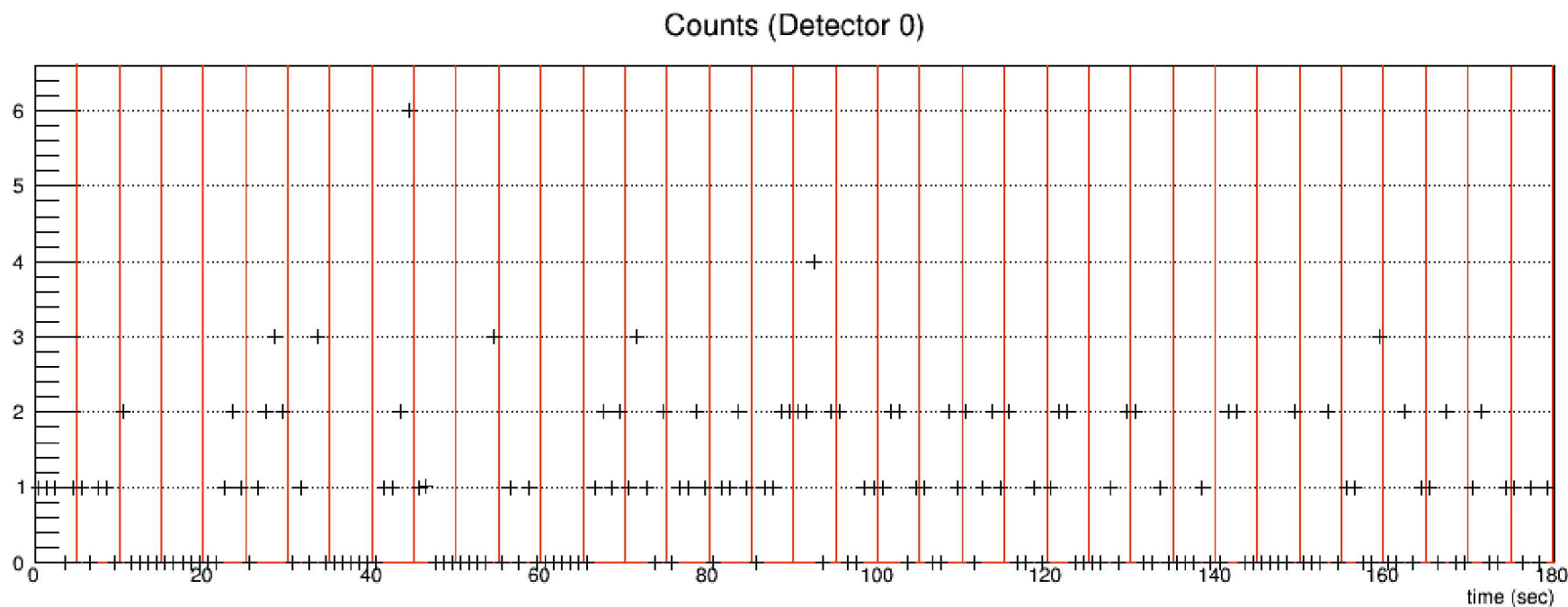
- Saving events time/location could reveal sensitive information

Counts (Detector 0)



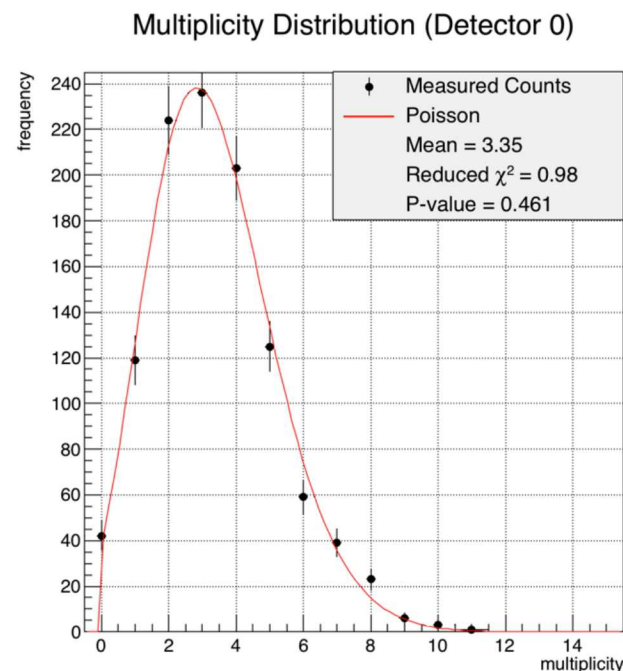
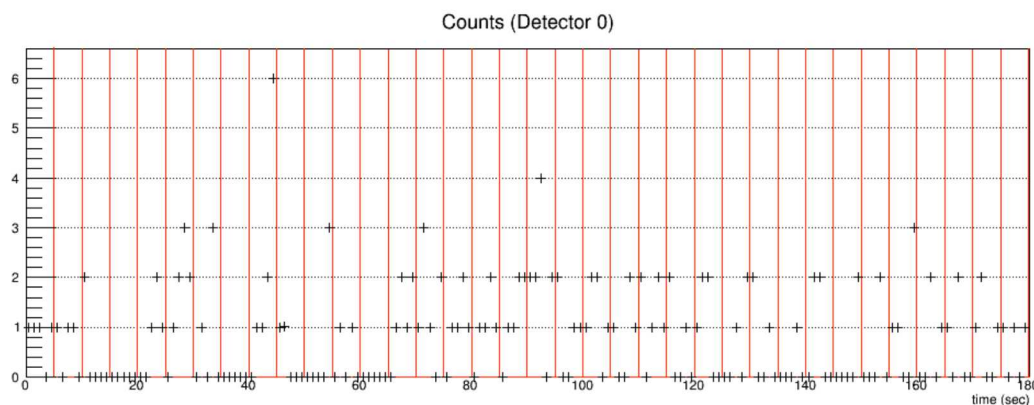
Multiplicity

- Saving events time/location could reveal sensitive information
- Count the number of events in angle bin, removing exact location



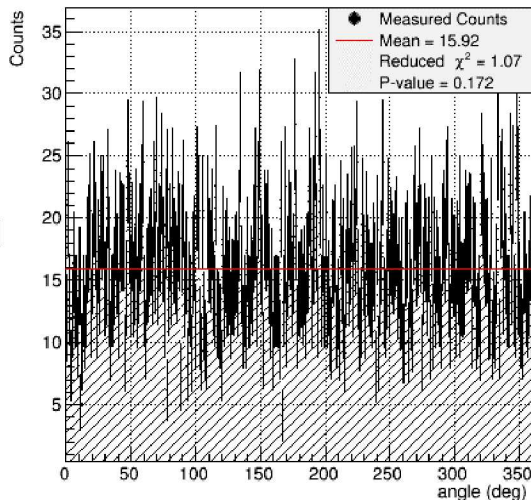
Multiplicity

- Saving events time/location could reveal sensitive information
- Count the number of events in angle bin, removing exact location
- Looks like a multiplicity using time windows



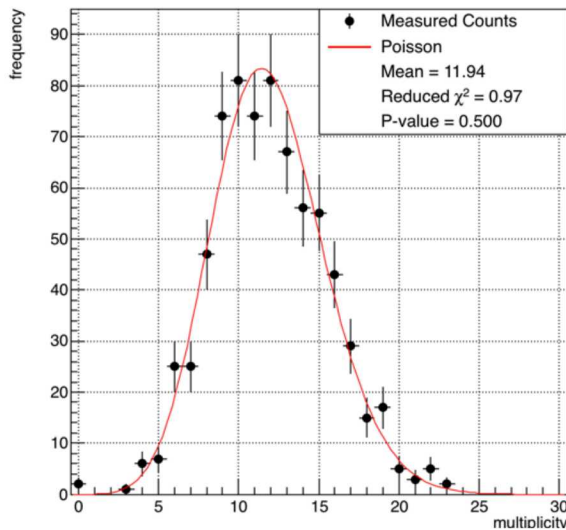
Multiplicity comparison

Detector Counts (det 0)

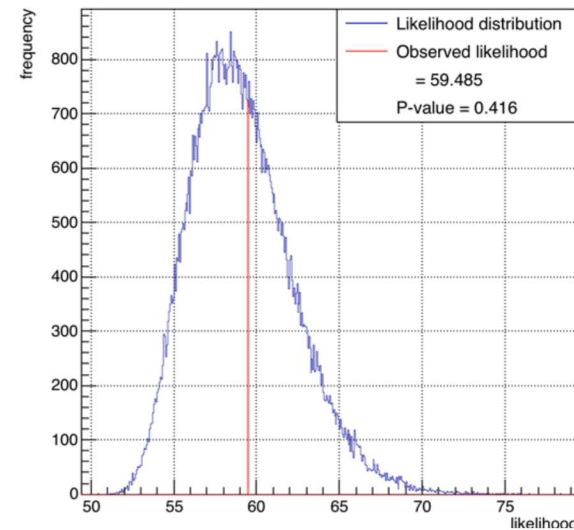


Matched

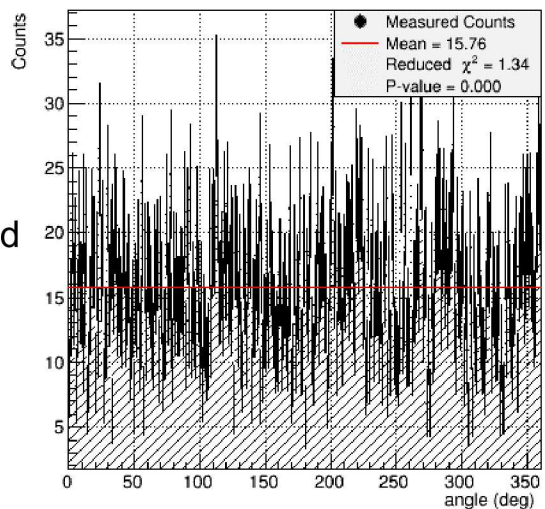
Multiplicity Distribution (Detector 0)



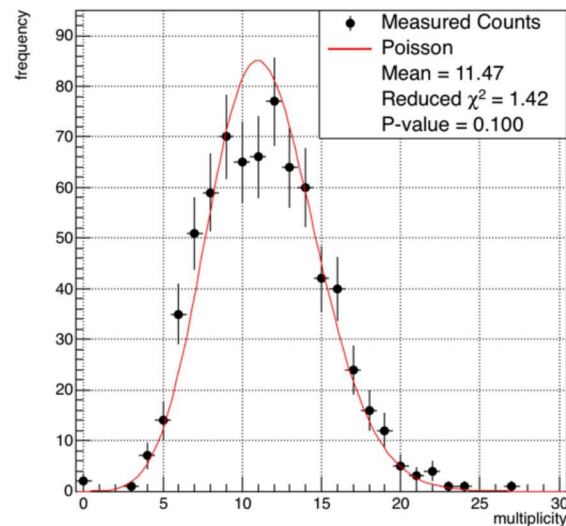
Likelihood Distribution (Det 0)



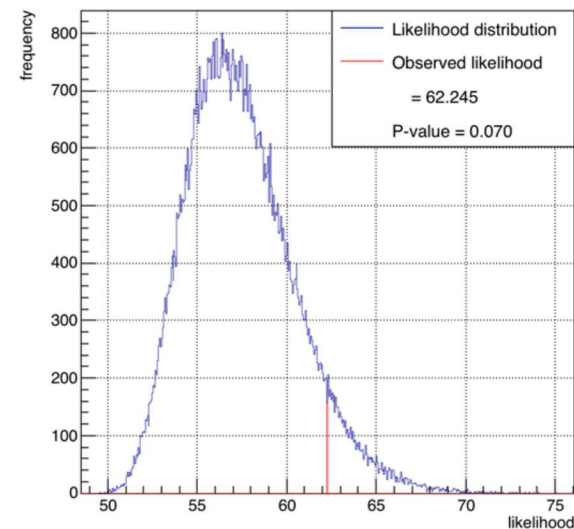
Detector Counts (det 0)



Multiplicity Distribution (Detector 0)



Likelihood Distribution (Det 0)

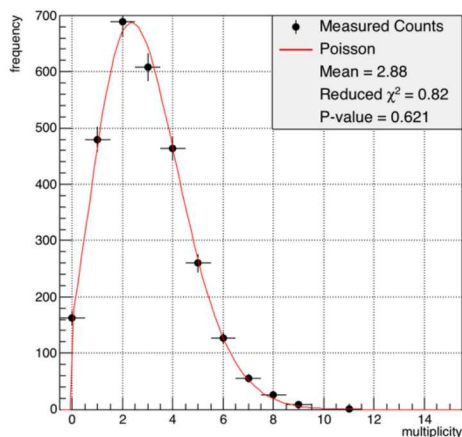


Misaligned

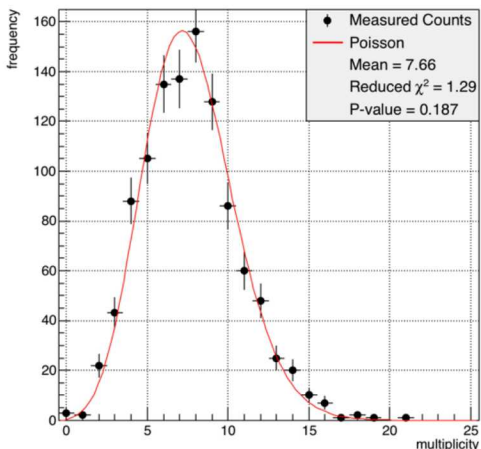
Limitations using multiplicity

Misaligned Pu hemisphere data at different “speeds”

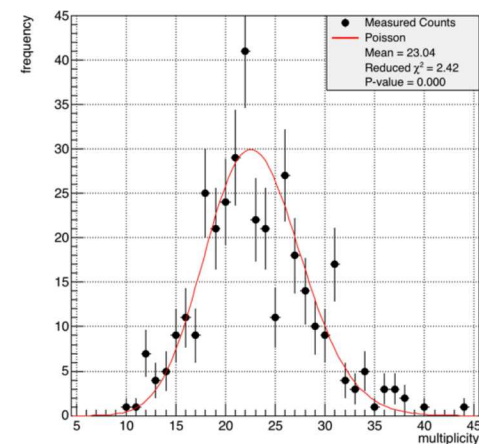
Multiplicity Distribution (Detector 0)



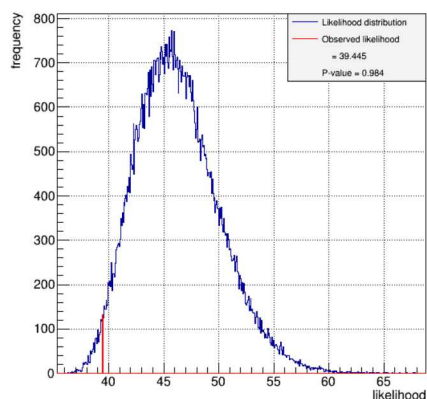
Multiplicity Distribution (Detector 0)



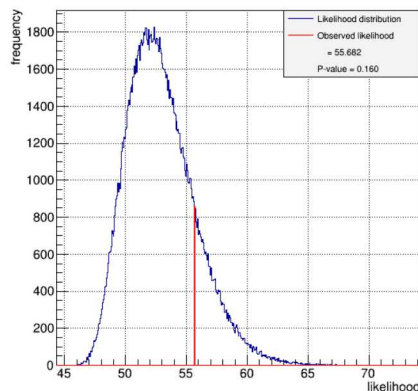
Multiplicity Distribution (Detector 0)



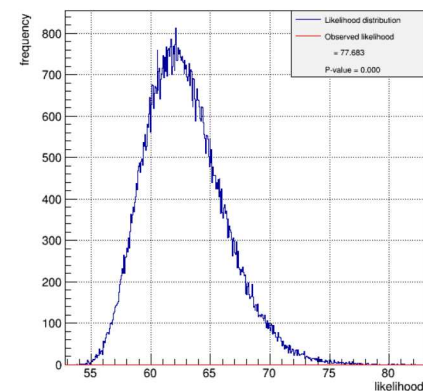
Likelihood Distribution (Det 0)



Likelihood Distribution (Det 0)



Likelihood Distribution (Det 0)



Works best with a mean higher than ~10 counts/angle, which may require a very slow rotation speed and a long total measurement time

Future work

- Optimal multiplicity system design
 - Constraints
 - Spatial resolution (angle)
 - Mean rate (rotation speed)
 - Total time
- Gamma system
 - Improves confidence to measure both gamma rays and neutrons

Disclaimer



Sandia National Laboratories

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Patricia Schuster

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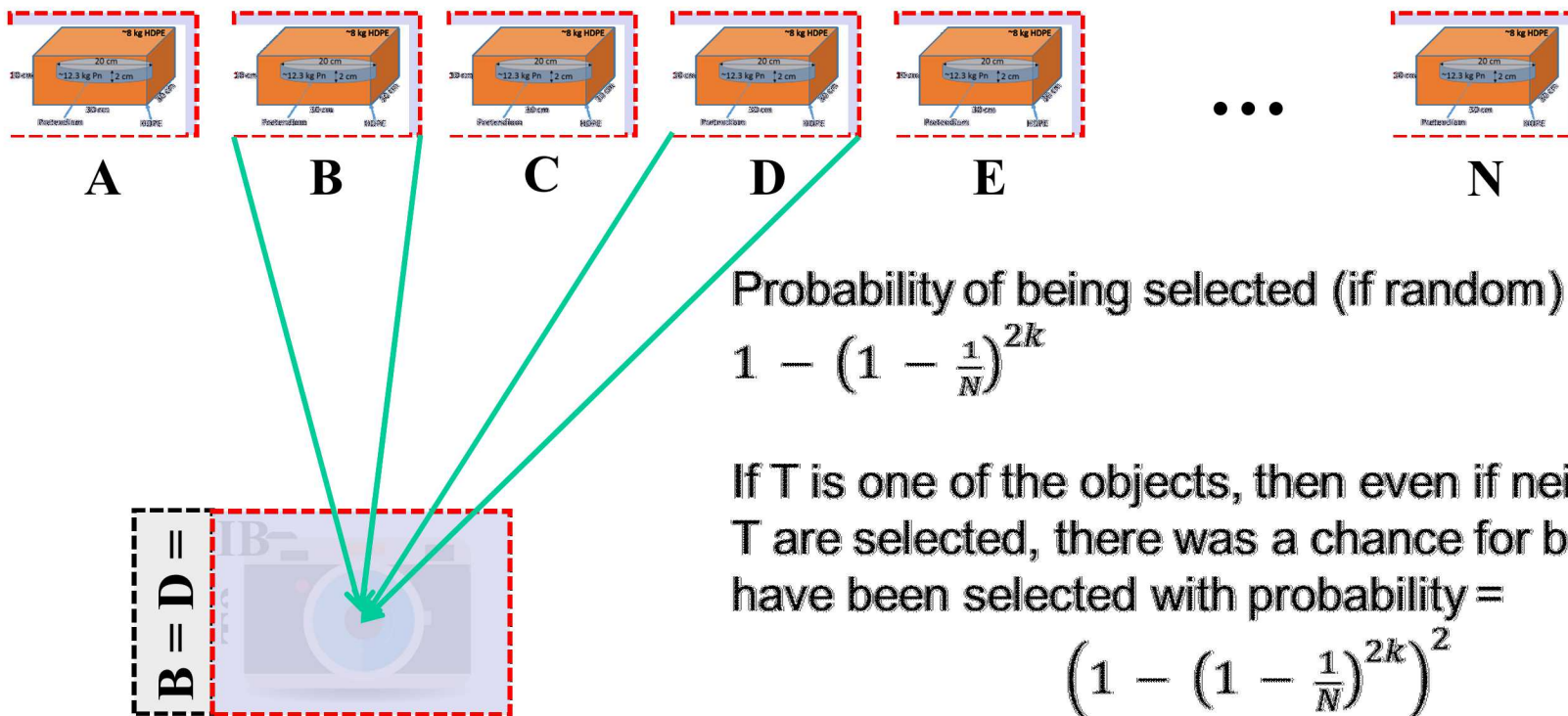
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Extra Slides

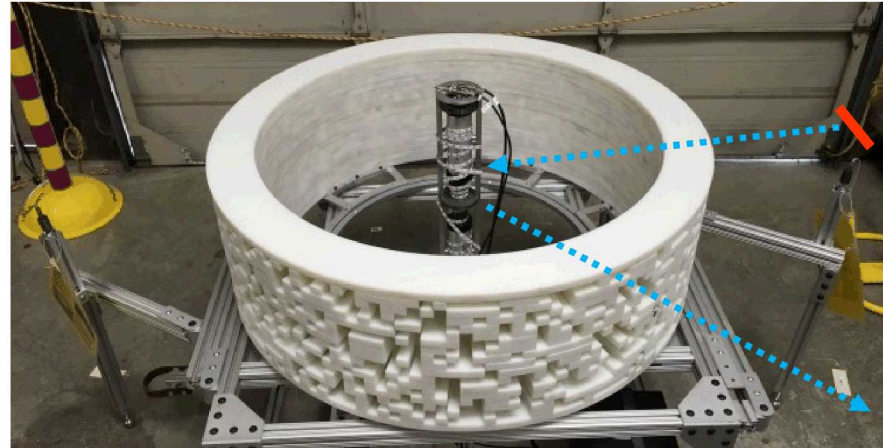
CONOPS and Inspector Choice

- The ZKP CONOPS offers an interesting way to gain authentication confidence.
- Presented with N objects and k comparison measurements will be made.

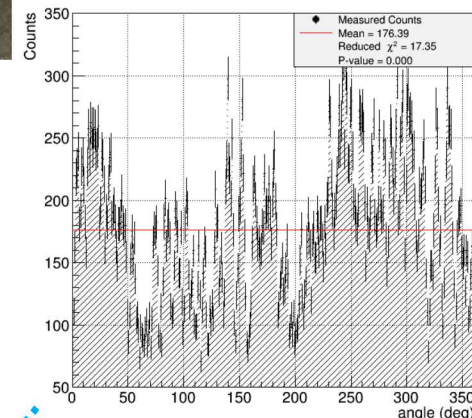


Results: Double Point Source Measurements

Measurement of a double “line” source (~20 hours)

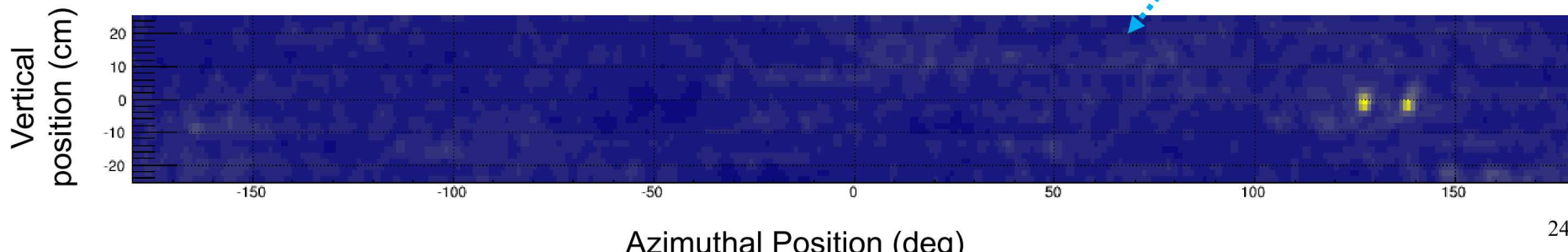


Neutron Counts



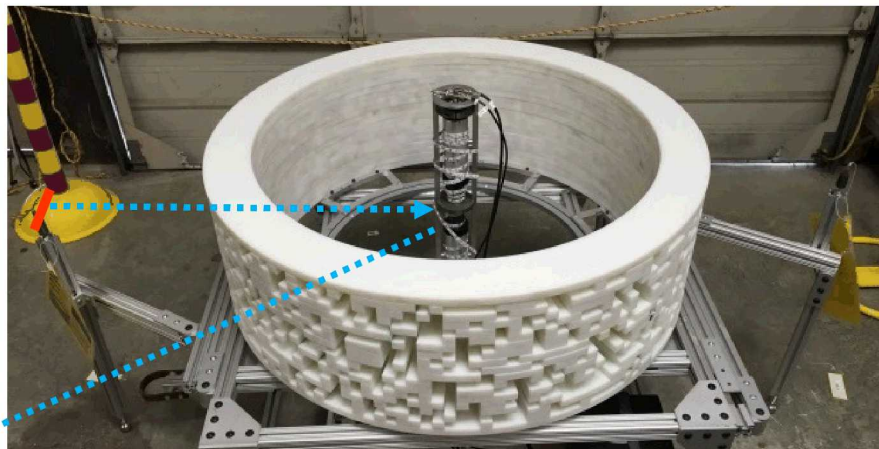
MLEM Reconstruction

Rotation Angle (deg)

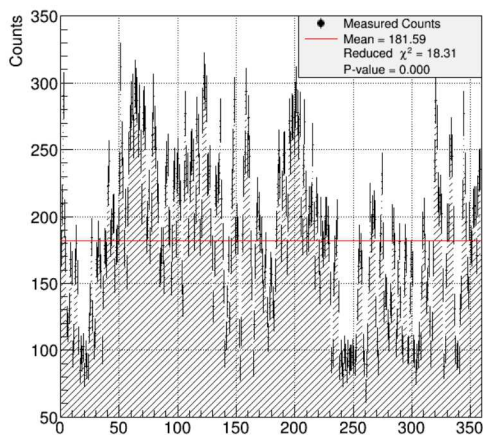


Results: Double Point Source Measurements

Measurement of a double “line” source (~20 hours)

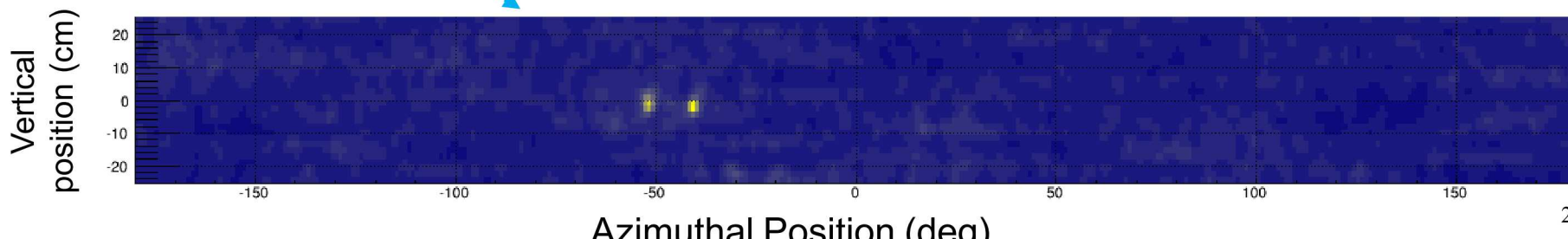


Neutron Counts



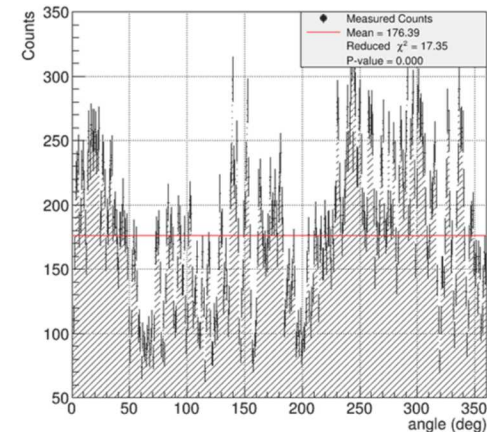
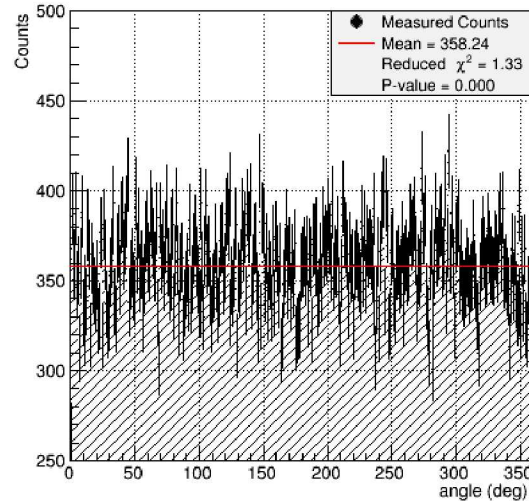
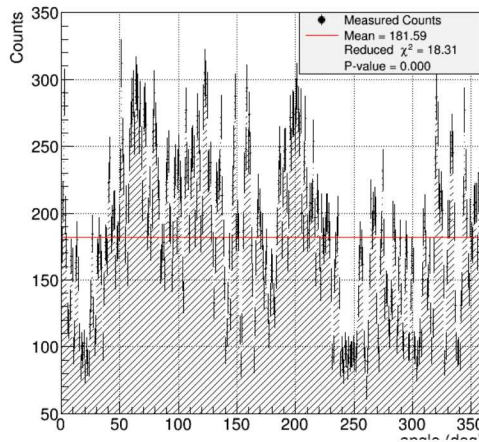
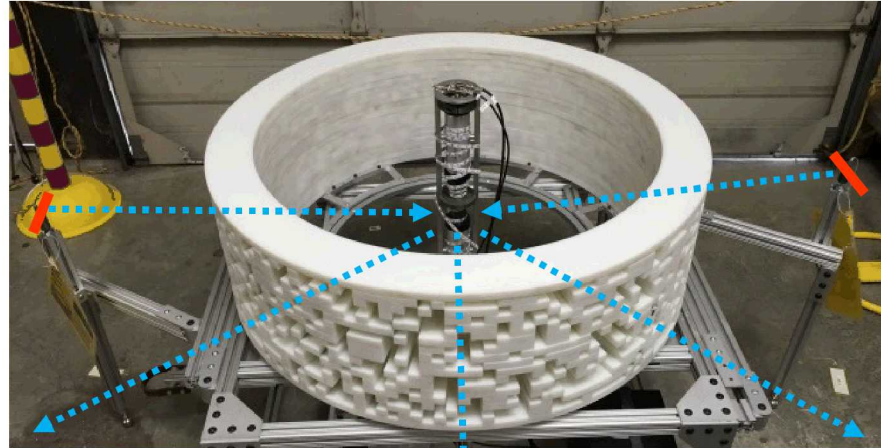
Rotation Angle (deg)

MLEM Reconstruction



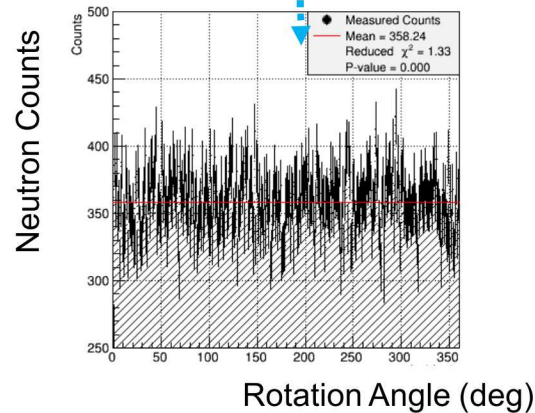
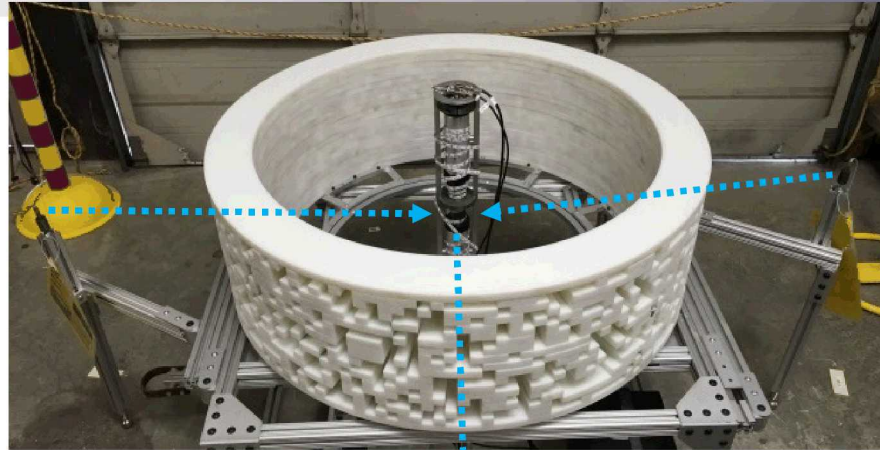
Results: Double Point Source Measurements

Measurement of
two double “line”
sources on
opposite sides
simultaneously
(~20 hours)

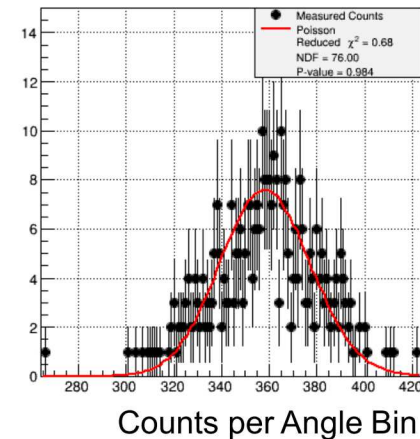


Results: Double Point Source Measurements

Measurement of two double “line” sources on opposite sides *simultaneously* (~20 hours)



Count Distribution
(Poisson – red curve)



MLEM Reconstruction

