

# Consistent + Conservative Meshfree Discretization

Nat Trask

# Compadre – Compatible Particle Discretization

## Objectives:

- Meshless schemes with rigorous approximation theory and mimetic properties like compatible mesh-based methods
- Software library supporting solution of general meshless schemes with tools for coarse+fine grain parallelism and preconditioning

## People:

- Pavel Bochev (PI)
  - “Compatible Meshless Methods” Structural Eng. Seminar
- Kara Peterson
  - “Improving the accuracy of MPM”
- Mauro Perego
  - “Approximation properties of functional reconstruction using GMLS”
- Paul Kuberry
  - “The Compadre toolkit”
- Pete Bosler
  - In Albuquerque, interested in particle discretization for climate applications

## Key tools:

- Optimization based approaches to develop meshfree discretizations with reproduction properties
- Primarily strong form discretizations, to avoid expensive quadrature

# Generalized moving least squares (GMLS)

$$\tau(u) \approx \tau^h(u)$$

$$p^* = \operatorname{argmin}_{p \in \mathbf{V}} \left( \sum_j \lambda_j(p) - \lambda_j(u) \right)^2 W(\tau, \lambda_j)$$

$$\tau^h(u) := \tau(p^*)$$

## Example:

To recover classical MLS approximation:

Target functional  $\tau_i = D^\alpha \circ \delta_{x_i}$

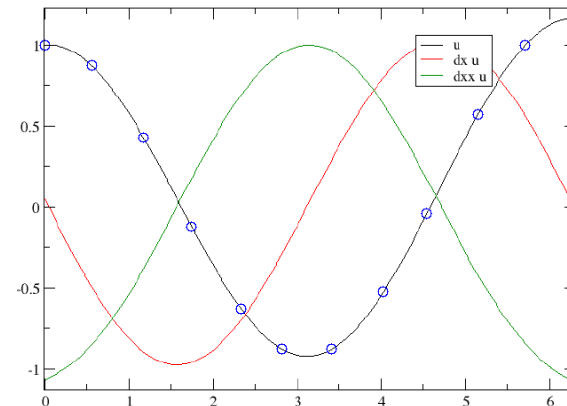
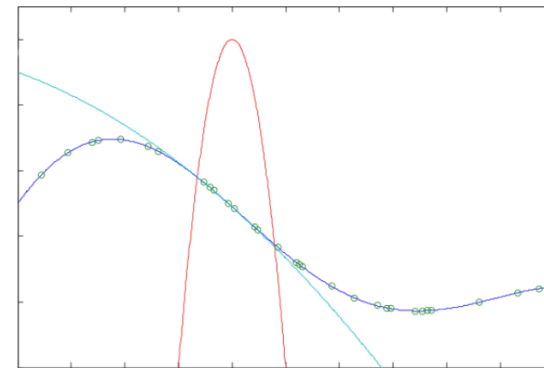
Reconstruction space  $\mathbf{V} = P^m$

Sampling functional  $\lambda_j = \delta_{x_j}$

Weighting function  $W = W(\|x_i - x_j\|)$

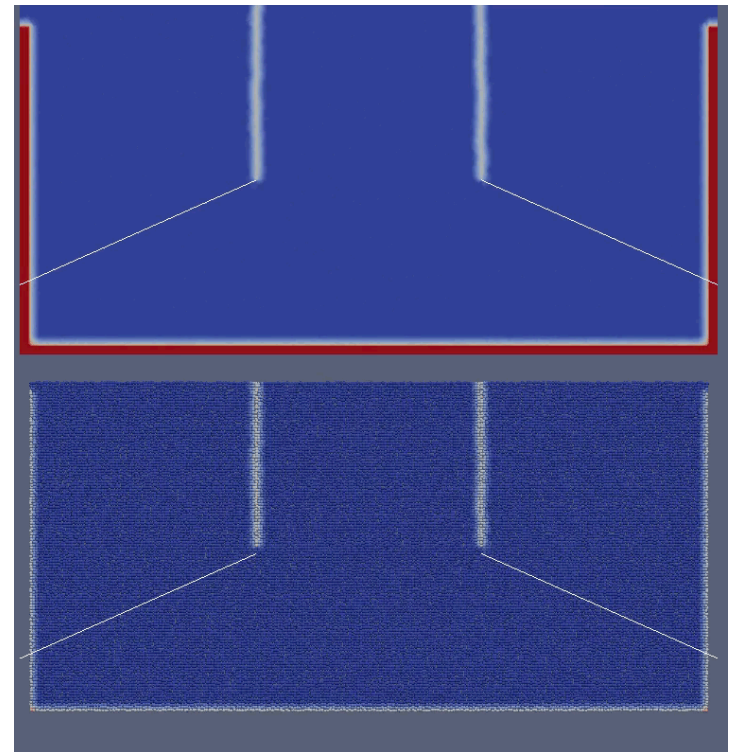
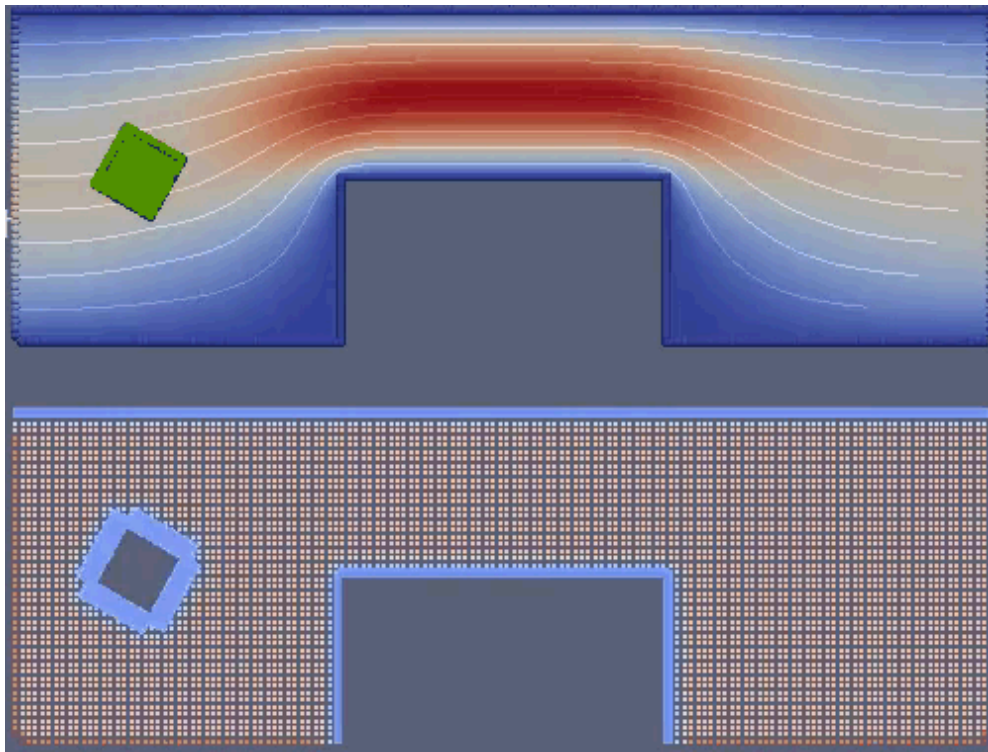
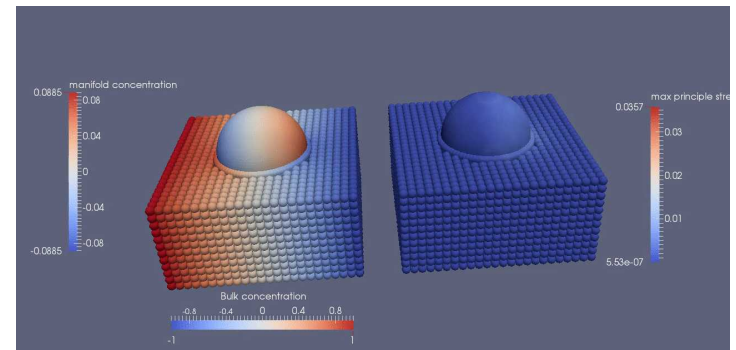
## Generalization:

Pick e.g. integral targets, div-free  $\mathbf{V}$ , etc

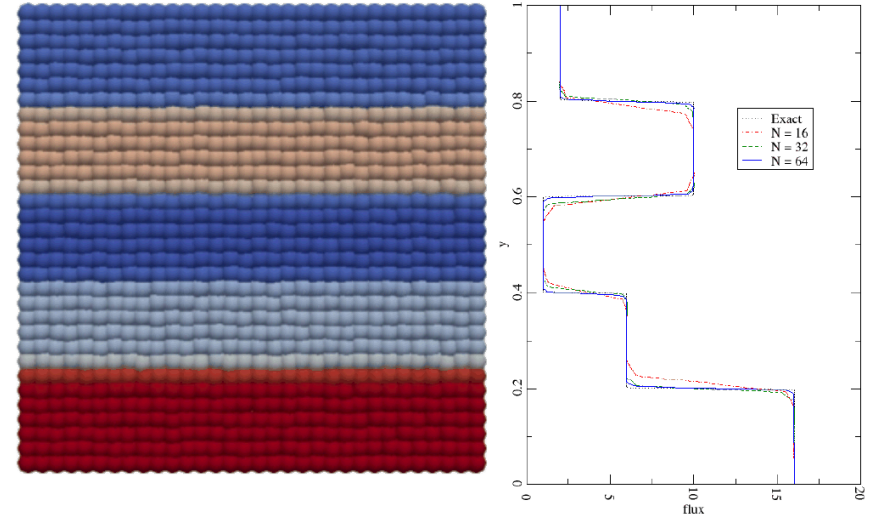
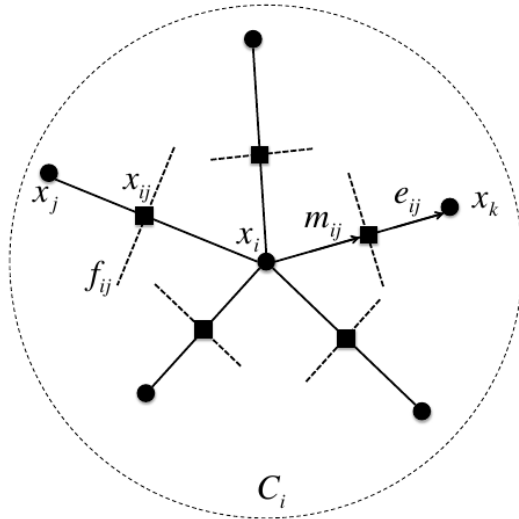


# The generalized part of GMLS

- Saddle point problems
  - div-grad, div-curl, stationary Stokes
- Surface PDE
  - Bulk-manifold coupling, deposition
- Local/Non-local mechanics
  - Asymptotically compatible discretization



# Locally compatible meshfree discretization



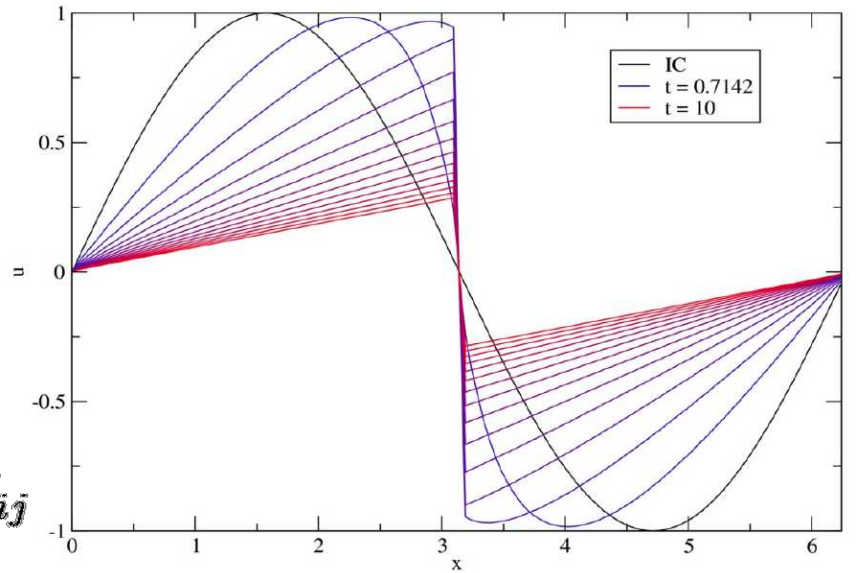
$$GRAD : V \rightarrow E$$

$$DIV : E \rightarrow V$$

$$GRAD\phi_{ij} := \int_{e_{ij}} \nabla\phi \cdot ds = \phi_j - \phi_i$$

$$DIV\mathbf{u}_i := \nabla \cdot \mathbf{p}_i$$

$$\mathbf{p}^* = \operatorname{argmin}_{\mathbf{p} \in \mathbf{V}} \sum_j \left( \int_{e_{ij}} (\mathbf{u} - \mathbf{p}) \cdot ds \right)^2 W_{ij}$$



# Objective: A globally compatible discretization

- Mesh-based physics compatible schemes are rooted in exterior calculus
- The key ingredient to these schemes is the generalized Stokes theorem (or the Gauss divergence theorem for div-grad problems)
- If we want to obtain a scheme with a discrete divergence principle, need to make sense of

$$I_c[\phi] = \int_c \phi dV$$

$$I_f[\mathbf{F}] = \int_f \mathbf{F} \cdot d\mathbf{A}$$

$$I_c[\nabla \cdot \mathbf{F}] = \sum_{f \in \partial c} I_f[\mathbf{F}]$$

↑
↑  
**3 form**
**2-forms**

**Tricky part:** Particles only naturally have 0-form DOFs  
 how do we introduce a notion of particle volume?

# Target functionals revisited: GMLS quadrature

$$\mathbf{b}^* = \operatorname{argmin}_{\mathbf{b} \in \mathbb{R}^{\dim(\mathbf{V})}} \left( \sum_j \mathbf{b}^\top \lambda_j(\mathbf{P}) - \lambda_j(u) \right)^2 W(\|x - x_j\|)$$

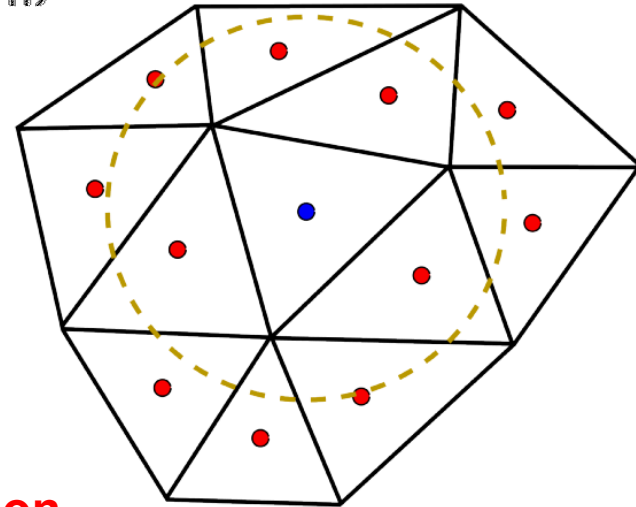
$$\mathbf{V} = \operatorname{span}(p_1, \dots, p_{\dim(\mathbf{V})})$$

$$\mathbf{P}(x) = \{p_1(x), \dots, p_{\dim(\mathbf{V})}(x)\}$$

$$\tau_h(u) = \tau(\mathbf{P})^\top \mathbf{b}^* := \mathbf{v}_\tau^\top \mathbf{b}^*$$

**metric  
information**

**function  
approximation**



$$I_c^h[\phi] := \mathbf{v}_c^\top \mathbf{b}_\phi^*$$

$$I_f^h[\mathbf{F}] := \mathbf{v}_f^\top \mathbf{b}_\mathbf{F}^*$$

$$\mathbf{v}_c^\alpha = \int_c p_\alpha dx$$

$$\mathbf{v}_f^\alpha = \int_f \mathbf{p}_\alpha \cdot d\mathbf{A}$$

$\mathbf{v}$  encodes metric information

- can we come up with a similar vector encoding **virtual particle volume**?

# Virtual particle volumes & particle quadrature

- Precompute cell moments

$$V_c^\alpha = \int_c \phi^\alpha dV$$

- Define compactly supported partition of unity mapping from cells to particles

$$\sum_p W_{pc} = 1$$

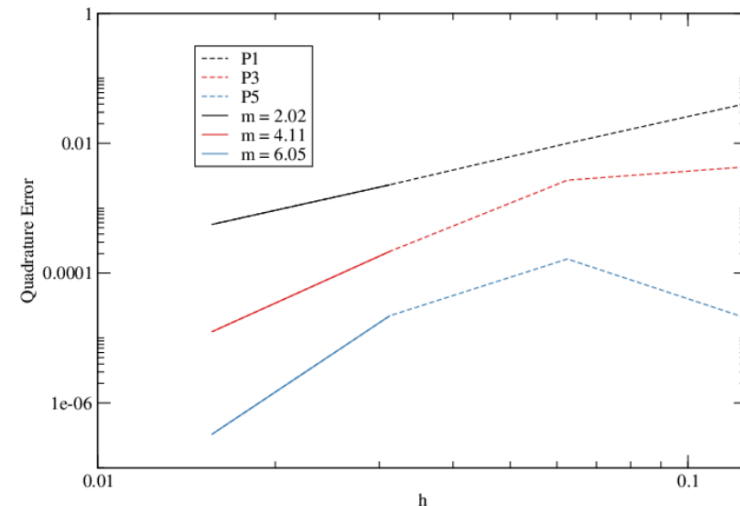
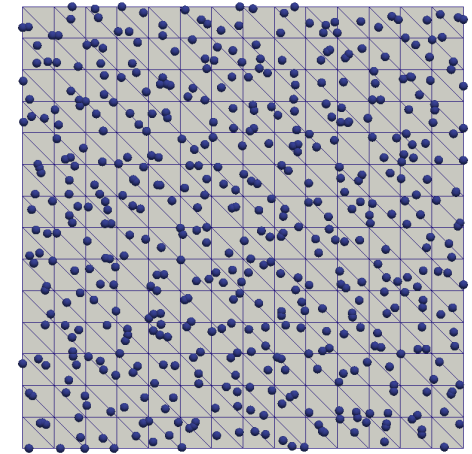
$$\|\mathbf{x}_p - \mathbf{x}_c\| < \epsilon \implies W_{pc} = 0$$

- Scatter mesh volume to particles

$$V_p^\alpha = \sum_c W_{pc} V_c^\alpha$$

$$I_p^h[\phi] := \mathbf{v}_p^\top \mathbf{b}_\phi^*$$

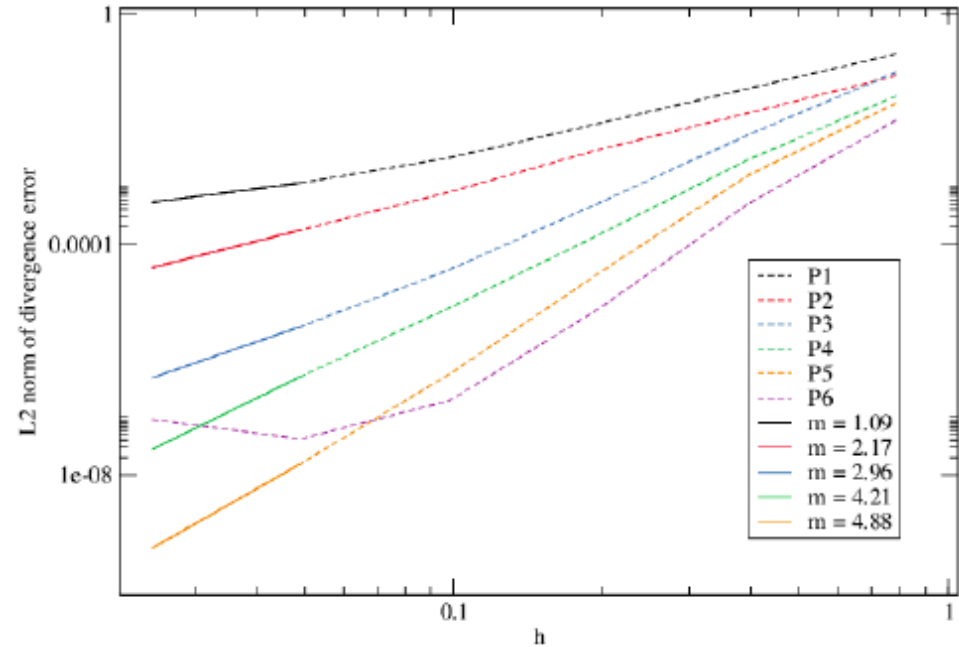
$$\sum_p I_p[\phi] = \sum_c I_c[\phi] = \int_\Omega \phi dV, \quad \forall \phi \in \mathbf{V}_h$$





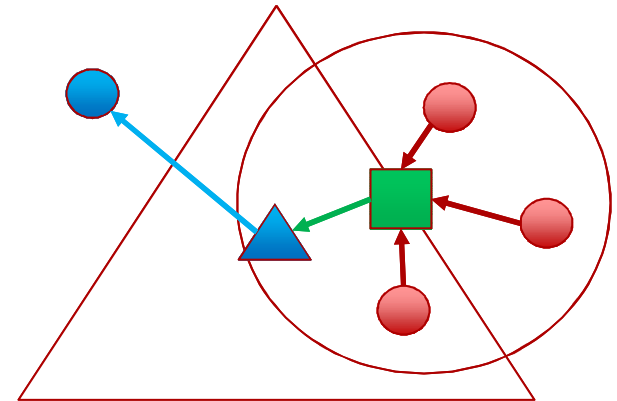
Formally...

$$\begin{aligned}
 DIV_h \mathbf{F} &= I_p[\nabla \cdot \mathbf{F}] \\
 &= \sum_c W_{pc} I_c[\nabla \cdot \mathbf{F}] \\
 &= \sum_{c, f \in \partial c} W_{pc} I_f[\mathbf{F}]
 \end{aligned}$$



To obtain point value of  $\text{div}(\mathbf{F})$  at particles:

$$\begin{aligned}
 I_p[d] &= DIV_h \mathbf{F} \\
 \mathbf{M} \vec{d} &= \mathbf{D} \vec{\mathbf{F}}
 \end{aligned}$$



# Solving a conservation law

$$\partial_t u = -\nabla \cdot \mathbf{F}$$

$$\begin{aligned} \frac{d}{dt} I_p[u] &= -I_p[\nabla \cdot \mathbf{F}] \\ &= -\sum_c W_{pc} I_c[\nabla \cdot \mathbf{F}] \\ &= -\sum_{c,f \in \partial c} W_{pc} I_f[\mathbf{F}] \end{aligned}$$

**Discrete conservation principle:**

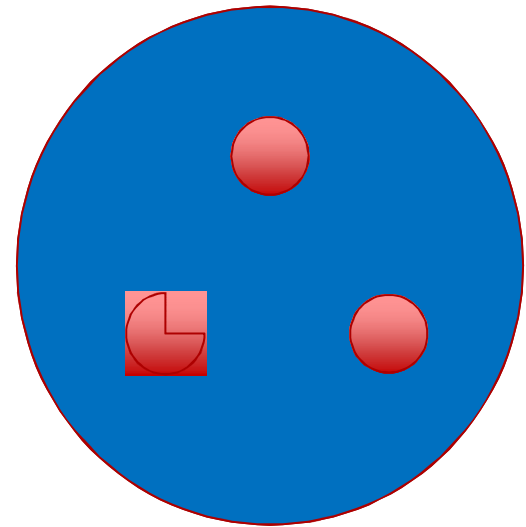
$$\begin{aligned} \frac{d}{dt} \sum_p I_p[u] &= -\sum_{p,c,f \in \partial c} W_{pc} I_f[\mathbf{F}] \\ &= \sum_{f \in \partial \Omega} \int_f \mathbf{F} \end{aligned}$$

**Example:**

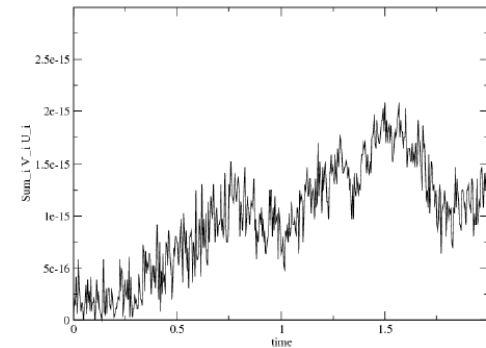
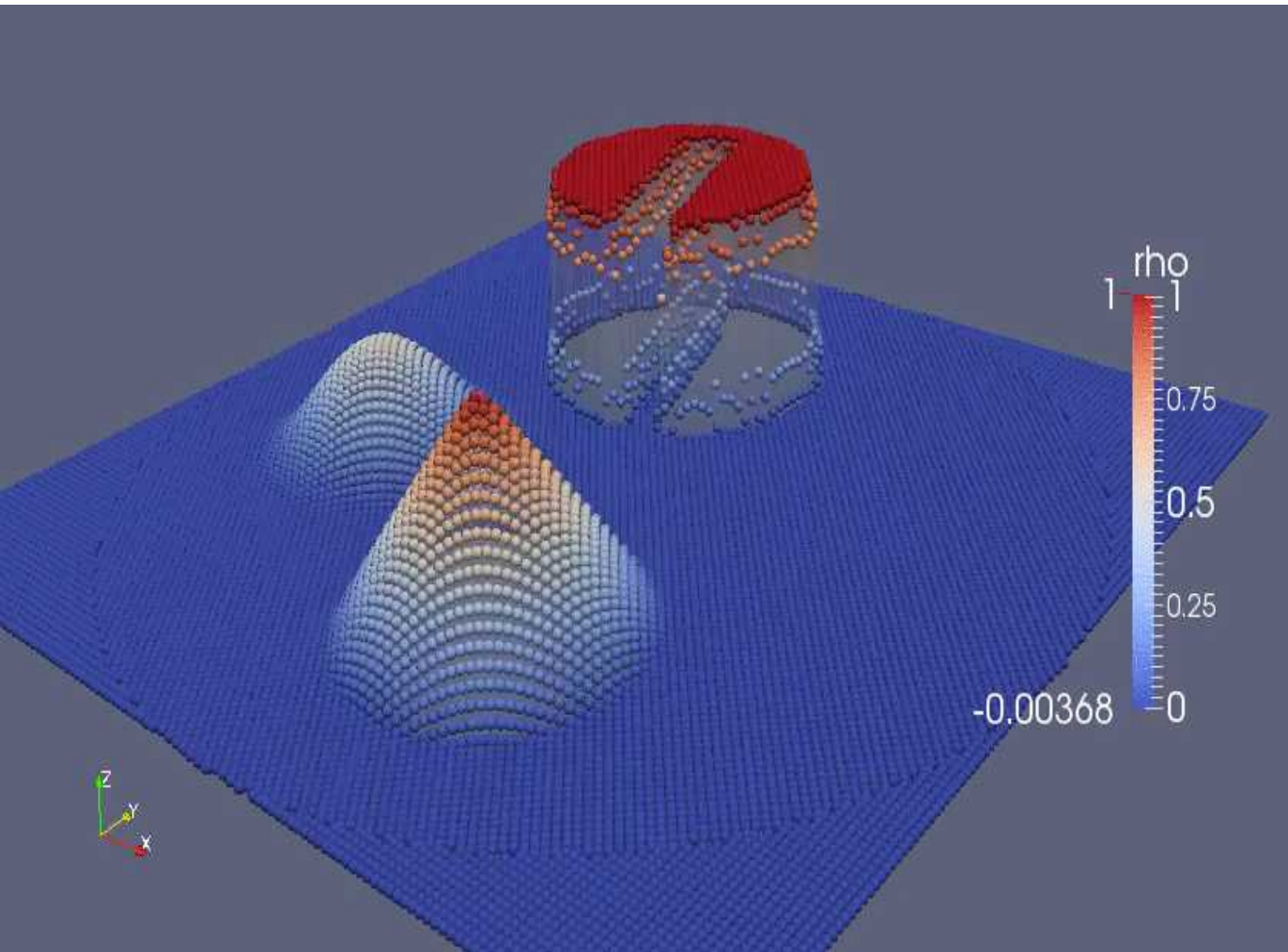
Leveques spinning disk

$$\mathbf{F} = -\mathbf{v}u$$

$$\mathbf{v} = \left\langle \frac{1}{2} - y, x - \frac{1}{2} \right\rangle$$



# Leveque's spinning disk in Lagrangian frame



**Disclaimer:**  
Careful with  
GCL

**Key Idea:**  
Preprocess  
moments on static  
mesh, scatter  
moments as  
particles move

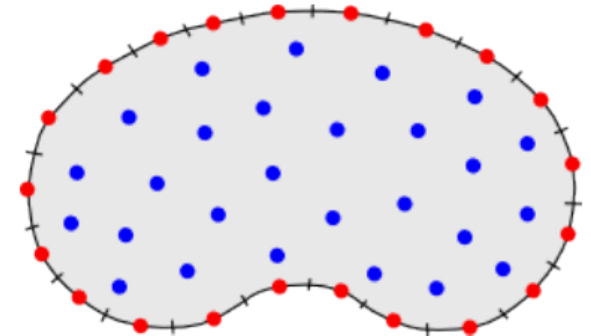
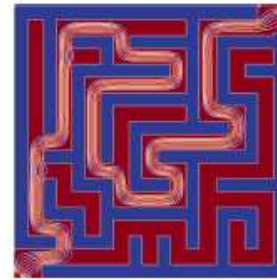
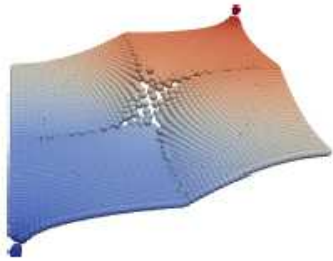
# Truly meshfree methods for conservation laws

Need metric information from somewhere

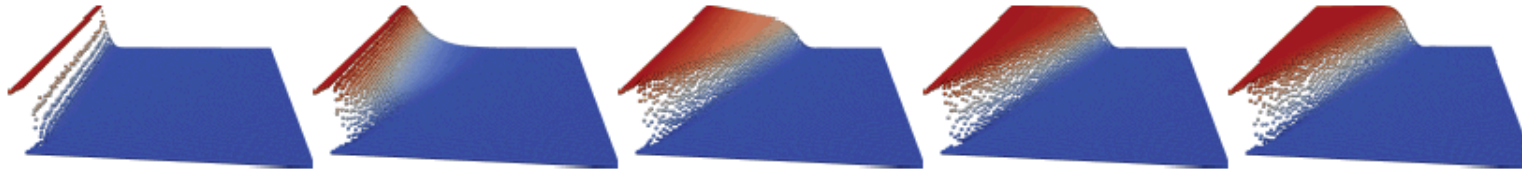
– we get it by applying some ideas from combinatorial Hodge theory

## Darcy flow

Jumps in permissivity  $\frac{\kappa_1}{\kappa_2} \in \{1, 10, 100, \infty\}$



## Singularly perturbed steady advection-diffusion



Single timestep  $Co \in \{1, 10, 100, 1000, \infty\}$  demonstrating L-stability

# Conclusions

- Some research snapshots of the discretizations + applications we're currently interested in
  - Locally compatible schemes
    - Stable solution of div-grad, curl-curl, Stokes, Darcy
  - Globally compatible schemes
    - Constructing discrete notions of conservation on point clouds
      - Hybrid particle/mesh, pure meshfree
    - Moving beyond div-grad to full de Rham complex
  - Meshfree for surface PDE
    - Using GMLS to parameterize diffeomorphism to tangent space on local patches
    - Couple bulk-manifold transport problems, topology optimization
  - Strong form discretizations of Lagrangian solid mechanics
    - Locally compatible discretizations of elastic materials
    - Discretizations of non-local mechanics for fracture problems