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A Bayesian Framework for the Estimation of Regional Methane Fluxes

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Outline

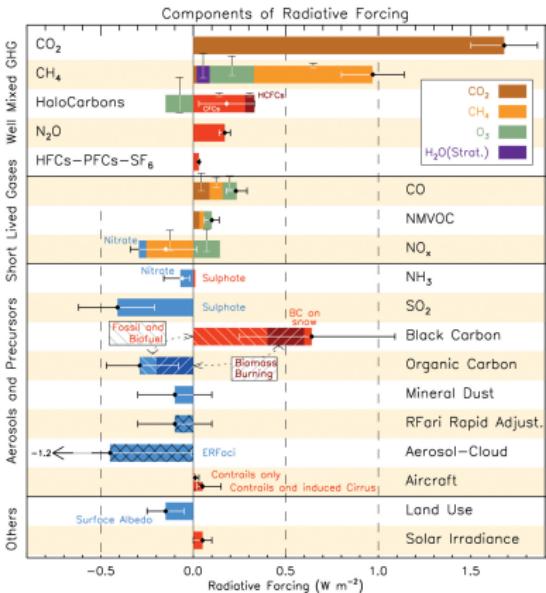
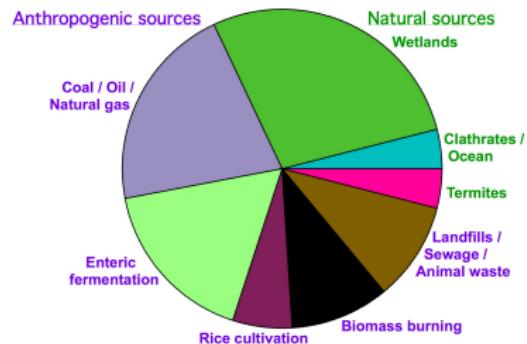
- Motivation
- Parameter Estimation Framework
 - Experimental Observations
 - Atmospheric Transport Framework (equations, discretization, assumptions)
 - Modeling the Discrepancy between Model Predictions and Experiments
- Results
- Future Work

Motivation - Methane (CH₄) Emissions

CH₄ is a significant contributor to radiative forcing

- anthropogenic sources are ~ 70% of current total
- wetlands account for ~ 25% of total emissions
- coal/oil/natural gas are ~ 30% of anthropogenic
- short atmospheric lifetime: ~ 12 yrs (>1000 years for CO₂)

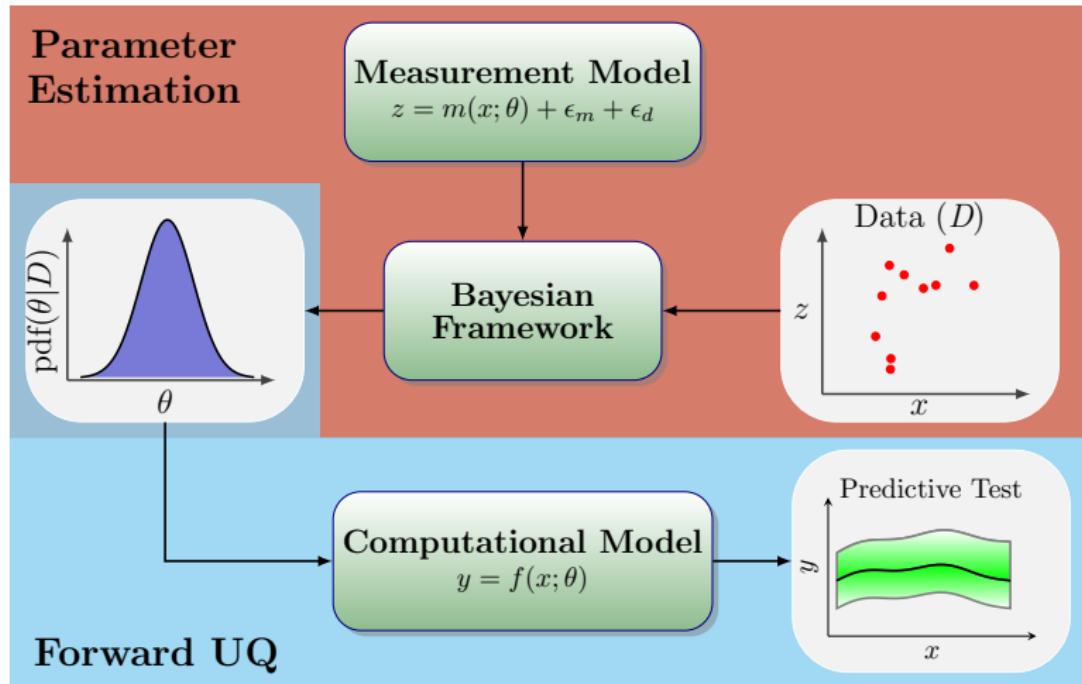
current increase in global CH₄ levels are not explained



IPCC AR5 (2013)

Slugokenky et. al. 2011 (10.1098/rsta.2010.0341)

Uncertainty Quantification in Computational Science



Bayes formula for Parameter Inference

- Data Model (fit model + noise): $z = m(x; \theta) + \epsilon$

- Collectively $D = \{z_1, z_2, \dots\}$

- Bayes Formula:

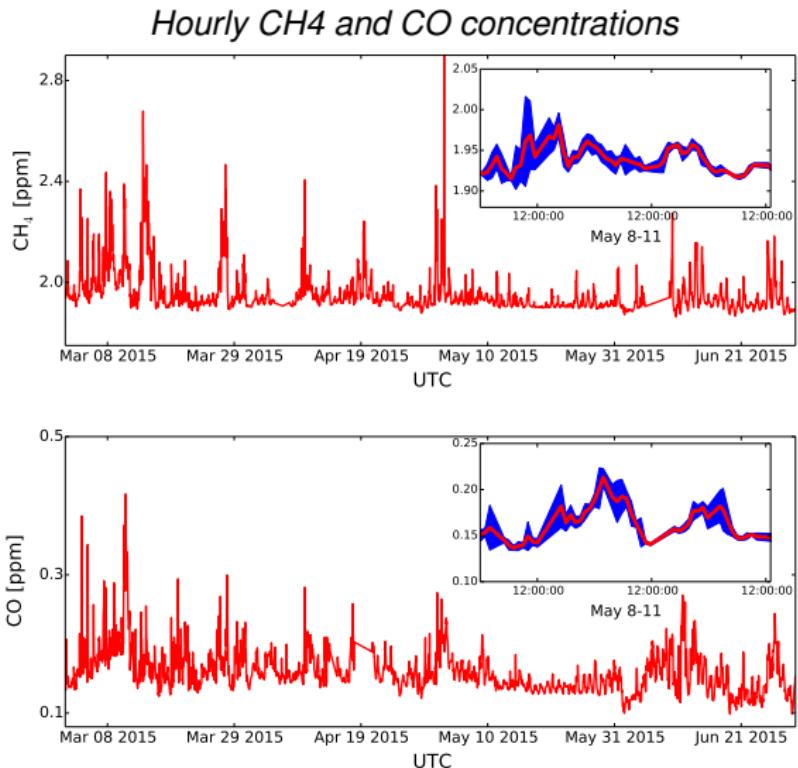
$$p(\theta, D|M) = p(\theta|D, M)p(D|M) = p(D|\theta, M)p(\theta|M)$$

$$p(\theta|D, M) = \frac{p(D|\theta, M)p(\theta|M)}{p(D|M)}$$

Posterior Likelihood Prior Evidence

- Prior: knowledge of θ prior to data
- Likelihood: forward model (M) and measurement noise
- Posterior: combines information from prior and data
- Evidence: normalizing constant, used for model comparison

Experimental Observations - Livermore, CA

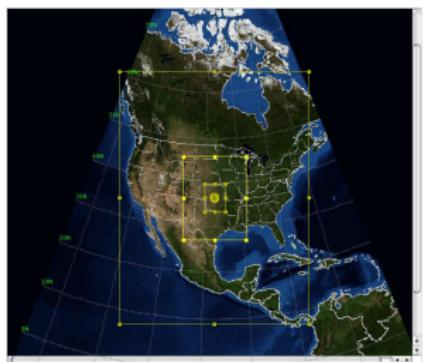


Livermore, CA: ~150m above sea level and 27m above ground level

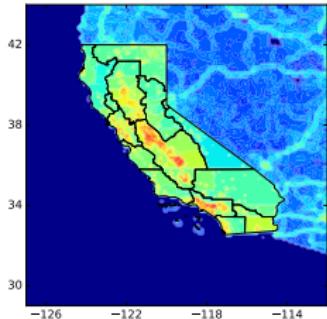
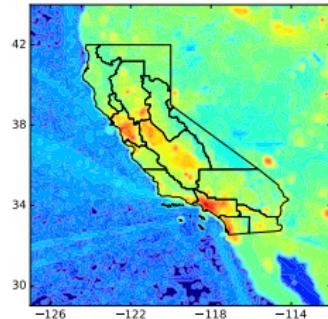


Model - Atmospheric Transport

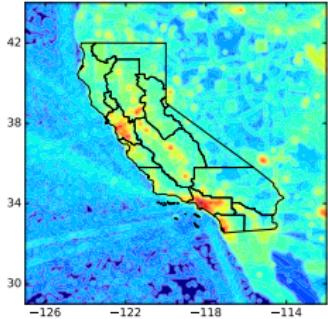
- The Weather Research & Forecasting (WRF) Model
 - transport of mass, momentum, energy
 - vertical coordinate: hydrostatic pressure - terrain following coordinate
 - parameterizations, boundary conditions (*surface fluxes*)
- Stochastic Time-Inverted Lagrangian Transport (STILT) Model
 - Lagrangian particle dispersion model
 - Derive the upstream influence region on atmospheric measurement locations



Model - Surface Fluxes

CALGEM - CH₄EDGAR - CH₄

EDGAR - CO



- Given footprint $f(x_r, t_r | x, t)$, the concentration y at receptor point (x_r, t_r) is written as

$$y(x_r, t_r) = \int_{t_0}^{t_r} \int_S f(x_r, t_r | x, t) E(x, t) dx dt + y_0(x_r, t_r)$$

- Emission databases: $E(x, t) \rightarrow E(x)$

$$y(x_r, t_r) = \int_S \left(\int_{t_0}^{t_r} f(x_r, t_r | x, t) dt \right) E(x, t) dx + y_0(x_r, t_r)$$

Model - Footprints

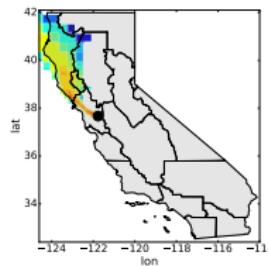
- Numerical discretization in space and time

$$\int_{t_0}^{t_r} f(x_r, t_r | x, t) dt \rightarrow \sum_i f_i(x) \rightarrow \sum_i f_{i,j}; \quad i : \text{time}, j : \text{space}$$

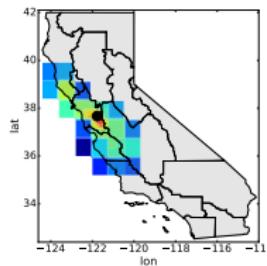
- The concentration at the measurement site

$$y = F \times E + y_0$$

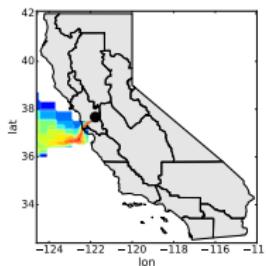
Feb 28, 2015



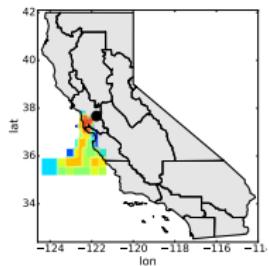
Mar 14, 2015



Apr 7, 2015



June 28, 2015



Footprints representative for Livermore, CA

Statistical Discrepancy: Model - Data

$$y = F \times E + y_0 + \underbrace{\epsilon_F + \epsilon_E}_{\text{transp, surface error}} + \underbrace{\epsilon_0}_{\text{bgrd error}} + \underbrace{\epsilon_D}_{\text{exper. error}}$$

- Hard to disambiguate between transport and surface flux error
- Simultaneously infer CH₄ and CO fluxes.
 - surface CO fluxes are well understood, leading to the combined parameter estimation problem

$$y_{CH4} = F \times E_{CH4} + y_{0,CH4} + \epsilon_F + \epsilon_{E,CH4} + \epsilon_{0,CH4} + \epsilon_{D,CH4}$$

$$y_{CO} = F \times E_{CO} + y_{0,CO} + \epsilon_F + \epsilon_{0,CO} + \epsilon_{D,CO}$$

- CO observations will inform on ϵ_F , while CH₄ will inform on both ϵ_F and $\epsilon_{E,CH4}$.

Representation of Model Error - ϵ_F & ϵ_E

Augment the footprint F and emission fluxes E with additional terms to account for model imperfections/limitations

- Global bias terms

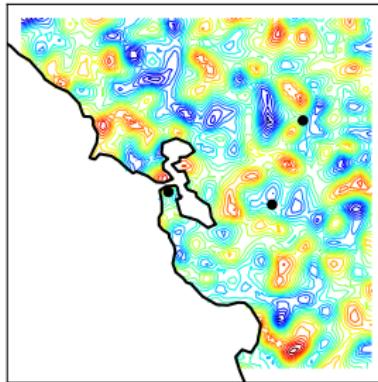
$$F \rightarrow F(1 + \lambda_F) \text{ & } E \rightarrow E(1 + \lambda_E)$$

- Region- and sector-dependent bias terms

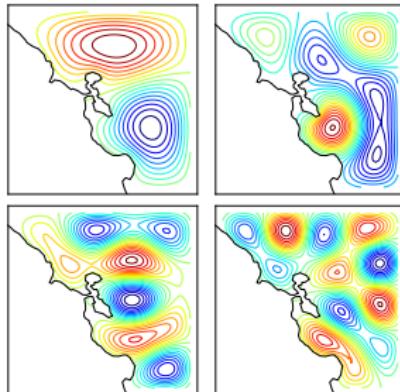
$$F_{j,k} \rightarrow F_{j,k}(1 + \lambda_{F,j,k}) \text{ & } E_{j,k} \rightarrow E_{j,k}(1 + \lambda_{E,j,k})$$

- High-dimensional bias terms, represented as random fields (RF) via Karhunen-Loeve Expansions

Gaussian RF over the Bay Area

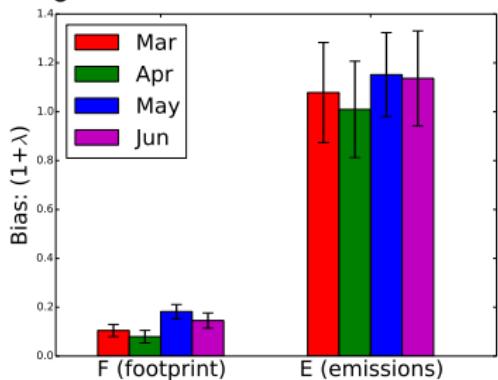


RF Modes

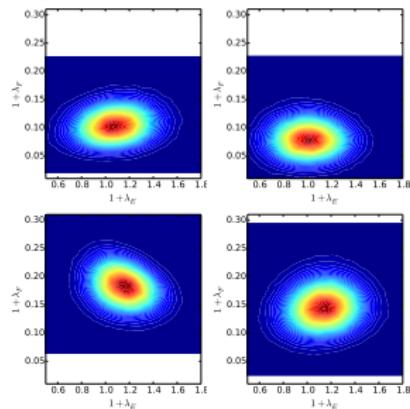


Results - Transport and Fluxes for 2015 (Mar-June)

Magnitude of bias terms for F and E



2D Marginal PDFs for 2015, March-June



- CO data induce a significant correction for the magnitude of F
 - Currently exploring ways to validate these results, possibly via additional observations of trace species
- Limited dependence between F and E - distance correlation between λ_F and λ_E are small (< 0.2)
 - Predictive studies can employ corrected F values for other species

Summary

- Assembled a framework for the assessment of biases in atmospheric transport models and emission databases
 - Multiple data streams are used to inform on different model components (transport vs boundary conditions)
 - Transport bias was significant; currently looking at other sources that can impact the results, e.g. background model.
- Moving forward to estimate corrections as random fields.
 - Determine the appropriate model parsimony using Bayesian model evidence