

Controlling qubit drift by recycling error correction syndromes

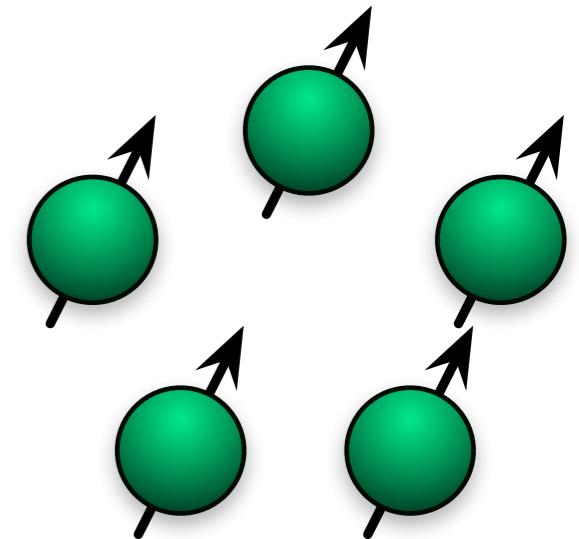
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The Situation:



You have some qubits. You'd like to do something with them. Like run a quantum circuit. Maybe error correction.

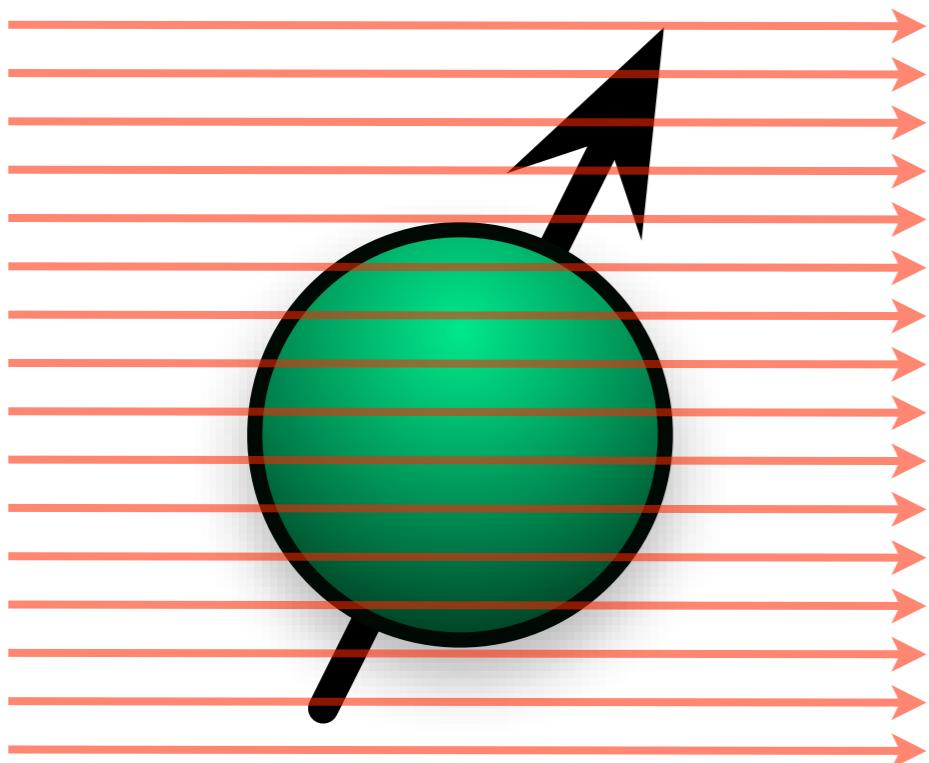
Problem 1: Your unitary gates aren't stable! Control parameters **drift** over time. Error rates rise. This is bad.

Problem 2: Dynamical decoupling (DCG) only works if your gates are *already* pretty good (need decent π pulses).

Solution: You're already doing error correction, right? Here's how to compensate drift using QEC syndrome data.

Hamiltonians drift 😞

$$\mathbf{H} = B(t)\sigma_x$$



\mathbf{H} causes errors. It is unknown *and* changes in time.

DD/DCG (dynamical decoupling) can help -- but only within limits.
If we *knew* $B(t)$, we could just compensate it away!

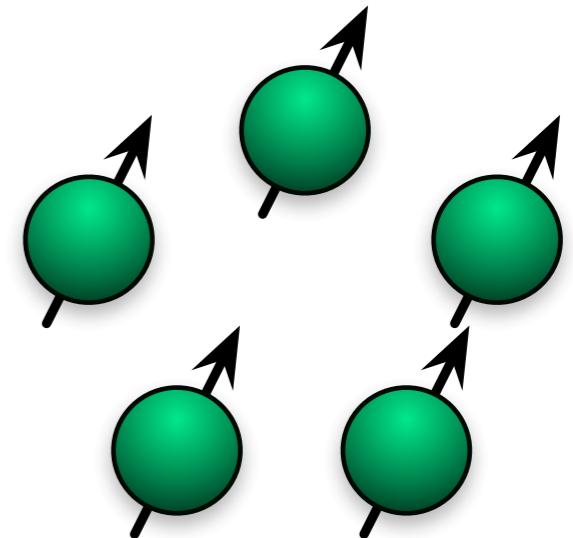
The Basic Idea

I'll assume your qubits are engaged in error correction.

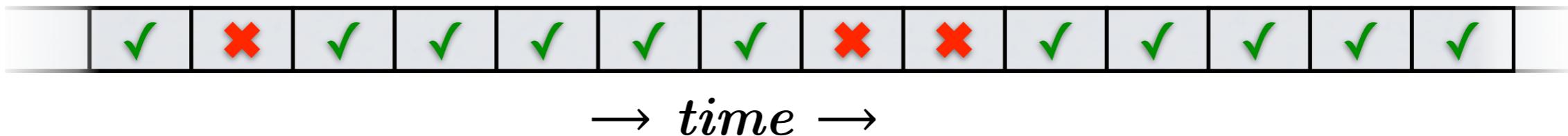
Every *cycle*, you measure stabilizers.

Result = *syndrome*.

Syndromes => what error happened.



By monitoring this stream of syndromes,
we can infer which qubits are going bad... and fix them.



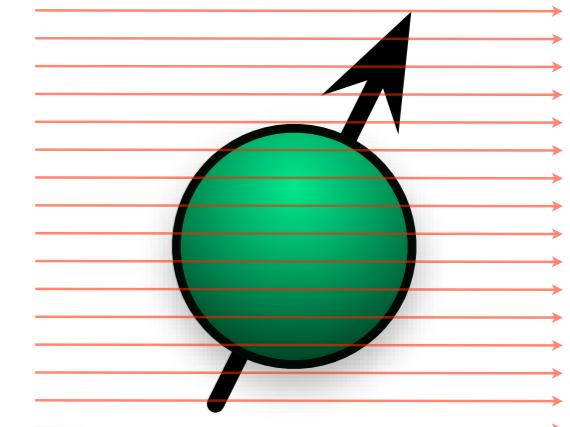
Disclaimer: all results in this talk are THEORY.

A simple example

1. One physical qubit in a [1,0,1] code.
2. Hamiltonian fluctuates as $H = B(t)\sigma_x$
where $B(t)$ = random walk.

$$\frac{d}{dt} \langle B^2 \rangle = \eta$$

3. We measure σ_z every *cycle* (Δt)
and check for *errors*.



4. The probability of an error in a cycle is:

$$P_{err} = \sin^2(\Delta\theta)$$

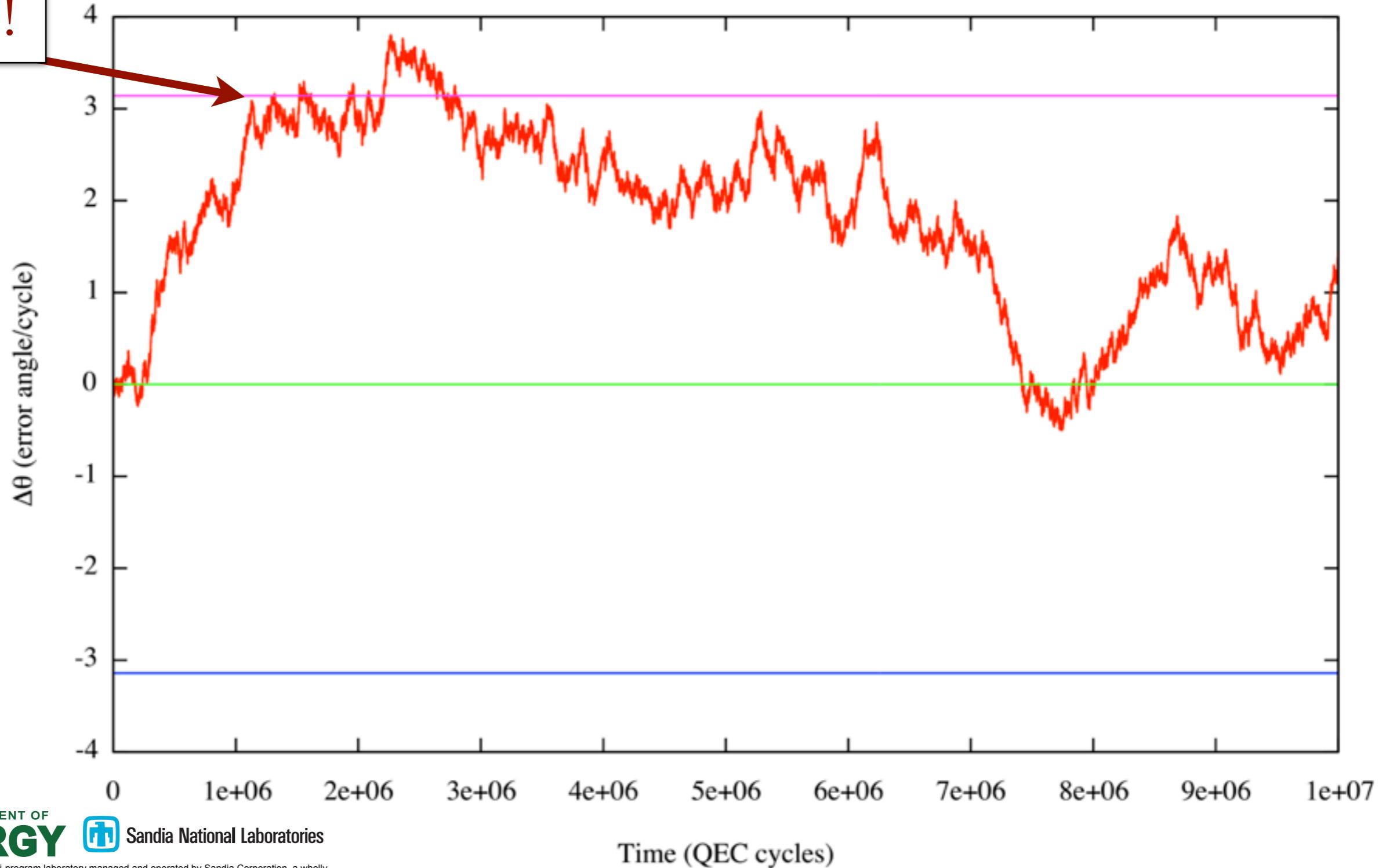
$$\Delta\theta = B(t) \cdot \Delta t$$

6. For now, assume errors are *only* caused by H .

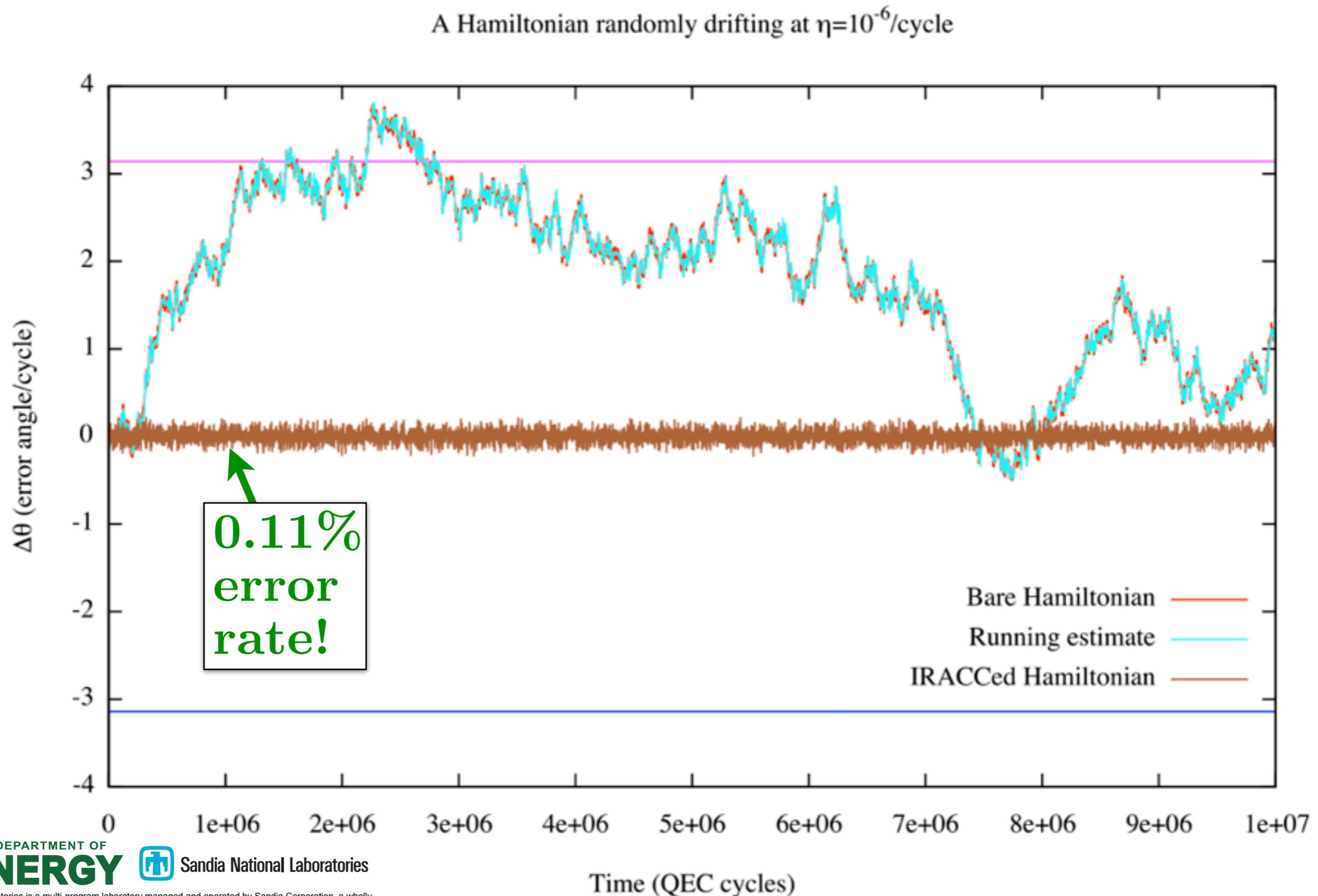
Uncompensated $B(t)$ drift

100%
error
rate!

A Hamiltonian randomly drifting at $\eta=10^{-6}/\text{cycle}$



What's left after compensation



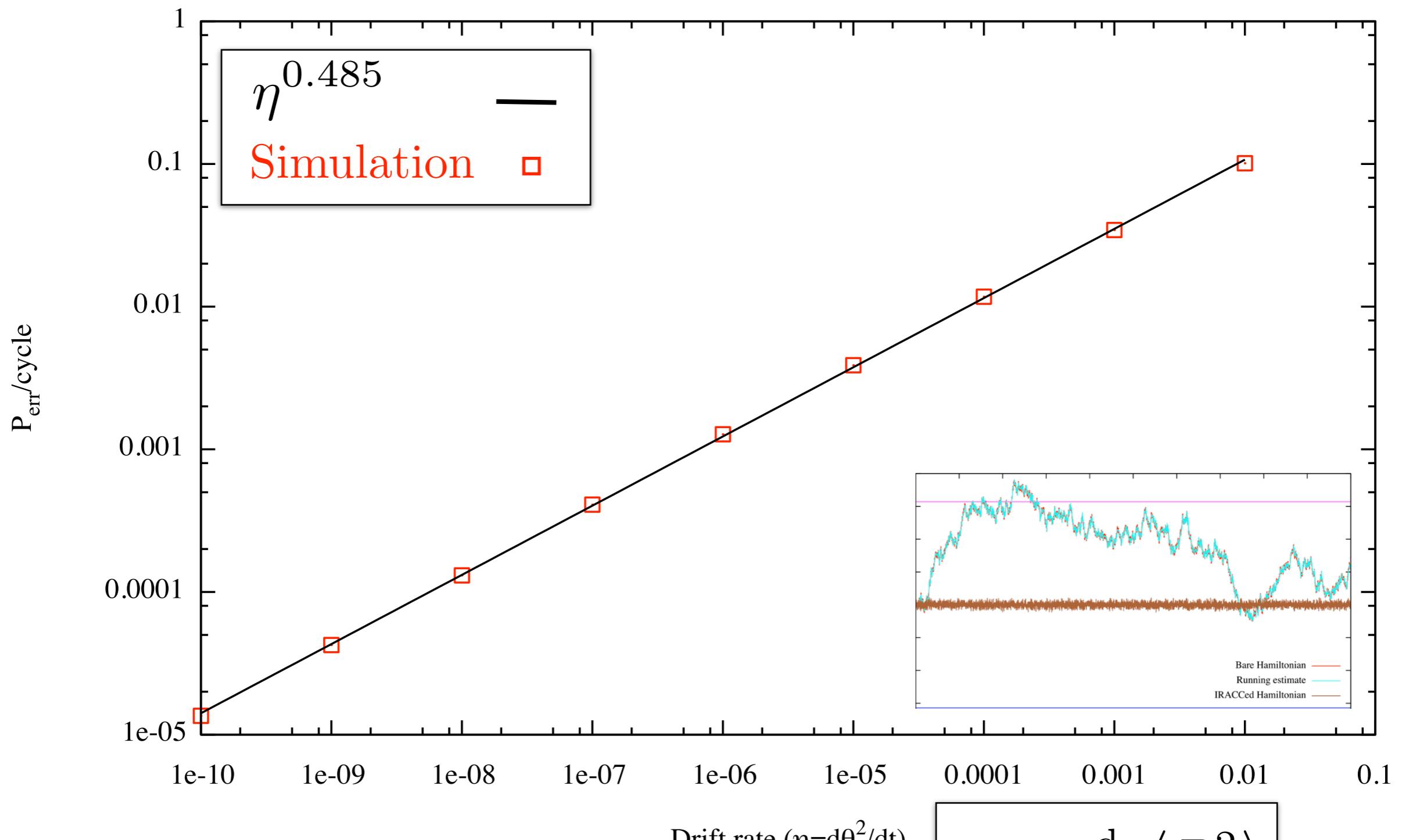
The Algorithm

1. Count cycles (T) until 1 error occurs.
2. Guess $p_{\text{err}} = \theta^2 = P/T \Rightarrow \theta = \sqrt{P/T}$.
3. Compensate by adding $\Delta H = \pm \theta / \Delta T$.
4. Next time, choose the opposite sign. GOTO 1.

Want to see how well this works?

Stabilized error rate vs η

Single-species error rate



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Okay. Monitoring syndrome measurements can stabilize drift. **But does it help QEC?**

Let's apply this to a real code. Like [5,1,3].

$$\begin{aligned} & X \otimes Z \otimes Z \otimes X \otimes I, \\ & I \otimes X \otimes Z \otimes Z \otimes X, \\ & X \otimes I \otimes X \otimes Z \otimes Z, \\ & Z \otimes X \otimes I \otimes X \otimes Z. \end{aligned}$$

1. Now we measure 4 Pauli stabilizers, & get one of 16 outcomes.
2. “0” means no error. $\{1..15\}$ indicate X/Y/Z errors on qubits 1-5.
3. So now we have to monitor 15 syndrome streams in parallel...
... and adjust 15 terms in the Hamiltonian.

Two errors in the same cycle \Rightarrow DEATH.

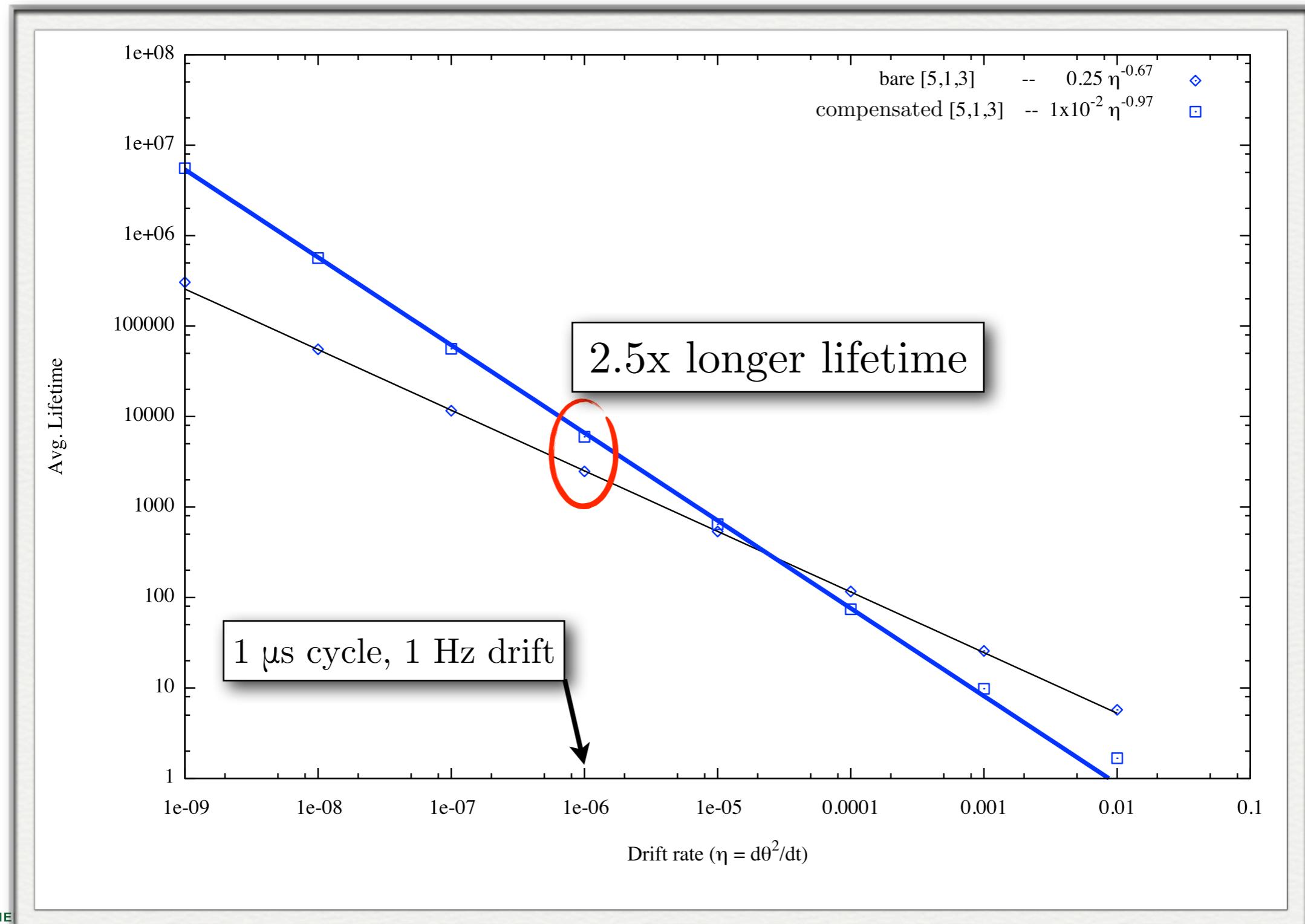
Natural metric: *expected logical qubit lifetime.*



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Drift control improves logical qubit lifetime *if* drift rate is low enough



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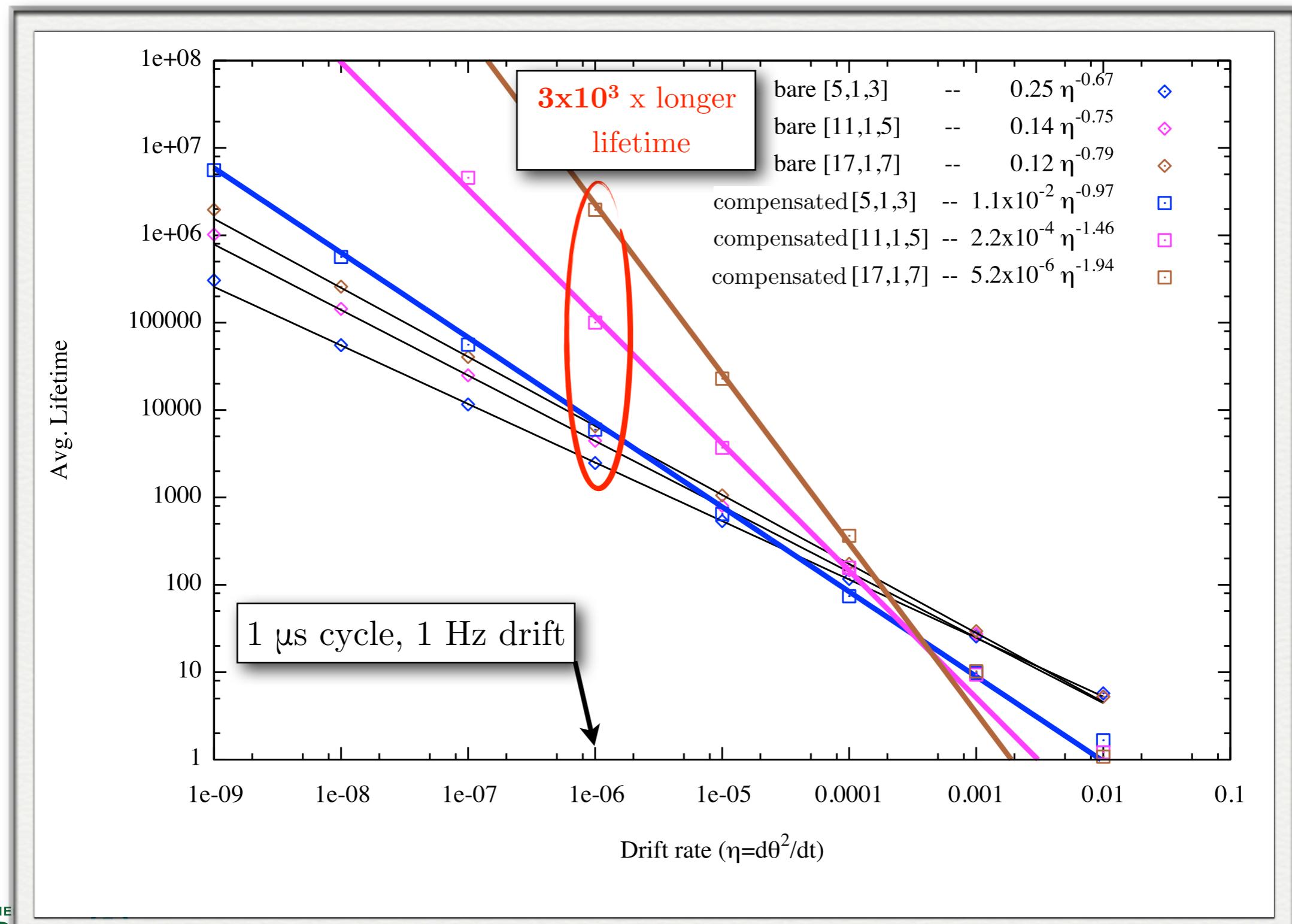
How about a bigger code?

The $[5,1,3]$ code can tolerate 1 error.

A $[11,1,5]$ code can tolerate 2 errors.

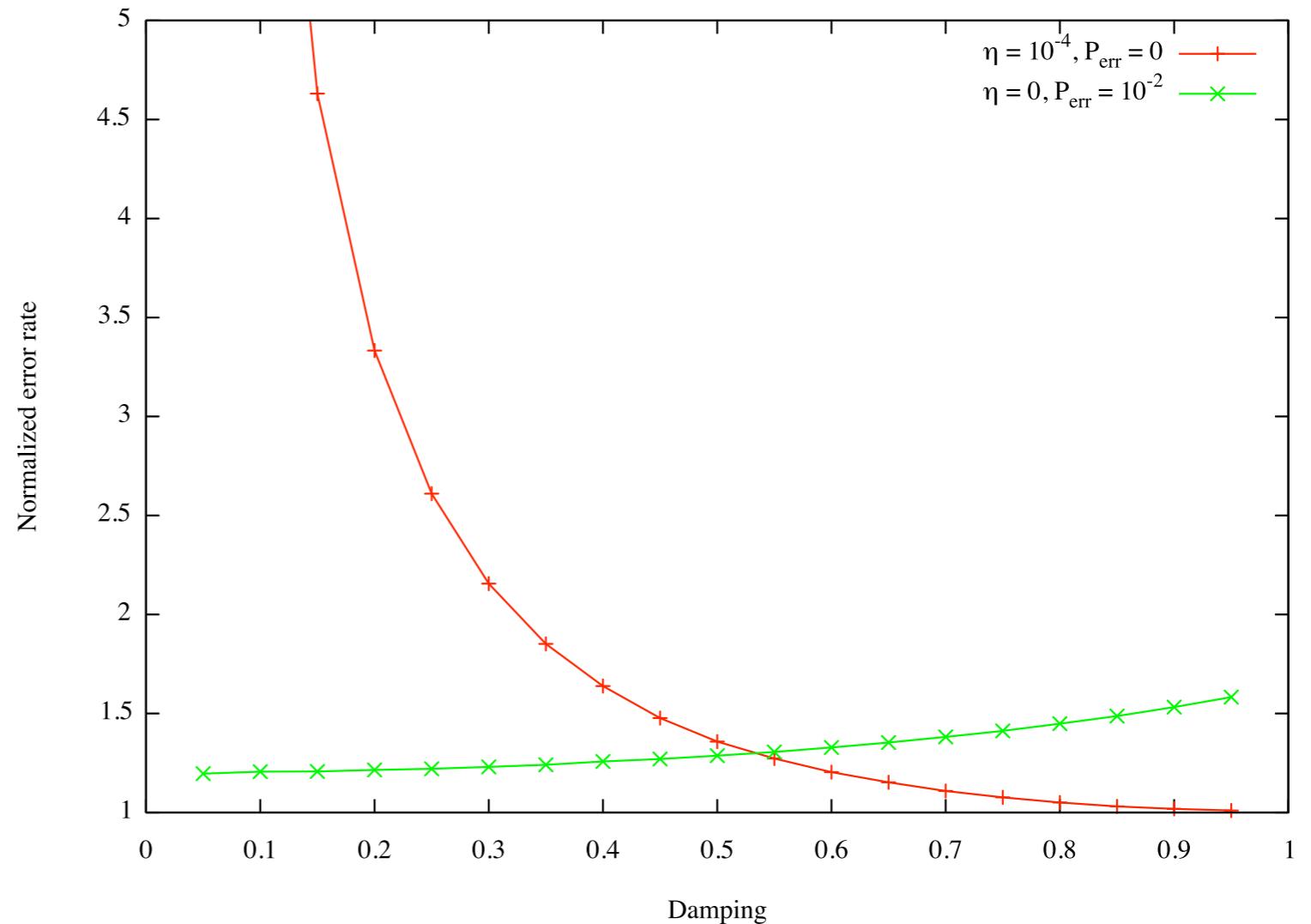
A $[17,1,7]$ code can tolerate 3 errors.

Lifetimes for [11,1,5] and [17,1,7] codes



What if there's incoherent noise?

- Stochastic noise causes errors even when $H=0$.
==> We can't tell these errors from ones caused by H !
- Easy fix:
“Damp” each adjustment by a factor ≈ 0.55 .
- Stabilized error rate is within 30% of optimal.



FAQ

Q: Wouldn't a more sophisticated algorithm do better?

A: Our protocol gets $p_{\text{err}} = \eta^{0.485}$. I can prove a lower bound of $\eta^{0.5}$.

Q: Is it fault tolerant?

A: Yes, if you ignore two consecutive errors (=failed measurement).

Q: Does it work for $1/f$ noise?

A: Sure. But $1/f$ noise is a lot whiter than Brownian drift, so there's a lot less that *anything* can do about it.

Q: What about degenerate codes?

A: Good question! We already deal with $+/$ - degeneracy in H , but truly degenerate codes are harder. It *does* work (cycle through possible errors), but this needs more research.