



Model Calibration and Forward Uncertainty Quantification for Large-Eddy Simulation of Turbulent Flows

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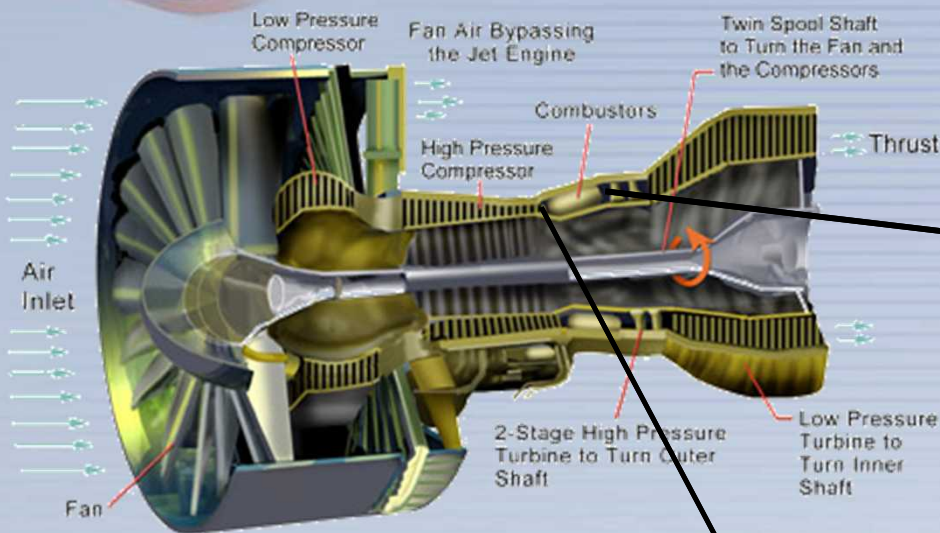
CRF Research Highlight Series

September 18, 2014

**Special thanks to: Jeremy Templeton, Cosmin Safta,
 Stefan Domino, John Hewson**



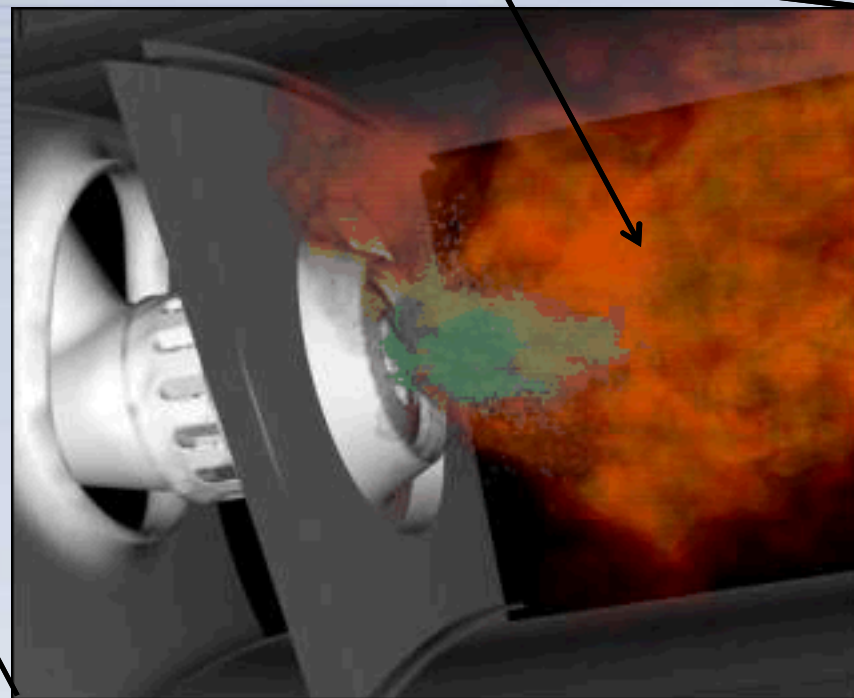
Gas Turbine Challenges



Gas Turbine Engine

Complex flow physics coupled with chemistry drives efficiency and pollutant emissions

RANS solutions and modeling strategies are inadequate given the free flow and turbulence driven by heat release



Gas Turbine Combustor Flow
Stanford ASCI Alliance Center



Motivation



Re 6600 turbulent jet using
SIERRA Fuego

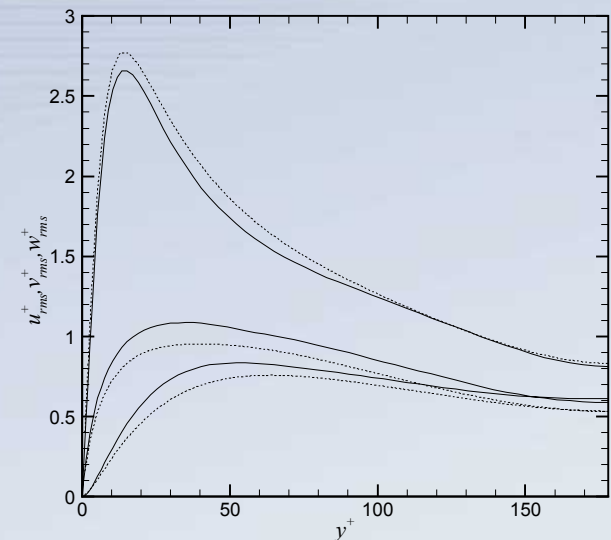
High-Fidelity LES Advantages:

- Resolves many turbulent structures
- Less dependent on model form
- Verified predictivity for combustion

Engineering LES Challenges:

- Insufficient turbulence models
Combustion models taken from RANS
- Complex interactions with mesh and models impacting mesh refinement
- Difficult to assess with UQ

Gas Turbine combustion processes offer such complexity that new approaches to enable high-fidelity calculations are needed to enable next-generation technology



Overprediction of turbulent kinetic energy,
Templeton 2006



Breath of Study

- **Cold Flow**

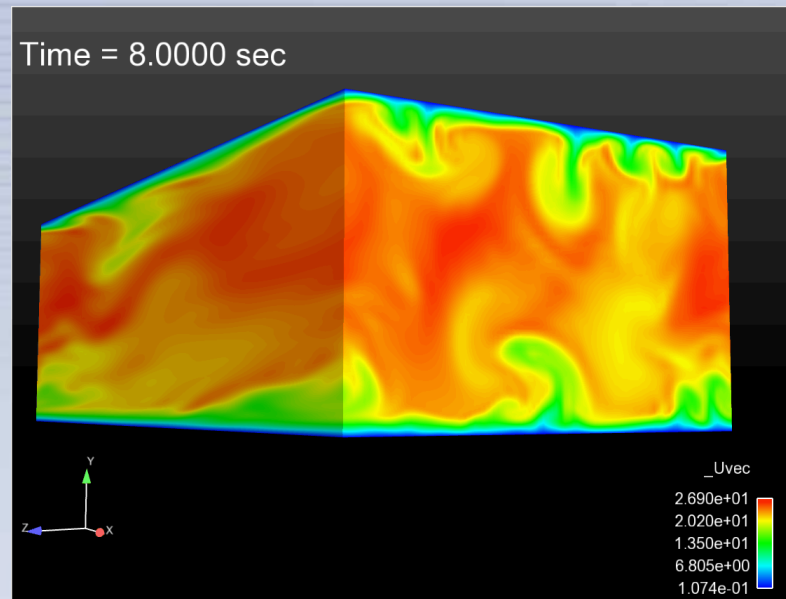
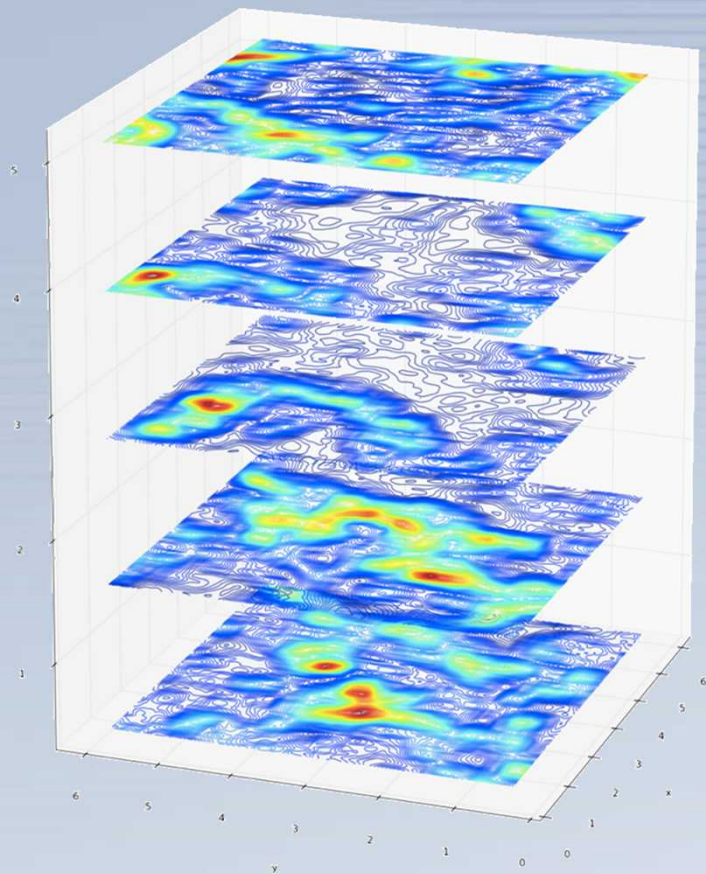
- Comparison between engineering and high-fidelity LES
- Develop UQ strategies and calibrate turbulence model parameters using channel flow
- Application: Jet-in-Crossflow
- *Developed approaches and are applying them to: k-SGS model calibration, wall-modeling, jet-in-crossflow*

- **Reacting Flow**

- Implement industrial and advanced combustion models
- Infer combustion model parameters
- UQ of reacting jet-in-crossflow and complex geometry flow
- *Currently implementing Burke-Schumann with mixture fraction table look up*



UQ of Channel Flow





Calibrate Subgrid-Scale Kinetic Energy One-Equation LES Model

Model:

$$\int \frac{\partial \bar{\rho} k^{sgs}}{\partial t} dv + \int \bar{\rho} k^{sgs} \bar{u}_j n_j dS = \int \frac{\mu_t}{\sigma_k} \frac{\partial k^{sgs}}{\partial x_j} n_j dS + \int (P_k^{sgs} - D_k^{sgs}) dv$$

Production:
$$P_k^{sgs} = \left[2\mu_t \left(\tilde{S}_{ij} - \frac{1}{3} \tilde{S}_{kk} \delta_{ij} \right) - \frac{2}{3} \bar{\rho} k^{sgs} \delta_{ij} \right] \frac{\partial \tilde{u}_i}{\partial x_j}$$

$$\mu_t = C_{\mu\epsilon} \Delta \sqrt{k^{sgs}}$$

Dissipation:
$$D_k^{sgs} = C_\epsilon \frac{\sqrt{(k^{sgs})^3}}{\Delta}$$

Calibrate: C_ϵ and $C_{\mu\epsilon}$



Bayesian Calibration

Bayes formula:

$$P(\theta|D) = \frac{P(D|\theta)P(\theta)}{P(D)}$$

Diagram illustrating the Bayes formula with labels and arrows:

- likelihood**: points to $P(D|\theta)$
- prior**: points to $P(\theta)$
- evidence**: points to $P(D)$
- posterior**: points to $P(\theta|D)$

- Data D based on DNS of Isotropic Turbulence
- Model parameters θ are the k^{sgs} model constants
- The **prior distribution** $P(\theta)$ is set to MVN with diagonal covariance, centered around the current nominal values for θ .
- The **likelihood** $P(D|\theta)$ is assumes a Gaussian discrepancy between the data and the model
- The **posterior distribution** $P(\theta|D)$ is sampled via and adaptive Markov

Chain Monte Carlo algorithm



Data

Bayes formula:

$$P(\theta|D) = \frac{P(D|\theta)P(\theta)}{P(D)}$$

Diagram illustrating the components of Bayes' formula:

- likelihood**: Points to $P(D|\theta)$
- prior**: Points to $P(\theta)$
- evidence**: Points to $P(D)$
- posterior**: Points to $P(\theta|D)$

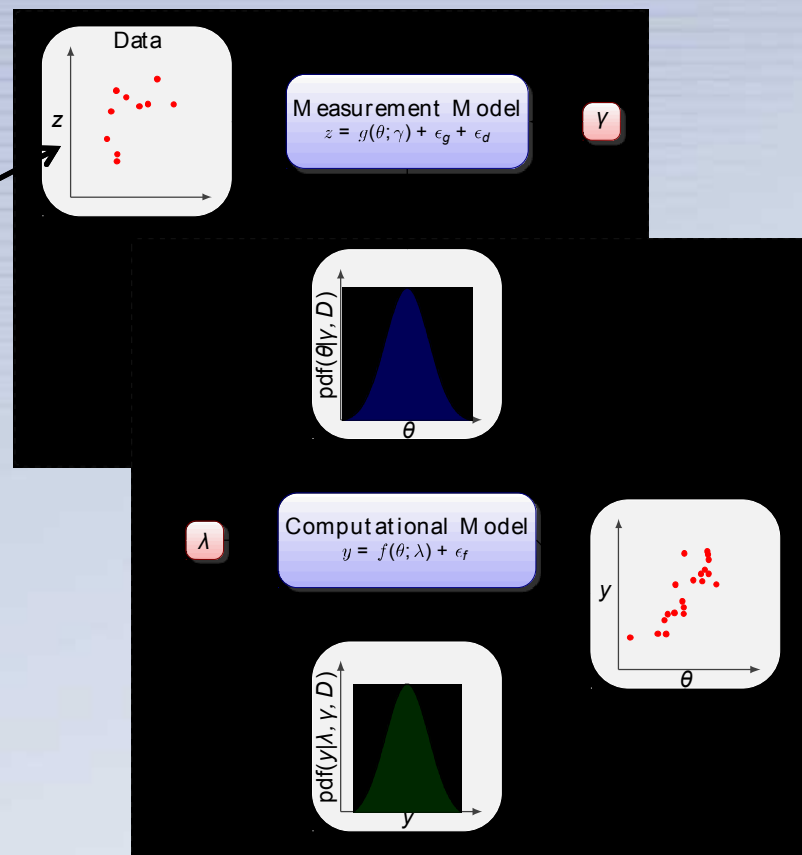
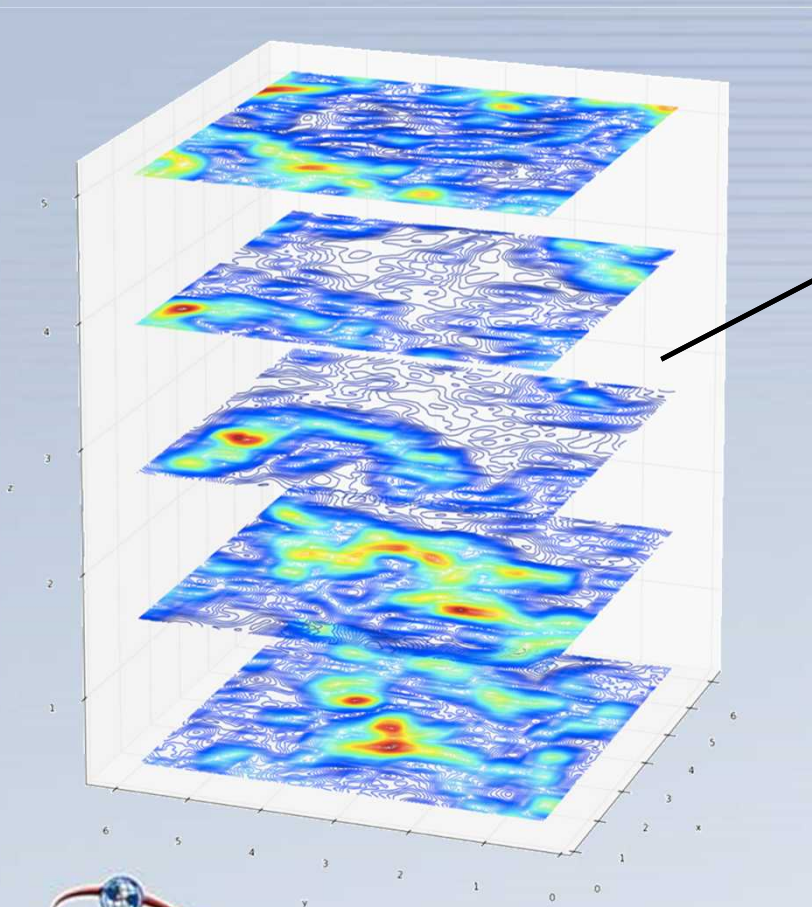
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- Model parameters θ are the k^{sgs} model constants
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DNS-Informed Calibration

Filtered DNS k^{sgs} (JHU)



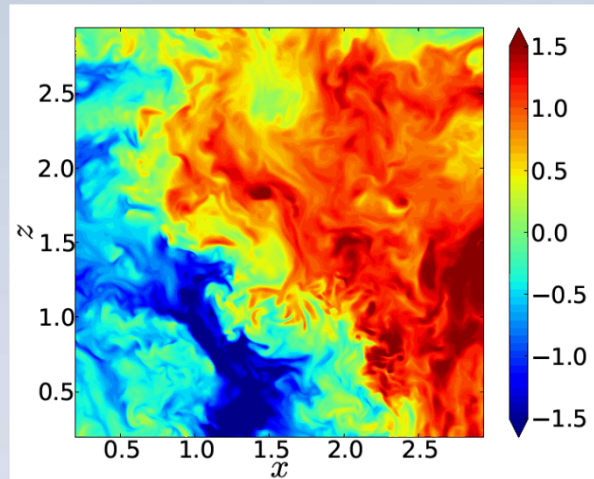
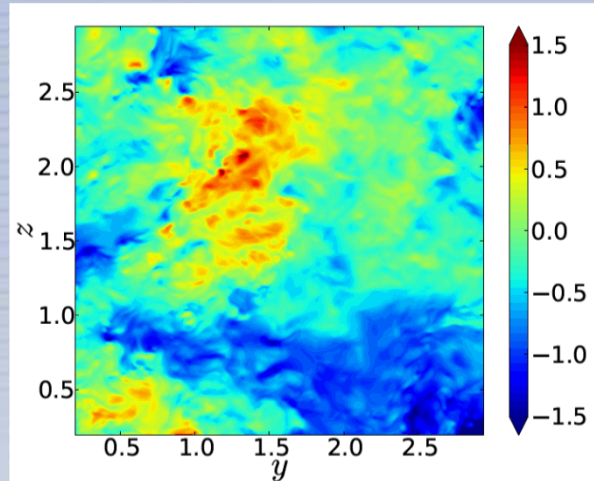


Data is Filtered DNS to LES scale

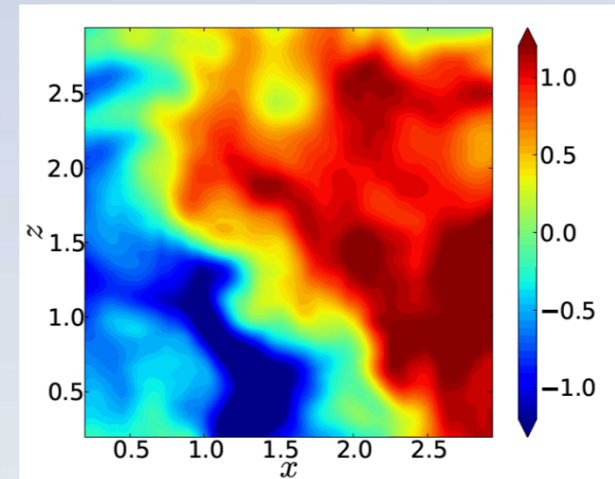
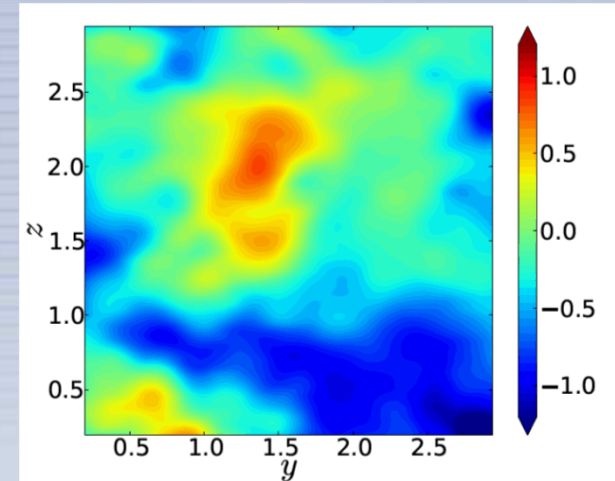
3 Filter sizes:

- $\Delta = L/64$
- $\Delta = L/32$
- $\Delta = L/16$

DNS



$\Delta = L/32$





Bayesian Calibration: Likelihood

Bayes formula:

$$P(\theta|D) = \frac{P(D|\theta)P(\theta)}{P(D)}$$

Diagram illustrating the Bayes formula with labels and arrows:

- likelihood**: Points to $P(D|\theta)$ (circled in red).
- prior**: Points to $P(\theta)$.
- evidence**: Points to $P(D)$.
- posterior**: Points to $P(\theta|D)$.

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Chain Monte Carlo algorithm



Likelihood

- **Classical Approach**

$$f_k(t; \Delta) = C_{\mu_\epsilon} f_P(t; \Delta) - C_\epsilon f_D(t; \Delta) + \epsilon_m + \epsilon_d.$$

$$L_{\mathcal{D}}(\theta) = \prod_{i=1}^{N_t} \frac{1}{\sqrt{2\pi}\sigma_i} \exp \left(-\frac{(f_{k,i} - C_{\mu_\epsilon} f_{P,i} + C_\epsilon f_{D,i})^2}{2\sigma_i^2} \right)$$

- **Embedded Error (K. Sargsyan, H.N. Najm, and R. Ghanem - 2014)**



Bayesian Calibration: Prior

Bayes formula:

$$P(\theta|D) = \frac{P(D|\theta)P(\theta)}{P(D)}$$

Diagram illustrating the Bayes formula with labels and arrows:

- likelihood** points to $P(D|\theta)$
- prior** (circled in red) points to $P(\theta)$
- evidence** points to $P(D)$
- posterior** points to $P(\theta|D)$

- Data D based on DNS of Isotropic Turbulence
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Chain Monte Carlo algorithm



Independent Gaussian Priors

- Centered at values from the literature ($C_{\mu\epsilon}$, C_{ϵ})

$$\mu_1^{pr} = (0.0845, 0.85)$$

$$\mu_2^{pr} = (0.07, 1.05)$$

- Range of Marginal Standard Deviations

$$\sigma_1^{pr} = (0.04, 0.4), \sigma_2^{pr} = (0.02, 0.2), \sigma_3^{pr} = (0.01, 0.1)$$



Bayesian Calibration: Posterior

Bayes formula:

$$P(\theta|D) = \frac{P(D|\theta)P(\theta)}{P(D)}$$

Diagram illustrating the Bayes formula with labels and arrows:

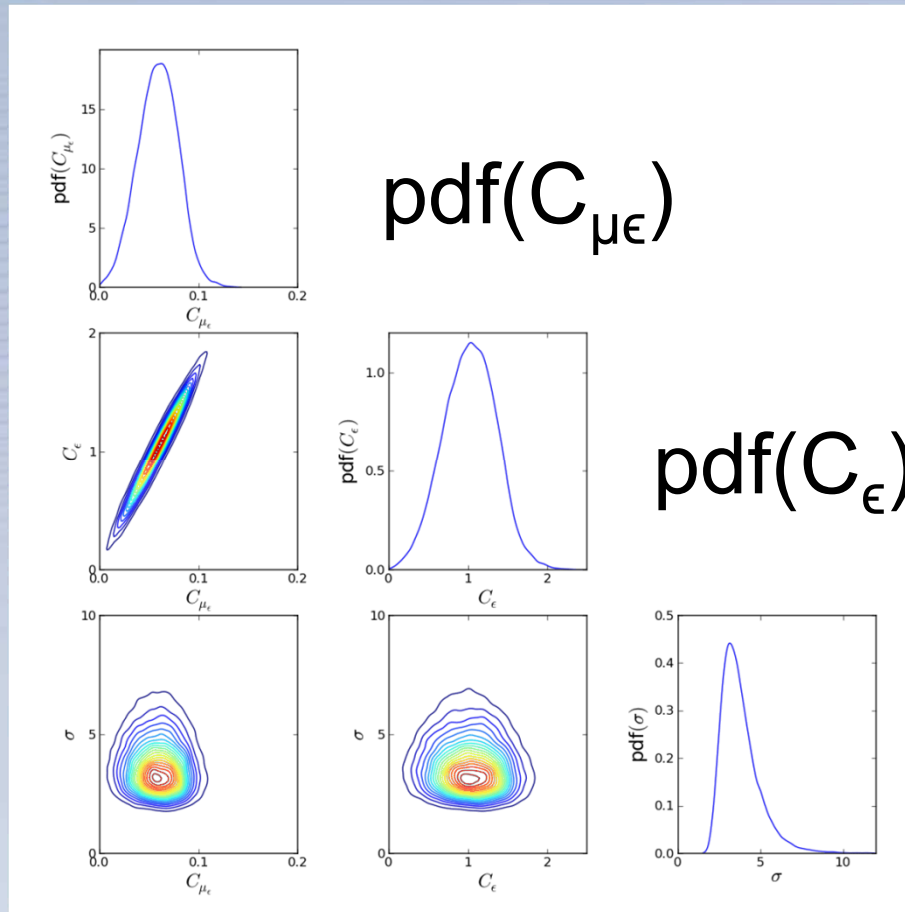
- likelihood**: points to $P(D|\theta)$
- prior**: points to $P(\theta)$
- evidence**: points to $P(D)$
- posterior**: points to $P(\theta|D)$ (circled in red)

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Sample Posterior Distributions



$C_{\mu\epsilon}$

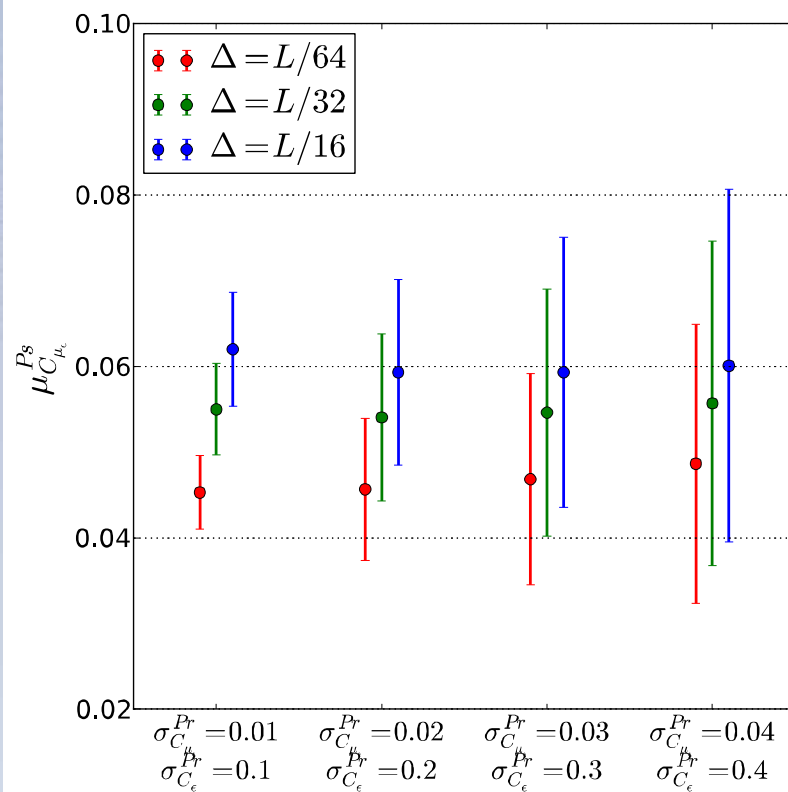
C_{ϵ}

σ

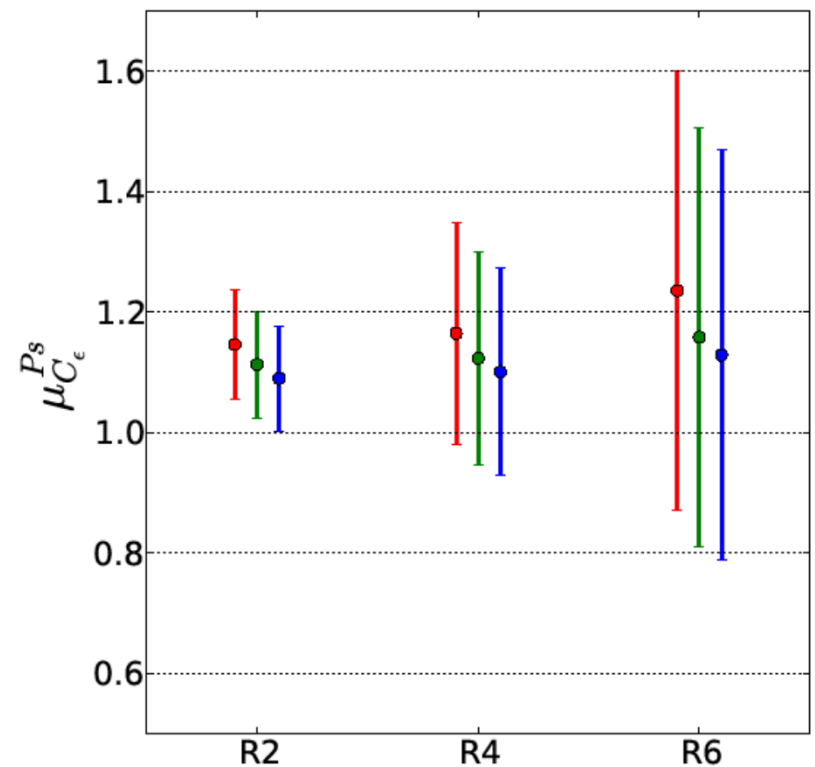


Effect of Filter Size and Prior

Posterior for $C_{\mu\epsilon}$



Posterior for C_ϵ





Forward UQ – Predictive Assessment

Employ Polynomial Chaos (PC) Expansion to propagate uncertainties from input parameters to output Quantities of Interest

$$M(C_\epsilon, C_{\mu_\epsilon}) \approx \sum_{k=0}^P c_k \Psi_k(\xi_1, \xi_2)$$

$$C_\epsilon = C_\epsilon(\xi_1, \xi_2), C_{\mu_\epsilon} = C_{\mu_\epsilon}(\xi_1, \xi_2)$$

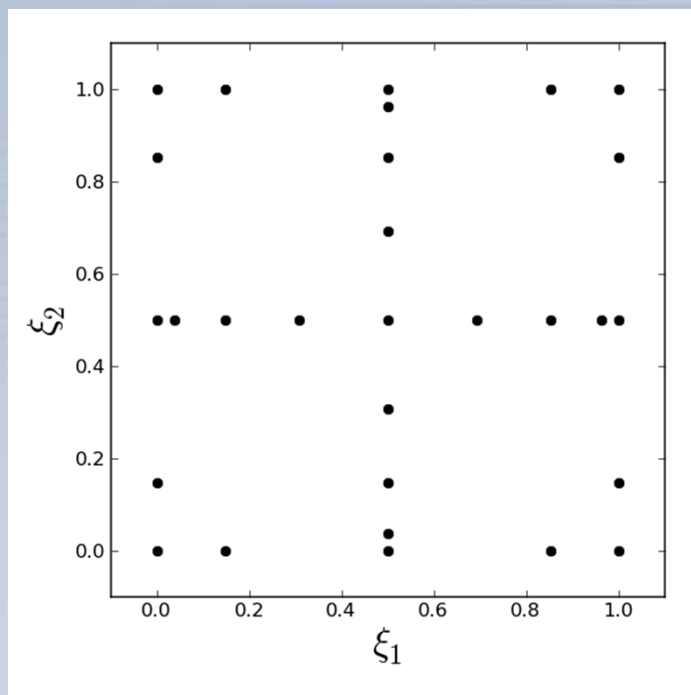
Employ quadrature to compute PC coefficients

$$c_k = \frac{\langle M(C_\epsilon, C_{\mu_\epsilon}) \Psi_k(\xi_1, \xi_2) \rangle}{\langle \Psi_k^2(\xi_1, \xi_2) \rangle}$$

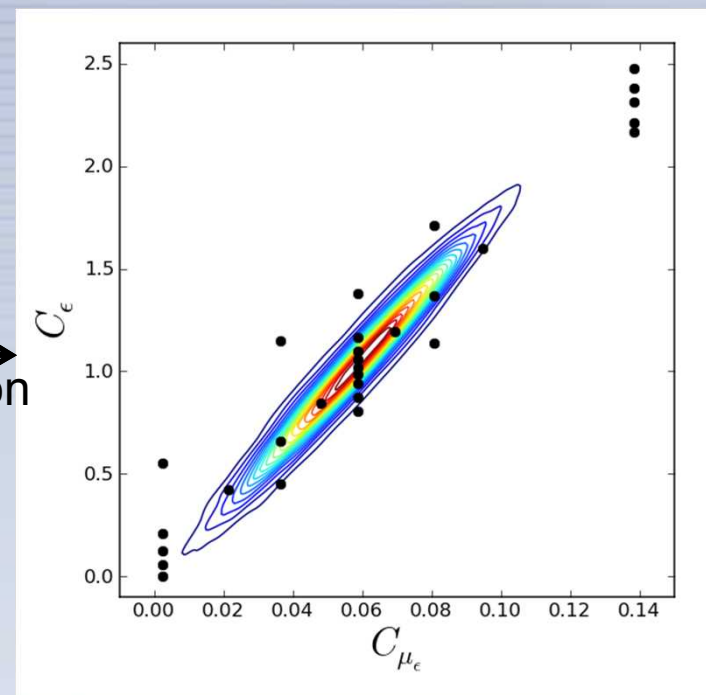


Sparse Quadrature to Construct PC Expansion for Model Output

$$C_\epsilon = C_\epsilon(\xi_1, \xi_2), \quad C_{\mu_\epsilon} = C_{\mu_\epsilon}(\xi_1, \xi_2)$$



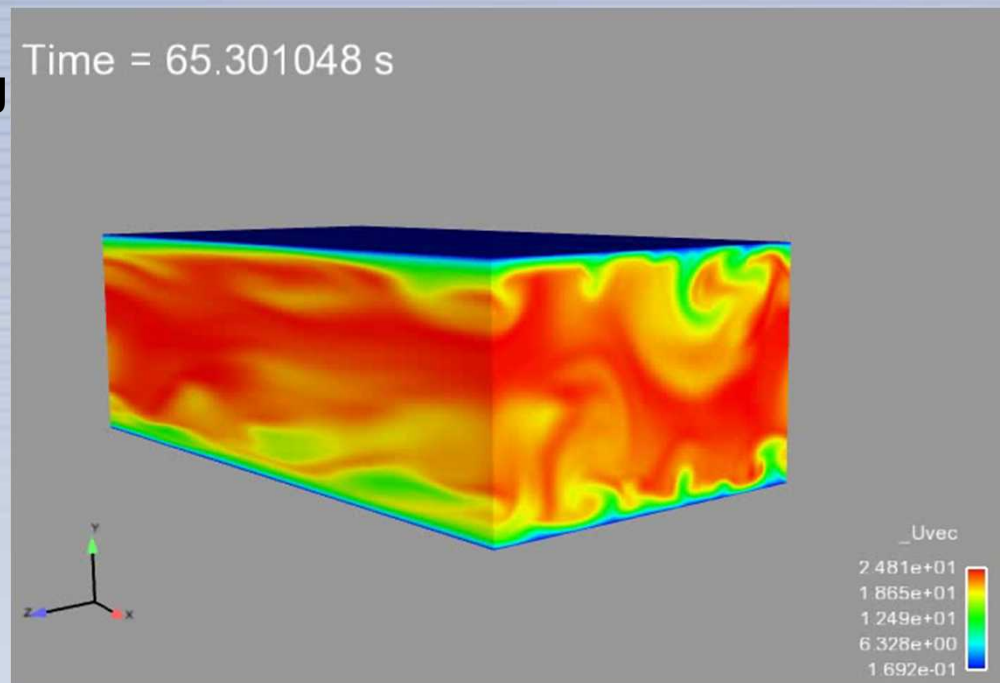
Rosenblatt
Transformation





Fuego LES Simulations with Calibrated Parameters

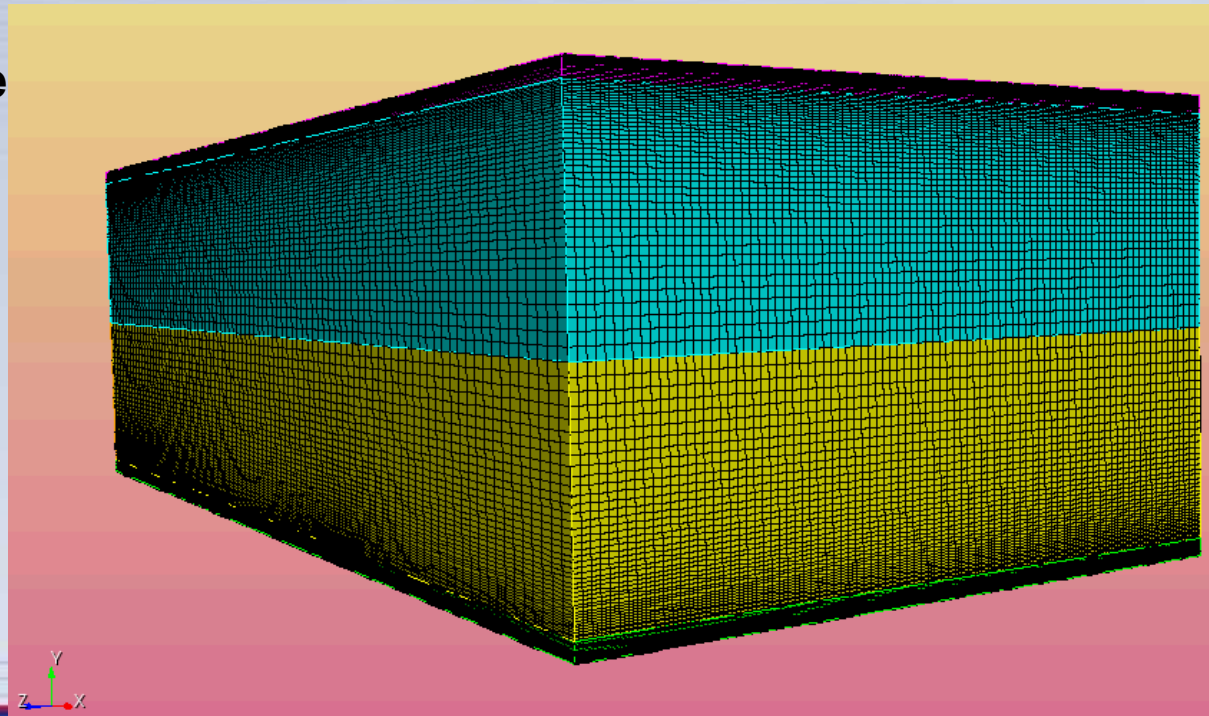
- k^{sgs} Turbulence Model with various C_ϵ and $C_{\mu\epsilon}$ corresponding to quadrature points
- Normalized Input Parameters
 - $\rho = 1.0$
 - $\mu = 1/Re_\tau = 1/590$
- No slip walls at top and bottom
- Periodic in x and z
- Body force in x-direction to produce flow





Mesh

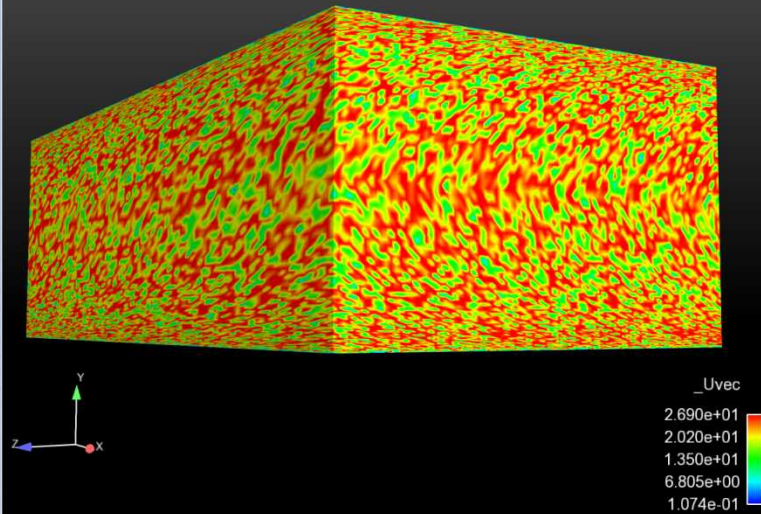
- **Dimensions:**
 - Flow direction: $x = 2\pi$ (periodic)
 - Wall normal direction: $y = 2$
 - Cross flow direction: $z = \pi$ (periodic)
- **Grid size:**
 $90 \times 116 \times 90 = 931500$ points
- $y^+ \approx 1.15$ at walls
- Hyperbolic tan to same spacing as in z



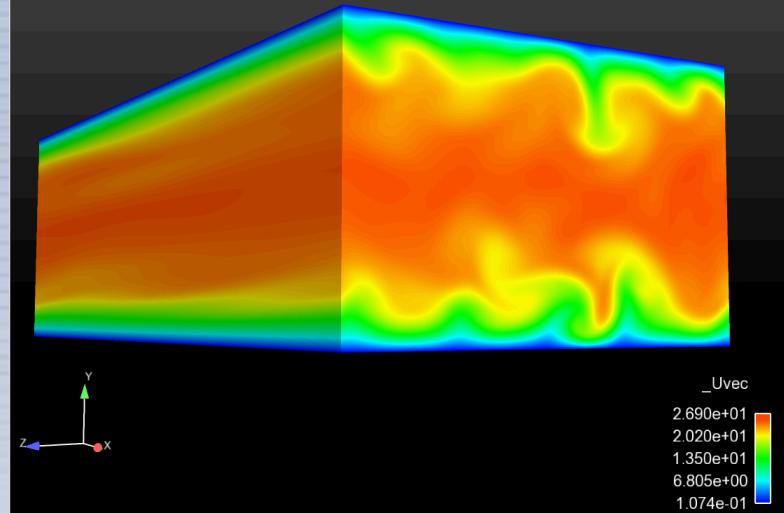


Fuego LES Simulations

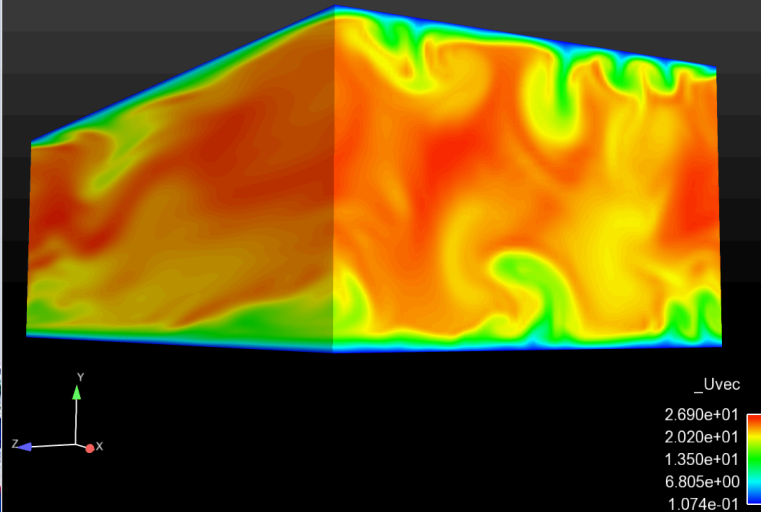
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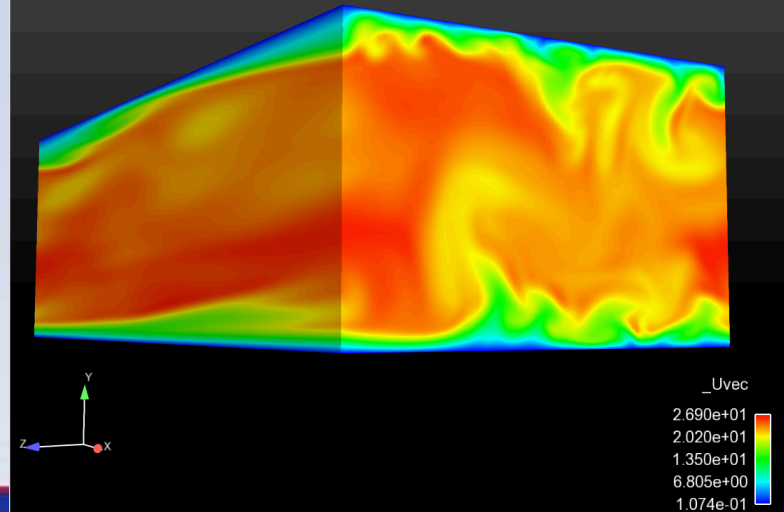
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Time = 8.0000 sec

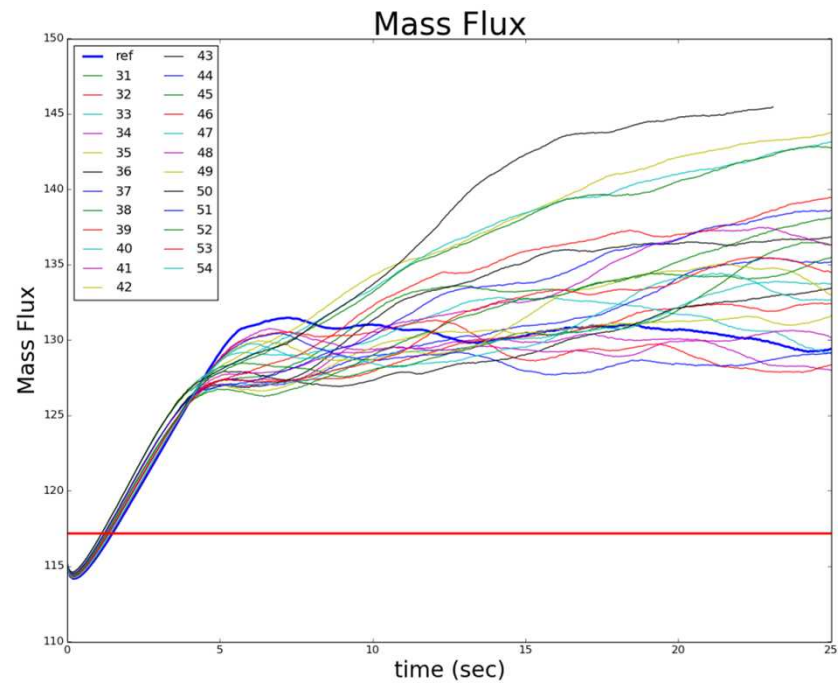
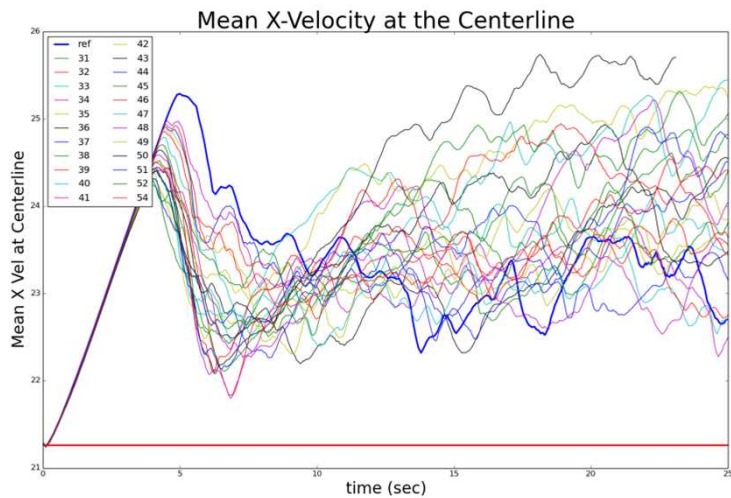


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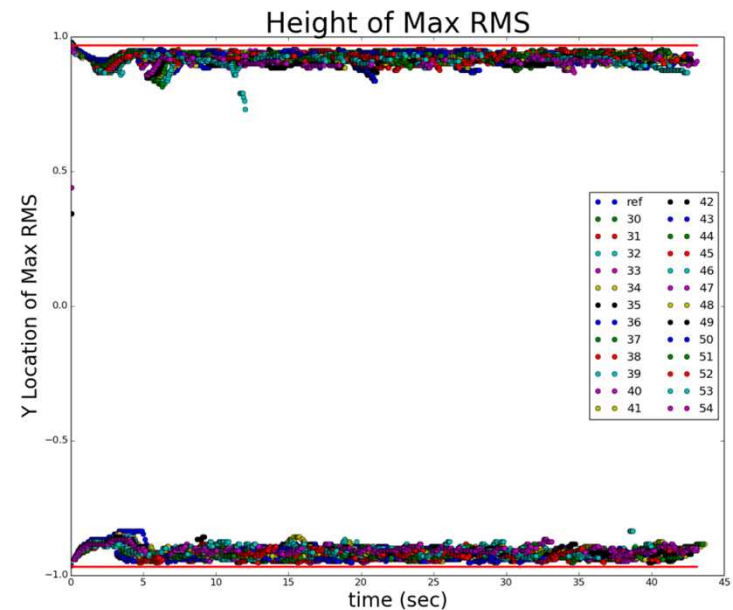
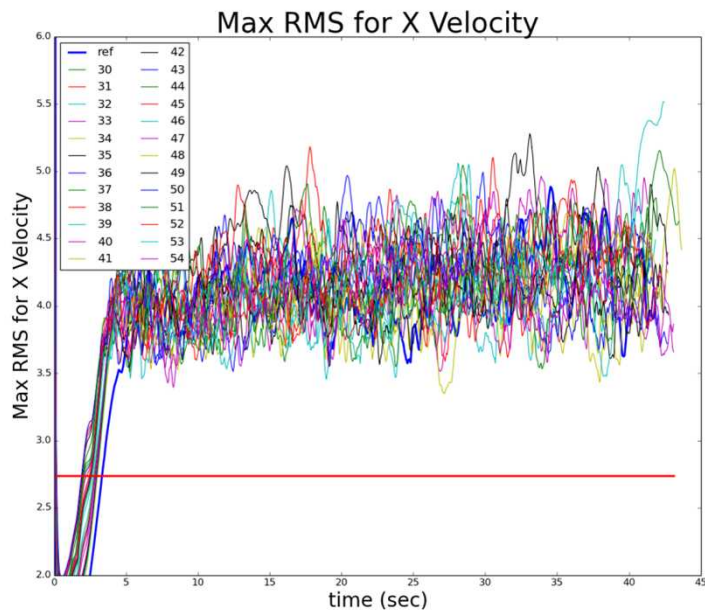


QoIs: Velocity and Mass Flux





QoI: RMS of Centerline Velocity





Forward UQ – Predictive Assessment

Evaluate weights with values from LES

$$c_k = \frac{\langle M(C_\epsilon, C_{\mu_\epsilon}) \Psi_k(\xi_1, \xi_2) \rangle}{\langle \Psi_k^2(\xi_1, \xi_2) \rangle}$$

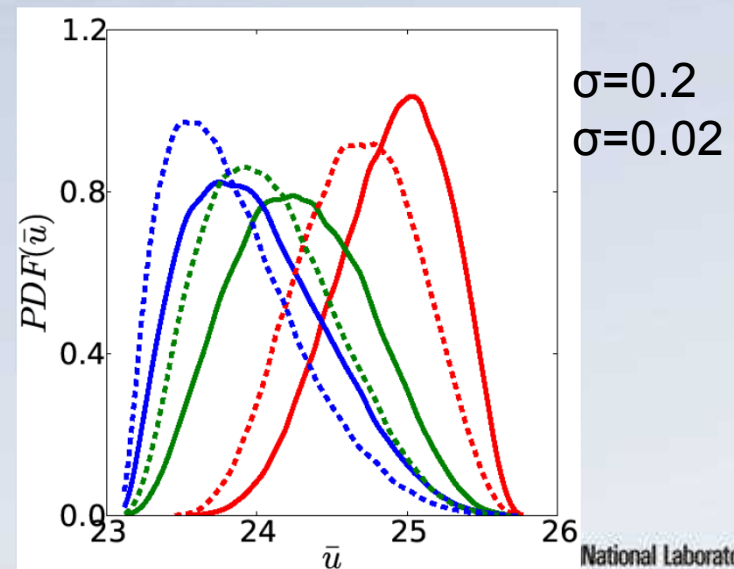
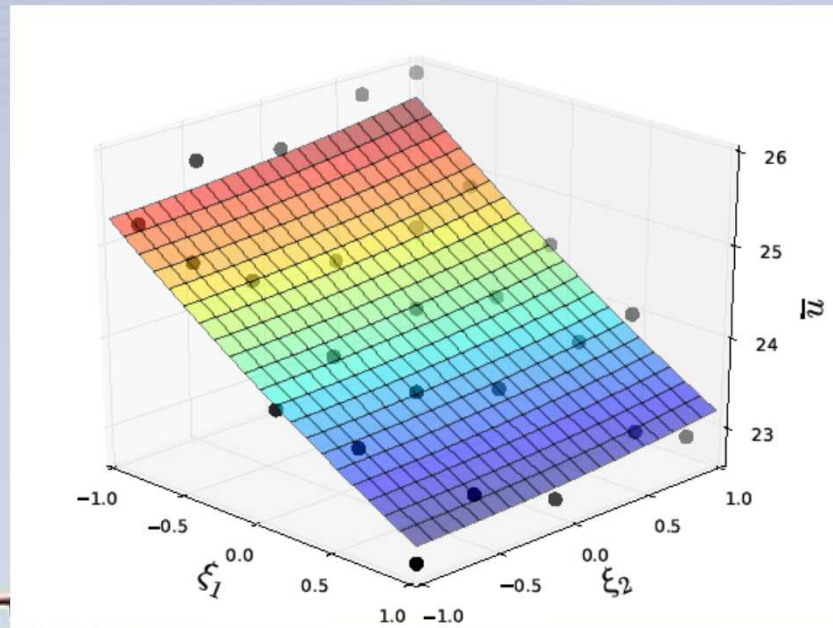
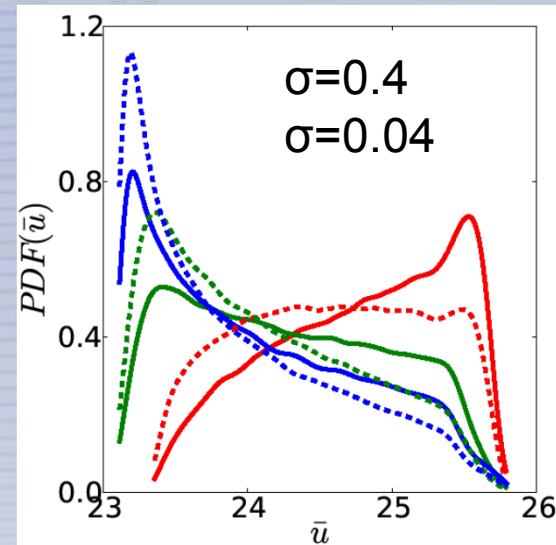
Employ Polynomial Chaos (PC) Expansion to propagate uncertainties from input parameters to output Quantities of Interest

$$M(C_\epsilon, C_{\mu_\epsilon}) \approx \sum_{k=0}^P c_k \Psi_k(\xi_1, \xi_2)$$



Midline Average Velocity

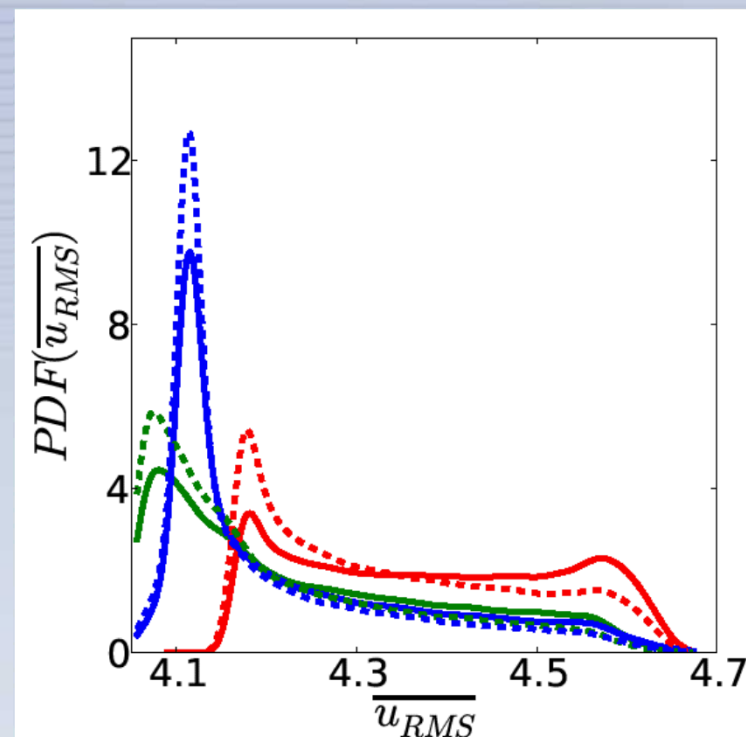
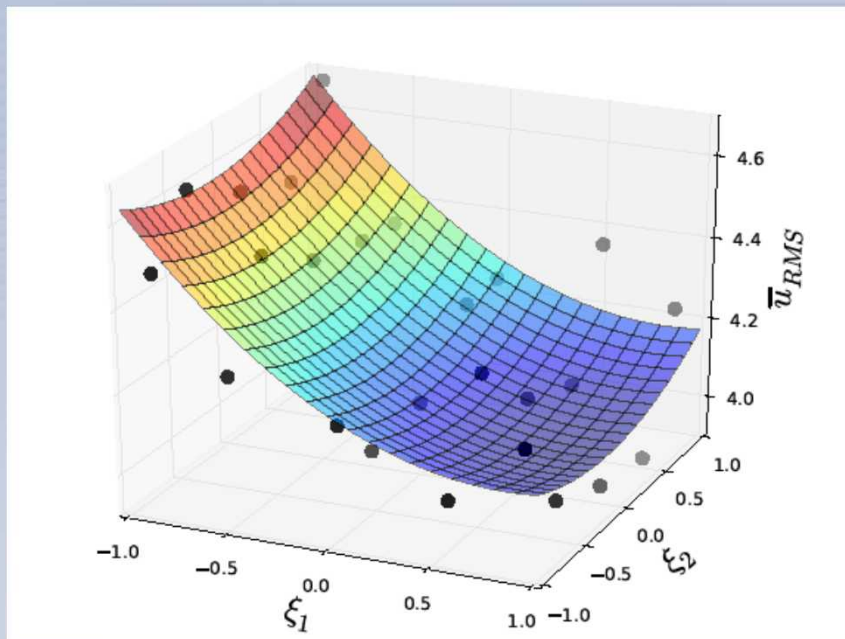
- DNS = 21.26
- Solid = $\mu_1^{pr} = (0.0845, 0.85)$
- Dashed = $\mu_2^{pr} = (0.07, 1.05)$





RMS of Centerline Velocity

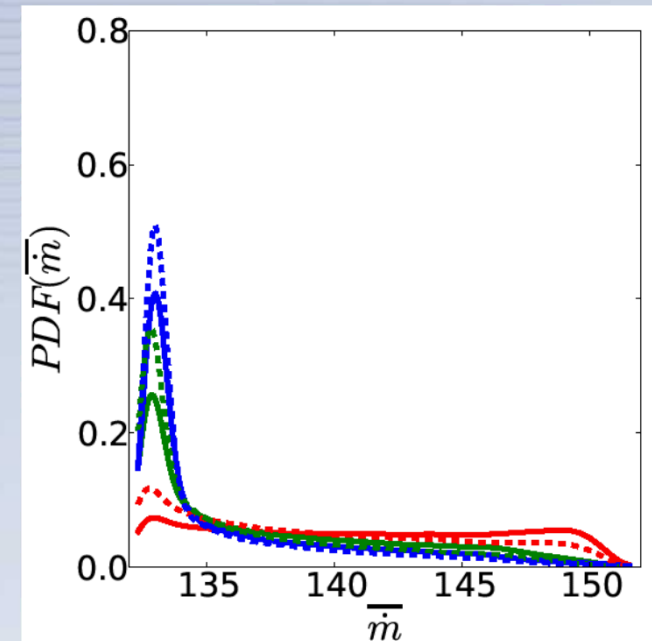
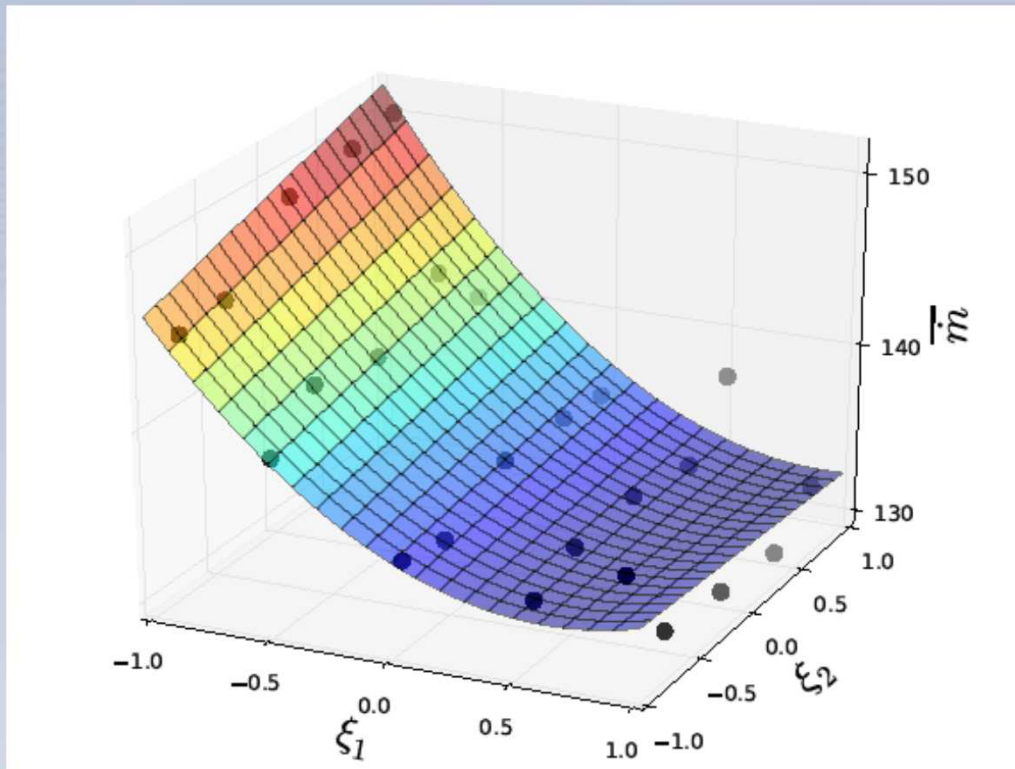
- DNS = 2.7





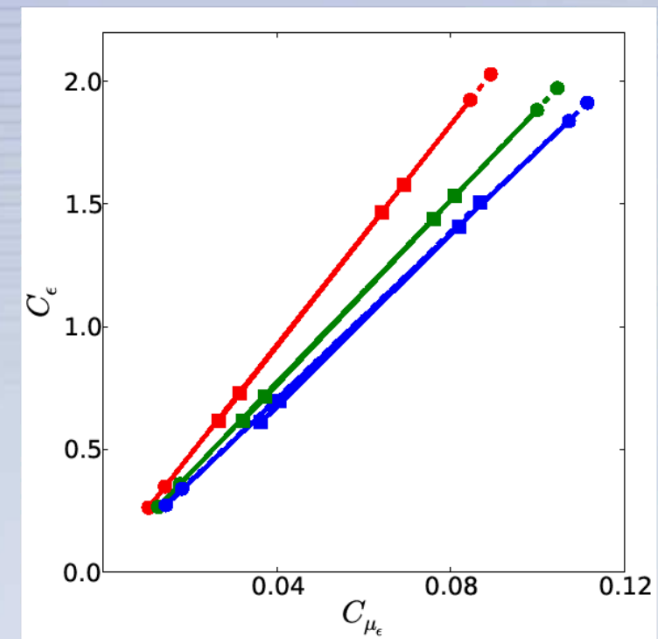
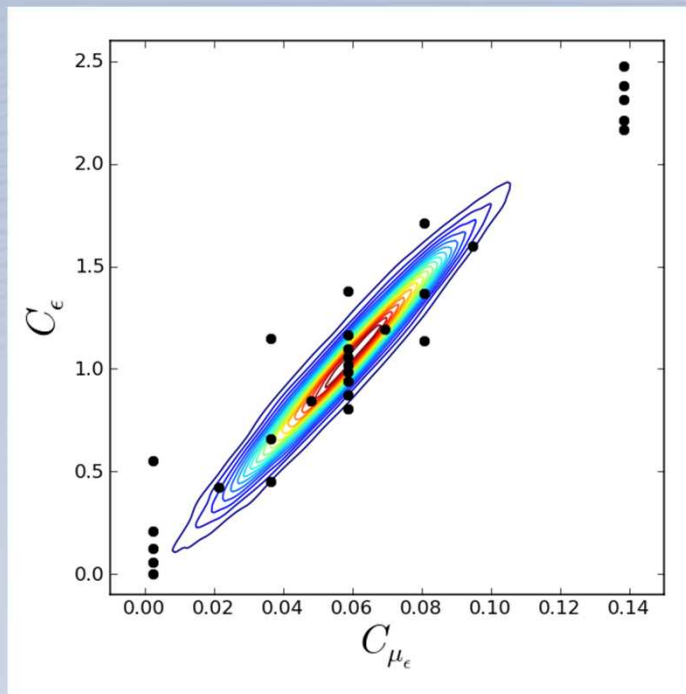
Mean Mass Flux

- DNS = 117





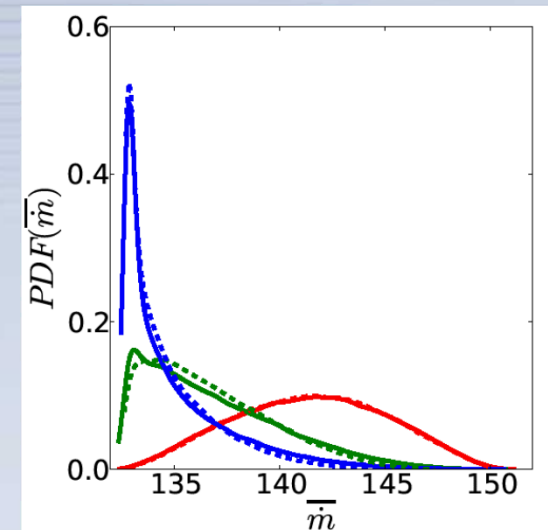
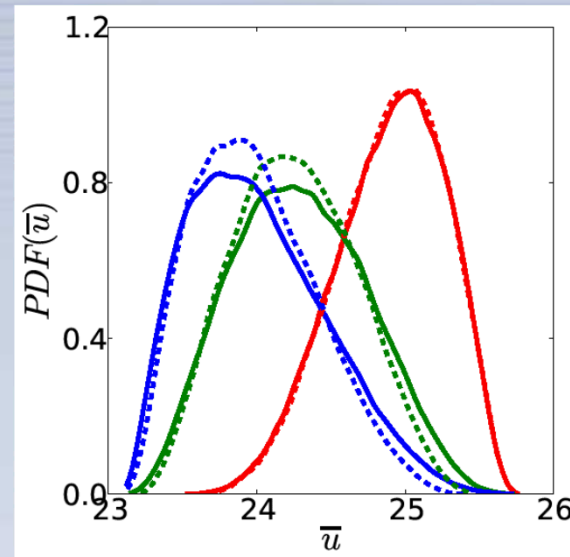
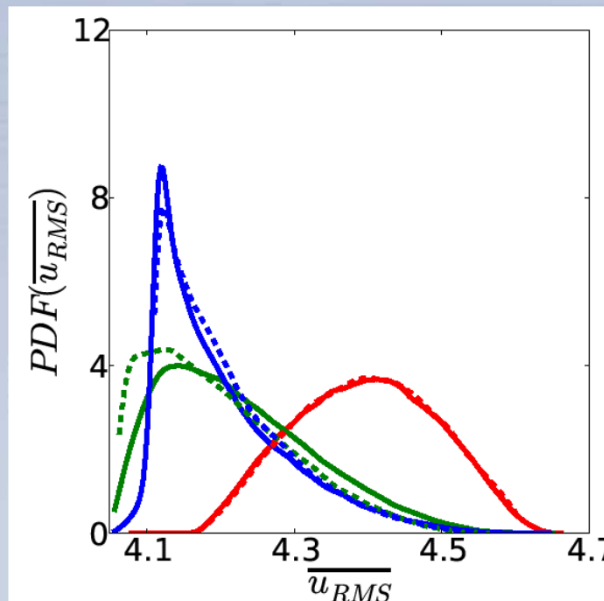
Principal Component Analysis of Joint PDF's





First Principal Component yields similar results to Joint PDF

- Solid – Joint PDF
- Dashed – 1st PC





Conclusions

- **Used DNS isotropic turbulence to predict engineering LES channel flow QoI**
- **Production and dissipation terms for the k_{sgs} model are highly correlated**
- **Discrepancy in QoI values from DNS**
 - Isentropic turbulence to channel flow
 - “engineering level”
 - Errors in k_{sgs}



Path Forward in FY15

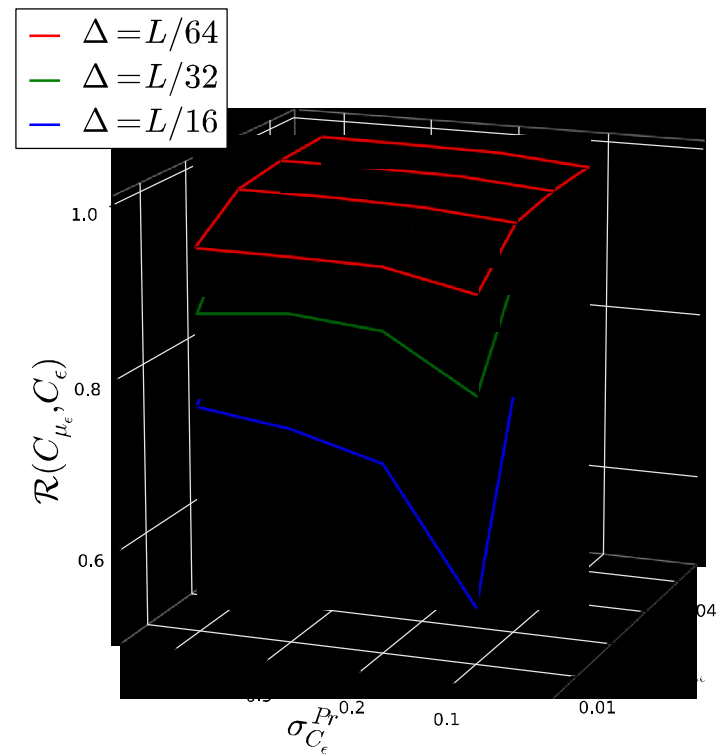
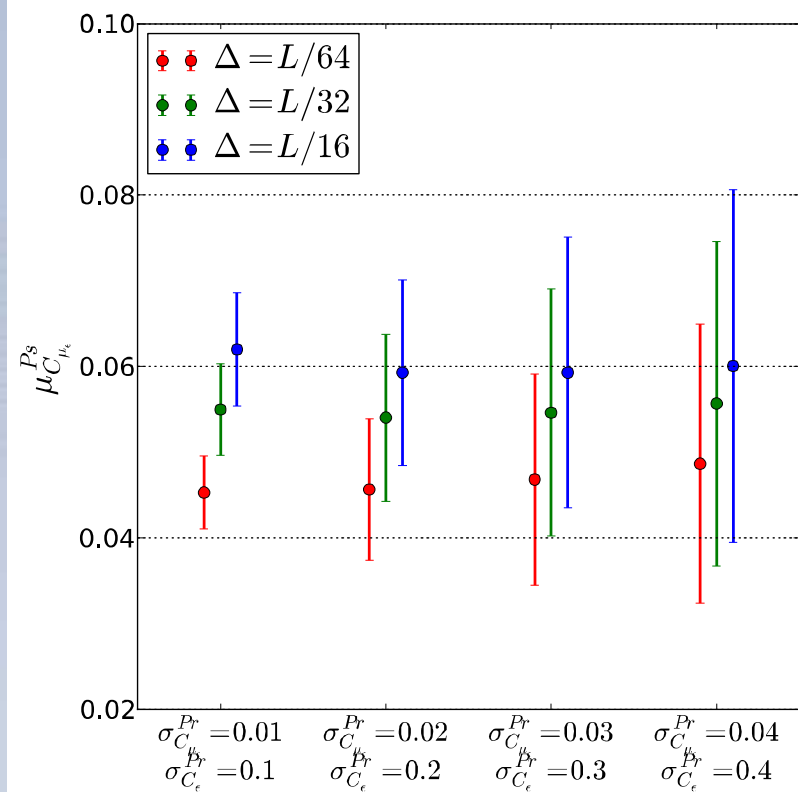
- **Complete combustion model implementation in Nalu**
 - Coordinate reaction flow case with J. Oefelein et al
 - Extra development effort from Blaylock & Hewson
- **Calibrate combustion model coefficients**
- **Tie reacting flow simulation with ODT-informed PCE model to estimate probability of extinction**
- **UQ of reacting flow simulation**
- **UQ of wall model for channel flow and backward facing step**
- **Make UQ/calibration tools available through SNL git repository**



Thank You & Questions

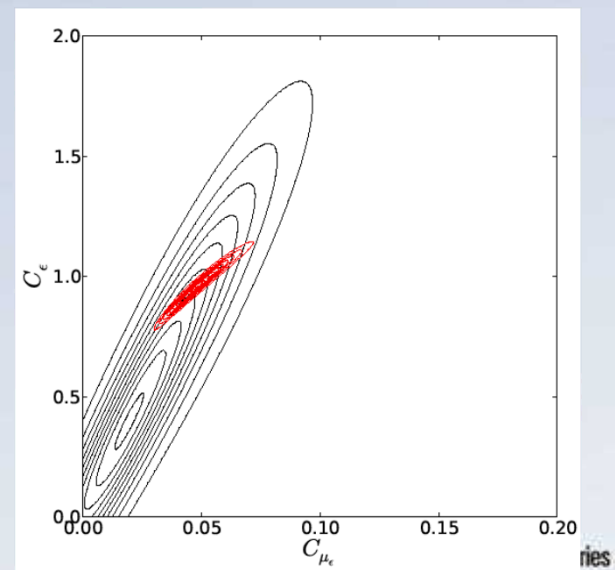
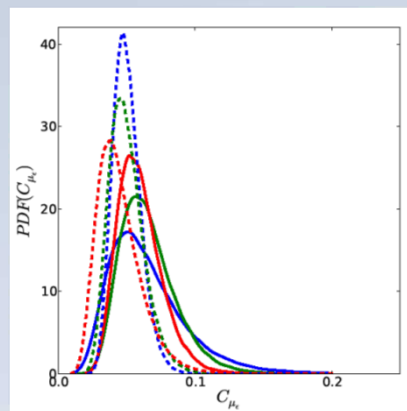
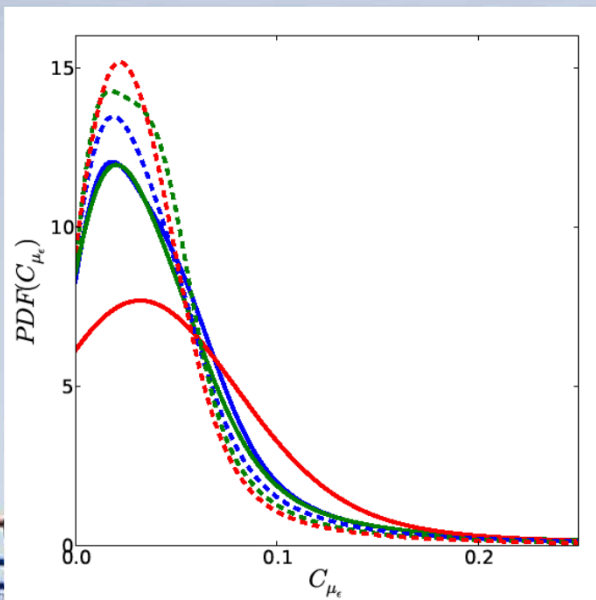
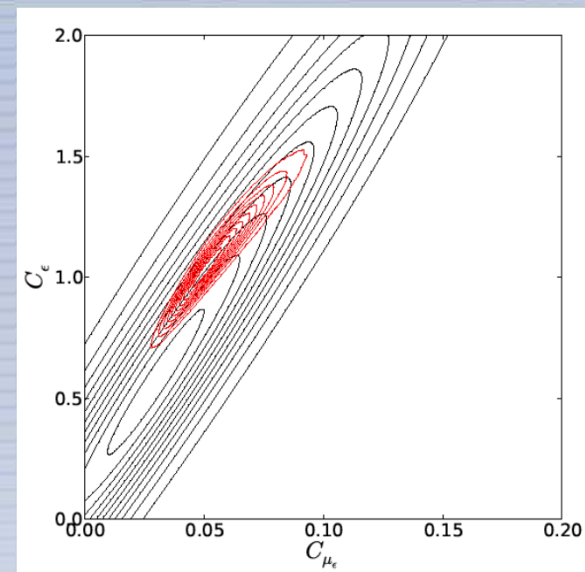
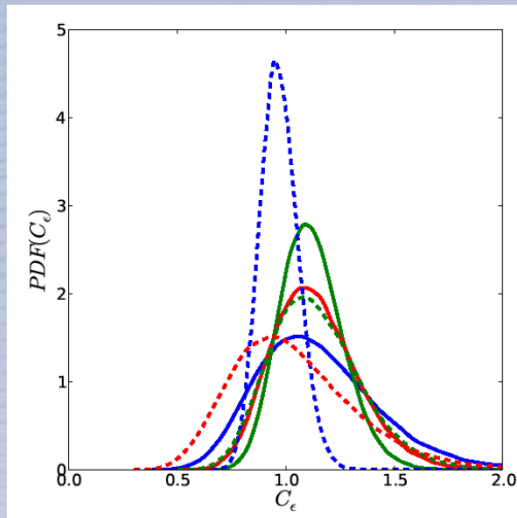
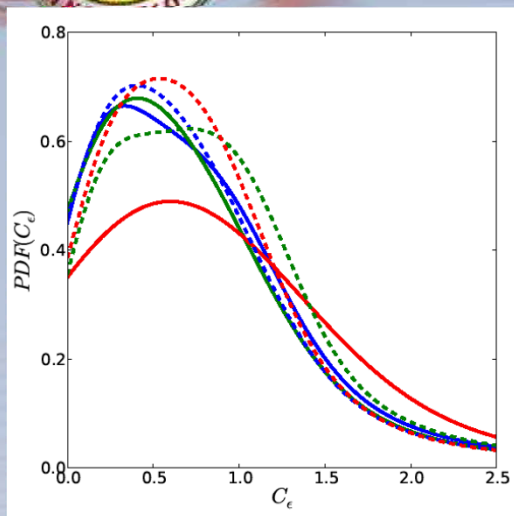


Effect of Filter Size and Prior



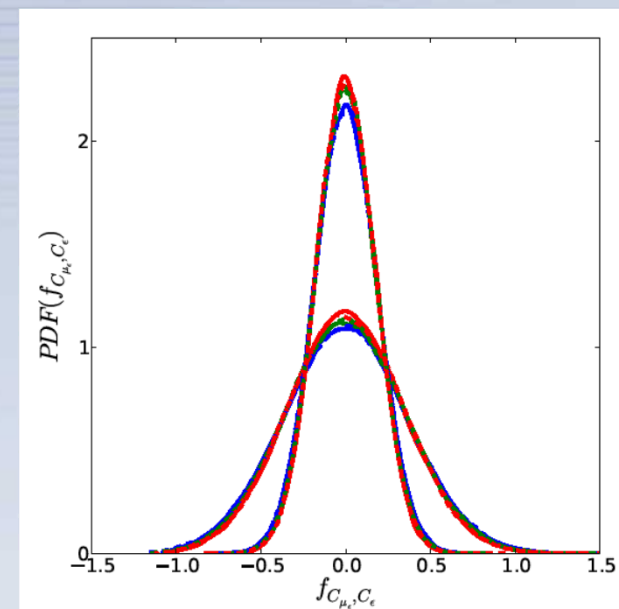
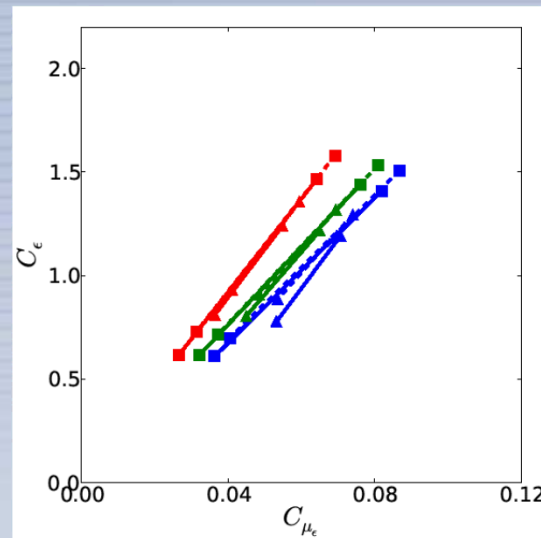
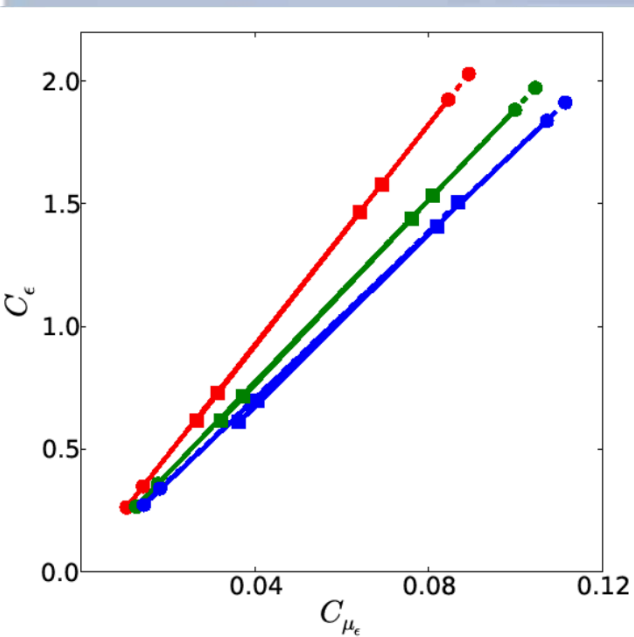


Posterior





Principal Component Analysis of Joint PDF's

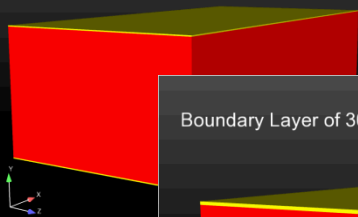




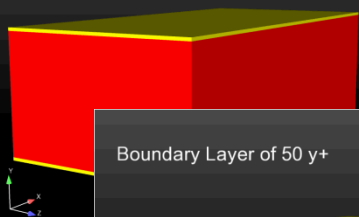
Wall-Model Calibration (in progress)

Calibrate boundary layer and bulk model parameters

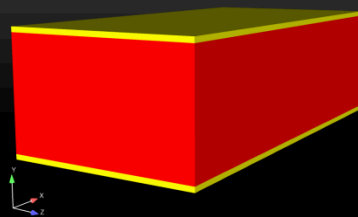
Boundary Layer of 10 y^+



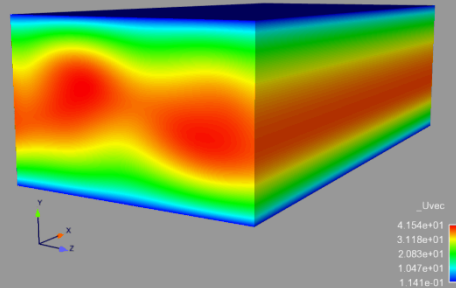
Boundary Layer of 30 y^+



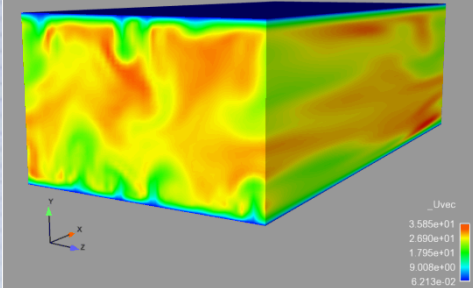
Boundary Layer of 50 y^+



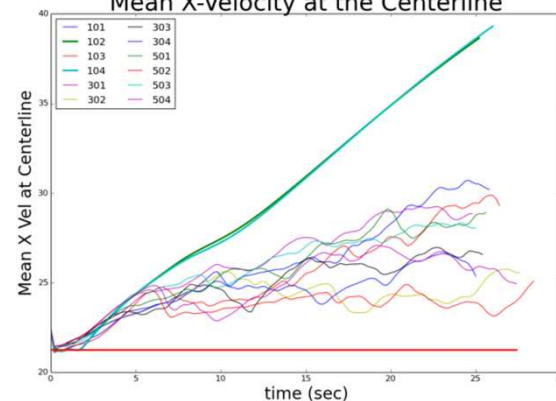
Time = 25.00 s



Time = 25.00 s

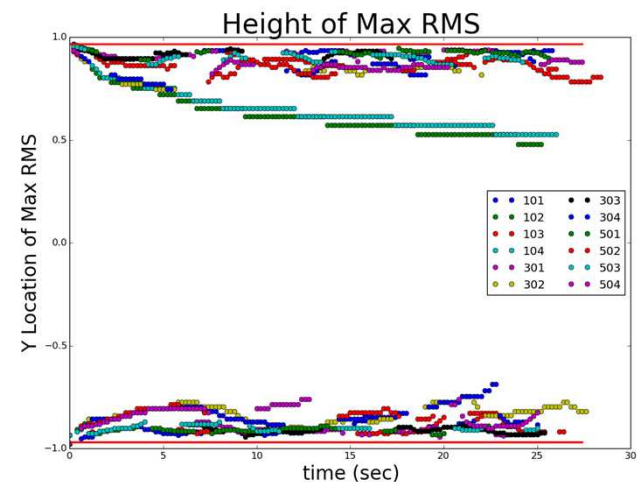
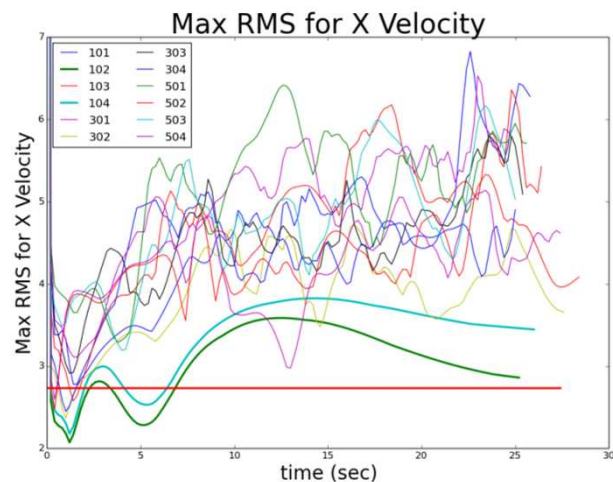
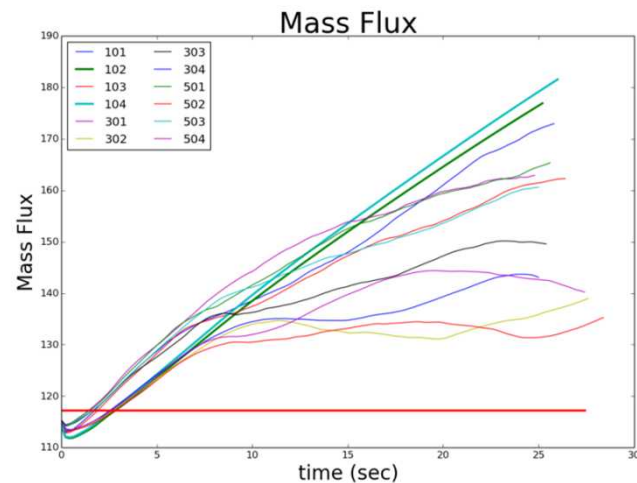
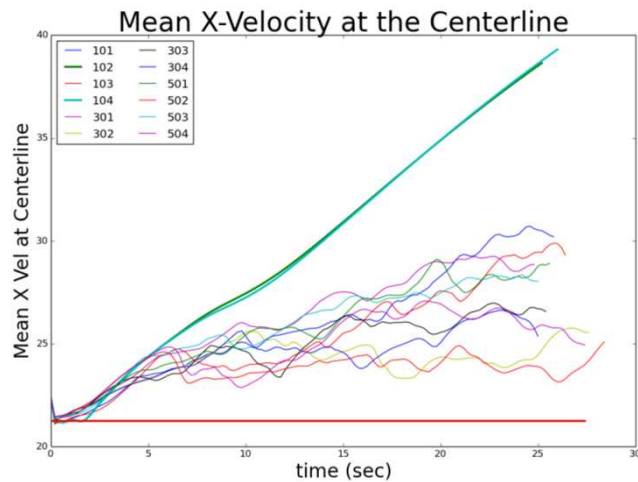


Mean X-Velocity at the Centerline





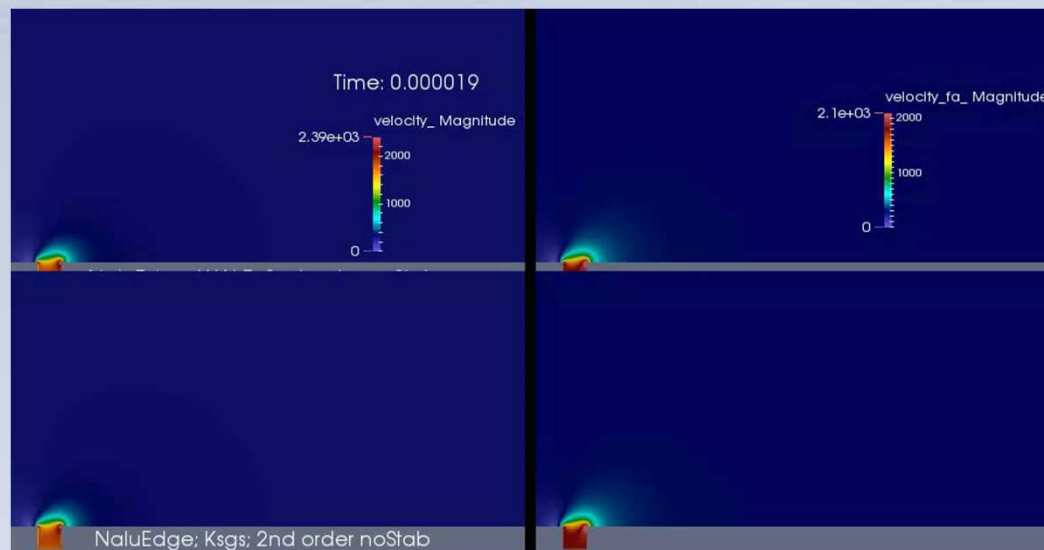
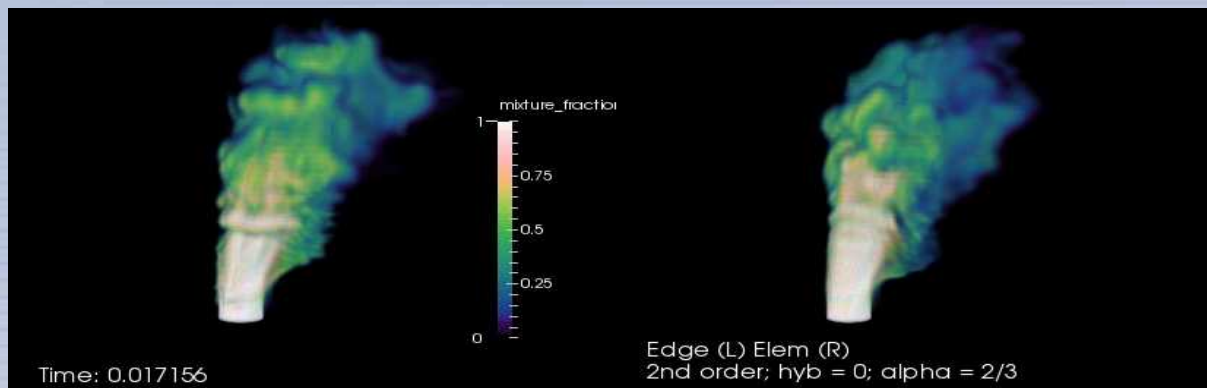
Wall Model Results





Jet-in-Crossflow UQ (in progress)

Simulation capability implemented in Nalu
Validate against Su & Mungal Re 5K case

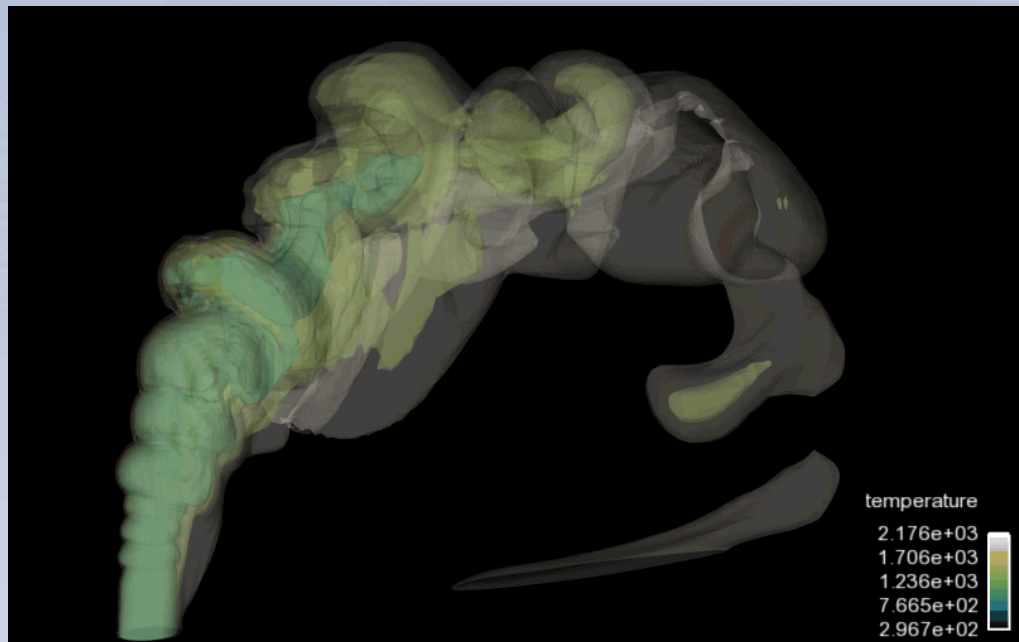


Collaborating with
Ruiz, Lacaze,
Oefelein,
“Assessing the
accuracy of Large
Eddy Simulation in
a Jet In Cross Flow
Configuration,” (*in
prep*)

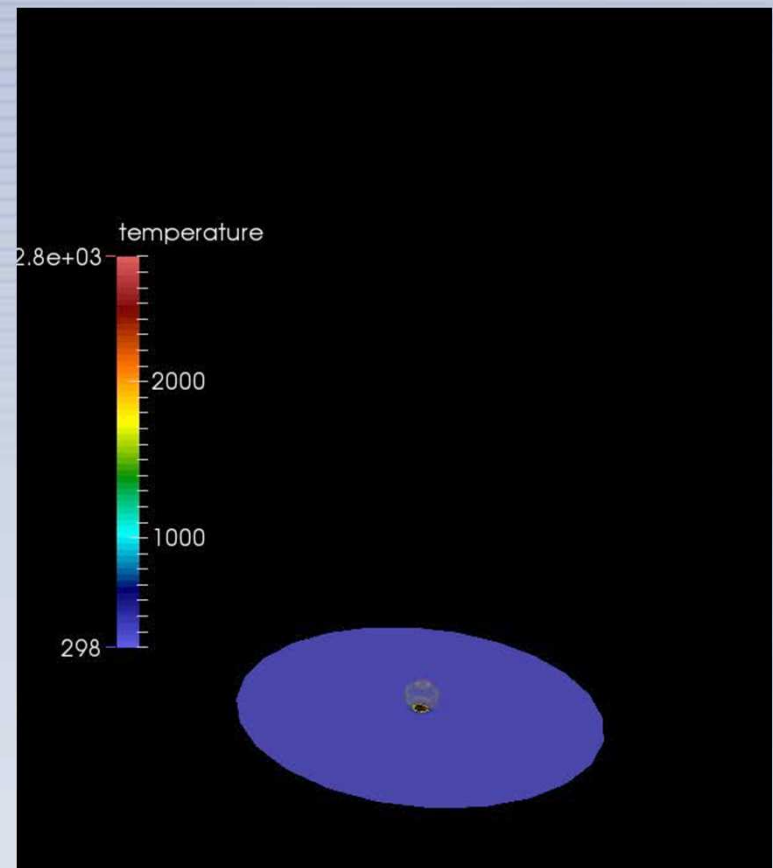


Combustion Model Implementation

Re $\sim 25,000$; Burke Schumann Methane Combustion



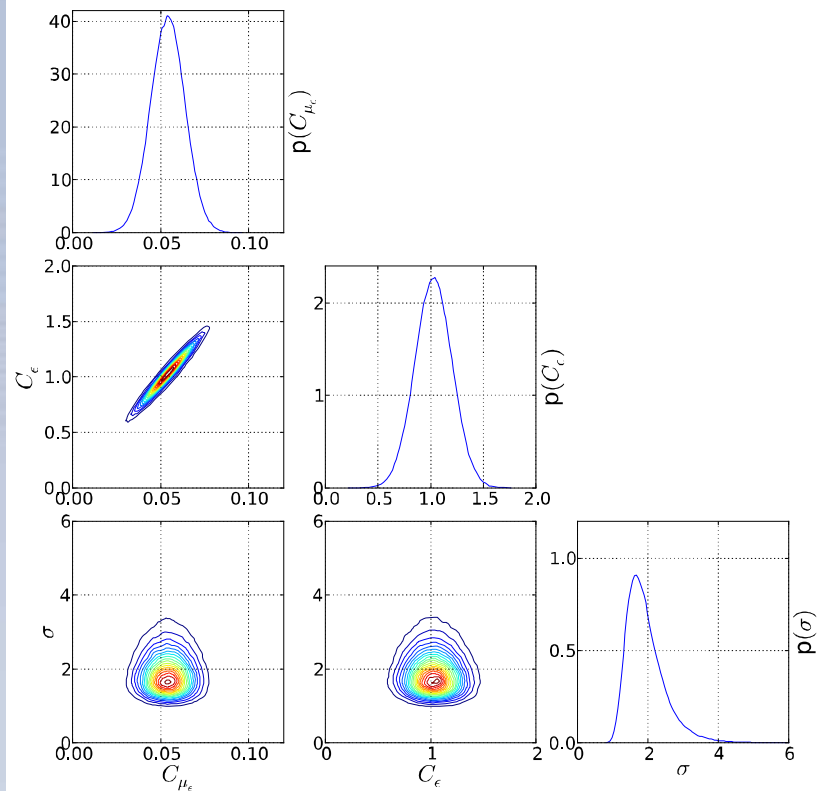
Mixture fraction iso-surfaces colored by temperature





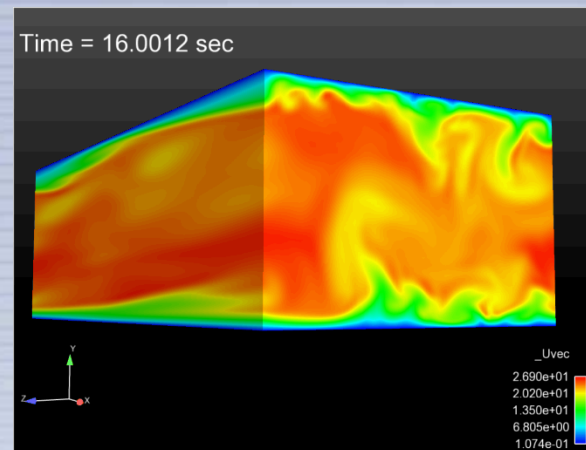
Forward UQ

Joint PDF of Model Parameters



Safta, Blaylock, Templeton, Domino,
 “Parameter Uncertainty in LES of
 Channel Flow,” *(in prep.)*

Propagation in Turbulent Channel



Running Average of the Mean X-Velocity at the Centerline

