



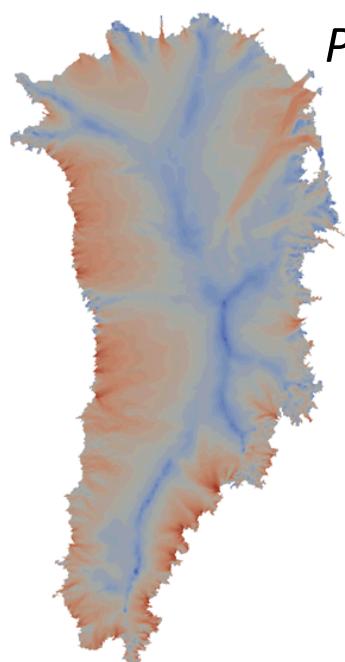
# An Update on the Albany/FELIX First-Order Stokes Finite Element Solver & its Coupling to Land Ice Dycores

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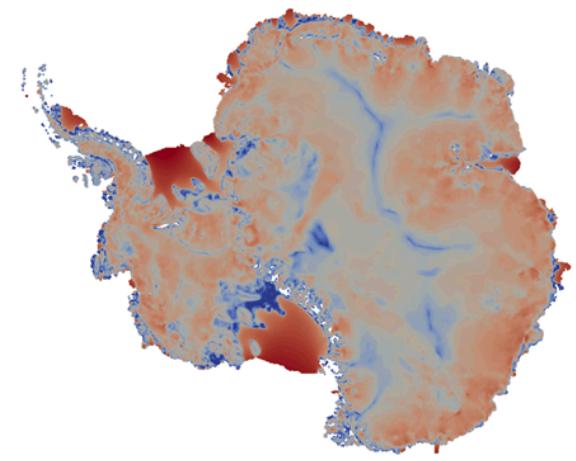
**Irina Kalashnikova, Andy Salinger, Mauro Perego,  
Ray Tuminaro, Steve Price**

*In collaboration with Matt Hoffman, Doug Ranken, Kate Evans,  
Pat Worley, Matt Norman, Mike Eldred, John Jakeman and  
Irina Demeshko.*



Sandia National Laboratories\*

CESM Annual Workshop  
June 16-19, 2014



The Village at Breckenridge  
Breckenridge, Colorado

\*Sandia is a multiprogram laboratory operated by Sandia corporation, a Lockheed Martin Company, for the U.S. Department of Energy under contract DE-AC04-94AL85000.

# PISCEES Project & the Albany/FELIX First-Order Stokes Dycore

To **develop** and **support** a robust and scalable unstructured grid finite element land ice dycore based on the “first-order” (FO) Stokes physics → *Albany/FELIX dycore*

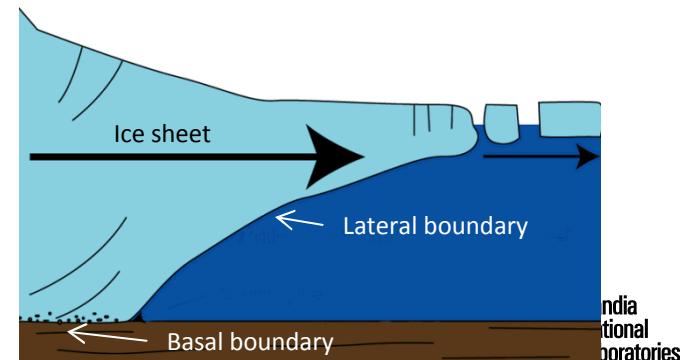
- **Finite element method.**
- Parallel, unstructured grid with **partitioning**.
- **Automatic differentiation** for (exact) Jacobians.
- Globalized **Newton's method** nonlinear solver.
- Preconditioned (ILU or algebraic multigrid) iterative **Krylov linear solvers**.
- **Performance-portable kernels** to run on new architecture machines / GPUs (in progress).
- **Analysis tools:** UQ, sensitivity analysis, optimization.
- **Software tools:** git / cmake / ctest / jenkins.

## First Order Stokes Model

$$\begin{cases} -\nabla \cdot (2\mu\dot{\epsilon}_1) = -\rho g \frac{\partial s}{\partial x} \\ -\nabla \cdot (2\mu\dot{\epsilon}_2) = -\rho g \frac{\partial s}{\partial y} \end{cases}$$

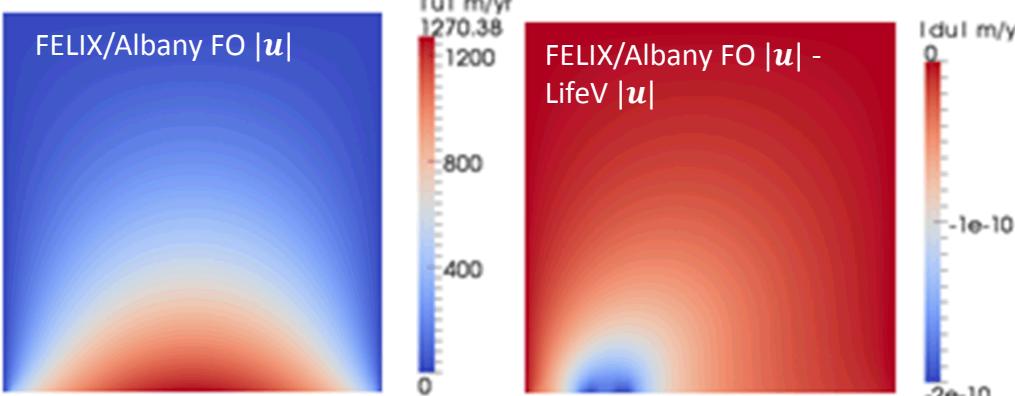
## Boundary conditions

• No-slip	• Basal Sliding
• Stress-free	• Open-ocean



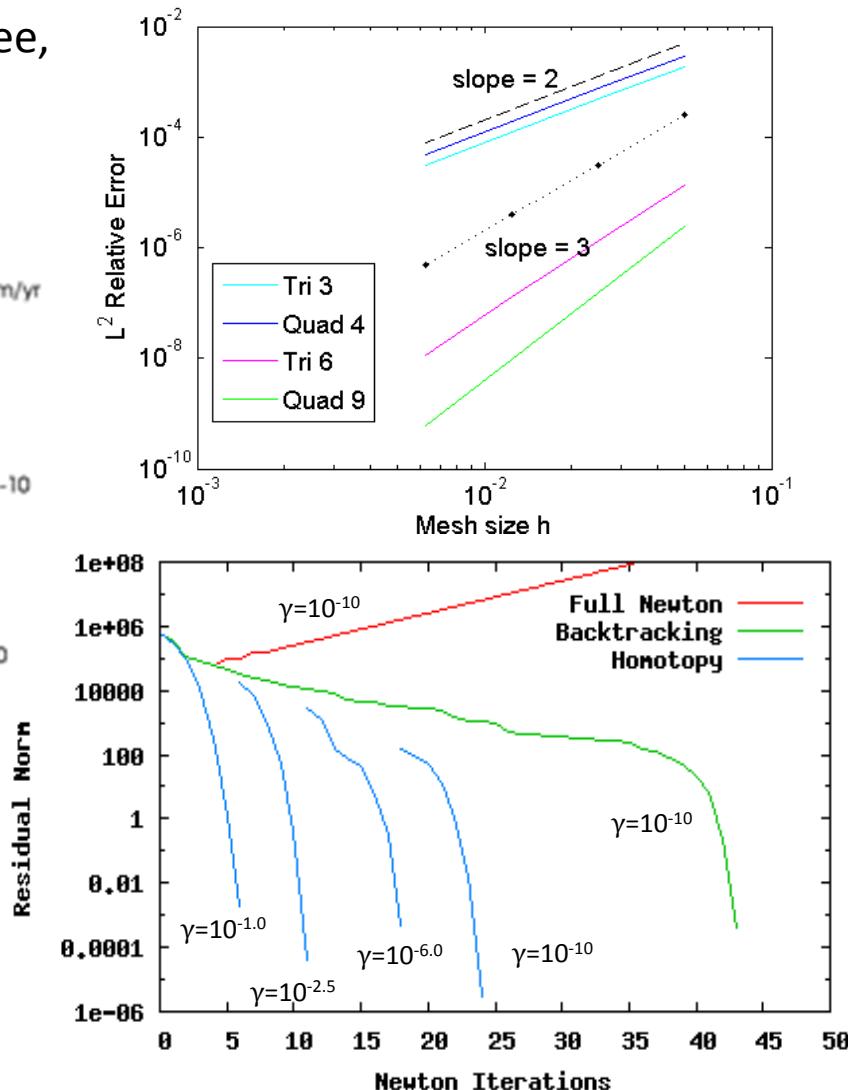
# Code Verification and Performance

- Implementation of PDEs + BCs (no-slip, stress-free, basal sliding, open-ocean) has been **verified** through MMS tests (right) and code-to-code comparisons (confined-shelf, below).

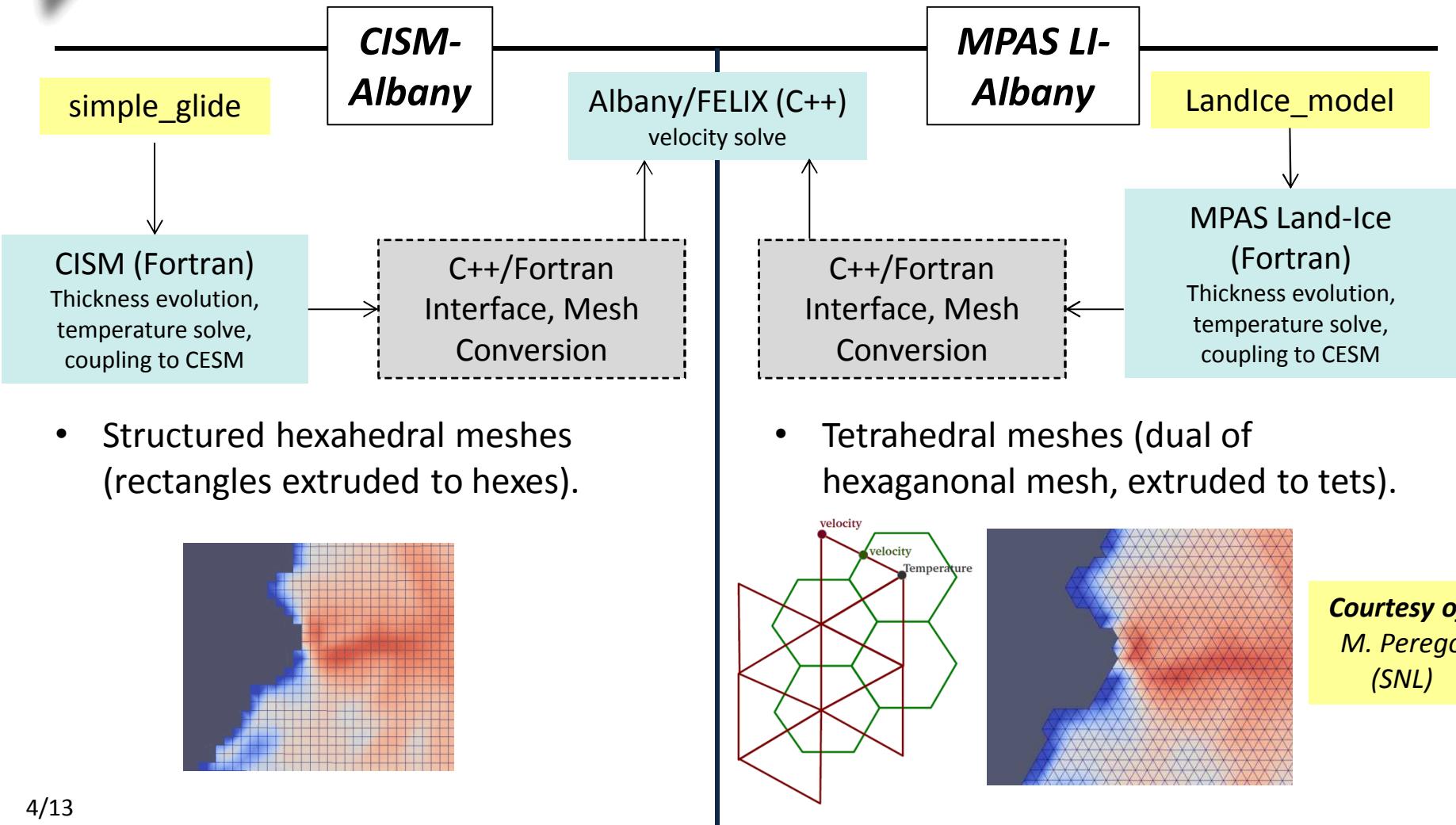


- Robust** nonlinear solves (Newton converges out-of-the-box!) with **homotopy** continuation of  $\gamma$  in Glen's law viscosity:

$$\mu = \frac{1}{2} A^{-\frac{1}{n}} \left( \frac{1}{2} \sum_{ij} \dot{\epsilon}_{ij}^2 + \gamma \right)^{\left( \frac{1}{2n} - \frac{1}{2} \right)}$$

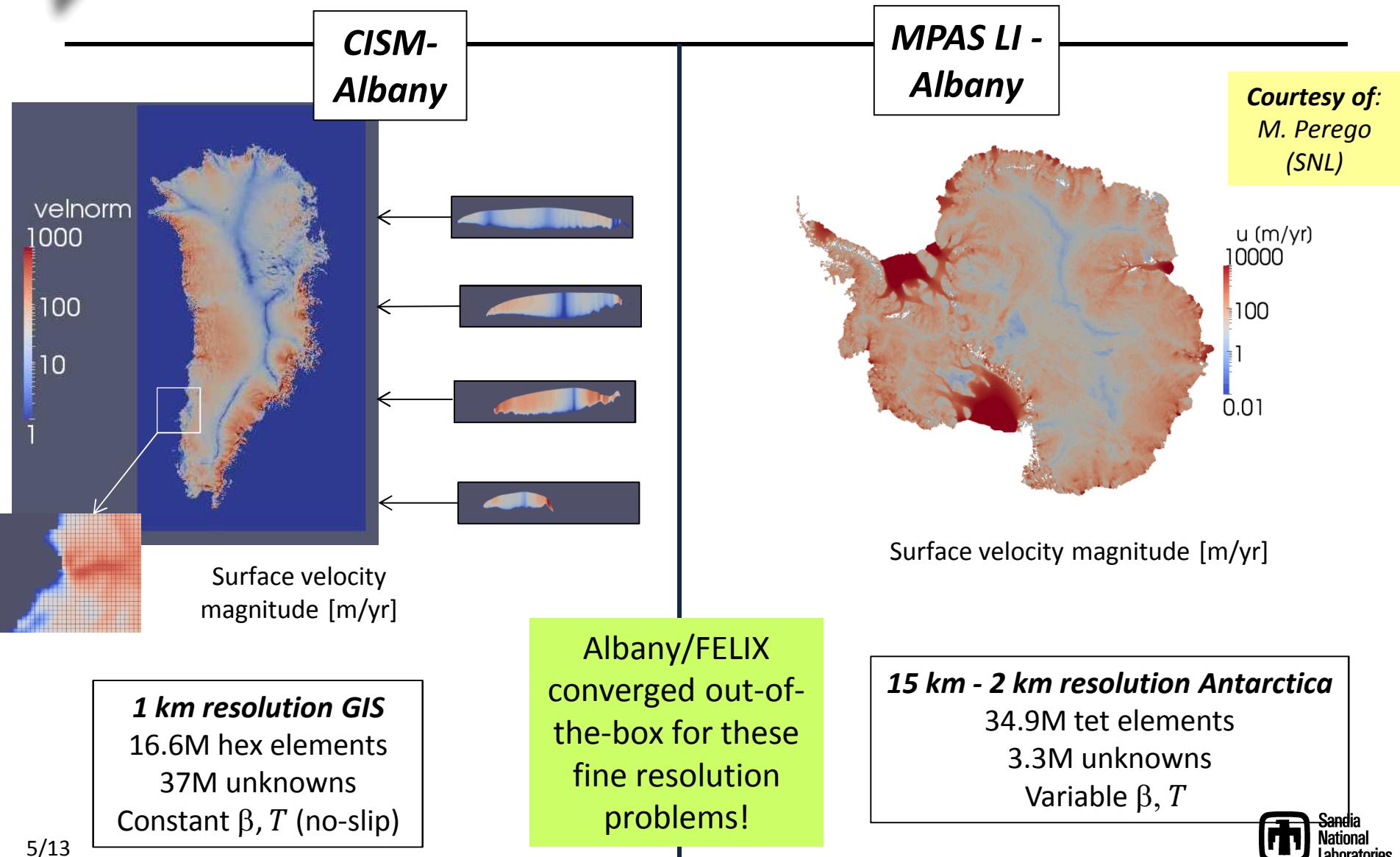


# Dycore Interfaces and Meshes



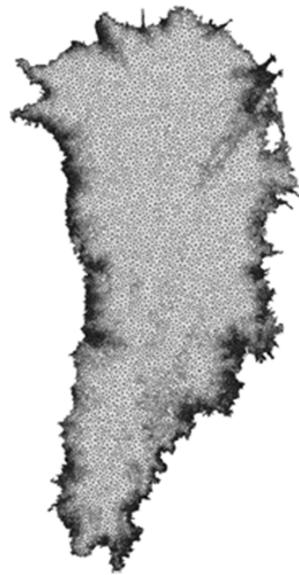
We support several full **mesh/data** (geometry, topography, surface height, basal traction, temperature, etc.) import methods: **\*.exo**, **ASCII** (stand-alone Albany), **\*.nc** (Dycore-Albany);

# Steady Runs Using Dycore Interfaces

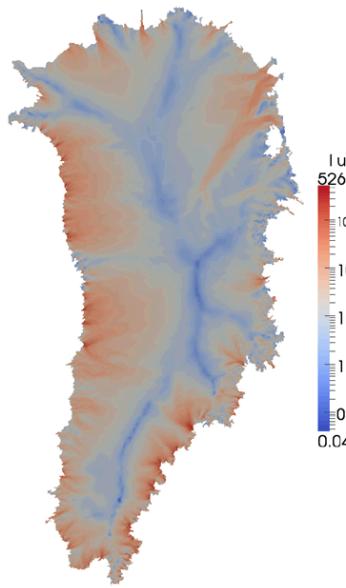




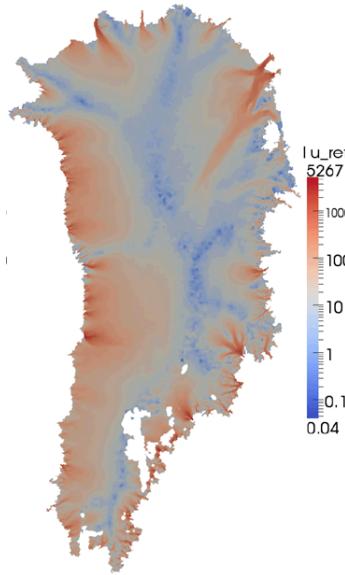
# Regional Refinement (work-in-progress using MPAS LI)



Unstructured Delaunay triangle mesh

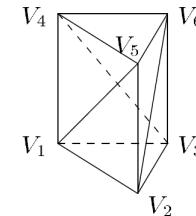


|computed surface velocity| [m/yr]



|reference surface velocity| [m/yr]

**Mesh Details**  
Min  $h$ : 4 km  
Max  $h$ : 15 km  
32K nodes



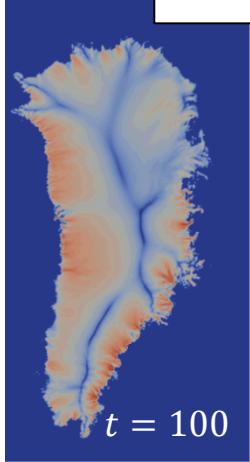
- **Step 1:** determine geometry boundaries and possible holes (**MATLAB**).
- **Step 2:** generate uniform triangular mesh and refine based on **gradient of measured surface velocity (Triangle – a 2D meshing software)**.
- **Step 3:** obtain 3D mesh by extruding the 2D mesh in the vertical direction as **prism**, then splitting each prism into 3 **tetrahedra (Albany)**.

**Courtesy of:**  
M. Perego  
(SNL)

# Dynamic Runs Using Dycore Interfaces (work-in-progress)

Surface velocity [m/yr]

**CISM-  
Albany**



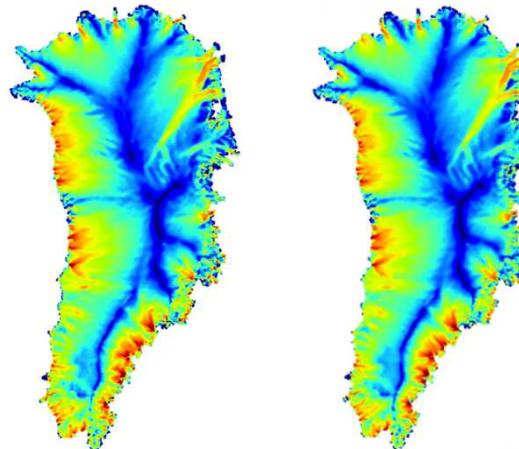
$t = 0$

$t = 100$

**100 year 4 km GIS  
transient run using  
converges on Titan  
*out-of-the box*  
( $\Delta t = 0.1$  years)!**

**MPAS LI-  
Albany**

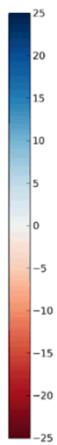
Surface velocity [km/yr]



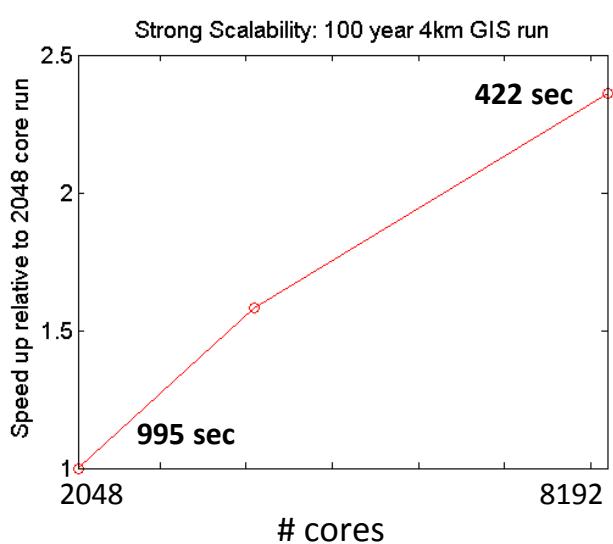
$t = 0$

$t = 13$

Elevation change [m]



**Strong  
scaling study:**  
2.35  $\times$   
speedup with  
4  $\times$  # cores



**Courtesy of:**  
P. Worley  
(ORNL)

- Preliminary (proof-of-concept, 5 km GIS) result up to  $t = 13$  years (CFL violated with  $\Delta t = 0.1$  years).
- MPAS temperature solve is work-in-progress.

**Courtesy of:** M. Perego (SNL);  
M. Hoffman (LANL)

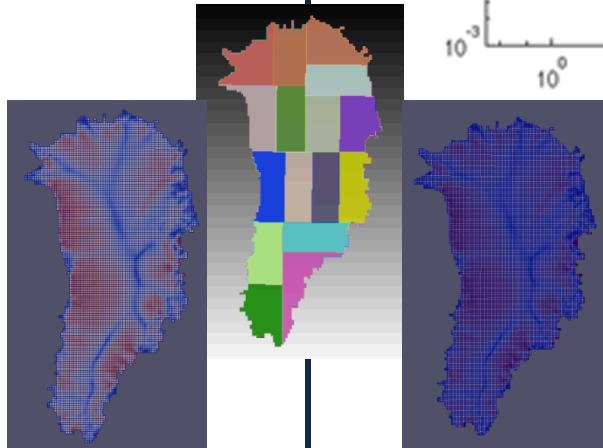
# Greenland Mesh Convergence Study

## z Mesh-Convergence Study

How many vertical layers are needed?

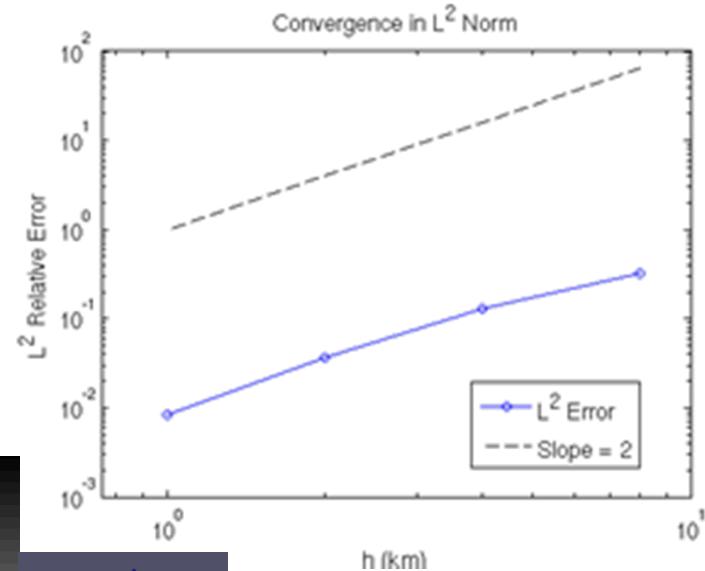
# z layers/ # cores	# dofs	Total Time – Mesh Import	Solution Average	Error
5/128	21.0M	519.4 sec	2.827	3.17e-2
10/256	38.5M	525.4 sec	2.896	8.04e-3
20/512	73.5M	499.8 sec	2.924	2.01e-3
40/1024	143M	1282 sec	2.937	4.96e-4
80/2048	283M	1294 sec	2.943	1.20e-4
160/4096	563M	1727 sec	2.945	2.76e-5

- z mesh-convergence study for 1 km GIS.
- Important to do **partition** of **2D mesh** for parallel refined mesh (center).
- QOI (solution average) does change with z-refinement.



## Full 3D Mesh-Convergence Study

Are the GIS problems resolved?  
Is theoretical convergence rate achieved?

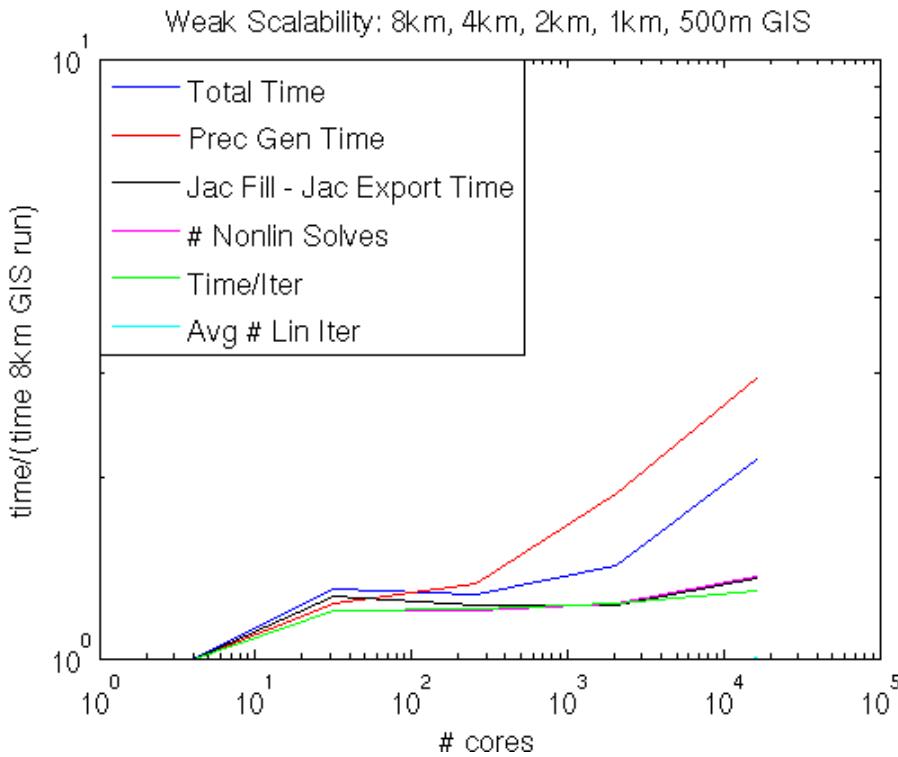


- **Full 3D mesh convergence** study (uniform refinement, fixed data w.r.t. reference solution) for GIS gives theoretical convergence rate of 2 in  $L^2$  norm.

# Greenland Controlled Weak Scalability Study

Courtesy of:  
R. Tuminaro (SNL)

## New ML preconditioner

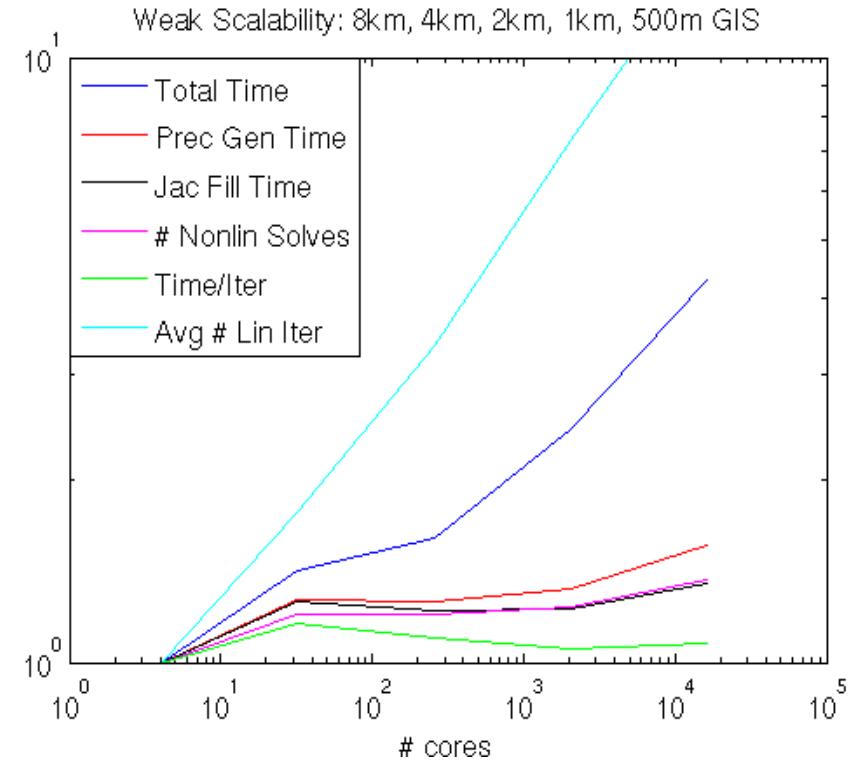


4 cores  
334K dofs  
8 km GIS,  
5 vertical layers

$\times 8^4$   
scale up

16,384 cores  
**1.12B dofs(!)**  
0.5 km GIS,  
80 vertical layers

## ILU preconditioner



- **Significant improvement** in scalability with new ML preconditioner over ILU preconditioner!

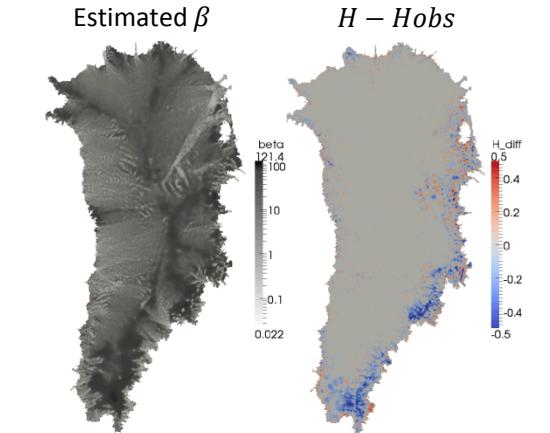
# Deterministic Inversion: Estimation of Ice Sheet Initial State

## First-Order Stokes PDE Constrained Optimization Problem:

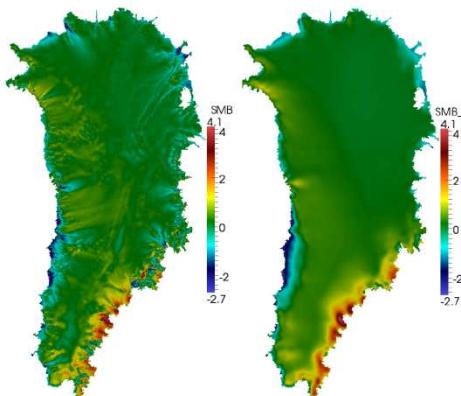
$$J(\beta, H) = \frac{1}{2} \alpha \int_{\Gamma} |\operatorname{div}(\mathbf{U}H) - SMB|^2 ds + \frac{1}{2} \alpha_v \int_{\Gamma_{top}} |\mathbf{u} - \mathbf{u}^{obs}|^2 ds + \frac{1}{2} \alpha_H \int_{\Gamma_{top}} |H - H^{obs}|^2 ds + \mathcal{R}(\beta) + \mathcal{R}(H)$$

- Minimize difference between:
  - Computed divergence flux and measured **surface mass balance (SMB)**.
  - Computed and measured **surface velocity ( $\mathbf{u}^{obs}$ )**.
  - Computed and **reference thickness ( $H^{obs}$ )**.
- Control variables:
  - **Basal friction ( $\beta$ )**.
  - **Thickness ( $H$ )**.
- Software tools: **LifeV** (assembly), **Trilinos** (linear/nonlinear solvers), **ROL** (gradient-based optimization).

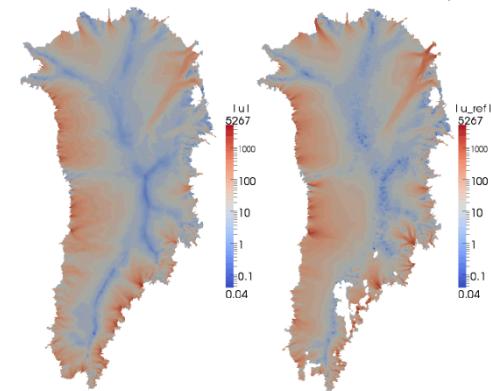
Courtesy of: M. Perego  
(SNL); S. Price (LANL);  
G. Stadler (UT)



Estimated divergence (left) vs.  
reference SMB (right)



Estimated (left) vs. reference surface velocity (right)



# Bayesian Inversion/Uncertainty Quantification (work-in-progress)

**Difficulty in UQ: “Curse of Dimensionality”**

The  $\beta$ -field inversion problem has  $O(20,000)$  dimensions!

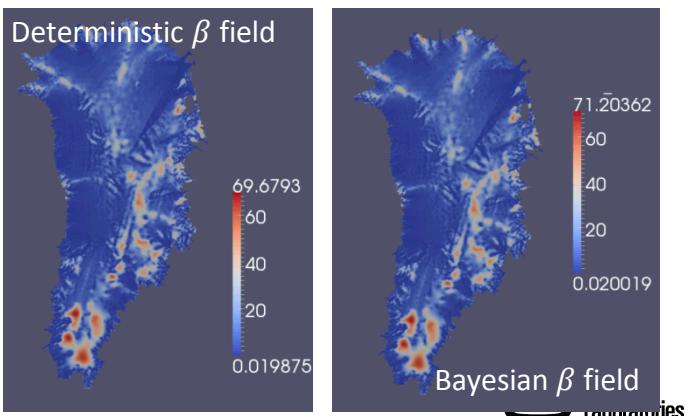
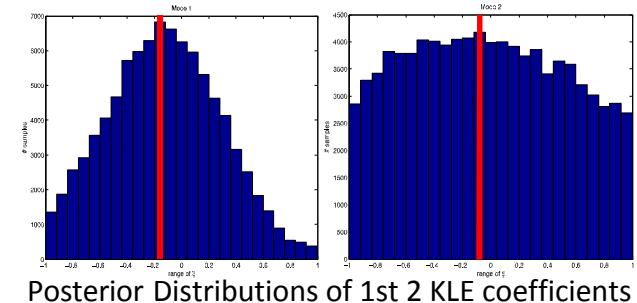
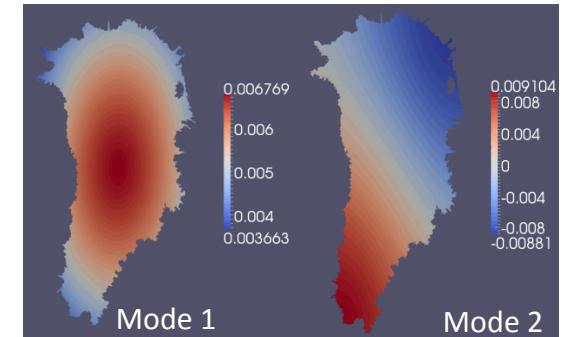
- **Step 1:** Model reduction (from  $O(20,000)$  parameters to  $O(5)$  parameters) using ***Karhunen-Loeve Expansion*** (or ***eigenvectors of Hessian***, in future) of basal sliding field:

$$\log(\beta(\omega)) = \bar{\beta} + \sum_{k=1}^K \sqrt{\lambda_k} \phi_k \xi_k(\omega)$$

- **Step 2: Polynomial Chaos Expansion (PCE)** emulator for mismatch over surface velocity discrepancy.
- **Step 3: Markov Chain Monte Carlo (MCMC)** calibration using PCE emulator.



**With:**  
J. Jakeman,  
M. Eldred (SNL)

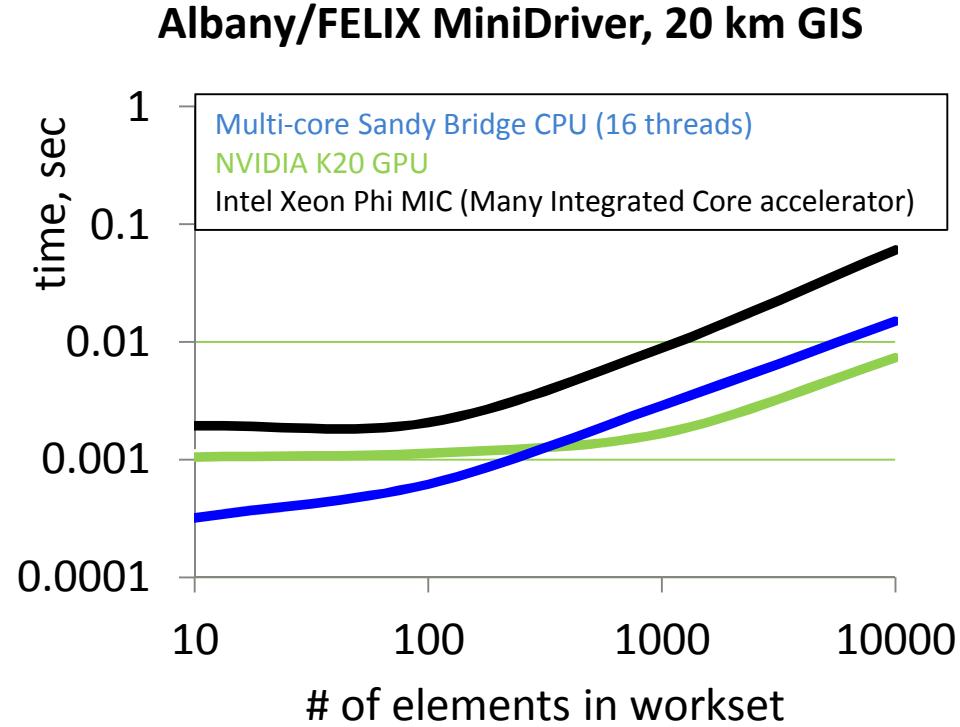


# Conversion to Performance-Portable Kernels (work-in-progress)

Trilinos

We need to be able to run Albany/FELIX on ***new architecture machines*** (hybrid systems) and ***manycore devices*** (multi-core CPU, NVIDIA GPU, Intel Xeon Phi, etc.).

- **Kokkos**: Trilinos C++ library that provides performance portability across diverse devices with different memory models.
- With Kokkos, you write an algorithm once, and just change a template parameter to get the optimal data layout for your hardware.
- Albany/FELIX ***finite element assembly*** has been converted to ***Kokkos functors*** in Albany/FELIX MiniDriver (I. Demeshko).



Courtesy of: I. Demeshko (SNL)



# Summary and Future Work

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## Summary:

- Albany/FELIX first-order Stokes dycore can be run on Greenland/Antarctica problems discretized by several kinds of meshes and is nearly ready for science.
- The Albany/FELIX dycore has been hooked up to the CISM and MPAS codes.
- Convergence, scalability and robustness of the Albany/FELIX code has been verified.

Verification, Greenland/Antarctica runs, scalability, robustness, UQ, advanced analysis, performance-portability: all attained in **~2 FTE of effort!**

## Ongoing/future work:

- Mature dynamic evolution capabilities.
- Perform deterministic and stochastic initialization runs.
- Finish conversion to performance-portable kernels.
- Journal article on Albany/FELIX (I. Kalashnikova, A. Salinger, M. Perego, R. Tuminaro, S. Price, M. Hoffman).
- Delivering code to users in climate community.
- Coupling to community earth system model (CESM).



# Funding/Acknowledgements

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**PISCEES team members:** *W. Lipscomb, S. Price, M. Hoffman, A. Salinger, M. Perego, I. Kalashnikova, R. Tuminaro, P. Jones, K. Evans, P. Worley, M. Gunzburger, C. Jackson;*

**Trilinos/Dakota collaborators:** *E. Phipps, M. Eldred, J. Jakeman, L. Swiler.*

**Thank you! Questions?**



## References

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- [3] M. Perego, M. Gunzburger, J. Burkardt. "Parallel finite-element implementation for higher-order ice-sheet models". *J. Glaciology* **58**(207) 76-88 (2012).
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- [5] A.G. Salinger, E. T. Phipps, R.A. Bartlett, G.A. Hansen, **I. Kalashnikova**, J.T. Ostien, W. Sun, Q. Chen, A. Mota, R.A. Muller, E. Nielsen, X. Gao. "Albany: A Component-Based Partial Differential Equation Code Build on Trilinos", submitted to *ACM. Trans. Math. Software*.
- [6] M. Hoffman, **I. Kalashnikova**, M. Perego, S. Price, A. Salinger, R. Tuminaro. "A New Parallel, Scalable and Robust Finite Element Higher-Order Stokes Ice Sheet Dycore Built for Advanced Analysis", in preparation for submission to *The Cryosphere*.