

# An Update on the Albany/FELIX First-Order Stokes Finite Element Solver & its Coupling to Land Ice Dycores

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Irina Demeshko.*

Sandia National Laboratories\*

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Breckenridge, Colorado

\*Sandia is a multiprogram laboratory operated by Sandia corporation, a Lockheed Martin Company, for the U.S. Department of Energy under contract DE-AC04-94AL85000.

# PISCEES Project & the Albany/FELIX First-Order Stokes Dycore

To **develop** and **support** a robust and scalable unstructured grid finite element land ice dycore based on the “first-order” (FO) Stokes physics → **Albany/FELIX dycore**

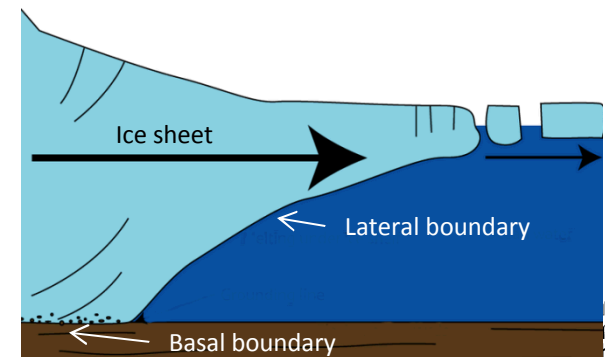
- **Finite element method.**
- Parallel, unstructured grid with **partitioning**.
- **Automatic differentiation** for (exact) Jacobians.
- Globalized **Newton’s method** nonlinear solver.
- Preconditioned (ILU or algebraic multigrid) iterative **Krylov linear solvers**.
- **Performance-portable kernels** to run on new architecture machines / GPUs (in progress).
- **Analysis tools**: UQ, sensitivity analysis, optimization.
- **Software tools**: git / cmake / ctest / jenkins.

## First Order Stokes Model

$$\begin{cases} -\nabla \cdot (2\mu \dot{\epsilon}_1) = -\rho g \frac{\partial s}{\partial x} \\ -\nabla \cdot (2\mu \dot{\epsilon}_2) = -\rho g \frac{\partial s}{\partial y} \end{cases}$$

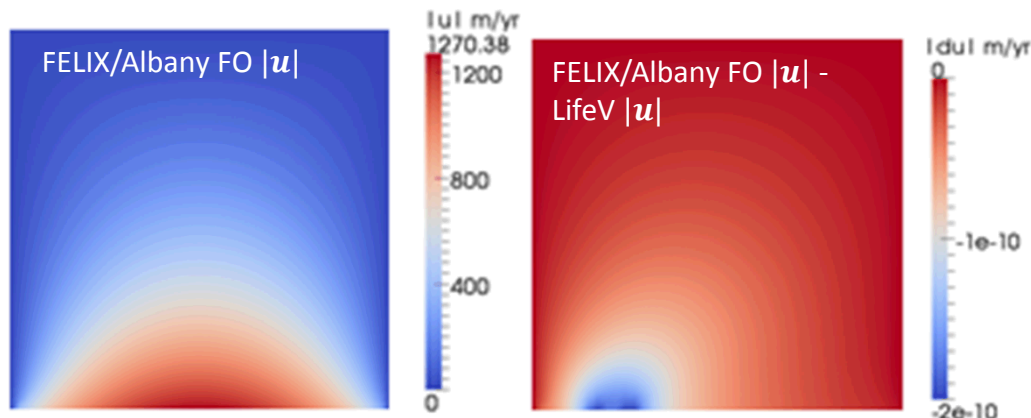
## Boundary conditions

- |               |                 |
|---------------|-----------------|
| • No-slip     | • Basal Sliding |
| • Stress-free | • Open-ocean    |



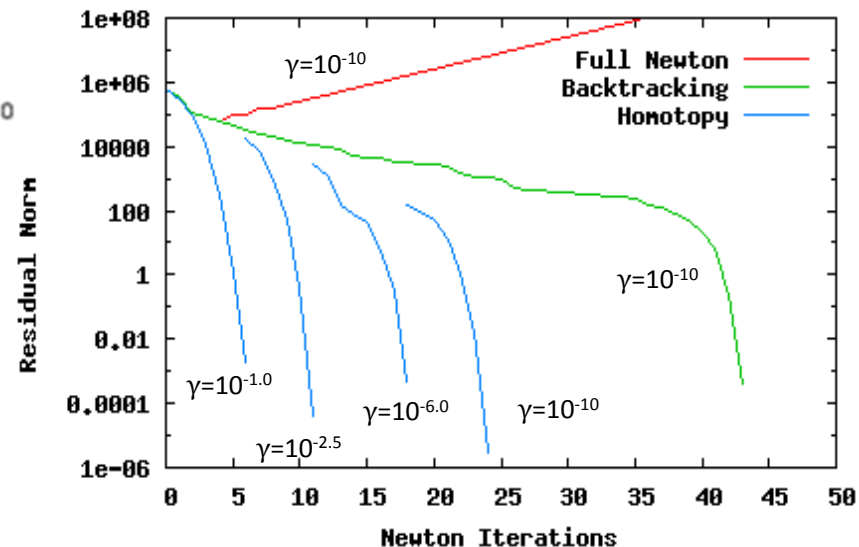
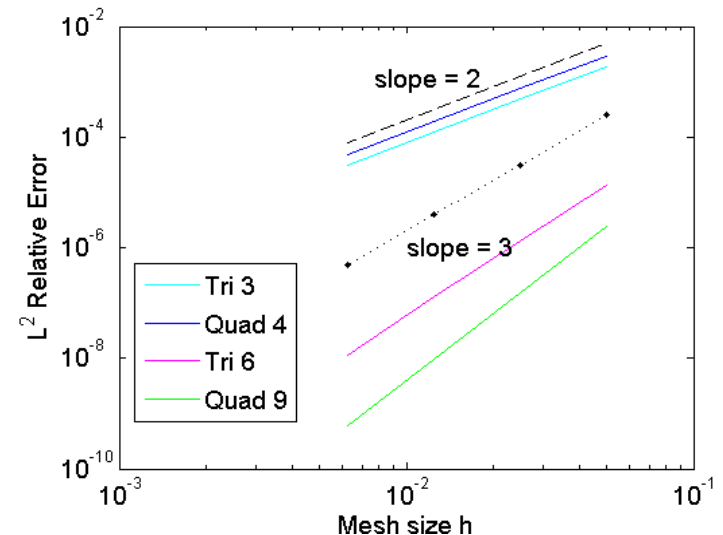
# Code Verification and Performance

- Implementation of PDEs + BCs (no-slip, stress-free, basal sliding, open-ocean) has been **verified** through MMS tests (right) and code-to-code comparisons (confined-shelf, below).

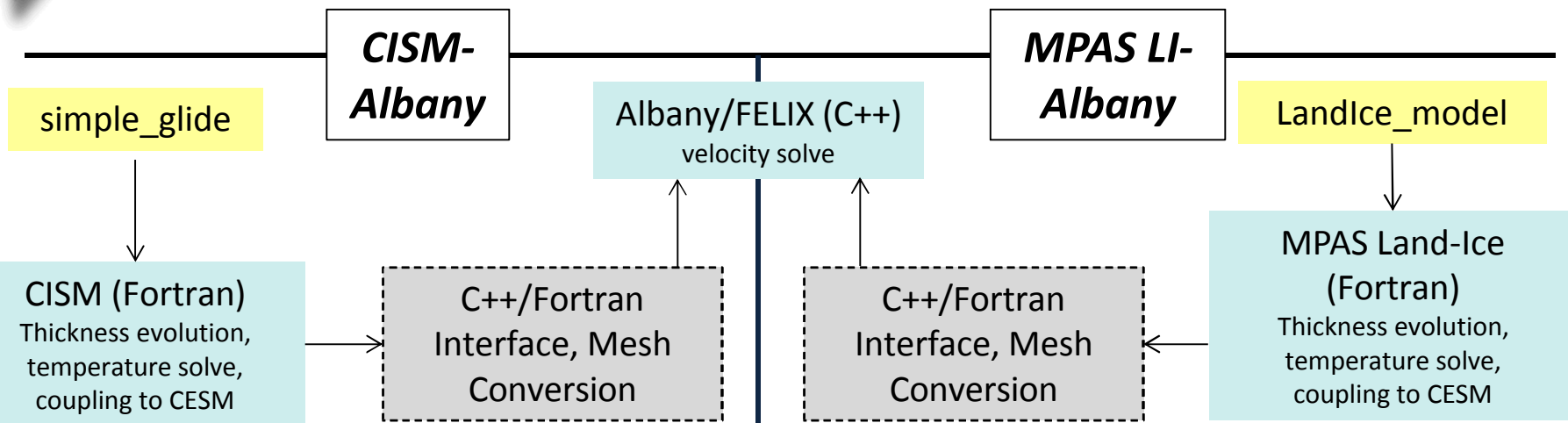


- Robust** nonlinear solves (Newton converges out-of-the-box!) with **homotopy** continuation of  $\gamma$  in Glen's law viscosity:

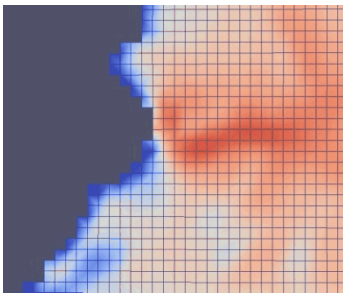
$$\mu = \frac{1}{2} A^{-\frac{1}{n}} \left( \frac{1}{2} \sum_{ij} \dot{\epsilon}_{ij}^2 + \gamma \right)^{\left( \frac{1}{2n} - \frac{1}{2} \right)}$$



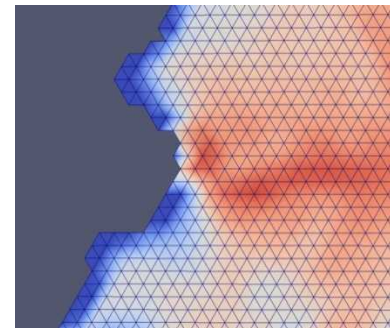
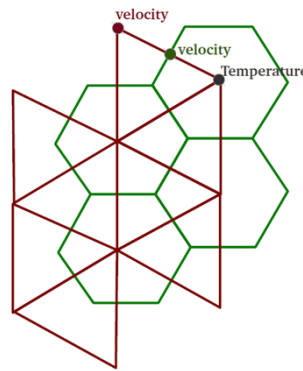
# Dycore Interfaces and Meshes



- Structured hexahedral meshes (rectangles extruded to hexes).



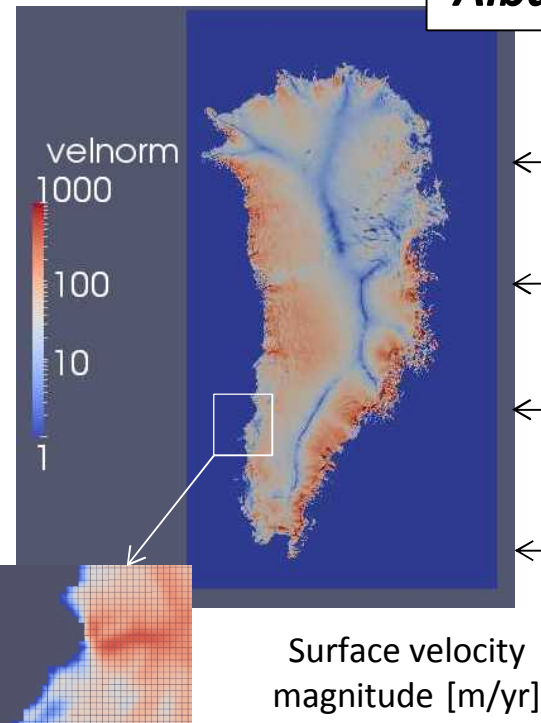
- Tetrahedral meshes (dual of hexagonal mesh, extruded to tets).



*Courtesy of:*  
M. Perego  
(SNL)

# Steady Runs Using Dycore Interfaces

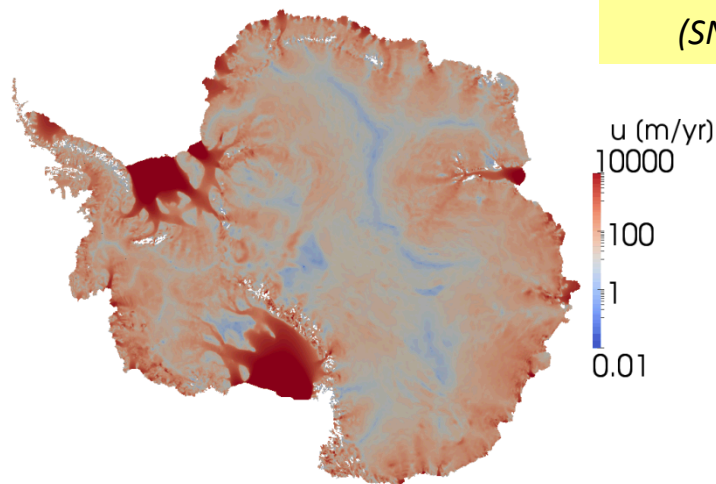
**CISM-  
Albany**



Surface velocity  
magnitude [m/yr]

**1 km resolution GIS**  
16.6M hex elements  
37M unknowns  
Constant  $\beta$ ,  $T$  (no-slip)

**MPAS LI -  
Albany**



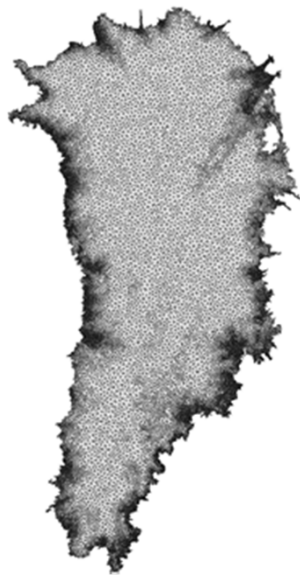
Surface velocity magnitude [m/yr]

**15 km - 2 km resolution Antarctica**  
34.9M tet elements  
3.3M unknowns  
Variable  $\beta$ ,  $T$

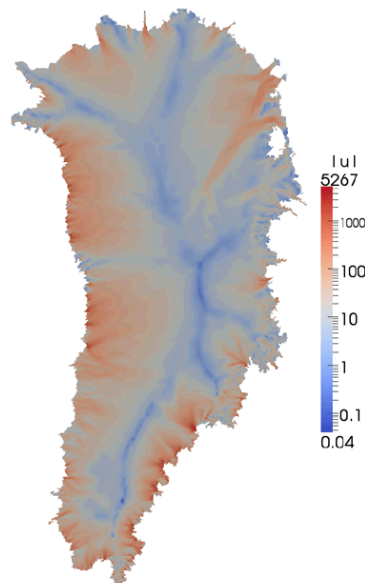
Albany/FELIX  
converged out-of-  
the-box for these  
fine resolution  
problems!

Courtesy of:  
M. Perego  
(SNL)

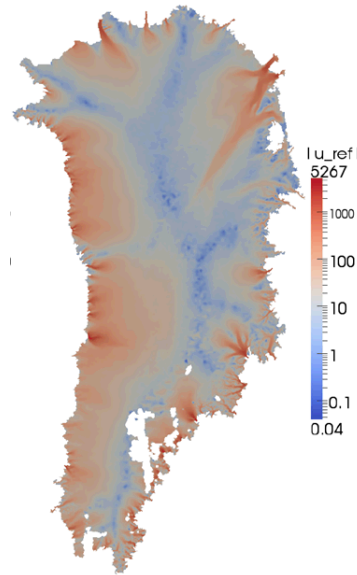
# Regional Refinement (work-in-progress using MPAS LI)



Unstructured Delaunay  
triangle mesh

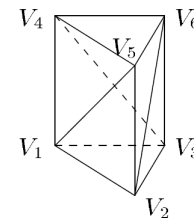


|computed surface  
velocity| [m/yr]



|reference surface  
velocity| [m/yr]

**Mesh Details**  
Min  $h$ : 4 km  
Max  $h$ : 15 km  
32K nodes



- **Step 1:** determine geometry boundaries and possible holes (*MATLAB*).
- **Step 2:** generate uniform triangular mesh and refine based on *gradient of measured surface velocity* (*Triangle – a 2D meshing software*).
- **Step 3:** obtain 3D mesh by extruding the 2D mesh in the vertical direction as *prism*, then splitting each prism into 3 *tetrahedra* (*Albany*).

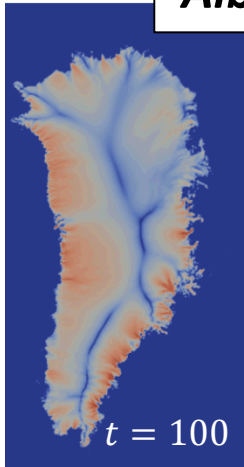
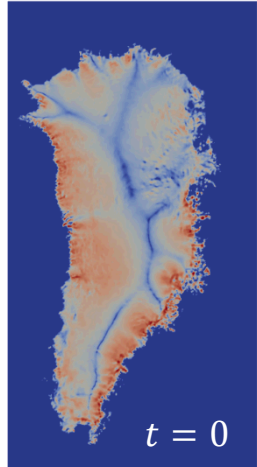
**Courtesy of:**  
*M. Perego*  
(*SNL*)



# Dynamic Runs Using Dycore Interfaces (work-in-progress)

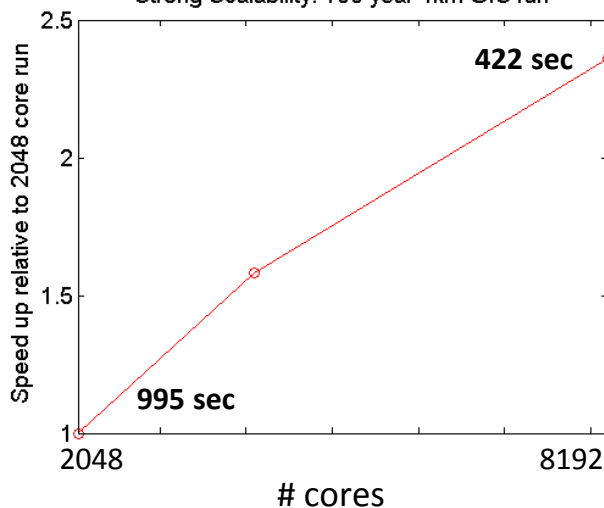
## CISM-Albany

Surface velocity [m/yr]



**100 year** 4 km GIS transient run using converges on Titan **out-of-the box** ( $\Delta t = 0.1$  years)!

Strong Scalability: 100 year 4km GIS run

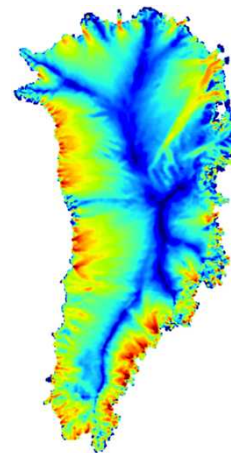


**Strong scaling study:**  
2.35  $\times$  speedup with 4  $\times$  # cores

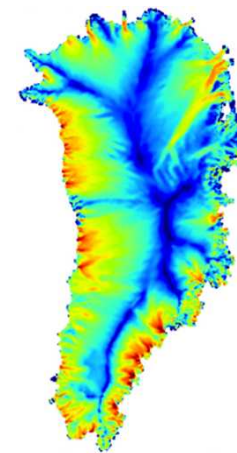
**Courtesy of:**  
P. Worley (ORNL)

## MPAS LI-Albany

Surface velocity [km/yr]

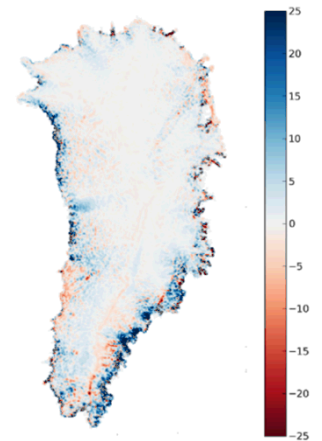


$t = 0$



$t = 13$

Elevation change [m]



- Preliminary (proof-of-concept, 5 km GIS) result up to  $t = 13$  years (CFL violated with  $\Delta t = 0.1$  years).
- MPAS temperature solve is work-in-progress.

**Courtesy of:** M. Perego (SNL);  
M. Hoffman (LANL)

# Greenland Mesh Convergence Study

## z Mesh-Convergence Study

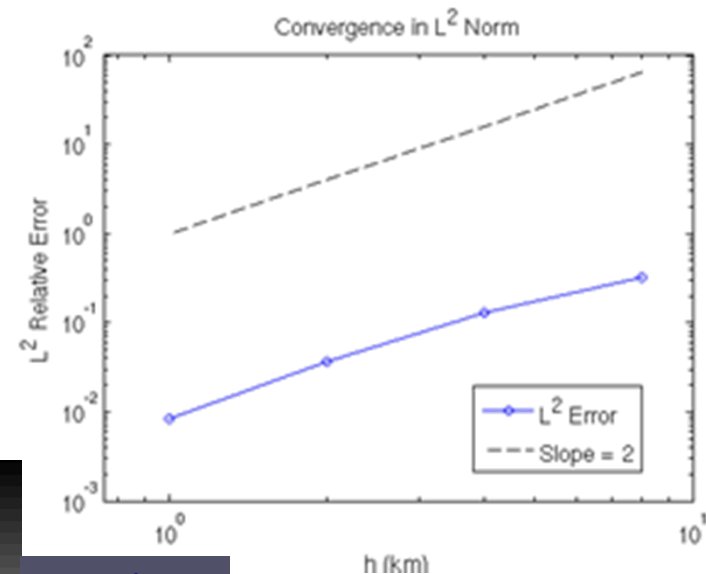
*How many vertical layers are needed?*

# z layers/ # cores	# dofs	Total Time – Mesh Import	Solution Average	Error
5/128	21.0M	519.4 sec	2.827	3.17e-2
10/256	38.5M	525.4 sec	2.896	8.04e-3
20/512	73.5M	499.8 sec	2.924	2.01e-3
40/1024	143M	1282 sec	2.937	4.96e-4
80/2048	283M	1294 sec	2.943	1.20e-4
160/4096	563M	1727 sec	2.945	2.76e-5

- z mesh-convergence study for 1 km GIS.
- Important to do **partition** of **2D mesh** for parallel refined mesh (center).
- QOI (solution average) does change with z-refinement.

## Full 3D Mesh-Convergence Study

*Are the GIS problems resolved?  
Is theoretical convergence rate achieved?*



- **Full 3D mesh convergence** study (uniform refinement, fixed data w.r.t. reference solution) for GIS gives theoretical convergence rate of 2 in  $L^2$  norm.

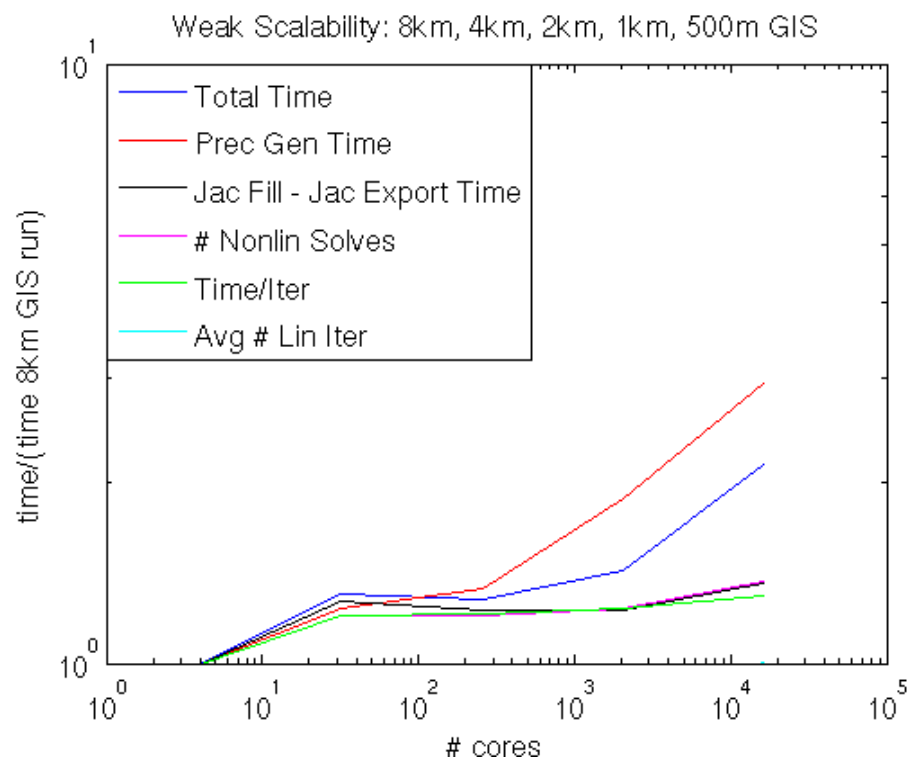




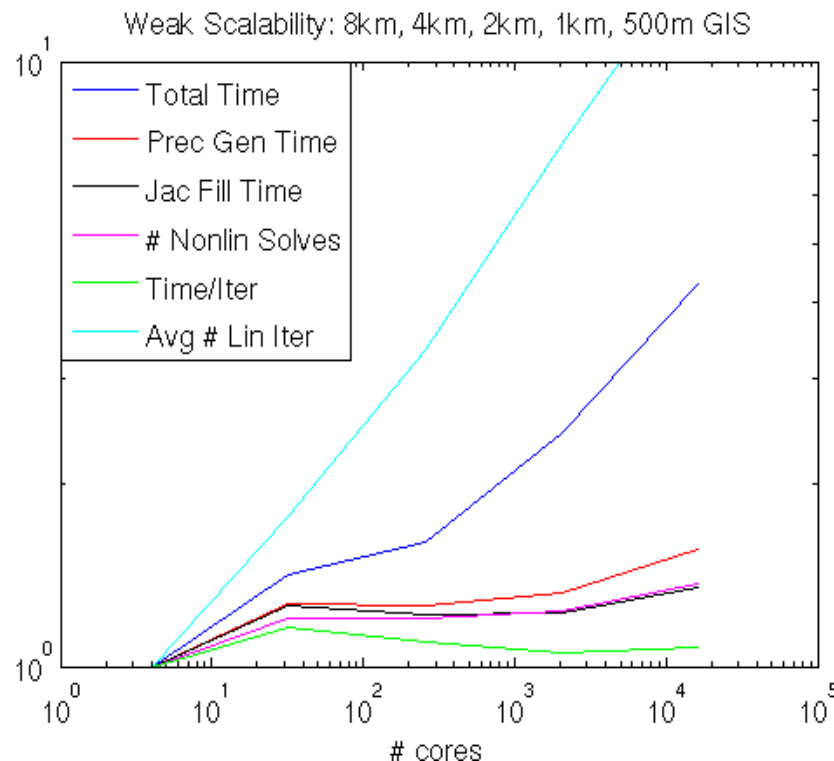
# Greenland Controlled Weak Scalability Study

*Courtesy of:  
R. Tuminaro (SNL)*

## New ML preconditioner



## ILU preconditioner



4 cores  
334K dofs  
8 km GIS,  
5 vertical layers

$\times 8^4$   
scale up

16,384 cores  
**1.12B dofs(!)**  
0.5 km GIS,  
80 vertical layers

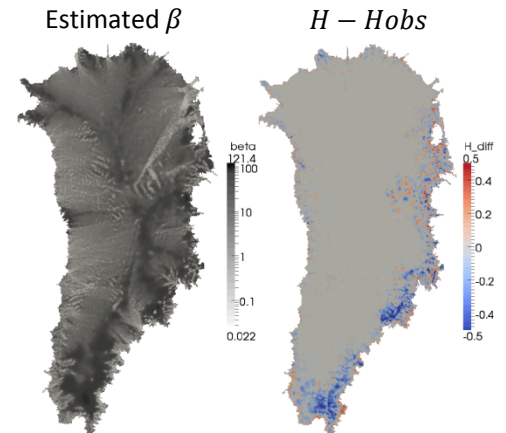
- **Significant improvement** in scalability with new ML preconditioner over ILU preconditioner!

# Deterministic Inversion: Estimation of Ice Sheet Initial State

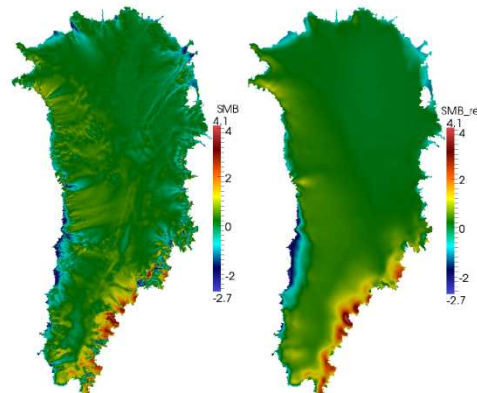
## First-Order Stokes PDE Constrained Optimization Problem:

$$J(\beta, H) = \frac{1}{2} \alpha \int_{\Gamma} |\operatorname{div}(\mathbf{U}H) - \operatorname{SMB}|^2 ds + \frac{1}{2} \alpha_v \int_{\Gamma_{top}} |\mathbf{u} - \mathbf{u}^{obs}|^2 ds + \frac{1}{2} \alpha_H \int_{\Gamma_{top}} |H - H^{obs}|^2 ds + \mathcal{R}(\beta) + \mathcal{R}(H)$$

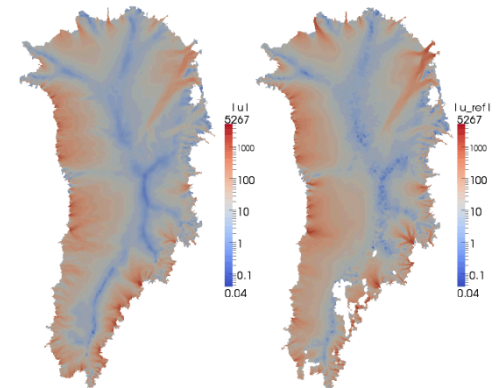
- Minimize difference between:
  - Computed divergence flux and measured **surface mass balance (SMB)**.
  - Computed and measured **surface velocity** ( $\mathbf{u}^{obs}$ ).
  - Computed and **reference thickness** ( $H^{obs}$ ).
- Control variables:
  - Basal friction** ( $\beta$ ).
  - Thickness** ( $H$ ).
- Software tools: **LifeV** (assembly), **Trilinos** (linear/nonlinear solvers), **ROL** (gradient-based optimization).



Estimated divergence (left) vs. reference SMB (right)



Estimated (left) vs. reference surface velocity (right)



**Courtesy of:** M. Perego (SNL); S. Price (LANL); G. Stadler (UT)

# Bayesian Inversion/Uncertainty Quantification (work-in-progress)

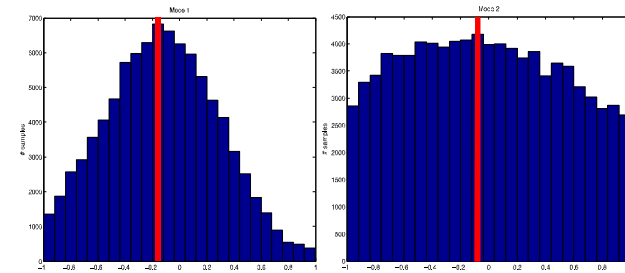
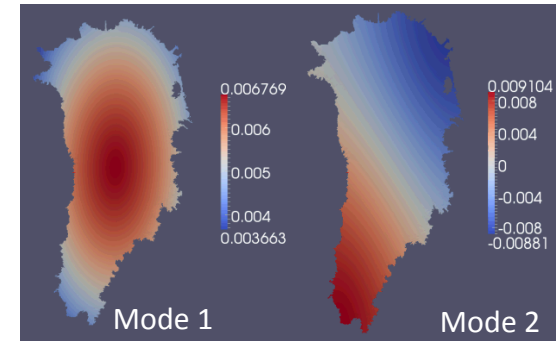
## Difficulty in UQ: “Curse of Dimensionality”

The  $\beta$ -field inversion problem has  $O(20,000)$  dimensions!

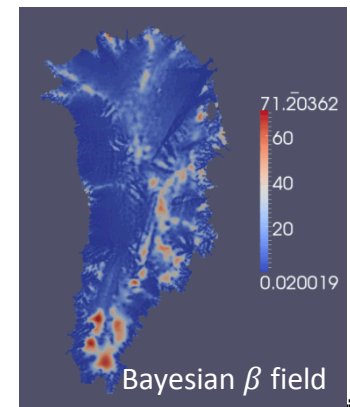
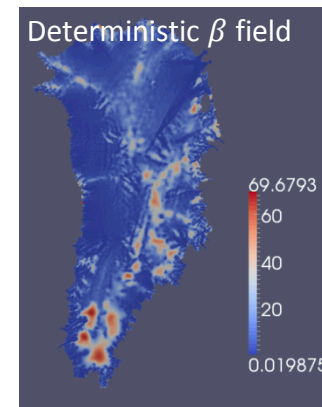
- Step 1:** Model reduction (from  $O(20,000)$  parameters to  $O(5)$  parameters) using **Karhunen-Loeve Expansion** (or **eigenvectors of Hessian**, in future) of basal sliding field:

$$\log(\beta(\omega)) = \bar{\beta} + \sum_{k=1}^K \sqrt{\lambda_k} \phi_k \xi_k(\omega)$$

- Step 2:** **Polynomial Chaos Expansion (PCE)** emulator for mismatch over surface velocity discrepancy.
- Step 3:** **Markov Chain Monte Carlo (MCMC)** calibration using PCE emulator.



Posterior Distributions of 1st 2 KLE coefficients



**With:**  
J. Jakeman,  
M. Eldred (SNL)

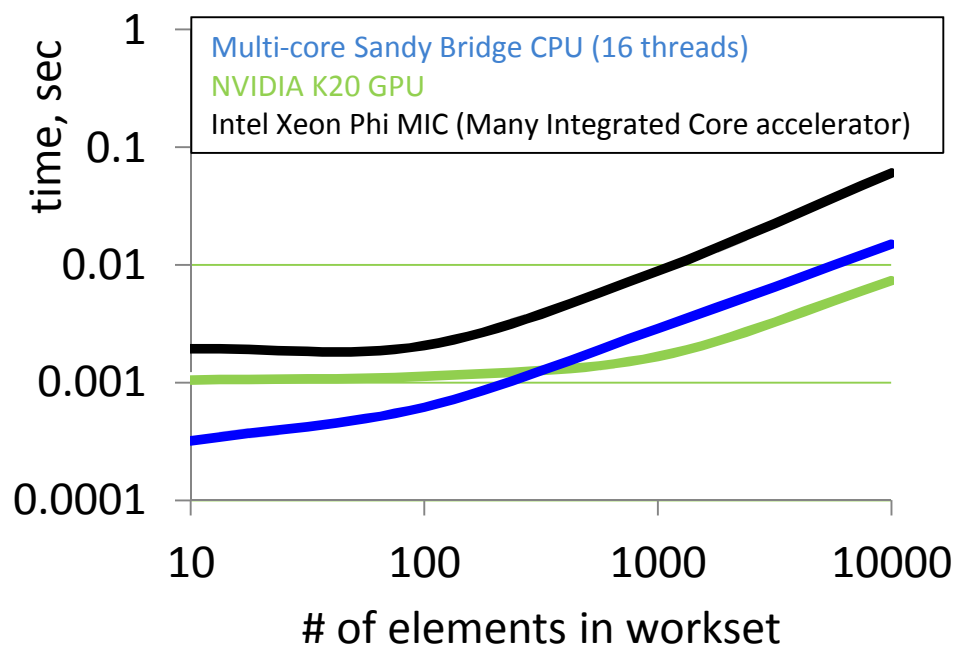


# Conversion to Performance-Portable Kernels (work-in-progress)

We need to be able to run Albany/FELIX on **new architecture machines** (hybrid systems) and **manycore devices** (multi-core CPU, NVIDIA GPU, Intel Xeon Phi, etc.) .

- **Kokkos**: Trilinos C++ library that provides performance portability across diverse devices with different memory models.
- With Kokkos, you write an algorithm once, and just change a template parameter to get the optimal data layout for your hardware.
- Albany/FELIX **finite element assembly** has been converted to **Kokkos functors** in Albany/FELIX MiniDriver (I. Demeshko).

Albany/FELIX MiniDriver, 20 km GIS



Courtesy of: I. Demeshko (SNL)



# Summary and Future Work

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## Summary:

- Albany/FELIX first-order Stokes dycore can be run on Greenland/Antarctica problems discretized by several kinds of meshes and is nearly ready for science.
- The Albany/FELIX dycore has been hooked up to the CISM and MPAS codes.
- Convergence, scalability and robustness of the Albany/FELIX code has been verified.

Verification, Greenland/Antarctica runs, scalability, robustness, UQ, advanced analysis, performance-portability: all attained in **~2 FTE of effort!**

## Ongoing/future work:

- Mature dynamic evolution capabilities.
- Perform deterministic and stochastic initialization runs.
- Finish conversion to performance-portable kernels.
- Journal article on Albany/FELIX (I. Kalashnikova, A. Salinger, M. Perego, R. Tuminaro, S. Price, M. Hoffman).
- Delivering code to users in climate community.
- Coupling to community earth system model (CESM).



# Funding/Acknowledgements

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**PISCEES team members:** W. Lipscomb, S. Price, M. Hoffman, A. Salinger, M. Perego, I. Kalashnikova, R. Tuminaro, P. Jones, K. Evans, P. Worley, M. Gunzburger, C. Jackson;  
**Trilinos/Dakota collaborators:** E. Phipps, M. Eldred, J. Jakeman, L. Swiler.

**Thank you! Questions?**



# References

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- [2] F. Pattyn *et al.* “Benchmark experiments for higher-order and full-Stokes ice sheet models (ISMIP-HOM)”. *Cryosphere* **2**(2) 95-108 (2008).
- [3] M. Perego, M. Gunzburger, J. Burkardt. “Parallel finite-element implementation for higher-order ice-sheet models”. *J. Glaciology* **58**(207) 76-88 (2012).
- [4] J. Dukowicz, S.F. Price, W.H. Lipscomb. “Incorporating arbitrary basal topography in the variational formulation of ice-sheet models”. *J. Glaciology* **57**(203) 461-466 (2011).
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- [6] M. Hoffman, **I. Kalashnikova**, M. Perego, S. Price, A. Salinger, R. Tuminaro. "A New Parallel, Scalable and Robust Finite Element Higher-Order Stokes Ice Sheet Dycore Built for Advanced Analysis", in preparation for submission to *The Cryosphere*.