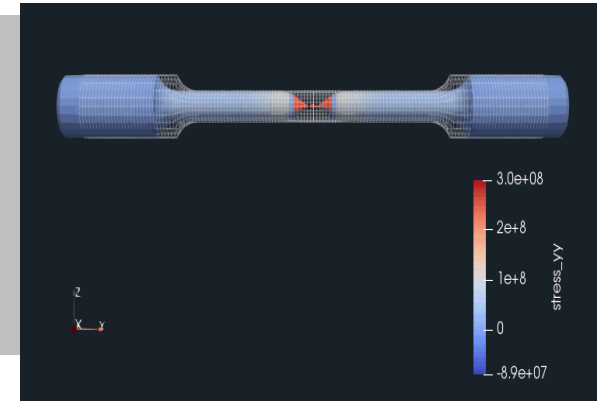
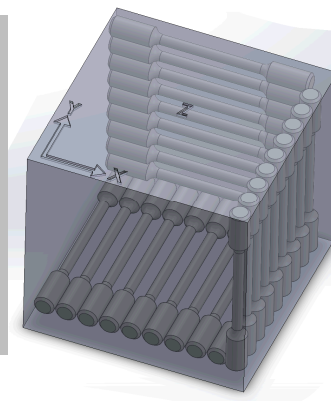
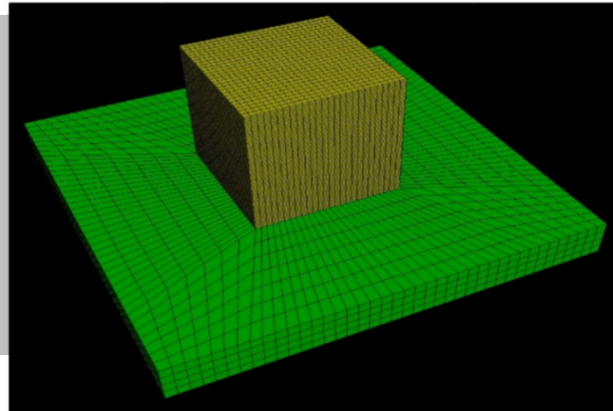
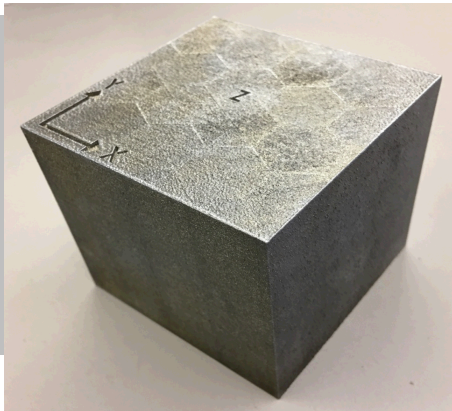


Investigation of Dynamic Strain Aging Behavior of Stainless Steel for Additive Manufacturing Applications

Phi Nguyen | University of California, San Diego  
Mentors: Coleman Alleman & Michael Stender  
Sandia Summer Intern | Sept 14, 2017

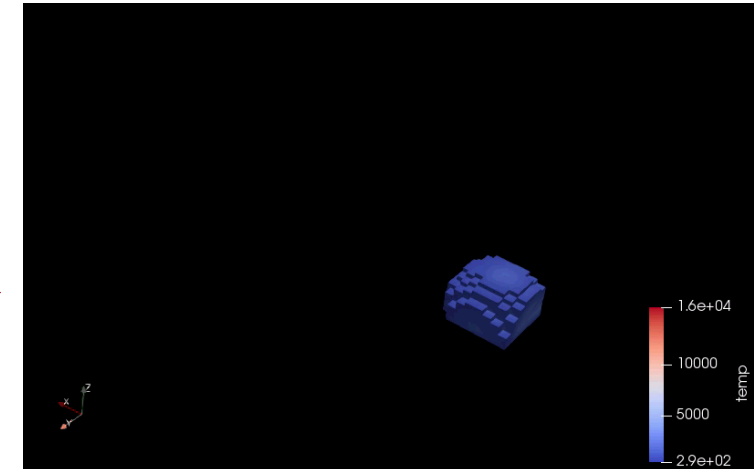
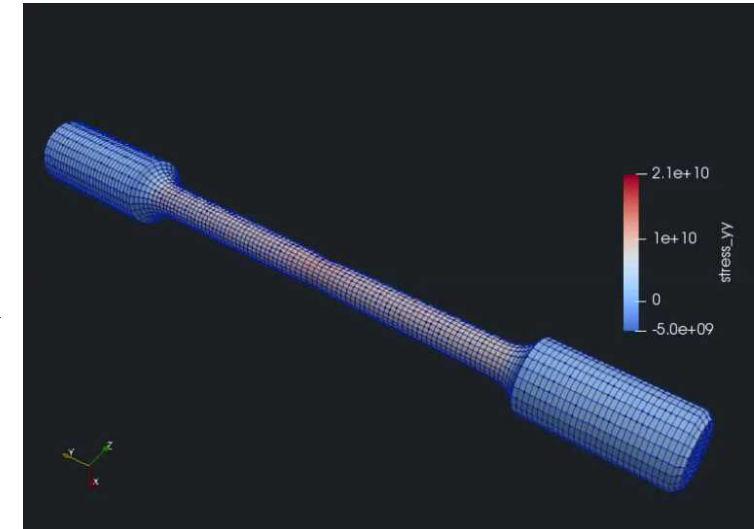


## Investigation of Dynamic Strain Aging Behavior of Stainless Steel for Additive Manufacturing Applications

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# Motivations

- Understand the behavior of the current dynamic strain aging model with higher temperatures
- Calibrate a physically-based constitutive model with experimental data
- Test the constitutive model fit on a tensile specimen to predict localization leading to failure
- Map the result from the processing simulation including residual stress and internal state variables onto the experimental specimen



F. Lin 2017

# Constitutive Material Model (DSA/BCJ\_MEM)

The hypoelastic constitutive material model

$$\dot{\sigma} = E(\dot{\epsilon} - \dot{\epsilon}_p)$$

With the evolution of the plastic flow rule

$$\dot{\epsilon}^p = f(\theta) \sinh \left\langle \frac{\sigma}{\kappa + Y(\theta)} - 1 \right\rangle^{n(\theta)}$$

Evolution of the isotropic hardening variable

$$\dot{\kappa} = [H(\theta) - R_d(\theta)\kappa]\dot{\epsilon}_p - \boxed{R_s(\theta)\kappa \sinh(Q_s(\theta)\kappa)}$$

Evolution of the kinematic hardening variable

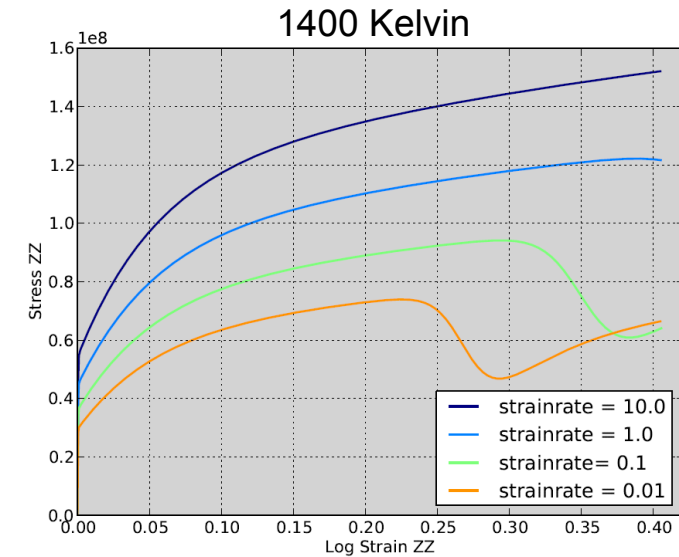
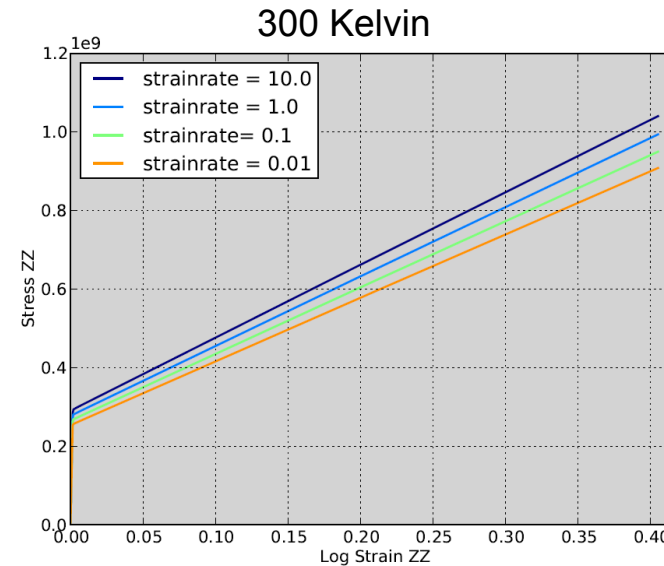
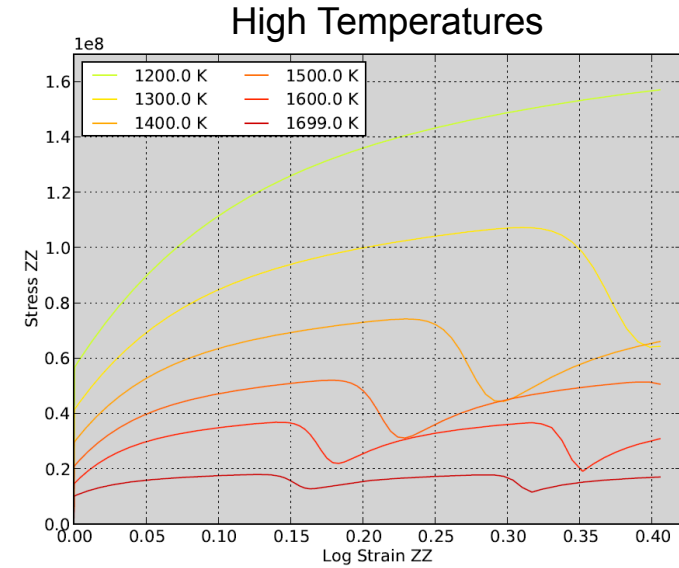
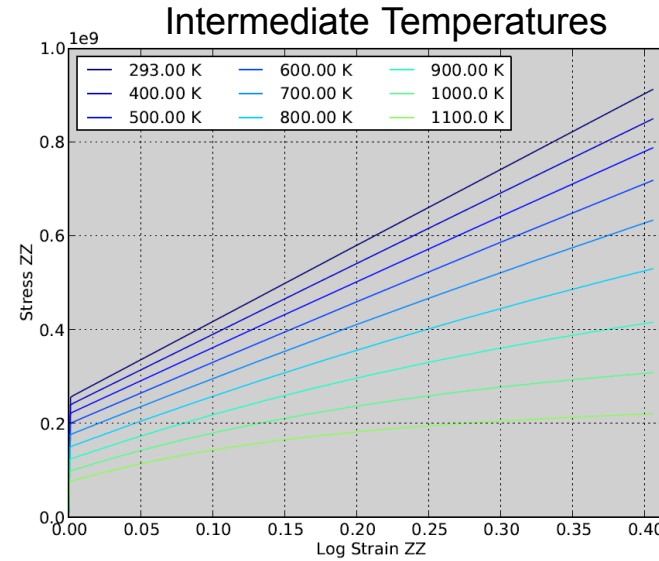
$$\dot{\alpha} = \boxed{h(\theta)}\|D^p\| - \sqrt{\frac{3}{2}}\dot{\epsilon}_p R_d(\theta)\alpha\|\alpha\|$$

Nomenclature	
$f(\theta)$	Flow Rule Coefficient
$n(\theta)$	Flow Rule Exponent
$Y(\theta)$	Temp Dependent Initial Yield Strength
$H(\theta)$	Hardening Parameter
$R_d(\theta)$	Dynamic Recovery
$R_s(\theta)$	Static Recovery
$Q_s(\theta)$	Sinh Static Recovery
$h(\theta)$	Backstress Hardening

# Single Element Uniaxial Tension Test for Baseline DSA Parameters with Varying Temperatures & Strain Rate

## Baseline DSA Parameters

$f_1$	9.178e-02
$n_2$	5.699e+03
$Y_0$	5.264e+09
$Y_1$	2.688e+05
$Y_2$	1.87e-03
$Y_3$	8.683e+02
$Y_4$	3.316e+01
$H_\mu$	0.01
$Rd_1$	8.565e+02
$Rd_2$	5.419e+03

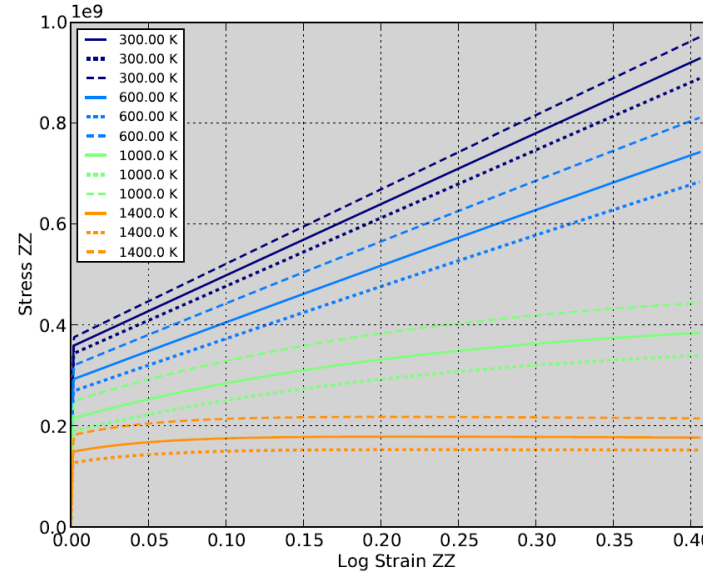


# BCJ\_MEM Flow Rule

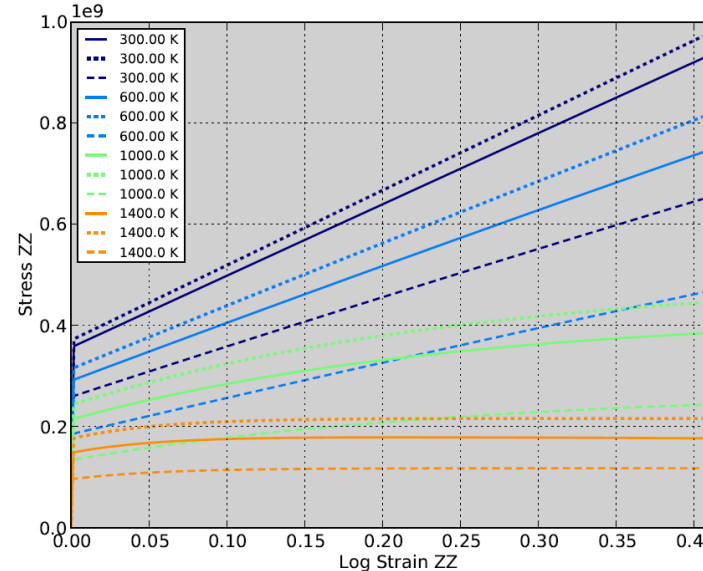
With the evolution of the plastic flow rule

$$\dot{\varepsilon}^p = f(\theta) \sinh \left\langle \frac{\sigma}{\kappa + Y(\theta)} - 1 \right\rangle^{n(\theta)}$$

$$Y(\theta) = \frac{Y_0}{Y_4 + e^{-Y_1/\theta}} \frac{1}{2} [1 + \tanh(Y_2(Y_3 - \theta))]$$



$$f(\theta) = f_1 e^{-f_2/\theta}$$



$$n(\theta) = n_1 + \frac{n_2}{\theta}$$

# Dynamic Recovery & Hardening Parameter

Evolution of the isotropic hardening variable

$$\dot{\kappa} = [H(\theta) - R_d(\theta)\kappa]\dot{\epsilon}_p$$

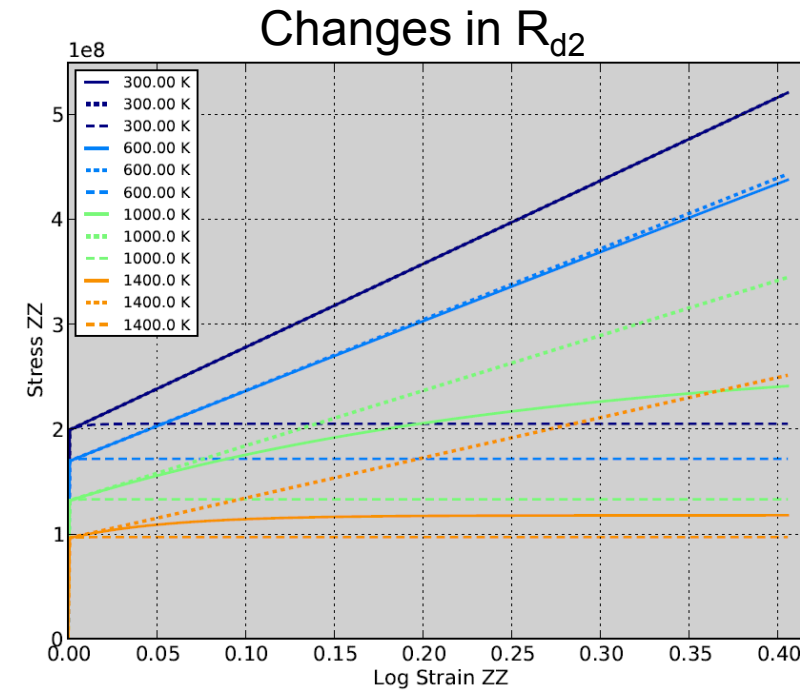
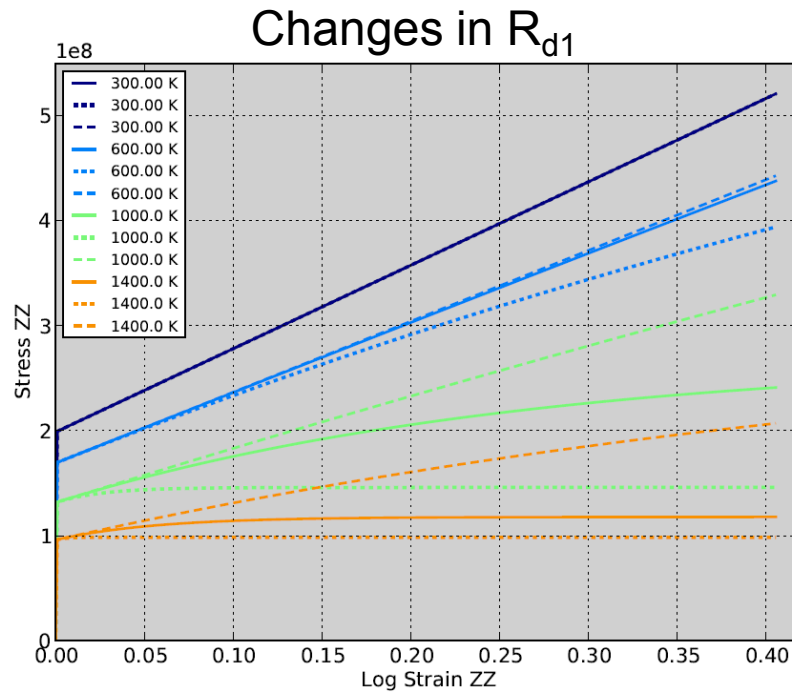
Evolution of the kinematic hardening variable

$$\dot{\alpha} = -\sqrt{\frac{3}{2}}R_d(\theta)\dot{\epsilon}_p\alpha\|\alpha\|$$

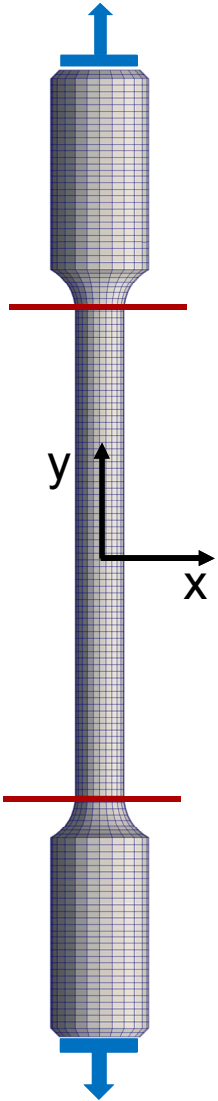
$$H(\theta) = H_1 - H_2\theta$$

$$H(\theta) = H_\mu\mu(\theta)$$

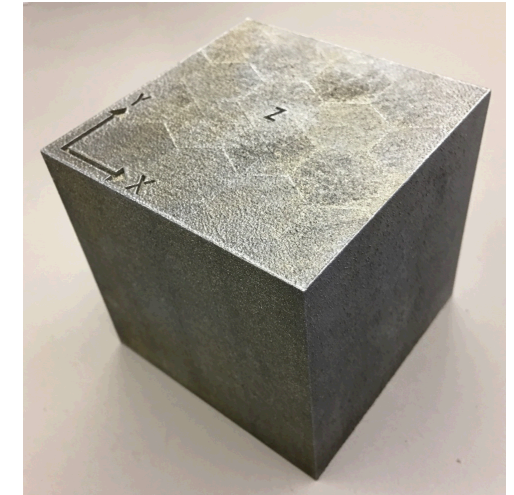
$$R_d(\theta) = R_{d1}e^{-R_{d2}/\theta}$$



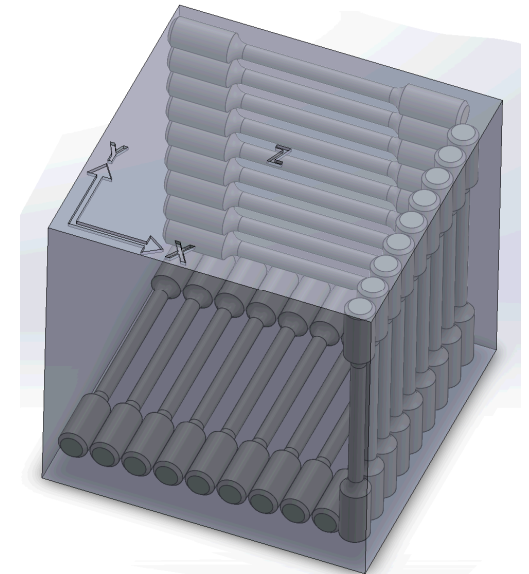
# Tensile Specimen Geometry and Boundary Conditions



- The total length of specimen is 63.25 mm
- The center rod (gauge section,  $L_0$ ) is 31.75 mm
- Center radius of the gauge section is tapered by  $10^{-2} * R$ 
  - Where R is 1.5875 mm
- The top and bottom surfaces are fixed in the X & Z direction
- The top and bottom surfaces have an applied constant velocity of  $v = \frac{1}{2} \dot{\epsilon} * L_0$  in the Y direction

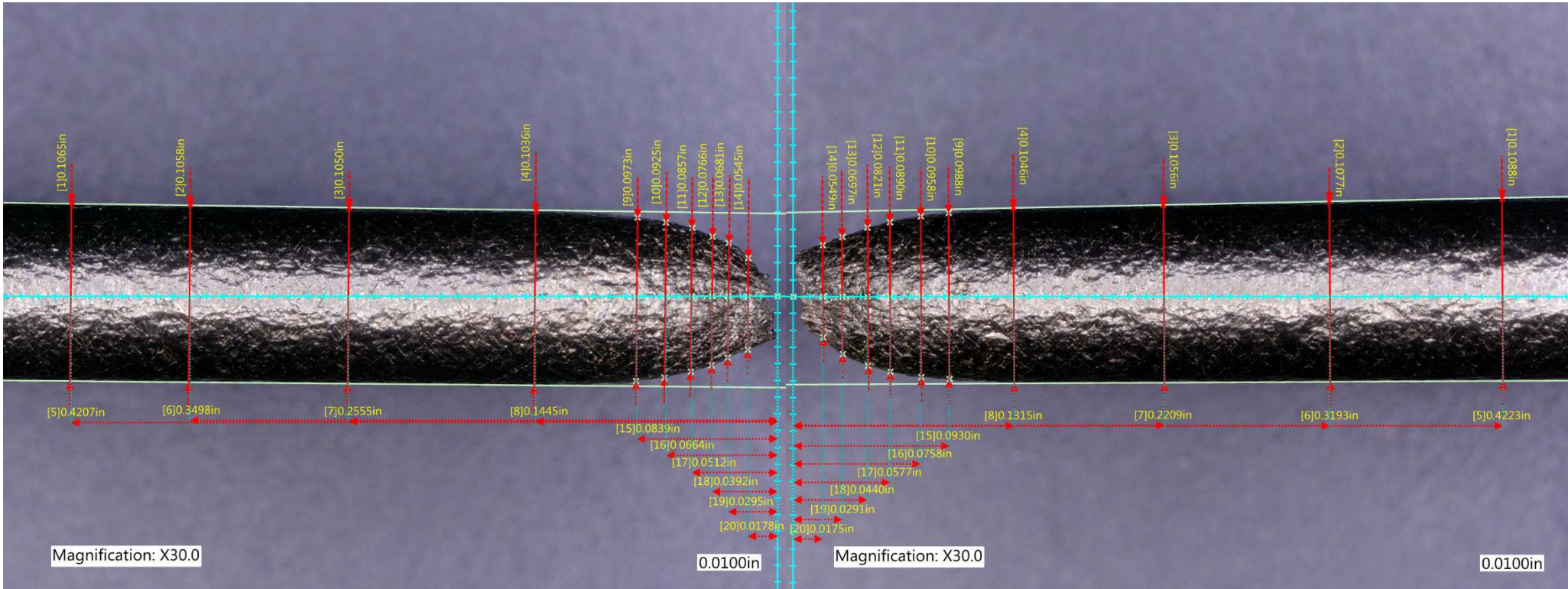


Antoun, Connelly, 2017





# Experimental Tensile Specimen Failure



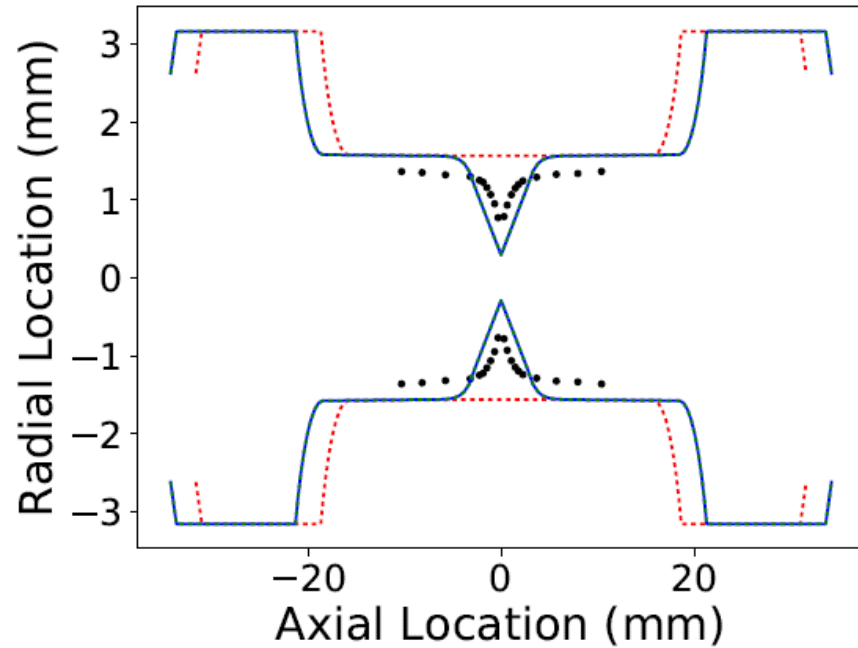


# Simulation Results with Baseline DSA Parameters

- Temperature = 300K
- Strain rate = 0.01



# Elastic Plastic Model

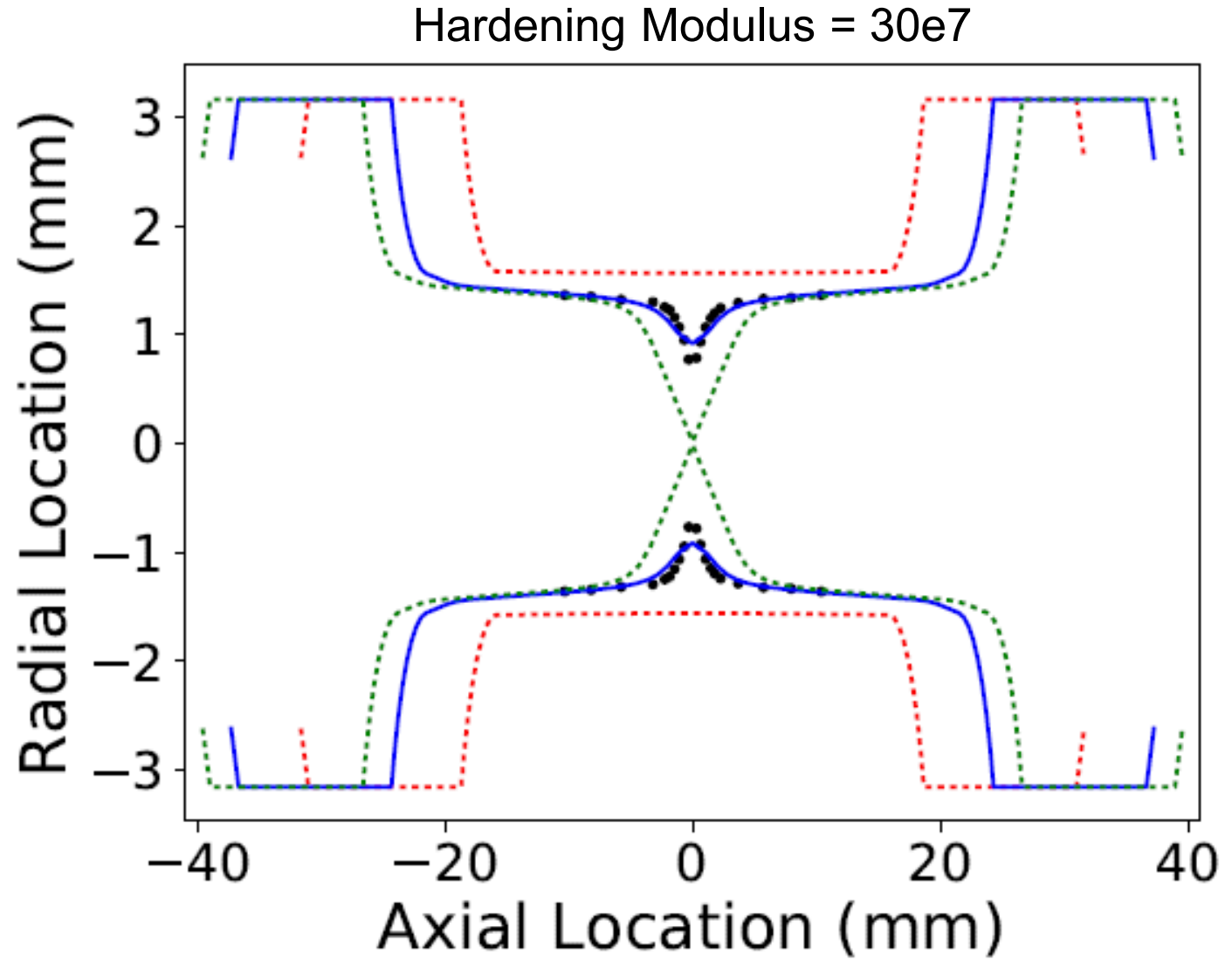
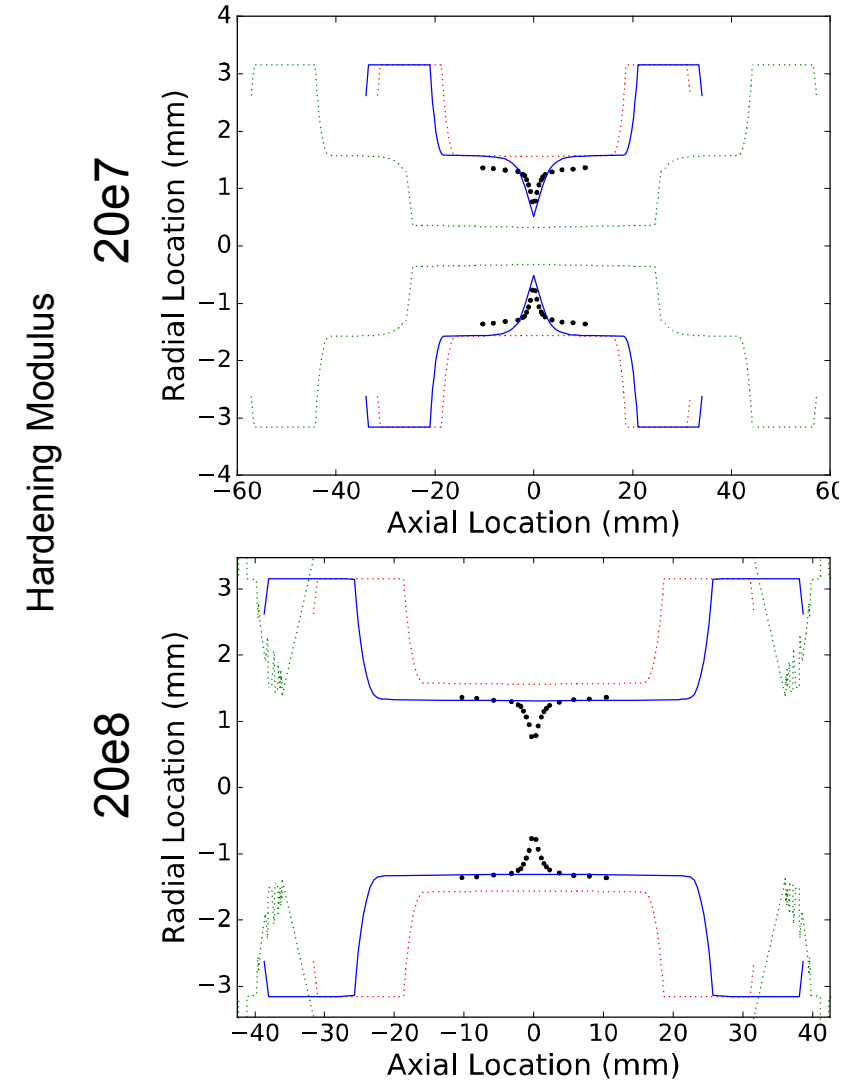


- Experiment
- Simulation Initial
- Simulation Best Match (222)
- Simulation End (222)

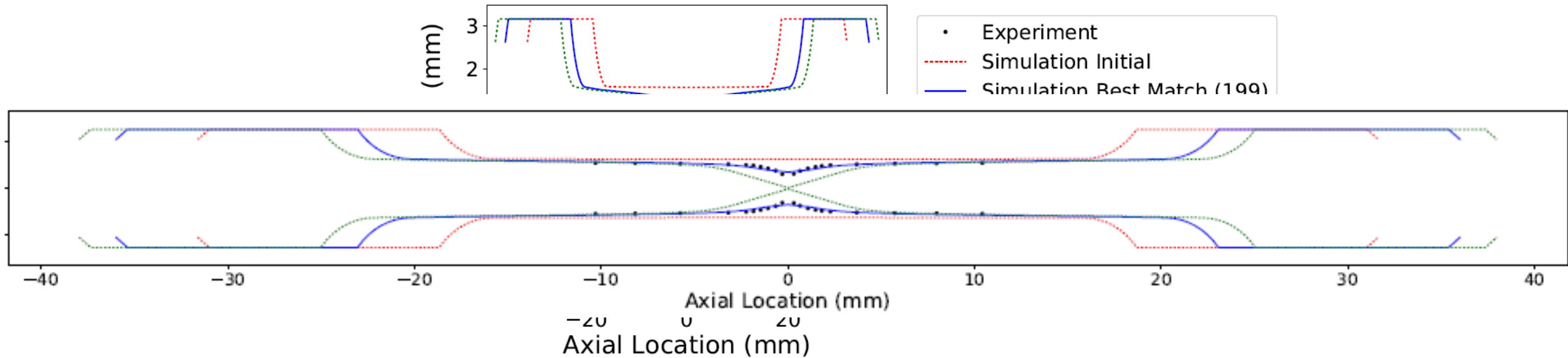
$E = 200e9$   
 $\nu = 0.25$   
Yield Stress =  $200e6$   
Hardening Modulus =  $20e6$



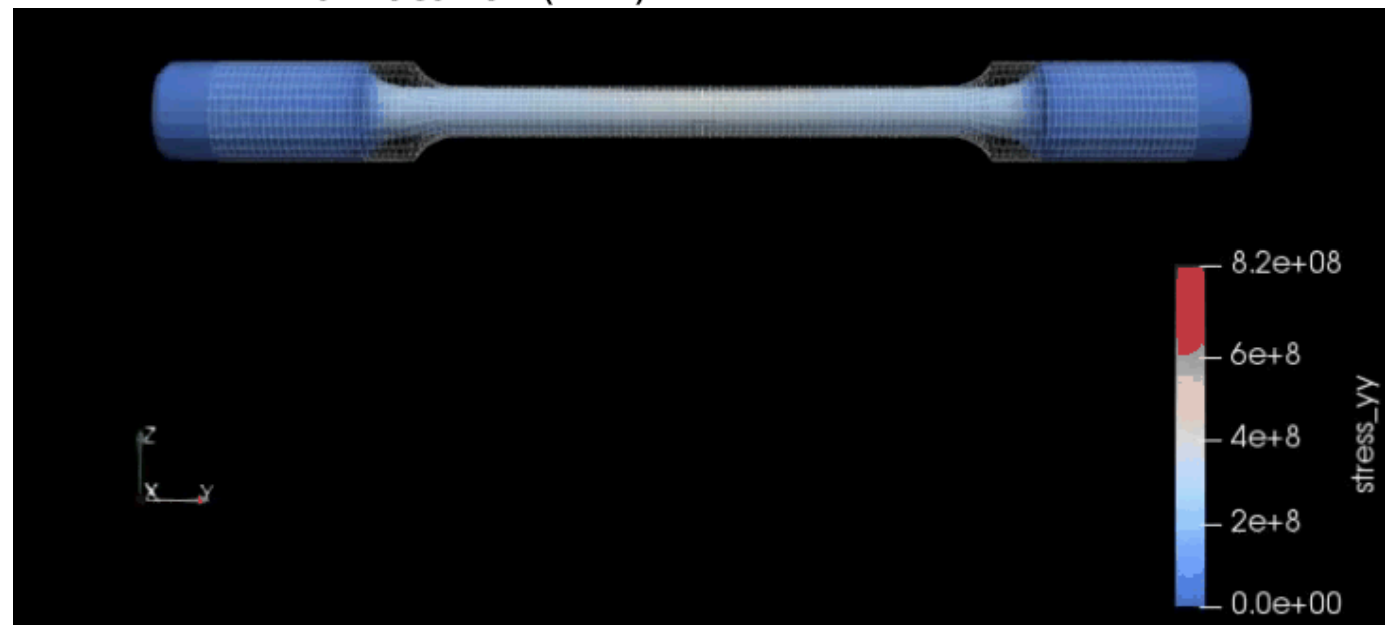
# Elastic Plastic Model



# DSA/BCJ\_MEM Model for Tensile Specimen



$H_{\mu}^{BL} = 0.01$   
 $H_{\mu} = 0.00085$   
All other values  
are baseline  
parameters.

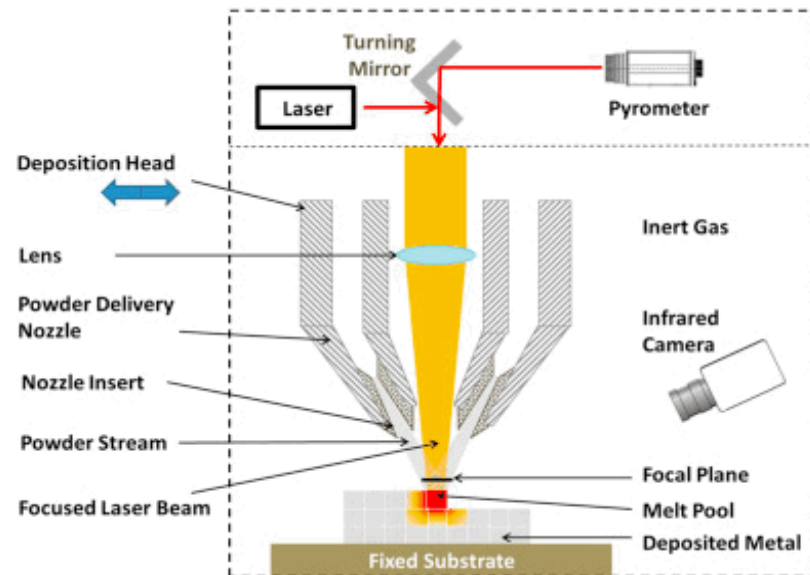


# Conclusion

- Affects of Varying Model Parameters
- Recalibration of isotropic hardening shear coefficient
- Parameter sets for DSA model

## Directed Energy Deposition

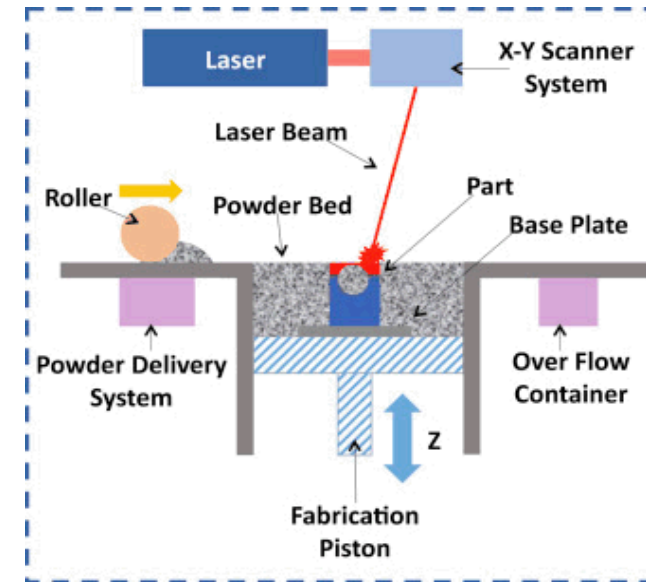
Laser Engineered Net Shaping (LENS)



<https://doi.org/10.1016/j.addma.2015.07.001>

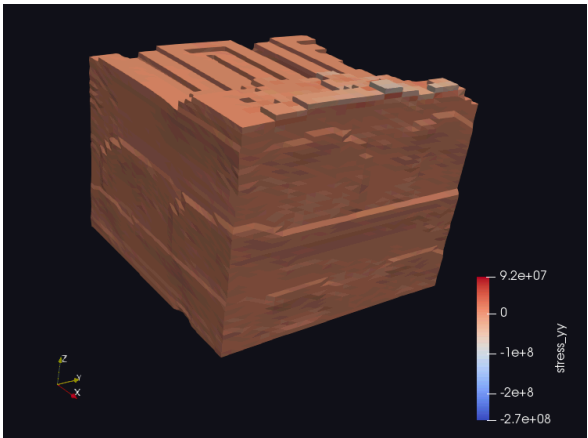
## Selective Laser Melting

Powder Bed Fusion

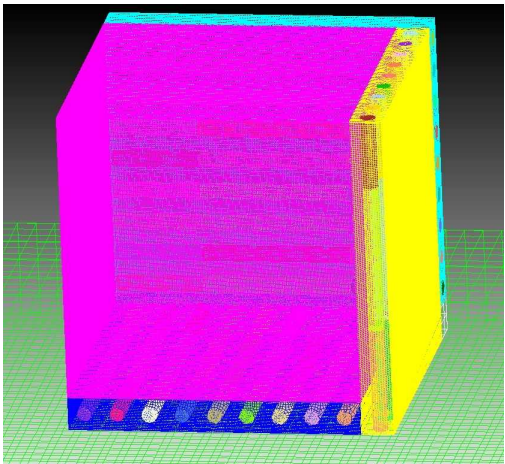


<https://doi.org/10.1016/j.addma.2015.07.001>

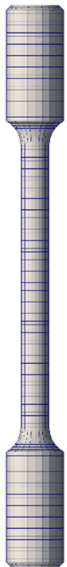
# Future Work



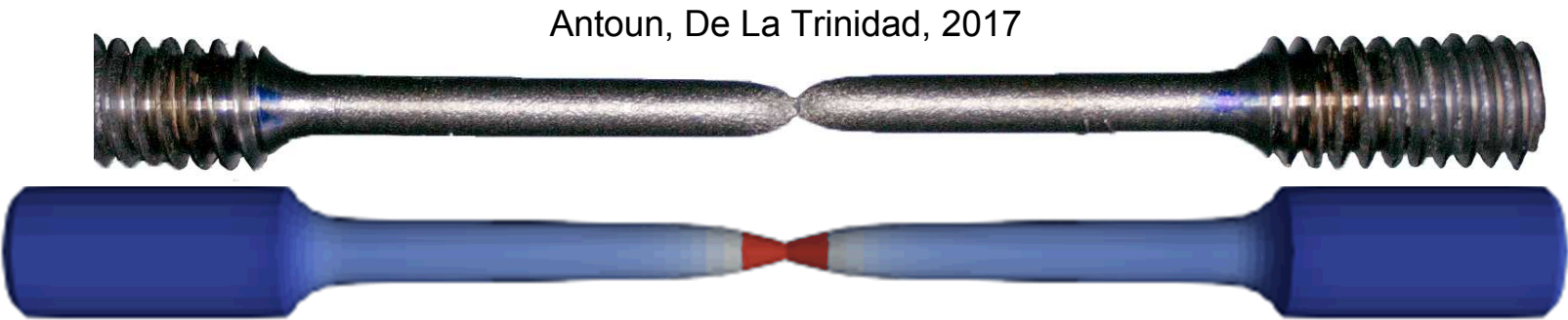
Process Simulation



Computational Geometry



Simulation Design



Antoun, De La Trinidad, 2017

Validation Analysis