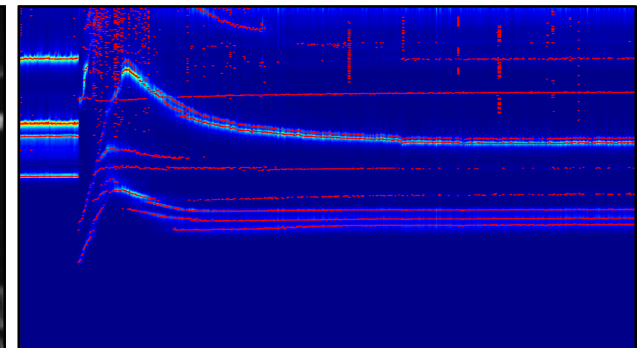
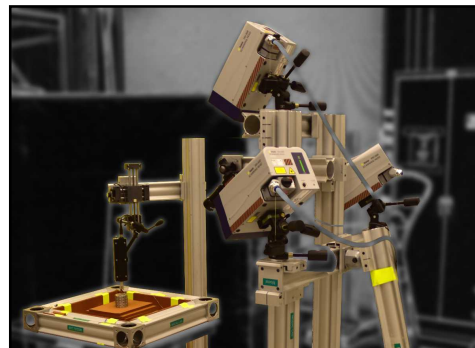
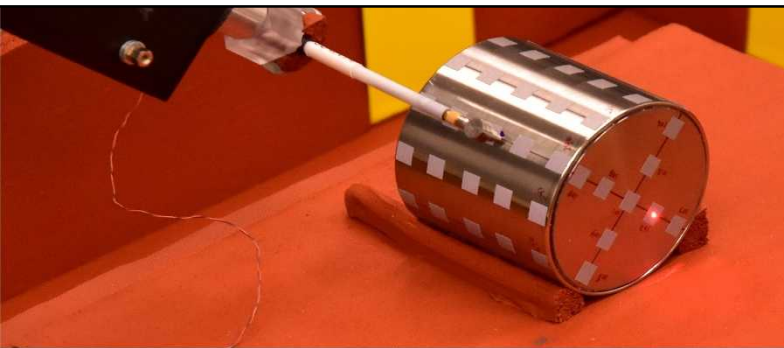


Thermal Battery Modal Testing and Time Varying System Dynamics with 3D SLDV

Thermal Battery
Modal Testing



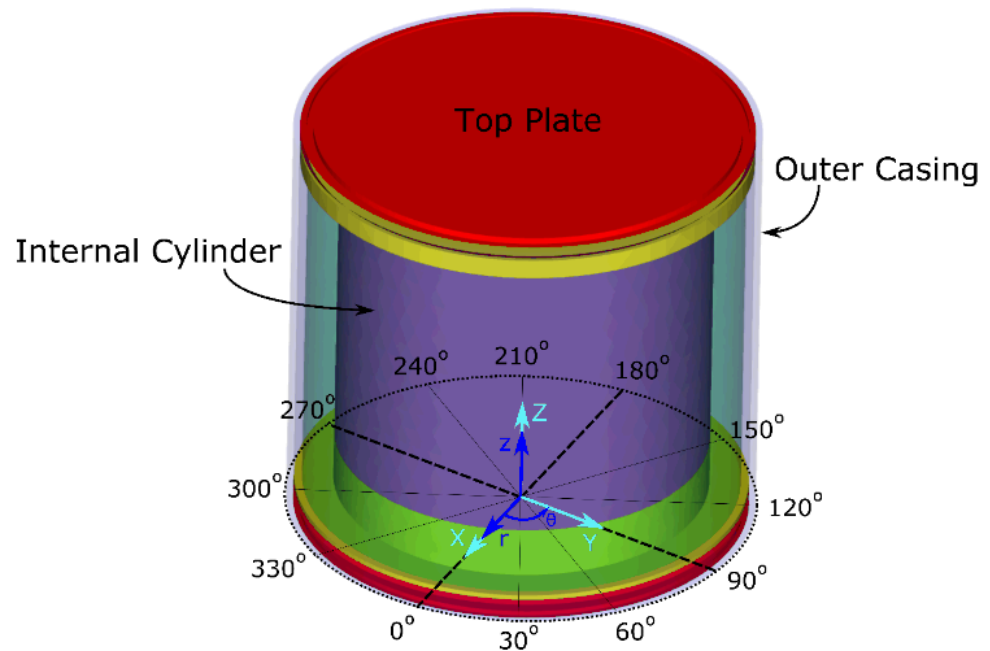
Thermal Battery Modal Testing and Time Varying System Dynamics with 3D SLDV

Bryan Witt & Brandon Zwink

Outline

- Test article
- Motivation
- Preliminary FEM
- Pre-Activation Testing
 - Roving hammer
 - 3D scanning laser Doppler vibrometer
 - Method comparisons
- Activation Testing
 - Setup
 - Data processing/presentation
 - Mode tracking
- Conclusions

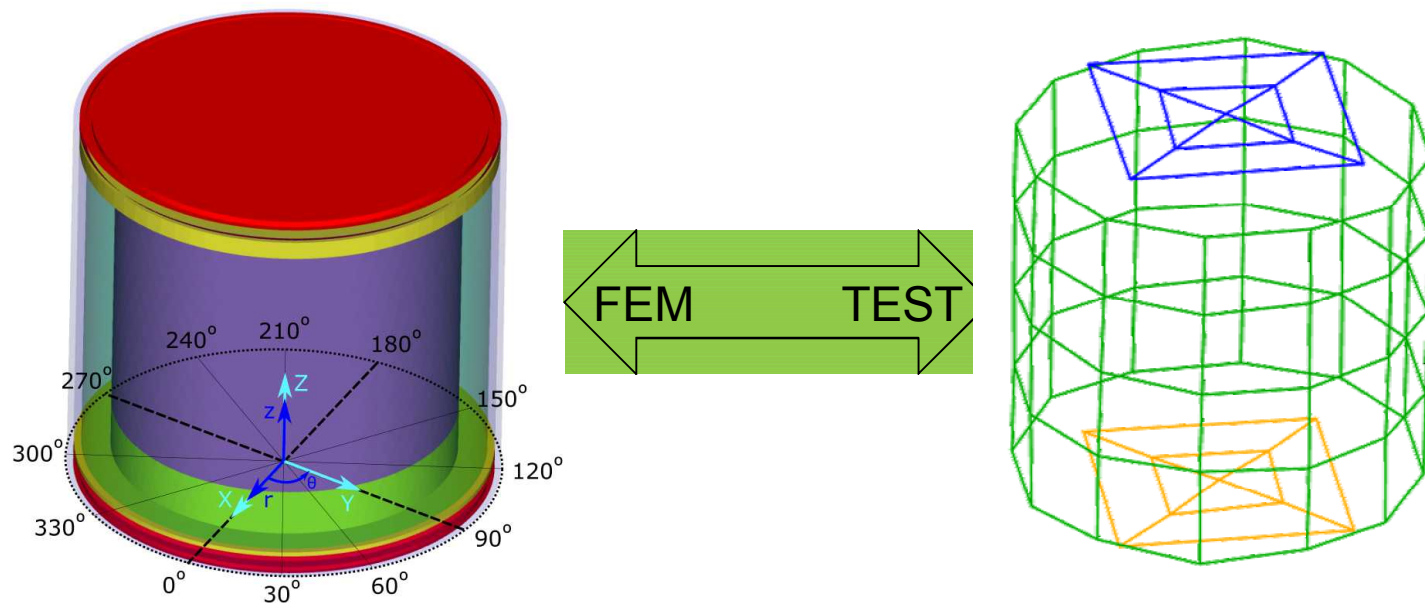
Test Articles



- Thermal Battery
 - Approximate dimensions: height = 6 cm, O.D. = 6 cm, mass = 0.5 kg
 - Six units tested
- Internals under preload, surrounded by insulation material
- Sealed system

Motivation

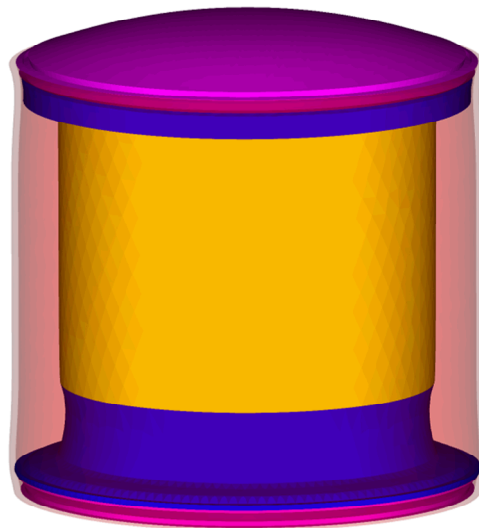
- Need to develop correlated Finite Element Model (FEM)
- No previous experimental data for model correlation
- Establish baseline modal properties
 - Second phase of testing to investigate variation in modal properties during internal state changes



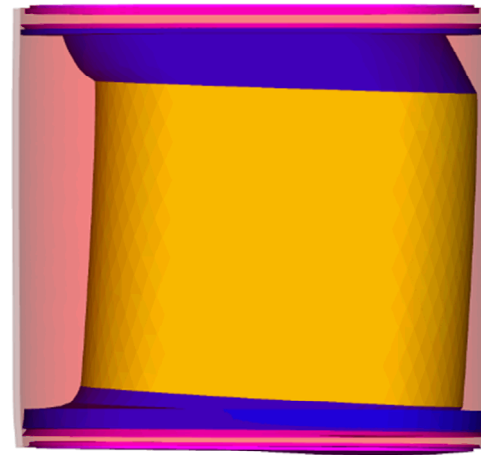
Finite Element Model

- Uncorrelated FEM primary modes of interest:
 - Internal cylinder axial and shear modes
 - Not accessible to measure, no internal instrumentation

Axial Mode

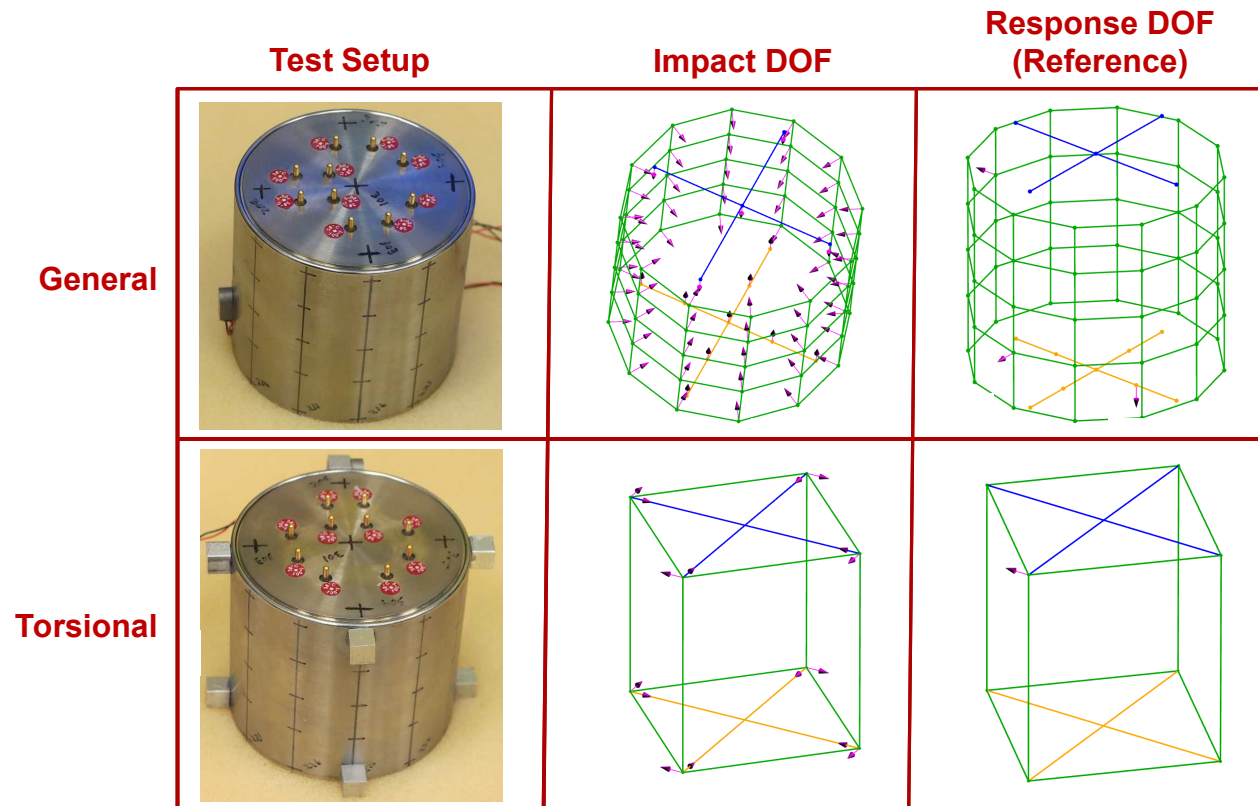


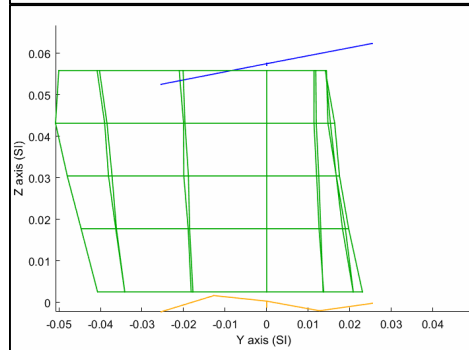
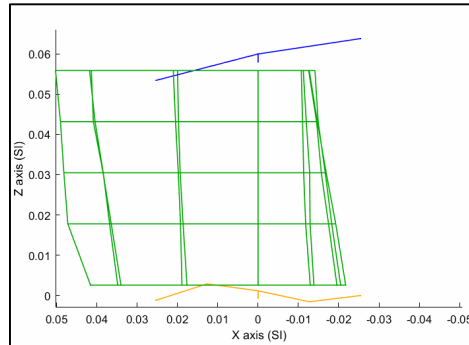
Shear Mode (Pair)



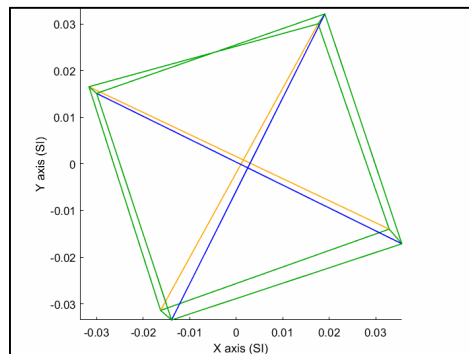
Pre-Activation: Roving Hammer

- Attempt to avoid mass loading small test article
 - Including additional reference accelerometers
- Can only collect degrees of freedom (DOF) normal to surfaces
- Torsion degrees of freedom measured with separate configuration
 - Small aluminum blocks added at 90° for mounting/impact surfaces

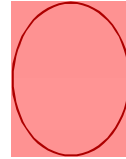
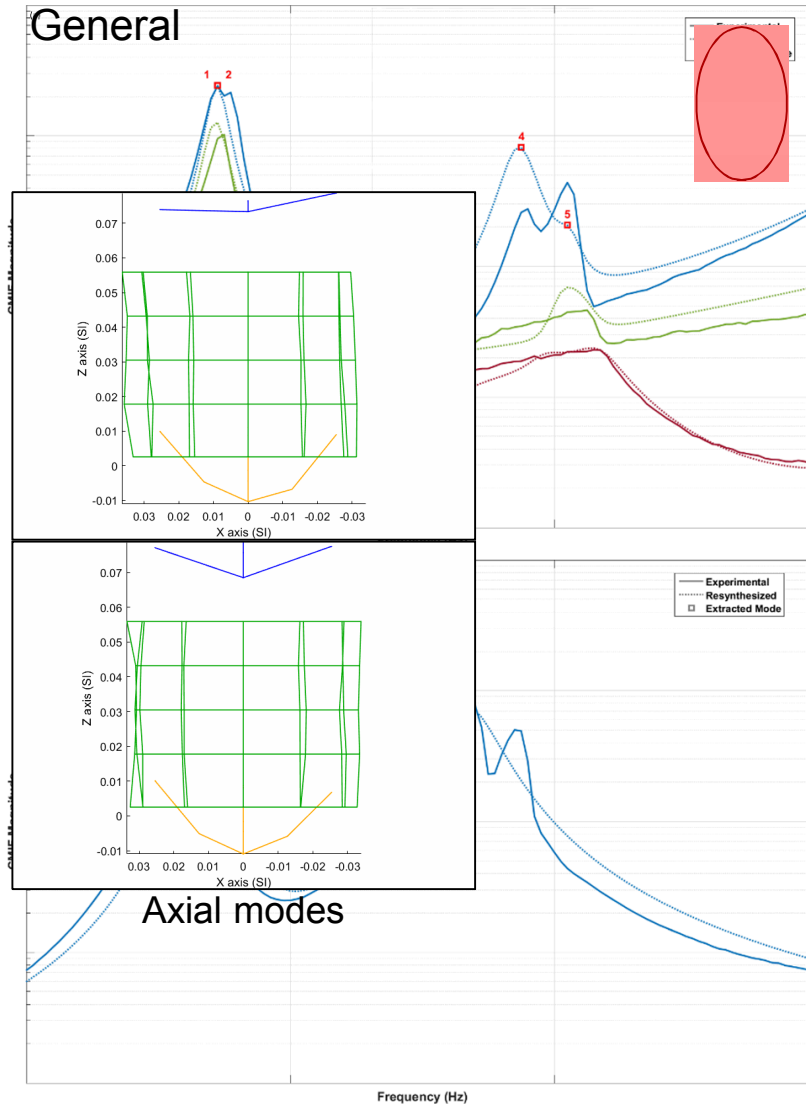




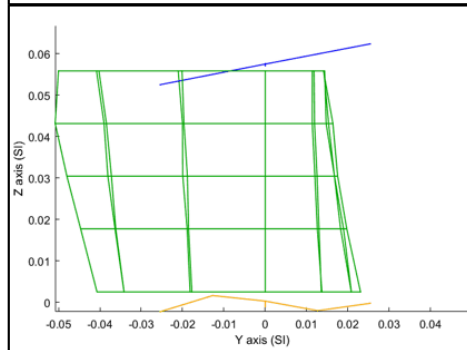
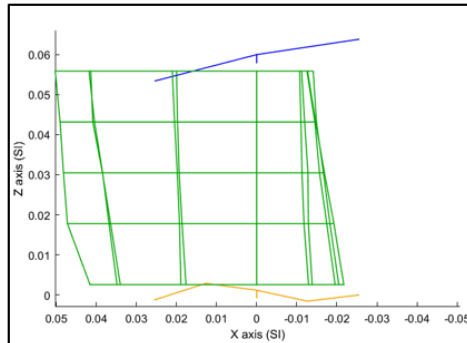
Internal shear modes



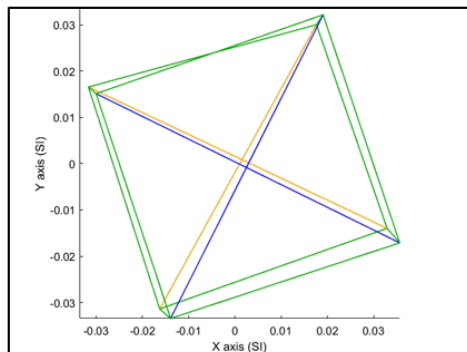
Internal torsion mode



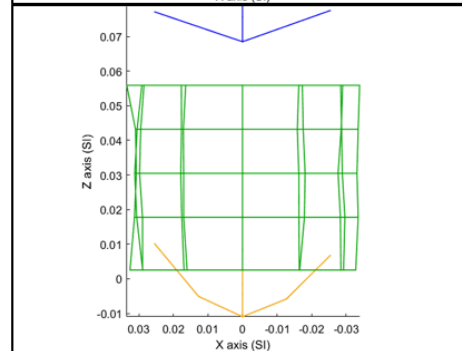
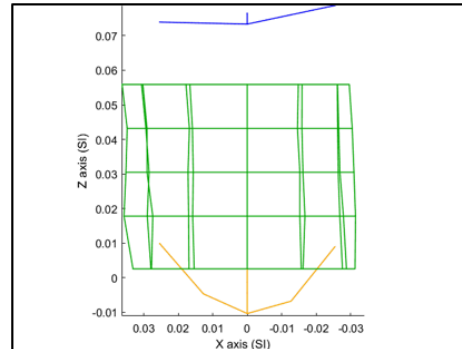
Pre-Activation: Roving Hammer



Internal shear modes

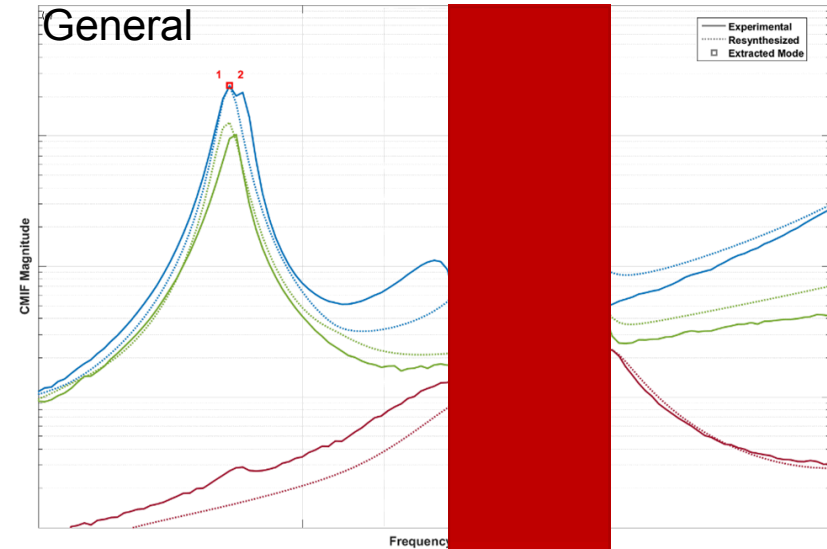


Internal torsion mode

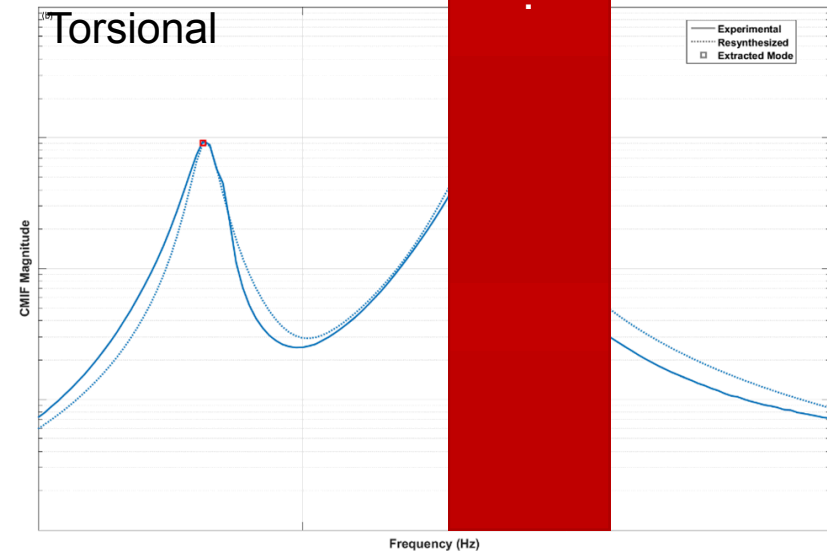


Axial modes

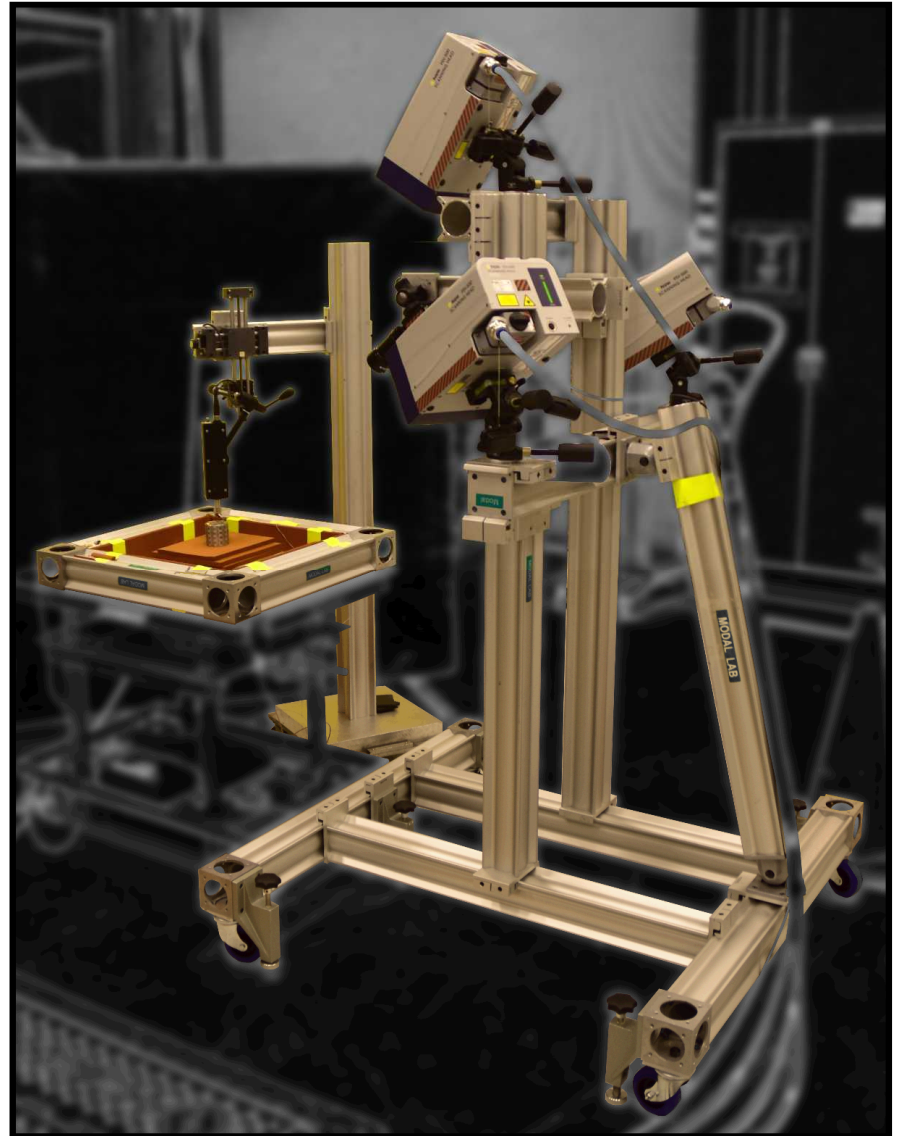
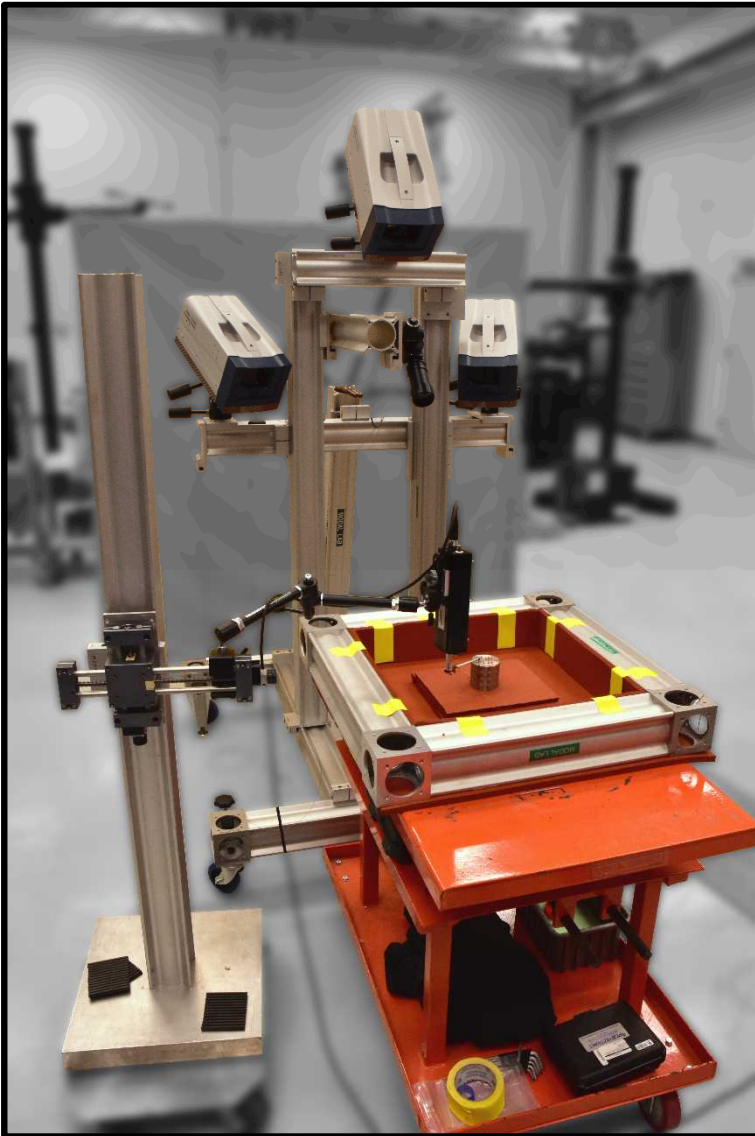
General



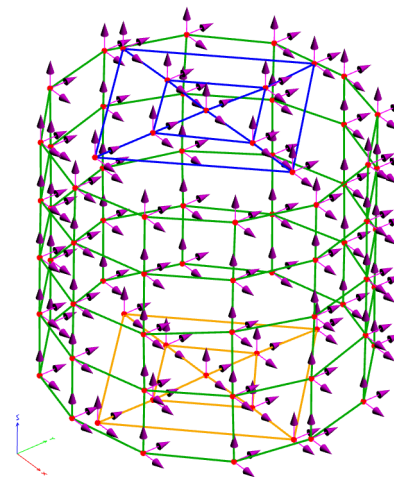
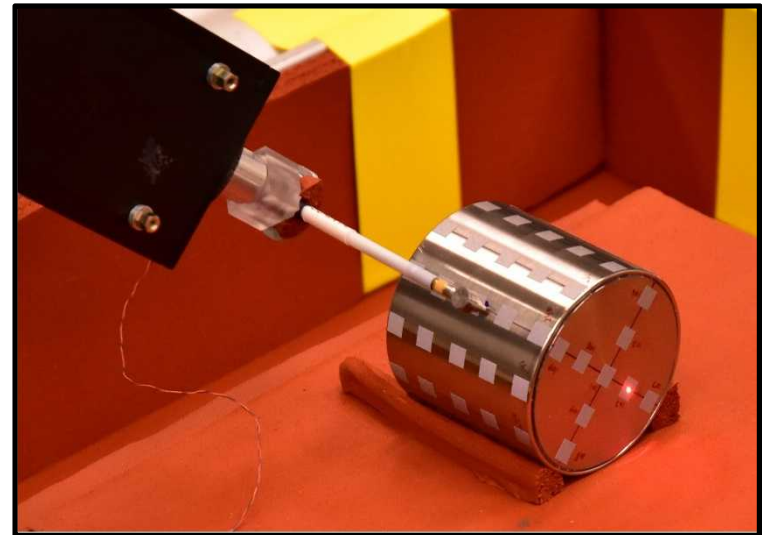
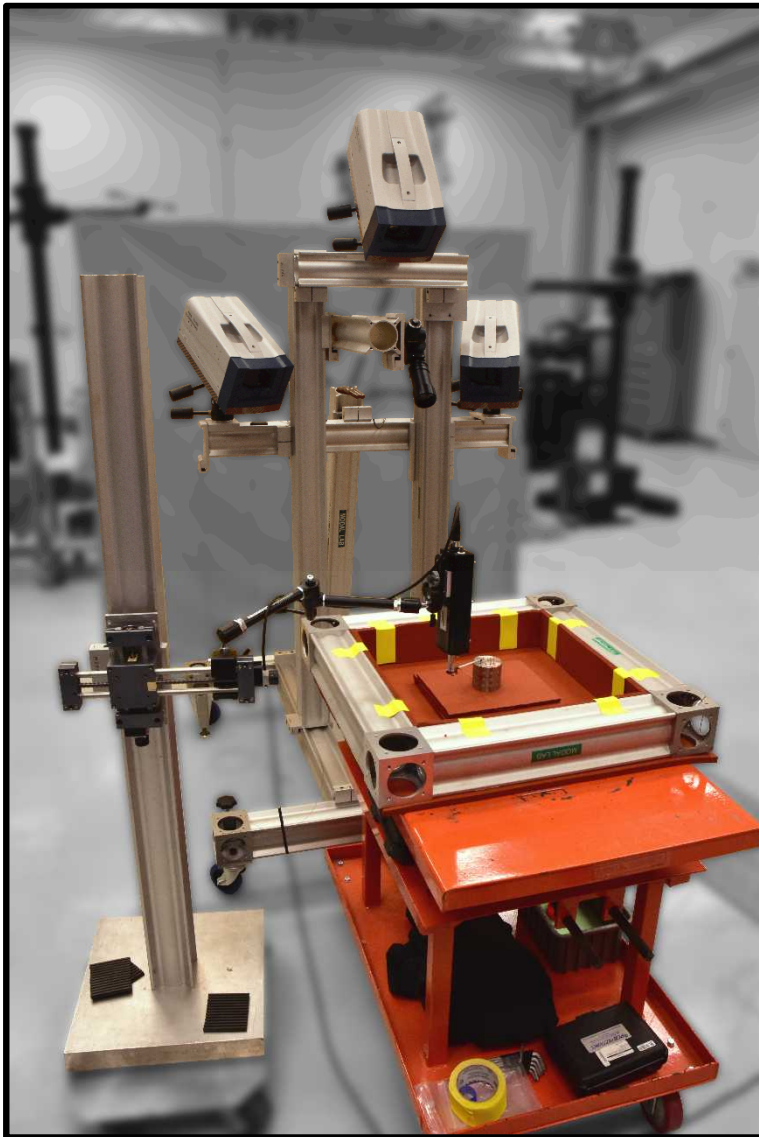
Torsional



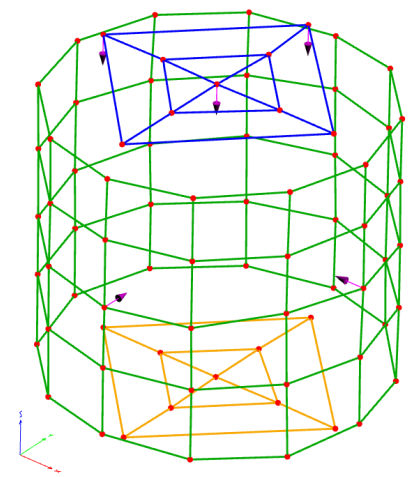
Pre-Activation: 3D SLDV



Pre-Activation: 3D SLDV

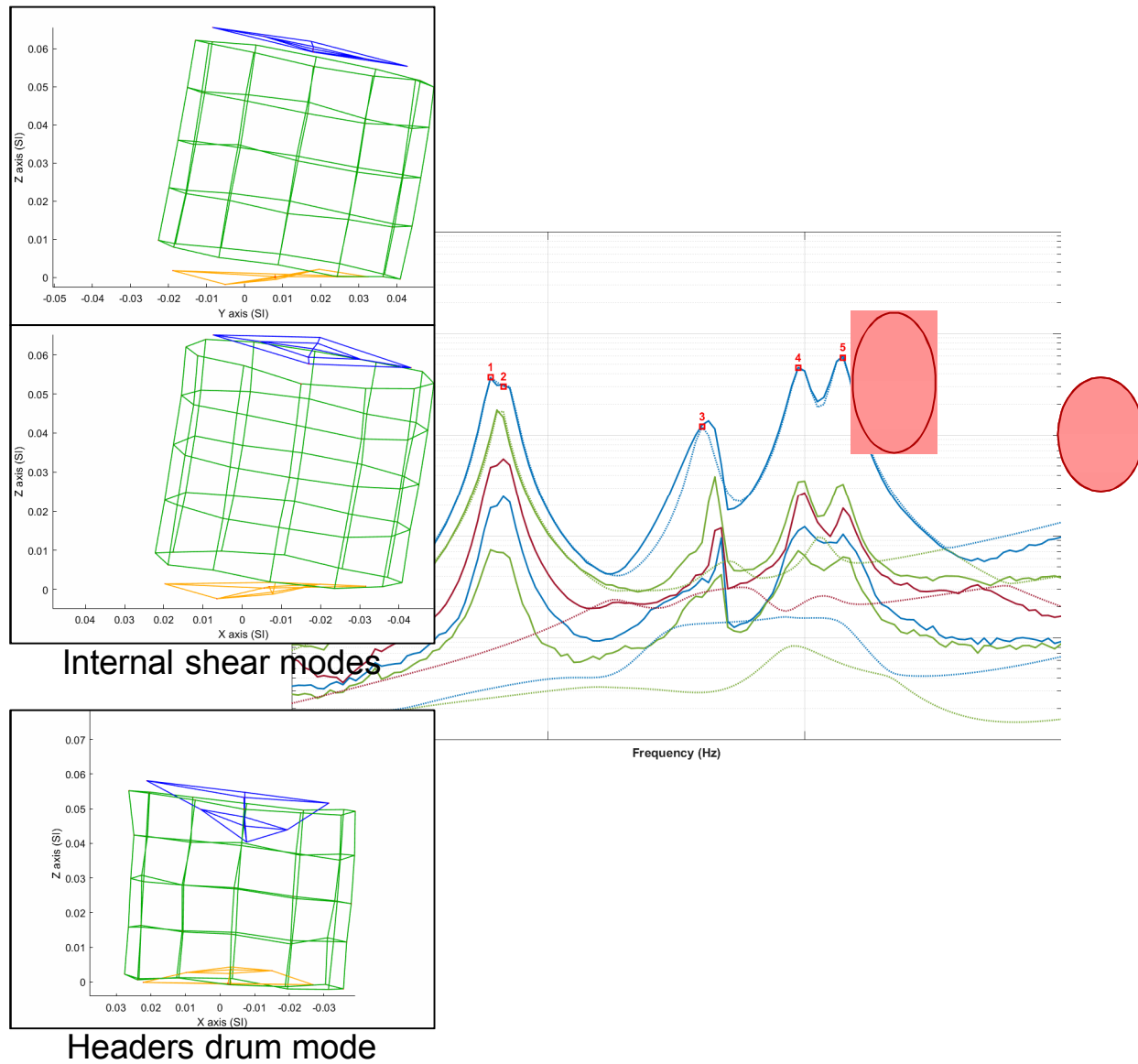


Response DOF

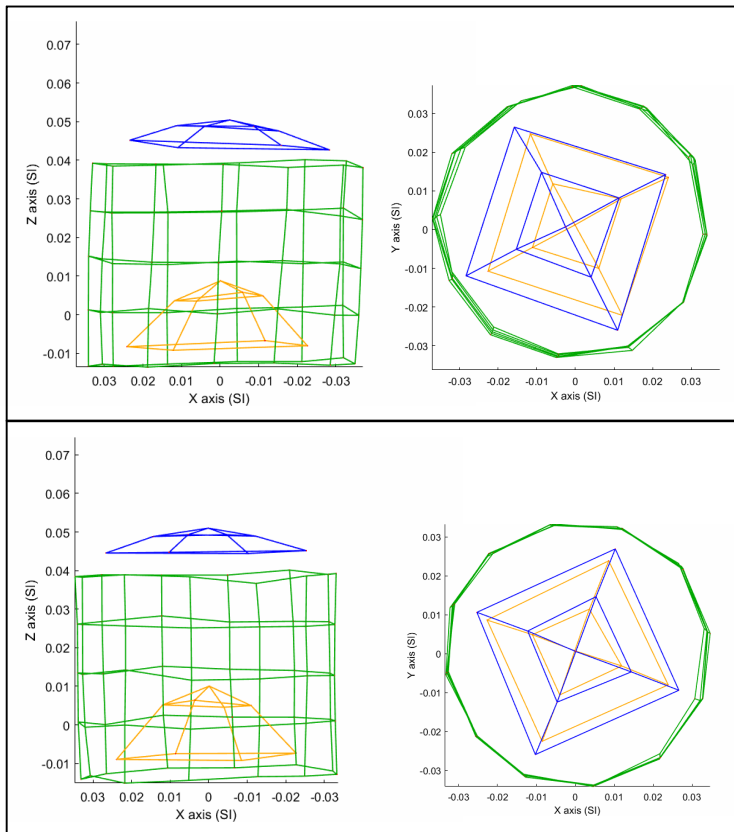


Impact DOF
(Reference)

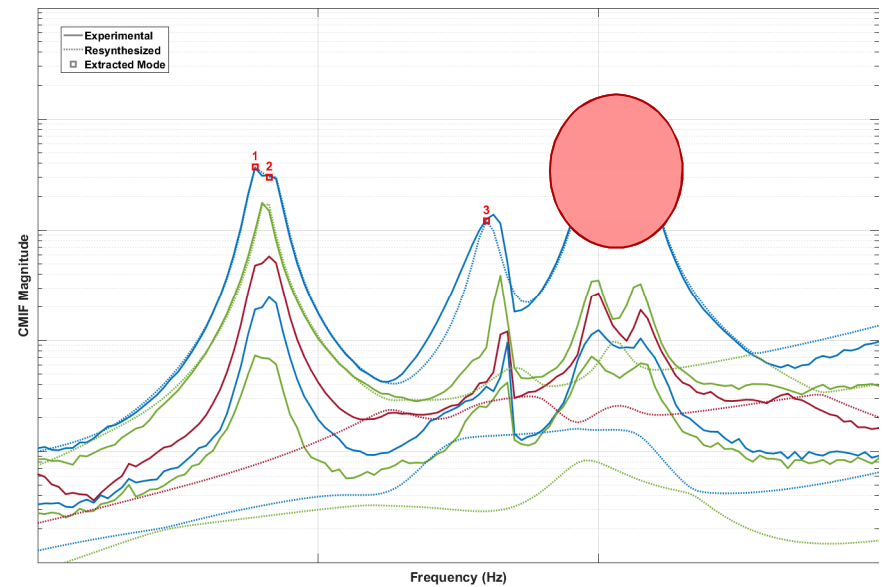
Pre-Activation: 3D SLDV



Pre-Activation: 3D SLDV

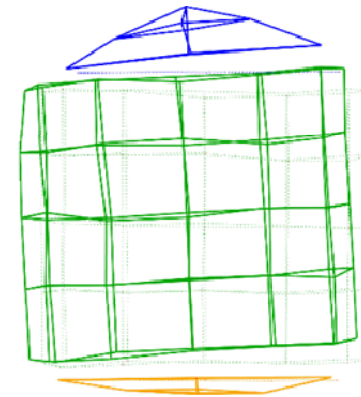
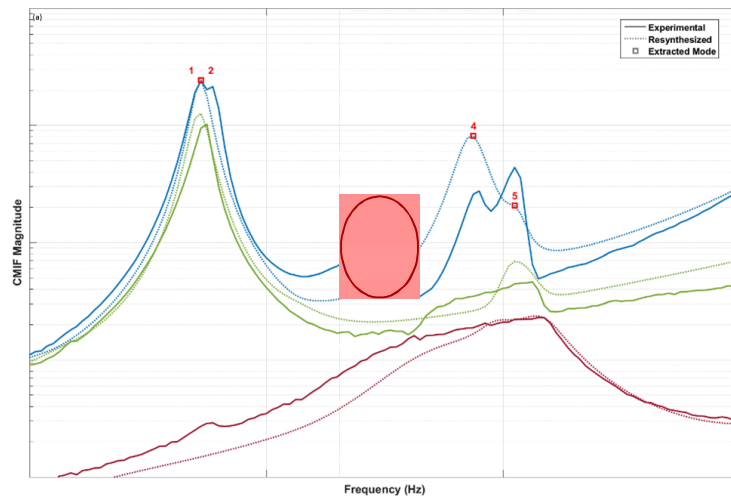


Axial + torsion modes



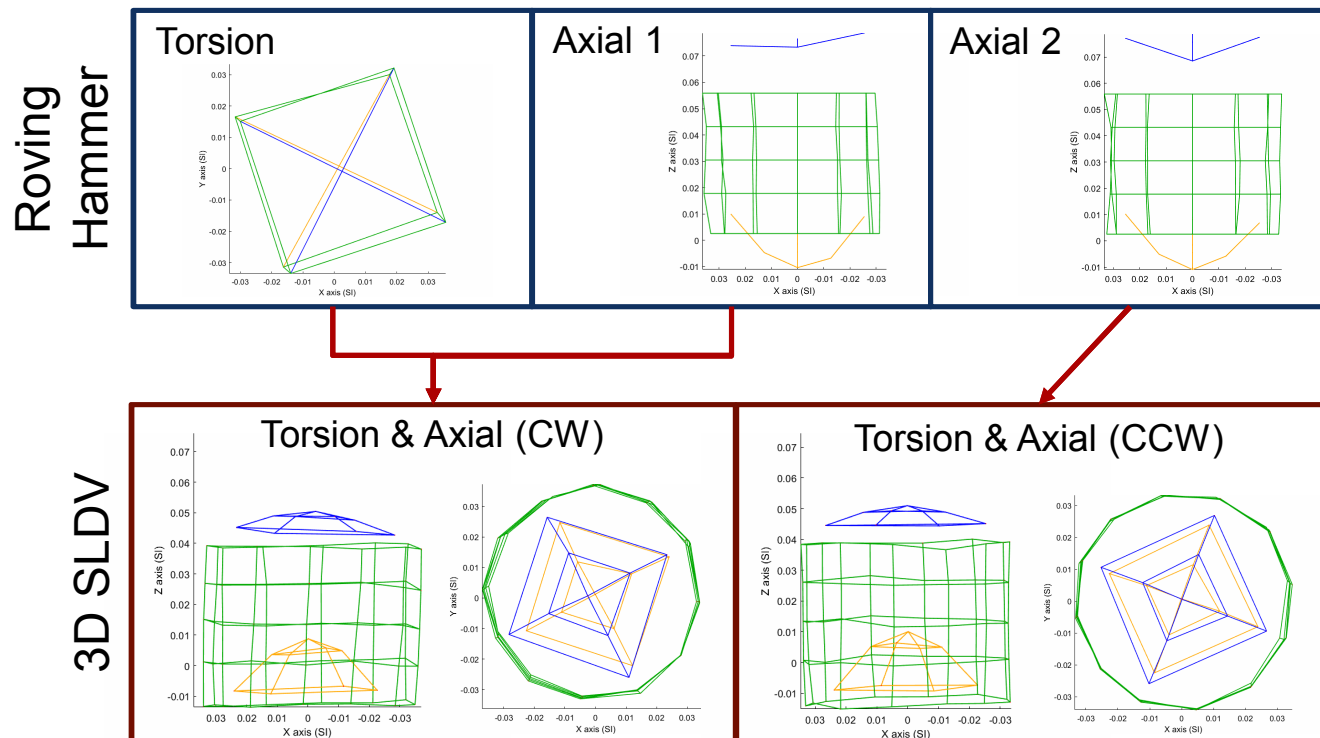
Pre-Activation: Method Comparison

- Roving hammer test results were inadequate in several regards:
 - *Missed header drum mode*
 - Limited reference accelerometers not positioned well
 - With 3D SLDV, easier to increase reference DOF without mass loading



Pre-Activation: Method Comparison

- Roving hammer test results were inadequate in several regards:
 - *No pure internal torsion mode*
 - 3D SLDV measured all necessary DOF in one test article configuration
 - *Axial modes only distinguished by (unmeasured) torsional components*

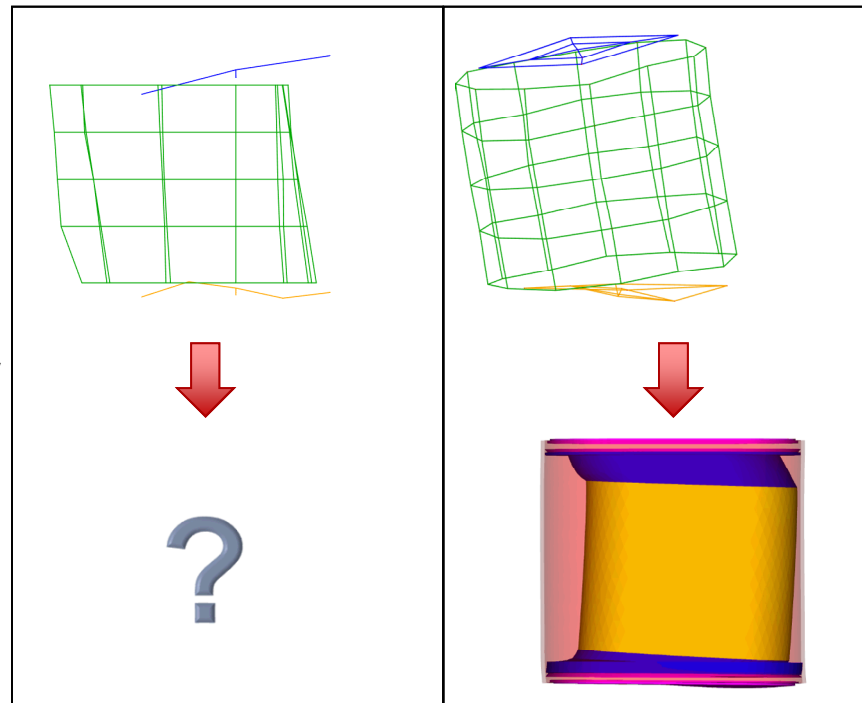


Pre-Activation: Method Comparison

- Roving hammer test results were inadequate in several regards:
 - *Important internal motion coupling not properly characterized!*

- *Shear (without rocking)*
- *Torsion (without axial)*
- *Axial (without torsion)*

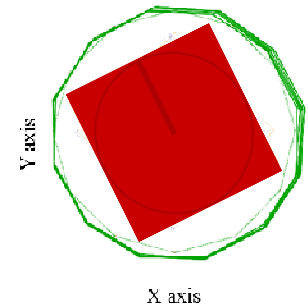
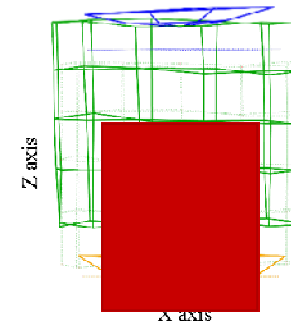
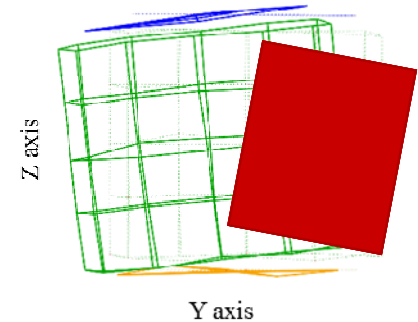
Roving
Hammer



3D SLDV

Pre-Activation: Method Comparison

- **Internal motions deduced from external 3D SLDV measurements**
 - *Additional DOF (especially, in-plane) were critical*
 - *Higher frequency modes that look “rigid” are due to internal feature motion*
 - Conservation of momentum; internals moving opposite external observations
 - *Identifying couplings were essential in model updating*
 - Shear + rocking
 - Torsion + axial
 - Informed model mechanical behavior and material property updates

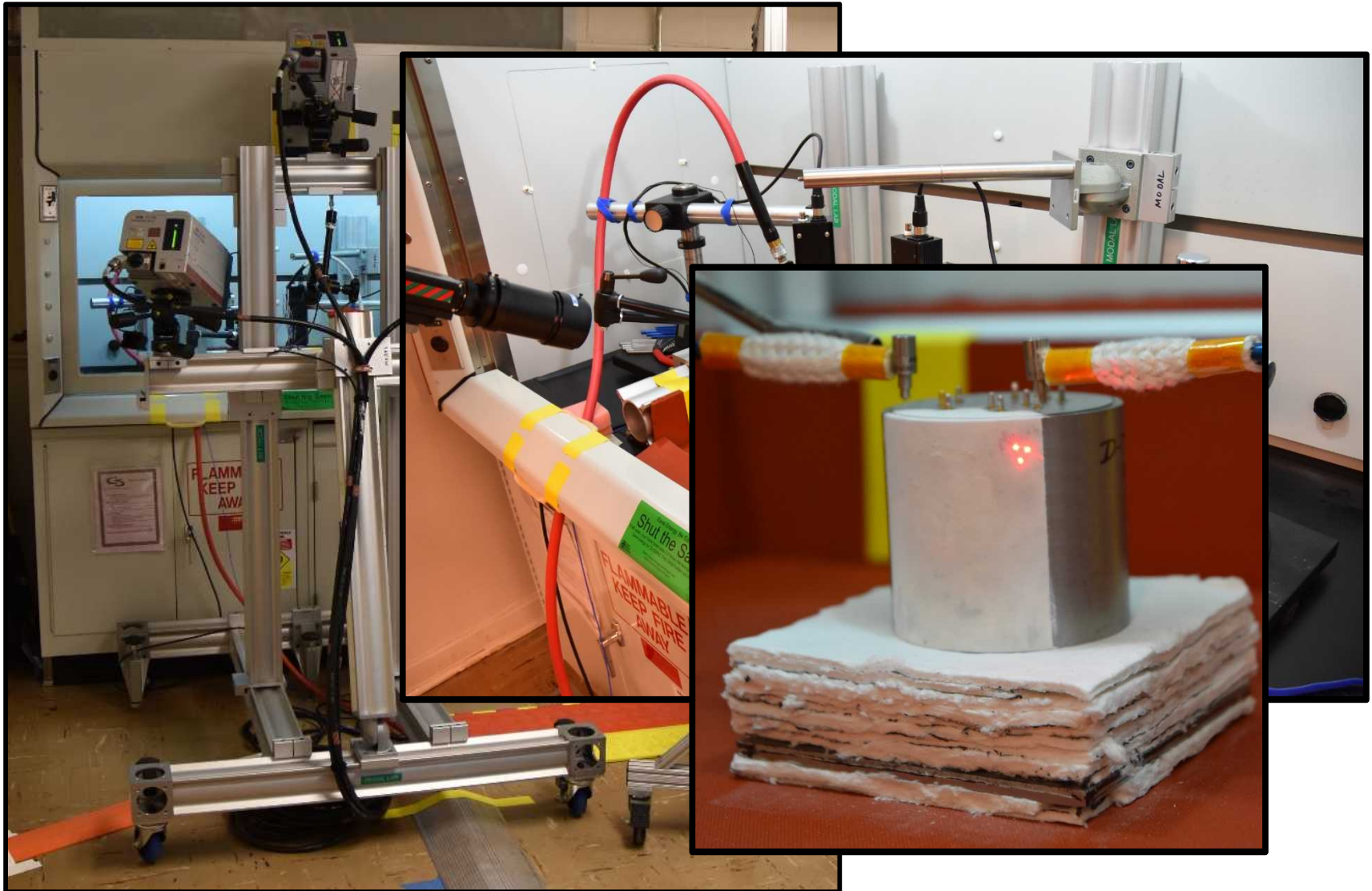


Activated Battery Testing

- Baseline modal characteristics established
 - How do they track with internal state changes?

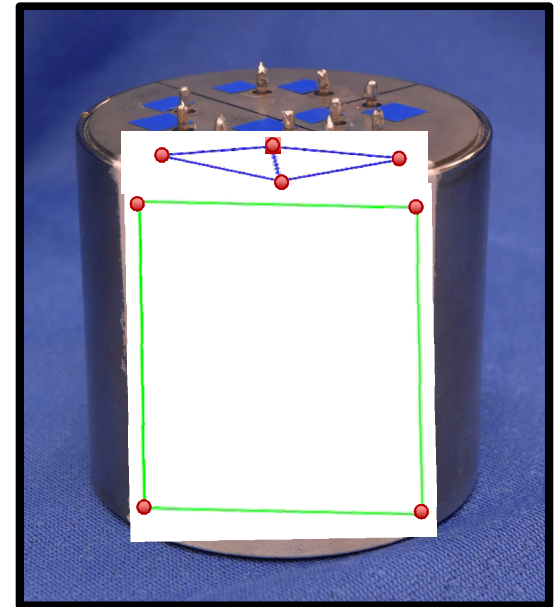
- FE models want to reflect dynamic characteristics in time following activation
 - Previously, modal testing would be limited to pre-activation or post-activation states (ambient conditions)
 - Expected dynamic characteristics pre/post activation to be different
 - How different?
 - What goes on in between these end points?

Activated Battery Testing



Activated Battery Testing

- Collected data at reduced set of nodes to speed up acquisition
 - 8 Nodes, 24 DOF
 - Sufficient to visualize modes of interest
 - Collected time histories only
- Fast data acquisition:
 - Used Visual Basic macro to automate Polytec data acquisition
 - Hammer function generators at 0.34 sec
 - Impacts spaced ~100 msec apart
 - One scan per node (no averaging)
 - **~6 seconds to collect all 48 time histories**
 - *File write time was limiting factor*



Surface Preparation:

White high-temperature paint covered with retroreflective beads

Activated Battery Testing

- CMIF Spectrogram

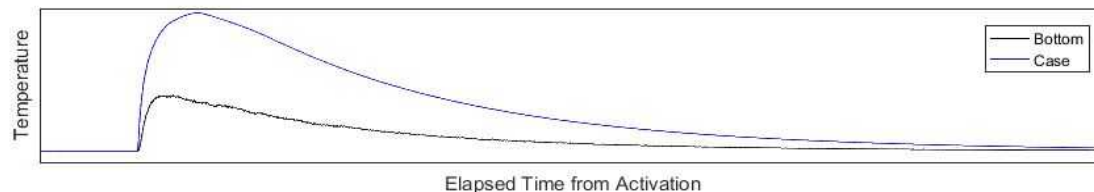
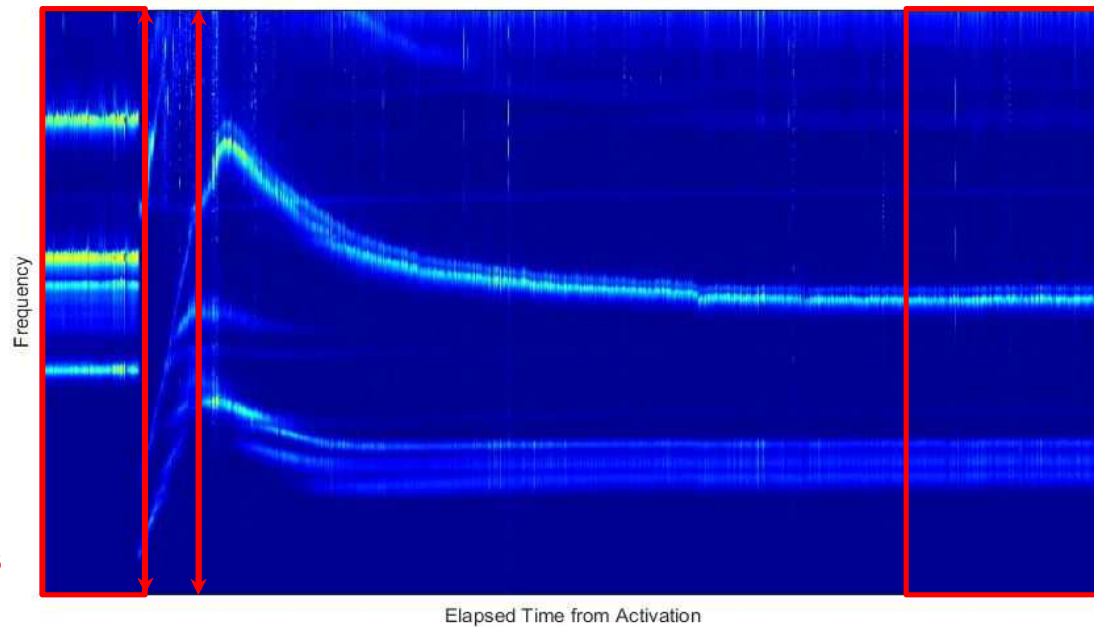
- Each time slice is a Complex Mode Indicator Function (CMIF)
- Each vertical line represents a full set of FRFs

Ambient Conditions
Pre-initiation

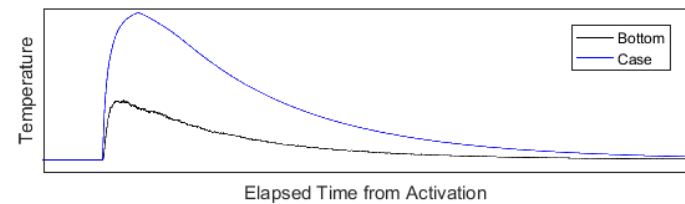
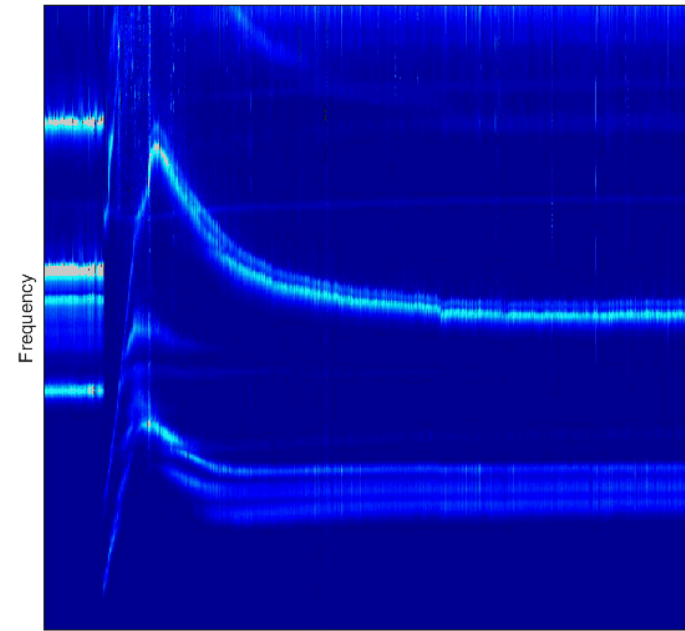
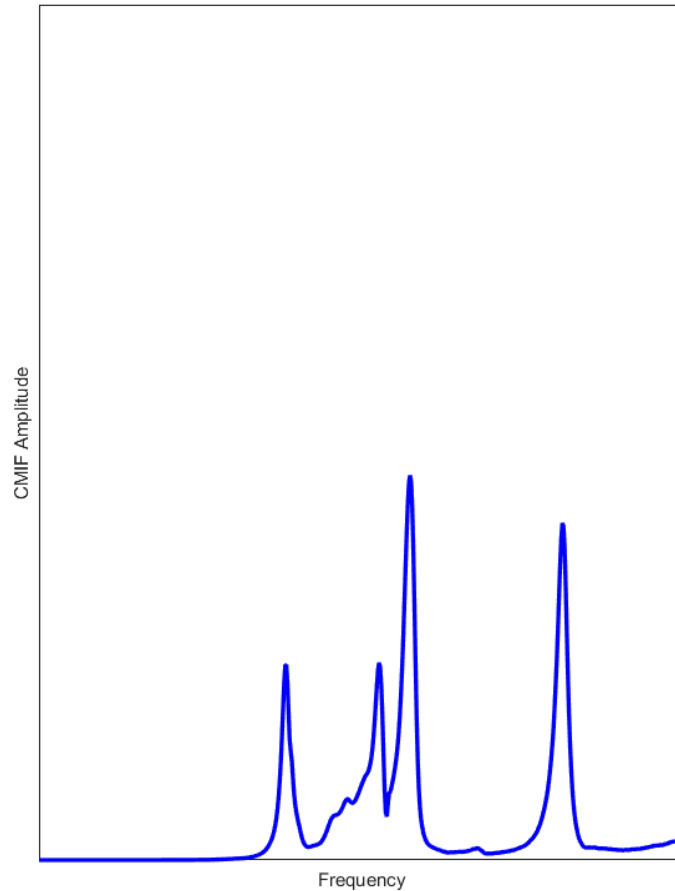
Initiation

Peak External Temp

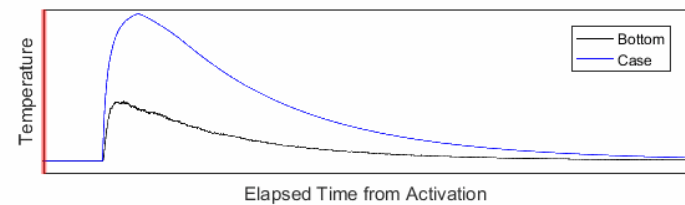
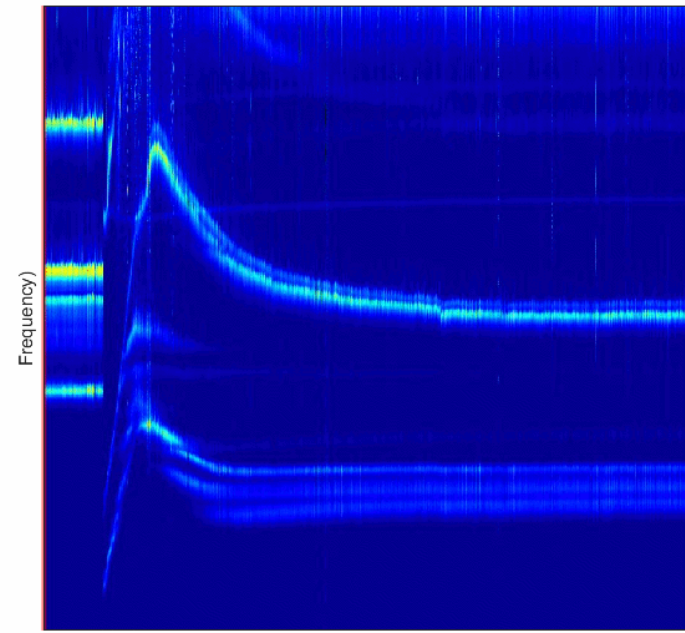
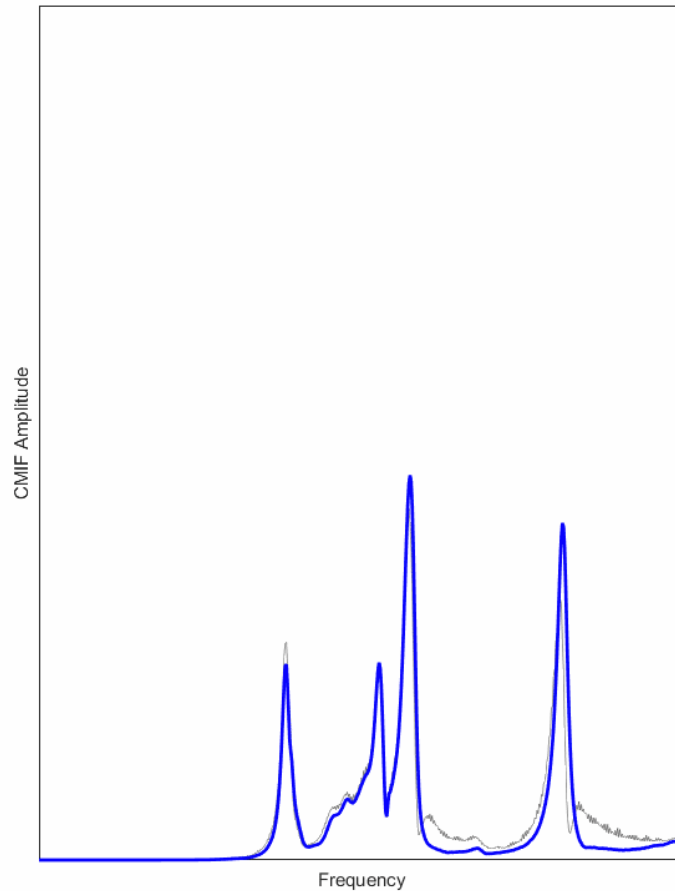
Return to Ambient
(External) Conditions



Activated Battery Testing

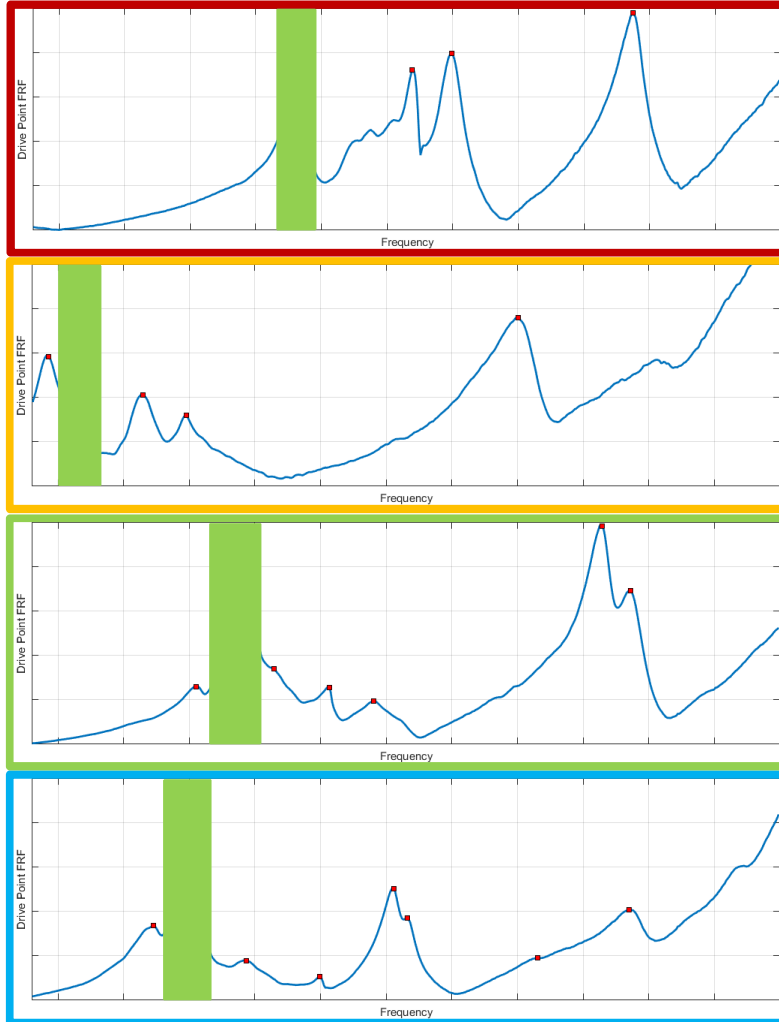


Activated Battery Testing

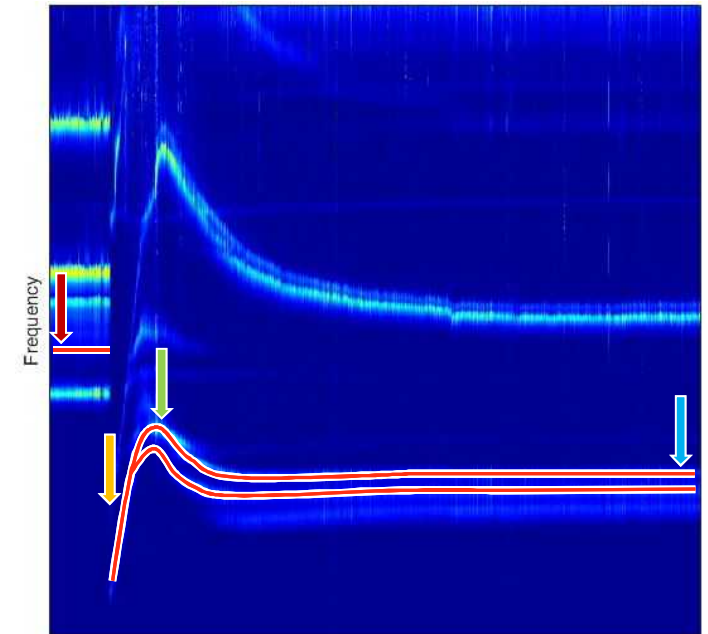
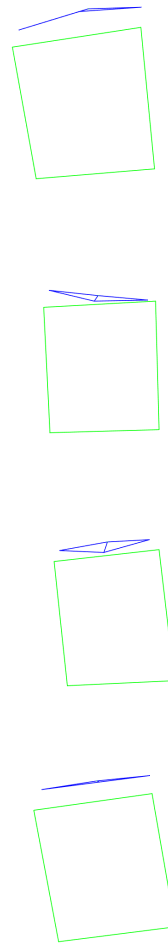


Activated Battery Testing

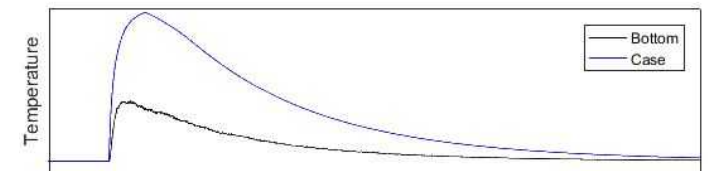
Internal Shear Modes



Operational Deflection Shape (ODS)



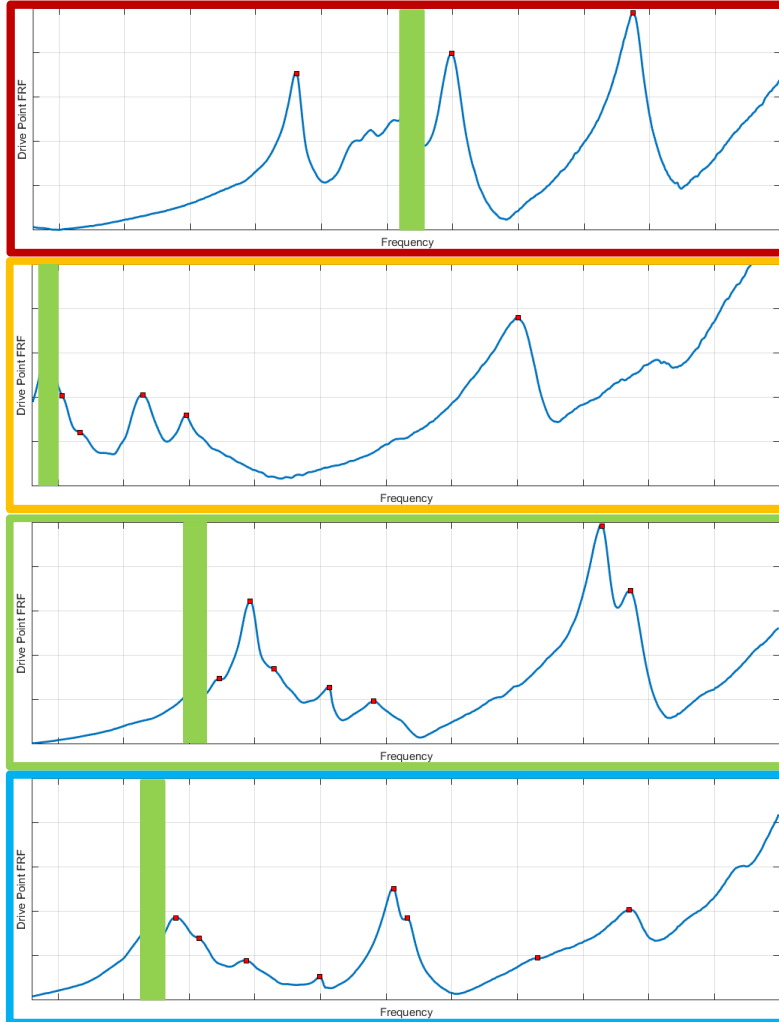
Elapsed Time from Activation



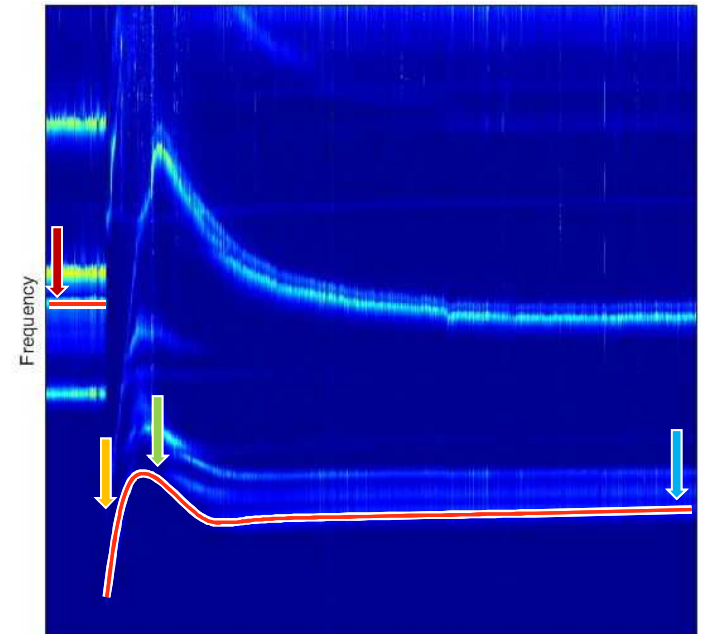
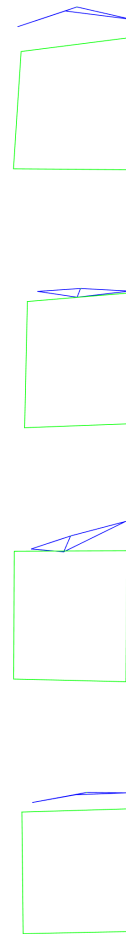
Elapsed Time from Activation

Activated Battery Testing

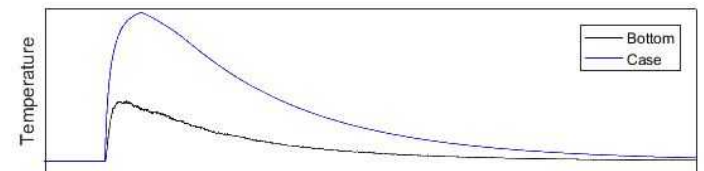
Internal Axial Mode



ODS



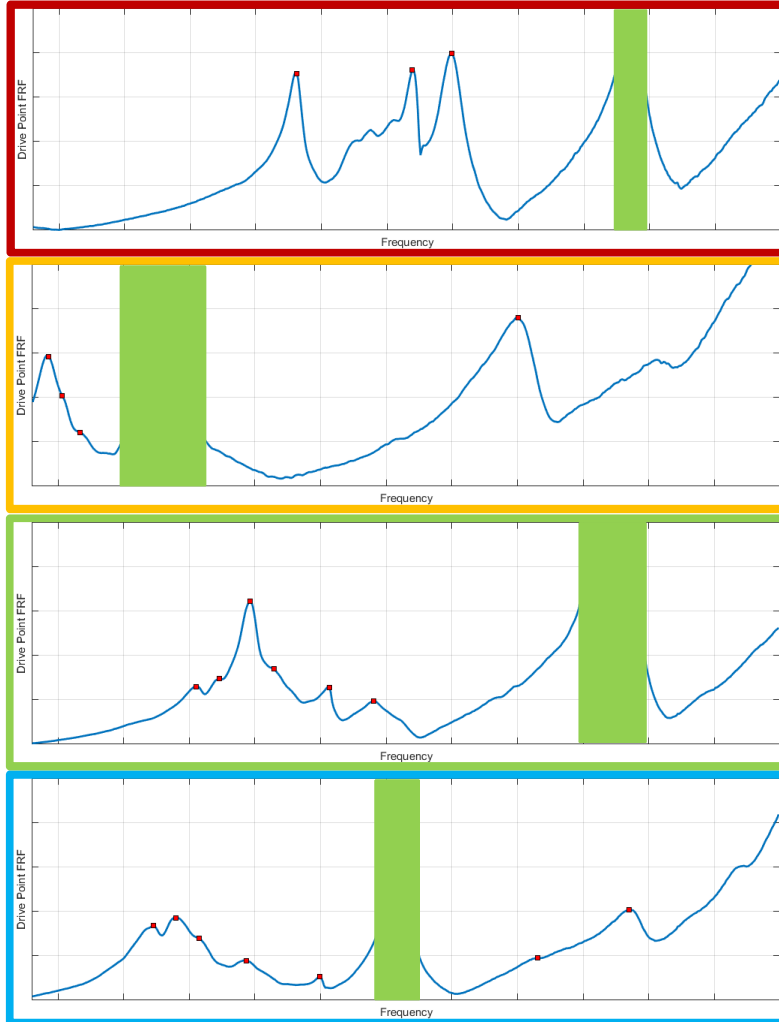
Elapsed Time from Activation



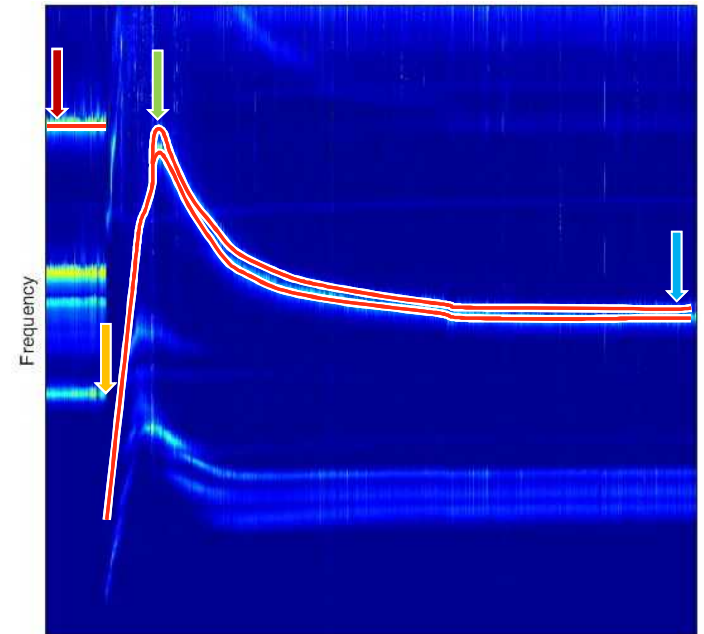
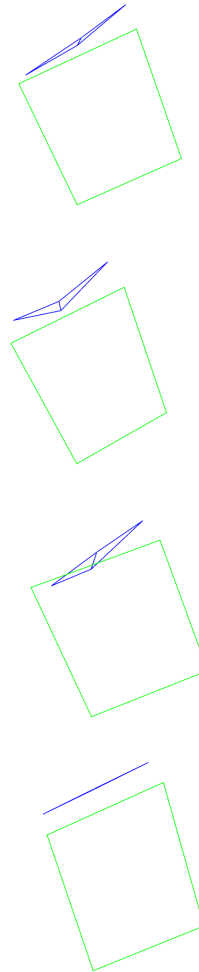
Elapsed Time from Activation

Activated Battery Testing

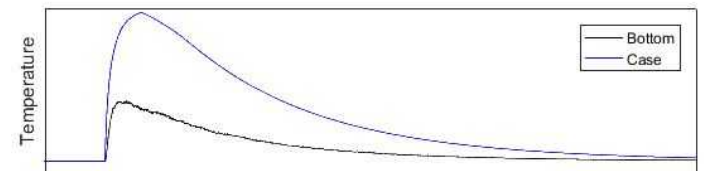
Internal Rocking Modes



ODS



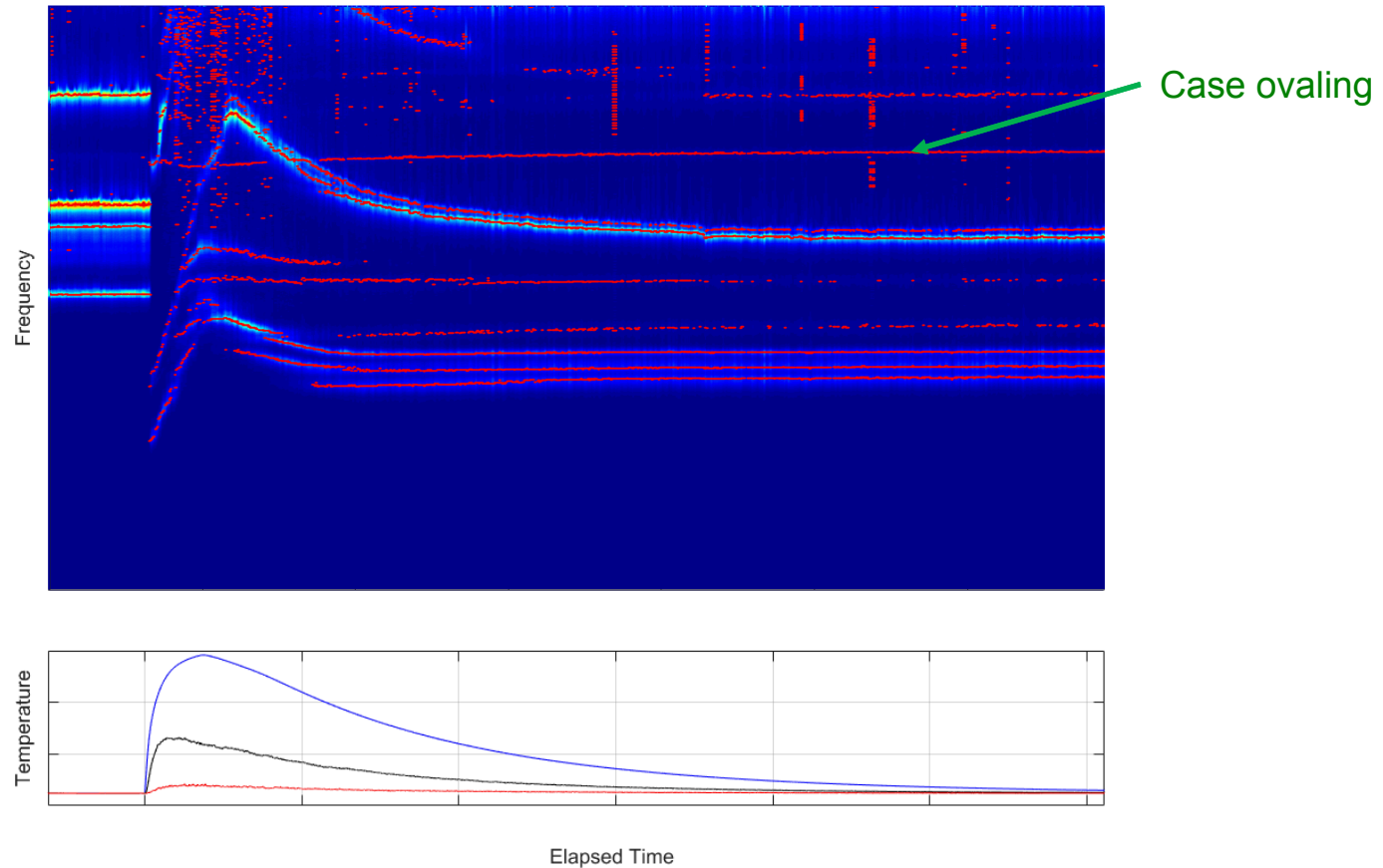
Elapsed Time from Activation



Elapsed Time from Activation

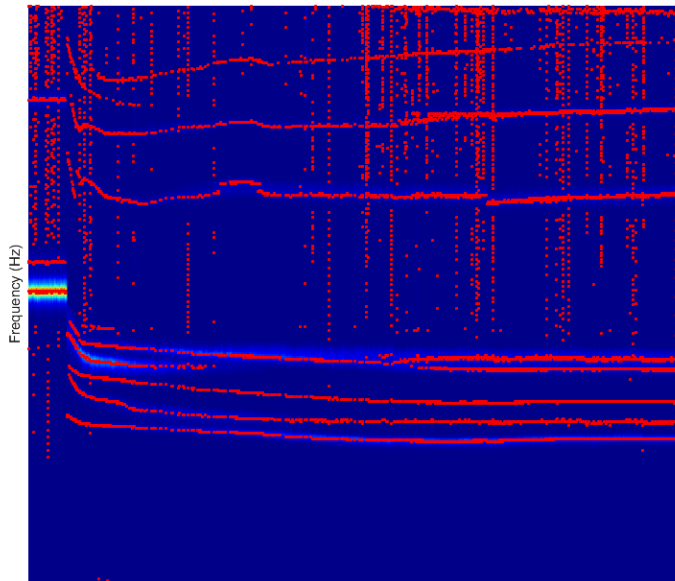
Activated Battery Testing

- Case ovaling modes less affected by internal changes

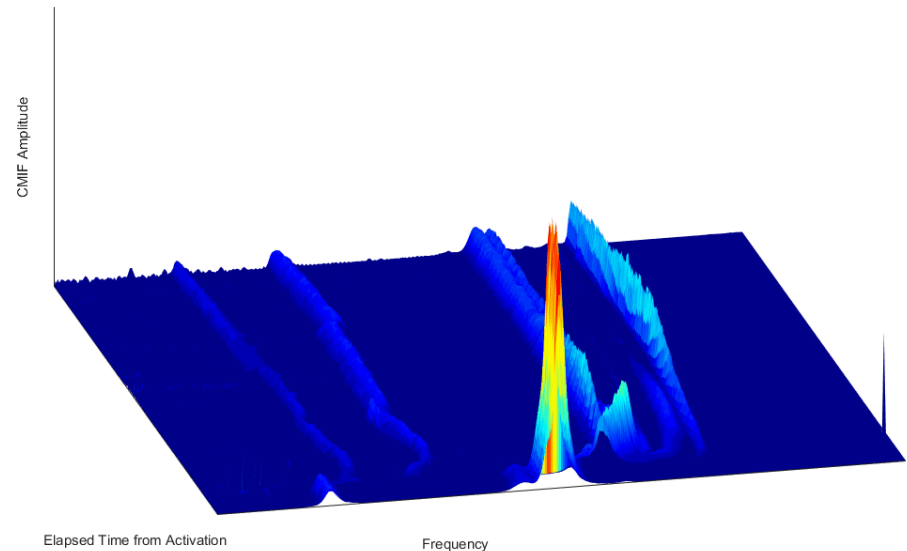


Activated Battery Testing

- Second type of thermal battery was also tested
 - Similar but different designs
 - Different trends altogether



Elapsed Time from Activation



Elapsed Time from Activation

Frequency

Conclusions

- **3D SLDV benefits:**
 - Higher point density without mass loading
 - Out of plane measurements & high fidelity shape spatial resolution
 - Non-contact for test articles at extreme temperatures
 - Essentially: allowed us to do a test we couldn't before
- **3D SLDV drawbacks/issues:**
 - Typical deficiencies: Line of sight only, small displacements only
 - LDV affected by thermal gradients around test article at extreme temperatures
 - Changes in refractive index around part caused appreciable speckle noise (hypothesis)
 - Indications that this can be mitigated in some circumstances
 - Surface preparation can be a challenge for high temperatures
 - Mitigated with new PSV-500 Xtra (IR) system
 - High-temp sponge has a high coefficient of thermal expansion
 - Caused first test articles to displace upwards, causing hammer contact/double impacts
 - Had to change base material, stiffer but rigid body modes still well below elastic
 - It worked, but...SLDV not optimal for this application!
 - Changes too quickly for averaging and induces FRF inconsistencies during scans
 - Multipoint 1D/3D LDV, possibly DIC?