

# Toward a Paver Replacement

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Osting**

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**26<sup>th</sup> International Meshing Roundtable**

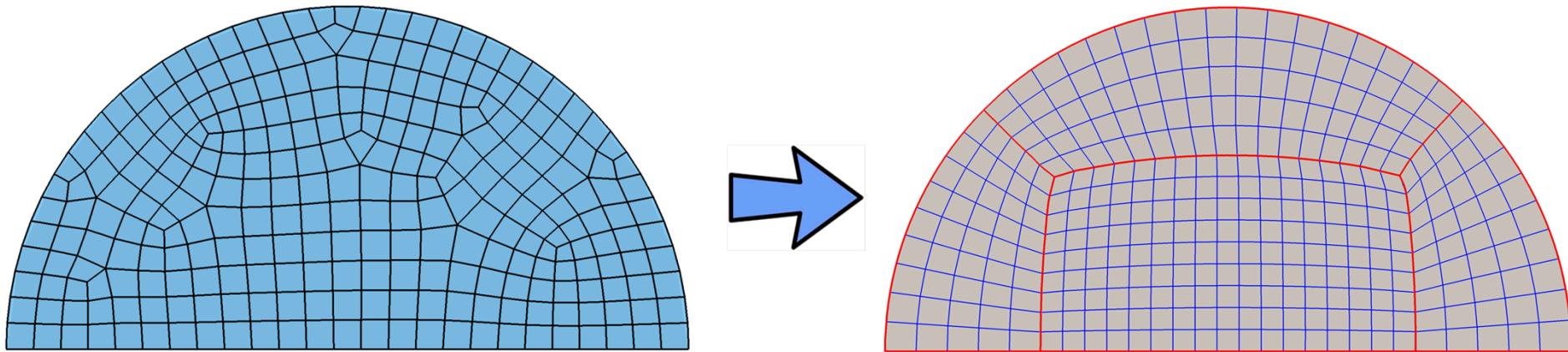
**Barcelona, Spain**



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# Introduction

# Paver Replacement



## Wish List

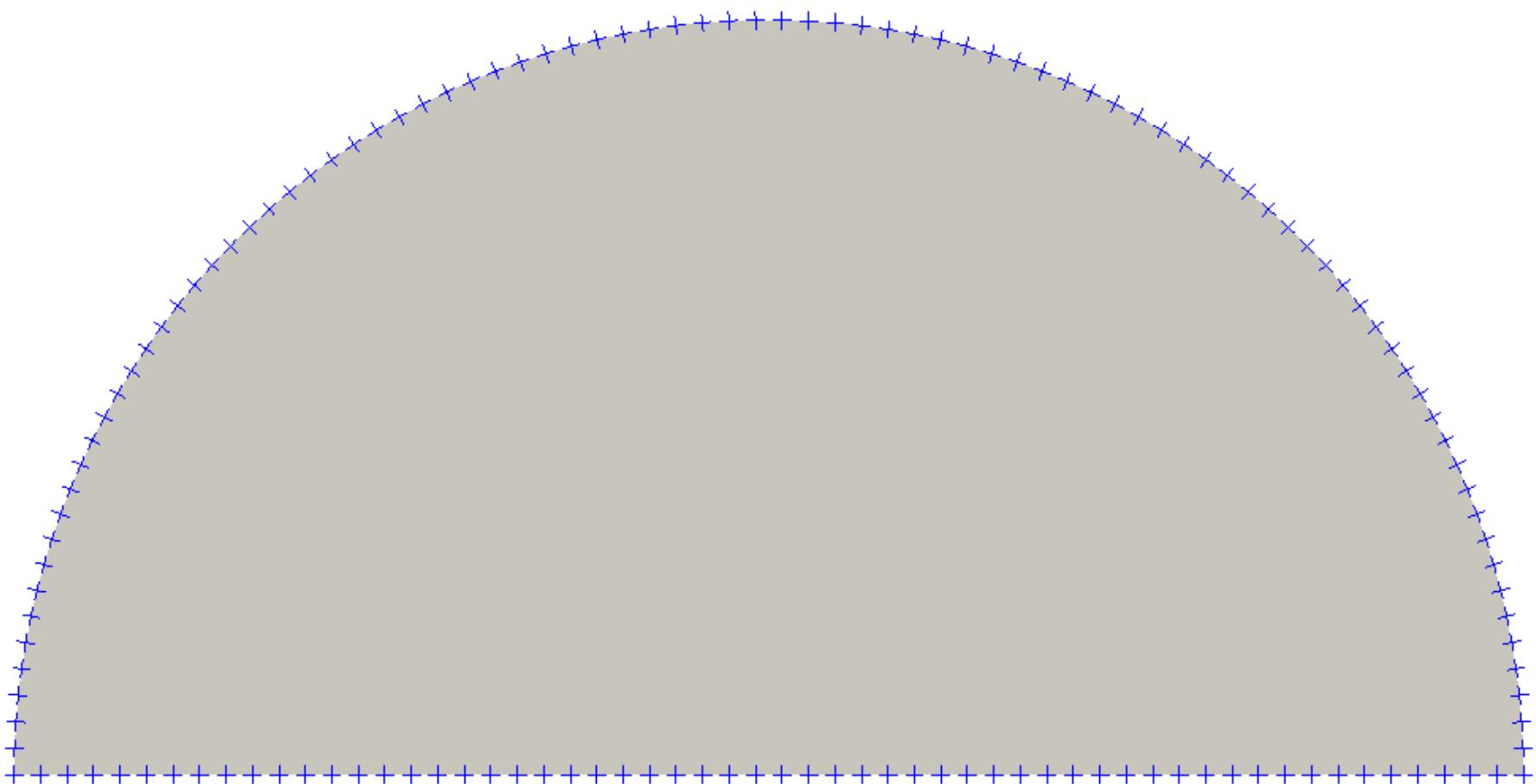
1. High element quality
2. Boundary aligned elements
3. Block Structured mesh
4. Prescribed size map
5. Prescribed boundary intervals.
6. Guaranteed results
7. Produces predictable output

# Basic Cross Field Meshing Algorithm (Kowalski et al. 2013)

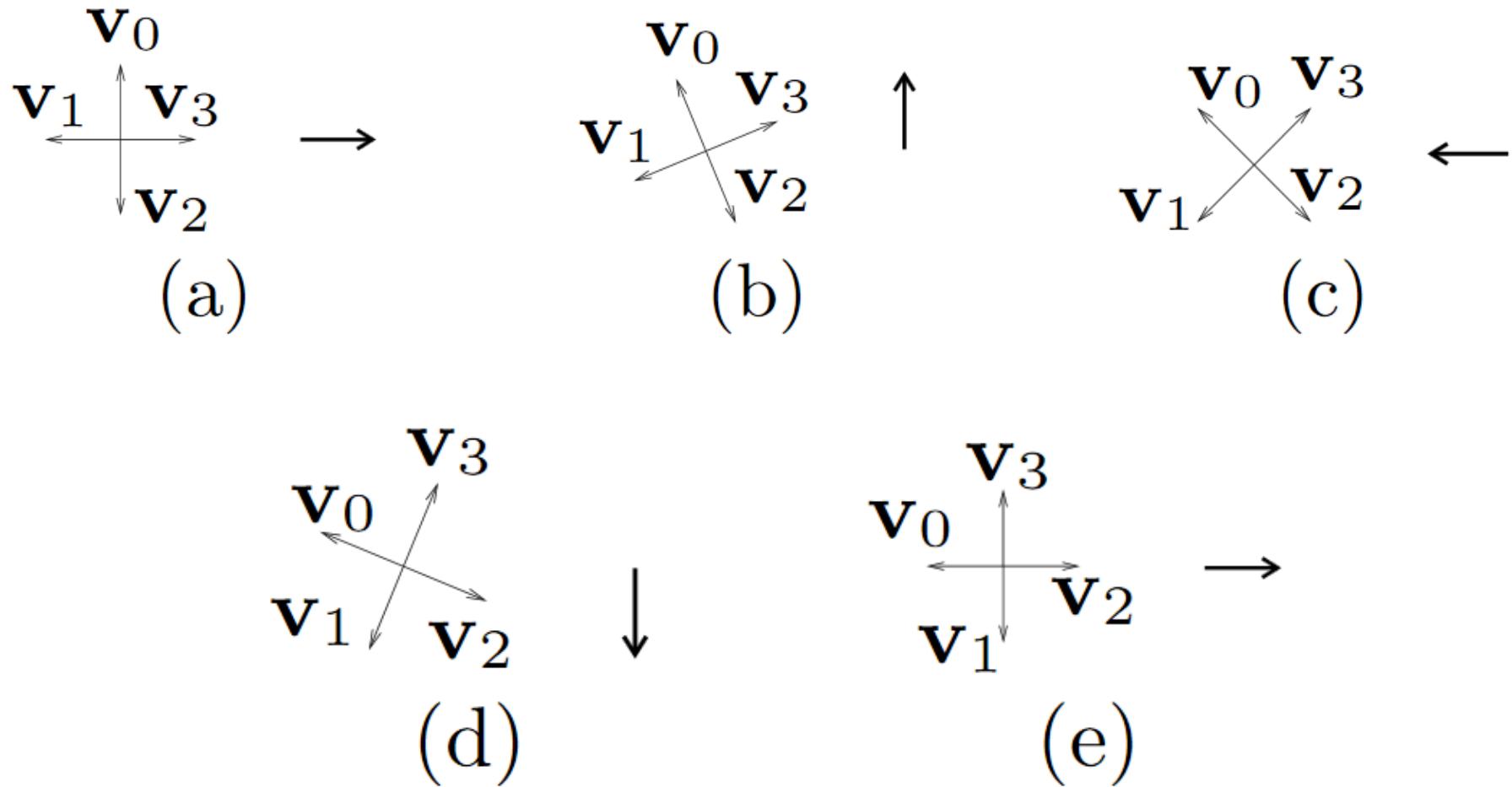
# 2D Cross Field Meshing Algorithm



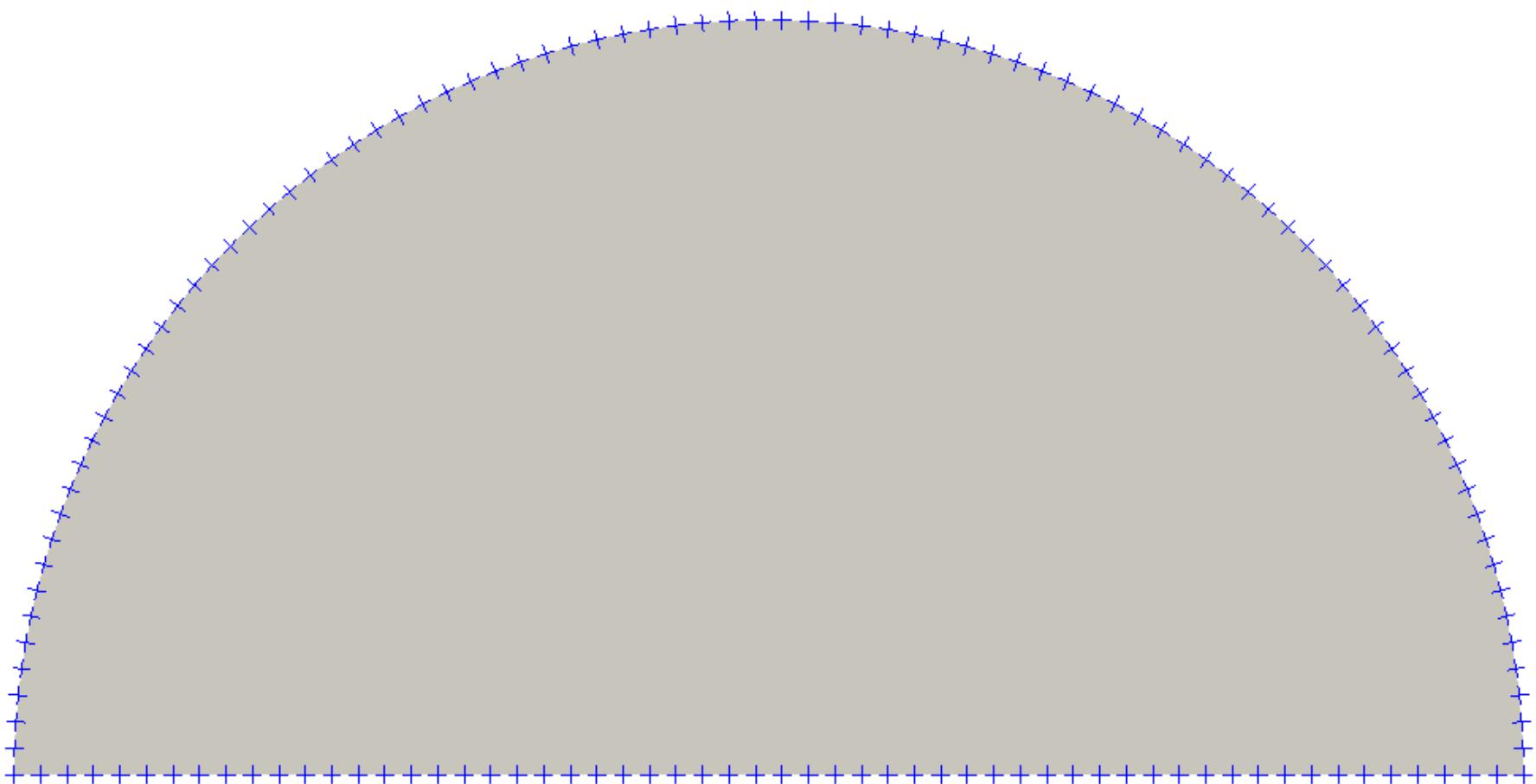
# 2D Cross Field Meshing Algorithm



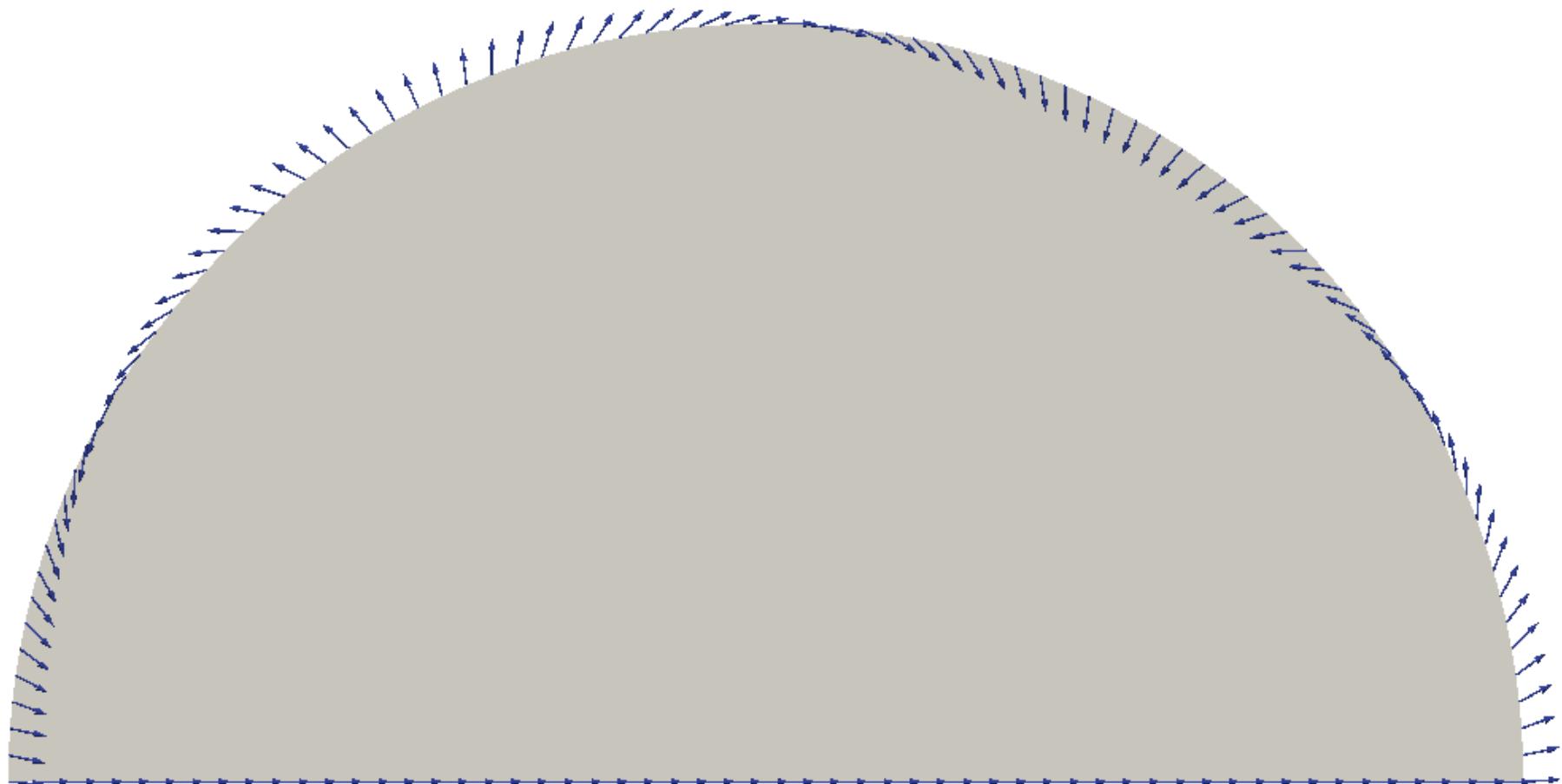
# Crosses and Representation Vector



# 2D Cross Field Meshing Algorithm



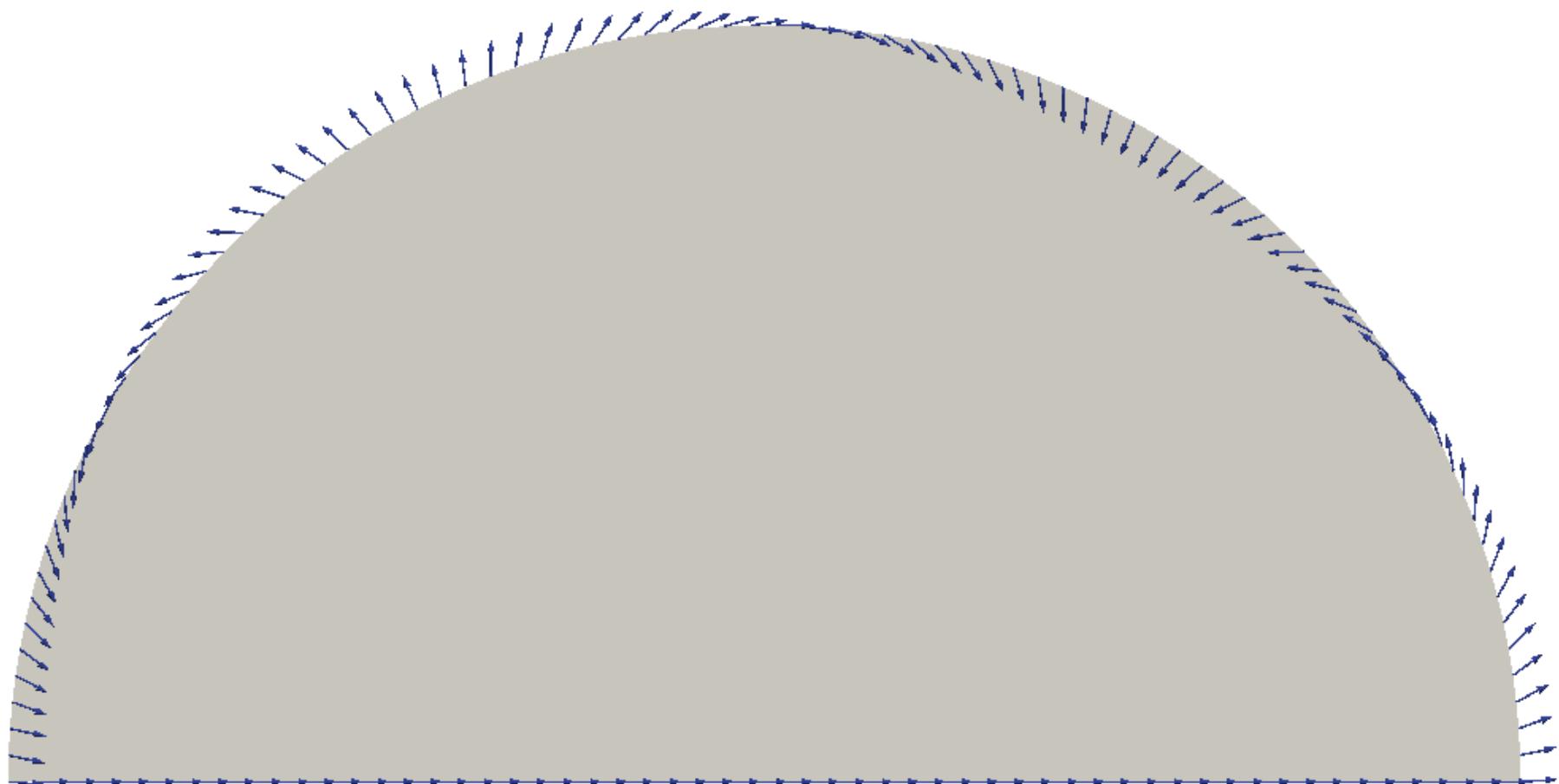
# 2D Cross Field Meshing Algorithm



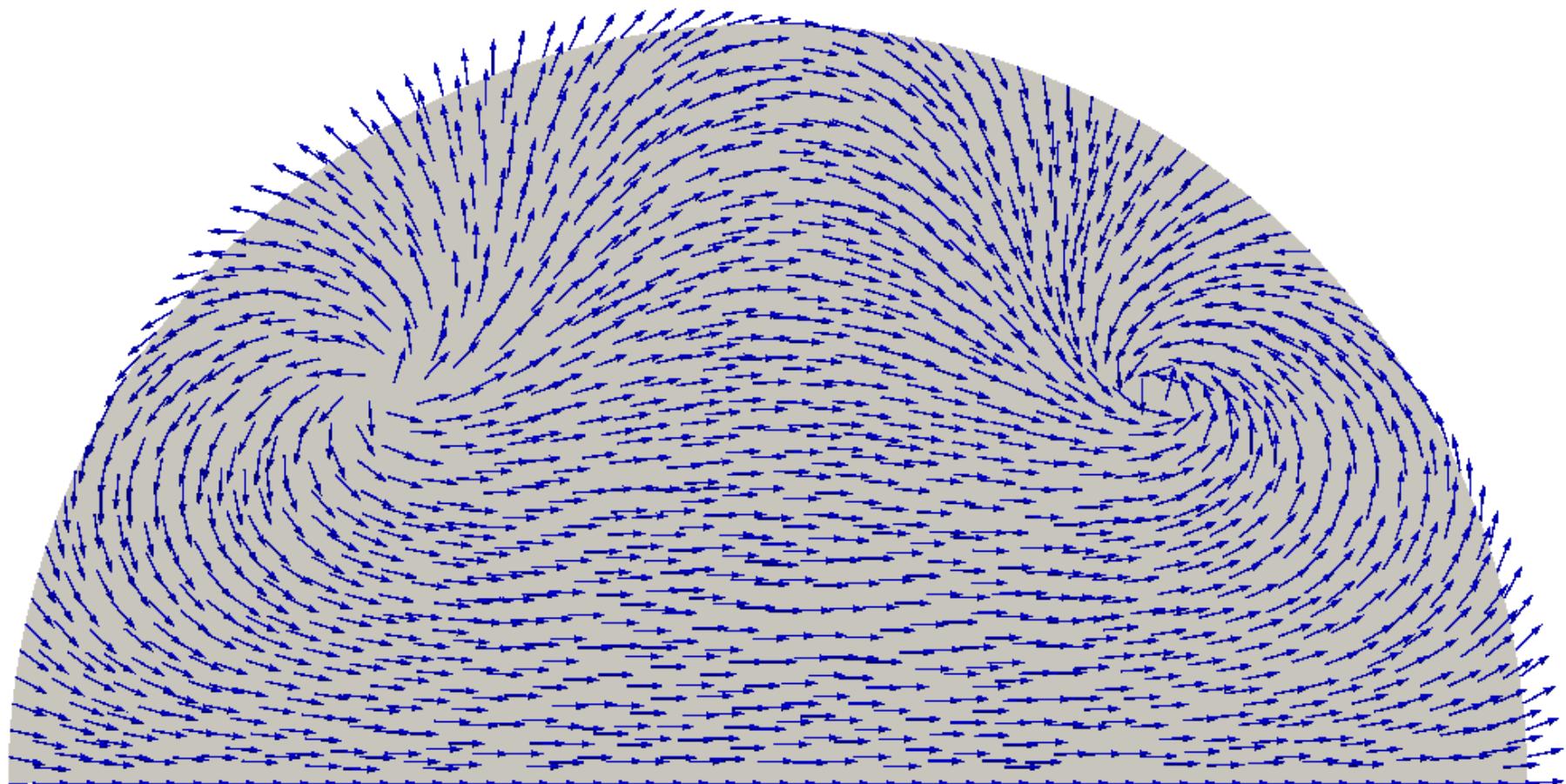
# 2D Cross Field Meshing Algorithm

$$\left\{ \begin{array}{l} \min_u E(u) \\ E(u) = \frac{1}{2} \int_D |\nabla u|^2 dA \\ u(x) = R(f_0(x)) \quad \forall x \in \partial D \\ |u(x)| = 1 \quad a.e. x \in D \end{array} \right.$$

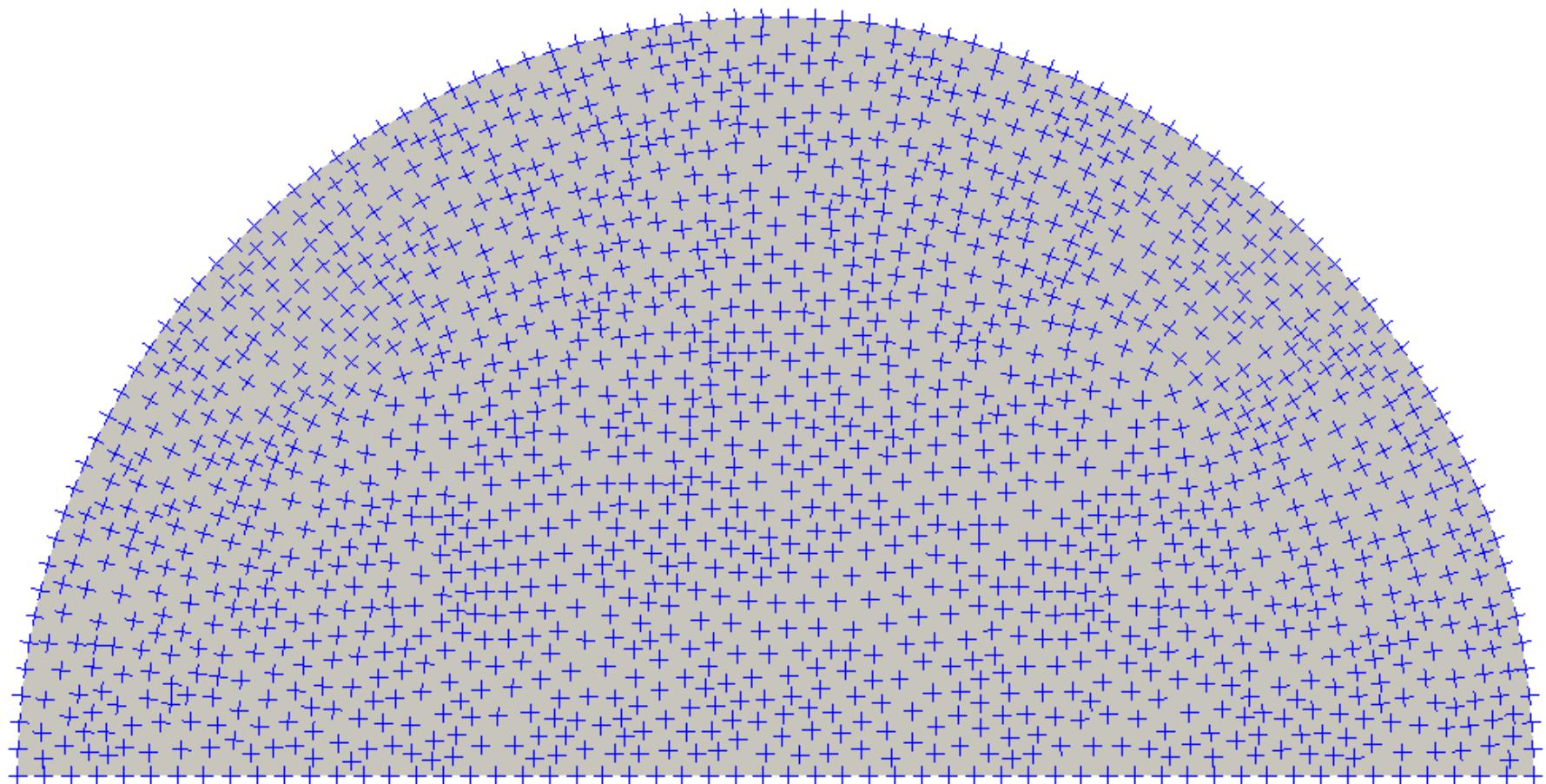
# 2D Cross Field Meshing Algorithm



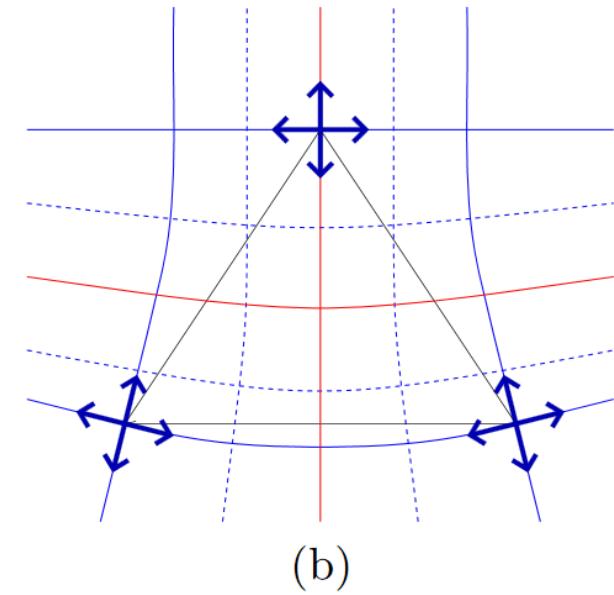
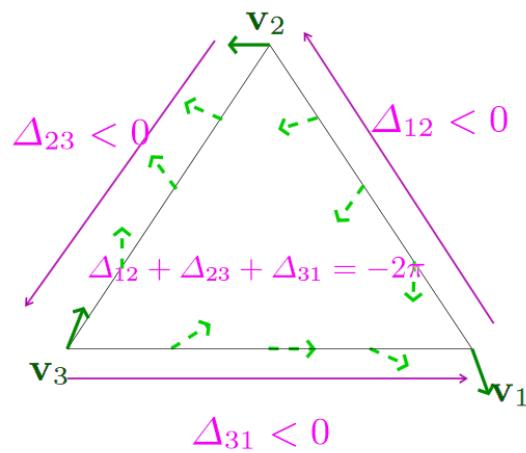
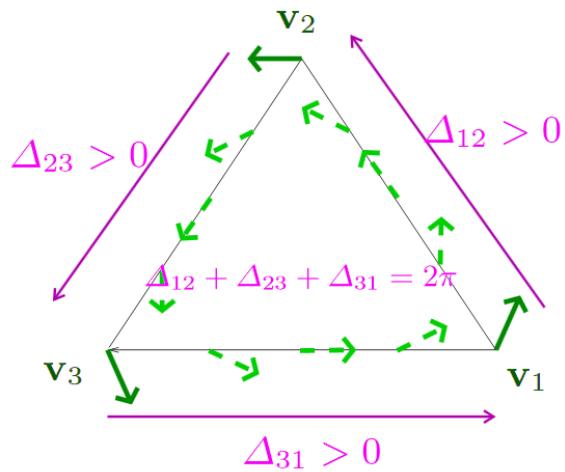
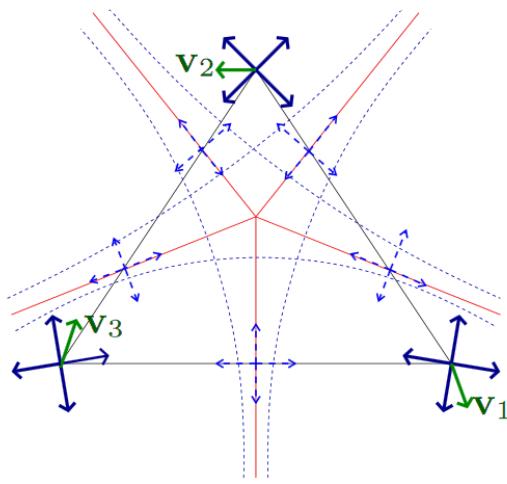
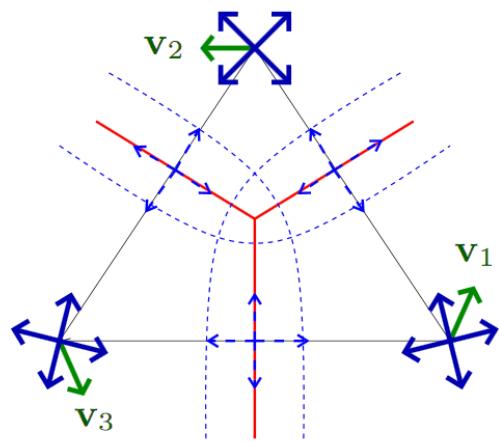
# 2D Cross Field Meshing Algorithm



# 2D Cross Field Meshing Algorithm



# Cross Field Singularities

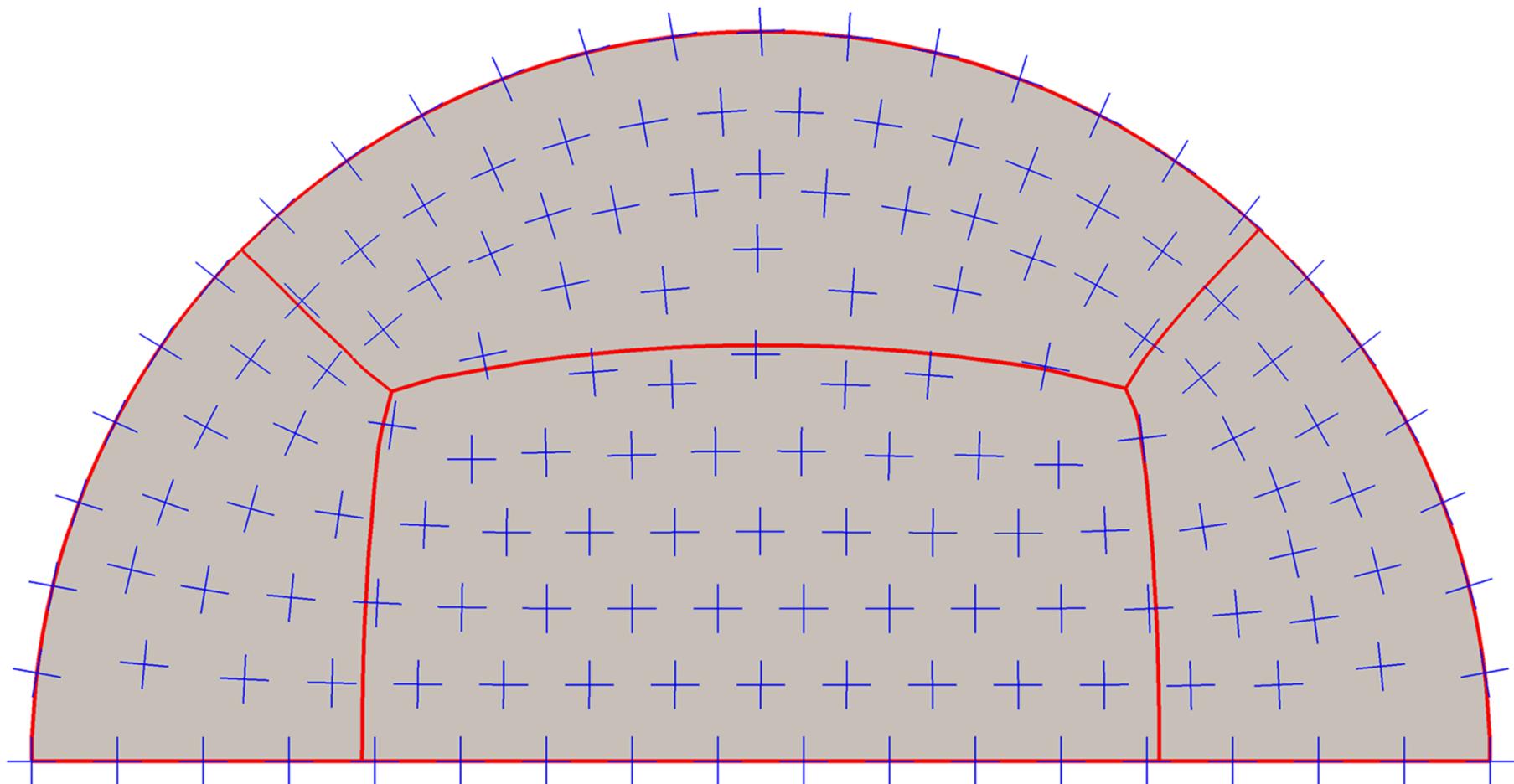


Nonsingular Triangle

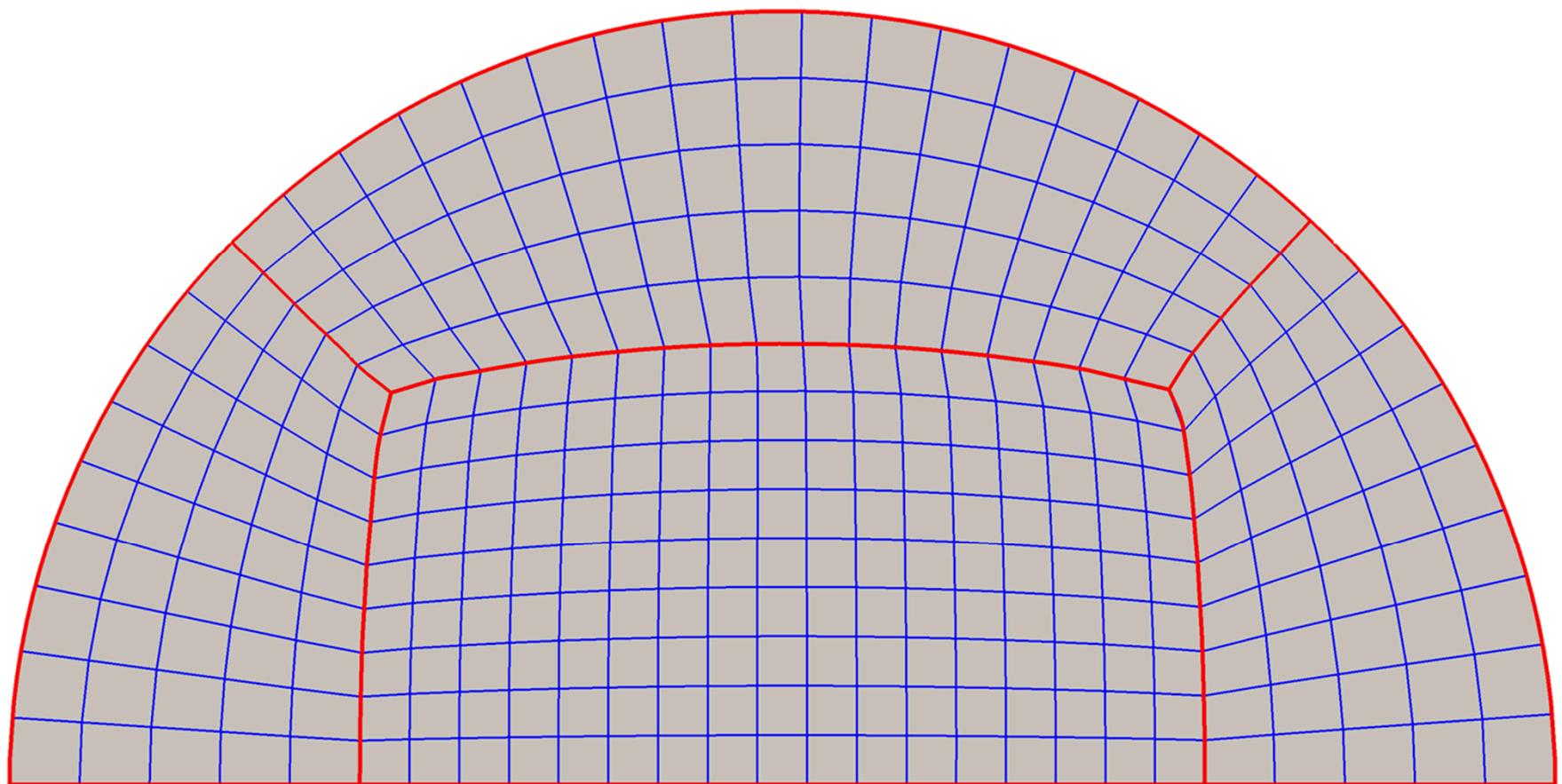
Singular Triangles

Kowalski et al. 2013

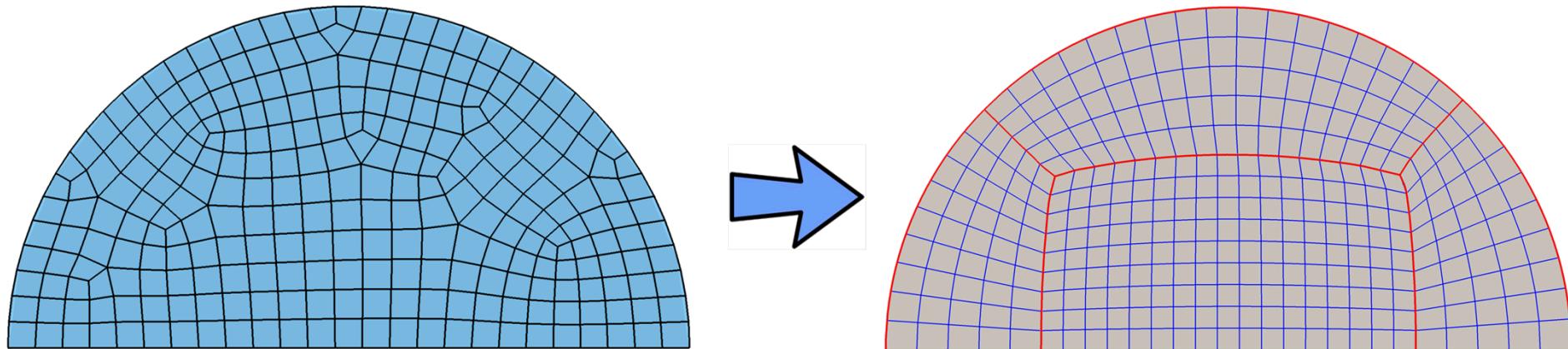
# 2D Cross Field Meshing Algorithm



# 2D Cross Field Meshing Algorithm



# Candidate: Cross field guided methods



## Wish List

1. High element quality ✓
2. Boundary aligned elements ✓
3. Block Structured mesh ?
4. Prescribed size map
5. Prescribed boundary intervals.
6. Guaranteed results
7. Produces predictable output

# Connection to Ginzburg- Landau Theory

# Ginzburg-Landau Functional

Original problem is not well defined:

$$\left\{ \begin{array}{l} \min_u E(u) \\ E(u) = \frac{1}{2} \int_D |\nabla u|^2 dA \\ u(x) = g(x) \quad \forall x \in \partial D \\ |u(x)| = 1 \quad a.e. x \in D \end{array} \right.$$

Relaxed problem:

$$\min_{u \in H_g^1(D, \mathbb{C})} E_\varepsilon(u)$$

$$E_\varepsilon(u) = \frac{1}{2} \int_G |\nabla u|^2 + \frac{1}{4\varepsilon^2} \int_G (|u|^2 - 1)^2$$

# Result: Well Defined Limit of Relaxed Problem

**Theorem 2.2.2** (Bethuel et al. [4]). *Let  $d = \deg(g, \partial D)$ . Given a sequence  $\varepsilon_n \rightarrow 0$  there exists a subsequence  $\varepsilon_{n_i}$  and exactly  $d$  points  $a_1, a_2, \dots, a_d$  in  $D \subset \mathbb{C}$  and a smooth harmonic map  $u_*: D \setminus \{a_1, \dots, a_d\} \rightarrow \mathbb{T}$  with  $u_* = g$  on  $\partial D$  such that*

$$u_{\varepsilon_{n_i}} \rightarrow u_* \text{ in } C_{loc}^k(D \setminus \bigcup_i (a_i)) \quad \forall k \text{ and in } C^{1,\alpha}(\bar{D} \setminus \bigcup_i (a_i)) \quad \forall \alpha < 1$$

*In addition, if  $d \neq 0$  each singularity of  $u_*$  has index  $\text{sgn}(d)$  and, more precisely, there are complex constants  $(\alpha_i)$  with  $|\alpha_i| = 1$  such that*

$$\left| u_*(z) - \alpha_i \frac{z - a_i}{|z - a_i|} \right| \leq C|z - a_i|^2 \text{ as } z \rightarrow a_i, \quad \forall i$$

This gives us a generalized sense in which to understand the energy minimization problem

# **Merriman-Bence-Osher (MBO) Method**

# Merriman-Bence-Osher (MBO) Method

## Original Method

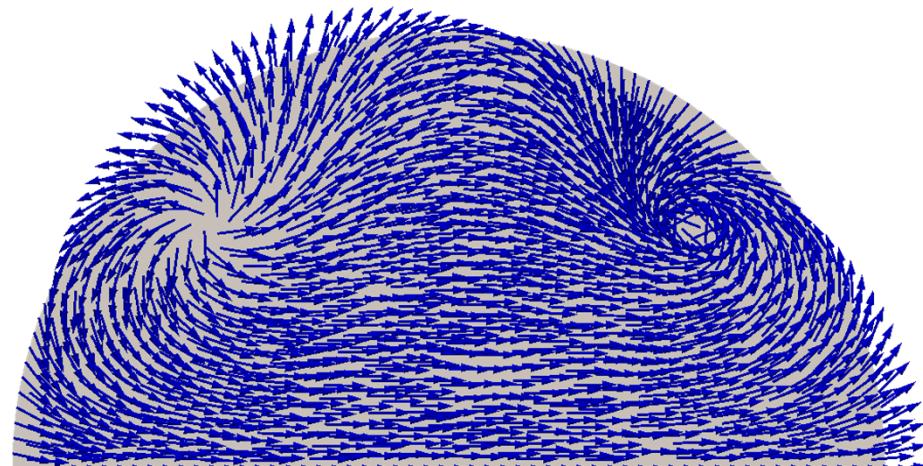
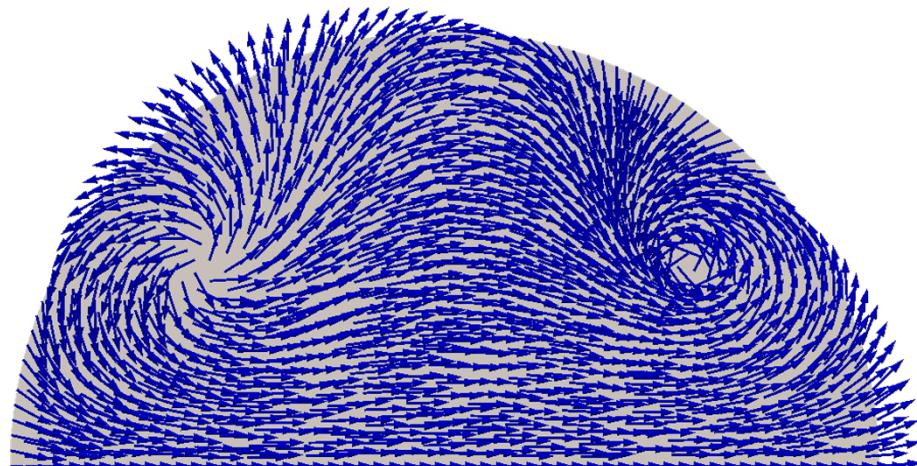
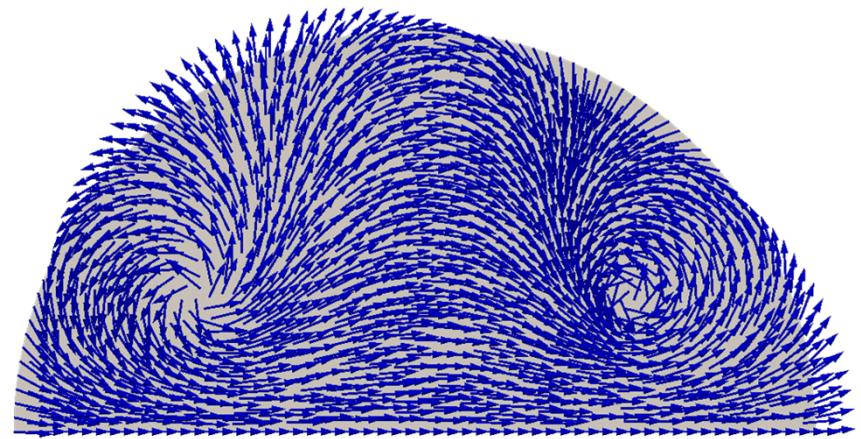
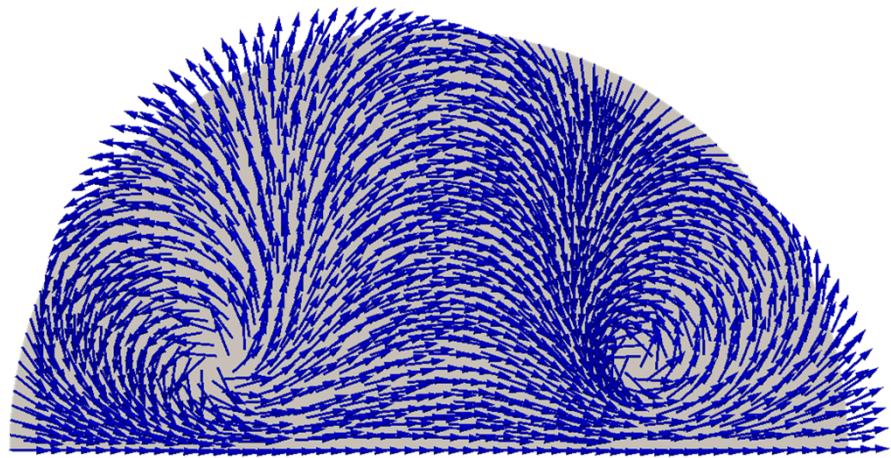
- Introduced as a method for motion by mean curvature
- Minimizes a two-well potential energy analogous to the complex GL energy

## New Application to Frame Fields

- Iterative method to minimize cross field energy:

$$u_0 = \frac{\tilde{u}}{|\tilde{u}|} \quad \text{and} \quad u_k = \frac{e^{\tau\Delta} u_{k-1}}{|e^{\tau\Delta} u_{k-1}|} \quad k \geq 1.$$

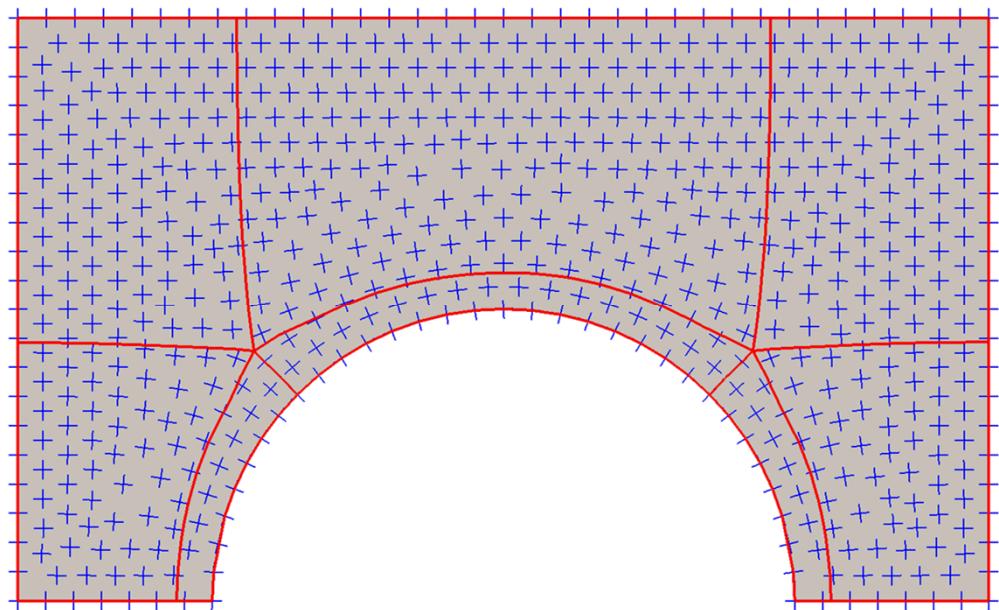
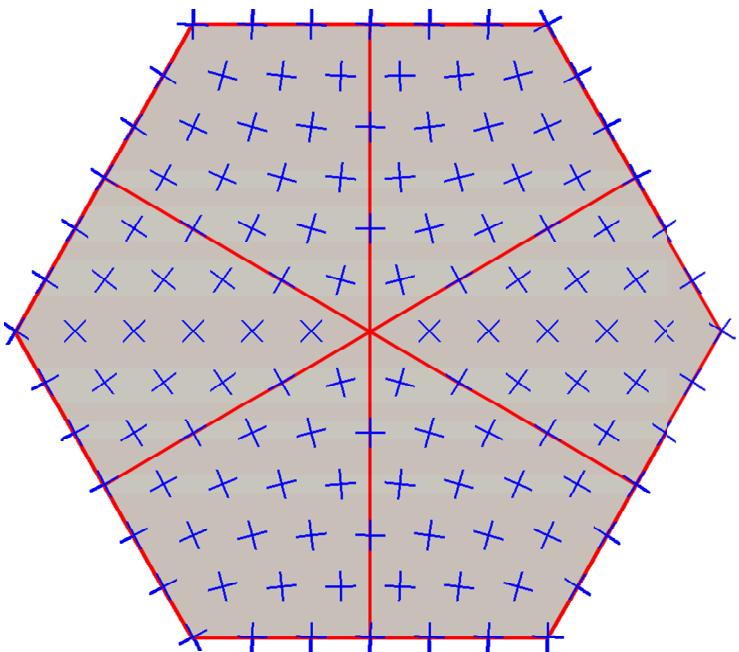
# MBO Method



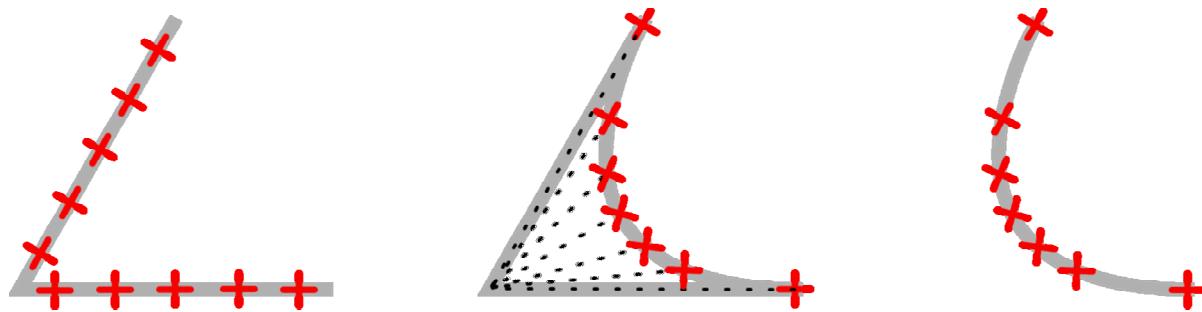
# Asymptotic Behavior of Cross Fields Near Singularities

# Separatrices of a Singularity

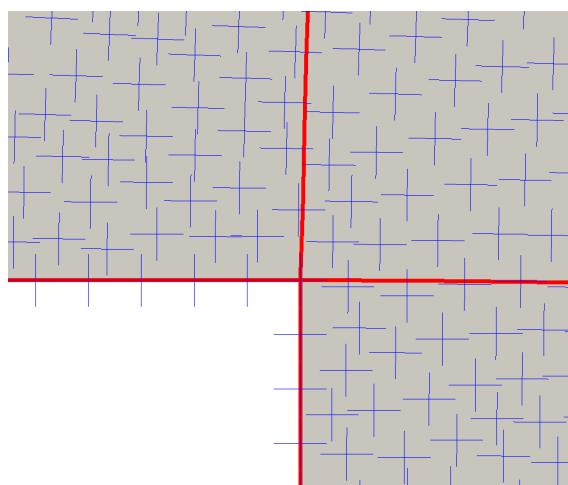
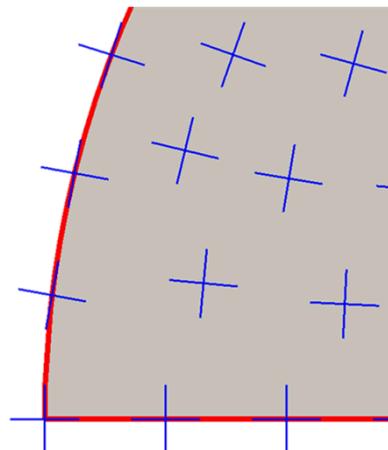
LEMMA 5.1. *Let  $f$  be a boundary-aligned canonical harmonic cross field on  $D$ . Let  $a$  be an interior singularity of  $f$  of index  $d/4$  with  $d < 4$ . There are exactly  $4 - d$  separatrices meeting at  $a$ . These separatrices partition a neighborhood of  $a$  into  $4 - d$  even-angled sectors.*



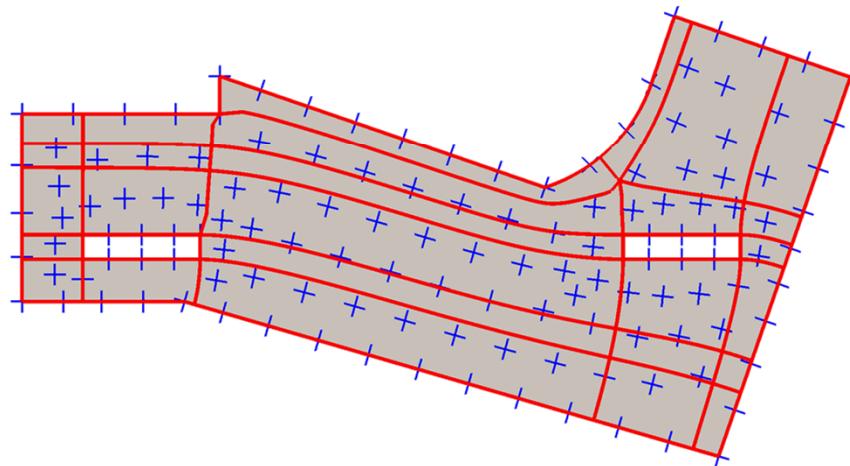
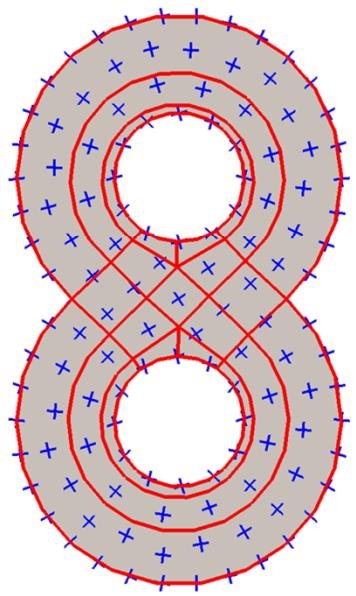
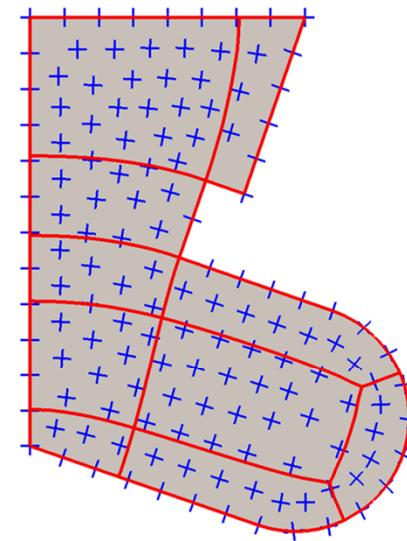
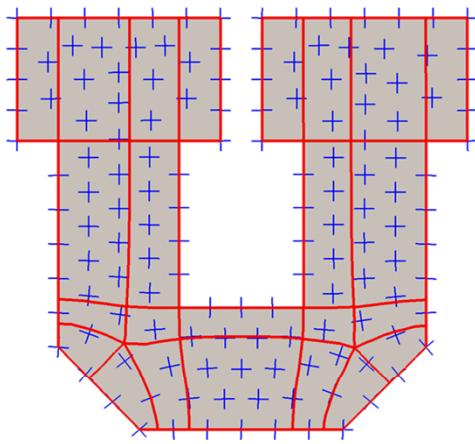
# Boundary Singularities



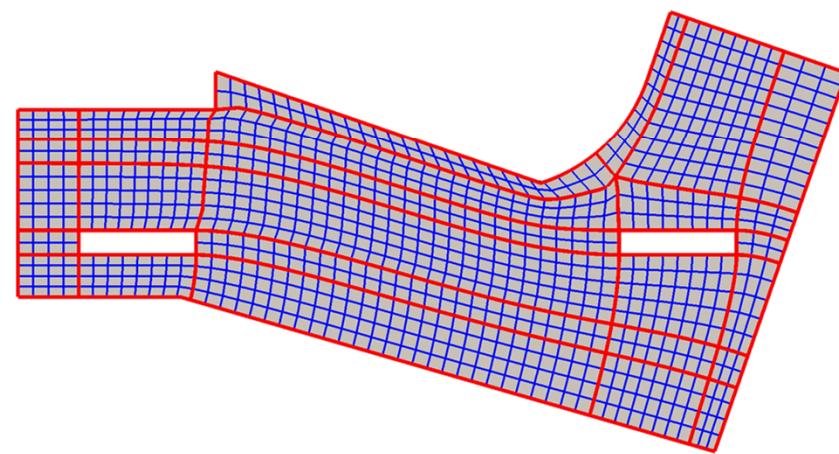
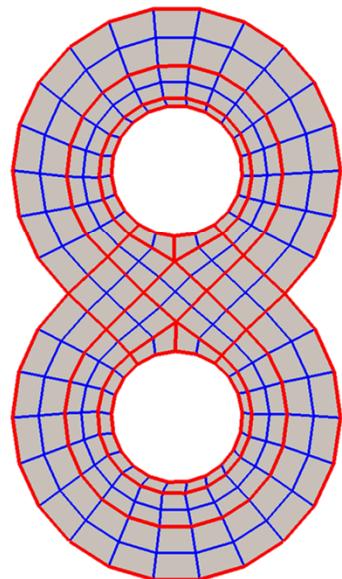
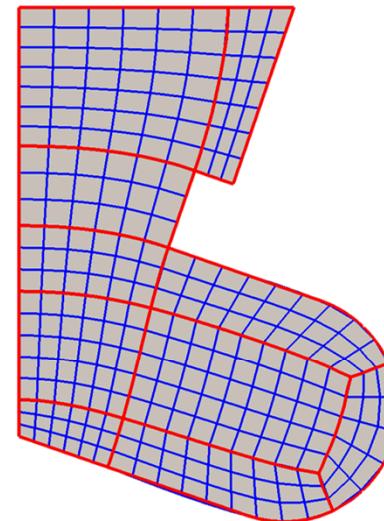
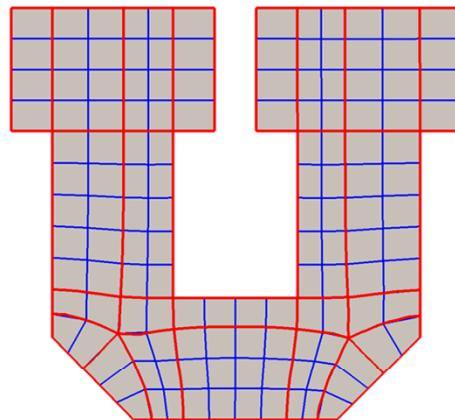
LEMMA 5.4. Let  $c$  be a boundary singularity of  $f$  of index  $d/4$  with  $d < 2$ . There are exactly  $3 - d$  separatrices meeting at  $c$  (including the boundaries themselves). These separatrices partition a neighborhood of  $c$  into  $2 - d$  even-angled sectors.



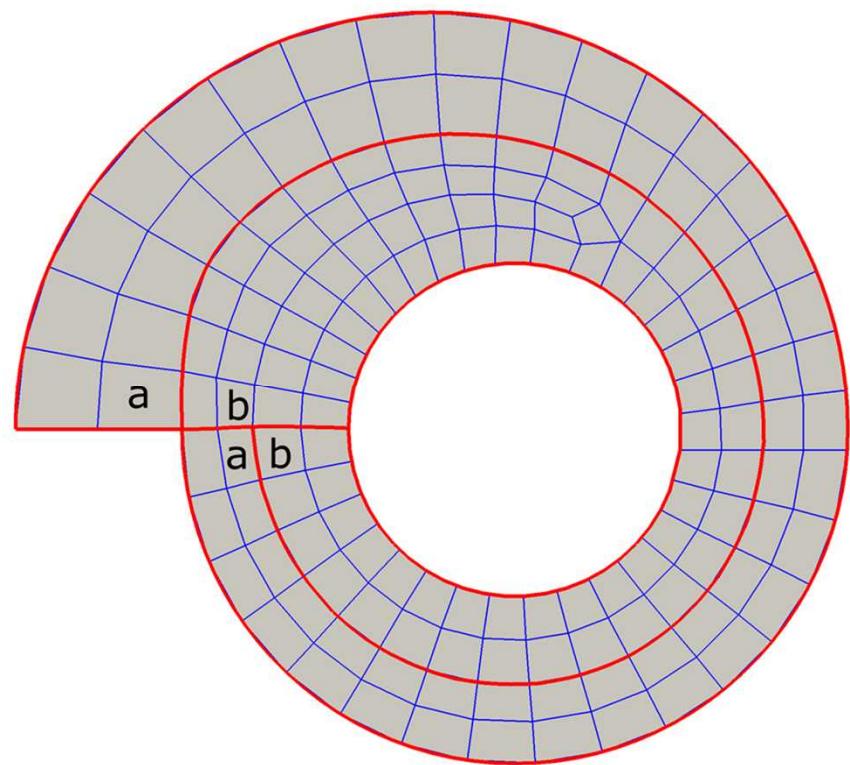
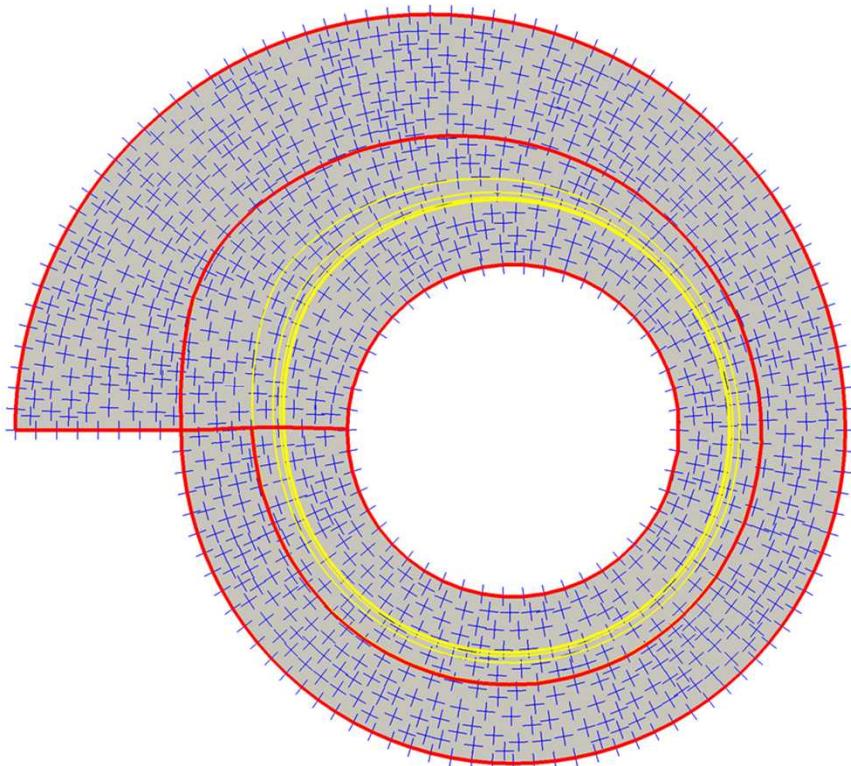
# Partition into four-sided regions



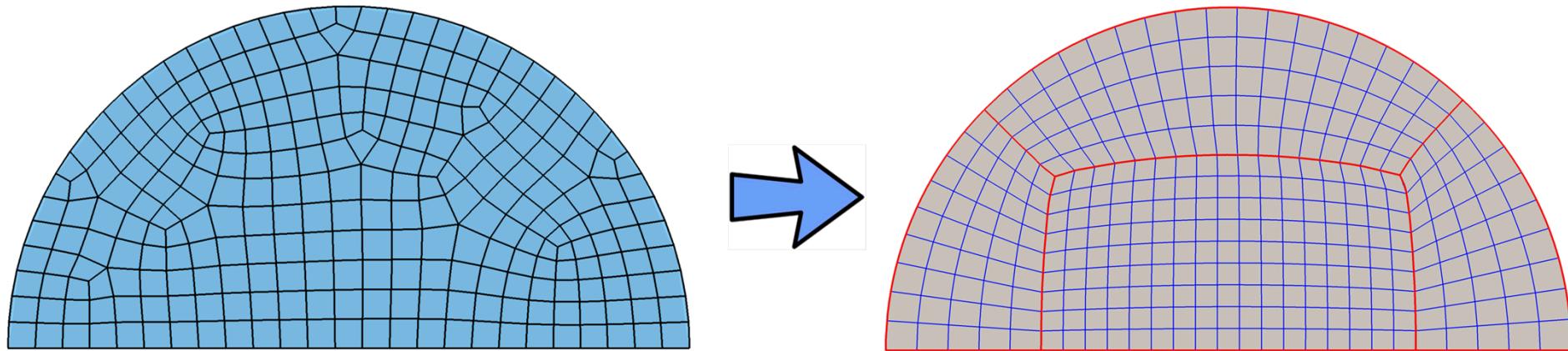
# Meshing



# Limit Cycles



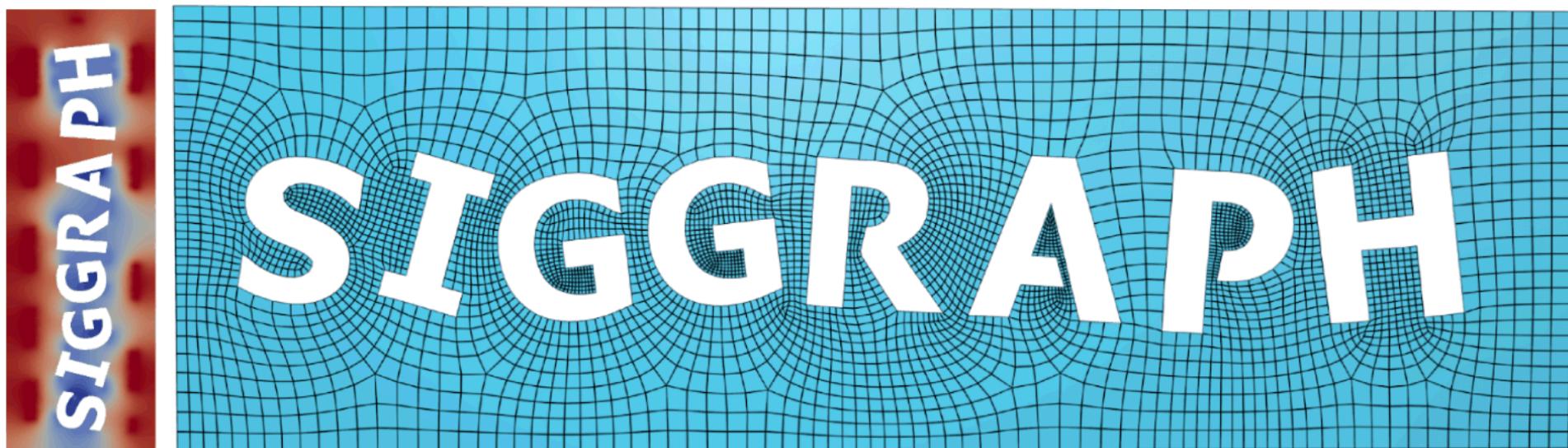
# Candidate: Cross field guided methods



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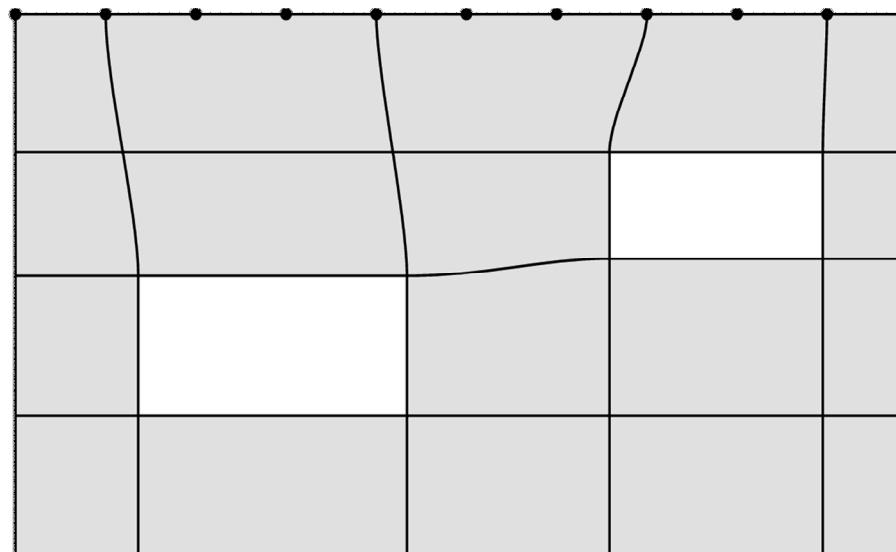
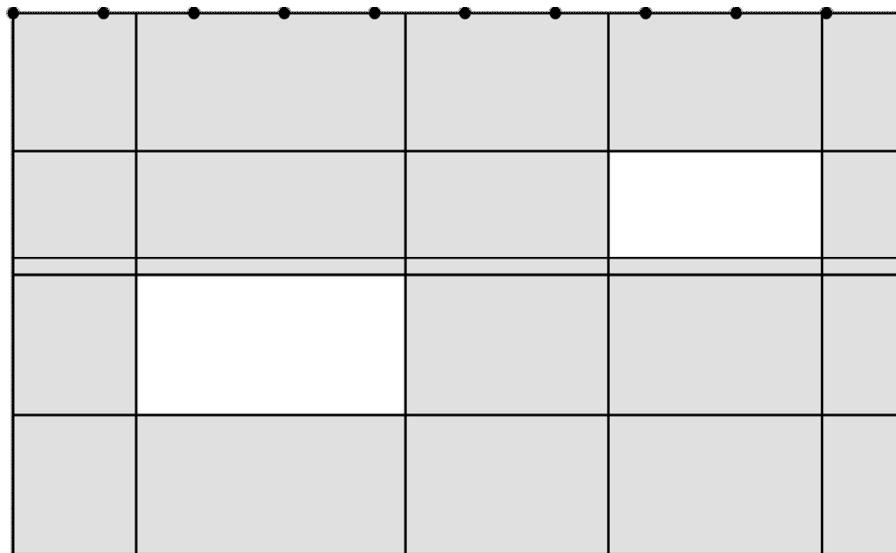
# Size Map



- T. Jiang, X. Fang, J. Huang, H. Bao, Y. Tong, M. Desbrun, Frame field generation through metric customization, ACM Transactions on Graphics 34 (2015).

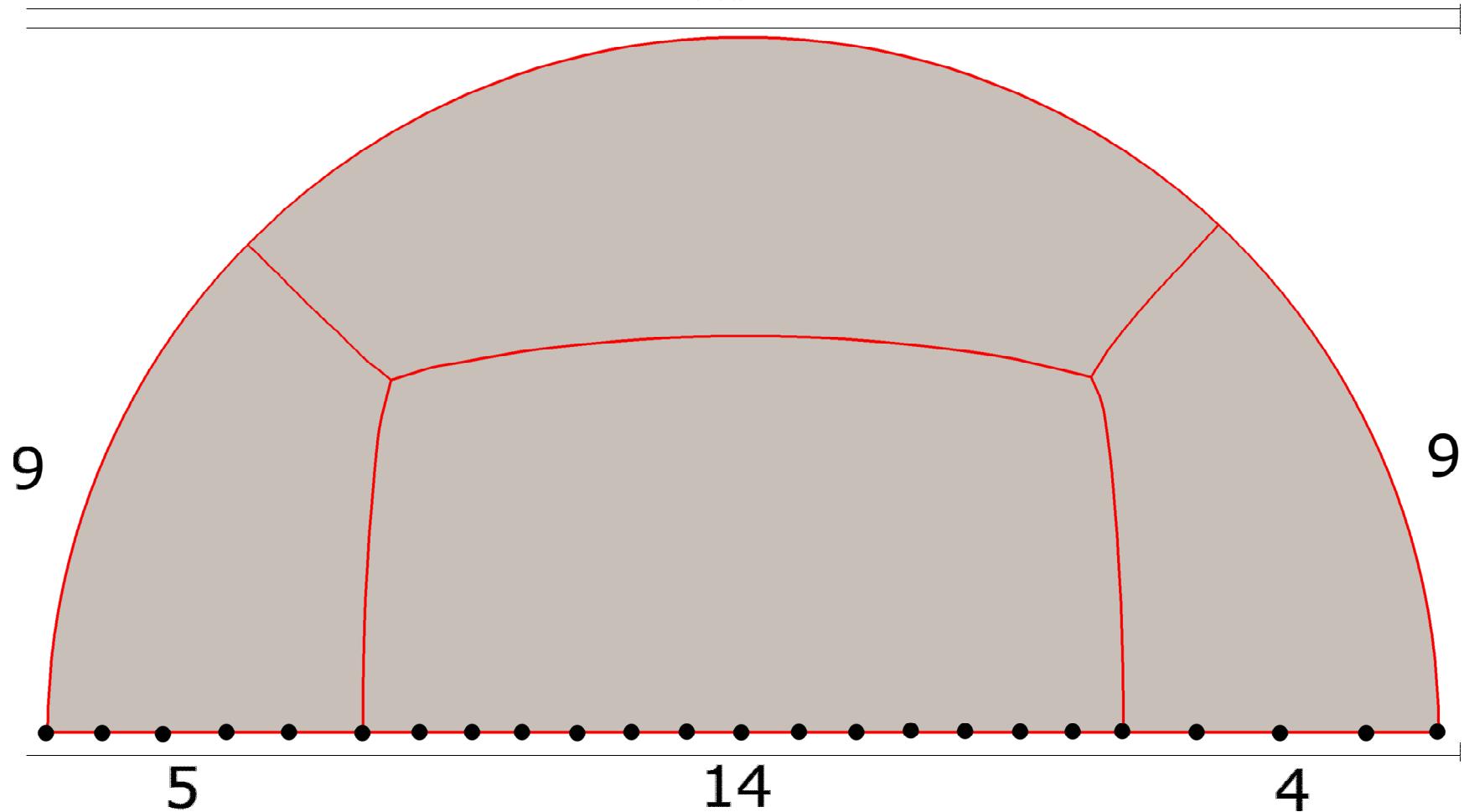
We intend to adapt the work of Jiang et al. to the MBO method for designing cross fields

# Partition Modification



# Boundary Interval Assignment

17



- S. A. Mitchell, High fidelity interval assignment, International Journal of Computational Geometry & Applications 10 (2000) 399–415.

# Summary

1. Connection with Ginzburg-Landau Theory
2. MBO method for minimizing cross field energy
3. Fixed Frame field design method
4. Asymptotic Behavior of Singularities
5. Cross Field Partitioning Theorem

# Acknowledgements

- Sandia National Labs
- University of Utah
- NSF DMS 16-19755
- Matt Staten
- Braxton Osting