

Multi-Level Acceleration of Scattering-Source Iterations with Application to Electron Transport

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Motivation

- Traditional source iteration (SI) can converge slowly for certain transport problems, e.g. electron transport
- Preconditioning/acceleration strategies have been developed over the past few decades
 - Diffusion Synthetic Acceleration (DSA)
 - Transport Synthetic Acceleration (TSA)
 - Krylov methods
- Effectiveness of these methods are highly problem dependent
 - Scattering ratio and degree of scattering anisotropy
 - Material discontinuities, e.g. highly scattering regions and streaming/void regions
 - Different physics for different particle types and energy ranges
- Finding an effective general preconditioner difficult
- Multiple levels of preconditioning can be more effective



Overview

- Description of the capabilities of the SCEPTRE radiation transport code
- Transport Synthetic Acceleration (TSA) applied to transport sweeps
 - Overview of the method
 - Implementation into the SCEPTRE code
 - Application of the method to a practical photon/electron transport problem
- Krylov/GMRES (Generalized Minimum RESidual) alternative to transport sweeps
 - Overview of the method
 - TSA-preconditioned Krylov algorithm
- Application of TSA and Krylov algorithms to a model 3-region cylinder test problem
 - Electron transport in uniform lead
 - Electron transport in non-uniform material (lead/void/lead)
 - Artificial cross sections: pure-scattering
 - *Compare P_3 and P_7 scattering*



SCEPTRE radiation transport code

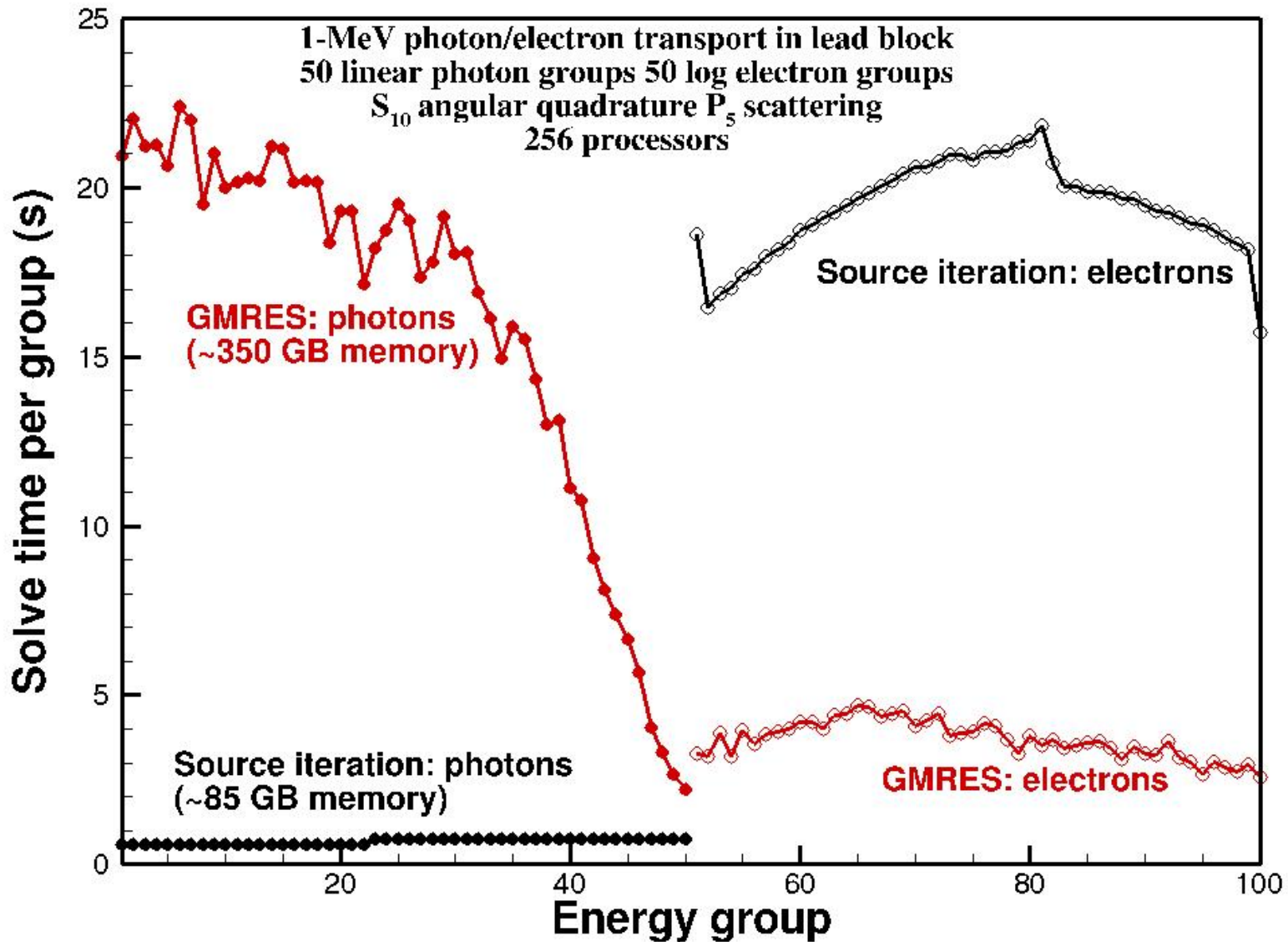
- Sandia Computational Engine for Particle Transport for Radiation Effects
- Unstructured-mesh spatial finite elements
 - Discontinuous finite elements (DFE)
 - Continuous finite elements (CFE)
- Discrete ordinates (S_N) or spherical harmonics (P_N) angular treatment
- Multigroup energy treatment
- Primary application: coupled photon/electron/positron transport
- Different solver type may be used for each energy group
 - User defines arbitrary number of different solvers
 - Individual solvers assigned to each energy group
 - Different solvers tend to be more efficient for specific particle types, material media, energy range ...



Solvers available in SCEPTRE

- Sweep-based source iteration (SI)
 - 1st-order form of the transport equation
 - Discontinuous finite elements (DFE) in space
- Krylov-based, full-matrix-system solution
 - No within-group SI (solve space-angle dependence simultaneously using Trilinos solvers)
 - Generalized Minimum RESidual (GMRES)
 - *1st-order transport equation*
 - *DFE spatial differencing*
 - *Asymmetric*
 - *P_N or S_N*
 - Conjugate Gradients (CG)
 - *Self-adjoint angular flux (SAAF) form of the transport equation*
 - *Least-squares (LS) approximation*
 - *Continuous finite elements (CFE) in space*
 - *Symmetric Positive Definite (SPD)*
 - *P_N or S_N*
- Krylov/GMRES matrix-free
 - 1st-order transport equation
 - DFE spatial differencing
 - Sweeping algorithm used to construct Krylov subspace

Comparison of solver time: source iteration (SI) vs. full-matrix Trilinos/GMRES iteration





Transport-synthetic acceleration (TSA) for source iteration (SI)

$$\mathcal{T}\psi(\mathbf{r}, \Omega) = \mathcal{S}\psi(\mathbf{r}, \Omega) + Q(\mathbf{r}, \Omega)$$

Streaming plus collision operator $\mathcal{T} \circ = \Omega \cdot \nabla \circ + \sigma_t \circ$

Scattering operator $\mathcal{S} \circ = \int d\Omega' \sigma_s(\Omega' \rightarrow \Omega) \circ$

Source iteration with TSA:

1. Fine-level sweep

$$\mathcal{T}\psi^{(k+1/2)} = \mathcal{S}\psi^{(k)} + Q$$

2. Error term

$$\varepsilon^{(k+1/2)} = \psi - \psi^{(k+1/2)}$$

3. Residual

$$r^{(k+1/2)} = \mathcal{S}(\psi^{k+1/2} - \psi^k)$$

Restriction operator

4. Coarse-level solve

$$(\mathcal{T}_c - \mathcal{S}_c)\varepsilon_c^{(k+1/2)} = \mathcal{R}r^{(k+1/2)}$$

5. Apply correction term

$$\psi^{(k+1)} = \psi^{(k+1/2)} + \mathcal{P}\varepsilon_c^{(k+1/2)}$$

Prolongation operator

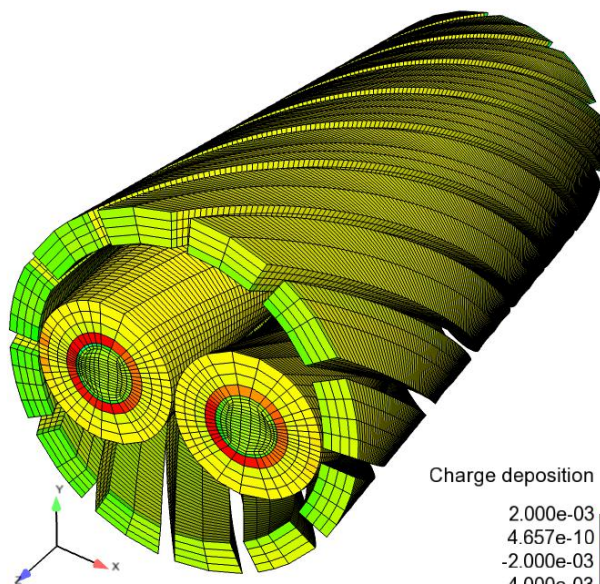
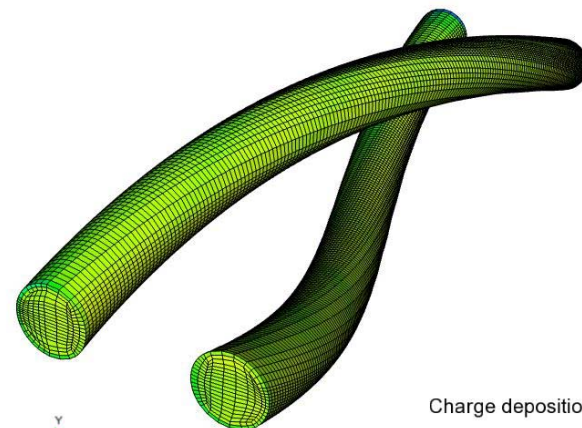
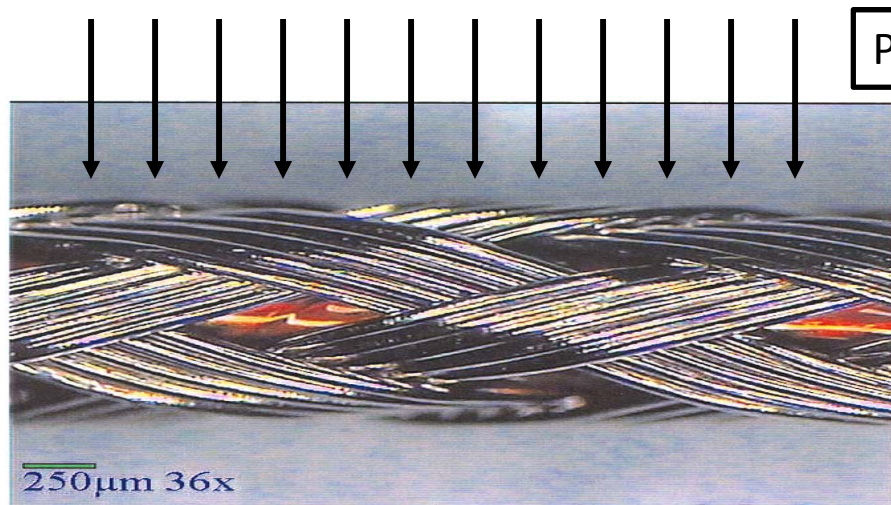


Coarse-level solve (Krylov full matrix)

$$(\mathcal{T}_c - \mathcal{S}_c)\varepsilon_c^{(k+1/2)} = r_c^{(k+1/2)}$$

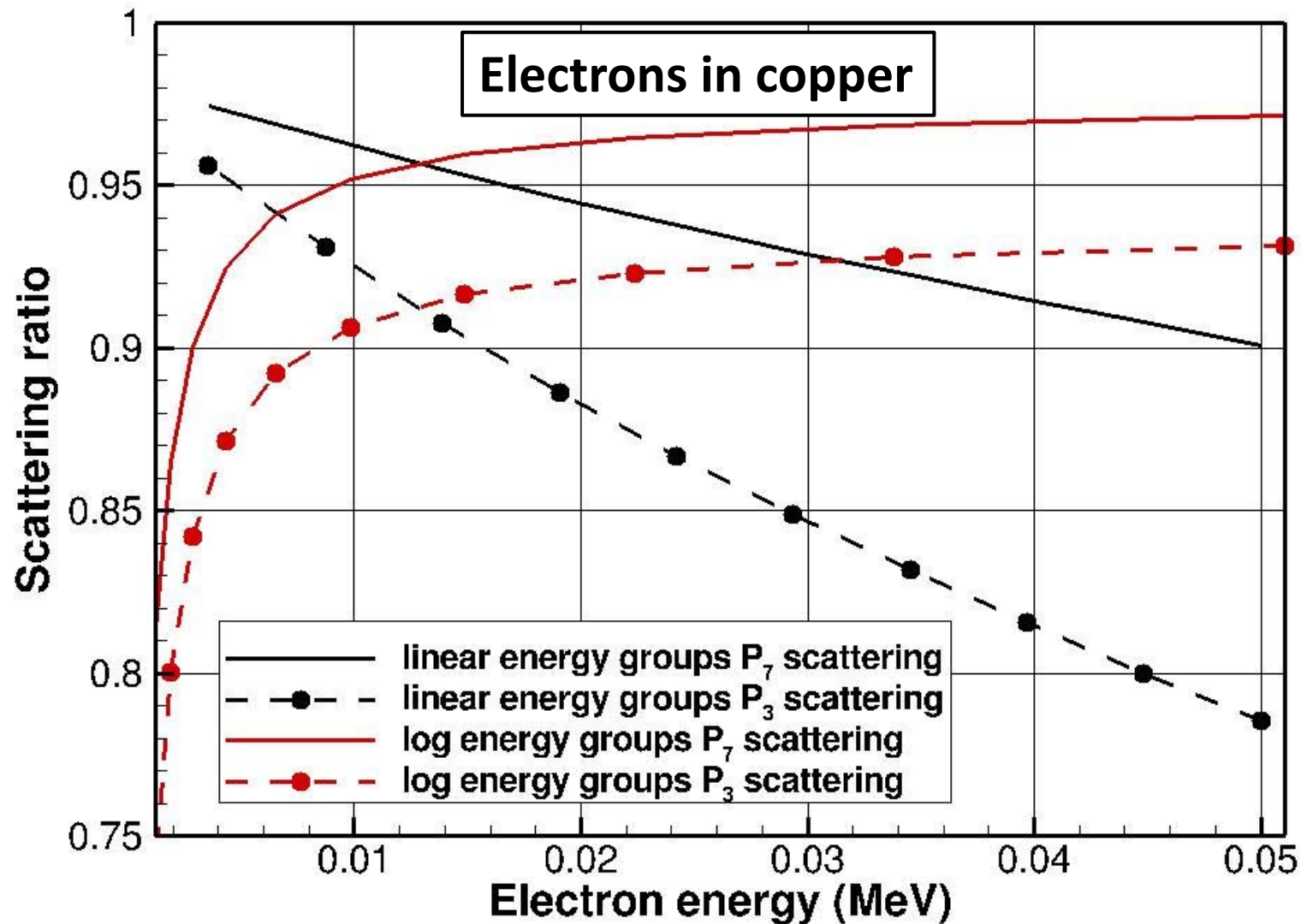
- GMRES (P_N or S_N)
 - 1st-order transport equation
 - DFE spatial differencing
 - Asymmetric
 - More expensive per iteration
 - More effective at accelerating SI
- CG (P_N or S_N)
 - Self-adjoint angular flux (SAAF) form of the transport equation
 - Least-squares (LS) approximation
 - Continuous-finite elements (CFE)
 - Symmetric Positive Definite (SPD)
 - Less expensive per iteration
 - Less effective at accelerating SI
- Off-the-shelf preconditioners from Trilinos applied to coarse-level solves
 - Incomplete-factorization (IF)
 - Multi-level (ML)
- Relative effectiveness of different TSA coarse-level solvers problem dependent
- Reasonable memory requirement for coarse-level solves

First test problem: photon/electron transport on twisted-pair braided shielded cable



Twisted-pair with shield removed

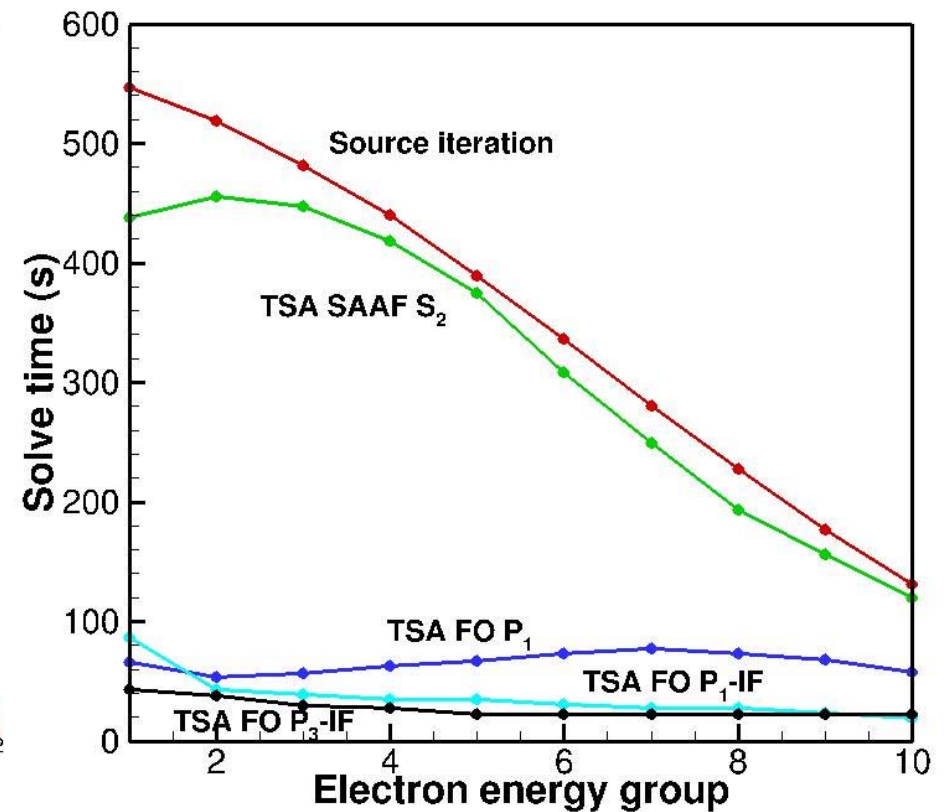
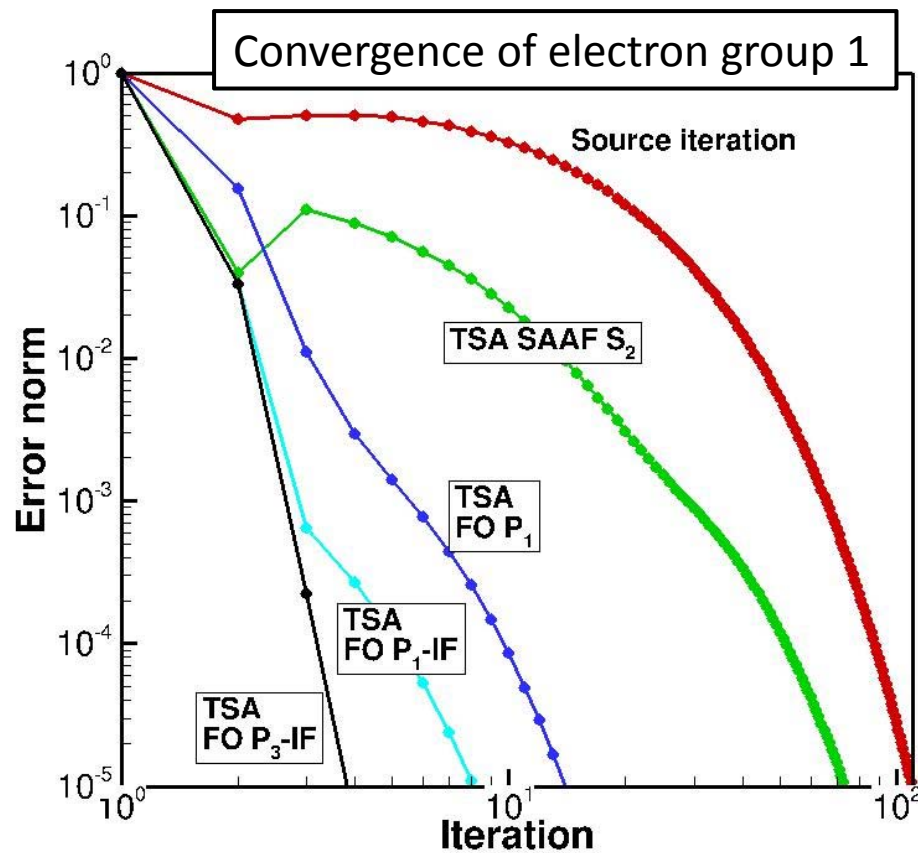
Scattering ratio depends on energy group structure and Legendre expansion order



Effectiveness of TSA methods in accelerating convergence and reducing solve time



- Source iteration with Trilinos-based TSA
- S_8 quadrature, P_3 scattering, 10 linear photon and 10 log electron energy groups
- Timing results with 256 Intel Sandy Bridge 2.6 GHz cores



Effectiveness of TSA depends upon which coarse-level solver is used



TSA method	Coarse-level parameters			Total solve time for electron groups (s)	Speed up
	Preconditioner	Convergence tolerance	Max iterations		
None	-	-	-	3530	1
FO P ₁	None	0.01	100	653	5.4
FO P ₁	Incomplete factorization	0.01	10	365	9.7
FO P ₃	Incomplete factorization	0.01	10	272	13.
SAAF S ₂	none	10 ⁻⁴	1000	3160	1.1

GMRES iteration applied to within-group iteration

- **Generalized Minimum Residual Method (Saad, 1986) to solve a linear system of equations based on the Krylov subspace**

Linear System $Ax = b$

Krylov Subspace $\mathcal{K}_m = \text{span}[r_0, Ar_0, A^2r_0, \dots, A^{m-1}r_0]$

Projection $x_m = x_0 + V_m y_m$

$$y_m = \min_y \|Ax - b\|_2$$

- **Applied to radiation transport by Patton (1996), Warsa (2004) and others**

Transport Equation $\mathcal{T}\psi = \mathcal{S}\psi + Q$

$$(I - \mathcal{T}^{-1}\mathcal{S})\psi = \mathcal{T}^{-1}Q$$

\mathcal{T}^{-1} is simply a transport sweep operation

Map to Linear System $Ax \rightarrow (I - \mathcal{T}^{-1}\mathcal{S})\psi$

$$b \rightarrow \mathcal{T}^{-1}Q$$

Av_j operations are replaced by $(I - \mathcal{T}^{-1}\mathcal{S})v_j$ without forming a matrix system.

- **Convergence depends on the distribution of eigenvalues of $I - \mathcal{T}^{-1}\mathcal{S}$ rather than the maximum eigenvalue, as in source iteration**

GMRES Algorithm with TSA

- **Preconditioned solver for linear system**

Linear System $Ax = b$

Left Preconditioning $M^{-1}Ax = M^{-1}b$

M^{-1} is chosen such that $M^{-1} \approx A^{-1}$

- **TSA-based preconditioner**

Transport Equation $(I - \mathcal{T}^{-1}\mathcal{S})\psi = \mathcal{T}^{-1}Q$

Inverse Operator $(I - \mathcal{T}^{-1}\mathcal{S})^{-1} = I + (\mathcal{T} - \mathcal{S})^{-1}\mathcal{S}$

TSA Preconditioner $\mathcal{M}^{-1} = I + \mathcal{P}(\mathcal{T}_c - \mathcal{S}_c)^{-1}\mathcal{R}\mathcal{S}$

\mathcal{T}_c and \mathcal{S}_c are coarse level transport and scattering operators

\mathcal{R} and \mathcal{P} are restriction and prolongation operators

- **Each GMRES iteration involves two steps**

a transport sweep operation $(I - \mathcal{T}^{-1}\mathcal{S})v_j$

a coarse transport solve $(\mathcal{T}_c - \mathcal{S}_c)u_c = v_c$

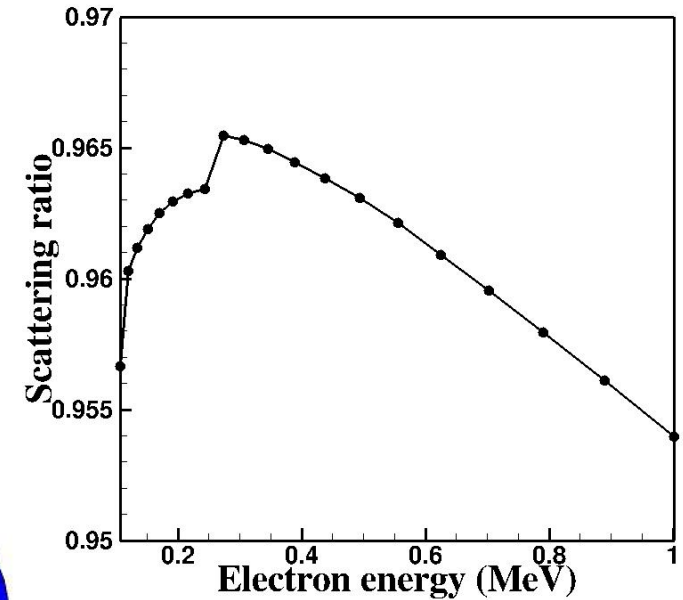
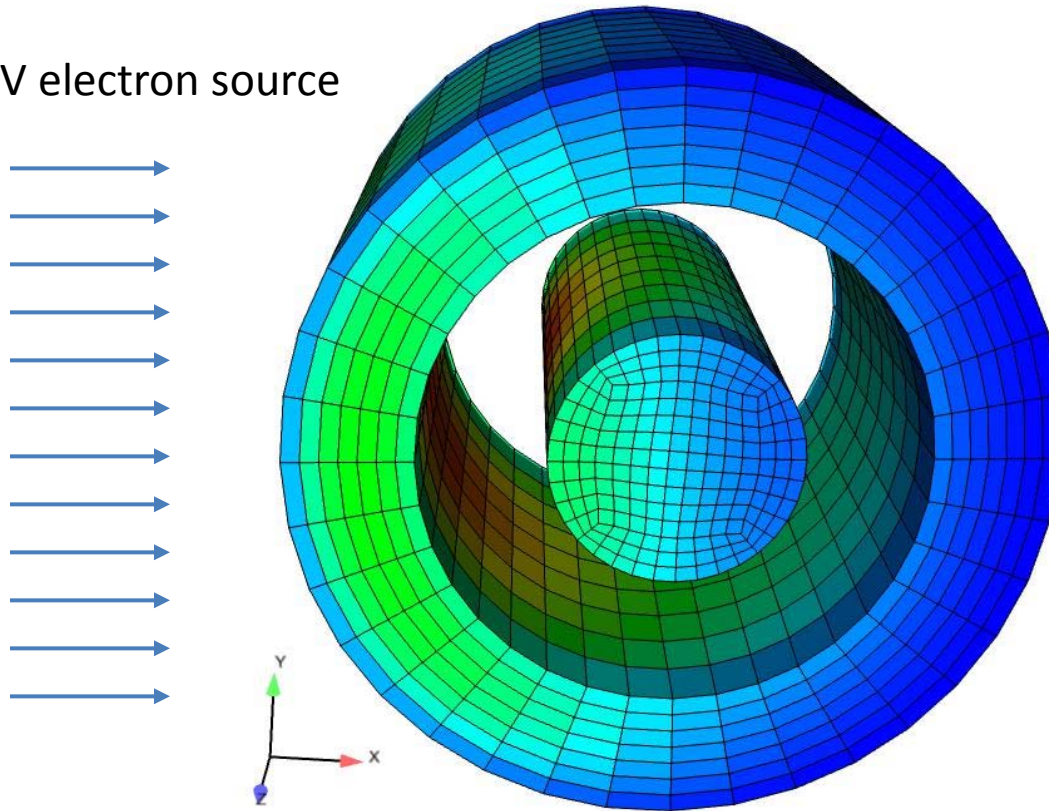
- **Coarse-level transport equation solved by GMRES iteration**

Test problem: three-region cylinder (Z=0.05 cm R=0.03 cm)



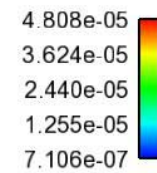
- Compare preconditioners for:
 - Material discontinuities
 - Scattering anisotropy

1-MeV electron source

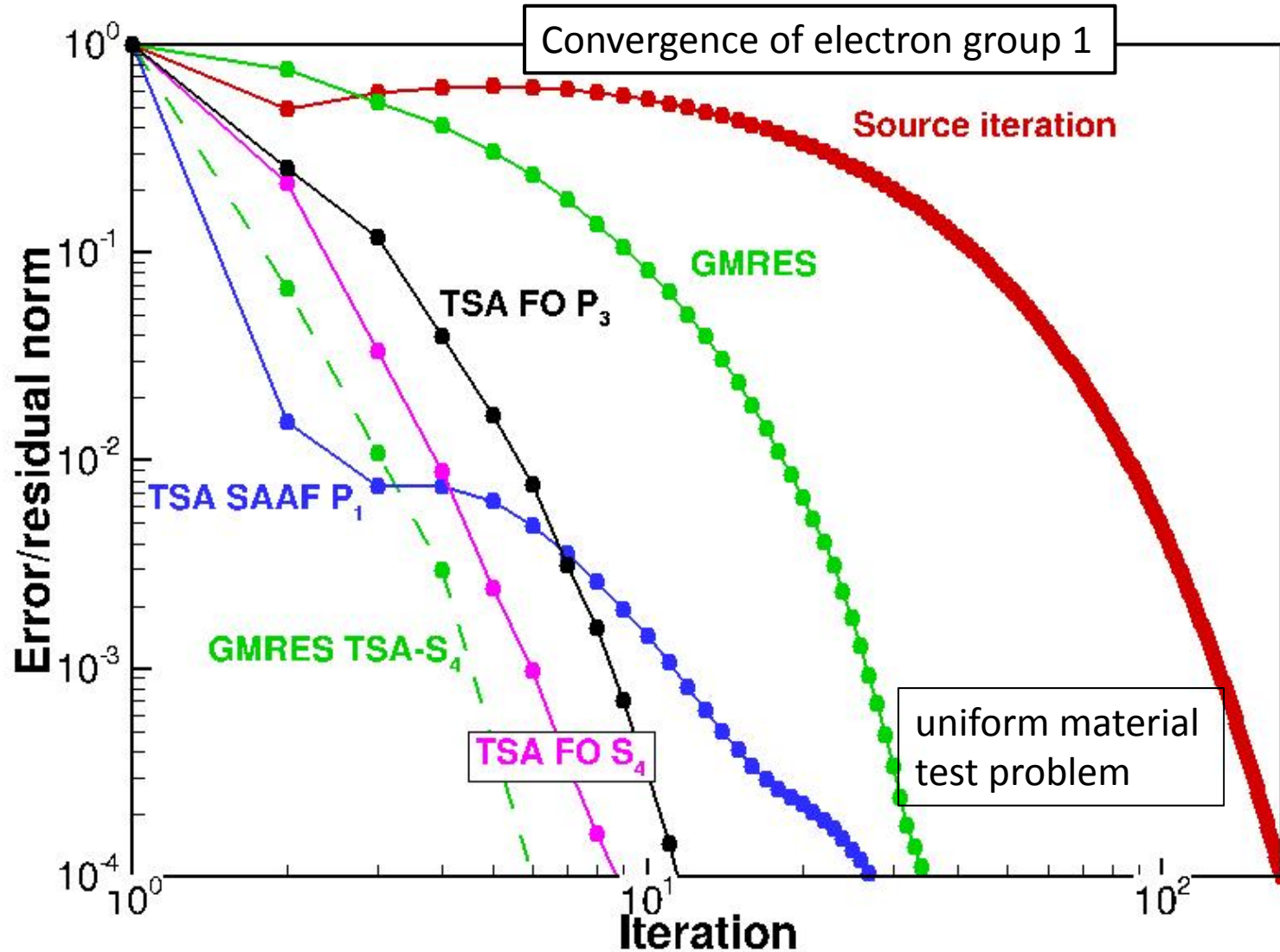


Scattering ratio:
electron transport in lead
20 log energy groups
 P_5 scattering

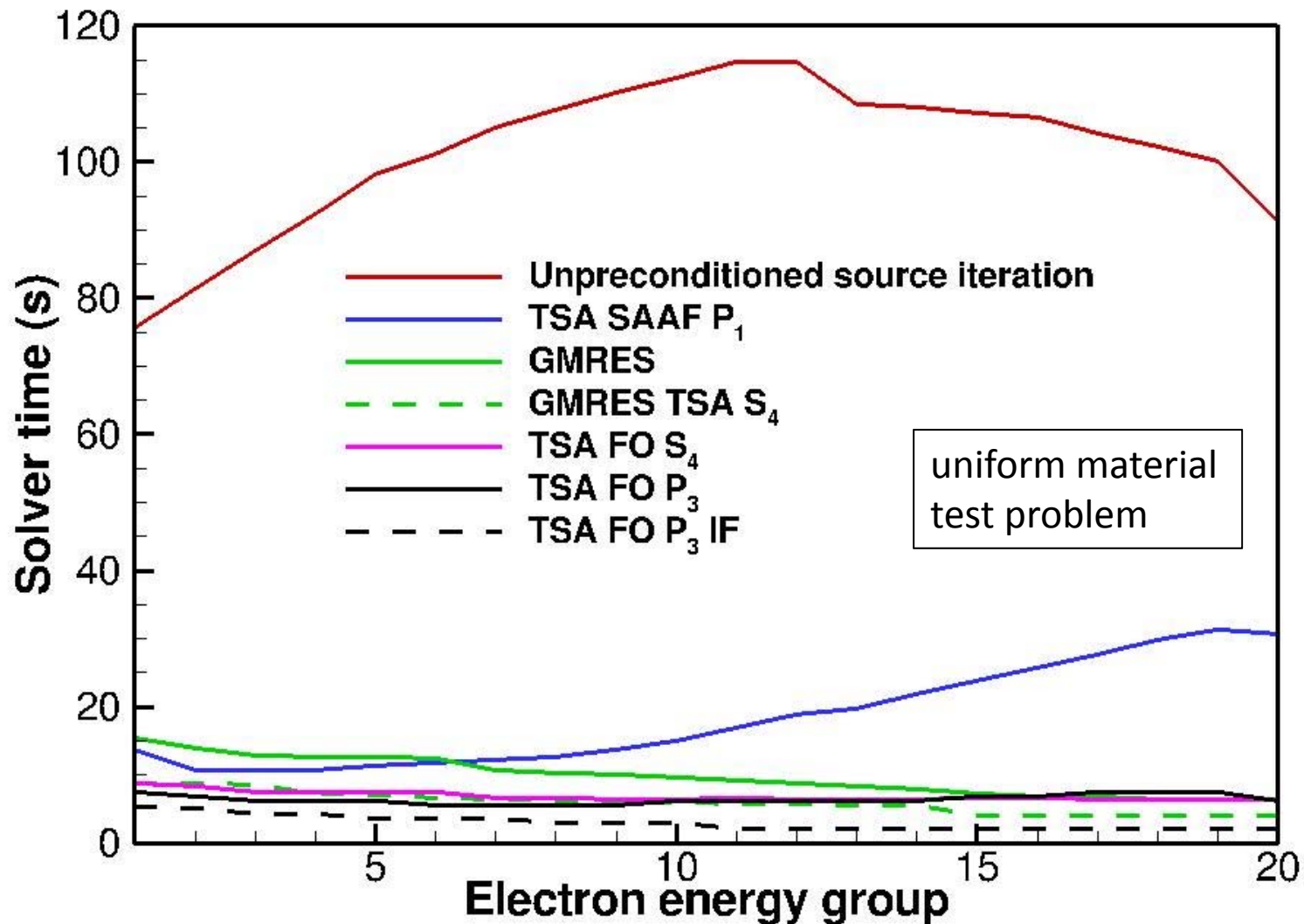
Scalar Flux



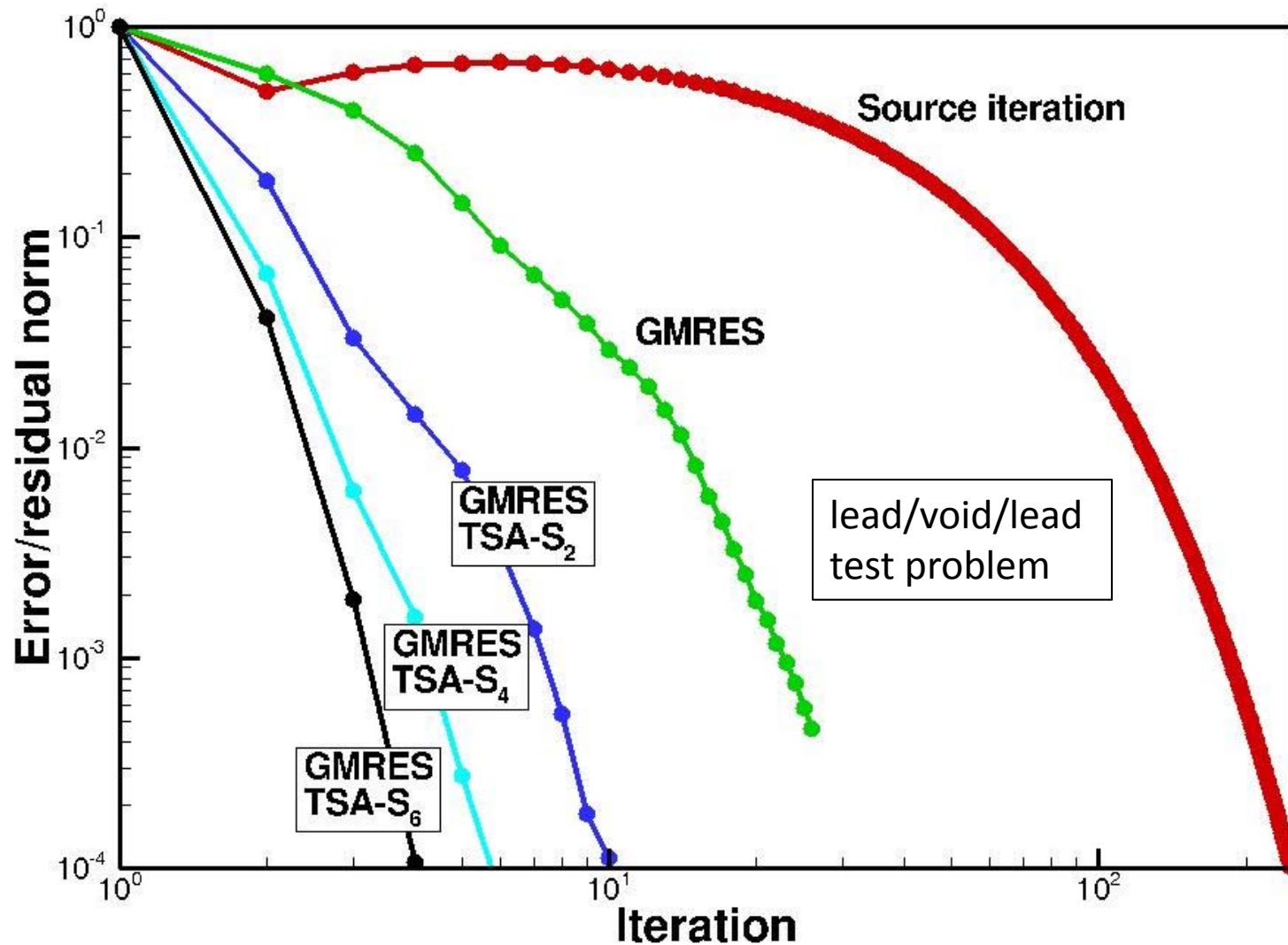
Comparison of convergence rates for various solvers and preconditioners



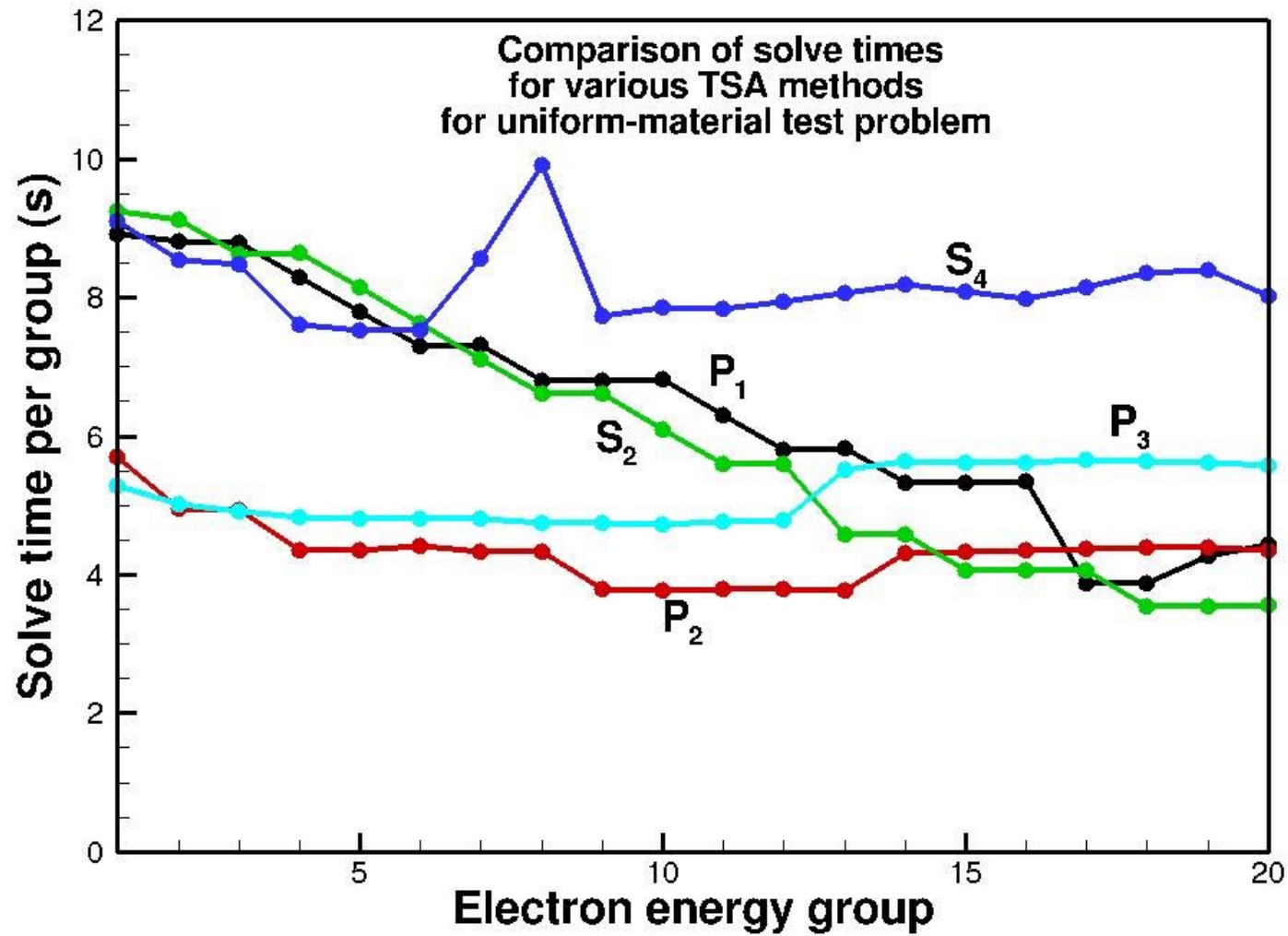
Timing results for various solvers and preconditioners



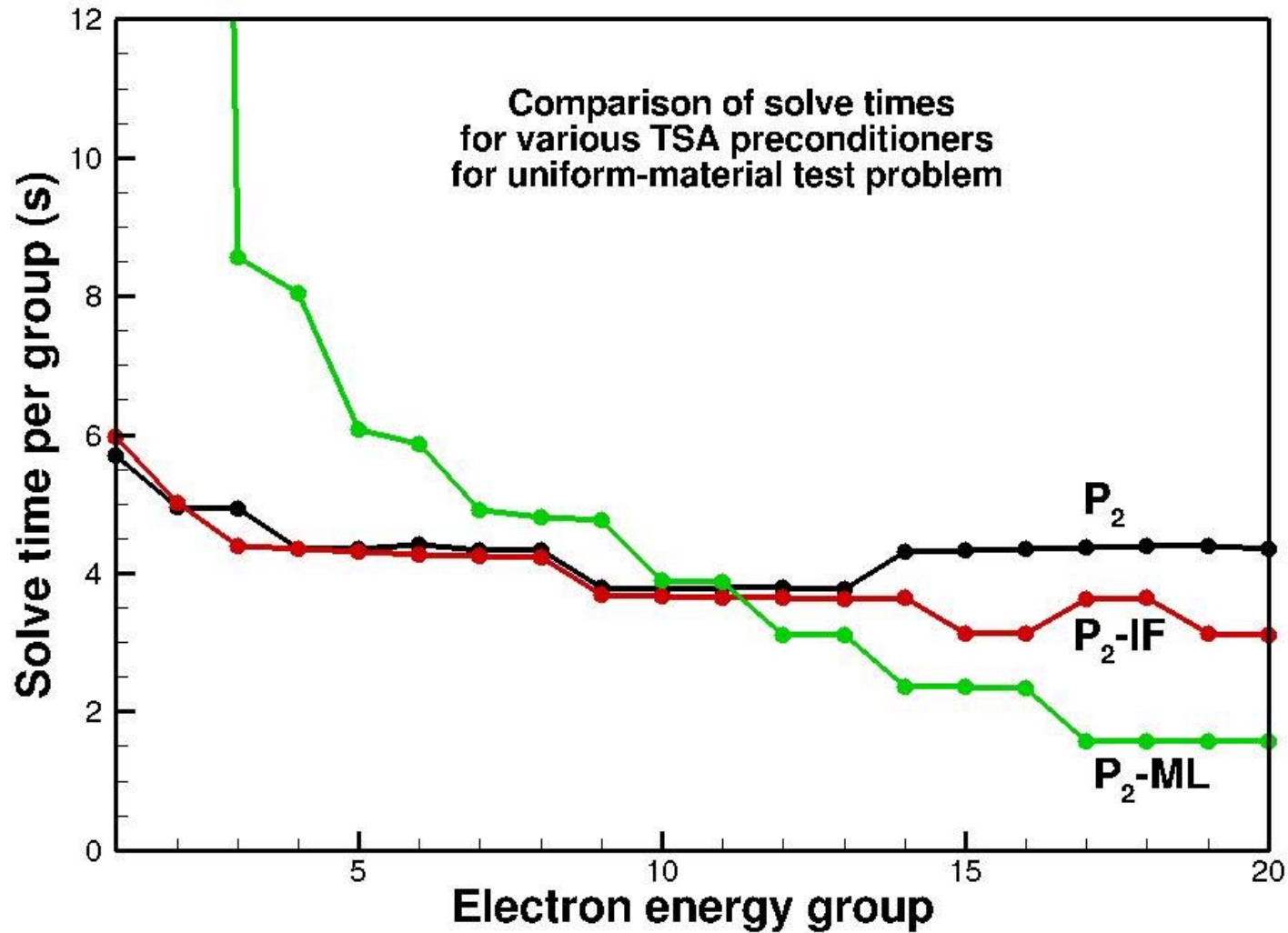
TSA preconditioning of GMRES solver accelerates convergence



Effectiveness comparison of various coarse-level solvers



Effectiveness of preconditioning applied to the coarse-level solver





Solver time comparisons: uniform vs. non-uniform

solver	TSA method	Solve time		Speed up	
		Uniform material	Non-uniform material	Uniform material	Non-uniform material
SI	none	2030	1940	1	1
GMRES	none	214	243	9.5	8.0
GMRES	GMRES-S ₂	212	241	9.6	8.0
SI	FO-P ₃	151	173	13.	11.
SI	FO-P ₃ IF	83	166	25.	12.
SI	FO-P ₃ ML	311	Not converged	6.5	-
SI	FO-S ₂ ML	192	Not converged	11.	-



Preconditioner effectiveness vs. scattering order

$$\sigma_t = 10^4 \quad \sigma_s = [10^4, 0.9 \times 10^4, 0.8 \times 10^4, 0.7 \times 10^4, \dots]$$

$$c = 1$$

- Three concentric cylinders
- Void region between two material regions
- S_{16} discrete ordinates
- Planar boundary source term

Acceleration method	Solver time (s)	
	P_3 scattering	P_7 scattering
none	-	-
GMRES	110	140
GMRES TSA S_4	88	102
FO TSA P_1	36	38



Summary and future work

- Two acceleration methods implemented and tested
 - TSA applied to source iteration (SI)
 - Krylov/GMRES alternative to SI
- Order of magnitude speedup demonstrated
- Preconditioning of the preconditioner
 - Off-the-shelf IF or ML applied to TSA
 - TSA applied to Krylov/GMRES
- Preconditioner effectiveness highly problem-dependent
 - Material discontinuities
 - Scattering anisotropy
 - Characteristics of the source term
 - Problem size
 - Characteristics of the coarse-level solver
 - Convergence metrics applied to the coarse-level solver
 - Tuning parameters applied to the IF and ML preconditioners