

Approved for unlimited release
Tracking Number: 611605

Roadmapping and the Future of Computing

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Vision

R&D programs and roadmaps

- What new idea will spawn the next Google/Facebook?
- My guess: An application in AI and robotics/mobility
- However, the software will be too compute-intensive for CMOS + von Neumann
- Answer: Driver is a killer app not identified yet that will drive R&D requirements in architecture and devices

Future technology

- Quantum computing
 - good idea if it works someday
- Neural networks
 - novel in displacing programmers not just computers
- CMOS, 3D, architecture, new applications
 - there is a lot of future here
- Reversible and other exotic
 - Next-next generation

Categorization by Limits

Name of approach	Performance limit or other capability	Investment to date
Neural networks (irrespective of implementation)	Learning and maybe intelligence ¹	Billions
Quantum computing (superconducting electronics)	Quantum speedup	Billions
Neuromorphic computing, i. e. implementations of neural networks	Thermodynamic (kT) ¹	Billions
Novel devices: Spintronics, Carbon Nanotubes, Josephson Junctions, new memories, etc.	Thermodynamic (kT) ²	Millions (each)
Analog computing	Thermodynamic (kT) ³	Millions
"3D+architecture," i. e. continuation of Moore's law	Thermodynamic (kT) ⁴	Trillion
Reversible computing	Arbitrarily low energy/op	Millions

¹ DeBenedictis, Erik P. "Rebooting Computers as Learning Machines." *Computer* 49.6 (2016): 84-87.

² DeBenedictis, Erik P. "The Boolean Logic Tax." *Computer* 49.4 (2016): 79-82.

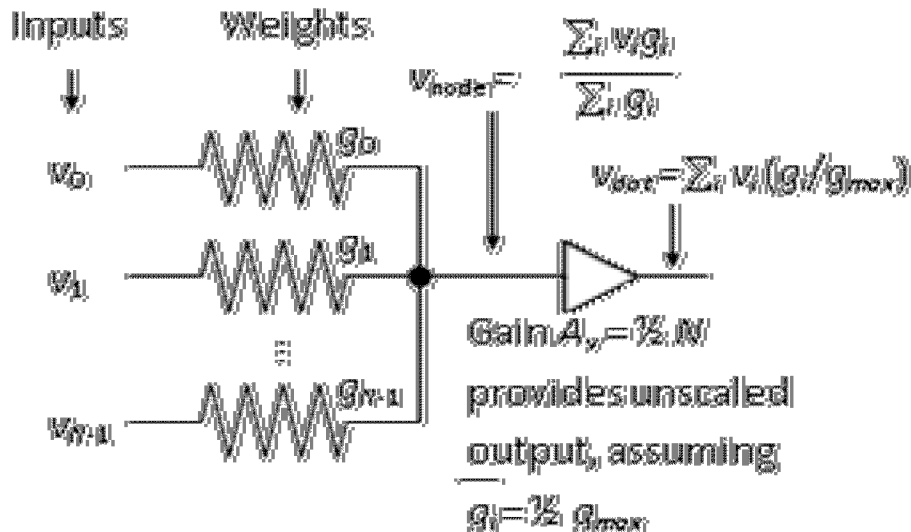
³ DeBenedictis, Erik P. "Computational Complexity and New Computing Approaches." *Computer* 49.12 (2016): 76-79.

⁴ DeBenedictis, Erik P. "It's Time to Redefine Moore's Law Again." *Computer* 50.2 (2017): 40-43 (still in print)

Comparing Architectures – as broadly defined

Example analog circuit

- Inputs v and $w = 1/a$



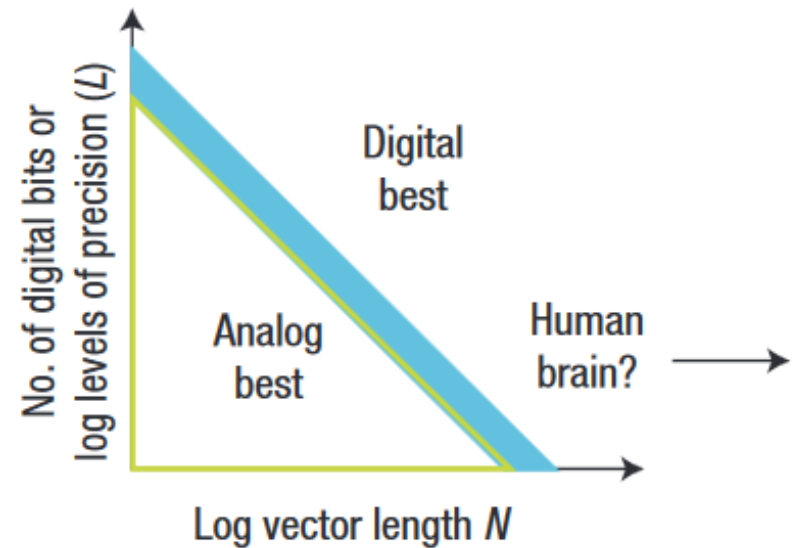
Circuit analysis (computational complexity)

$$E_{\text{digital}} = \sim 24 \ln(1/p_{\text{error}}) \log_2^2(L) N kT$$

$$E_{\text{analog}}^{(B)} = \sim 1/24 \ln(1/p_{\text{error}}) L^2 N^2 kT$$

Which is better?

- We can rigorously say “it depends”



Application Functionality Roadmap

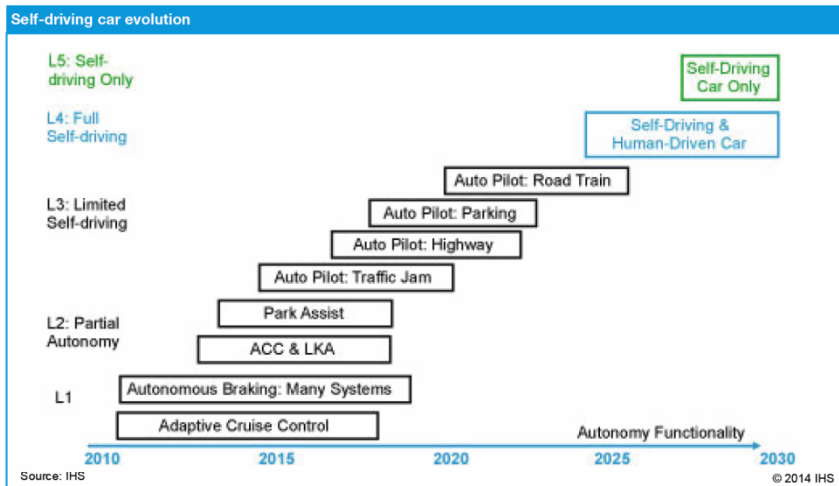
SAE now US DOT Levels of Automation

0. None, 1. Driver Assist, 2. Partial, 3. Conditional, 4. High, 5. Full

(from ¹)

General application areas and Moonshots (from ²)

- Big Data Analytics
- AI, such as robotics, human-computer interaction
- Manufacturing
- Biotechnology
- Supercomputers
- Spacecraft



¹<http://1.bp.blogspot.com/-68WQ4LKWiTg/VltzSFdmibI/AAAAAABEwI/jvUXiYz1dyY/s1600/levelsofautonomy.png>

²PCAST, Ensuring Long-Term U.S. Leadership in Semiconductors

Roadmapping in the Future

AI Milestone	Task Description	Technology / Architecture	<u>Power</u> Ops	Year
Driver assist	Identify cars in other land when driver activates turn signal	CPU	<u>50 W</u> 10^x	2000-2009
Full Self-drive	Drive car from sensors and visual cues	GPU	<u>50 W</u> 10^y	20yy (safely)
Fully autonomous mini-robot	Plan, move, and carry out missions	Neuro-morphic?	<u>50 mW</u> 10^z	20zz

Summary

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Thank You

See my Rebooting Computing Column in IEEE Computer

- April '16 Boolean Logic Tax
- June '16 Learning Machines
- August '16 Search for Secretariat
- October '16: Help Wanted Turing
- December '16 (see first page) →
- February '17 Redefine Moore's Law
- April '17 Architecture's Role

