



Investigation into Practical Implementations of a Zero Knowledge Protocol: Key Verification Assets Fund Program Review

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CONFIRMATION using a Fast-neutron Imaging Detector with Anti-image NULL- positive Time Encoding (CONFIDANTE)

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**P. Marleau, R. Krentz-Wee, "Investigation into Practical
Implementations of a Zero Knowledge Protocol", SAND2017-1649**

Outline



- Authentication and Certification. What's the problem?
- Attribute-based measurements
- Template-based measurements
- Zero Knowledge – what does it buy you?
 - Is this better than a template?
- Comparison Measurements – a new CONOPS?
- Two-dimensional time-encoded imaging
- CONfirmation using a Fast-neutron Imaging Detector with Anti-image NULL-positive Time Encoding (CONFIDANTE)
- Measurement campaign results – it works!



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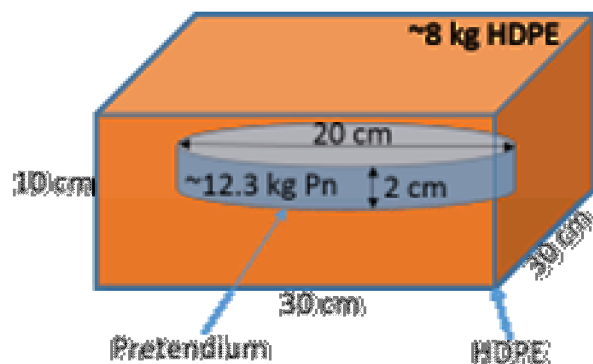
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What's the problem?



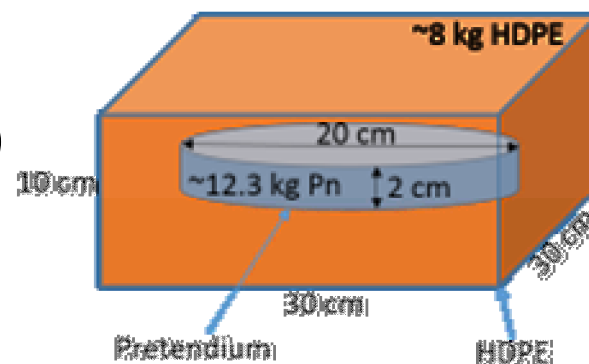
Authentication - the process by which a monitoring party gains confidence that reported characteristics of an entity reflect the true state of that entity

Certification – the process by which a host party gains confidence that sensitive information regarding an entity or facility remains secure.



Object T = valid type 1 TAI

= (?)



Object X = ?



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E. Brubaker, "Workshop on Techniques for Protection of Imaging Information: Challenge Problem", SAND2016-4047 O

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Can we measure it?

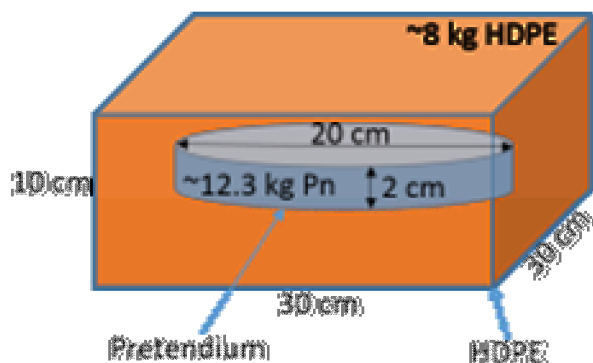


Authentication

- Measurement must be relevant
- Measurement must be specific

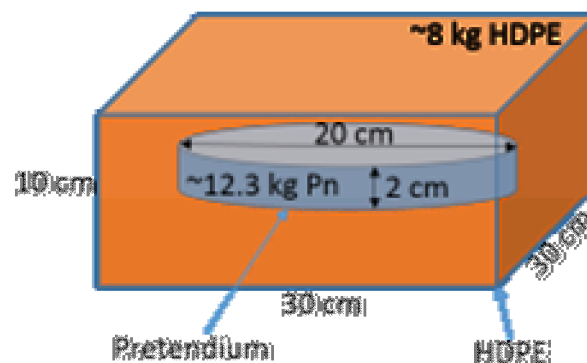
Certification

- Measurement must not do more than required.
- Most distinguishing characteristics imply design/sensitive information.



Object T = valid type 1 TAI

= (?)



Object X = ?



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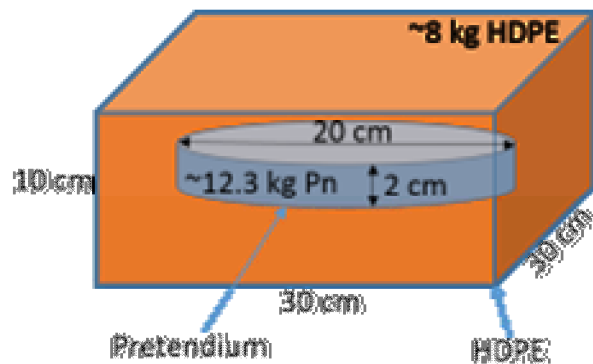
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Specificity through attributes?



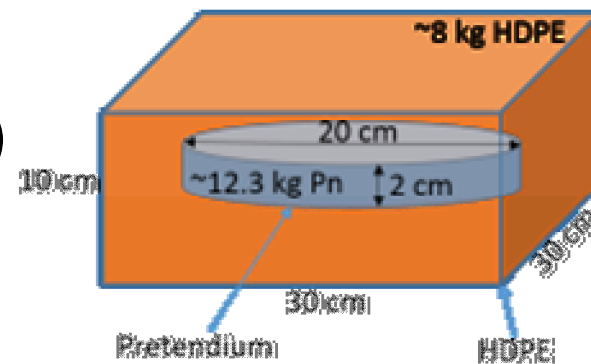
Authentication

- Relevant and specific attributes can be defined.
- Attributes can be derived from measurements.



Object T = valid type 1 TAI

= (?)



Object X = ?



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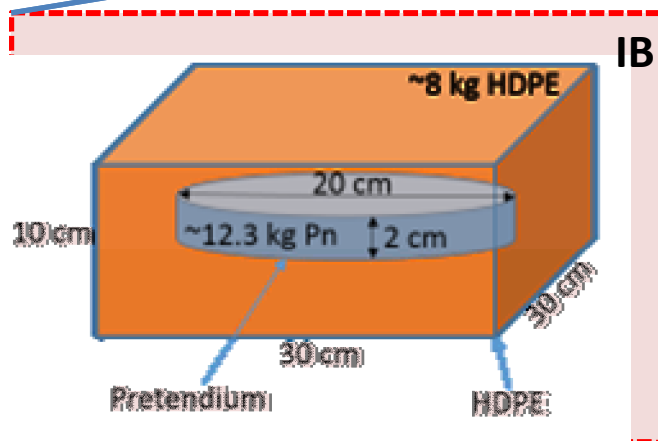
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Attributes – necessitate an IB



Radius = r ; Thickness = t ;
Volume = $t * \pi * r^2$
Flux = $f \rightarrow \text{mass} > M$



Object T = valid type 1 TAI

- We could declare that Object T has an attribute (i.e. $\text{mass} > M$)
- This defines what it means to be a TAI without carrying around sensitive information.
- But the measurement and calculation will probably reside behind an information barrier (IB) ...

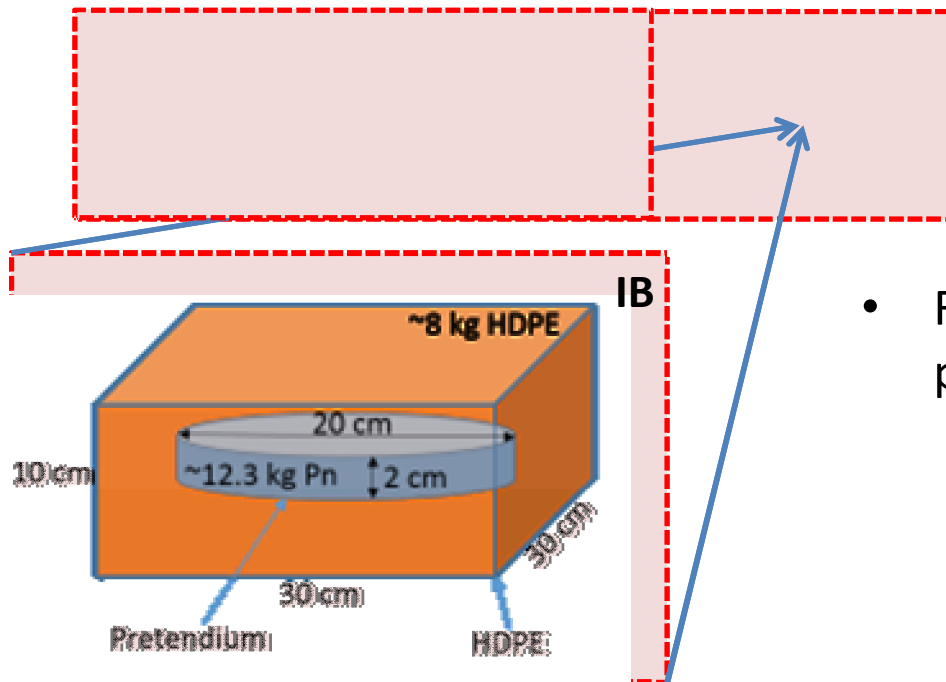


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Attributes – necessitate an IB



Object T = valid type 1 TAI

- Radiation imaging accesses many possible attributes:
 - Shape
 - Size
 - Composition
 - Mass
 - Intervening material
 - Etc. Etc.
- But calculations can be quite intensive.



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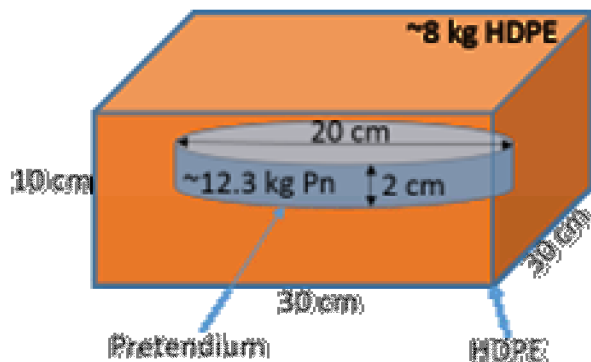
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Specificity through templates?



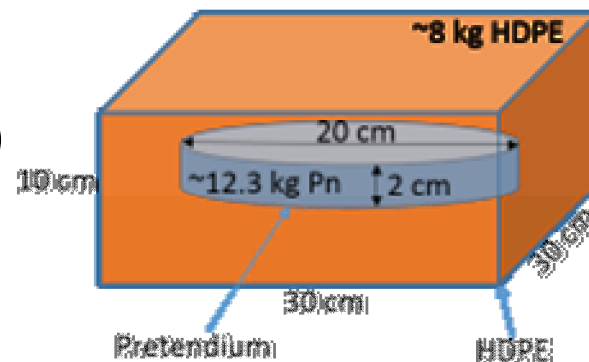
Authentication

- Relevant and specific attributes can be defined by what is measured by a system ***without complicated analysis!***



Object T = valid type 1 TAI

= (?)



Object X = ?



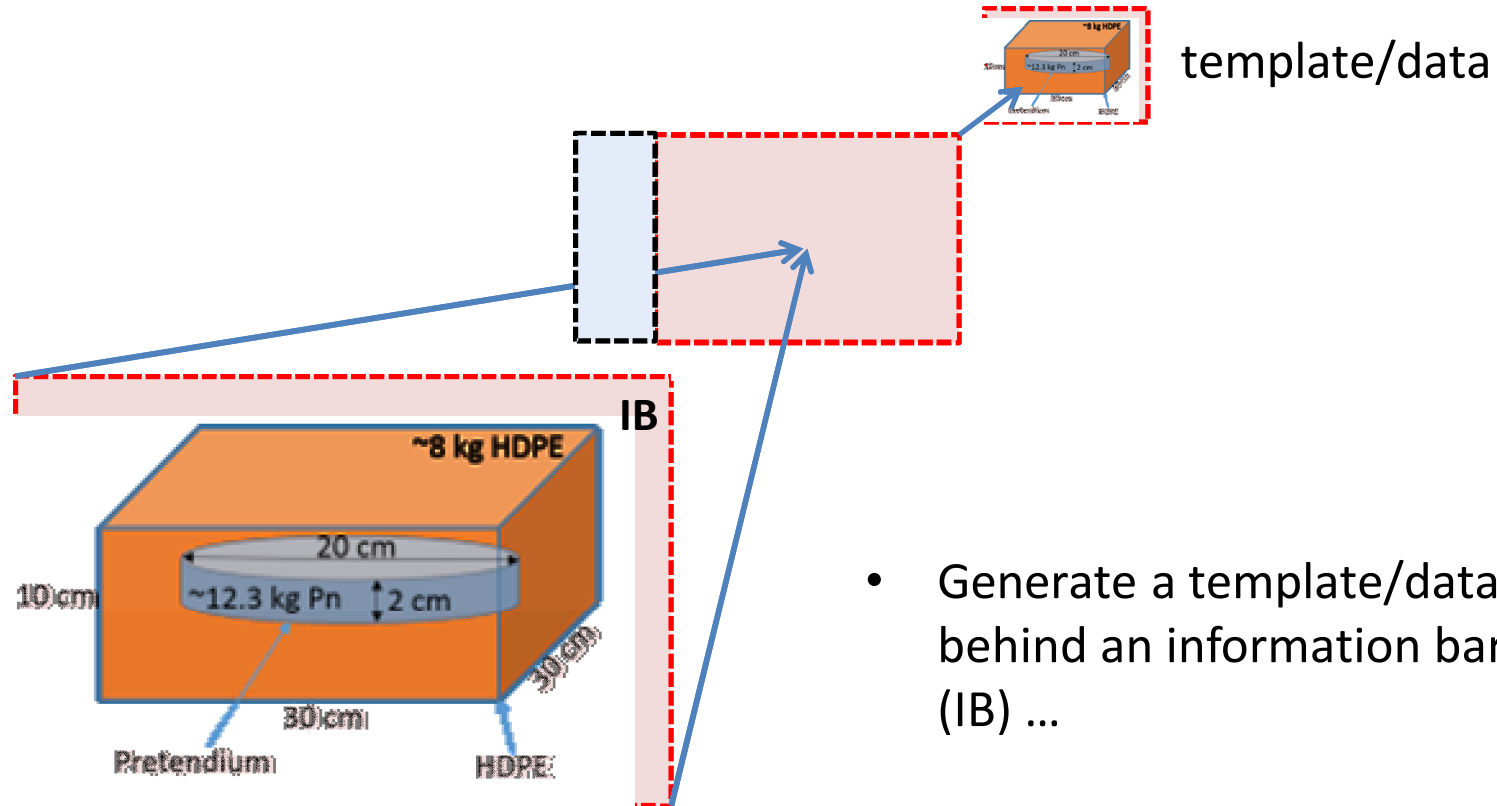
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Traditional Templates - generation



- Generate a template/data behind an information barrier (IB) ...

Object T = valid type 1 TAI



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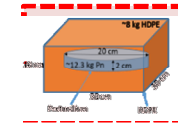
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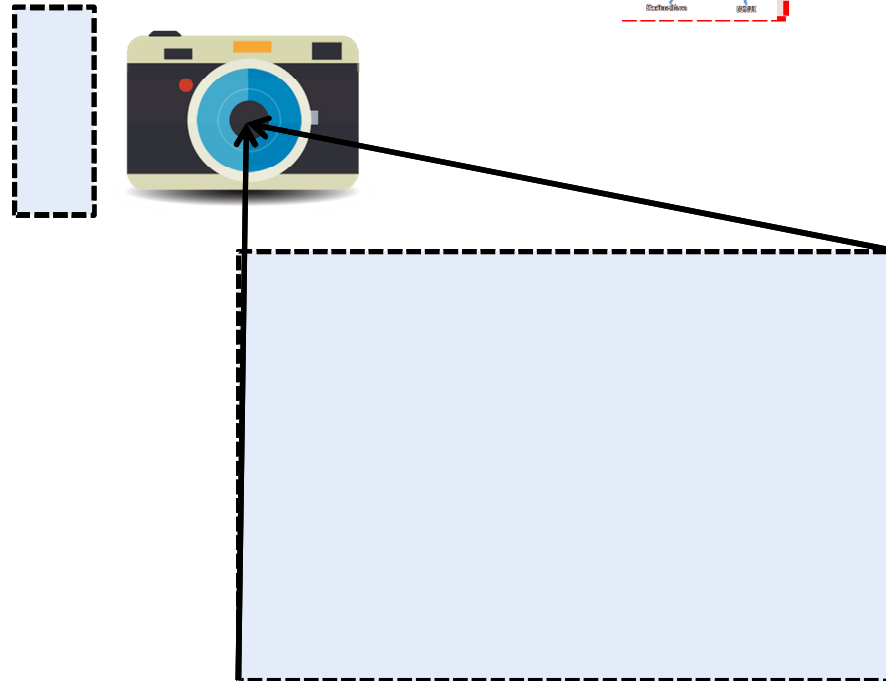
Traditional Templates - authentication

- Sequester template/data which may be sensitive
- Authenticate equipment ...

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template/data



Object Z = ?



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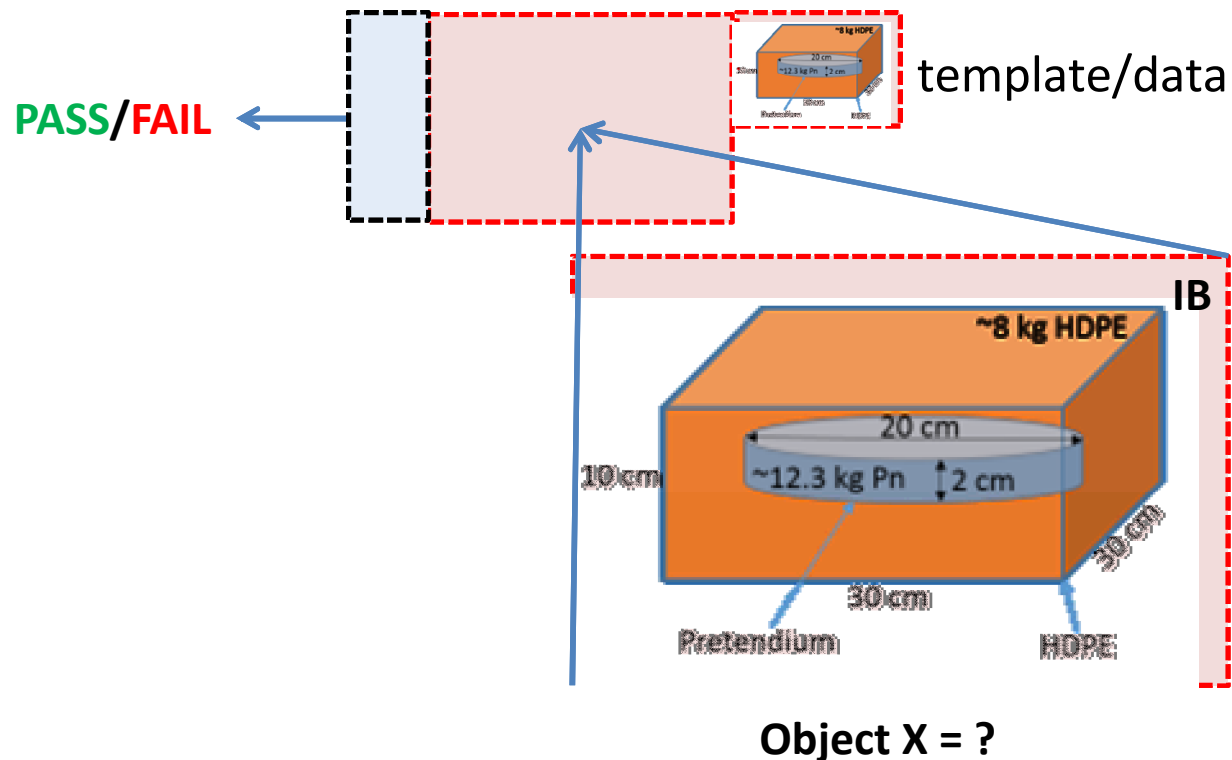
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Traditional Templates - comparison

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- Measure object declared to be of like type.
- Analysis is simple; does the data match within expected uncertainties?



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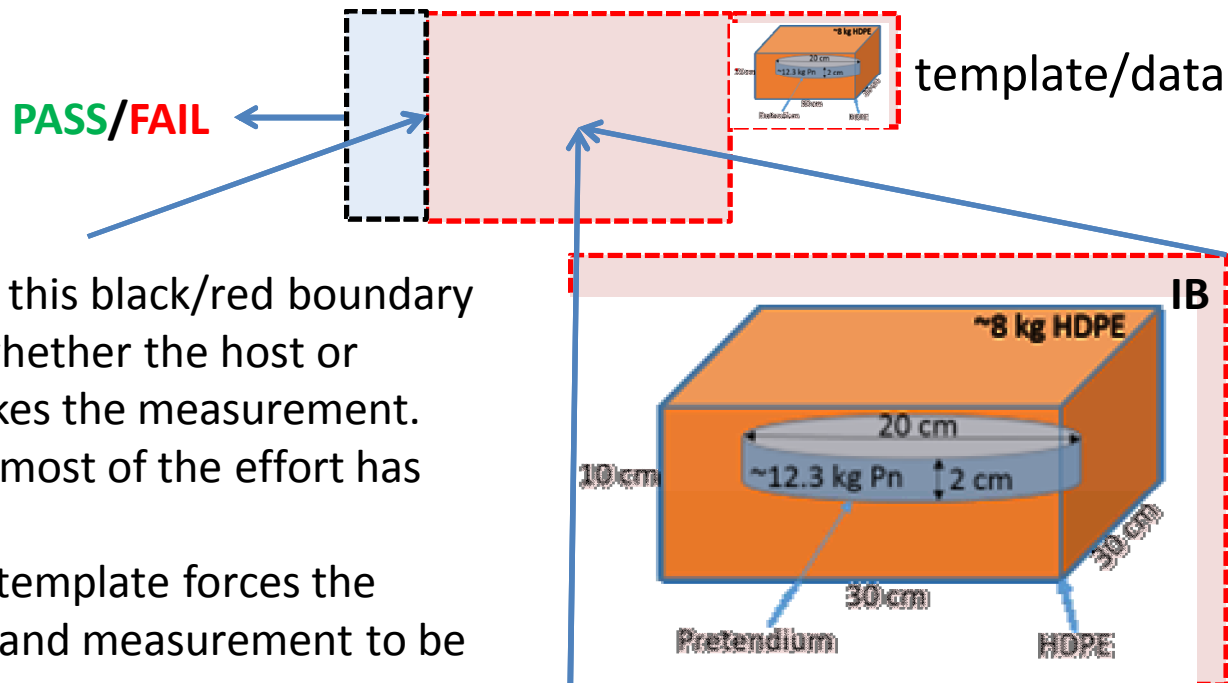
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Templates – who measures?



- Who makes the measurement? Is the measurement itself authenticatable?



- The nature of this black/red boundary determines whether the host or inspector makes the measurement.
- This is where most of the effort has gone.
- At worst, the template forces the entire device and measurement to be behind an IB.

Object X = ?



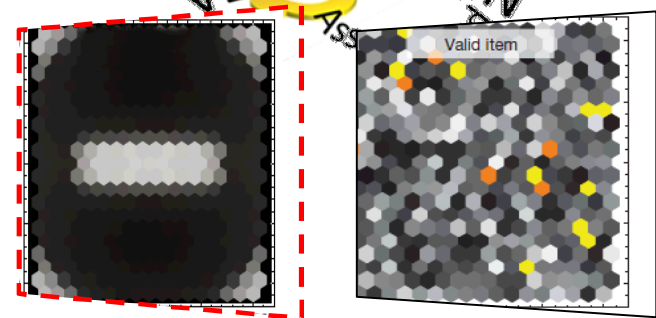
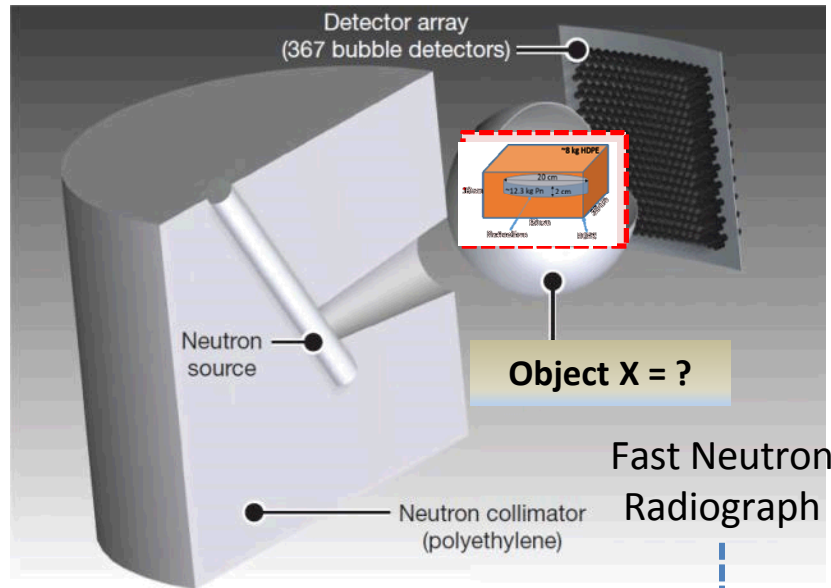
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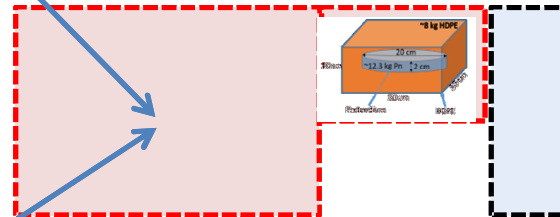
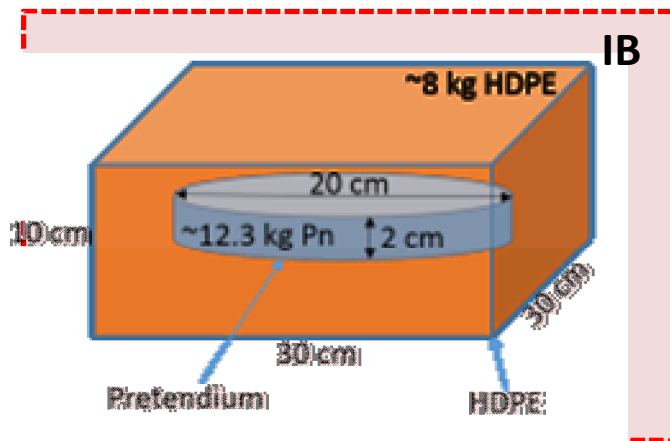
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ZKP – Glaser, Barak, and Golston



Analog bubble detectors with preloaded complement "template"

Flat featured image (NULL) indicates a true positive.



PASS/FAIL

Has this boundary moved?



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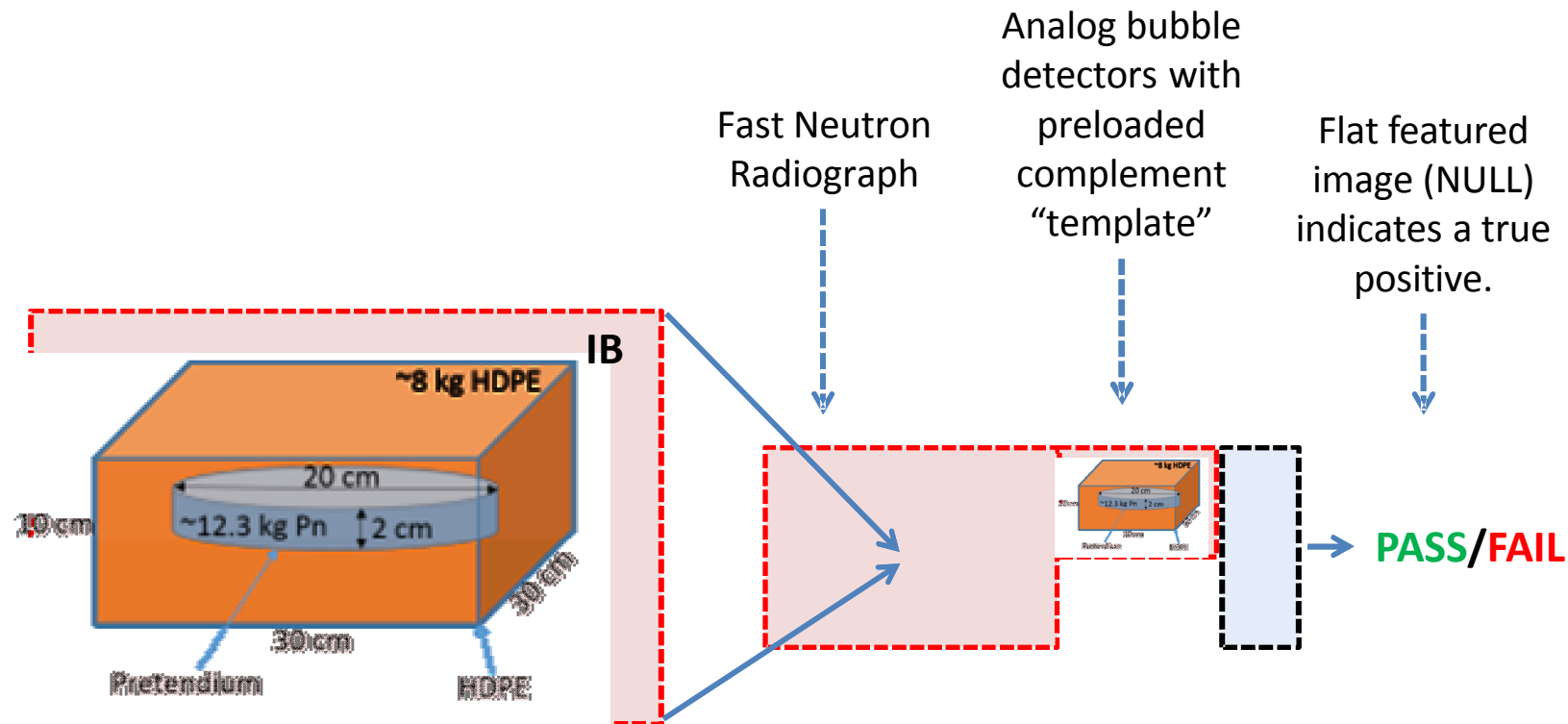
Images borrowed from: Glaser, Barak, and Goldston, "A zero-knowledge protocol for nuclear warhead verification", doi:10.1038/nature.134557

ZKP – authentication measures



• Research Questions

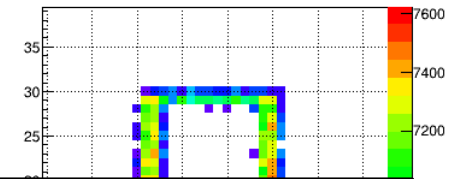
- Is there anything that we can do to make this more authenticatable?
- Can we share the rates in a subset (up to all) of the detector pixel counts with spatial information removed before/during/after the measurement?
- **What sensitive information is at risk?**



Rectangular Source Counts

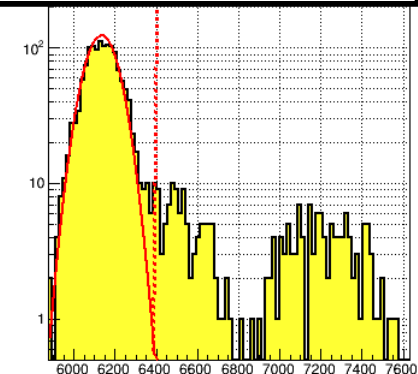
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Observation plane



See Final Report: "Investigation of Practical Implementations of a Zero Knowledge Protocol", SAND2017-1649

- 8.57e6 counts represented in Gaussian.
- 1.43e6 counts in source.
- There are 230 pixels to the right of the threshold. Therefore these excess source counts are distributed across an object of this **total angular size**.
- What else can we learn? What can the shape of the distribution tell us? Have we gone far enough?



→ *Classified Study*



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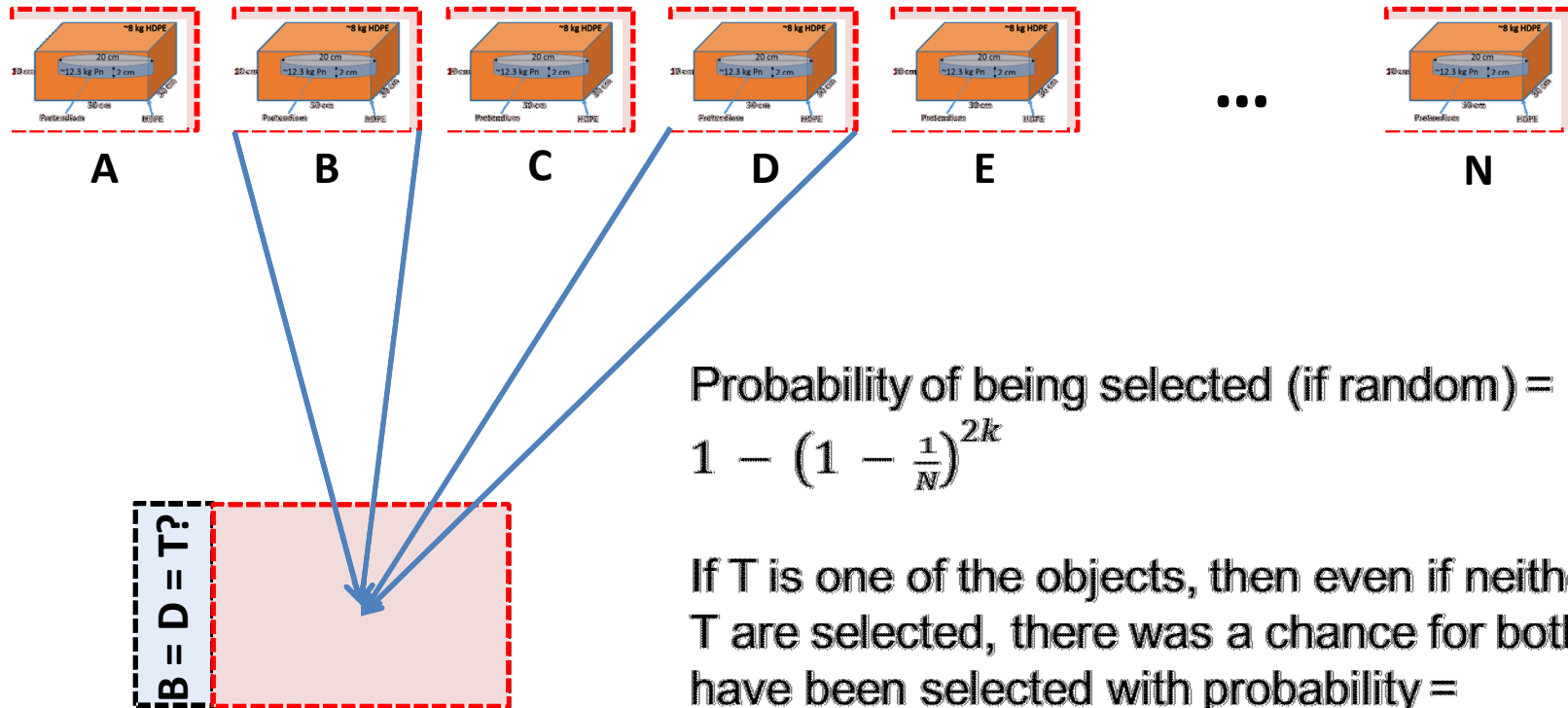
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ZKP – CONOPS and Inspector choice



- The ZKP CONOPS offers an interesting way to gain authentication confidence.
- Presented with N objects and k comparison measurements will be made.



Probability of being selected (if random) =
 $1 - \left(1 - \frac{1}{N}\right)^{2k}$

If T is one of the objects, then even if neither X nor T are selected, there was a chance for both to have been selected with probability =

$$\left(1 - \left(1 - \frac{1}{N}\right)^{2k}\right)^2$$

providing some degree of confidence



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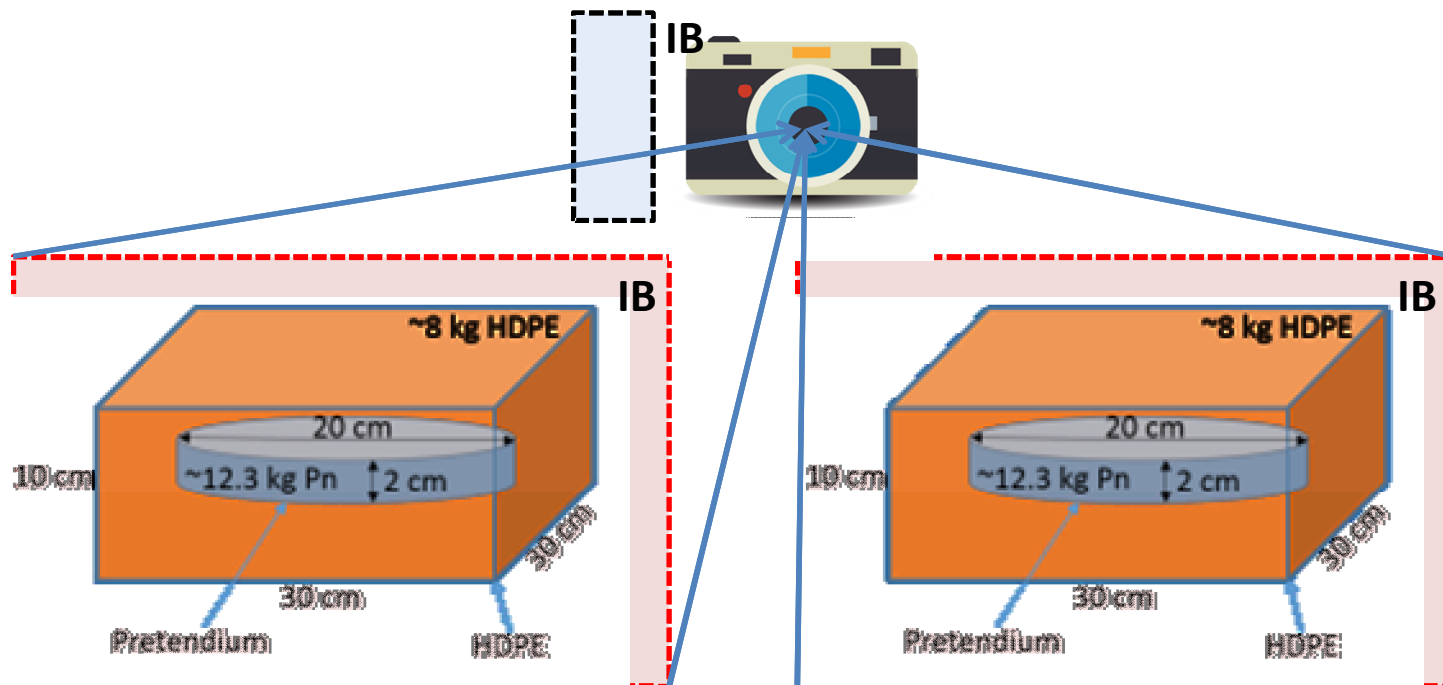
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Zero Knowledge comparison measurement?

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- Is there a physical implementation of the confirmation measurement that the inspector can watch and authenticate?
- **It would be great if we could get a physical NULL as an indication of positive confirmation at all times, *not just at the end.***



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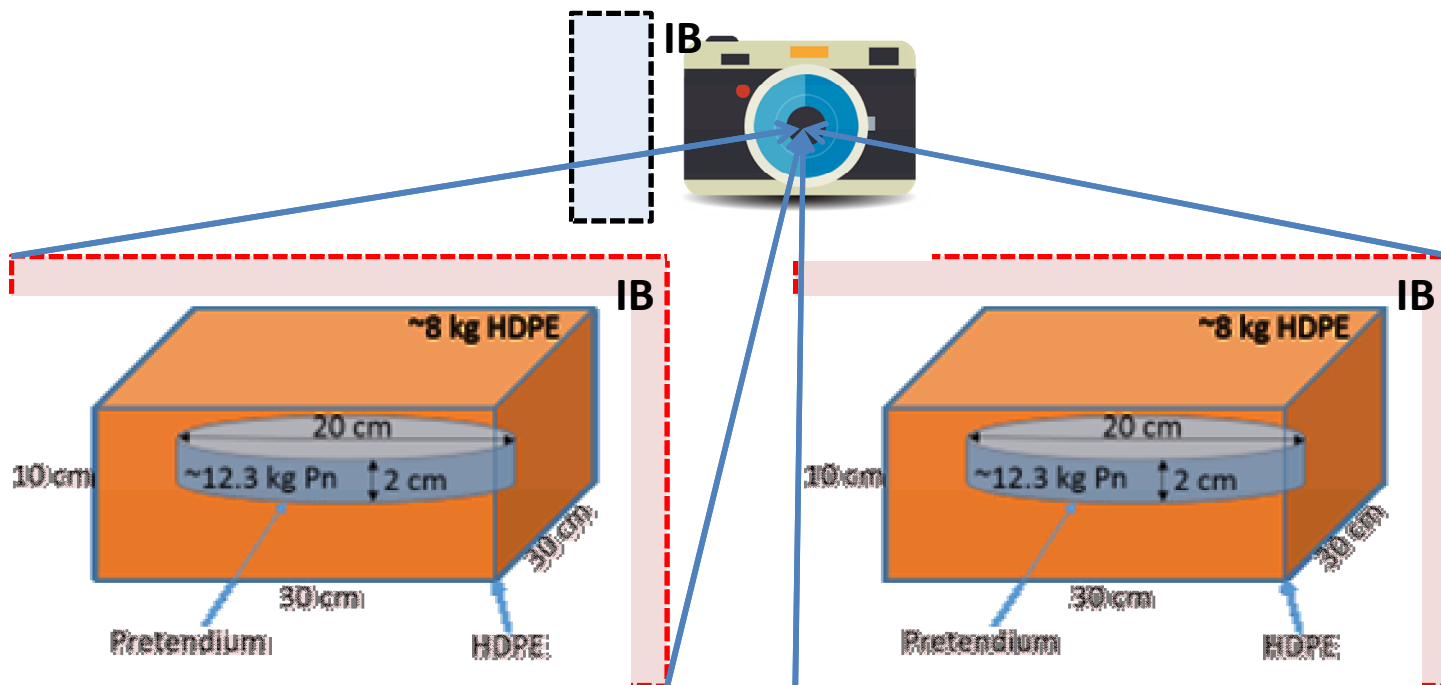
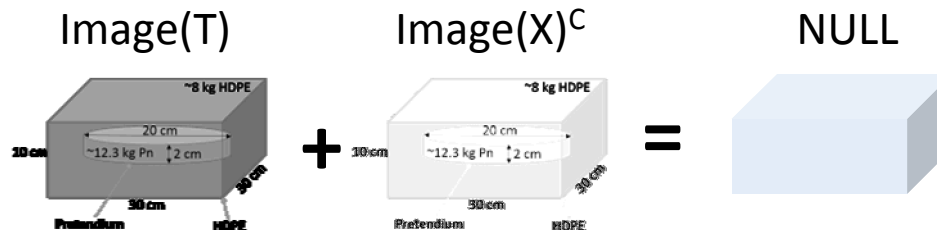
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Proposal – complementary comparison

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- What we need is to turn one image into its complement *at all times.*



Object T = valid type 1 TAI

Object X = ?



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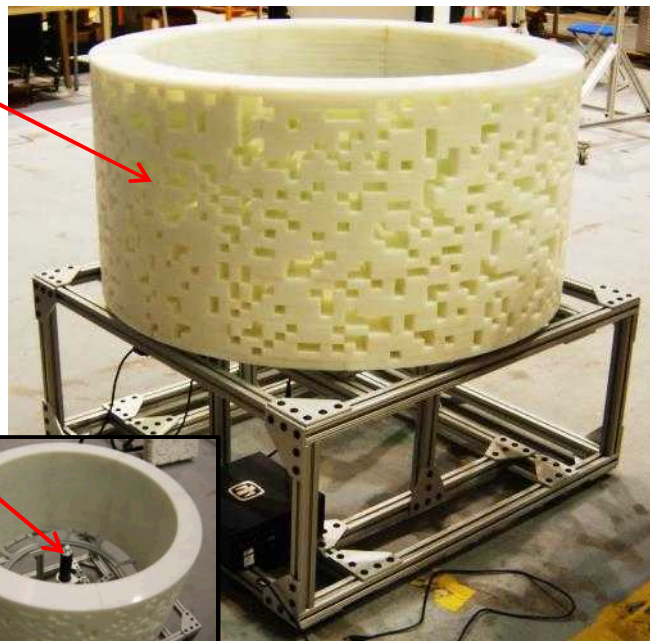
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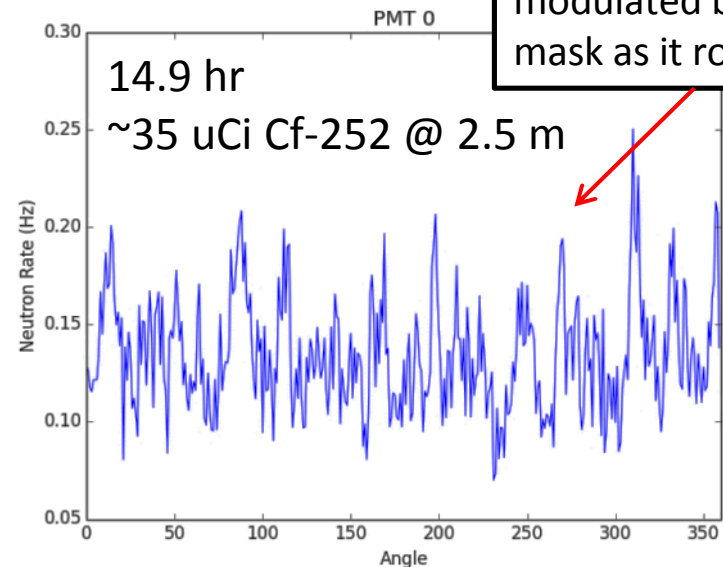
2D Time-encoded Imaging (TEI)

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Asset

2-d
coded
mask

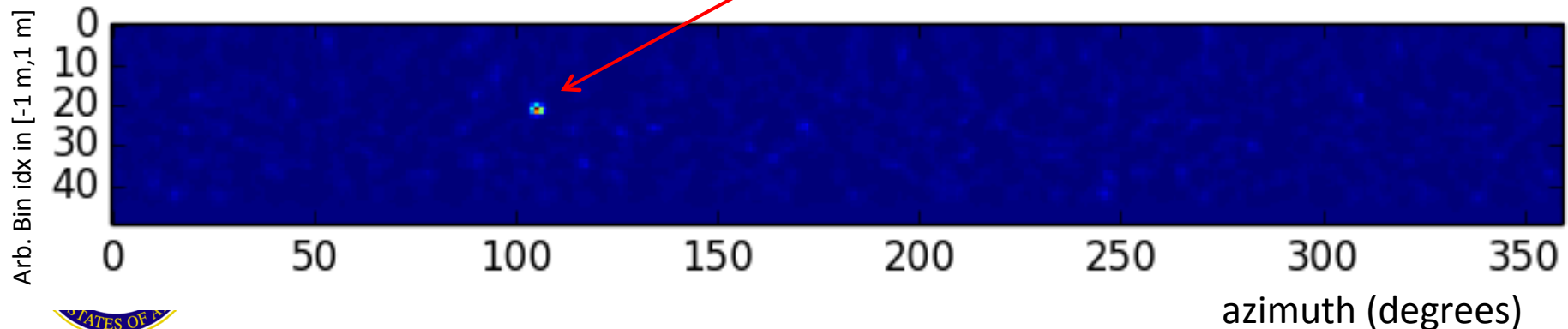


Single 1" D
x 1" LS
pixel



Single pixel rate is
modulated by the
mask as it rotates.

Modulation pattern is unfolded to 2-D image



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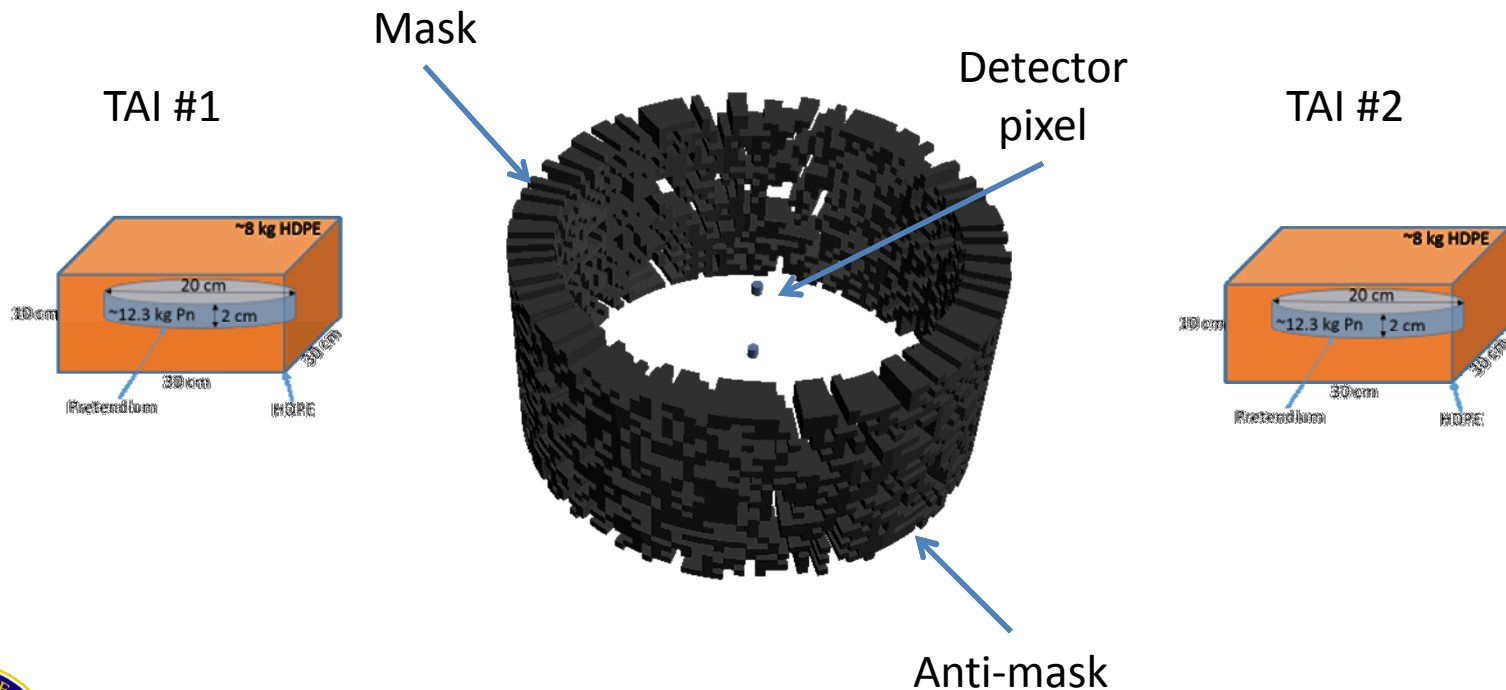
J. Brennan, E. Brubaker, M. Gerling, P. Marleau, K. McMillan, A. Nowack, N. LeGalloudec, M. Sweany,

"Demonstration of Two-dimensional Time-encoded Imaging of Fast Neutrons", Nuclear Instruments and Methods A, 2015

Here's where the magic happens ...

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Assets Fund

If the mask is designed such that one side is the anti-mask of the other, then **TAI #2 projects the anti-image of TAI #1 at all times**
if and only if they are identical!



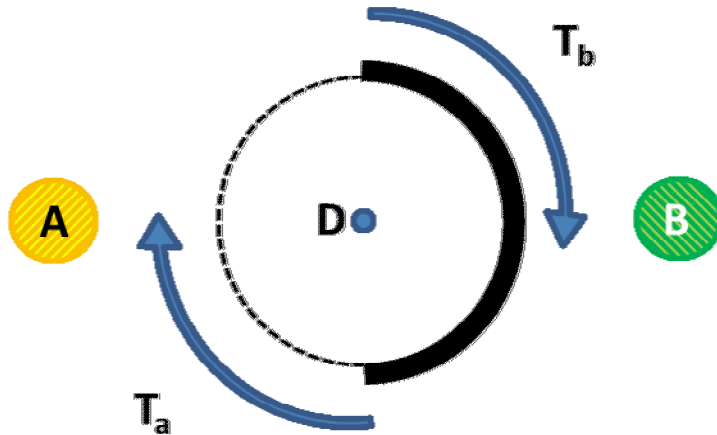
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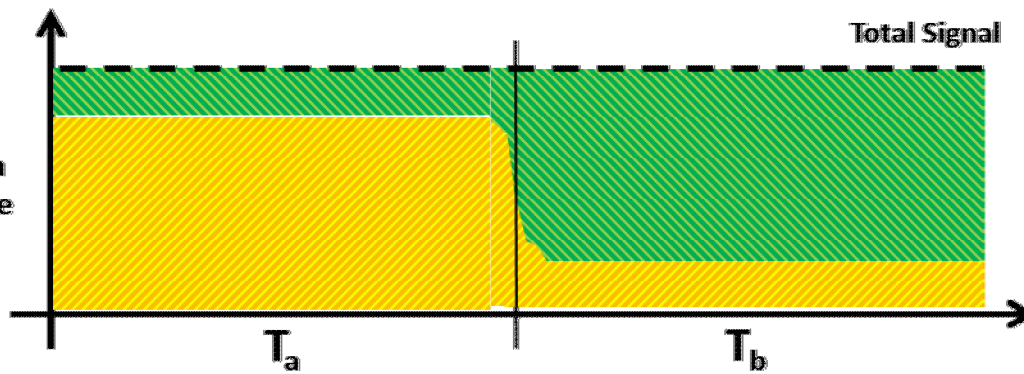
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A very simple example



- For example, take a very simple mask: half mask, half aperture.
- The fraction of total count rate coming from A and B is unknown at any given angle.
- In this example, the location (and shape) of the boundary between regions is not revealed.



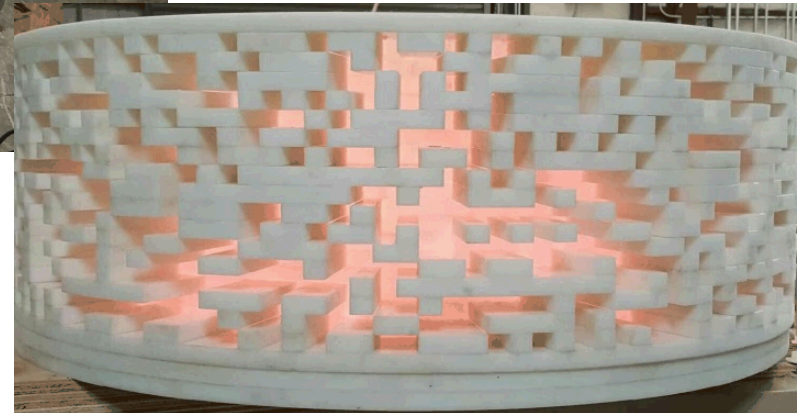
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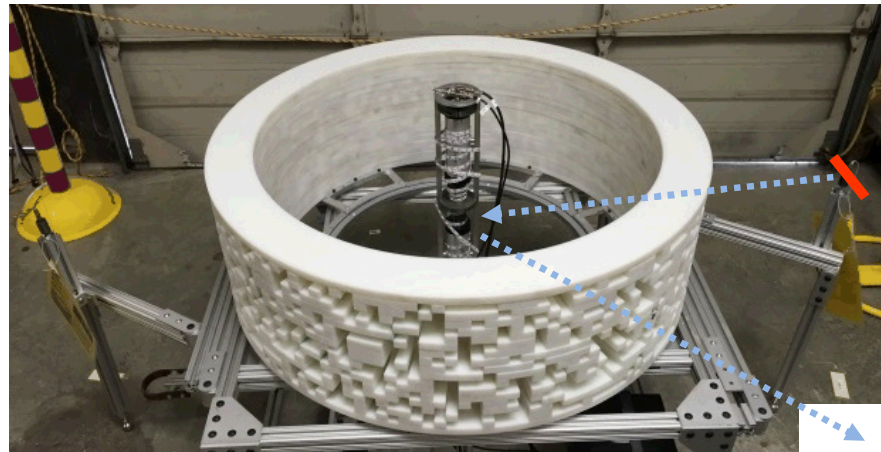


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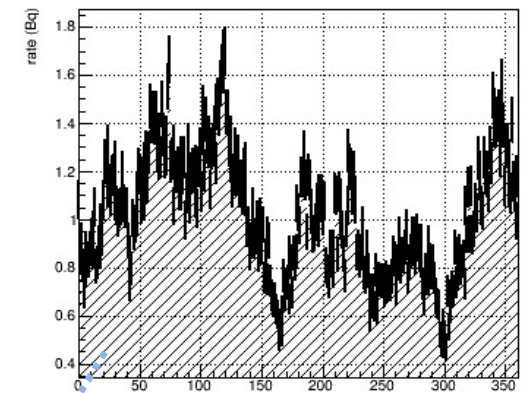
Results – Double point source measurements

Measurement of a double “line” source

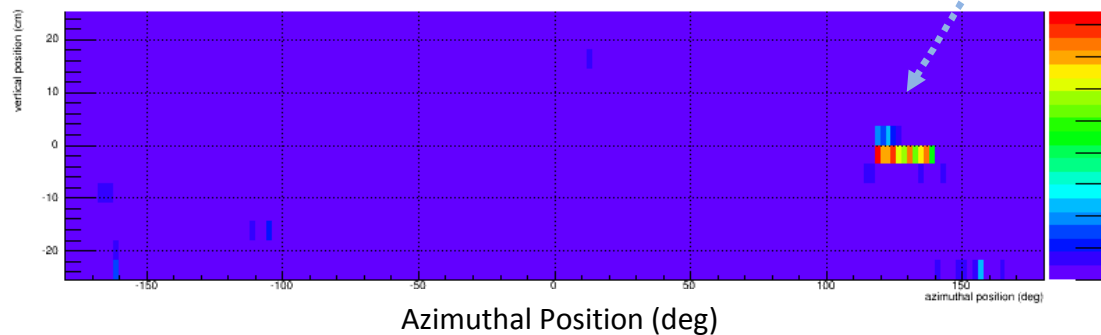


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Assets Fund

Neutron Rate



MLEM Reconstruction



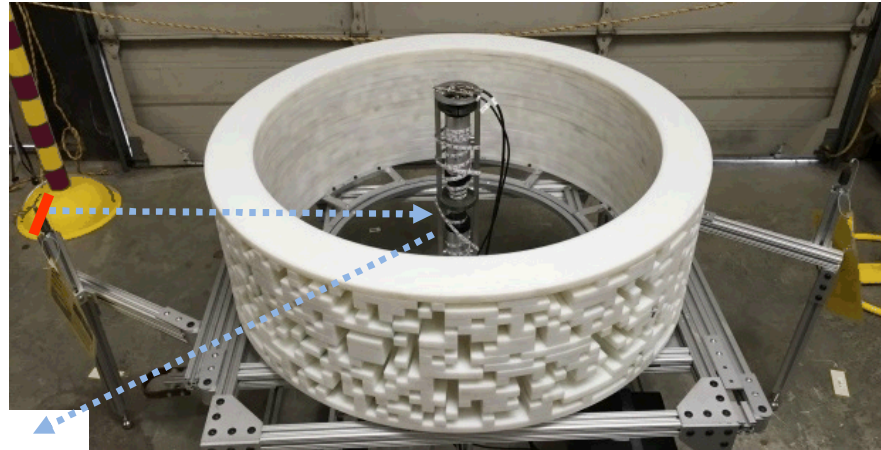
Rotation Angle (deg)



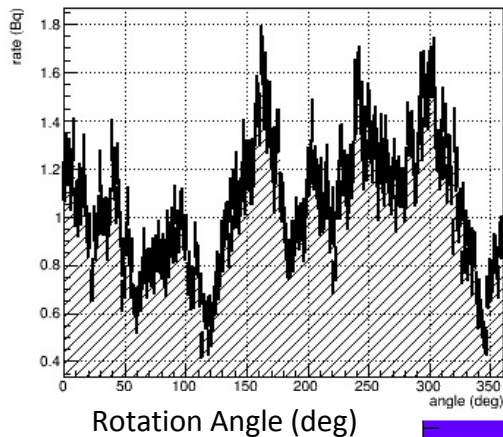
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Results – Double point source measurements

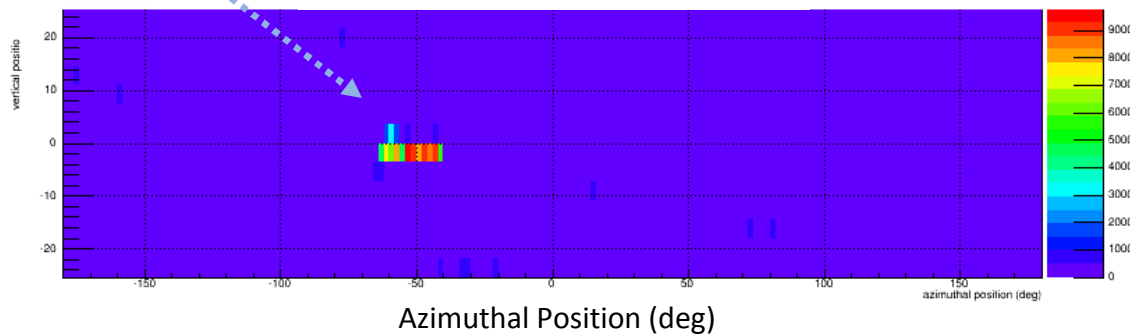
Measurement of a
double “line” source
(~20 hours)



Neutron Rate



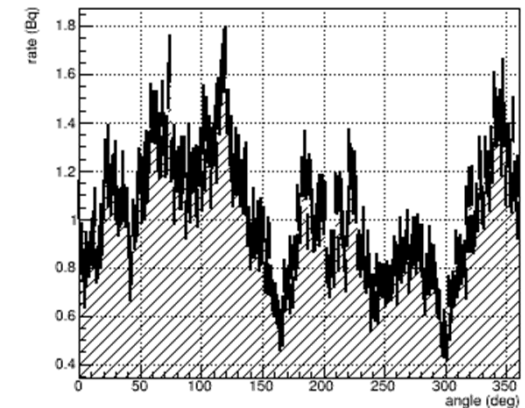
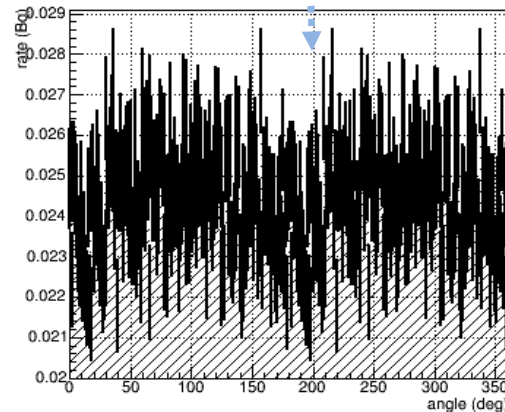
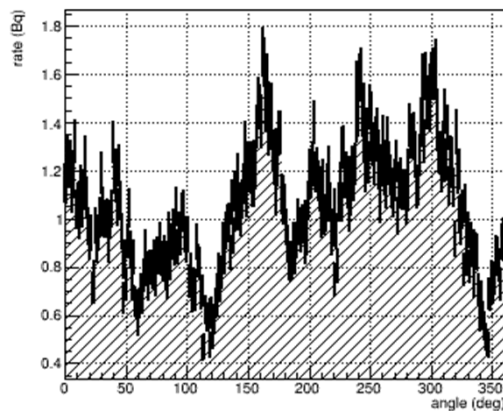
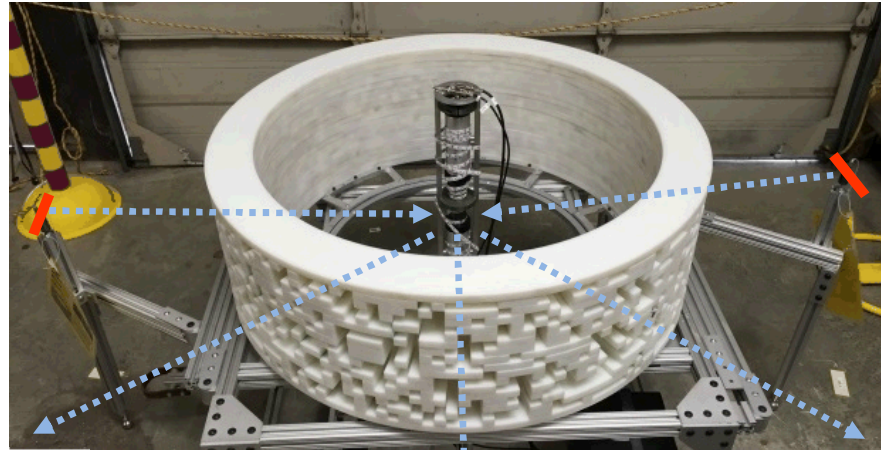
MLEM Reconstruction



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Results – Double point source measurements

Measurement of a
double “line” source
(~20 hours)



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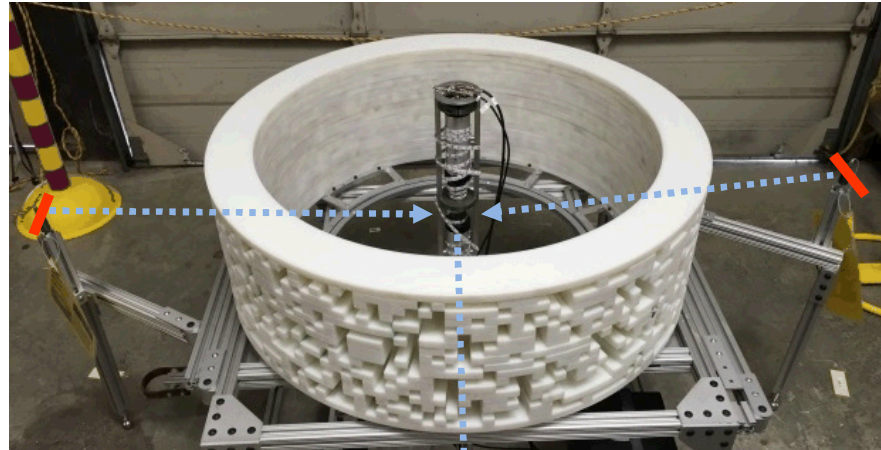
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Results – Double point source measurements

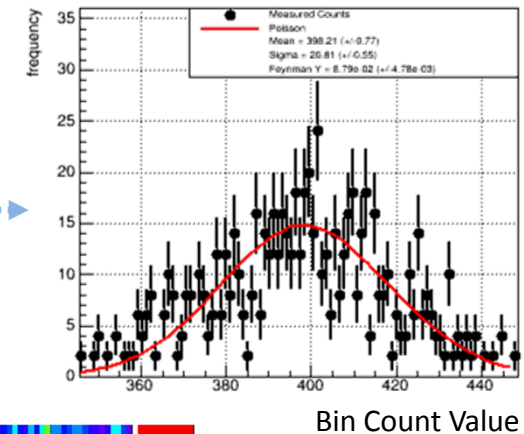
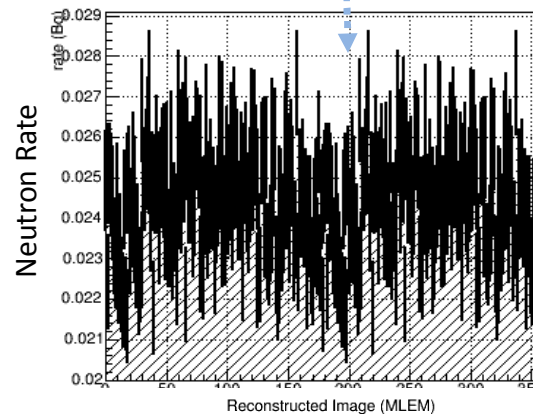
Measurement of a double “line” source (~20 hours total)



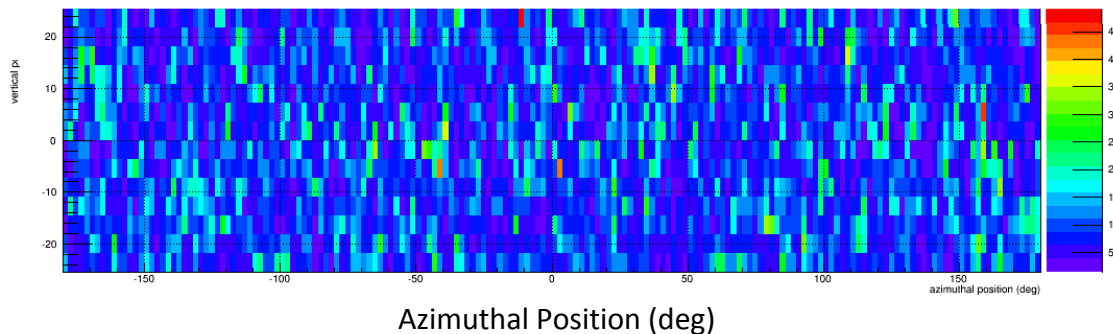
VERIFICATION
Assets Fund

$$\begin{aligned} \text{Feynman } Y &= \left(\frac{\text{variance}}{\text{mean}} - 1 \right) \\ &= 0.0879 \pm 0.00478 \end{aligned}$$

Count Distribution
(Poisson – red curve)



MLEM
Reconstruction

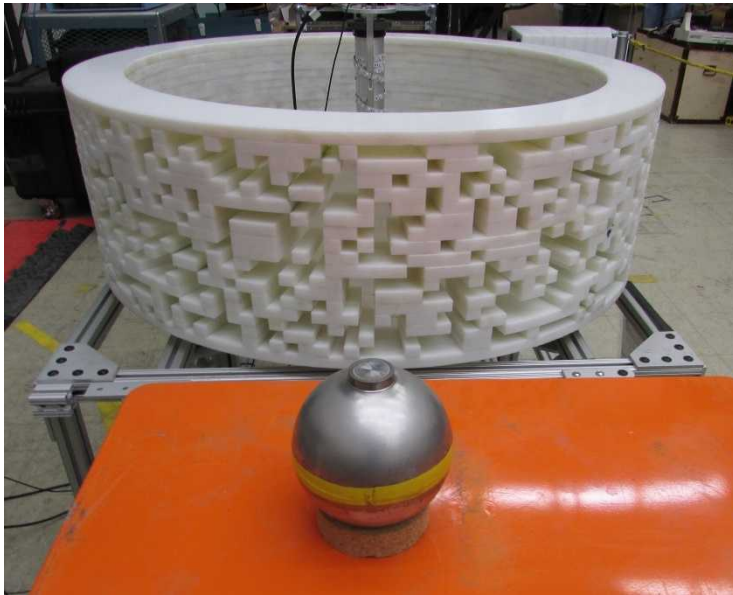


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Azimuthal Position (deg)

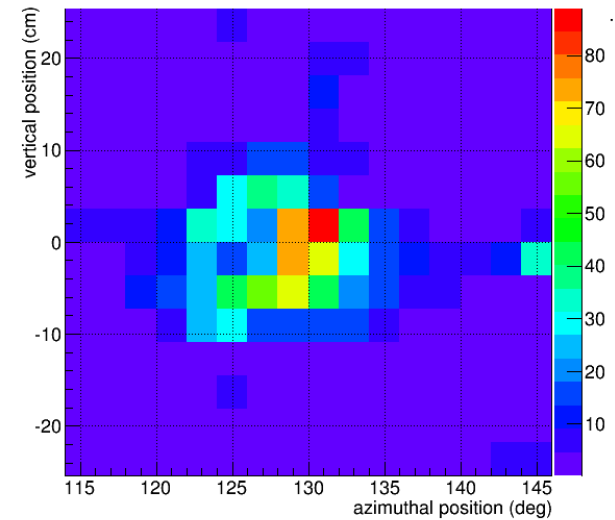
LLNL's PuO₂ Hemispheres

Measurement of plutonium dioxide hemispherical shells at LLNL.



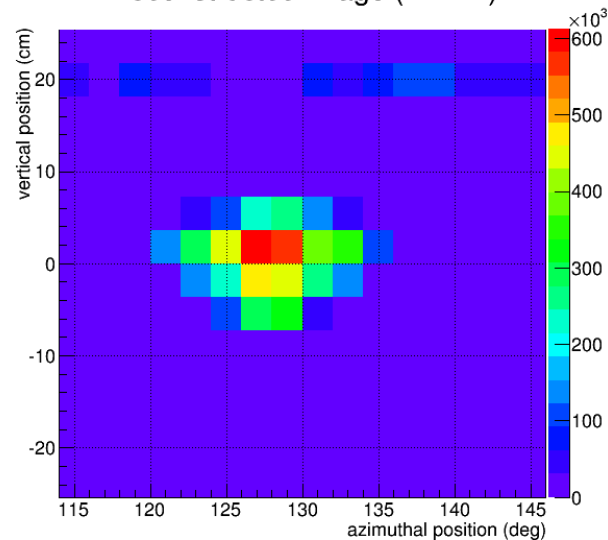
VERIFICATION

Reconstructed Image (MLEM)



Neutron Image

Reconstructed Image (MLEM)



Gamma-ray Image



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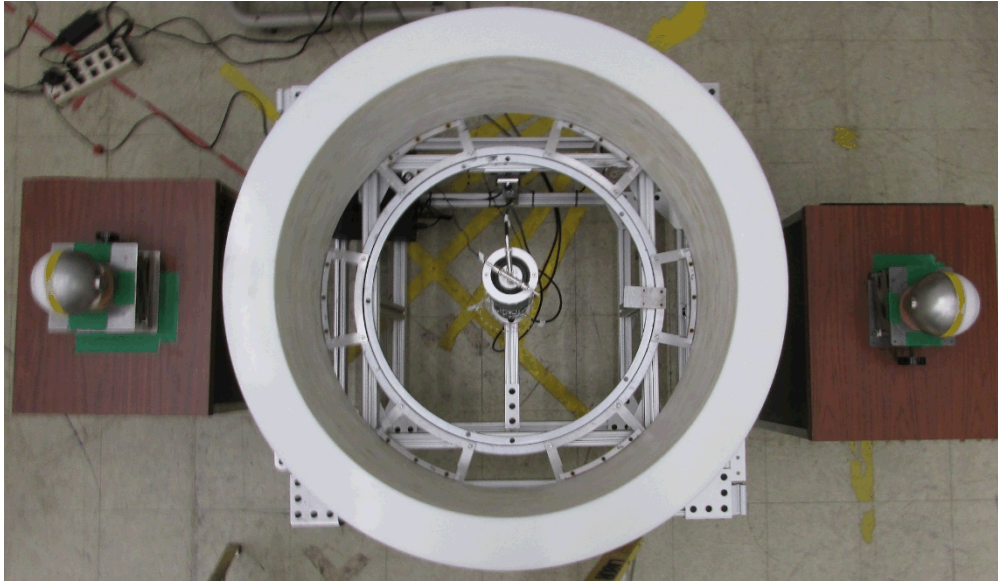
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LLNL's PuO₂ Hemisphere comparison measurement

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- One hemisphere was placed on either side of CONFIDANTE (180 deg. apart).
- ~68 hours of data was taken.



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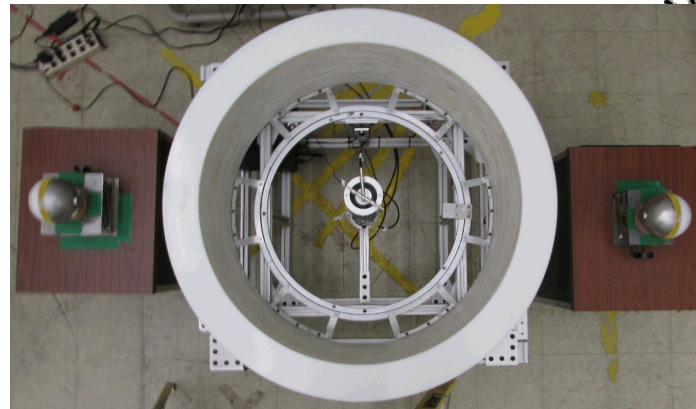


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LLNL's PuO₂ Hemi positive measurement

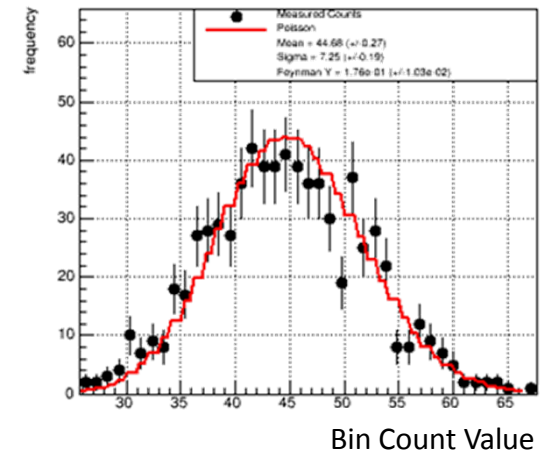
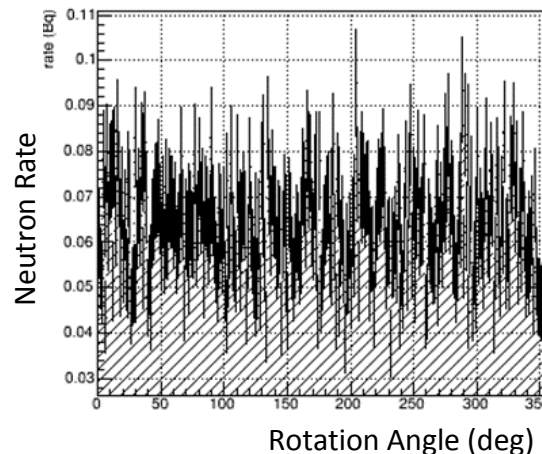
- One hemisphere was placed on each side (180 deg) of CONFIDANTE.
- ~68 hours of data was taken.



VERIFICATION
Assets Fund

$$\begin{aligned} \text{Feynman Y} &= \left(\frac{\text{variance}}{\text{mean}} - 1 \right) \\ &= 0.0176 \pm 0.00103 \end{aligned}$$

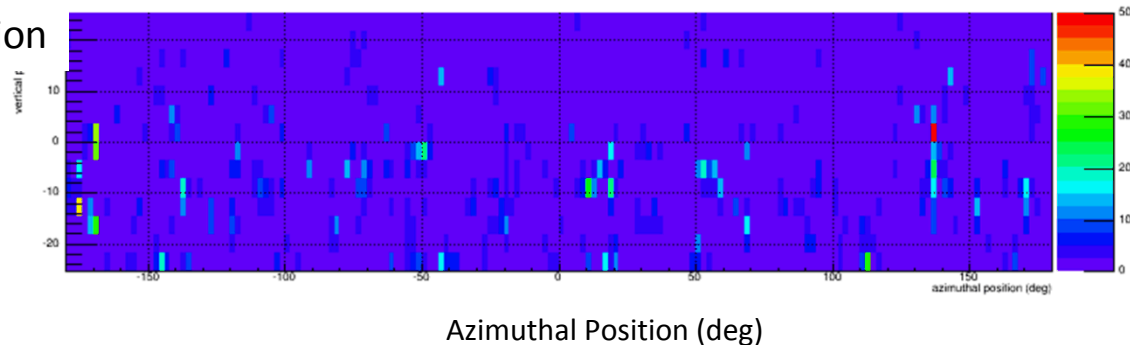
Count Distribution
(Poisson – red curve)



MLEM
Reconstruction



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LLNL's PuO₂ Hemi negative measurement

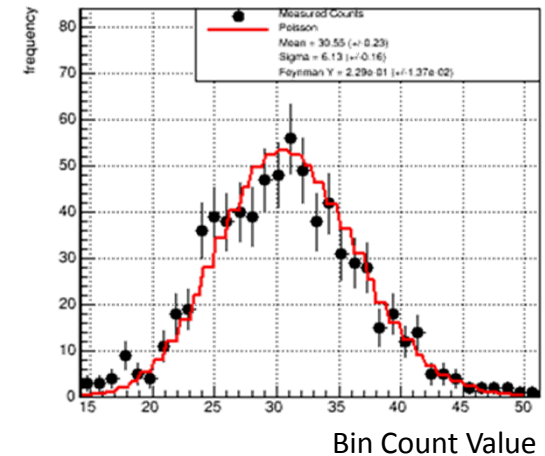
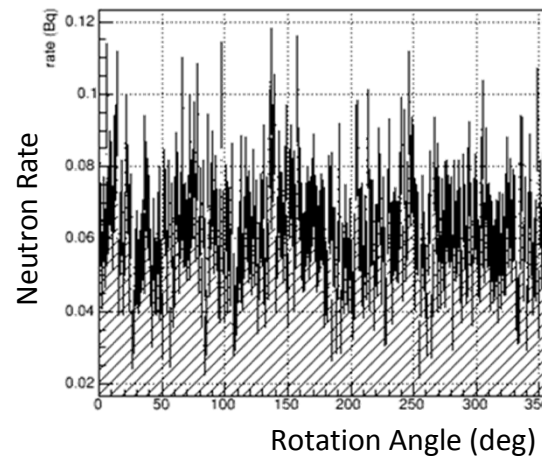
- One hemisphere was placed on each side (180 deg) of CONFIDANTE.
- One was rotated by 90 degrees.
- ~48 hours of data was taken.



VERIFICATION
Assets Fund

$$\begin{aligned} \text{Feynman Y} &= \left(\frac{\text{variance}}{\text{mean}} - 1 \right) \\ &= 0.229 \pm 0.0137 \end{aligned}$$

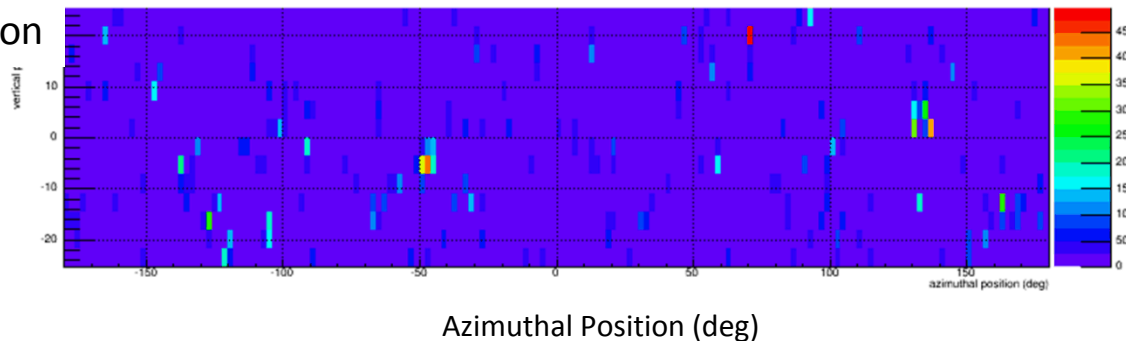
Count Distribution
(Poisson – red curve)



MLEM
Reconstruction

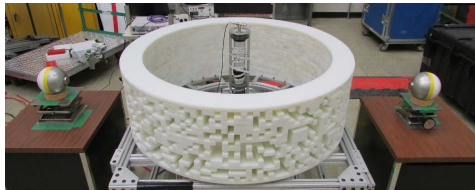


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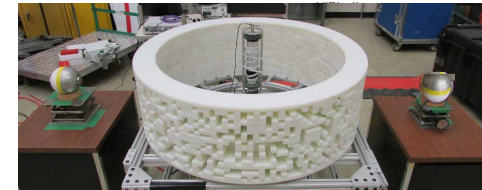


Feynman Y Test Statistic – 10,000 bootstrapped trials

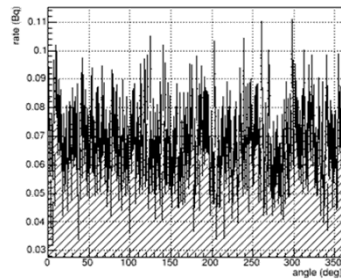
Identical Hemis



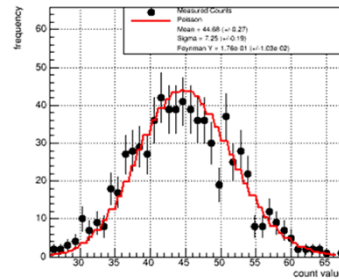
Misaligned Hemis



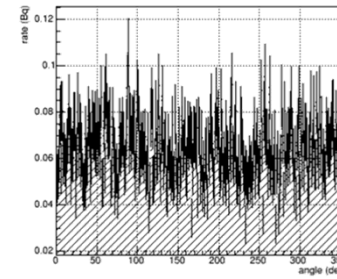
Detector Rate (det 1)



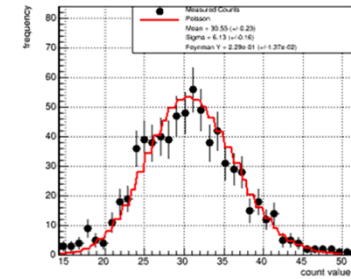
Measured Count Distribution (Run 0)



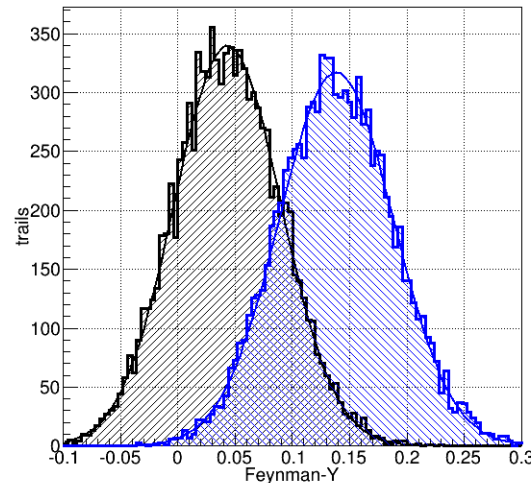
Detector Rate (det 1)



Measured Count Distribution (Run 0)



Distribution of Feynman-Y Test Statistics



Black – 10,000 bootstrapped trials of two “identical” PuO_2 hemispheres (~48 hours)

Blue – 10,000 trials of two “non-identical PuO_2 hemispheres (~48 hours) (one side rotated by 90 deg.)



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Conclusions



- Feasibility for the CONFIDANTE concept has been proven.
- CONFIDANTE is a simple system based on single pixel compressive imaging.
- CONFIDANTE may offer a more easily authenticatable system:
 1. Confirms that two objects are identical in a single measurement with NULL (constant rate) indicating a positive result.
 2. Because a NULL (constant rate) is present at all times, the inspecting party might be allowed full access to the measurement and data.
 3. A test statistic relating to how “Poisson” that count rate is can be updated to further protect against sensitive information loss.
 4. Can image any third inspector provided object during the confirmation measurement without revealing the first two objects as an authentication measure.



Extra Slides



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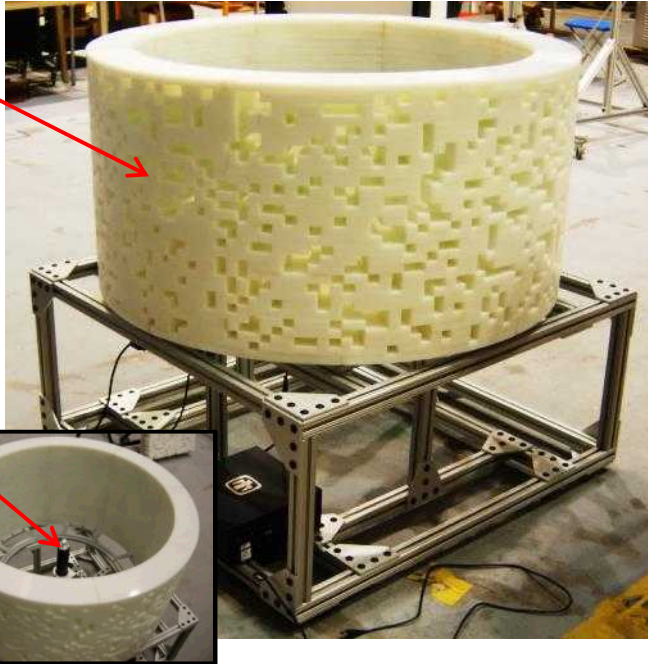
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2D TEI – confirmation measurements?

VERIFICATION
Assets Fund

2-d
coded
mask

Single 1"D
x 1" LS
pixel



- **TEI is simple**

1. Only one instrumented channel.
2. Minimal calibration issues
 - a) Information encoded in the relative rate of a single detector.
 - b) Absolute gain doesn't matter.
 - c) Gain can drift over time.
3. Potential real-time analysis
 - a) Single data stream.
 - b) Events can be processed one at a time and update a test statistic.



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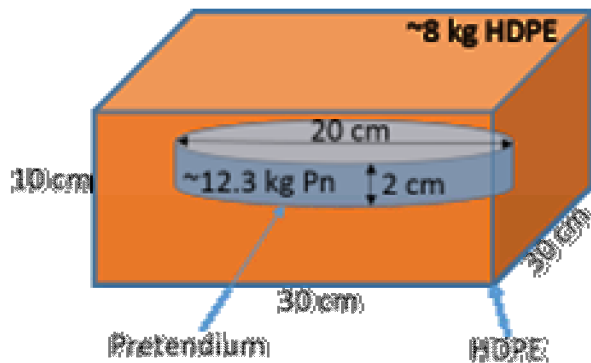
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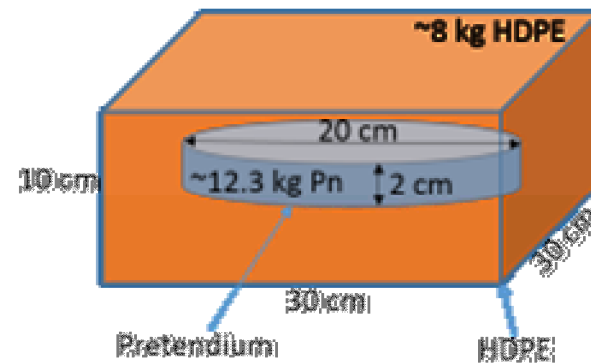
Challenge problem



- The inspecting party has or had access to measure item T, which is known to be a valid type 1 treaty accountable TAI through some other mechanism.
- In the course of an inspection, the host presents item X and declares it as a type 1 TAI
- Item X should pass the verification measurement if it is a type 1 TAI, and fail if it is significantly different.



**Object T = valid type
1 TAI**



Object X = ?



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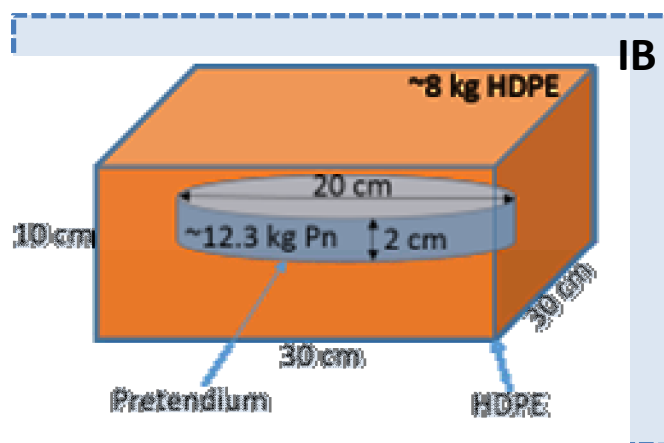
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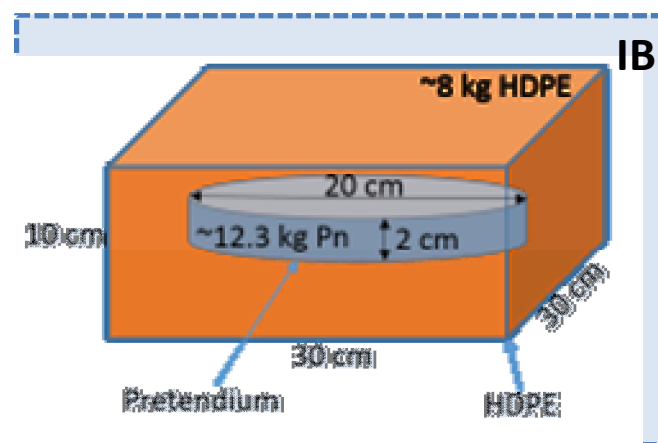
Challenge problem



- The host must be confident that the inspector has not learned the diameter d of the pretendium in item X, or any type 1 TAI



Object T = valid type
1 TAI



Object X = ?



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