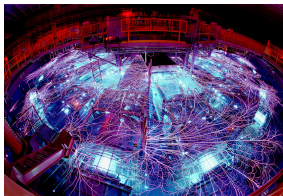


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SAND2017-0326C



Model Reduction Capabilities in Albany

Albany User Meeting, January 2017

Jeffrey A. Fike

Sandia National Laboratories

1/9/17



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Unlimited Release

Acknowledgement

The majority of the capabilities described here were originally implemented in Albany by Julian Cortial.

Outline

Motivation and Introduction

Model Reduction Implementation in Albany

Reduced-Order Model Workflow

Current and Future Work

Motivation

High-fidelity computational analysis is often accurate but very computationally expensive

- In some cases, a single analysis run can take several weeks using thousands of processors on modern supercomputers

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Reduced-order models (ROMs) can be used as surrogates for the high-fidelity analysis

- Need to retain a sufficient level of accuracy
- Need to have a significantly lower computational cost

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Reduced-order models (ROMs) can be used as surrogates for the high-fidelity analysis

- Need to retain a sufficient level of accuracy
- Need to have a significantly lower computational cost

ROMs can then be used for:

- Real-time analysis
- Uncertainty Quantification (UQ) methods, which often require very many analysis runs

Offline/Online Separation

Offline Training Stage:

- Generate and store information to be used during online stage
- Involves one (or more) high-fidelity analysis run(s)
- Computationally expensive, but performed once

Online Evaluation Stage:

- Many evaluations of the reduced-order model
- Computationally inexpensive

Nomenclature

The following terms are used throughout this presentation, often interchangeably:

- High-fidelity analysis, full-order model, FOM
- Model reduction, MOR, reduced-order model, ROM
- Reduced basis, modal basis, POD basis, basis
- Galerkin projection, Galerkin ROM
- Least-squares Petrov-Galerkin projection, LSPG ROM, minimum-residual ROM
- Generalized coordinates, modal coefficients, ROM coefficients

Projection-Based Model Reduction

During the offline training stage, we construct a modal basis, Φ

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The state of the system, x , can then be approximated as

$$x \approx \tilde{x} = \bar{x} + \Phi \hat{x}$$

- \bar{x} is some reference state
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The system of equations for the ROM coefficients is constructed by projecting the governing equations onto a test basis, Ψ

Continuous vs. Discrete Projection

Continuous Projection

- The continuous governing equations (PDEs) are projected onto the test basis in offline stage
- For polynomial nonlinearities, this results in a set of ODEs for the modal coefficients
- For other nonlinearities, techniques such as Gappy POD or Empirical Interpolation are required

Discrete Projection

- The discretized governing equations (discrete residual and Jacobian) are projected onto the test basis
- For nonlinear equations this requires embedding the projection operation in the analysis code

Outline

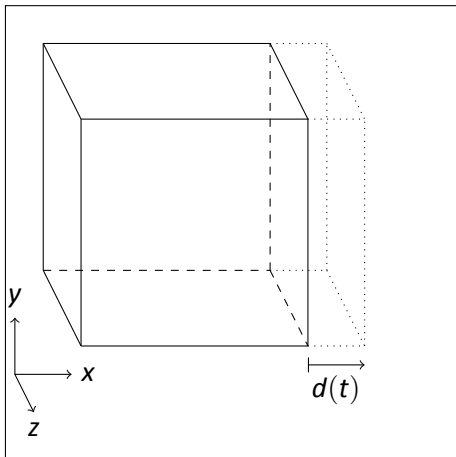
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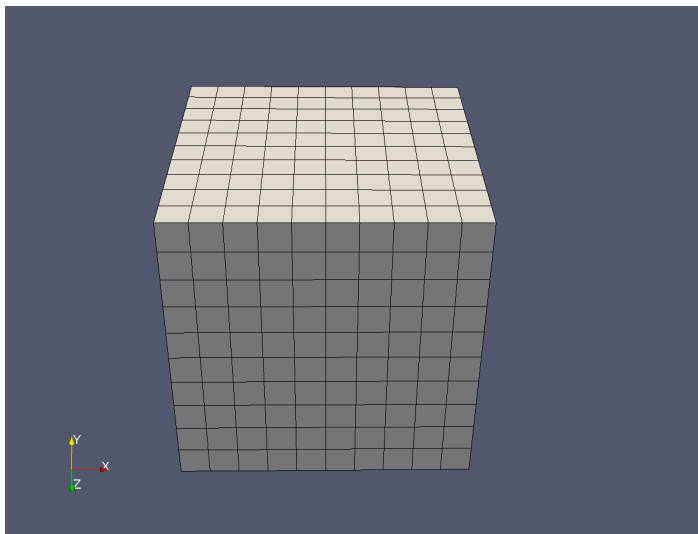
Current and Future Work

Solid Mechanics Example in Albany

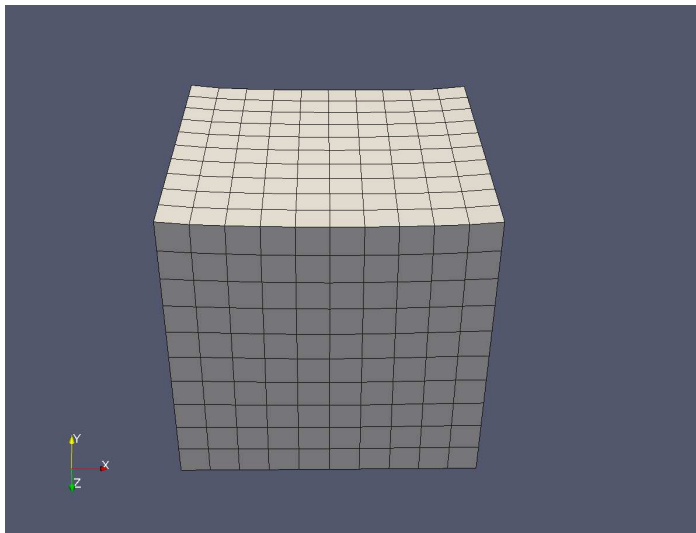


- Steel cube
- Time-varying displacement applied to one side
- Fixed displacement on other end
- Quasistatic problem using LOCA

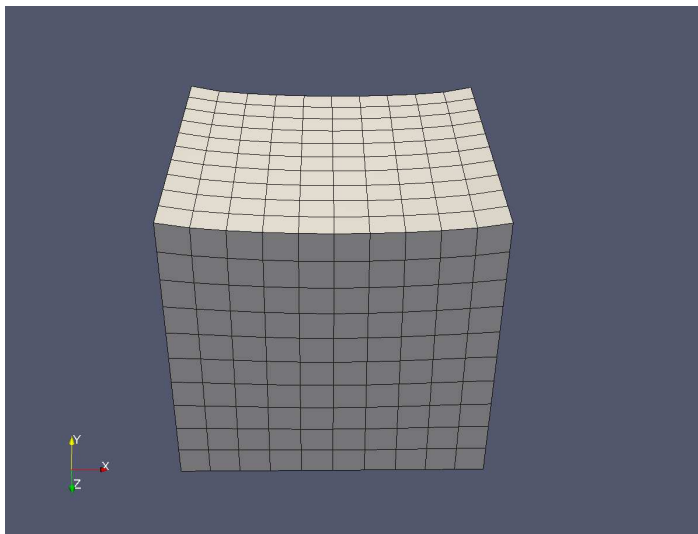
Solid Mechanics Example in Albany



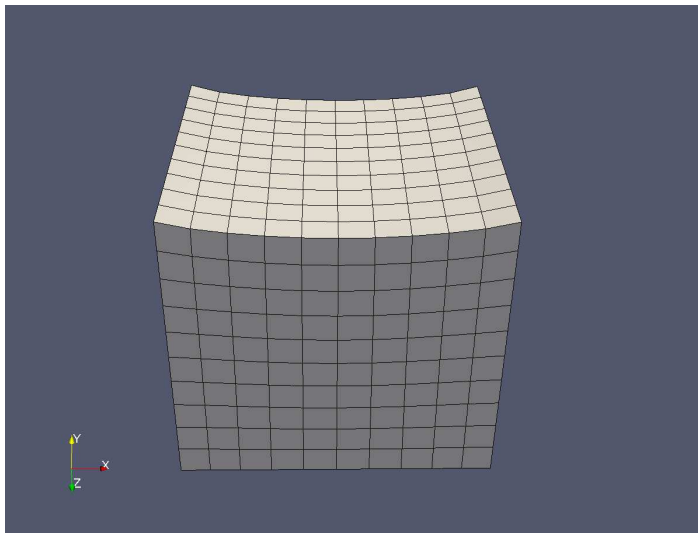
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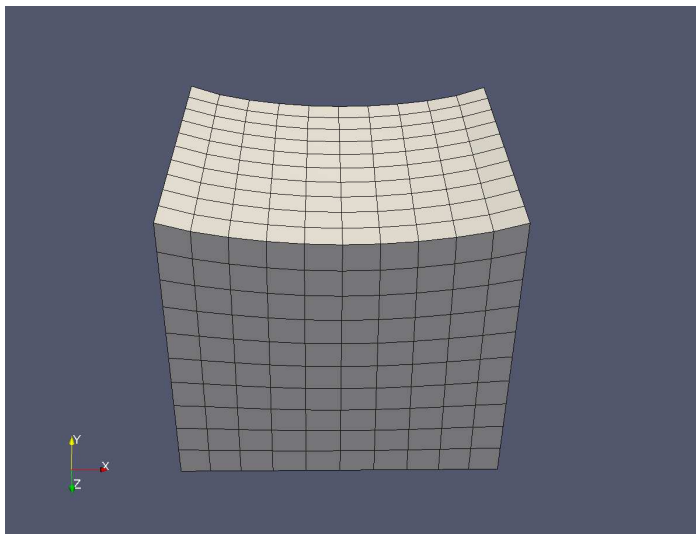
Solid Mechanics Example in Albany



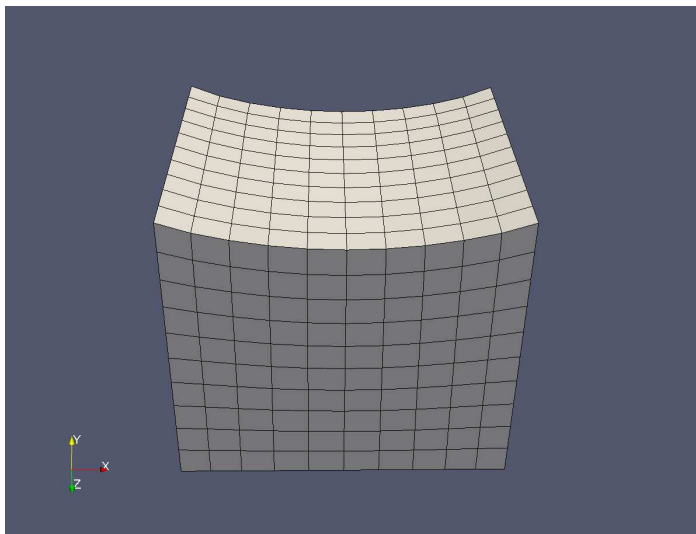
Solid Mechanics Example in Albany



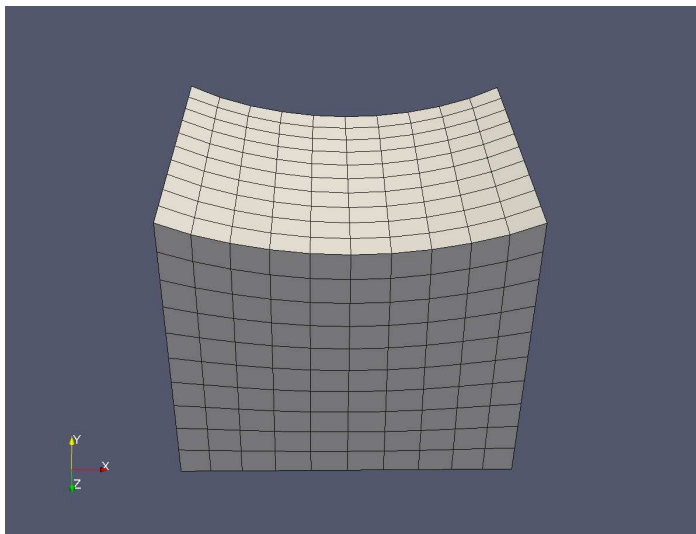
Solid Mechanics Example in Albany



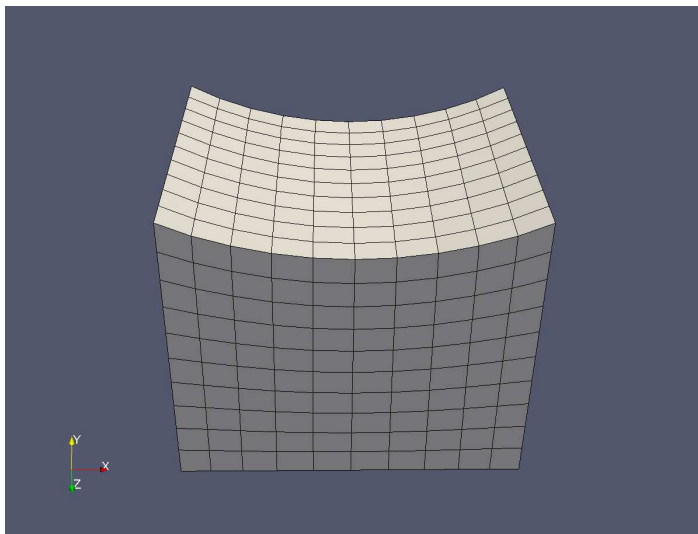
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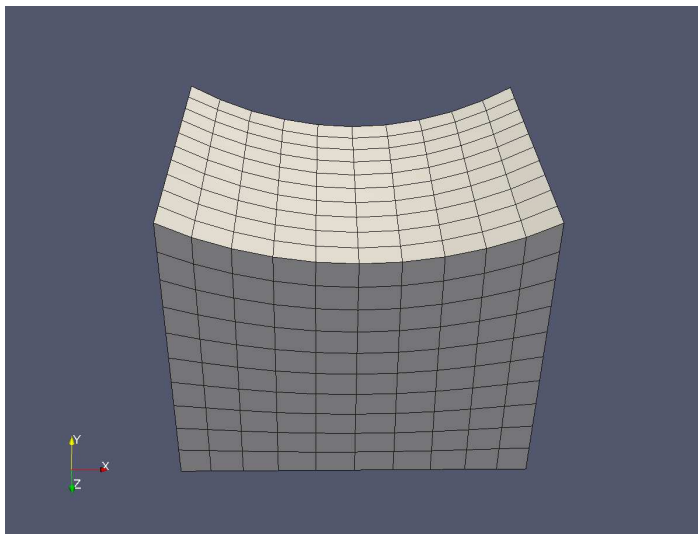
Solid Mechanics Example in Albany



Solid Mechanics Example in Albany



Solid Mechanics Example in Albany



Quasistatic Problem Solved Using Continuation (LOCA)



During each continuation step:

- Increment time, i.e. $t = t + \Delta t$
- Applied displacement boundary condition increases linearly with time
- Solve for change in state of the system (i.e. deformation) using Newton iterations (NOX)

$$W(x)\Delta x = -f(x)$$

Albany_ModelEvaluator provides residual, f , and Jacobian, W

Reduced-Order Model Solution

During each continuation step:

- Increment time, i.e. $t = t + \Delta t$
- Approximate the state of the system $x \approx \tilde{x} = \bar{x} + \Phi \hat{x}$
- Applied displacement boundary condition increases linearly with time
- Solve for change in modal coefficients, $\Delta \hat{x}$, using Newton iterations (NOX)

$$W_r(\tilde{x}) \Delta \hat{x} = -f_r(\tilde{x})$$

MOR_ReducedOrderModelEvaluator provides reduced residual, f_r , and reduced Jacobian, W_r

- Calls Albany_ModelEvaluator to get full residual, f , and full Jacobian, W

MOR Implementation in Albany

The MOR_ReducedOrderModelEvaluator can be thought of as a wrapper around the Albany_ModelEvaluator

- Sometimes referred to as the MOR facade
- Only activated when reduced-order model options are enabled in the input file

Implementation generic enough to create ROMs for various solvers and physics sets enabled in Albany

- Current projects focus on using LOCA for LCM problems

However, the current MOR capabilities are built on the EpetraExt_ModelEvaluator

- Will not work for packages that are built only on the Thyra_ModelEvaluator, such as Aeras
- Future work may convert implementation to Thyra

Reduced-Order Model Details

Full-Order Model involves solving

$$W(x)\Delta x = -f(x)$$

Reduced-Order Model involves solving

$$W_r(\tilde{x})\Delta \hat{x} = -f_r(\tilde{x})$$

where

$$W_r(\tilde{x}) = \Psi^T W(\tilde{x}) \Phi$$

$$f_r(\tilde{x}) = \Psi^T f(\tilde{x})$$

and the choice of the test basis, Ψ , depends on the type of reduced-order model chosen

Reduced-Order Model Types in Albany

There are currently two options implemented in Albany for the type of reduced-order model

- Galerkin Projection
- Minimum Residual (aka Least-Squares Petrov-Galerkin)

In Galerkin projection, the test basis, Ψ , is the trial basis, Φ and we have

$$W_r(\tilde{x}) = \Phi^T W(\tilde{x}) \Phi$$

$$f_r(\tilde{x}) = \Phi^T f(\tilde{x})$$

Minimum Residual ROM

The minimum residual or least-squares Petrov-Galerkin ROM involves finding the solution to the nonlinear least-squares problem

$$\hat{x} = \arg \min_y \|f(\bar{x} + \Phi y)\|_2^2$$

Using the Gauss-Newton approach, this involves solving a sequence of linear least-squares problems

$$\Delta \hat{x} = \arg \min_y \|W(\tilde{x})\Phi y + f(\tilde{x})\|_2^2$$

The normal equation form is

$$\Phi^T W^T(\tilde{x})W(\tilde{x})\Phi \Delta \hat{x} = -\Phi^T W^T(\tilde{x})f(\tilde{x})$$

which corresponds to choosing $\Psi = W(\tilde{x})\Phi$, and giving

$$W_r(\tilde{x}) = \Phi^T W^T(\tilde{x})W(\tilde{x})\Phi$$

$$f_r(\tilde{x}) = \Phi^T W^T(\tilde{x})f(\tilde{x})$$

Dimension Reduction

Full-Order Model involves solving

$$W(x)\Delta x = -f(x)$$

- Typically $\mathcal{O}(10^6)$ degrees of freedom

Reduced-Order Model involves solving

$$W_r(\tilde{x})\Delta \hat{x} = -f_r(\tilde{x})$$

- Typically $\mathcal{O}(100)$ modal coefficients

Dimension Reduction

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Reduced-Order Model involves solving

$$W_r(\tilde{x})\Delta \hat{x} = -f_r(\tilde{x})$$

- Typically $\mathcal{O}(100)$ modal coefficients

Despite the reduction in the dimension of the problem, there is not typically a reduction in computational cost

- Constructing reduced residual and Jacobian requires evaluating full residual and Jacobian for every DOF

Hyper-Reduction

Introduce a sampling operation to select a small subset of the total DOFs where the residual and Jacobian are computed

- $Zf(\tilde{x})$ and $ZW(\tilde{x})$ are the selected residual and Jacobian entries
- Z denotes the concept of a sampling matrix
- In practice there is no actual multiplication, the selected entries are simply evaluated without explicitly forming Z , f , or W

For the LSPG ROM, this gives

$$W_r(\tilde{x}) = \Phi^T W^T(\tilde{x}) Z^T Z W(\tilde{x}) \Phi$$

$$f_r(\tilde{x}) = \Phi^T W^T(\tilde{x}) Z^T Z f(\tilde{x})$$

- Provides reduction in computational cost

Outline

Motivation and Introduction

Model Reduction Implementation in Albany

Reduced-Order Model Workflow

Current and Future Work

Configure and Build Albany and Trilinos

Configure Trilinos and build:

- `-D Trilinos_ENABLE_Anasazi:BOOL=ON`
- `-D Anasazi_ENABLE_RBGen:BOOL=ON`
- `-D CMAKE_CXX_FLAGS:STRING="-DEPETRA_LAPACK3"`

Configure and Build Albany and Trilinos

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Configure Albany:

- `-D ENABLE_MOR=ON`

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Configure Albany:

- `-D ENABLE_MOR=ON`

Building Albany should produce the standard executables, plus some ROM specific utilities

- AlbanyRBGen - used to generate modal basis
- AlbanyMeshSample - used to generate sample mesh
- AlbanyRomPostProcess - used to recreate full solution after running ROM with sample mesh

Reduced-Order Model Workflow

Offline Stage:

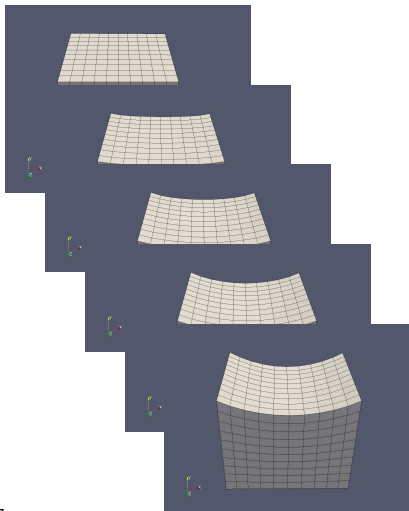
- Run full-order model in Albany to generate training data
- Construct modal basis
- Construct sample mesh

Online Stage

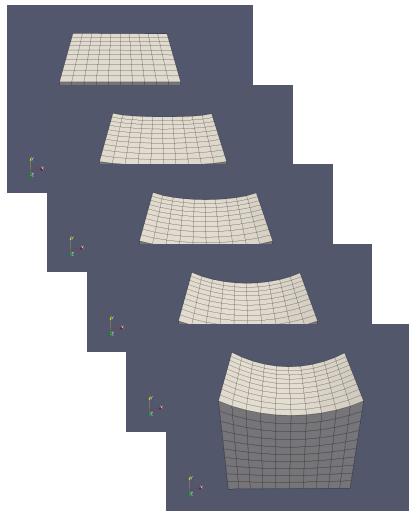
- Run reduced-order model in Albany
- Post-process results

Run FOM to Generate Training Data

Poisson Ratio $\nu = 0.25$



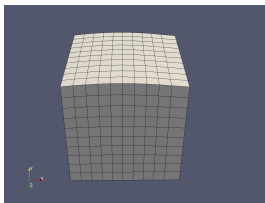
Poisson Ratio $\nu = 0.30$



Create Modal Basis

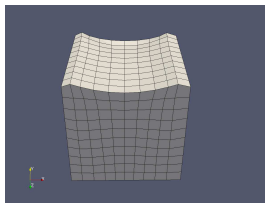
Run AlbanyRBGen executable

- Uses Proper Orthogonal Decomposition (POD) to create a basis



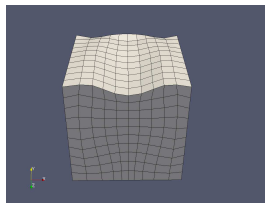
Mode 1

...



Mode 3

...



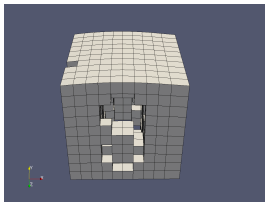
Mode 5

...

Create Sample Mesh

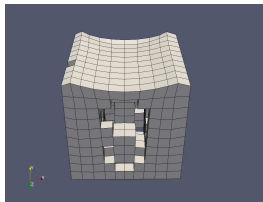
Run AlbanyMeshSample executable

- Uses a greedy algorithm to select nodes that best represents the full basis
- 400 sample nodes (out of 1331 total nodes) for a 35 mode basis



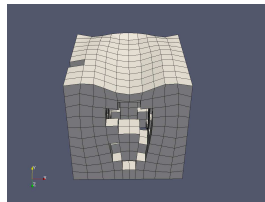
Mode 1

...



Mode 3

...



Mode 5

...

Run Reduced-Order Model in Albany

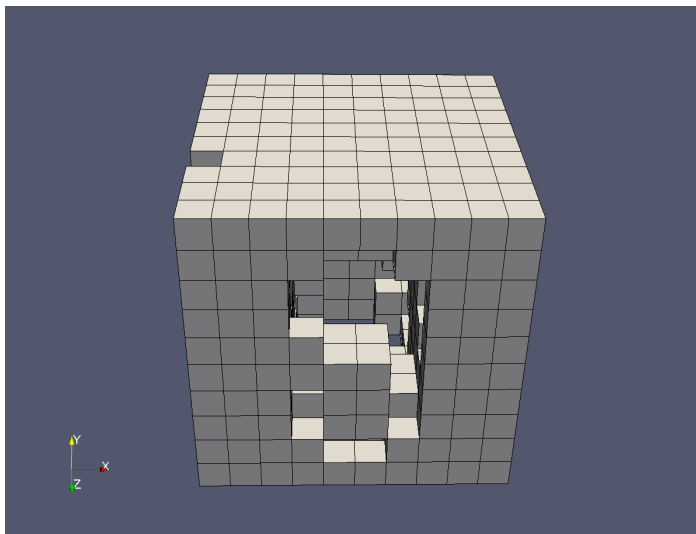
Run ROM at point not in training data

- Poisson Ratio $\nu = 0.2857$

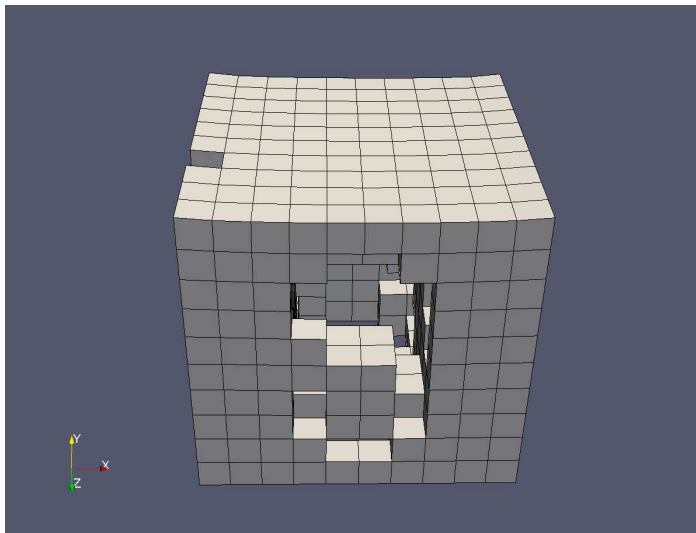
Modify the Albany input file:

- Specify the Exodus file containing the basis
- Add a Model Order Reduction section to the input file
- Specify various options such as the number of modes
- Possibly change the linear solver
 - FOM - typically involves a large, sparse system
 - ROM - involves a small, dense system

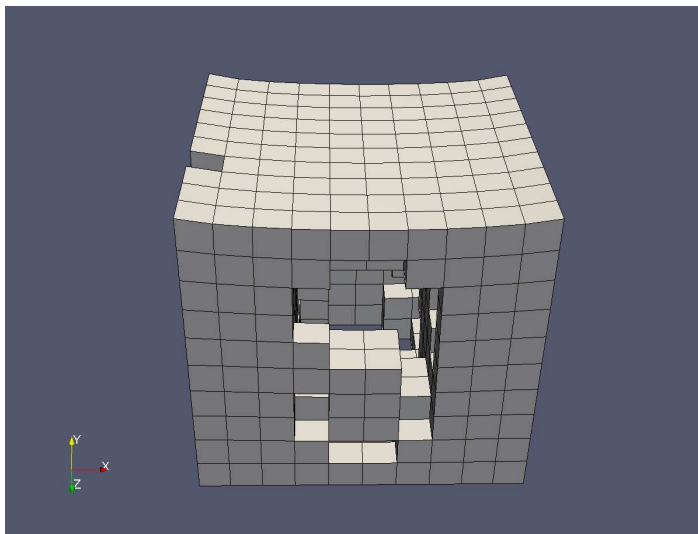
Galerkin ROM, 30 Modes, 400 Sample Nodes



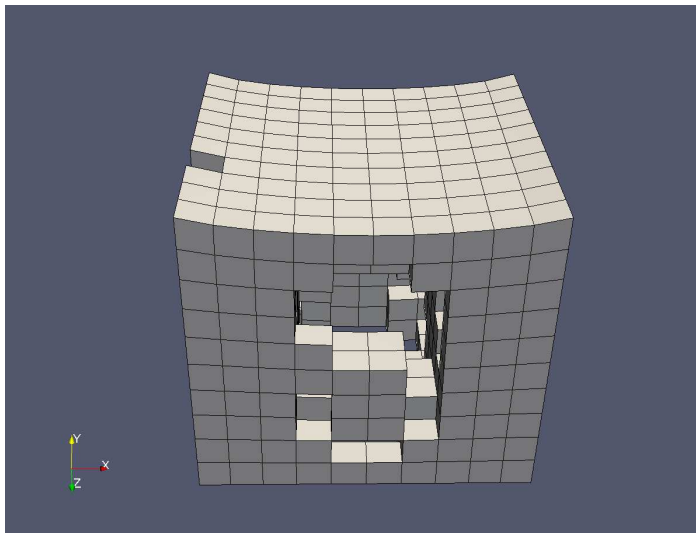
Galerkin ROM, 30 Modes, 400 Sample Nodes



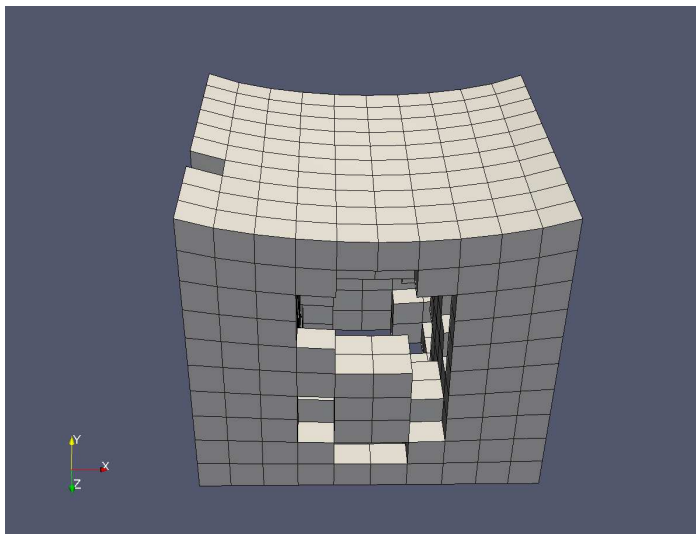
Galerkin ROM, 30 Modes, 400 Sample Nodes



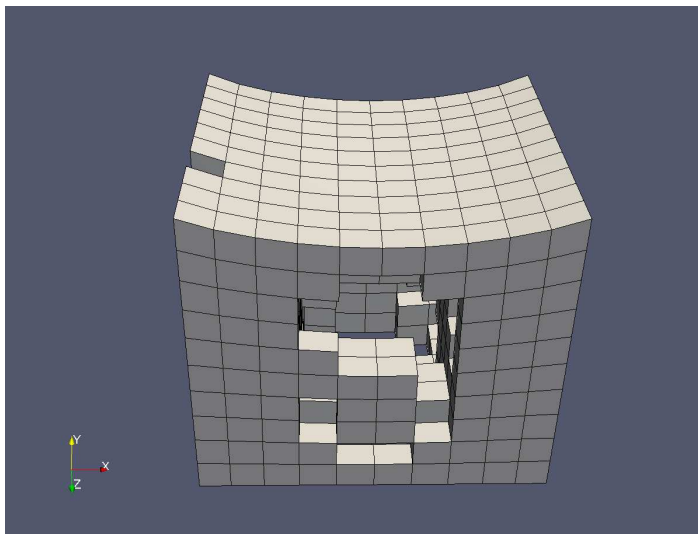
Galerkin ROM, 30 Modes, 400 Sample Nodes



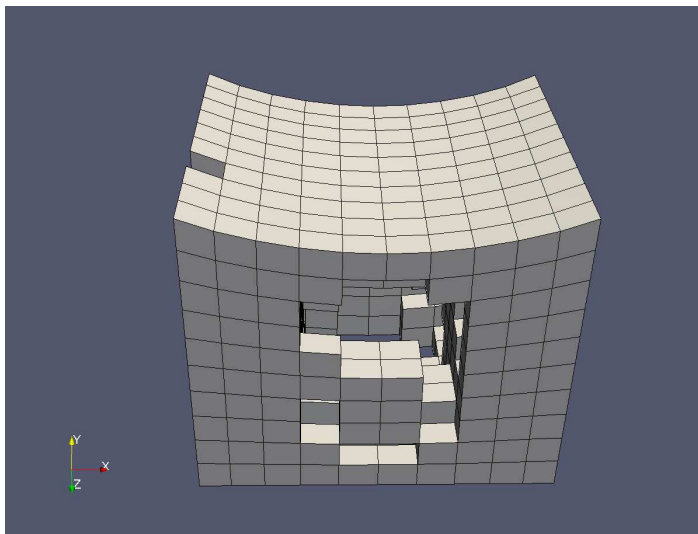
Galerkin ROM, 30 Modes, 400 Sample Nodes



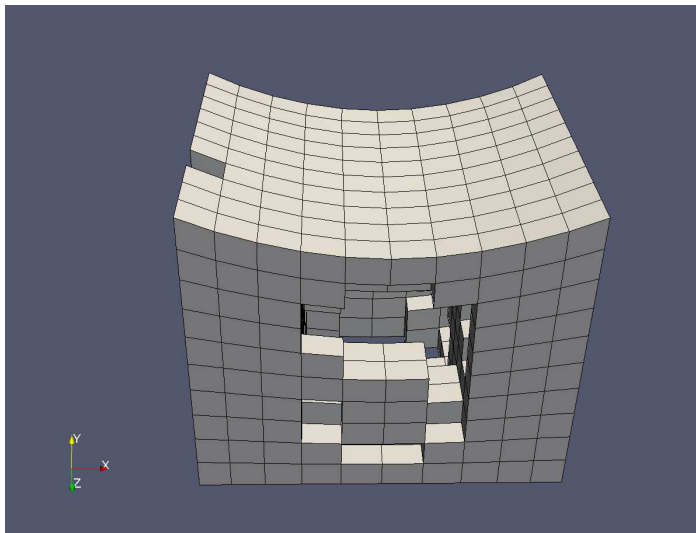
Galerkin ROM, 30 Modes, 400 Sample Nodes



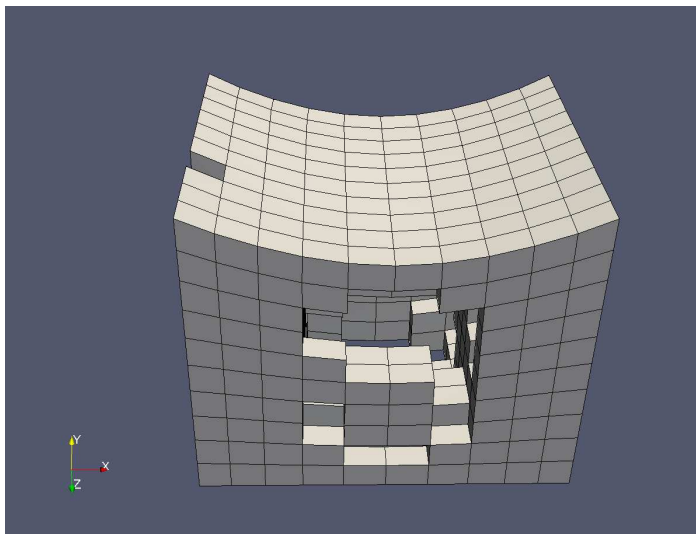
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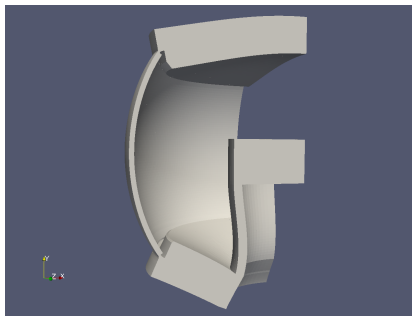
Reduced-Order Model Workflow

Current and Future Work

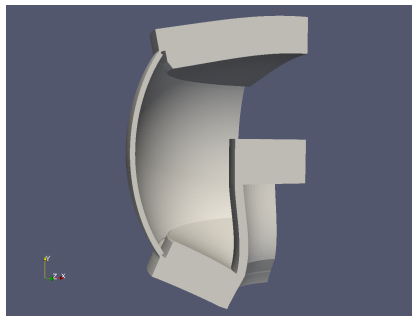
Current and Future Work

Current work is focused on creating ROMs for complex mechanical and coupled thermal-mechanical systems of interest at Sandia

- Predictive Capability Assessment Project (PCAP) test case



Full-Order Model



Galerkin ROM, no truncation, no hyper-reduction

Current and Future Work

Model Reduction capabilities in Albany are being improved and extended

- LSPG ROMs have improved handling of boundary conditions
- Preconditioned LSPG ROMs have been implemented using IFPACK to try to improve the accuracy and robustness of ROMs
- Investigating structure preserving constraints that may improve the accuracy of the ROMs

Questions?