

Epetra & Tpetra (Sparse linear algebra) overview



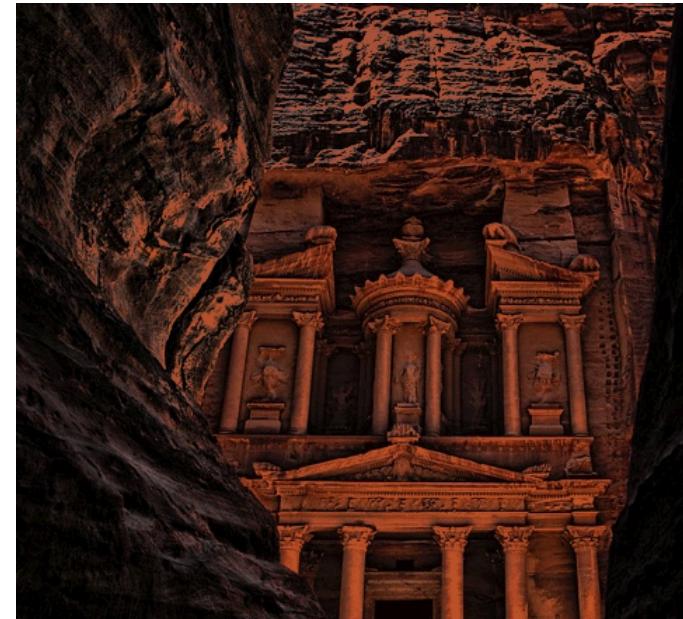
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Trilinos' Common Language: Petra

- “Common language” for distributed sparse linear algebra
- Petra¹ provides parallel...
 - ◆ Sparse graphs & matrices
 - ◆ Dense vectors & multivectors
 - ◆ Data distributions & redistribution
- “Petra Object Model”:
 - ◆ Describes objects & their relationships abstractly, independent of language or implementation
 - ◆ Explains how to construct, use, & redistribute parallel graphs, matrices, & vectors
- We maintain 2 implementations

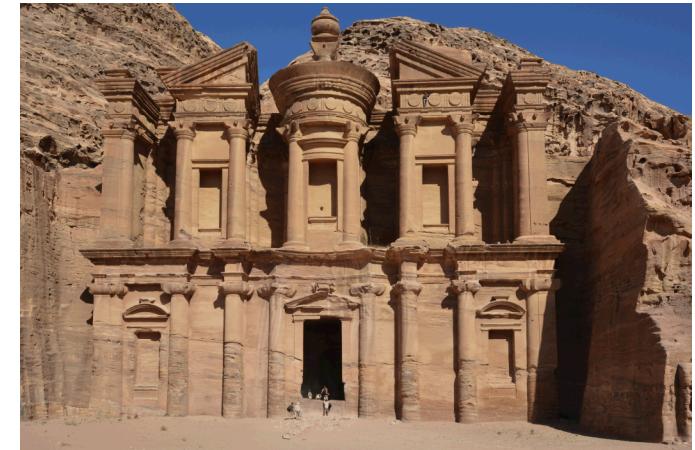


Al Khazneh (“The Treasury”), in the ancient city of Petra, in modern Jordan.

¹Petra (πέτρα) is Greek for “foundation.”

Petra Implementations

- Epetra (Essential Petra):
 - ◆ Earliest & most heavily used
 - ◆ C++ <= 1998 (“C+/- compilers” OK)
 - ◆ Real, double-precision arithmetic
 - ◆ C & Fortran interfaces
 - ◆ MPI only (very little OpenMP support)
 - ◆ Some support for problems with over two billion unknowns (“Epetra64”)
- Tpetra (Templated Petra):
 - ◆ Supports & **requires** C++11 (as of 11.14)
 - ◆ Real, complex, extended-precision, automatic differentiation, etc. types
 - ◆ Can solve problems with > 2B unknowns
 - ◆ “MPI+X” (shared-memory parallel)



Al Deir (“The Monastery”) at Petra.



Two “software stacks”: Epetra & Tpetra

- Many packages were built on Epetra’s interface
- Users want features that break interfaces
 - ◆ Support for solving huge problems (> 2B entities)
 - ◆ Arbitrary & mixed precision
 - ◆ Hybrid (MPI+X) parallelism (← most radical interface changes)
- Users also value backwards compatibility
- We decided to build a (partly) new stack using Tpetra
- Some packages can work with either Epetra or Tpetra
 - ◆ Iterative linear solvers & eigensolvers (Belos, Anasazi)
 - ◆ Multilevel preconditioners (MueLu), sparse direct (Amesos2)
- Which do I use?
 - ◆ Epetra is more stable; Tpetra is more forward-looking
 - ◆ For MPI only, their performance is comparable
 - ◆ For MPI+X, Tpetra will be the only path forward

Kokkos: Thread-parallel programming model & more

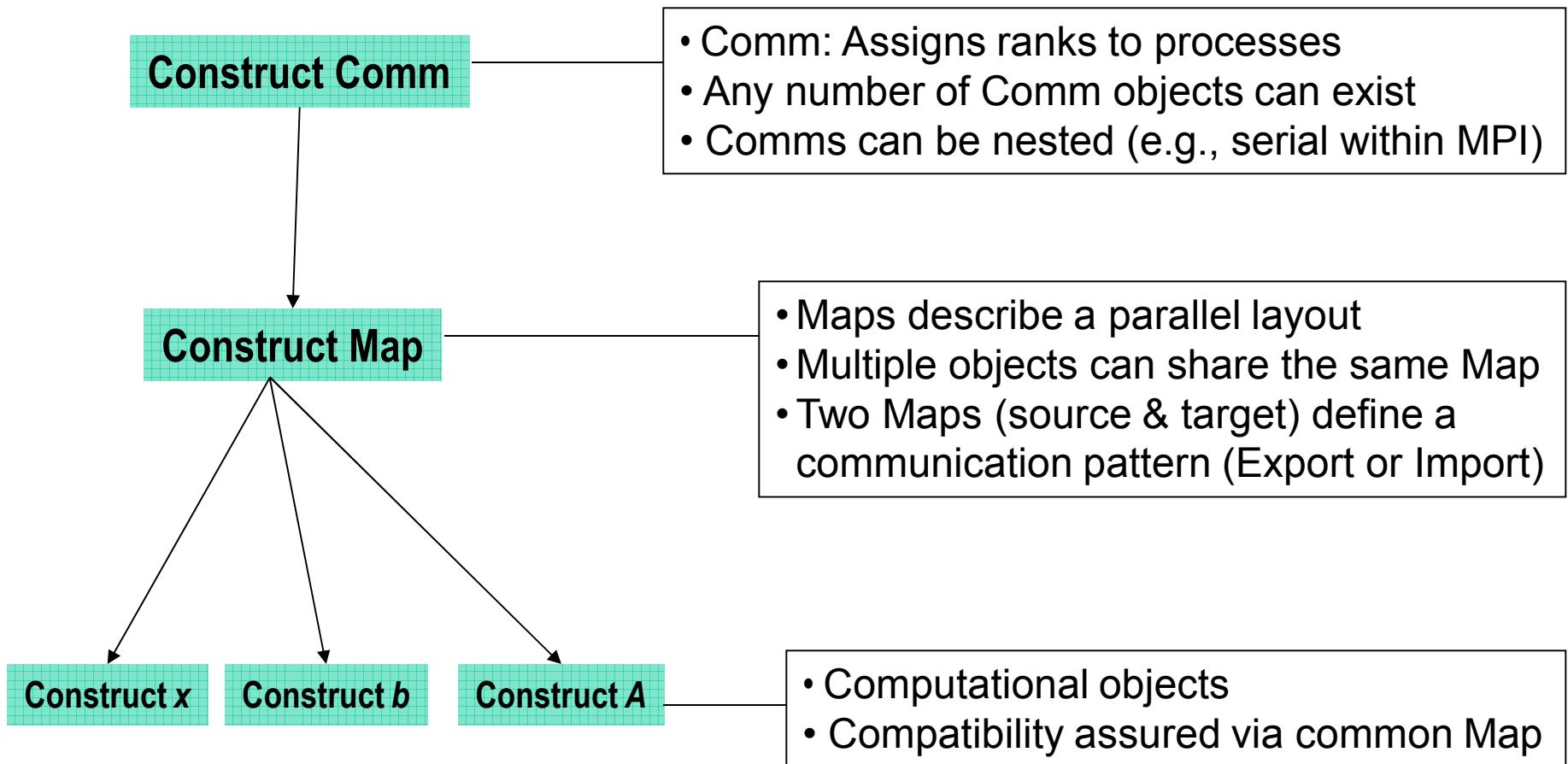
- Performance-portable abstraction over many different thread-parallel programming models: OpenMP, CUDA, Pthreads, ...
 - ◆ Avoid risk of committing code to hardware or programming model
 - ◆ C++ library: Widely used, portable language with good compilers
- Abstract away physical data layout & target it to the hardware
 - ◆ Solve “array of structs” vs. “struct of arrays” problem
- Expose different memory & execution spaces
- Data structures & idioms for thread-scalable parallel code
 - ◆ Multi-dimensional arrays, hash table, sparse graph & matrix
 - ◆ Automatic memory management, atomic updates, vectorization, ...
- Stand-alone; does not require other Trilinos packages
 - ◆ Used in LAMMPS molecular dynamics code
 - ◆ Growing use in Trilinos; other apps starting too



Petra distributed object model

Solving $Ax = b$:

Typical Petra Object Construction Sequence



A Simple Epetra/AztecOO Program

```
// Header files omitted...
int main(int argc, char *argv[]) {
Epetra_SerialComm Comm();

// ***** Map puts same number of equations on each pe *****
int NumMyElements = 1000 ;
Epetra_Map Map(-1, NumMyElements, 0, Comm);
int NumGlobalElements = Map.NumGlobalElements();

// ***** Create an Epetra_Matrix tridiag(-1,2,-1) *****
Epetra_CrsMatrix A(Copy, Map, 3);
double negOne = -1.0; double posTwo = 2.0;

for (int i=0; i<NumMyElements; i++) {
    int GlobalRow = A.GRID(i);
    int RowLess1 = GlobalRow - 1;
    int RowPlus1 = GlobalRow + 1;
    if (RowLess1!= -1)
        A.InsertGlobalValues(GlobalRow, 1, &negOne, &RowLess1);
    if (RowPlus1!= NumGlobalElements)
        A.InsertGlobalValues(GlobalRow, 1, &negOne, &RowPlus1);
    A.InsertGlobalValues(GlobalRow, 1, &posTwo, &GlobalRow);
}
A.FillComplete(); // Transform from GIDs to LIDs

// ***** Create x and b vectors *****
Epetra_Vector x(Map);
Epetra_Vector b(Map);
b.Random(); // Fill RHS with random #s

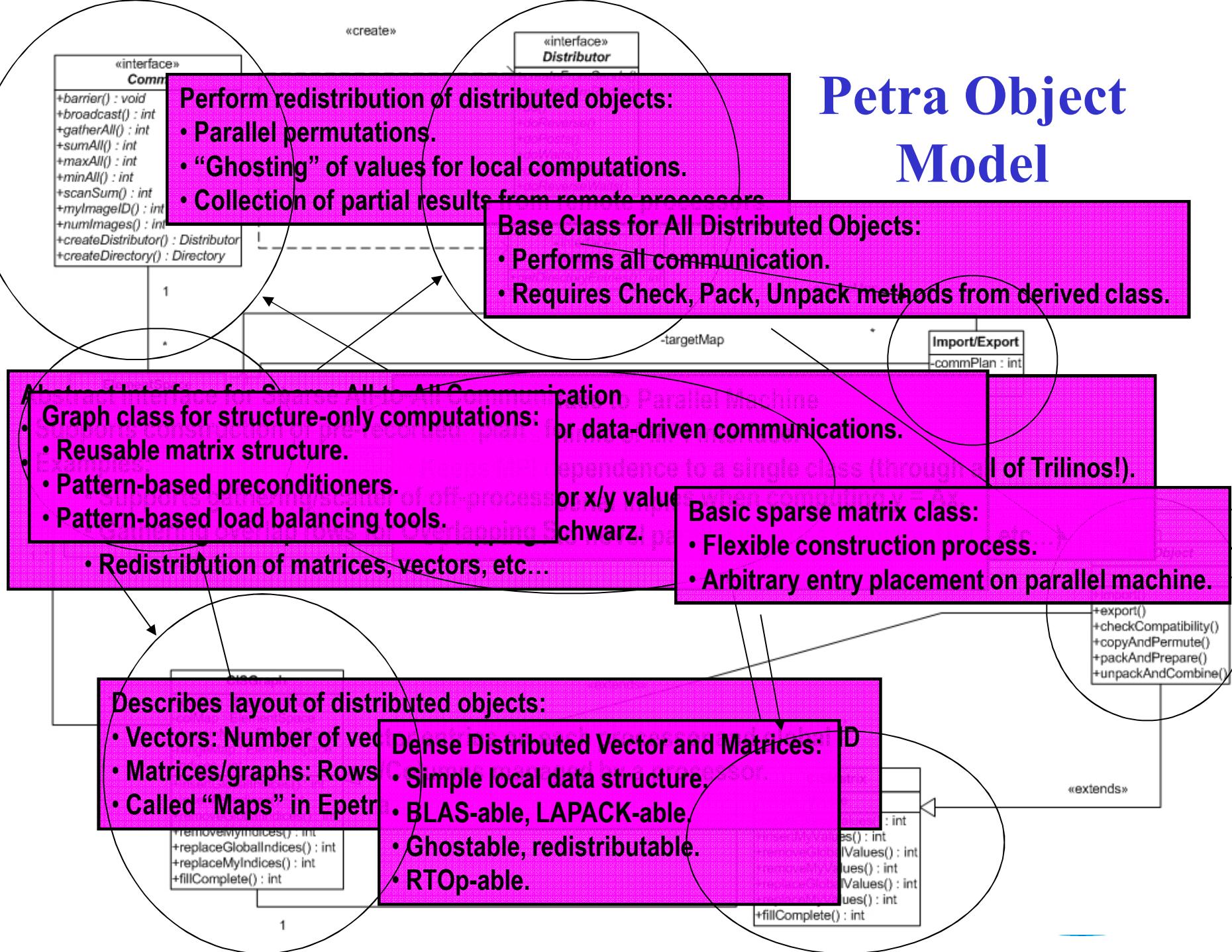
// ***** Create Linear Problem *****
Epetra_LinearProblem problem(&A, &x, &b);

// ***** Create/define AztecOO instance, solve *****
AztecOO solver(problem);
solver.SetAztecOption(AZ_precond, AZ_Jacobi);
solver.Iterate(1000, 1.0E-8);

// ***** Report results, finish *****
cout << "Solver performed " << solver.NumIters()
    << " iterations." << endl
    << "Norm of true residual = "
    << solver.TrueResidual()
    << endl;

return 0;
}
```

Petra Object Model



A Map describes a data distribution

- A Map...
 - ◆ has a Comm(unicator)
 - ◆ is like a vector space
 - ◆ assigns entries of a data structure to (MPI) processes
- Global vs. local indices
 - ◆ You care about global indices (independent of # processes)
 - ◆ Computational kernels care about local indices
 - ◆ A Map “maps” between them
- Parallel data redistribution = function betw. 2 Maps
 - ◆ That function is a “communication pattern”
 - ◆ {E,T}petra let you precompute (expensive) & apply (cheaper) that pattern repeatedly to different vectors, matrices, etc.

1-to-1 Maps

- A Map is 1-to-1 if...
 - ◆ Each global index appears only once in the Map
 - ◆ (and is thus associated with only a single process)
- For data redistribution, {E,T}petra cares whether source or target Map is 1-to-1
 - ◆ “Import”: source is 1-to-1
 - ◆ “Export”: target is 1-to-1
- This (slightly) constraints Maps of a matrix:
 - ◆ Domain Map must be 1-to-1
 - ◆ Range Map must be 1-to-1

2D Objects: Four Maps

- Epetra 2D objects: graphs and matrices

Typically a 1-to-1 map

Typically NOT a 1-to-1 map

- Have four maps:

- ◆ **Row Map:** On each process, the global IDs of the **rows** that process will “manage.”
- ◆ **Column Map:** On each processor, the global IDs of the **columns** that process will “manage.”
- ◆ **Domain Map:** The layout of domain objects (the x (multi)vector in $y = Ax$).
- ◆ **Range Map:** The layout of range objects (the y (multi)vector in $y = Ax$).

Must be 1-to-1 maps!!!

Sample Problem

$$\begin{matrix} \mathbf{y} \\ \left[\begin{matrix} y_1 \\ y_2 \\ y_3 \end{matrix} \right] \end{matrix} = \begin{matrix} \mathbf{A} \\ \left[\begin{matrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{matrix} \right] \end{matrix} \begin{matrix} \mathbf{x} \\ \left[\begin{matrix} x_1 \\ x_2 \\ x_3 \end{matrix} \right] \end{matrix}$$

Case 1: Standard Approach

- ◆ First 2 rows of A , elements of y and elements of x , kept on PE 0.
- ◆ Last row of A , element of y and element of x , kept on PE 1.

PE 0 Contents

$$y = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}, \dots A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \end{bmatrix}, \dots x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

- Row Map = {0, 1}
- Column Map = {0, 1, 2}
- Domain Map = {0, 1}
- Range Map = {0, 1}

PE 1 Contents

$$y = [y_3], \dots A = [0 \quad -1 \quad 2], \dots x = [x_3]$$

- Row Map = {2}
- Column Map = {1, 2}
- Domain Map = {2}
- Range Map = {2}

Original Problem

$$y \quad A \quad x$$
$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

Notes:

- Rows are wholly owned.
- Row Map = Domain = Range (all 1-to-1).
- Column Map is NOT 1-to-1.
- Call to fillComplete: `A.fillComplete(); // Assumes`

Case 2: Twist 1

- First 2 rows of A , first element of y and last 2 elements of x , kept on PE 0.
- Last row of A , last 2 element of y and first element of x , kept on PE 1.

PE 0 Contents

$$y = [y_1], \dots, A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \end{bmatrix}, \dots, x = \begin{bmatrix} x_2 \\ x_3 \end{bmatrix}$$

PE 1 Contents

$$y = [y_2, y_3], \dots, A = [0 \quad -1 \quad 2], \dots, x = [x_1]$$

- Row Map = {0, 1}
- Column Map = {0, 1, 2}
- Domain Map = {1, 2}
- Range Map = {0}

- Row Map = {2}
- Column Map = {1, 2}
- Domain Map = {0}
- Range Map = {1, 2}

Notes:

- Rows are wholly owned.
- Row Map NOT = Domain Map
NOT = Range Map (all 1-to-1).
- Column Map NOT 1-to-1.
- Call to fillComplete:
A.fillComplete(domainMap, rangeMap);

Original Problem

$$y = A x$$

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

Case 2: Twist 2

- First row of A , part of second row of A , first element of y and last 2 elements of x , kept on PE 0.
- Last row, part of second row of A , last 2 element of y and first element of x , kept on PE 1.

PE 0 Contents

$$y = [y_1], \dots, A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 1 & 0 \end{bmatrix}, \dots, x = \begin{bmatrix} x_2 \\ x_3 \end{bmatrix}$$

PE 1 Contents

$$y = [y_2, y_3], \dots, A = \begin{bmatrix} 0 & 1 & -1 \\ 0 & -1 & 2 \end{bmatrix}, \dots, x = [x_1]$$

- Row Map = {0, 1}
- Column Map = {0, 1}
- Domain Map = {1, 2}
- Range Map = {0}

- Row Map = {1, 2}
- Column Map = {1, 2}
- Domain Map = {0}
- Range Map = {1, 2}

Original Problem

$$y = [y_1, y_2, y_3] \quad A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \quad x = [x_1, x_2, x_3]$$

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

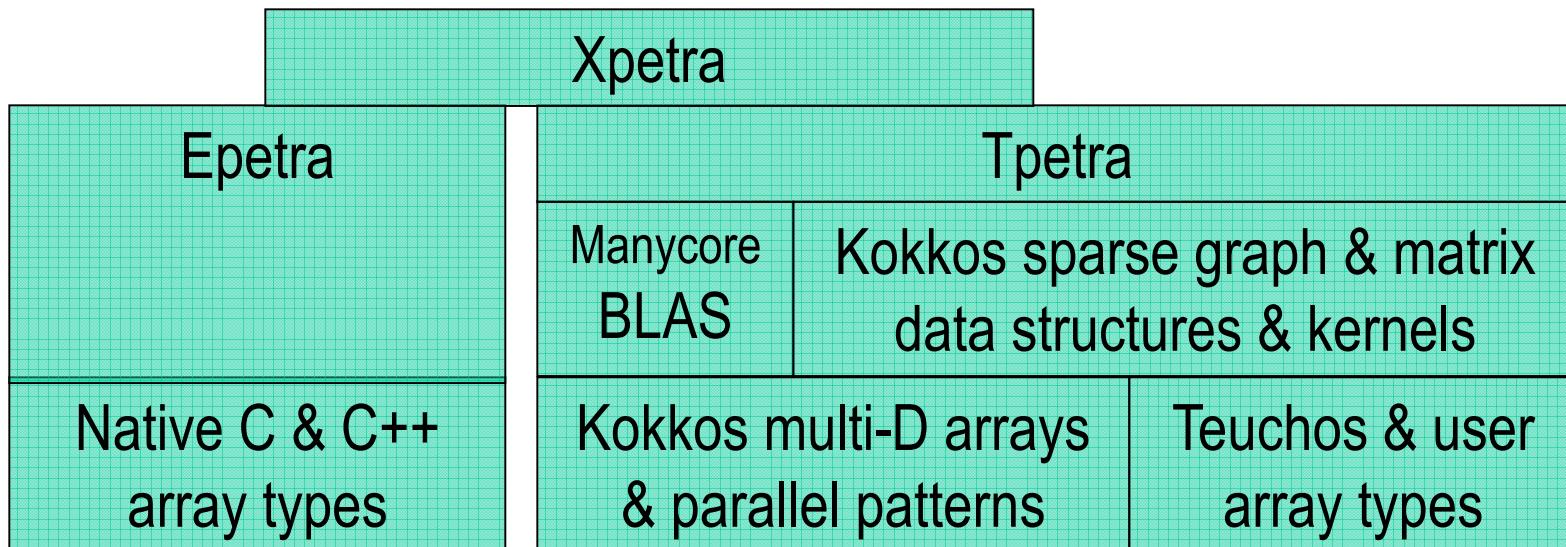
Notes:

- Rows are NOT wholly owned.
- Row Map NOT = Domain Map
NOT = Range Map (all 1-to-1).
- Row Map and Column Map NOT 1-to-1.
- Call to fillComplete:
A.fillComplete(domainMap, rangeMap);

What does fillComplete do?

- Signals you're done
 - ◆ Defining graph structure of the matrix
 - ◆ Modifying the matrix's values
- Creates communication patterns for distributed sparse matrix-vector multiply:
 - ◆ If Column Map \neq Domain Map, create Import
 - ◆ If Row Map \neq Range Map, create Export
- A few rules:
 - ◆ Non-square matrices will *always* require:
`A.fillComplete(domainMap, rangeMap);`
 - ◆ Domain Map & Range Map *must be 1-to-1*

Data Classes Stacks



Classic Stack

New Stack



Questions?