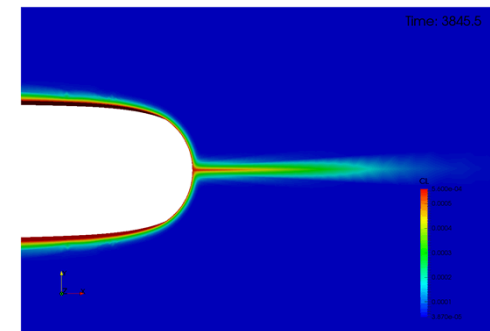
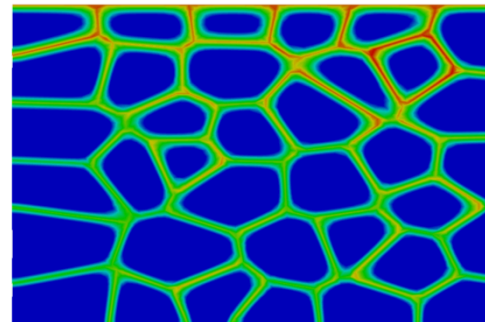
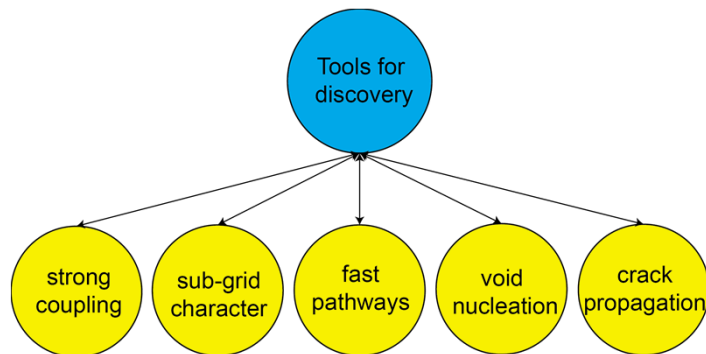


Exceptional service in the national interest



Simulating hydrogen embrittlement and fast pathways for diffusion

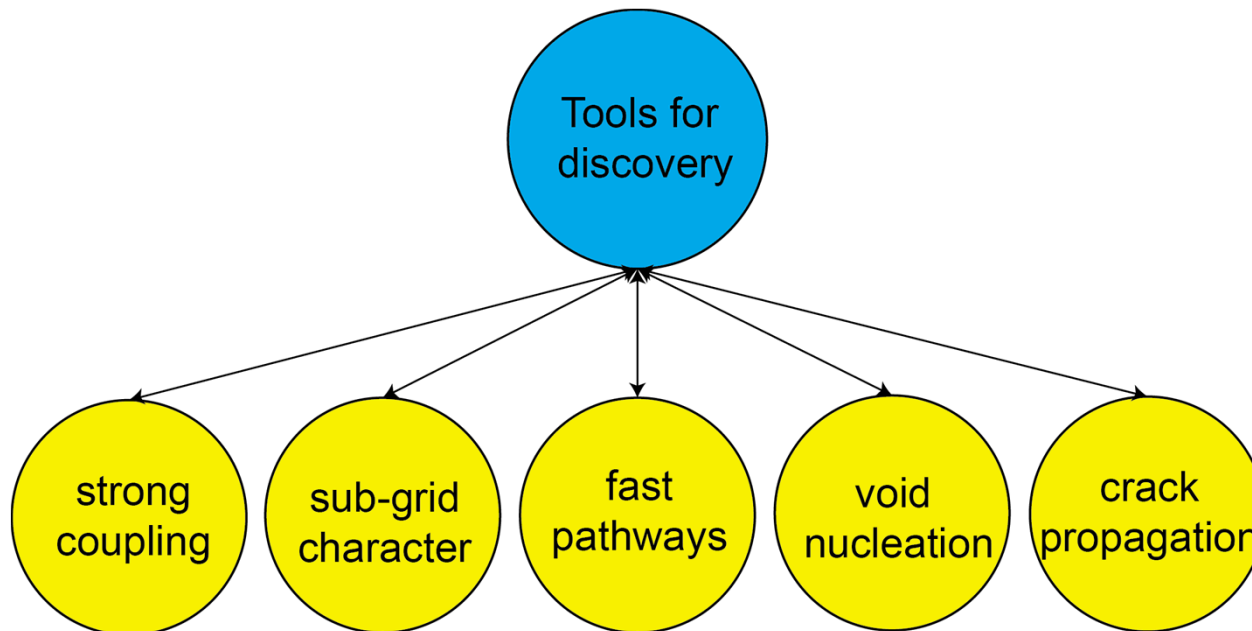
J. Foulk III, J. Ostien, A. Mota, Steve Sun, Guy Bergel, Gabriel de Frias

Collaborators: Bill Wolfer, C. San Marchi, B. Somerday

October 27, 2016

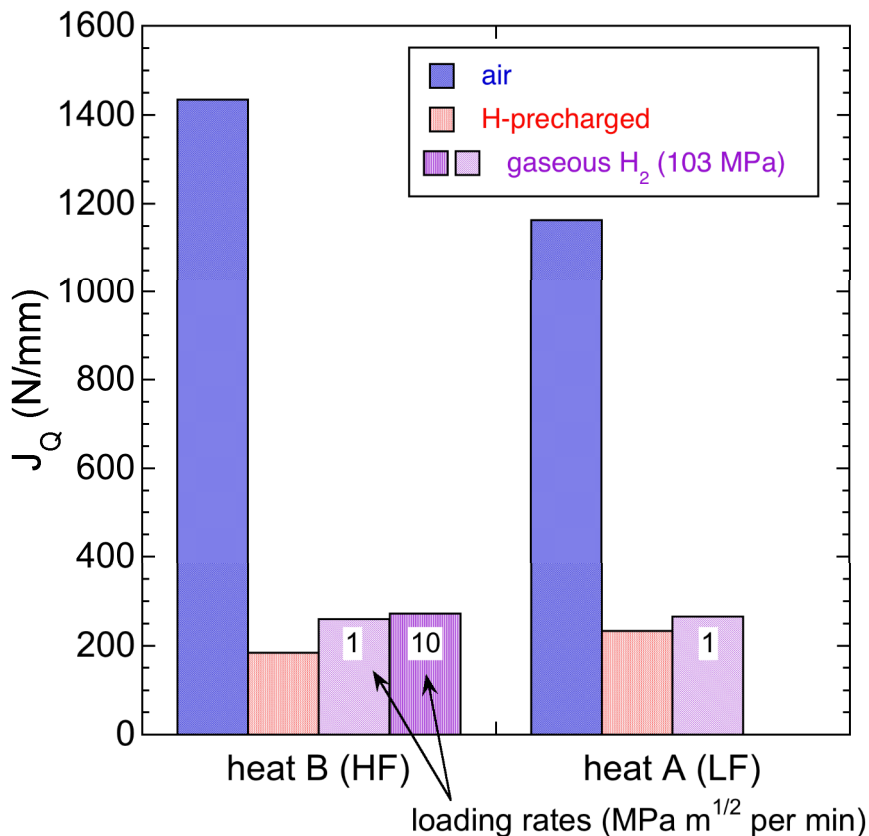
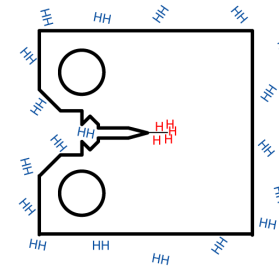
Tools for discovery and prediction

- Motivated through observation
- Strong chemo-mechanical coupling
- Capture sub-grid processes through a surface approach
- Explore fast pathways for diffusion at structural and microstructural scales
- Develop models for H/T/He embrittlement w/focus on void nucleation
- Demonstrate crack initiation and propagation via the SFC

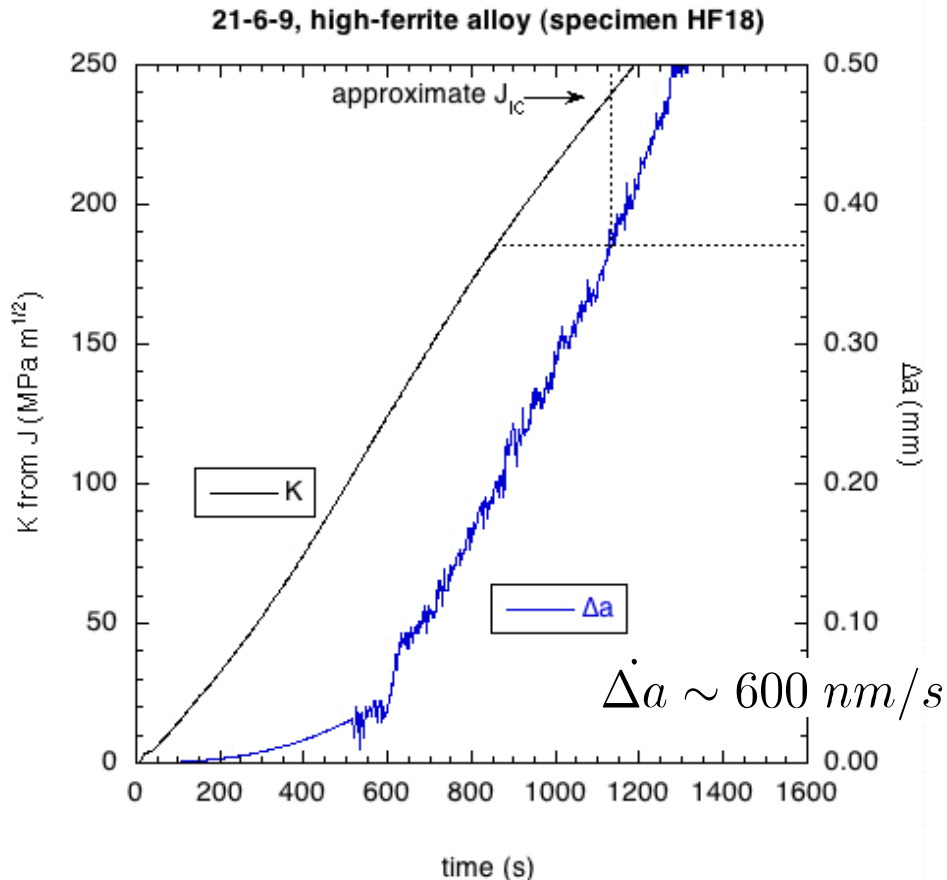


Initial studies in 21Cr-6Ni-9Mn SS

- Compact tension specimens, B ~ 13 mm; W ~ 26 mm
- Constant pressure of gaseous hydrogen: 103 MPa
- “Loading rates” ~ 0.6 - 10 MPa m^{1/2} per minute



Note: 220 MPa m^{1/2} = 224 kJ/m² (N/mm)



(C. San Marchi, SNL)

Aging of stainless steels in H isotopes

- Fracture toughness degrades with increasing helium concentrations
- Both tritium and helium are requisite for degradation
- Transition from void evolution to fracture along twin and grain boundaries

Morgan and Tosten, Tritium and decay helium effects on the fracture toughness, International Conference on Hydrogen (1994)

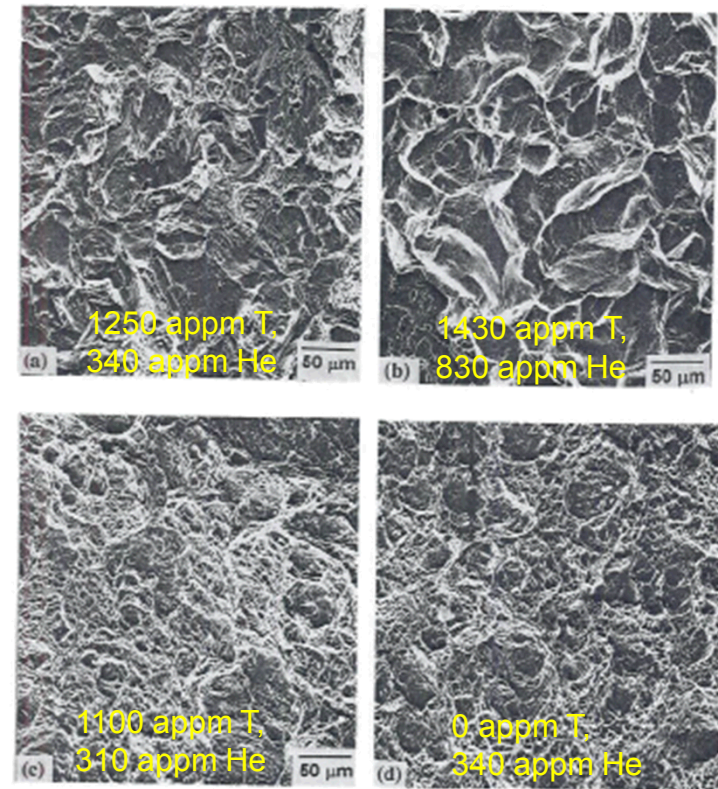
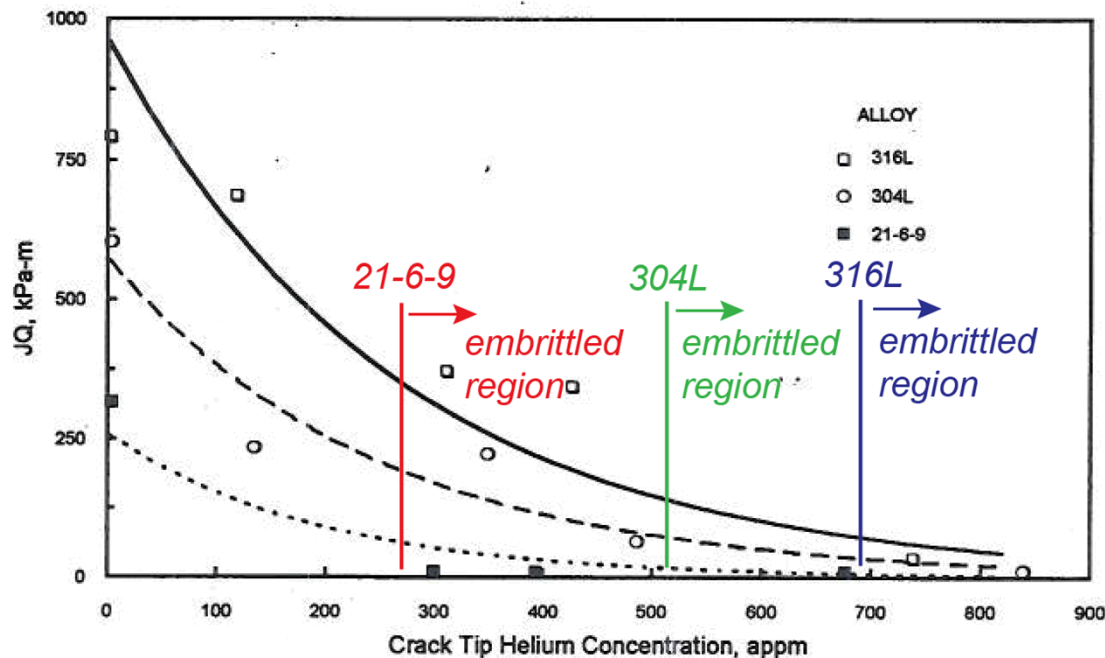


Figure 4 - Fracture Modes In Tritium-Exposed-And-Aged Stainless Steels: (a) Type 304L, 1250 Tritium, 340 appm He; (b) Type 304L, 1430 Appm Tritium, 830 appm He; (c) Type 316L Steel 1100 appm Tritium 310 appm He; (d) Type 304L, Tritium Degassed, ~0 appm T, 340 appm He.

Finite deformation diffusion of H

This path heavily leverages Sofronis/McMeeking (1989)* and Krom (1998).
Recent work by Leo and Anand (2013).

Transport of hydrogen in the current configuration

$$D^* \dot{c}_l + C^* \operatorname{div} \mathbf{v} - \nabla_{\mathbf{x}} \cdot \mathbf{d}_l \nabla_{\mathbf{x}} c_l - \nabla_{\mathbf{x}} \cdot \frac{c_l}{J} \mathbf{d}_l \nabla_{\mathbf{x}} J + \nabla_{\mathbf{x}} \cdot \frac{c_l V_H}{RT} \mathbf{d}_l \nabla_{\mathbf{x}} \tau_h + \frac{\theta_l}{J} \frac{\partial N_T}{\partial \epsilon_p} \dot{\epsilon}_p - \frac{\theta_t N_T}{J^2} \dot{J} = 0$$

Transport of hydrogen in the reference configuration (push back)

$$D^* \dot{C}_L - \nabla_{\mathbf{X}} \cdot \mathbf{d}_l \mathbf{C}^{-1} \nabla_{\mathbf{X}} C_L + \nabla_{\mathbf{X}} \cdot \frac{d_l V_H}{RT} \mathbf{C}^{-1} \nabla_{\mathbf{X}} \tau_h C_L + \theta_T \frac{dN_T}{d\epsilon_p} \dot{\epsilon}_p$$

*transient
term*

*diffusion
term*

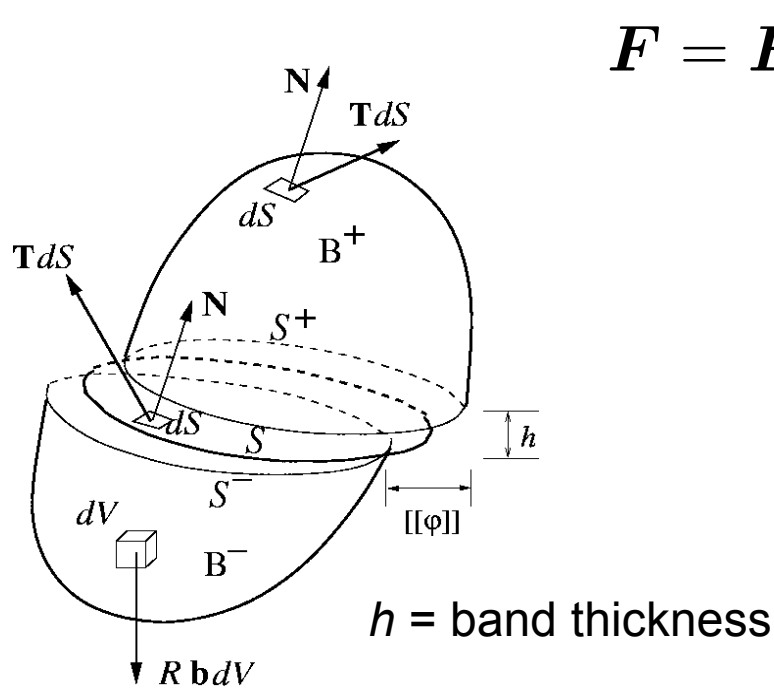
*advection term
from pressure*

*source term
from trapping*

Deformation-dependent diffusivity $\mathbf{D}_L = \mathbf{F}^{-1} \mathbf{d}_l \mathbf{F}^{-T} = \mathbf{d}_l \mathbf{C}^{-1}$

Capture sub-grid processes for R(a)

Goal: Capture sub-grid processes through methods that regularize the jump



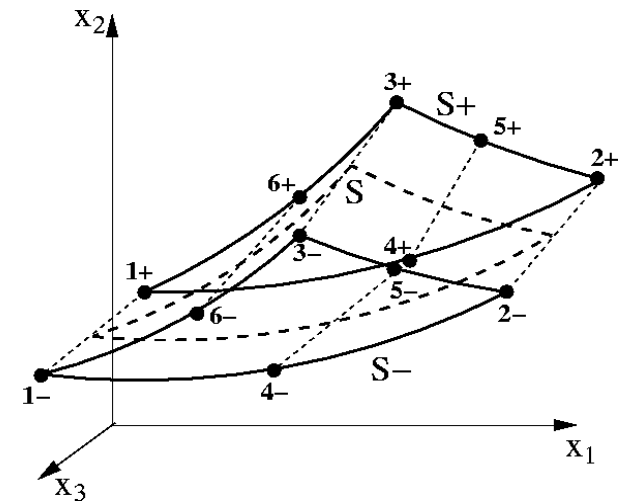
$$\mathbf{F} = \mathbf{F}^{\parallel} \mathbf{F}^{\perp}$$

$$\mathbf{F}^{\parallel} = \mathbf{g}_i \otimes \mathbf{G}^i$$

$$\mathbf{F}^{\perp} = \mathbf{I} + \frac{[[\Phi]]}{h} \otimes \mathbf{N}$$

$$\mathbf{F} = \mathbf{F}^{\parallel} + \frac{[[\varphi]]}{h} \otimes \mathbf{N}$$

- Finite-deformation kinematics
- Simulation of strain localization
- No additional constitutive assumptions



Akin to "cohesive" element

Yang, Mota and Ortiz (IJNME, 2005), Armero and Garikipati (IJSS, 1996)

Extend sub-grid model for multiphysics Sandia National Laboratories

Fox and Simo (1990), Callari, Armero, Abati (2010)

redefine space $\mathbf{X} = \mathbf{\Phi}(\xi^1, \xi^2, \xi^3) = \bar{\mathbf{\Phi}}(\xi^1, \xi^2) + \mathbf{N}(\xi^1, \xi^2)\xi^3$ $G_i = \mathbf{\Phi}_{,i} = \frac{\partial \mathbf{X}}{\partial \xi^i}$

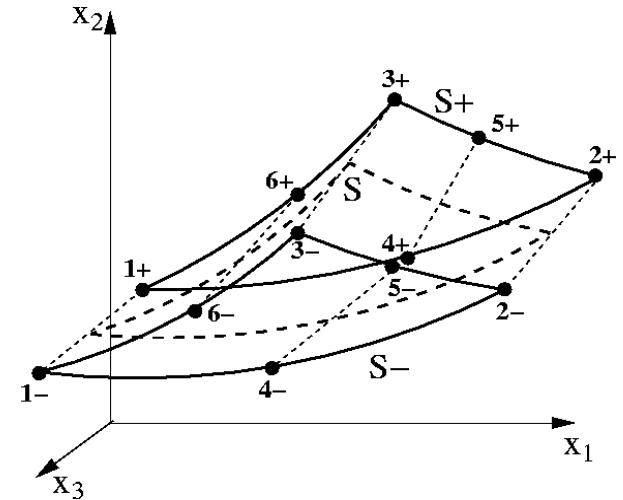
include jump in C $C(\mathbf{X}) = \bar{C}(\phi[\xi^1, \xi^2]) + \frac{[[C]](\phi[\xi^1, \xi^2])}{h}\xi^3$ $\nabla_{\mathbf{X}} C = (\nabla \mathbf{\Phi})^{-T} \frac{\partial C}{\partial \xi^i}$

Finite element implementation is straightforward

$$\nabla_{\mathbf{X}} C|_{\xi^3=0} = [B] \begin{bmatrix} \{C\}^+ \\ \{C\}^- \end{bmatrix} = \begin{bmatrix} [B]^+ & [B]^- \end{bmatrix} \begin{bmatrix} \{C\}^+ \\ \{C\}^- \end{bmatrix}$$

$$B_{ia}^{\pm} = [G_i^1 \quad G_i^2 \quad G_i^3] \cdot \left[\frac{1}{2} \frac{\partial N_a}{\partial \xi^1} \quad \frac{1}{2} \frac{\partial N_a}{\partial \xi^2} \quad \pm \frac{1}{h} N_a \right]$$

$i = \# \text{ dimensions}, a = \# \text{ nodes}$



Given this gradient operator, we can use the same PDE for finite-deformation diffusion

$$D^* \dot{C}_L - \nabla_{\mathbf{X}} \cdot d_l \mathbf{C}^{-1} \nabla_{\mathbf{X}} C_L + \nabla_{\mathbf{X}} \cdot \frac{d_l V_H}{RT} \mathbf{C}^{-1} \nabla_{\mathbf{X}} \tau_h C_L + \theta_T \frac{dN_T}{d\epsilon_p} \dot{\epsilon}_p$$

Simple channel w/fast pathway

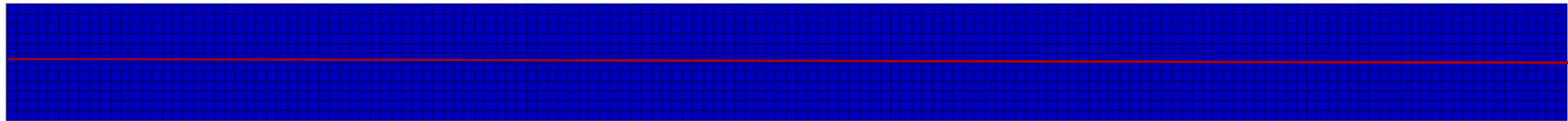
Implementation of fast pathway (no deformation):

$$\int_{\mathcal{B}^G} \nabla_{\mathbf{X}} v D_L(\mathbf{X}) \nabla_{\mathbf{X}} C \, dV \approx h \sum_{j=1}^{N_{\text{int}}^M} \overline{W}(\xi_j^1, \xi_j^2) \begin{bmatrix} v_a^+(\xi_j^1, \xi_j^2) & v_a^-(\xi_j^1, \xi_j^2) \end{bmatrix} \begin{bmatrix} \vec{B}^+(\xi_j^1, \xi_j^2) \\ \vec{B}^-(\xi_j^1, \xi_j^2) \end{bmatrix} D_L(\mathbf{X})$$

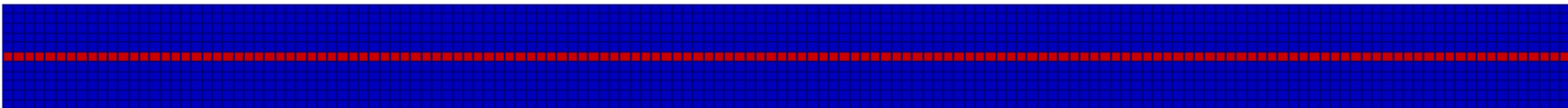
$$\begin{bmatrix} \vec{B}^+(\xi_j^1, \xi_j^2) & \vec{B}^-(\xi_j^1, \xi_j^2) \end{bmatrix} \begin{bmatrix} C_a^+ \\ C_a^- \end{bmatrix}$$

(\)

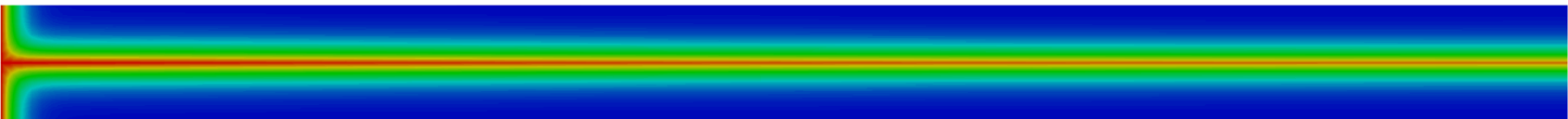
Surface fast pathway



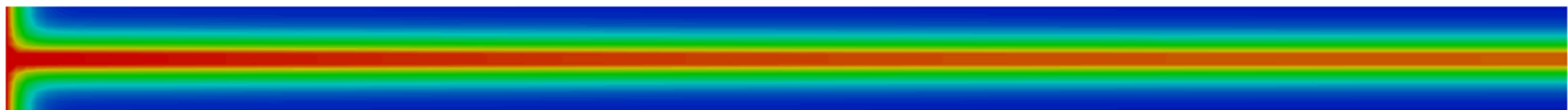
Channel fast pathway



Surface fast pathway, $10^5 D_0$



Channel fast pathway, , $10^5 D_0$

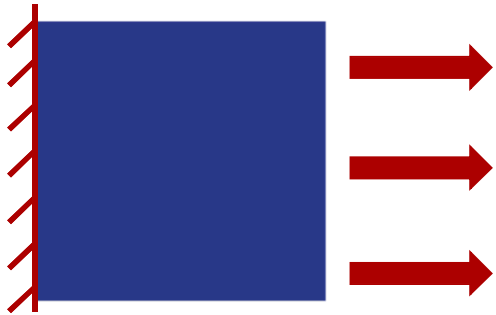


CL



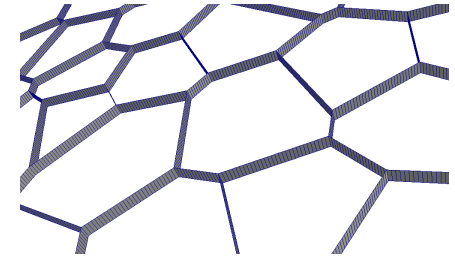
Polycrystals with fast pathway

Grain interface diffusion coupled with mechanical loading:

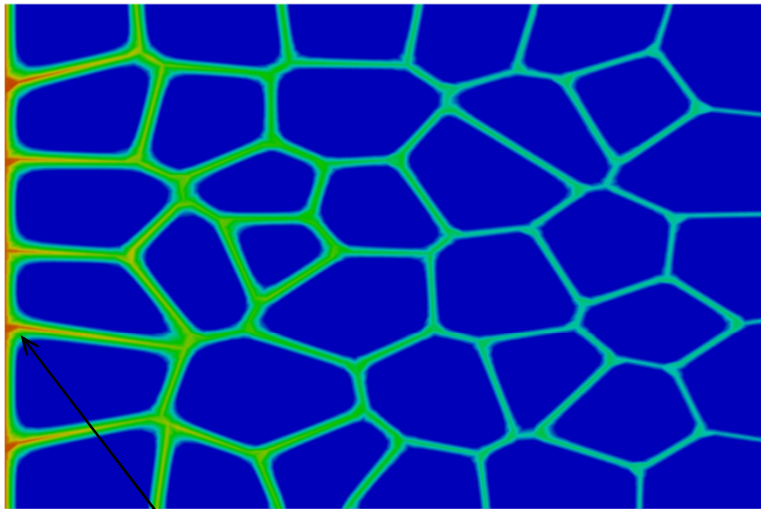


- Stretched in horizontal direction
- Fast pathway = $10^5 D_0$
- Horizontal diffusion
- Vertical diffusion

$$D_L = F^{-1} d_l F^{-T} = d_l C^{-1}$$

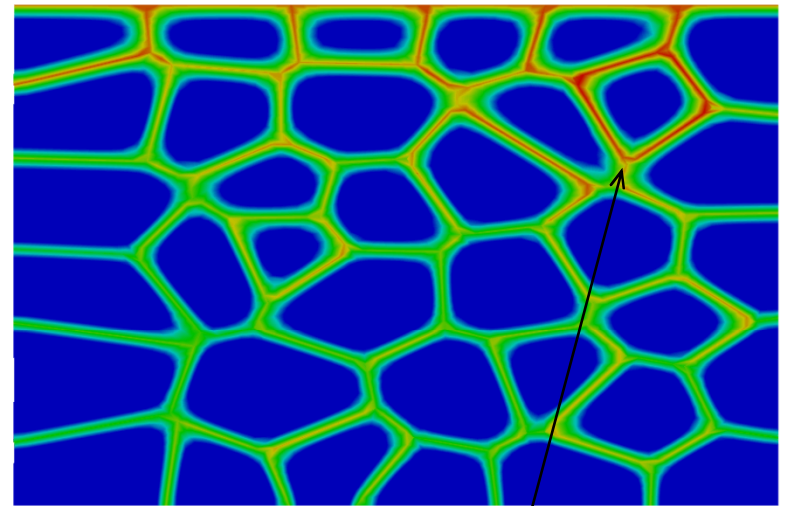


Horizontal diffusion



Diffusion slows down due to increasing length.

Vertical diffusion

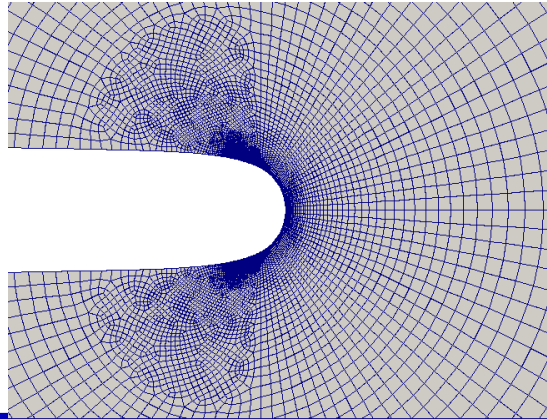


Diffusion speeds due to decreasing length

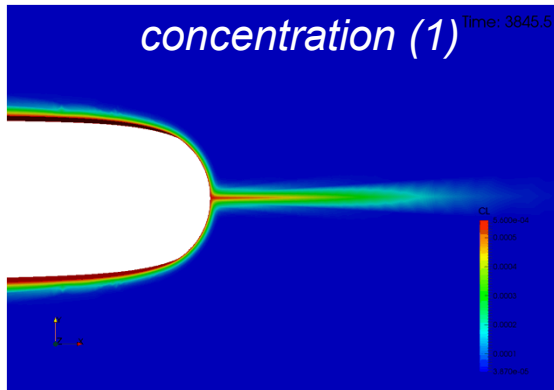
Solving 5 fields simultaneously

Units are scaled in the balance of linear momentum, conservation of concentration, and L_2 projection to improve condition number of the system

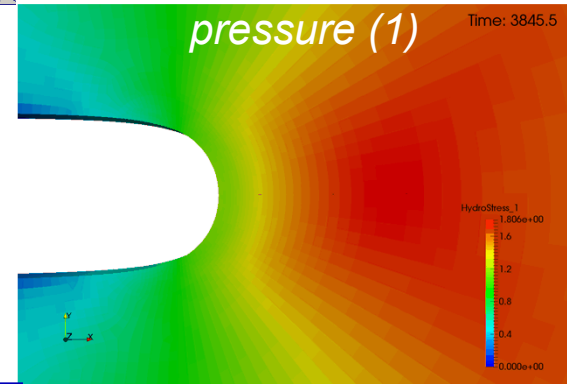
$$D^* \dot{C}_L$$



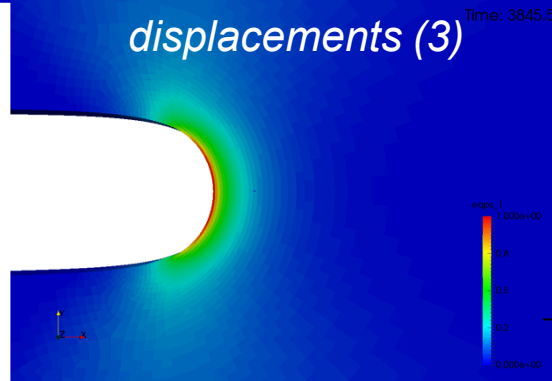
<https://software.sandia.gov/albany/>



- Path: $10^5 D_0$
- K_{app} : 85 MPa $m^{1/2}$
- Time: 3850 s



$$\nabla_{\mathbf{X}} \cdot d_l \mathbf{C}^{-1} \nabla_{\mathbf{X}} C_L$$

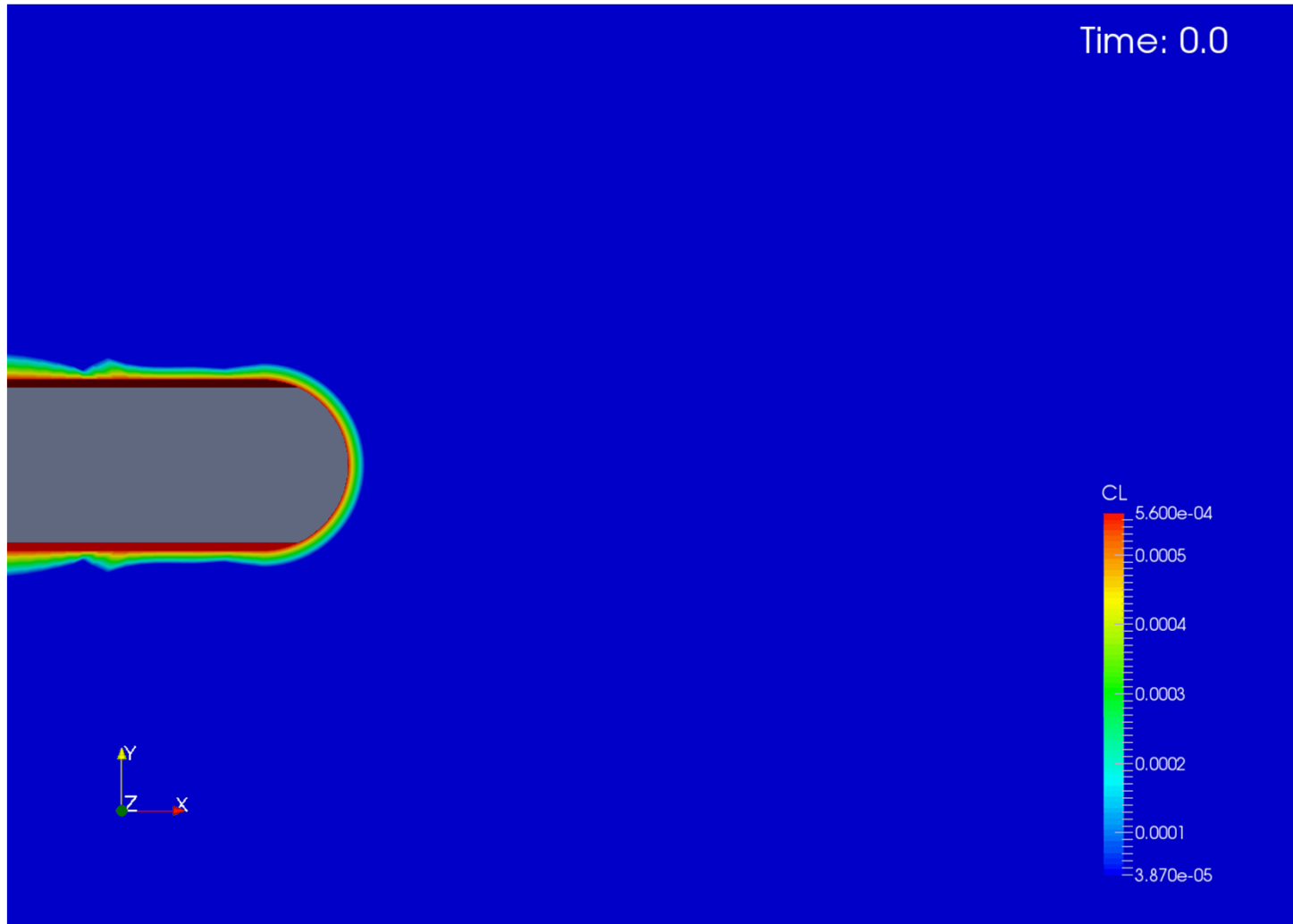


$$\nabla_{\mathbf{X}} \cdot \frac{d_l V_H}{RT} \mathbf{C}^{-1} \nabla_{\mathbf{X}} \tau_h C_L$$

NOTE: 85 MPa $m^{1/2}$ is well below J_Q for 21Cr-6Ni-9Mn (220 MPa $m^{1/2}$)

$$+ \theta_T \frac{dN_T}{d\epsilon_p} \dot{\epsilon}_p$$

Evolution of concentration at crack tip



H isotope diffusion w/ He bubbles

We seek to find descriptors of helium bubble formation that result from the radioactive decay of tritium (T) to He.

- Schaldach and Wolfer (2004) focus on the total number of clusters (total bubble density)

1000s of ODEs for helium clusters are condensed into 3 coupled ODEs written in

- Single He (monomers) N_1 , total bubble density, N_b , and bubble volume fraction S_b
- ODEs are nonlinear. We can integrate them implicitly with Newton's method
- Chemo-mechanical solution (T , \mathbf{u}). Solve ODEs (dependent on T) at integration points.

$$\frac{dN_1}{dt} = G(t) - 16\pi(r_1 + r_1)DN_1^2 - 4\pi DN_1 \left(\frac{3}{4\pi}\right)^{\frac{1}{3}} S_b^{\frac{1}{3}} N_b^{\frac{2}{3}}$$

$$\frac{dN_b}{dt} = 8\pi(r_1 + r_1)DN_1^2$$

$$\frac{\eta}{\Omega} \frac{dS_b}{dt} = 16\pi(r_1 + r_1)DN_1^2 + 4\pi DN_1 \left(\frac{3}{4\pi}\right)^{\frac{1}{3}} S_b^{\frac{1}{3}} N_b^{\frac{2}{3}}$$

$$C_{He} = N_1 + \left(\frac{\eta}{\Omega}\right) S_b$$

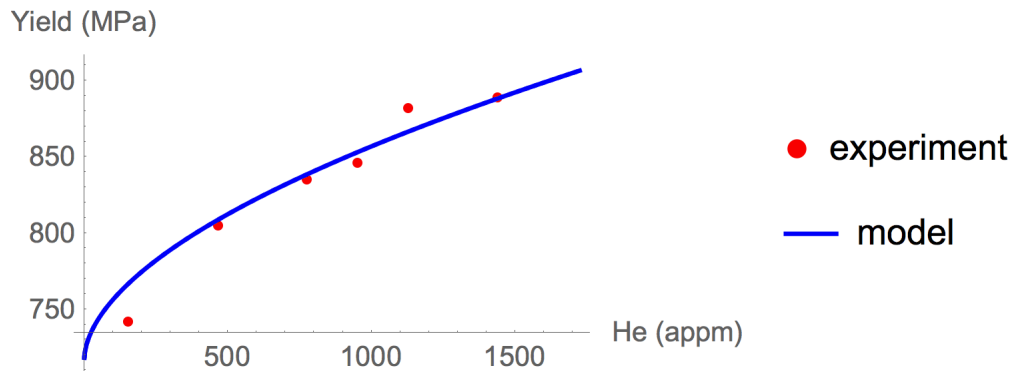
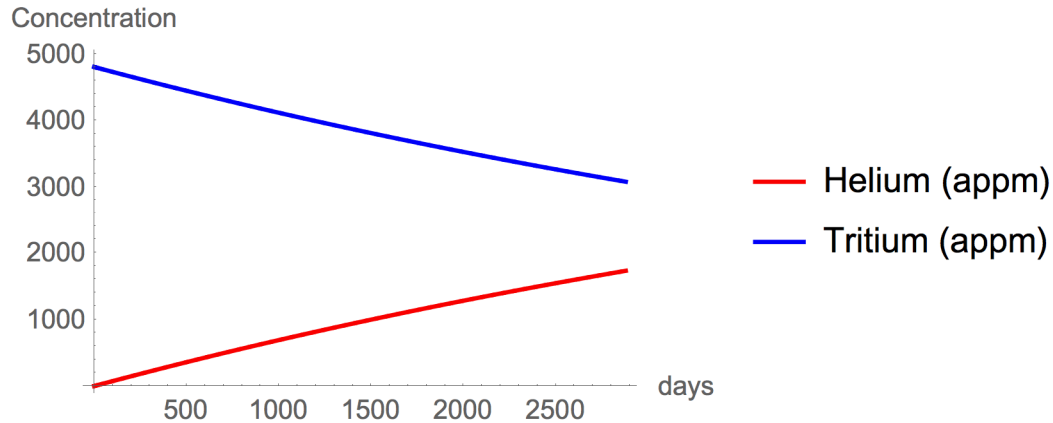
$G(t)$ – helium source term

r_1 - initial bubble radius

η - number of He atoms/vacant site

Ω - partial molar volume

Effects of tritium & helium on yield



Comparison of current model to experimental data by Robinson and Thomas (1991). Data from hydrogen yields α_1 (hydrogen = tritium). Nonlinearity in fit stems from average bubble radius, not fitting parameter α_2 . Both parameters are needed to accurately fit Robinson's data.

From helium bubble ODEs, we have:

N_b total bubble density

S_b bubble volume fraction

Calculate average bubble radius:

$$\bar{R}_b = \left(\frac{3S_b}{4\pi N_b} \right)^{\frac{1}{3}}$$

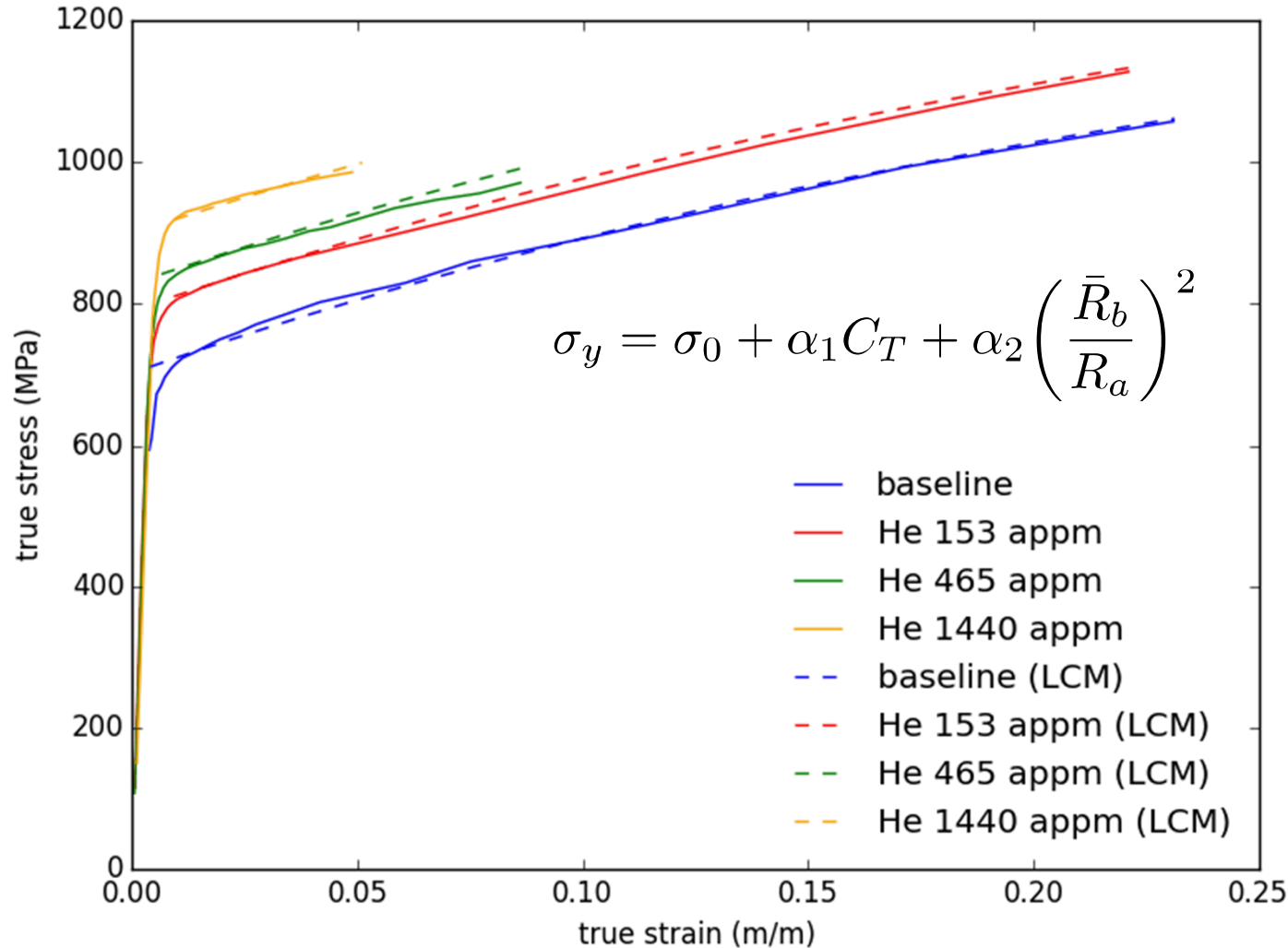
Assumptions for yield stress σ_y :

- Rate independent yield stress σ_0
- Proportional to T concentration, C_T
- Misfit strengthening from He is dominant (Arsenlis, Wolfer, JNM)
- Misfit strengthening varies w/ R_b^2
- Normalize w/He atomic radius R_a

$$\sigma_y = \sigma_0 + \alpha_1 C_T + \alpha_2 \left(\frac{\bar{R}_b}{R_a} \right)^2$$

α_1 and α_2 are constants fit to experiments

Yield dominant in flow behavior



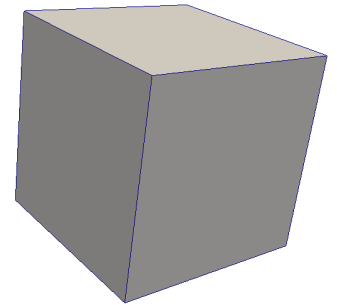
$$\sigma_0 = 710 \text{ MPa}$$

$$H = 0.0149 \mu$$

$$R_d = 3.5$$

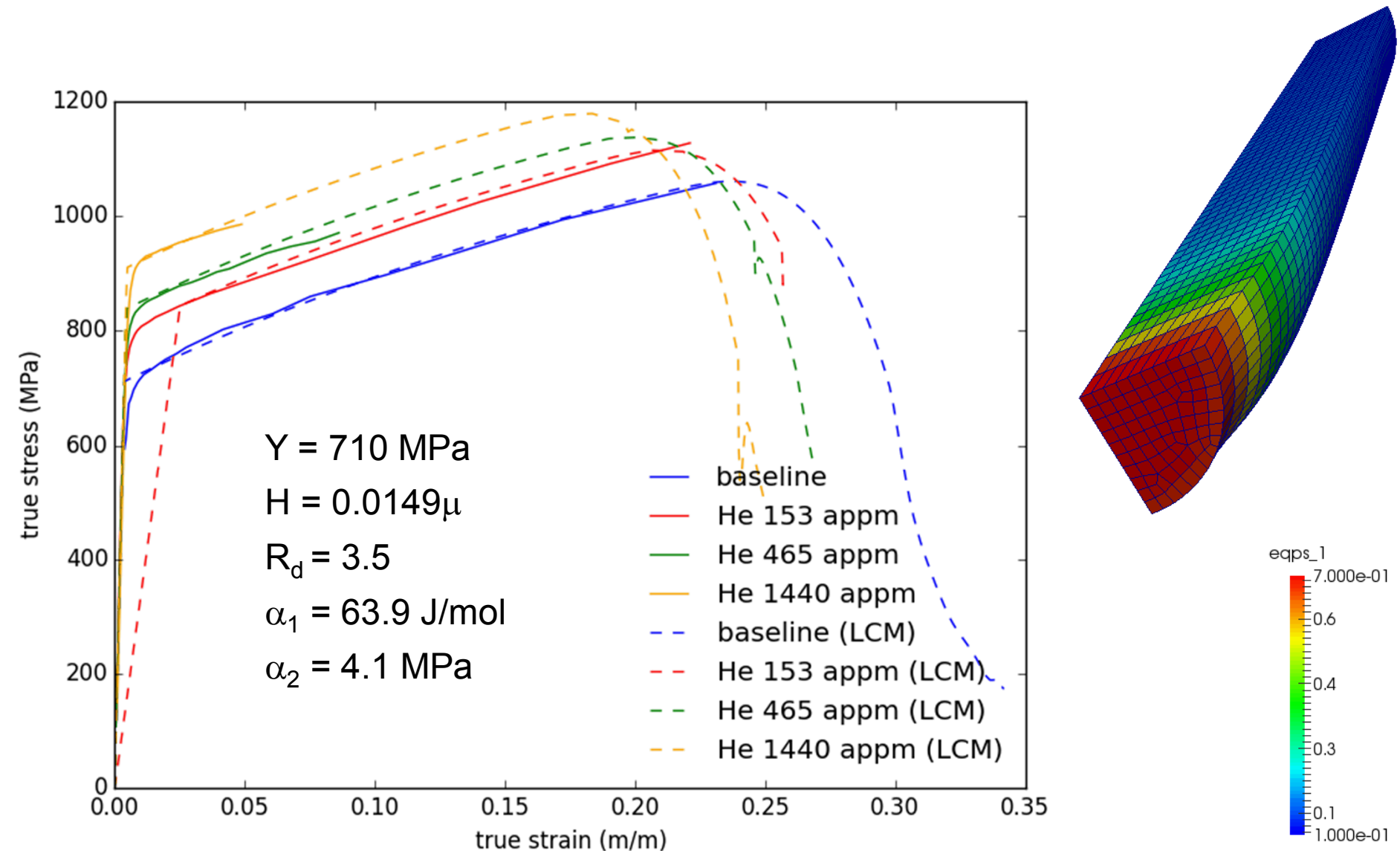
$$\alpha_1 = 63.9 \text{ J/mol}$$

$$\alpha_2 = 4.1 \text{ MPa}$$



From Robinson and Thomas, "Accelerated Fracture due to Tritium and Helium in 21-6-9 Stainless Steel" (1991). *We cannot locate the source data. Missing He concentrations of 774, 950, and 1128 appm.*

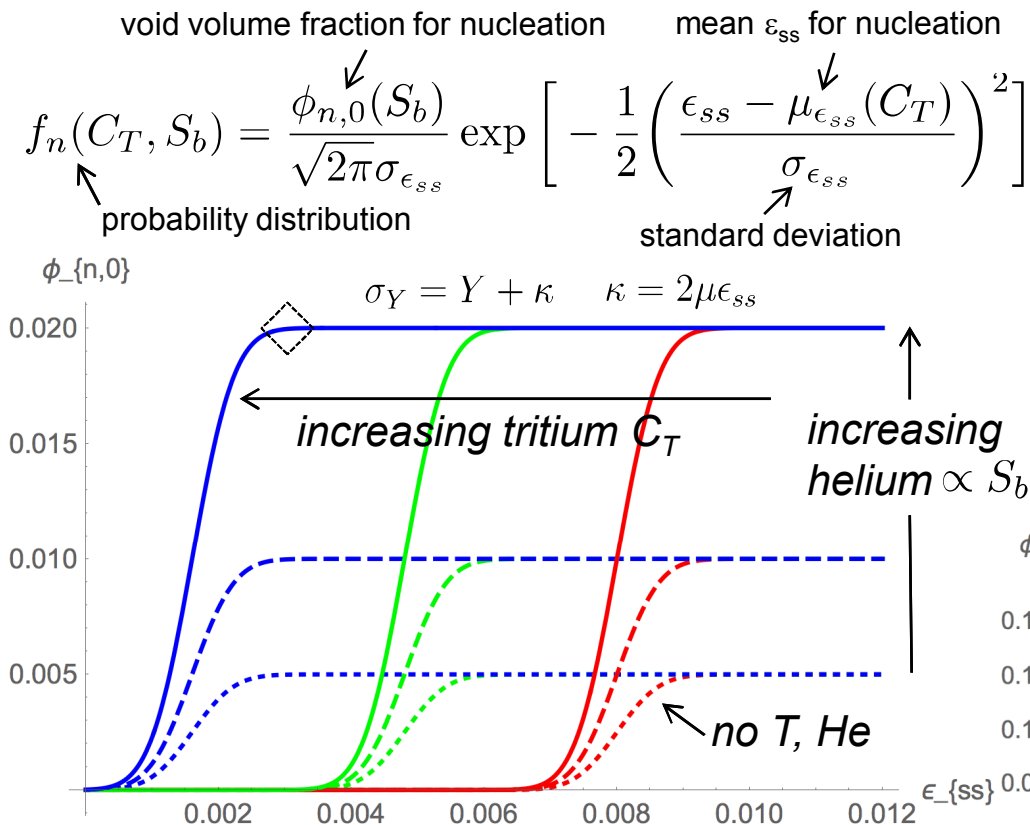
T/He nucleation needed for failure



Model results reduced through volume preservation to create true stress-strain curves.

T/He nucleation, growth, coalescence

In spirit of Chu and Needleman (1980) we choose an appropriate state variable to capture void nucleation through elevated stresses at pile-ups.

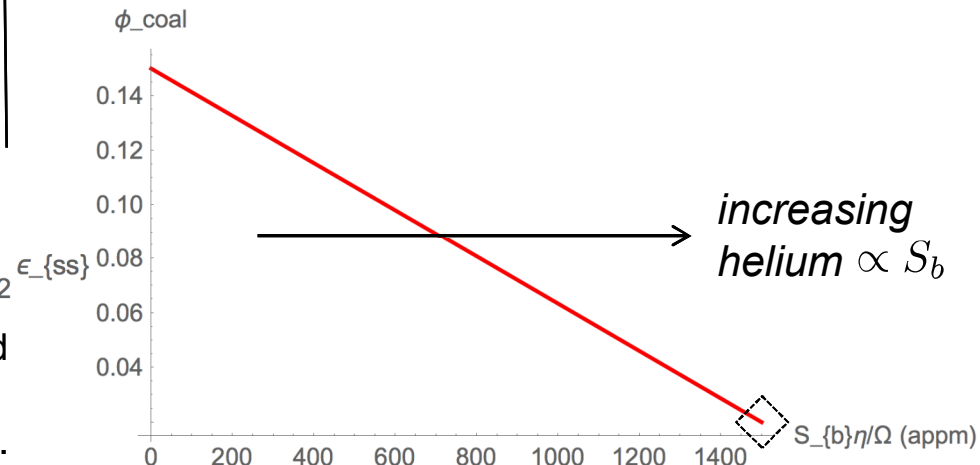


Statistical nucleation: Tritium localizes deformation and enables voids to nucleate earlier in the deformation. Helium-hardened microstructure nucleates more voids.

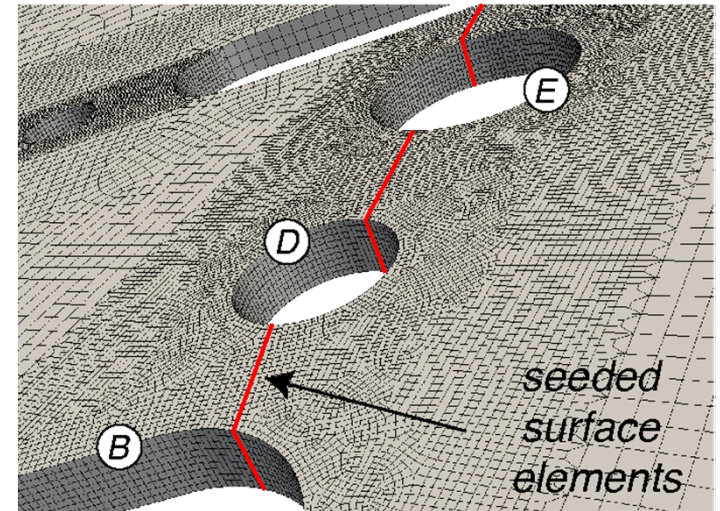
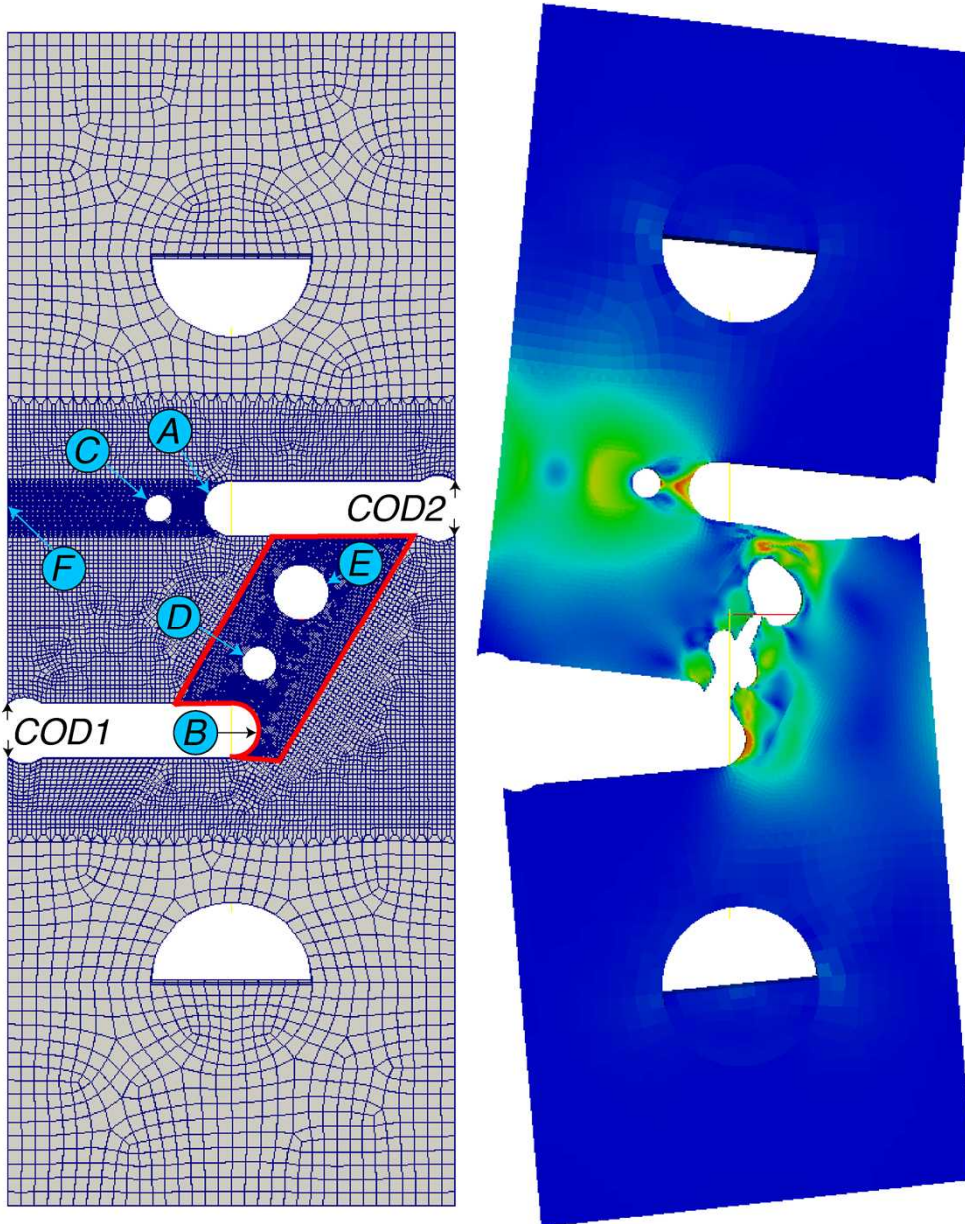
A tritium-embrittled, helium-hardened microstructure can move from nucleation to coalescence

Initial model for void evolution:

- Void nucleation driven by deformation (dislocations, twins) $\propto \epsilon_{ss}$
 - Tritium C_T hastens process
 - Helium amplifies process
- Void growth through Gurson
- Void coalescence governed by S_b
 - Nucleated voids connected by smaller helium bubbles



Crack initiation and growth in SFC

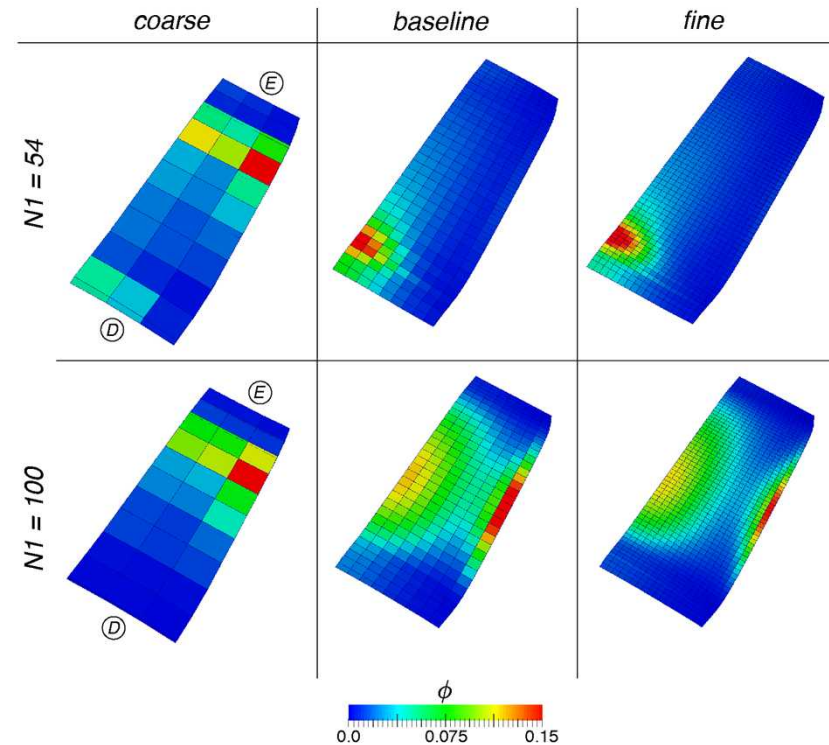
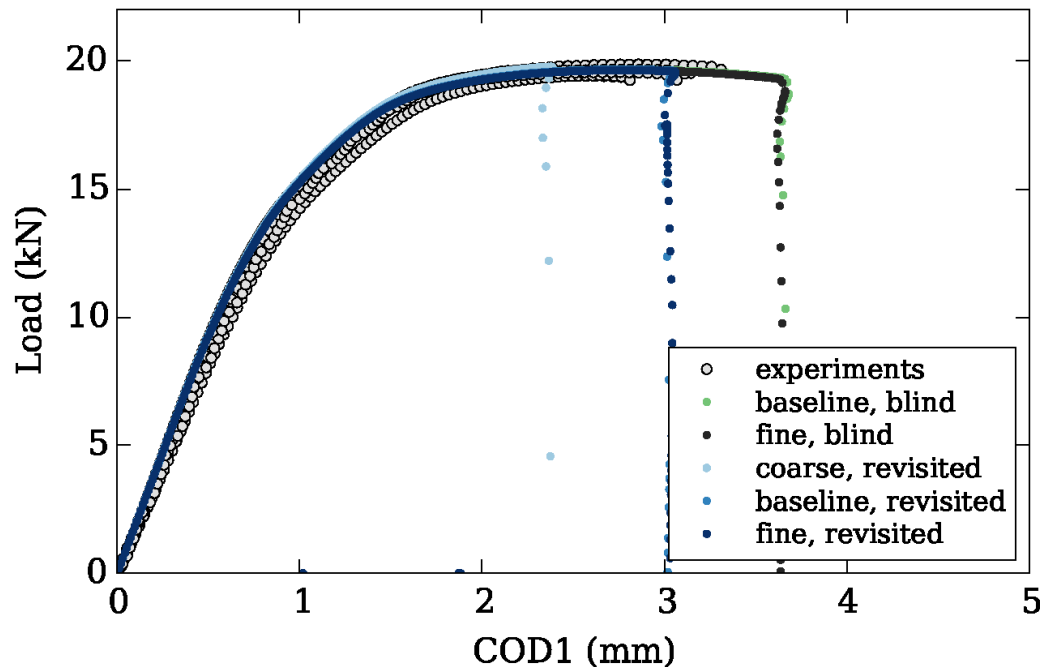


2nd Sandia Fracture Challenge (SFC)

- Ti-6Al-4V plate
- Anisotropy
- Mixed-mode loading
- Slow/fast rates of loading
- Thermomechanical coupling
- Dynamics (unstable propagation)
- Employed surface elements
- Multiple damage models
- Implicit solution
- *Sierra SolidMechanics*

Regularized solution

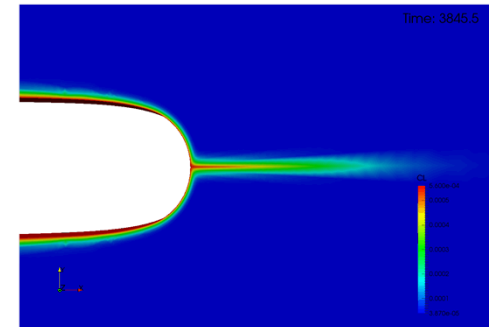
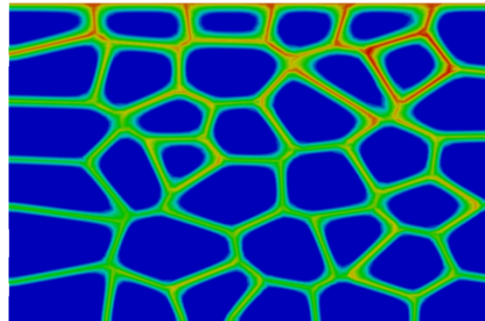
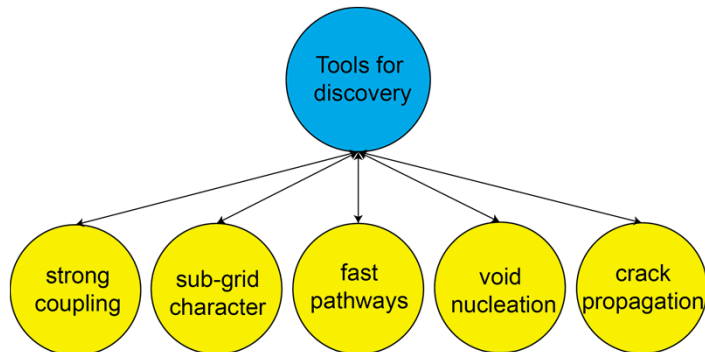
- Localization elements yield convergence in the load displacement curve at slow, isothermal rates
- Constitutive model incorporates anisotropy in yield and shear nucleation in damage evolution



- Convergence in both the far-field and near-field quantities
- Increasing the role of shear nucleation ($N1$) transitions crack initiation from the interior to the surface

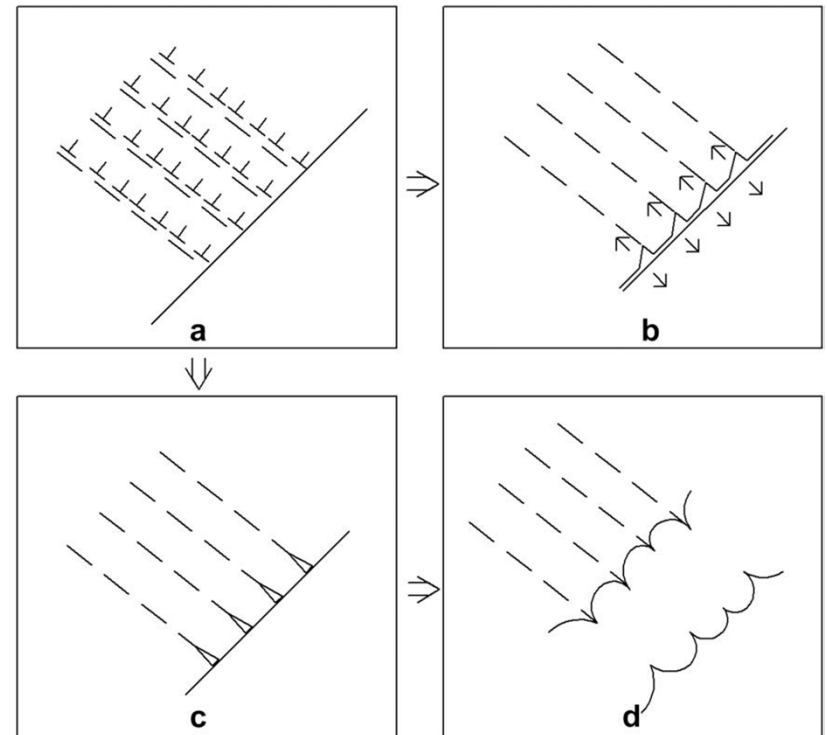
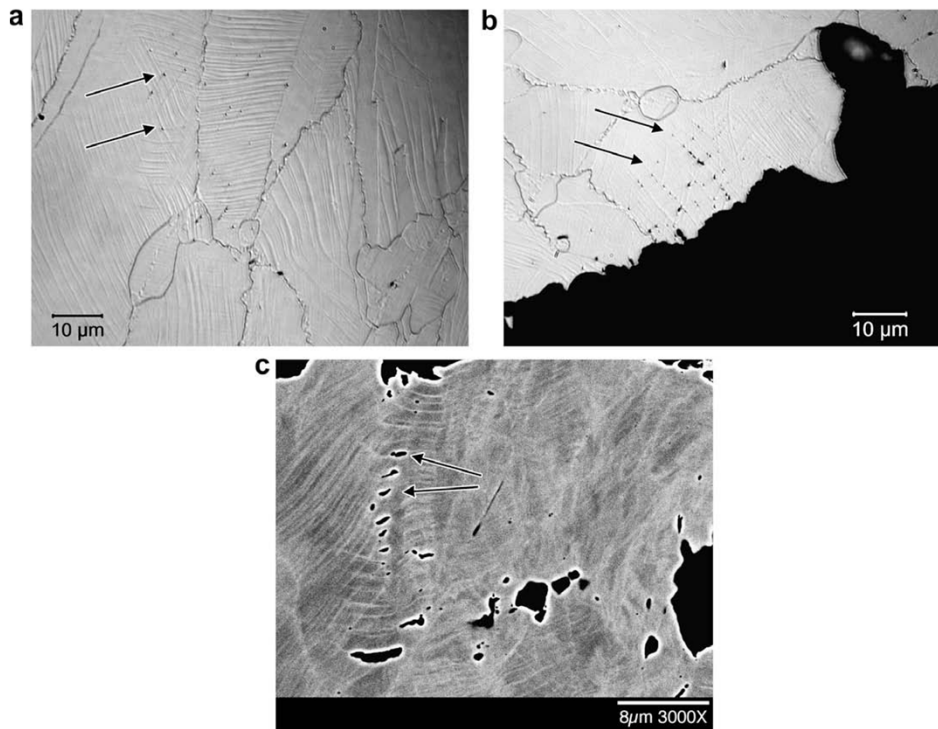
Summary and path forward

- Illustrated strong chemo-mechanical coupling
- Surface approaches capable of capturing multiphysics on multiple scales
- Progress in H/T/He embrittlement w/focus on void nucleation
- SFC illustrates the applicability of approach to H/T/He embrittlement
- Future work will focus on
 - Parameterization of nucleation processes and transition to coalescence
 - Predicting the time-dependent toughness of 21Cr-6-9Mn
 - Transitioning technology from research environment to production



BACKUP SLIDES

Damage nucleation model w/H

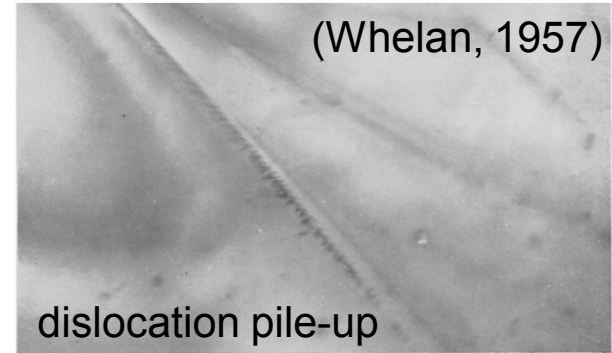
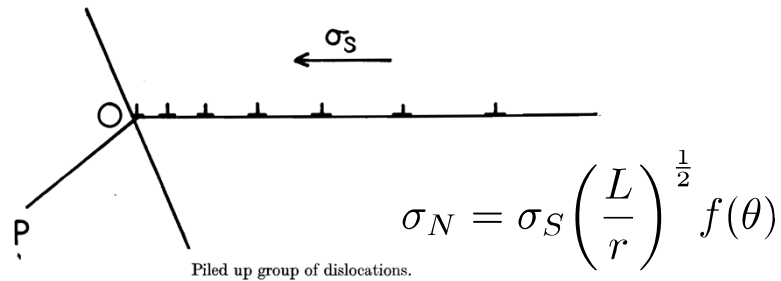


IDEA: Hydrogen enables the premature formation of planar deformation bands that impinge on boundaries of grains, annealing twins, and/or other deformation bands. The stress concentration induced by the intersection may nucleate a void of large aspect ratio (cylinder) that will evolve, coalesce and create the observed “fluted” fracture surface.

The fracture process is still ductile! Need to capture the premature nucleation of voids in the presence of hydrogen. Can we first construct a simple model to aid our intuition?

Analytical basis for nucleation

Stroh, A Theory of the Fracture of Metals, 1957



Using a work argument, the normal stress σ_N for nucleation can be derived from the shear stress σ_S given the fracture energy γ and the number of dislocations n in a pile-up (band) along a boundary.

$$\sigma_{S,crit} = \frac{3\pi^2\gamma}{8n(\rho_{ss}, \theta_T)b} \quad n = A(\theta_T)\rho_{ss} = hs(\theta_T)\rho_{ss} \quad \begin{aligned} \kappa &= \mu\epsilon_{ss} \\ \epsilon_{ss} &= b\sqrt{\rho_{ss}} \end{aligned}$$

Given b is burgers vector and A is an effective area characterized by the grain size h and the pile-up spacing s . We relate the pile-up spacing to the occupancy of hydrogen in the traps θ_T . If we approximate σ_S through the yield stress σ_y and the isotropic hardening variable κ , we can express nucleation in terms of a scalar strain metric ϵ_{ss} that is reflective of the dislocation density ρ_{ss} .

$$\epsilon_{ss,crit}^3 + \frac{\sigma_y}{\mu}\epsilon_{ss,crit} - \frac{3\pi b\gamma}{4hs(\theta_T)\mu} \quad \text{permits analytical solution (1 real root)}$$

If we assume heavily worked materials, $\rho_{ss} \sim 10^{15}$, the specification of $s(\theta_T)$ becomes problematic. We need to construct a simplified model for nucleation in the correct state variable ϵ_{ss} that can capture a statistical sampling of boundary orientations having dislocation pile-ups (bands) which are stabilized and extended through hydrogen transport.

$$\theta_T = \frac{C_T}{N_T} \quad \text{Occupancy of hydrogen in the traps } \theta_T \text{ derives from trapped concentration } C_T \text{ and the number of traps } N_T.$$

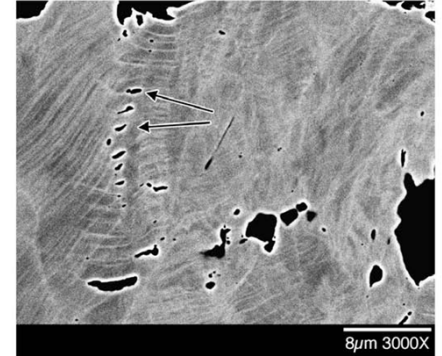
Phenomenological extension

The deformation bands that evolve under large deformations cannot be easily idealized

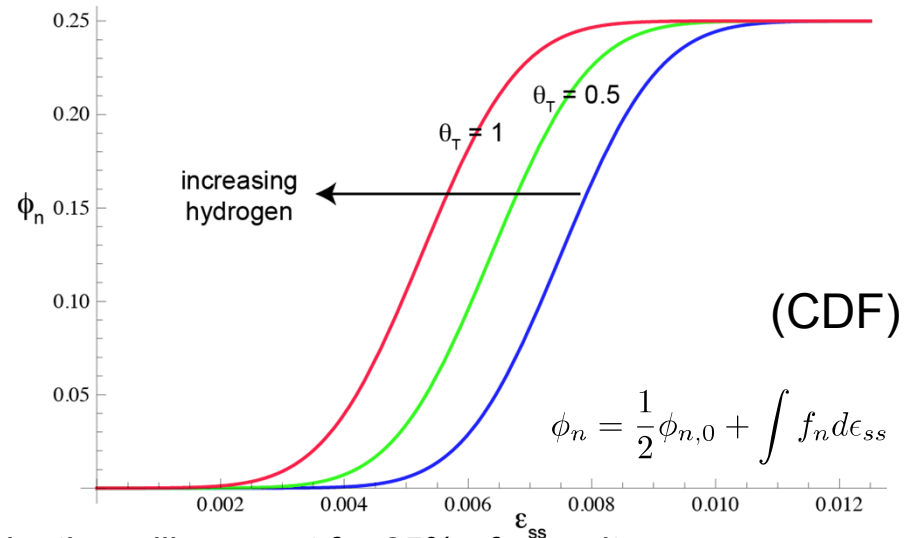
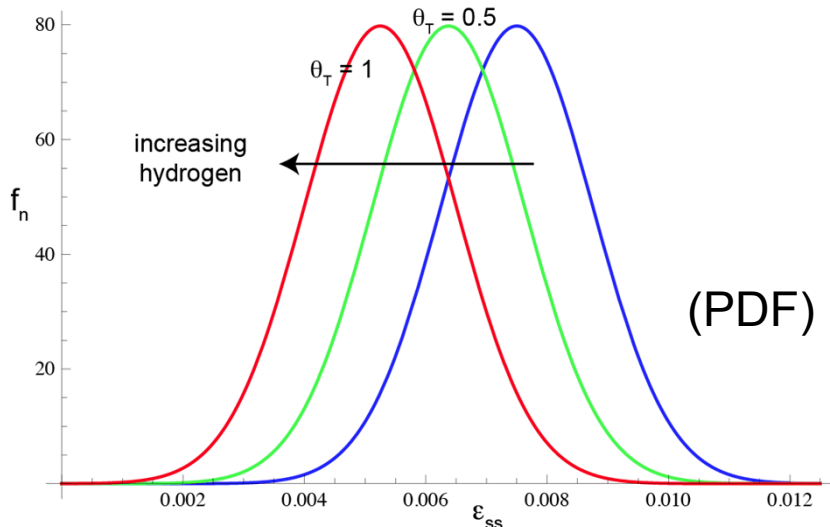
$$f_n = \frac{\phi_{n,0}}{\epsilon_{ss,std}\sqrt{2\pi}} \exp \left[-\frac{1}{2} \left(\frac{\epsilon_{ss} - \epsilon_{ss,mean}}{\epsilon_{ss,std}} \right)^2 \right]$$

In spirit of Chu and Needleman (1980) we choose an appropriate state variable to capture void nucleation through elevated stresses at pile-ups. We assume the probability of void nucleation f_n follows a normal distribution.

We assume that hydrogen affects the mean $\epsilon_{ss,mean}$ and not the standard deviation $\epsilon_{ss,std}$ through the occupancy of hydrogen in the traps θ_T . The nucleated void volume fraction ϕ_n can be found through integration and is limited by $\phi_{n,0}$.



(Nibur, 2009)

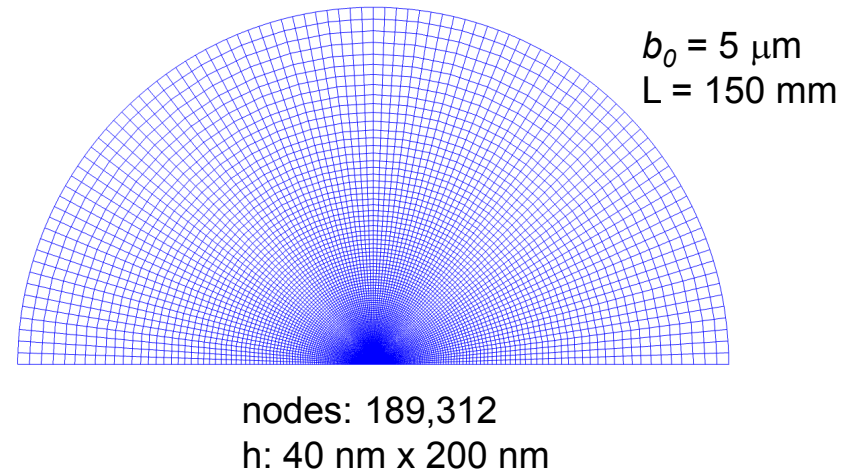
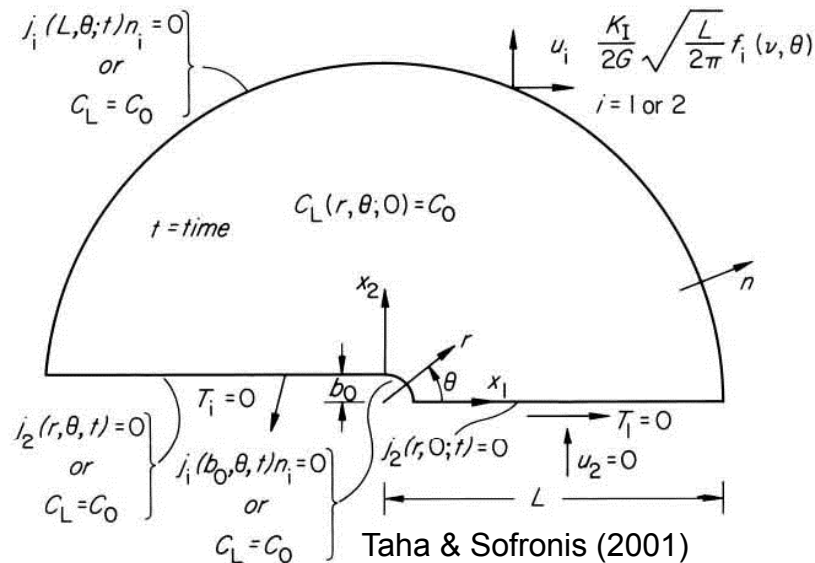
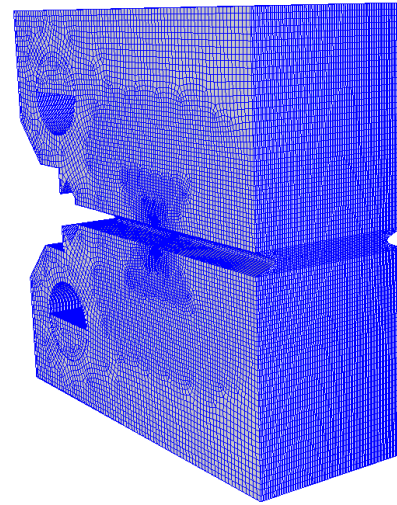


NOTE: In this case, we assume that $\phi_{n,0}$ is 0.25. Nucleation will account for 25% of porosity

Modeling 21Cr-6Ni-9Mn in H₂ gas

Before moving to complex and computationally challenging fracture geometries, we need to understand phenomena in plane strain

Mechanical analysis should be performed to help experimentalists reduce driving forces from non-standard fracture geometry. Iteration required.



NOTE: Not pre-charged, constant concentration $C_{L,applied}$ applied to crack faces

Coupled hydrogen transport

This path heavily leverages Sofronis/McMeeking (1989)* and Krom (1998).

Recent work by Leo and Anand (2013).

*chemical
potential*

$$\mu_l = \mu_0 + RT \ln(\theta_l) - v_h \sigma_h$$

*model
for flux*

$$\dot{j}_l = -m_l c_l \nabla_x \mu_l$$

*conservation
of hydrogen*

$$\frac{d}{dt} \int_B c dv = - \int_{\partial B} \mathbf{j} \cdot \mathbf{n} da \quad \dot{c} = \dot{c}_l + \frac{\partial c_t}{\partial c_l} \dot{c}_l + \frac{\partial c_t}{\partial n_t} \frac{\partial n_t}{\partial \epsilon_p} \dot{\epsilon}_p + \frac{\partial c_t}{\partial n_t} \frac{\partial n_t}{\partial J} \dot{J}$$

*equilibrium of
lattice/trap sites*

$$\theta_t = \frac{1}{1 + \frac{1}{k_t \theta_l}}$$

$$\mathbf{F} = \frac{\partial \mathbf{x}}{\partial \mathbf{X}}$$

$$J = \det[\mathbf{F}]$$

$$\theta_l = c_l / n_l$$

$$\theta_t = c_t / n_t$$

$$n_l = N_L / J$$

$$n_t = N_T(\epsilon_p) / J$$

$$v_h = V_H J$$

$$\tau_h = J \sigma_h$$

$$d_l = RT m_l$$

$$c_t = c_t(c_l, \epsilon_p, J)$$

$$C^* = c_l + \frac{n_t}{1 + \frac{n_l}{k_t c_l}} \quad D^* = 1 + \frac{\partial c_t}{\partial c_l}$$

$$D^* \dot{c}_l + C^* \operatorname{div} \mathbf{v} - \nabla_x \cdot \mathbf{d}_l \nabla_x c_l - \nabla_x \cdot \frac{c_l}{J} \mathbf{d}_l \nabla_x J + \nabla_x \cdot \frac{c_l V_H}{RT} \mathbf{d}_l \nabla_x \tau_h +$$

*P. Sofronis and R.M. McMeeking, J. Mech. Phys. Solids 37 (1989) 317

$$\frac{\theta_l}{J} \frac{\partial N_T}{\partial \epsilon_p} \dot{\epsilon}_p - \frac{\theta_t N_T}{J^2} \dot{J} = 0$$

Baseline properties for 21Cr-6Ni-9Mn

Transport*

$$D_0 = 5.4E-7 \text{ m}^2/\text{s}$$

$$Q = 53.9E3 \text{ J/mol}$$

$$R = 8.314 \text{ J/(mol K)}$$

$$T = 300 \text{ K}$$

$$D_L = 2.2E-16 \text{ m}^2/\text{s}$$

$$N_A = 6.0232 \text{ atoms/mol}$$

$$V_M = 7.116E-6 \text{ m}^3/\text{mol} - \text{molar volume of Fe}$$

$$V_H = 2.0E-6 \text{ m}^3/\text{mol} - \text{partial molar volume of H}$$

$$N_L = 8.46E28 \text{ atoms/m}^3 = 1.40E5 \text{ solvent lattice mol/m}^3$$

$$C_{L,0} = 38.7 \text{ mol/m}^3 \text{ (from 316 alloys, assumes 5 wppm)}$$

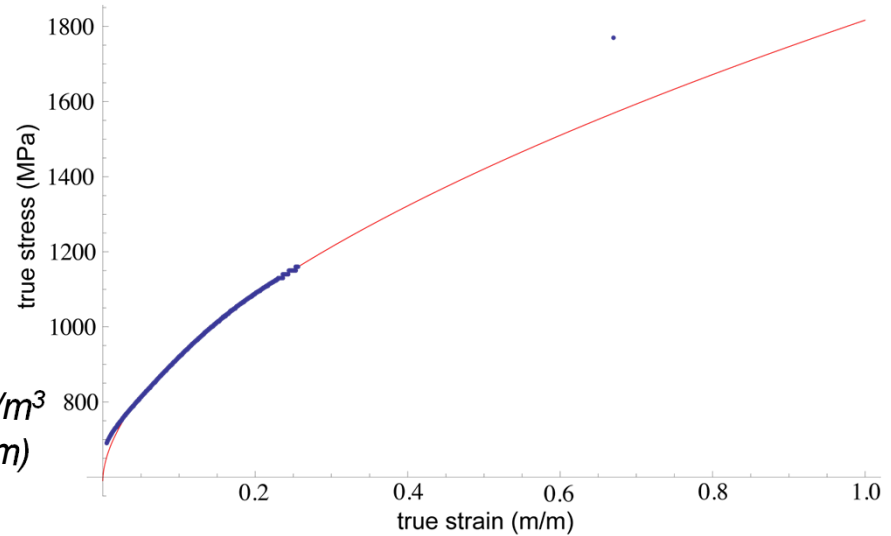
$$C_{L,\text{applied}} = 560 \text{ mol H/m}^3 \text{ (280 moles H}_2\text{/m}^3\text{)}$$

$$N_{T,\text{total}} = \alpha N_T = 10 N_T = 10^{(26.6 - 1.5 \exp(-6.96 \epsilon))} \text{ mole/m}^3$$

$$C_{T,0} = 3.94E24 \text{ atoms/m}^3 = 6.542 \text{ mol/m}^3$$

$$W_B = 9.65E3 \text{ J/mol}$$

$$K_T = 47.9$$



$$C_{L,\text{applied}} = K f^{\frac{1}{2}} \quad \text{San Marchi, et al., IJHE, 2007}$$

Mechanics – non-charged, forged, transverse, LF

$$\rho = 7806 \text{ kg/m}^3$$

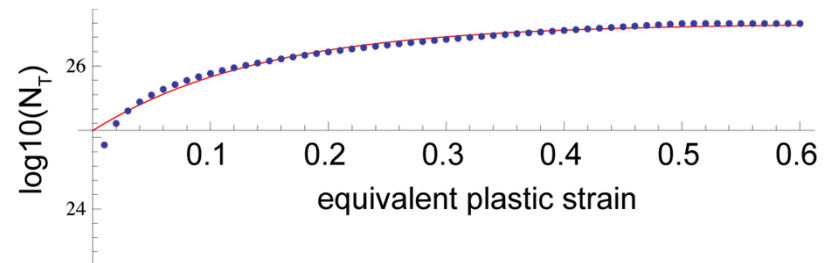
$$E = 196.6 \text{ GPa}$$

$$\nu = 0.3$$

$$\sigma_0 = 590 \text{ MPa}$$

$$H = 1227 \text{ MPa}$$

$$m = 0.563$$

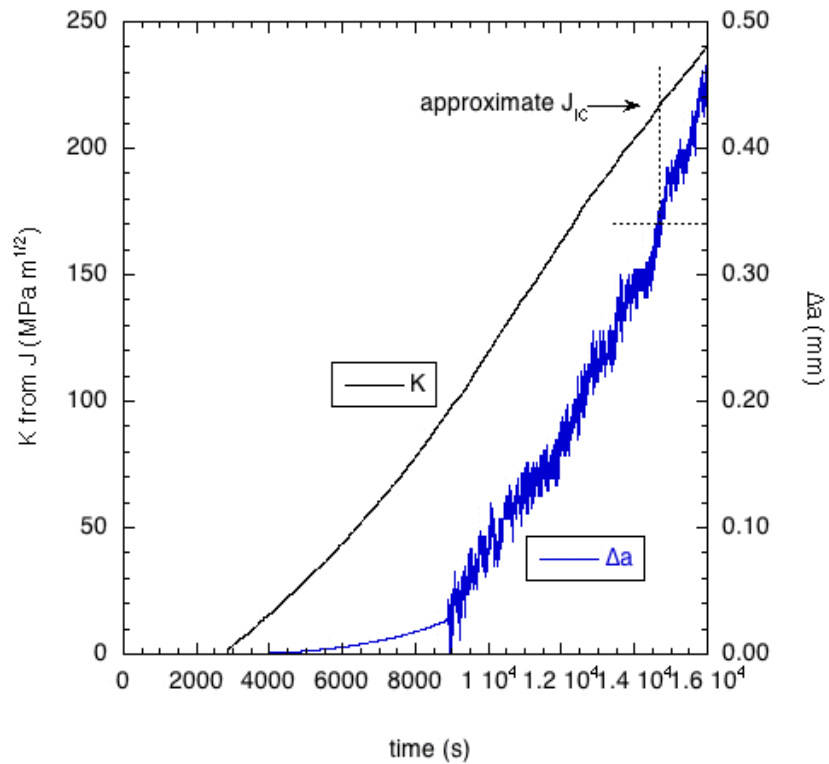


*Transport properties aligned with Somerday, et al., Met Trans, 2009

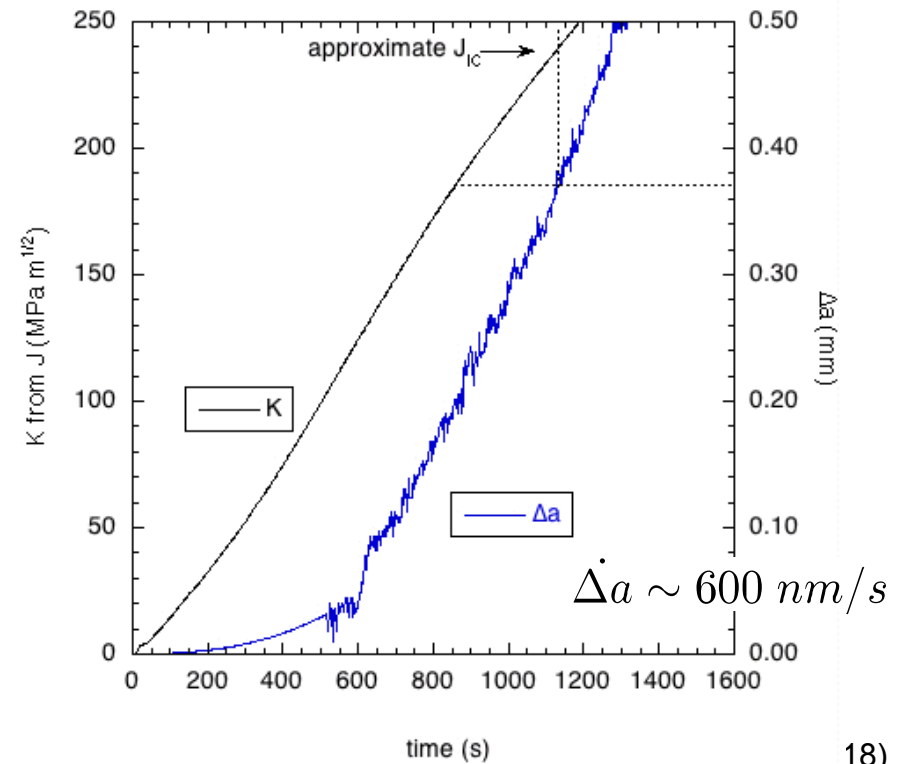
NOTE: Constant concentration, not chemical potential, is applied. Will fix.

Initial studies in 21Cr-6Ni-9Mn SS

21-6-9, high-ferrite alloy (specimen HF12)



21-6-9, high-ferrite alloy (specimen HF18)



18)

