

Evaluation of Interface Reductions for Craig Bampton Substructured Models

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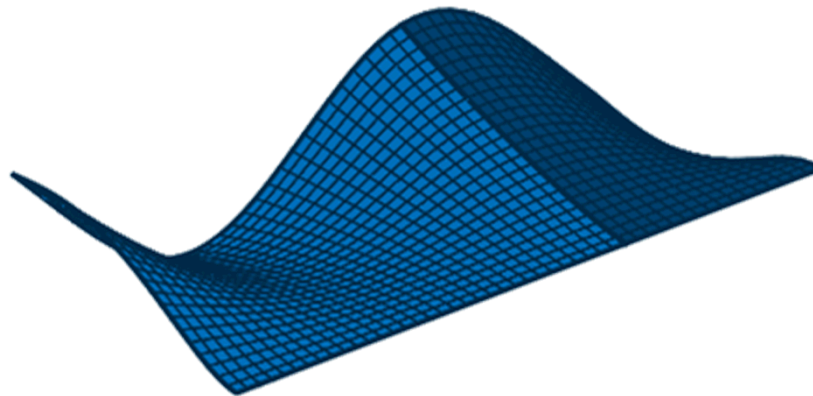
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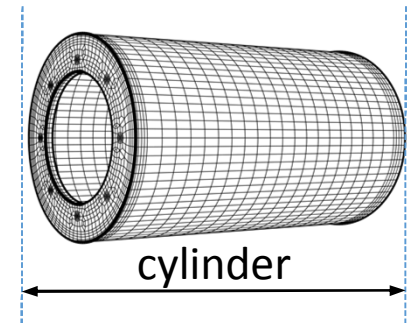
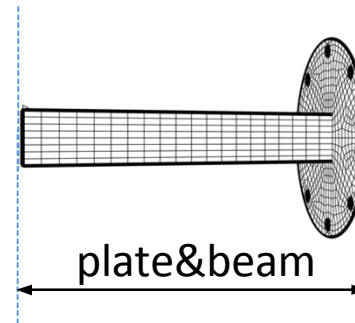
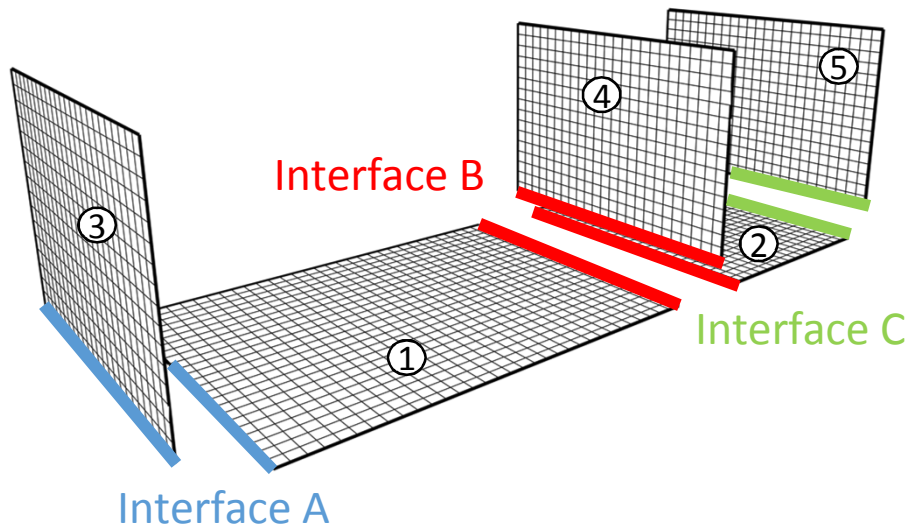
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Introduction

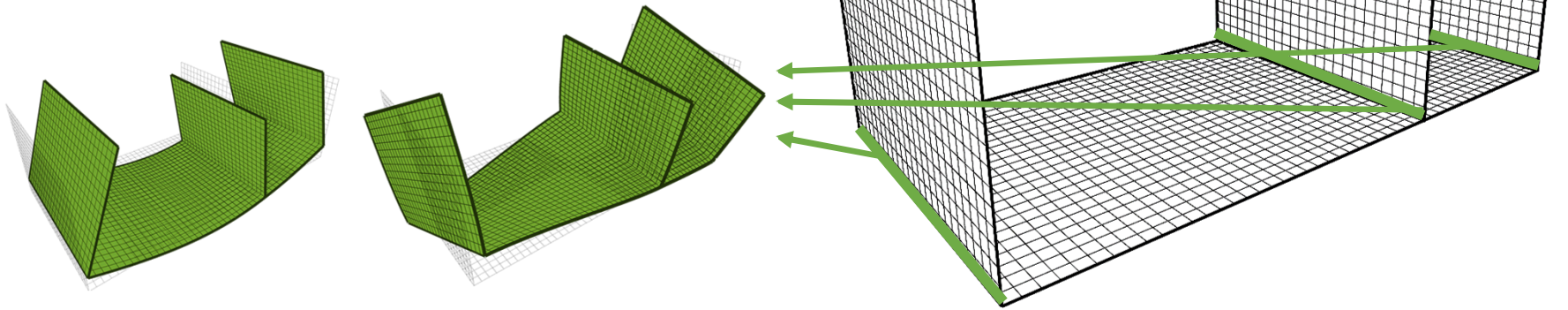
- The Craig-Bampton (CB) approach can be used to assemble substructures into a reduced order system model but all physical degrees of freedom at the substructure interfaces are retained, which can lead to unacceptably large equations of motion
- 5 different interface reduction techniques for reducing the interface degrees of freedom are evaluated
 - System characteristic constraint (S-CC)
 - Hybrid characteristic constraint (H-CC)
 - Exact compatibility local characteristic constraint (L-CC)
 - Undeformed interface method (UIM)
 - Weak compatibility L-CC

Finite Element Models



Method: S-CC [2]

- Secondary modal analysis of **system interface**: $(K_{\Gamma} - \lambda^{CC} M_{\Gamma}) \boldsymbol{\phi}^{CC} = 0$

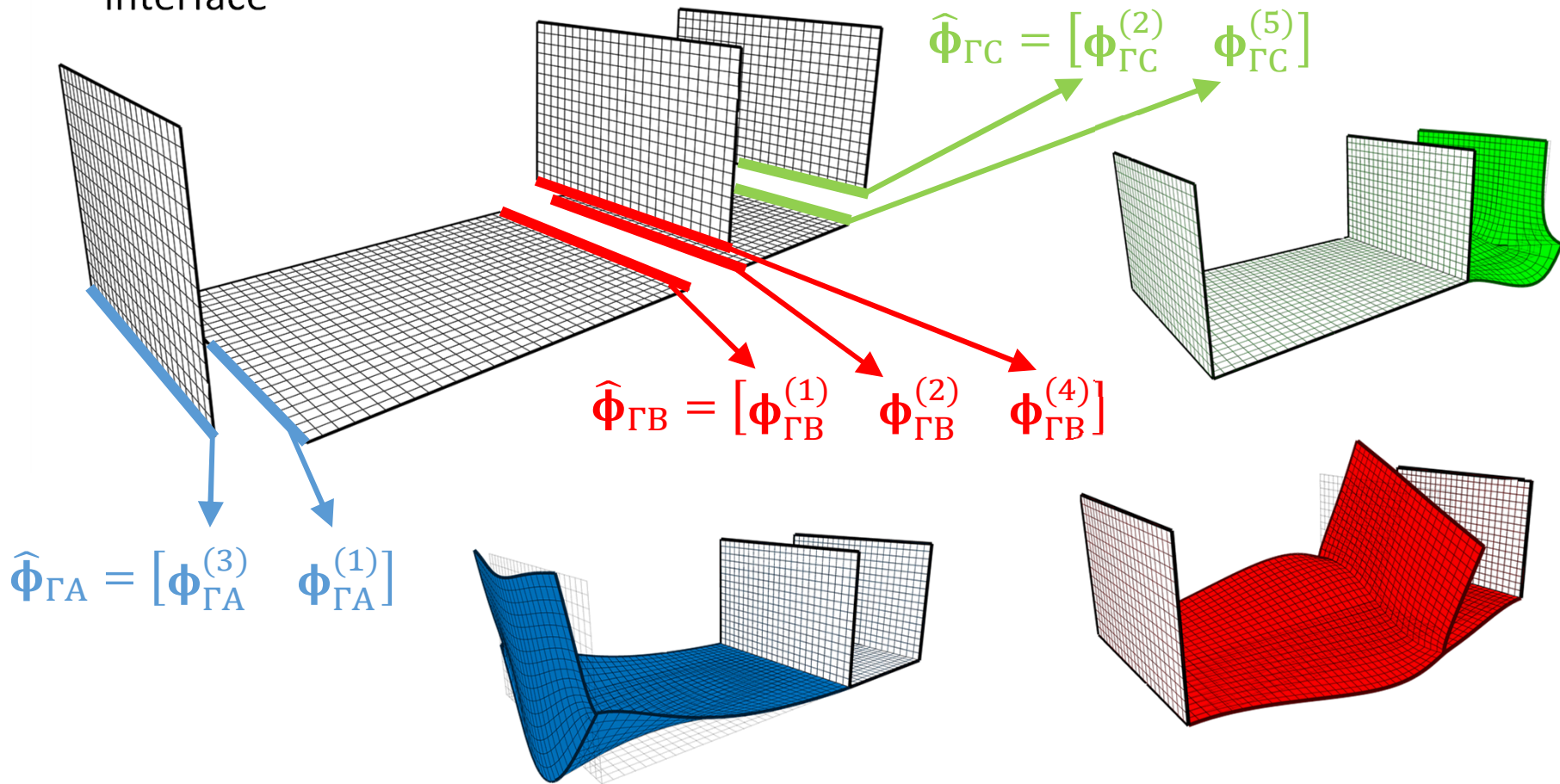


Example characteristic constraint
mode shapes

- Interface eigenvectors are truncated and used as a reduced basis for the interface $\rightarrow \hat{\boldsymbol{\phi}}^{CC}$

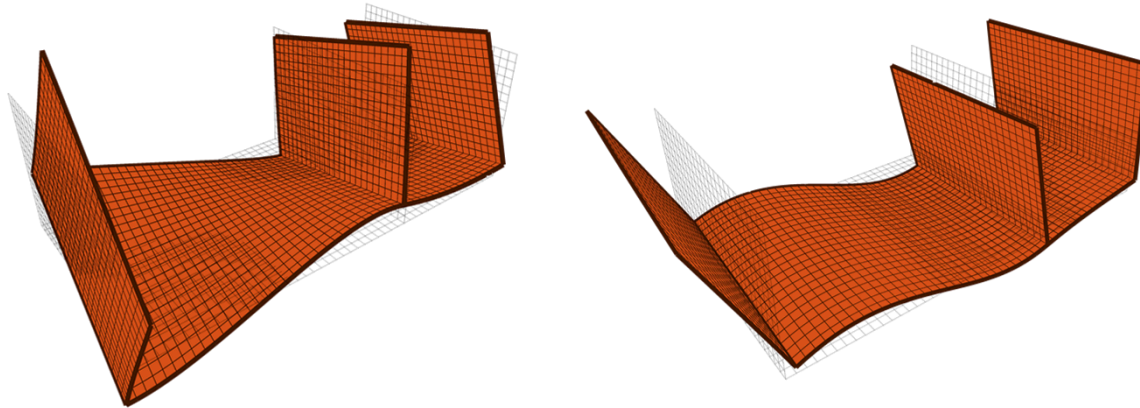
Method: Exact-Compatibility L-CC ^[3]

- Collect modes for each interface set from all connected substructures
- Combined mode set is orthogonalized and then used as a basis for that interface



Method: Weak-Compatibility L-CC ^[4]

- Each substructure's interface is reduced by a set of its own interface modes (i.e. not a combined set)
- Weak compatibility is enforced by linking a linear combination of interface modes from one substructure to a linear combination of interface modes from a neighboring substructure.

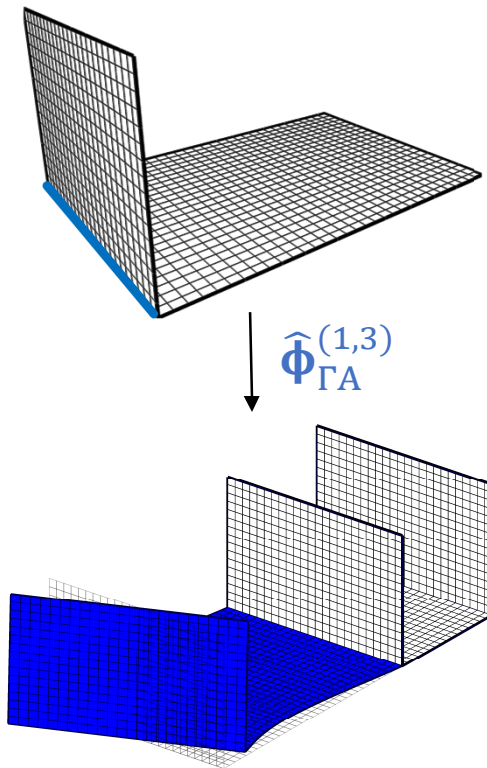


Example interface modes after weak-compatibility enforcement

Method: H-CC

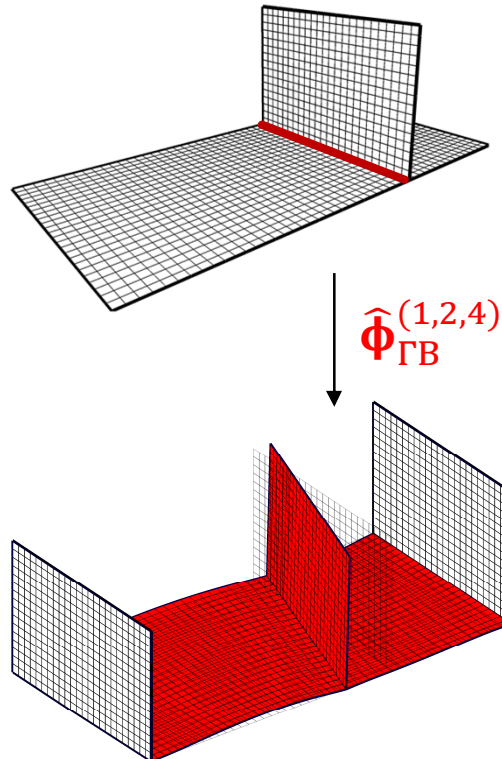
- A secondary eigenvalue analysis is performed at the interface partitions of the assembled stiffness and mass matrices among localized substructures sharing the same interface
- This technique is a combination of the S-CC and L-CC approach to keep good accuracy and localize the eigenvalue analysis for each interface

Interface A



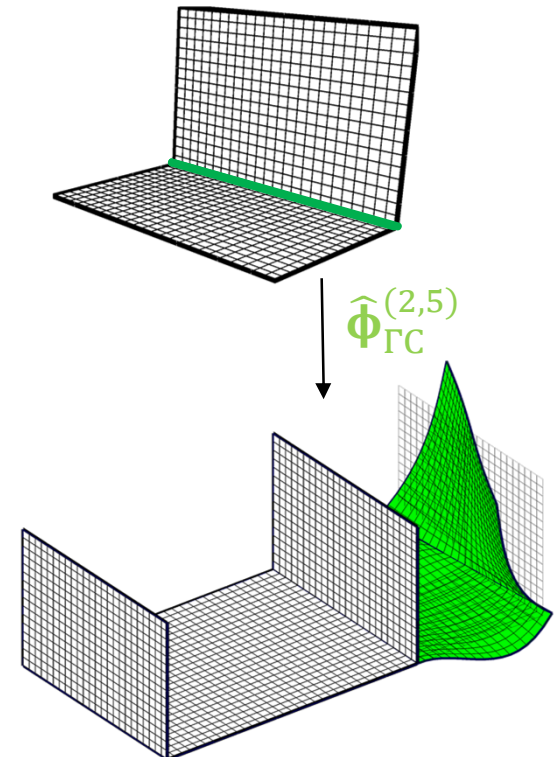
$$\hat{\Phi}_{\Gamma A}^{(1,3)}$$

Interface B



$$\hat{\Phi}_{\Gamma B}^{(1,2,4)}$$

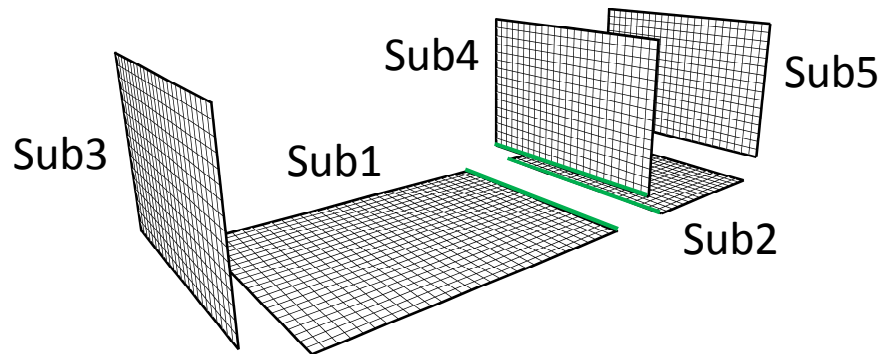
Interface C



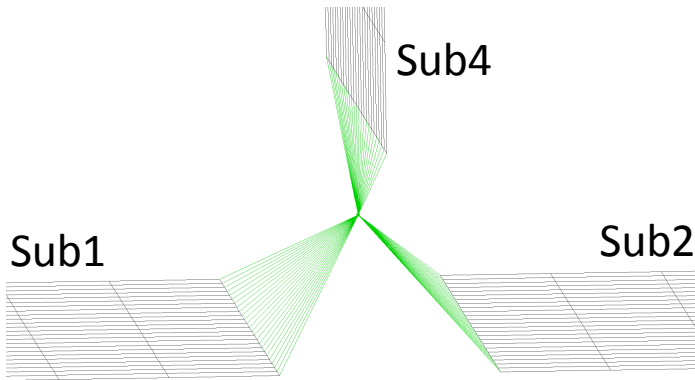
$$\hat{\Phi}_{\Gamma C}^{(2,5)}$$

Method: Undeformed Interface

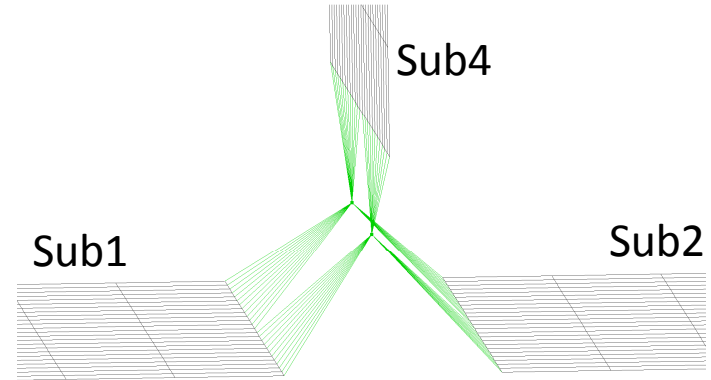
- Each interface node is tied to one of n virtual nodes
- Each virtual node is represented by three rigid translations and rotations, that retain an undeformed interface shape



1 virtual node



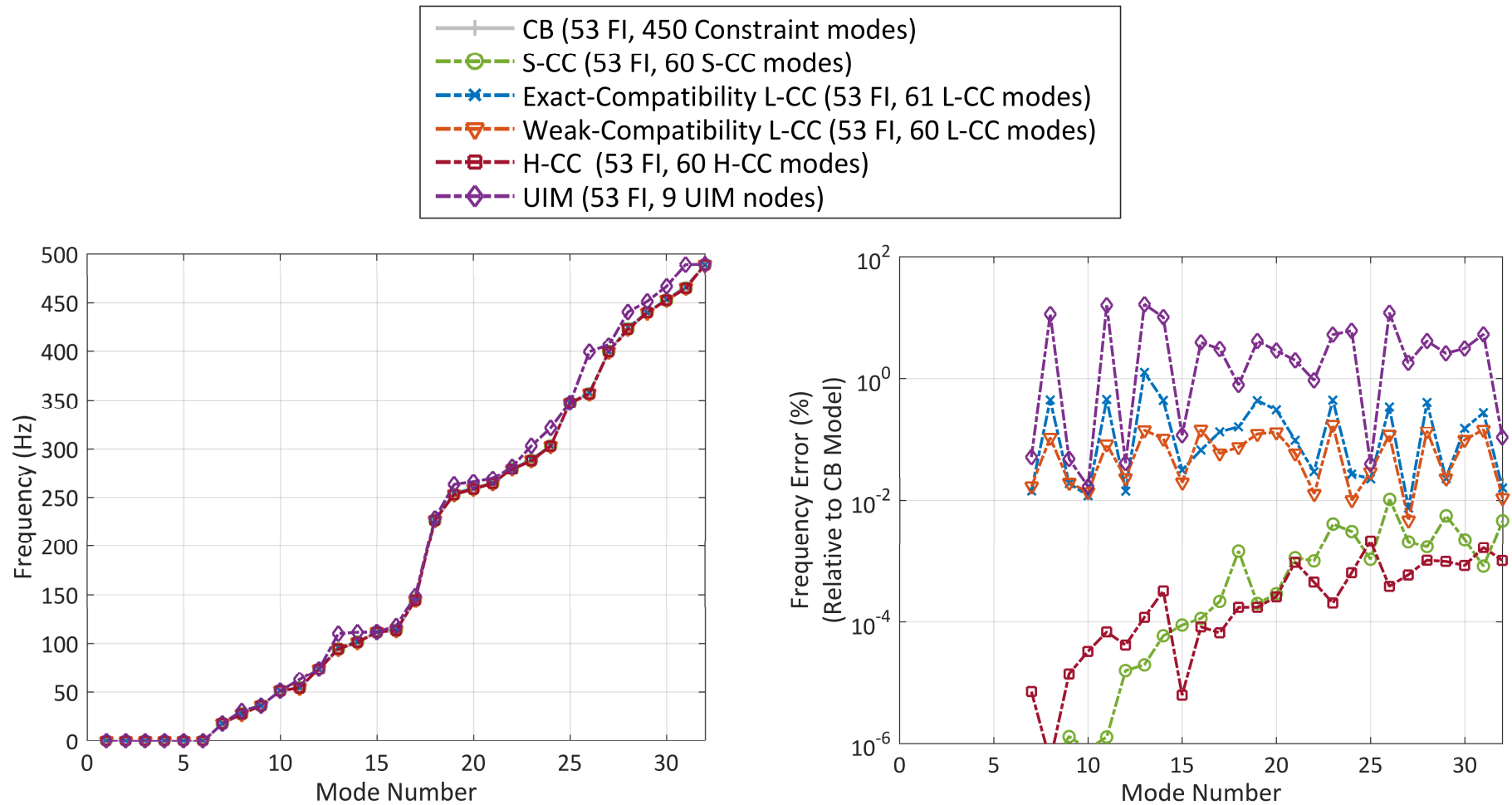
2 virtual nodes



Method: Mode Selection

- The choice of CC modes forming the interface reduction basis influences the reduced model's accuracy
- Influence factors: selected CC modes & number of CC modes
- Mode selection criteria:
 - Frequency cutoff rule (FC)
 - Modified Effective Interface Mass (EIM) ^[7]
 - Coupling matrix based (CMS χ) ^[8]

Results: Frequency Comparison

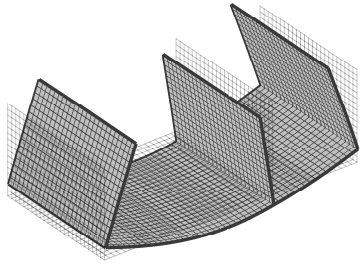


Frequencies and corresponding relative error comparison for different interface reduction techniques

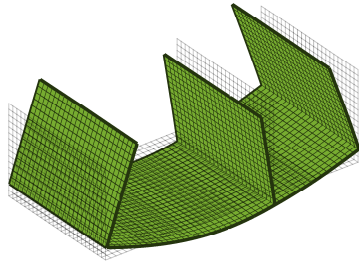
Results: Mode Comparison

7th mode

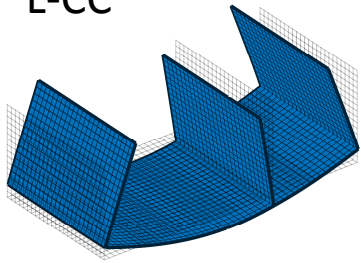
CB method ([reference](#))



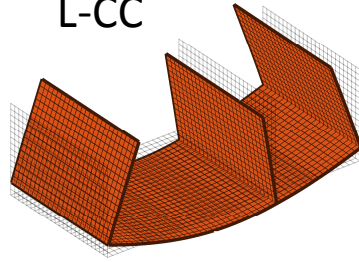
S-CC



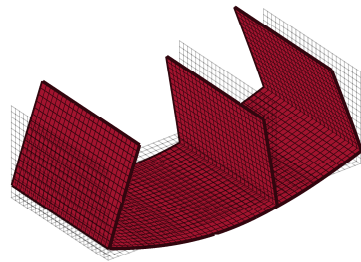
Exact-Compatibility
L-CC



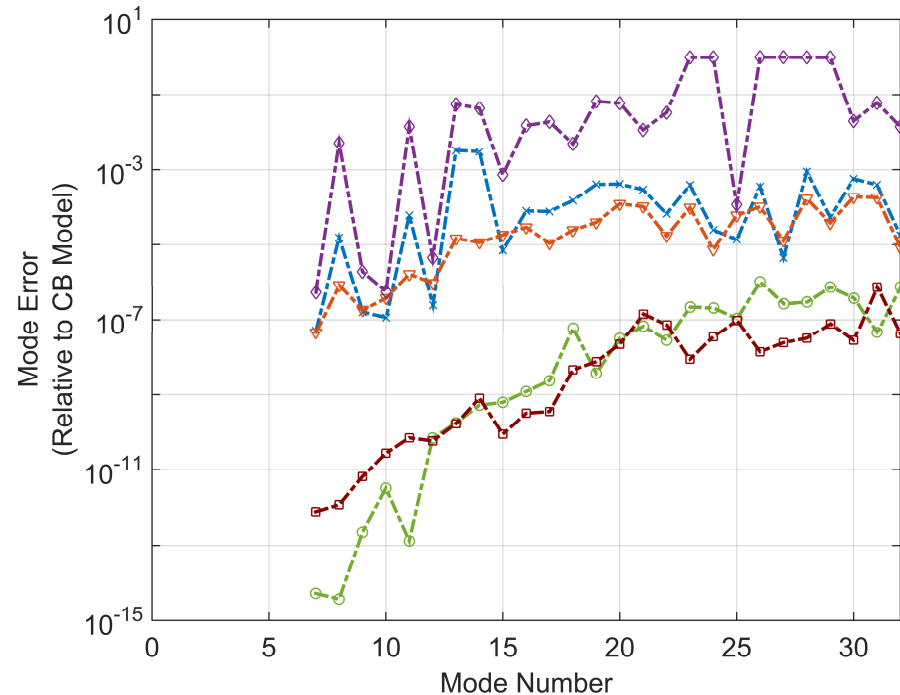
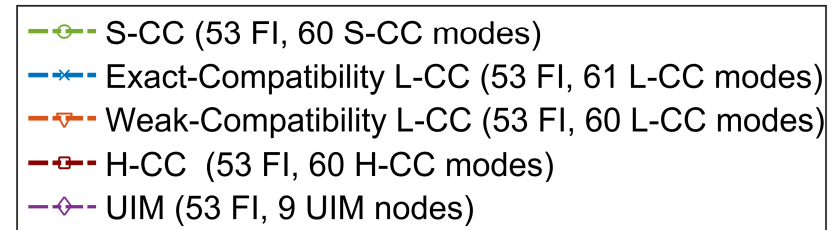
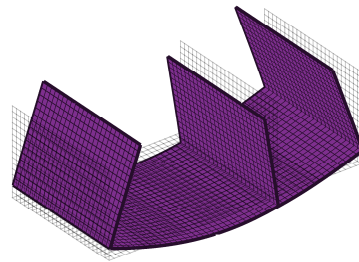
Weak-Compatibility
L-CC



H-CC



UIM



References

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