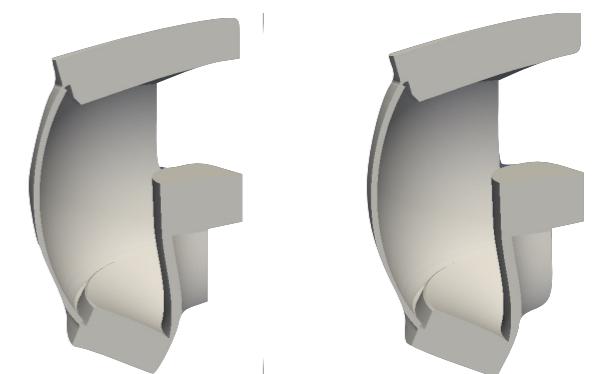
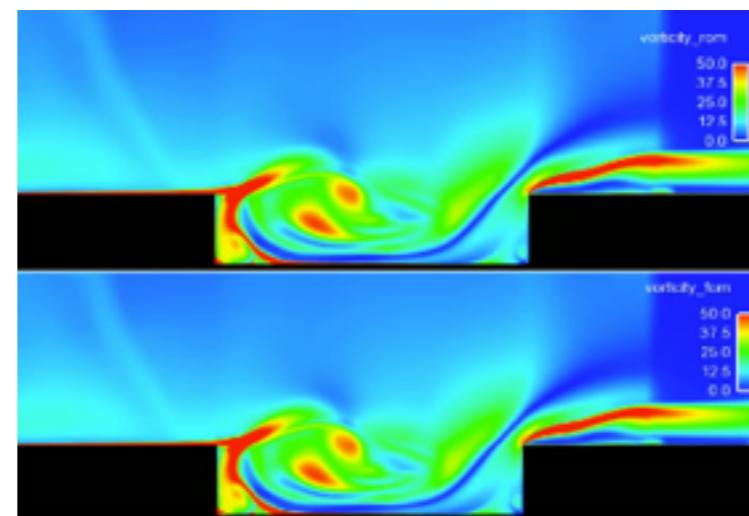
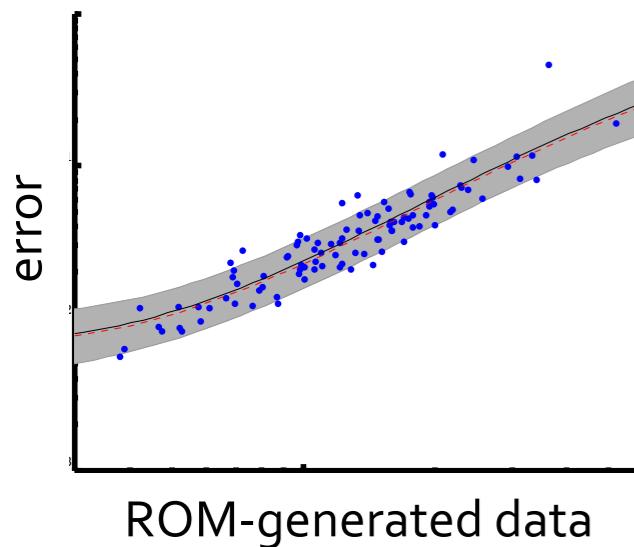
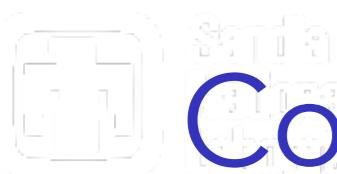


Breaking computational barriers via nonlinear model reduction



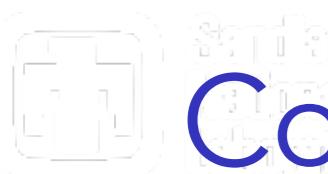
Kevin Carlberg
CIS External Review
Sandia National Laboratories
June 7, 2016



Computational barrier

High-fidelity simulation

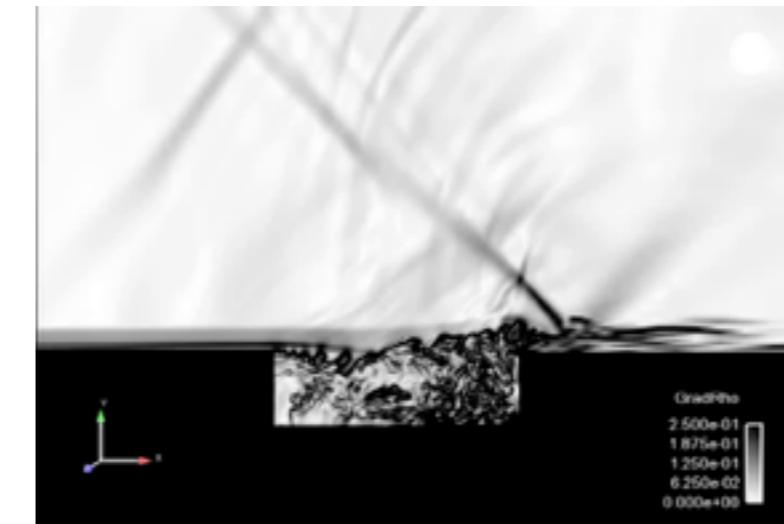
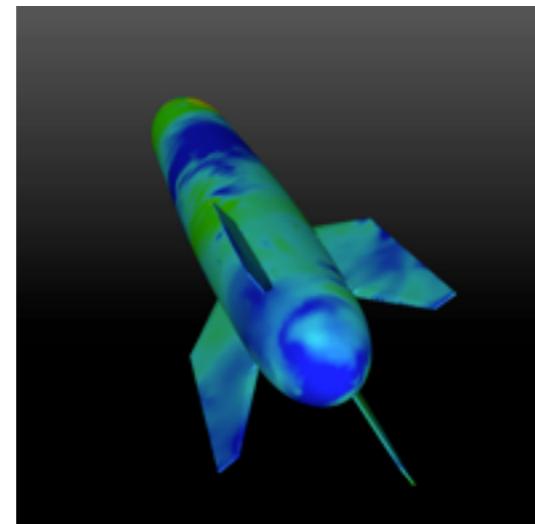
- + Indispensable in mission-critical applications
- *High fidelity*: large-scale nonlinear dynamical system models



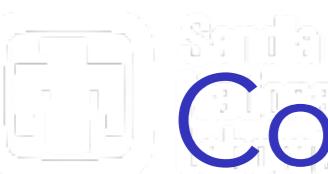
Computational barrier

High-fidelity simulation

- + Indispensable in mission-critical applications
- *High fidelity*: large-scale nonlinear dynamical system models



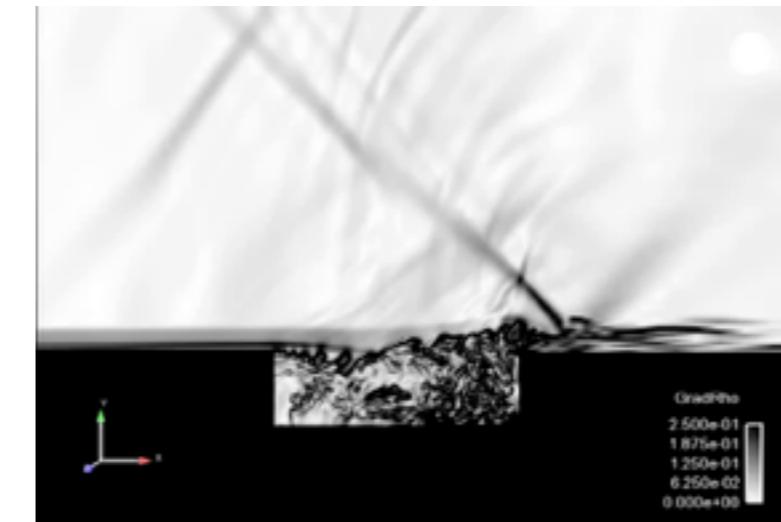
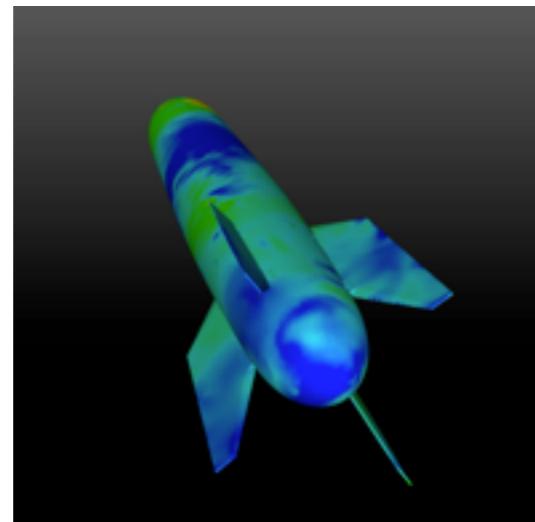
- + *Validated, predictive model*: matches experiment to within 5%
- *High simulation costs*: 6 weeks, 5000 cores



Computational barrier

High-fidelity simulation

- + Indispensable in mission-critical applications
- *High fidelity*: large-scale nonlinear dynamical system models



- + *Validated, predictive model*: matches experiment to within 5%
- *High simulation costs*: 6 weeks, 5000 cores

barrier

Time-critical applications

- rapid design
- stochastic optimization
- uncertainty quantification



Model reduction

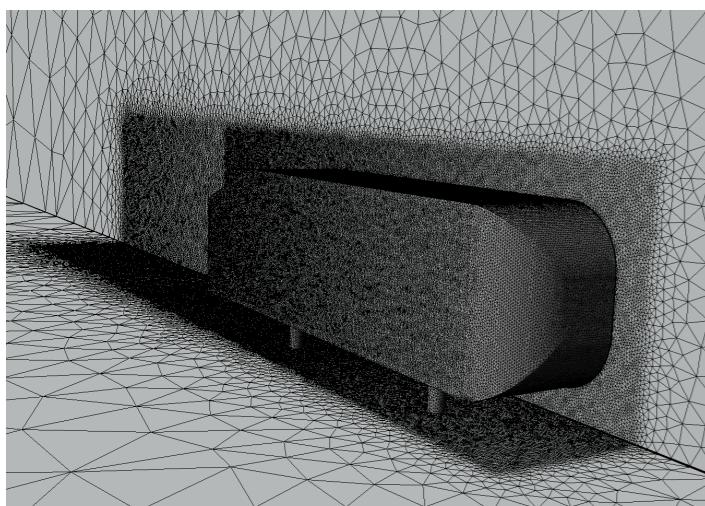
Goal: Exploit data to drastically reduce simulation costs



Model reduction

Goal: Exploit data to drastically **reduce simulation costs**

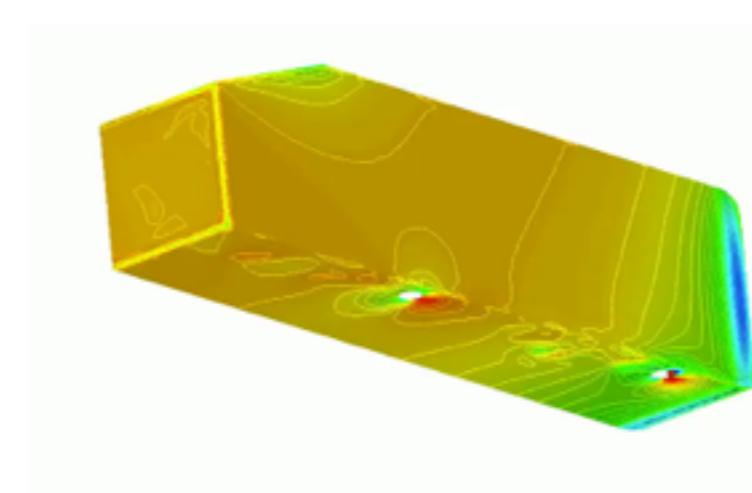
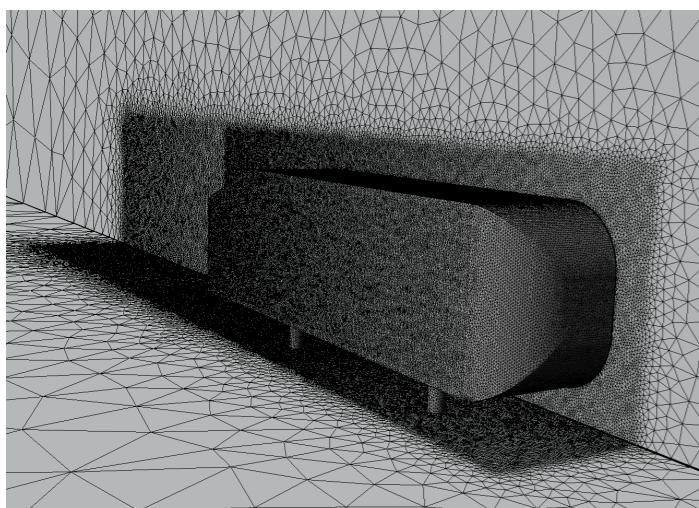
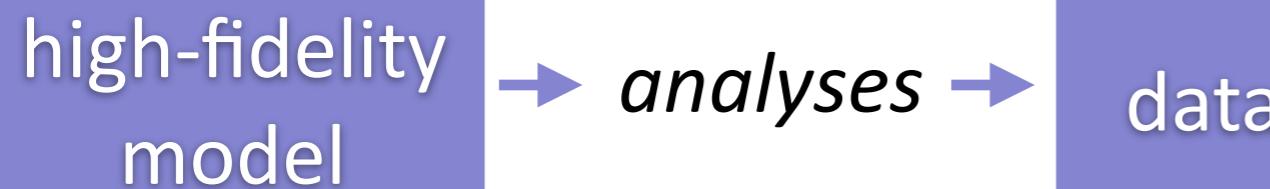
high-fidelity
model





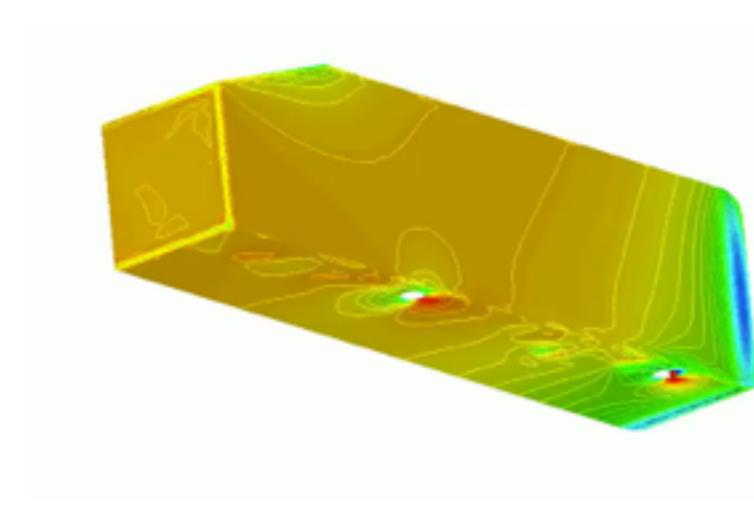
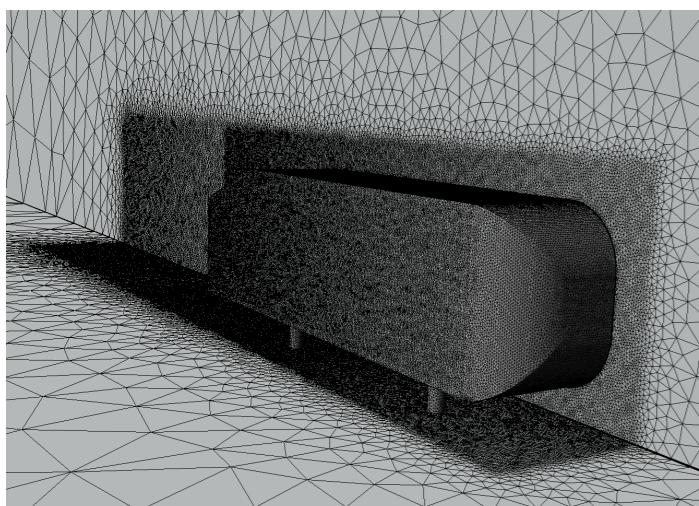
Model reduction

Goal: Exploit **data** to drastically **reduce simulation costs**



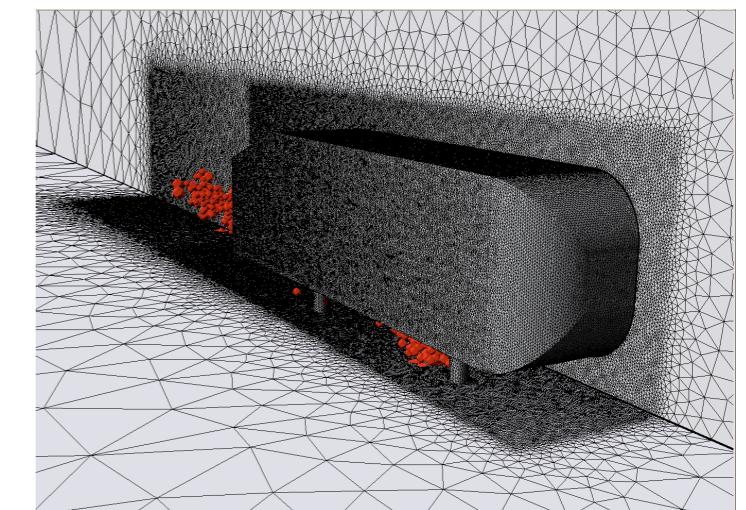
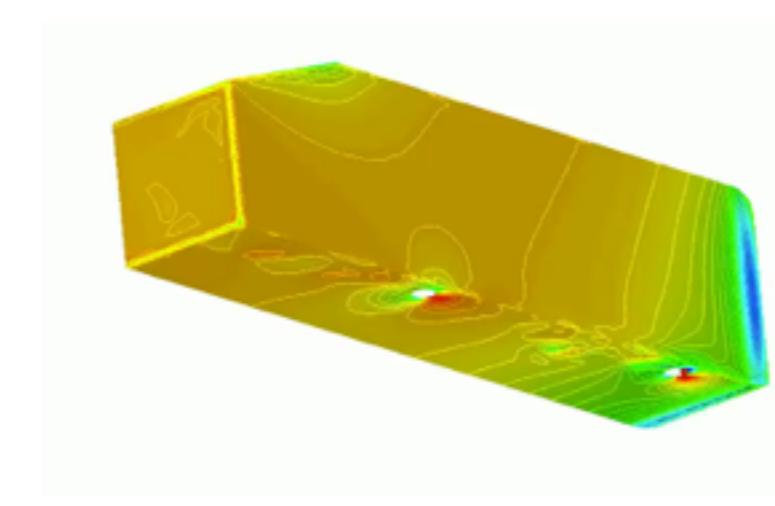
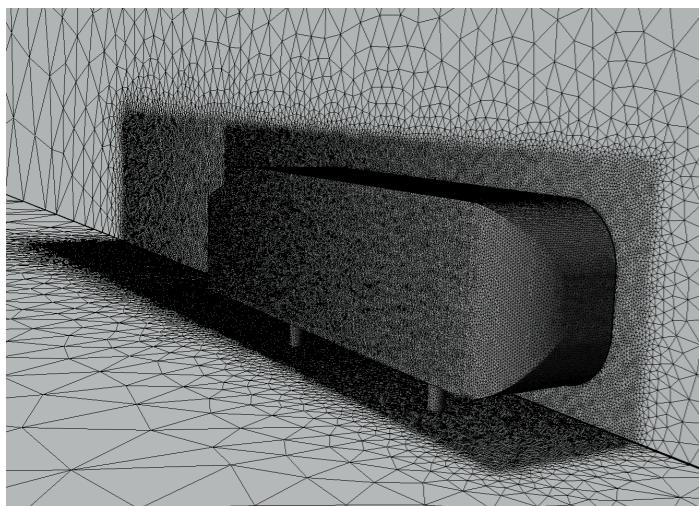
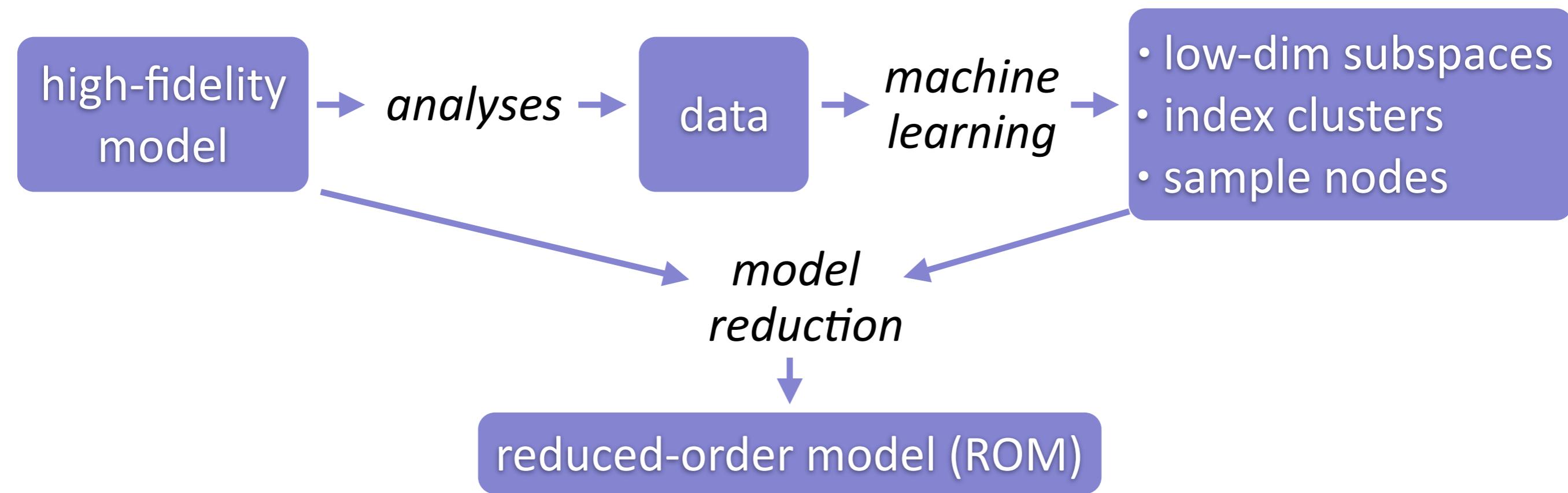
Model reduction

Goal: Exploit **data** to drastically **reduce simulation costs**



Model reduction

Goal: Exploit **data** to drastically **reduce simulation costs**





ROM: state of the art



ROM: state of the art

- Linear time-invariant systems: **mature** [Antoulas, 2005]
 - Balanced truncation [Moore, 1981]
 - Empirical balanced truncation [Willcox and Peraire, 2002; Rowley, 2005]
 - Moment matching [Bai, 2002; Freund, 2003; Gallivan et al, 2004; Baur et al., 2001]
 - Loewner framework [Lefteriu and Antoulas, 2010; Ionita and Antoulas, 2014]
 - + *Reliable*: guaranteed stability, *a priori* error bounds
 - + *Certified*: sharp, computable *a posteriori* error bounds



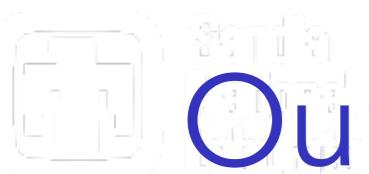
ROM: state of the art

- Linear time-invariant systems: **mature** [Antoulas, 2005]
 - Balanced truncation [Moore, 1981]
 - Empirical balanced truncation [Willcox and Peraire, 2002; Rowley, 2005]
 - Moment matching [Bai, 2002; Freund, 2003; Gallivan et al, 2004; Baur et al., 2001]
 - Loewner framework [Lefteriu and Antoulas, 2010; Ionita and Antoulas, 2014]
 - + *Reliable*: guaranteed stability, *a priori* error bounds
 - + *Certified*: sharp, computable *a posteriori* error bounds
- Elliptic/parabolic PDEs: **mature** [Rozza et al., 2008]
 - Reduced-basis method [Prud'Homme et al., 2001, Veroy et al., 2003, Barrault et al., 2004]
 - + *Reliable*: *a priori* error bounds
 - + *Certified*: sharp, computable *a posteriori* error bounds



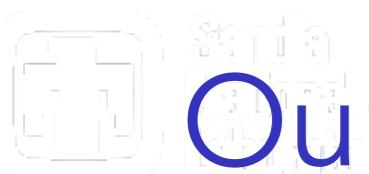
ROM: state of the art

- Linear time-invariant systems: **mature** [Antoulas, 2005]
 - Balanced truncation [Moore, 1981]
 - Empirical balanced truncation [Willcox and Peraire, 2002; Rowley, 2005]
 - Moment matching [Bai, 2002; Freund, 2003; Gallivan et al, 2004; Baur et al., 2001]
 - Loewner framework [Lefteriu and Antoulas, 2010; Ionita and Antoulas, 2014]
 - + *Reliable*: guaranteed stability, *a priori* error bounds
 - + *Certified*: sharp, computable *a posteriori* error bounds
- Elliptic/parabolic PDEs: **mature** [Rozza et al., 2008]
 - Reduced-basis method [Prud'Homme et al., 2001, Veroy et al., 2003, Barrault et al., 2004]
 - + *Reliable*: *a priori* error bounds
 - + *Certified*: sharp, computable *a posteriori* error bounds
- Nonlinear dynamical systems: **unproven**
 - Proper orthogonal decomposition (POD)–Galerkin [Sirovich, 1987]
 - *Not reliable*: often unstable and inaccurate
 - *Not certified*: error bounds not sharp



Our research

*Nonlinear model-reduction methods that are
accurate, low cost, certified, and reliable*



Our research

Nonlinear model-reduction methods that are accurate, low cost, certified, and reliable

- + **Accuracy**
 - Least-squares Petrov–Galerkin (LSPG) projection [C. et al., 2011*, C. et al., 2015a]

* #2 most-cited paper, IJNME 2011



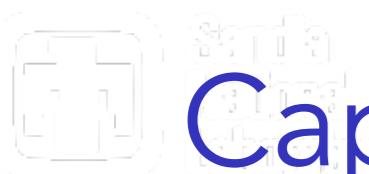
Our research

*Nonlinear model-reduction methods that are
accurate, low cost, certified, and reliable*

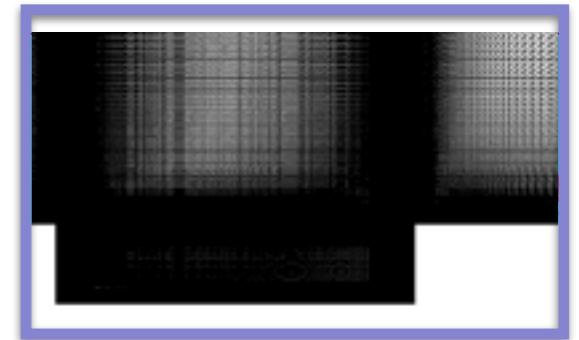
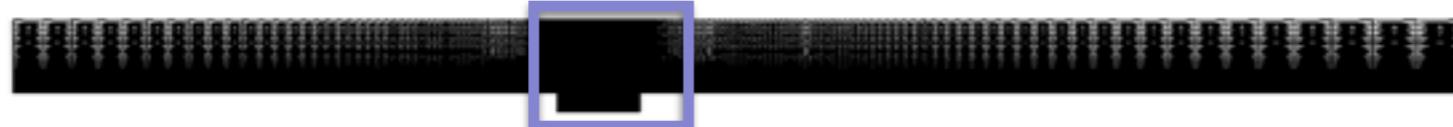
- + **Accuracy**
 - › Least-squares Petrov–Galerkin (LSPG) projection [C. et al., 2011*, C. et al., 2015a]
- + **Low cost**
 - › Sample-mesh approach [C. et al., 2013†]

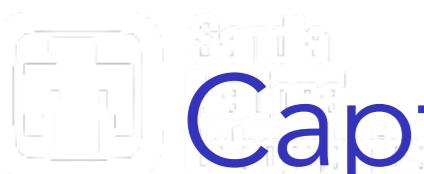
* #2 most-cited paper, IJNME 2011

† #1 most-cited paper, JCP 2013



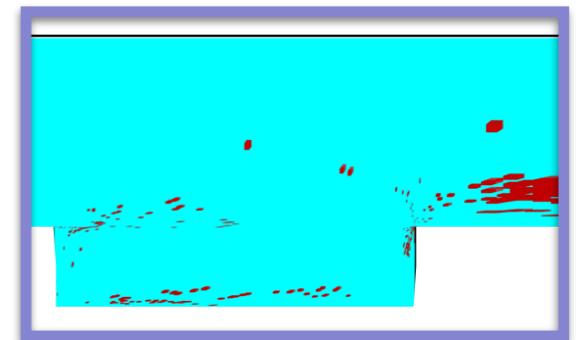
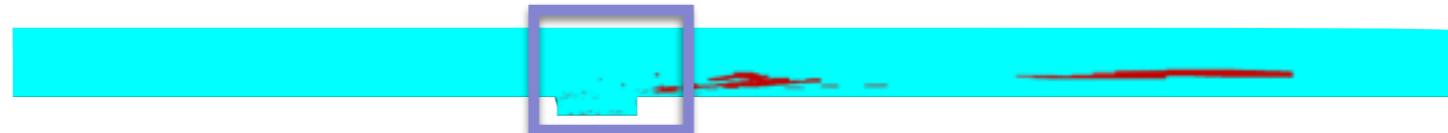
Captive-carry results





Captive-carry results

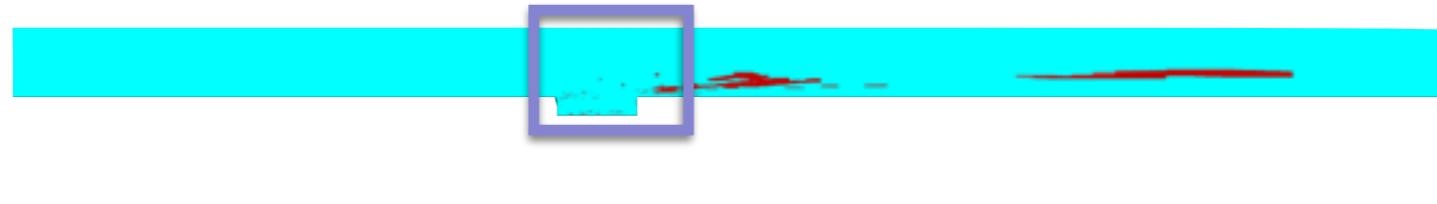
sample
mesh



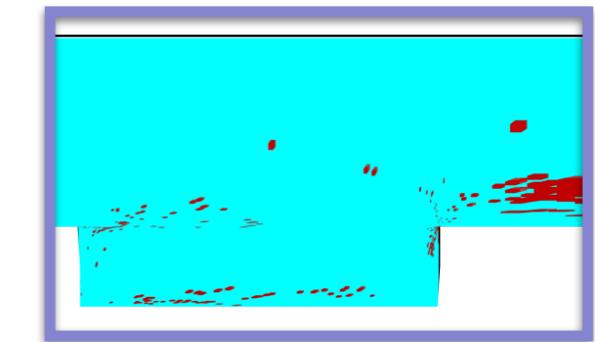
+ HPC on a laptop

Captive-carry results

sample
mesh



+ HPC on a laptop

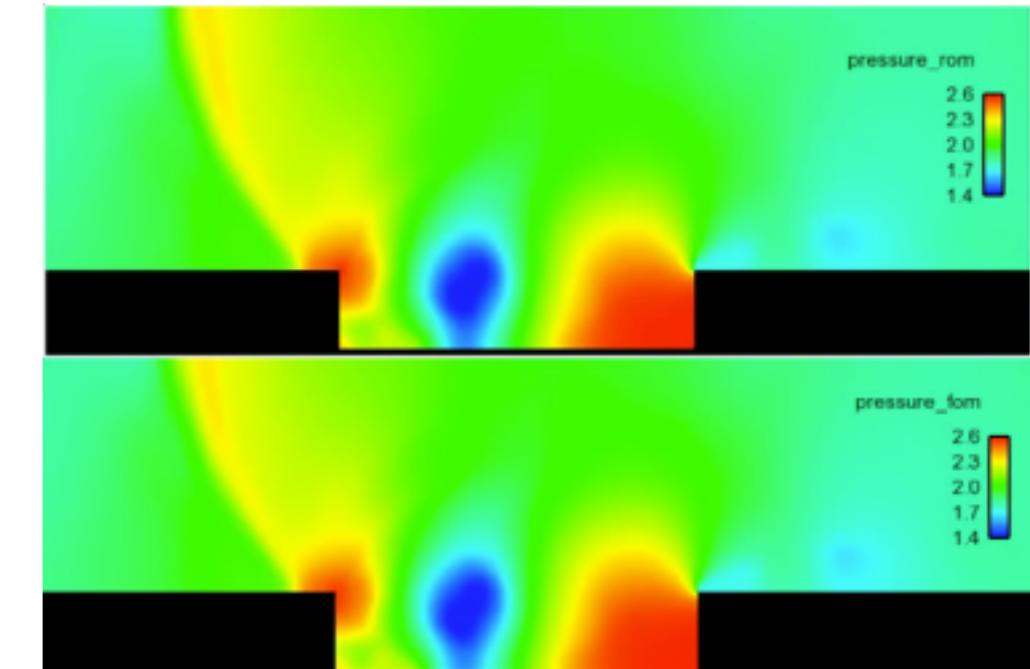
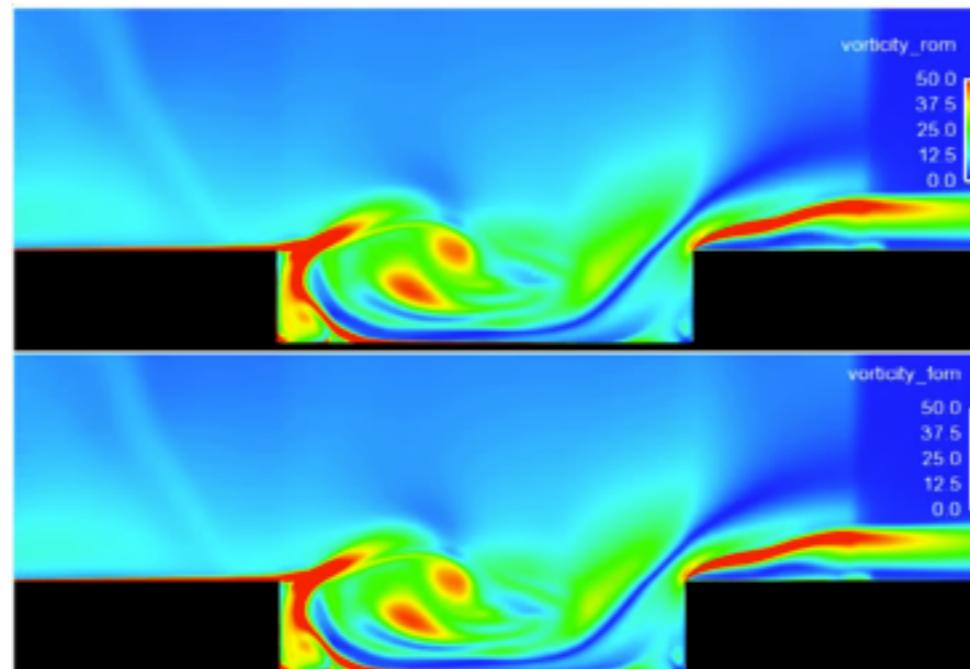


vorticity field

pressure field

LSPG ROM

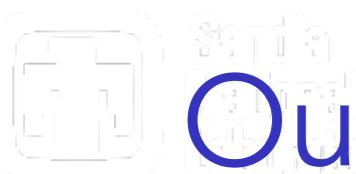
32 min, 2 cores



high-fidelity

5 hours, 48 cores

+ 229x savings in core-hours



Our research

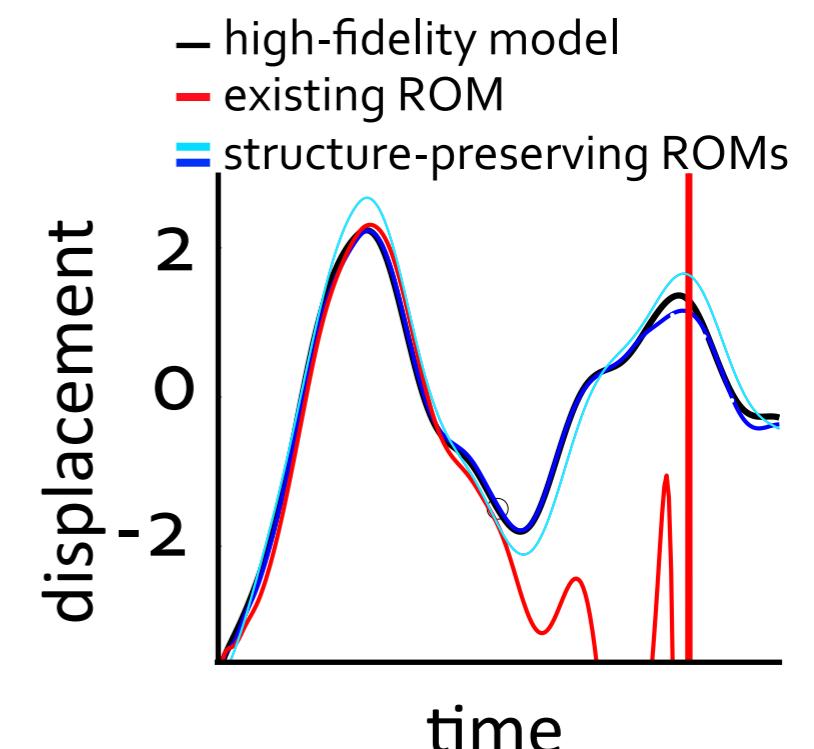
*Nonlinear model-reduction methods that are
accurate, low cost, certified, and reliable*

+ Accuracy

- LSPG projection [C. et al., 2011*, C. et al., 2015a]
- Structure preservation [C. et al., 2015c^]

+ Low cost

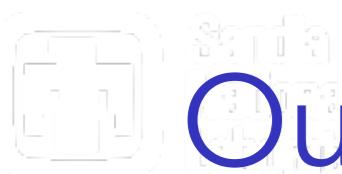
- Sample-mesh approach [C. et al., 2013†]



* #2 most-cited paper, IJNME 2011

† #1 most-cited paper, JCP 2013

^ Featured Article, SISC 2015



Our research

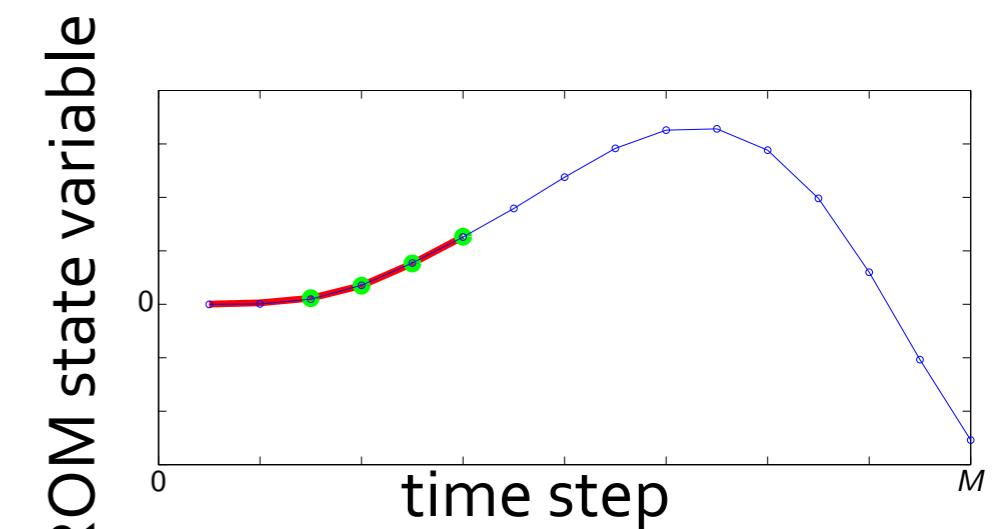
*Nonlinear model-reduction methods that are
accurate, low cost, certified, and reliable*

+ Accuracy

- LSPG projection [C. et al., 2011*, C. et al., 2015a]
- Structure preservation [C. et al., 2015c^]

+ Low cost

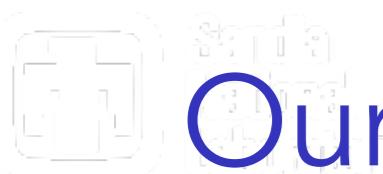
- Sample-mesh approach [C. et al., 2013†]
- Leverage time-domain data [C. et al., 2015b]



* #2 most-cited paper, IJNME 2011

† #1 most-cited paper, JCP 2013

^ Featured Article, SISC 2015



Our research

*Nonlinear model-reduction methods that are
accurate, low cost, certified, and reliable*

+ Accuracy

- LSPG projection [C. et al., 2011*, C. et al., 2015a]
- Structure preservation [C. et al., 2015c^]

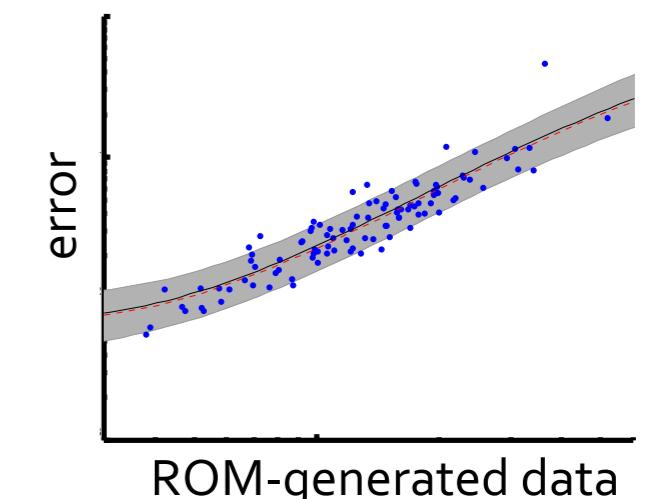
+ Low cost

- Sample-mesh approach [C. et al., 2013†]
- Leverage time-domain data [C. et al., 2015b]

+ Certification

- Error bounds [C. et al., 2015a]
- Statistical error modeling [Drohmann and C., 2015]

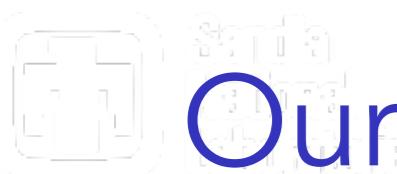
Statistical error modeling



* #2 most-cited paper, IJNME 2011

† #1 most-cited paper, JCP 2013

^ Featured Article, SISC 2015



Our research

*Nonlinear model-reduction methods that are
accurate, low cost, certified, and reliable*

+ Accuracy

- LSPG projection [C. et al., 2011*, C. et al., 2015a]
- Structure preservation [C. et al., 2015c^]

+ Low cost

- Sample-mesh approach [C. et al., 2013†]
- Leverage time-domain data [C. et al., 2015b]

+ Certification

- Error bounds [C. et al., 2015a]
- Statistical error modeling [Drohmann and C., 2015]

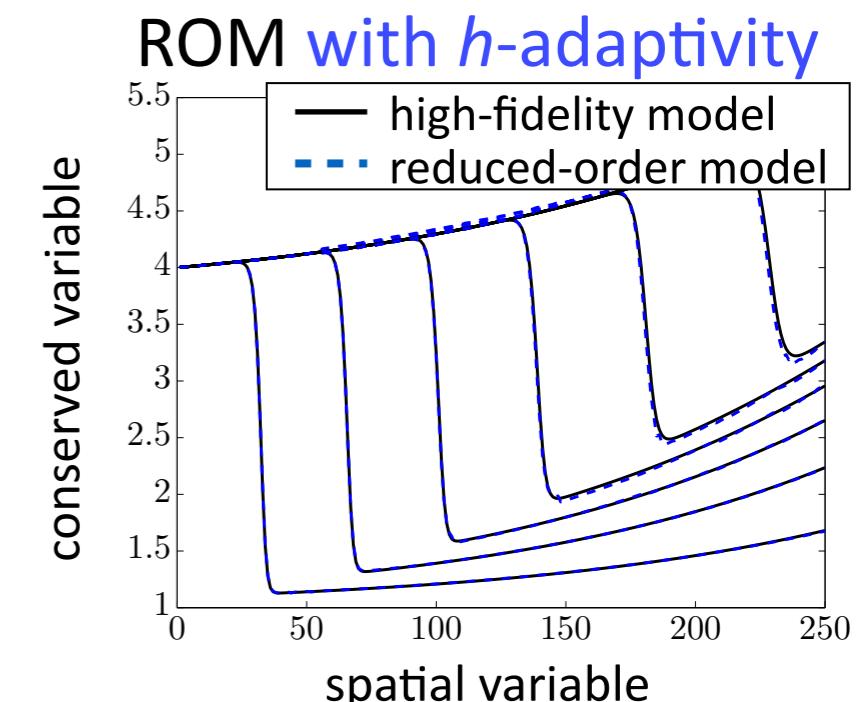
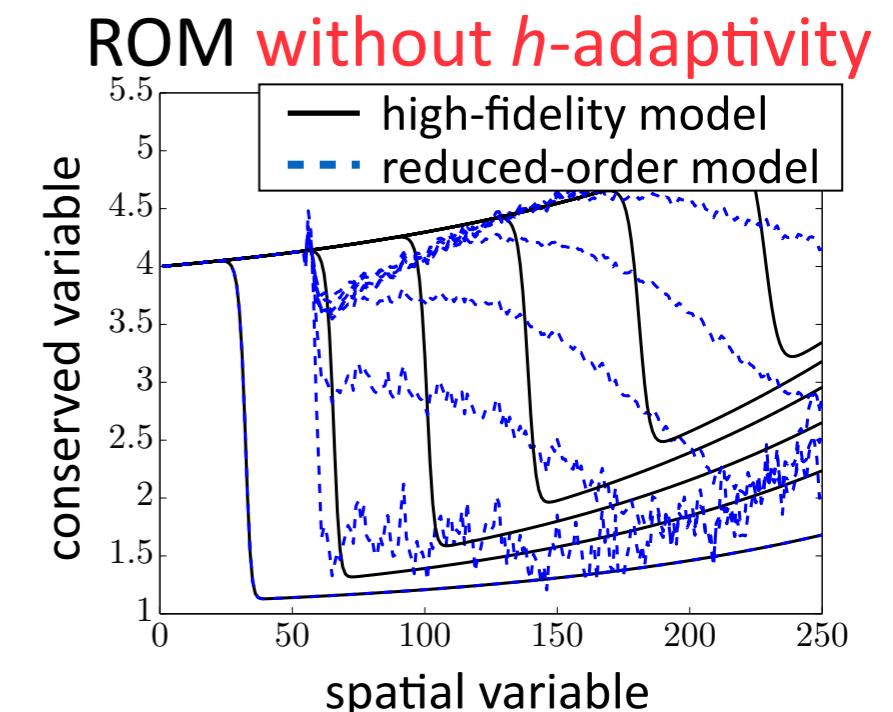
+ Reliability

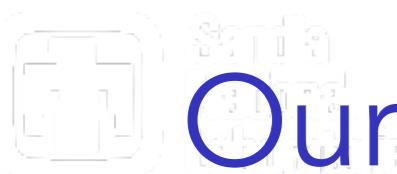
- *A posteriori h-refinement* [C., 2015]

* #2 most-cited paper, IJNME 2011

† #1 most-cited paper, JCP 2013

^ Featured Article, SISC 2015





Our research

*Nonlinear model-reduction methods that are
accurate, low cost, certified, and reliable*

+ Accuracy

- LSPG projection [C. et al., 2011*, C. et al., 2015a]
- Structure preservation [C. et al., 2015c^]

+ Low cost

- Sample-mesh approach [C. et al., 2013†]
- Leverage time-domain data [C. et al., 2015b]

+ Certification

- Error bounds [C. et al., 2015a]
- Statistical error modeling [Drohmann and C., 2015]

+ Reliability

- *A posteriori* h -refinement [C., 2015]

+ HPC implementation

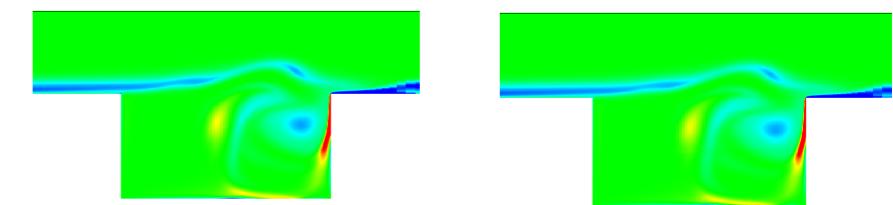
- Three computational-mechanics codes

* #2 most-cited paper, IJNME 2011

† #1 most-cited paper, JCP 2013

^ Featured Article, SISC 2015

SPARC

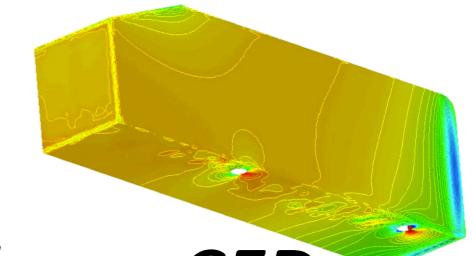
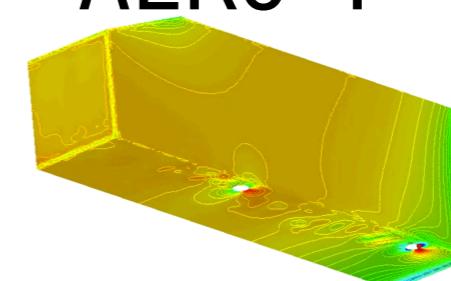


finite volume CFD



finite element multiphysics

AERO-F



finite volume CFD



\$3.1M Funding

2011–2014	<i>LDRD: Truman Fellowship</i> \$260k/year 3 postdocs, 1 summer student
2014–present	<i>NNSA/ASC/V&V: Fluid dynamics</i> \$250k/year 4 staff, 1 postdoc
2014–present	<i>NNSA/ASC/V&V: Thermomechanics</i> \$425k/year 3 staff, 2 postdocs, 1 summer student
2014–present	<i>NNSA/ASC/V&V: Nonlinear model reduction</i> \$200k/year 2 staff, 1 postdocs, 1 summer student
2015–present	<i>LDRD: Model reduction in extreme-scale networks</i> \$500k/year 3 staff, 2 postdocs, 1 summer student



Interdisciplinary team

Computational mathematics



Fluid dynamics

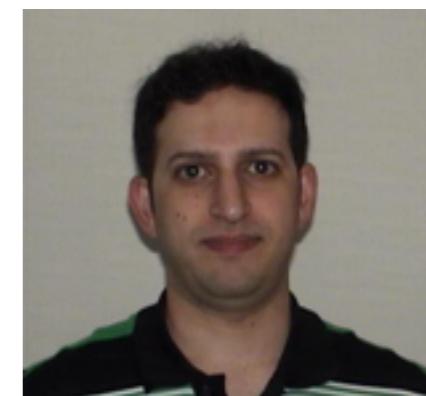
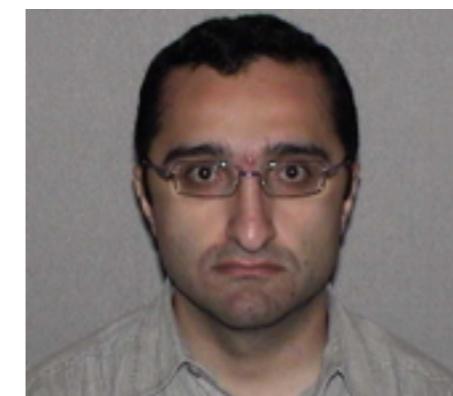


Optimization

Thermomechanics



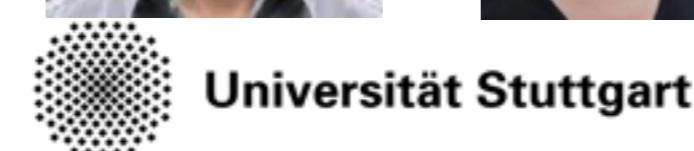
Uncertainty Quantification





External collaborators

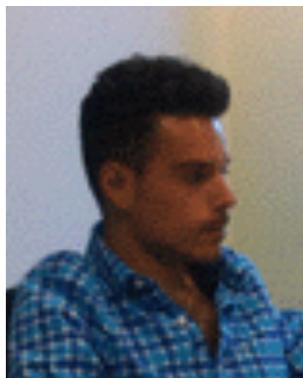
Faculty



Lawrence Berkeley National Laboratory



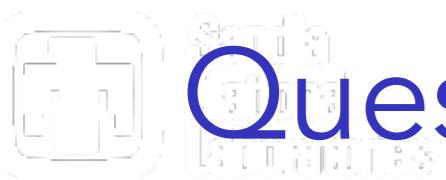
Students and Postdocs





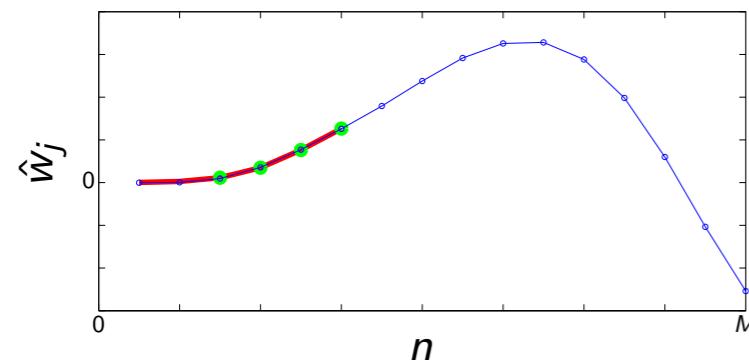
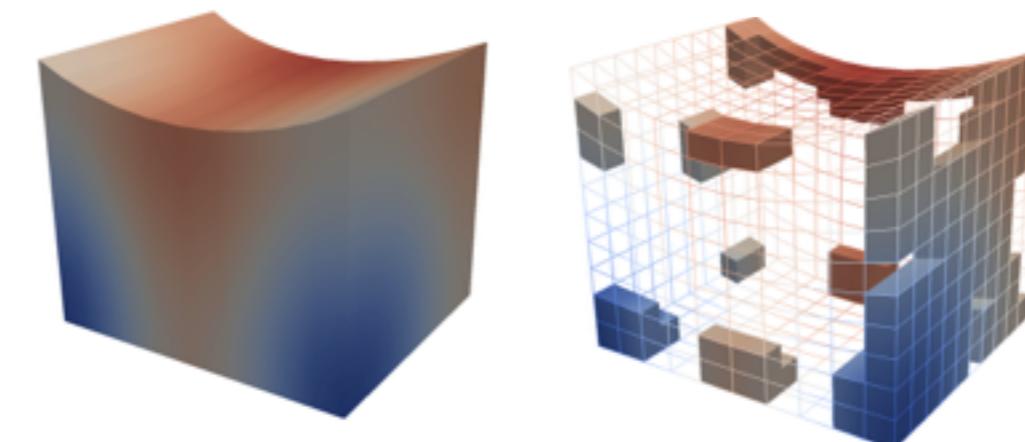
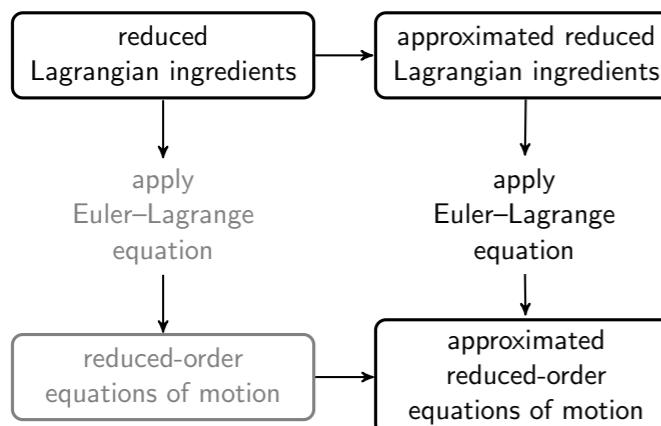
Summary

- 15 publications
 - *Featured article*, June 2015, SIAM J Sci Comput
 - *#1 most cited paper*, 2013, J Comput Phys
 - *#2 most cited paper*, 2011, Int J Numer Meth Eng
- 35 presentations
 - *Keynote lecture*: Model Order Reduction & Machine Learning, 2016
 - 13 invited talks (including MIT, Stanford, UC Berkeley, Cornell)
- Implementation in 3 HPC codes
- Team and funding
 - Span research and development spectrum
 - Range of real-world problems and applications
 - *Internal*: 13 staff, 6 postdocs
 - *External*: 13 faculty, 14 students/postdocs

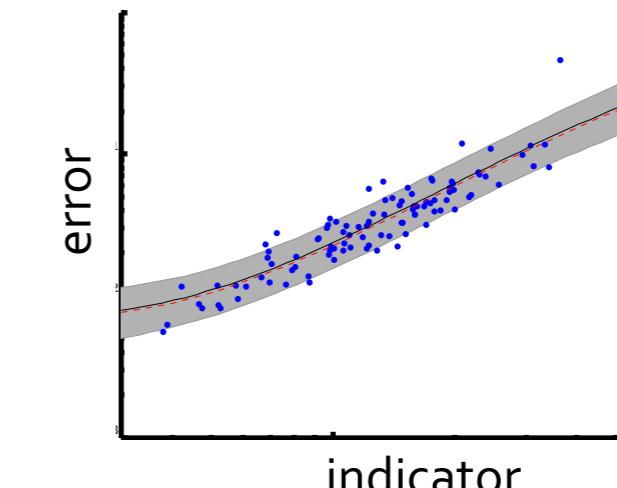


Questions?

12

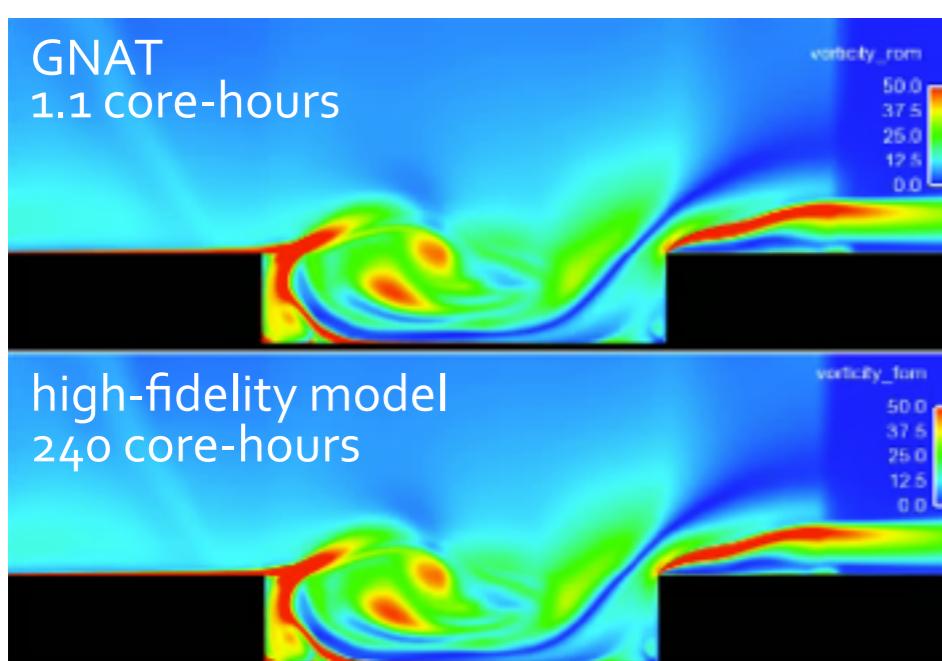


\hat{w}_j so far; memory $\alpha = 4$; forecast

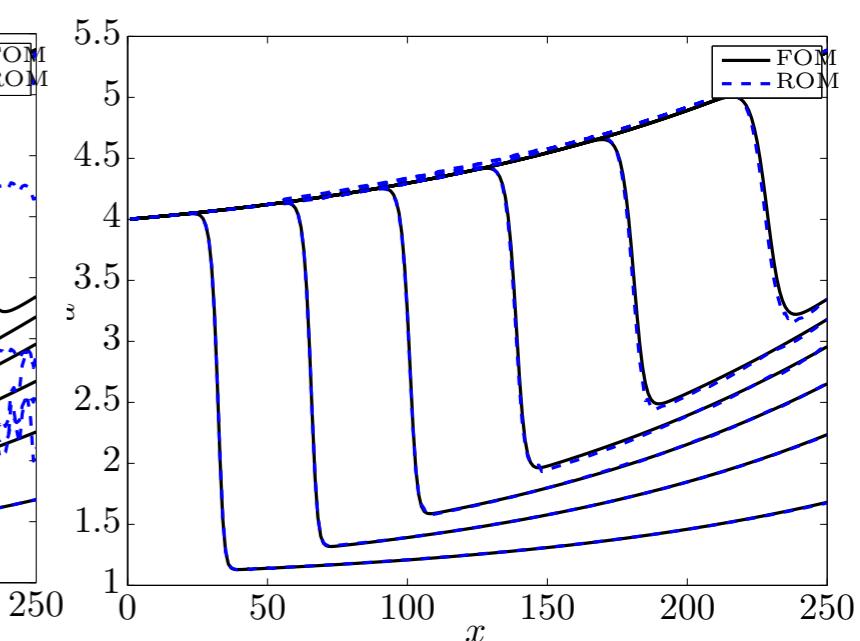
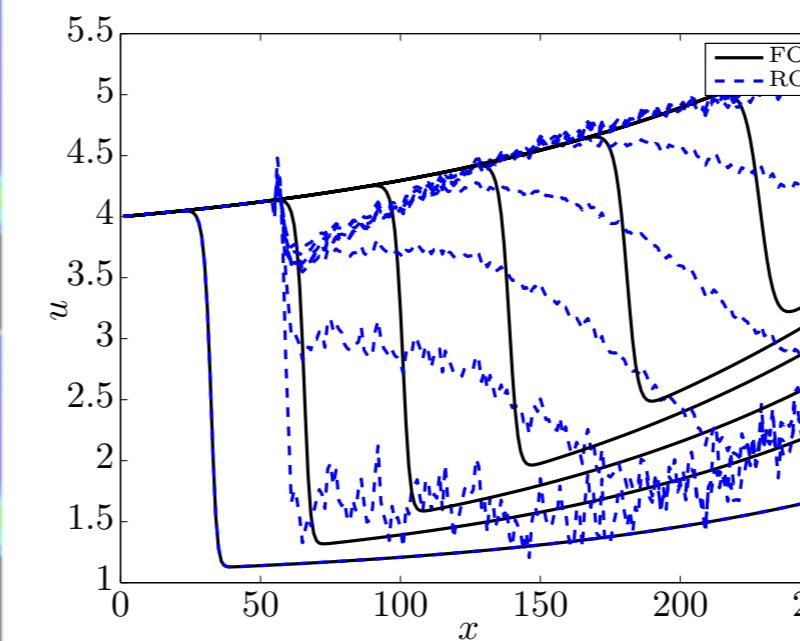


ROM

ROM with h -adaptivity



Nonlinear model reduction



Kevin Carlberg