

Exceptional service in the national interest

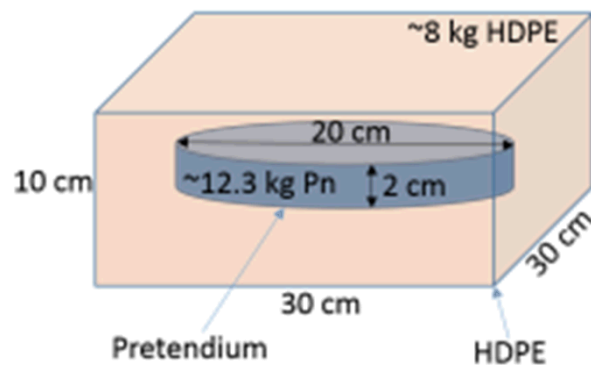


CONFIRMATION using a Fast-neutron Imaging Detector with Anti-image NULL-positive Time Encoding (CONFIDANTE)

Peter Marleau

Challenge problem

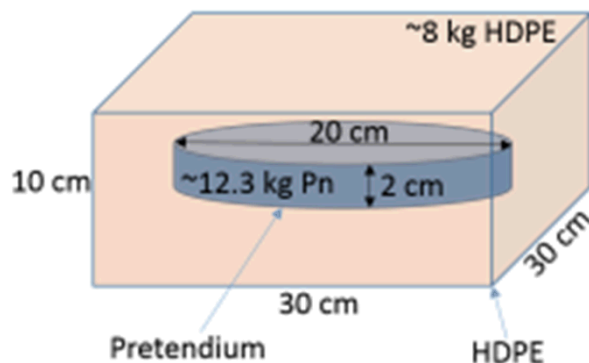
- The inspecting party has or had access to measure item T, which is known to be a valid type 1 treaty accountable item (TAI) through some other mechanism.



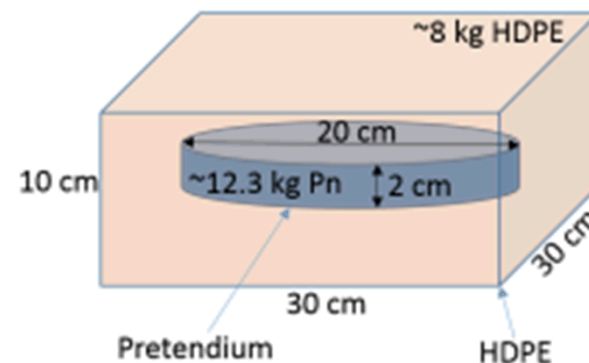
**Object T = valid
type 1 TAI**

Challenge problem

- The inspecting party has or had access to measure item T, which is known to be a valid type 1 TAI through some other mechanism.
- In the course of an inspection, the host presents item X and declares it as a type 1 TAI
- Item X should pass the verification measurement if it is a type 1 TAI, and fail if it is significantly different.



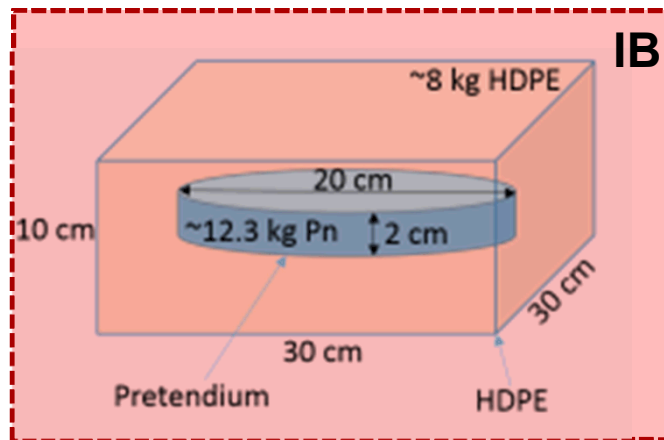
**Object T = valid
type 1 TAI**



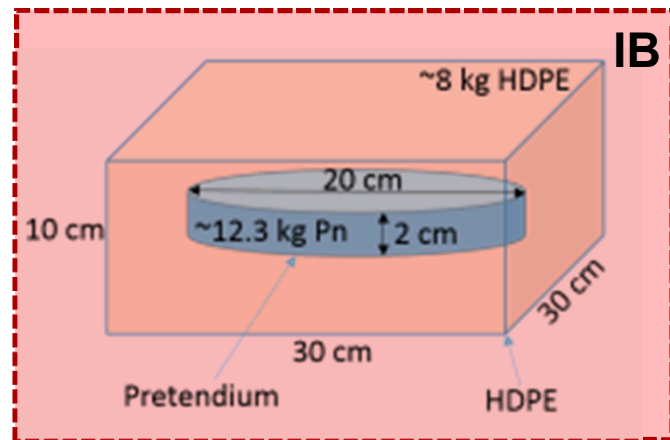
Object X = ?

Challenge problem

- The inspecting party has or had access to measure item T, which is known to be a valid type 1 TAI through some other mechanism.
- In the course of an inspection, the host presents item X and declares it as a type 1 TAI
- Item X should pass the verification measurement if it is a type 1 TAI, and fail if it is significantly different.
- The host must be confident that the inspector has not learned the diameter d of the pretendium in item X, or any type 1 TAI



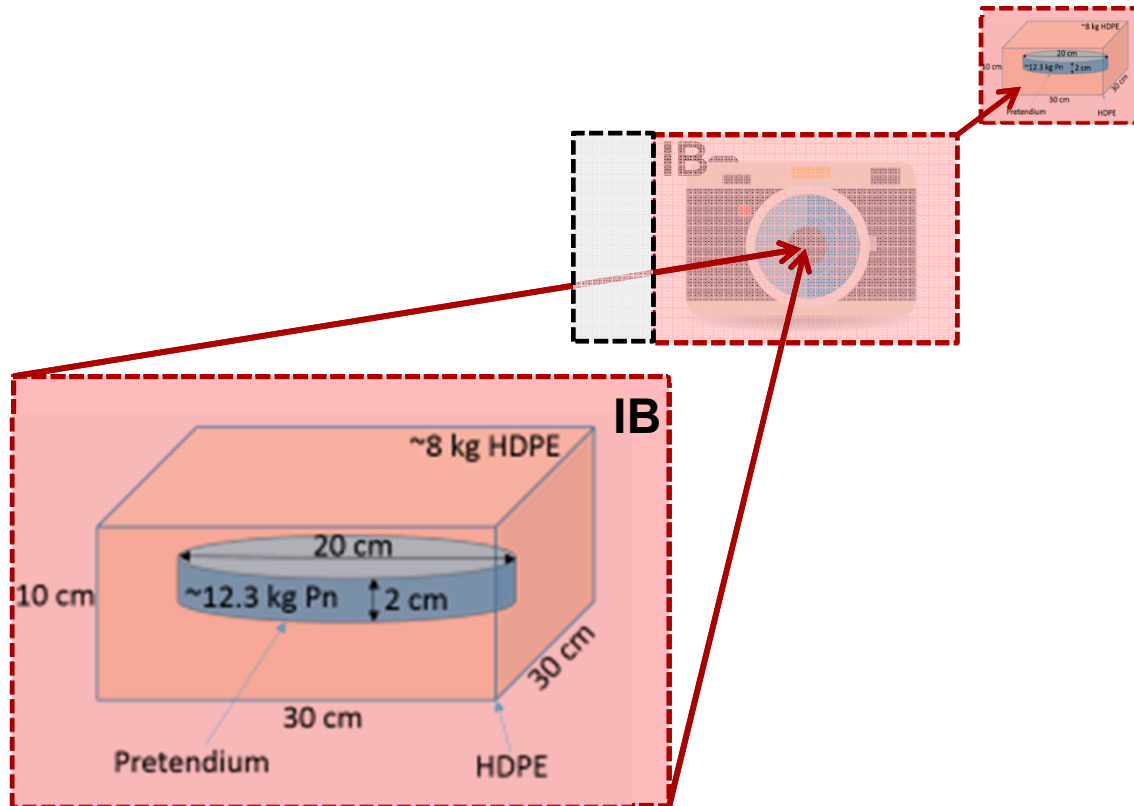
**Object T = valid
type 1 TAI**



Object X = ?

Templates - generation

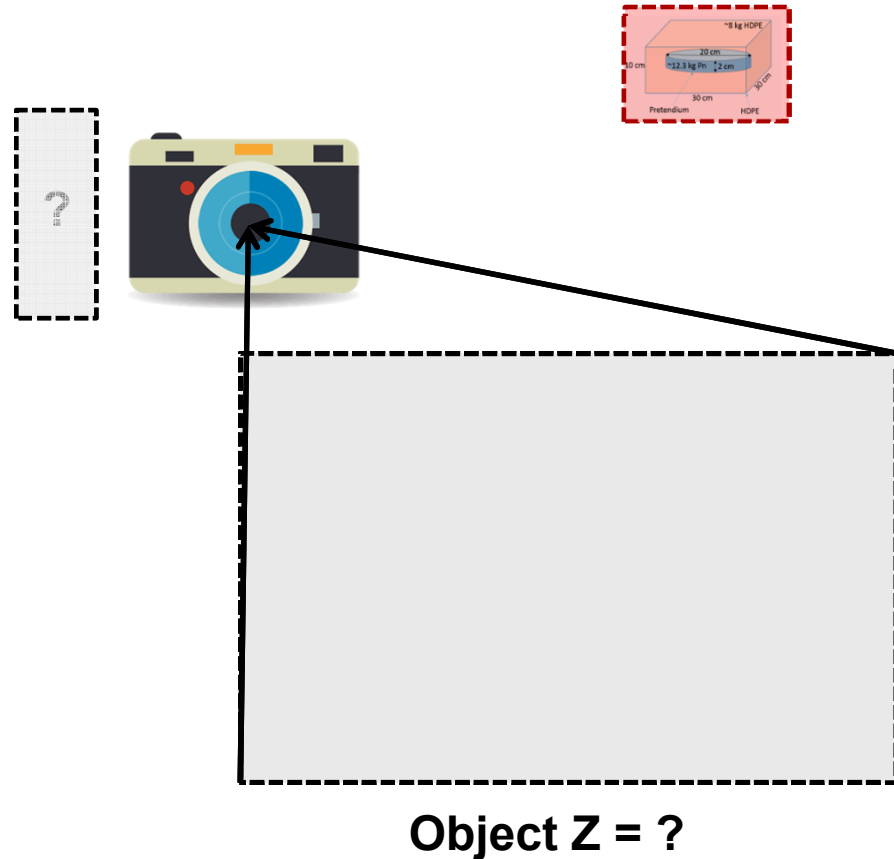
- We could generate a template behind an information barrier (IB) ...



**Object T = valid
type 1 TAI**

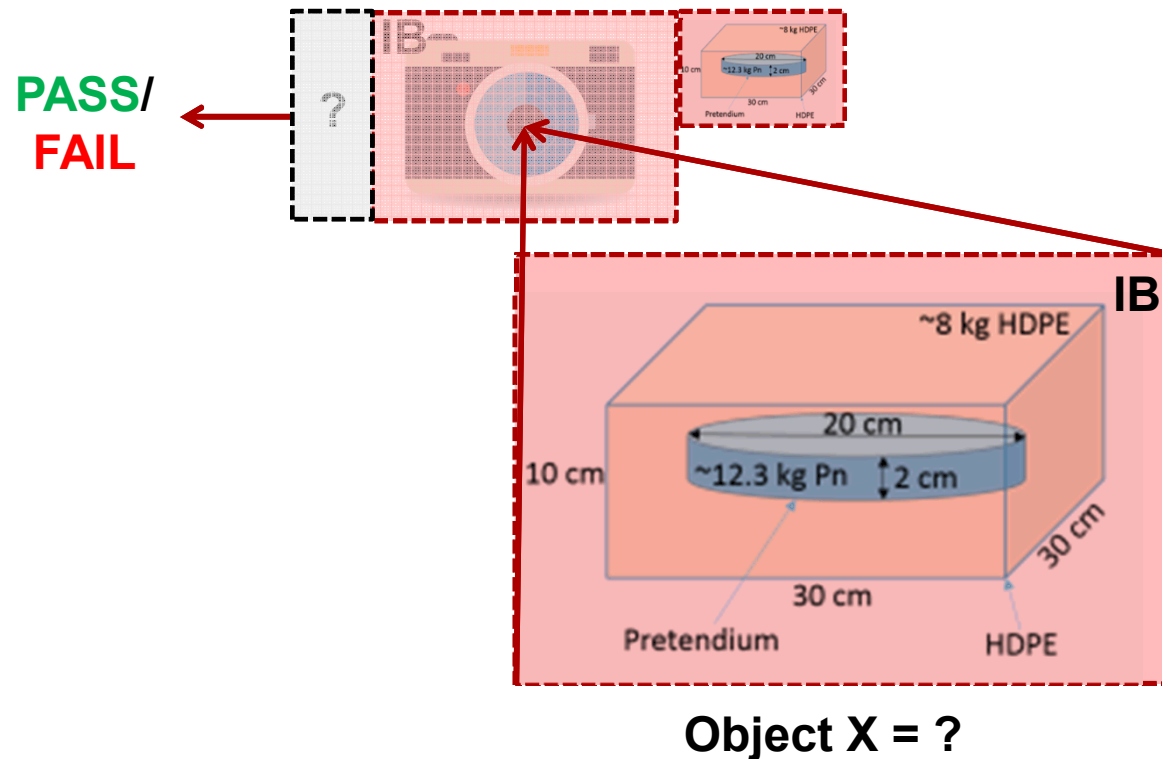
Templates - authentication

- Authenticate equipment ...



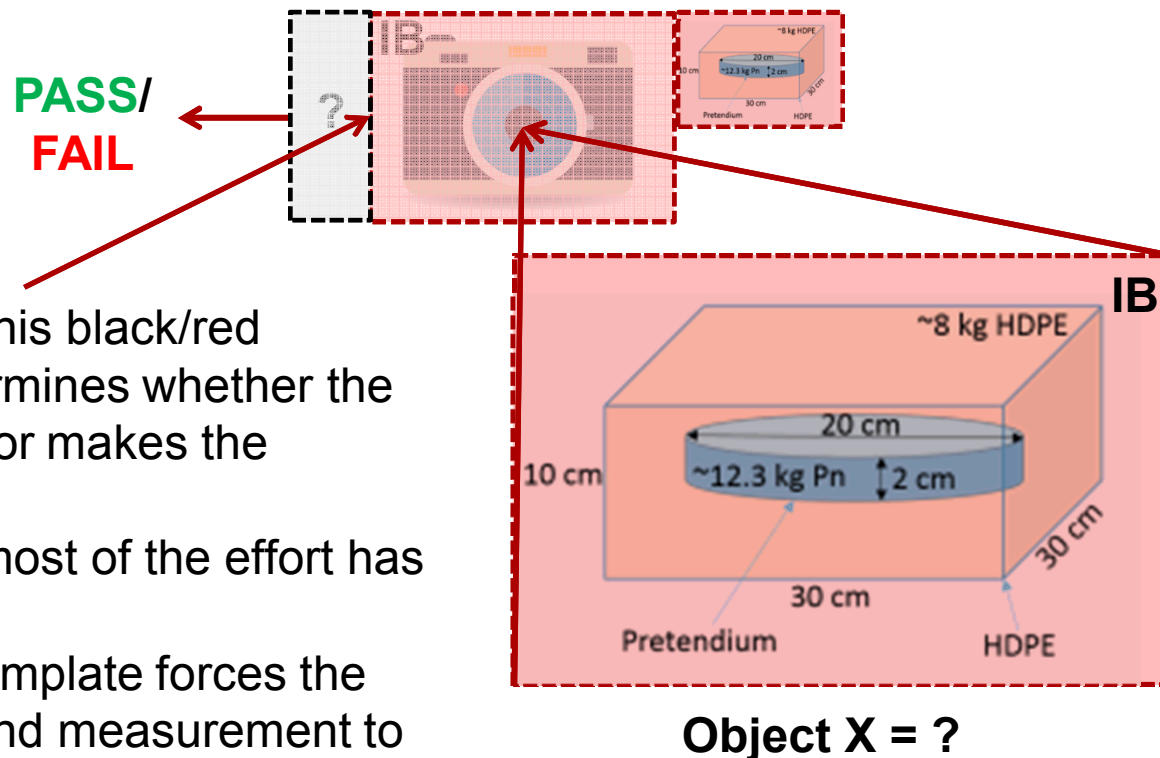
Templates - comparison

- Make comparison measurement...



Templates – who measures?

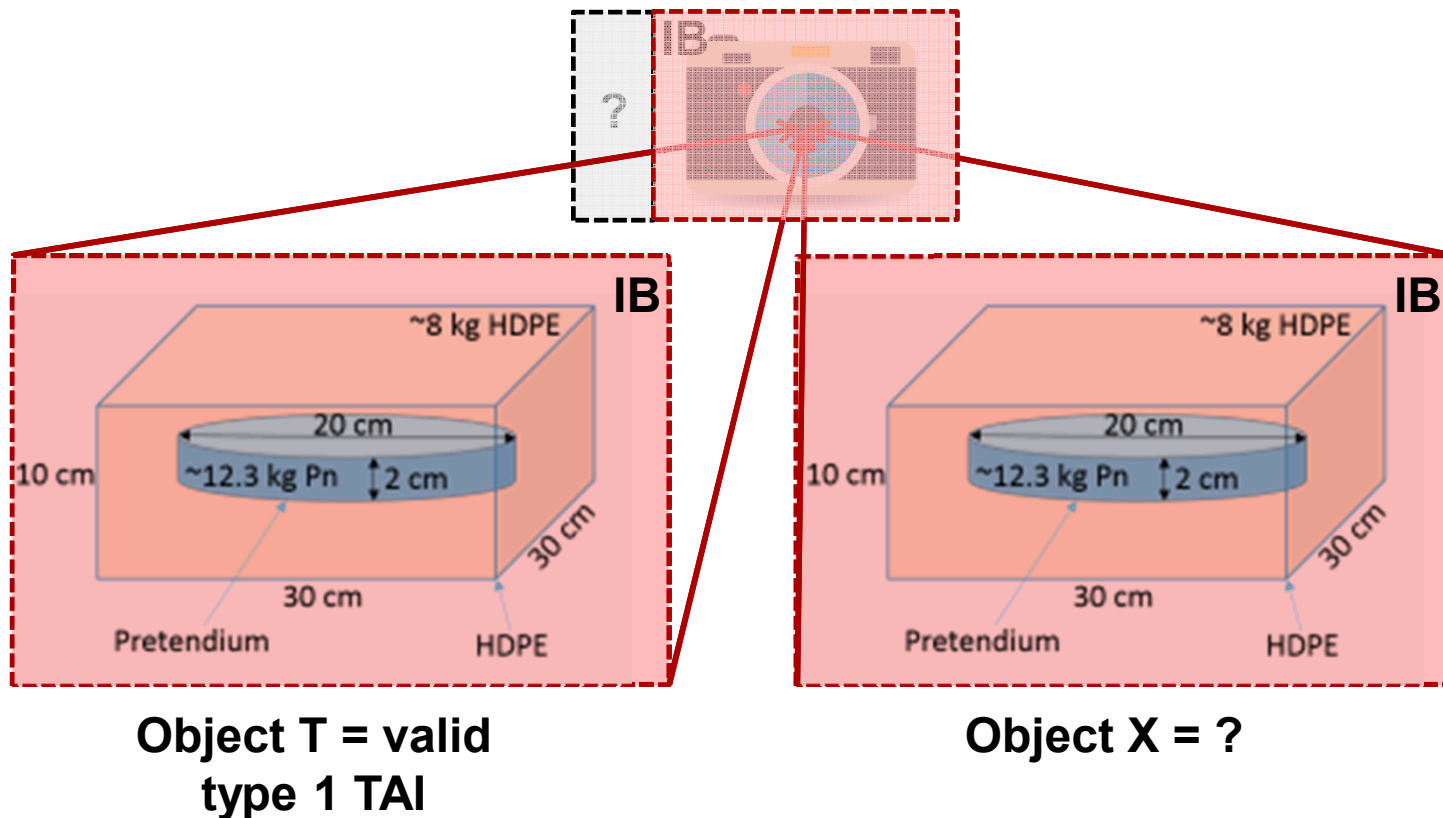
- Who makes the measurement? Is the measurement itself authenticatable?



- The nature of this black/red boundary determines whether the host or inspector makes the measurement.
- This is where most of the effort has gone.
- At worst, the template forces the entire device and measurement to be behind an IB.

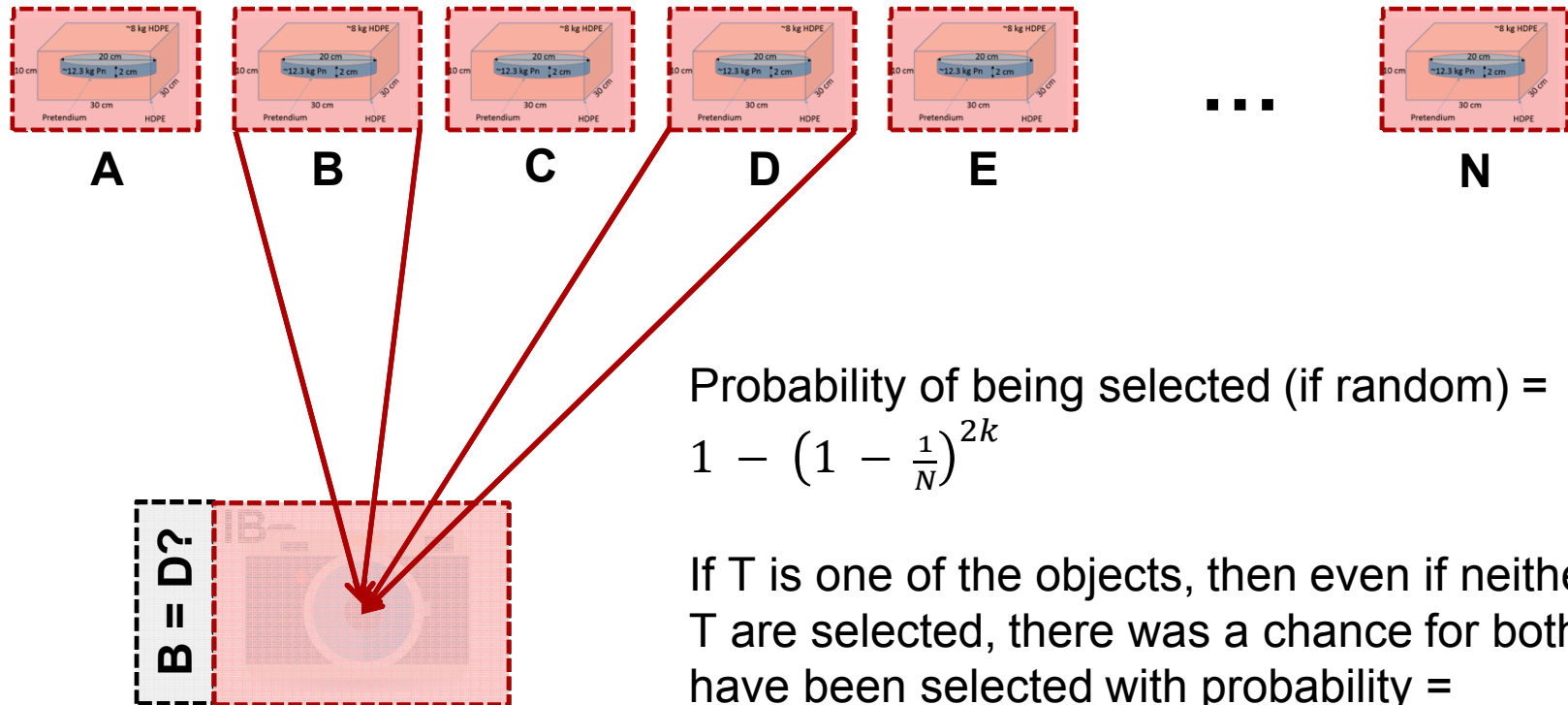
Proposal – comparison measurements

- Can we compare two objects directly without generating a template?
- If one object is T, then X is confirmed as a type 1 TAI.
- If neither object is T, then they are confirmed to be identical, but not T.
- If multiple object comparisons are confirmed and even one is T, then all objects are confirmed as type 1 TAIs.



Proposal – CONOPS and Inspector choice

- Presented with N objects and k comparison measurements will be made.



Probability of being selected (if random) =
 $1 - \left(1 - \frac{1}{N}\right)^{2k}$

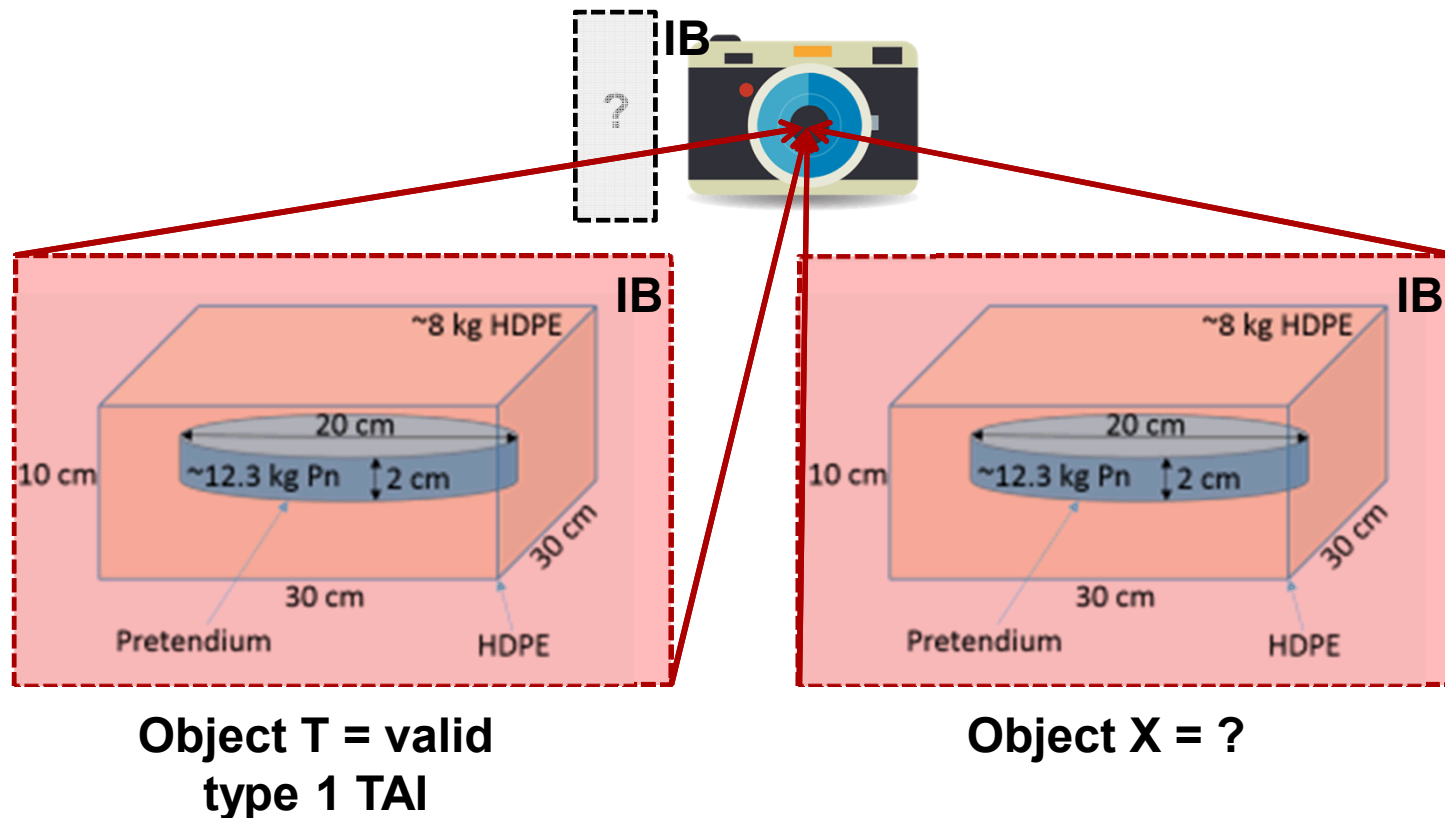
If T is one of the objects, then even if neither X nor T are selected, there was a chance for both to have been selected with probability =

$$\left(1 - \left(1 - \frac{1}{N}\right)^{2k}\right)^2$$

providing some degree of confidence

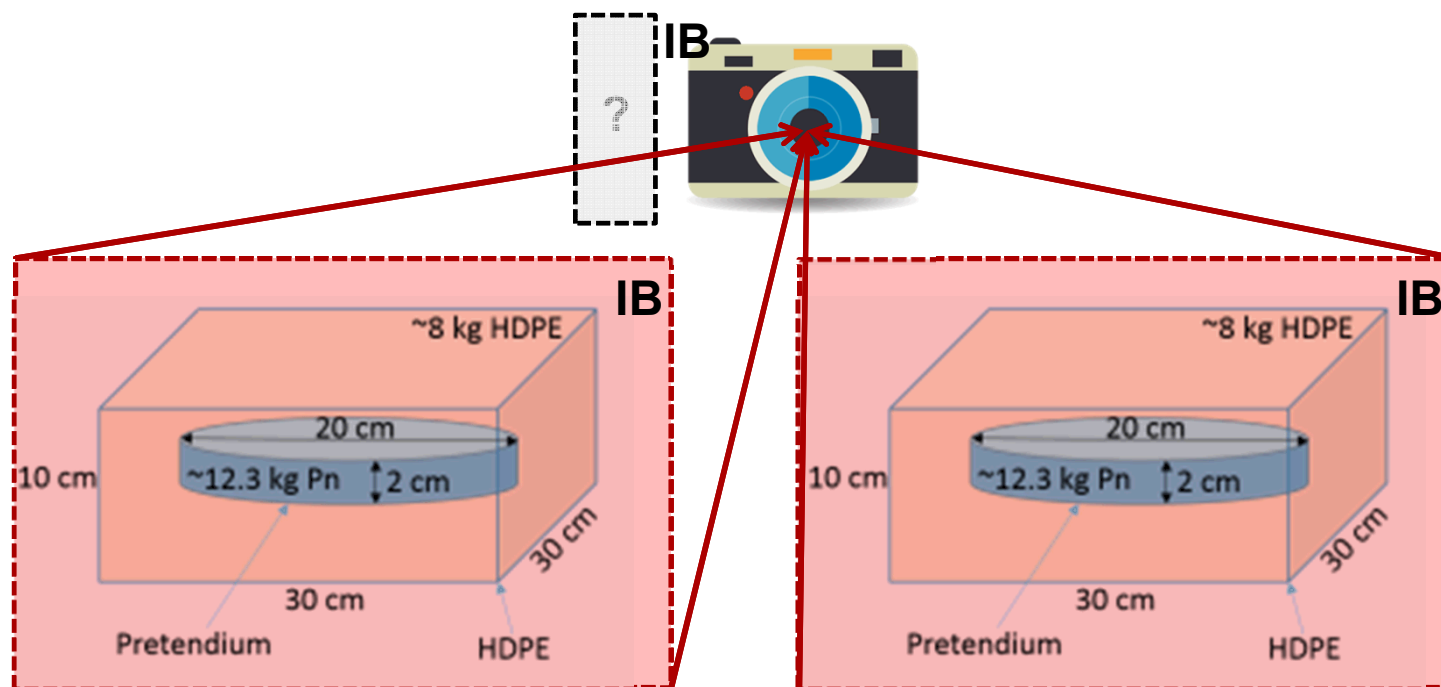
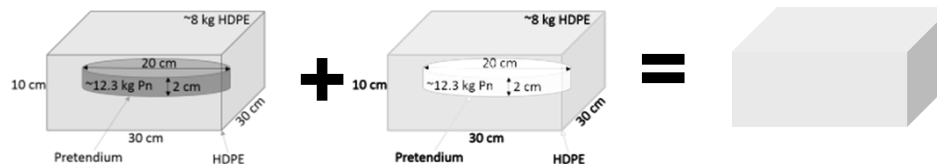
Proposal – comparison measurements

- Is there a physical implementation of the confirmation measurement that the inspector can watch and authenticate?
- **It would be great if we could get a physical NULL as an indication of positive confirmation at all times, even during the measurement.**



Proposal – complementary comparison

- What we need is to turn one image into the complement of the other *at all times*.

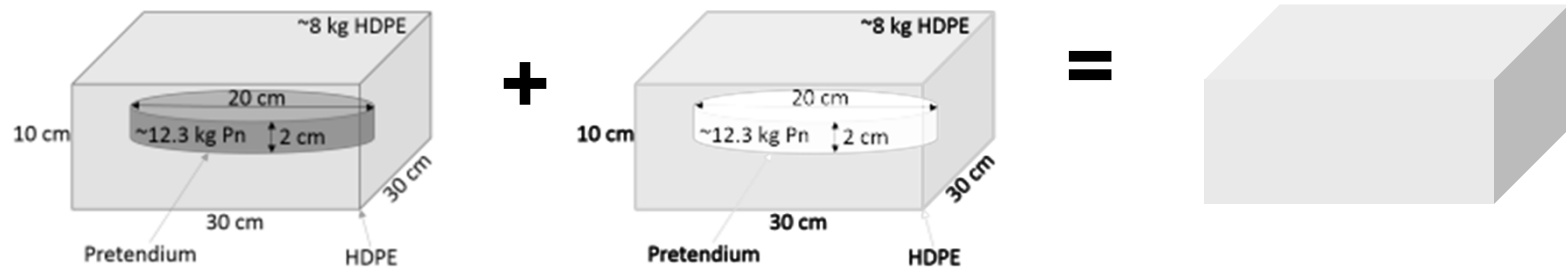


**Object T = valid
type 1 TAI**

Object X = ?

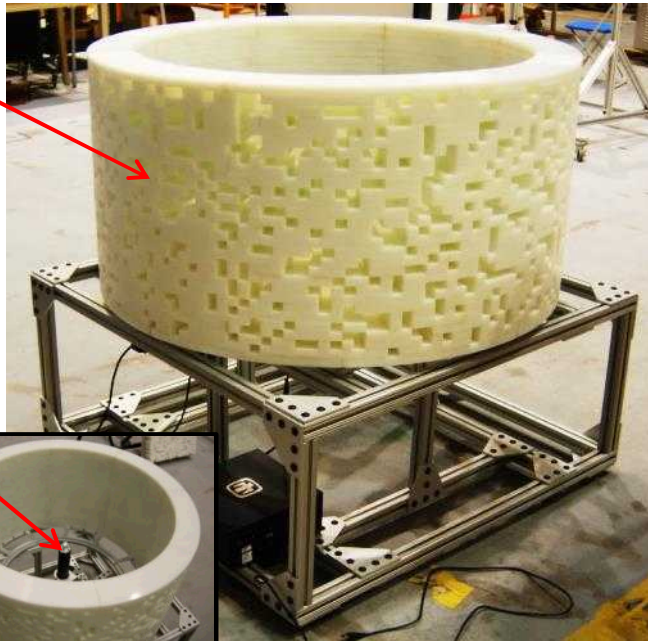
Ok, but how? ...

- One image is the complement of the other ***at all times***.

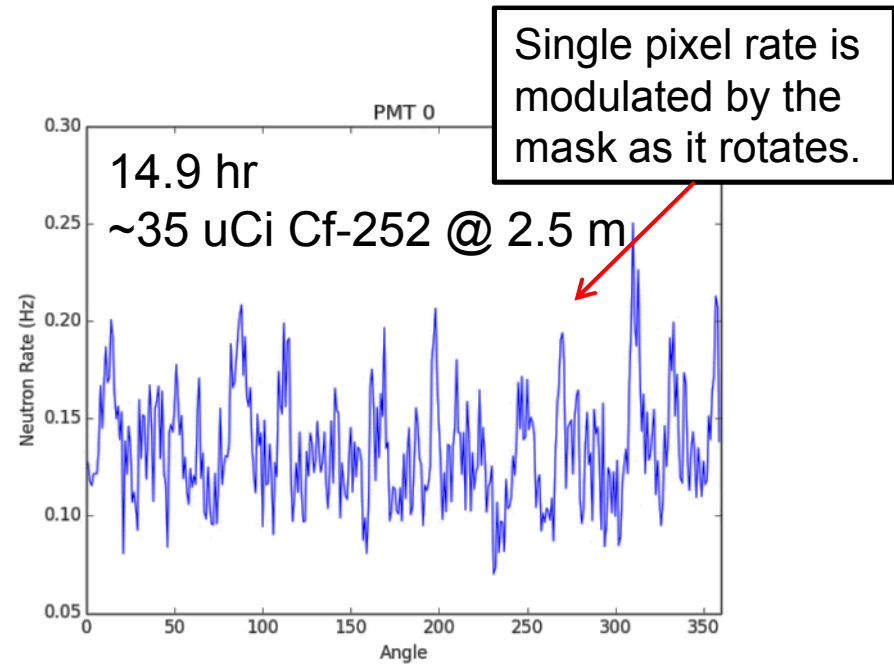


2D Time-encoded Imaging (TEI)

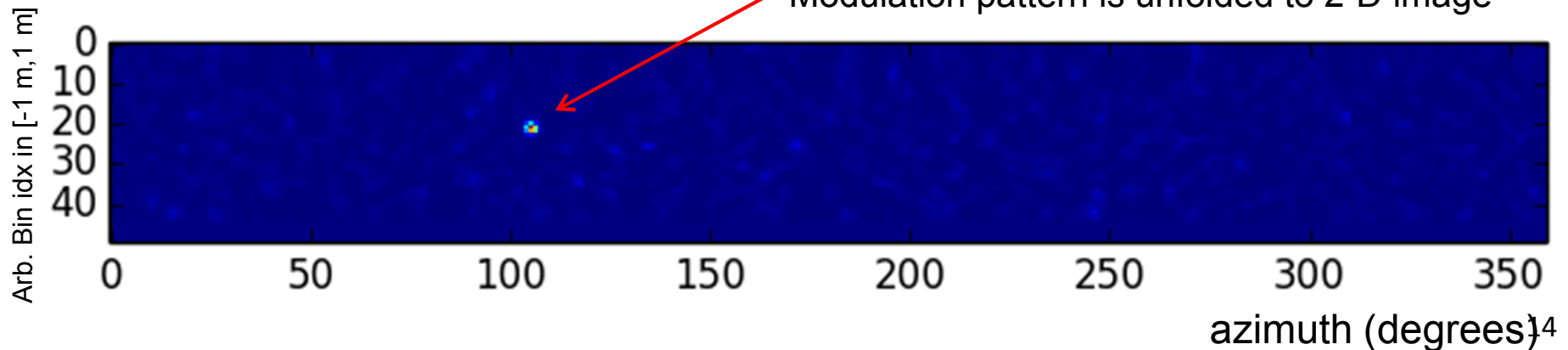
2-d
coded
mask



Single
1"D x 1"
LS pixel



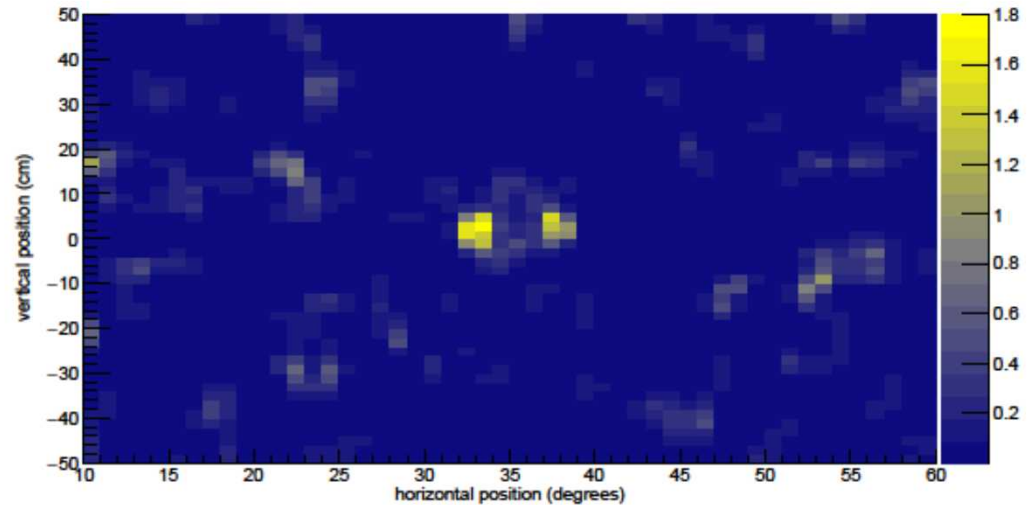
Modulation pattern is unfolded to 2-D image



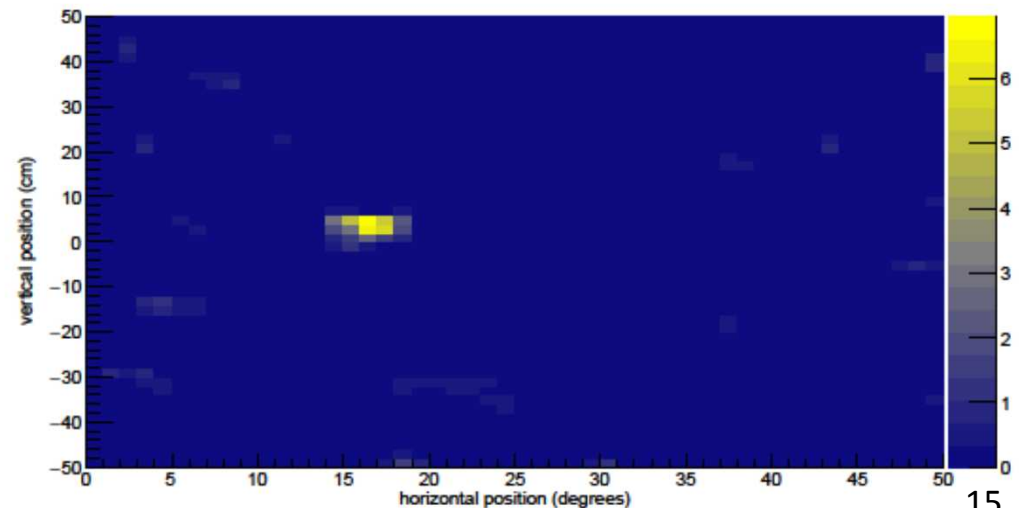
TEI-2D imaging – two point sources

Two 1.4×10^5 n/s ^{252}Cf point sources at 2.0 meters stand-off.

5 degree separation in 1 hour
(50 mlem iterations)



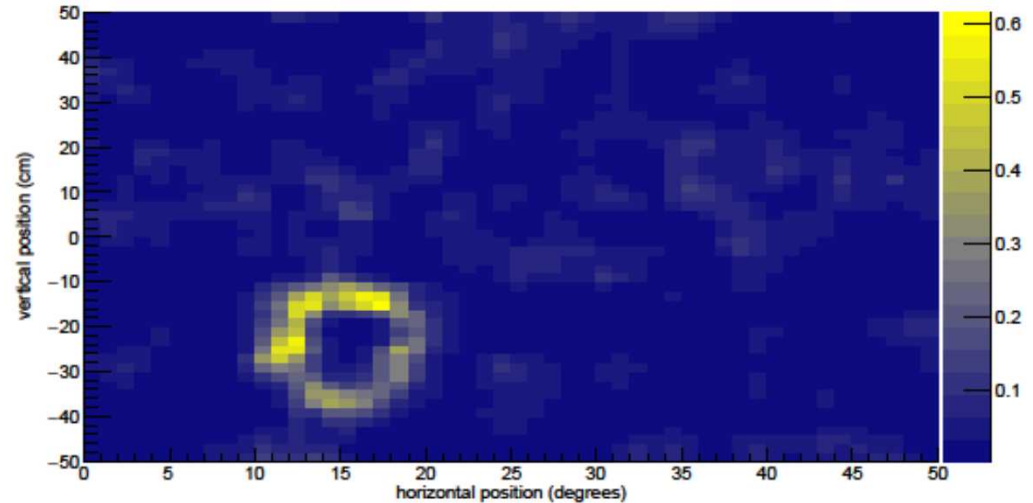
2 degree separation in 24 hours
(250 mlem iterations)



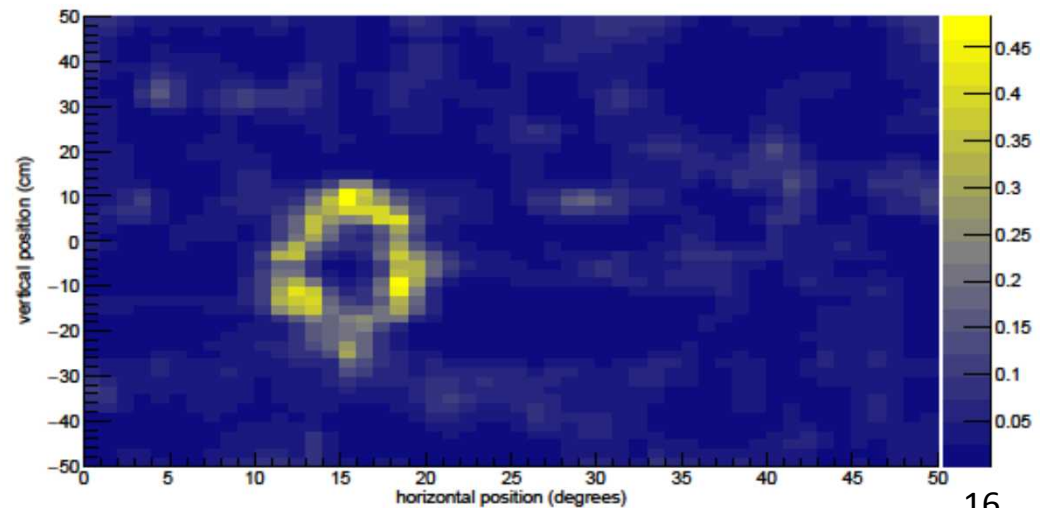
TEI-2D imaging – extended sources

A single 1.4×10^5 n/s ^{252}Cf source move through an extended pattern at 2 m.

72 hours
(100 mlem iterations)

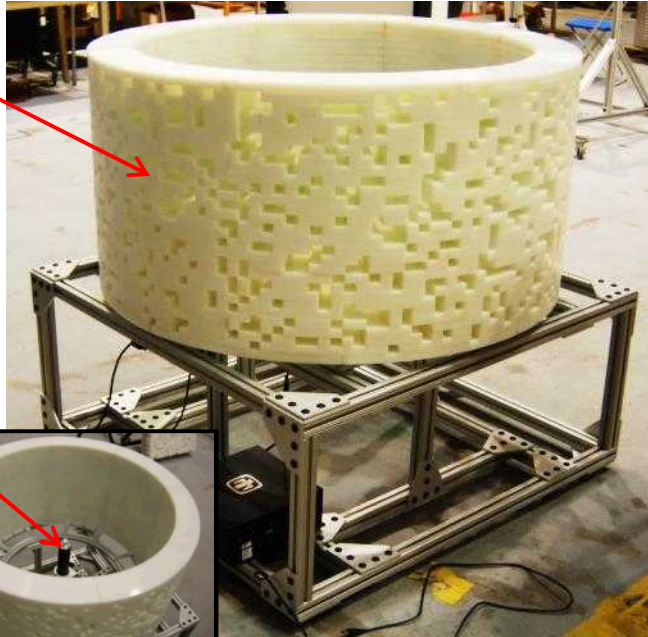


94 hours
(100 mlem iterations)



2D TEI – confirmation measurements?

2-d
coded
mask

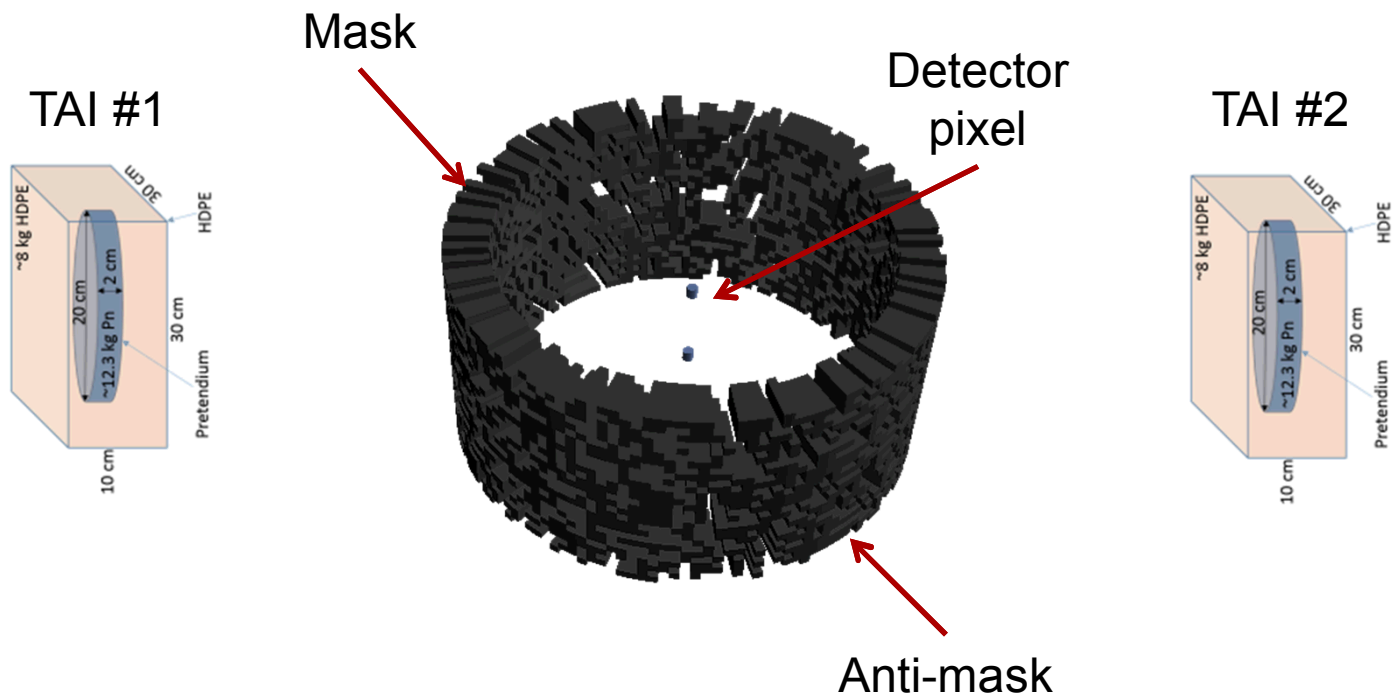


Single
1"D x 1"
LS pixel

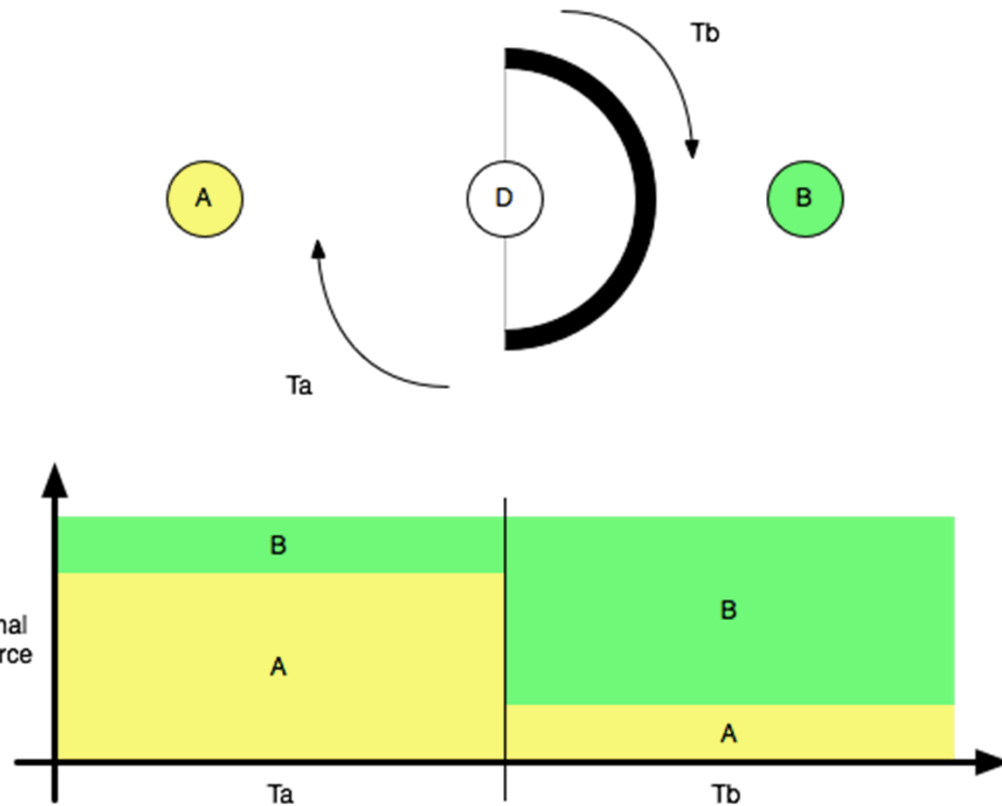
- **TEI is simple**
 1. Only one instrumented channel.
 2. Minimal calibration issues
 - a) Information encoded in the relative rate of a single detector.
 - b) Absolute gain doesn't matter.
 - c) Gain can drift over time.
 3. Potential real-time analysis
 - a) Single data stream.
 - b) Events can be processed one at a time and update a test statistic.
- **Can we design a TEI confirmation system such that the detection rates can be monitored by an inspector without putting sensitive information at risk?**

Here's where the magic happens ...

If the mask is designed such that one side is the anti-mask of the other,
then **TAI #2 projects the anti-image of TAI #1 at all times**
if and only if they are identical!

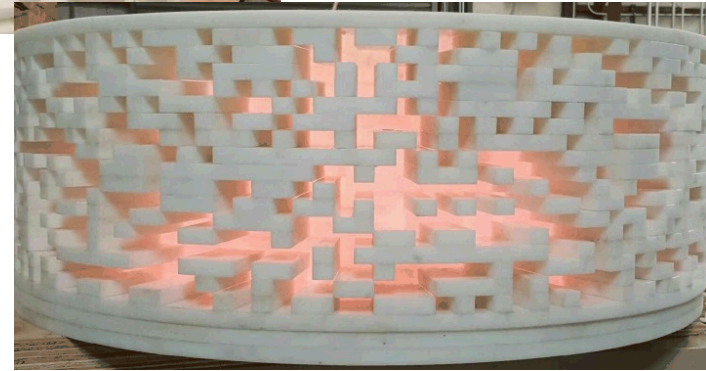
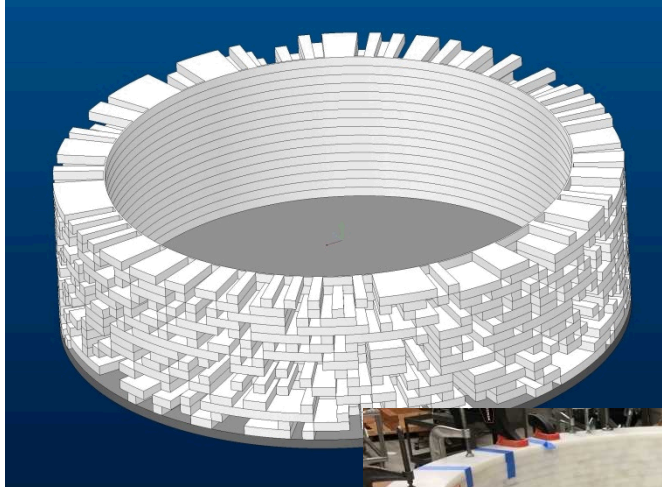


A very simple example



- For example, take a very simple mask: half mask, half aperture.
- The fraction of total count rate coming from A and B is unknown at any given angle.
- In this example, the location (and shape) of the boundary between regions is not revealed.

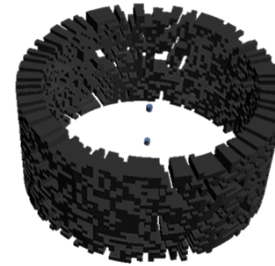
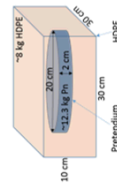
We're working on it



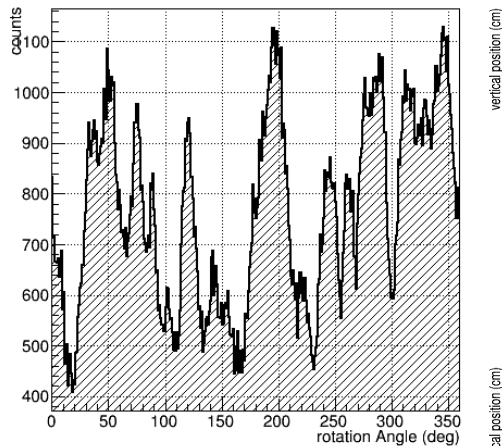
Modeling results - Single type 1 TAI (5e5 counts)

The system still functions as a standard TEI imager for any single object.

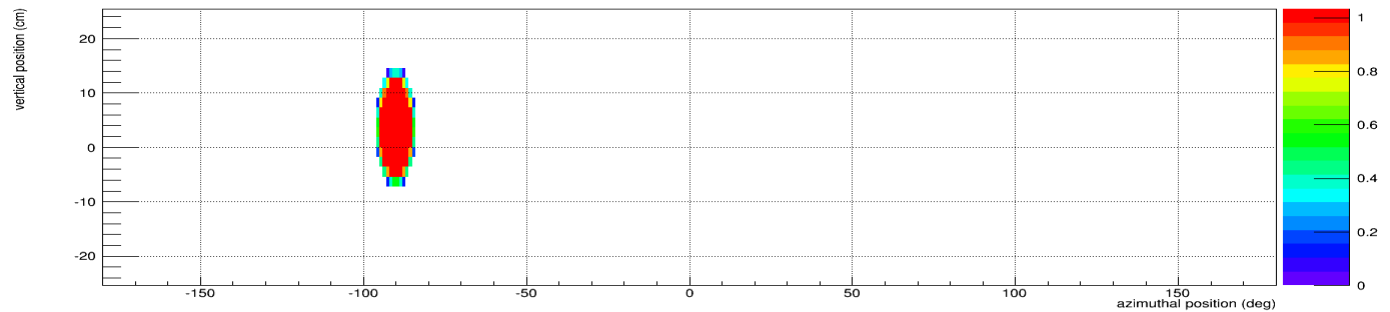
TAI T



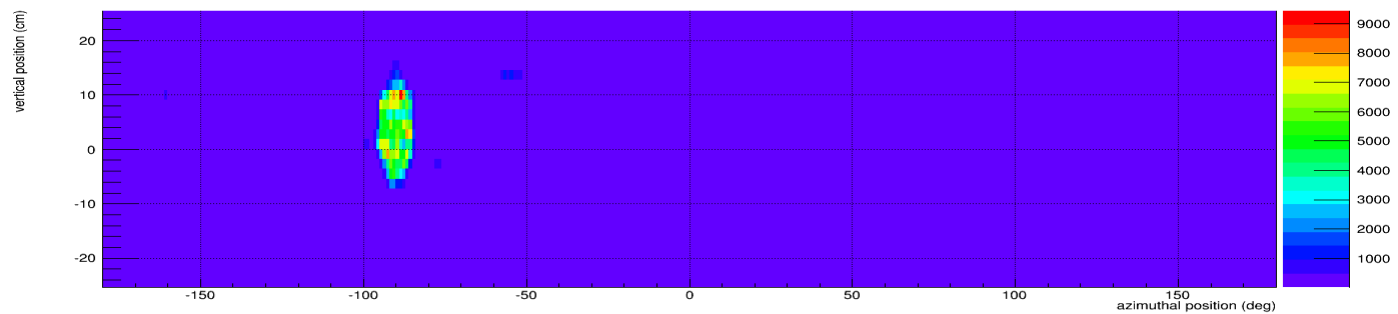
Pixel Counts



Iso-Background plus Source

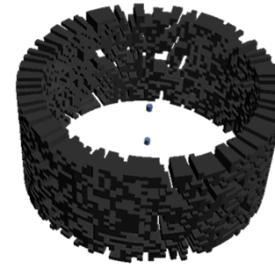
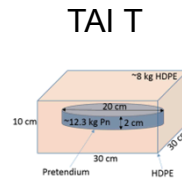


Reconstructed Image (MLEM)

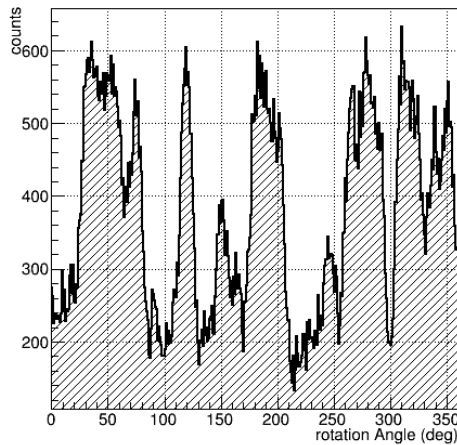


Modeling results - Single type 1 TAI (2.5e5 counts)

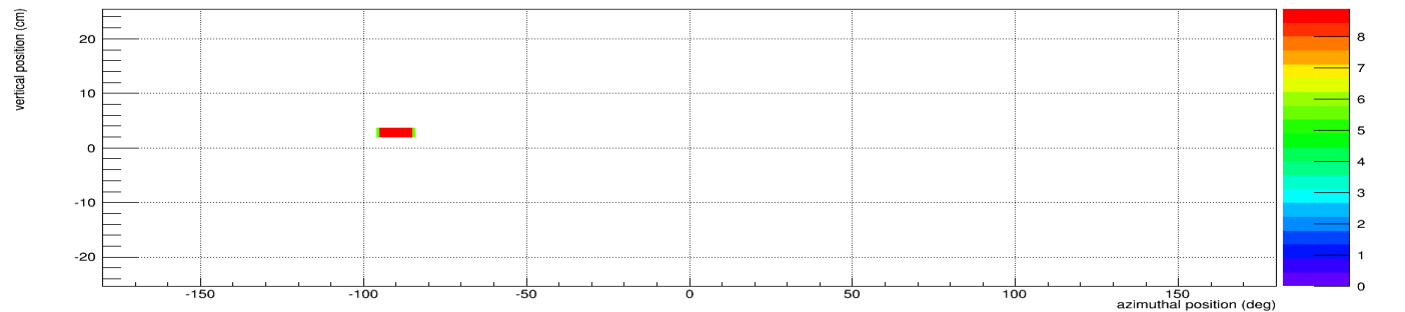
This orientation provides better discrimination between objects T and F.



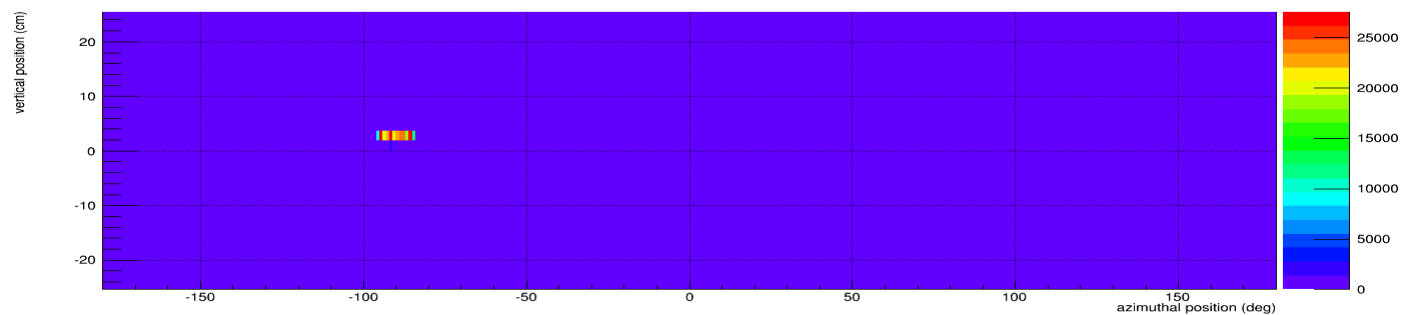
Pixel Counts



Iso-Background plus Source

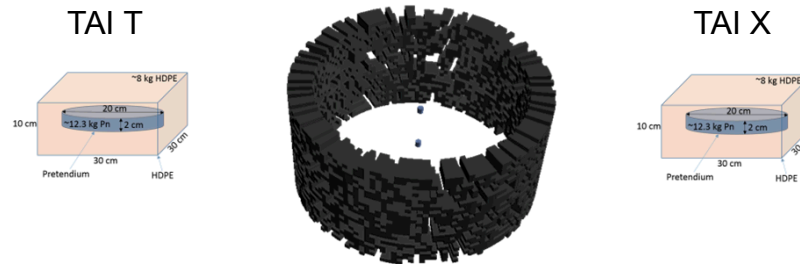


Reconstructed Image (MLEM)

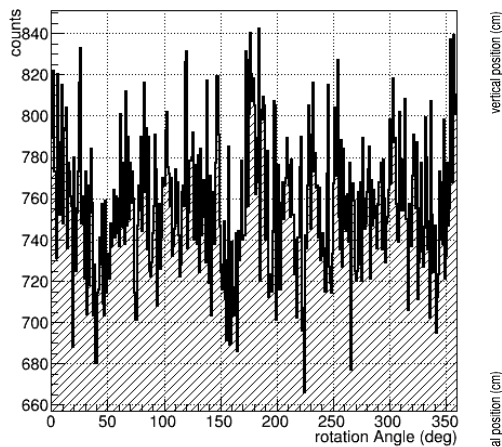


Modeling results – T vs. X (5e5 counts)

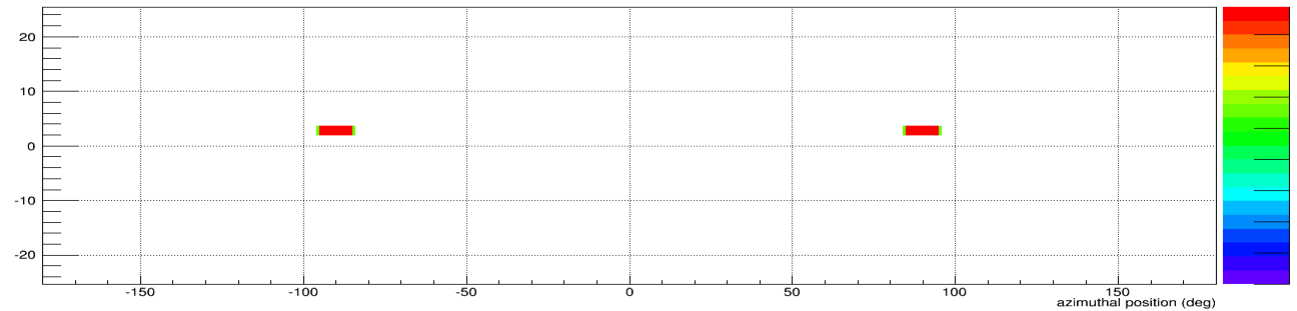
True “null”-positive
confirmation comparison
measurement between
two type 1 TAIs.



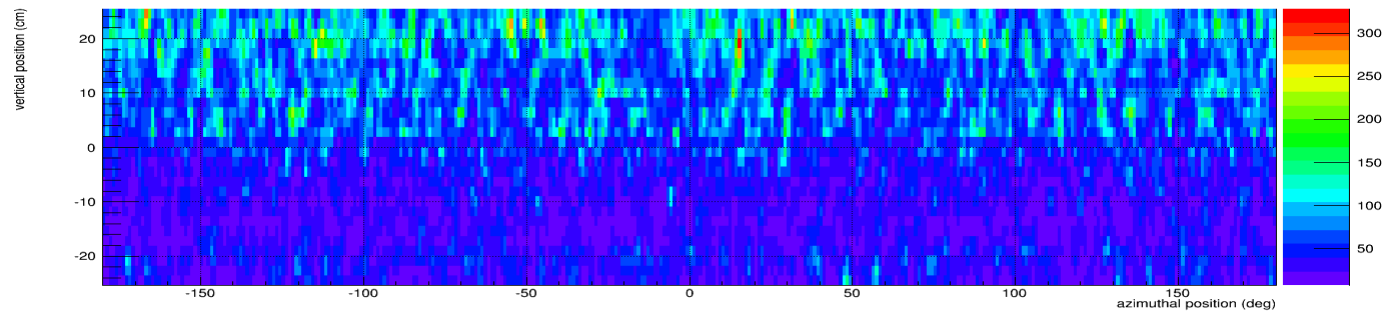
Pixel Counts



Iso-Background plus Source



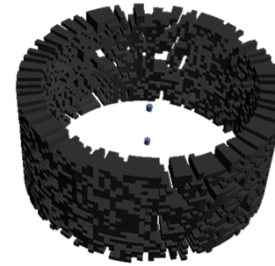
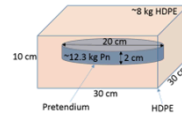
Reconstructed Image (MLEM)



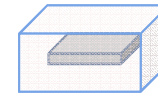
Modeling results – T vs. F (5e5 counts)

True non-null-negative
confirmation comparison
measurement between
objects T and F.

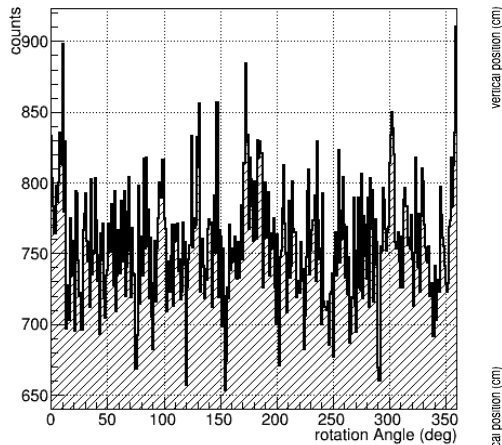
TAI T



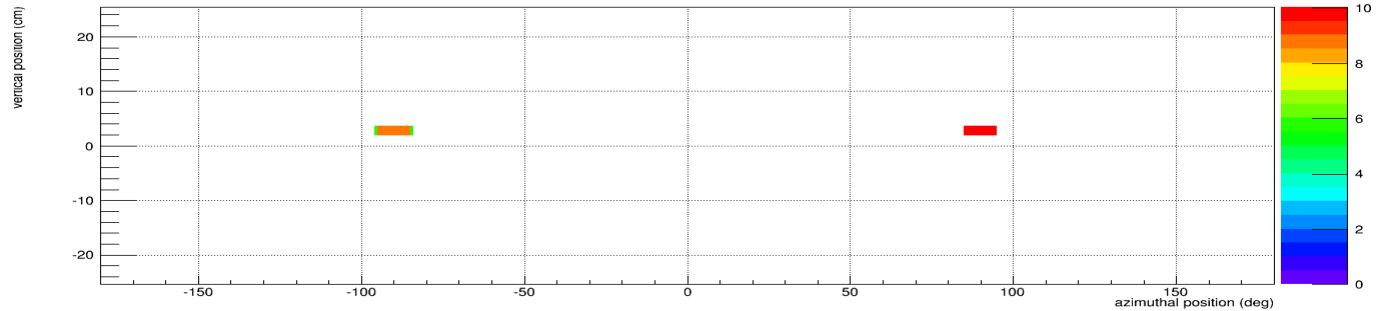
TAI F



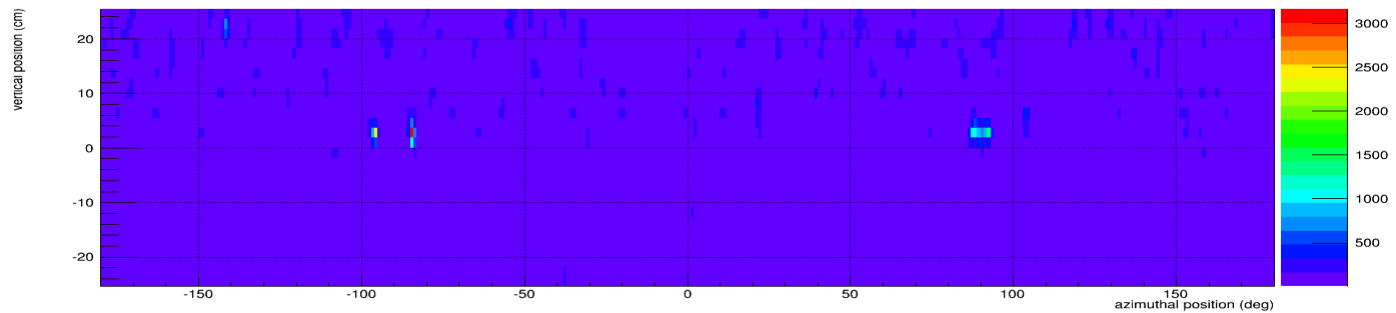
Pixel Counts



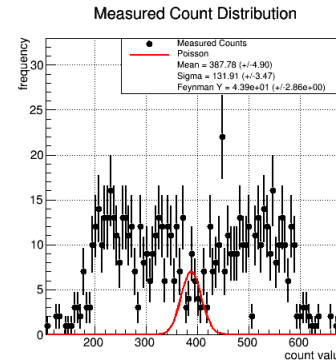
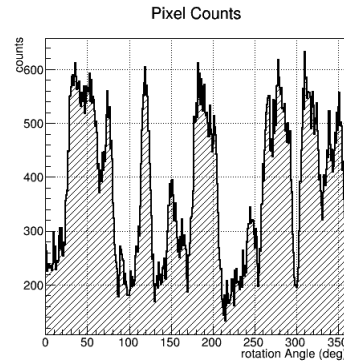
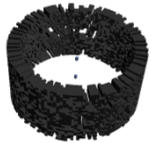
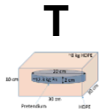
Iso-Background plus Source



Reconstructed Image (MLEM)

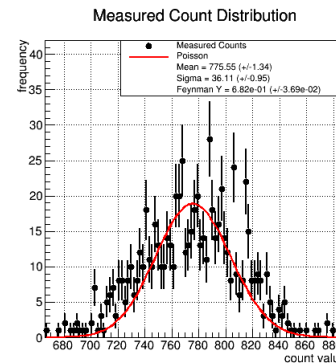
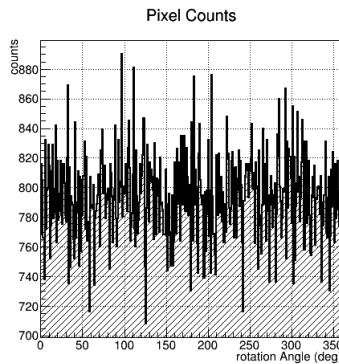
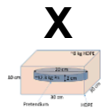
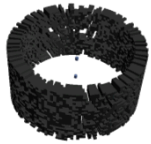
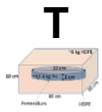


Single Test Statistic – Feynman Y



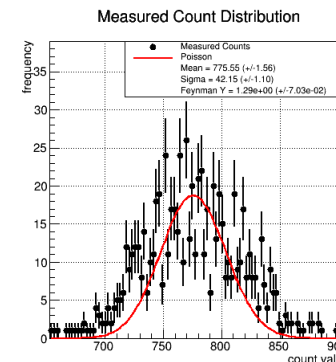
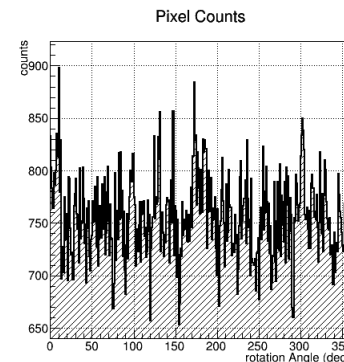
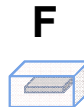
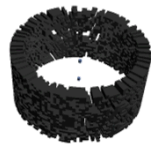
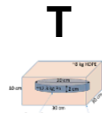
$$\text{Feynman Y} = \left(\frac{\text{variance}}{\text{mean}} - 1 \right)$$

$$= 86.8 (+/-5.7) \rightarrow \text{Far from Poisson}$$



$$\text{Feynman Y} = \left(\frac{\text{variance}}{\text{mean}} - 1 \right)$$

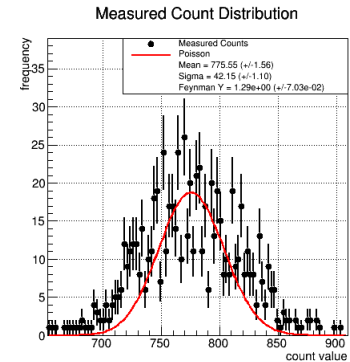
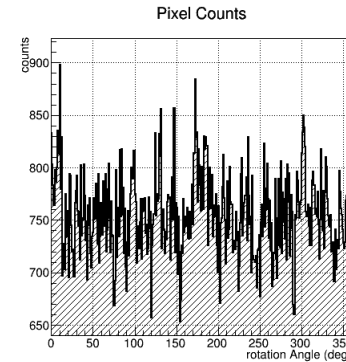
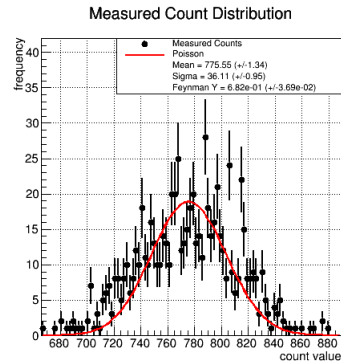
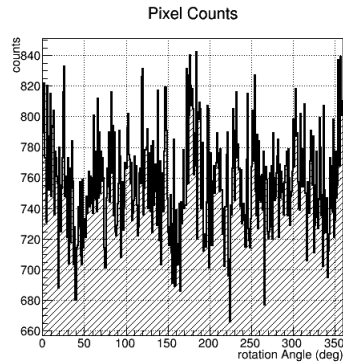
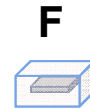
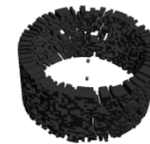
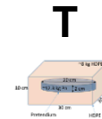
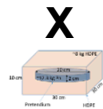
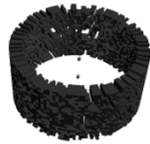
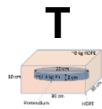
$$= 0.68 (+/-0.04) \rightarrow \text{Fairly Poisson}$$



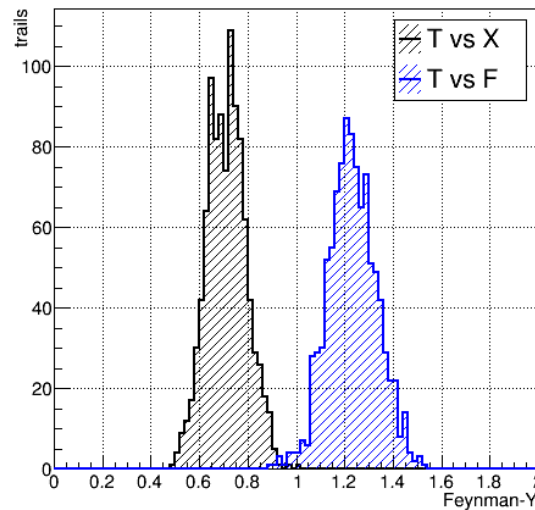
$$\text{Feynman Y} = \left(\frac{\text{variance}}{\text{mean}} - 1 \right)$$

$$= 1.3 (+/-0.07) \rightarrow \text{Less Poisson}$$

Feynman Y Test Statistic – 1000 trials of 5e5 counts

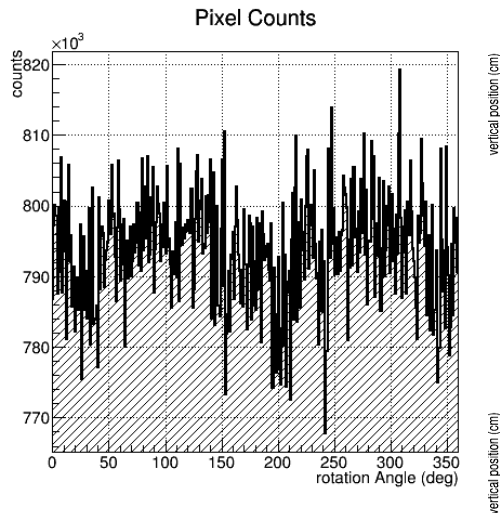
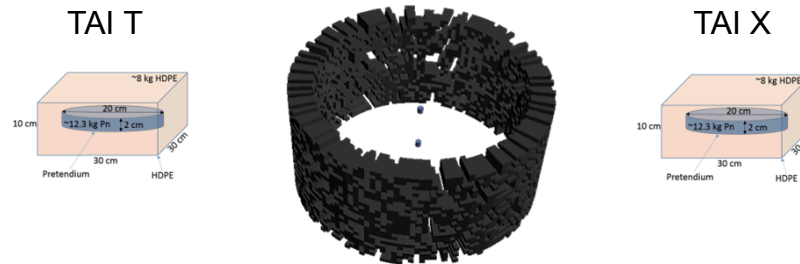


Distribution of Feynman-Y Test Statistics



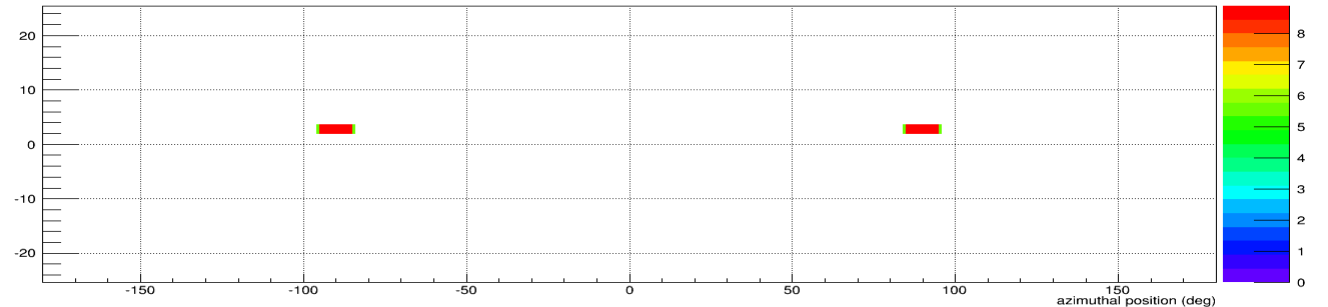
Modeling results – T vs. X (1000 trials of 5e5 counts)

Even after summing 1000 trials worth of data, there isn't much evidence that sensitive information is present. **This must be made more rigorous.**

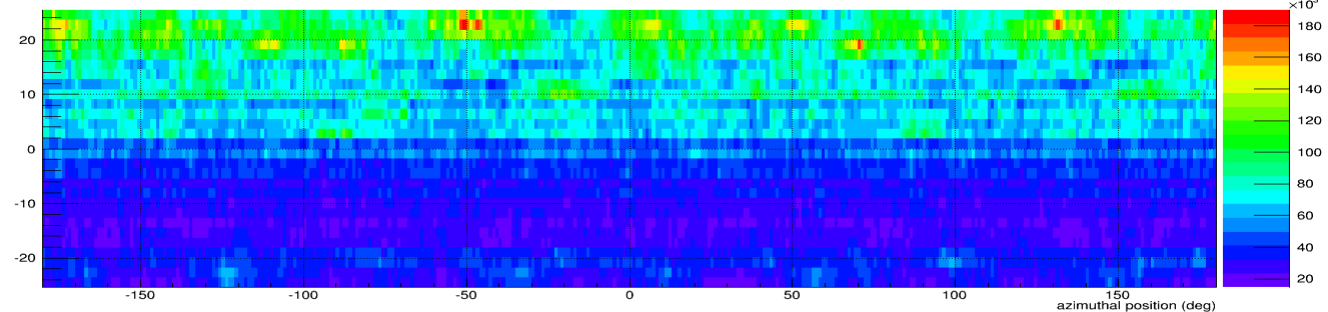


vertical position (cm)

Iso-Background plus Source

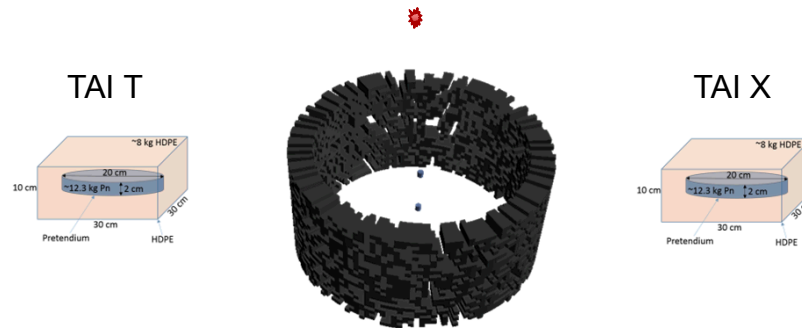


Reconstructed Image (MLEM)

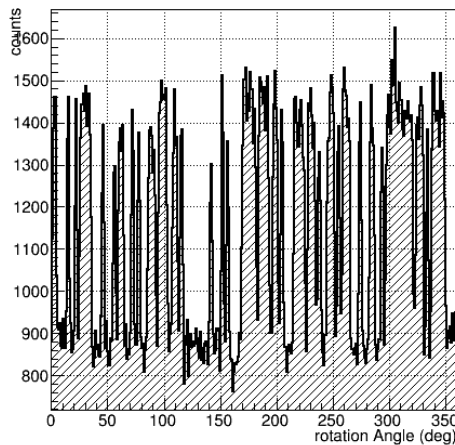


Modeling results – T vs. X plus point source (8e5 counts)

If (and only if) the TAIs are identical, only the third source is visible!



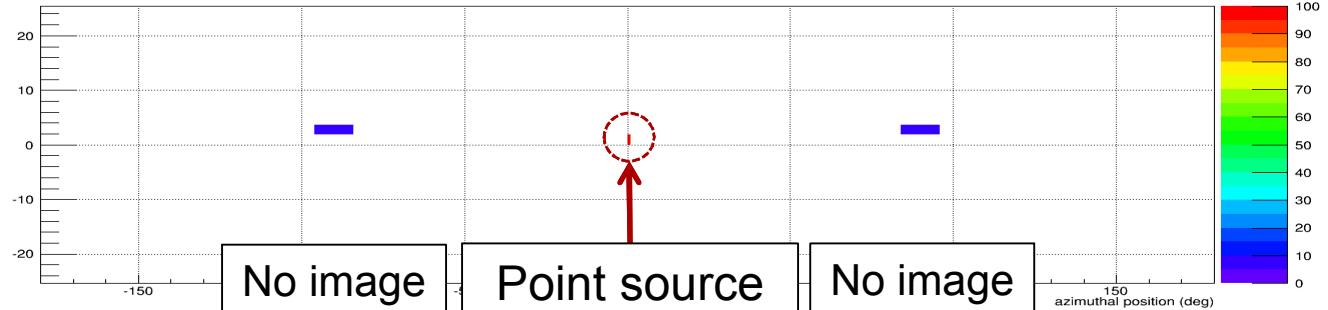
Pixel Counts



vertical position (cm)

vertical position (cm)

Iso-Background plus Source

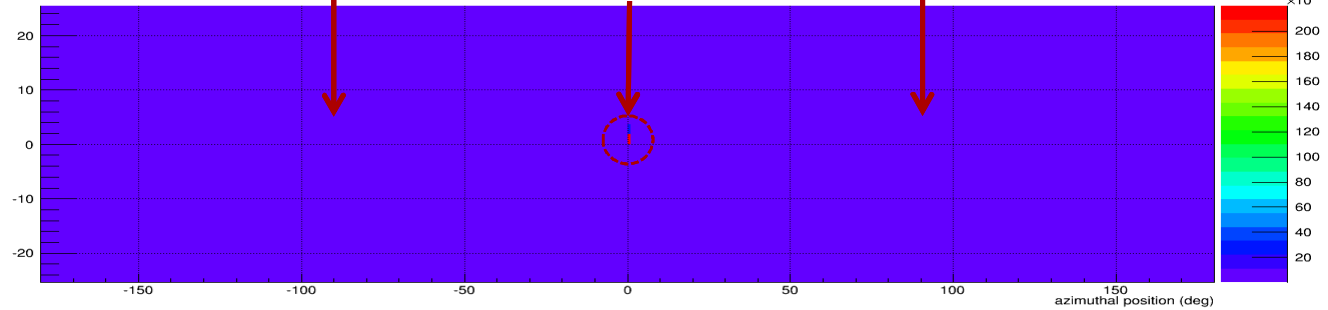


No image

Point source

No image

MLEM Reconstruction



Conclusions

A properly designed two-dimensional time-encoded imager can:

1. Confirm that two objects are identical in a single measurement with NULL (constant rate) indicating a positive result.
2. Because a NULL (constant rate) is present at all times, the inspecting party might be allowed full access to the measurement and data.
3. The Feynman-Y test statistic can be updated to further protect against sensitive information loss.
4. Can image any third inspector provided object during the confirmation measurement without revealing the first two objects as an authentication measure.

Extra Slides

Certification vs. Authentication: It's not just for hardware

Certification – the process by which a host party gains confidence that sensitive information regarding an entity or facility remains secure.

Authentication - the process by which a monitoring party gains confidence that reported characteristics of an entity reflect the true state of that entity