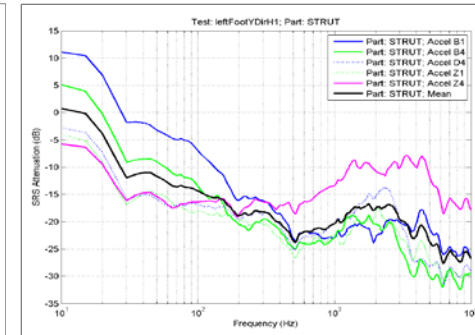
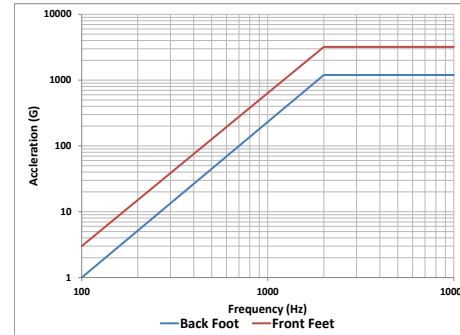
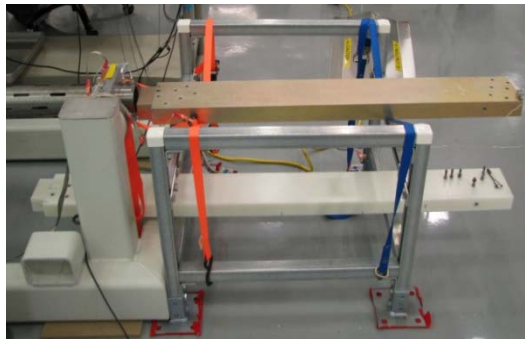
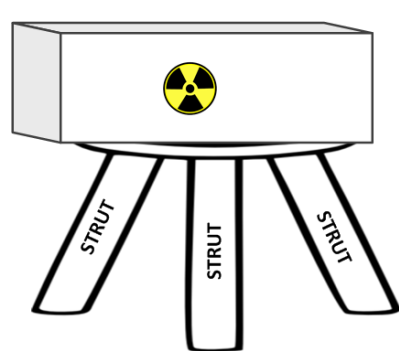


Exceptional service in the national interest



Spacecraft Shock Attenuation: Satellite Payload Case Study

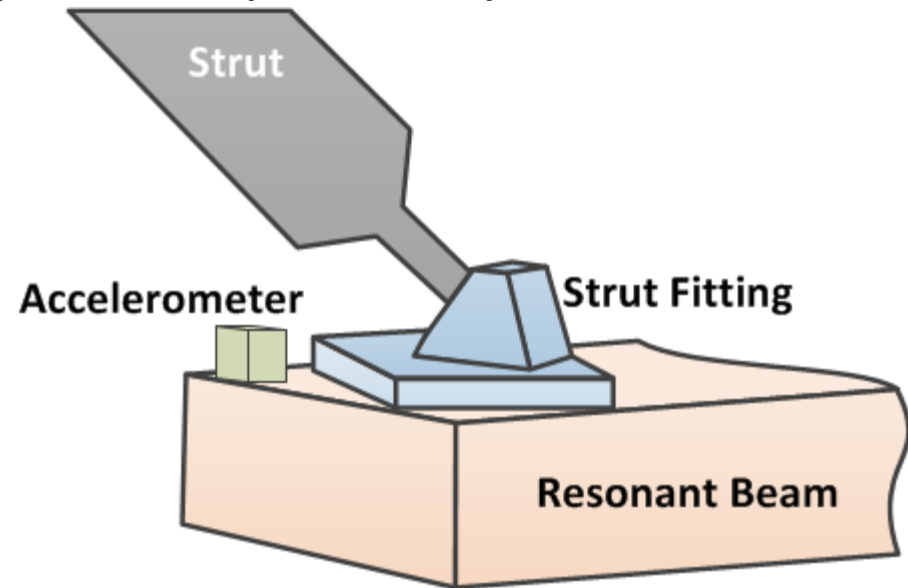
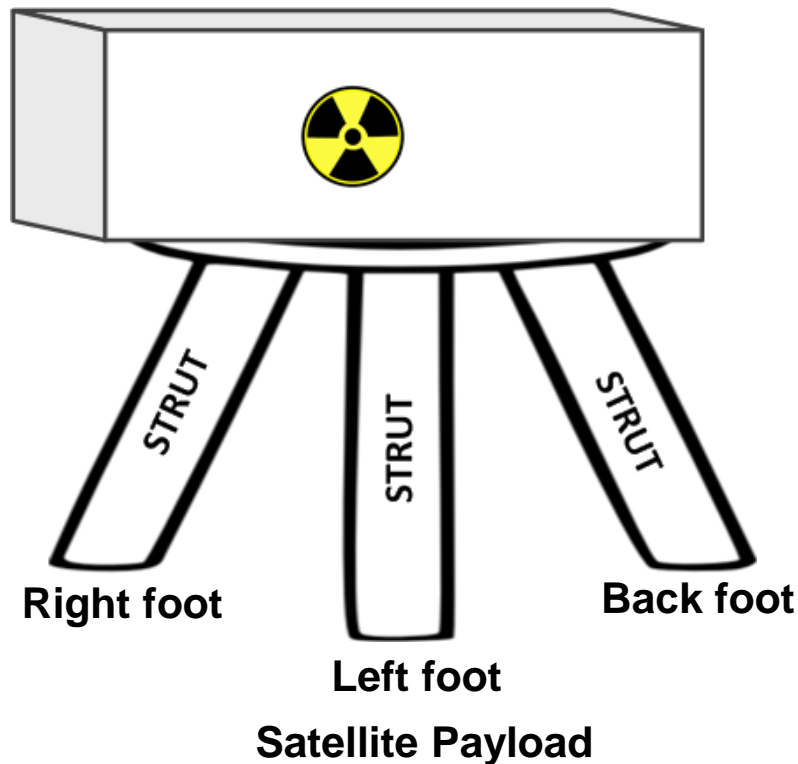
Vit Babuska, Eric Pulling & Scott Klenke

Introduction

- Almost a decade ago, Sandia National Laboratories conducted shock tests on a satellite payload
 - Resonant beam test to simulate the SRS of a pyroshock
- This presentation gives an overview of the level of attenuation seen at various parts of the payload
- Agenda
 - Payload Description
 - Input SRS
 - Shock Attenuation Factors
 - Shock Attenuation Data
 - Summary Observations

Payload Description

- The structure tested was spacecraft payload with struts attaching it to the main structure
- Shocks were applied at 3 foot pads independently

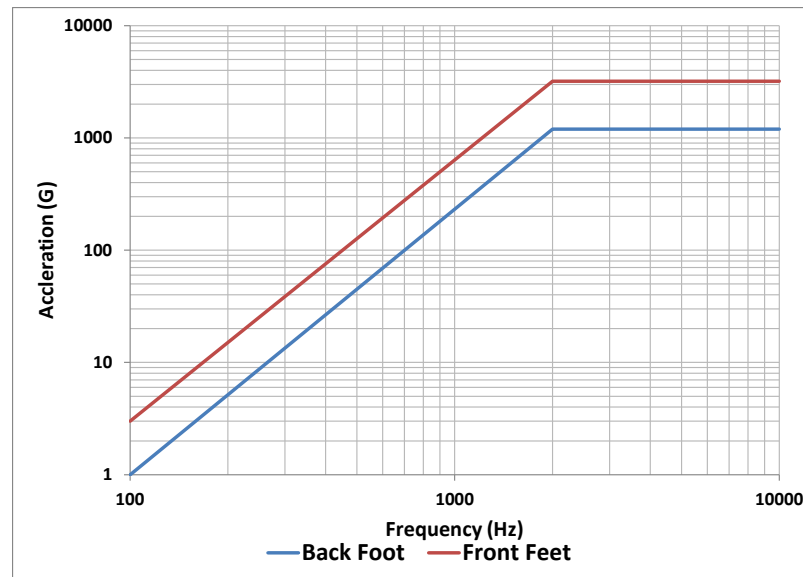


**Resonant beam was bolted to a foot pad
Accelerometer was attached to the beam
near the pad**

Shock Environment

- Different shocks were applied to the front feet and the back foot

SRS Breakpoints (Q = 10)	
Back Foot	
Frequency (Hz)	G
100	1
2000	1200
10,000	1200
Front Feet	
Frequency (Hz)	G
100	3
2000	3200
10,000	3200



Vertical Orientation

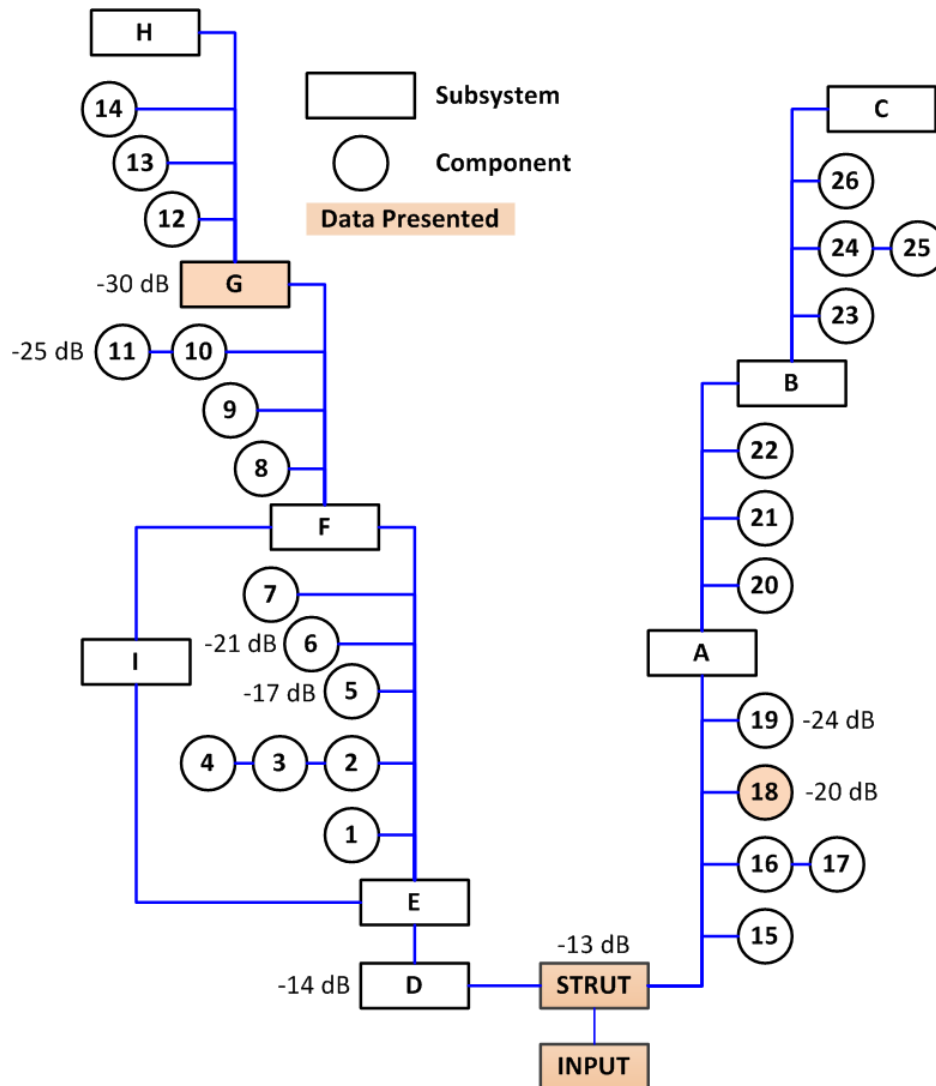


**Shock Actuator
SNL Air Gun**



Resonant Beam

Shock Attenuation Factors



■ Design Attenuation Factors

- Rotational Joint: -3dB
- Distance: -3dB
- Right Angle: -0 dB
- Bolted Joint: -3dB
- Bonded Joint: -1 dB
- Flexure: - 0 dB
- Material: -1 dB

■ Attenuation plots shown for Struts, Subsystem G, and Part 18

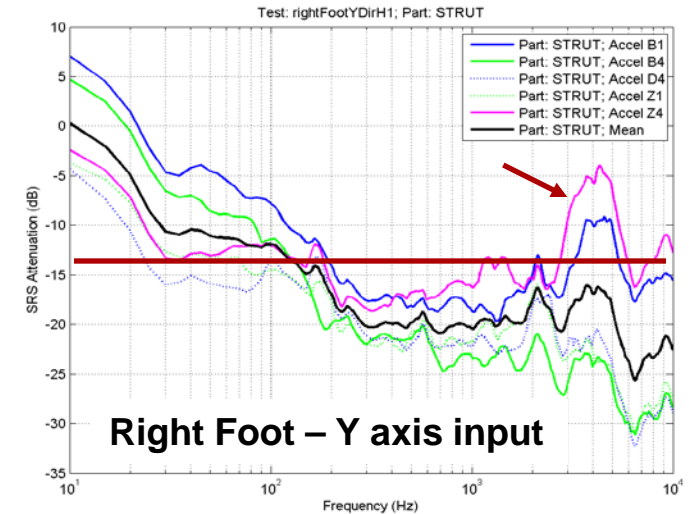
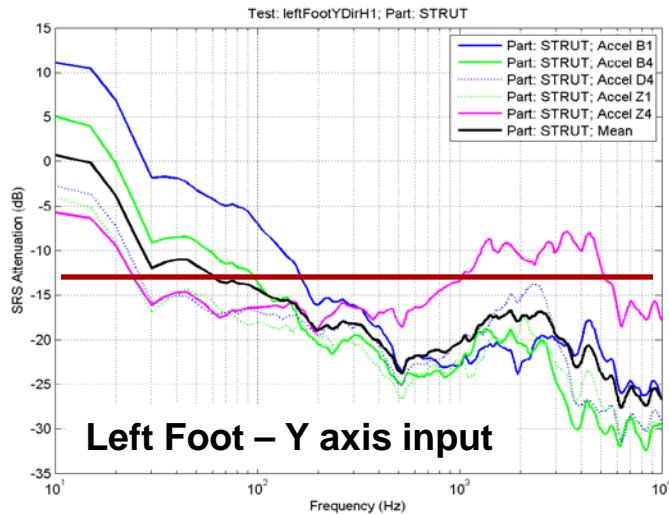
Load Path Tree

Shock Attenuation Analysis

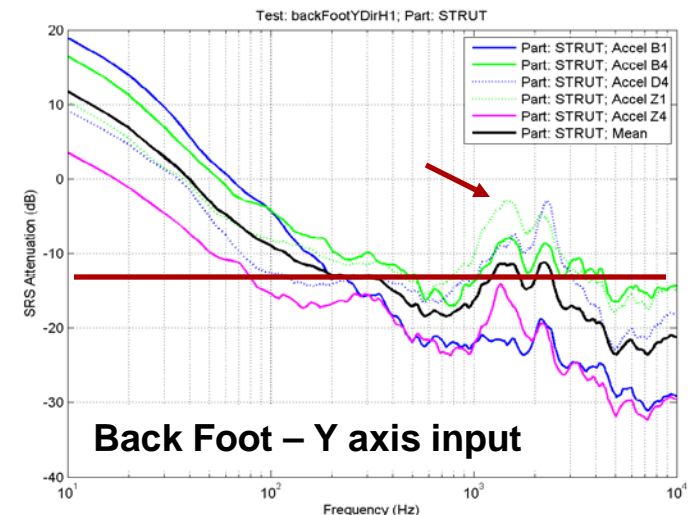
- Shock attenuation assessment is based on SRS
 - Compute a “Shock Attenuation Spectrum”
 - Ratio of the Response SRS to the Input SRS
 - $\text{dB } (20\log_{10}(X))$ vs Frequency
 - Due to ambiguity of accelerometer frames, the input and response X, Y, Z SRS are each RSS'd first
- All sensors associated with a part or subsystem are grouped together
 - Shock Attenuation Mean Spectrum is calculated when there is more than one sensor

Shock Attenuation Results – Across Struts

Y-Axis

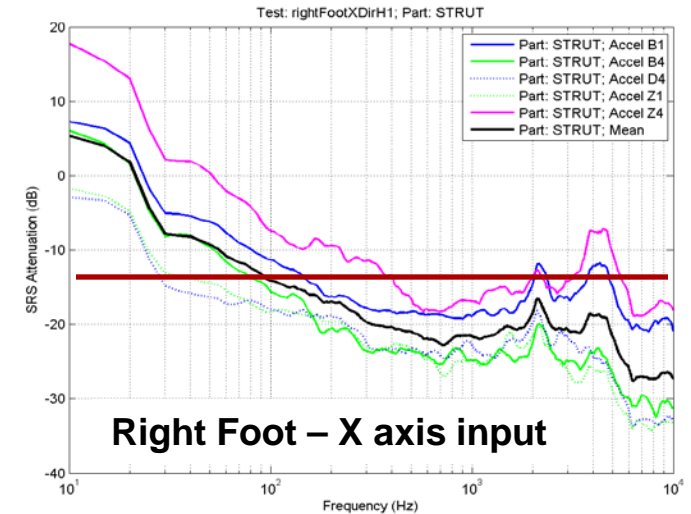
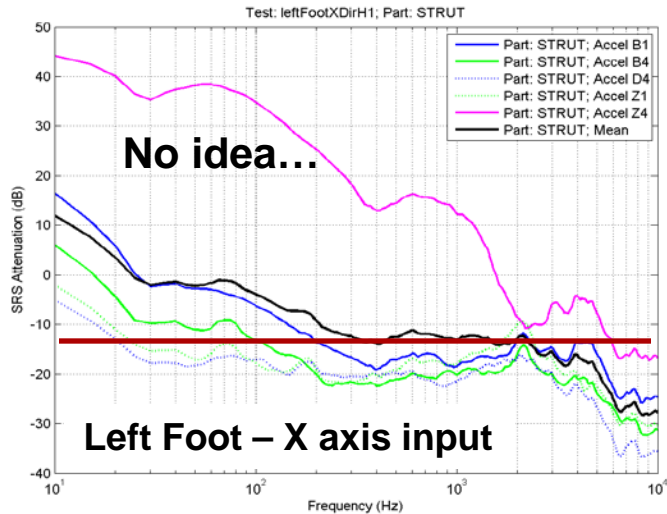


- Design attenuation factor for the struts was -13 dB
- May not have been conservative enough for parts located close to the ends of some struts
 - The design factors should be conservative

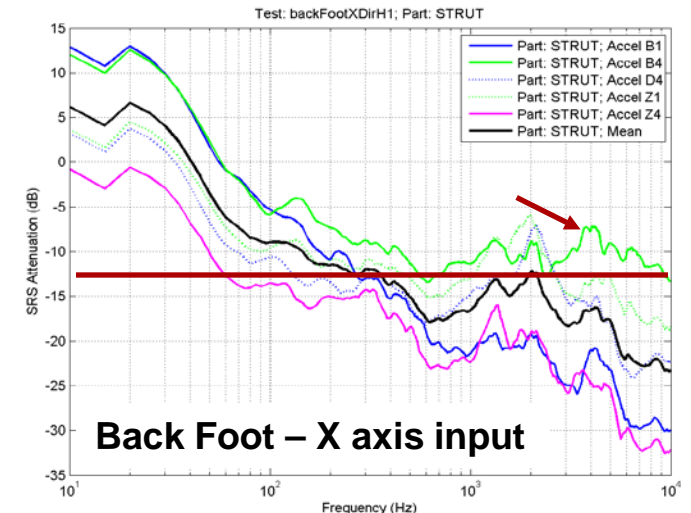


Shock Attenuation Results – Across Struts

X-Axis

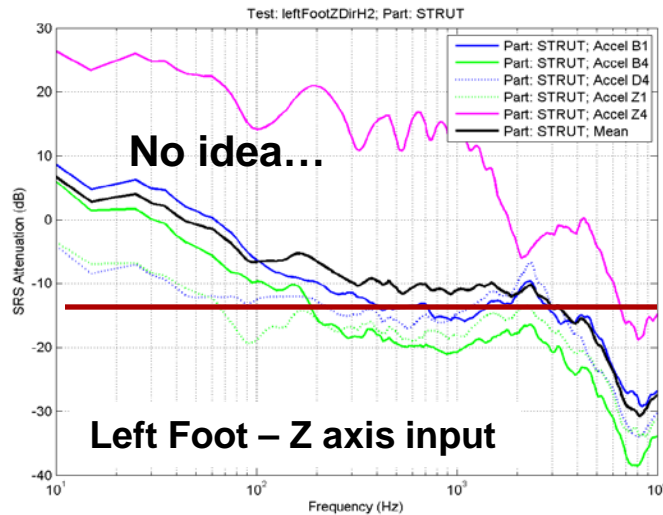


- Design attenuation factor for the struts was -13 dB
- May not have been conservative enough for parts located close to the ends of some struts



Shock Attenuation Results – Across Struts

Z-Axis

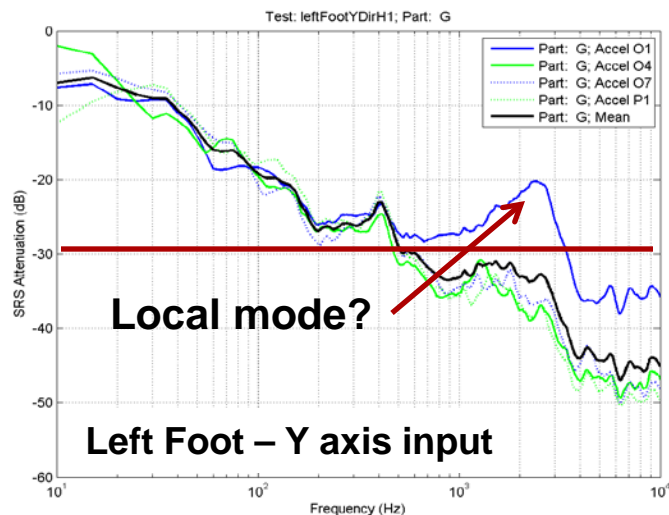


No Z-axis shocks at the right foot and the back foot

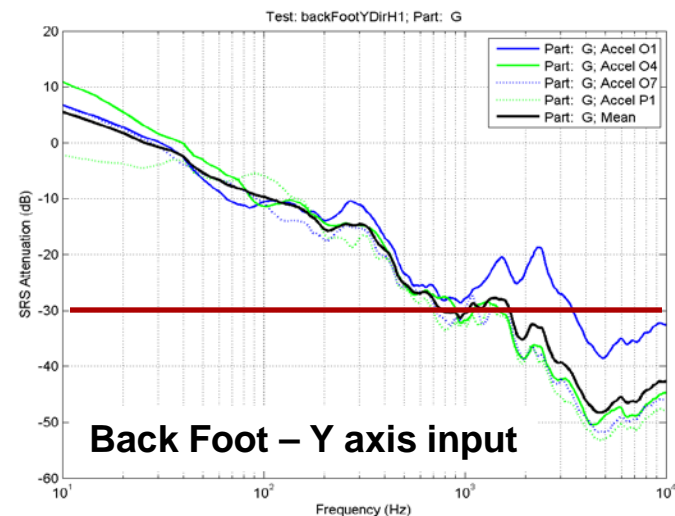
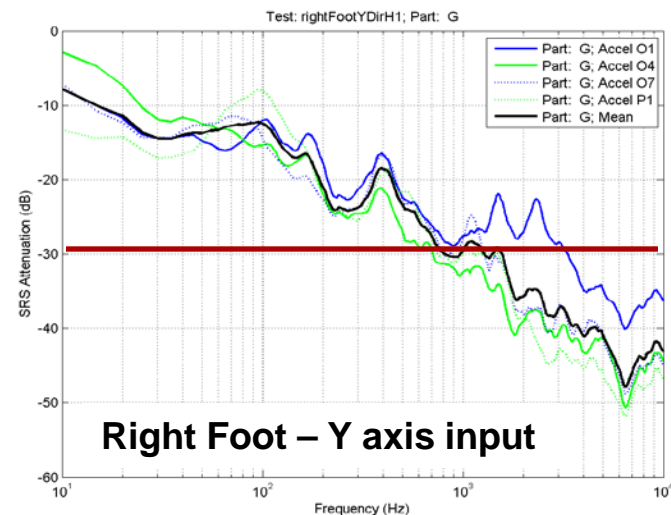
- Design attenuation factor for the struts was -13 dB
- May not have been conservative enough for parts located close to the ends of some struts

Shock Attenuation Results – Subsystem G

Y-Axis

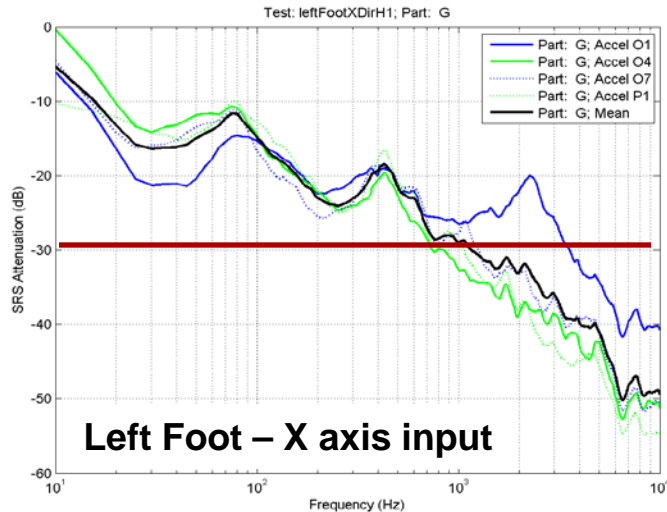


- Design attenuation factor for Subsystem G was -30 dB
- Attenuation was much less locally (near accelerometer O1)
- Overall prediction was good

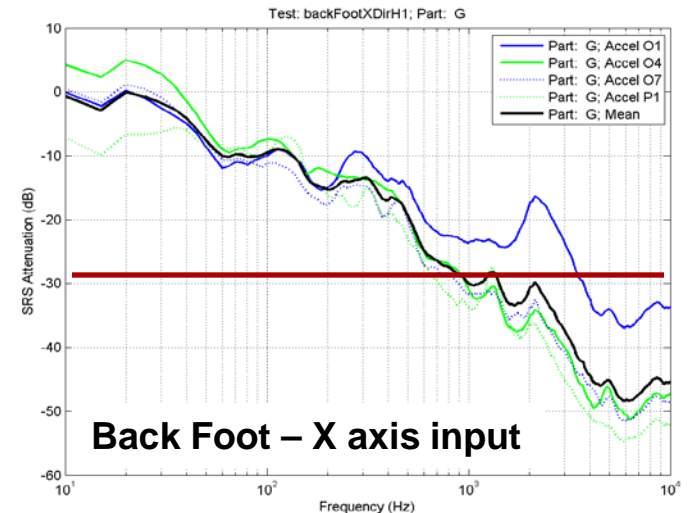
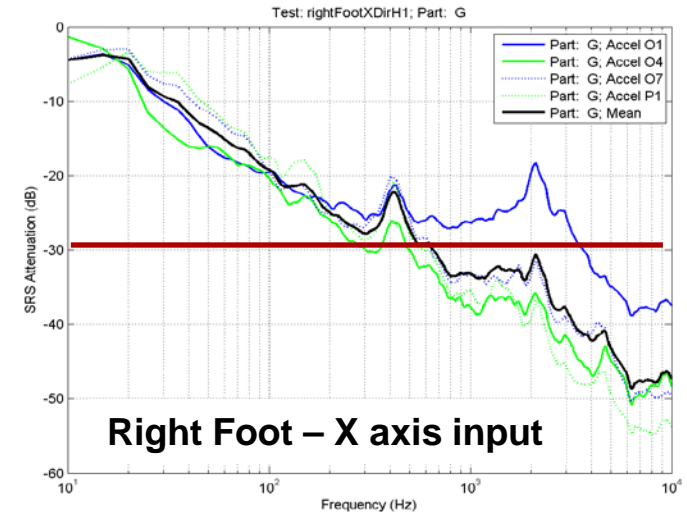


Shock Attenuation Results – Subsystem G

X-Axis

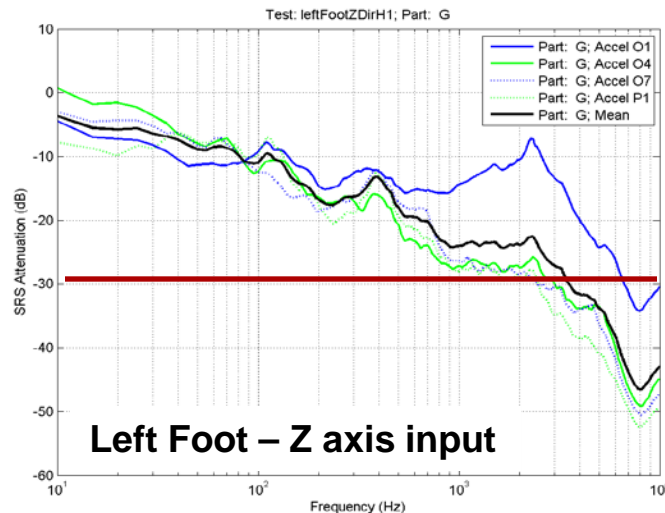


- Design attenuation factor for Subsystem G was -30 dB
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Shock Attenuation Results – Subsystem G

Z-Axis

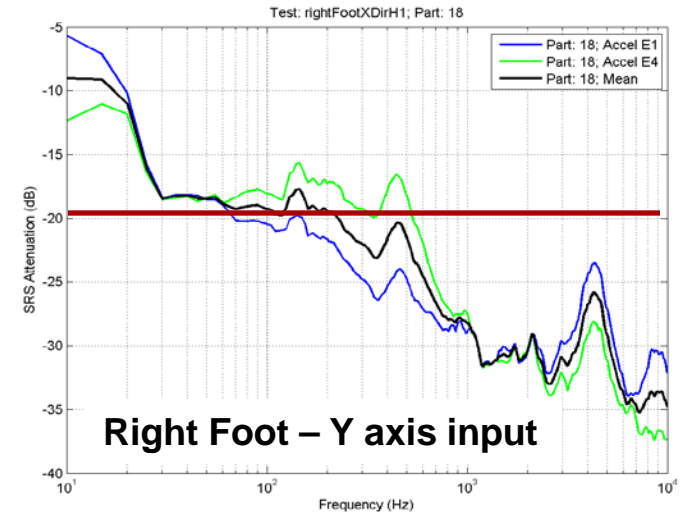
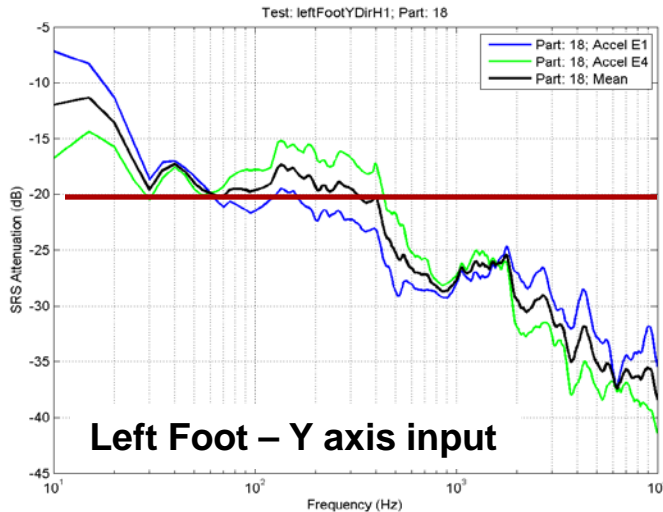


No Z-axis shocks at the right foot and the back foot

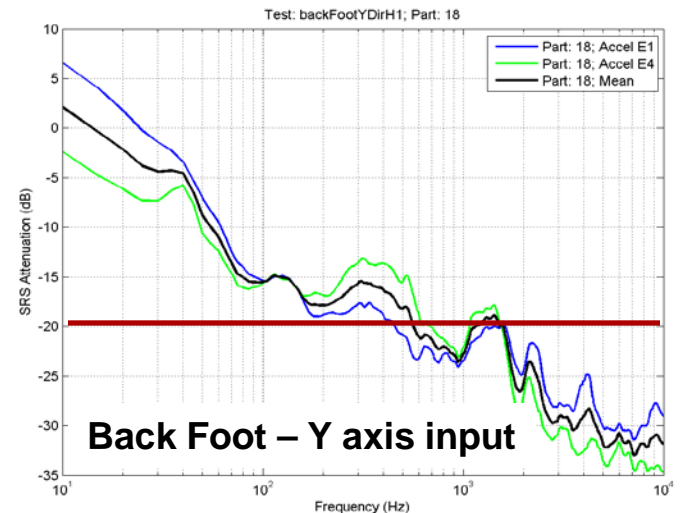
- Design attenuation factor for Subsystem G was -30 dB
- Attenuation was much less locally (near accelerometer O1)
- Overall prediction was good

Shock Attenuation Results – Part 18

Y-Axis

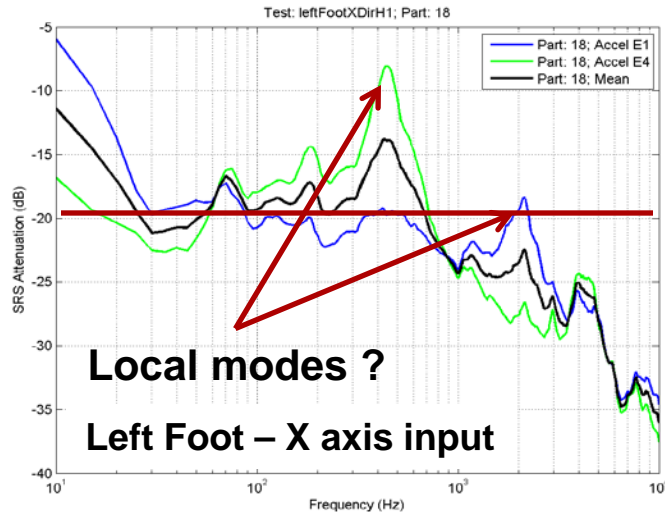


- Design attenuation factor for Part 18 was -20 dB
- Overall prediction was conservative
 - Best result above 1000 Hz

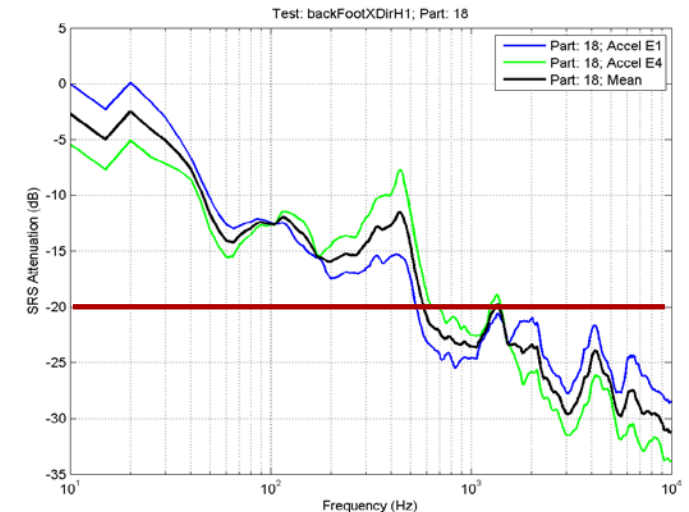
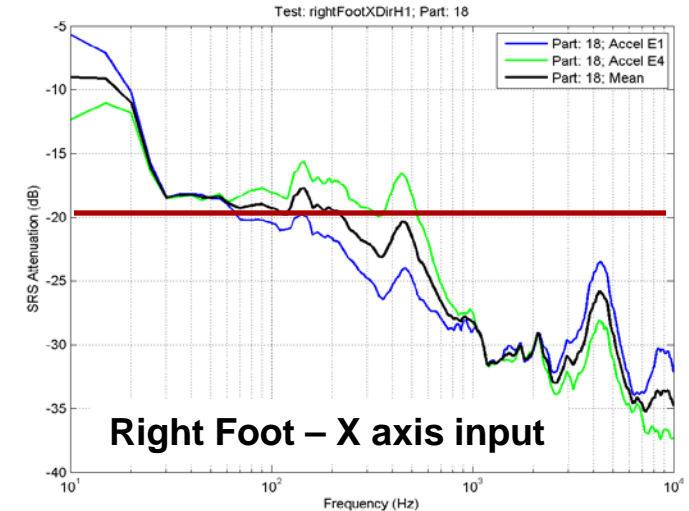


Shock Attenuation Results – Part 18

X-Axis

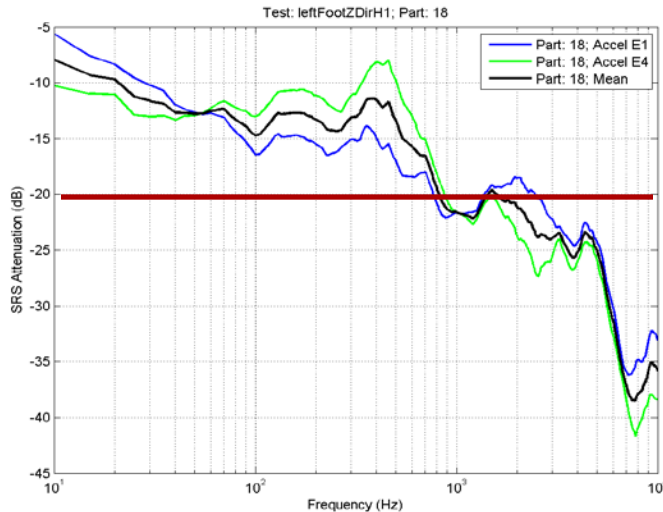


- Design attenuation factor for Part 18 was -20 dB
- Overall prediction was good
 - Not as conservative as the Y-axis



Shock Attenuation Results – Part 18

Z-Axis



No Z-axis shocks at the right foot and the back foot

- Design attenuation factor for Part 18 was -20 dB
- Overall prediction was good
 - Not as conservative as the Y-axis

Summary Observations

- Shock attenuation factors were generated by the systems engineering team to provide guidance to designers on satellite component shock levels
 - Took into account:
 - Distance, Right Angles, Rotational Joints, Bolted Joints, Bonded Joints, Flexures, and Material
 - Cascaded these features through the load path
 - Did not follow NASA 7005 guidelines, such as the “3-joint rule”, strictly
- The attenuation factors backed-out from the shock test were remarkably consistent with the systems engineering design factors
 - Local modes reduced the attenuation factors at some frequencies for some components