

Peridynamics

Ordinary Isotropic Plasticity

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Plasticity model**

- ↪ Generalization/extension of local Von Mises plasticity to peridynamics
- ↪ Continuum and ordinary-state constitutive model
- ↪ Isotropic
- ↪ Inherits all of the advantages for modeling fracture
- ↪ Satisfies 2nd law of thermodynamics
- ↪ Single step return algorithm for time integration
- ↪ Linearization of discrete return algorithm
- ↪ Applicable to implicit/explicit peridynamics codes

***John A. Mitchell. A nonlocal, ordinary, state-based viscoelasticity model for peridynamics. Sandia Report SAND2011-8064, 2011.*



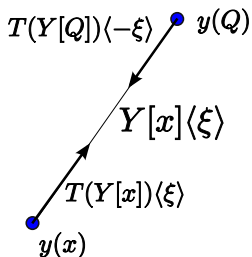
Talking points

- Review ordinary LPS model
- Summarize perfect plasticity model and discrete return algorithm
- Introduce hardening
- Iterative return algorithm
- Simple numerical examples
- PALS-like treatment for surface effects

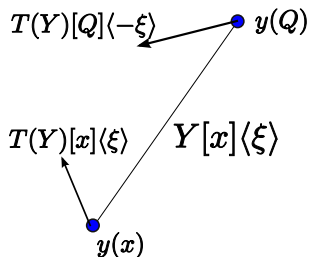


Ordinary and Non-ordinary Materials

Ordinary



Non-ordinary



Vector force state T :

$$T(Y) = t(Y)M(Y) \quad \text{where} \quad M(Y) = \frac{Y}{|Y|}$$



Vector force state T :

$$T(Y) = t(Y)M(Y) \quad \text{where} \quad M(Y) = \frac{Y}{|Y|}$$

Isotropic and elastic material

$$t(Y) = \frac{3k\theta}{m}\omega_{\underline{x}} + \alpha\omega e^d$$



Vector force state T :

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Isotropic and elastic material

$$t(Y) = \frac{3k\theta}{m}\omega_{\underline{x}} + \alpha\omega e^d$$

Isotropic and elastic-plastic material

$$t(Y) = \frac{3k\theta}{m}\omega_{\underline{x}} + \alpha\omega \underbrace{(e^d - e^{dp})}_{\text{elastic}}$$



Summary of Governing Equations and Constraints

- Additive decomposition of extension state: $e^d = e^{de} + e^{dp}$
- Elastic force state relations: $t(Y) = \frac{3k\theta}{m}\omega\underline{x} + \alpha\omega(e^d - e^{dp})$
- Elastic force states domain defined by a yield surface/function that depends upon the deviatoric force state:

$$f(t^d) = \psi(t^d) - \psi_0 \leq 0, \text{ where } \psi(t^d) = \frac{\|t^d\|^2}{2}$$

- Flow rule which describes rate of plastic deformation:
 $\dot{e}^{dp} = \lambda \nabla^d \psi$
- Loading/un-loading conditions (Kuhn-Tucker constraints):
 $\lambda \geq 0, f(t^d) \leq 0, \lambda f(t^d) = 0$
- Consistency condition: $\lambda \dot{f}(t^d) = 0$



Elastic-Plastic Constitutive Model

Implicit Time Integration of Model**

Exact Solution to Associated Backward Euler Approximation

- Compute trial deviatoric force state: $t_{trial}^d = \alpha \omega (e_{n+1}^d - e_n^{dp})$
- if $f(t_{trial}^d) \leq 0$, then step is elastic, $\Delta\lambda = 0$, and $t_{n+1}^d = t_{trial}^d$
- else

$$t_{n+1}^d = \sqrt{2\psi_0} \frac{t_{trial}^d}{\|t_{trial}^d\|}, \quad e_{n+1}^{dp} = e_n^{dp} + \frac{1}{\alpha} \left[\frac{\|t_{trial}^d\|}{\sqrt{2\psi_0}} - 1 \right] t_{n+1}^d$$

Practical value** for ψ_0

$$\begin{aligned} \psi_0 &= \frac{1}{2} \left[\frac{15\mu}{m} \right]^2 \|e^d\|^2 \\ &= \frac{75}{8\pi} \frac{E_y^2}{\delta^5} \end{aligned}$$

where E_y is the shearing yield stress and δ is the *horizon*

***John A. Mitchell. A nonlocal, ordinary, state-based viscoelasticity model for peridynamics. Sandia Report SAND2011-8064, 2011.*



Outline of Newton Algorithm

Implicit Update of Plasticity State

Initialize yield function

Let $f(\Delta\lambda_k) = \frac{1}{2} \|t^d(\Delta\lambda_k)\|^2 - (\psi_0 + H\|\beta(\Delta\lambda_k)\|)$

Newton steps for calculation of $\Delta\lambda_k$

while $f(\Delta\lambda_k) > 0$ {

– Solve: $0 = f(\Delta\lambda_k) + Df(\Delta\lambda_k)[u]$ for u
 $Df(\Delta\lambda_k)[u] = -f(\Delta\lambda_k)$

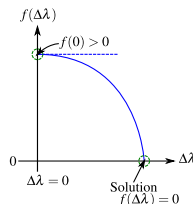
– Increment: $\Delta\lambda_{k+1} = \Delta\lambda_k + u$

– Evaluate: $f(\Delta\lambda_{k+1}) = \frac{1}{2} \|t^d(\Delta\lambda_{k+1})\|^2 - (\psi_0 + H\|\beta(\Delta\lambda_{k+1})\|)$

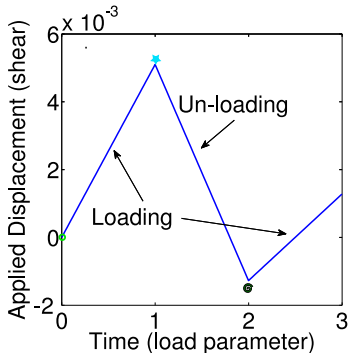
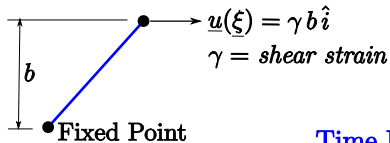
}

Where

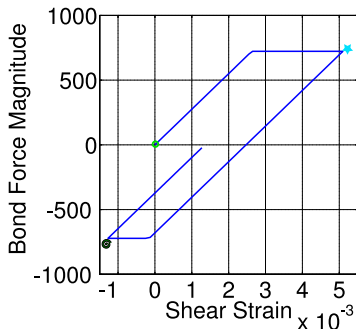
$Df(\Delta\lambda_k)$ is Fréchet derivative of f @ $\Delta\lambda_k$



Elastic-Plastic Constitutive Model

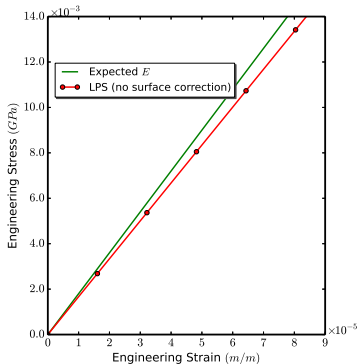


Time Integration of Single Bond



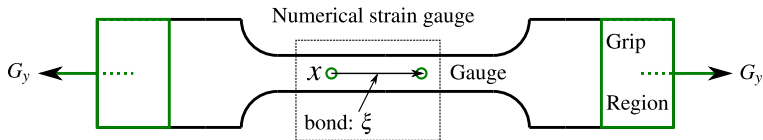
What is the *Dreaded Surface Effect*?

Example: Isotropic-Ordinary Model (LPS)



The following related aspects contribute to mismatch.

- Geometric surface effects
- Nonlocal model kinematics
- Nonlocal model properties
- Discretization error

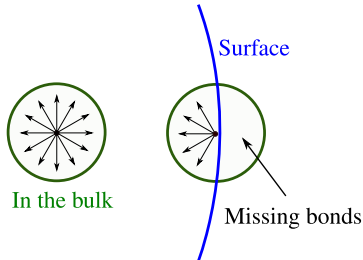


Ordinary peridynamic models

Dreaded Surface Effect

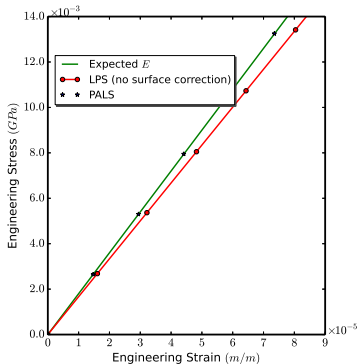
Causes relate to material points near surface

- ↪ Mathematical models assume all points are in the *bulk*
 - * Points near surface are *missing bonds*
 - * *Missing bonds* imply and induce incorrect material properties
 - * In the bulk mathematical models are consistent
- ↪ Isotropic ordinary materials have a *dilatation defect* at the surface



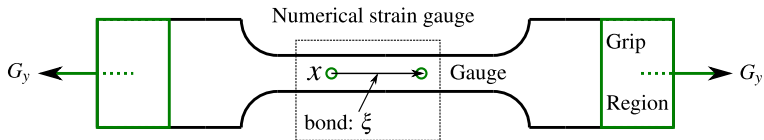
Re-visit tensile test using PALS and LPS

Influence functions: $\underline{\omega}^0 = \underline{\sigma}^0 = 1$



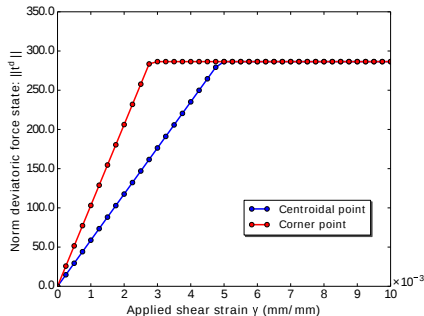
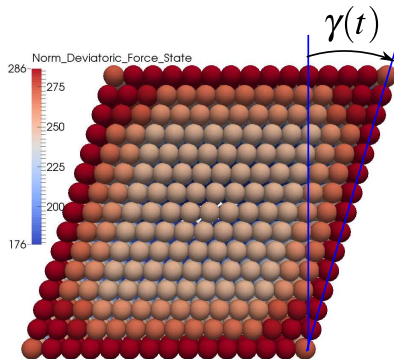
Results

- PALS sharply reduces error



Elastic-Plastic Constitutive Model

- ↪ Perfect plasticity yield function: $f(t^d) = \frac{\|t^d\|^2}{2} - \psi_0$
- ↪ Position sensitive yield (*undesirable*) but fixable using PALS-like approach

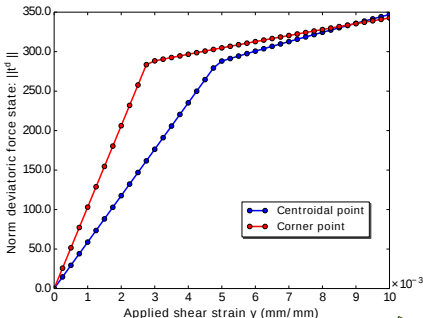
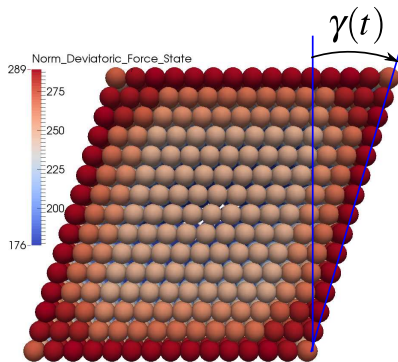


Elastic-Plastic Constitutive Model

↪ Plasticity w/hardening yield function

$$f(t^d) = \frac{\|t^d\|^2}{2} - (\psi_0 + H\|\beta\|)$$

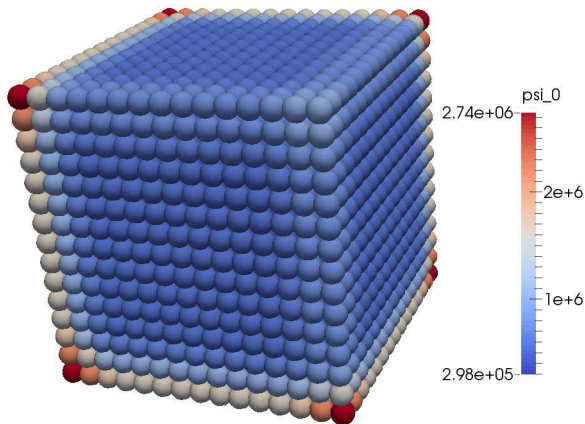
↪ Position sensitive yield (*undesirable*) but fixable using PALS-like approach



Position Aware Yield Condition: Status

PALS-like correction for yield value ψ_0

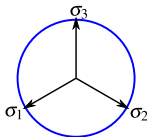
↪ Artifact showing but confident this is fixable.



Brief Comparison (food for thought)

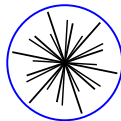
VonMises Model with Nonlocal Model

- ↪ Both models principally apply to metals
- ↪ Plastic deformations volume preserving, independent of pressure
- ↪ Yield functions are quite different



Octahedral/deviatoric plane

- $f(\sigma) = \sqrt{3J_2} - \sigma_0$
- Principal values $\sigma_1, \sigma_2, \sigma_3$
- Yield defined @ point
- Two-dimensional yield surface



Schematic of bonds @ point

- $f(t^d) = \frac{\|t^d\|^2}{2} - \psi_0$
- Neighborhood of a point
- Yield defined @ point via collective
- Yielding occurs on bond
- Infinite dimensional aspect due to bonds
- Length scale is native to the model



Summary

- ↪ Presented non-local peridynamics plasticity model
- ↪ Non-local equivalence to Von Mises model
- ↪ Non-local model has far more information embedded
- ↪ PALS-like surface correction underway

THANK YOU
Questions?

