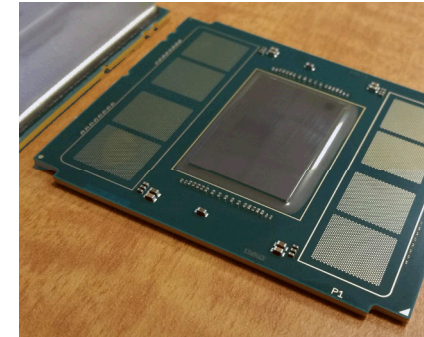
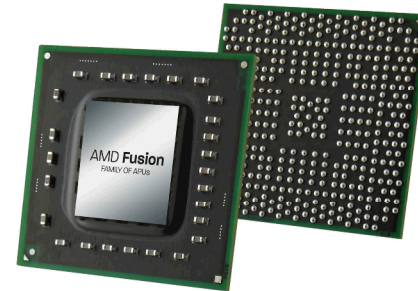
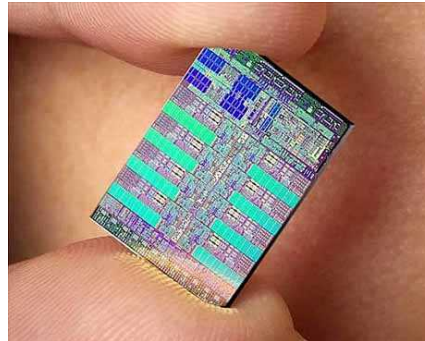


*Exceptional service in the national interest*



# Performance Portability for Linear Algebra with Kokkos

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Mehmet Deveci, Erik Boman, Andrew Bradley, Mark Hoemmen, Siva Rajamanickam

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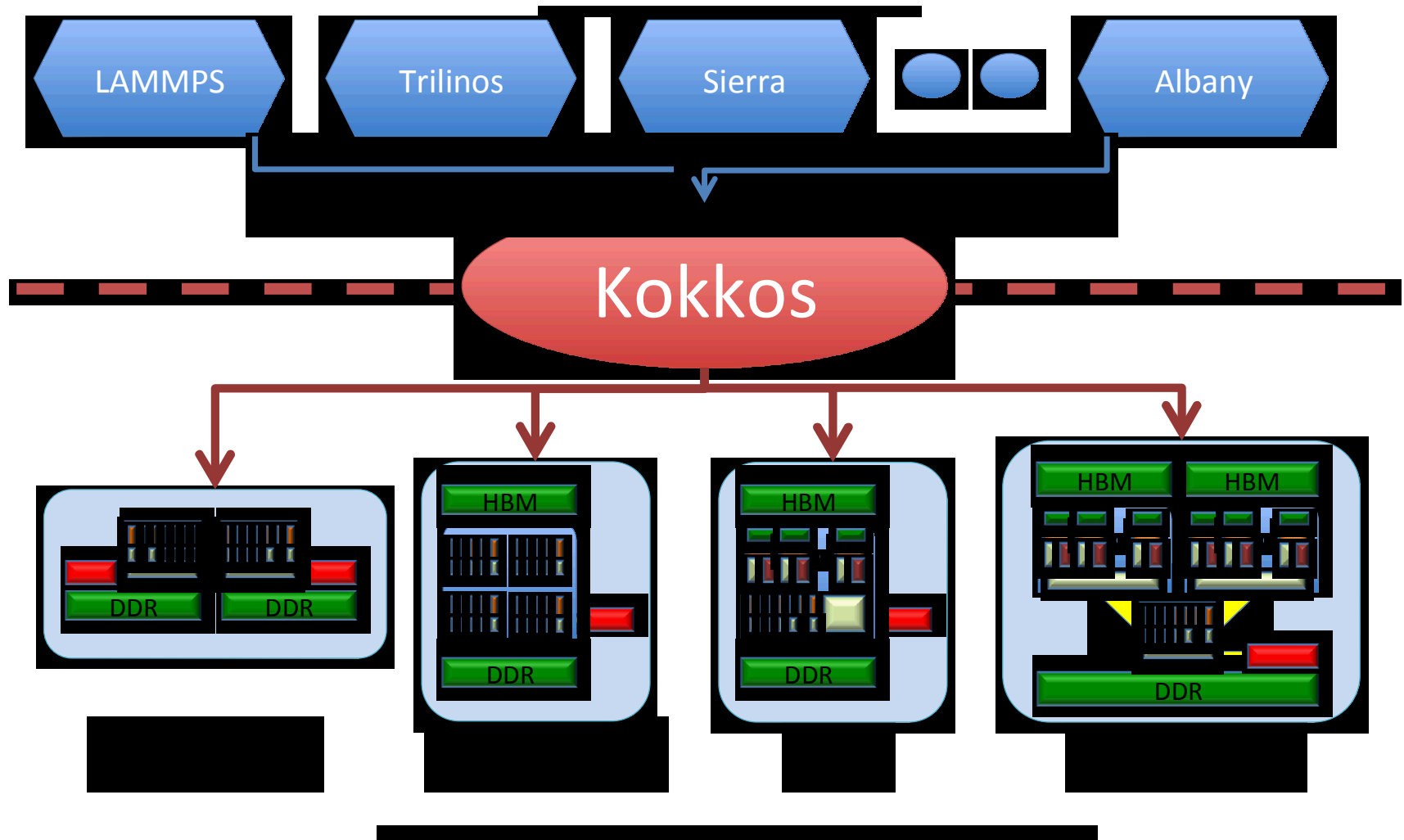
Center for Computing Research

Sandia National Laboratories, NM



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# Kokkos: *Performance, Portability and Productivity*



- A programming model implemented as a C++ library
- Abstractions for Parallel Execution and Data Management
  - Execution Pattern: What kind of operation (for-each, reduction, scan, task)
  - Execution Policy: How to execute (Range Policy, Team Policy, DAG)
  - Execution Space: Where to execute (GPU, Host Threads, PIM)
  - Memory Layout: How to map indices to storage (Column/Row Major)
  - Memory Traits: How to access the data (Random, Stream, Atomic)
  - Memory Space: Where does the data live (High Bandwidth, DDR, NV)
- Supports multiple backends: OpenMP, Pthreads, Cuda, Qthreads, Kalmar (experimental)
- Sandia application teams committed to Kokkos as its path for transitioning legacy codes, and as part of its new codes
  - Trilinos, LAMMPS, Albany, Sierra Mechanics, ...

# Going Production

- Kokkos released on github in March 2015
  - Develop / Master branch system => merge requires application passing
  - Testing Nightly: 11 Compilers, total of 90 backend configurations, warnings as errors
  - Extensive Tutorials and Documentation > 300 slides/pages
- Trilinos NGP stack uses Kokkos as only backend
  - Tpetra, Belos, MueLu etc.
  - Working on threading all kernels, and support GPUs
- Sandia Sierra Mechanics going to transition to Kokkos
  - Decided to go with Kokkos instead of OpenMP (only other realistic choice)
  - FY 2016: prototyping threaded algorithms, explore code patterns
  - Data management postponed to FY 2017 and follow on
- Sandia ATDM has Kokkos as big component
  - All ATDM Apps are using Kokkos
  - Add System level Tasking with Dharma later

# KokkosP Profiling Interface

- Dynamic Runtime Linkable profiling tools
  - Not LD\_PRELOAD based (horray!)
  - Profiling hooks are always enabled (i.e. also in release builds)
    - Compile once, run anytime, profile anytime, no confusion or recompile!
  - Tool Chaining allowed (many results from one run)
  - Very low overhead if not enabled
- Simple C Interface for Tool Connectors
  - Users/Vendors can write their own profiling tools
  - VTune, NSight and LLNL-Caliper
- Parallel Dispatch can be named to improve context mapping
- Initial tools: simple kernel timing, memory profiling, thread affinity checker, vectorization connector (APEX-ECLDRD)
- Contact: Simon Hammond (sdhammo@sandia.gov)

- C++11 Feature which simplify using abstraction layers

## **Pragma Based OpenMP:**

```
#pragma omp parallel for  
for(int i=0; i<N; i++) {  
    a[i] += b[i];  
}
```

## **Functor Based Kokkos:**

```
struct vector_add {  
    View<double*> a;  
    View<double*> b;  
    vector_add(View<double*> a_, View<double*> b_):  
        a(a_),b(b_){}  
    KOKKOS_INLINE_FUNCTION  
    void operator() (const int&i) const {  
        a(i) += b(i);  
    }  
};  
  
parallel_for( N, vector_add(a,b));
```

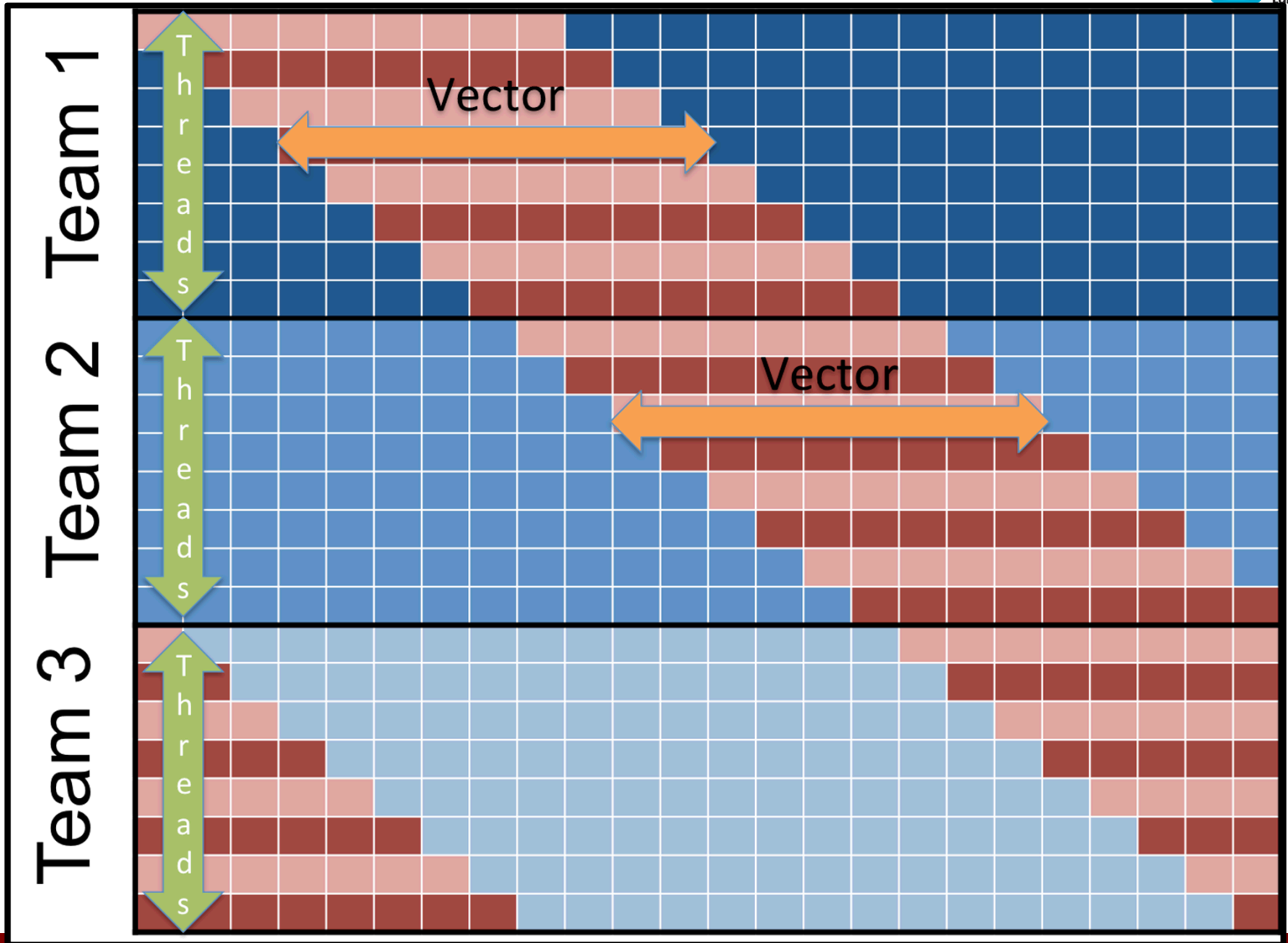
## **LAMBDA Based Kokkos:**

```
parallel_for( N, KOKKOS_LAMBDA (const int& i) {  
    a[i] += b[i];  
});
```

# Under development: KokkosKernels Sandia National Laboratories

- Provide BLAS (1,2,3); Sparse; Graph and Tensor Kernels
- No required dependencies other than Kokkos
- Local kernels (no MPI)
- Hooks in TPLs such as MKL or CuBlas/CuSparse if applicable
- Provide kernels for all levels of hierarchical parallelism:
  - Global Kernels: use all execution resources available
  - Team Level Kernels: use a subset of threads for execution
  - Thread Level Kernels: utilize vectorization inside the kernel
  - Serial Kernels: provide elemental functions (OpenMP declare SIMD)
- Work started based on customer priorities; expect multi-year effort for broad coverage
- People: Many developers from Trilinos contribute
  - Consolidate node level reusable kernels previously distributed over multiple packages

# SPMV – Using Hierarchical Parallelism



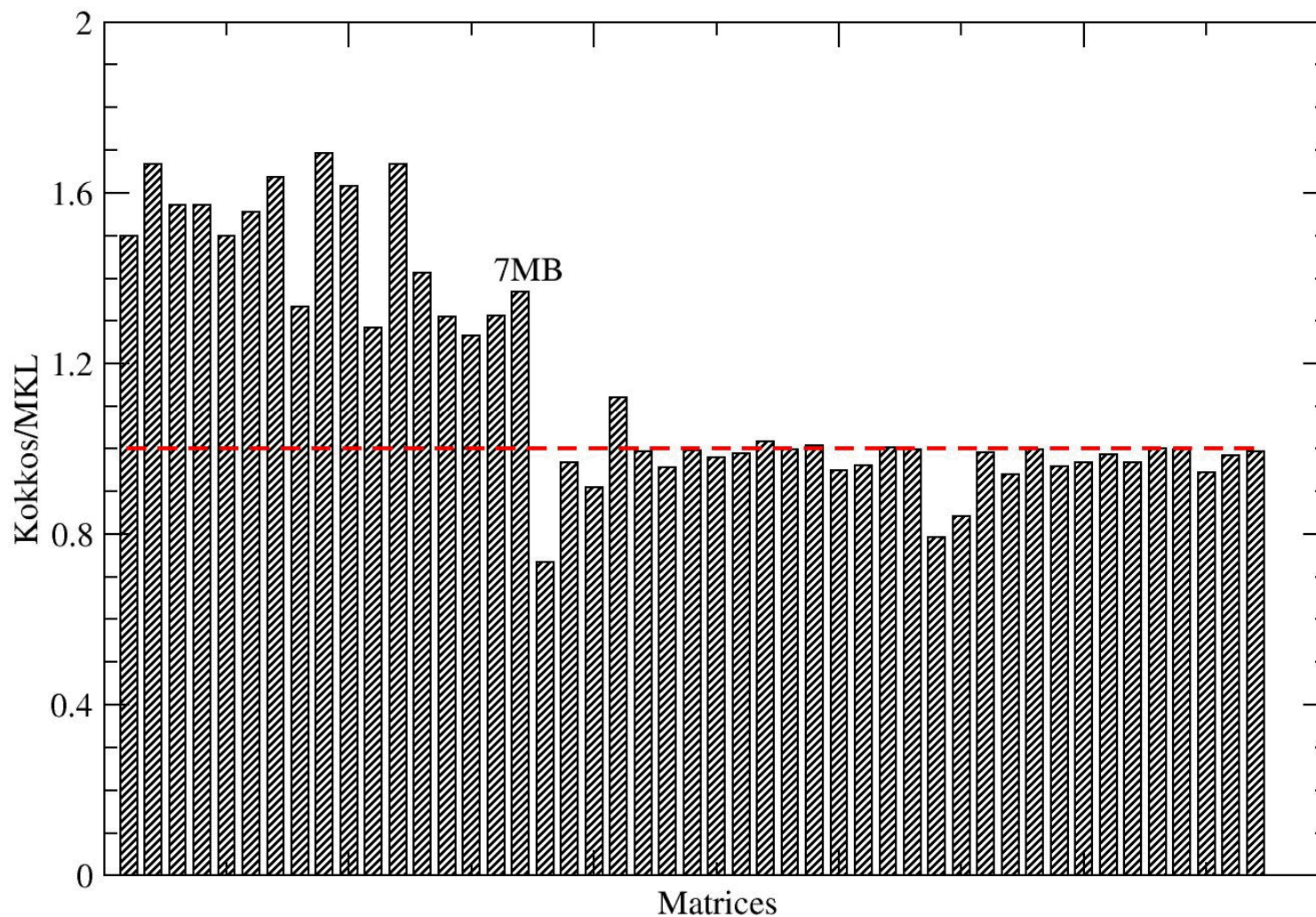


# SPMV – Using Hierarchical Parallelism

```
void spmv(Matrix A, Scalar alpha, XType x, Scalar beta, YType y) {  
    int nnz_per_team = 2048;  
    int conc = execution_space::concurrency();  
    while((conc * nnz_per_team * 4 > A.nnz()) && (nnz_per_team > 256)) nnz_per_team /= 2;  
  
    int nnz_per_row = A.nnz() / A.numRows();  
    int rows_per_team = (nnz_per_team + nnz_per_row - 1) / nnz_per_row;  
    int vector_length = GetVectorLength(A);  
    const int nworkset = (y.dimension_0() + rows_per_team - 1) / rows_per_team;  
  
    parallel_for(TeamPolicy<Schedule<Dynamic>>(nworkset, AUTO(), vector_length),  
        KOKKOS_LAMBDA(const TeamPolicy<>::member_type& team) {  
        const int startRow = team.league_rank() * rows_per_team;  
        const int endRow = startRow + rows_per_team < A.numRows() ?  
            startRow + rows_per_team : A.numRows();  
  
        parallel_for(TeamThreadRange(team, startRow, endRow), [&](const int& loop) {  
            const SparseRowViewConst<MatrixType, SizeType> row = A.template rowConst<SizeType>(iRow);  
            const int row_length = row.length();  
            Scalar sum = 0;  
  
            parallel_reduce(ThreadVectorRange(team, row_length), [&](const int& iEntry, Scalar& lsum) {  
                const Scalar val = conjugate ?  
                    ATV::conj(row.value(iEntry)) :  
                    row.value(iEntry);  
                lsum += val * x(row.colidx(iEntry));  
            }, sum);  
  
            single(PerThread(team), [&]() {  
                sum *= alpha;  
                y(iRow) = beta * y(iRow) + sum;  
            });  
        });  
    }  
}
```

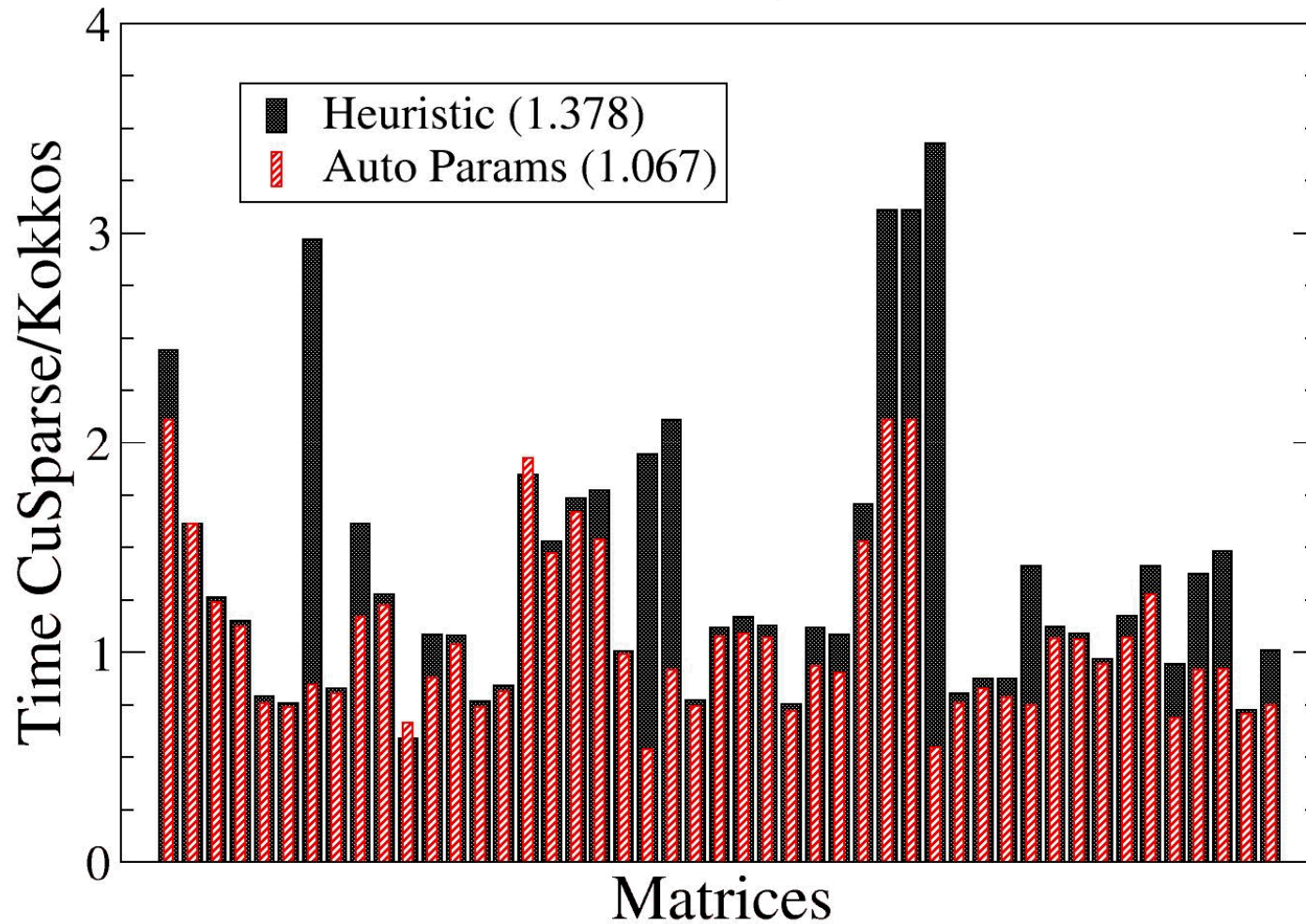
# SPMV Benchmark: MKL vs Kokkos

1S HSW 24 Threads, Matrices sorted by size, Matrices obtained from UF



# SPMV Benchmark: CuSparse vs Kokkos

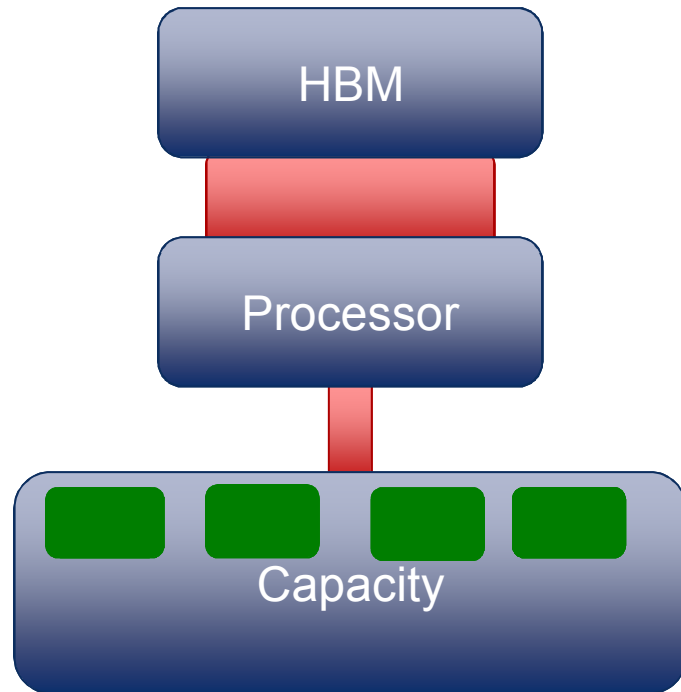
K40c Cuda 7.5; Matrices sorted by size; Matrices from UF.



# High Bandwidth Memory

- Main Problem: How to decide who can put things in scarce HBM
- Strategy One: Stage in individual linear systems temporarily
  - Most of our Apps solve multiple linear systems at the same time
  - Aggregate Memory footprint  $>$  HBM, but individual linear system  $<$  HBM
  - Can be supported by TPeTra today: Keep copies of all systems in capacity memory, create temporary copies in HBM for individual solves
- Strategy Two: Domain Decomposition Solvers
  - Divide full problem into subdomains
  - Develop solvers which can work on individual subdomains with enough data reuse to amortize data transfer
  - Copy in one subdomain at a time
- Advantage: Relatively straight forward, No persistent HBM usage
  - No need for inter-package arbitration on HBM usage quotas

# High Bandwidth Memory



## Cost Estimate (Bandwidth Bound):

*Run From Capacity Memory*

$$\text{Time} = N_{\text{iter}} * \text{Size} / \text{BW}_{\text{Capacity}}$$

*Run From HBM*

$$\text{Time} = N_{\text{iter}} * \text{Size} / \text{BW}_{\text{HBM}} + \text{Size} / \text{BW}_{\text{Capacity}}$$

*Expect*

$$\text{BW}_{\text{HBM}} / \text{BW}_{\text{Capacity}} \sim 5-20$$

**Question:** Generally need higher parallelism to achieve  $\text{BW}_{\text{HBM}}$  vs  $\text{BW}_{\text{Capacity}}$   
=> What about Direct Solvers?

# The Way Forward

- Stabilize Kokkos Capabilities
  - Support tasking on all platforms
  - Make sure compilers optimize through layers
  - Harden KNL support for High Bandwidth Memory
- Broaden Implementation Coverage for Kokkos Kernels
- Support Production Teams in Adoption
- Develop more Documentation
- Extend profiling tools to help with transition

[www.github.com/kokkos/kokkos](https://www.github.com/kokkos/kokkos):

[www.github.com/kokkos/kokkos-tutorials](https://www.github.com/kokkos/kokkos-tutorials):

[www.github.com/kokkos/kokkos-tools](https://www.github.com/kokkos/kokkos-tools):

[www.github.com/trilinos/Trilinos](https://www.github.com/trilinos/Trilinos):

Kokkos Core Repository

Kokkos Tutorial Material

Kokkos Profiling Tools

Trilinos Repository





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