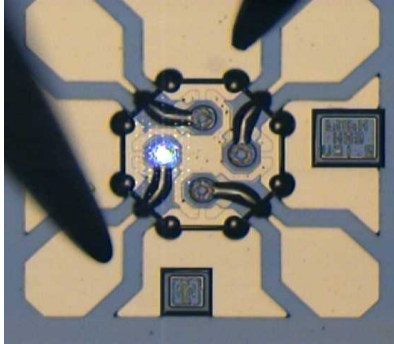
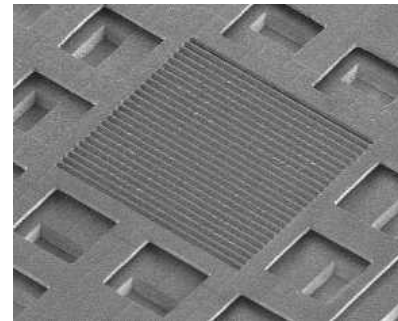


**Single-Frequency VCSEL**



**MEMS Grating Interferometer**



SAND2016-1480C

## **VCSELs for Interferometric Readout of MEMS Sensors**

**SPIE Photonics West 2016, San Francisco, CA  
February 2016**

**Darwin Serkland, Kent Geib, Greg Peake, Gordon Keeler,  
Mike Shaw, Mike Baker, Murat Okandan\***  
***Sandia National Laboratories***  
***\* EIOS, Inc.***

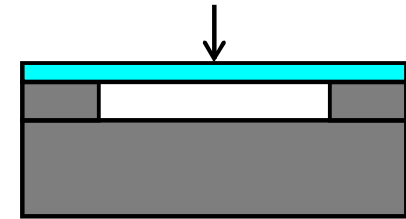
Sandia National Laboratories is a multi-program laboratory managed and operated by Sandia Corporation, a wholly owned subsidiary of Lockheed Martin Corporation, for the U.S. Department of Energy's National Nuclear Security Administration under contract DE-AC04-94AL85000.

# Outline

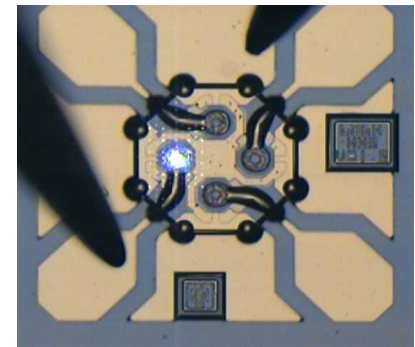
- MEMS sensors
  - Raw signal is position of moving mass
- Capacitive Readout Options
  - Vary gap
  - Vary overlap
- Optical Interferometer Options
  - Two-mirror Michelson
  - Grating Interferometer
- VCSEL requirements
  - Single mode
  - Stable wavelength
  - Low amplitude and phase noise
- Summary

## MEMS Pressure Sensor

Pressure differential displaces membrane



## Single-Frequency VCSEL

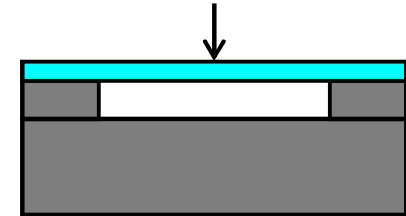


# MEMS Sensors

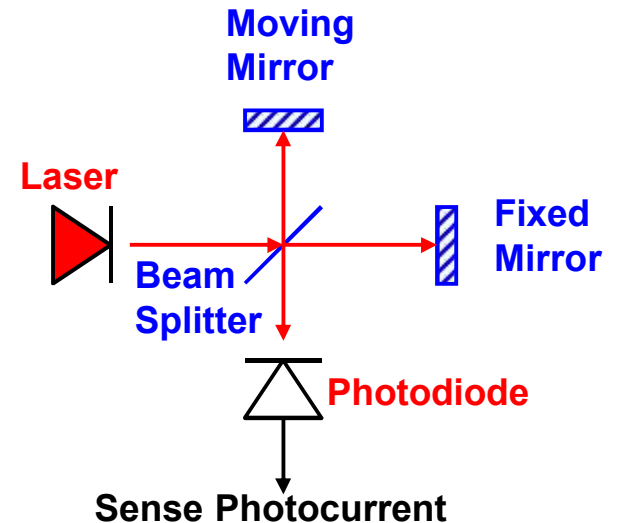
- MEMS sensors offer low-cost due to batch fabrication
  - Pressure sensors, microphones, accelerometers, gyroscopes
- Raw signal is position of moving mass (proof mass)
- Traditionally MEMS position readout is capacitive
- Optical interferometric readout can improve resolution and dynamic range
  - But increases system complexity

## MEMS Pressure Sensor

Pressure differential displaces membrane

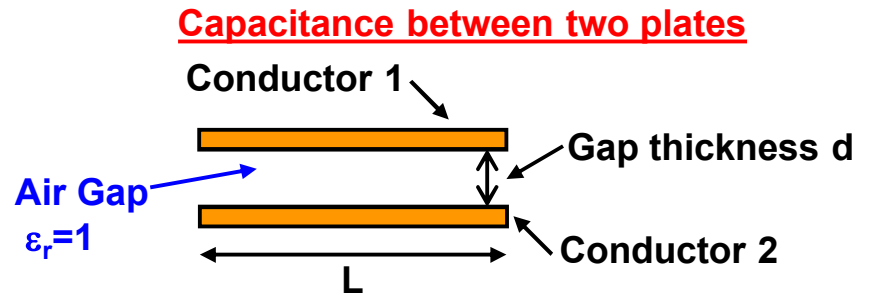


## Michelson Interferometer

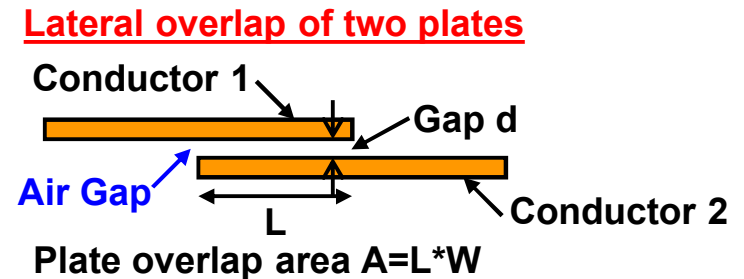


# MEMS Sensors: Capacitive Readouts

- Parallel plate capacitance
  - Capacitance between two plates varies as  $C = \epsilon_0 \epsilon_r A/d$
  - Need  $C > 10\text{pF}$  to measure with decent SNR
    - $A = (1\text{mm})^2, d = 2\mu\text{m}$ :  $C = 5\text{pF}$
    - Gap  $d$  must be small and fixed
- Option 1. Change gap between plates
  - Nonlinear sensitivity vs. position
  - Limited dynamic range
- Option 2. Change lateral overlap between plates
  - Periodic signal like interferometer
    - Period larger than 4 microns
    - Sensitivity 10x worse than interferometer

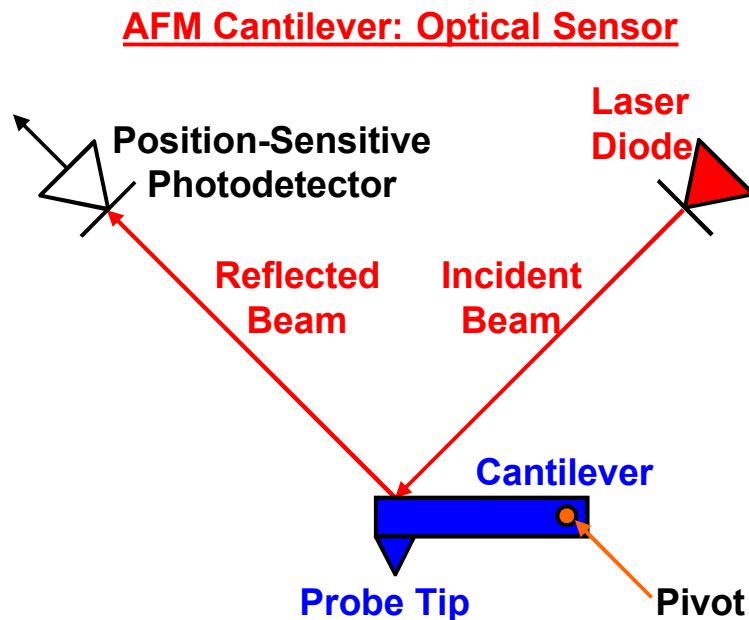


Capacitance  $C = \epsilon_0 \epsilon_r A/d$



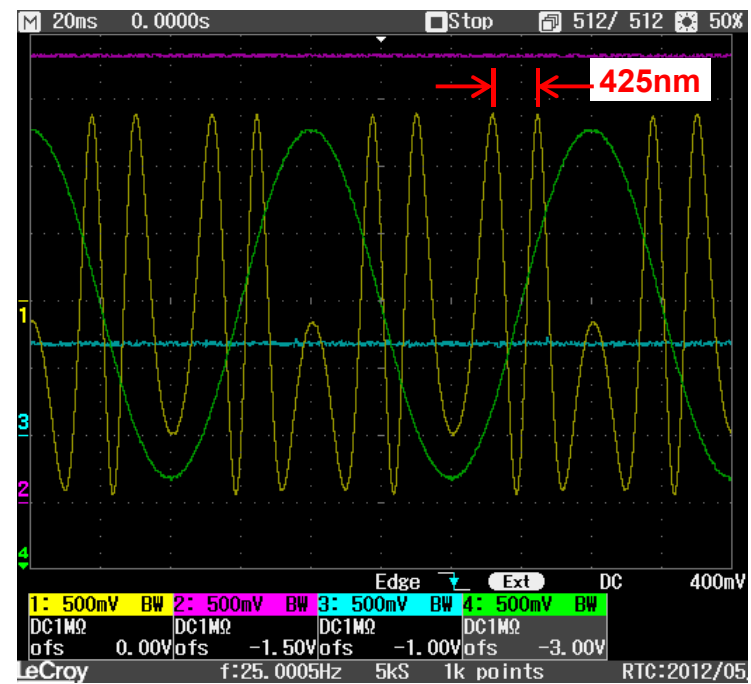
# MEMS Sensors: Optical Readouts

- Historically motivated by Atomic Force Microscope (AFM) usage of optical readouts
- Option 1. Change angle of beam
  - Requires a long “lever” arm



- Option 2. Interferometer
  - Can sense position changes much smaller than 1 wavelength (850nm)
    - SNR=10<sup>5</sup> (100dB) yields 1pm (0.01Å) resolution

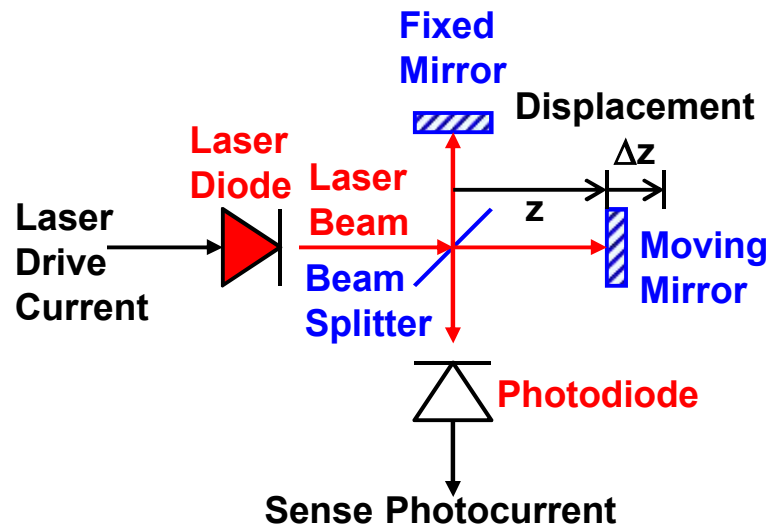
**Interferometer Readout: Period =  $\lambda/2$**



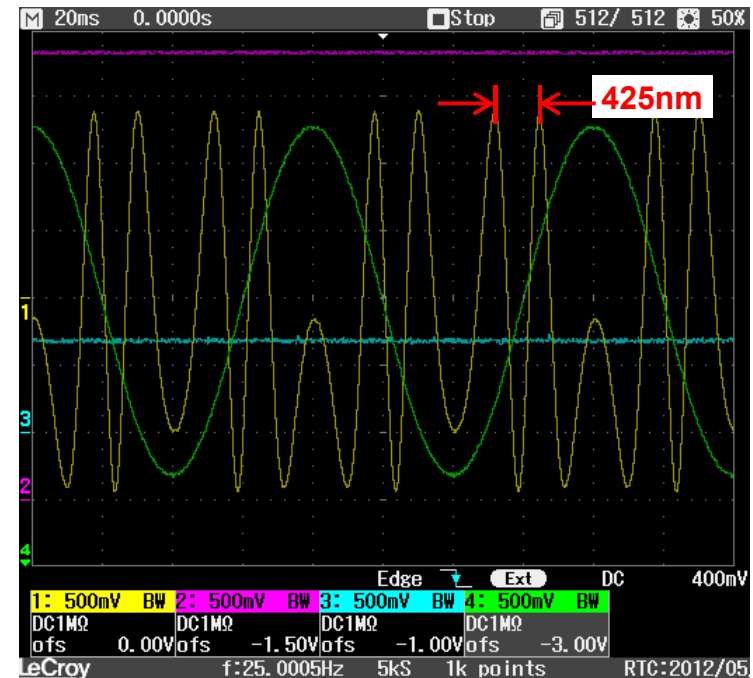
# Interferometer Option 1: Two-Mirror Michelson

- Michelson topology
  - Advantage is large dynamic range
    - MEMS can move by  $>100\lambda$
- Michelson data
  - Reference mirror driven with piezo over distance 900 nm
    - Noise is hardly visible:  $\text{SNR} > 1,000$ , resolution  $< 0.1\text{nm}$

Michelson Schematic



Michelson Data

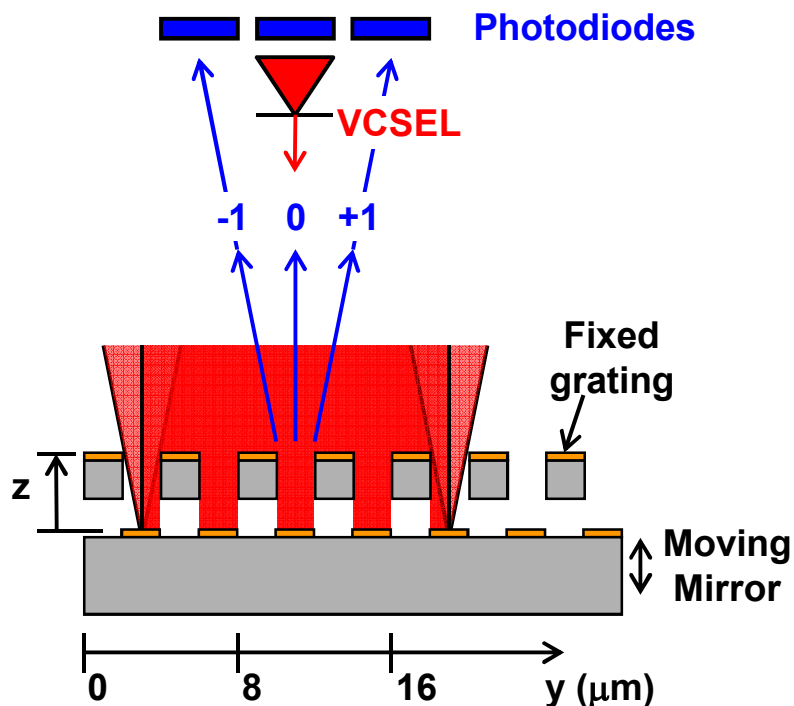


# Interferometer Option 2: Grating Interferometer

- Grating Interferometer Topology

- Advantage is monolithic implementation

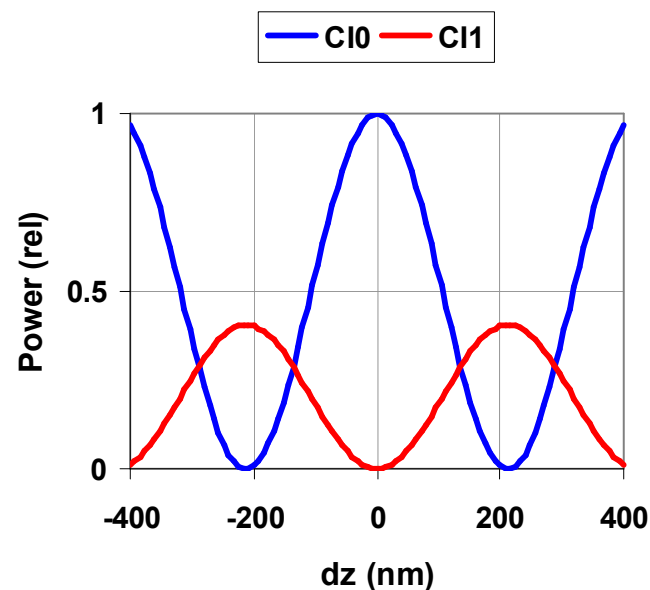
## MEMS Cross-Section



- Grating Interferometer Theory

- Grating is beam splitter (and one mirror)
- Senses gap between grating and “moving mirror”

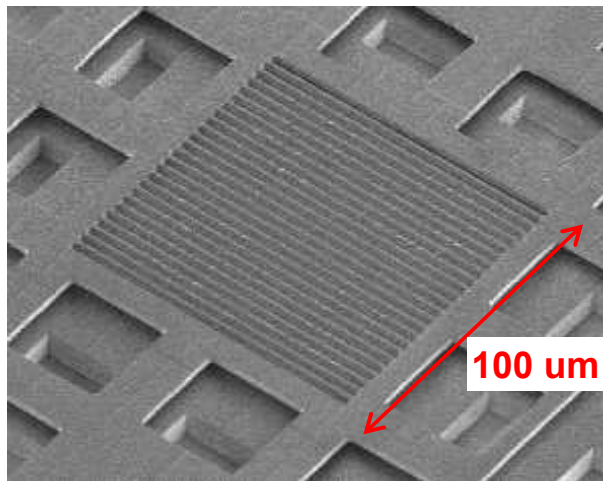
## Photodiode Signals: 0<sup>th</sup> and 1<sup>st</sup> orders



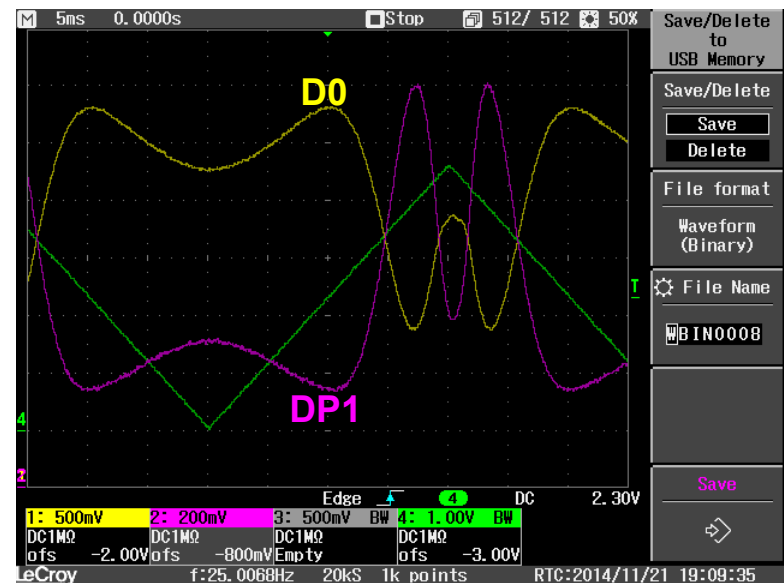
# Grating Interferometer Data

- Grating Interferometer Fabrication
  - Grating fabricated of 2.25-um thick polysilicon
  - SacOx thickness 3 um
- VCSEL + Interferometer Data
  - Drive proof mass electrically relative to grating
  - Detect 0 and +1 orders

Grating: 4-um Period



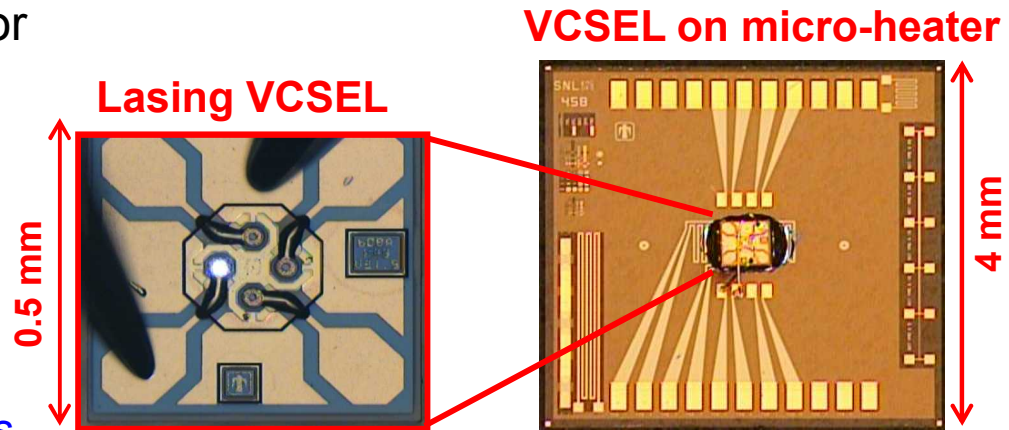
Photodiode Signals: 0<sup>th</sup> and 1<sup>st</sup> orders



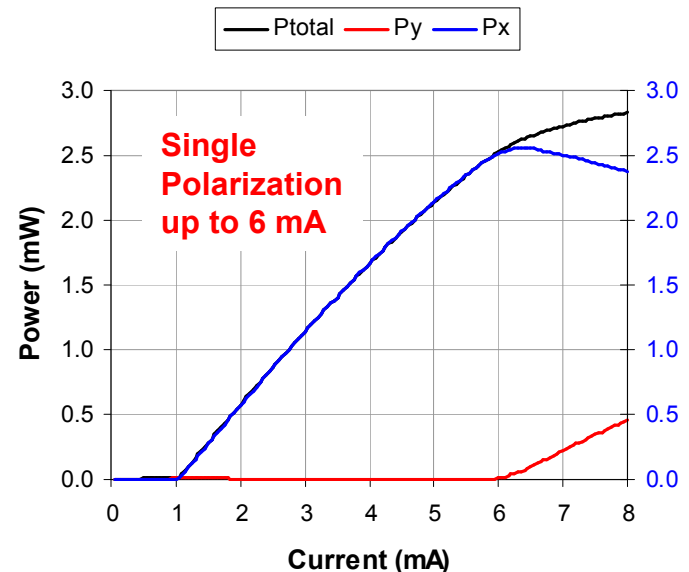


# Single-frequency VCSEL Light Sources

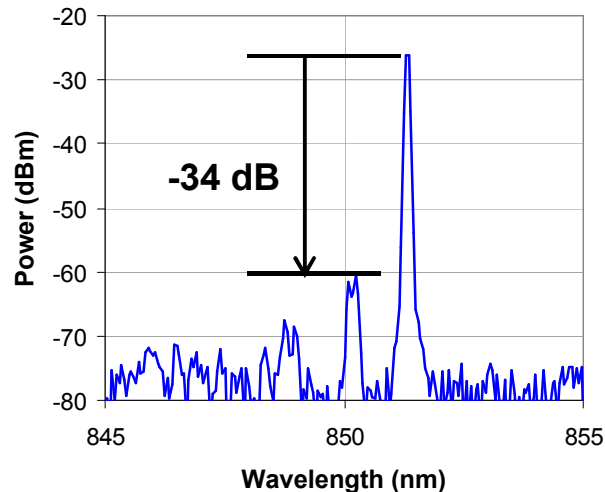
- A single-frequency laser is ideal for driving most interferometers
  - Large displacement range
  - Narrow collimated beams
- VCSEL
  - Compact form factor
  - Low-power consumption
  - Compatible with integrated circuits
    - Drive with 2mA current at 1.7V drop
  - Single frequency, single polarization



**VCSEL Output Power vs. Current**



**Single-frequency VCSEL spectrum**

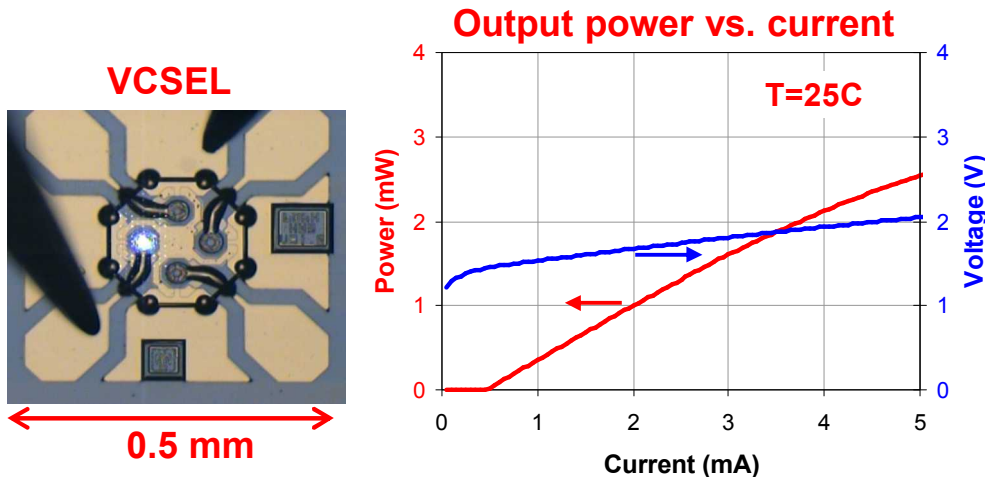


# VCSEL frequency stability

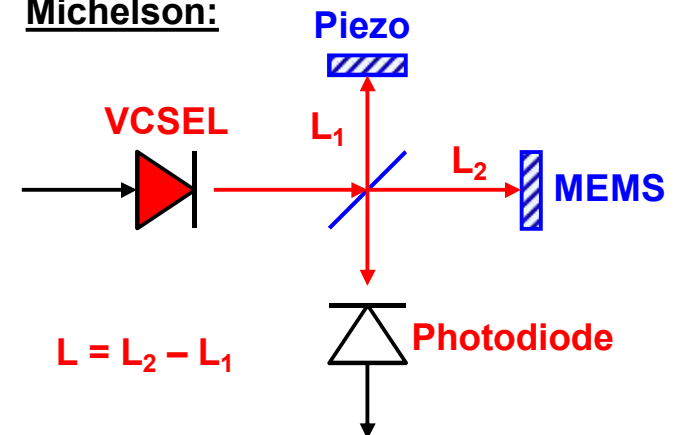
- Spectroscopy-grade VCSEL
  - Wavelength = 850 nm
    - Frequency = 353 THz
  - Current = 2 mA
    - Threshold  $I_{th} = 1$  mA
  - Voltage = 1.7 V
  - Output power = 0.2 mW (at 100 C)
  - Linewidth = 50 MHz
  - Temperature tuning = -25 MHz/mK
  - Current tuning = -125 MHz/uA

- Interferometer converts FM to AM
  - Un-equal arm lengths yield sensitivity to laser frequency
    - Example:
      - Laser:  $\lambda=850\text{nm}$ ,  $f=353\text{THz}$
      - Interferometer:  $\Delta L=10\mu\text{m}$
      - Frequency change:  $df=50\text{MHz}$
      - Differential phase change:  $d\phi=1\text{E-}5$

$$d\phi = 2\pi \left( \frac{L}{\lambda} \right) \left( \frac{df}{f} \right)$$

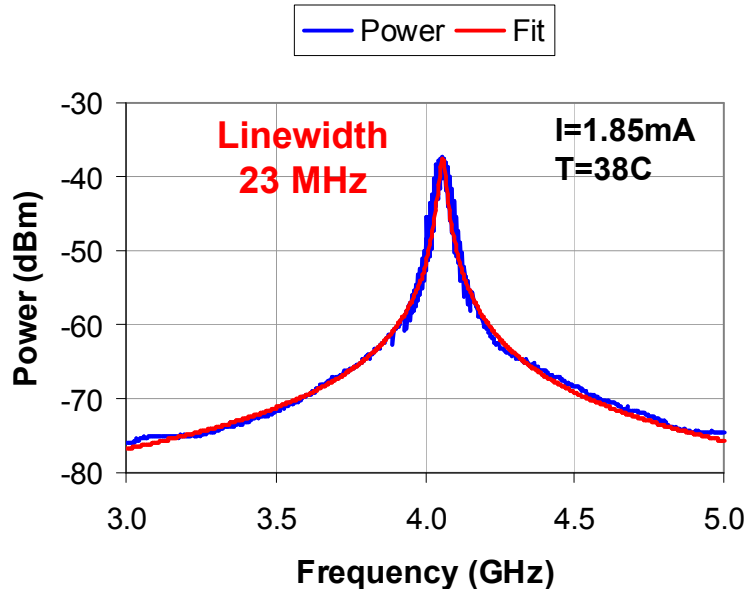


**Michelson:**

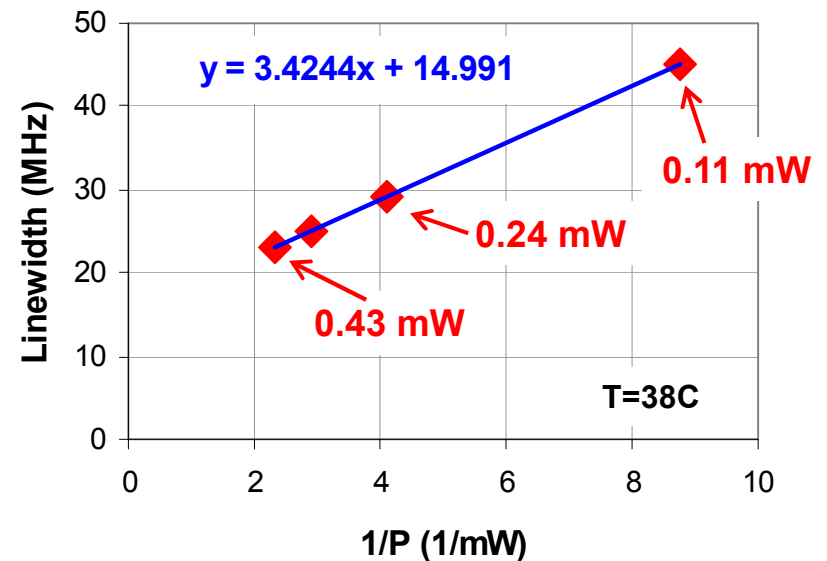


# Narrow Linewidth VCSELs

- VCSEL linewidth measurement
  - 23 MHz measured
    - Some slow frequency drift observed during 5-second spectrum analyzer sweep



- Linewidth versus output power
  - Expect  $1/P$  dependence



# Summary

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- MEMS sensors offer high performance, small form factor, and low cost
  - COTS sensors use capacitive sensing of MEMS position
- Optical readouts can improve MEMS sensor performance
  - Higher Sensitivity
  - Large Dynamic Range
- Single-frequency VCSELs can meet the needs for MEMS readout
  - Low cost
  - Compact integration with MEMS
  - DC accuracy requires stable wavelength
  - High SNR requires low intensity noise and frequency noise