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Development of a Single Input Multiple Output (SIMO) Input Derivation Algorithm for Oscillatory Decaying Shocks

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Chad Heitman, Jerry Cap, Vit Babuska
Sandia National Laboratories
Albuquerque, NM

Jack Reid
Massachusetts Institute of Technology
Cambridge, MA



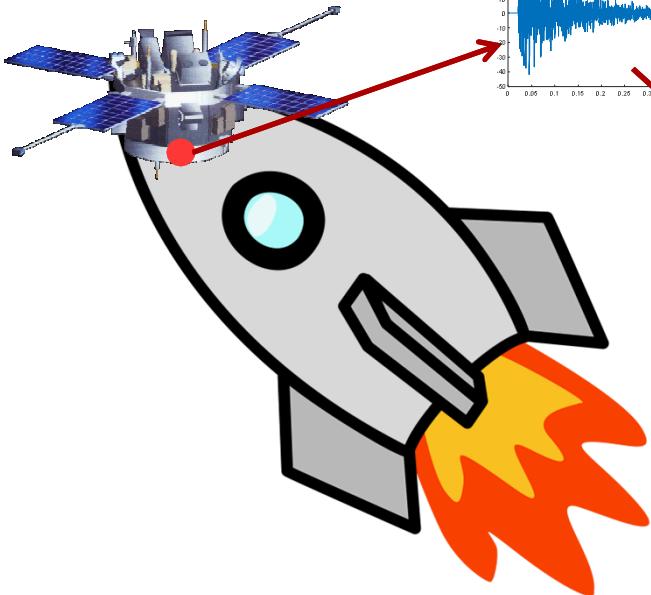
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Acknowledgments

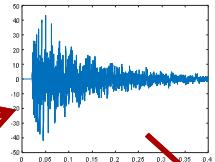
- Coauthor
 - Jack Reid, Jerry Cap, Dr. Vit Babuska
- Code Development & Validation
 - Jack Reid
- Technical Discussion & Analysis
 - David Smallwood
- Management
 - Scott Klenke

Traditional Laboratory Shaker Shock

Field Test

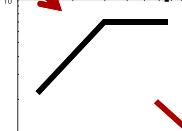


Time History

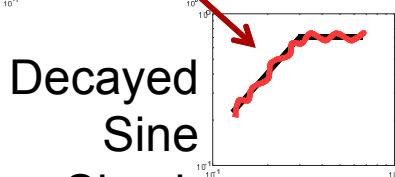


SRS

Requirement



Decayed Sine Shock



Lab Test



The shaker can match the defined input - but either no attempt is made to match the other response locations to their field responses or it is done manually

Sum of Decayed Sinusoids Shaker Shock

- Convenient to describe shock time history as sum of decayed sines
- Sine tones are described by amplitude, frequency, decay, and delay
- Frequency, decay, and delay are predefined by user based on the characteristics of the shock
- Amplitude is optimized to match reference SRS

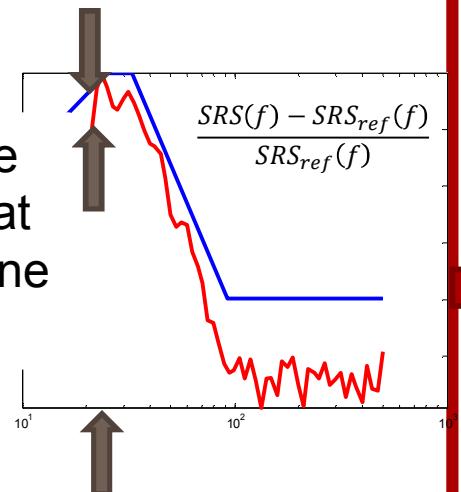
$$\sum_{i=1}^N A_i e^{-\lambda_i w_i t} \sin(w_i t + \phi_i)$$



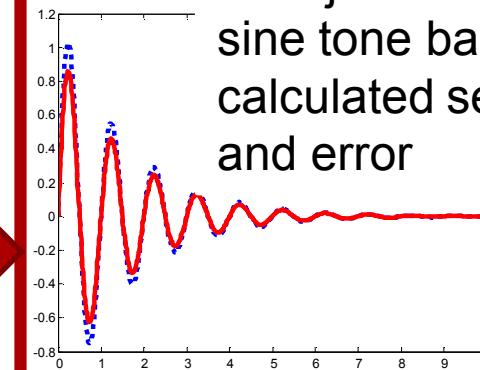
Smallwood's Optimization Algorithm

1. Make a guess of the sine tone amplitudes

2. Calculate SRS error at first sine tone frequency



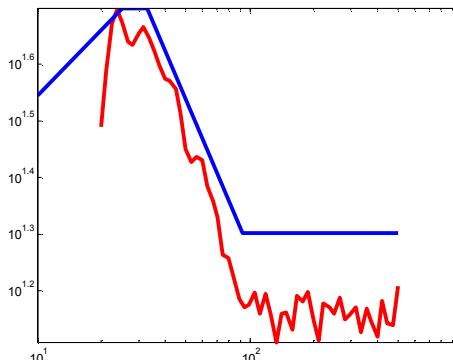
3. Adjust Amplitude of sine tone based on calculated sensitivity and error



4. Calculate new SRS

5. Calculate new time history with adjusted amplitude of one sine tone

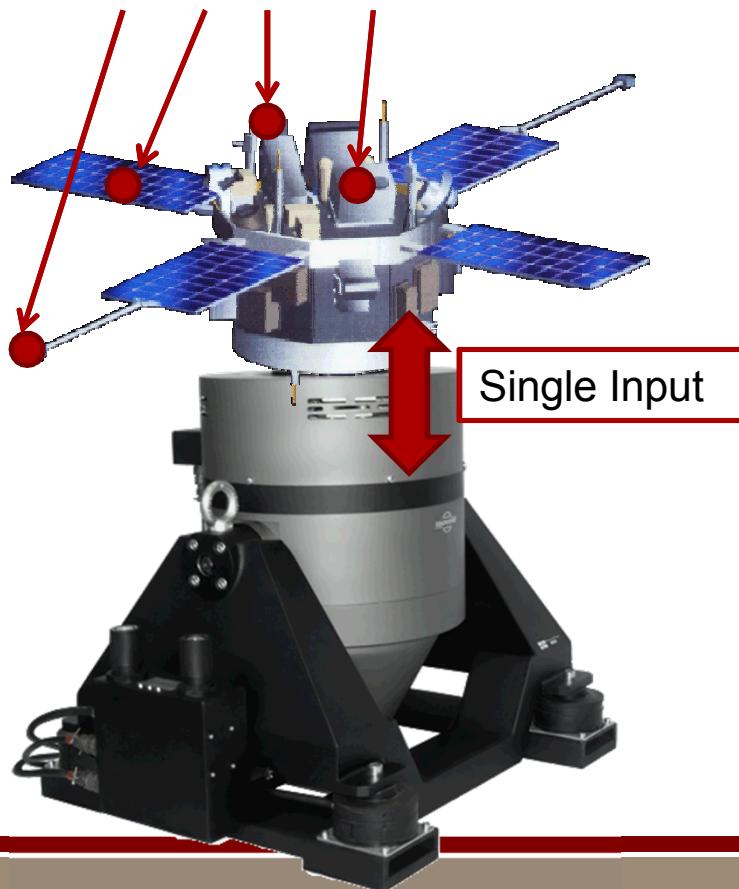
6. Compute the error at the sine tone frequency – if within tolerance then move to the next sine tone



The algorithm steps through from the lowest frequency sine tone to the highest frequency sine tone

Single Input Multiple Output Shock

Points of Interest – Want to match these shaker test SRSs to reference SRSs



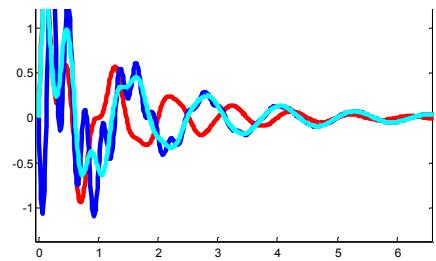
Objective – Find an input that will suitably match the response points of interest to their reference SRSs

Recognize that single axis input cannot exactly match multiple responses except as a weighted average

Single Input Multiple Output Shock

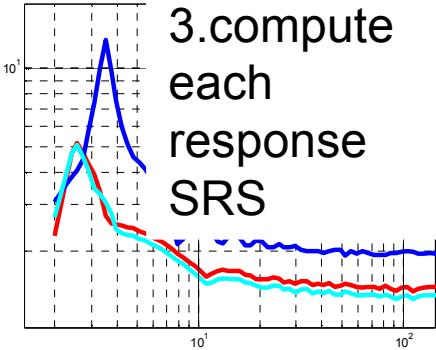
1. Make a guess of the sine tone amplitudes

2. Convolve the input with each response transfer function to obtain response time history

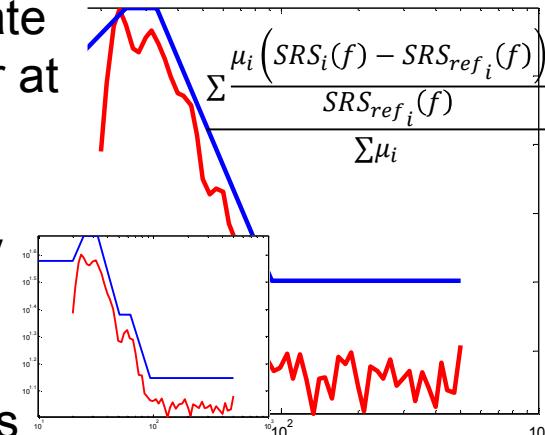


5. Adjust Amplitude of sine tone based on calculated sensitivity and error

3. compute each response SRS



4. Calculate SRS error at first sine tone frequency based on assigned weightings



If error is within tolerance, go to next frequency

Weightings of Target SRSs

- Error function allows for the weighting of each response error (0,1)
- If one response location (target SRS) is more critical then unequal weightings may be better
- Weightings could be developed further to include
 - Prioritizing the minimization of the largest error rather than minimizing the average error
 - Response limited weighting scheme - Allow the 1 response SRS to be equal or less than the target SRS while the other response SRSs are all less than their targets



Test Case 1: Coupled System

Drive toy problem with experimental input

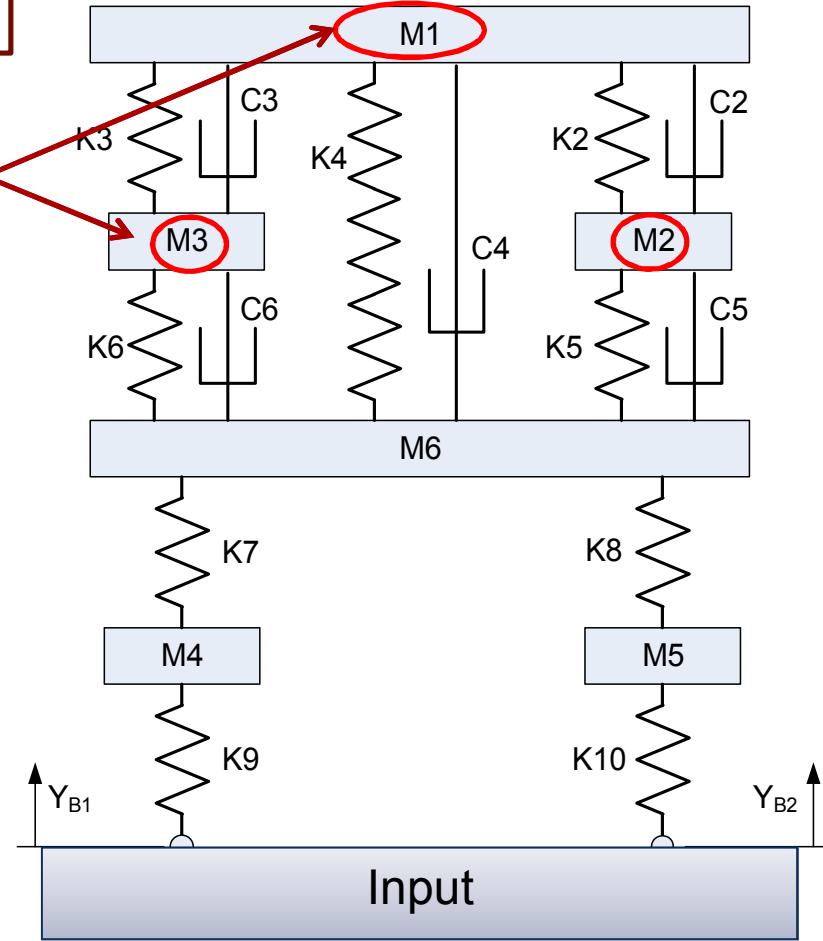
Calculate response at points of interest

Calculate Target SRS

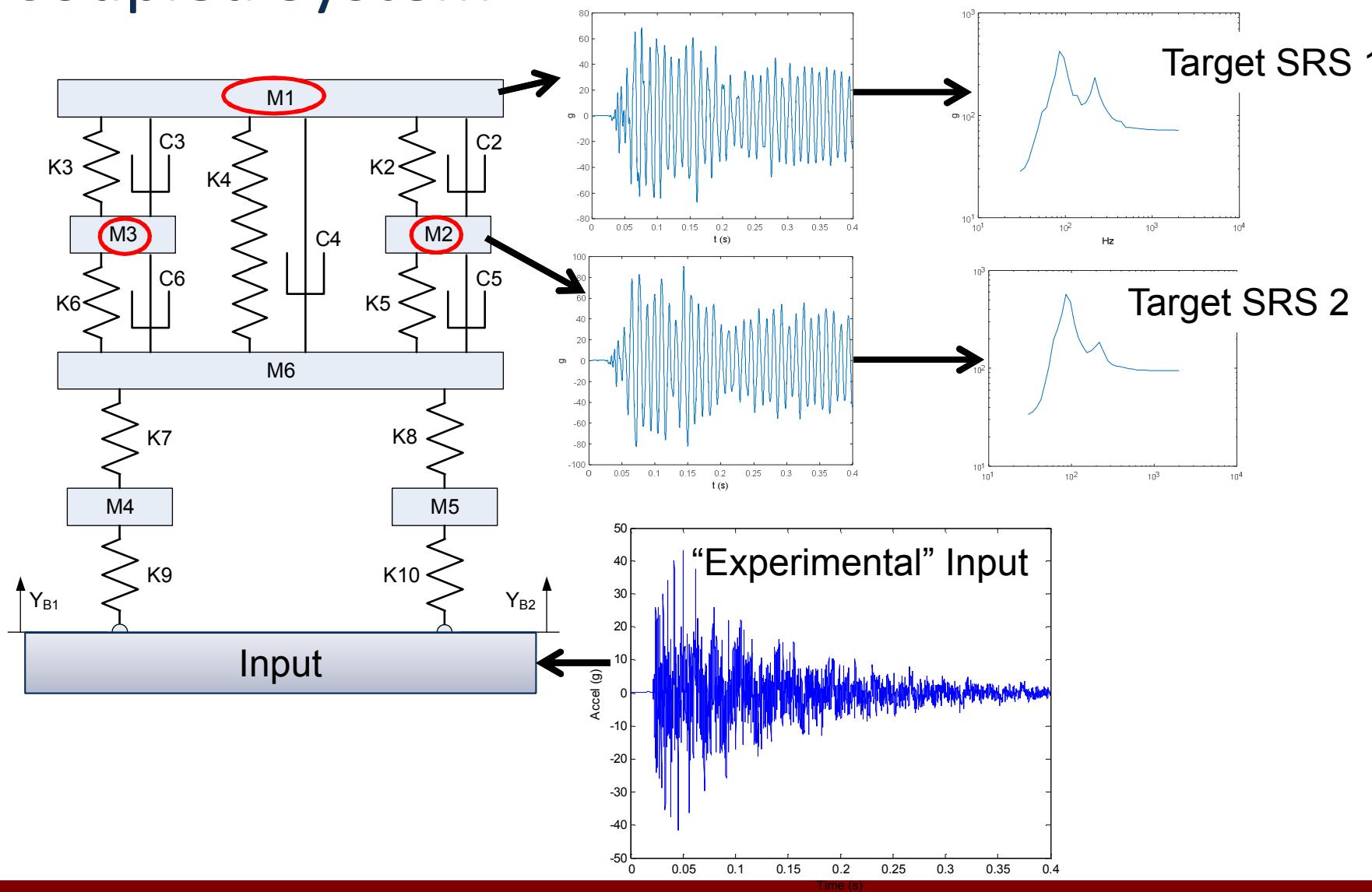
Use SIMO algorithm to compute input and predicted SRSs at points of interest

Do the predicted SRSs match the target SRSs?

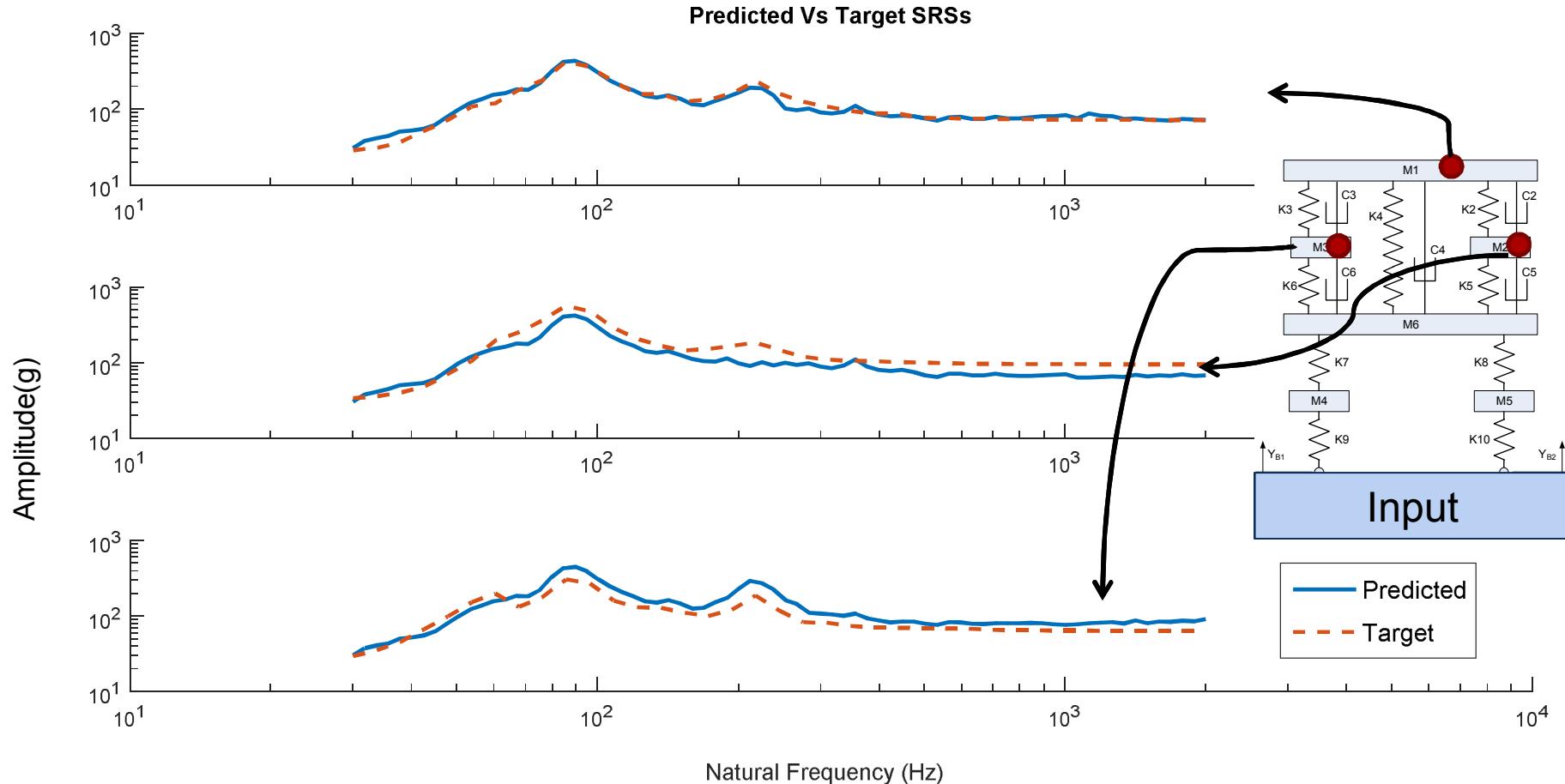
How does the computed input match the experimental input?



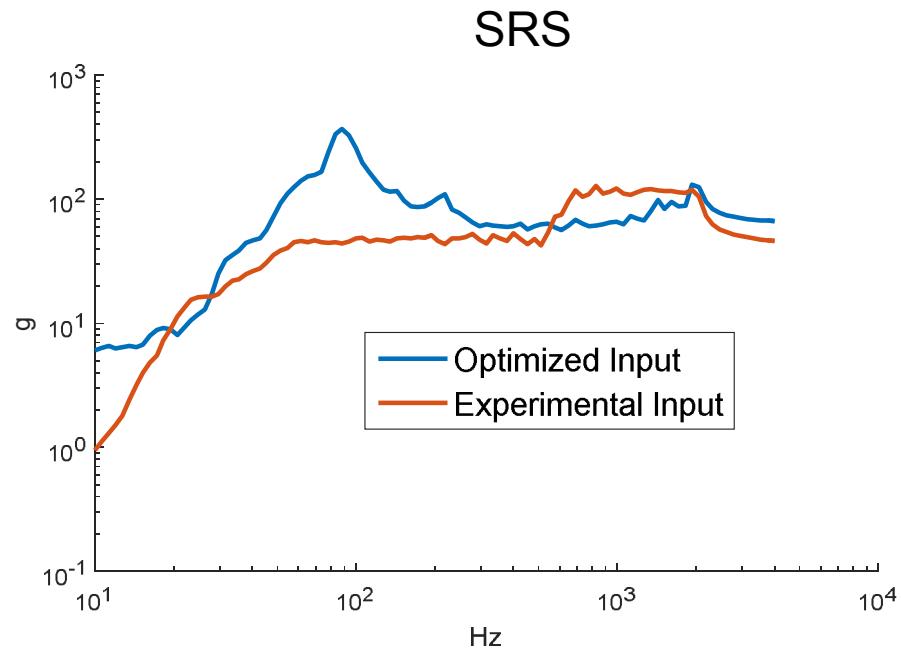
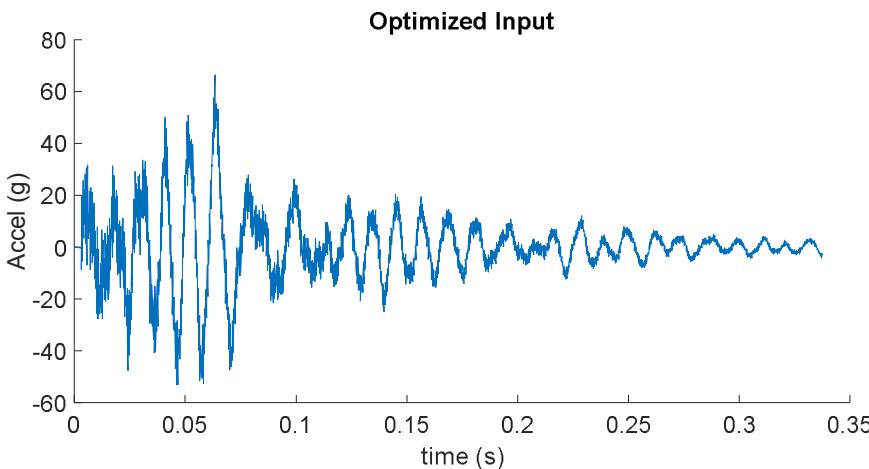
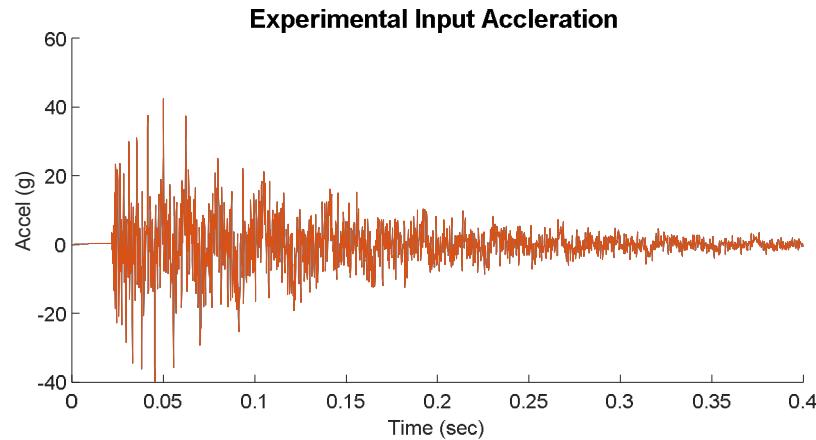
Test Case 1: Field Response for Single Input Coupled System



Test Case 1: Predicted vs Target SRSs

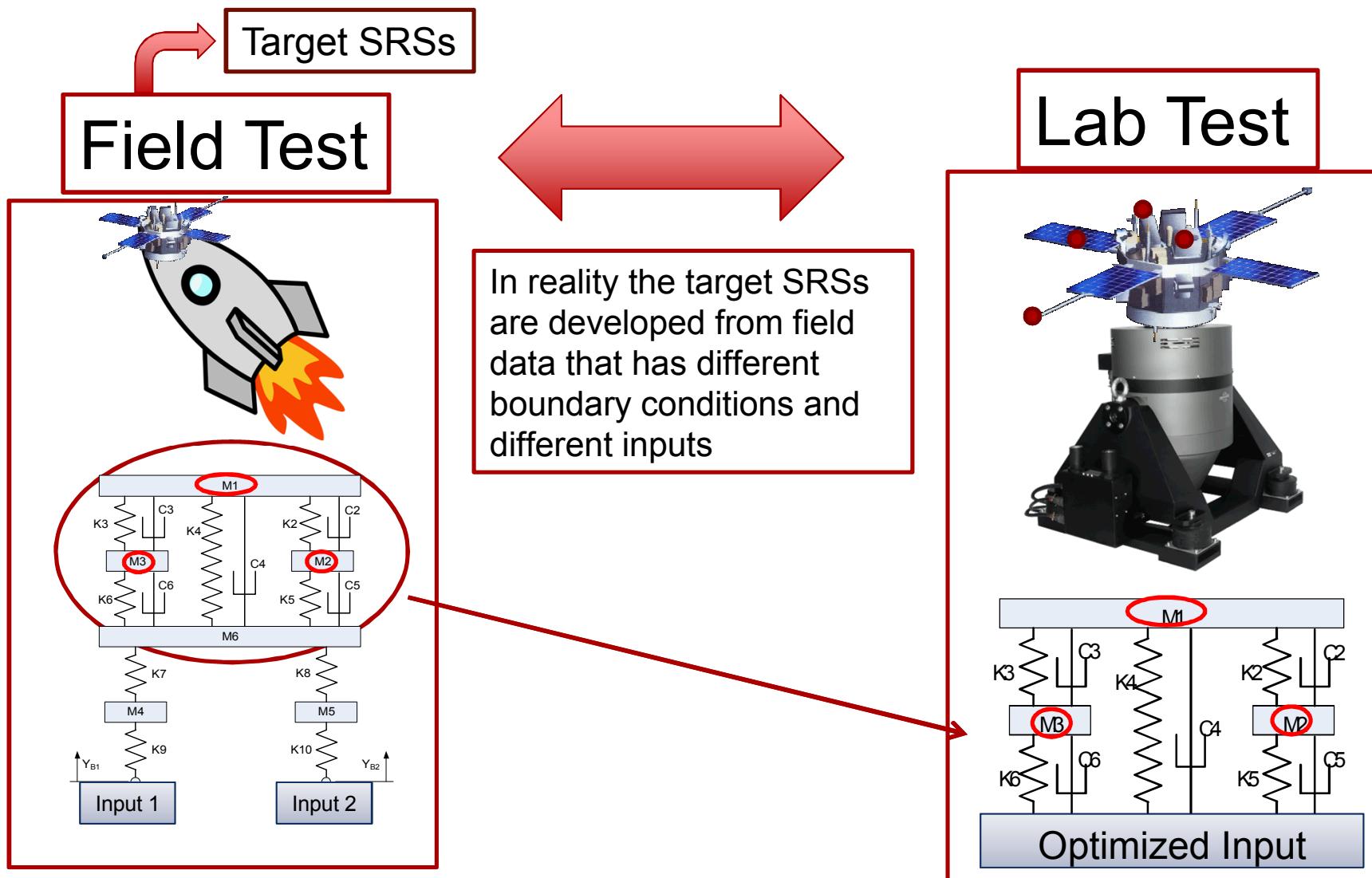


Test Case 1: Experimental Input vs Optimized Input

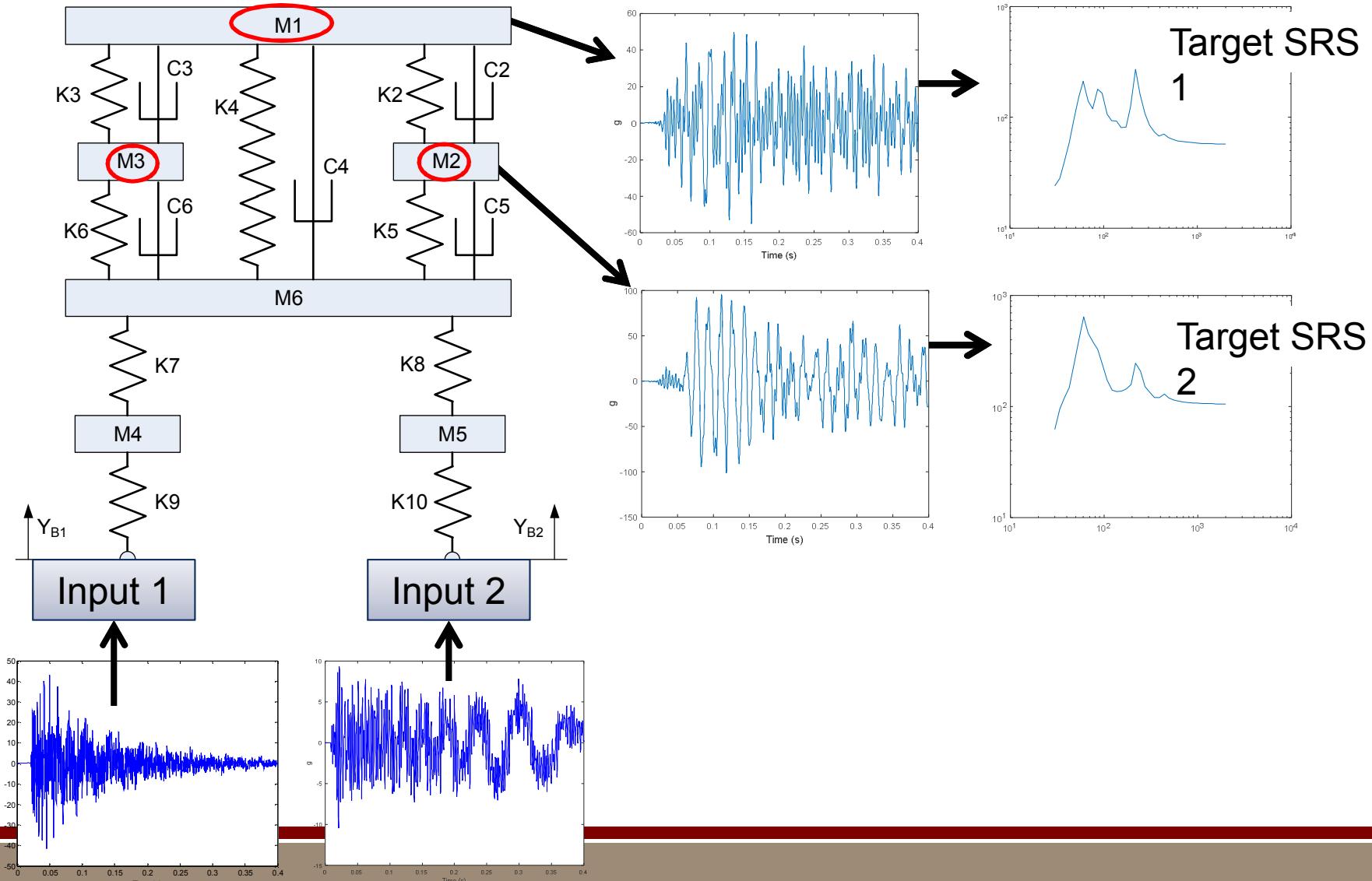


- Significant differences in experimental and optimized input
- Further investigation needed
- Not trying to match inputs
- Significant difference in complexity of each input

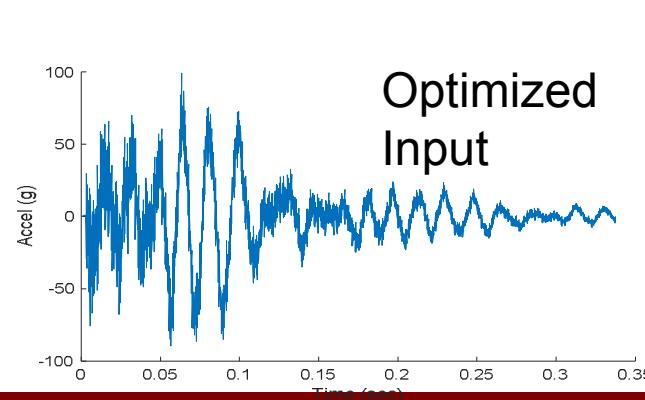
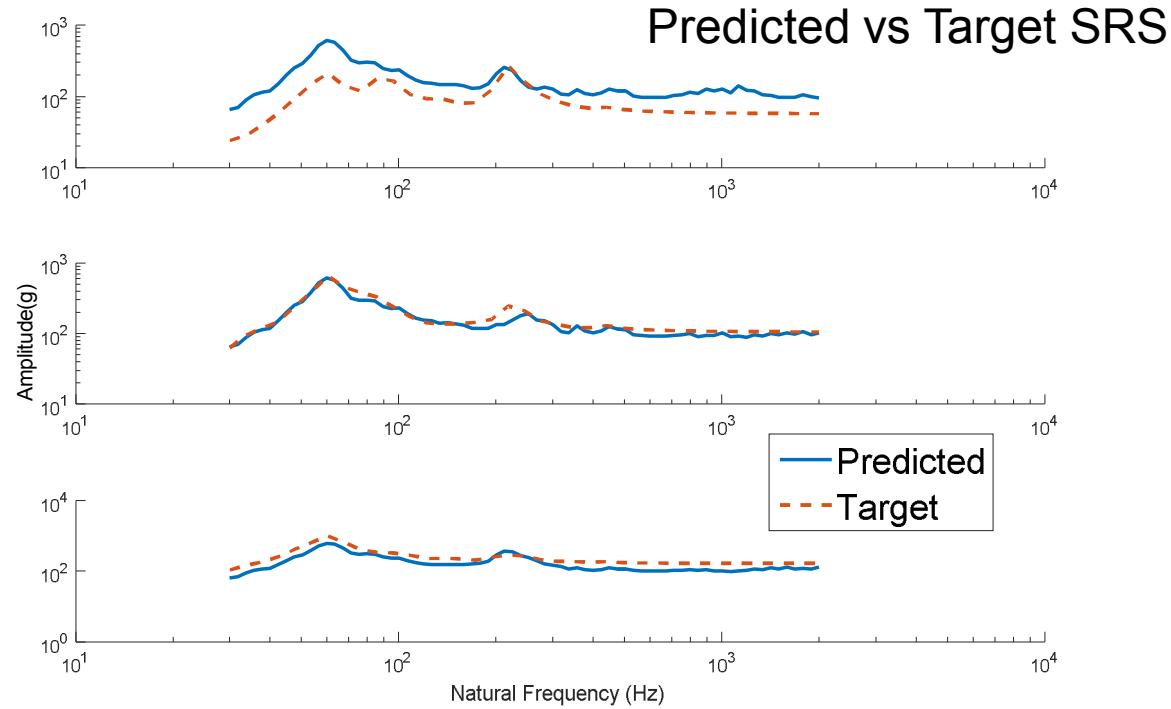
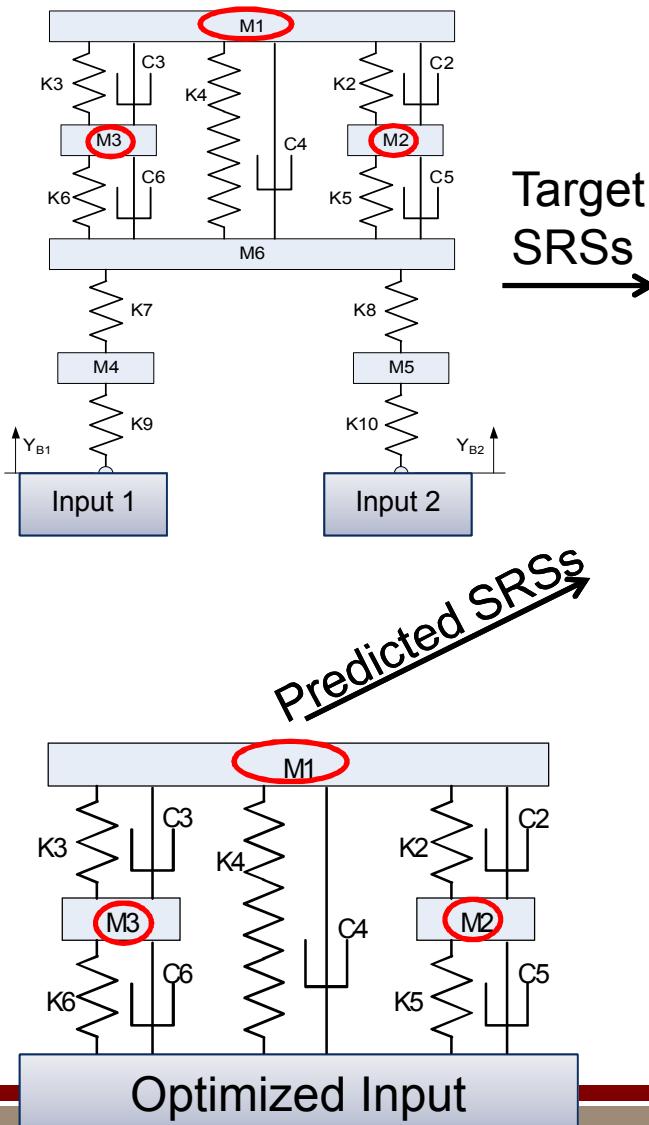
Test Case 2: Decoupled Lab Test



Test Case 2: Field Response for 2 Input Coupled System



Test Case 2: Optimized Input and Predicted SRSs



Summary & Conclusion

Find a decayed sines shaker input that will suitably match the response points of interest to their reference SRSs

