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Nonlinear Dirac equation solitary waves in the presence of external driving forces

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We consider the nonlinear Dirac (NLD) equation in 1+1 dimension with scalar-scalar self-interaction in the presence of external forces as well as damping of the form $f(x, t) - i\mu\gamma^0\Psi$, where both f and Ψ are two-component spinors. We develop an approximate variational approach using collective coordinates (CC) for studying the time dependent response of the solitary waves to these external forces. This approach predicts intrinsic oscillations of the solitary waves, i.e. the amplitude, width and phase all oscillate with the same frequency. The translational motion is also affected, because the soliton position oscillates around a mean trajectory. We then compare the results of the variational approximation with numerical simulations of the NLD equation, and find a good agreement, if we take into account a certain linear excitation with specific wavenumber that is excited together with the intrinsic oscillations such that the momentum in a transformed NLD equation is conserved. We also solve explicitly the CC equations of the variational approximation in the non-relativistic regime for a homogeneous external force and obtain excellent agreement with the numerical solution of the CC equations.

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I. INTRODUCTION

Since the first nonlinear generalization of the Dirac equation by Ivanenko [1], the nonlinear Dirac (NLD) equation has emerged naturally as a practical model in many physical systems, such as extended particles [2–4], the gap solitons in nonlinear optics [5], light solitons in waveguide arrays and experimental realization of an optical analog for relativistic quantum mechanics [6–8], Bose-Einstein condensates in honeycomb optical lattices [9], phenomenological models of quantum chromodynamics [10], as well as matter influencing the evolution of the Universe in cosmology [11]. To maintain the Lorentz invariance of the NLD equation, the self-interaction Lagrangian can be built up from the bilinear covariants. Different self-interactions give rise to different NLD equations. Several interesting models have been proposed and investigated based on the scalar bilinear covariant [12–15], the vector bilinear covariant [16], the axial vector bilinear covariant [17], both scalar and pseudoscalar bilinear covariants [18], both scalar and vector bilinear covariants [19, 20] among others.

A key feature of these NLD equations is that they allow solitary wave solutions or particle-like solutions – localized solutions with finite energy and charge [21]. That is, the particles appear as intense localized regions of field which can be recognized as the basic ingredient in the description of extended objects in quantum field theory [22]. For the NLD equation in (1+1) dimensions (*i.e.* one time dimension plus one space dimension), several analytical solitary wave solutions were derived for the cubic nonlinearity [23, 24], for fractional nonlinearity [25] as well as for general nonlinearity [19, 26, 27] by using explicitly the constraints resulting from energy-momentum conservation; and this is well summarized by Mathieu [28]. With the help of the analytical expressions of the NLD solitary wave solutions, the interaction dynamics among them has been studied and rich nonlinear phenomena have been revealed in a series of works [29–34].

An interesting topic for the NLD equation solitary waves is the stability issue, which has been the central topic in works spread out over several decades that is still ongoing. Analytical studies of the NLD solitary wave stability face serious obstacles [35–37], while results of computer simulations are contradictory [17, 38–40]. Numerical results inferred that both the multi-hump profile and high-order nonlinearity could undermine the stability during the scattering of the NLD solitary waves [30, 33]. For the NLD equation with scalar-scalar interactions (*i.e.* the Soler model) the solitary wave solutions can have either one hump or two humps. Quite recently, for the Soler model, we found that all stable NLD solitary waves have a one-hump profile, but not all one-hump waves are stable, while all waves with two humps are unstable [41]. This result is in agreement with the rigorous analysis in the nonrelativistic limit [42]. In order to further understand the behavior and the stability of NLD solitary waves, the NLD equation in the presence of external potentials has been investigated [43–46] and a sufficient dynamical condition for instability to arise was postulated through a collective coordinates (CC) theory [46]. In this work, we will continue to study the NLD solitary waves under external forces.

For the forced nonlinear Schrödinger (NLS) equation when subject to an external force of the form $f(x) = r \exp(-iKx)$, the authors found [47–49] that intrinsic soliton oscillations are excited, *i.e.*, the soliton amplitude, width, phase, momentum, and velocity all oscillate with the same frequency. This behavior was predicted by a collective coordinates theory and was confirmed by numerical simulations. Moreover, one specific plane wave phonon (short for a linear excitation) with wavenumber $k = -K$ is also excited such that the total momentum in a transformed NLD equation is conserved. This phonon mode was not included in the CC theory and had to be calculated separately [50].

In the present paper we consider the relativistic generalization of our previous work on the forced NLS equation, namely the behavior of solitary wave solutions to the NLD equation when subjected to an external force which is now a two-component spinor. In Sec. II we review exact analytical solutions for the unperturbed NLD equation. In Sec. III we present the NLD equation with external force $f_j(x, t) = r_j \exp[i(\nu_j t - K_j x)]$, $j = 1, 2$, and the corresponding Lagrangian density. Using the energy-momentum tensor we show that the total energy is conserved if the force is time independent ($\nu_j = 0$).

For the case $K_1 = K_2 = K$, $\nu_j = 0$ and zero dissipation we perform in Sec. IV a transformation such that the transformed NLD equation is invariant under space translations and thus the momentum is conserved. In Sec. V we make a variational ansatz with three collective coordinates. All integrals that appear in the Lagrangian can be performed exactly and we finally have a set of 3 ODEs as CC equations. For a special case these equations can be simplified and an approximate analytical solution can be obtained. Solutions are also obtained in the non-relativistic regime, when $K = 0$, by an expansion up to order v^2 , where v is the velocity.

In Sec. VI the spectrum of the linear excitations (phonons) is calculated and together with the numerical solutions of the CC equations this is compared with the results from our numerical simulations (Sec. VII). We always obtain periodic solutions and the spectra of these solutions exhibit two dominant peaks: The phonon frequency $\Omega_K = \sqrt{m^2 + K^2}$ and the intrinsic oscillation frequency Ω_{sim} . The frequency Ω_{sim} agrees nearly perfectly with the prediction Ω_{cc} from solving numerically the CC equations (Table I). The soliton position $q(t)$ performs small oscillations around a mean trajectory $\bar{v}_{sim} t$. This translational motion is only weakly affected by the intrinsic soliton oscillations. Further \bar{v}_{cc} agrees with \bar{v}_{sim} within an error of about 14% (Table I). The reason is that the plane wave phonons with $k = -K$

are not taken into account in the CC theory. The summary of our main results is contained in Sec. VIII.

II. REVIEW OF EXACT SOLUTIONS TO THE NLD EQUATION

In this section we review the exact solitary wave solutions to the NLD equation,

$$(i\gamma^\mu \partial_\mu - m)\Psi + g^2(\bar{\Psi}\Psi)^\kappa \Psi = 0, \quad (2.1)$$

where we use the representation for the 1+1 dimensional Dirac Gamma matrices: $\gamma^0 = \sigma_3$; $\gamma^1 = i\sigma_2$, which we also used in [46]. The solitary wave solution in the rest frame is represented by

$$\Psi(x, t) = e^{-i\omega t} \psi(x) = e^{-i\omega t} \begin{pmatrix} A(x) \\ i B(x) \end{pmatrix}, \quad (2.2)$$

where A and B satisfy

$$\begin{aligned} \frac{dA}{dx} + (m + \omega)B - g^2(A^2 - B^2)^\kappa B &= 0, \\ \frac{dB}{dx} + (m - \omega)A - g^2(A^2 - B^2)^\kappa A &= 0. \end{aligned} \quad (2.3)$$

The solutions of these equations vanishing at infinity are

$$\begin{aligned} A &= \sqrt{\frac{(m + \omega) \cosh^2(\kappa\beta x)}{m + \omega \cosh(2\kappa\beta x)}} \left[\frac{(\kappa + 1)\beta^2}{g^2(m + \omega \cosh(2\kappa\beta x))} \right]^{\frac{1}{2\kappa}}, \\ B &= \sqrt{\frac{(m - \omega) \sinh^2(\kappa\beta x)}{m + \omega \cosh(2\kappa\beta x)}} \left[\frac{(\kappa + 1)\beta^2}{g^2(m + \omega \cosh(2\kappa\beta x))} \right]^{\frac{1}{2\kappa}}, \end{aligned} \quad (2.4)$$

where $\beta = \sqrt{m^2 - \omega^2}$. We are interested in bound state solutions that correspond to positive frequency $\omega > 0$ and which have energies in the rest frame less than the mass parameter m , i.e. $\omega < m$.

Because of Lorentz invariance we can find the solution in a frame moving with velocity v with respect to the rest frame. The Lorentz boost is given in terms of the rapidity variable η as follows (here $c = 1$):

$$v = \tanh \eta; \quad \gamma = \frac{1}{\sqrt{1 - v^2}} = \cosh \eta; \quad \sinh \eta = \frac{v}{\sqrt{1 - v^2}}. \quad (2.5)$$

In the moving frame, the transformation law for spinors tells us that:

$$\Psi(x, t) = \begin{pmatrix} \cosh(\eta/2) & \sinh(\eta/2) \\ \sinh(\eta/2) & \cosh(\eta/2) \end{pmatrix} \begin{pmatrix} \Psi_1^0[\gamma(x - vt), \gamma(t - vx)] \\ \Psi_2^0[\gamma(x - vt), \gamma(t - vx)] \end{pmatrix}, \quad (2.6)$$

since

$$\cosh(\eta/2) = \sqrt{(1 + \gamma)/2}; \quad \sinh(\eta/2) = \sqrt{(\gamma - 1)/2}. \quad (2.7)$$

This in component form reads:

$$\begin{aligned} \Psi_1(x, t) &= (\cosh(\eta/2)A(x') + i \sinh(\eta/2)B(x')) e^{-i\omega t'}, \\ \Psi_2(x, t) &= (\sinh(\eta/2)A(x') + i \cosh(\eta/2)B(x')) e^{-i\omega t'}, \end{aligned} \quad (2.8)$$

where

$$x' = \gamma(x - vt); \quad t' = \gamma(t - vx). \quad (2.9)$$

Note that $\cosh^2(\eta/2) + \sinh^2(\eta/2) = \cosh \eta = \gamma$.

III. EXTERNALLY DRIVEN NLD EQUATION

In previous papers [47, 49] we investigated the externally driven NLS equation

$$i\frac{\partial}{\partial t}\psi + \frac{\partial^2}{\partial x^2}\psi + g^2(\psi^*\psi)^\kappa\psi + \delta\psi = re^{-iKx} - i\mu\psi, \quad (3.1)$$

where μ is the dissipation coefficient, and r and K are constants. This equation can be derived by means of a generalization of the Euler-Lagrange equation

$$\frac{d}{dt}\frac{\partial\mathcal{L}}{\partial\psi_t^*} + \frac{d}{dx}\frac{\partial\mathcal{L}}{\partial\psi_x^*} - \frac{\partial\mathcal{L}}{\partial\psi^*} = \frac{\partial\mathcal{F}}{\partial\psi_t^*}, \quad (3.2)$$

where the Lagrangian density reads

$$\mathcal{L} = \frac{i}{2}(\psi_t\psi^* - \psi_t^*\psi) - |\psi_x|^2 + \frac{g^2}{\kappa+1}(\psi^*\psi)^{\kappa+1} + \delta|\psi|^2 - re^{-iKx}\psi^* - re^{iKx}\psi, \quad (3.3)$$

and the dissipation function density is given by

$$\mathcal{F} = -i\mu(\psi_t\psi^* - \psi_t^*\psi). \quad (3.4)$$

For the NLD case we instead consider a two-component spinor forcing term

$$f = \begin{pmatrix} f_1(x, t) \\ f_2(x, t) \end{pmatrix} \quad (3.5)$$

with the NLD equation

$$(i\gamma^\mu\partial_\mu - m)\Psi + g^2(\bar{\Psi}\Psi)^\kappa\Psi = f(x, t) - i\mu\gamma^0\Psi. \quad (3.6)$$

In what follows we will generalize our choice for the NLS equation by choosing

$$f_j(x, t) = r_j e^{i(\nu_j t - K_j x)}, \quad j = 1, 2, \quad (3.7)$$

with real parameters r_j , ν_j and K_j . Note that the phase of f is invariant under Lorentz transformations. As the second component of the spinor Ψ is the so-called ‘‘small component’’, which is smaller than the first component by the factor $\alpha = \sqrt{(m - \omega)/(m + \omega)}$, we will only consider cases with $r_2 = \epsilon r_1$, where $\epsilon = O(\alpha)$ or smaller.

Equation (3.6) can be derived in a standard fashion from the Lagrangian density

$$\mathcal{L} = \left(\frac{i}{2}\right)[\bar{\Psi}\gamma^\mu\partial_\mu\Psi - \partial_\mu\bar{\Psi}\gamma^\mu\Psi] - m\bar{\Psi}\Psi + \frac{g^2}{\kappa+1}(\bar{\Psi}\Psi)^{\kappa+1} - \bar{\Psi}f - \bar{f}\Psi + \mathcal{L}_0(b), \quad (3.8)$$

where $\mathcal{L}_0(b)$ is determined later on and $b = \lim_{x \rightarrow \pm\infty}\Psi(x, t)$. The term in the Lagrangian density which pertains to forcing can be written as

$$\mathcal{L}_3 = -2Re(\bar{f}\Psi), \quad (3.9)$$

and the full interaction part of the Lagrangian density is now

$$\mathcal{L}_I = \frac{g^2}{\kappa+1}(\bar{\Psi}\Psi)^{\kappa+1} - \bar{\Psi}f - \bar{f}\Psi. \quad (3.10)$$

The generalized Euler-Lagrange equation can be written as

$$\partial_\mu\frac{\partial\mathcal{L}}{\partial(\partial_\mu\bar{\Psi})} - \frac{\partial\mathcal{L}}{\partial\bar{\Psi}} = \frac{\partial\mathcal{F}}{\partial(\partial_t\bar{\Psi})}, \quad (3.11)$$

where the dissipation function density is now

$$\mathcal{F} = -i\mu(\bar{\Psi}\gamma^0\partial_t\Psi - \partial_t\bar{\Psi}\gamma^0\Psi). \quad (3.12)$$

The adjoint equation comes from the Euler-Lagrange equation:

$$\partial_\mu \frac{\partial \mathcal{L}}{\partial (\partial_\mu \Psi)} - \frac{\partial \mathcal{L}}{\partial \Psi} = \frac{\partial \mathcal{F}}{\partial (\partial_t \Psi)}, \quad (3.13)$$

from this we get the adjoint driven NLD equation

$$-i\partial_\mu \bar{\Psi} \gamma^\mu - m\bar{\Psi} + g^2(\bar{\Psi} \Psi)^\kappa \bar{\Psi} = \bar{f} + i\mu \bar{\Psi} \gamma^0. \quad (3.14)$$

To generalize our discussion of external forces from the NLS equation to the NLD equation we have included a dissipation term in our general formulations. However, in most sections that follow we will concentrate on the case where the dissipation coefficient $\mu = 0$, so that the energy is conserved.

When $K_1 = K_2 = K$, $\nu_i = 0$ and $\mu = 0$ we choose $KL = \pi n$ (n is an integer, $2L$ is the total length of the system) and periodic boundary conditions such that $f_j(x, t)$ goes to r_j and the wave function goes to a constant spinor b for $L \rightarrow \infty$. In that case a constant solution of the forced NLD equation with $\Psi = b$ satisfies the nonlinear equation:

$$-mb + g^2(\bar{b}b)^\kappa b = r, \quad (3.15)$$

where r represents a spinor with components r_1 and r_2 .

A. Energy flow equations and the conservation of energy

From the NLD equation with external sources and the definition of the energy-momentum tensor:

$$T^{\mu\nu} = \frac{i}{2} [\bar{\Psi} \gamma^\mu \partial^\nu \Psi - \partial^\nu \bar{\Psi} \gamma^\mu \Psi] - g^{\mu\nu} \mathcal{L}, \quad (3.16)$$

we have that

$$\partial_\mu T^{\mu\nu} = F^\nu, \quad (3.17)$$

where

$$F^\nu = \bar{\Psi}(\partial^\nu f) + (\partial^\nu \bar{f})\Psi. \quad (3.18)$$

The energy density is given by

$$T^{00} = -\frac{i}{2} [\bar{\Psi} \gamma^1 \partial_x \Psi - \partial_x \bar{\Psi} \gamma^1 \Psi] + m\bar{\Psi} \Psi - \mathcal{L}_I - \mathcal{L}_0, \quad (3.19)$$

where now

$$\mathcal{L}_I = \frac{g^2}{\kappa+1} (\bar{\Psi} \Psi)^{\kappa+1} - \bar{f} \Psi - \bar{\Psi} f, \quad (3.20)$$

and \mathcal{L}_0 is chosen so that T^{00} vanishes at $x = \pm L$, when $L \rightarrow \infty$. Therefore, from Eqs. (3.15) and (3.19) we obtain

$$\mathcal{L}_0 = m\bar{b}b - \frac{g^2}{\kappa+1}(\bar{b}b)^{\kappa+1} + \bar{b}r + \bar{r}b = -m\bar{b}b + \frac{g^2(2\kappa+1)}{\kappa+1}(\bar{b}b)^{\kappa+1}, \quad (3.21)$$

Now we will assume that in the lab frame $f(x, t)$ is independent of t and of the form:

$$f_j(x) = r_j e^{-iK_j x}, \quad j = 1, 2, \quad (3.22)$$

with real parameters r_j and K_j . In that case from Eq. (3.18), we have that $F^0 = 0$ and

$$\partial_t T^{00} + \partial_x T^{10} = 0, \quad (3.23)$$

where

$$T^{00} = -\frac{i}{2} [\bar{\Psi} \gamma^1 \partial_x \Psi - \partial_x \bar{\Psi} \gamma^1 \Psi] + m\bar{\Psi} \Psi - \frac{g^2}{\kappa+1} (\bar{\Psi} \Psi)^{\kappa+1} + \bar{\Psi} f + \bar{f} \Psi, \quad (3.24)$$

$$T^{10} = -\frac{i}{2} [\bar{\Psi}_t \gamma^1 \Psi - \bar{\Psi} \gamma^1 \Psi_t]. \quad (3.25)$$

Integrating Eq. (3.23), and under the assumption that $T^{10}(+\infty, t) - T^{10}(-\infty, t) = 0$, then the energy of the driven NLD equation,

$$E^{total} = \int_{-\infty}^{+\infty} dx T^{00}, \quad (3.26)$$

is conserved.

IV. TRANSFORMED NLD EQUATION WITH EXTERNAL FORCE

Let us consider the case of external force (3.5) and (3.7) with $\nu_j = 0$ and $K_1 = K_2 = K$,

$$f(x) = \begin{pmatrix} r_1 \\ r_2 \end{pmatrix} e^{-iKx} \equiv re^{-iKx}. \quad (4.1)$$

After the following transformation

$$\Psi(x, t) = \chi(x, t)e^{-iKx}, \quad (4.2)$$

Eq. (3.8) becomes

$$\mathcal{L} = \left(\frac{i}{2} \right) [\bar{\chi} \gamma^\mu \partial_\mu \chi - \partial_\mu \bar{\chi} \gamma^\mu \chi] - m \bar{\chi} \chi + \frac{g^2}{\kappa + 1} (\bar{\chi} \chi)^{\kappa+1} - \bar{\chi} r - \bar{r} \chi + K \bar{\chi} \gamma^1 \chi + \mathcal{L}_0(a), \quad (4.3)$$

where the constant $\mathcal{L}_0(a)$ now depends on a constant vector $a = \lim_{x \rightarrow \pm\infty} \chi(x, t)$, determined by the algebraic equations:

$$-ma + g^2(\bar{a}a)^\kappa a = r - K\gamma^1 a. \quad (4.4)$$

From the Euler-Lagrange equation:

$$\partial_\mu \frac{\partial \mathcal{L}}{\partial(\partial_\mu \bar{\chi})} - \frac{\partial \mathcal{L}}{\partial \bar{\chi}} = 0, \quad (4.5)$$

we obtain the following perturbed NLD equation

$$(i\gamma^\mu \partial_\mu - m)\chi + g^2(\bar{\chi} \chi)^\kappa \chi = r - K\gamma^1 \chi. \quad (4.6)$$

The corresponding adjoint equation reads

$$-i\partial_\mu \bar{\chi} \gamma^\mu - m \bar{\chi} + g^2(\bar{\chi} \chi)^\kappa \bar{\chi} = \bar{r} - K \bar{\chi} \gamma^1. \quad (4.7)$$

Equation (4.6) is not only invariant under time-translation, but also under space-translation. Therefore, the total energy and the total momentum should be conserved quantities. Indeed, multiplying Eq. (4.6) from the left by $\bar{\chi}_t$ and Eq. (4.7) from the right by χ_t , and then adding both expressions, we again obtain the continuity equation (3.23), now with

$$T_\chi^{00} = -\frac{i}{2} [\bar{\chi} \gamma^1 \partial_x \chi - \partial_x \bar{\chi} \gamma^1 \chi] + m \bar{\chi} \chi - \frac{g^2}{\kappa + 1} (\bar{\chi} \chi)^{\kappa+1} + \bar{\chi} r + \bar{r} \chi - K \bar{\chi} \gamma^1 \chi - \mathcal{L}_0(a), \quad (4.8)$$

where $\mathcal{L}_0(a)$ is chosen as

$$\mathcal{L}_0(a) = m \bar{a} a - \frac{g^2}{\kappa + 1} (\bar{a} a)^{\kappa+1} + \bar{a} r + \bar{r} a - K \bar{a} \gamma^1 a, \quad (4.9)$$

so that T_χ^{00} vanishes at $x = \pm L$, when $L \rightarrow \infty$. Moreover,

$$T_\chi^{10} = -\frac{i}{2} [\bar{\chi}_t \gamma^1 \chi - \bar{\chi} \gamma^1 \chi_t]. \quad (4.10)$$

Integrating Eq. (3.23), and again assuming $T_\chi^{10}(+\infty, t) - T_\chi^{10}(-\infty, t) = 0$, the energy of the driven NLD equation (4.4) given by

$$E_\chi^{total} = \int_{-\infty}^{+\infty} dx T_\chi^{00}, \quad (4.11)$$

is conserved. Inserting the transformation (4.2) into the equation (3.26), it can be verified that

$$E_\Psi^{total} = E_\chi^{total}. \quad (4.12)$$

Now multiplying Eq. (4.6) from the left by $\bar{\chi}_x$ and Eq. (4.7) from the right by χ_x , and then adding both expressions, we obtain the continuity equation for momentum flow

$$\frac{\partial}{\partial t} T_{\chi}^{01} + \frac{\partial}{\partial x} T_{\chi}^{11} = 0, \quad (4.13)$$

with

$$T_{\chi}^{01} = \frac{i}{2} [\bar{\chi}_x \gamma^0 \chi - \bar{\chi} \gamma^0 \chi_x], \quad (4.14)$$

and

$$T_{\chi}^{11} = \frac{i}{2} [\bar{\chi} \gamma^0 \chi_t - \bar{\chi}_t \gamma^0 \chi] - m \bar{\chi} \chi + K \bar{\chi} \gamma^1 \chi + \frac{g^2}{\kappa + 1} (\bar{\chi} \chi)^{\kappa+1} - \bar{\chi} r - \bar{r} \chi + \mathcal{L}_0(a). \quad (4.15)$$

Integrating Eq. (4.13), if $T_{\chi}^{11}(+\infty, t) - T_{\chi}^{11}(-\infty, t) = 0$, then the momentum of the transformed driven NLD equation is given by

$$P_{\chi} = \int_{-\infty}^{+\infty} dx \frac{i}{2} [\bar{\chi}_x \gamma^0 \chi - \bar{\chi} \gamma^0 \chi_x], \quad (4.16)$$

which is also conserved. Now inserting the transformation (4.2) into (4.16)

$$P_{\chi} = \int_{-\infty}^{+\infty} dx \left\{ K \Psi^{\dagger} \Psi + \frac{i}{2} [\bar{\Psi}_x \gamma^0 \Psi - \bar{\Psi} \gamma^0 \Psi_x] \right\}. \quad (4.17)$$

The right hand side of Eq. (4.17) cannot be separated into two integrals due to the fact that $\Psi^{\dagger} \Psi$ does not vanish at $x \rightarrow \pm\infty$. However, in simulations when we deal with a finite domain, we have

$$P_{\chi} = KQ + P_{\Psi}, \quad (4.18)$$

where now

$$P_{\chi} = \int_{-L}^{+L} dx \frac{i}{2} [\bar{\chi}_x \gamma^0 \chi - \bar{\chi} \gamma^0 \chi_x], \quad (4.19)$$

$$Q = \int_{-L}^{+L} dx \Psi^{\dagger} \Psi, \quad (4.20)$$

$$P_{\Psi} = \int_{-L}^{+L} dx \frac{i}{2} [\bar{\Psi}_x \gamma^0 \Psi - \bar{\Psi} \gamma^0 \Psi_x]. \quad (4.21)$$

V. VARIATIONAL (COLLECTIVE COORDINATE) ANSATZ FOR THE NLD EQUATION WITH EXTERNAL DRIVING FORCES

Our ansatz for the trial variational wave function is to assume that because of the smallness of the perturbation the main modification to our exact solutions to the NLD equation (without driving forces) is that the parameters describing the position $q(t)$, width parameter $\beta(t)$ and phase $\phi(t)$ become time dependent functions. We assume that the driving term is specified in the lab frame, and that the initial condition on the solitary wave is that it is a Lorentz boosted exact solution moving with velocity v . To describe the position of the solitary wave we introduce the parameter $q(t)$ which replaces vt for the unforced case. We then let the width parameter β and thus $\omega = \sqrt{m^2 - \beta^2}$ become functions of time. We next rewrite the phase of the exact solution as

$$\omega t' = \gamma \omega (t - vx) \rightarrow \phi(t) - p(t)(x - q(t)) \quad (5.1)$$

to mimic our parametrization of the collective coordinates in the nonlinear Schrödinger equation. Next, we let $p(t) \equiv \omega(t) \gamma(\dot{q}) \dot{q}$ be determined from $\omega(t)$ and $q(t)$ and let the phase $\phi(t)$ be an independent collective variable. That is, in Eq. (2.8) we replace

$$vt \rightarrow q(t); \quad \beta \rightarrow \beta(t); \quad \omega t' = \gamma \omega (t - vx) \rightarrow \phi(t) - p(t)(x - q(t)), \quad (5.2)$$

where $p(t) = \gamma(t)\omega(t)\dot{q}(t)$.

Thus our trial wave function in component form is given by:

$$\begin{aligned}\Psi_1(x, t) &= \left(\cosh \frac{\eta}{2} A(z) + i \sinh \frac{\eta}{2} B(z) \right) e^{-i\phi+ip(x-q)}, \\ \Psi_2(x, t) &= \left(\sinh \frac{\eta}{2} A(z) + i \cosh \frac{\eta}{2} B(z) \right) e^{-i\phi+ip(x-q)},\end{aligned}\quad (5.3)$$

where $z = \cosh \eta (x - q(t))$. Note that ω , which was a parameter in Eq. (2.4), now is time dependent because of $\omega = \sqrt{m^2 - \beta^2(t)}$. Using the trial wave function Eq. (5.3) we can determine the effective Lagrangian for the variational parameters. Writing the Lagrangian density as

$$\mathcal{L} = \mathcal{L}_1 + \mathcal{L}_2 + \mathcal{L}_3, \quad (5.4)$$

where

$$\begin{aligned}\mathcal{L}_1 &= \frac{i}{2} (\bar{\Psi} \gamma^\mu \partial_\mu \Psi - \partial_\mu \bar{\Psi} \gamma^\mu \Psi), \\ \mathcal{L}_2 &= -m \bar{\Psi} \Psi + \frac{g^2}{\kappa + 1} (\bar{\Psi} \Psi)^{\kappa+1}; \quad \mathcal{L}_3 = -\bar{\Psi} f - \bar{f} \Psi.\end{aligned}\quad (5.5)$$

Integrating over x and changing integration variables to z one obtains

$$L_1 = \int_{-\infty}^{\infty} dx \mathcal{L}_1 = Q \left(p\dot{q} + \dot{\phi} - p \tanh \eta \right) - I_0 \cosh \eta - J_0 \tanh \eta, \quad (5.6)$$

where the charge

$$Q = \int dz [A^2(z) + B^2(z)], \quad (5.7)$$

and the rest frame kinetic energy $I_0 = H_1$

$$I_0 = \int dz (B'A - A'B) = H_1, \quad (5.8)$$

are given by Eqs. (A1) and (A2), respectively, in the Appendix. Here $B'(x') = \frac{dB(x')}{dx'}$, and

$$J_0 = \int dz \left(\dot{B}A - \dot{A}B \right), \quad (5.9)$$

and

$$\dot{A} = \frac{dA}{dt} = \frac{dA}{dz} \frac{dz}{dt}, \quad (5.10)$$

with a similar relation holding for \dot{B} . Since $z = (x - q(t)) \cosh \eta$, we have

$$\frac{dz}{dt} = -\dot{q} \cosh \eta - z \tanh \eta \dot{\eta} \quad (5.11)$$

and

$$J_0 = -\cosh \eta \dot{q} I_0 - \dot{\eta} \tanh \eta \int dz z (AB' - BA'). \quad (5.12)$$

The integrand in the second term is odd in z , so the integral vanishes and we are left with;

$$L_1 = \int dx \mathcal{L}_1 = Q \left(p\dot{q} + \dot{\phi} - p \tanh \eta \right) - I_0 (\cosh \eta - \dot{q} \sinh \eta), \quad (5.13)$$

$$L_2 = \int dx \mathcal{L}_2 = -\frac{m}{\cosh \eta} I_1 + \frac{g^2}{(\kappa + 1) \cosh \eta} I_2, \quad (5.14)$$

where

$$I_1 = \int dz (A^2(z) - B^2(z)) = \frac{H_2}{m}; \quad I_2 = \int dz (A^2(z) - B^2(z))^{\kappa+1} = \frac{\kappa+1}{g^2} H_3 = \frac{\kappa+1}{g^2 \kappa} H_1. \quad (5.15)$$

For L_3 we have

$$L_3 = -2 \int dx \operatorname{Re} [f_1^* \Psi_1 - f_2 \Psi_2] = \frac{1}{\gamma} \int dz \mathcal{L}_3. \quad (5.16)$$

We obtain for the integrand

$$\begin{aligned} \mathcal{L}_3 = & -2r_1 \cos(\phi - K_1 q) \left\{ \cosh \frac{\eta}{2} A(z) \cos \frac{p+K_1}{\gamma} z - \sinh \frac{\eta}{2} B(z) \sin \frac{p+K_1}{\gamma} z \right\} \\ & + 2r_2 \cos(\phi - K_2 q) \left\{ \sinh \frac{\eta}{2} A(z) \cos \frac{p+K_2}{\gamma} z - \cosh \frac{\eta}{2} B(z) \sin \frac{p+K_2}{\gamma} z \right\}, \end{aligned} \quad (5.17)$$

where we have not included terms that are odd in z . Performing the integration we get

$$L_3 = -2 \frac{r_1}{\gamma} \cos(\phi - K_1 q) \left(\cosh \frac{\eta}{2} J_1 - \sinh \frac{\eta}{2} N_1 \right) - 2 \frac{r_2}{\gamma} \cos(\phi - K_2 q) \left(\sinh \frac{\eta}{2} J_2 - \cosh \frac{\eta}{2} N_2 \right), \quad (5.18)$$

$$J_j(\omega, \dot{q}) = \int dz A(z) \cos \frac{p+K_j}{\gamma} z = \frac{\pi \cos b_j}{g \sqrt{\omega} \cosh a_j \pi}, \quad a_j = \frac{p+K_j}{2\beta\gamma}, \quad b_j = a_j \cosh^{-1} m/\omega, \quad (5.19)$$

$$N_j(\omega, \dot{q}) = \int dz B(z) \sin \frac{p+K_j}{\gamma} z = \frac{\pi \sin b_j}{g \sqrt{\omega} \cosh a_j \pi}. \quad (5.20)$$

The integrals I_1 , I_2 , J_j and N_j are done exactly in the Appendix. Putting all terms together and using the fact that $\dot{q} = v = \tanh \eta$ we obtain:

$$\begin{aligned} L &= Q \dot{\phi} - I_0 \operatorname{sech} \eta - m I_1 \operatorname{sech} \eta + \frac{g^2}{\kappa+1} I_2 \operatorname{sech} \eta + L_3, \\ L_3 &= -\frac{2\pi}{g\gamma\sqrt{\omega}} \left\{ \frac{r_1 \cos(\phi - K_1 q)}{\cosh a_1 \pi} C_1 - \frac{r_2 \cos(\phi - K_2 q)}{\cosh a_2 \pi} S_2 \right\}, \\ C_j &= \cosh \frac{\eta}{2} \cos b_j - \sinh \frac{\eta}{2} \sin b_j, \quad S_j = \sinh \frac{\eta}{2} \cos b_j - \cosh \frac{\eta}{2} \sin b_j, \quad j = 1, 2. \end{aligned} \quad (5.21)$$

Since we are using the exact solutions of the NLD equation as our trial wave functions for the forced problem, the integrals I_0 , I_1 and I_2 are related since for the NLD equation without the presence of external forces, the solitary wave with $v = 0$ obeys the relationship [23]

$$\omega \psi^\dagger \psi - m \bar{\psi} \psi + \frac{g^2}{\kappa+1} (\bar{\Psi} \Psi)^{\kappa+1} = 0. \quad (5.22)$$

For our problem this converts into

$$\omega (A^2 + B^2) - m (A^2 - B^2) + \frac{g^2}{\kappa+1} (A^2 - B^2)^{\kappa+1} = 0. \quad (5.23)$$

Integrating this relationship we obtain:

$$m I_1 - \frac{g^2}{\kappa+1} I_2 - \omega Q = H_2 - \frac{H_1}{\kappa} - \omega Q = 0. \quad (5.24)$$

Using this relation to replace I_1 and I_2 in L we obtain

$$L = Q \dot{\phi} - \frac{1}{\gamma} (I_0 + \omega Q) - U(q, \dot{q}, \beta, \phi) = Q \dot{\phi} - \frac{M_0}{\gamma} - U(q, \dot{q}, \beta, \phi), \quad (5.25)$$

where $U = -L_3$, and $M_0 = I_0 + \omega Q$ is the rest frame energy of the solitary wave for $\kappa = 1$.

From Eq. (3.12) we can calculate the dissipation function F for the CC equations. We find

$$\begin{aligned} F &= 2\mu \int_{-\infty}^{+\infty} dx \text{Im}(\Psi^\dagger \partial_t \Psi) \\ &= 2\mu \int_{-\infty}^{+\infty} \frac{dz}{\cosh \eta} \left[\sinh \eta (A \dot{B} - B \dot{A}) - \cosh \eta (p \dot{q} + \dot{\phi}) (A^2 + B^2) \right]. \end{aligned} \quad (5.26)$$

We recognize the integrals as being related to $J_0 = -\cosh \eta \dot{q} I_0$ and Q , so we obtain

$$F = -2\mu \left[I_0 \sinh \eta \dot{q} + Q(p \dot{q} + \dot{\phi}) \right]. \quad (5.27)$$

We can simplify this by introducing the boosted rest frame mass:

$$M = \gamma M_0 \equiv \gamma(I_0 + \omega Q) \quad (5.28)$$

and use the definition of $p(t) = \gamma \omega \dot{q}$ so that

$$F = -2\mu(M \dot{q}^2 + Q \dot{\phi}). \quad (5.29)$$

This is the relativistic generalization of our expression that we found for the forced NLS equation [49]. Now we are ready to derive Lagrange's equations for the collective coordinates using Eq. (5.25). From

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{q}} - \frac{\partial L}{\partial q} = \frac{\partial F}{\partial \dot{q}}, \quad (5.30)$$

we obtain

$$\frac{d}{dt} (M \dot{q}) = F_{eff}, \quad (5.31)$$

where

$$F_{eff} = \frac{d}{dt} \frac{\partial U}{\partial \dot{q}} - \frac{\partial U}{\partial q} + \frac{\partial F}{\partial \dot{q}}. \quad (5.32)$$

We also have a contribution from dissipation from the equation

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{\phi}} - \frac{\partial L}{\partial \phi} = \frac{\partial F}{\partial \dot{\phi}}, \quad (5.33)$$

which gives us a first order differential equation for ω

$$\dot{Q} = Q'(\omega) \dot{\omega} = -2\mu Q - \frac{\partial U}{\partial \phi}, \quad (5.34)$$

where the prime denotes the derivative with respect to ω .

As L does not depend on $\dot{\beta}$, the final Lagrange equation is $\partial L / \partial \beta = 0$. After changing to the variable $\omega = \sqrt{m^2 - \beta^2}$ we have

$$\frac{\partial L}{\partial \omega} = 0. \quad (5.35)$$

This leads to a first order differential equation for ϕ

$$Q'(\omega) \dot{\phi} = \frac{1}{\gamma} M'_0(\omega) + \frac{\partial U}{\partial \omega}. \quad (5.36)$$

In what follows we will make the simplification $\mu = 0$ in our comparison of the CC equations with the numerical solution of the forced NLD equation, so that we have energy conservation as a check for our simulations.

A. Simplification at $\kappa = 1, K_1 = K, r_1 = r, r_2 = \mu = 0$

In that case $U = -L_3$ simplifies to be:

$$U(q, \dot{q}, \omega, \phi) = 2r \cos(\phi - Kq) \left[\frac{\cosh \eta/2}{\cosh \eta} J_1(\omega, \dot{q}) - \frac{\sinh \eta/2}{\cosh \eta} N_1(\omega, \dot{q}) \right], \quad (5.37)$$

where

$$J_1(\omega, \dot{q}) = \frac{\pi \cos b}{g\sqrt{\omega} \cosh a\pi}; \quad N_1(\omega, \dot{q}) = \frac{\pi \sin b}{g\sqrt{\omega} \cosh a\pi} \quad (5.38)$$

and

$$\begin{aligned} a(\omega, \dot{q}) &= \frac{p + K}{2\beta\gamma} = \frac{\omega\gamma\dot{q} + K}{2\beta\gamma}, \quad \beta = \sqrt{m^2 - \omega^2}, \\ b(\omega, \dot{q}) &= a \cosh^{-1}(m/\omega), \quad \gamma(\dot{q}) = \cosh \eta(\dot{q}) = (1 - (\dot{q})^2)^{-1/2}. \end{aligned} \quad (5.39)$$

From the expressions (A1) and (A3) in the Appendix we obtain

$$M'_0(\omega) = \omega Q'(\omega). \quad (5.40)$$

Inserting Eqs. (5.40), (A1), and (5.37) in Eqs. (5.36) and (5.34) we obtain, respectively,

$$\dot{\phi} = \frac{\omega}{\gamma} - \frac{g^2 r \beta(\omega) \omega^2 \cos(\phi - Kq)}{m^2} \left[\frac{\cosh \eta/2}{\cosh \eta} \frac{\partial J_1(\dot{q}, \omega)}{\partial \omega} - \frac{\sinh \eta/2}{\cosh \eta} \frac{\partial N_1(\dot{q}, \omega)}{\partial \omega} \right], \quad (5.41)$$

$$\dot{\omega} = -\frac{g^2 r \beta \omega^2 \sin(\phi - Kq)}{m^2} \left[\frac{\cosh \eta/2}{\cosh \eta} J_1(\dot{q}, \omega) - \frac{\sinh \eta/2}{\cosh \eta} N_1(\dot{q}, \omega) \right]. \quad (5.42)$$

In the special case of $\mu = 0$, from Eqs. (5.31) and (5.32) we obtain

$$\frac{d}{dt}(M_0 \gamma(t) \dot{q}) = \frac{d}{dt} \frac{\partial U}{\partial \dot{q}} - \frac{\partial U}{\partial q}. \quad (5.43)$$

B. Solutions when $K = v_0 = q_0 = 0$

When we look in the rest frame where $v = 0$ and look for solutions, we notice when $K = v_0 = 0$ that $a = b = 0$. Thus $N_1 = 0$ and

$$J_1 = \frac{\pi}{g\sqrt{\omega}}; \quad U = 2r \cos(\phi) \frac{\pi}{g\sqrt{\omega}}, \quad \frac{dJ_1}{d\omega}|_{(K=0)} = -\frac{\pi}{2g\omega^{3/2}}. \quad (5.44)$$

Therefore, the equation of motion given by (5.43) is always satisfied. The Eqs. (5.41) and (5.42), respectively, become:

$$\dot{\phi} = \omega + \frac{g\pi r \beta \omega^{1/2} \cos \phi}{2m^2}, \quad (5.45)$$

$$\dot{\omega} = -\frac{\pi g r \beta \omega^{3/2} \sin \phi}{m^2}. \quad (5.46)$$

Note that if $\phi = \bar{\phi} + \phi_0$ and we start with $\phi_0 = n\pi$ (n is an integer) we have

$$\dot{\bar{\phi}} = \omega + \frac{g\pi r \beta \omega^{1/2} (-1)^n \cos \bar{\phi}}{2m^2}, \quad (5.47)$$

$$\dot{\omega} = -\frac{\pi g r \beta \omega^{3/2} (-1)^n \sin \bar{\phi}}{m^2}. \quad (5.48)$$

This has an unstable stationary solution for $n = 1$, namely

$$\dot{\bar{\phi}} = 0, \quad \bar{\phi} = 0, \quad \omega_0 = \frac{g\pi r}{2m^2} \beta_0 \sqrt{\omega_0}. \quad (5.49)$$

For small $g\pi r$

$$\omega_0 = \frac{g^2 \pi^2 r^2}{4m^2}. \quad (5.50)$$

This solution is unstable to small perturbations.

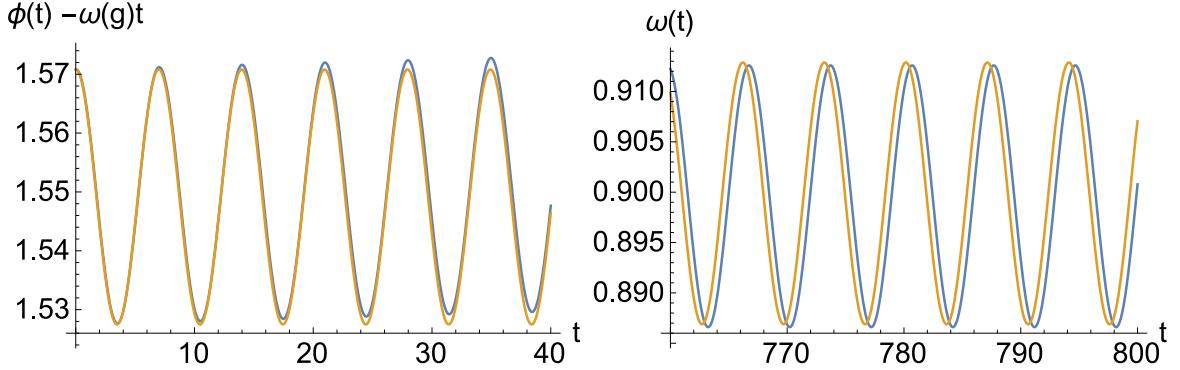


FIG. 1. Left panel: $\phi(t) - \omega(g)t$ vs t , Right panel: $\omega(t)$ vs t . Blue curves are the analytic result. Red curves are the result of solving numerically the CC equations. Parameters are: $\omega_0 = 0.9$, $\dot{q}(0) = 0$, $K = 0$, $r_1 = 0.01$, $r_2 = 0$, $m = 1$ and $g = 1$.

1. Analytic solutions for $\phi_0 = \pi/2$, $K = v = 0$ and $g\pi r/m^2 \ll 1$

If we choose $\phi_0 = \pi/2$, we get the simple equations:

$$\dot{\phi} = \omega - \frac{g\pi r\beta\omega^{1/2} \sin \bar{\phi}}{2m^2}, \quad (5.51)$$

$$\dot{\omega} = -\frac{\pi gr\beta\omega^{3/2} \cos \bar{\phi}}{m^2}. \quad (5.52)$$

One can expand these equations as a power series in $\tilde{g} = g\pi r/m^2$. To order \tilde{g}^2 we obtain:

$$\phi(t) = \frac{\pi}{2} + \left[\omega_0 + \frac{\tilde{g}^2}{2} (m^2 - 2\omega_0^2) \right] t + \frac{3\tilde{g}\beta_0[\cos(\omega_0 t) - 1]}{2\sqrt{\omega_0}} + \tilde{g}^2 \frac{\sin(2\omega_0 t)}{8\omega_0} (7\omega_0^2 - 5m^2) + O(\tilde{g}^3), \quad (5.53)$$

$$\omega(t) = \omega_0 - \tilde{g}\sqrt{\omega_0}\beta_0 \sin(\omega_0 t) + \tilde{g}^2 \sin^2(\omega_0 t) \left(\frac{3}{2}m^2 - 2\omega_0^2 \right) + O(\tilde{g}^3), \quad (5.54)$$

where $\beta_0 = \sqrt{m^2 - \omega_0^2}$. We notice that the term in $\phi(t)$ that is linear in t shows a constant shift from its initial value ω_0 , namely $\omega_0 \rightarrow \omega(g) = \omega_0 + \frac{1}{2}\tilde{g}^2(m^2 - 2\omega_0^2)$. For $g = m = 1$, $r = 0.01$ and $\omega_0 = 0.9$ we find $\omega(g) = 0.899694$. For these initial data we have compared our analytic solutions with the numerical solutions of the CC equations. At all times the $\omega(t)$ found analytically from Eq. (5.54) tracks the numerical solution almost perfectly slightly getting out of phase at late times. The phase ϕ , after we eliminate the linear growth as determined numerically, gradually starts diverging from the analytical result Eq. (5.53) even at modest times. These results are shown in Fig. 1.

C. Variational method for the transformed NLD equation with external force, $K_1 = K_2 = K$

Let us now consider the case of an external force (3.7) with $\nu_j = 0$ and $K_1 = K_2 = K$. From (4.2) and the ansatz (5.3) it follows that

$$\begin{aligned} \chi_1(x, t) &= \left(\cosh \frac{\eta}{2} A(z) + i \sinh \frac{\eta}{2} B(z) \right) e^{-i\tilde{\phi} + i\tilde{p}(x-q)}, \\ \chi_2(x, t) &= \left(\sinh \frac{\eta}{2} A(z) + i \cosh \frac{\eta}{2} B(z) \right) e^{-i\tilde{\phi} + i\tilde{p}(x-q)}, \end{aligned} \quad (5.55)$$

where

$$\begin{aligned} \tilde{p} &= \gamma\omega\dot{q} + K, \\ \tilde{\phi} &= \phi - Kq. \end{aligned} \quad (5.56)$$

Inserting (5.55) into the Lagrangian density (4.3) and integrating over x we obtain

$$\tilde{L} = Q(\dot{\tilde{\phi}} + K\dot{q}) - \frac{M_0}{\gamma} - \tilde{U}(\dot{q}, \beta, \tilde{\phi}), \quad (5.57)$$

where

$$\tilde{U}(\dot{q}, \beta, \tilde{\phi}) = \frac{2\pi \cos \tilde{\phi} (r_1 \tilde{C} - r_2 \tilde{S})}{g\gamma\sqrt{\omega} \cosh \tilde{a}\pi}, \quad (5.58)$$

with $\tilde{a} = \tilde{p}/(2\beta\gamma)$, $\tilde{b} = \tilde{a} \cosh^{-1} m/\omega$, and \tilde{C} and \tilde{S} are defined by Eq. (5.21) with \tilde{b} instead of b . Remarkably, \tilde{L} does not depend on q because the potential \tilde{U} in Eq. (5.58) no longer depends on q .

From the Lagrange equation

$$\frac{d}{dt} \frac{\partial \tilde{L}}{\partial \dot{Y}} - \frac{\partial \tilde{L}}{\partial Y} = 0, \quad (5.59)$$

with $Y = q$, it is clear that the canonical momentum

$$\tilde{P}_q = \frac{\partial \tilde{L}}{\partial \dot{q}} = \gamma M_0 \dot{q} + KQ - \frac{\partial \tilde{U}}{\partial \dot{q}}, \quad (5.60)$$

is conserved. Moreover, we obtain

$$(\dot{\phi} + K\dot{q}) \frac{dQ}{d\omega} - \frac{1}{\gamma} \frac{dM_0}{d\omega} - \frac{\partial \tilde{U}}{\partial \omega} = 0, \quad (5.61)$$

$$\frac{dQ}{dt} + \frac{\partial \tilde{U}}{\partial \tilde{\phi}} = 0, \quad (5.62)$$

from (5.59) with $Y = \omega$, $Y = \tilde{\phi}$, respectively. Multiplying Eq. (5.60) by \ddot{q} , using (5.61)-(5.62), and integrating over t we obtain that the energy

$$\tilde{E}_{cc} = \frac{M_0}{\gamma} + (\tilde{P}_q - KQ)\dot{q} + \tilde{U}, \quad (5.63)$$

is conserved.

Inserting the ansatz (5.55) into the expression for the field momentum (4.16) we obtain

$$\tilde{P}_\chi = \tilde{p}Q + \dot{q}\gamma H_1. \quad (5.64)$$

This means that in the solutions of collective coordinates equations, \tilde{P}_q must be a conserved quantity. In simulations of the transformed NLD equation (4.4), the momentum (4.16) must be conserved and equal to $\tilde{P}_\chi(0)$.

A similar remark holds for the energy. Indeed, inserting the ansatz (5.55) into (4.11) and integrating over x we obtain

$$\tilde{E}_\chi = \gamma H_2 + \tilde{U}(\dot{q}, \beta, \tilde{\phi}). \quad (5.65)$$

This energy is equal to the energy of the driven NLD equation E_Ψ obtained by inserting the ansatz (5.3) into (3.26). The energy \tilde{E}_{cc} (5.63) obtained from the solutions of the collective coordinates equations must be constant, while the energies E_Ψ^{total} and E_χ^{total} , computed from the simulations of the driven NLD equation and transformed NLD equation, respectively, not only must be equal to each other, but also they must be constant if the energy density satisfies certain condition at the boundaries.

As \tilde{U} in Eq. (5.58) does not depend on $q(t)$; using $v(t) = \dot{q}$ as a new collective coordinate we obtain one algebraic equation (5.60) and the following two differential equations of first order:

$$\dot{\omega} = -\frac{\pi g \beta \omega^{3/2}}{\gamma m^2} \frac{\sin \tilde{\phi}}{\cosh \tilde{a}\pi} (r_1 C - r_2 S) + \frac{2}{m^2} \mu \omega \beta^2, \quad (5.66)$$

$$\dot{\tilde{\phi}} = -K\dot{q} + \frac{\omega}{\gamma} - \frac{g^2 \omega^2 \beta}{2m^2} \frac{\partial U}{\partial \omega}, \quad (5.67)$$

where in γ we should also replace $\dot{q} = v(t)$ and

$$\frac{\partial U}{\partial \omega} = -\frac{U}{2\omega} - \pi U \tilde{a}_\omega \tanh \tilde{a}\pi + \frac{2\pi \cos \tilde{\phi} (r_1 C_\omega - r_2 S_\omega)}{g\gamma \sqrt{\omega} \cosh \tilde{a}\pi}, \quad (5.68)$$

$$\tilde{a}_\omega = \frac{K\omega + \gamma m^2 \dot{q}}{2\gamma \beta^3}, \quad \tilde{b}_\omega = \tilde{a}_\omega \cosh^{-1} \frac{m}{\omega} - \frac{\tilde{a}m}{\omega \beta}, \quad (5.69)$$

$$C_\omega = -\tilde{b}_\omega \left[\sinh \frac{\eta}{2} \cos \tilde{b} + \cosh \frac{\eta}{2} \sin \tilde{b} \right], \quad (5.70)$$

$$S_\omega = -\tilde{b}_\omega \left[\cosh \frac{\eta}{2} \cos \tilde{b} + \sinh \frac{\eta}{2} \sin \tilde{b} \right], \quad (5.71)$$

$$\frac{\partial U}{\partial \dot{q}} = \frac{2\pi \cos \tilde{\phi}}{g\gamma \sqrt{\omega} \cosh \tilde{a}\pi} \left(-(\dot{q}\gamma^2 + \pi \tilde{a}_\dot{q} \tanh \pi \tilde{a})(r_1 C - r_2 S) + r_1 C_\dot{q} - r_2 S_\dot{q} \right), \quad (5.72)$$

$$\tilde{a}_\dot{q} = \frac{\omega - K\dot{q}\gamma}{2\beta}, \quad (5.73)$$

$$C_\dot{q} = \frac{\gamma^2 S}{2} - \tilde{a}_\dot{q} \cosh^{-1} \frac{m}{\omega} \left[\sinh \frac{\eta}{2} \cos \tilde{b} + \cosh \frac{\eta}{2} \sin \tilde{b} \right], \quad (5.74)$$

$$S_\dot{q} = \frac{\gamma^2 C}{2} - \tilde{a}_\dot{q} \cosh^{-1} \frac{m}{\omega} \left[\cosh \frac{\eta}{2} \cos \tilde{b} + \sinh \frac{\eta}{2} \sin \tilde{b} \right]. \quad (5.75)$$

The Eqs. (5.66)-(5.67) can be obtained using the Lagrange equation (5.59) and setting $Y = \tilde{\phi}, \omega$, respectively. Now we need to solve two first order differential equations (5.66) and (5.67) and one algebraic equation (5.60), where the three unknowns are $\omega(t)$, $v(t)$ and $\tilde{\phi}(t)$. Then, using the substitution (5.56) one can obtain $\phi(t)$.

In the above equations the subscripts on the variables $\tilde{a}, \tilde{b}, C, S$ refer to (partial) derivatives with respect to the subscript variable.

D. Non-relativistic (NR) regime with $K_1 = K$, $r_1 = r$, $r_2 = 0$.

In the non-relativistic regime, $v = \dot{q} \ll 1$. Therefore,

$$\sinh \delta_1 \eta \rightarrow \delta_1 \dot{q}; \quad \cosh \delta_1 \eta \rightarrow 1; \quad p \rightarrow \omega \dot{q}; \quad \gamma \rightarrow 1, \quad (5.76)$$

where in our case $\delta_1 = 1/2$ or $\delta_1 = 1$. Thus in determining U ,

$$\tilde{a}(\dot{q}, \omega) = \frac{\omega \dot{q} + K}{2\beta}; \quad \tilde{b}(\dot{q}, \omega) = \tilde{a} \cosh^{-1}(m/\omega). \quad (5.77)$$

For determining the NR equations for ϕ and ω we need an expression for \tilde{U} valid up to terms linear in \dot{q} . We find

$$\tilde{U} = 2r \cos \tilde{\phi} \left[J_1(\dot{q}, \omega) - \frac{\dot{q}}{2} N_1(\dot{q}, \omega) \right]. \quad (5.78)$$

Thus the equations of motion (5.66) and (5.67) become, respectively,

$$\dot{\omega} = -\frac{g^2 r \beta \omega^2 \sin \tilde{\phi}}{m^2} \left[J_1(\dot{q}, \omega) - \frac{\dot{q}}{2} N_1(\dot{q}, \omega) \right], \quad (5.79)$$

$$\dot{\tilde{\phi}} = -K\dot{q} + \omega - \frac{g^2 r \beta \omega^2 \cos \tilde{\phi}}{m^2} \left[\frac{\partial J_1(\dot{q}, \omega)}{\partial \omega} - \frac{\dot{q}}{2} \frac{\partial N_1(\dot{q}, \omega)}{\partial \omega} \right], \quad (5.80)$$

and the canonical momentum (5.60) becomes:

$$\tilde{P}_q = \frac{2K\beta}{g^2 \omega} + \frac{4m}{g^2} \tanh^{-1} \sqrt{\frac{m-\omega}{m+\omega}} \dot{q} - \frac{\partial \tilde{U}}{\partial \dot{q}}. \quad (5.81)$$

To determine the conserved \tilde{P}_q up to terms linear in v , we need an expression for \tilde{U} up to terms of order v^2 . We find

$$\tilde{U} = -\frac{\pi r \cos(\tilde{\phi}) \operatorname{sech} \left(\frac{\pi K}{2\sqrt{m^2 - \omega^2}} \right)}{4g\sqrt{\omega} (m^2 - \omega^2)^{3/2}} (a_0 + a_1 v + a_2 v^2 + \dots), \quad (5.82)$$

where we have

$$a_0 = -8(m^2 - \omega^2)^{3/2} \cos\left(\frac{K \cosh^{-1}\left(\frac{m}{\omega}\right)}{2\sqrt{m^2 - \omega^2}}\right) \quad (5.83)$$

and

$$\begin{aligned} a_1 = & 4(m^2 - \omega^2)^{3/2} \sin\left(\frac{K \cosh^{-1}\left(\frac{m}{\omega}\right)}{2\sqrt{m^2 - \omega^2}}\right) + 4\omega(m^2 - \omega^2) \cosh^{-1}\left(\frac{m}{\omega}\right) \sin\left(\frac{K \cosh^{-1}\left(\frac{m}{\omega}\right)}{2\sqrt{m^2 - \omega^2}}\right) \\ & + 4\pi\omega(m^2 - \omega^2) \tanh\left(\frac{\pi K}{2\sqrt{m^2 - \omega^2}}\right) \cos\left(\frac{K \cosh^{-1}\left(\frac{m}{\omega}\right)}{2\sqrt{m^2 - \omega^2}}\right). \end{aligned} \quad (5.84)$$

Note that when $K = 0$, $a_1 \rightarrow 0$. We will display a_2 for $K = 0$ below.

1. Nonrelativistic solutions with $K = 0$

When $K = 0$, it is easy to expand \tilde{U} up to order v^2 , and obtain the two equations of motion and one constraint equation up to order v . One has:

$$\begin{aligned} \tilde{U}_{nr} = & \frac{2\pi r \cos(\phi)}{g\sqrt{\omega}} \\ & \times \left(1 - \frac{v^2 \left(\sqrt{m^2 - \omega^2} (3m^2 + (\pi^2 - 3)\omega^2) + \omega^2 \sqrt{m^2 - \omega^2} \cosh^{-1}\left(\frac{m}{\omega}\right)^2 + 2\omega(m^2 - \omega^2) \cosh^{-1}\left(\frac{m}{\omega}\right) \right)}{8(m^2 - \omega^2)^{3/2}} \right). \end{aligned} \quad (5.85)$$

We have

$$\begin{aligned} -\frac{\partial \tilde{U}_{nr}}{\partial v} = & \frac{2\pi r \cos(\phi)}{g\sqrt{\omega}} \\ & \times \frac{v \left(\sqrt{m^2 - \omega^2} (3m^2 + (\pi^2 - 3)\omega^2) + \omega^2 \sqrt{m^2 - \omega^2} \cosh^{-1}\left(\frac{m}{\omega}\right)^2 + 2\omega(m^2 - \omega^2) \cosh^{-1}\left(\frac{m}{\omega}\right) \right)}{4(m^2 - \omega^2)^{3/2}}. \end{aligned} \quad (5.86)$$

The non-relativistic conservation law for \tilde{P}_q when $K = 0$, valid to linear order in v is then

$$\tilde{P}_q = M_0(\omega)v - \frac{\partial \tilde{U}_{nr}}{\partial v}. \quad (5.87)$$

This allows us to explicitly solve for v as a function of $\omega(t)$, $\phi(t)$ and the initial values of v, ϕ and ω . Note that because the velocity corrections to \tilde{U} start at v^2 , the leading terms to solve for ϕ and ω are the *same* equations that we needed to solve in the $v = 0$ case, namely:

$$\dot{\omega} = -\frac{\pi gr\beta\omega^{3/2} \sin\phi}{m^2}, \quad (5.88)$$

$$\dot{\phi} = \omega + \frac{g\pi r\beta\omega^{1/2} \cos\phi}{2m^2}, \quad (5.89)$$

which we have already solved explicitly as a power series in \tilde{g} . These solutions are given in Eqs. (5.53), (5.54). We have that

$$\begin{aligned} \frac{v}{v_0} = & \tilde{P}_q(v_0, \omega_0, \phi_0) \\ & \times \left[M_0(\omega) + \frac{2\pi r \cos(\phi)}{g\sqrt{\omega}} \frac{\left(\beta(\omega) (3m^2 + (\pi^2 - 3)\omega^2) + \omega^2 \beta(\omega) \cosh^{-1}\left(\frac{m}{\omega}\right)^2 + 2\omega \beta^2(\omega) \cosh^{-1}\left(\frac{m}{\omega}\right) \right)}{4\beta^3(\omega)} \right]^{-1}. \end{aligned} \quad (5.90)$$

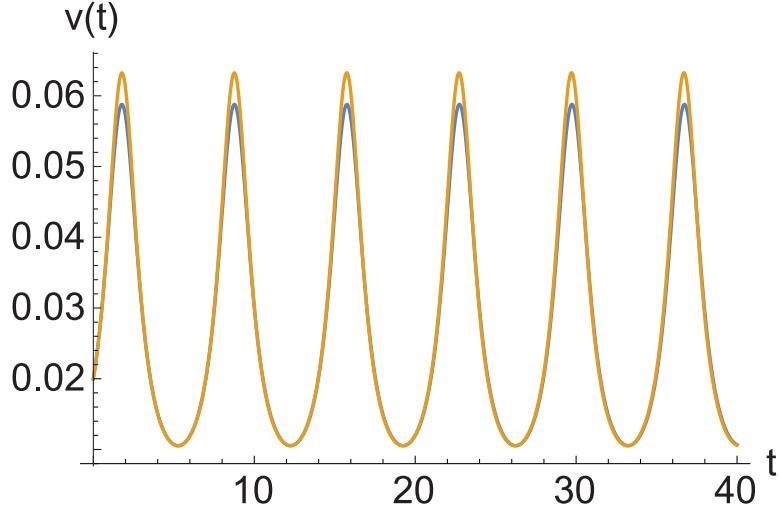


FIG. 2. v as a function of time t for an initial non-relativistic velocity $v_0 = 1/50$. Parameters are: $\omega_0 = 0.9$, $K = 0$, $r_1 = r = 0.01$, $r_2 = 0$, $m = 1$, $g = 1$. The upper curve is the analytic solution.

For the case $\phi_0 = \frac{\pi}{2}$, one has $\tilde{P}_q(v_0, \omega_0, \phi_0) = M_0(\omega_0)$. For the initial conditions we considered earlier when $v_0 = 0$, namely $K = 0$, $r = 1/100$, $m = 1$, $g = 1$, and initial velocity $v_0 = 1/50$ we get the result shown in Fig. 2. In that figure we compare the analytic result with the solution of the CC equations. The analytic result is slightly higher at the maxima of $v(t)$.

VI. SPECTRUM OF THE LINEAR EXCITATIONS (PHONONS)

Similar to the case of the forced NLS equation [50], the external force $f_j = r_j e^{-iK_j x}$ [see Eq. (3.22)] excites not only soliton oscillations, but also a plane wave phonon (short for a linear excitation) such that the total momentum is conserved.

The general solution of the linearized NLD equation without damping [Eq. (3.6) with $\mu = 0$] and $K_1 = K_2 = K$, reads

$$\Psi_{ph} = b e^{i(kx - \omega_{ph} t + \theta)} + c e^{-iKx}, \quad (6.1)$$

with the phonon dispersion curve

$$\omega_{ph}(k) = \sqrt{m^2 + k^2}, \quad (6.2)$$

and arbitrary, but small b . In the case $r_1 = r$ and $r_2 = 0$, which was considered in Sec. V, the spinor c has the simple form

$$c = \frac{r}{\Omega_K^2} \begin{pmatrix} -m \\ K \end{pmatrix}, \quad \Omega_K = \sqrt{m^2 + K^2}. \quad (6.3)$$

We choose $|K| \ll m$, then the second component of c is much smaller than the first one [see below Eq. (3.7)].

In the presence of a soliton we need to know the phonons only far away from the soliton. For example, when both the soliton and the phonon move to the right, at the far left the phonon wave function is given by Eq. (6.1) with $\theta = 0$, while at the far right there is a phase shift $\theta \neq 0$.

We now calculate the charge Q_{ph} and the momentum P_{ph} of the phonon by integrating $\Psi^\dagger \Psi$ and T^{01} over the interval $-L \leq x \leq L$. Here we must distinguish two cases: $k \neq -K$ and $k = -K$. In the latter case the x -dependent parts in the integrands of P_{ph} and Q_{ph} drop out. We then obtain

$$Q_{ph} = 2L(b^\dagger b + c^\dagger c) + 2L \operatorname{Re}\{c^\dagger b e^{-i(\omega_K t - \theta)} - b^\dagger c e^{i\omega_K t}\}. \quad (6.4)$$

We also find $P_{ph} = -KQ_{ph}$ so that

$$P_{ph} + KQ_{ph} = 0. \quad (6.5)$$

The left hand side of Eq. (6.5) is the total momentum in the transformed system discussed in Sec. IV. It is zero because the wave function describing the phonon,

$$\chi_{ph} = \Psi_{ph} e^{iKx} = b e^{-i(\omega_K t - \theta)} + c, \quad (6.6)$$

is simply a homogeneous oscillation and does not travel in the transformed system.

In our simulations which will be presented in the next section, we use a finite system of length $2L$ and periodic boundary conditions. The predicted phonon mode with wavenumber $k = -K$ is clearly identified in the spectrum of $Q(t)$, see panel (e) of Figs. 5, 7 and 9. The observed frequencies ω_2 agree very well with Ω_K given by Eq. (6.3) for $K = 0$ and $K = \pm \frac{3\pi}{L}$ with $L = 100$.

The phonon mode is also seen indirectly in the spectrum of the maximum of the charge density $\rho(x, t)$ shown in panel (f) of Figs. 5, 7 and 9. This is a *local* quantity which is used for the computation of the soliton position $q(t)$, in contrast to the *global* quantity $Q(t)$ which is obtained by integration over the whole system. The phonon frequency ω_2 is observed in the difference $\omega_3 = \omega_2 - \omega_1$, where ω_1 is identified as the frequency of the intrinsic soliton oscillations discussed in the next section.

VII. SIMULATIONS VS NUMERICAL SOLUTIONS OF COLLECTIVE COORDINATES EQUATIONS

In order to obtain the numerical solutions of the collective coordinates equations we need to set initial conditions for $\dot{q}(0)$, $\omega(0)$ and $\tilde{\phi}(0)$. In simulations we use the soliton solution of the unperturbed NLD equation with the same initial conditions. We would like to stress here that arbitrary sets of these initial conditions produce different quantities for P_q and \tilde{P}_χ (see Fig. 3). Numerical solutions of collective coordinates must conserve P_q and E_{cc} , whereas in simulations \tilde{P}_χ and \tilde{E}_χ are conserved. Therefore, good agreement between simulations and numerical solutions is expected only for the initial conditions that guarantee $P_q = \tilde{P}_\chi$ and $E_{cc} = \tilde{E}_\chi$. The simplest case is to choose initially $\tilde{\phi}(0) = \pm\pi/2$, $q(0) = 0$ and arbitrary values for $\dot{q}(0)$ and $\omega(0)$ (see Fig. 4).

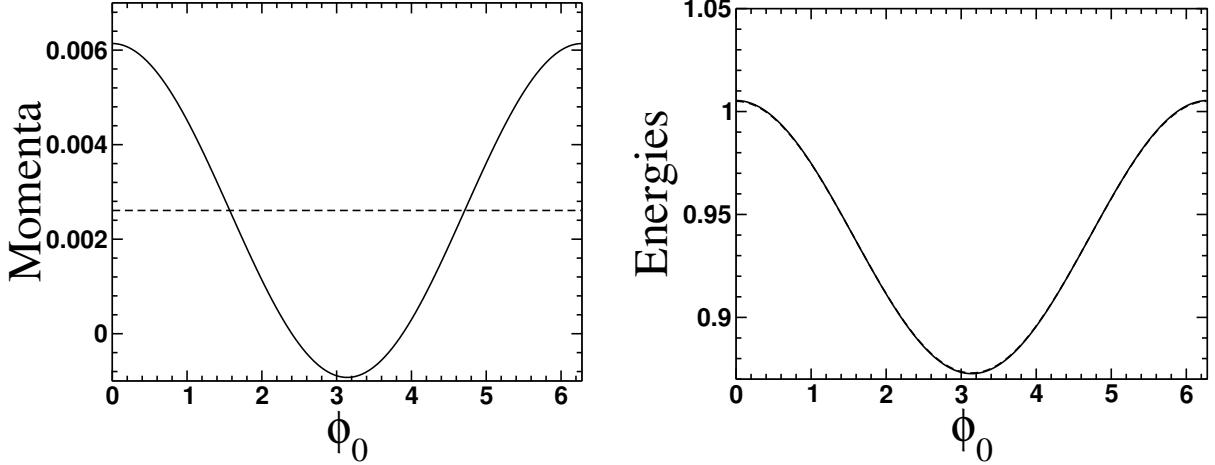


FIG. 3. Left panel: P_q (solid line) and \tilde{P}_χ (dashed line) vs initial phase. Right panel: E_{cc} (solid line) and \tilde{E}_χ (dashed line superimposed) vs initial phase. The maximum difference between E_{cc} and \tilde{E}_χ is of order of 10^{-4} . Parameters are: $\omega_0 = 0.9$, $\dot{q}(0) = 0.1$, $K = -3\pi/100$, $r_1 = r = 0.01$, $r_2 = 0$, $m = 1$, $g = 1$.

The CC theory leads to the algebraic equation (5.60) and the two ODEs (5.66), and (5.67) which are solved by a MATHEMATICA program. The driven NLD Eq. (3.6) is a PDE for which various numerical schemes have been proposed that are reviewed in Ref. [33]. It is also reported there that the operator splitting (OS) method performs better than the other schemes in terms of accuracy and efficiency. Therefore we have applied a fourth-order OS method in a recent paper on the stability of solitons in the undriven NLD equation [41] and the readers are referred to Refs. [33] and [41] for a detailed description of the method. For the driven NLD equation we again employ the same scheme used in Ref. [41], but instead of nonreflecting boundary conditions, we take periodic boundary conditions. This has the advantage that tests of the conservation laws for momentum and energy (see Secs. IV and III) yield an accuracy of the order of 10^{-10} and 10^{-14} , respectively. Here we adopt the computational domain $[-100, 100]$, (i.e. $L = 100$), the time step $\Delta t = 0.025$, and the final time $t_{fin} = 800$.

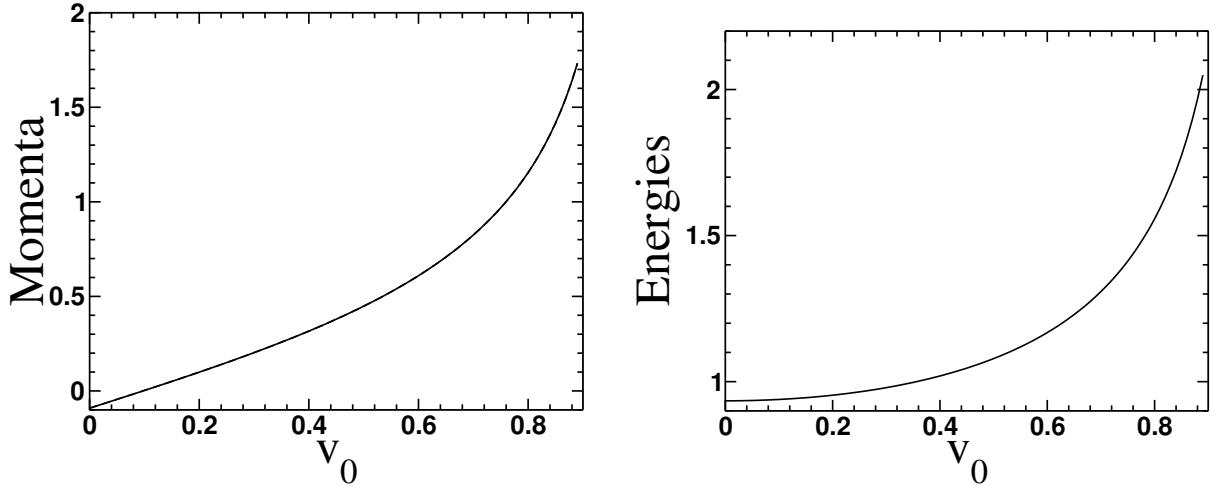


FIG. 4. Left panel: $P_q = \tilde{P}_\chi$ vs initial velocity. Right panel: $E_{cc} = \tilde{E}_\chi$ vs initial velocity. Parameters are: $\omega_0 = 0.9$, $\phi(0) = \pi/2$, $K = -3\pi/100$, $r_1 = r = 0.01$, $r_2 = 0$, $m = 1$, $g = 1$.

In the previous section we have identified plane wave phonons in the spectra of the soliton charge and amplitude (maximum of the charge density). Now we discuss the peaks due to the intrinsic oscillations of the soliton shape and velocity and compare with our CC results. The highest peak $\omega_1 = \Omega_{sim}$ in the spectra of $Q(t)$ is always close to the initial value $\omega_0 = 0.9$ and always agrees nearly perfectly with the predicted frequency Ω_{cc} of the CC theory, see Figs. 5 and 7-10 and Table I. The dependency on the parameter K is weak which means that the periodicity of the force $f_1 = r \exp(-iKx)$ has little influence on the intrinsic oscillations; this includes the case $K = 0$ where the force is homogeneous. Exactly the same frequencies are observed in the spectra of the soliton amplitude [in the simulations this is the maximum of the charge density, and in the CC theory this is $a = 2 \frac{(m-\omega(t))}{g^2}$]. Table II contains the parameters of harmonic and biharmonic functions which have been fitted to the data for the soliton charge and amplitude for three cases of the parameter K . Comparing CC theory with simulations, we see that the results for the mean values and the amplitudes of the first harmonics agree qualitatively. Finally we discuss the results for the translational motion of the solitons. There are very small oscillations of the soliton position $q(t)$ around a mean trajectory $\bar{v} t$, see Figs. 8 and 10. We compute the discrete Fourier transform (DFT) of $q(t) - \bar{v}t$ for the CC theory and simulations and observe the same frequencies as above for the soliton charge and amplitude.

Table I shows that \bar{v} is always close to the initial value $v_0 = 0.1$ which means that the translational motion is only weakly affected by the intrinsic soliton oscillations. The agreement between \bar{v}_{cc} and \bar{v}_{sim} is not so good (the maximal error in Table I is about 14%). The reason is that the plane wave phonons with $k = -K$ are not taken into account in the CC theory. The monotonic behavior of \bar{v}_{sim} as a function of K is explained qualitatively in the following way: For positive K the phonon phase velocity is negative, which results in head-on collisions with the soliton. Here $\bar{v}_{sim} < v_0$, which can be explained by assuming negative spatial shifts of the soliton due to the collisions. For negative K the plane wave phonon overtakes the soliton which results in positive shifts explaining that $\bar{v}_{sim} > v_0$.

VIII. SUMMARY

We investigated how a solitary wave solution of the nonlinear Dirac (NLD) equation evolves in time under an external force with the components $f_j = r_j \exp[-i(\nu_j t - K_j x)]$, $j = 1, 2$. As an ansatz for a collective coordinate (CC) theory we took the exact Lorentz boosted solitary wave solution of the unperturbed NLD equation. The collective variables are the soliton position $q(t)$, inverse width $\beta(t)$ and phase $\phi(t)$. The variable β is related to the frequency $\omega(t) = \sqrt{m^2 - \beta^2}$ that appears in the solitary wave solution and lies in the range $0 < \omega < m$. In the non-relativistic regime ω is close to the mass m . The forced NLD equation is obtained in a standard way from a Lagrangian density. We restricted ourselves to the case with $\nu_j = 0$, inserted our ansatz, integrated over space, and obtained the Lagrangian as a function of the collective coordinates. The Lagrange equations are three coupled ODEs. In two special cases we obtained approximate analytical solutions, but in general the ODEs were solved numerically by a MATHEMATICA program. We chose parameters and initial conditions from the non-relativistic regime where solitary wave solutions are expected to be stable. The solutions are periodic in time, which means that the solitary waves exhibit intrinsic oscillations with frequency Ω_{cc} . The translational motion is also affected, though weakly, because the position $q(t)$

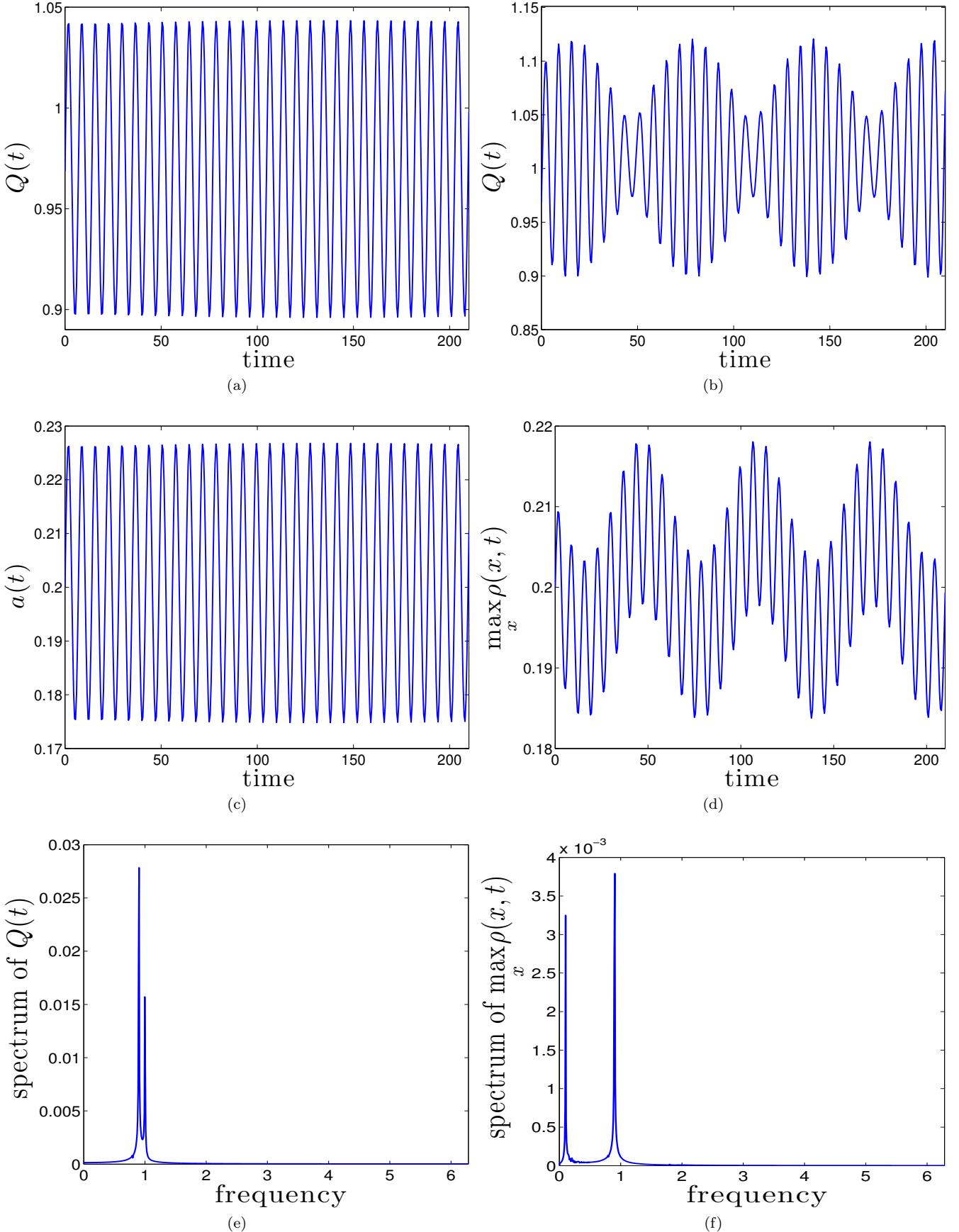


FIG. 5. Intrinsic soliton oscillations for the case of constant, homogeneous force ($K = 0$) and zero initial velocity ($v_0 = 0$). Other parameters and initial condition (IC): $g = 1$, $m = 1$, $r = 0.01$, $\omega_0 = 0.9$, $\phi_0 = \pi/2$, integration time $t_f = 800$. Panels (a) and (b): charge from CC theory and simulation, respectively. Panels (c) and (d): amplitude $a = 2[m - \omega(t)]/g^2$ and $\max_x \rho(x, t)$, respectively. Panel (e): discrete Fourier transform (DFT) of $Q(t)$, soliton peak at $\omega_1 = 0.9032$ and phonon peak at $\omega_2 = 0.997 \approx \sqrt{1 + k^2}$ with $k = -K = 0$. Panel (f): DFT of $\max_x \rho(x, t)$, peaks at $\omega_1 = 0.9032$, $\omega_3 = \omega_2 - \omega_1 = 0.0942$.

$K(\pi/100)$	Ω_{cc}	Ω_{sim}	\bar{v}_{cc}	\bar{v}_{sim}
-6	0.911062	0.91106	0.0855975	0.10012
-5	0.911062	0.91106	0.0865441	0.10008
-4	0.911062	0.91106	0.0914469	0.10005
-3	0.903208	0.90321	0.101902	0.10005
-2	0.903208	0.90321	0.111025	0.10004
-1	0.895354	0.89535	0.114524	0.10001
0	0.8875	0.89535	0.114569	0.099968
1	0.8875	0.89535	0.112703	0.099932
2	0.879646	0.8875	0.109807	0.09987
3	0.879646	0.8875	0.10646	0.099805
4	0.879646	0.87965	0.103058	0.099745
5	0.871792	0.87965	0.0999051	0.099677
6	0.871792	0.87965	0.0972293	0.099607

TABLE I. Frequency of intrinsic soliton oscillations and average soliton velocity as a function of the parameter K . We compare the results of the CC method and numerical simulation at various values of K in multiples of $\pi/100$. Here we choose the initial conditions $v_0 = 0.1, \omega_0 = 0.9, \phi_0 = \pi/2, r_1 = r = 0.01, r_2 = K_2 = 0, t_{fin} = 800$, and t_{fin} denotes the integration time.

Parameters	Theory		Simulations	
$K = 0, v_0 = 0$	$Q(t) \approx 0.97 - 0.072 \cos(\omega_1 t + 1.15)$	$a(t) \approx 0.2 - 0.025 \cos(\omega_1 t + 1.15)$	$Q(t) \approx 1.0097 - 0.049 \cos(\omega_1 t + 0.058) - 0.034 \cos(\omega_2 t + 0.88)$	$\max_x \rho \approx 0.2 - 0.0067 \cos(\omega_1 t + 0.036) + 0.0065 \cos(\omega_3 t + 0.98)$
$K = -3\pi/100, v_0 = 0.1$	$Q(t) \approx 0.97 - 0.073 \cos(\omega_1 t + 1.67)$	$a(t) \approx 0.2 - 0.026 \cos(\omega_1 t + 1.67)$	$Q(t) \approx 1.0092 - 0.071 \cos(\omega_1 t + 2.0239) - 0.038 \cos(\omega_2 t - 6.74)$	$\max_x \rho \approx 0.2 - 0.0096 \cos(\omega_1 t + 2.02) + 0.0061 \cos(\omega_3 t + 0.797)$
$K = 3\pi/100, v_0 = 0.1$	$Q(t) \approx 0.97 - 0.0594 \cos(\omega_1 t + 1.31)$	$a(t) \approx 0.2 - 0.021 \cos(\omega_1 t + 1.31)$	$Q(t) \approx 1.0093 - 0.054 \cos(\omega_1 t + 0.72) - 0.029 \cos(\omega_2 t - 0.2)$	$\max_x \rho \approx 0.2 - 0.0089 \cos(\omega_1 t + 0.72) - 0.00797 \cos(\omega_3 t - 0.26)$

TABLE II. Least-squares fits to $Q(t)$, amplitude $a = 2[m - \omega(t)]/g^2$, and $\max_x \rho$ from theory and simulation. Other parameters as in Figs. 5-10. Note that ω_1, ω_2 and ω_3 are given in the captions of Figs. 5, 7-10.

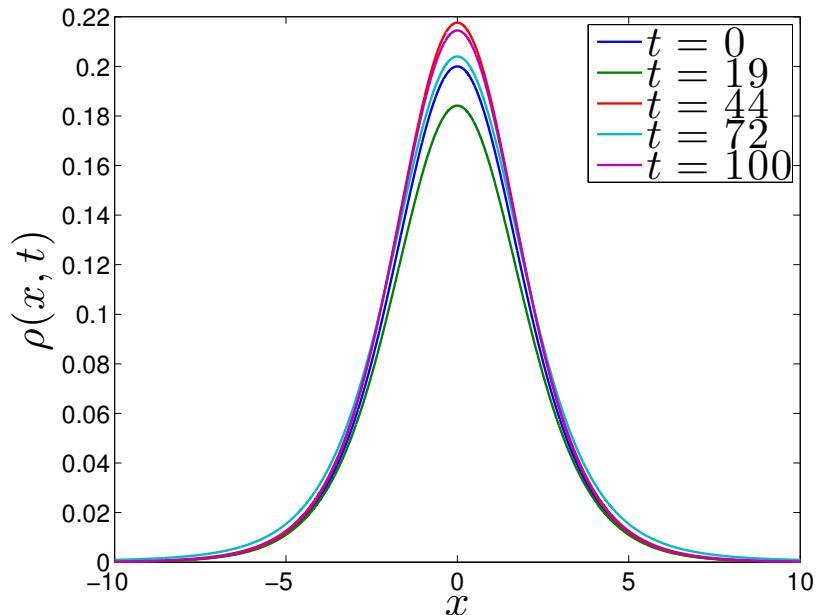


FIG. 6. Snapshots of the soliton profile at different times. Same parameters and initial conditions as in Fig. 5.

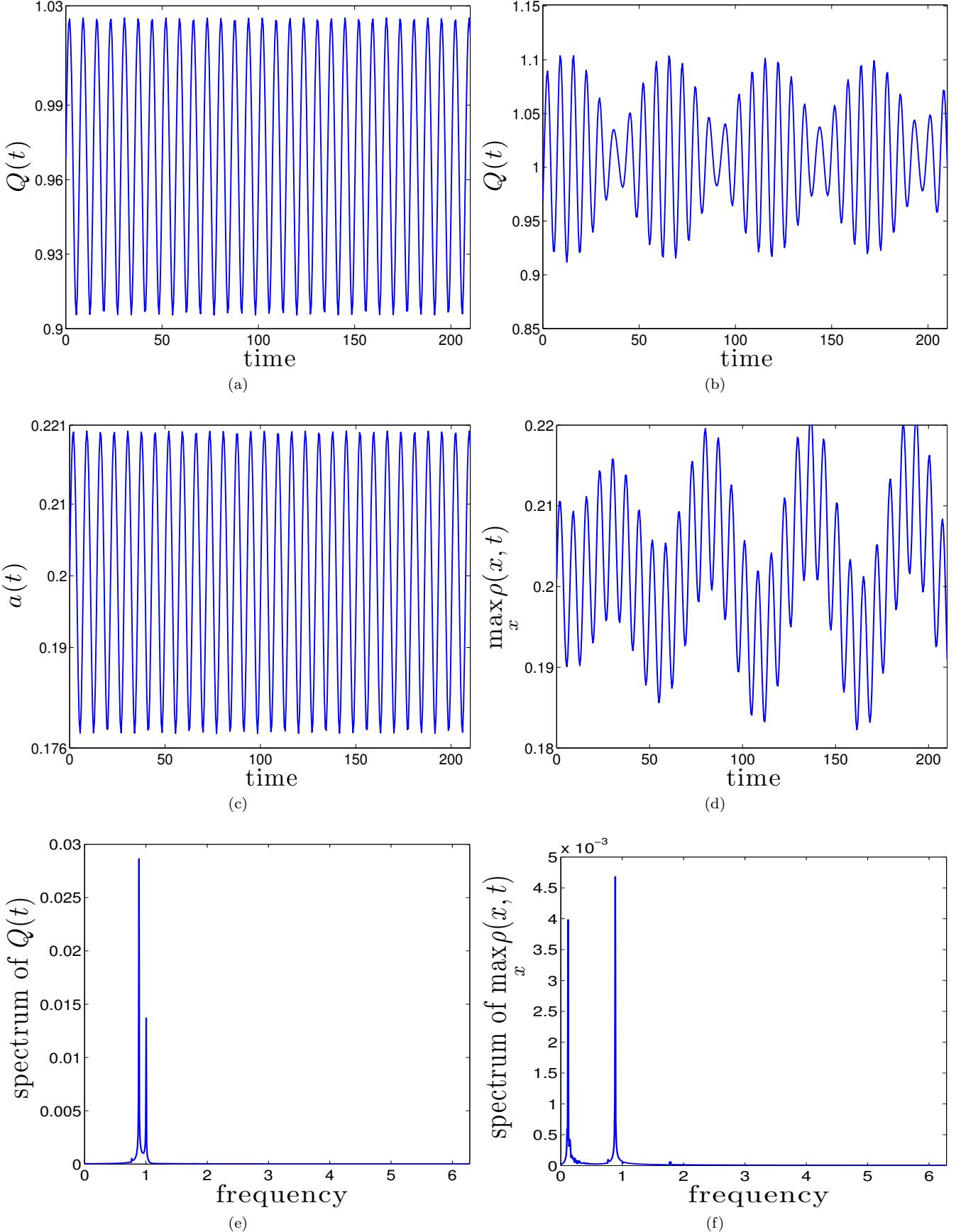


FIG. 7. Intrinsic soliton oscillations for the case of a harmonic inhomogeneous force ($K = 3\pi/100 \approx 0.094248$) and $v_0 = 0.1$. Other parameters and initial conditions as in Fig. 5. Panels (a) and (b): charge from CC theory and simulation, respectively. Panels (c) and (d): amplitude $a = 2[m - \omega(t)]/g^2$ and $\max_x \rho(x, t)$, respectively. Panel (e): DFT of $Q(t)$, soliton peak at $\omega_1 = 0.8875$ and phonon peak at $\omega_2 = 1.0053 \approx \sqrt{1 + k^2}$ with $k = -K$. Panel (f): DFT of $\max_x \rho(x, t)$, peaks at $\omega_1 = 0.8875$, $\omega_3 = \omega_2 - \omega_1 = 0.11781$.

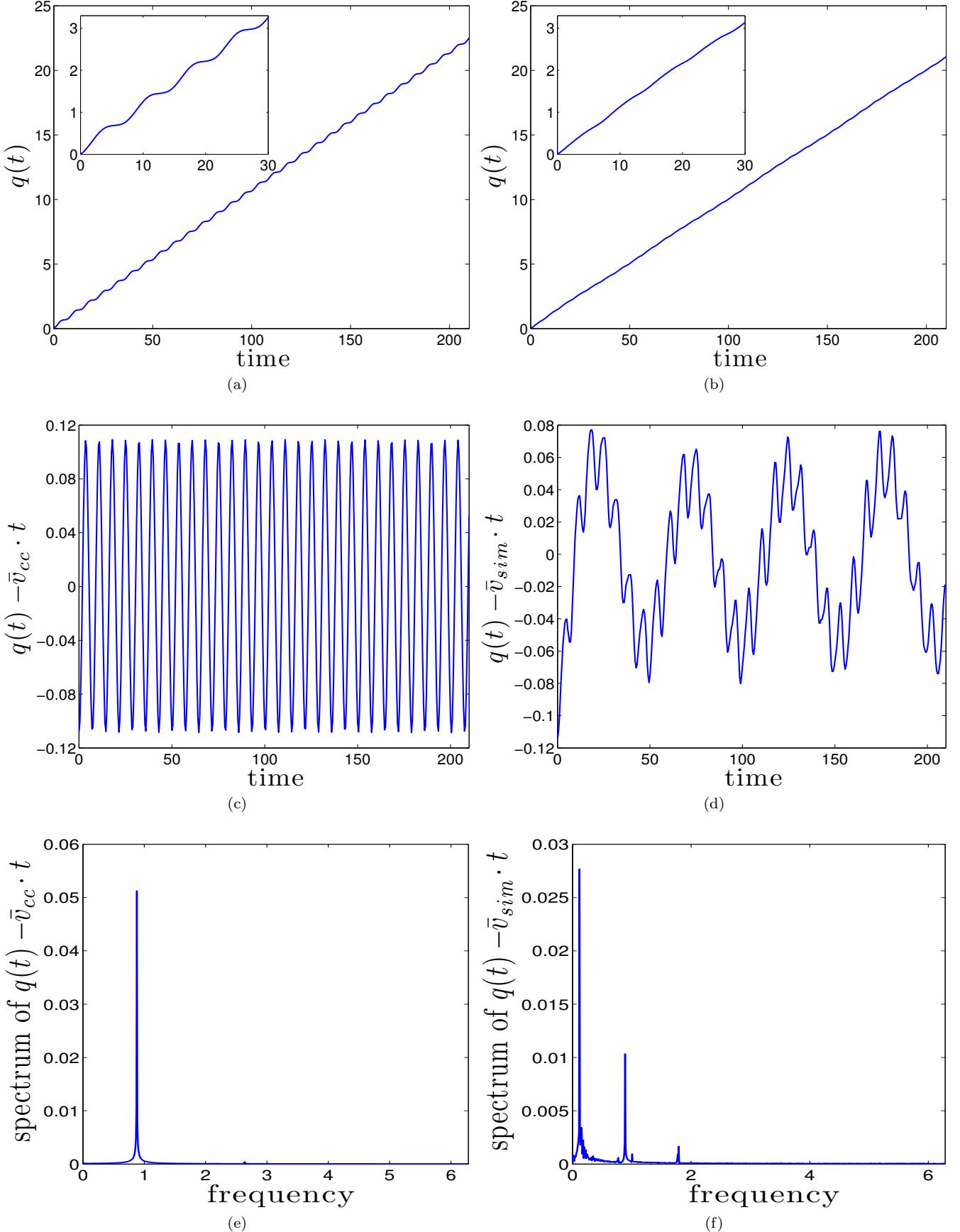


FIG. 8. Oscillations of the translational motion of the soliton. $K = 3\pi/100 \approx 0.094248$ and $v_0 = 0.1$. Other parameters and initial conditions as in Fig. 5. Panels (a) and (b): $q(t)$ from CC theory and simulation, respectively. Panels (c) and (d): $q(t) - \bar{v}t$ from theory ($\bar{v} = \bar{v}_{cc} = 0.1065$) and simulation ($\bar{v} = \bar{v}_{sim} = 0.099805$), respectively. Panel (e): DFT of $q(t) - \bar{v}_{cc}t$, peak at $\omega_1 = 0.87965$. Panel (f): DFT of $q(t) - \bar{v}_{sim}t$, peaks at $\omega_1 = 0.8875$, $2\omega_1 = 1.7750$ and at $\omega_3 = \omega_2 - \omega_1 = 0.11781$.

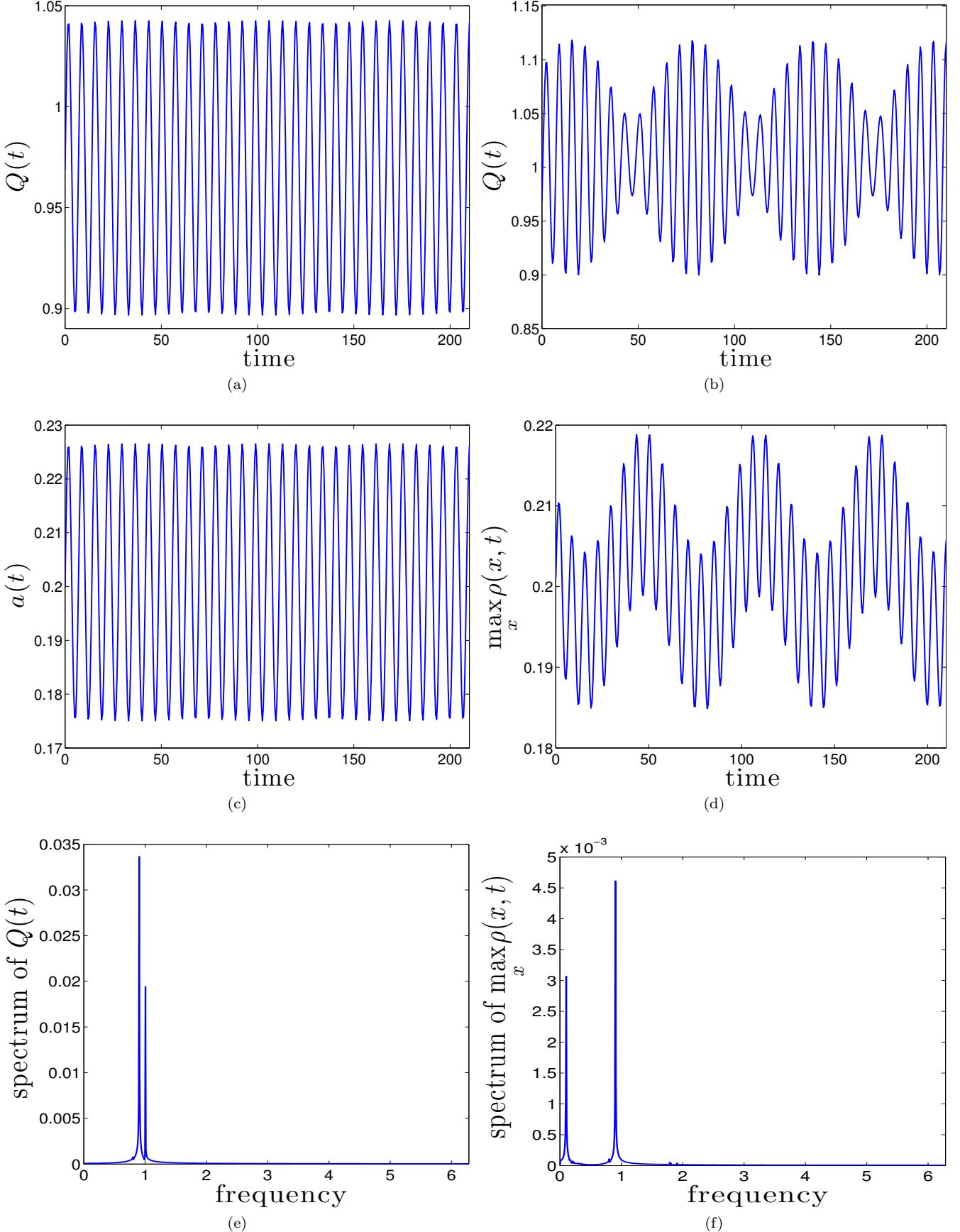


FIG. 9. Intrinsic soliton oscillations for the case of a harmonic inhomogeneous force ($K = -3\pi/100 \approx -0.094248$) and $v_0 = 0.1$. Other parameters and initial conditions as in Fig. 5. Panels (a) and (b): charge from CC theory and simulation, respectively. Panels (c) and (d): amplitude $a = 2[m - \omega(t)]/g^2$ and $\max_x \rho(x, t)$, respectively. Panel (e): DFT of $Q(t)$, soliton peak at $\omega_1 = 0.9032$ and phonon peak at $\omega_2 = 1.0053 \approx \sqrt{1 + k^2}$ with $k = -K$. Panel (f): DFT of $\max_x \rho(x, t)$, peaks at $\omega_1 = 0.9032$, $\omega_3 = \omega_2 - \omega_1 = 0.1021$.

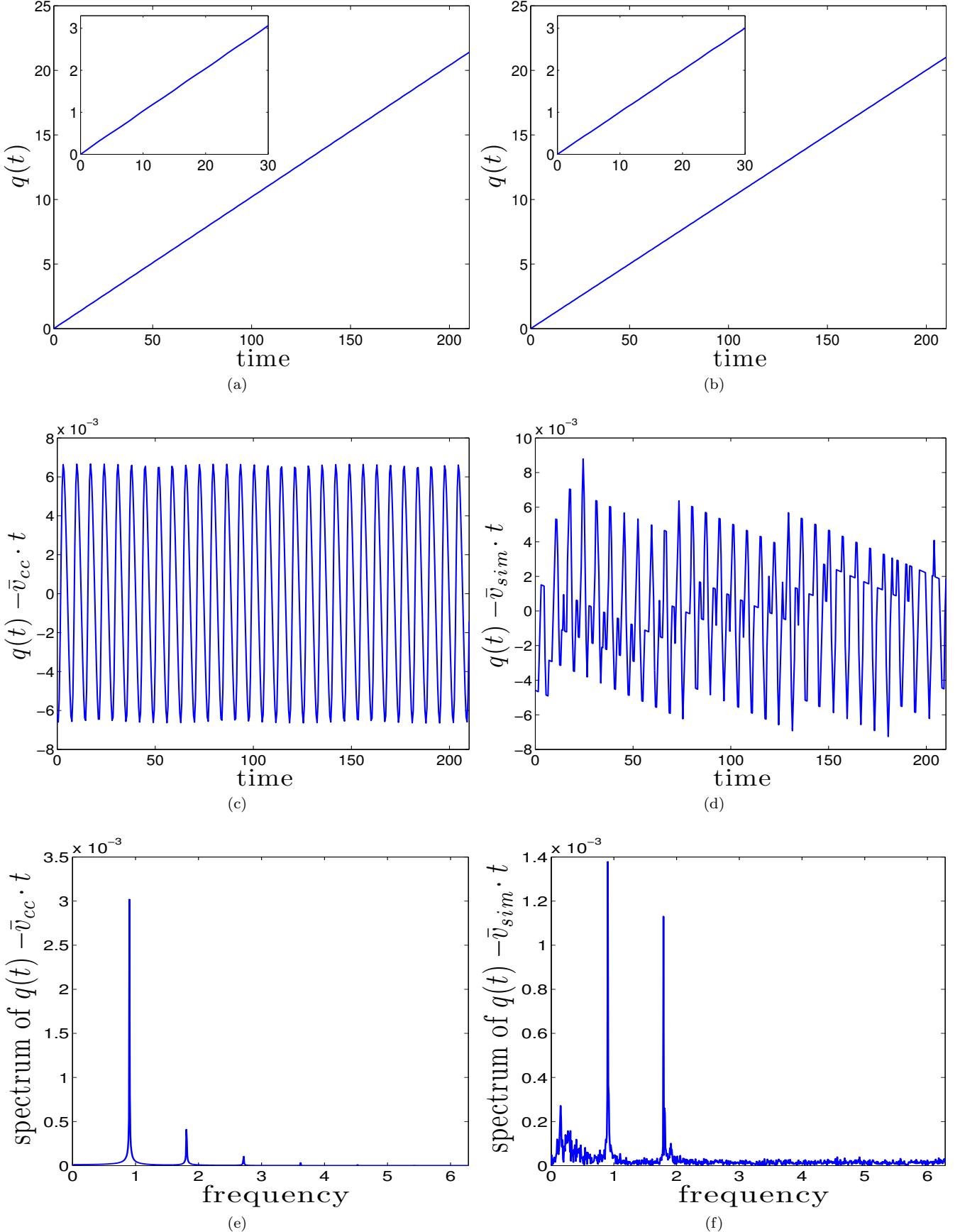


FIG. 10. Oscillations of the translational motion of the soliton. $K = -3\pi/100 \approx -0.094248$ and $v_0 = 0.1$. Other parameters and initial conditions as in Fig. 5. Panels (a) and (b): $q(t)$ from CC theory and simulation, respectively. Panels (c) and (d): $q(t) - \bar{v}t$ from theory ($\bar{v} = \bar{v}_{cc} = 0.1019$) and simulation ($\bar{v} = \bar{v}_{sim} = 0.10005$), respectively. Panel (e): DFT of $q(t) - \bar{v}_{cc}t$, soliton peaks at $\omega_1 = 0.9032$ and $2\omega_1 = 1.8064$. Panel (f): DFT of $q(t) - \bar{v}_{sim}t$, peaks at $\omega_1 = 0.9032$ and $1.7907 \approx 2\omega_1$.

oscillates around a mean trajectory $\bar{v}_{cc}t$. We compared our CC predictions with numerical simulations of the forced NLD equation: The solitary wave solutions are in fact stable and periodic. The observed frequency $\Omega_{sim} = \omega_1$ is nearly identical with Ω_{cc} . However, \bar{v}_{sim} agrees with \bar{v}_{cc} with an error of about 14%. The reason for this is that the CC theory does not include phonons (short for linear excitations). In fact, a specific plane wave phonon mode with wavenumber $k = -K$ is excited together with the intrinsic oscillations in order to conserve the total momentum. The predicted frequency $\Omega_K = \sqrt{m^2 + K^2}$ agrees perfectly with the frequency ω_2 in the spectra of all variables.

For the future work we plan to take initial conditions away from the non-relativistic regime, i.e. initial ω not close to m , and initial velocity not much smaller than the speed of light. Moreover, it will be very interesting to see what is the influence of time dependent external forces, i.e. non-vanishing ν_j .

IX. ACKNOWLEDGMENTS

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Appendix A: Relevant Integrals

For our ansatz in the rest frame, we have that for $\kappa = 1$ the charge Q is

$$Q = \int dx \Psi^\dagger \Psi = \int dx (A^2 + B^2) = \frac{2\beta^2}{g^2(m + \omega)} \int_{-\infty}^{\infty} dx \frac{1 + \alpha^2 \tanh^2 \beta x}{(1 - \alpha^2 \tanh^2 \beta x)^2} \operatorname{sech}^2 \beta x = \frac{2\beta}{g^2 \omega} \quad (\text{A1})$$

For Sec. V we need explicit expressions for the following integrals (in what follows, $y = \tanh \beta x$):

$$\begin{aligned} H_1 &= -\frac{i}{2} \int dx [\bar{\Psi} \gamma^1 \partial_x \Psi - \partial_x \bar{\Psi} \gamma^1 \Psi] = \int dx (B' A - A' B) = \frac{2(m - \omega)}{g^2} \alpha \int_{-1}^1 dy \frac{1 - y^2}{(1 - \alpha^2 y^2)^2} \\ &= \frac{2}{g^2} \left(2 \tanh^{-1} \left(\sqrt{\frac{m - \omega}{\omega + m}} \right) - \beta \right) = I_0, \end{aligned} \quad (\text{A2})$$

$$\begin{aligned} H_2 &= m \int dx \bar{\Psi} \Psi = m I_1 = m \int dx (A^2 - B^2) = \frac{2m\beta}{g^2(m + \omega)} \int_{-1}^1 dy \frac{1}{(1 - \alpha^2 y^2)} = \frac{4m\beta}{g^2(m + \omega)} \frac{\tanh^{-1}(\alpha)}{\alpha} \\ &= \frac{4m}{g^2} \tanh^{-1}(\alpha) = M_0, \end{aligned} \quad (\text{A3})$$

where M_0 is the mass in the rest frame. Note that M_0 has the property of going to zero as $\omega \rightarrow 1$.

$$\begin{aligned} I_2 &= \int dx (A^2 - B^2)^2 = \frac{4\beta^3}{g^4(m + \omega)^2} \int_{-1}^1 dy \frac{1 - y^2}{(1 - \alpha^2 y^2)^2} = \frac{4\beta^3}{g^4(m + \omega)^2} \left(\frac{(\alpha^2 + 1) \tanh^{-1}(\alpha) - \alpha}{\alpha^3} \right) \\ &= \frac{2}{g^2} I_0 = \frac{2}{g^2} H_1. \end{aligned} \quad (\text{A4})$$

To calculate the integral J_j defined in (5.18), first we rewrite it as

$$\begin{aligned} J_j(\omega, \dot{q}) &= \int_{-\infty}^{+\infty} dz A(z) \cos(2\beta a_j z) = \frac{\sqrt{2(m + \omega)} \beta}{g\omega} \int_{-\infty}^{+\infty} dz \frac{\cosh(\beta z) \cosh(i2\beta a_j z)}{\frac{m}{\omega} + \cosh(2\beta z)} \\ &= \frac{\sqrt{2(m + \omega)} \beta}{g\omega} \int_0^{+\infty} dz \frac{\cosh[(1 + i2a_j)\beta z] + \cosh[(1 - i2a_j)\beta z]}{\frac{m}{\omega} + \cosh(2\beta z)}. \end{aligned} \quad (\text{A5})$$

Now using expression (6) on page 357 of [51], after some straightforward calculations we obtain

$$J_j(\omega, \dot{q}) = \frac{\pi \cos b_j}{g\sqrt{\omega} \cosh a_j \pi}, \quad (\text{A6})$$

where a_j and b_j are defined in Eq. (5.18). The integral N_j can be calculated in a similar way.

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