

Sierra SM 4.30 Release

Wednesday, October 9, 2013
(9 sprints)

SAND Number: 2013-9599 C

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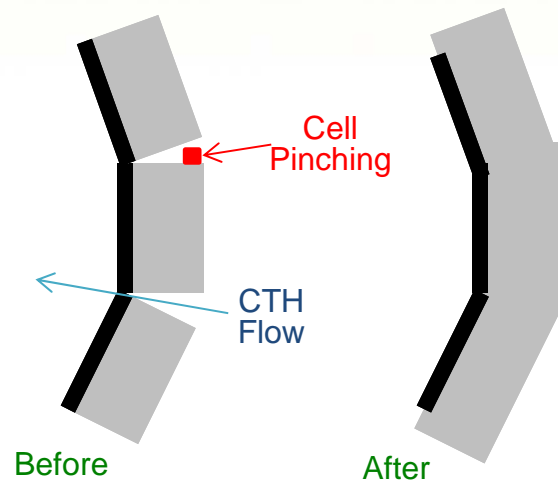


Fortissimo

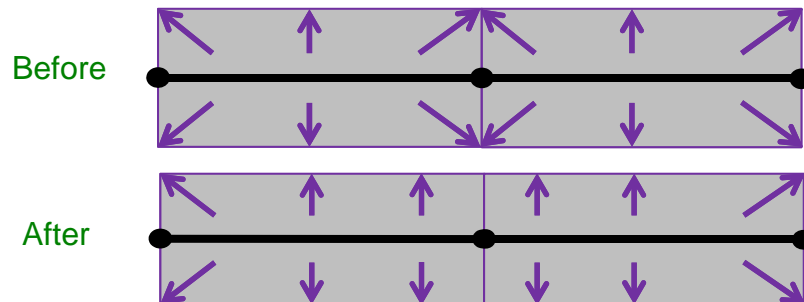
Blast-on-Structure
Sierra-SM coupled to CTH

Fortissimo with Shells

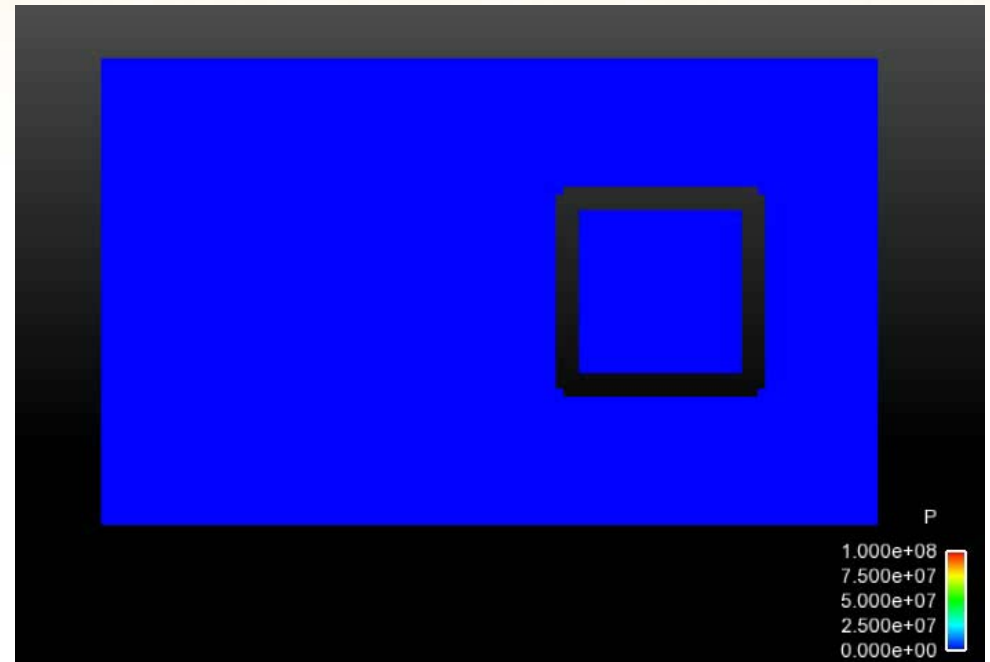
- 1) Expand lofted shells to close gaps in lofted geometry



- 2) More robust normal calculation



- 3) Greatly expanded test coverage

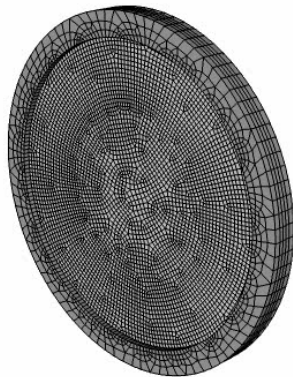


Status

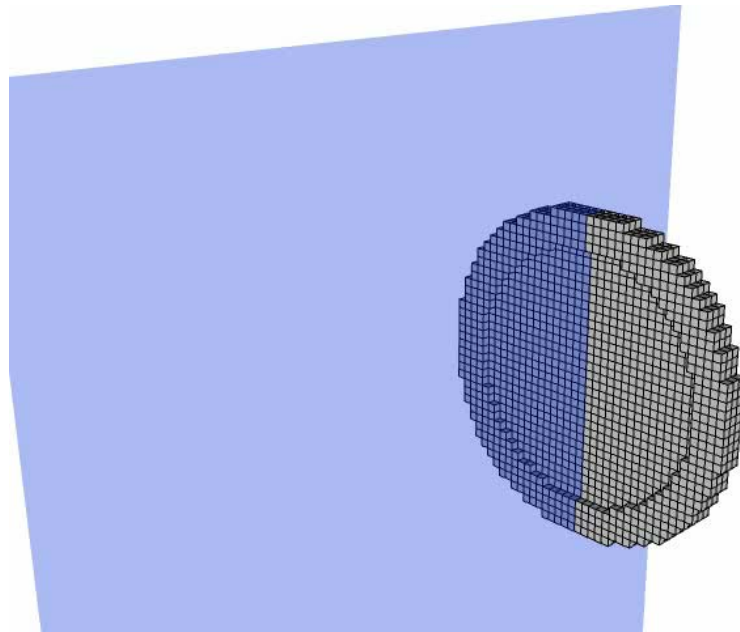
- Bleed through issue fixed
- CTH instability issues appear resolved
- Performance improved 400%
- Ready for friendly user testing

Fortissimo With Element Death

- Properly update Lagrangian boundary representation during element death
- Fix segfaults when using element death with CTH adaptive mesh refinement
- Allow particle conversion in Fortissimo (particles created in Sierra, though not inserted to CTH now)

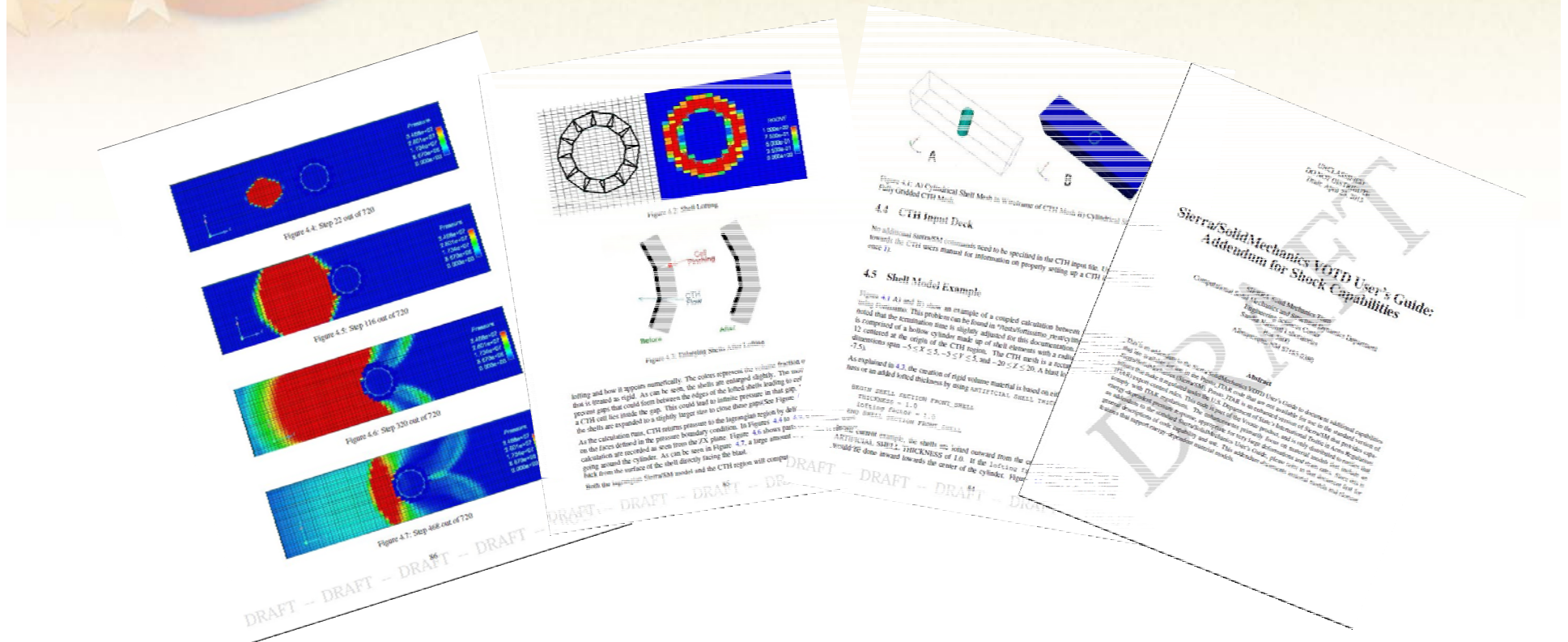


What Sierra Sees



What CTH Sees

Fortissimo Documentation

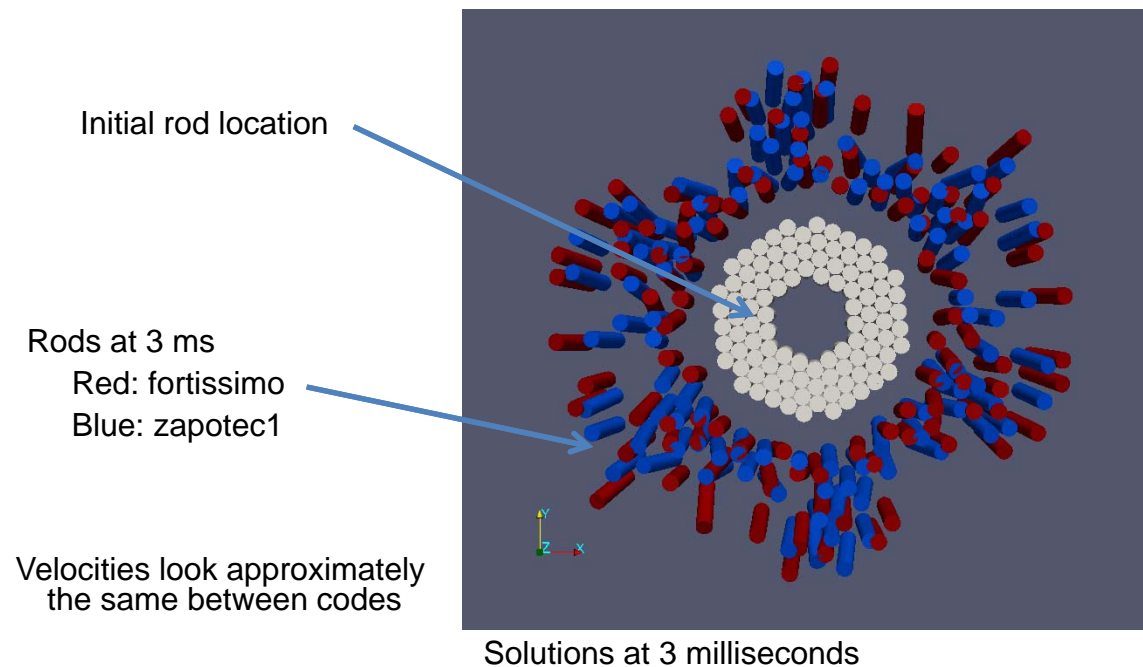


- Added documentation to **Sierra/SolidMechanics VOTD User's Guide: Addendum for Shock Capabilities**.
- Discussed coupling between Sierra and CTH using Fortissimo.
- Explained how shell lofting works
- Includes an example problem

Fortissimo Parallel Performance

Beginning of Sprint Results

	Zapotec 1	Fortissimo
Run Time (hrs)	6.39	44.11
CTH cycles	17701	10323
Lagrangian cycles	43782	29833



(Courtesy of Arne Gullerud)

Fortissimo Performance

	4.29.7	4.29.8
Volume Insertion	4.1	0.9 (4.5X)
Pressure	1.5	0.2 (7.5X)
CTH	4.3	3.8 (*)
Presto	0.1	0.1
REDSKY (64P)	10 Hours	5 Hours

* CTH Version was updated during the sprint.



Elements & Materials

Element Energy Calculations

Following Element Quantities are now Available:

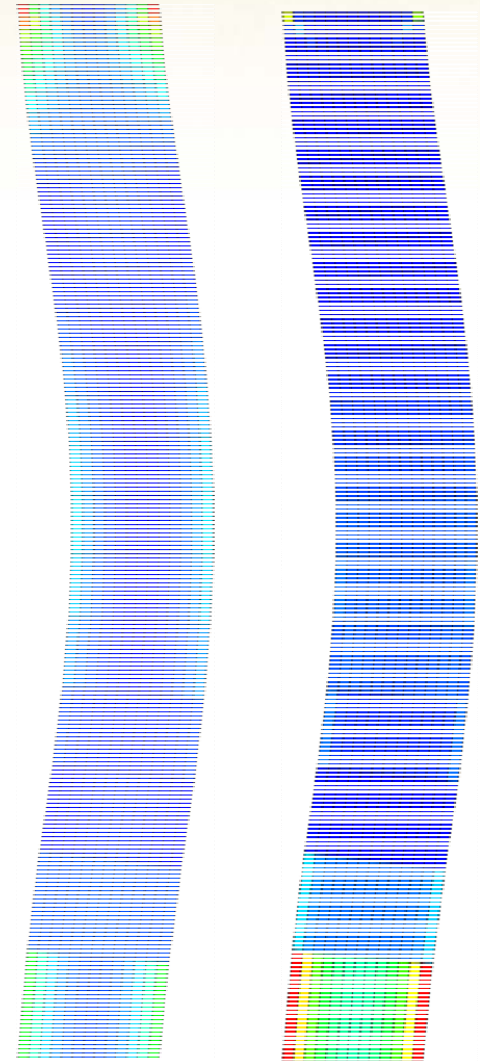
Name	Available For	Description
<i>Internal_energy</i>	~All Elements	Total element internal energy
<i>Internal_energy_density</i>	All Solid Elements	Internal_energy/volume
<i>Hourglass_energy</i>	~All Elements	Total element hourglass energy
<i>Hourglass_energy_density</i>	All Solid Elements	Hourglass_energy/volume
<i>Deformation_energy_density</i>	All Solid Elements	Internal_energy_density minus Hourglass_energy_density
<i>Strain_energy_density</i>	Single Integration Point Solid Elements	Integral of material stress dot material strain
<i>Strain_energy</i>	Single Integration Point Solid Elements	Strain_energy_density * volume

Note:

“*Deformation_energy_density*” should match JAS3D “**EINENG**”

“*Strain_energy_density*” should match ABAQUS “**SENER**”

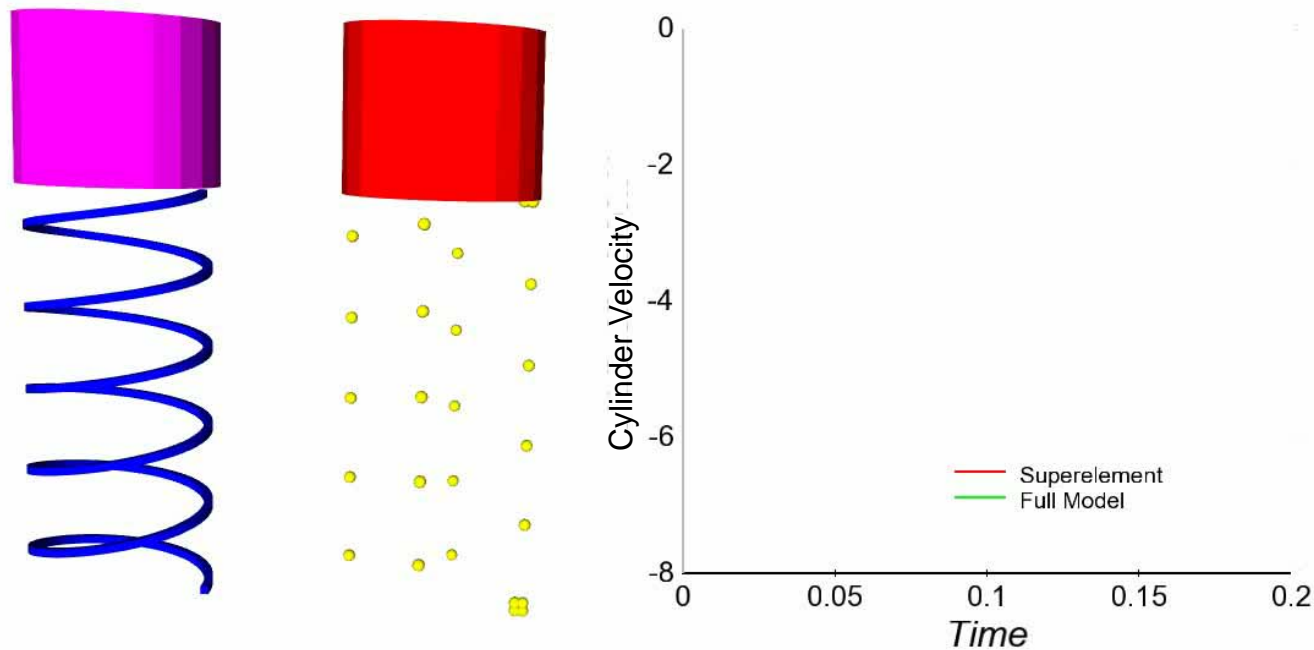
In absence of thermal strains these two quantities are identical



Strain Energy
Density

Hourglass Energy
Density

Superelement Example



Full Model

Adagio Runtime: 7 hours

Superelement Composite Model
(150 Modes)

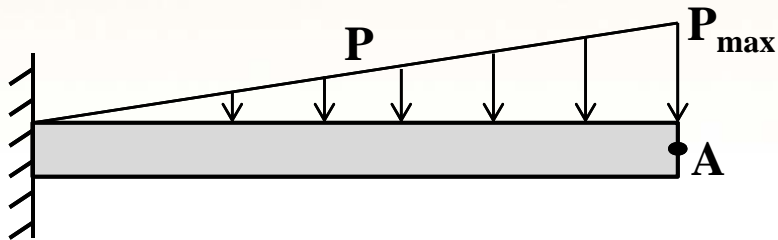
Linear Spring + Nonlinear
Contact

Salinas Runtime: 2 minutes
Adagio Runtime: 3 minutes
Total Runtime: 5 minutes

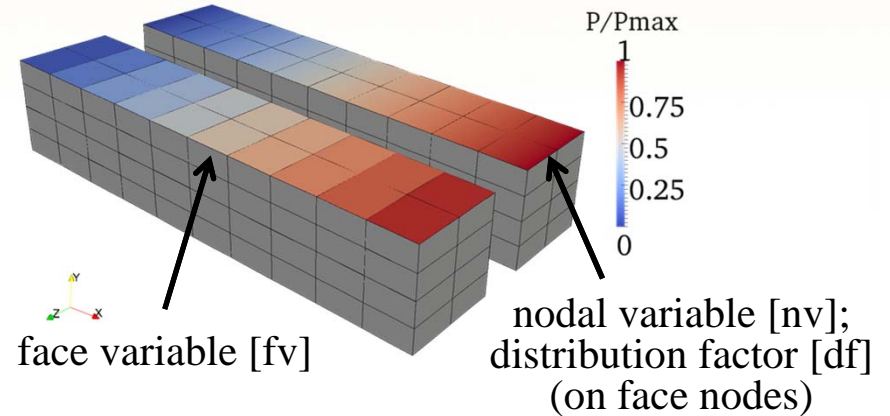
Super element composite model captures most
spring behavior:

- Vertical stiffness of spring
- Lateral shift in spring due to vertical load
- Slip of spring off cylinder
- Ultimate velocity of cylinder

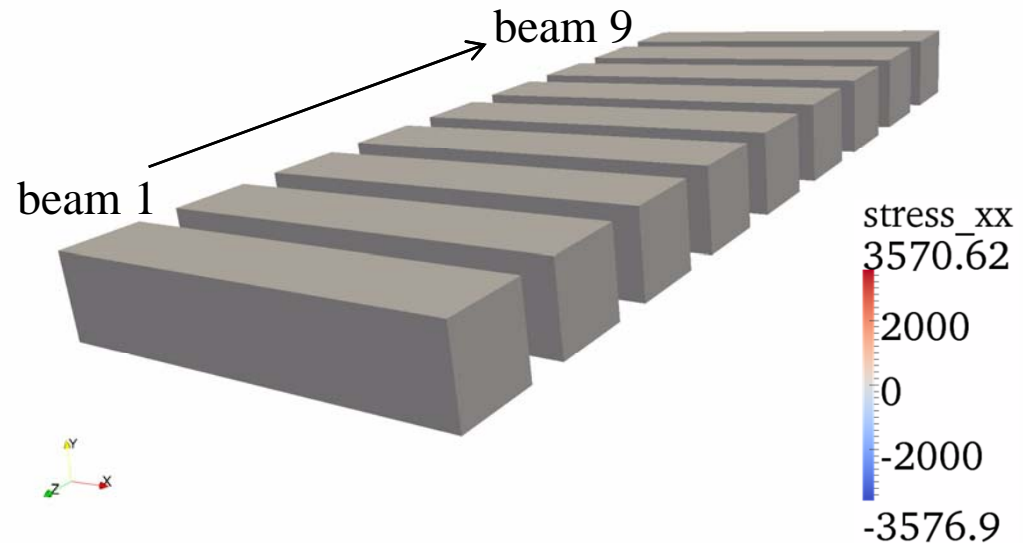
Element Consistent Pressure Loads



3 Ways to Apply Spatially Varying Pressure:



beam	elem	df fv df	$\Delta_{A,max}$
1	hex8	df	0.146
2	hex8	fv	0.145
3	hex8	nv	0.146
4	hex20	df	0.144
5	hex20	fv	0.143
6	hex20	nv	0.144
7	hex27	df	0.144
8	hex27	fv	0.143
9	hex27	nv	0.144
Euler-Bernouli sol'n :			0.138



Hyperfoam Modulus

Objective:

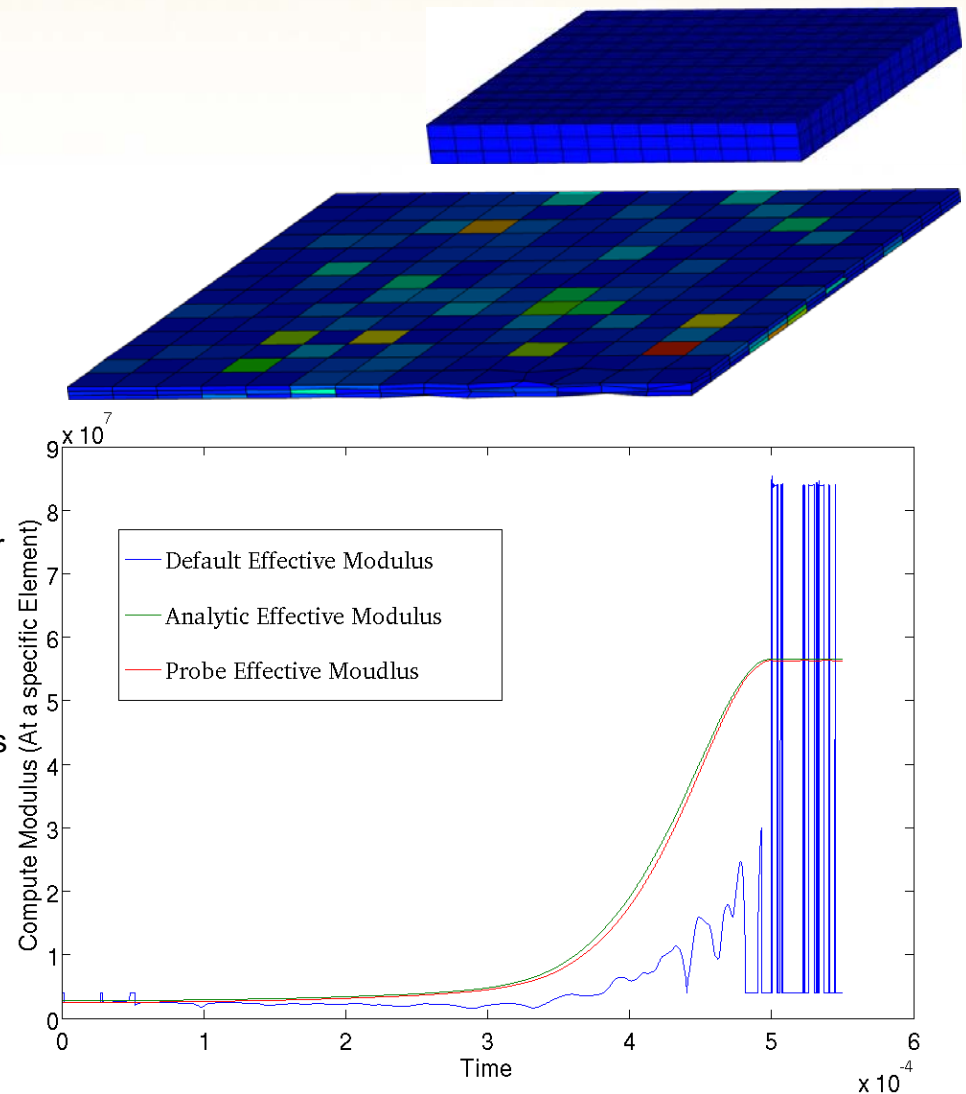
Repair instability issues in systems models using the hyperfoam material model. Hyperfoam material exhibits substantial stiffening under compression.

Issues Identified with Default Modulus:

- If strain increment too small default secant modulus reverts to uncompressed modulus
- Modulus can be significantly anisotropic, different strain directions yield different modulus.
- Modulus controls hourglass and time step. If wrong or volatile causes instability.

Done this Sprint:

- ✓ Implement optional PROBE effective material modulus option. Much more robust, somewhat more expensive, can be used with any material.
- ✓ Bill Scherzinger implemented analytic stiffness for hyperfoam model.



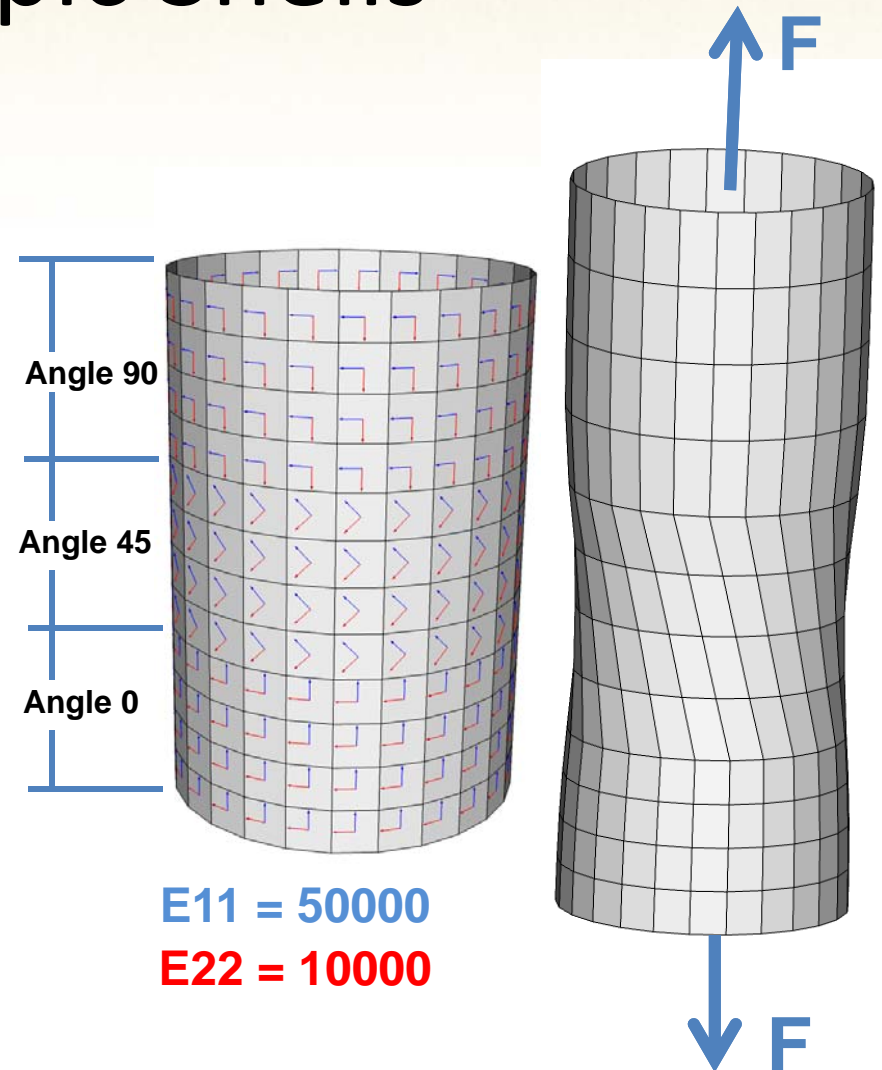
Orthotropic Shells

Objective:

Initial implementation for orthotropic shells in Sierra/SM

Done:

- ✓ Implement basic 2D orthotropic elastic shell model (six elastic constants)
- ✓ Implement syntax to read and create element local coordinate systems. Based on R vector, T vector, and orientation angle.
- ✓ Allow visualization of rotated reference frame
- ✓ Verified: Correct response for orthotropic hoop and axial strain in cylinder
- ✓ Verified: Model correctly reproduces isotropic results for isotropic inputs





XFEM

Failure modeling

2-D XFEM Example Problems

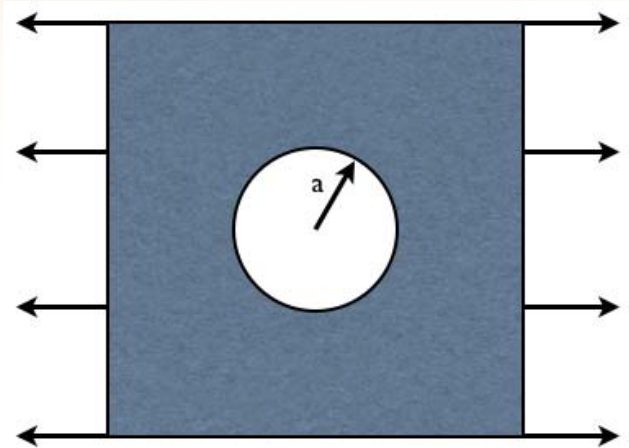
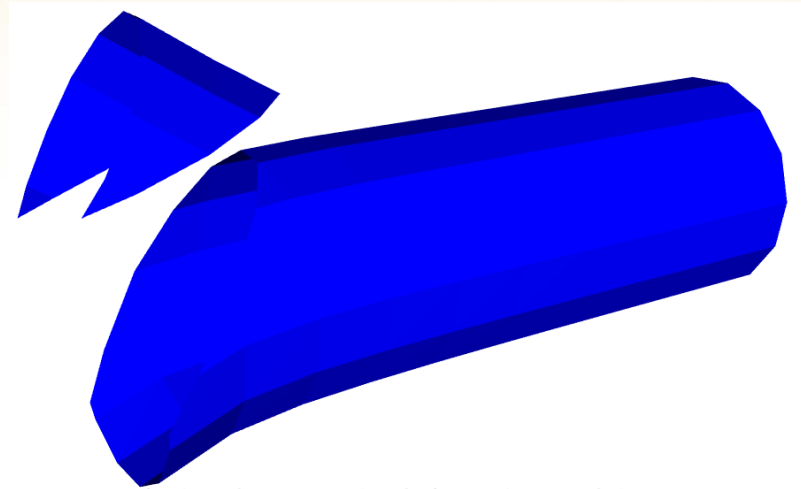


Plate with hole problem
Capabilities tested: Crack nucleation, planar crack growth, cohesive zone insertion



Cylinder Angled Crack Problem
Capabilities tested: Angled prescribed crack and planar crack growth

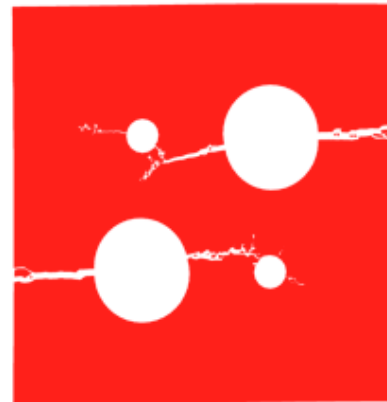
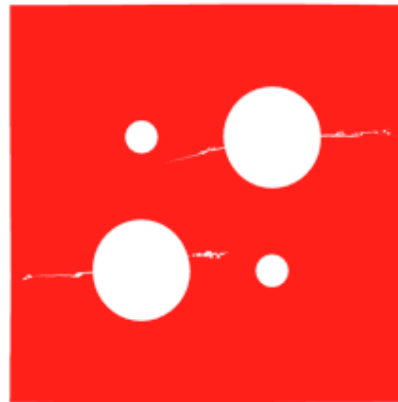
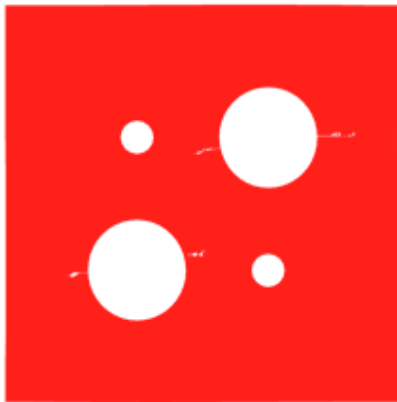
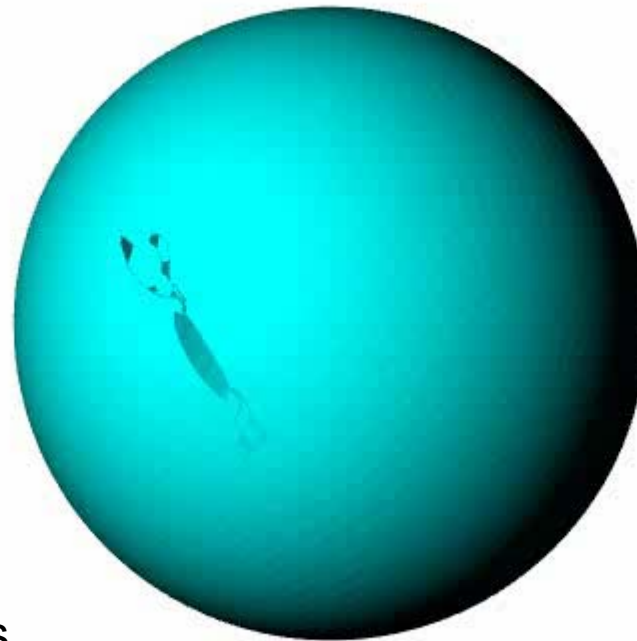


Plate with Multiple Holes Problem
Capabilities tested: Crack nucleation, branching, piecewise-linear crack growth

2D: XFEM with Element Death



Mark Merewether's test case.

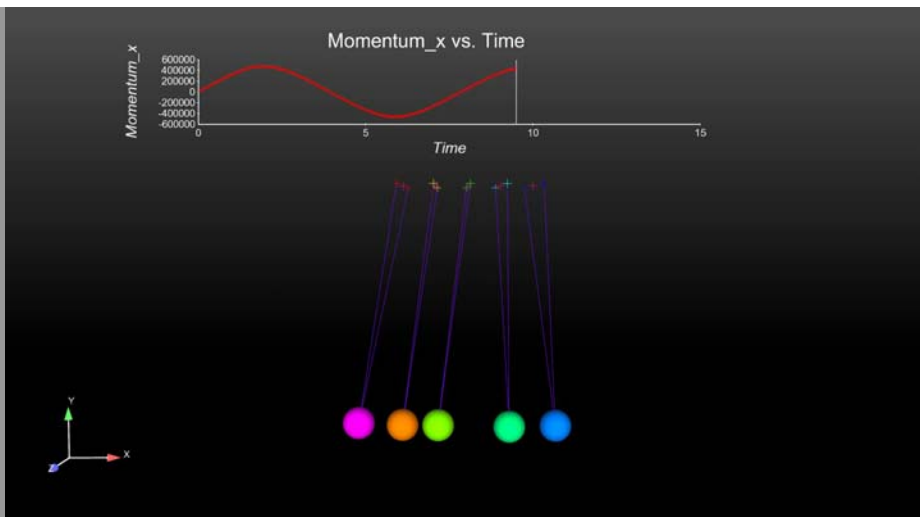
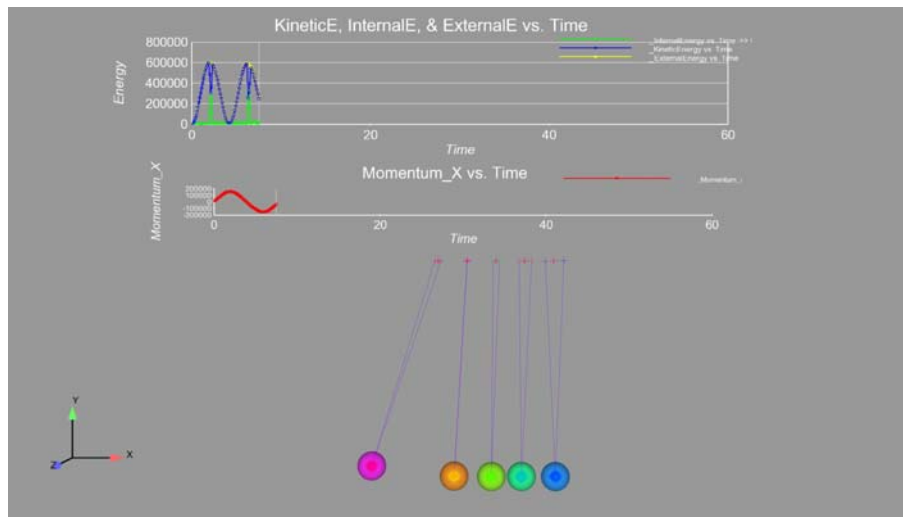
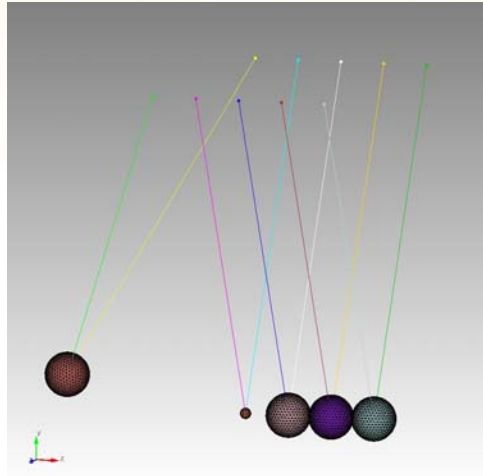
- XFEM to model initial mechanics driven cracking
- Element death to resolve complex crack intersection and remove instabilities



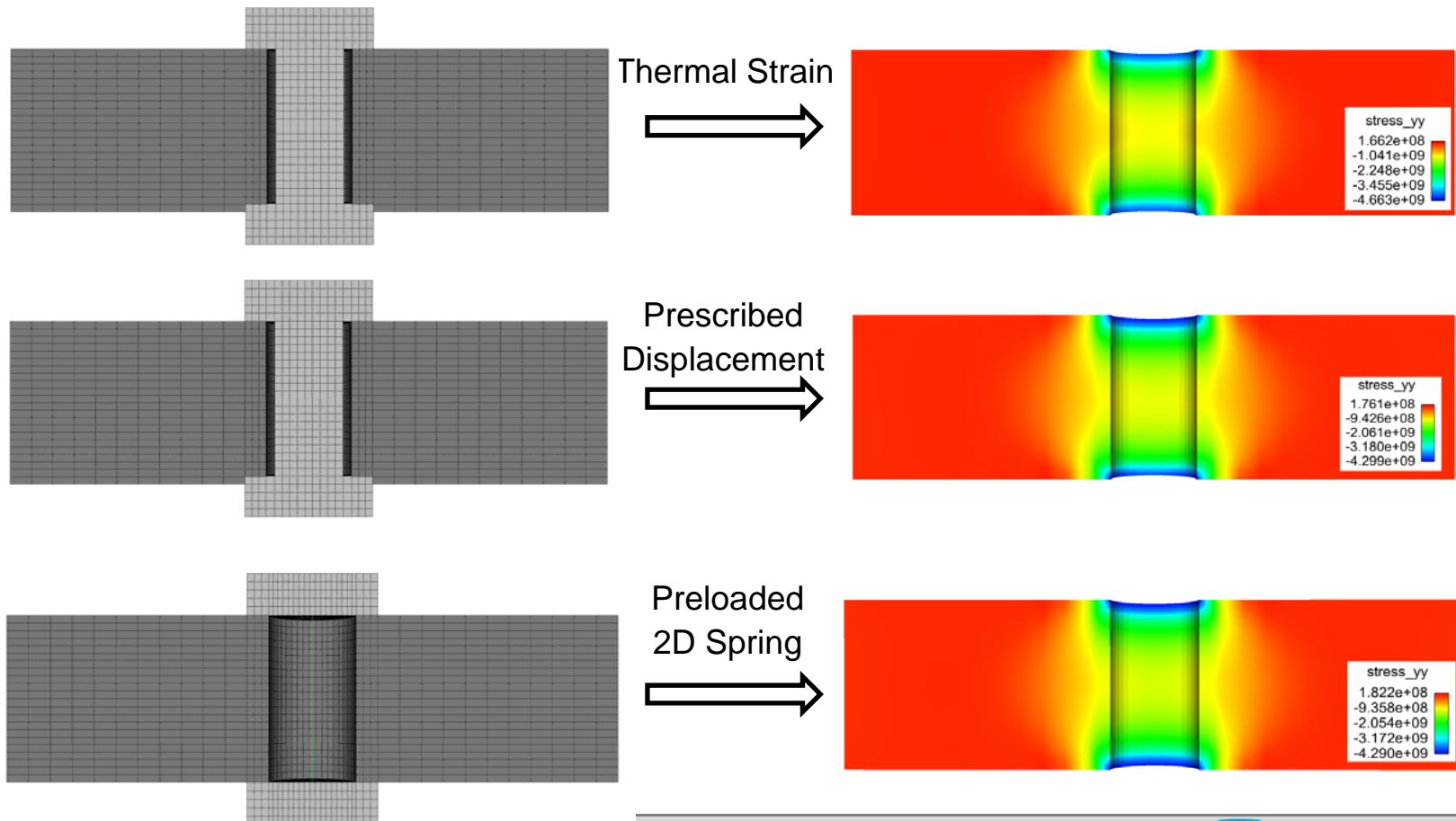
Example Problem Manual

Newton's Cradle

- Rigid Bodies
- Truss Elements
- Gravity Load
 - Fixed Displacement: x y z
 - Fixed Rotation: x y



Bolt Preload



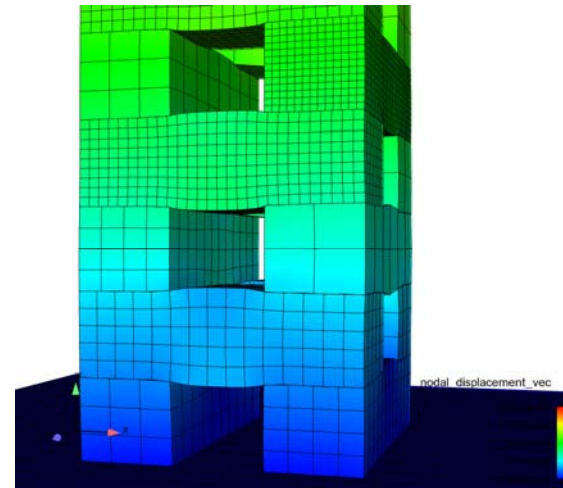
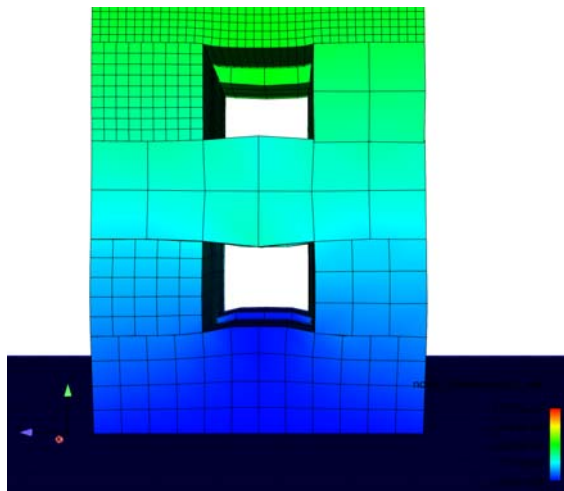
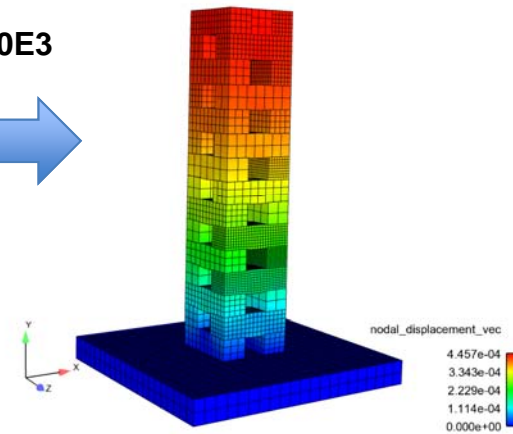
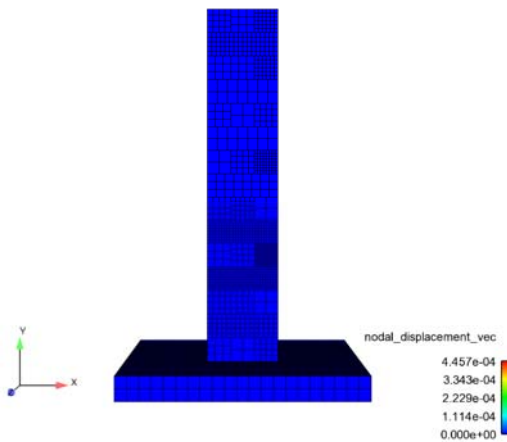
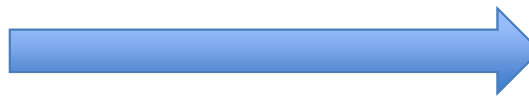
Jenga Tower

Initial Tower

Final Tower

Gravity Preloaded

Displacement Factor: 2.00E3





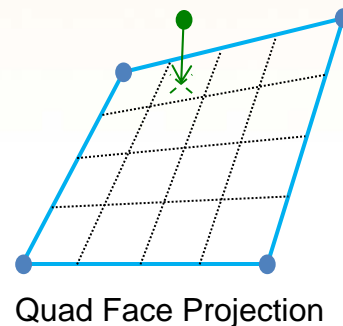
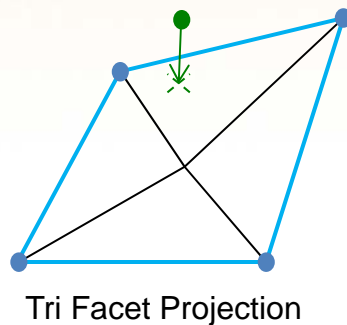
Contact

SM/SD/TF

Friction Models

Marching towards default DASH

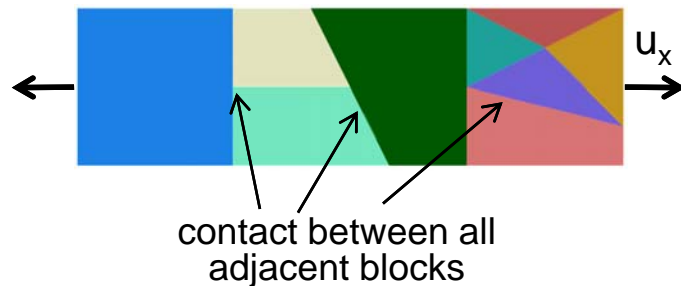
Quad Face Projection in DASH



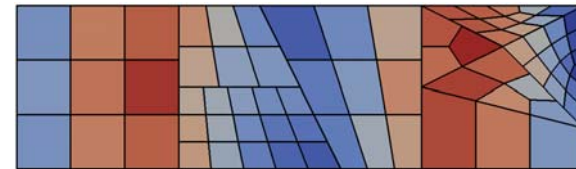
- **Done this sprint:**
 - Enable capability in DASH
 - Not default (yet); undocumented
 - Regression tests in explicit & implicit
- **To do next:**
 - Optimization, Performance & robustness testing

Beam Tied Contact Test, Explicit Transient Dynamics

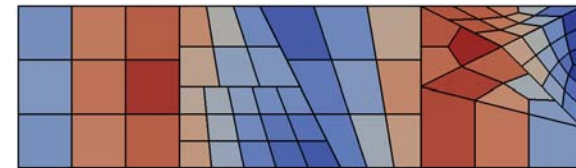
- stress_xx waves should be continuous



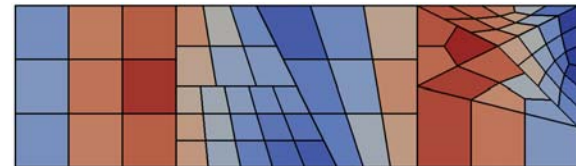
ACME --
QUAD FACE
PROJECTION



DASH --
QUAD FACE
PROJECTION

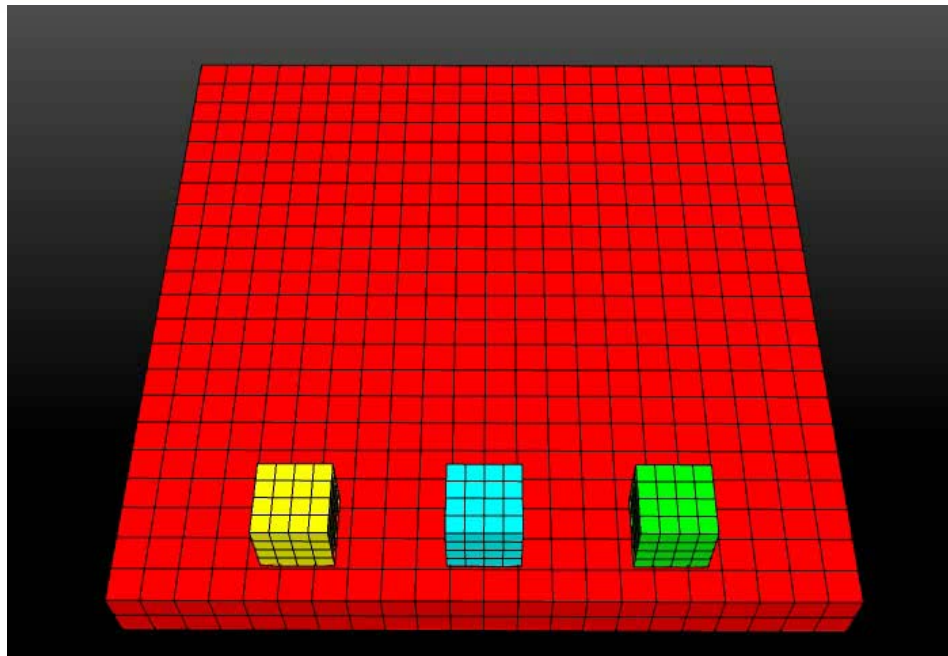


DASH -- TRI
FACET
PROJECTION



stress_xx
25000
24000
20000
16000
12000
8000
6500

Contact: Refactoring Friction Models and Add Time Varying Friction Model



Frictionless

Time-Varying

Constant Coulomb

- Refactored Dash friction models section of contact for easier friction model implementation
 - Moved friction model classes to individual files
 - Moved implicit calculations onto the friction model class
 - Each friction model class has implicit AND explicit functions
- Implemented a time-varying friction model
 - Refactoring of friction models allowed for 1.5 day implementation of new model

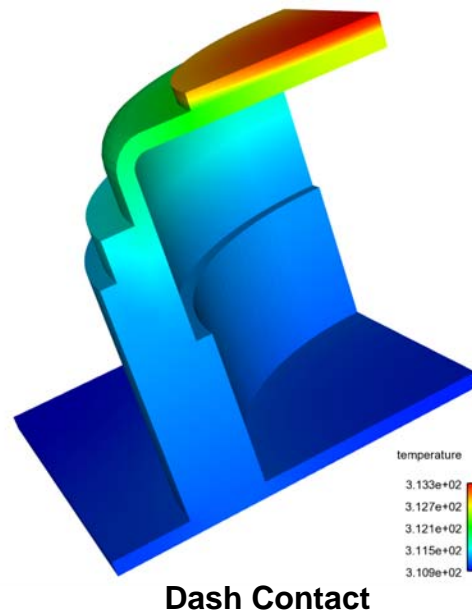
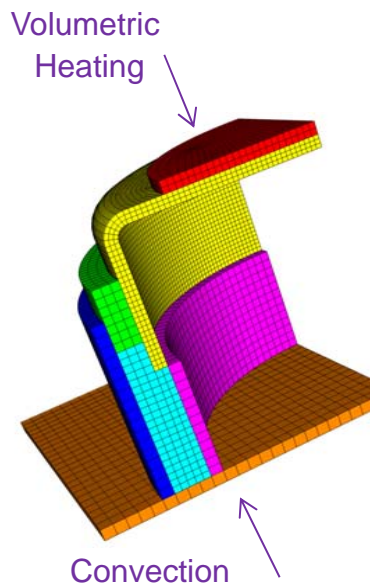
Migrate Dash Contact to Aria

What Was Done:

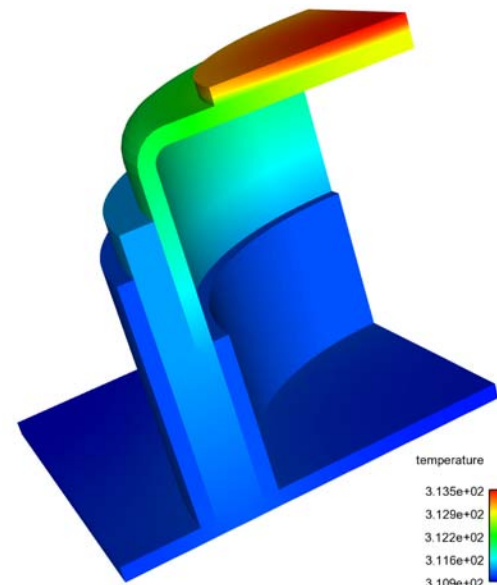
- Some generalizations to contact of concepts like stiffness, mass, and displacement to thermal contact
- Enable use of Dash defined contact constraints in Aria Thermal contact
- Testing, debugging, verification, and more debugging

Purpose:

- Leverage structural contact work to provide robust and efficient thermal contact
- Make a single contact definition work for both structural and thermal contact with the same options and behavior



Dash Contact



Generalized Contact

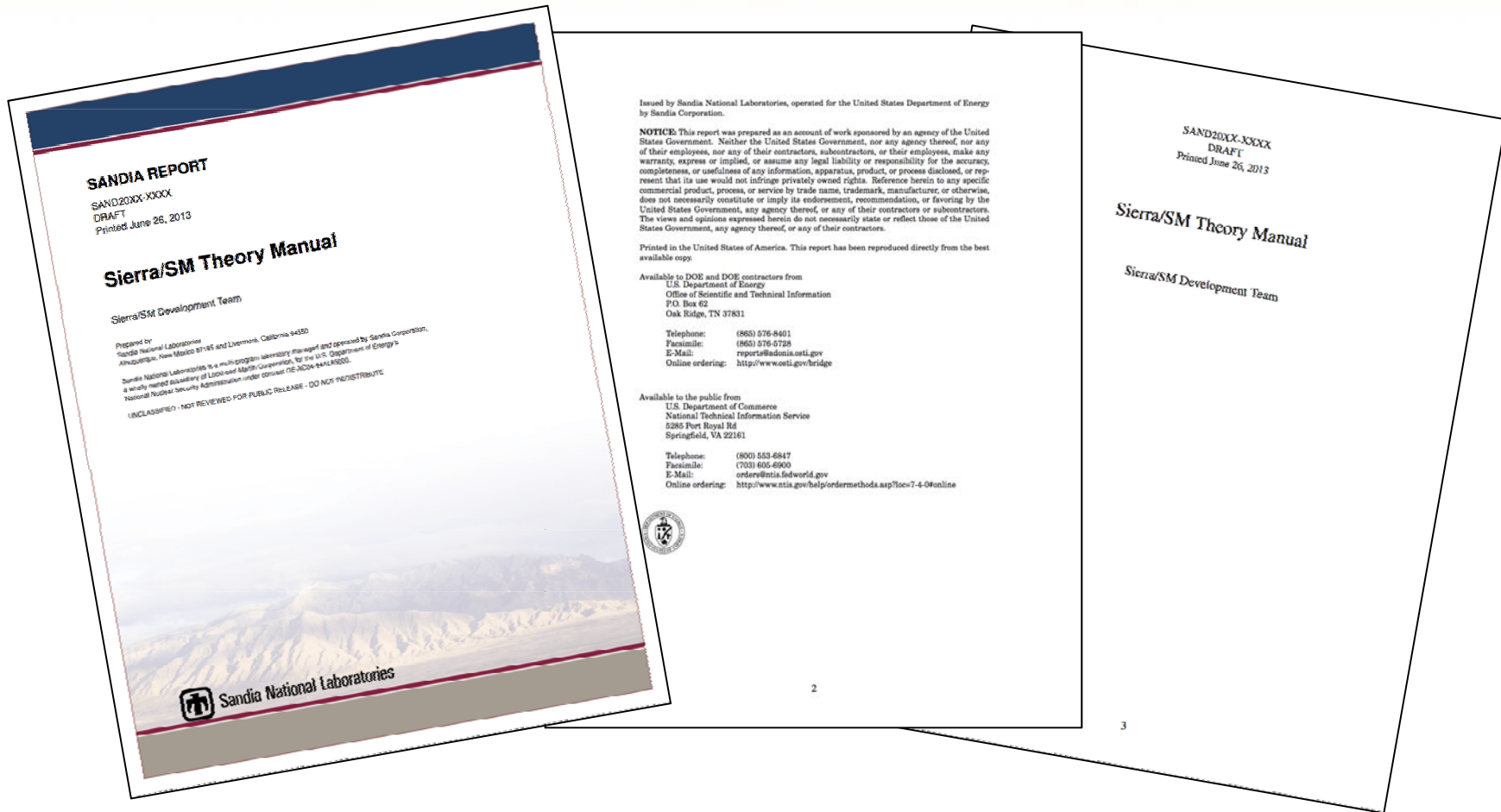


Documentation

Theory Manual

OBJECTIVE

- Get theory manual ***draft*** ready for R&A [DONE]



Updated Verification Tests Manual



- Manual status
 - 4.26 release (end of FY12):
 - # pages: 250
 - # nightly test runs: 38
 - 4.28 release:
 - # pages: 310
 - # nightly test runs: 78
 - 4.30 release (end of FY13):
 - # pages: 470
 - # nightly test runs: 106
- New features in 4.30 release:
 - Significant improvements in contact feature coverage
 - Especially for implicit
 - Contact mesh convergence tests
 - Improved Introduction
 - Background
 - Discussion of verification approaches

**180%
increase
during FY13**

Testing

Nightly Memory Usage Testing

Motivation:

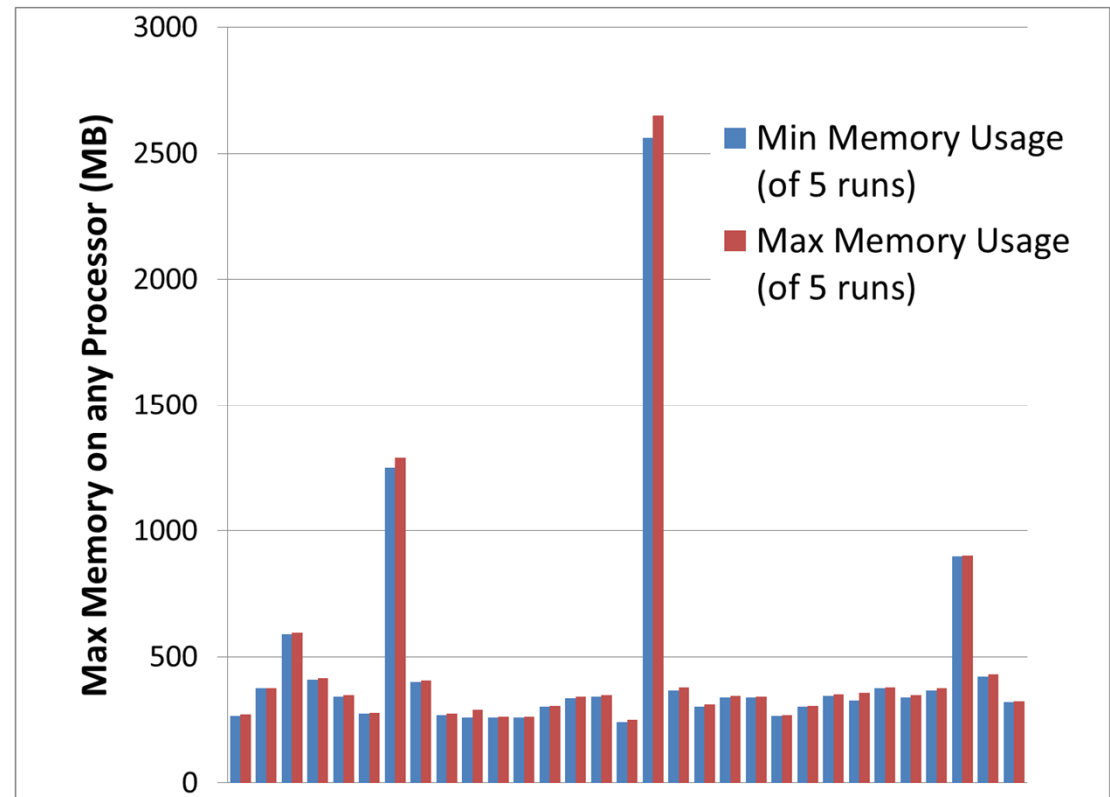
Ensure that future changes to STK mesh or other new code development does not adversely increase the memory usage of Sierra Solid Mechanics analysis runs.

What was done:

- Memory logging added to all redsky performance tests (~45 tests)
- Tests pass if memory usage is within 5% of current baseline

Lessons Learned

- Some variance night to night, but low.
- All Sierra jobs require at least 250 MB memory per processor no matter the size.



Performance Test Suite

OBJECTIVE

- Evaluate and start refactoring our performance tests.

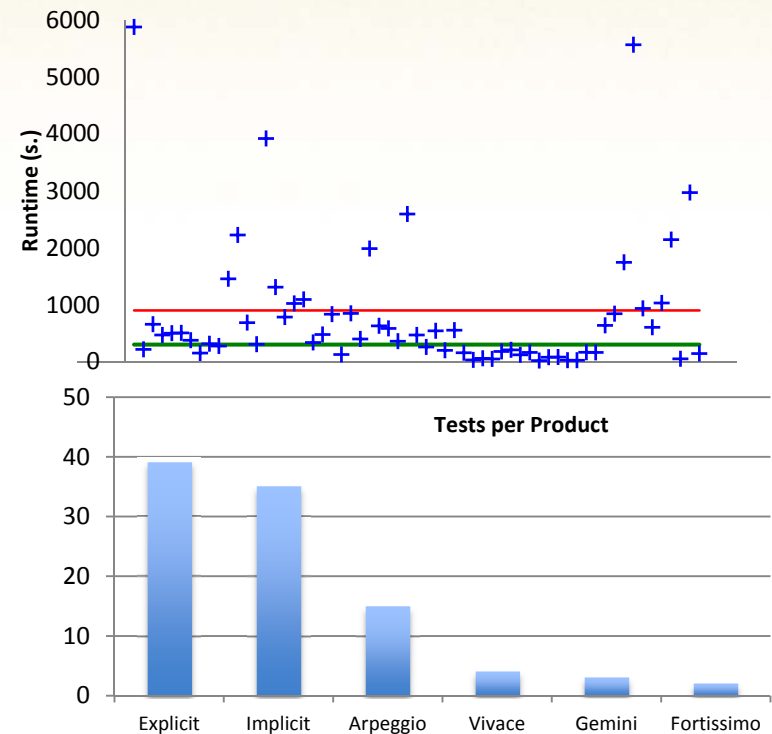
DONE this sprint

- Reorganized all performance tests under performance folders, located inside each product's test directory.
- Removed fast running performance tests by moving them out of the performance folder, and eliminating the "performance" keyword from their *.test file.
- Added missing performance checks (runtime, memory) to worthy tests with the "performance" keyword in their *.test file.
- Classify them depending on product, feature coverage, solver settings, runtime, element type and size.

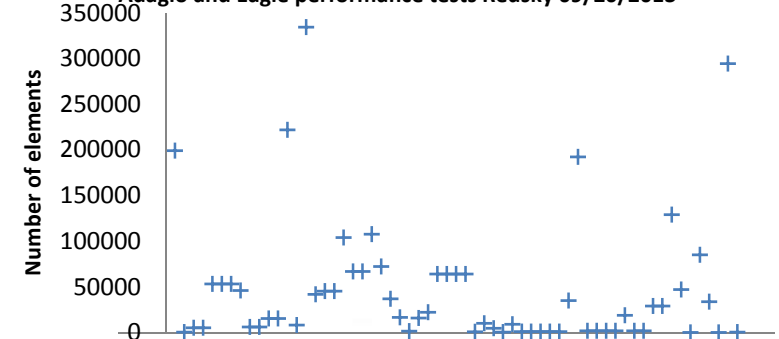
Potential next steps

- A natural next step is to evaluate all data gathered during this sprint and make recommendations for improving our performance testing.
- One recommendation is to establish a weekly test suite to include performance testing of full scale analyses.

Adagio and Eagle performance tests Redsky 09/20/2013



Adagio and Eagle performance tests Redsky 09/20/2013





Thank You!

The Solid Mechanics Team was able to deliver these capabilities while also addressing ~25 user support tickets per sprint!

The Solid Mechanics PMs who organized the important user support and any major user requested capability development!

The Solid Mechanics Scrum Master who are invaluable in organizing the reviews, planning meetings, and daily standups!

The Solid Mechanics Users who have identified issues to fix, documentation to update, and been generous with their time in verifying user support issues.